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INFORMAL REPORT

A TAUT WIRE BUOY ARRAY
FOR ENVIRONMENTAL MONITORING
IN AUTECH

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INFORMAL REPORT

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ABSTRACT

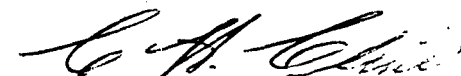
The Taut Wire Buoy Array (TWBA) of the AUTECH Environmental Monitoring Station has recently completed recording more than two years of almost continuous temperature and pressure data from 14 selected levels at a fixed site in the Tongue of The Ocean. This report covers some of the general aspects of the system, including: array description and operation, significant events of its existence, and data handling and programming.

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This report has been reviewed and is approved for release as an UNCLASSIFIED Informal Report.



Clifford H. Cline
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INTRODUCTION

It is the purpose of this report to call attention to a significant and unique prototype electronic system, the Taut Wire Buoy Array (TWBA), functioning in the Tongue of the Ocean as a permanently installed deep-water environmental monitor. In support of the Atlantic Underwater Test and Evaluation Center, the U.S. Naval Oceanographic Office sponsored installation of the TWBA in the Tongue of the Ocean (TOTO) at a point roughly eight miles east of Salvador Point, Andros Island. (Array 1 in Figure 1)

An important step was reached in the history of the TWBA, when in October of 1967 the system had collected more than two years of almost continuous temperature and pressure data. These data are available to those interested agencies or persons having a requirement for it. Closer study of these data applying electronic data processing methods is being completed, which will enhance and intensify our present knowledge about the time variations of temperature within the water column in TOTO.

The major task for NAVOCEANO in AUTECH is to define the oceanographic environment in TOTO so that meaningful interpretations can be made of test data from range operations conducted there. With the advent of this monitoring system prototype, a technological milestone has been reached, providing an abundance of high quality data, thereby enabling better comprehension of ocean environments.

The pronounced success of this monitoring array has since led to expansion of the system by the installation of two new arrays in September, 1967. The ramifications of system expansion and the increased advantage of synoptic environmental measurements in TOTO will be the subject of a later report.

Attention in this report will be focused on the general aspects of the original one-array system: system and subsystem description; chronology of significant events in contracting, developing, installing, and operating the TWBA, and data handling and programming.

ENVIRONMENTAL MONITORING SYSTEM

FUNCTIONS

The Taut Wire Buoy Array has 24 measuring instruments (21 temperature, 3 pressure) together with frequency multiplexing

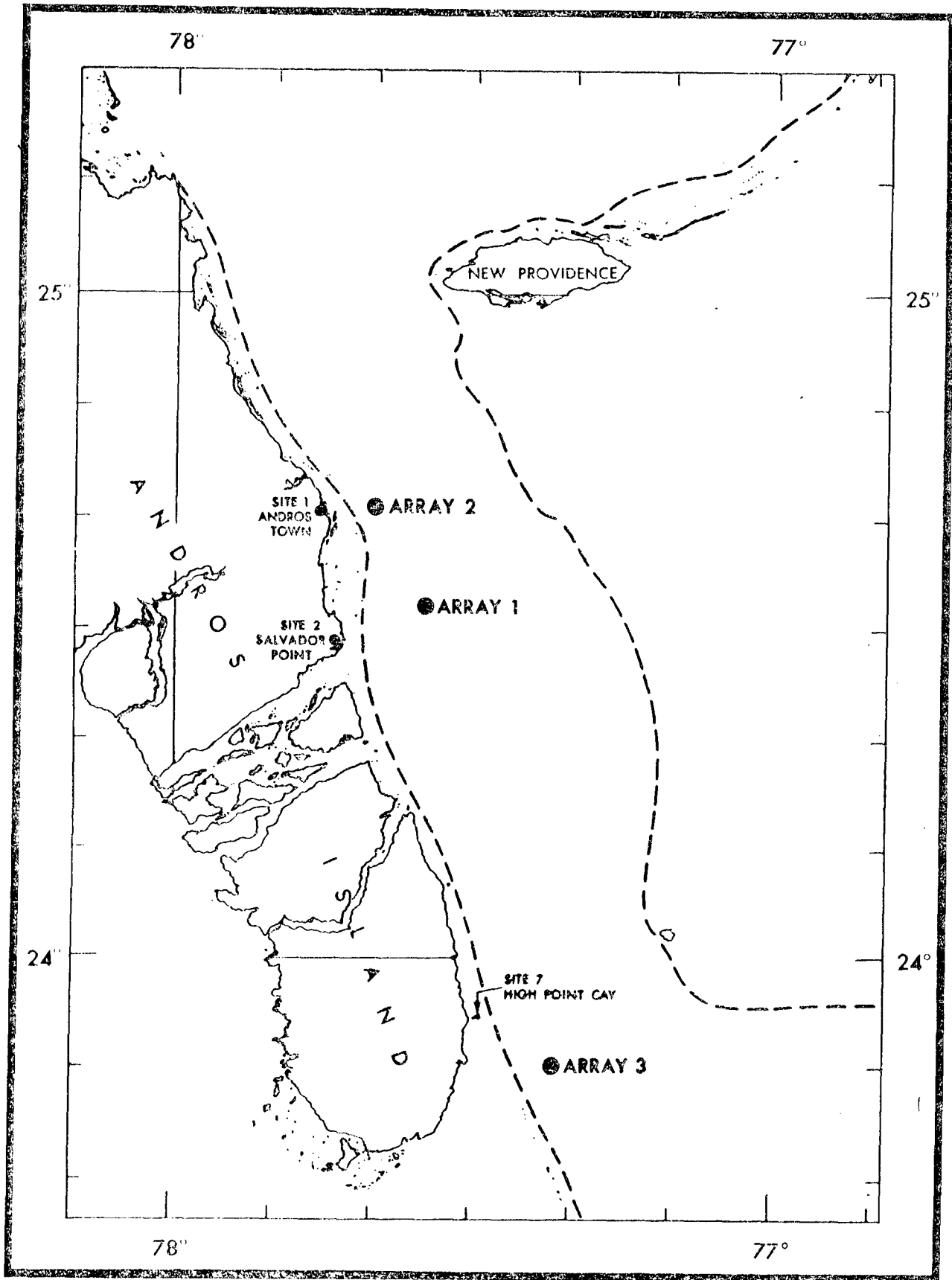


FIGURE 1 TAUT WIRE BUOY ARRAY LOCATIONS

units installed at 14 selected levels along a taut, vertical, armored coaxial cable in 1643 meters of water (Figure 2). Information gathered at the TWBA is transmitted along a 10-mile stretch of submarine coaxial cable to the shore station (Figure 3) near Salvador Point, AUTECH Site 2, where the data are normally recorded on magnetic tape and/or paper tape. When the tape recorder becomes inoperable only paper punch tape recording is possible. Direct print-outs can automatically be made simultaneously by means of an electric typewriter, a Friden Flexowriter in this case.

Output frequencies from the sensors are demultiplexed and processed to provide real-time digital data in standard metric units. These data are displayed visually on the preset frequency counters, while simultaneously being recorded and stored in a format for direct input to computers. The display of data for any depth may be monitored continually in a manual mode which provides sensor values every five seconds.

The date and time is entered on the record with each sequential scanning of the array. Incorporation into the system of a digital clock and calendar provides these and other manually controlled data.

The mode of sampling may be at 32, 16, 8, 4, or 2 minute intervals. Since the sequential sampling duration requires eighty-five seconds, the least possible sampling mode must be two-minutes. Level one through level fourteen respond in sequence when electronically scanned (Table 1). Temperature is recorded at all fourteen levels and, at each even-number level, a secondary sensor was attached for redundant temperature sampling. Pressure readings are sampled at levels 1, 3 and 8.

Sound velocities at 6 levels in the array configuration (level 2, 4, 8, 10, 13 and 14) were to be included in the data records. During the first array installation one velocimeter proved to not be operable and two others failed shortly afterward.

SYSTEM DESCRIPTION

Sensors

Table 1 gives the locations of all sensors in the array in depth from the surface at low water. Following is a description of the sensors:

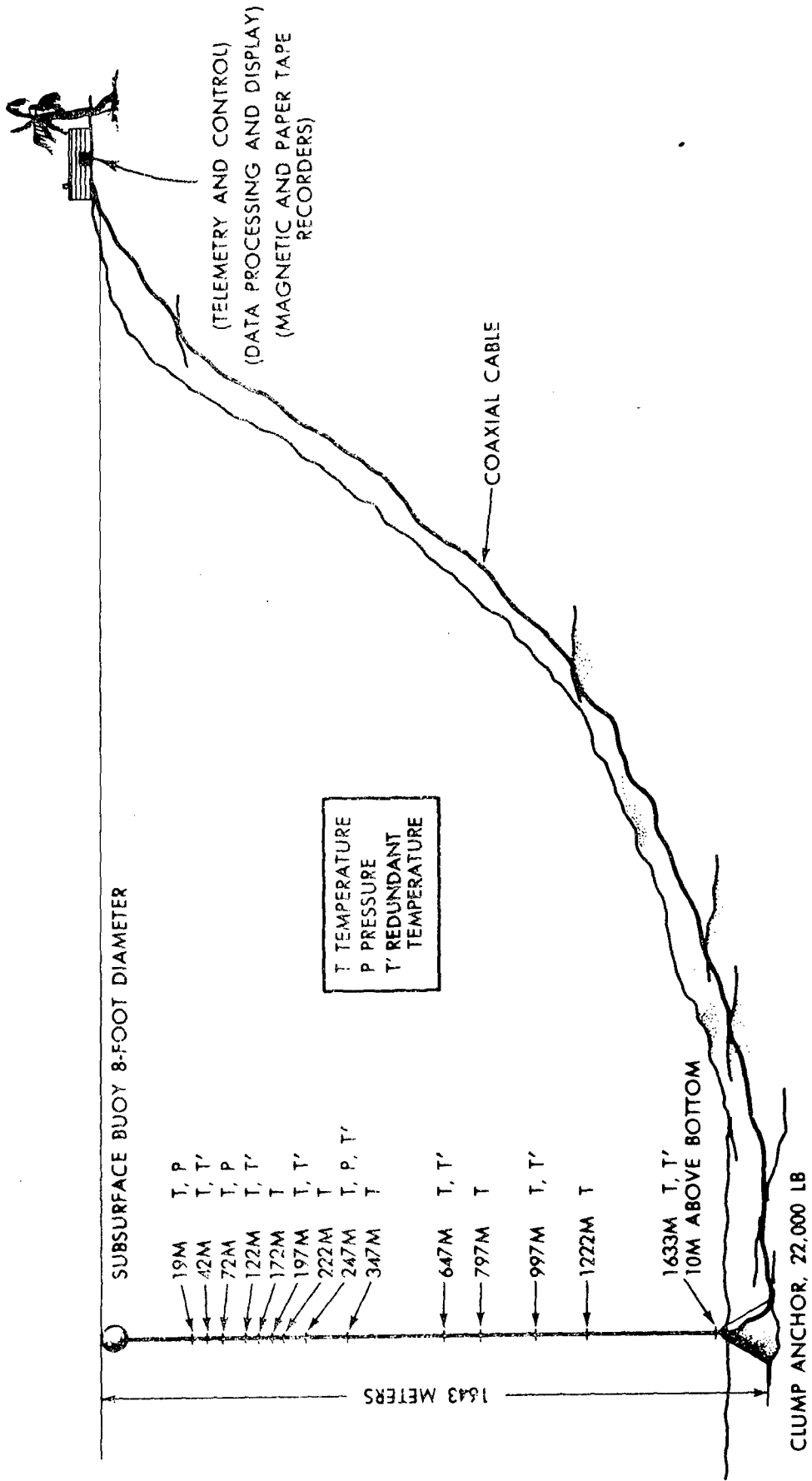


FIGURE 2 AUTEC ENVIRONMENTAL MONITORING ARRAY



FIGURE 3 AUTEC SITE #2 SHORE STATION

1. Temperature Sensors. Model 4003, manufactured by the Hytech Division of the Bissett-Berman Corporation, are the primary temperature sensors. These units employ a rapid response, platinum wire resistance-controlled telemetry oscillator operating in IRIG* subcarrier bands 7, 8, and 9. Located at all fourteen levels, they transmit information as FM signals. PARALOC**, an electronic circuit which converts the resistance of the platinum thermometer into a frequency corresponding to the temperature, is employed with all of the temperature sensors.
2. Secondary (Redundant) Temperature Sensors. Modified Model 4005 sensors (Hytech) operate in portions of IRIG bands 10, 11, and 12.
3. Pressure Sensors. Model 4004 WB sensors (Hytech) employ strain-gauge type sensors in conjunction with a resistance-controlled oscillator similar to that in the temperature sensor. The 19- and 72-meter units operate in IRIG band 11 with +9.75 percent bandwidth. The 247-meter unit operates in portions of bands 12 and 13.

At each of the fourteen levels on the array, telemetry units provide for group band-shifting of the sensor subcarrier tones upwards into suitable data transmission bands lying between 40 KHz and 285 KHz. Telemetry units are designed to minimize the possibility of generating interfering frequencies in the array should a malfunction occur. These units also supply regulated voltage to the associated sensors.

Array Physical Description

Buoyancy Tanks - One subsurface buoy (or buoyancy tank) provides the lift necessary to maintain tautness and stability to the array by maintaining a total net buoyancy of 26,600 pounds. Adequate tension for restricting the buoy to within a 50-yard scope at the subsurface float is based on a design current profile varying from 1 knot at the surface to 0.4 knots below 1000 feet. The top of the tank is 15 meters below the sea surface.

The tank, eight feet in diameter and spherical in form, is comprised of shaped, 1/4-inch welded steel plate segments, and is finished with four coats of zinc chromate primer and two

* Standard term in the electronic industry for a telemetry band

** A HYTECH registered tradename

TABLE I

Sensor Location, AUTECH Environmental Monitoring Array,
Salvador Point

Sensor Level	Sensor No. and Type*	Depth from Surface at Low Water	
		(Meters)	(Feet)
1	1(T), 2(P)	19	62
2	3(T), 4(T')	42	138
3	5(T), 6(P)	72	236
4	7(T), 8(T')	122	400
5	9(T)	172	564
6	10(T), 11(T')	197	646
7	12(T)	222	728
8	13(T), 14(P), 15(T')	247	810
9	16(T)	347	1138
10	17(T), 18(T')	647	2123
11	19(T)	797	2615
12	20(T), 21(T')	997	3271
13	22(T)	1222	4009
(Bottom) 14	23(T), 24(T')	1633	5358

*(T) Temperature, Hytech Model 4003 with Rosemont probe

(T') Temperature (Redundant), Hytech Model 4005 with Rosemont probe

(P) Pressure, Hytech Model 4004 WB with strain gage

coats of anti-fouling red vinyl paint. Two internal steel partitions divide the tank into three buoyancy sections, two of which can together provide sufficient buoyancy for the array. The buoyancy tank is shown in Figure 6.

Anchor - The anchor assembly is a reinforced concrete and scrap iron clump weighing 22,000 pounds in air and 17,000 pounds in water and it is connected to the array at the fishplate. A lowering line connected at this point, used to lower the array during final installation, was streamed out in a given direction from the array and dropped to the bottom. Future retrieval of the array will be achieved by first grappling this line. By bringing up the anchor assembly with this line, undue strain will be negated on the array cable and its components.

Transmission Cables - The array cable is a double-armored coaxial cable with a breaking strength of 38,000 pounds. An insulated solid copper core conductor with a return circuit of copper tapes constitute the electrical portion of the cable. At breakouts along the array cable are positioned the sensors with associated multiplex equipment, mounted in steel, cage-like enclosures.

Measures have been taken, both conventional and unconventional, to protect the array cable and its components against fouling and corrosion. Conventional means are employed, such as: zinc galvanizing, zinc anodes, and anti-fouling paint. The passage of D.C. current into the sea water through a special, nonconsuming electrode, composed of silver-alloyed lead, causes the release of poisonous chlorine gas to retard fouling - a most unconventional approach to the fouling problem. The toxicity of the gas released has affect only within inches of the electrode surface.

The array cable terminates at the fishplate assembly, the point at which it is spliced to the submarine coaxial (sea) cable (Figure 8). The anchor attachment hardware also is joined to the fishplate assembly.

The electrical portions of the sea cable and of the shore-end cable (the last cable link for transmission into the shore facilities) are of similar fabrication. These two cables were also spliced on shipboard, and the splice was lowered well seaward of the reef.

Toward shore, the more heavily armored shore-end cable is secured by bags of ready-mix concrete; and on shore, the cable is entrenched to its termination point.

Shore Station Electronics

The shore station equipment accomplishes six major functions:

- (1) demultiplexing;
- (2) sequential scanning of signals, level by level;
- (3) digitizing of sensor signals at each level in scientific (metric) units;
- (4) conversion of digital signals to required format for recording;
- (5) control of each of three recording devices;
- (6) timing and generation of time and identifying codes.

The entire array and shore station electronics is powered at the shore station by a 120-volt, single-phase, 60-cps utility power generator. Shore station electronics are housed at the instrument room in standard, six-foot electronics racks (Figure 5-center and right rack).

A pair of regulated power supply units (Trygon Electronics Inc. Model M 160-5A), connected in series, supply power for the array sensors and multiplex units. They provide a current capacity to 5 amperes at voltages up to 320 volts, though the array normally runs on 3 amperes at 225 volts.

Frequency multiplexed signals coming from the array pass through a power separation filter which separates the array signals from the D.C. power. Array signals then pass to a bank of relays which, under control of the timing logic, connect the desired signal separation filter. These filters, identical to the ones used in the array multiplexer units, separate the sensor signals from one another and from unwanted demodulation products. Signals are then applied to the appropriate digitizing counters to be read as input data.

Data Processing Subsystem

Input data, consisting of time and day of the year, auxiliary data (inserted by manual thumb-wheel switches), record number, and the temperature and pressure readings from the TWBA, are presented to the tape recorder and Flexowriter in binary coded decimal (BCD) form and are visually displayed in decimal numbers. The six-digit record number derived from a stepping switch counter, the day-of-the-year, and the time in hours and minutes begin each readout cycle. The time, in hours (to 24), minutes and seconds is derived from a one pulse-per-second input supplied to a Parabam digital clock. A one pulse-per-day input is supplied the Parabam digital calendar for the year. Three digits for the day of the year, two for the hour, and two for the

minutes give a total of seven digits in the date-time group.
(Appendix I)

As the recording cycle is synchronized with a two-minute period, the time is recorded once each two-minute period on the exact minute at which the scan cycle begins.

The actual measured temperature and pressure readings are sampled in sequence from level 1 through level 14. These parameters are displayed on HP Model 5214L preset counters, which convert the presented input frequencies to BCD output in scientific units. Five digits of information are recorded from each counter, alternately interrogated.

Two basic modes of operation provided by the data processing subsystem are "record" and "playback".

RECORD MODE - With the sequential readout of the entire array in record mode, data from the digitizing counters are read, reformatted, and recorded on magnetic tape and/or punched paper tape, and/or a Flexowriter listing. The desired repetition rate of array scan for maximum data output is two minutes. A pinboard programmer, however, allows selection of any or all data for printout at any of the five selected rates: 2, 4, 8, 16 or 32 minutes.

Five seconds are allowed at each level for the digital display on the preset counters and the recording, both on tape or by the Flexowriter, of two six-digit data words. The program control subsystem switches the data, one word at a time, from the counters and is presented, one character at a time, to the tape recorder and to the Flexowriter.

In order to make individual sensor checks, a "manual" switch is thrown which permits the observation of data from any level without recording it. In the manual mode, new data are digitized each five seconds.

PLAYBACK MODE - Previously recorded data may be reviewed by playing the data back through the Flexowriter in the same format as it was recorded. Following the printing of each character, the Flexowriter signals the tape recorder that it is finished. The recorder then reads out another character, concurrently generating a command for the Flexowriter to print it. The Flexowriter will print the data at the maximum operating speed of 9.6 characters per second. Figure 4 shows in simplified form how the data flows through the data processing subsystem.

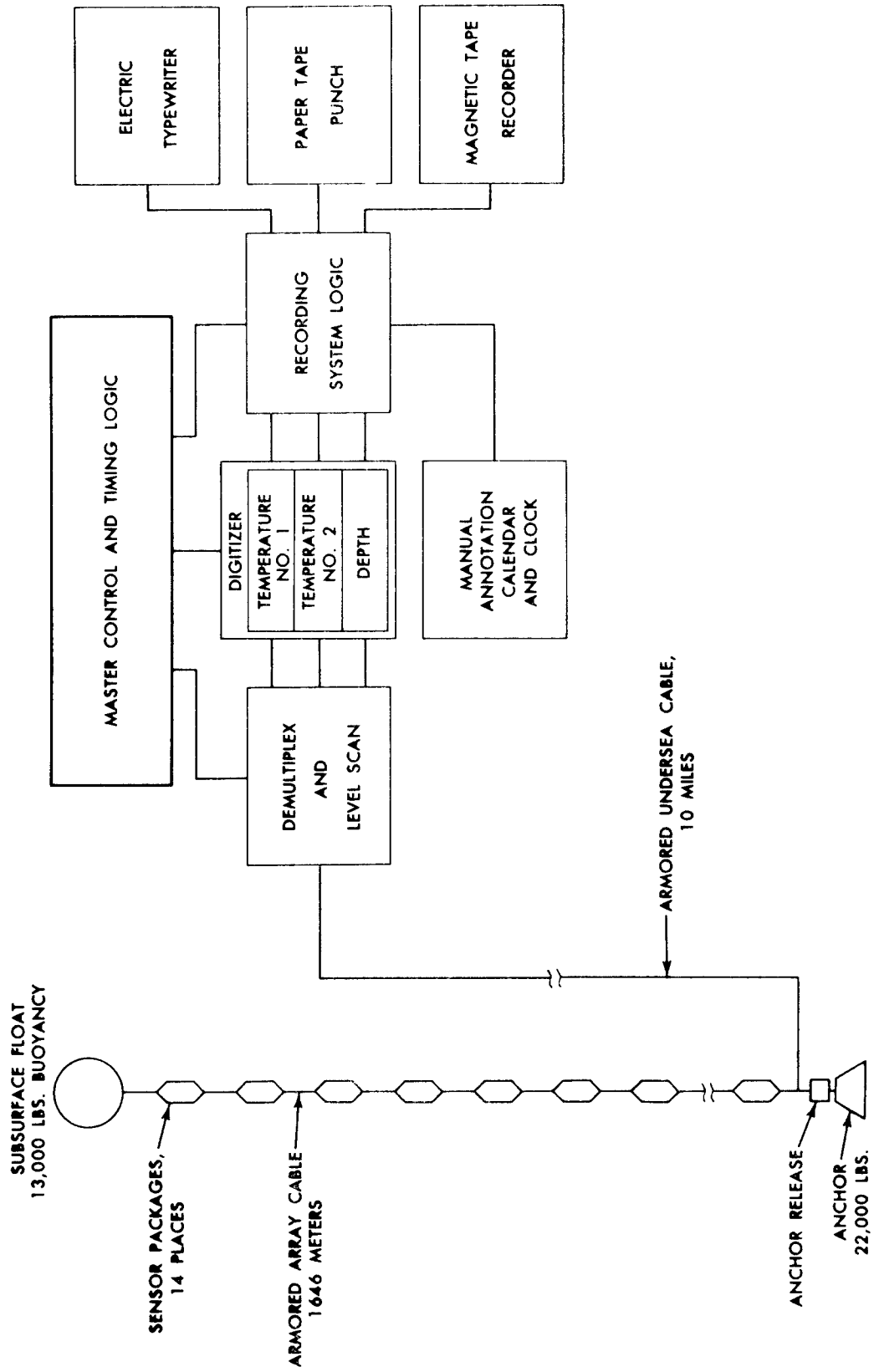
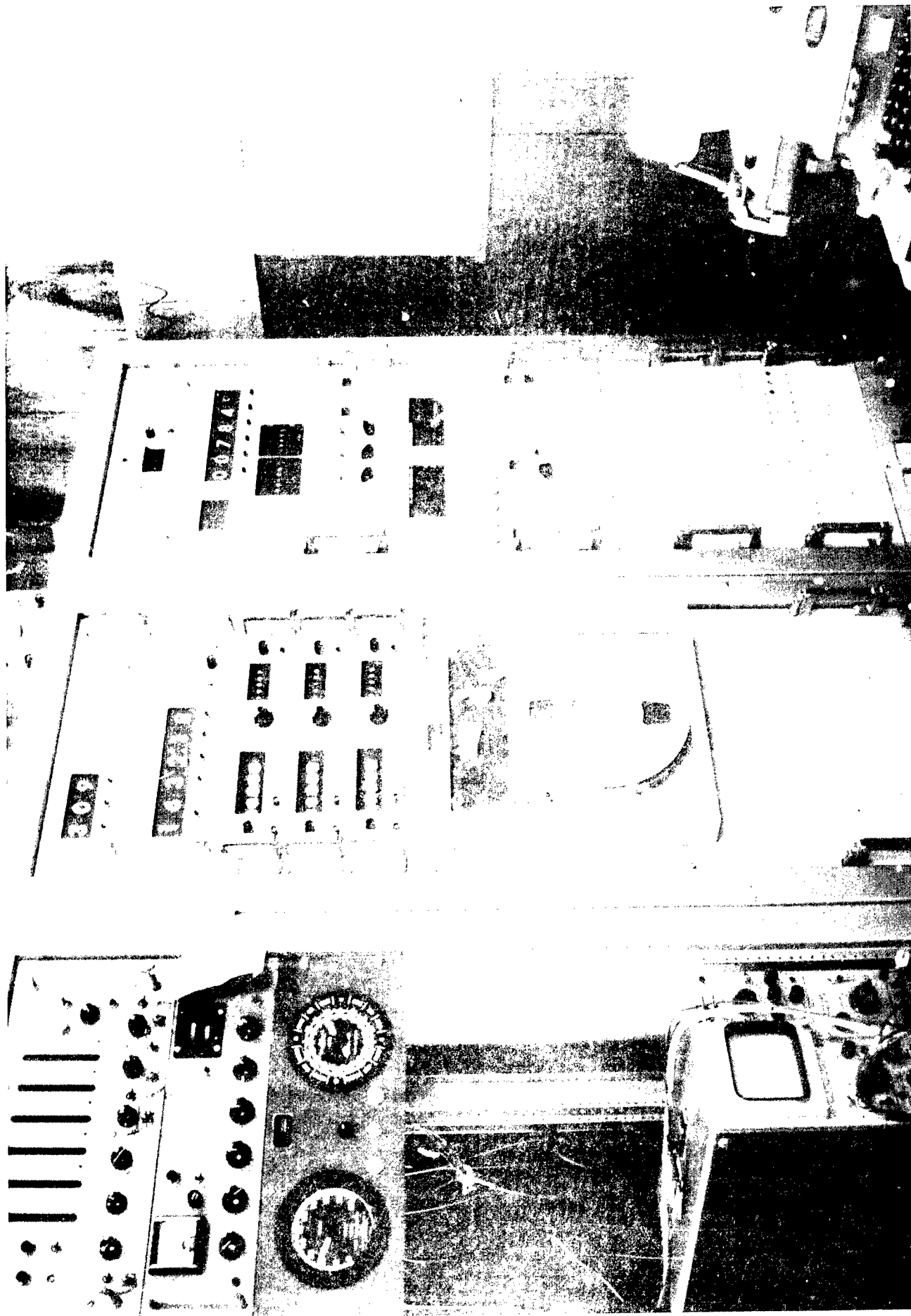


FIGURE 4 TAUT WIRE BUOY ARRAY, SIMPLIFIED BLOCK DIAGRAM

FIGURE 5 TWBA SHORE STATION INSTRUMENTATION



MONITORING STATION

The AUTECH Environmental Monitoring Station is located at AUTECH Site 2, just adjacent to Cargill's Wells Settlement, and a few hundred yards north of Salvador Point. Two trailers, a laundry shack and a generator building comprise that part of Site 2 occupied by NAVOCEANO personnel.

Two NAVOCEANO personnel man the station at any one time, an oceanographer and an electronic technician. A scarcity of personnel frequently necessitated substituting of physical science technicians for oceanographers.

It is the primary duty of the oceanographer to monitor and make an evaluation of data from the TWBA. He makes daily validity checks of temperature and pressure data for all sensors, relying upon an "envelope" of historical data for comparison. He makes comparisons of data from redundant temperature sensors to provide additional information on sensor performance. The oceanographer may interrupt automatic sampling at any time in order to intensify surveillance of certain sensors during the data validity checks by placing the system in "manual" mode.

Secondary functions for the site oceanographer are maintaining a weather station and making weather and supplementary oceanographic observations. Standard meteorological instruments, i.e., hygrothermograph, microbarograph, rain gage, and anemometer, are located at the site for the purpose of recording air temperature, relative humidity, amount of precipitation, and wind speed and direction. Cloud type and amount are also recorded during observation times. A bubbler tide gage installed in the instrument room continuously records sea level variations in the site turning basin. The tide graph is annotated daily in order to check the clock mechanism in the tide gage recording system. A fixed tide staff provides a rough visual calibration factor with which the oceanographer can determine tide gage accuracy in recording tide height. The site oceanographer makes his observations at 0700, 1200, and 1700 hours daily. At these times, he also measures the sea surface temperature in degrees Fahrenheit using a simple bucket thermometer.

The duties of the electronics technician are basically to maintain all electronic equipment, primarily the shore electronics for the TWBA, and to assist in site maintenance. When drifting occurs between redundant temperatures, or a sensor malfunctions, he runs frequency checks at each sensor to verify malfunction.

The site personnel also give support to other NAVOCEANO personnel involved in duties that include functions at Site 2, providing this service does not in any way interfere with their own mission.

Since the installation of a telephone by RCA, site personnel can more easily arrange for supply delivery to Site 2. Boat and, less often, helicopter are the means of transportation used to supply the site, always a troublesome activity. Prior to telephone installation, site personnel had to arrange travel to Fresh Creek to order supplies and to phone NAVOCEANO. These inconvenient trips often were difficult to arrange besides being time-consuming. With telephone communications now available at Site 2, the necessity for leaving the monitoring station has been kept to a minimum.

SIGNIFICANT EVENTS

BACKGROUND

Prior to the installation of the environmental monitoring array, NAVOCEANO's efforts in support of the projected AUTECH Range had been dependent upon shipboard operations. NAVOCEANO's responsibility to define and document the ocean environment for AUTECH by shipboard methods required frequent surveys in both the Tongue of the Ocean and Exuma Sound. Operations were either acoustical, hydrographic, geodetic, or oceanographic in nature, or a varying combination of all or some of these. They sampled and measured certain parameters employing methods ranging from those considered of a classical nature to others of a high degree of sophistication.

Short-term variations in physical properties in excess of what previously had been considered possible led to the initial concept of a permanent monitor for certain parameters in TOTO. G.S. Ruggles pointed out in his IHR, "Periodic Variations Within the Water Column in the Tongue of the Ocean, Bahamas", that two independent sets of data, March 1962 and May 1962, definitely show that the time rates of change of a parameter which characterize long-period fluctuations at a given level are much less than the time rates of change attributed to the ebb and flow of the tide". He advocated an effort to develop a permanently installed oceanographic monitoring system that would permit recording both short-term and long-term changes in oceanographic and acoustic parameters.

From studies based on data collected from ship operations, apparent amplitudes and phase relationships of temperature

variations were documented, and, on this basis, sensor depths were later selected. It was found necessary to locate the sensors in horizontal layers providing optimum results. Determination of aperiodic vertical displacement of horizontal layers and the extent of migration would thus be made possible.

Project AUTECH*deemed it advisable in mid-1963 to prepare a formal requirements specification for the Taut Wire Buoy Array.

CONTRACT HISTORY

Actual contract development began on 3 May 1963 when NAVOCEANO solicited fixed-price technical and cost proposals in accordance with NAVOCEANO's performance specification ID-DE-0442 (dated 15 March 1963). In response, fifteen companies submitted technical proposals for evaluation. The technical proposals contained detailed information on specific sensors and the system design that would furnish NAVOCEANO its required data.

An evaluation panel consisting of NAVOCEANO technical personnel was appointed on 31 July 1963 to evaluate the fifteen proposals that had been received. The three companies that had submitted technically feasible proposals were selected for further negotiations by the contracting officer. Cost negotiations ensued and on 23 December 1963 the contract was awarded to the Martin Company (later assigned to the subsidiary company, Bunker-Ramo) for the lowest priced, technically qualified offer. The promised delivery date was to be exactly six months later, on 23 June 1964.

During the following months, a demonstration of systems workability was viewed at the contractor's plant by NAVOCEANO personnel. The cable and sensors had been earlier subjected to a test pressure of 3000 psi at the David Taylor Model Basin with no apparent malfunctioning.

INSTALLATION

Initial Implantment

On 22 July 1964 the array was installed, initially touching down in water 60 feet deeper than the design depth of 5400 feet. The array was lifted and moved, however, into a shallower depth where allowable depth tolerances on the flotation buoy were encountered. The submarine cable was laid to a point just seaward

*Project AUTECH refers here to NAVOCEANO's effort in TOTO.

of the Andros Barrier reef on 22 July. Cable laying from seaward of the reef to the shore facilities was accomplished on 23 July 1964, and the two submarine cables were spliced by the 24th.

Upon immersion, one temperature sensor and a sound velocimeter failed. The remaining two sound velocimeters failed subsequent to implantation. Power supply and tape recorder malfunctioning plagued the system during three weeks of intermittent operation until it ceased to operate entirely on 19 August. On both the 19th and 29th of August, attempts were made to "bake out" intermittent short circuits in the system by applying a current overload, but this did not remedy the situation. On 1 November 1964, the array was retrieved by Bunker-Ramo and shipped back to the plant for refurbishing.

Second Implantment

A second implantment of the TWBA was made in April 1965, after factory rework. All sensors performed for a period of approximately twelve hours before a short developed in the array cable at the breakout for sensor level nine. The array was immediately retrieved and efforts were made on site to repair the malfunction. The attempts were unsuccessful, however, and the array and sea cable were entirely recovered and returned for additional rework.

Final Implantment

The AUTECH TWBA was finally implanted on Thursday, 21 October 1965. This implantation, in a depth of nearly 5400 feet, at last provided NAVOCEANO with an operating deep-water environmental monitoring system.

The period from 6 October to 18 October was spent in preparing the array for installation, with actual implantment commencing on the morning of 18 October. Three ships were required for the operation: the cable ship, WESTERN UNION, which was the control ship; the H.J.W. FAY; and the H.G. WILLIAMS, a tug.

The array cable was played out over the port side of the WESTERN UNION and towed away by the support vessel, H.J.W. FAY (Figures 6, 7). Flotation devices kept the array buoyant until the entire array cable was stretched horizontally between the two ships. The fishplate (Figure 8), termination point for the array and sea cables, was passed from the WESTERN UNION to the tug, H.G. WILLIAMS. The H.G. WILLIAMS then lowered the cable and sea anchor with a lowering line while the WESTERN UNION played out the sea cable. Monitoring sensor frequencies along the cable from the deck of the WESTERN UNION, after placing of the array on the bottom, showed the system to be

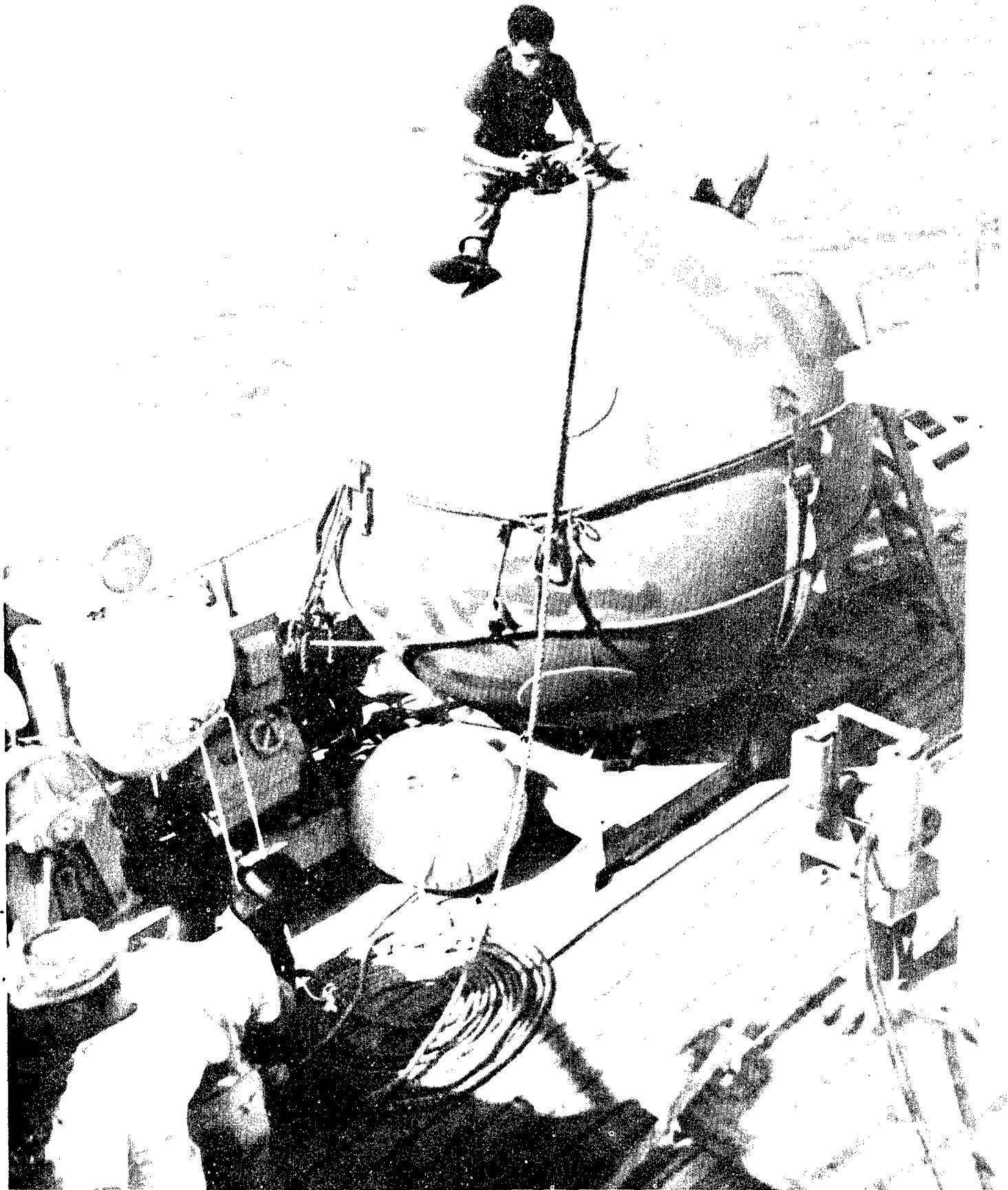


FIGURE 6 BUOYANCY TANK

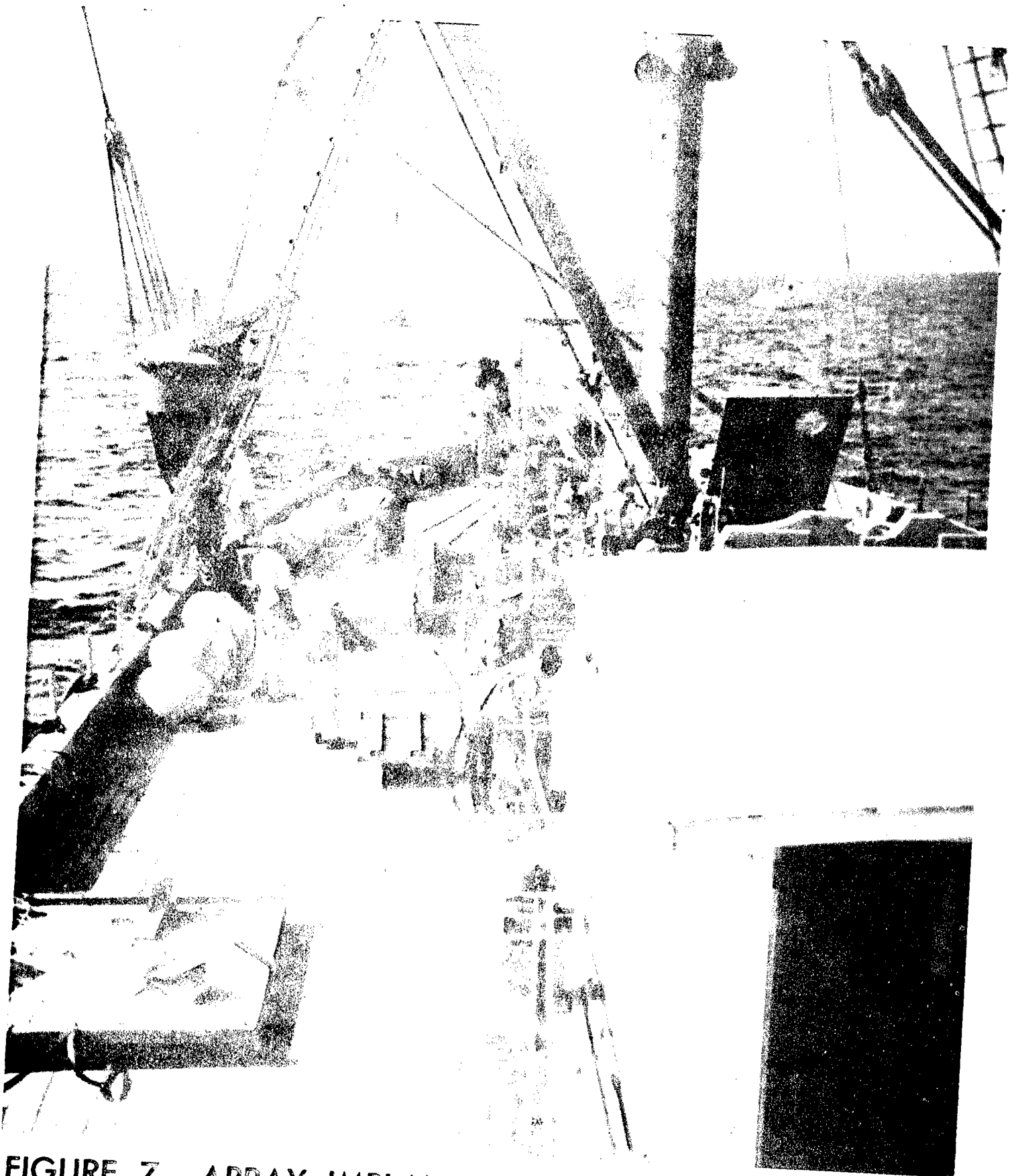


FIGURE 7 ARRAY IMPLANTMENT—H.J.W. FAY TOWING
AWAY ARRAY CABLE

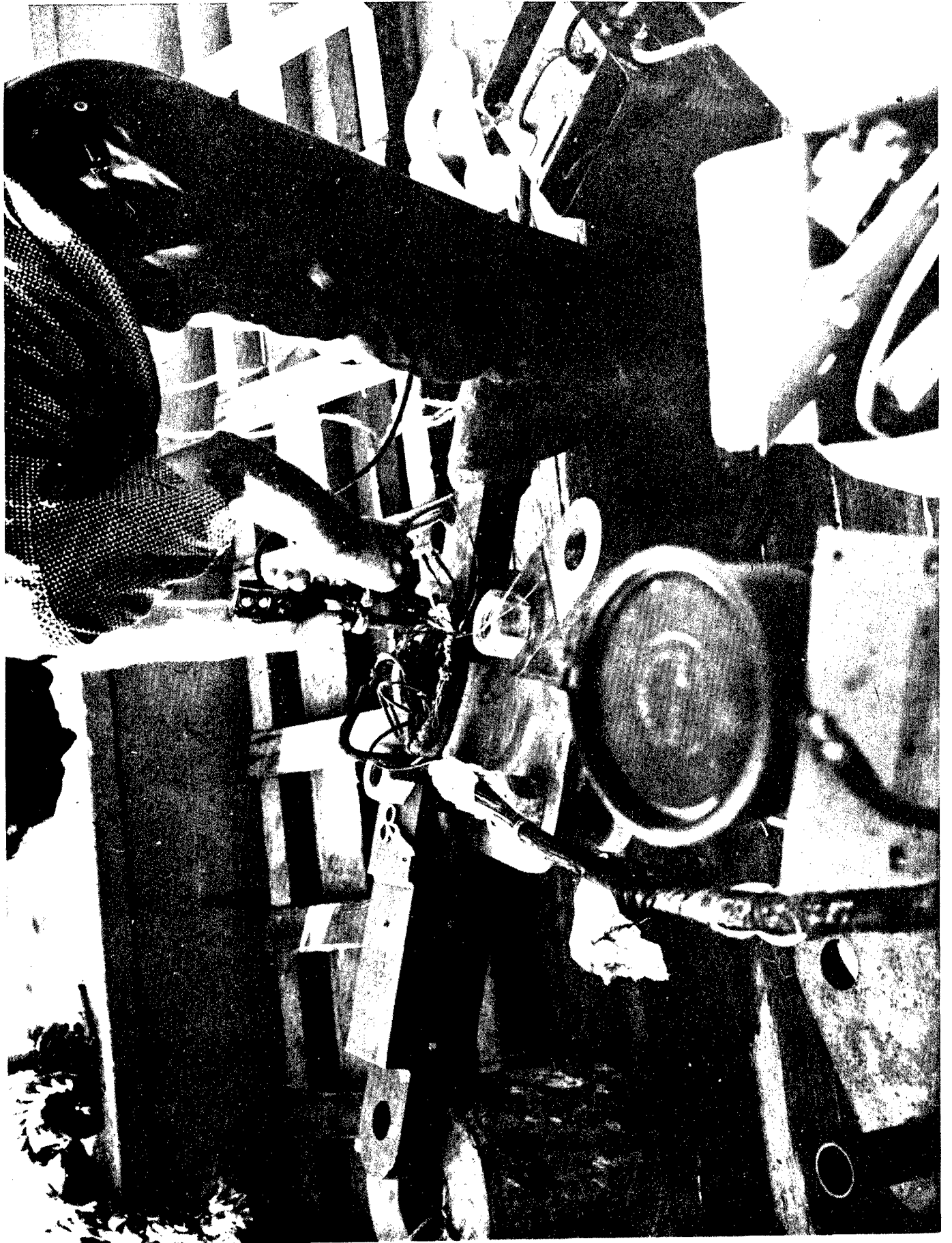


FIGURE 8 SPlicing OF ARRAY AND SEA CABLES

100 percent operational. Following this check, the remaining seven miles of sea cable was laid toward the shore station at Site 2. Splicing the shore and sea cables was completed at 2400 hours on 21 October, thus terminating the implantment operation. From that time on, all monitoring was performed at the shore station.

Some sensor failures and data handling problems occurred during the ensuing forty-five day acceptance period; however, the system continued to operate within the limits of acceptance performance. Among problems occurring within the data handling system were: the data sampling rate controls not sequencing properly, and the tape recorder failing to operate in the play-back mode.

OPERATION

SENSOR ENDURANCE

The TWBA temperature and pressure sensors have been remarkably reliable and consistent since installation. Of the 24 sensors on the array, 17 still function properly and only 6 have not lasted. The Sensor Endurance Bar Graph (Figure 9) shows the functional duration of all sensors through February 1967. Broken bars indicate erratic operation; solid bars indicate operation at an acceptable performance level.

Reasons for sensor failure may be inferred, but definite conclusions would be impossible to make without first examining the sensor and break-out area. The inaccessibility of the underwater portion of the array makes it impossible to inspect the suspect individual sensor when a failure is discovered. Recovery and overhaul are excessively costly operations that must be restricted to total or near-total array failures.

All of the six temperature sensors that failed did so within the first six months in the operational period of the system. The last sensor to give out was sensor 4 at level 2, which had been drifting and functioning erratically until it ceased operating on 20 June 1966. Both temperature sensors at level 6 failed on 13 April 1966. Sensor 21 at level 12 stopped on 26 January 1966. Also, on 6 November 1965, sensor 12 at level 7 failed. Though sensor 24 at level 12 functioned properly when monitored from the deck of the WESTERN UNION during installation procedure, it did not do so when monitoring commenced at the shore station. There is no data record, therefore, from sensor 24.

It appears that, unless marine fouling or more catastrophic events soon occur, the marine environment has determined the "survival of the fittest" of these sensors. From all indications the system has essentially stabilized itself, and it should continue operating at an acceptable level of performance for some time.

SENSOR ACCURACY

All sensors were pre-tested in a laboratory tank to prove capability of the sensors to operate accurately under pressure conditions simulating those encountered in the sea.

The total loss of sensor data within the accuracy specified ($+0.05^{\circ}\text{C}$ for temperature sensors; $\pm 0.25\%$ of full scale for pressure sensors) defines "sensor failure". Conversely, all sensor data collected within these limits defines sensor accuracy. This definition, established in the contract for the 45-day test period, leaves no question of marginal sensor operation; the limits are very clearly defined. Yet, to expect absolute conformity to these accuracy specifications is nearly impossible.

Temperature sensors are declared to be operating accurately if the output values conform to the range of historical values appropriate to that sensor depth. Accurate operation of pressure sensors is declared if (1) output values remain conformable to expected values based on the knowledge of approximate buoy depth, or (2) the relative depth readings of two pressure sensors clearly conform to the design dimension (\pm allowable errors) between the two sensors.

An even more important determination of sensor accuracy is predicated on performance with time. The time concept implies consistency and stability in sensor operation and will be approached separately for both temperature and pressure sensors.

TEMPERATURE SENSOR STABILITY

A consistent departure of greater than 0.10°C in corrected temperature values at levels of redundancy defines a failure of one or both sensors at that level. Clearly, a satisfactory degree of accuracy of the entire array with time is suggested by adequate conformity with this standard over all the levels of redundancy.

One way of graphically demonstrating the maintaining of accurate operation of the TWBA is to show statistical consistency between temperature values at redundant levels- (See figure 10). By plotting the standard deviation from the mean

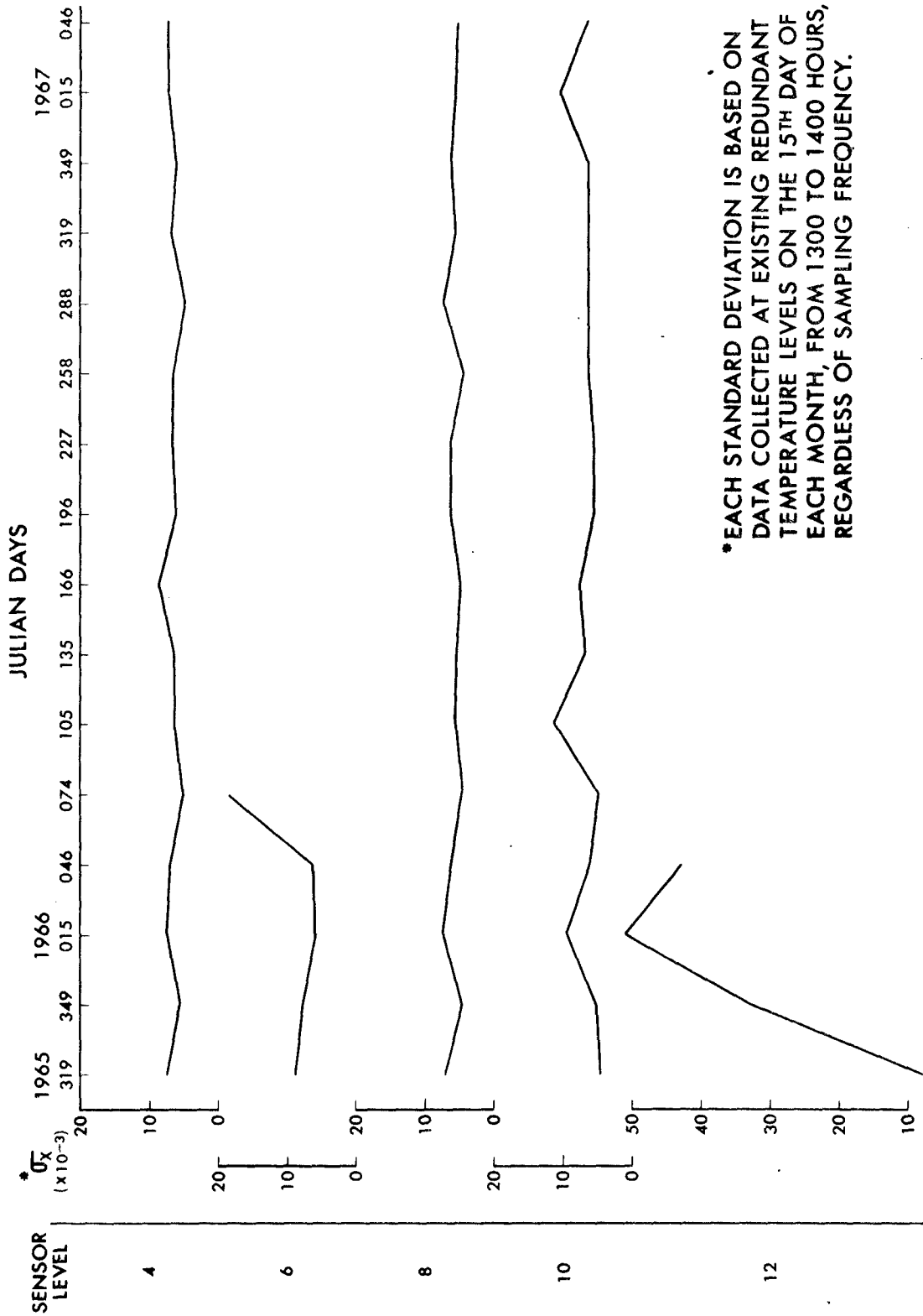


FIGURE 10 STANDARD DEVIATIONS FROM THE MEAN OF REDUNDANT TEMPERATURE ($^{\circ}\text{C}.$) DIFFERENCES

of one-hour temperature differences per month (1300-1400 hours on the 15th day of each month was selected) from November, 1965, through February, 1967, this consistency can be shown.

Dispersions about a mean temperature difference maintain consistency throughout this 14-month period as demonstrated by temperature sensors at levels 4, 8, and 10. At level 6, both sensors failed on 13 April 1966. The sudden positive gradient occurring between (Julian) days 046 and 074 reveals sensor trouble. At level 12 a steep positive gradient occurring from the outset results from difficulty with sensor 21. As it drifted, the dispersions about the mean temperature difference grew increasingly large.

In calculating the means for days 074 and 166, 1966, only eight differences were averaged as compared to thirty for each of the other days. Fewer values were available for that same hour as the array was operating on the 8-minute sampling mode rather than on the 2-minute mode. The results, though representing fewer samples, seem equally valid in presentation.

Note that for levels 4, 8, and 10, almost all of the dispersions fall between 0.007 and 0.010°C, maintaining consistency throughout.

PRESSURE SENSOR STABILITY

The only way of making a continuous accuracy check of the pressure sensors of the TWBA is to employ methods based on pressure reading differences. There is no "envelope" of historical data upon which to compare pressure readings for validity as there is for temperature data. Only the constancy of pressure differences between sensors over long periods is truly indicative of stable pressure sensor performance.

Pressure data in decibars from the 316th day of 1965 at 0000 hours were used to determine how accurately the pressure sensors were positioned on the array (Table 2). The results may be used as a reference for future pressure data as it can be assumed that positions on the array cable will remain constant. The corrected value at each level was used to arrive at an estimated actual geometric depth, which compares favorably to the depths as planned in the array construction. Table 2 lists the results of calculations: Standard Geopotential Depth, Estimated Geopotential Distance from the Surface, and finally, Geometric Depth.

Starting with the corrected pressure reading at level 01, 19.52 decibars, one can follow through the table to determine

TABLE 2

PRESSURE SENSOR DATA

1. Data Selected: Time 0000 hours (mid-tide range), Day 316, 1965

Level 1 reading 19.50 + 0.02 correction = 19.52 decibars

Level 3 reading 72.92 + 0.18 correction = 73.10 decibars

Level 8 reading 251.0 - 0.10 correction = 250.0 decibars

II. Comparisons

A. Depth Estimations		LEVELS	1	3	8
STANDARD GEOPOTENTIAL DEPTH (dynamic meters)			18.99	71.09	243.0
ESTIMATED GEOPOTENTIAL DISTANCE FROM SURFACE* (dynamic meters)			19.03	71.27	243.7
ESTIMATED GEOMETRIC DISTANCE (meters)**			19.41	72.70	248.6
ARRAY CONSTRUCTION PLAN (meters)			21.4	75.0	248.6
B. DIFFERENCES		LEVELS	1 - 3	3 - 8	1 - 8
PRESSURE (decibars)			53.6	176.9	230.5
STANDARD GEOPOTENTIAL (dynamic meters)			52.1	171.9	224.0
ESTIMATED ACTUAL GEOPOTENTIAL (dynamic meters)			52.2	172.4	224.7
ESTIMATED ACTUAL GEOMETRIC (meters)			53.3	175.9	229.19
CONSTRUCTION (meters)			53.6	175	238.6

* Obtained by using the equation: αdp , the Hydrostatic Equation. The average Specific Volume in the upper layer reported by Magnitzky and Fréñch (Ref. 2) is 0.9749.

** Sverdrup, Johnson, and Fleming approximate the geometric depth should be 1.02 times the Geopotential depth: (19.03) 1.02 = 19.41 meters.

the estimated actual geometric depth, 19.41 meters.

First, employ table II of "The Oceans" (p. 1054) and interpolate to obtain the Standard Geopotential Depth, 18.99 dynamic meters, a value that would exist in an homogeneous ocean at 0 °C. and 35‰ salinity.

Second, the Estimated Geopotential Distance from the Surface is determined by αdp , the Hydrostatic Equation. The average value of specific volume (α) is reported by Magnitzky and French (ref. 2) to be 0.9749. The Estimated Geopotential Distance from the surface is 19.03 dynamic meters.

Third, Sverdrup, Johnson, and Fleming relate both the approximate geometric depth and the standard geopotential depth to pressure in decibars. 990 meters (geometric) is equivalent to 970.4 meters (geopotential). This leads to the approximation that geometric depth should be 1.02 times the geopotential (The Oceans, p. 1054). This factor times 19.03 gives us the geometric depth of 19.41 meters. For level 03 and level 08, the same procedure is followed.

Table 2-B reveals the close comparisons of planned positions of sensors in the array to the calculated results. These small differences between derived depths and the construction plan depths can be explained by a combination of sensor error, cable measurement error, and variations in cable strain.

ARRAY DATA

CONTINUITY

Data from the TWBA may set precedent as a record amount resulting from the operation of any permanently installed, buoyed environmental monitor. Data collected since the successful reinstallation of the array, aside from being abundant, is of high quality. The continuity of the data is marred, however, by gaps resulting mostly from system shut-down, whether voluntarily or involuntarily.

Voluntary shut-down of the TWBA occurs for the following reasons: (1) switching to another generator for power source; (2) closing up the station during times of natural disaster, i.e., hurricane, floods, etc.; (3) changing magnetic tapes. Involuntary shut-downs, which cause the greatest record loss, occur when: (1) the array fails or malfunctions; or (2) the generator fails or malfunctions.

Other gaps may show up in the data record for reasons unrelated to system stoppage, such as: (1) running checks or tests on the equipment, (2) running sensor checks (system on the manual mode provides no data record) and (3) playing back the tape. In these cases the array is in operation but not in the "record" mode.

The cause of most recording time lost lies with the generators which originally supplied power to the array. Normal wear has been the greatest source of trouble with generators. The most common of these have been: worn brushes, faulty fuel pump, electrical wire disconnects, corroded commutator, clogged fuel line, and fuel leaks.

Troubles arising from the TWBA also create gaps in the data record, especially when parts replacement time is involved. For example, in late December 1966 and early January, 1967, much of the record was lost in waiting for a power supply replacement.

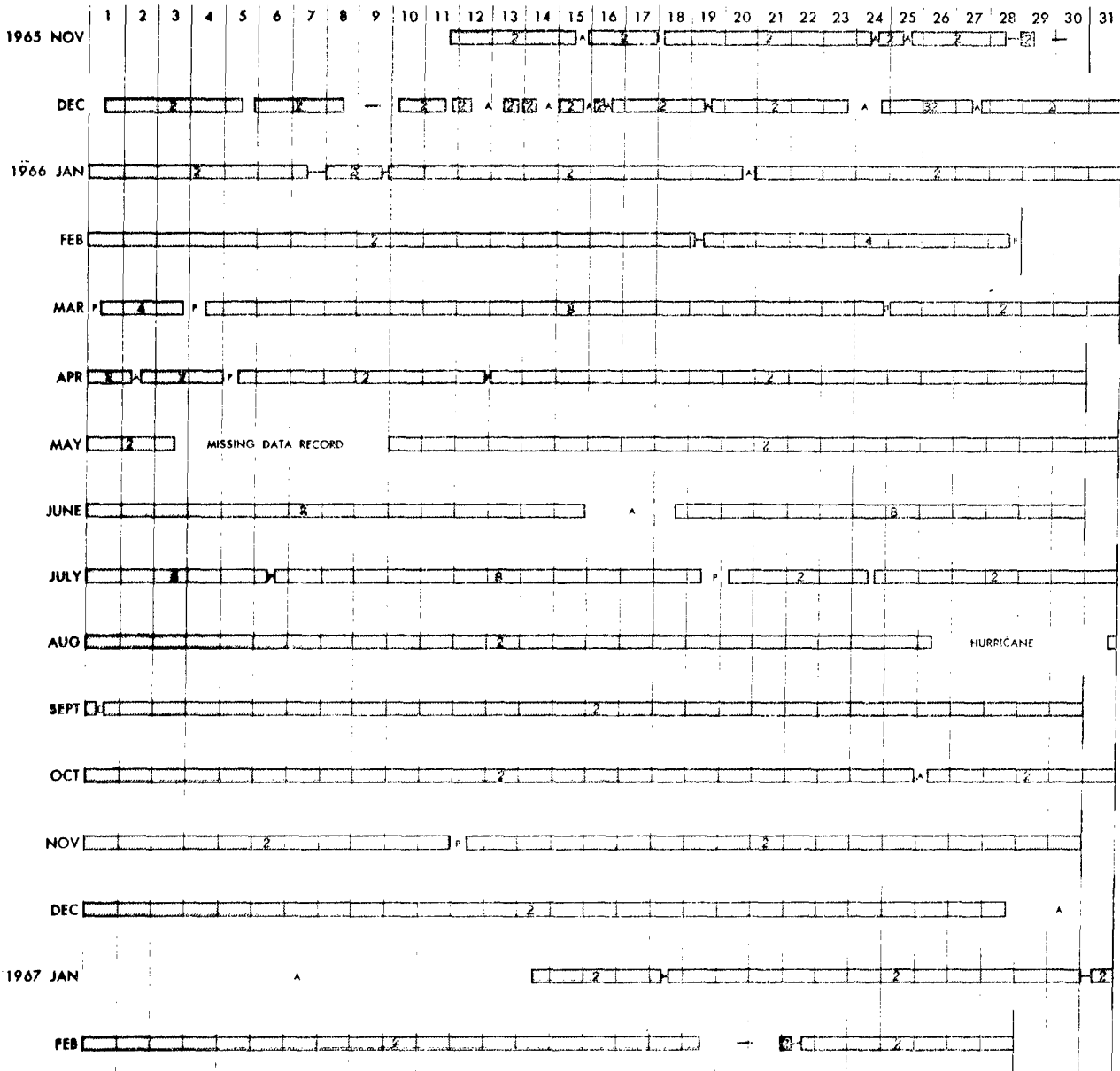
Most of the troubles arising in the array came from within the recording subsystem, such as: faulty logic cards, malfunctions in the stepping mechanism for demultiplexing of array signals, relays burning out, and a variety of problems with the Flexowriter and tape recorder.

Data breaks may also derive from within the AUTECH Statistical Analysis Program. Limits for each sensor are written into the program, above or below which all non-compliant data are rejected. Recent expansions have had to be made when it was discovered that realistic data were being rejected.

It is difficult to account for many of the smaller record gaps, especially those which appear in data recorded early in the career of the TWBA. Serious "bugs" in any electronic system arise most frequently in the early operational stages, and the TWBA was no exception. At that time, concentration was focused more on system operational evaluation than on the quantity or quality of recorded data. Also, frequent checks were necessary to test system operation. Data record breaks resulting from these were most often unreported in the site situation reports.

Data continuity is illustrated in Figure 11. Continuity was determined by visually scanning the data-time group of the corrected print-outs. By following along the date-time group in chronological sequence, time gaps were immediately discerned and depicted in the graph.

The TWBA Data Continuity Record shows only record gaps of



A ARRAY FAILURE
 P POWER FAILURE (GENERATORS)
 C EQUIPMENT CHECK
 — UNEXPLAINED

FIGURE 11 TWBA DATA CONTINUITY
 (ONLY DATA BREAKS >4 HOURS DEPICTED)

greater than 4-hour duration. Although array operation commenced on 21 October, 1965, the more convenient starting date of 11 November is used on this graph. Only data through February, 1967, are presented in Figure 11.

Numbers enclosed within the continuity bars in Figure 11 are the sampling time modes employed during the respective operating intervals. Most frequently the 2-minute mode has been used in sequential sampling. The variety of modes used early in the operation of the TWBA was the result of system experimentation.

These gaps of greater than 4 hours usually result from failure or malfunction within the system (A) or with the generators powering the system (P). The record gap for 3 to 9 May 1966, is due to missing data for which there can be found no explanation.

To facilitate data analysis and to readily identify the reasons for data gaps in time sequences from the array, a procedure has been initiated for system operators to follow when restarting the recording subsystem following any interruption in automatic sampling. The procedure is to substitute the manually controlled data field for "year" with one of the identifications in Table 3. This will be done for the first record only after automatic sampling and data recording is resumed. (see below)

TABLE 3

CODING SCHEDULE FOR (COMPUTER) IDENTIFICATION OF OFF-TIME ON
THE TAUT WIRE BUOY ARRAY

1111	Array failure or malfunction
2222	Power failure (Generator)
3333	checks or test being made on equipment
4444	Generators switched
5555	Hurricane or natural disaster
6666	Sensor check/system on manual mode
7777	Tape change
8888	Corrected error in digital clock

DIGITAL FORMAT

Tapes are written in low density (200 bits/inch), odd parity, IBM-format Binary Coded Decimal numeric form. Characters are entered onto five of the seven tape channels, specifically channels 1,2,3,4 and 7 (a parity channel). Figure 12a shows how each numeric character from 0 to 9 is entered onto tape channels. Note that zero is recorded on tape as a blank with a mark in the parity channel.

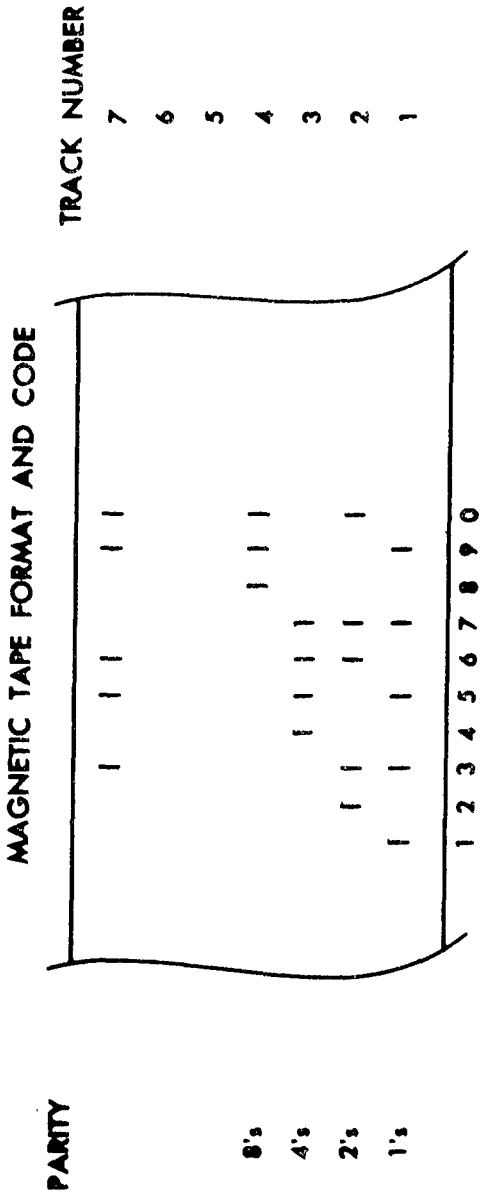


FIGURE 12a EXAGGERATED SEGMENT OF MAGNETIC TAPE SHOWING BINARY CODED DECIMAL FORM

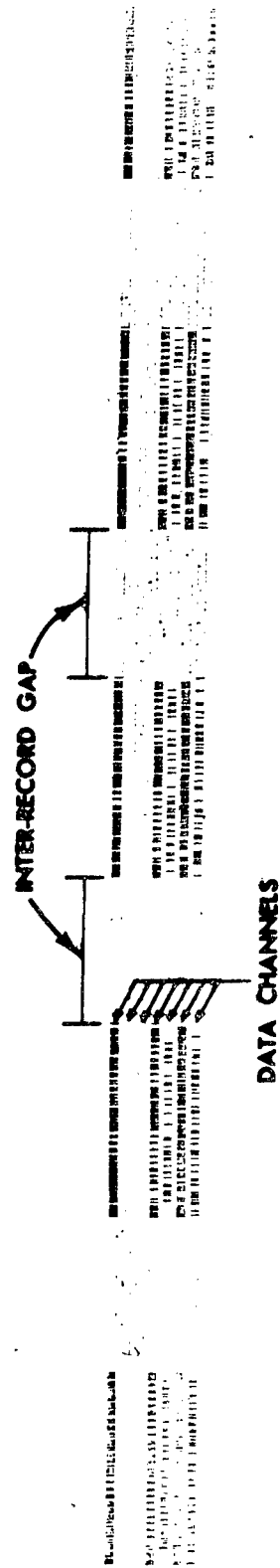


FIGURE 12b "DEVELOPED" SEGMENT OF MAGNETIC TAPE SHOWING INDIVIDUAL DATA RECORDS

A complete RECORD on an original tape has 168 characters followed by an END-OF-RECORD mark consisting of three blank spaces, then a special mark which is a longitudinal parity check character. Figure 12b is a continuous real record sequence on magnetic tape with data channels and inter-record gaps indicated.

ACCUMULATED DATA

The "valid" chronological sequence of original data tapes as they are presently numbered is as follows: 6,7,12,11,10, 13,14 . . . and so on. Number 21 has never been assigned to a tape. Tapes 1 and 5 were test tapes, therefore not included. Program rewriting by Bunker-Ramo Corporation of tapes 8 and 9 resulted in new numbers, 12 and 11, being substituted respectively. Each tape differs from the others in record duration and in sampling modes used during the data collection. Data backlog continues to be one of the major problems in processing and analyzing the array data, resulting from the inavailability of the required amount of computer time. Eventually, all of the tapes will be consolidated, the chronology errors eliminated and the data corrected and processed. Data presentations will be performed for regular time periods; e.g., monthly summaries. Future consolidation will eliminate the existing haphazard numerical order with the assignment of new numbers to the tapes.

COMPUTER PROGRAMS

Several programs have been written to facilitate the retrieval, evaluation, and presentation of the data. One program converts the original magnetic tape to an "intermediate" tape by reformatting the data, placing the array number before rather than after the record number, and reducing the number of characters from 168 to 120. The reduction is made possible by deleting unused characters in each data word (each sensor field utilizes only four of the six digits available in each parameter field).

The AUTECS Statistical Analysis Program (ASAP) is the major tool for the processing of TWBA data tapes. In addition to performing editing and correcting functions, this program performs basic statistical analyses upon the data sequences from the array sensors. Following is an outline of ASAP functions (see Appendix II for the 1200 hours, Day 296, to 2358 hours, Day 298, 1965).

1. Eliminate erroneous sensor readings according to the following criteria:
 - a. Any sensor reading falling outside the maximum and minimum parameter limits (envelope);
 - b. Any sensor reading exceeding a predetermined time rate of change.
2. Corrects recorded values using data provided by the manufacturer.
3. Computes (Appendix II-1 through II-6):
 - a. the mean and standard deviation from the mean for data sequences from each sensor;
 - b. the mean arithmetic change between consecutive observations of each sensor (sign considered);
 - c. the mean change (sign not considered) and standard deviation between consecutive observations of each sensor;
 - d. total number of data points and missing points;
 - e. the maximum and minimum reading from each sensor, frequency of occurrence, and time of first occurrence.
4. Compares corrected temperature values at the same depth (Appendix II-6) by computing the mean difference between paired (redundant) sensor readings and the standard deviation from the mean.
5. Compares corrected temperature values at different depths (Appendix II-7) by computing the average gradients between them in units/meter and computing the standard deviations of gradients.
6. Computes the average difference between pressure sensors.

The AUTEC Statistical Analysis Program has recently been documented as an informal report by the program developer.

A Data Compacting Program has been written that averages observations over specified time periods, thereby reducing the bulk of data listings (Appendix III). This type of pro-

gram offers the advantages of handling ease and of serving users not particularly interested in short-term variations in the parameters measured.

Plotting programs have been prepared for analog representation of temperature with depth and of temperature with time. The plotter programs are written for use on the Calcomp plotter, which is a digital incremental drum plotter with a basic resolution of five-thousandths of an inch. The plotter programs are flexible in size up to the maximum of 29 inches - the width of the drum. Figure 13 is a temperature with depth profile plotted for 1000 hours on Julian day 105, 1966. Figure 14 shows time-series temperature plots for selected sensors over a 24-hour period, 1000 hours (LCT) on day 281 to 1000 hours (LCT) on day 282, 1966. A second sample time-series representation, figure 15, covers levels 1,2, and 3 for the period 11-13 October, 1966.

Figure 16 shows a short temperature time-series for the interval 0000 to 0922 hours on day 297, 1965. Although not an automated plot, this figure is a reasonably typical sampling of the array data and demonstrates the value of analog presentations in interpreting and evaluating time series data from the array. In order to avoid confusion, only primary sensor readings were plotted, and certain recording levels were omitted as superfluous to a streamlined plot. A general rise in the temperature is immediately noticeable in the graph at about 0500 hours. The thermal gradient between sensors 1 and 5 is greatest between 0000 and 0200 hours and smallest between 0400 and 0700 hours. The most definite rise is shown by sensor 7 to occur between 0300 and 0600. This is probably the expression of a semidiurnal high tide, and although it is supported by temperature plots of deep sensors, the magnitude of change in the latter is far less. Sensor 9 (172 meters) exhibits the largest fluctuations which are anomalous in that temperatures, peaking at 0300 hours, fall to a low during a time span when the other plots show a high.

Other programs on the development agenda that are based on array data involve harmonic analyses and power spectra.

The major technical problems in the storage and retrieval of the array data have been solved, but there still remain some data processing problems arising from the backlog of data accumulated over the long period of almost continuous operation. The overall length and continuity of the TWBA data record make it a valuable tool for detailed oceanographic studies, especially the longer term processes about which little is presently known.

AUTEC ENVIRONMENTAL MONITORING ARRAY DATA

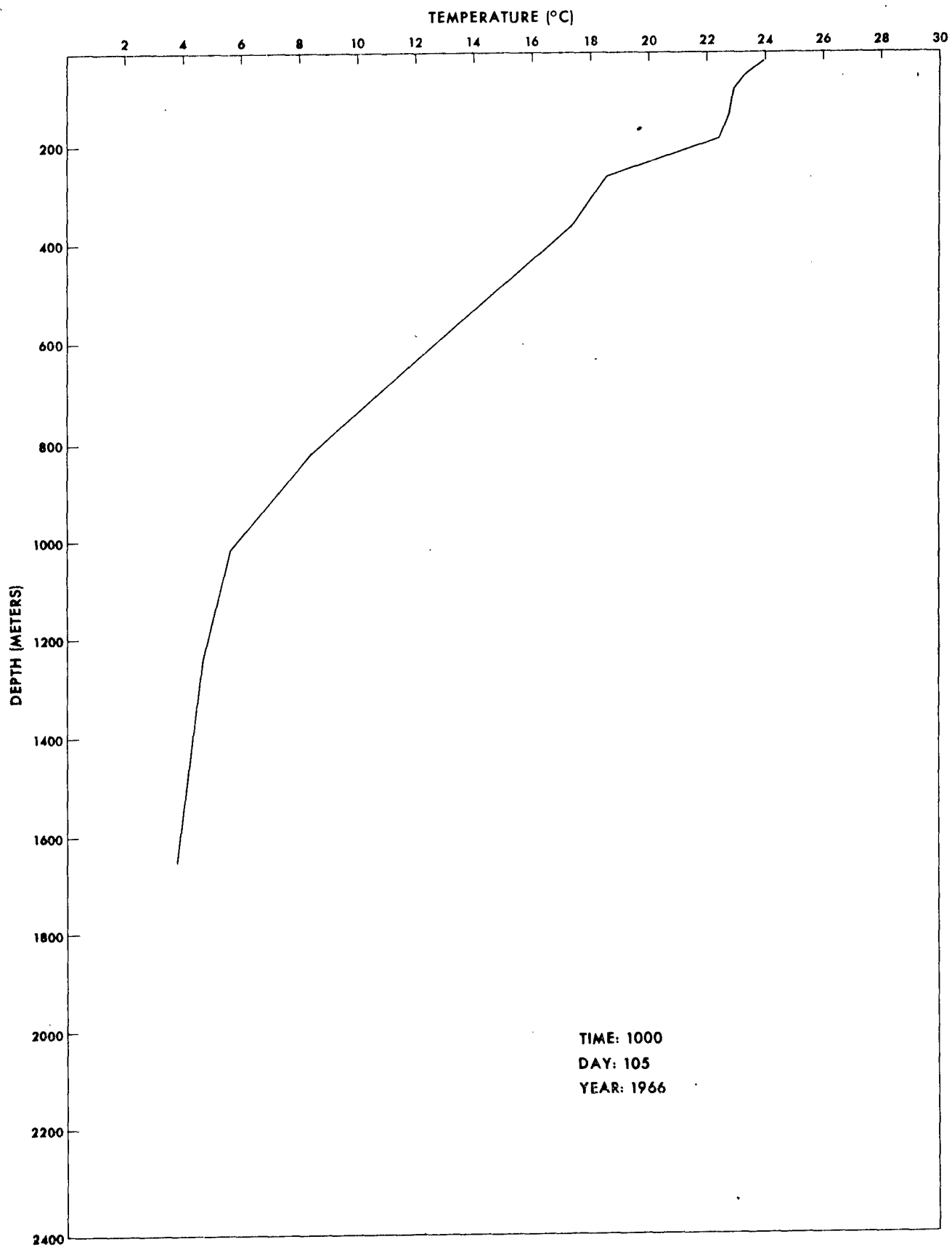


FIGURE 13 TEMPERATURE - DEPTH PROFILE

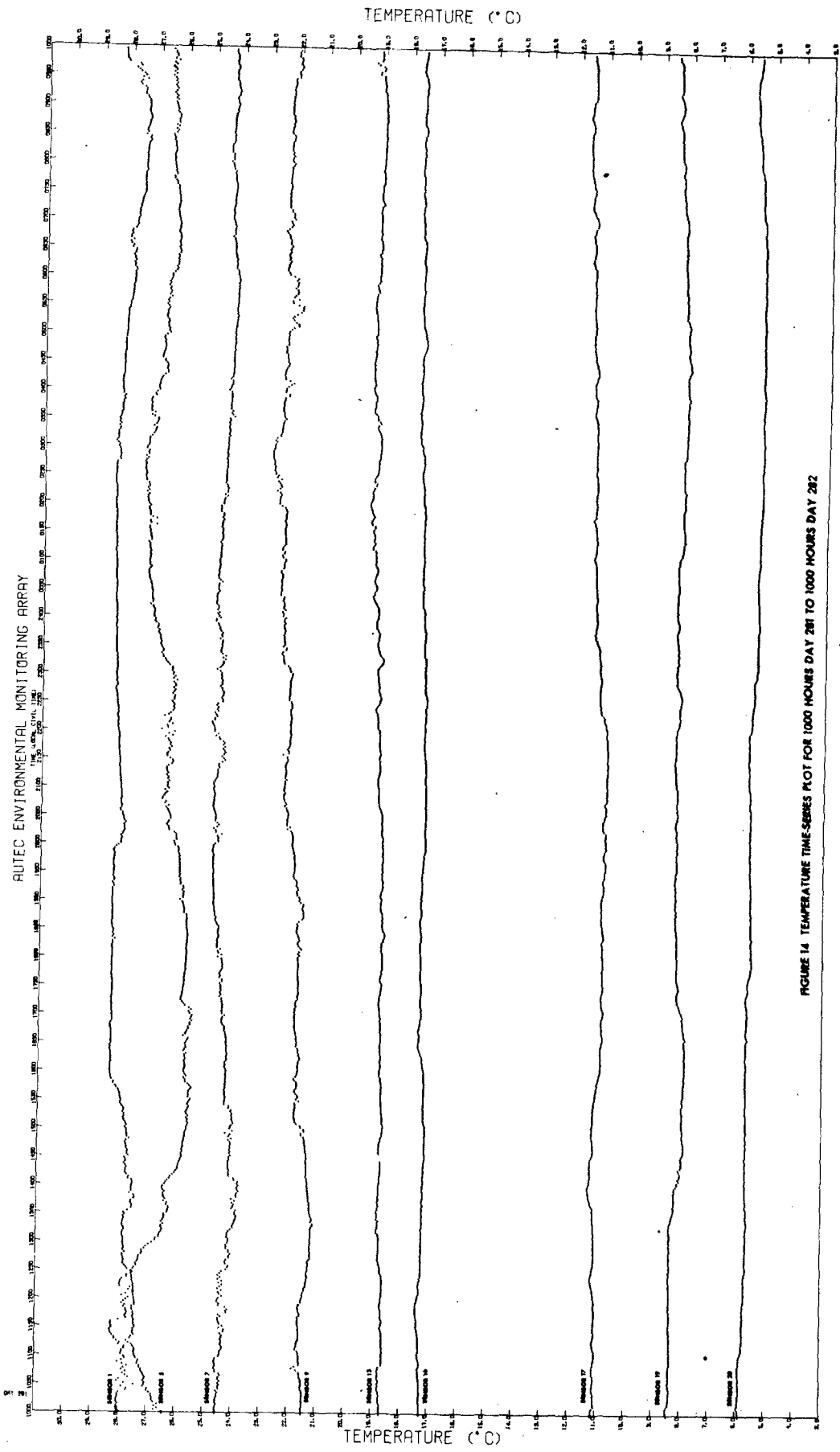
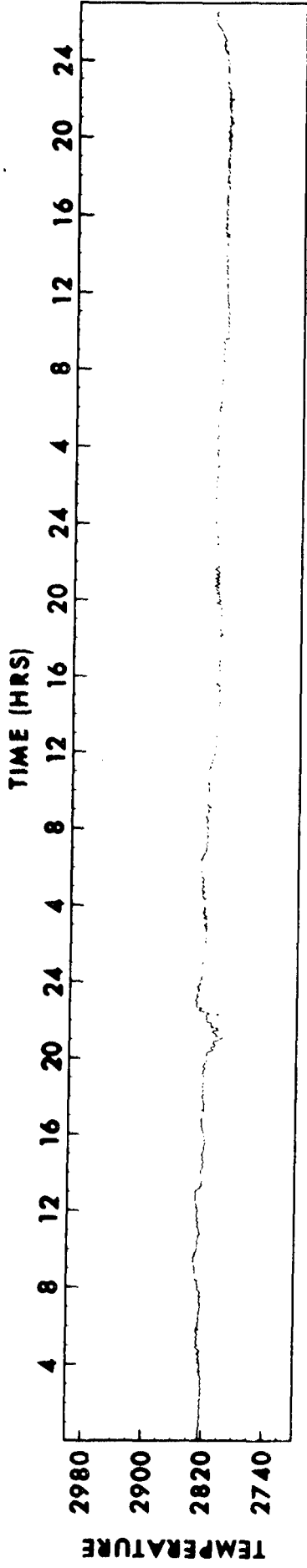
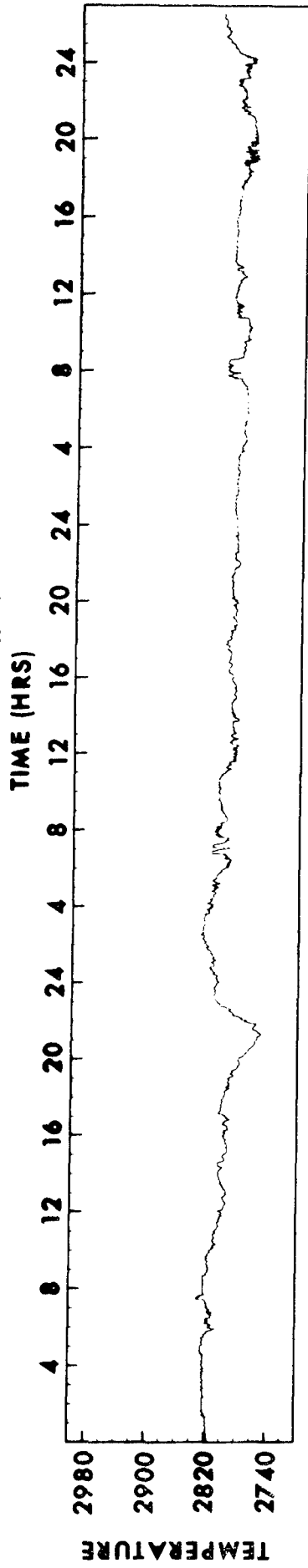


FIGURE 14. TEMPERATURE TIME-SERIES PLOT FOR 1000 HOURS DAY 281 TO 1000 HOURS DAY 282

TEMPERATURE TIME-SERIES 22M
PERMANENT ARRAY



TEMPERATURE TIME-SERIES 45M
PERMANENT ARRAY



TEMPERATURE TIME-SERIES 75M
PERMANENT ARRAY

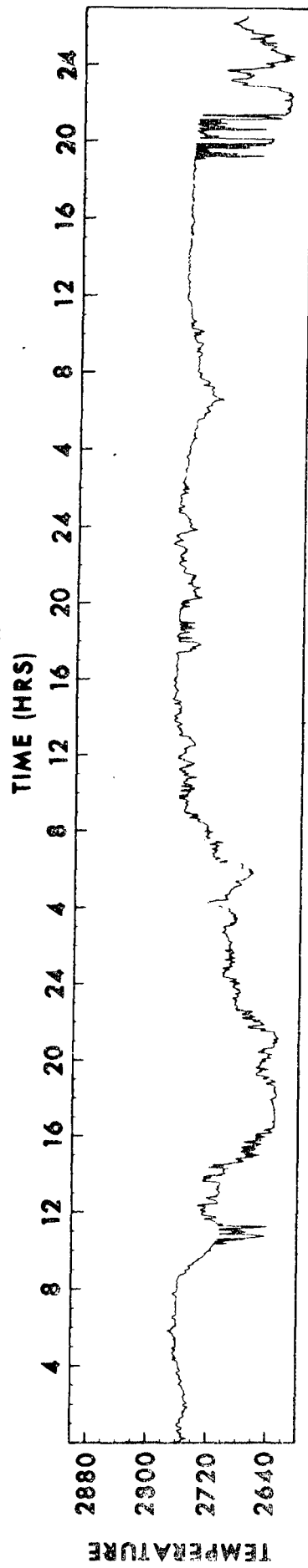


FIGURE 15 TEMPERATURE TIME-SERIES FOR 11-13 OCTOBER, 1966

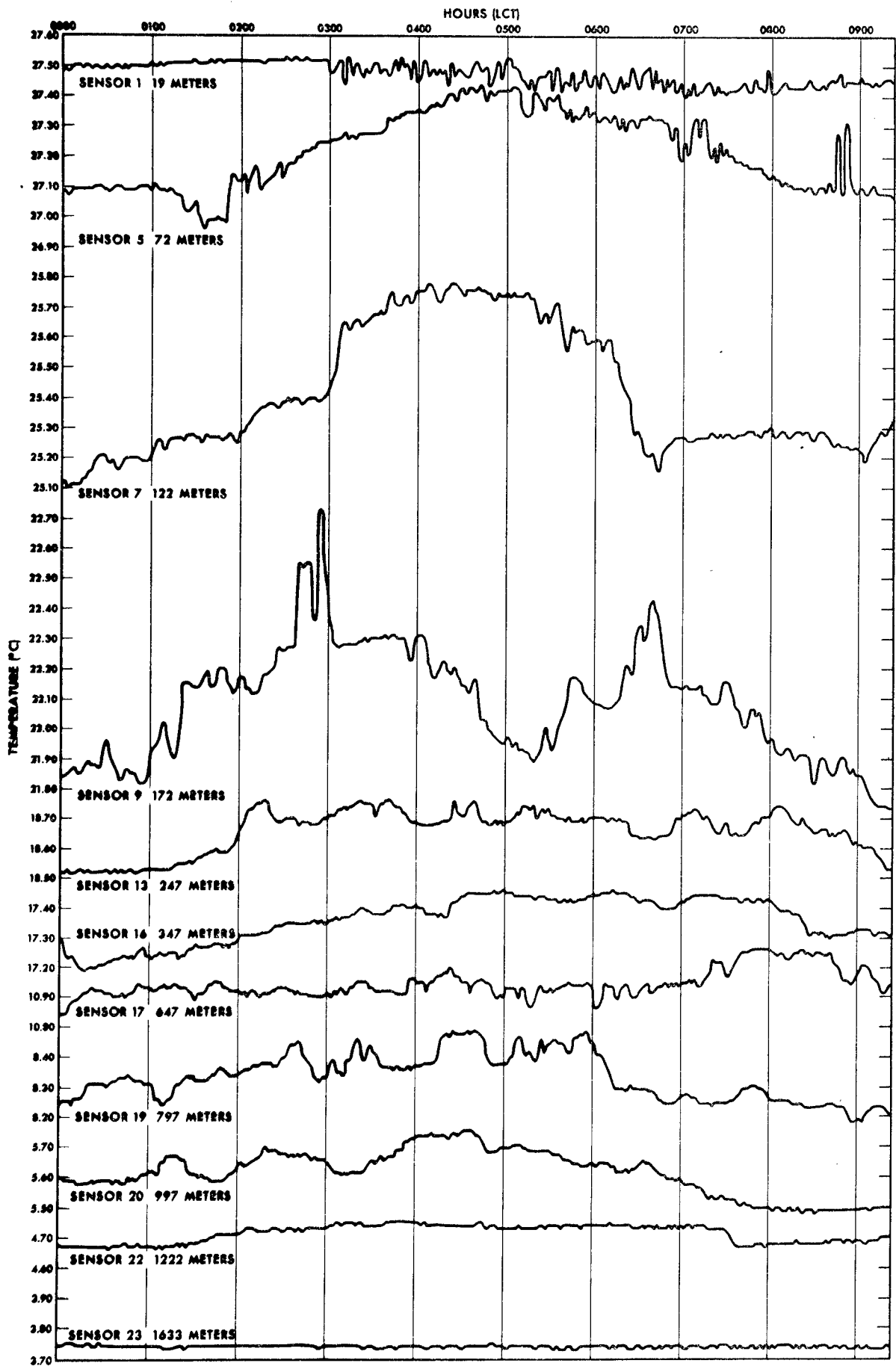


FIGURE 16 TWBA TEMPERATURE TIME SERIES, DAY 297, YEAR 1965, 0000-0922 HOURS

All data tapes are stored at the Data Processing Systems Office at NAVOCEANO, however, requests for any data should be directed to the National Oceanographic Data Center (NODC). Data for specified time periods will consist of edited and corrected temperature and pressure data listings reduced to page size, such as it appears in page 1-1 of the Appendix. Note that in page 1-1, the first and second data columns that do not have headings are the "Array Number" and the "Record Number". Data columns that are blank or partially blanked out are the result of exclusion by the program (ASAP) of unacceptable data. Decimal places fall after the second digit in each four-digit group, except for sensor 14 (P) where the decimal falls after the third digit of the four-digit group.

NEW ARRAY INSTALLATION

Two new taut wire buoy arrays have been installed in TOTO, similar in design to the existing TWBA, but with slight changes in sensor locations. One array is located southeast of High Point Cay (AUTEK Site 7) and the other is located southeast of Andros Town (AUTEK Site 1).

The manner of data transfer for the two new arrays has been altered for the expanded 3 - array monitoring system. Data from Site 2 and Site 7 is telemetered to the Central Data Collection Point at the Command Control Building at Site 1. Data from the Site 1 array is cabled directly into the same point, where data from all three arrays are recorded on magnetic tape. A microwave transmission network, primarily used for weapons range tracking operations, is used for array data transmission. Data sampling is performed sequentially, requiring no more than two minutes per array and no more than six minutes for all three arrays. The order of reporting is a Site 1, Site 2, Site 7 sequence (Figure 1).

Bissett-Berman Corporation installed the additional arrays in early September, 1967. As the contractor, it was their responsibility to implant the array, lay the transmission cable to shore, and install the shore terminal equipment into existing government-furnished facilities. A more comprehensive report on the expansion of the AUTEK Environmental Monitoring System to a 3-array system will be forthcoming.

APPENDIX I

AUEC ENVIRONMENTAL MONITORING ARRAY

YEAR	DAY	TIME	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
1	201	1965	2961848275620632761276226907421251024972203	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	202	1965	2961850275520552761276226917415251024982203	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	203	1965	2961852275320592761276126917420251225002202152	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	204	1965	29618542756205927612762269174182512250022020	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	205	1965	2961856275420592761276126907416251225012202	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	206	1965	2961858275320522761276126917409251250002197	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	207	1965	29619002754206127602761269074202512250021972291	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	208	1965	2961902275620582752759226897417251225012202	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	209	1965	2961904275320582759226897416251225022201	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	210	1965	296190627562061275727526907416251425022198	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	211	1965	29619082756204927582759269074122514250121972153	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	212	1965	296191027520612759275926907420251225032202	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	213	1965	296191227552052760276126917418251225032203	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	214	1965	296191427532048276127612692740825125032201	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	215	1965	296191627552058276127612693742125122502202057	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	216	1965	2961918275620582761276126937416251225002203086	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	217	1965	29619202756205827612760269174192512250022042082	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	218	1965	2961922275620542761276126907409251225022203	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	219	1965	296192427520522761276226897415251225022002084	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	220	1965	29619262758205627612760269274132512250321922084	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	221	1965	29619282756205827602760269174162512250421962085	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	222	1965	29619302757204927572758269174092512250421962089	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	223	1965	29619322756205127602760269474182512250421962090	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	224	1965	296193427520327602760269374152512250421962090	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	225	1965	2961936275720527582758269374112512250421962087	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	226	1965	2961938275520532757275269574132512250521982084	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	227	1965	2961940275620527572758269674012512250521992077	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	228	1965	29619422756205127582759269574132512250622002074	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	229	1965	29619442756204827612761269574052512250621982069	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	230	1965	29619462756204927602760269574102512250421962065	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	231	1965	29619482756203527612761269573972512250421952065	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	232	1965	29619502757204627612761269574052512250621942064	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	233	1965	29619522757204427632763269774042512250572193	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	234	1965	2961954275620382762276326977403251225052190	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	235	1965	2961956275204227632763269774032512250321902068	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	236	1965	2961958275204627622762269874082512250321882062	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	237	1965	29620002758204327622761269774032512250621862062	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	238	1965	2962002275203927622762269473992512250621862057	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	239	1965	296200427520362763276326937401251225062188	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	241	1965	296200627520452762276326947401251225062187	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	241	1965	2962008275620432762276326947399251225072186	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	242	1965	2962010275620392761276226927403251225082177	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	243	1965	2962012275620402762276226927401250205082172	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	244	1965	2962014275620432762276226917402251225072175	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	245	1965	296201627552042763276226937401251225082187	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	246	1965	296201827520402763276226947402250205072182	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	247	1965	296202027520392762276326947399251225062183	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	248	1965	2962022275620402762276326947397251225072183	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	249	1965	2962024275620442763276226947403251225082181	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	250	1965	2962136275620442763276226957403251225052180	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	251	1965	2962028275720342762276326957395251225012182	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

APPENDIX II

ANALYSIS OF MONITORING ARRAY FROM 1200 HRS, DAY NO. 296 TO 2358 HRS, DAY NO. 298,

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
1	27.47	0.14	-0.00	0.02	0.16	830	2

THE MAXIMUM VALUE WAS 27.58. THIS VALUE OCCURRED 7 TIMES AND OCCURRED FIRST ON DAY 296 AT 1716 HOURS.

THE MINIMUM VALUE WAS 24.23. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 298 AT 2012 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
2	19.99	0.54	0.00	0.07	0.17	825	7

THE MAXIMUM VALUE WAS 20.76. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 297 AT 710 HOURS.

THE MINIMUM VALUE WAS 17.67. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 298 AT 2236 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
3	27.56	0.12	-0.00	0.01	0.02	830	2

THE MAXIMUM VALUE WAS 27.73. THIS VALUE OCCURRED 2 TIMES AND OCCURRED FIRST ON DAY 297 AT 402 HOURS.

THE MINIMUM VALUE WAS 27.26. THIS VALUE OCCURRED 4 TIMES AND OCCURRED FIRST ON DAY 298 AT 2348 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
4	27.57	0.13	-0.00	0.01	0.02	832	0

THE MAXIMUM VALUE WAS 27.73. THIS VALUE OCCURRED 7 TIMES AND OCCURRED FIRST ON DAY 297 AT 354 HOURS.

THE MINIMUM VALUE WAS 27.26. THIS VALUE OCCURRED 2 TIMES AND OCCURRED FIRST ON DAY 298 AT 2350 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
5	27.17	0.26	0.00	0.02	0.04	830	2

THE MAXIMUM VALUE WAS 27.69. THIS VALUE OCCURRED 12 TIMES AND OCCURRED FIRST ON DAY 298 AT 1454 HOURS.

THE MINIMUM VALUE WAS 26.69. THIS VALUE OCCURRED 2 TIMES AND OCCURRED FIRST ON DAY 296 AT 1438 HOURS.

APPENDIX II

ANALYSIS OF MONITORING ARRAY FROM 1200 HRS, DAY NO. 296 TO 2358 HRS, DAY NO. 298

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
6	73.64	0.41	0.00	0.05	0.09	803	29

THE MAXIMUM VALUE WAS 74.36. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 297 AT 800 HOURS.

THE MINIMUM VALUE WAS 72.86. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 298 AT 1506 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
7	25.50	0.42	0.00	0.02	0.03	829	3

THE MAXIMUM VALUE WAS 26.46. THIS VALUE OCCURRED 4 TIMES AND OCCURRED FIRST ON DAY 298 AT 1648 HOURS.

THE MINIMUM VALUE WAS 24.88. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 296 AT 1236 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
8	25.38	0.42	0.00	0.02	0.03	832	0

THE MAXIMUM VALUE WAS 26.35. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 298 AT 1654 HOURS.

THE MINIMUM VALUE WAS 24.77. THIS VALUE OCCURRED 3 TIMES AND OCCURRED FIRST ON DAY 296 AT 1236 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
9	22.18	0.43	0.00	0.02	0.04	830	2

THE MAXIMUM VALUE WAS 23.28. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 298 AT 1602 HOURS.

THE MINIMUM VALUE WAS 21.47. THIS VALUE OCCURRED 2 TIMES AND OCCURRED FIRST ON DAY 296 AT 1236 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
10	20.81	0.98	0.00	0.14	0.54	401	431

THE MAXIMUM VALUE WAS 26.53. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 296 AT 2008 HOURS.

THE MINIMUM VALUE WAS 18.25. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 298 AT 1646 HOURS.

APPENDIX II

ANALYSIS OF MONITORING ARRAY FROM 1200 HRS, DAY NO. 296 TO 2358 HRS, DAY NO. 298

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
11	21.31	2.53	0.21	0.09	0.43	115	717

THE MAXIMUM VALUE WAS 26.92. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 297 AT 308 HOURS.

THE MINIMUM VALUE WAS 17.99. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 297 AT 403 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
12	19.32	0.15	0.00	0.01	0.02	831	1

THE MAXIMUM VALUE WAS 19.81. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 298 AT 1948 HOURS.

THE MINIMUM VALUE WAS 18.88. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 296 AT 2158 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
13	18.66	0.13	0.00	0.01	0.03	827	5

THE MAXIMUM VALUE WAS 18.94. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 298 AT 1932 HOURS.

THE MINIMUM VALUE WAS 17.98. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 296 AT 1430 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
14	251.72	0.42	0.00	0.07	0.11	803	29

THE MAXIMUM VALUE WAS 252.45. THIS VALUE OCCURRED 20 TIMES AND OCCURRED FIRST ON DAY 297 AT 626 HOURS.

THE MINIMUM VALUE WAS 250.90. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 298 AT 1504 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
15	18.64	0.13	0.00	0.01	0.01	832	0

THE MAXIMUM VALUE WAS 18.91. THIS VALUE OCCURRED 5 TIMES AND OCCURRED FIRST ON DAY 298 AT 1924 HOURS.

THE MINIMUM VALUE WAS 18.37. THIS VALUE OCCURRED 6 TIMES AND OCCURRED FIRST ON DAY 296 AT 1320 HOURS.

APPENDIX II

ANALYSIS OF MONITORING ARRAY FROM 1200 HRS, DAY NO. 296 TO 2358 HRS, DAY NO. 298

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
16	17.38	0.11	-0.00	0.00	0.01	829	3

THE MAXIMUM VALUE WAS 17.62. THIS VALUE OCCURRED 9 TIMES AND OCCURRED FIRST ON DAY 296 AT 1344 HOURS.

THE MINIMUM VALUE WAS 17.19. THIS VALUE OCCURRED 2 TIMES AND OCCURRED FIRST ON DAY 297 AT 16 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
17	10.96	0.09	0.30	0.01	0.02	828	4

THE MAXIMUM VALUE WAS 11.26. THIS VALUE OCCURRED 3 TIMES AND OCCURRED FIRST ON DAY 296 AT 1556 HOURS.

THE MINIMUM VALUE WAS 10.75. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 296 AT 1236 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
18	10.95	0.12	0.00	0.02	0.12	831	1

THE MAXIMUM VALUE WAS 11.27. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 296 AT 1600 HOURS.

THE MINIMUM VALUE WAS 8.60. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 298 AT 2012 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
19	8.33	0.14	-0.00	0.01	0.02	828	4

THE MAXIMUM VALUE WAS 8.62. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 296 AT 1710 HOURS.

THE MINIMUM VALUE WAS 8.03. THIS VALUE OCCURRED 3 TIMES AND OCCURRED FIRST ON DAY 298 AT 1932 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
20	5.63	0.09	0.00	0.01	0.02	829	3

THE MAXIMUM VALUE WAS 5.84. THIS VALUE OCCURRED 5 TIMES AND OCCURRED FIRST ON DAY 296 AT 1552 HOURS.

THE MINIMUM VALUE WAS 5.33. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 296 AT 2340 HOURS.

APPENDIX II

ANALYSIS OF MONITORING ARRAY FROM 1200 HRS, DAY NO. 296 TO 2358 HRS, DAY NO. 298

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
21	5.62	0.09	-0.00	0.01	0.01	832	0

THE MAXIMUM VALUE WAS 5.83. THIS VALUE OCCURRED 4 TIMES AND OCCURRED FIRST ON DAY 296 AT 1552 HOURS.

THE MINIMUM VALUE WAS 5.45. THIS VALUE OCCURRED 7 TIMES AND OCCURRED FIRST ON DAY 296 AT 2048 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
22	4.72	0.04	0.00	0.00	0.01	830	2

THE MAXIMUM VALUE WAS 4.80. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 298 AT 1918 HOURS.

THE MINIMUM VALUE WAS 4.64. THIS VALUE OCCURRED 9 TIMES AND OCCURRED FIRST ON DAY 296 AT 2138 HOURS.

SENSOR NUMBER	MEAN VALUE	STD. DEV	MEAN CHANGE	AVERAGE CHANGE	ST DEV CHANGE	DATA POINTS	MISSING POINTS
23	3.76	0.19	0.00	0.04	0.21	806	26

THE MAXIMUM VALUE WAS 5.90. THIS VALUE OCCURRED 1 TIMES AND OCCURRED FIRST ON DAY 296 AT 2312 HOURS.

THE MINIMUM VALUE WAS 3.61. THIS VALUE OCCURRED 5 TIMES AND OCCURRED FIRST ON DAY 296 AT 1556 HOURS.

APPENDIX II

ANALYSIS OF MONITORING ARRAY FROM 1200 HRS, DAY NO. 296 TO 2358 HRS, DAY NO. 298

SENSOR NUMBERS	AVERAGE DIFFERENCE	STANDARD DEVIATION	DATA POINTS	DEPTH (METERS)
3- 4	-0.01	0.01	830	45.
7- 8	0.12	0.01	829	125.
10-11	0.11	0.37	56	200.
13-15	0.02	0.02	827	250.
17-18	0.00	0.01	828	650.

APPENDIX II

ANALYSIS OF MONITORING ARRAY FROM 1200 HRS, DAY NO. 296 TO 2358 HRS, DAY NO. 298

SENSOR NUMBERS A - B	AVERAGE GRADIENT (UNITS/M.)	ST. DEV GRADIENT	DATA POINTS	DEPTH(M.) SENSOR A	DEPTH(M.) SENSOR B
1- 3	-0.0037	0.0054	830	20.	45.
1- 4	-0.0040	0.0055	830	20.	45.
1- 5	0.0053	0.0064	830	20.	75.
3- 5	0.0128	0.0117	830	45.	75.
4- 5	0.0131	0.0118	830	45.	75.
5- 7	0.0335	0.0049	829	75.	125.
5- 8	0.0359	0.0049	830	75.	125.
5- 9	0.0499	0.0027	830	75.	175.
7- 9	0.0663	0.0036	829	125.	175.
8- 9	0.0639	0.0036	830	125.	175.
19-20	0.0135	0.0007	828	800.	1000.
19-22	0.0085	0.0003	828	800.	1225.
19-23	0.0055	0.0003	804	800.	1636.
20-22	0.0041	0.0003	829	1000.	1225.
22-23	0.0023	0.0005	806	1225.	1636.
2- 6	53.5846	0.1000	801	20.	75.
2-14	231.6692	0.5167	799	20.	250.
6-14	178.0858	0.5329	801	75.	250.

APPENDIX II

1965 295 2334 1965 295 2336 DATA IS RECORDED AT 2 MINUTES INTERVAL

BREAKS IN DATA GREATER THAN 8 MINUTES

YEAR DAY HOUR	YEAR DAY HOUR	DATA IS RECORDED AT	INTERVAL
1965 295 2338	1965 296 1236	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 296 1338	1965 296 1342	DATA IS RECORDED AT	2 MINUTES INTERVAL
1965 296 1342	1965 296 1432	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 296 1428	1965 296 1434	DATA IS RECORDED AT	2 MINUTES INTERVAL
1965 296 1432	1965 296 1446	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 296 1442	1965 296 1448	DATA IS RECORDED AT	2 MINUTES INTERVAL
1965 296 1446	1965 296 1452	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 296 1448	1965 296 1458	DATA IS RECORDED AT	2 MINUTES INTERVAL
1965 296 1452	1965 296 1502	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 296 1502	1965 296 1600	DATA IS RECORDED AT	6 MINUTES INTERVAL
1965 296 1600	1965 296 1608	DATA IS RECORDED AT	2 MINUTES INTERVAL
1965 296 1620	1965 296 1634	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 296 1658	1965 296 1702	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 296 1702	1965 296 1704	DATA IS RECORDED AT	2 MINUTES INTERVAL
1965 296 1752	1965 296 1758	DATA IS RECORDED AT	6 MINUTES INTERVAL
1965 296 1758	1965 296 1800	DATA IS RECORDED AT	2 MINUTES INTERVAL
1965 296 1800	1965 296 1804	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 296 2022	1965 296 1806	DATA IS RECORDED AT	2 MINUTES INTERVAL
1965 296 2400	1965 296 2400	DATA IS RECORDED AT	2 MINUTES INTERVAL
1965 296 2136	1965 296 2136	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 296 2028	1965 296 2028	DATA IS RECORDED AT	*8 MINUTES INTERVAL
1965 296 2134	1965 296 2030	DATA IS RECORDED AT	2 MINUTES INTERVAL
1965 296 2134	1965 296 2134	DATA IS RECORDED AT	0 MINUTES INTERVAL
1965 296 2138	1965 296 2138	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 296 2226	1965 296 2140	DATA IS RECORDED AT	2 MINUTES INTERVAL
1965 296 2318	1965 296 2238	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 296 2322	1965 296 2322	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 297 422	1965 296 2324	DATA IS RECORDED AT	2 MINUTES INTERVAL
1965 297 426	1965 297 426	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 297 520	1965 297 428	DATA IS RECORDED AT	2 MINUTES INTERVAL
1965 297 524	1965 297 524	DATA IS RECORDED AT	4 MINUTES INTERVAL
1965 297 922	1965 297 526	DATA IS RECORDED AT	2 MINUTES INTERVAL
	1965 297 1000	DATA IS RECORDED AT	2 MINUTES INTERVAL

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Unclassified

Security Classification

DOCUMENT CONTROL DATA - R & D

(Security classification of title, body of abstract and indexing annotation must be entered when the overall report is classified)

1. ORIGINATING ACTIVITY (Corporate author)		2a. REPORT SECURITY CLASSIFICATION	
U.S. Naval Oceanographic Office		Unclassified	
		2b. GROUP	
3. REPORT TITLE			
A Taut Wire Buoy Array For Environmental Monitoring In AUTEK			
4. DESCRIPTIVE NOTES (Type of report and inclusive dates)			
Informal Report			
5. AUTHOR(S) (First name, middle initial, last name)			
Richard F. Rooney			
6. REPORT DATE		7a. TOTAL NO. OF PAGES	7b. NO. OF REFS
October 1967			
8a. CONTRACT OR GRANT NO.		9a. ORIGINATOR'S REPORT NUMBER(S)	
None		IR No. -68-35	
b. PROJECT NO. 715			
c.		9b. OTHER REPORT NO(S) (Any other numbers that may be assigned this report)	
d.		None	
10. DISTRIBUTION STATEMENT			
This document has been approved for public release and sale; its distribution is unlimited.			
11. SUPPLEMENTARY NOTES		12. SPONSORING MILITARY ACTIVITY	
		Naval Ships Systems Command	
13. ABSTRACT			
<p>The Taut Wire Buoy Array (TWBA) of the AUTEK Environmental Monitoring Station has recently completed recording more than two years of almost continuous temperature and pressure data from 14 selected levels at a fixed site in the Tongue of The Ocean. This report covers some of the general aspects of the system, including: array description and operation, significant events of its existence, and data handling and programming.</p>			

14 KEY WORDS	LINK A		LINK B		LINK C	
	ROLE	WT	ROLE	WT	ROLE	WT
AUTEC (Atlantic Undersea Test and Evaluation Center) Taut Wire Buoy Array (TWBA) TOTO Environmental Monitoring Temperature Sensing (or sampling) Pressure Sensing (or sampling) Andros Island, Bahamas AUTEC Statistical Analysis Program (ASAP)						