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1966-8

R. Teoste

Haystack Pointing System:  
Satellite Acquisition

30 March 1966

Prepared under Electronic Systems Division Contract AF 19(628)-5167 by

## Lincoln Laboratory

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

Lexington, Massachusetts



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MASSACHUSETTS INSTITUTE OF TECHNOLOGY  
LINCOLN LABORATORY

HAYSTACK POINTING SYSTEM: SATELLITE ACQUISITION

*R. TEOSTE*

*Group 62*

TECHNICAL NOTE 1966-8

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#### ABSTRACT

Haystack Pointing System consists of hardware and software which points the Haystack 120-foot X-band antenna dish with great accuracies. The Satellite Acquisition program, described in this report, generates acquisition scans and searches for target returns. Once the target has been sighted, the program tracks the target by conical scanning. After acquisition, time correction can be made in the orbit computations.

Accepted for the Air Force  
Franklin C. Hudson  
Chief, Lincoln Laboratory Office

## HAYSTACK POINTING SYSTEM: SATELLITE ACQUISITION

### INTRODUCTION

One of the objectives of the Haystack facility is to track satellites for various experiments. Monopulse autotrackers have been built for this purpose. The autotrackers require that the antenna beam be pointed at the satellite, before automatic tracking can take place. The satellite program<sup>1,2</sup> of the Haystack Pointing System<sup>3</sup> is capable of computing azimuth and elevation commands from orbit parameters; but past experience has shown that the accuracy of the available orbit parameters is too poor to place the satellite within the antenna beam. An initial search has to be conducted to locate the satellite before autotracking can take place.

An acquisition program has been written for the Univac 490 computer to facilitate a more orderly search and acquisition. The primary objective of this program is to find the target and point the antenna at it long enough for the autotracker to lock on and follow the target from the acquisition point. However, the program is capable of independently tracking the satellite by continuously sensing the discrepancy between the computed commands and the actual target position.

The program was written to be used with the first Haystack radar equipment and the sequential doppler processor built by W. F. Kelley<sup>4</sup>. This equipment generates a pulse, called a RP2 pulse, whenever the receiver output exceeds a given threshold. These pulses can be generated by noise and false targets as well as the target which is being tracked.

Indeed, the program only requires that a RP2 like signal be given the computer whenever the target is within the antenna beam. Hence, any equipment that generates

1. A. A. Mathiasen and J. D. Drinan, editors, "Haystack Pointing System: Satellite," Lincoln Laboratory Technical Note 1965-36, (9 September 1965).
2. A. A. Mathiasen, editor, "Haystack Pointing System: Mathematical Development for Satellites and Belts," Lincoln Laboratory Technical Note 1965-49, (23 September 1965).
3. A. A. Mathiasen and J. D. Drinan, "Haystack Pointing System: Control Structure," Lincoln Laboratory Technical Note 1966-10, (March 9, 1966).
4. H. G. Weiss, "The Haystack Experimental Facility," Lincoln Laboratory Technical Report 365, (15 September 1964).

such a pulse can be used in conjunction with the acquisition program. R. Silva has constructed a CW monopulse autotracker which generates the RP2 pulse whenever signals exceed a threshold. The acquisition program has successfully acquired one of the Lincoln experimental satellites, LES II, using this equipment.

The Haystack computer can send pointing commands to the Westford antenna over telephone lines<sup>5</sup>. A. Dockrey has built circuitry at the Westford site to allow a RP2 pulse to be sent back to the Haystack U-490 computer under various modes of Westford equipment operation. The acquisition program has acquired satellites by means of Westford equipment in the radar mode as well as in the CW mode.

Since the doppler and range predictions are usually within the required accuracies, the acquisition program only searches and acquires in azimuth and elevation angles. No provision has been made for range or doppler acquisition.

The program acquires in two phases. First, a search scan is generated which grossly looks for the target. It does this by superimposing a long and narrow scan along the orbit and searching for RP2 pulses. Secondly, when a hit is received (designated by an RP2 pulse), the values of azimuth and elevation for the target are observed and a local scan is initiated around these coordinates. The local scan consists of a set of concentric circles. The radius of the consecutive circles being increased by about one beamwidth from one circle to the next. The local scan is continuously computed, even after the antenna is controlled by the analog tracker; so that if at any time the analog tracker should lose the target, the computer will have a correct pointing angle already computed in the buffer region. By simply changing the antenna mode to computer pointing, the target will again be acquired.

When the program has made three successful local scans, a message is printed to indicate that the target has been acquired. At this time the operator can ask the program to compute and affect a time correction in orbit computations which is expected to correct most of the error in predicted angles. If reacquisition is later required, the acquisition program will not have to search quite as large an area. A local scan may be sufficient for reacquisition after time correction has been made.

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5. J. E. Gillis, "Haystack-West Ford Intersite Coupling Link," Lincoln Laboratory Group Report 1964-25, (14 May 1964).

The program is under complete control of the operator. The automatic sequence of scans just described can be overridden by means of the keyboard. For instance, at any time the search scan can be made to start over, fixed biases can be added to the predicted commands, the program computed errors can be set to zero, only local scan can be requested if predictions are known to be sufficiently accurate, etc.

## OPERATOR INTERVENTION

Figure 1 shows a typical on-line record of operator action. Typical acquisition scans are shown by Fig. 2 where the command elevation is plotted as a function of command azimuth. When the pointing system is requested to point at a satellite, the question "Do you want acquisition" is asked and three choices are given as shown in Fig. 1. The only other method of getting to the acquisition program is through the attention symbol as shown by Fig. 1. When the program is reached through the attention symbol, the operator is offered more choices.

### 1. Stop Acquisition

This choice stops the acquisition scans and causes the program to ignore the RP2 interrupts.

### 2. Search Scan

This choice sets up the normal acquisition mode. The program will first scan in a long and narrow area of uncertainty along the orbit. The scan shown in Fig. 3 is superimposed on the computed pointing commands. The length and width of the scan is requested through the keyboard. When RP2 pulses are observed, the program automatically switches to local scan. When RP2 pulses disappear for a sufficiently long period the program goes back to search scan.

### 3. Local Scan

This choice allows the program to superimpose only a local scan on the pointing commands. Figure 4 shows a local scan. The RP2 pulses are observed as usual.

```

SYSTEM DATA RECORDING...COMPLETE(0) PARTIAL(1) NONE(2) 0
*

DO YOU WANT ACQUISITION

NO(1) SEARCH SCAN(2) LOCAL SCAN(3)
2*

ENTER SCAN LENGTH IN DEGREES
3*

ENTER SCAN WIDTH IN DEGREES
.4*

DATA PROCESSING PROGRAM..
NONE(0) RADIOMETER(1) RADIOMETER SCAN(2) MERCURY EXP(3)
*
⊙

SIGN OFF(1) MOD(2) NEXT RUN(3) PRINT(4)
2*

SAT (1) DATA PROCESSING(2) SCAN(3) RECORDING(4) TIMING(5) OTHER(6)
6*

RA-DEC DISPLAY(1) CORRECTION(2) PARAMETERS(3) ACQUISITION(4)
CC(5) DYDMP(6) PLOT(7) AUTOT(8)
4*

STOP (1) SEARCH(2) LOCAL(3) CL BIAS(4) SET BIAS(5) TIME (6) HS(7) WF(8)
5*

ENTER AZIMUTH BIAS IN DEGREES
5.328 *

ENTER ELEVATION BIAS IN DEGREES
3.8 *
⊙

SIGN OFF(1) MOD(2) NEXT RUN(3) PRINT(4)
1*

TITLE

```

Fig. 1. Example of on-line printout.

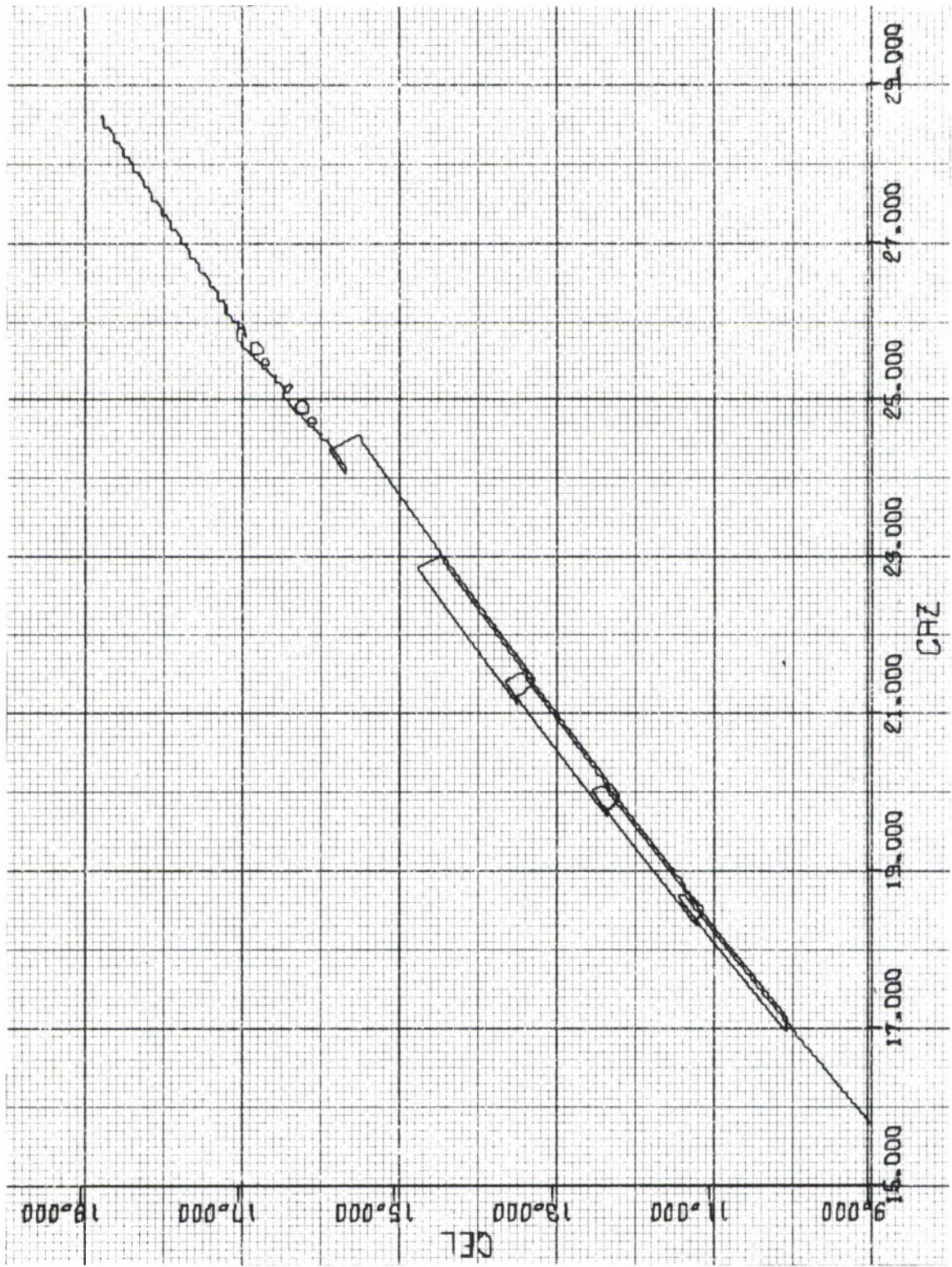


Fig. 2. Typical acquisition.

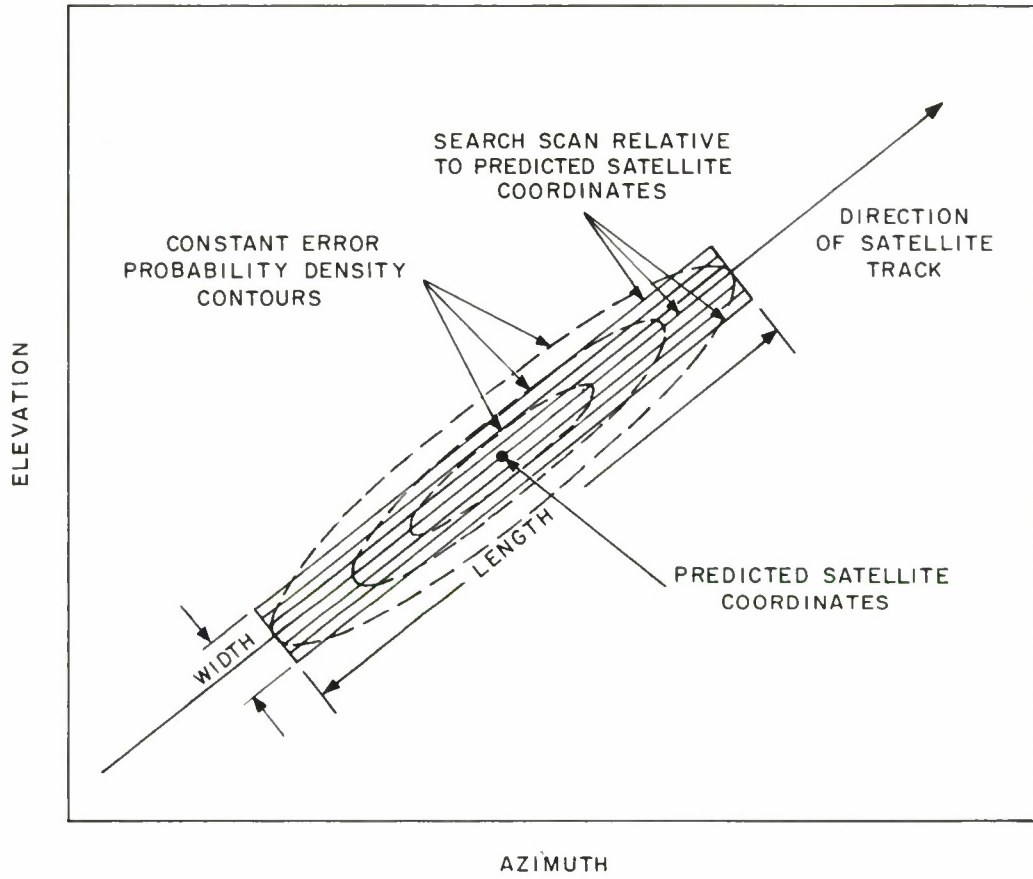


Fig. 3. Search scan.

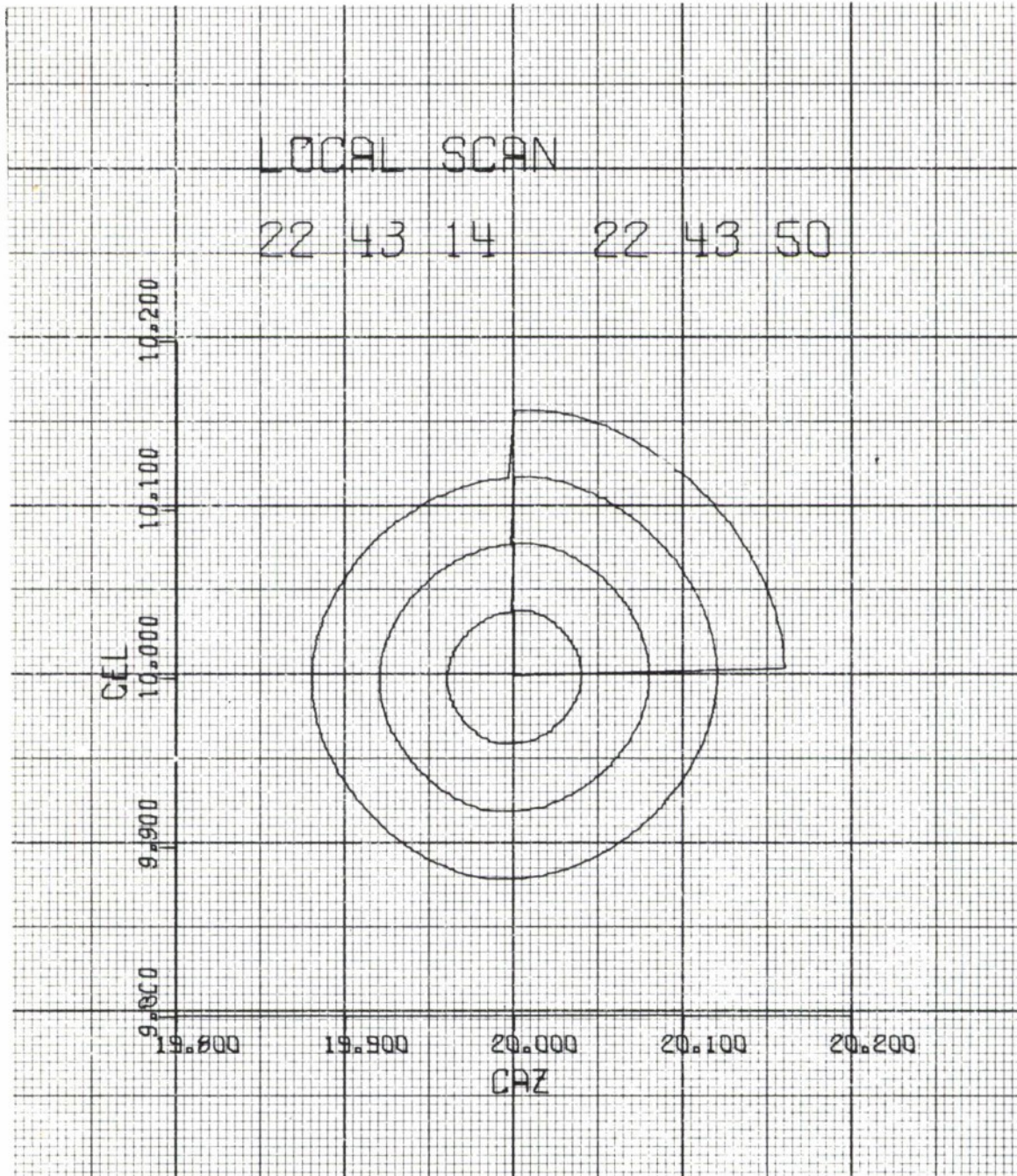


Fig. 4. Local scan.

4. Clear Biases

This choice clears the computed error biases in the local scan.

5. Set Biases

This choice sets the azimuth and elevation local scan biases to the keyboard entered values.

6. Time Correction

This choice causes a time correction to be made in the ephemeris computation, based on the errors in commands at that particular time.

7. Haystack Acquisition

This choice makes the program operate with Haystack RP2 pulses (channel 8 external interrupts). Search or local scan must be requested before the new site RP2 pulses will be used.

8. Westford Acquisition

This choice makes the program operate with Westford RP2 pulses (channel 12 external interrupts). Search or local scan must be requested before the new site RP2 pulses will be used.

## PROGRAM INPUTS AND OUTPUTS

Basically the acquisition program computes four values of azimuth and elevation using predicted pointing azimuth and elevation from common storage and puts the four resulting values into common storage. However, additional inputs and outputs are used.

### Core Storage Inputs

W(CAZIM):- Predicted satellite azimuth coordinate for  $T_0 + 4$  seconds in revolutions B27.  $T_0$ ,  $T_0 + 2$  is the two second time interval for which the next data is to be interpolated.

W(CELEV):- Predicted satellite elevation coordinate for  $T_0 + 4$  seconds in revolutions B27.

W(AZIMOVER):- A code to indicate where the first azimuth point is to be placed. When AZIMOVER is positive first azimuth will be placed in the main antenna zone. When AZIMOVER is negative first azimuth will be placed in the overlap zone.

W(TIMEMODE):- A code to indicate if system is running in real time. When TIMEMODE is positive, the system is running in real time. Negative TIMEMODE indicates simulated time.

W(INAZIMADD):- INAZIMADD gives the input azimuth buffer locations. Upper half gives the first word address of presently read into buffer. Lower half gives first word address of previously read in buffer.

W(113):- Azimuth in buffer control word.

#### Interrupt Inputs

The program uses external interrupts on channel 8 (range channel) for Haystack gear and channel 10 (intersite coupling channel) for Westford gear.

#### Keyboard Inputs

The program accepts search scan length and width in degrees whenever search scan is requested. It also accepts the local scan azimuth and elevation biases when operator requests that option. Keyboard entered parameters are in degrees.

#### Core Storage Outputs

W(ACQAZIM), + 1, + 2, + 3:- Four values of azimuth which have acquisition commands superimposed on predicted azimuth commands. Values are in revolutions B27.

W(ACQELEV), + 1, + 2, + 3:- Four values of elevation which have acquisition commands superimposed on predicted elevation commands. Values are in revolutions B27.

W(TIMECORR):- Time correction in days B28.

W(TRACKINDIC):- A code which is set to  $-0$  whenever RP2 pulses are observed and to  $+0$  when no RP2 pulses are observed.

### On-Line Printer Output

When a target has been acquired, a message "Target Acquired" is printed on the high-speed printer by means of the printer log program<sup>6</sup>.

### Keyboard Outputs

Miscellaneous typing out is performed by means of INTERCOM<sup>7</sup> as shown by Fig. 1.

### INTERNAL OPERATION OF PROGRAM

Initially, the program is made to scan either according to the search scan or the local scan. When the target is observed, the equipment external to the U-490 computer generates a RP2 pulse which appears at the computer as an external interrupt. The interrupt answering routine collects the interrupts in a table over the two second pointing system cycle. Every two seconds, the acquisition program is entered and all of the RP2 pulses are averaged to obtain an average target position. Then the predicted position is computed for that precise instant and an error is computed. This error is added to the future predicted commands and a local scan is initiated around these new coordinates. False alarms are allowed in the sense that if during the whole local scan no RP2 pulses are received, search will be continued by returning to the scan which was previously in operation. If RP2 pulses are observed during a local scan, a new local scan will be generated with the new errors as the new center point for the scan. Thus, once the target is observed, the program will track the target by continuously making one local scan after another. When three successful local scans have been made, a message is printed on the high-speed printer and only then a request for time correction will be honored.

### Search Scan

The selection of search scan has received considerable attention. Typical prediction errors show that the error along the satellite track is much greater than

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6. J. D. Drinan (editor), "Haystack Pointing System: Auxiliary Real-Time Programs," Lincoln Laboratory Technical Note 1966-6, (31 January 1966).
  7. A. A. Mathiasen and J. D. Drinan, editors, "Haystack Pointing System: INTERCOM," Lincoln Laboratory Technical Note 1965-39, (9 September 1965).

the deviation from the track. These errors specify a long narrow area of uncertainty with the highest probability of actual target location occurring in the center and along the satellite track. Obviously, one would like to scan the highest probability area first and then proceed to the lower probability areas. Typical constant error probability density contours are shown in Fig. 3.

The search scan also depends on the equipment limitations. The antenna control characteristics are such that large pointing errors occur when the antenna is asked to follow high rates. This suggests slow scans. Also the radar pulse repetition frequency determines minimum dwell time. One would like to have the target in the antenna beam long enough to get at least one and preferably several radar returns. These considerations dictate a quite slow search procedure. With a constant acceleration scan just slow enough for the antenna servo, an area of one degree by five degrees can be scanned in about eight minutes.

The values of  $L$  (the length along trajectory) and  $W$  (the width of scan) are given to the acquisition program via the keyboard routine. A scan is generated which goes along the trajectory  $L/2$  ahead of the predicted value and  $L/2$  behind the predicted value, then moves almost one beamwidth ( $.04^\circ$ ) in cross-scan direction and repeats the scan along the trajectory, then moves almost one beamwidth to the other side of the trajectory and repeats again. The lateral distance from the trajectory is increased almost one beamwidth from one along the trajectory scan to the next, until a width of  $W/2$  is scanned on each side of the trajectory. If the target has not been found then, a new scan is initiated with parameters  $L$  and  $W$  increased by 50%.

It is expected that the satellite acquisition program will be used mainly on the horizon when the satellite first comes into view. The first scan simply waits on the horizon and adjusts the azimuth so that a satellite could be acquired if it is early or late in its orbit. After this first scan, the above described pattern is used.

The scan along the satellite orbit ( $S$ ) is computed by using a constant acceleration scan.

$$S = 2aI[2N - |I|] \quad , \quad (1)$$

where  $a$  is the constant acceleration,  $I$  is an index which is increased or decreased every two seconds, and  $N$  is the number of two second intervals in the half scan, and is computed by first computing a time ( $T$ ).

$$T = \sqrt{\frac{L}{a_{\max}}} \quad , \quad (2)$$

where  $L$  is the scan length and  $a_{\max}$  is the maximum allowable acceleration of pointing commands.  $N$  is then computed such that

$$T \leq 2N - .5 \quad . \quad (3)$$

The value of the constant scan acceleration,  $a$ , is computed by

$$a = \frac{L}{(2N)^2} \quad . \quad (4)$$

The value of  $a$  obtained by this procedure is approximately equal to  $a_{\max}$ .

From the azimuth and elevation differences performed on the previous values, the trackangle,  $\theta$ , is determined by

$$\theta = \tan^{-1} \left[ \frac{E_1 - E_{-1}}{A_1 - A_{-1}} \right] \quad , \quad (5)$$

where  $E_i$  are the elevation values and  $A_i$  azimuth values corresponding to time  $T_i$ , as shown in Fig. 5.  $T_0, T_0 + 2$  corresponds to the time period for which the commands are to be interpolated next.

The elevation command is then computed by adding the elevation component of the scan to the elevation predicted position.

$$E_2^* = E_2 + S \sin \theta \quad , \quad (6)$$

where  $E_2^*$  is the elevation coordinate of the command with the scan added. Now a azimuth value ( $A_2^*$ ) is computed so that the resulting point is constrained to fall on the satellite trajectory which is indicated on Fig. 5 as the point labeled  $X_2$ . This is accomplished by a second order fit and extrapolation

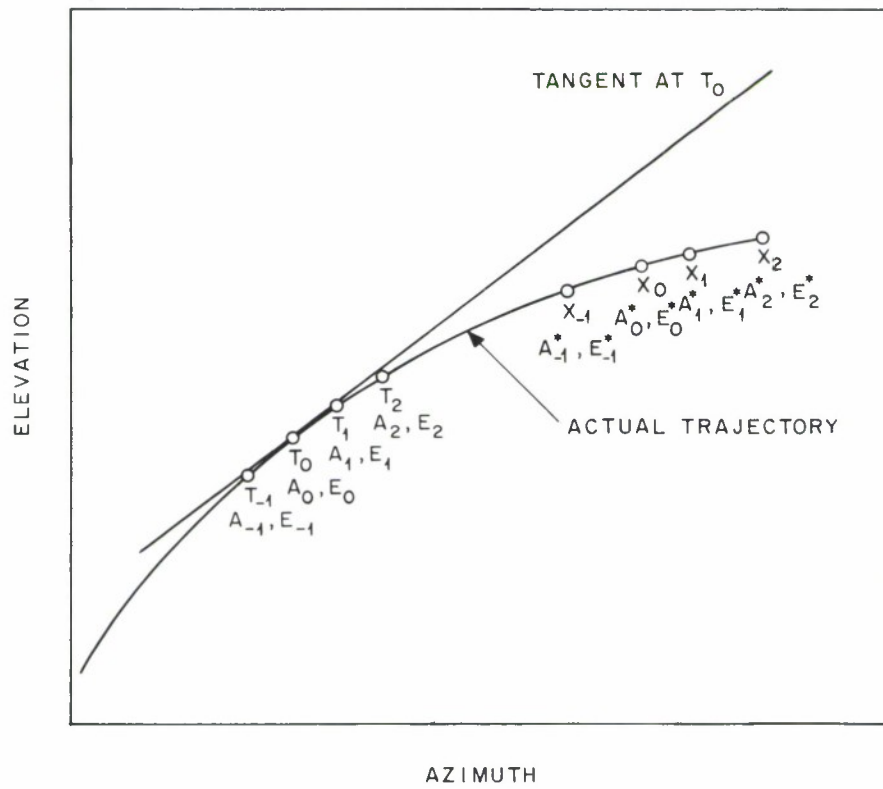


Fig. 5. Satellite trajectory.

$$\begin{aligned}
A_2^* &= A_2 + \frac{(A_{-1} - A_0)(E_2 - E_0)^2 - (A_2 - A_0)(E_{-1} - E_0)^2}{(E_{-1} - E_0)(E_2 - E_0)[(E_2 - E_0) - (E_{-1} - E_0)]} (E_2^* - E_0) \\
&+ \frac{(A_2 - A_0)(E_{-1} - E_0) - (A_{-1} - A_0)(E_2 - E_0)}{(E_{-1} - E_0)(E_2 - E_0)[(E_2 - E_0) - (E_{-1} - E_0)]} (E_2^* - E_0)^2 \quad . \quad (7)
\end{aligned}$$

In order to prevent singularities in the computations, when  $\theta < 45^\circ$ , the azimuth component of the scan is computed instead by

$$A_2^* = A_2 + S \cos \theta \quad (8)$$

and the elevation is computed to fall on the curve by

$$\begin{aligned}
E_2^* &= E_2 + \frac{(E_{-1} - E_0)(A_2 - A_0)^2 - (E_2 - E_0)(A_{-1} - A_0)^2}{(A_{-1} - A_0)(A_2 - A_0)[(A_2 - A_0) - (A_{-1} - A_0)]} (A_2^* - A_0) \\
&+ \frac{(E_2 - E_0)(A_{-1} - A_0) - (E_{-1} - E_0)(A_2 - A_0)}{(A_{-1} - A_0)(A_2 - A_0)[(A_2 - A_0) - (A_{-1} - A_0)]} (A_2^* - A_0)^2 \quad . \quad (9)
\end{aligned}$$

When the elevation is on the horizon, the minimum elevation is used as  $E_2^*$  and  $A_2^*$  is computed by Eq. (7).

The cross-scan is added to the commands by adding the components of the cross-scan to the azimuth and elevation commands.

$$\Delta C_A = \Delta C \sin \theta \quad , \quad (10)$$

and

$$\Delta C_E = \Delta C \cos \theta \quad , \quad (11)$$

where  $\Delta C$  is the incremental increase in cross-scan from one scan to the next and  $\Delta C_A$  and  $\Delta C_E$  are the two corresponding increments, in the azimuth and elevation directions respectively.

## Local Scan

The local scan configuration is not very critical and does not have to be computed very accurately, since the scan itself has very small dimensions. The local scan which was chosen first points at the center point of the scan for six seconds. Six seconds allows the antenna to move into the local scan region and allows all transients to be decreased to negligible values. Three circular scans are then performed around the center point. Each circle is made in eight seconds, and has a radius which increases almost one beamwidth ( $.04^\circ$ ) from one circle to the next. The velocity in the smallest circle is such that the target will be observed approximately 1.25 seconds, which allows 25 hits when the pulse rate is 20 a second. The second and third circles will allow 12 and 8 hits respectively. Since the scan is relative to the predicted target position and moves along in the expected trajectory, the errors should be so small that the larger circular scans are never used. This occurs because, whenever hits are received during a local scan, the local scan is restarted with the scan center at the coordinates where hits were received.

The circular scans are computed in a novel way. The antenna commands are interpolated from four values of azimuth and elevation by means of the interpolation program<sup>8</sup>. The four values given to the interpolation program are such that a smooth circle is interpolated between the points. The following values of azimuth and elevation are given at the time when new points are to be interpolated between  $T_0$  and  $T_0 + 2$ .

	$A_{-1}$	$E_{-1}$	$A_0$	$E_0$	$A_1$	$E_1$	$A_2$	$E_2$
1st quadrant	-R	-R	0	R	R	0	-R	-R
2nd quadrant	-R	R	R	0	0	-R	-R	R
3rd quadrant	R	R	0	-R	-R	0	R	R
4th quadrant	R	-R	-R	0	0	R	R	-R

The value of azimuth and elevation at  $T_0$  are  $A_0$  and  $E_0$  respectively, and R is the radius of the scan at the time of computation.

8. R. Teoste, "Haystack Pointing System: Interpolation," MIT Lincoln Laboratory Group Report 1964-57, (28 October 1964).

### Average Error Computation

When RP2 interrupts occur, an interrupt answering routine stores the pertinent information in a table, one interrupt at a time. During the two second cycle the acquisition program analyses the information in these tables. Each interrupt has four words of information as follows:

1. Azimuth input buffer control word
2. Range command
3. Doppler command
4. Azimuth input buffer control word

In addition, there is a table of weights which indicates the likelihood of the RP2 being a true target. Presently the table of weights consists of equal weights, because the hardware does not provide measured doppler and range information.

Every two seconds when the pointing system cycles through the acquisition program, the interrupt tables are examined and an average buffer control word  $(BCW)_{avg}$  is computed for the previous two second interval by

$$(BCW)_{avg} = \frac{1}{N} \sum_{i=1}^N W_i (BCW)_i \quad (12)$$

where  $N$  RP2 pulses had been observed and  $W_i$  and  $(BCW)_i$  were the weights and the buffer control words of the individual table entries. The average buffer control word is rounded to the nearest integer, and the antenna azimuth and elevation angles which correspond to this average buffer control word are read.

Predicted azimuth and elevation angles are also computed for that instant of time. Bessel's four point interpolation formula is used for this purpose which is similar to the one used in the interpolation program. The azimuth is given by

$$A(y) = \sum_{i=-1}^2 \sum_{j=0}^3 C_{ij} y^j A_i \quad (13)$$

and

$$E(y) = \sum_{i=-1}^2 \sum_{j=0}^3 C_{ij} y^j E_i \quad (14)$$

where  $A(y)$  is the value of azimuth interpolated for the time shift  $y$  (in fractions of 2 seconds) as indicated by the average buffer control word. The values of  $C_{ij}$  are a direct result of the Bessel interpolation coefficients<sup>9</sup>.  $A_i$  are the values of azimuth with  $A_0$  corresponding to the predicted command given at the beginning of the two second interval for which  $A(y)$  is to be interpolated.  $E(y)$  and  $E_i$  have the same meanings for the elevation commands.

Now the error can be computed which would have occurred, had the predicted commands been given. This is simply obtained by subtracting the interpolated predicted commands  $A(y)$  and  $E(y)$  from the actual values of antenna azimuth and elevation as indicated by the average buffer control word and the input angles.

In the case of the search scan, this average error over two seconds is added to the predicted commands and a local scan is generated around these coordinates. However, when RP2 pulses are observed during a local scan, the program is allowed to finish the circle and then an average error is computed for the whole circular scan. This way the antenna corrections are made in the proper direction.

### Time Correction

If the operator decides that the desired target has been sighted, the program can be signaled to make a time correction in the orbit computations.

The time correction is made by computing two time increments,

$$\Delta t_1 = \frac{6}{E_2 - E_{-1}} [E_r - E_c] \quad \text{and} \quad (15)$$

$$\Delta t_2 = \frac{6}{A_2 - A_{-1}} [A_r - A_c] \quad , \quad (16)$$

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9. D. R. Hartree, "Numerical Analysis," Oxford University Press, London, 1955, p. 68.

where  $E_p$  and  $A_p$  are the antenna pointing angles at the time of time correction and  $E_c$  and  $A_c$  are the predicted target coordinates at the same time.  $A_p - A_c$  and  $E_p - E_c$  are actually the averaged pointing corrections computed previously for locating the local scan.

Weighting elevation time correction by  $\frac{E_2 - E_{-1}}{E_2 - E_{-1} + A_2 - A_{-1}}$  and azimuth time correction by  $\frac{A_2 - A_{-1}}{E_2 - E_{-1} + A_2 - A_{-1}}$ , we get

$$\Delta t = \frac{6(E_p - E_c + A_p - A_c)}{E_2 - E_{-1} + A_2 - A_{-1}}, \quad (17)$$

where  $\Delta t$  is the desired time correction. The azimuth and elevation biases that remain will be computed by

$$\Delta A = A_p - A_c - (A_2 - A_{-1}) \frac{\Delta t}{6} \quad (18)$$

and

$$\Delta E = E_p - E_c - (E_2 - E_{-1}) \frac{\Delta t}{6} \quad (19)$$

Since the new azimuth and elevation corrections  $\Delta A$  and  $\Delta E$  are approximate, it may take a local scan to again precisely point the antenna at the target.

#### PROGRAM DETAILS

The acquisition program has three entries: working entry, initialization entry and interrupt entry. The working section is entered every two seconds in the pointing system cycle, the initialization section is entered at the beginning of a run or when requested through the attention symbol, and the interrupt answering routine is entered whenever a RP2 interrupt occurs. Figures 6, 7, and 8 show the working, initialization, and interrupt section flow diagrams respectively. The flow diagrams, in conjunction with the program listing in the APPENDIX, are self explanatory.

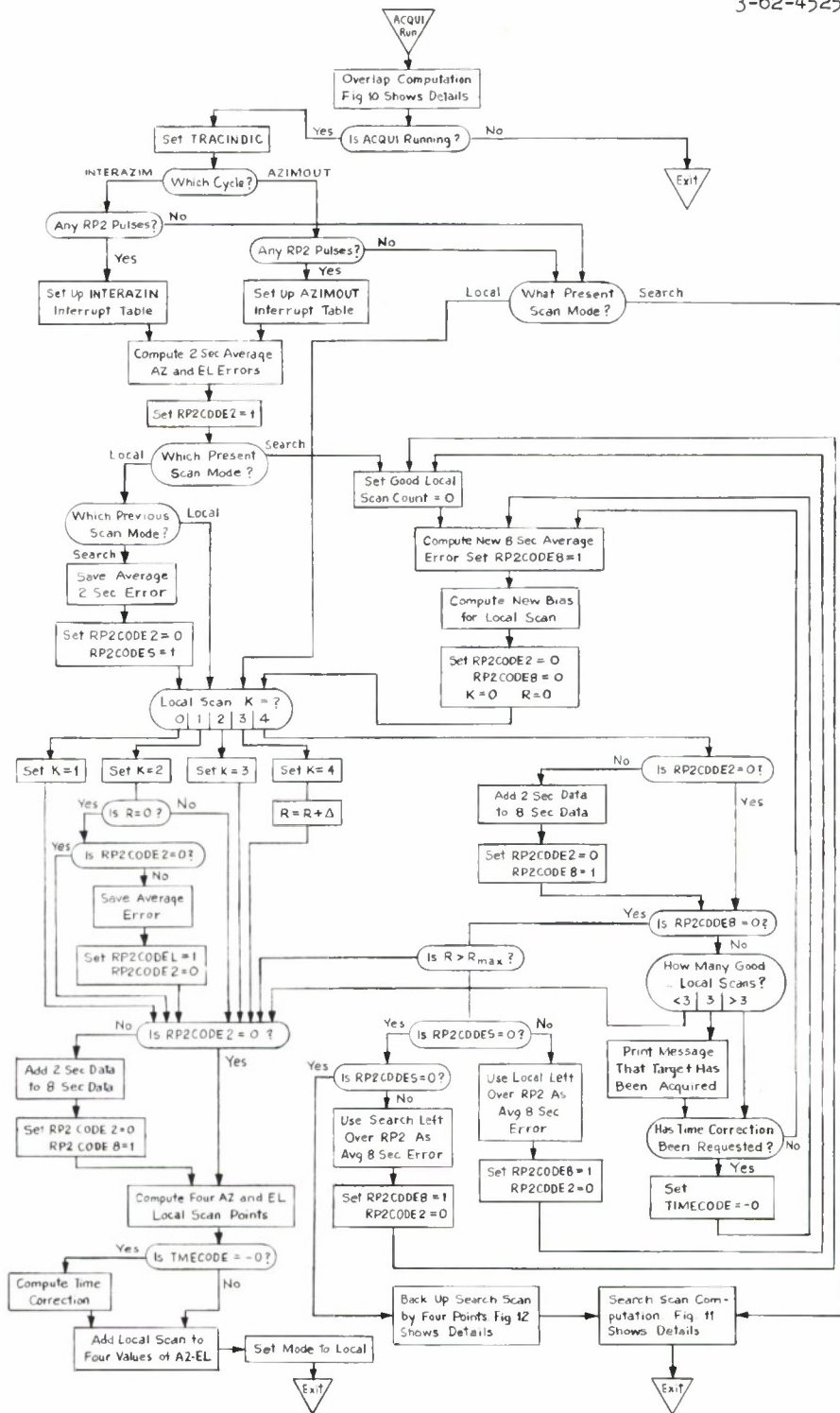


Fig. 6. Acquisition working section flow diagram.

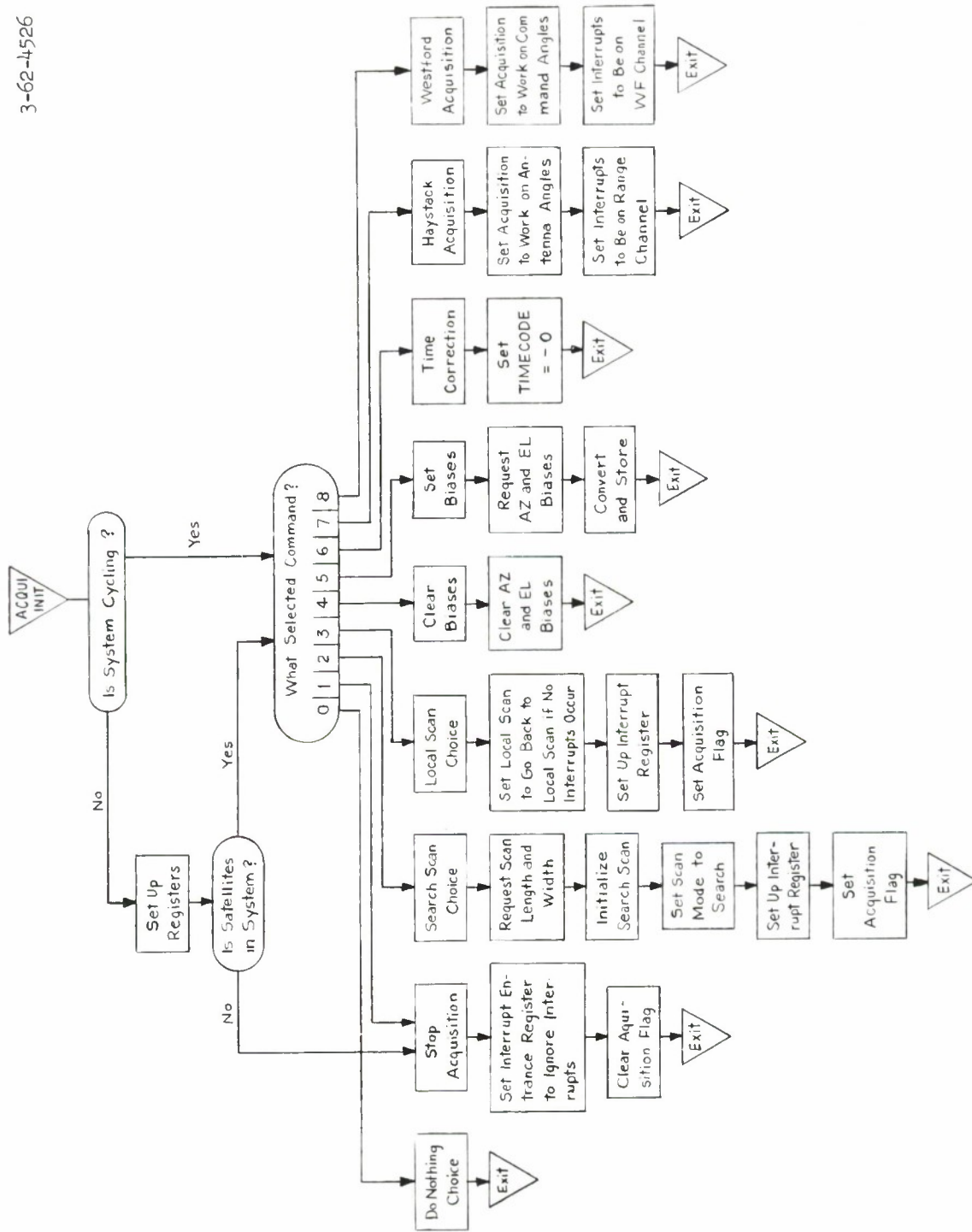


Fig. 7. Acquisition program initialization flow diagram.

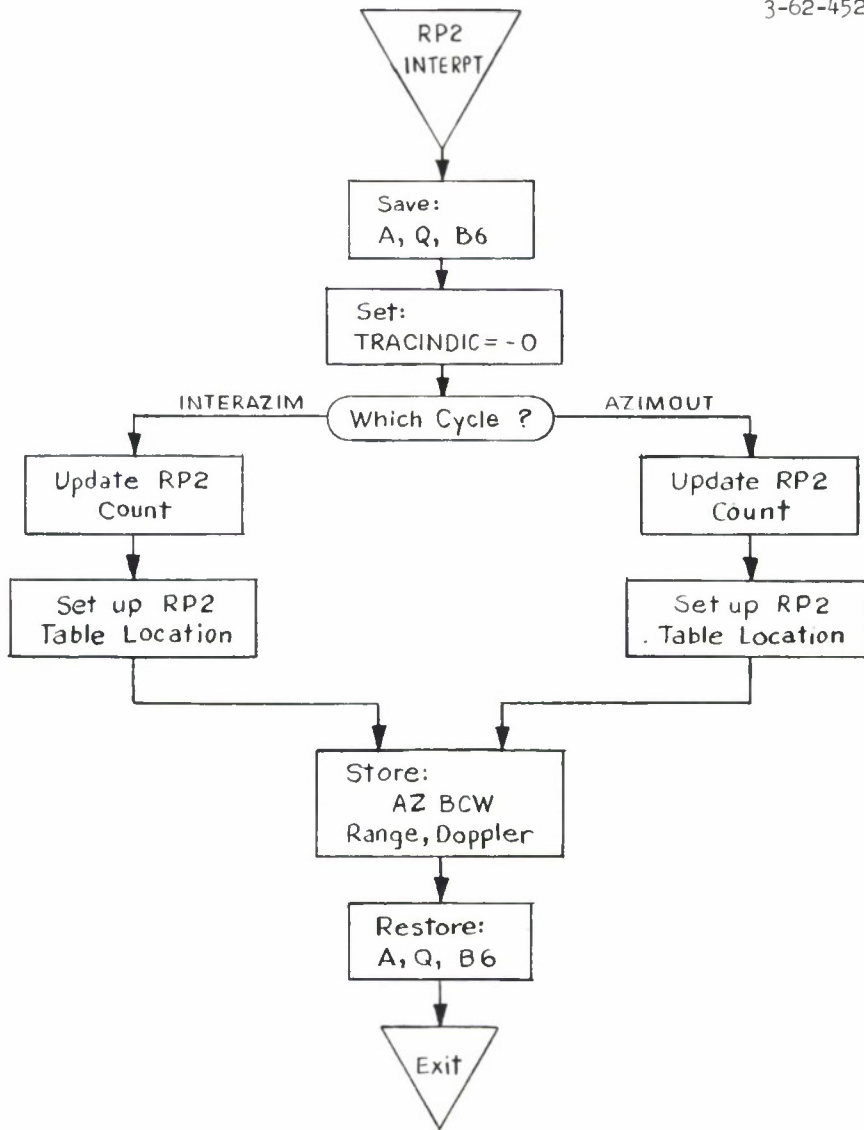


Fig. 8. Interrupt answering routine.

The initialization section performs a variety of functions. Each function is a direct result of the keyboard request, which are explained in the OPERATOR INTERVENTION section.

The interrupt answering routine serves the function of recording information when RP2 interrupts occur. This routine is entered either by the Westford RP2 interrupts or the Haystack RP2 interrupts as requested by the operator. The interrupt answering routine also sets the TRACKINDIC which is the location of a code to indicate that the target is within the antenna beam, and is used by the autotracking program.

The working section of the program contains most of acquisition program. When acquisition has not been requested, most of this program is bypassed. The values of azimuth and elevation are corrected for overlap purposes and are passed on to the interpolation program.

The Haystack antenna is capable of travelling 600 degrees in the azimuth plane. Figure 9 shows the azimuth travel limits and labels the overlap zones. The azimuth angles given the acquisition program are always between 0 and 360 degrees. The acquisition program computes the overlap information so that the antenna goes smoothly through north. The detailed computations are outlined by Fig. 10.

When the acquisition program has been asked to function, after several tests, the program computes either a local scan or a search scan. The local scan computation is broken into five alternative computations (five values of  $k$ ), one for each of the four quadrants plus an additional one that is used when the local scan is reinitiated ( $k = 0$  case).  $k = 4$  is the first quadrant computation; during this time the previous circle is examined for RP2 pulses and appropriate computations are made when some RP2 pulses have occurred.

Figure 11 shows the search scan computations logic, while Fig. 12 shows the logic when the search scan has to be backed up four points so that continuity is preserved when after a false target the search scan is continued.

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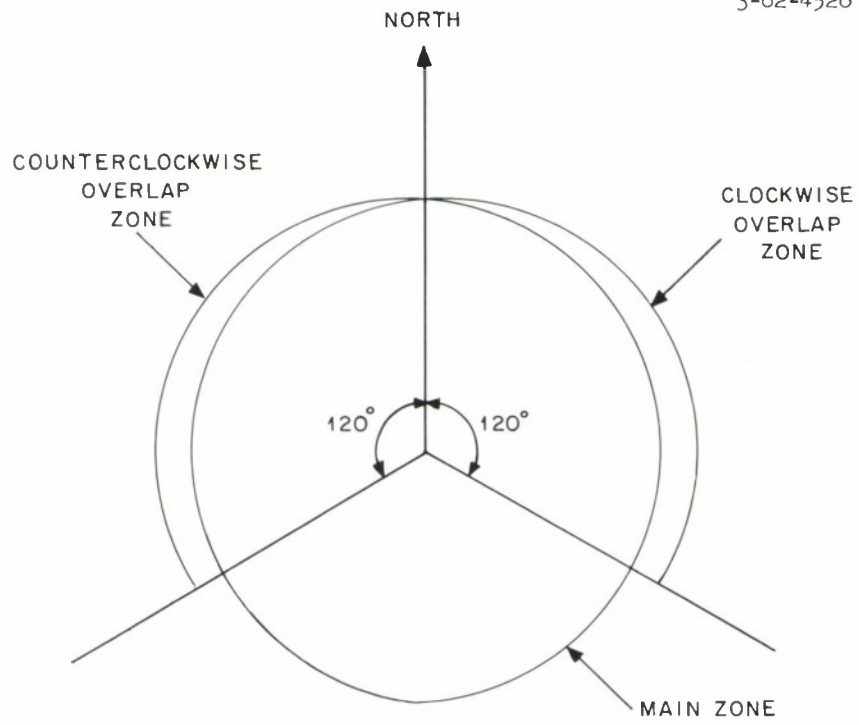


Fig. 9. Overlap zones.

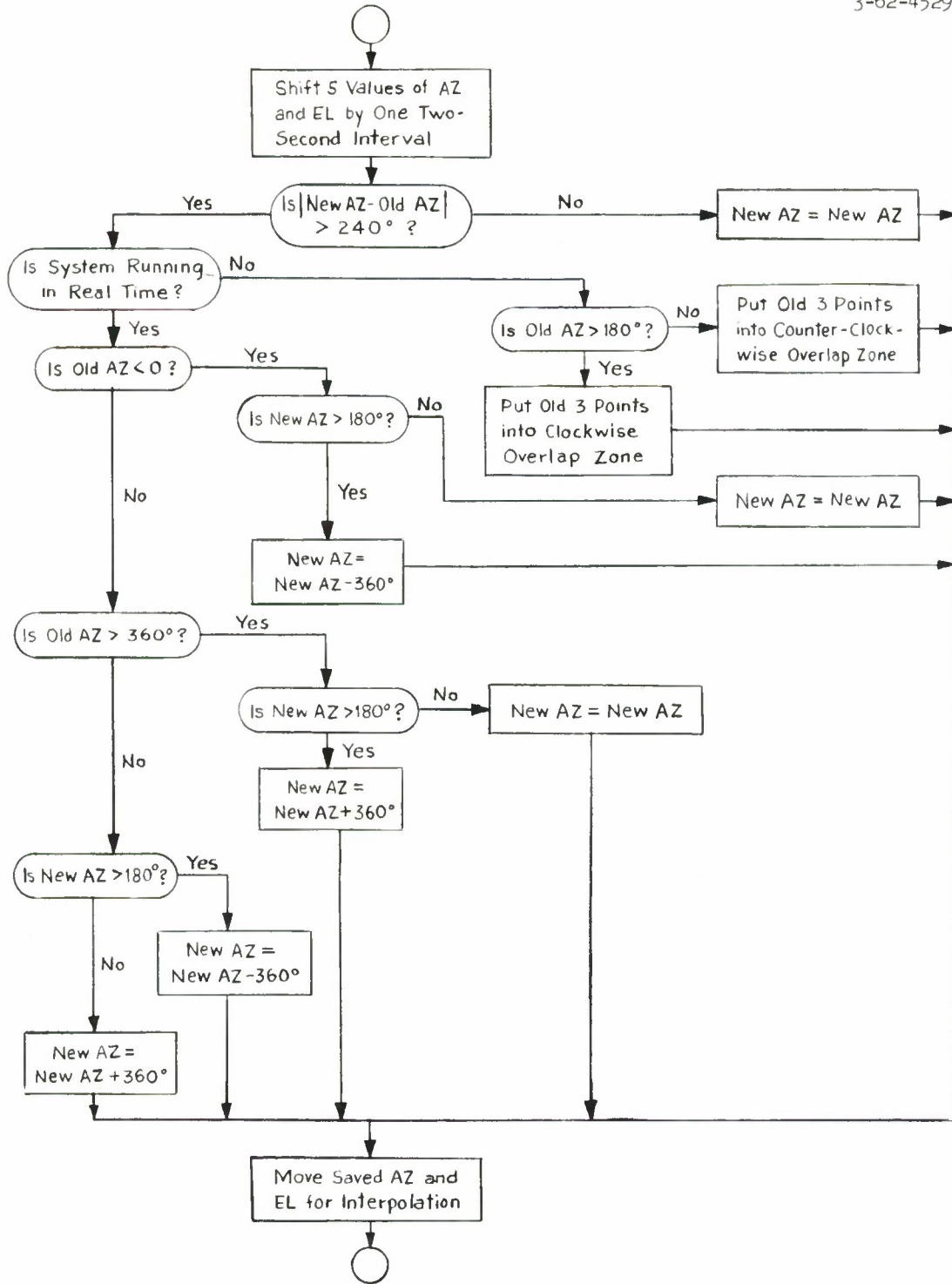


Fig. 10. Overlap computation.

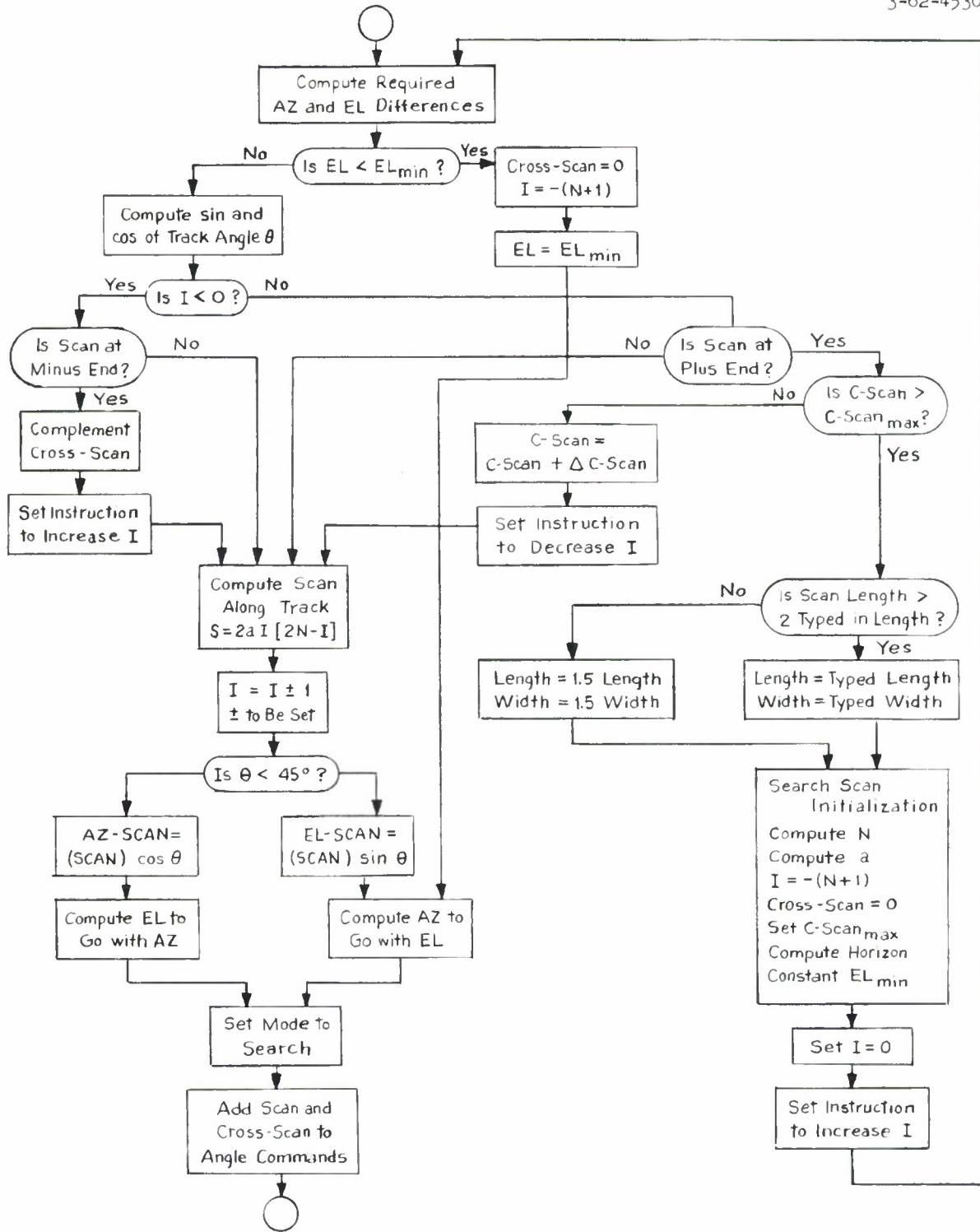


Fig. 11. Search scan computation.

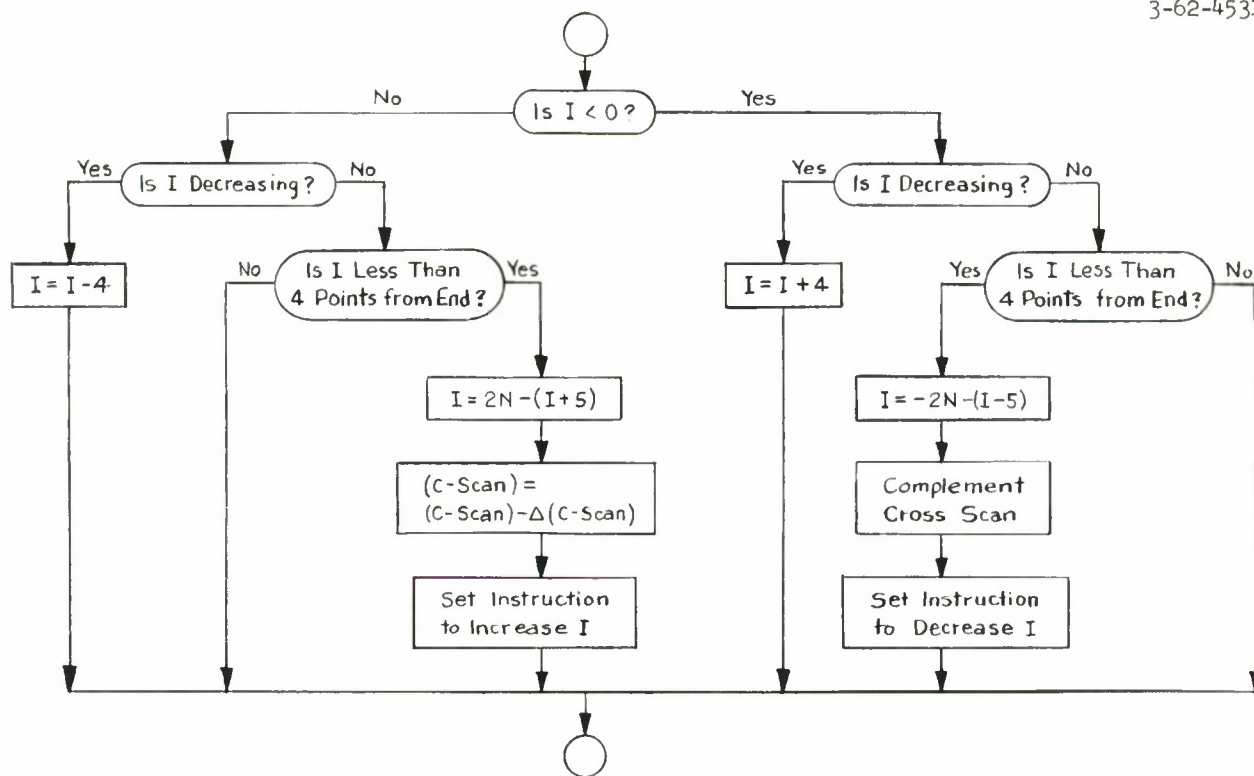


Fig. 12. Back up search scan.

APPENDIX: PROGRAM LISTING

SPURT OUTPUT NO. 110

TEOSTE\*10FEB66

CARDS	L1 ID LABEL	TA STATEMENT	LOC	F	JKB	Y	NOTES
.	0000 ACQUI	PROGRAM TEOSTE*10FEB66	0000	00360	00002		
.	00001 ACQUIRE	U-TAG ACQUIRUN*ACQUIINIT	0001	06102	63216		
.	00002	FD 1*ACQUI	0002	61000	00000		
.	00003 ACQUIINIT	ENTRY	0003	11750	63313		IS SYSTEM CYCLING
.	00004	ENT A*LX(SYSTAT1)*ANEG	0004	61000	00034		
.	00005	JP ATTENTINIT	0005	16030	00272		
.	00006	CL W(AZENTBIAS)	0006	16030	00273		
.	00007	CL W(ELENTBIAS)	0007	16030	00217		
.	00010	CL W(TIMECODE)	0010	10000	00001		
.	00011	PUT 1*L(CHOICE)	0011	14010	00040		
.	00012	ENT A*(TEST3)	0012	11030	00344		
.	00013	STR A*(STARTAZ)	0013	15030	00370		
.	00014	CL W(RP2CODE2)	0014	16030	01215		U(LOCAL SCAN K) L(RP2CODE2)
.	00015	CL W(RP2CODE8)	0015	16030	01216		U(END LOC SCAN) L(RP2CODE8)
.	00016	CL W(RP2CODES)	0016	16030	01217		L(RP2CODES) U(N0 OF GOOD LOCAL SCANS)
.	00017	CL W(RP2COUNT)	0017	16030	02573		
.	00020	CL L(RP2CODEL)	0020	16010	01220		L(RP2CODEL)
.	00021	CL W(RP2AVG8E)	0021	16030	01231		
.	00022	CL W(RP2AVG8A)	0022	16030	01212		
.	00023	ENT A*L(SYSTAT2)	0023	11010	63314		
.	00024	SUB A*2*AZERO	0024	21400	00002		IS SATELLITES IN SYSTEM
.	00025	JP STOPACQUI	0025	61000	00042		NO
.	00026	RJP U(INTERCOM)	0026	65020	63426		YES
.	00027	U-TAG QUEST1*0	0027	00060	00000		DO YOU WANT ACQUISITION
.	00030	RJP U(INTERCOM)	0030	65020	63426		
.	00031	U-TAG QUEST3*ANSWER1	0031	00105	00070		N0(1) SEARCH SCAN(2) LOCAL S CAN(3)
.	00032	ENT B7*L(CHOICE)	0032	12710	00040		
.	00033	JP L(PROGTABLE+B7)	0033	61017	00074		JUMP TO THE REQUESTED PROGRAM
.	00034 ATTENTINIT	RJP U(INTERCOM)	0034	65020	63426		ATTENTION INITIALIZATION
.	00035	U-TAG QUEST2*ANSWER2	0035	00120	00142		
.	00036	ENT B7*L(CHOICE)	0036	12710	00040		
.	00037	JP L(PROGTABLE+B7)	0037	61017	00074		JUMP TO THE REQUESTED PROGRAM
.	00040 CHOICE	1	0040	00000	00001		
.	00041 DONOTHING	JP L(ACQUIINIT)	0041	61010	00002		
.	00042 STOPACQUI	RJP A*(S+1)*SKIP	0042	11130	00043		SKIP ALL OF ACQUI
.	00043	RJP NOINTERR	0043	65000	00052		
.	00044	STR A*(30)	0044	15030	00030		
.	00045	STR A*(34)	0045	15030	00034		
.	00046	CL W(ACQUIONOFF)	0046	16030	00057		
.	00047	PUT -0*(TRACKINDIC)	0047	10040	77777		
.	00050	JP L(ACQUIINIT)	0050	14030	63026		
.	00051 NOINTERR	ENTRY	0051	61010	00002		
.	00052	PUT -0*(TRACKINDIC)	0052	61000	00000		SET TRACK INDIC. WHEN NOT ACQU IRING
.	00053	STR C14*(RP2CHANNEL)	0053	10040	77777		
.	00054		0054	14030	63026		
.	00055		0055	17630	02575		







00244	LOCCHOICE	ENT	A*(LOCSONLY)	00330	11030	00342	PREVENT SCAN FROM GOING TO SFA RCH
00245		CL	W(RP2COUNT)	00331	16030	02573	
00246		SIL	A*(BACKUPSCAN)	00332	64000	00000	
00247		STR	-0*(ACQUISITIONOFF)	00333	15030	01633	
00250		PUT	W(RP2INTRJP)*W(30)	00334	10040	77777	
00251	WFHSACQUI5	PUT	W(SCANMODE) L(ACQUINIT)	00335	14030	00057	SET MODE TO LOCAL
00252		CL	INITLOCSC	00336	10030	00343	
00253		JP	RP2INTERP	00337	14030	00030	
00254	LOCSONLY	RJP	S+1	00340	16030	00576	
00255	RP2INTRJP	JP	ENT A*(TEST4)	00341	60110	00002	
00256	TEST3	STR	ENT A*(STARTAZ)	00342	61000	01563	
00257		ENT	ENT A*(AZIMOVER)*ANEG	00343	65000	02577	
00260		ENT	ENDAZ-1	00344	61000	00345	FIRST TIME THROUGH FIX OVERLAP
00261		JP	ENT G*(CAZIM)	00345	11030	00357	
00262	TEST5	LSH	AG*3	00346	15030	00370	
00263		ENT	ENT A*(CAZIM)*GPOS	00347	11730	63325	
00265		ENT	SUB A*(REV)*SKIP	00350	61000	00402	PUT POINT IN OVERLAP REGION
00266		ADD	JP ENDAZ	00351	10030	63060	
00267		JP	127000000	00352	07000	00003	
00270	TEST4	ENTRY	ENT A*(ELEVSH+1+B7)	00353	11230	63060	
00271		CL	STR A*(ELEVSH+B7)	00354	21130	00466	
00272	ACQUIRUN	BK	JP B7*4	00355	20030	00466	
00273		JP	ENT A*(CELEV)	00356	61000	00403	
00274		ENT	STR A*(ELEVSH+5)	00357	01270	00000	
00275		CL	CL B7	00360	61000	00000	
00276		STR	ENT A*(AZIMSH+1+B7)	00361	12700	00000	
00277		BK	STR A*(AZIMSH+B7)	00362	11037	00477	
00300		JP	JP S-3	00363	15037	00476	
00301	STARTAZ	ENT	ENT A*(AZIMSH+4)	00364	71700	00004	NEW ELEVATION
00302		CL	STR A*(CAZIM)*APOS	00365	61000	00362	
00303		STR	STR A*(MARGIN)*ANEG	00366	11030	63061	
00304		ENT	TEST1	00367	15030	00503	
00305		BK	ENT A*(CAZIM)	00370	12700	00000	
00306		JP	STR A*(AZIMSH+5)	00371	11037	00471	
00307		JP	ENT A*(AZIMSH+B7)	00372	15037	00470	
00310		ENT	BK B7*4	00373	71700	00004	
00311		STR	JP S-3	00374	61000	00371	NEW AZIMUTH OVERLAP DETERMINATION
00312		SUB	ENT A*(AZIMSH+4)	00375	11030	00474	
00313		STR	A*(CAZIM)*APOS	00376	21630	63060	
00314		SUB	STR A*(AZIMSH+5)	00377	15040	00000	
00315		SUB	SUB A*(MARGIN)*ANEG	0400	21730	00467	
00316		JP	TEST1	0401	61000	00444	
00317		ENT	ENT A*(CAZIM)	0402	11030	63060	POINT IN NONOVERLAP REGION
00320	ENDAZ	STR	STR A*(AZIMSH+5)	0403	15030	00475	
00321		ENT	ENT A*(ELEVSH+5)	0404	11030	00503	
00322		STR	STR A*(ACGELEV+3)	0405	15030	63100	
00323		ENT	ENT A*(AZIMSH+5)	0406	11030	00475	
00324		STR	STR A*(ACGAZIM+3)	0407	15030	63074	
00325		ENT	ENT A*(ACQUISITIONOFF)*ANOT	0410	11530	00057	
00326		JP	L(ACQUIRUN)	0411	61010	00360	
00327		ENT	ENT A*(RP2COUNT)*ANOT	0412	11530	02573	
00330		CL	W(TRACKINDIC)	0413	16030	63026	
00331		ENT	ENT A*(INAZIMADD)	0414	11020	63446	WHICH PREVIOUS CYCLE
00332		SUB	A*(AZIMIN*AZERO)	0415	21400	75000	
00333		JP	INTERAZCY	0416	61000	01277	
00331		ENT	A*(RP2COUNT)*AZERO	0417	11420	02573	AZIMUTH OVERLAP DETERMINATION

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00332 NORP2PULSE JP AVGAZOCY 10000 01273
00333 NORP2PULSE ENT A*(SCANMODE)*AZERO 00420
00334 SEARCHSCAN+1 JP LOCALSCAN 11420 00576
00335 SIMULATION JP LOCALSCAN 61000 00762
00336 SIMULATION ENT A*(AZIMSH+4) 00423
00337 SUB A*04000000000*AP0S 00424
00340 JP PUTINCW 21630 02773
00341 PUTINCW ENT B5*2 00426
00342 PUTINCW ENT A*(ACQAZIM+B5) 00427
00343 PUTINCW SUB A*(REV) 00430
00344 PUTINCW STR A*(ACQAZIM+B5) 00431
00345 PUTINCW+1 BJP B5*PUTINCW+1 15035 63071
00346 PUTINCW JP ENDAZ-1 72500 00430
00347 PUTINCW ENT B5*2 61000 00402
00350 PUTINCW ENT A*(ACQAZIM+B5) 00435
00351 PUTINCW ADD A*(REV) 00436
00352 PUTINCW STR A*(ACQAZIM+B5) 00437
00353 PUTINCW+1 BJP B5*PUTINCW+1 15035 63071
00354 PUTINCW JP ENDAZ-1 72500 00436
00355 PUTINCW ENT A*(AZIMSH+4)*ANEG 00442
00356 TEST1 ENT A*(TIMEMODE)*AP0S 11730 00474
00357 TEST1 JP SIMULATION 00443
00360 TEST1 ENT A*(AZIMSH+4)*ANEG 11630 63103
00361 TEST1 JP TEST2 00446
00362 TEST1 ENT G*(CAZIM) 61000 00474
00363 TEST1 LSH A*3*QNEG 00447
00364 TEST1 JP ENDAZ-1 61000 00456
00365 TEST1 ENT A*(CAZIM) 00450
00366 TEST1 SUB A*(REV) 10030 63060
00367 TEST1 JP ENDAZ 00451
00370 TEST1 SUB A*(REV)*AP0S 00452
00371 TEST1 JP TESTS 11030 63060
00372 TEST1 ENT G*(CAZIM) 00453
00373 TEST1 LSH A*3*QPOS 00455
00374 TEST1 JP ENDAZ-1 61000 00403
00375 TEST1 LSH A*270 00456
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00377 TEST1 JP ENDAZ 00457
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00753 AZIMSH 0002523114 00815
00754 REV 100000000 00816
00755 MARGIN 0527024365 00817
00756 AZIMSH 0002523114 00818
00757 REV 100000000 00819
00758 MARGIN 0527024365 00820
00759 AZIMSH 0002523114 00821
00760 REV 100000000 00822
00761 MARGIN 0527024365 00823
00762 AZIMSH 0002523114 00824
00763 REV 100000000 00825
00764 MARGIN 0527024365 00826
00765 AZIMSH 0002523114 00827
00766 REV 100000000 00828
00767 MARGIN 0527024365 00829
00768 AZIMSH 0002523114 00830
00769 REV 100000000 00831
00770 MARGIN 0527024365 00832
00771 AZIMSH 0002523114 00833
00772 REV 100000000 00834
00773 MARGIN 0527024365 00835
00774 AZIMSH 0002523114 00836
00775 REV 100000000 00837
00776 MARGIN 0527024365 00838
00777 AZIMSH 0002523114 00839
00778 REV 100000000 00840
00779 MARGIN 0527024365 00841
00780 AZIMSH 0002523114 00842
00781 REV 100000000 00843
00782 MARGIN 0527024365 00844
00783 AZIMSH 0002523114 00845
00784 REV 100000000 00846
00785 MARGIN 0527024365 00847
00786 AZIMSH 0002523114 00848
00787 REV 100000000 00849
00788 MARGIN 0527024365 00850
00789 AZIMSH 0002523114 00851
00790 REV 100000000 00852
00791 MARGIN 0527024365 00853
00792 AZIMSH 0002523114 00854
00793 REV 100000000 00855
00794 MARGIN 0527024365 00856
00795 AZIMSH 0002523114 00857
00796 REV 100000000 00858
00797 MARGIN 0527024365 00859
00798 AZIMSH 0002523114 00860
00799 REV 100000000 00861
00800 MARGIN 0527024365 00862
00801 AZIMSH 0002523114 00863
00802 REV 100000000 00864
00803 MARGIN 0527024365 00865
00804 AZIMSH 0002523114 00866
00805 REV 100000000 00867
00806 MARGIN 0527024365 00868
00807 AZIMSH 0002523114 00869
00808 REV 100000000 00870
00809 MARGIN 0527024365 00871
00810 AZIMSH 0002523114 00872
00811 REV 100000000 00873
00812 MARGIN 0527024365 00874
00813 AZIMSH 0002523114 00875
00814 REV 100000000 00876
00815 MARGIN 0527024365 00877
00816 AZIMSH 0002523114 00878
00817 REV 100000000 00879
00818 MARGIN 0527024365 00880
00819 AZIMSH 0002523114 00881
00820 REV 100000000 00882
00821 MARGIN 0527024365 00883
00822 AZIMSH 0002523114 00884
00823 REV 100000000 00885
00824 MARGIN 0527024365 00886
00825 AZIMSH 0002523114 00887
00826 REV 100000000 00888
00827 MARGIN 0527024365 00889
00828 AZIMSH 0002523114 00890
00829 REV 100000000 00891
00830 MARGIN 0527024365 00892
00831 AZIMSH 0002523114 00893
00832 REV 100000000 00894
00833 MARGIN 0527024365 00895
00834 AZIMSH 0002523114 00896
00835 REV 100000000 00897
00836 MARGIN 0527024365 00898
00837 AZIMSH 0002523114 00899
00838 REV 100000000 00900
00839 MARGIN 0527024365 00901
00840 AZIMSH 0002523114 00902
00841 REV 100000000 00903
00842 MARGIN 0527024365 00904
00843 AZIMSH 0002523114 00905
00844 REV 100000000 00906
00845 MARGIN 0527024365 00907
00846 AZIMSH 0002523114 00908
00847 REV 100000000 00909
00848 MARGIN 0527024365 00910
00849 AZIMSH 0002523114 00911
00850 REV 100000000 00912
00851 MARGIN 0527024365 00913
00852 AZIMSH 0002523114 00914
00853 REV 100000000 00915
00854 MARGIN 0527024365 00916
00855 AZIMSH 0002523114 00917
00856 REV 100000000 00918
00857 MARGIN 0527024365 00919
00858 AZIMSH 0002523114 00920
00859 REV 100000000 00921
00860 MARGIN 0527024365 00922
00861 AZIMSH 0002523114 00923
00862 REV 100000000 00924
00863 MARGIN 05
```



00507	AZPOINT	0		00575	00000	00000	00000	N
00510	SCANMODE	-1	RESERVE 3	00576	77777	77776		B27 AZIMUTH COMPONENT OF SCAN
00511	JUNK	0		00577	00000	00000		
00512	FITDENOM	0		00602	00000	00000		B36 DEN OF FIT EXPRESSION
00513	FITQUAD	0		00603	00000	00000		B24 QUADRATIC COEFFICIENT
00514	FITLIN	0		00604	00000	00000		B21 LINEAR COEFFICIENT
00515	SC5	ENT	G*(SCANPOINT)	00605	10030	00563		
00516		MUL	W(SCC05)	00606	22030	00557		
00517		LSH	AG*2	00607	07000	00002		
00520		STR	A*(AZPOINT)	00610	15030	00575		B27 AZIMUTH SCAN
00521		ENT	G*(AZDIF20)	00611	10030	00566		
00522		SUB	G*(AZDIFM10)	00612	27030	00565		
00523		MUL	W(AZDIF20)	00613	22030	00566		
00524		RSH	AG*180	00614	03000	00022		
00525		MUL	W(AZDIFM10)	00615	22030	00565		
00526		LSH	AG*120*ANOT	00616	07500	00014		
00527		JP	ENDFIT+1	00617	61000	01117		
00530		STR	A*(FITDENOM)	00620	15030	00602		B45 DEN OF QUADRATIC EXPR.
00531		ENT	G*(ELDIFM10)	00621	10030	00567		
00532		MUL	W(AZDIF20)	00622	22030	00566		
00533		LSH	AG*120	00623	07000	00014		
00534		STR	A*(JUNK)	00624	15030	00577		B36
00535		ENT	G*(ELDIF20)	00625	10030	00570		
00536		MUL	W(AZDIFM10)	00626	22030	00565		
00537		LSH	AG*120	00627	07000	00014		
00540		STR	A*(JUNK+1)	00630	15030	00600		B36
00541		SUB	A*(JUNK)	00631	21030	00577		
00542		RSH	AG*3	00632	03000	00003		
00543		DIV	W(FITDENOM)	00633	23030	00602		
00544		STR	G*(FITQUAD)	00634	14030	00603		B18 QUADRATIC COEFFICIENT
00545		ENT	G*(JUNK+1)	00635	10030	00600		
00546		MUL	W(AZDIFM10)	00636	22030	00565		
00547		LSH	AG*120	00637	07000	00014		
00550		STR	A*(JUNK+1)	00640	15030	00600		B45
00551		ENT	G*(JUNK)	00641	10030	00577		
00552		MUL	W(AZDIF20)	00642	22030	00566		
00553		LSH	AG*120	00643	07000	00014		
00554		SUB	A*(JUNK+1)	00644	21030	00600		B45
00555		RSH	AG*150	00645	03000	00017		
00556		DIV	W(FITDENOM)	00646	23030	00602		
00557		STR	G*(FITLIN)	00647	14030	00604		B15 LINEAR COEFFICIENT
00560		ENT	G*(FITQUAD)	00650	10030	00603		
00561		MUL	W(AZPOINT)	00651	22030	00575		B15
00562		ADD	A*(FITLIN)	00652	20030	00604		
00563		ENT	G*A	00653	10070	00000		B12
00564		MUL	W(AZPOINT)	00654	22030	00575		
00565		LSH	AG*150	00655	07000	00017		ELEVATION TO GO WITH AZIMUTH B
00566		STR	A*(ELPOINT)	00656	15030	00574		27
00567		JP	ENDFIT+1	00657	61000	01117		
00570	SC3	ENT	A*(ECROSSCAN)	00660	11030	00553		CHANGE POLARITY OF CROSSCAN
00571		STR	A*A	00661	15040	00000		
00572		STR	A*(ECROSSCAN)	00662	15030	00553		
00573		ENT	A*(ACROSSCAN)	00663	11030	00554		
00574		STR	A*A	00664	15040	00000		
00575		STR	A*(ACROSSCAN)	00665	15030	00554		

```

00576      ENT A*36030
00577      STR A*(SC10)
00600      RPL Y+1*(W(I))
00601      JP SC1
00602      SC4
00603      SUB A*(N)*AP05
00604      ENT A*(CROSSCAN)
00605      SUB A*(CRSCW)*ANEG
00606      JP ENDSSC
00607      ENT G*(CROSSCAN)
00610      ADD G*(DELCRSC)
00611      STR G*(CROSSCAN)
00612      MUL W*(SCSIN)
00613      LSH AG*2
00614      STR A*A
00615      STR A*(ACROSSCAN)
00616      ENT G*(CROSSCAN)
00617      MUL W*(SCC05)
00620      LSH AG*2
00621      STR A*(ECROSSCAN)
00622      ENT A*37030
00623      STR A*(SC10)
00624      RPL Y-1*(W(I))
00625      JP SC1
00626      ENT A*(LENGTH)
ENDSSC

00627      RSH AG*2
00630      SUB A*(LENGTH)*AP05
00631      JP ENDSSC1
00632      PUT W*(LENGTH)*W*(LENGTH)

00633      PUT W*(WIDTH)*W*(WIDTH)

00634      SEARCH101
00635      RJP SSCANINIT
00636      CL W(I)
00637      ENT B7*37030
00640      STR B7*(SC10)
00641      JP SEARCHSCAN+1
00642      ENT A*(LENGTH)
00643      RSH A*1
00644      ADD A*(LENGTH)
00645      STR A*(LENGTH)
00646      ENT A*(WIDTH)
00647      RSH A*1
00650      ADD A*(WIDTH)
00651      STR A*(WIDTH)
00652      JP SEARCH101
00653      WIDITH 000314631
00654      LENGTH 004000000
00655      CL SC1
00656      W(CROSSCAN)
00657      CL W(CROSSCAN)
00660      ENT A*-1
00661      SUB A*(N)
00662      STR A*(I)
00663      ENT G*(SCMINEL)
00664      SUB G*(ELEVSH*3)
00665      STR G*(ELPOINT)

CHANGE DIRECTION OF I
11000 36030
15020 01036
36030 00561
61000 01027
21630 00562
61000 01027
11030 00552
21730 00560
61000 00716
10030 00552
26030 00555
14030 00552
22030 00556
07000 00002
15040 00000
15030 00554
10030 00552
22030 00557
07100 00002
15030 00553
11000 37030
15020 01036
37030 00561
61000 01027
11030 01204

AZIMUTH COMPONENT
15030 00554
10030 00552
22030 00557
07100 00002
15030 00553
11000 37030
15020 01036
37030 00561
61000 01027
11030 01204

ELEVATION COMPONENT
CHANGE DIRECTION OF I
15030 00554
10030 00552
22030 00557
07100 00002
15030 00553
11000 37030
15020 01036
37030 00561
61000 01027
11030 01204

IS L FOUR TIMES THE ORIGINAL L
03000 00002
21630 00745
61000 00733
10030 00745
14030 01204
10030 00744
14030 01205
65000 01134
16030 00561
12700 37030
16720 01036
61000 00762
11030 01204
20030 00001
15030 01204
11030 01205
02000 00001
20030 01205
15030 01205
61000 00726
00003 14631
00040 00000
61000 01027
16030 00552
16030 00554
16030 00553
11040 77776
I = -N-1

.4818 KEYBOARD ENTERED WIDTH
.4818 KEYBOARD ENTERED LENGTH
SET CROSSCAN TO ZERO

EL = MINIMUM SCAN ELEVATION
14030 00574

```

00666	SEARCHSCAN	JP AZT0G0MEL	00760	61000	01051
00667		N0-0P	00761	12000	00000
00670		ENT G*(ELEVSH+5)	00762	10030	00503
00671		SUB G*(ELEVSH+3)	00763	27030	00501
00672		STR G*(ELDIF20)	00764	14030	00570
00673		MUL W(ELDIF20)	00765	22030	00570
00674		LSH AG*6	00766	07000	00006
00675		STR A*(ELDIF20SQ)	00767	15030	00571
00676		ENT G*(ELEVSH+2)	00770	10030	00500
00677		SUB G*(ELEVSH+3)	00771	27030	00501
00700		STR G*(ELDIFM10)	00772	14030	00567
00701		ENT G*(AZIMSH+2)	00773	10030	00472
00702		SUB G*(AZIMSH+3)	00774	27030	00473
00703		STR G*(AZDIFM10)	00775	14030	00565
00704		ENT G*(AZIMSH+5)	00776	10030	00475
00705		SUB G*(AZIMSH+3)	00777	27030	00473
00706		STR G*(AZDIF20)	01000	14030	00566
00707		MUL W(AZDIF20)	01001	22030	00566
00710		LSH AG*6	01002	07000	00006
00711		STR A*(AZDIF20SQ)	01003	15030	00572
00712		ENT A*(ELEVSH+5)	01004	11030	00503
00713		SUB A*(HORIZTEST)*AP05	01005	21630	00564
00714		JP BELOWHORIZ	01006	61000	00747
00715		ENT A*(AZDIF20SQ)	01007	11030	00572
00716		ADD A*(ELDIF20SQ)	01010	20030	00571
00717		RJP SQRT	01011	65000	00504
00720		JP ENDANGLE+1	01012	61000	01023
00721		STR A*(SQRTDEN)*AN0T	01013	15330	00573
00722		JP ENDANGLE+1	01014	61000	01023
00723		ENT A*(ELDIF20)	01015	11030	00570
00724		DIV W(SQRTDEN)	01016	23030	00573
00725		STR G*(SCSIN)	01017	14030	00556
00726		ENT A*(AZDIF20)	01020	11030	00566
00727		DIV W(SQRTDEN)	01021	23030	00573
00730	ENDANGLE	STR G*(SCCOS)	01022	14030	00557
00731		ENT A*(I)*ANEG	01023	11730	00561
00732		JP SC4	01024	61000	00672
00733		ADD A*(N)*AP05	01025	20630	00562
00734		JP SC3	01026	61000	00660
00735	SC1	ENT G*(I)*QP05	01027	10230	00561
00736		STR G*Q	01030	14000	00000
00737		SUB G*(SCANLIN)	01031	27030	00550
00740		MUL W(I)	01032	22030	00561
00741		MUL W(SCANACNEG)	01033	22030	00551
00742		RSH AG*2	01034	03000	00002
00743		STR G*(SCANP0INT)	01035	14030	00563
00744	SC10	RPL Y+1*(I)	01036	36030	00561
00745	SC2	ENT A*(AZDIF20)*AP05	01037	11630	00566
00746		STR A*A	01040	15040	00000
00747		ENT G*(ELDIF20)*QP05	01041	10230	00570
00750		STR G*Q	01042	14000	00000
00751		SUB G*A*QP05	01043	27670	00000
00752		JP SC5	01044	61000	00605
00753		ENT G*(SCANP0INT)	01045	10030	00563
00754		MUL W(SCSIN)	01046	22030	00556
00755		LSH AG*2	01047	07000	00002
00756		STR A*(ELPOINT)	01050	15030	00574
00757	AZT0G0MEL	ENT G*(ELDIF20)	01051	10030	00570
00760		SUB G*(ELDIFM10)	01052	27030	00567

SET UP DIFFERENCES

B27 E2 - F0

B30 (E2 - E0)SQ

B27 E-1 - E0

B27 A-1 - A0

B27 A2 - A0

B30 (A2 - A0)SQ

IS ELEVATIO BELOW HORIZON

B29 SQUARE ROOT OF DENOM

B28 SINE OF ANGLE

B28 COSINE OF ANGLE

IS I POSITIVE

IS SCAN AT LOWER END

IS MAG(DIFEL-DIFAZ) P05

B27 ELEVATION SCAN



```

. 01053 STR A*(N) 1145 15030 00562
. 01054 LSH A*1 1146 06000 00001
. 01055 STR A*(SCANLIN) 1147 15030 00550
. 01056 ENT G*(N) 1150 10030 00562
. 01057 MUL W(N) 1151 22030 00562
. 01060 STR G*(JUNK) 1152 14030 00577
. 01061 ENT G*(LENGTH) 1153 10030 01204
. 01062 LSH AG*9D 1154 07000 00011
. 01063 DIV W(JUNK) 1155 23030 00577
. 01064 MUL W(RECIPREV) 1156 22030 01202
. 01065 RSH AG*29D 1157 03000 00035
. 01066 STR G*G 1160 14000 00000
. 01067 STR G*(SCANACCNEG) 1161 14030 00551

. 01070 ENT A*-1 1162 11040 77776
. 01071 SUB A*(N) 1163 21030 00562
. 01072 STR A*(I) 1164 15030 00561
. 01073 CL W(CROSSCAN) 1165 16030 00552
. 01074 CL W(ECROSSCAN) 1166 16030 00553
. 01075 CL W(ACROSSCAN) 1167 16030 00554
. 01076 ENT G*(WIDTH) 1170 10030 01205
. 01077 MUL W(RECIPREV) 1171 22030 01202
. 01100 LSH AG*8D 1172 07000 00010
. 01101 STR A*(CRSCW) 1173 15030 00560

. 01102 ENT G*(LENGTH) 1174 10030 01204
. 01103 MUL W(RECIPREV) 1175 22030 01202
. 01104 RSH AG*22D 1176 03000 00026
. 01105 ADD G*(SCMINEL) 1177 26030 01206
. 01106 STR G*(HORIZTEST) 1200 14030 00564
. 01107 EXIT 1201 61010 01134
. 01110 RECIPREV 0013301330
. 01111 MAXSCACC 0000000507

. 01112 LENGTH 0012000000
. 01113 WIDTH 0001000000
. 01114 SCMINEL 0001014223

. 01115 NARBITRARY 100000
. 01116 NROUND 340000
. 01117 RP2AVG2A 0
. 01120 RP2AVG8A 0
. 01121 RP2AVGSA 0
. 01122 RP2AVGLA 0
. 01123 RP2CODE2 0
. 01124 RP2CODE8 0
. 01125 RP2CODES 0
. 01126 RP2CODEL 0

. 01127 LOCCK EQUALS RP2CODE2
. 01130 RAIUS 0
. 01131 AVGBCW 0
. 01132 DELRADIUS 0000035062
. 01133 MAXRADIUS 0000127434

. 01145 15030 00562
. 01146 06000 00001
. 01147 15030 00550
. 01150 10030 00562
. 01151 22030 00562
. 01152 14030 00577
. 01153 10030 01204
. 01154 07000 00011
. 01155 23030 00577
. 01156 22030 01202
. 01157 03000 00035
. 01160 14000 00000
. 01161 14030 00551

. 01162 11040 77776
. 01163 21030 00562
. 01164 15030 00561
. 01165 16030 00552
. 01166 16030 00553
. 01167 16030 00554
. 01170 10030 01205
. 01171 22030 01202
. 01172 07000 00010
. 01173 15030 00560

. 01174 10030 01204
. 01175 22030 01202
. 01176 03000 00026
. 01177 26030 01206
. 01200 14030 00564
. 01201 61010 01134
. 01202 00133 01330
. 01203 00000 00507
. 01204 00120 00000
. 01205 00010 00000
. 01206 00010 14223
. 01207 00001 00000
. 01210 00003 40000
. 01211 00000 00000
. 01212 00000 00000
. 01213 00000 00000
. 01214 00000 00000
. 01215 00000 00000
. 01216 00000 00000
. 01217 00000 00000
. 01220 00000 00000
. 01221 00000 00000
. 01222 00000 00000
. 01223 00000 35062
. 01224 00001 27434

. 0000035062
. 0000127434

. 000111827
. 000334827

. 000111827
. 000334827

```

LOCSCABIAS	0	01134	LOCSCABIAS	0	01225	00000	00000	B27 COMPUTED LOCAL SCAN AZIMUT
WEIGHTSUM	0	01135	WEIGHTSUM	0	01226	00000	00000	H BIAS
LOCSCEBIAS	0	01136	LOCSCEBIAS	0	01227	00000	00000	SUM OF WEIGHTS FOR RP2 PULSES
RP2AVG2E	0	01137	RP2AVG2E	0	01230	00000	00000	B27 COMPUTED LOCAL SCAN ELEVAT
RP2AVG8E	0	01140	RP2AVG8E	0	01231	00000	00000	ION BIAS
RP2AVGSE	0	01141	RP2AVGSE	0	01232	00000	00000	
RP2AVGLE	0	01142	RP2AVGLE	0	01233	00000	00000	
FIVEHUND	0	01143	FIVEHUND	0	01234	00762	00000	
GOODLSCNT	4980	01144	GOODLSCNT	0				
LOCSCCTABLE	EQUALS	01145	LOCSCCTABLE	-1	01235	77776	77776	NO. OF GOOD LOCAL SCANS IN U
		01146		-1	01236	77776	00001	1ST SCAN, 1ST POINT (OLDEST)
		01147		1	01237	00001	00001	2ND AZ IN U, EL IN L
		01150		1	01240	00001	77776	3RD
		01151		-1	01241	77776	77776	4TH
		01152		0	01242	00000	00001	5TH
		01153		1	01243	00001	00000	1ST SCAN, 2ND POINT
		01154		0	01244	00000	77776	
		01155		-1	01245	77776	00000	
		01156		0	01246	00000	00001	
		01157		1	01247	00001	00000	1ST SCAN, 3RD POINT
		01160		0	01250	00000	77776	
		01161		-1	01251	77776	00000	
		01162		0	01252	00000	00001	
		01163		1	01253	00001	00000	
		01164		-1	01254	77776	77776	1ST SCAN, 4TH POINT
		01165		-1	01255	77776	00001	
		01166		1	01256	00001	00001	
		01167		1	01257	00001	77776	
		01170		-1	01260	77776	77776	
		01171	GETAVG8	ENTRY	01261	61000	00000	GET AZ AVERAGE
		01172		ENT A** (RP2AVG8A)	01262	11030	01212	
		01173		ADD A** (RP2AVG2A)	01263	20030	01211	
		01174		STR A** (RP2AVG8A)	01264	15030	01212	GET EL AVERAGE
		01175		ENT A** (RP2AVG8E)	01265	11030	01231	
		01176		ADD A** (RP2AVG2E)	01266	20030	01230	
		01177		STR A** (RP2AVG8E)	01267	15030	01231	
		01200		RPL Y+1*L (RP2C0DE8)	01270	36010	01216	INCREASE CODE BY ONE
		01201		CL L (RP2C0DE2)	01271	16010	01215	CLEAR 2SEC CODE
		01202		EXIT	01272	61010	01261	
		01203	AVGAZOCY	B6*(RP2TABLEID)	01273	12620	02576	
		01204		ENT Q*(WEIGHTTTID)	01274	10020	02646	
		01205		CL U (RP2COUNT)	01275	16020	02573	
		01206	INTERAZCY	JP AVGRoutine	01276	61000	01304	
		01207		ENT A*(RP2COUNT)*ANOT	01277	11510	02573	ANY RP2 PULSES
		01210		JP NORP2PULSE	01300	61000	00421	
		01211		ENT B6*(RP2TABLEID)	01301	12610	02576	
		01212		ENT Q*(WEIGHTTTID)	01302	10010	02646	
		01213		CL L (RP2COUNT)	01303	16010	02573	
		01214	AVGRoutine	STR Q*(AVGL00P+2)	01304	14010	01322	
		01215		STR Q*(AVGL00P+6)	01305	14010	01326	
		01216		CL W (AVGBCW)	01306	16030	01222	
		01217		CL W (WEIGHTSUM)	01307	16030	01226	
		01220		CL B7	01310	12700	00000	
		01221		RSH A*2	01311	02000	00002	
		01222		SUB A*1	01312	21000	00001	
		01223		STR A*(AVGL00P+11)	01313	15010	01331	

•	01224	ENT B6*3+B6	01314	12606	00003
•	01225	STR B6*L(AVGL00P)	01315	16610	01320
•	01226	STR B6*L(AVGL00P+1)	01316	16610	01321
•	01227	CL B6	01317	12600	00000
•	01230	AVGL00P	01320	10026	00000
•	01231	ENT G*U(B6)	01321	27016	00000
•	01232	SUB G*L(B6)	01322	22037	00000
•	01233	MUL W(B7)	01323	26030	01222
•	01234	ADD G*(AVGBCW)	01324	14030	01222
•	01235	STR G*(AVGBCW)	01325	11030	01226
•	01236	ENT A*(WEIGHTSUM)	01326	20037	00000
•	01237	ADD A*(B7)	01327	15030	01226
•	01240	STR A*(WEIGHTSUM)	01330	12606	00004
•	01241	ENT B6*4+B6	01331	71700	00000
•	01242	BSK B7*0	01332	61000	01320
•		JP AVGL00P			
•	01243	CL A	01333	11000	00000
•	01244	LSH A*15D	01334	07000	00017
•	01245	DIV W(WEIGHTSUM)	01335	23030	01226
•	01246	ADD G*40000	01336	26000	40000
•	01247	SUB G*(FIVEHUND)*Q05	01337	27630	01234
•	01250	ADD G*(FIVEHUND)*SKIP	01340	26130	01234
•	01251	ENT G*(FIVEHUND)*SKIP	01341	10030	01234
•	01252	STR G*(AVGBCW)	01342	14030	01222
•	01253	ENT A*(AVGBCW)	01343	11020	01222
•					
•	01254	CL Q	01344	10000	00000
•	01255	DIV 4000D	01345	23000	07640
•	01256	STR G*(ACQY)	01346	14030	02051
•	01257	MUL W(ACQY)	01347	22030	02051
•	01260	LSH A*3	01350	07000	00003
•	01261	STR A*(ACQYQ)	01351	15030	02052
•	01262	ENT G*A	01352	10070	00000
•	01263	MUL W(ACQY)	01353	22030	02051
•	01264	LSH A*3	01354	07000	00003
•	01265	STR A*(ACQYQ)	01355	15030	02053
•	01266	ENT G*(ACQY)	01356	10030	02051
•	01267	MUL W(THIRD)	01357	22030	02054
•	01270	STR A*(JUNK)	01360	15030	00577
•	01271	ENT G*(ACQYQ)	01361	10030	02053
•	01272	MUL W(THIRD)	01362	22030	02054
•	01273	STR A*(JUNK+1)	01363	15030	00600
•	01274	SUB A*(JUNK)	01364	21030	00577
•	01275	RSH A*1	01365	02000	00001
•	01276	STR A*(ACGA+3)	01366	15030	02061
•	01277	ENT A*(ACQYQ)	01367	11030	02052
•	01300	SUB A*(ACQYQ)	01370	21030	02053
•	01301	RSH A*1	01371	02000	00001
•	01302	ADD A*(ACQY)	01372	20030	02051
•	01303	STR A*(ACGA+2)	01373	15030	02060
•	01304	ENT A*(ACQYQ)	01374	11030	02053
•	01305	SUB A*(ACQY)	01375	21030	02051
•	01306	RSH A*1	01376	02000	00001
•	01307	SUB A*(ACQYQ)	01377	21030	02052
•	01310	ADD A*(ACGA1)	01400	20030	02062
•	01311	STR A*(ACGA+1)	01401	15030	02057
•	01312	ENT A*(ACQYQ)	01402	11030	02052
•	01313	SUB A*(ACQYQ)	01403	21030	00600
•	01314	RSH A*1	01404	02000	00001

COMPUTE AVERAGE BCW

AVG BCW IN AVGBCW AND Q WITH B  
15

ROUNDED BCW IN U(AVGBCW)  
COMPUTE INTERPOLATION COEFFICI  
ENTS

FOR THE AVG BCW

B27 Y

B27 YY

B27 YYY

B27 (113)Y

B27 (1/3)YYY

A2

A1

A0



01401	INOVERLAP	LSH	AQ*1*AP05	01475	07600	00001
01402		RSH	AQ*3*SKIP	01476	03100	00003
01403		LSH	AQ*S7D*SKIP	01477	07100	00071
01404		SUB	A*200	01500	21000	00200
01405		JP	NONOVERLAP+1	01501	61000	01442
01406	KTABLE	0	KIS0	01502	00000	01507
01407		0	KIS1	01503	00000	01511
01410		0	KIS2	01504	00000	01526
01411		0	KIS3	01505	00000	01530
01412		0	KIS4	01506	00000	01535
01413	KIS0	ENT	B6*1	01507	12600	00001
01414		JP	LOCSCCOMP1	01510	61000	01720
01415	KIS1	ENT	B6*2	01511	12600	00002
01416		ENT	A*(RAIUS)*AZERO	01512	11430	01221
01417		JP	LOCSCCOMP1	01513	61000	01720
01420		ENT	A*(RP2CODE2)*AN0T	01514	11510	01215
01421		JP	LOCSCCOMP1	01515	61000	01720
01422		PUT	W(RP2AVG2E)*W(RP2AVGLE)	01516	10030	01230
01423		PUT	W(RP2AVG2A)*W(RP2AVGLA)	01517	14030	01233
01424		PUT	1*(RP2C00EL)	01520	10030	01211
01425		CL	L(RP2C00E2)	01521	14030	01214
01426		JP	LOCSCCOMP1	01522	10000	00001
01427	KIS2	ENT	B6*3	01523	14010	01220
01430		JP	LOCSCCOMP1	01524	16010	01215
01431	KIS3	ENT	B6*4	01525	61000	01720
01432		ENT	A*(RAIUS)	01526	12600	00003
01433		ADD	A*(DELRAIUS)	01527	61000	01720
01434		STR	A*(RAIUS)	01530	12600	00004
01435		JP	LOCSCCOMP1	01531	11030	01221
01436	KIS4	ENT	A*(RP2C00E2)*AZERO	01532	20030	01223
01437		RJP	GETAVG8	01533	15030	01221
01440		ENT	A*(RP2C00E8)*AN0T	01534	61000	01720
01441		JP	LASTTEST	01535	11410	01215
01442		RPL	Y+1*(G000LSCNT)	01536	65000	01261
01443		SUB	A*3*AP05	01537	11510	01216
01444		JP	NEWMEAN	01540	61000	01572
01445		JP	ACQUIMSG*AZERO	01541	36020	01217
01446		RPL	Y-1*(G000LSCNT)	01542	21600	00003
01447		ENT	A*(TIMECODE)*ANEG	01543	61000	01553
01450		JP	NEWMEAN	01544	60400	02041
01451		PUT	-0*(TIMECORRC)	01545	37020	01217
01452		CL	U(TIMECODE)	01546	11760	00217
01453	NEWMEAN	ENT	A*(RP2AVG8A)	01547	61000	01553
01454		RSH	AQ*300	01550	10040	77777
01455		DIV	L(RP2C00E8)	01551	14020	02055
01456		STR	Q*(LOCSCABIAS)	01552	16020	00217
01457		ENT	A*(RP2AVG8E)	01553	11030	01231
01460		RSH	AQ*300	01554	03000	00036
01461		DIV	L(RP2C00E8)	01555	23010	01216
01462		STR	Q*(LOCSCABIAS)	01556	14030	01225
01463	INITLOCSC	ENT	A*(RP2AVG8E)	01557	11030	01231
01464		CL	W(RP2AVG8A)	01561	03000	00036
01465		CL	U(LOCSCCK)	01561	23010	01216
01466		CL	L(RP2C00E8)	01562	14030	01227
				01563	16030	01212
				01564	16030	01231
				01565	16020	01215
				01566	16010	01216

NO RP2 PULSES  
 STORE LEFT OVER RP2 PULSE  
 K IS 0  
 K IS 1  
 K IS 2  
 K IS 3  
 USE NEXT SCAN RADIUS  
 ANY RP2 PULSES IN LAST 8 SEC

COMPUTE LOCAL SCAN BIASES  
 FROM THE AVERAGES ACCUMULATED  
 OVER 8 SECOND INTERVAL

SET K TO ZERO

.	01467	CL	W(RAIUS)	16030	01221
.	01470	CL	L(RP2CODE2)	16010	01215
.	01471	JP	LOCALSCAN	01571	61000 01473
.	01472	ENT	B6*1	01572	12600 00001
.	01473	ENT	A*(RAIUS)	01573	11030 01221
.	01474	SUB	A*(MAXRADIUS)*AP05	01574	21630 01224
.	01475	JP	LOCSCC0MPI	01575	61000 01720
.	01476	ENT	A*(RP2CODE2)*AN0T	01576	11530 01215
.	01477	JP	FIRSTLOC	01577	61000 01612
.	01500	ENT	A*(RP2CODEL)*AN0T	01600	11510 01220
.	01501	JP	LEFTSSCRP2	01601	61000 01622
.	01502	CL	L(RP2CODEL)	01602	16010 01220
.	01503	PUT	W(RP2AVGLA)*W(RP2AVG8A)	01603	10030 01214
.	01504	PUT	W(RP2AVGLE)*W(RP2AVG8E)	01604	14030 01212
.	01505	ENT	Q*1	01606	14030 01231
.	01506	STR	Q*L(RP2CODE8)	01607	10000 00001
.	01507	JP	CLEARCOUNT	01610	14010 01216
.	01510	PUT	W(RP2AVG2A)*W(RP2AVG8A)	01611	61000 01620
.	01511	PUT	W(RP2AVG2E)*W(RP2AVG8E)	01612	10030 01211
.	01512	PUT	I*L(RP2CODE8)	01613	14030 01212
.	01513	CL	U(G00DLSCNT)	01614	10030 01230
.	01514	JP	NEWMEAN	01615	14030 01231
.	01515	CL	W(RAIUS)	01616	10000 00001
.	01516	ENT	A*(RP2CODES)*AN0T	01617	14010 01216
.	01517	JP	BACKUPSCAN	01620	16020 01217
.	01520	CL	L(RP2CODES)	01621	61000 01553
.	01521	PUT	W(RP2AVGSA)*W(RP2AVG8A)	01622	16030 01221
.	01522	PUT	W(RP2AVGSE)*W(RP2AVG8E)	01623	11510 01217
.	01523	JP	CLEARCOUNT-2	01624	61000 01633
.	01524	ENT	A*(I)*AP05	01625	16010 01217
.	01525	JP	NEGI	01626	10030 01213
.	01526	ENT	Q*(SC10)	01627	14030 01212
.	01527	SUB	Q*36030*0ZERO	01630	10030 01232
.	01530	JP	POSP05	01631	14030 01231
.	01531	SUB	A*4	01632	61000 01616
.	01532	STR	A*(I)	01633	11630 00561
.	01533	JP	SEARCHSCAN+1	01634	61000 01643
.	01534	ENT	Q*(SC10)	01635	10020 01036
.	01535	SUB	Q*37030*0ZERO	01636	27400 36030
.	01536	JP	\$+4	01637	61000 01672
.	01537	ADD	A*4	01640	21000 00004
.	01540	STR	A*(I)	01641	15030 00561
.	01541	JP	SEARCHSCAN+1	01642	61000 00762
.	01542	SUB	A*4	01643	10020 01036
.	01543	STR	A*(I)	01644	27400 37030
.	01544	ADD	A*(N)*ANEG	01645	61000 01651
.	01545	JP	SEARCHSCAN+1	01646	20000 00004
.	01546	STR	A*4	01647	15030 00561
.	01547	SUB	A*(N)	01650	61000 00762
.	01550	SUB	A*1	01651	21000 00004
.	01551	STR	A*(I)	01652	15030 00561
.				01653	20730 00562
.				01654	61000 00762
.				01655	15040 00000
.				01656	21030 00562
.				01657	21000 00001
.				01660	15030 00561

ALL THROUGH WITH LOCAL SCAN  
NO

ANY LEFT OVER LOCAL RP2 PULSES

NO  
INTERROGATE THE LOCAL RP2

NO  
INTERROGATE THE SEARCH RP2

IS I POSITIVE  
NO  
GOING TOWARD END  
NO  
YES  
GOING TOWARD END  
NO  
YES  
I IS I-4

NO  
GOING TOWARD END  
NO  
YES  
I IS I+4

NO  
IS IT LES THAN 4 FROM END  
NO  
I IS AT NEGATIVE END

01552	ENT	A*(ECROSSCAN)	01661	11030	00553	COMPLIMENT CROSSCAN
01553	STR	A*A	01662	15040	00000	
01554	STR	A*(ECROSSCAN)	01663	15030	00553	
01555	ENT	A*(ACROSSCAN)	01664	11030	00554	
01556	STR	A*A	01665	15040	00000	
01557	STR	A*(ACROSSCAN)	01666	15030	00554	
01560	ENT	A*37030	01667	11000	37030	MAKE SCAN GO THE OTHER WAY
01561	STR	A*(SC10)	01670	15020	01036	
01562	JP	SEARCHSCAN+1	01671	61000	00762	I IS AT POSITIVE END
01563	ADD	A*4	01672	20000	00004	
01564	STR	A*(I)	01673	15030	00561	
01565	SUB	A*(N)*APOS	01674	21630	00562	
01566	JP	SEARCHSCAN+1	01675	61000	00762	
01567	STR	A*A	01676	15040	00000	I IS AT POSITIVE END
01570	ADD	A*(N)	01677	20030	00562	
01571	SUB	A*1	01700	21000	00001	
01572	STR	A*(I)	01701	15030	00561	
01573	ENT	G*(CROSSCAN)	01702	10030	00552	SUBTRACT CROSSCAN INCREMENT
01574	SUB	G*(DELGRSC)	01703	27030	00555	
01575	STR	G*(CROSSCAN)	01704	14030	00552	
01576	MUL	W*(SCSIN)	01705	22030	00556	
01577	LSH	AG*2	01706	07000	00002	
01600	STR	Q*Q	01707	14000	00000	
01601	STR	A*(ACROSSCAN)	01710	15030	00554	
01602	ENT	G*(CROSSCAN)	01711	10030	00552	
01603	MUL	W*(CCOS)	01712	22030	00557	
01604	LSH	AG*2	01713	07000	00002	
01605	STR	A*(ECROSSCAN)	01714	15030	00553	
01606	ENT	A*36030	01715	11000	36030	MAKE SCAN GO THE OTHER WAY
01607	STR	A*(SC10)	01716	15020	01036	
01610	JP	SEARCHSCAN+1	01717	61000	00762	
01611	LOCSCCOMP1	B6*(LOCSC)	01720	16620	01215	
01612	ENT	A*(RP2CODE2)*AZERO	01721	11410	01215	ANY RP2 PULSES
01613	RJP	GETAVG8	01722	65000	01261	ADD THEM INTO THE SUM
01614	LOCSCCOMP	G*(RAIUS)	01723	10030	01221	
01615	MUL	UX*(LOCSC*TABLE+B6)	01724	22066	01235	
01616	ADD	G*(LOCSC*BIAS)	01725	26030	01225	
01617	ADD	G*(AZIMSH+2)	01726	26030	00472	
01620	STR	G*(ACQAZIM)	01727	14030	63071	OLDEST AZ POINT AZ-1
01621	ENT	G*(RAIUS)	01730	10030	01221	
01622	MUL	UX*(LOCSC*TABLE+5*B6)	01731	22066	01242	
01623	ADD	G*(LOCSC*BIAS)	01732	26030	01225	
01624	ADD	G*(AZIMSH+3)	01733	26030	00473	
01625	STR	G*(ACQAZIM+1)	01734	14030	63072	AZ0
01626	ENT	G*(RAIUS)	01735	10030	01221	
01627	MUL	UX*(LOCSC*TABLE+10D+B6)	01736	22066	01247	
01630	ADD	G*(LOCSC*BIAS)	01737	26030	01225	
01631	ADD	G*(AZIMSH+4)	01740	26030	00474	
01632	STR	G*(ACQAZIM+2)	01741	14030	63073	AZ1
01633	ENT	G*(RAIUS)	01742	10030	01221	
01634	MUL	UX*(LOCSC*TABLE+15D+B6)	01743	22066	01254	
01635	ADD	G*(LOCSC*BIAS)	01744	26030	01225	
01636	ADD	G*(AZIMSH+5)	01745	26030	00475	
01637	STR	G*(ACQAZIM+3)	01746	14030	63074	AZ2
01640	ENT	G*(RAIUS)	01747	10030	01221	
01641	MUL	LX*(LOCSC*TABLE+B6)	01750	22056	01235	
01642	ADD	G*(LOCSC*BIAS)	01751	26030	01227	
01643	ADD	G*(ELEVSH+2)	01752	26030	00500	
01644	STR	G*(ACQ*ELEV)	01753	14030	63075	EL-1

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01736      .

ENT Q*(RAIUS)
MUL LX(LOCSCCTABLE*5+B6)
ADD Q*(LOCSCCBIAS)
ADD Q*(ELEVSH+3)
STR Q*(ACQLELV+1)
ENT Q*(RAIUS)
MUL LX(LOCSCCTABLE*100*B6)
ADD Q*(LOCSCCBIAS)
ADD Q*(ELEVSH+4)
STR Q*(ACQLELV+2)
ENT Q*(RAIUS)
MUL LX(LOCSCCTABLE*150*B6)
ADD Q*(LOCSCCBIAS)
ADD Q*(ELEVSH+5)
STR Q*(ACQLELV+3)
ENT Q*(SCANMODE)
CL A
RSH AQ*150
STR Q*(SCANMODE)
ENT A*(TIMECORRC)*ANEG
JP L(ACQUIRUN)
CL W(TIMECORRC)
ENT A*(AZIMSH+5)
SUB A*(AZIMSH+2)
ADD A*(ELEVSH+5)
SUB A*(ELEVSH+2)
STR A*(JUNK)
ENT A*(LOCSCCBIAS)
ADD A*(LOCSCCBIAS)
CL Q
RSH AQ*9D
DIV W(JUNK)
LSH AQ*30D

STR A*(JUNK)
RSH AQ*8D
DIV W(S+1)*SKIP
3*41000000
STR Q*(TIMECORR)
ENT Q*(AZIMSH+2)
SUB Q*(AZIMSH+5)
MUL W(JUNK)
RSH AQ*21D
RPT 6*ADV
RPL Y-Q*(AZIMSH)
RPL Y+Q*(LOCSCCBIAS)
ENT Q*(ELEVSH+2)
SUB Q*(ELEVSH+5)
MUL W(JUNK)
RSH AQ*21D
RPT 6*ADV
RPL Y-Q*(AZIMSH)
RPL Y+Q*(LOCSCCBIAS)
ENT Q*(ELEVSH+2)
SUB Q*(ELEVSH+5)
MUL W(JUNK)
RSH AQ*21D
RPT 6*ADV
RPL Y-Q*(ELEVSH)
RPL Y+Q*(LOCSCCBIAS)
JP L(ACQUIRUN)
RJP U(PRLOG)
3 ACQUIMSG1
1 -28D
NO-0P
JP NEWMEAN

01003 01221
22056 01242
26030 01227
26030 00501
14030 63076
10030 01221
22056 01247
26030 01227
26030 00502
14030 63077
10030 01221
22056 01254
26030 01227
26030 00503
14030 63100
10030 00576
11000 00000
03000 00017
14030 00576
11730 02055
61010 00360
16030 02055
11030 00475
21030 00472
20030 00503
21030 00500
15030 00577
11030 01227
20030 01225
03000 00011
23030 00577
07000 00036

15030 00577
03000 00010
23130 02020
34100 00000
02020 14030 63107
02022 10030 00472
22030 00577
03000 00025
70100 00006
35030 00470
34030 01225
10030 00500
27030 00503
22030 00577
03000 00025
70100 00006
35030 00470
34030 01225
10030 00500
27030 00503
22030 00577
03000 00025
70100 00006
35030 00476
34030 01227
61010 00360
65020 63423
00003 02046
00001 77743
12000 00000
61000 01553

EL0
EL1
SET MODE TO LOCAL

TIME CORRECTION PROGRAM
A2 - A-1 + E2 - E-1
B21
TIME IN 6-SECOND INTERVALS B21

14400B15 NO OF 6 SEC IN A DAY
TIME CORRECTION TO MCP

PRINT ACQUIRED MESSAGE

```

•	01737	ACQUIMS61	FD	0*	TARGET ACQUIRED	02046	31062	71412	
•	01740	AC0Y	0			02047	31050	61026	
•	01741	AC0YSQ	0			02050	32162	71211	Y R27
•	01742	AC0YCUBE	0			02051	00000	00000	YY B27
•	01743	THIRD	0			02052	00000	00000	YYY B27
•	01744	TIMECORRC	0	2525252461		02053	00000	00000	.33333333B30 1/3 B30
•	01745	AC0A	0	RESERVE 4		02054	25252	52461	INTERPOLATION COEFFICIENTS B27
•	01746	AC0A1	1000000000	RESERVE 164D		02055	00000	00000	RP2 BUFFER TABLE N01 GOES WITH
•	01747	RP2TABLE1	RESERVE 164D	0		02056	00000	00000	AZIMOUT
•	01750	RP2TABLE2	RESERVE 164D	0		02327	00000	00000	RP2 BUFFER FABLE N02
•	01751	RP2COUNT	0	0		02573	00000	00000	RP2 COUNT U FOR TABLE1 L FOR
•	01752	JUNKY	RESERVE 1						TABLE2
•	01753	RP2CHANNEL	0	0		02574	00000	00000	TEMPORARY STORAGE
•	01754	RP2TABLEID	U-TAG	RP2TABLE1*RP2TABLE2		02575	00000	00000	
•	01755	RP2INTERPT	ENTRY			02576	02063	02327	
•	01756		STR	B6*(RP2INTERPT)		02577	61000	00000	
•	01757		STR	G*(JUNKG)		02600	16820	02577	SAVE A AND B6
•	01760		STR	A*(JUNKG)		02601	14030	02647	
•	01761		PUT	-0*(TRACKINDIC)		02602	15030	02574	
•	01762		ENT	G*(113)		02603	10040	77777	
•	01763		SUB	G*AZIMIN+4990*QZERO		02604	14030	63026	
•	01764		ENT	A*(RP2COUNT)*SKIP		02605	10020	00113	
•	01765		ENT	A*(RP2COUNT)		02606	27400	75763	
•	01766		SUB	A*164D*ANEG		02607	11110	02573	
•	01767		ENT	A*4*SKIP		02610	11020	02573	
•	01770		ADD	A*168D		02611	21700	00244	
•	01771		ADD	G*0*QZERO		02612	11000	00004	
•	01772		STR	A*(RP2COUNT)*SKIP		02613	20000	00250	
•	01773		STR	A*(RP2COUNT)*SKIP		02614	26400	00000	
•	01774		ADD	A*(RP2TABLEID)*SKIP		02615	15110	02573	
•	01775		ADD	A*(RP2TABLEID)		02616	15120	02573	
•	01776		SUB	A*4		02617	20110	02576	
•	01777		ENT	B6*A		02620	20020	02576	
•	02000		ENT	A*(113)		02621	21000	00004	
•	02001		STR	A*(B6)		02622	12670	00000	STORE AZIMOUT BCW
•	02002		STR	A*(3+B6)		02623	11030	00113	
•	02003		ENT	A*(RANGEADD)		02624	15036	00000	
•	02004		STR	A*(S+1)		02625	15036	00003	STORE RANGE
•	02005		ENT	A*(0)		02626	11020	63445	
•	02006		STR	A*(1+B6)		02627	15010	02630	
•	02007		ENT	A*(B6)		02630	11030	00000	
•	02010		SUB	A*(B6)		02631	15036	00001	STORE DOPPLER
•	02011		ADD	A*(D0PPADD)		02632	11026	00000	
•	02012		SUB	A*5000		02633	21016	00000	
•	02013		STR	A*(S+1)		02634	20020	63444	
•	02014		ENT	A*(0)		02635	21000	00764	
•	02015		STR	A*(2+B6)		02636	15010	02637	
•	02016		ENT	G*(JUNKG)		02637	11030	00000	
•	02017		ENT	A*(JUNKY)		02640	15036	00002	
•	02020		ENT	B6*(RP2INTERPT)		02641	10030	02647	RESTORE A AND B6
•	02021		STR	C14*(RP2CHANNEL)		02642	11030	02574	
•	02022		RILJP	L(RP2INTERPT)		02643	12620	02577	
•	02023	WEIGHTIID	U-TAG	WEIGHTI1*WEIGHTI2		02644	17630	02575	
•	02024	JUNKG	0			02645	60110	02577	ARCIFICIAL WEIGHT TABLE
•						02646	00000	00000	

02025	WEIGHTT1	1	0	02650	00001	00000	ALL RP2 PULSES HAVE EQUAL MAX WEIGHT
02026		1	0	02651	00001	00000	MAXIMUM VALUE COULD RE 1B15
02027		1	0	02652	00001	00000	
02030		1	0	02653	00001	00000	
02031		1	0	02654	00001	00000	
02032		1	0	02655	00001	00000	
02033		1	0	02656	00001	00000	
02034		1	0	02657	00001	00000	
02035		1	0	02660	00001	00000	
02036		1	0	02661	00001	00000	
02037		1	0	02662	00001	00000	
02040		1	0	02663	00001	00000	
02041		1	0	02664	00001	00000	
02042		1	0	02665	00001	00000	
02043		1	0	02666	00001	00000	
02044		1	0	02667	00001	00000	
02045		1	0	02670	00001	00000	
02046		1	0	02671	00001	00000	
02047		1	0	02672	00001	00000	
02050		1	0	02673	00001	00000	
02051		1	0	02674	00001	00000	
02052		1	0	02675	00001	00000	
02053		1	0	02676	00001	00000	
02054		1	0	02677	00001	00000	
02055		1	0	02700	00001	00000	
02056		1	0	02701	00001	00000	
02057		1	0	02702	00001	00000	
02060		1	0	02703	00001	00000	
02061		1	0	02704	00001	00000	
02062		1	0	02705	00001	00000	
02063		1	0	02706	00001	00000	
02064		1	0	02707	00001	00000	
02065		1	0	02710	00001	00000	
02066		1	0	02711	00001	00000	
02067		1	0	02712	00001	00000	
02070		1	0	02713	00001	00000	
02071		1	0	02714	00001	00000	
02072		1	0	02715	00001	00000	
02073		1	0	02716	00001	00000	
02074		1	0	02717	00001	00000	
02075		1	0	02720	00001	00000	
02076	WEIGHTT2	1	0	02721	00001	00000	
02077		1	0	02722	00001	00000	
02100		1	0	02723	00001	00000	
02101		1	0	02724	00001	00000	
02102		1	0	02725	00001	00000	
02103		1	0	02726	00001	00000	
02104		1	0	02727	00001	00000	
02105		1	0	02730	00001	00000	
02106		1	0	02731	00001	00000	
02107		1	0	02732	00001	00000	
02110		1	0	02733	00001	00000	
02111		1	0	02734	00001	00000	
02112		1	0	02735	00001	00000	
02113		1	0	02736	00001	00000	
02114		1	0	02737	00001	00000	
02115		1	0	02740	00001	00000	





01723	LOCSCCOMP	02041	ACQUIMSG	02046	ACQUIMSG1
02051	ACQY	02052	ACQYSQ	02053	ACQYCUBE
02054	THIRD	02055	TIMCORRC	02056	ACQA
02062	ACGAI	02063	RP2TABLE1	02327	RP2TABLE2
02573	RP2COUNT	02574	JUNKY	02575	RP2CHANNEL
02576	RP2TABLEID	02577	RP2INTERPT	02646	WEIGHTIID
02647	JUNKO	02650	WEIGHTI1	02721	WEIGHTT2
02773	A\$\$\$\$1111	02774	A\$\$\$\$1112	02775	A\$\$\$\$1113
63000	ID1CELCOR	63001	ID2CELCOR	63002	RA
63003	DEC	63004	SRA	63005	SDEC
63006	RADIUS	63007	RADOT	63010	DECOOT
63011	RADIUSD0T	63012	SIDERTIME	63013	VIZRA1
63014	VIZDEC1	63015	VIZRA2	63016	VIZDEC2
63017	TW0SEC00P	63020	PL0TAZIM\$	63021	PL0TELEV\$
63022	AZTRACKERR	63023	ELTRACKERR	63024	MODESWITCH
63025	AUTOSWITCH	63026	TRACKINDIC	63027	AZIMERROR\$
63030	ELEVEERROR\$	63050	ID1RADCOR	63051	ID2RADCOR
63052	RANGE	63053	AZIM	63054	ELEV
63055	SAZIM	63056	SELEV	63057	CRANGE
63060	CAZIM	63061	CELEV	63062	RANGED0T
63063	TRUERANGE	63064	SINORIENT	63065	COSORIENT
63066	SINAZEL	63070	COSAZEL	63071	ACGAZIM
63075	ACGELEV	63101	FRAMESIZE	63102	RADIOMETER
63103	TIMEMODE	63104	FIRSTELEV	63105	ASTRORA
63106	ASTRODEC	63107	TIMECORR	63110	KYBRDLEVEL
63111	TTYSTATUS	63112	RECORDSIZE	63113	CELBODY
63120	AZDIFS	63121	ELDIFS	63122	RDIFS
63123	R00TDIFS	63124	SLAVEOPTS	63125	SLAVEMODES
63126	SLAVE	63130	IDTIME	63131	IDTIME
63132	TRUETIME	63133	CELTIME	63134	SCELTIME
63135	CONVERTIME	63136	SRADTIME	63137	HOURMINUTE
63140	SECONDS	63141	DSECONDS	63142	ACTUALTIME
63143	ESTSHIFTED	63144	GMTSHIFTED	63145	GMTMODU24
63146	BLASTOFF	63147	YEARMONTH	63150	DAY
63151	HOURREG	63152	MINREG	63153	FIRSTTHRU
63154	DUMSECTTG	63155	RECRD SWITCH	63156	RELEASESW
63157	RADINDIC	63160	PRINRECSW	63161	REFRACIND\$
63162	AZELIND\$	63210	ID1RECRD	63211	ID2RECRD
63212	RECFILE	63310	ID1SYSPAR	63311	ID2SYSPAR
63312	RADARMODE	63313	SYSTAT1	63314	SYSTAT2
63315	SYSTATD	63316	DELTAEE	63317	FREQUENCY
63320	LONGITUDE	63321	GEODETLAT	63322	GEOCENLAT
63323	EQUATOR	63324	POLE	63325	AZIM0VER
63326	HEIGHT	63327	YRTRAN	63330	ZRTRAN
63331	SKIP	63332	MSFREQ	63333	WFFREQ
63334	MAINSWITCH	63335	VELOFLIGHT	63336	LSPERAU
63337	FLATTENING	63340	NMPERAU	63341	AUPEREGUAT
63342	KMPERNM	63344	KYBRDSPEC1	63345	KYBRDSPEC2
63346	KYBRDSPEC3	63347	KYBRDSPEC4	63350	EXPNAME
63410	IDIENTPNT	63411	ID2ENTPNT	63412	MCPGM
63413	INTER	63414	COC0N	63415	RECRD
63416	ADSCN	63417	AESCN	63420	CORCT
63421	DYDMP	63422	CHCOR	63423	PRLOG
63424	CELCOMPGM	63425	DATANALYZE	63426	INTERCOM
63427	ACQUI	63430	RDMPTR	63431	CHPAR
63432	#FORD	63433	RDXXX	63434	PLANP
63435	TIMEP	63436	PL0TP	63437	AUT0T
63440	ID1RADIO	63441	ID2RADIO	63442	AZIMADD
63443	ELEVADD	63444	DOPPAD	63445	RANGEADD



TEOSTE\*10FEB66

SPURT OUTPUT NO. 111

ACQUI

LABEL	LOC	LABEL	LOC	LABEL	LOC	LABEL	LOC
A\$\$\$\$1111	02773	A\$\$\$\$1112	02774	A\$\$\$\$1113	02775		
ACGA	02056	ACGA1	02062	ACGAZIM	63071		
ACGLEV	63075	ACQI	63427	ACQUIONOFF	00057		
ACQUINIT	00002	ACQIMSG	02041	ACQUIMSG1	02046		
ACQUIRE	00000	ACQIRUN	00360	ACGY	02051		
ACGYCUBE	02053	ACQYSQ	02052	ACROSSCAN	00554		
ACTUALTIME	63142	ADSCN	63416	AEROXLINES	63507		
AESCN	63417	ALNGOFFSET	63517	ALGACRSCN	63506		
ANSWER1	00070	ANSWER2	00142	ANSWER4	00231		
ANSWERS	00246	ANSWER6	00306	ANSWER7	00324		
ARCOFAZIM	63524	ARCOFDEC	63526	ARCOFELEV	63522		
ARCOFRA	63530	ASTRODEC	63106	ASTRORA	63105		
ATTENTINIT	00034	AUPEREGUAT	63341	AUTOSWITCH	63025		
AUTOT	63437	AVGAZOCY	01273	AVGBCW	01222		
AVGL00P	01320	AVGROUTINE	01304	AZDIF20	00566		
AZDIF20SQ	00572	AZDIFM10	00565	AZDIFS	63120		
AZELOTIME	63532	AZELBXSCAN	63500	AZELIND\$	63162		
AZENTBIAS	00272	AZIM	63053	AZIMOFFSET	63512		
AZIMOUT	64000	AZIMOVER	63325	AZIMADD	63442		
AZIMERRORS	63027	AZIMIN	75000	AZIMSH	00470		
AZMTHSCAN	63501	AZPOINT	00575	AZT0G0WEL	01051		
AZTRACKERR	63022	BODYSIZE	63462	BACKUPSCAN	01633		
BACKUPWD	00162	BELOWHORIZ	00747	BLASTOFF	63146		
COC0N	63414	CONVERTIME	63135	CORCT	63420		
COSORIENT	63065	COSAZEL	63070	CAZIM	63060		
CELBODY	63113	CELCOMPGM	63424	CELEV	63061		
CELTIME	63133	CHOICE	00040	CHCOR	63422		
CHPAR	63431	CLBIASES	00210	CLEARCOUNT	01620		
CROSSCAN	00552	CRANGE	63057	CRSCW	00560		
CRSSOFFSET	63516	D0N0THING	00041	D0PP0UT	66000		
D0PPADD	63444	D0N0THANLYZE	63425	D0Y	63150		
DEC	63003	DECOFFSET	63515	DECD0T	63010		
DECLINSCAN	63505	DELCRSC	00555	DELRADIUS	01223		
DELTATEE	63316	DSECONDS	63141	DUMSECTTG	63154		
DYDMP	63421	ECROSSCAN	00553	ELDIF20	00570		
ELDIF20SQ	00571	ELDIFM10	00567	ELDIFS	63121		
ELENTBIAS	00273	ELEV	63054	ELEV0FFSET	63513		
ELEVOUT	65000	ELEVADD	63443	ELEVERROR\$	63030		
ELEVIN	76000	ELEVSH	00476	ELPOINT	00574		
ELTRACKERR	63023	ELVTNSCAN	63502	ENDANGLE	01022		
ENDAZ	00403	ENDFIT	01116	ENDSSC	00716		
ENDSSC1	00733	EQUATOR	63323	ESTSHIFTED	63143		
EXPNAME	63350	FIRSTELEV	63104	FIRSTTHRU	63153		
FIRSTLOC	01612	FITDENOM	00602	FITLIN	00604		
FITQUAD	00603	FIVEHUND	01234	FLATTENING	63337		
FRAMESIZE	63101	FREQUENCY	63317	GOODLSCNT	01217		
GEOCENLAT	63322	GEODETLAT	63321	GETAVG8	01261		
GMTMODU24	63145	GMTSHIFTED	63144	HOLDNONHOLD	63511		
HORIZTEST	00564	HOURMINUTE	63137	HOURREG	63151		
HEIGHT	63326	HSACQUI	00146	I	00561		
ID10RAD10	66777	ID11RAD10	67776	ID12RAD10	67777		
ID13RAD10	70775	ID14RAD10	70776	ID15RAD10	71776		

ID16RADIO	71777	ID17RADIO	72776	ID18RADIO	73777
ID19RADIO	73776	ID1CELCOR	65000	ID1ENTPNT	63410
ID1RADCOR	63050	ID1RADIO	63440	ID1RECRD	63210
ID1SYSENT	77576	ID1SYSNAM	77676	ID1SYSPAR	63310
ID1TIME	63130	ID20RADIO	73777	ID21RADIO	74776
ID22RADIO	74777	ID23RADIO	75776	ID24RADIO	75777
ID25RADIO	76775	ID26RADIO	76776	ID2CELCOR	63001
ID2ENTPNT	63411	ID2RADCOR	63051	ID2RADIO	63441
ID2RECRD	63211	ID2SYSENT	77577	ID2SYSNAM	77677
ID2SYSPAR	63311	ID2TIME	63131	ID3RADIO	63776
ID4RADIO	63777	ID5RADIO	64776	ID6RADIO	64777
ID7RADIO	65776	ID8RADIO	65777	ID9RADIO	66776
INOVERLAP	01475	INAZIMADD	63446	INELEVADD	63447
INITLOCSC	01563	INTER	63413	INTERAZCY	01277
INTERAZIM	72000	INTERCOM	63426	INTERDOPP	74000
INTERELEV	73000	INTERLCKSW	63460	INTERRANGE	76777
JUNK	00577	JUNKG	02647	JUNKY	02574
KIS0	01507	KIS1	01511	KIS2	01526
KIS3	01530	KIS4	01535	KMPERNM	63342
KTABLE	01502	KYBRDLEVEL	63110	KYBRDSPEC1	63344
KYBRDSPEC2	63345	KYBRDSPEC3	63346	KYBRDSPEC4	63347
LOCALSCAN	01473	LOCCHOICE	00330	LOCSONLY	00342
LOCSCABIAS	01225	LOCSCCOMP	01723	LOCSCCOMP1	01720
LOCSCFIAS	01227	LOCCK	01215	LOCSCTABLE	01235
LONGITUDE	63320	LASTEST	01572	LEFTSSCRP2	01622
LENGTH	01204	LENGTHIN	00745	LSPERAU	63336
MODESWITCH	63024	MAINSWITCH	63334	MARGIN	00467
MAXRADIUS	01224	MAXSCACC	01203	MCPFILLER	71000
MCPGM	63412	MILLSTNADD	63451	MINREG	63152
MSFREQ	63332	N	00562	NOINTERR	00052
NONOVERLAP	01441	NORP2PULSE	00421	NARBITRARY	01207
NEGI	01643	NEWMEAN	01553	NMPERAU	63340
NROUND	01210	POLE	63324	POSPOS	01672
PERIODAZIM	63523	PERIODDEC	63525	PERIODELEV	63521
PERIODRA	63527	PL0TAZIM\$\$	63020	PLOTELEV\$\$	63021
PL0TP	63436	PLANP	63434	PROGTABLE	00074
PREVIOUSTM	63461	PRINRECSW	63160	PRL0G	63423
PUTINCCW	00427	PUTINCW	00435	QUEST1	00060
QUEST2	00120	QUEST3	00105	QUEST4	00220
QUEST5	00235	QUEST6	00275	QUEST7	00312
RA	63002	RAOFFSET	63514	RAD0T	63007
RADARMODE	63312	RADCBXSCAN	63503	RADECOTIME	63531
RADIODEC	63541	RADIOMETER	63102	RADIORA	63540
RADINDIC	63157	RADIUS	63006	RADIUSD0T	63011
RAIUS	01221	RANGE	63052	RANGE00T	70777
RANGEADD	63445	RANGED0T	63062	RASCTNSCAN	63504
R00DIFS	63123	RBOXLINES	63510	RDIFS	63122
ADMTR	63450	RDXXX	63433	RECORDSIZE	63112
RECAZIM	67000	RECELEV	70000	RECFILE	63212
RECIPREV	01202	RECRD	63415	RECRDSWTC	63155
REFRACINDS	63161	RELEASESW	63156	REV	00466
RP2AVG2A	01211	RP2AVG2E	01230	RP2AVG8A	01212
RP2AVG8E	01231	RP2AVGLA	01214	RP2AVGLE	01233
RP2AVGSA	01213	RP2AVGSE	01232	RP2C0DE2	01215
RP2C0DE8	01216	RP2C0DEL	01220	RP2C0DES	01217
RP2C0UNT	02573	RP2CHANNEL	02575	RP2INTERPT	02577
RP2INTRJP	00343	RP2TABLEI	02063	RP2TABLE2	02327
RP2TABLEID	02576	SAZIM	63055	SC1	01027
SC10	01036	SC2	01037	SC5	00660

SC4	00672	SC5	00605	SCANACCN	00551
SCANLIN	00550	SCANMODE	00576	SCANPOINT	00563
SCC0S	00557	SCELTIME	63134	SCHCHOICE	00163
SCMINEL	01206	SCSIN	00556	SOEC	63005
SEARCH101	00726	SEARCHSCAN	00761	SECONDS	63140
SELEV	63056	SETBIASES	00252	SIDERTIME	63012
SIMULATION	00424	SINORIENT	63064	SINAZEL	63066
SKIP	63331	SLAVE	63126	SLAVEOPTS	63124
SLAVEMODES	63125	SORT	00504	SORTDEN	00573
SRA	63004	SRADTIME	63136	SSCANINIT	01134
STOPACQUI	00042	STARTAZ	00370	SYNCTIMING	63542
SYSOMREG1	63452	SYSOMREG2	63453	SYSOMREG3	63454
SYSOMREG4	63455	SYSOMREG5	63456	SYSOMREG6	63457
SYSENTRIES	77600	SYSNAMES	77700	SYSTAT1	63313
SYSTAT2	63314	SYSTATD	63315	TEMPST	00274
TEST1	00444	TEST2	00456	TEST3	00344
TEST4	00357	TEST5	00351	THIRD	02054
TIMECODE	00217	TIMECORR	63107	TIMECORRC	02055
TIMECORREC	00214	TIMEMODE	63103	TIMEP	63435
TIMETHOLD	63520	TRACKINDIC	63026	TRUERANGE	63063
TRUETIME	63132	TTYSTATUS	63111	TWOSECCOP	63017
VELOFLIGHT	63335	VIZDEC1	63014	VIZDEC2	63016
VIZRA1	63013	VIZRA2	63015	WEIGHTSUM	01226
WEIGHTT1	02650	WEIGHTT2	02721	WEIGHTTID	02646
WFORD	63432	WFACQUI	00156	WFADD	63450
WFFREQ	63333	WFHSACQUI1	01432	WFHSACQUI2	01445
WFHSACQUI4	00205	WFHSACQUI5	00336	WFHSACQUI6	00151
WIDTH	01205	WIDTHIN	00744	YEARMONTH	63147
YRTRAN	63327	ZRTRAN	63330		

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13. ABSTRACT  <p>Haystack Pointing System consists of hardware and software which points the Haystack 120-foot X-band antenna dish with great accuracies. The Satellite Acquisition program, described in this report, generates acquisition scans and searches for target returns. Once the target has been sighted, the program tracks the target by conical scanning. After acquisition, time correction can be made in the orbit computations.</p>			
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