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AFATL-TR-72-129

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**TARGET DESCRIPTION
AND
VULNERABILITY PROGRAM**

MARTIN MARIETTA CORPORATION

TECHNICAL REPORT AFATL-TR-72-129

JUNE 1972

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AIR FORCE ARMAMENT LABORATORY

AIR FORCE SYSTEMS COMMAND • UNITED STATES AIR FORCE

EGLIN AIR FORCE BASE, FLORIDA

**Target Description
And
Vulnerability Program**

George W. Brooks

Harvey N. Lerman

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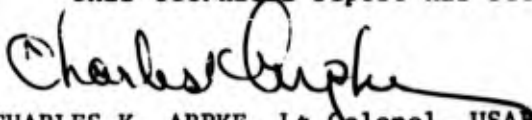
FOREWORD

This report summarizes the technical effort of Martin Marietta Corporation, Orlando, Florida, during the period 17 January through 19 May 1972 under Contract F08635-72-C-0103 with the Air Force Armament Laboratory, Eglin Air Force Base, Florida. The Armament Laboratory project engineer was TSgt Gary A. Brown (DLRV) Document No. OR 11,972 was assigned to the report by the contractor.

The Martin Marietta Corporation task leader for this program was Mr. George W. Brooks. Mr. Harvey N. Lerman was responsible for methodology formulation and the computer programming effort. Contributions were also made by Mr. George E. Belote III. This report was prepared by Messrs. George W. Brooks and Harvey N. Lerman under the direction of Mr. William R. Day, Chief of the Effectiveness Analysis Section, and Mr. Charles A. Borchert, Manager of the Warhead Technology Department.

Acknowledgement is made to TSgt Gary A. Brown and Mr. George Crews of the Air Force Armament Laboratory for their valuable technical assistance and guidance in the performance of this program.

This technical report has been reviewed and is approved.



CHARLES K. ARPKE, Lt Colonel, USAF
Chief, Weapons Effects Division

ABSTRACT

This program provided the Air Force an existing target description computer program which was demonstrated on the Eglin Air Force Base CDC 6600 computer by completing two check runs. The subsequent formulation, coding, and incorporation of two improvements in the program which provided a shielding capability and the input of standard geometrical shapes resulted in a modified program being adopted for use with the Eglin Air Force Base computer. The revised program was demonstrated by computing the presented area of the fuel tanks of a generic fighter aircraft, and making perspective plots of the target with hidden lines removed, using the SC4020 plotter.

This target description and vulnerability program also provides the Air Force with a unique tool for making rapid descriptive and vulnerability assessments of targets through the use of high speed computers and automatic plotting equipment.

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SECTION I

INTRODUCTION AND SUMMARY

This final report summarizes a four-month technical effort to develop a computer program for performing rapid target description studies and assessments of the vulnerability of target components.

1. PROGRAM OBJECTIVES

The overall objective of this effort was to develop a computer program for rapid evaluation of targets and for use in performing target description and vulnerability studies. Specific tasks of the effort, as specified in Reference 1, were as follows:

- 1 Provide a copy of the existing contractor target description and vulnerability program.
- 2 Adapt the existing program to the Eglin Air Force Base CDC 6600 computer and SC4020 plotter.
- 3 Modify the program to provide:
 - a A shielding capability in specifying the characteristics of target components.
 - b Input of standard geometrical shapes.
- 4 Analyze two targets using the original program on the Eglin AFB computer.
- 5 Adapt the revised program to the Eglin AFB CDC 6600 computer and SC4020 plotter.
- 6 Analyze and describe one target to demonstrate the revised program on the Eglin computing equipment.

2. APPROACH SUMMARY

Previous methods used for target analysis were complicated and time-consuming, often requiring as much as 18 engineering man-months to complete and requiring the categorizing of up to one-half million critical bits of information. These methods precluded fast response to changing target spectra and indicated a need for a program to make quick target analyses.

In determining target vulnerability data, a pictorial representation of the target is necessary. Such drawings can be used to show overall outlines of the targets as well as internal and external vulnerable components. As the target elements become complex and to easily obtain views from different angles, such drawings must be produced automatically rather than by laborious and time-consuming geometric projections. The combination of the computer and the plotter is a useful tool in generating the desired perspective drawings. In this new technique for describing a target, presented areas can be computed from these drawings for any viewing angle and the ratio of certain areas can be determined, such as the ratio of the presented area of vulnerable components to total presented area of the target. For example, in the case of simple targets with unprotected vulnerable component areas, this ratio provides an approximation for the probability of kill given a hit. In addition to the target plots obtained, with all hidden lines removed, the program computes presented areas for the perspective angles of interest.

3. ACHIEVEMENTS

During this effort, all technical requirements were achieved and resulted in a computer program which:

- 1 Computes and plots presented areas of targets from any viewing angle.
- 2 Accounts for shields and vulnerable components.
- 3 Produces plots of the targets which have hidden lines removed.
- 4 Accepts input in several forms depending on the target being evaluated.

A comprehensive user's guide was prepared, and several Air Force Armament Laboratory analysts were familiarized with program capabilities and utilization.

4. REPORT ORGANIZATION

This report discusses the methodology, capabilities, and utilization of this program. Section II describes the technical approach. Specific details of the program are contained in Section III. Section IV lists conclusions and recommendations for further work. The appendices contain flow charts, a program listing, common block descriptions, and input formats for using this program.

SECTION II

TECHNICAL APPROACH

1. METHODOLOGY

To develop a computerized technique for determining target and target component presented areas from different angles, simplified plan and side view drawings of the elements are necessary. In this approach complex shapes can be approximated with simple solid bodies, e.g., a parallelepiped may be used to represent an engine block of a truck. The coordinates (X, Y, Z) of the corners are determined for subsequent input into the computer program. Points to be connected by line segments can also be specified. The combination of solids, points, and line segments determines the various faces which approximate the target or component shapes. Since no provision is currently made for curved surfaces, they must be represented by a series of flat faces.

Having specified the target using the foregoing approximations, the presented area from any viewing angle can be computed. For a given target or group of components, only the outer defining lines are used to compute the presented area. Of more importance is the determination of average presented areas, i.e., presented areas at a given elevation angle but which have been averaged over all azimuth angles, since in an actual encounter the target orientation may not be reliably known. This is accomplished by taking the average area as seen from N views, where $N=2(K+1)$, and K is incremented by 1 until the change in the average area is less than the specified tolerance. This definition of N arises from the fact that the views must be spaced symmetrically about the target, so that any increase in the number of views must be by a factor of two. The location of the viewer relative to the target must also be specified.

As an aid in computing presented areas, the perimeter of this target description program is plotted. Perspective plots of the target and vulnerable components are made with the hidden lines and extra lines used to define odd-shaped surfaces removed. These plots are made for only specified views and are not intended to reflect the averaged areas. In computing presented areas and producing perspective plots, the program applies transformation equations to the three-dimensional points and projects them into a plane.

Ratios of areas may also be determined. For example, the ratio of the vulnerable area of a target to the total presented area would give an estimate of the single shot kill probability from that angle.

2. TARGET REPRESENTATION

The target to be run should be oriented so that if there is an axis of symmetry, it is the X axis. If there are two axes of symmetry, one should be X and the other Y.

Each part of the target should be redrawn so that it could be approximated by any one of the program's four standard solids (see Appendix I). Several solids may also be put together (but not touching) to form parts of the target. Any sections of the target which cannot be approximated accurately enough by use of standard solids must be described by means of face definitions. All points on the target which are either reference points of solids or part of a face description should be labeled for future reference.

The parts of the target should be grouped by object type, i.e., all parts which are shields should be denoted as type 2, while all vulnerable parts should be type 0. Parts which are neither shield nor vulnerable probably would be denoted as type 1, frame. An object's type can be changed from run to run, so the effect of adding or deleting a part (i.e., shield) can easily be determined.

SECTION III
COMPUTER PROGRAM

1. CAPABILITIES

This program can be used in many ways and can be the base for a more sophisticated system. Some of its capabilities are:

- 1 An object can be viewed from any point in space by providing elevation, azimuth, and range of the point from the object's origin,
- 2 An approach can be simulated by decreasing range on consecutive runs.
- 3 A movie can be generated by making small changes in elevation, azimuth, and/or range on consecutive runs.
- 4 An outer shell can be described and run as a frame in some runs and then run individually as a target. The ratio of the resultant areas would give the single-shot kill probability.
- 5 Other parametric studies could be made by changing object type (INOBJ) on card F of consecutive runs.
- 6 Open areas such as windows and doors can easily be described.

2. PROGRAM ORGANIZATION

The program consists of the following routines:

- 1 MAIN - Part 1 - Reads and generates the geometry,
Part 2 - Reads control card (F) and iterates on the azimuth until convergence.
- 2 ARCH 3 - For any given view this routine will generate the visible line segments of the target as well as the perimeter segments. The area is also calculated.
- 3 COVER - Determines whether a point is covered by a face in the viewing plane.

- 4 INTER - Calculates all edge intersections in the viewing plane.
- 5 SORTH - Sorting routine.
- 6 PLOTDD - Plotting routine.
- 7 ROTAT 3 - Three-dimensional point rotation routine.

The following perspective system routines are used:

- 1 INIT3D - Initializes the system for one perspective view.
- 2 XFORM - Projects the point onto the plane by calculating X and Y.

One other system routine is used:

DASHLN - Draws a dashed line between two points.

The following CRT routines from the Eglin library are used to replace the now dummy routine PLOTCC:

- 1 FRAMEV - Changes CRT frames.
- 2 LINEV - Draws a line on the CRT.

a. Perspective Equations

To produce perspective plots, transformation equations must be developed which, when applied to a point in three-space, will project it onto a plane. These equations can be easily derived and can be found in most texts on the subject. A summary of this derivation is explained below and shown in Figure 1.

The observer's eye is at point $\phi(\phi_X, \phi_Y, \phi_Z)$ and the line of sight, $\overline{\phi P}$, makes angles a, b, c, with the 3-space X-, Y-, Z- axis, respectively. $\overline{\phi D}$ is the perpendicular distance from the observer to the plane onto which point $P(P_X, P_Y, P_Z)$ is to be projected. If d is the distance $\overline{\phi D}$, the coordinates of D are

$$\begin{aligned}
 D_X &= \phi_X + d (\cos a) \\
 D_Y &= \phi_Y + d (\cos b) \\
 D_Z &= \phi_Z + d (\cos c).
 \end{aligned}
 \tag{1}$$

The coordinates of the projected point P' in three-space are

$$\begin{aligned}
 P'_X &= \phi_X + F (P_X - \phi_X) \\
 P'_Y &= \phi_Y + F (P_Y - \phi_Y)
 \end{aligned}
 \tag{2}$$

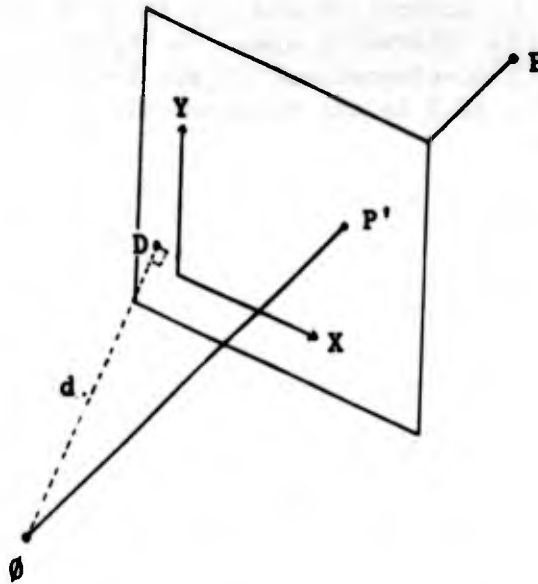


Figure 1. Geometry of Projection

$$P'_Z = \phi_Z + F (P_Z - \phi_Z)$$

$$\text{where } F = d / (P_X - \phi_X) \cos a + (P_Y - \phi_Y) \cos b + (P_Z - \phi_Z) \cos c. \quad (3)$$

The coordinates of P' on the new coordinate system then are

$$X = (P'_X - D_X) \cos b - (P'_Y - D_Y) \cos a / \sin c + X' \quad (4)$$

$$Y = (P'_Z - D_Z) / \sin c + Y'$$

where X', Y' is the distance from D to the origin of the new coordinate system.

Equations (1), (2), (3), and (4) can then be used to project any point in three-space (P) onto two-space (P').

The problem of scaling the object to be projected is readily solved by artificially moving the position of the observer's eye from point ϕ to point ϕ' such that $\phi'D = d/f$ where f is the desired scale factor. Rotation can be accomplished similarly by rotating the observer's eye about the object.

Another way to accomplish scaling is by moving the projection plane away from or toward the observer's eye. In Figure 2, a rectangular solid is drawn around the three-dimensional object to be projected. The size of the solid is such that if A is the minimum corner of the solid and B is the maximum corner, then

$$\begin{aligned} A_X &\leq P_X \leq B_X, \\ A_Y &\leq P_Y \leq B_Y, \text{ and} \\ A_Z &\leq P_Z \leq B_Z \end{aligned} \tag{5}$$

where P (P_X, P_Y, P_Z) is any arbitrary point within the object and A_X, A_Y, A_Z and B_X, B_Y, B_Z are the coordinates of A and B, respectively. If \emptyset is the observer's eye, rays $\emptyset A$ and $\emptyset B$ are the projection rays of the three-dimensional object. If the object is to be projected onto a plane so that it will fill an area ZDIM by YDIM, a rectangle of this size is moved, staying perpendicular to the line of sight from \emptyset so that two of the rectangles diagonally opposite corners A' and B' will fall on the two projection rays, $\emptyset A$ and $\emptyset B$, respectively. The farther the rectangle is moved from \emptyset , the larger the projection will be. If the rectangle falls between the object and the observer, the projection will be scaled downward. But if the rectangle is moved to the far side of the object (A'', B''), the projection will be scaled upward.

Windowing (viewing just part of the object) can be performed by using the rectangular solid originally chosen to enclose just the section of the object to be viewed. Then P(P_X, P_Y, P_Z) in Equation (5) becomes

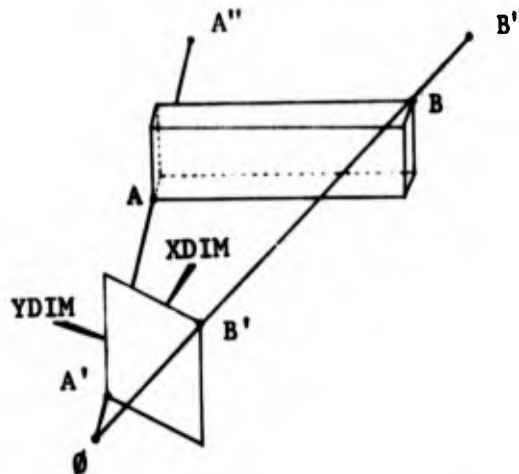


Figure 2. Geometry of Scaling

any arbitrary point within the window. Any other point, Q, within the object, but not the window, will be projected outside the projection rays and will not fall on the rectangle A'B'.

Once all the points in the object have been projected onto the plane, lines connecting these points can be drawn in the plane, thus projecting the whole object; however, the object is considered to be transparent, as all lines are drawn whether these lines can be seen by the observer or are actually hidden by some part of the object. The next important step is to determine which line segments are hidden from view. Then these segments can either be eliminated from the drawing or will show up as dashed.

b. Hidden Lines

One way of solving the hidden line problem requires that all surfaces in the three-dimensional object be approximated by flat planes which are called faces. The object can contain any number of faces, the boundaries of which are called edges, and must be approximated by straight lines. Edge ends are called vertices, and edges and vertices may be common to several faces or to only one face, as in describing an object shell. Faces may contain inner edges as well as outer edges, where the inner edges can define a window (a cutout or a transparent section). If several faces are coplanar, they can be combined into one face description. Using Equations (1) through (4), all the vertices in the object are projected onto the observation plane. By finding all edge intersections on this plane (Figure 3), the polyhedra problem can be simplified into the problem of determining whether a point is hidden by a face.

This simplification can readily be shown by observing that the edge connecting vertices V_1 and V_2 is composed of segments V_1I_1 , I_1I_2 , I_2I_3 , and I_3V_2 , where the points I_i are all the intersection points between this edge and all other edges. Since the I_i 's are all the intersections, there can be no intersections on the individual segments. The visibility of segment j is equivalent to the visibility of any point in segment j , since visibility can change only at a point of intersection. Hence, if P_j is visible, segment j is visible.

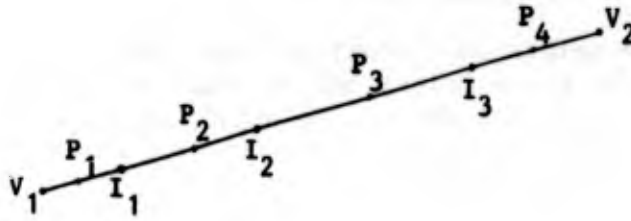


Figure 3. Edge Intersections

In order to determine the visibility of a point, one must first define the property of being covered. A point is said to be covered by a face if, in the observer's plane, the point falls within the area enclosed by the edges of the face. This property is easily determined by drawing a horizontal line through and to the left of the point and counting the number of edges crossed. (If an edge vertex is crossed, it is counted only if the edge is below the point.) If this number is odd, the point is covered; otherwise, it is not. Figure 4 contains some examples of determining the coverage of a point. Points P_1 and P_5 are shown to be covered by faces 1 and 2, respectively, while the other points are not covered.

Since faces are closed polygons, the total number of horizontal crossovers (to right as well as left) must be an even number (or zero). If an even number of crossovers is on the left, there also must be an even number on the right. And if an odd number of crossovers is on the left, there must be an odd number on the right. This property is observable as long as a face is described as a series of connected edges where the last vertex in the last edge is the same as the first vertex in the first edge (i.e., a closed figure). If face windows are described with this in mind, coverage is still observable. In Figure 5 the face is described by this ordered set of points 1, 2, 3, 4, 5, 1, 6, 7, 8, 9, 6,

1. Since face windows must also be closed polygons, the last point must be the same as the first. This causes the line between points 1 and 6 to be defined twice; as line 1, 6 and line 6, 1. This double line is called a pseudoedge and is ignored during actual plotting. These double lines can be thought of as a narrow cut allowing the window to be part of the outside. In this example, points P_2 , P_4 , and P_5 are covered while points P_1 and P_3 are not. The algorithm allows the window point, P_3 to show through.

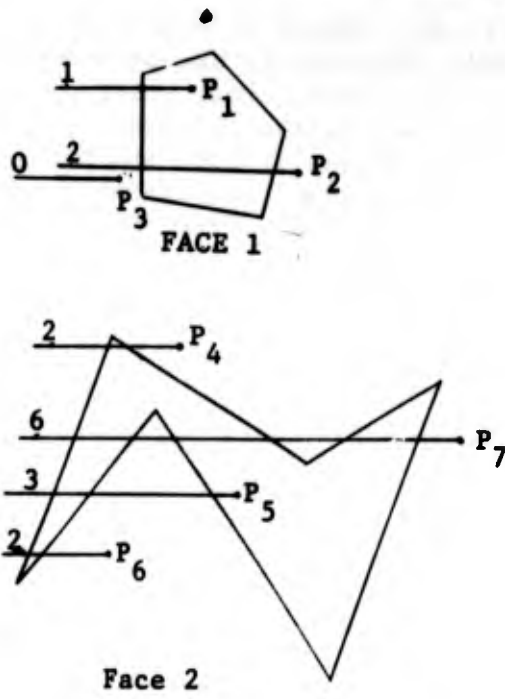


Figure 4. Coverage Geometry

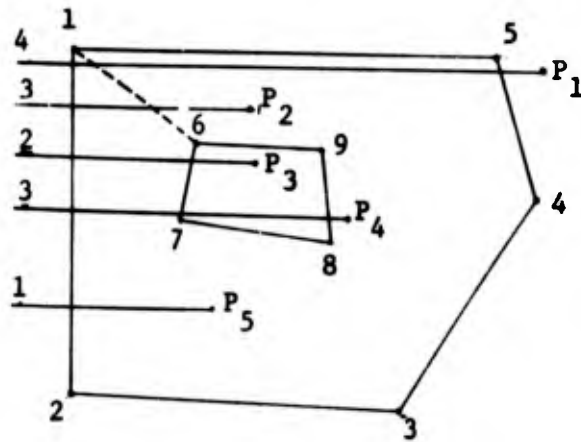


Figure 5. Window Coverage Geometry

If a point is not covered by any face, it is visible with no further tests required. But once it has been determined that a point is covered by a face, in order for that point to be visible it must be on the same side of the face as the observer's eye. This can be determined by putting the coordinates of both the point P_j and the observer's eye \emptyset in the equation of the plane containing the face. The results, D_{P_j} and D_{\emptyset} , are the signed distance from the face to P_j and \emptyset , respectively. If D_{P_j} and D_{\emptyset} have the same sign (i.e., $D_{P_j} * D_{\emptyset} > 0$), the point is visible. Otherwise, it is not.

The normal to the plane is determined by the cross-product of two of the edges in the plane. If $P_1 (X_1, Y_1, Z_1)$, $P_2 (X_2, Y_2, Z_2)$, and $P_3 (X_3, Y_3, Z_3)$ are three vertices of the face and V_1 and V_2 are the vectors connecting these points, respectively, then

$$V_1 \times V_2 = A_i + B_j + C_k \quad (6)$$

$$\text{where } A = a_{12} a_{23} - a_{13} a_{22}$$

$$B = a_{13} a_{21} - a_{11} a_{23}$$

$$C = a_{11} a_{22} - a_{12} a_{21}$$

$$\text{and } a = \begin{bmatrix} (X_1 - X_2) (Y_1 - Y_2) (Z_1 - Z_2) \\ (X_1 - X_3) (Y_1 - Y_3) (Z_1 - Z_3) \end{bmatrix}.$$

The equation of the plane containing this face is

$$A_x + B_y + C_z + D = 0 \quad (7)$$

where D is the distance from the origin to the plane. So

$$D = -(A_{x_1} + B_{y_1} + C_{z_1}). \quad (8)$$

The distance from the observer's eye to the plane is $D_{\emptyset} = A_{\emptyset_x} + B_{\emptyset_y} + C_{\emptyset_z} + D$ and the distance from point P_j to the plane is

$$D_{P_j} = A_{P_{j_x}} + B_{P_{j_y}} + C_{P_{j_z}} + D.$$

If $D_{\emptyset} * D_{P_j} > 0$, the point is visible.

If $D_{\emptyset} * D_{P_j} < 0$, the point is hidden

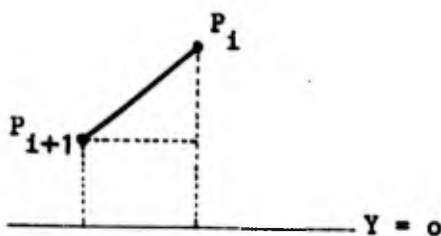
and the visibility of P_j with respect to \emptyset is determined.

Since the visibility of P_j determines the visibility of segment j , the three-dimensional object can be drawn in perspective with the hidden lines identified and either eliminated or dashed.

c. Projection Area

Once an object has been drawn in perspective, its projected area can be found by making use of the same covered property described before. It has been shown that to be visible a line segment either must not be covered by any face, or if covered, must be in front of that face. A line segment which meets the first of these conditions is denoted as a perimeter segment. The collection of perimeter segments generated in this manner can be arranged to form a closed polygon called the projection or "shadow" of the object.

The area covered by this polygon can be found by an integration technique shown in Figure 6. The area under the line from P_i to P_{i+1} is the sum of the areas of the square and the triangle.



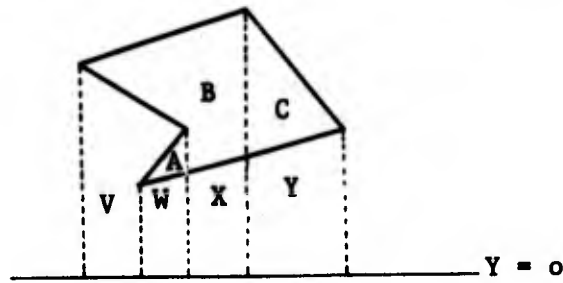
$$\begin{aligned} \text{AREA} &= (X_i - X_{i+1}) Y_{i+1} + \frac{1}{2} (X_i - X_{i+1}) (Y_i - Y_{i+1}) \\ &= (X_i - X_{i+1}) \left(\frac{Y_i + Y_{i+1}}{2} \right) \end{aligned}$$

Figure 6. Integration Methodology

To find the area of the projected polygon, the equation in Figure 6 can be applied to every line segment in the perimeter, giving

$$\text{Total Area} = 1/2 \left| \sum_{i=1}^n (X_i - X_{i+1}) (Y_i + Y_{i+1}) \right|. \quad (9)$$

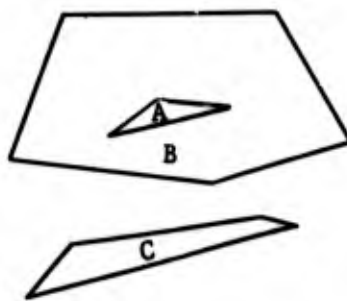
Since the polygon is closed, the areas not enclosed will cancel out (see Figure 7).



$$\begin{aligned}
 \text{Enclosed Area} &= (C+Y) + (A+B+V+W+X) \\
 &- (A+V+W) + (A+W) \\
 &- (W+X+Y) \\
 &= A+B+C
 \end{aligned}$$

Figure 7. Area Computation Methodology

Some objects may produce disjointed and/or window perimeters. Equation (9) is applied to each perimeter separately and then combined by a third application of the cover property. In Figure 8 the areas enclosed by the three perimeters are (A+B), A, and C.



$$\text{Area} = (A + B) + C - A = B + C$$

Figure 8. Disjointed and Window Perimeters

If a perimeter is covered by any other perimeter polygon, it encloses negative area. If not covered, it encloses positive area. In the example shown in Figure 8, the perimeter enclosing A is covered by the polygon (A + B). The other two perimeters are not covered. The resultant area sum is then

$$(A + B) + C - A = B + C.$$

Figures 9 through 15 show the overall flow diagrams of the program. Detailed flow diagrams are contained in Appendix II.

3. INPUT FORMAT

The target must be drawn on a grid in two orthogonal views to determine the coordinate of the end points of the line segments that define a face of the target. The input needed is shown below (also see Appendix I).

Card A

Columns 1 - 5 :	J-Number of points in figure ≤ 600 , $J \neq 0$	
8 :	ID3-Debug flag e	
10:	I \emptyset - Offset flag	
11 - 15:	Offset X	} Used on all points, if I $\emptyset \neq 0$
16 - 20:	Offset Y	
21 - 25:	Offset Z	
26 - 30:	FC-Factor converting input units to engineering units	
35:	JDID - Flag (not used on CRT plotter)	

Card B

Columns 1 - 5 :	X1	} As many cards as required to describe the J points; the order of the points determines the point number used on card D.
6 - 10:	Y1	
11 - 15:	Z1	
16 - 30:	X2, Y2, Z2	
31 - 45:	X3, Y3, Z3	
46 - 60:	X4, Y4, Z4	
61 - 75:	X5, Y5, Z5	

Range is determined from these points unless JDID $\neq 0$.
All points given need not be used on a D card. If I $\emptyset \neq 0$, each ordinate is offset by the appropriate value.

The objects to be presented may be described in several ways:

- 1 Describe each face in the object in terms of the points on card B,
- 2 Describe a solid object in terms of its size, location, and orientation.
- 3 Repeat, relocate, and reorient a previously described object.

MAIN

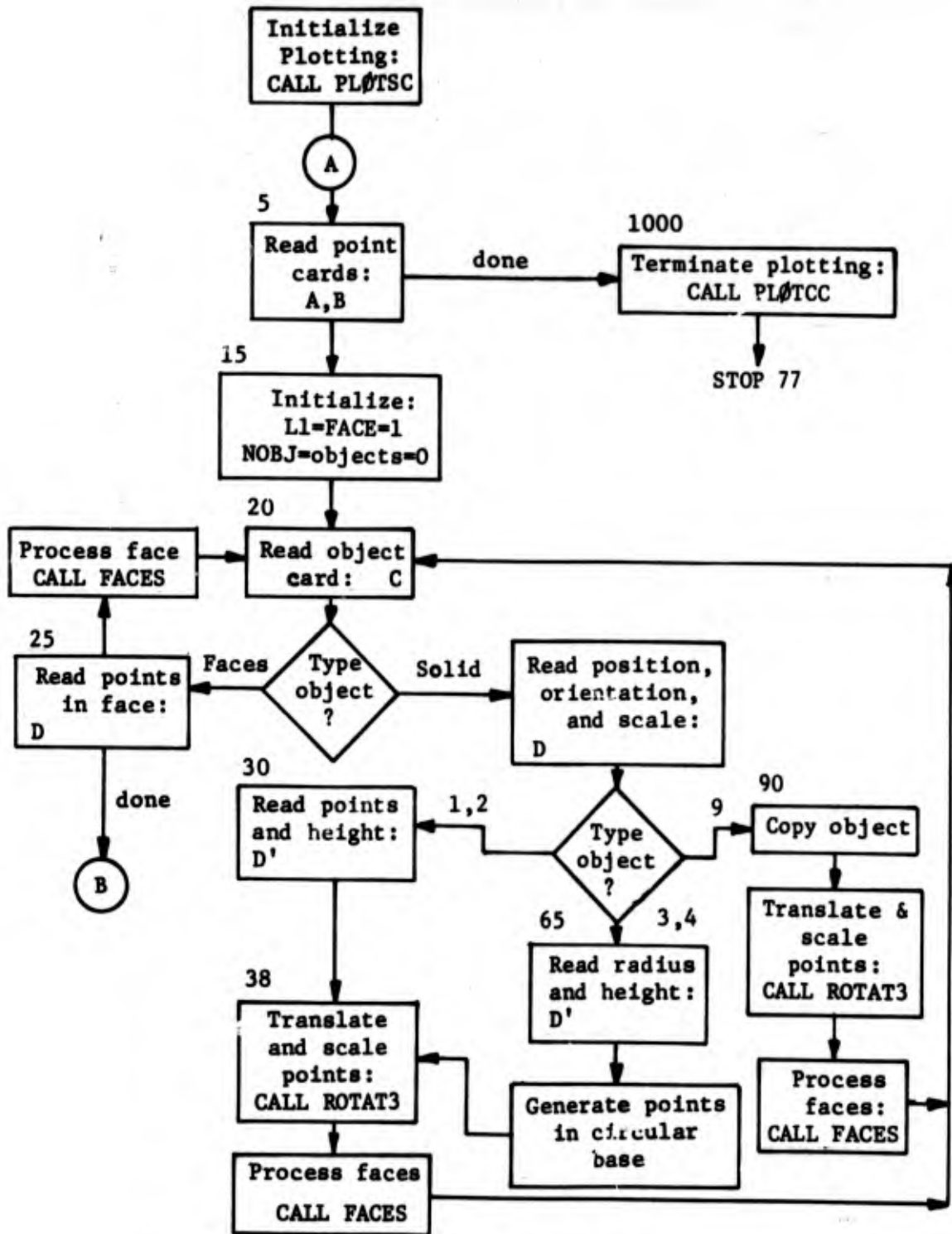


Figure 9. Subroutine MAIN

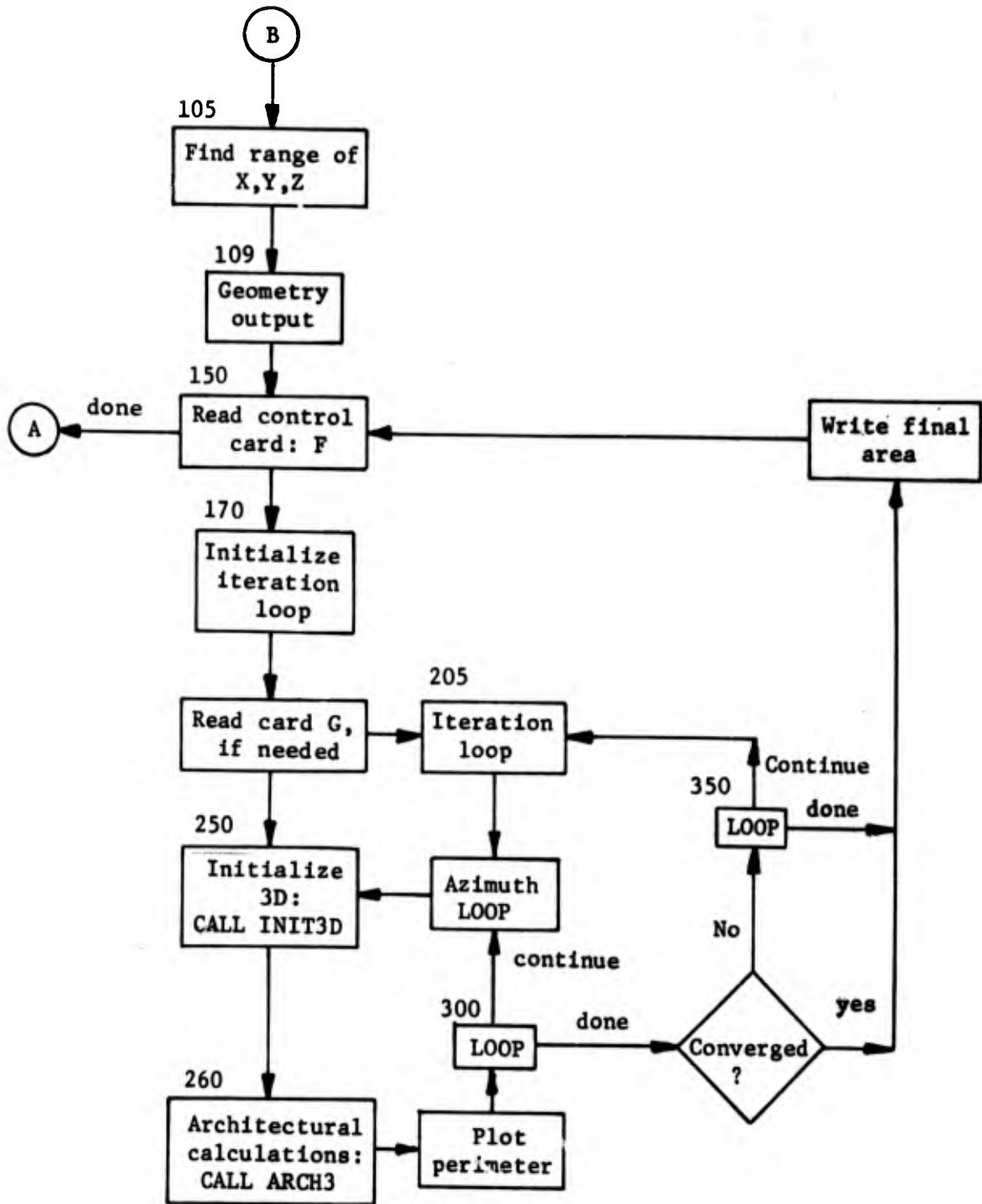


Figure 9. (Concluded)

ARCH3

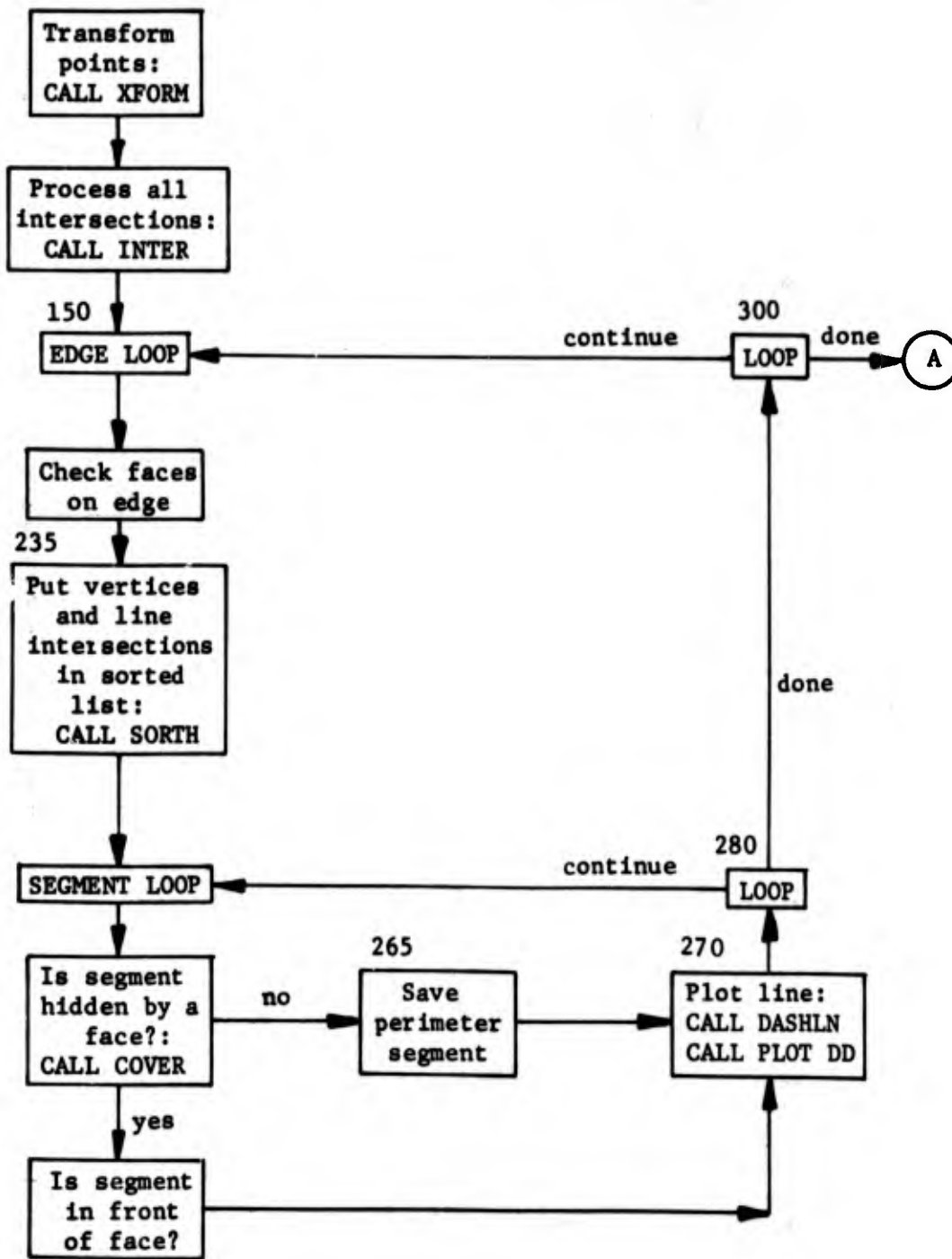


Figure 10. Subroutine ARCH3

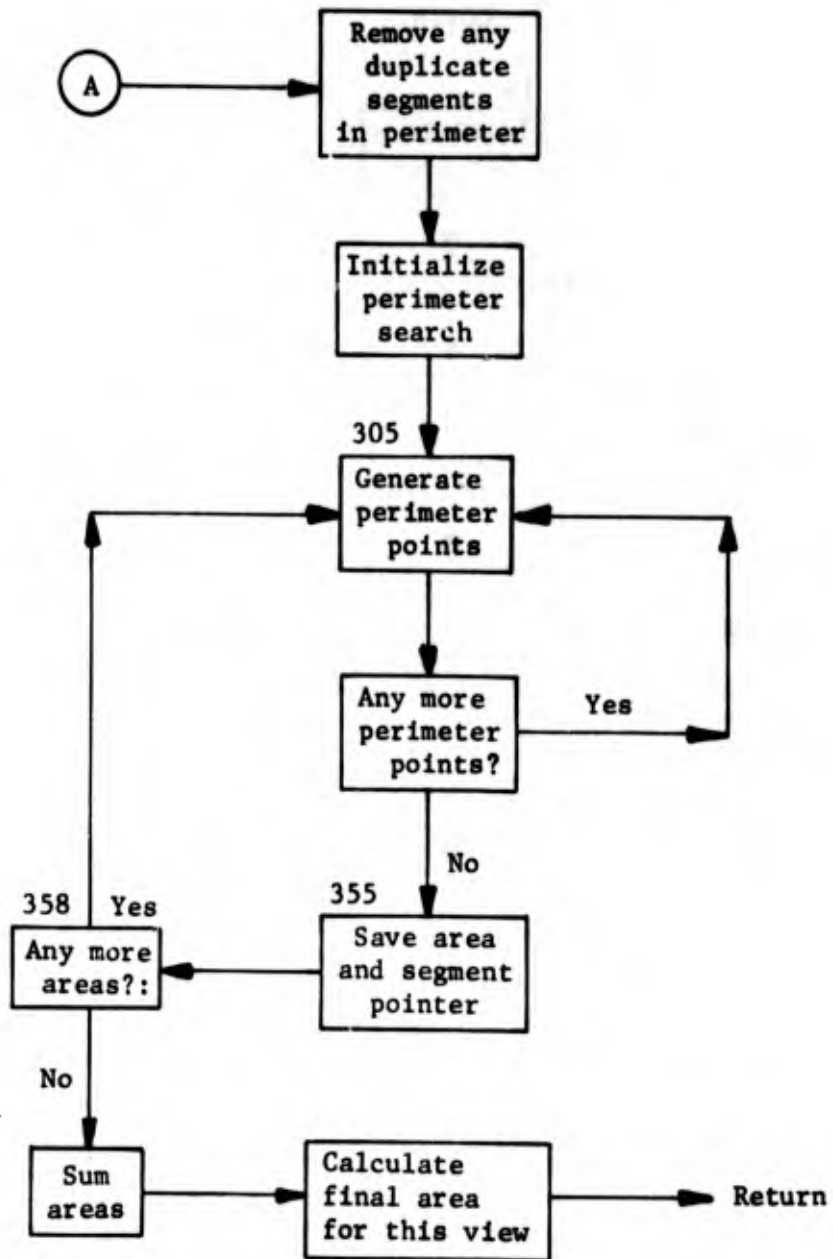


Figure 10. (Concluded)

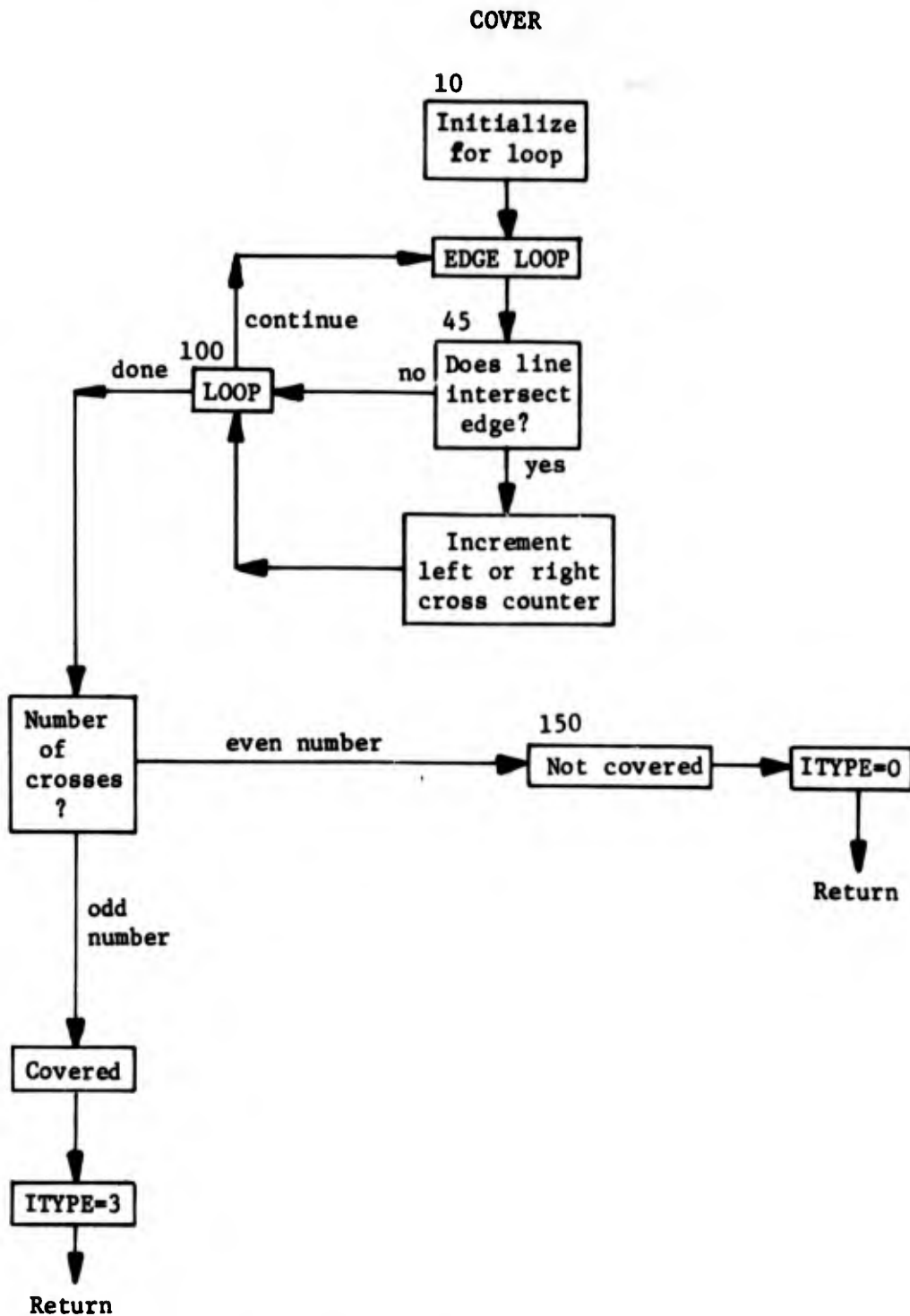


Figure 11. Subroutine COVER

INTER

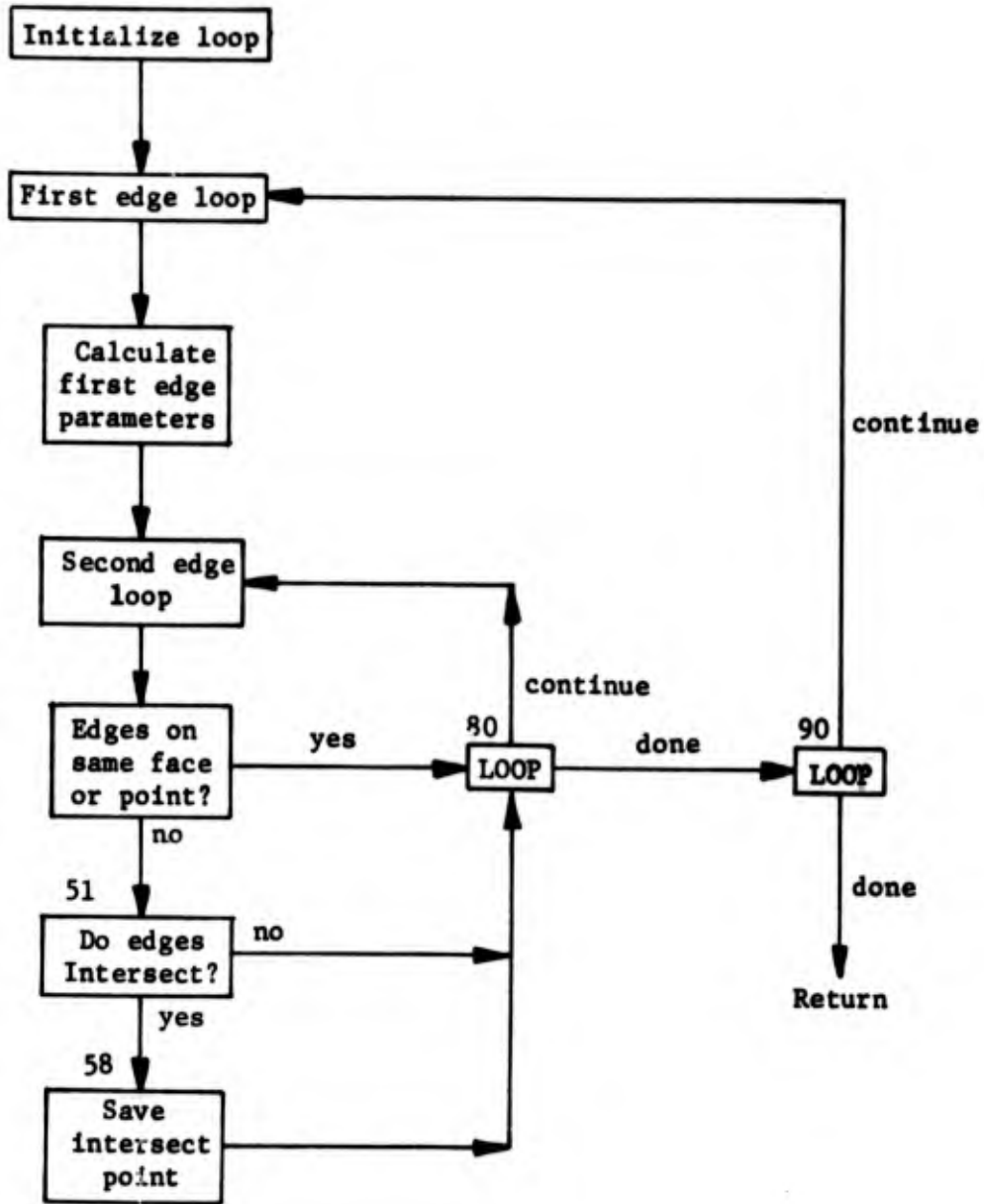


Figure 12. Subroutine INTER

SORTH

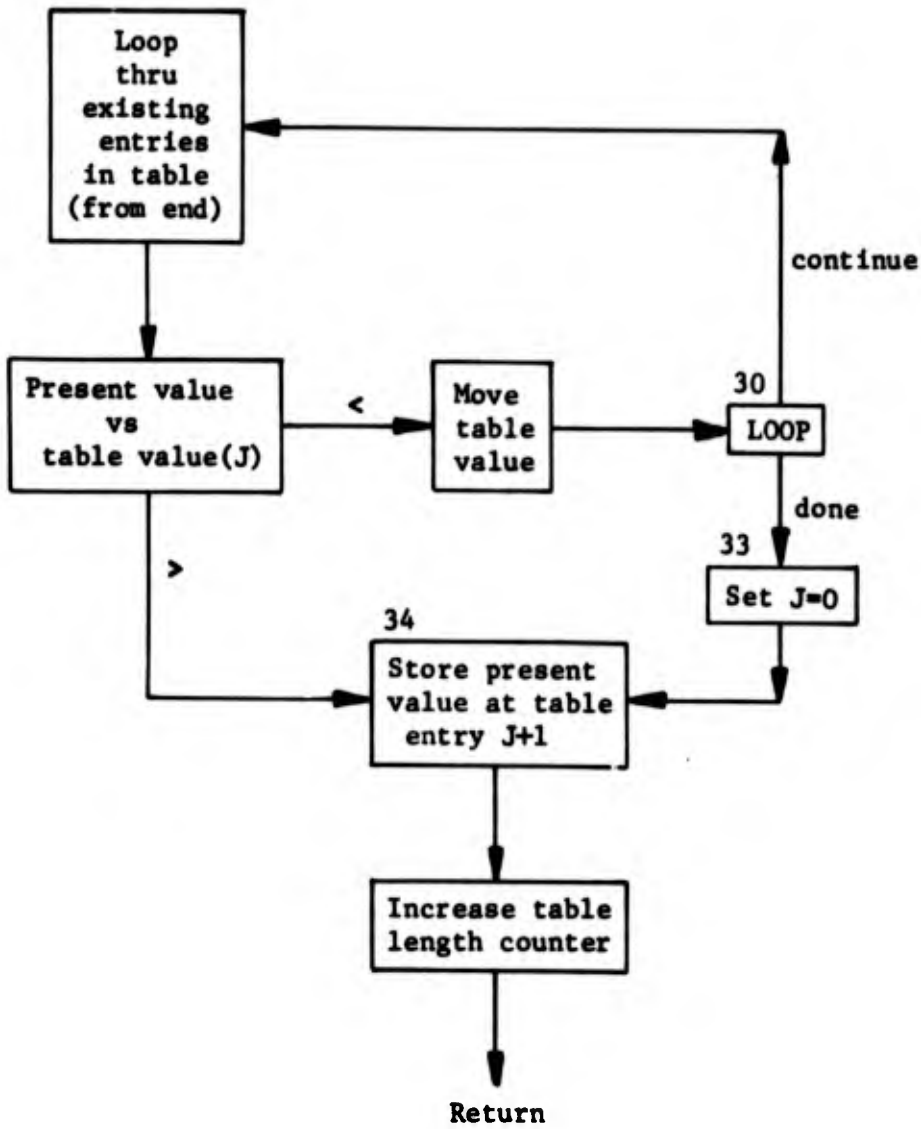


Figure 13. Subroutine SORTH

PLOTDD

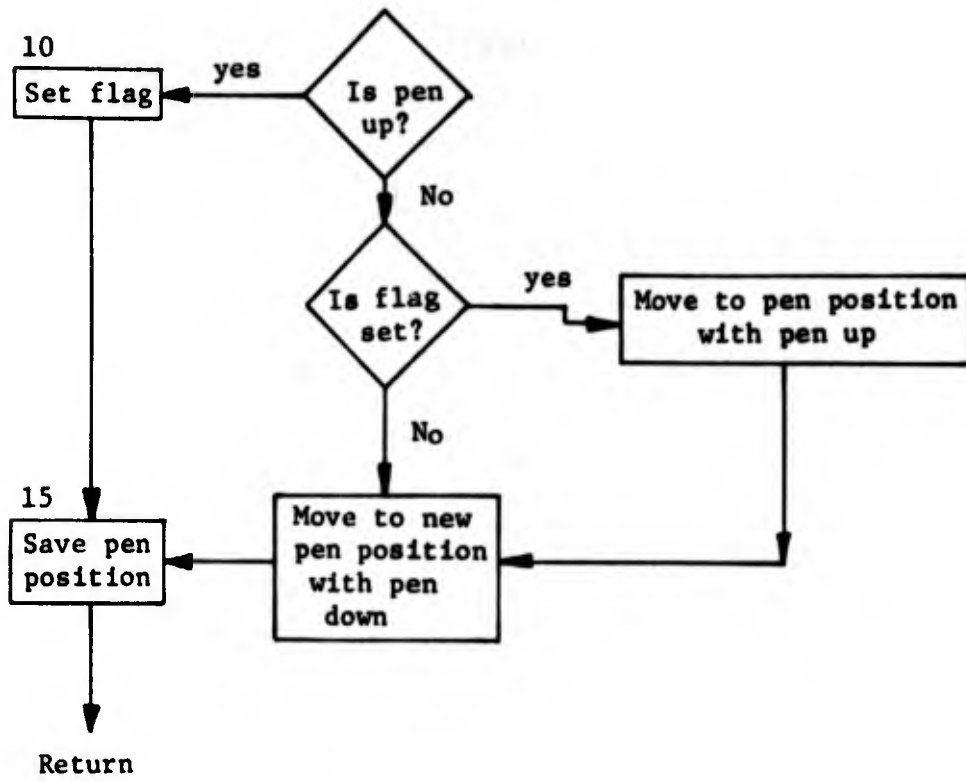


Figure 14. Subroutine PLOTDD

ROTAT3

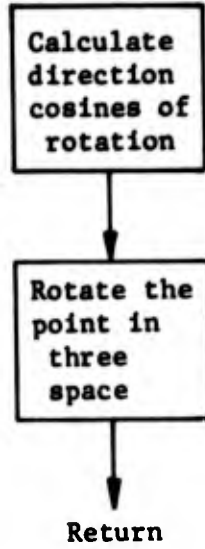


Figure 15. Subroutine ROTAT3

a. Faces

Card C

Columns 1 : 0 (or blank)
 2 - 5 : N - Number of points in the following face ≤ 25
 9 - 10: J \emptyset BJ - Non-blank, if this face is the first face in a new object.

Card D

Columns 1 - 3 : N₁
 4 - 6 : N₂
 . . .
 73 - 75: N₂₅ } Contiguous point numbers describing the face. There will be N numbers on this card. If an edge is included more than once, it is a pseudo-edge and is not drawn. N_i is the ith point on card B.

There must be a card C and D for each face to be described ≤ 300 .

b. Solid

Card C

Columns 1: K - Type solid
 2 - 5: N - Number of points in the following object base ≤ 20
 9 - 10: J \emptyset BJ - Object number (must be one number greater than previous number) (If blank, this solid is part of previous object)

Card D

Columns 1 - 5 : X₀
 6 - 10: Y₀
 11 - 15: Z₀ } Reference point (location) of object (See Figures)
 16 - 20: θ
 21 - 25: ψ
 26 - 30: \emptyset } Orientation (rotation) of object in degrees.
 θ = Azimuth about Z - axis: Turn) From + axis
 ψ = Pitch about Y - axis: Tilt) to minus axis
 \emptyset = Roll about X - axis: Aspect) the angle is + when CCW

31 - 35: F - scale factor

If K = 1

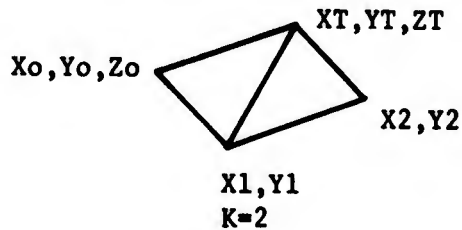
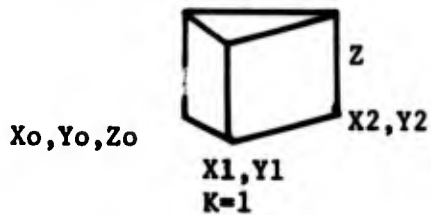
Card D'

Columns 1 - 5 : X₁
 6 - 10: Y₁
 . . .
 . . .
 X_{n-1}
 Y_{n-1} } The remaining points in the object base with reference to X₀, Y₀, Z₀ (before scale and rotation). Use as many cards (≤ 4) as required (Columns 1 - 70) to describe the N points (7 points per card).
 Z - Height of object

If K = 2

Card D'

Columns 1 - 5 :	X_1	} Same as for K = 1
6 - 10:	Y_1	
	.	
	.	
	.	
	X_{n-1}	} Coordinates of top point of object with reference to X_0, Y_0, Z_0
	Y_{n-1}	
	X_t	
	Y_t	
	Z_t	



If K = 3

Card D'

Columns 1 - 5 : R - Radius of circular base of N points centered X_0, Y_0, Z_0 . If N (see card C) is blank, 8 points are used.
6 - 10: Z - Height of object

If K = 4

Card D'

Columns 1 - 5 : R - Radius of circular base (See K = 3)
6 - 10: Z - Height of object (above center)



c. Repeat

Card C

Columns 1 : 9
2 - 5 : N - Object number to be repeated
9 - 10: JOBJ non-blank if start of new object

Card D

Columns 1 - 5 : X_0 }
6 - 10: Y_0 } Reference point }
11 - 15: Z_0 } } See b.
16 - 20: θ }
21 - 25: ψ } Orientation angles }
26 - 30: ϕ }
31 - 35: F - scale factor

No Card D'

All the parts of object N are repeated, further rotated, and further scaled, and placed at X_0 , Y_0 , Z_0 (which corresponds with the first point in the first face in object N).

Card E

Column 5 : $\begin{pmatrix} \text{Blank} \\ 2 \end{pmatrix}$ - End of face data. $\begin{pmatrix} \text{Do not} \\ \text{Do} \end{pmatrix}$ write geometry tables.

The above cards describe the geometry.

Card F

Columns 1 - 5 : P1 - Factor converting input units to plotter units $\neq 0$.
6 - 10: P2 - Plot reorigin (not used on CRT plotter)
11 - 20: θ - Elevation angle (degrees) of observer (at origin of figure).
21 - 30: E - Area convergence factor (input units), or (if negative) - I
- Number of iterations to be run and E is set to .5 (Not used if JR is given).
31 - 32: JR - Number of azimuth inputs (optional) ≤ 20 .
33: IM - Non-blank if only object types change (1 view only)
34: I1 - 1, if area calculations are desired.
35 - 40: R - Range from origin of figure (optional). Program uses a standard range of 1000.
41: \underline{S} - Symmetry flag { X - X axis
B - Both X and Y Axis

- 42: I2 - { 1, if perspective plotting is desired
(Iteration 1 only)
2, if perspective and perimeter plotting
is desired.
- 43: ID1 - Debug flag 1.
- 44: ID2 - Debug flag 2.
- 46: ID4 - Debug flag 4.
- 48 - 53: P3 - Plot reorigin before run (not used on CRT
plotter).
- 56 - 70: INOBJ - Object type (for each of the objects)

IE: Column 56 for Object 1
57 for object 2
. . . .
. . . .
70 for object 15

TYPE: 0 - Object is a target (blank column = 0)
1 - Object is a frame
2 - Object is a shield
3 - Object is ignored

A Card F is required for each elevation angle.

Card G (provided if JR is not blank)

Columns 1 - 10: AZM ₁	} JR azimuth angles. If JR is greater than 8, additional G cards follow. JR ≤ 20.
11 - 20: AZM ₂	
. .	
. .	
71 - 80: AZM ₈	

If this option is used, E and S on card F should be blank.

NOTE: Do not provide a card G if JR (columns 31-32 on card F)
is blank.

Card H

Columns 1 - 70: Blank

Jobs can be stacked by inserting additional jobs (cards A through H)
here.

Card I

Columns 1 - 70: Blank

Card J

Columns 1 - 70: Blank

In general, input variables starting with letters I through M are right adjusted integers. Otherwise, a decimal point is required, i.e., FC, offsets, X, Y, Z, P1, P2, Ø, E, and P3 require decimals.

4. PROGRAM OUTPUT

The program produces perspective plots of the target under study as well as a perimeter plot. Printed output consists of averaged area of the target from the given elevation angle. This output is in the following form:

AFTER (I4) ITERATIONS, THE AREA = (F8.3)

which gives the iteration number and the area in engineering units.

If additional output is desired, ID1 (card F) may be punched with a 1 or a 2. If ID3 (card A) is a 1, the coefficients of each face are also printed. Other debug options are available as shown in Table I.

TABLE I. DEBUG OUTPUT

ID VALUE	1	2	3	4
0	Final Area			
1	θ , AREA (plot) if in trouble, AREA by iteration	X, Y projected for each point. FINAL PERIMETERS	COEFFICIENT MATRIX and FACE EQUATIONS	INTERSECTION POINT table
2	θ , X, Y, AREA (plot) for each view	SEGMENTS of Perimeter		
3		Interaction POINTS by EDGE		
4		SEGMENTS of Perimeter and PERIMETER by PIECE		
5		AREA by segment		
6		"COVER" and "HIDDEN" parameters for each segment		

If ID contains a value ≥ 1 , all the outputs for 1 are given: i.e., if ID2 = 6, all outputs for ID2 are provided.

The program uses the STOPS listed in Table II.

TABLE II. PROGRAM STOPS

STOP	REASON
77	Normal termination
1234	Point number of a face description is too large (card D)
1357	More than 100 points in an object being repeated
2121	More than 25 points on a face (card C)
2442	Error in object number being repeated (card C)
3333	More than 15 objects
4444	More than 900 edges
5555	More than 300 faces
6736	More than 20 points in a solid's base (card C)
6761	More than 600 points (caused by solid)
6767	More than 600 points (card A)
7654	More than 50 segments on one line edge
7766	More than 99 points (198 segments) in perimeter

5. PROGRAM APPLICATION

This program can be used in determining the vulnerability of an aircraft. In this application a generic fighter aircraft was chosen as the target. No shields were used and the outer shell was ignored. First a drawing was made of the vulnerable components of the fighter. The center of the nose tank was chosen as the origin, and the X axis ran the length of the fighter to give one axis of symmetry. (It is assumed that only a direct hit of a vulnerable component will kill the fighter.) Then these components were approximated by use of the components standard solids. (Solid types 2, 3, and 4 were not used in this application.) The complex nose tank could not be approximated by a standard solid; therefore, it was broken into 30 points and 38 faces. (Because some faces were tilted, they had to be broken into several faces to guarantee point planarity within a face.) The remainder of the components consisted of 11 standard solids. The nose tank required 83 cards for its description while only 33 cards were required for the rest of the description. These cards, which are listed in Figure 16, and a card F are used to request a view from an elevation angle of 30 degrees and at an azimuth of 45 degrees. The resulting drawing of this target is shown in Figure 17.

5
 25 29 30 25 29
 3
 14 25 30
 5
 26 14 25 26 14
 5
 26 14 13 26 14
 5
 26 12 13 26 12
 5
 12 26 27 12 26
 5
 28 12 27 28 12
 5
 28 12 11 28 12
 5
 28 10 11 28 10
 7
 28 18 10 28 18 28 10
 5
 28 18 19 28 18
 1 10 2
 -.970 1.210 -90.0 1.0
 -.445 .810-1.26 1.03-1.26 .695-.710 .500-.495 -.710-.500-1.26-.695
 -1.26-1.03-.445-.810 2.85
 1 4 3
 -1.89 .980-.240 -90.0 1.0
 -.660-.340-.430-.730 -.380 1.34
 1 6 4
 -3.88 1.210 -90.0 1.0
 -.445 .810-.710 .500-.495 -.710-.500-.445-.810 1.40
 1 5 5
 -3.86 -.780 -90.0 1.0
 .150 .485-.320 .550-.320-.550 .150-.485 1.44
 1 10 6
 -5.32 1.210 -90.0 1.0
 -.445 .810-1.26 1.03-1.26 .695-.710 .500-.495 -.710-.500-1.26-.695
 -1.26-1.03-.445-.810 1.06
 1 10 7
 -6.47 1.210 -90.0 1.0
 -.445 .810-1.26 1.03-1.26 .695-.710 .500-.495 -.710-.500-1.26-.695
 -1.26-1.03-.445-.810 1.32
 9 7 8
 -7.86 1.210
 1 6 9
 -2.41 1.18 .100 1.0
 -1.51 -3.49 1.89-2.83 2.38-2.44 2.36 .31 .71 .295
 9 9 10
 -2.41-1.18 .395 180.0 1.0
 1 4 11
 -6.45 1.18 .105 1.0
 -1.37 -1.37 2.33 2.33 .280
 9 11 12
 -6.45-1.18 .385 180.0 1.0
 1.0 14. 30.0 1 15000.0 22
 45.

Figure 16. (Concluded)

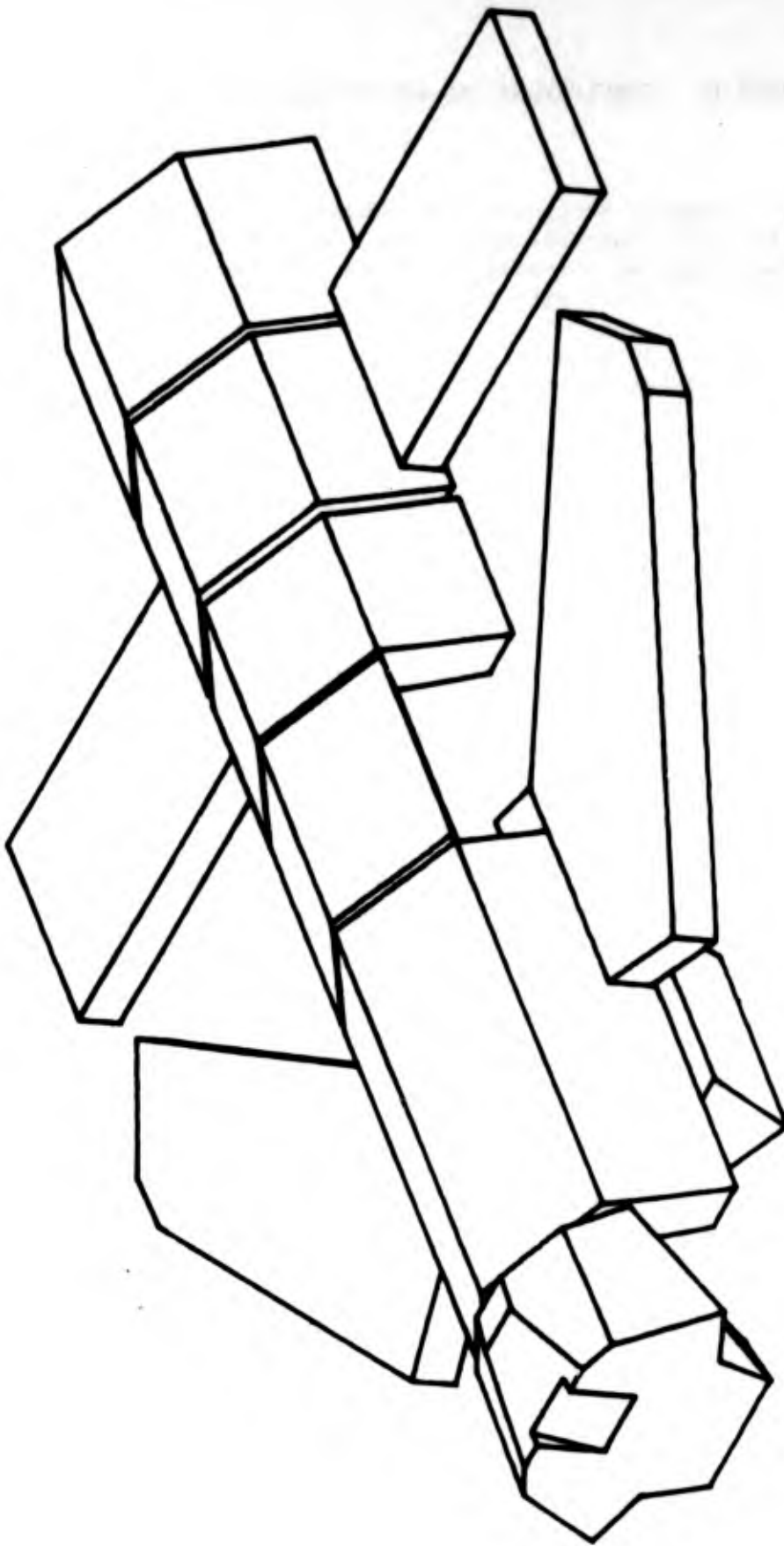


Figure 17. Fuel Tank - Generic Fighter Aircraft

SECTION IV. CONCLUSIONS AND RECOMMENDATIONS

1. CONCLUSIONS

In conclusion, a computer program was developed for rapidly performing target description and vulnerability studies. The program accepts input data in several forms, computes the presented area of a target from any viewing angle, and produces plots with hidden lines removed.

The program is written in modular form to permit future modification with minimal effort. State-of-the-art technology is employed in the target evaluation model.

2. RECOMMENDATIONS

Based on current target evaluation technology and the experience and knowledge acquired during the conduct of this program, it is recommended that the following items be investigated to further develop the capability to perform target evaluations:

- 1 Develop methods for using curved surfaces in the program.
- 2 Formulate additional input formats for special target cases.
- 3 Maintain program in highly efficient form by incorporating new technology into the program as it is developed.
- 4 Develop methods for combining digital and analog computer routines for time-sequencing control of dynamic target displays.

APPENDIX I

DETAILED INPUT FORMAT (See Section III, 3)

Card A: (I5, 2X, I1, 1X, I1, 4F5.0, I5)

J - The number of points to be read from card B. This value must not be zero (or blank); if all input is in the form of solids (i.e., no point input), J should be set to 1 and a blank card used for card B. This will define the first point as 0., 0., 0. and will never be used, except in the calculation of minimum and maximum point. If a 0., 0., 0. point is not in the range of the solid input, a non-blank card B should be used defining a more realistic dummy first point.

ID3 - If this is a 1, the coefficient matrix and face equations will be printed as they are calculated. This is an extra output option and need not be used unless the face geometry is being debugged. If all faces are defined by solids (rather than by points), this output is not needed.

IØ, ØFFSETX, ØFFSETY, ØFFSETZ - These are normally blank. But if IØ = 1 the offset values will be added to each point on card B.

FC - This factor converting input units to engineering units is only used in the calculation of the final area (i.e., area in input units times FC^2 equals area in engineering units). If FC is blank (or zero), it is set to 1.0.

JDID - This is a special flag for overlay plotting and should not be used with CRT output.

Card B: (15F5.0)

This card(s) defines the J input points as indicated by card A. At least one card must be present.

Xi, Yi, Zi - These are the first J points to be stored in PVXYZ and are in input units. They can be offset by using the appropriate option on Card A, but normally no offset is required. The points need not be in any order, and some may be defined but never used. However, the order the point appears in this list becomes the point's "point number". Columns 76-80 can be used for point number identification (user's aid only). Since there are five points to a card, this I.D. could be 001, 006, 011, etc. to identify the point number of the first point on each card. Blank fields are treated as zero, and (since points can be repeated and not used) points can be deleted from any card without causing any problem (other than wasting a point number).

Card C: (I1, I4, I5)

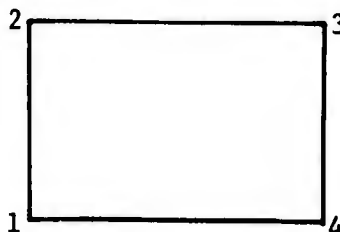
K - Type being described. If this is blank (or zero), a face is being described. If K is less than 5, a solid is being defined. If K=9, an existing object is to be repeated.

N - Number of points in the description (see Card D).

JØBJ - Object number, if different from the object number on the previous card C. The object number of the first card C is assumed to be 1. If the next card C has a blank (or zero) for JØBJ, that description will also be included as part of object 1. Whenever JØBJ is entered (non-zero), it must be exactly one increment greater than the previous object number. (Setting JØBJ to 1 on the second card C is not correct since the first card C is assumed to be object 1. A blank JØBJ on the second card C will include that description as part of object 1.) Only the objects having a unique type code on some card F need be identified; otherwise, all descriptions can be included under one object and JØBJ can be blank on all card C's. Another reason for using object numbers is that repeat cards can be used to repeat an object with similar geometry construction.

Card D (for faces): (2513)

Ni - The N point numbers, IFP, describing the face. The point numbers refer to the order in which the points were defined on card B. The point numbers must be given in either clockwise or counter-clockwise order around the face. All points given must be in a plane or the face should be broken into several triangular faces by means of pseudo edges. For example, to describe the following (tilted) face,



the following could be entered:

Card C: 3

Card D: 1 2 3 1 3

Card C: 3

Card D: 1 4 3 1 3

This double description of edge 1-3 defines a pseudo edge which will not be plotted.

If the face was not tilted (i.e., same Z or Y or X values for each point), a pseudo edge is not required and the following could be entered:

Card C: 4

Card D: 1 2 3 4

NOTE: Since the first three points given on card D define the plane on the face, they must be unique; i.e., the pseudo edge should be defined at the end of the card.

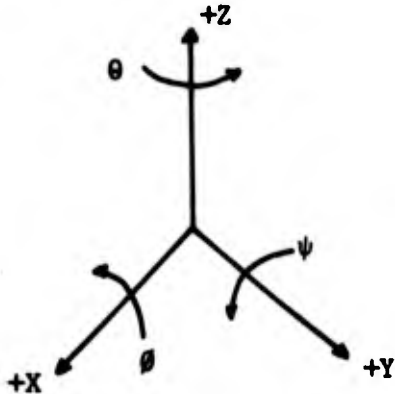
For the tilted face given above, card D should not be: 1 3 1 2 3

Card D (for solids): (7F5.0)

Xo, Yo, Zo - The reference point for this solid. This becomes the location and first point for the solid.

NOTE: All points generated by solid descriptions are included in PVXYZ, the point array initiated by card B, and so are included in point limitation count.

θ , ψ , ϕ - The orientation of the solid in degrees.



θ = Azimuth or turn

ψ = Pitch or tilt

ϕ = Roll or aspect

When looking down an axis from the plus side to the minus side, the corresponding angle is plus when counterclockwise and negative when clockwise.

F - This scale factor (FCT) is used only if the coordinates given on the following card(s) are not in input units; then each coordinate will be multiplied by this factor. If F is zero (or blank), it is set to 1.0.

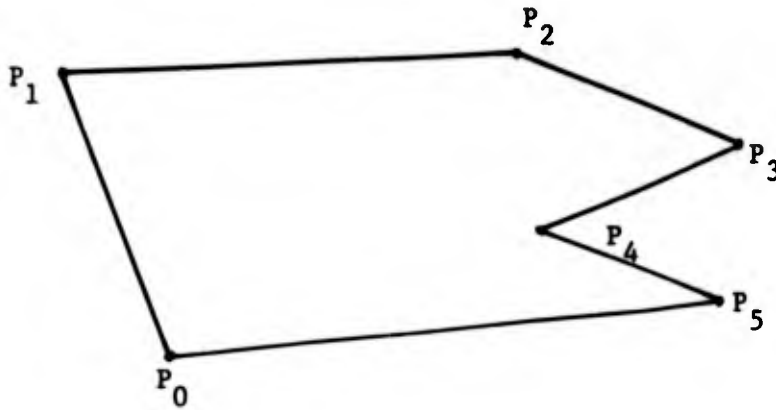
NOTE: All units are in input units unless otherwise denoted.

The type of solid (K, on card C) being described is determined as follows:

K = 1: Right polyhedron

This normally is the most common solid used. If the base of the solid is congruent to the top, and the lines connecting the common points form rectangles, the solid is a right polyhedron.

The base is initially described as being the X-Y plane, with translation, scaling, and rotation being accomplished by the information given on card D. There may be as many points (within reason) in the base as desired, one of which is the reference point.

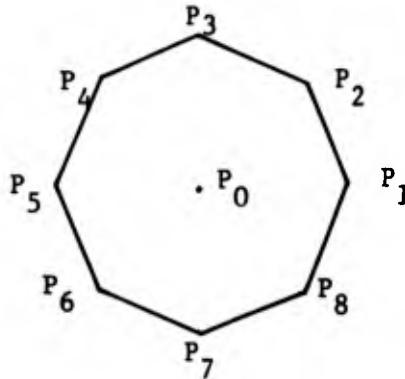


K = 2: Pyramid

This solid has a similar base to that described above, but the top is a single point instead of a plane.

K = 3: Right Cylinder

This type of solid is a right polyhedron whose base is (an approximation to) a circle of N (see card C) points centered about the reference point. N need not be given; if it is not given, the circle will contain eight points. Note that the reference point for this solid is the center of the (circular) base. As is the case for the right polyhedron, the top of the solid is assumed congruent to the base and is in the X-Y plane until translated (by the reference point), scaled (by the factor), and rotated (by the orientation).



K = 4: Right Cone

This solid has a similar base to that described above, but its top is a single point (right) above the base center.

Card D': (14F5.0)

- X1, Y1 - The N-1 points needed to complete the base of the solid (in the X-Y plane). The points must be given in either clockwise or counterclockwise order starting from (but not reentering) the reference point. The reference point is assumed to be at 0, 0, 0.
- Z (not used for type 2) - This is the height of the solid and is the distance between the solid's base and top.
- XT, YT, ZT (Type 2 only) - This is the solid's vertex and is given in three-space with respect to the reference point (i.e., assuming the reference point is 0, 0, 0).
- R (types 3 and 4) - This is the radius of the (circular) base.

Repeat Card

If K (on card C) is a 9, a repetition of a previously defined object is accomplished.

N is the number of the object to be repeated. This number is determined by JØBJ on previous card C's. The object may consist of one face, many faces, several solids, or any other combination of the above types. The reference point of an object is the first point in the object. If the object contains only solids, this first point is the reference point of the first solid, defined in that object (i.e., the one with a non-blank JØBJ).

JØBJ on the repeat card determines whether this new (repeat) description starts a new object definition. If not, this description becomes a part of the object being defined on the previous card C.

A card D is used following a repeat card to define the translation, rotation, and scale of the new description. If the original object had parts that had been rotated or scaled, they will be further rotated about the object's reference point (see above definition) and further scaled.

Card E: This is actually a card C that has N less than 3. Since no face can have less than three points for its definition, this card terminates the geometry input section.

If N is a 2, the geometry tables that had been generated are printed out. (Appendix IV contains a description of these tables.)

Card F: (2F5.2, 2F10.3, I2,2I1, F6.2, A1, 5I1, 1X, F6.2, 2X, 15I1)

P1 - This plot scale factor is used for plotting purposes only and

will not affect the final printed area. P1 should be chosen so that, when an input value is multiplied by P1, the result is less than 8. In fact, the difference between the maximum scale value and the minimum scale value should be less than 8. P1 is used to convert input units to inches. P1 should not be blank. If no scaling is needed, 1 should be entered.

- Ø - This is the elevation angle of the line of sight to the target's origin measured from the X-Y plane of the target. It is entered in degrees.
- E - This is the area convergence factor in input units, if an iterative run is being made. If the average target area seen after *i* iterations is within E of the previous average, then the run is considered to have converged. The program will terminate the run after six iterations in any case. Another method of running is to indicate the maximum number of iterations to be run. A negative number in the E field will indicate this option (i.e., if -2. is entered for E, two iterations will be run). In this alternate mode, the program will also terminate the run if the target areas after two consecutive iterations differ by less than .5. If the JR option is being used, E is ignored.
- JR - This is the number of azimuth angles entered on the next card (card G) to view the target from particular azimuths (instead of iterating).
- IM - This flag can be used to save a computer run time. If the only change on this card F from the previous card F is in columns 56-70 (object type), a 1 can be punched in this column).
Note: This can only be used if JR is 1.
- II - This flag indicates whether or not the area of the target is to be calculated. If left blank, the most that should be expected from the run is a perspective plot.
- R - Range from the target's origin in input units. Normally, this is blank and the program will use 1000. If some smaller range is desired, it may be entered. (Larger values of R will not appreciably affect the results.)
- S - If the geometry is set up so that the target is symmetric along the X axis (the X axis running through the center of the target), the character X can be punched. If the target is symmetric along both axes, the character B can be punched. This symmetry flag is only used to reduce the number of views needed in an iteration to calculate the average area.

I2 - This flag indicates whether plotting is desired. A 1 will give perspective plots, and a 2 will give both perspective and perimeter plots. If an iterative run is being made, plots will be produced during iteration 1 only.

ID1 } - Debug output flags. See Section III, 4. Normally, ID1 is a 1
 ID2 } or 2 while ID2 and ID4 are blank.
 ID4 }

INØBJ - This defines the types for the objects in the run. A blank or zero column indicates that the corresponding object is part of the target. A 2 indicates the object is a shield; a 1 indicates that the object is just a frame. If an object is to be ignored completely during this run, a 3 should be punched in the corresponding column.

Card G: (8F10.4)

AZM - These are the azimuths at which a view is to be made. If JR on card F is blank, this card must not be entered. Otherwise, views will be taken from the first JR fields on the card.

Card H:

This is a card F with P1 blank, and will terminate the job. Jobs may be stacked and the program will terminate when two additional blank cards follow a card H (also blank).

NUMBER OF VIEWS

ITERATION NUMBER	SYMMETRY		
	None	X	B
1	4	3	2
2	4	2	1
3	8	4	2
4	16	8	4
5	32	16	8

ie, For two iterations with no symmetry, a total of eight views is obtained.

NOTE: Plots are obtained during iteration 1 only.

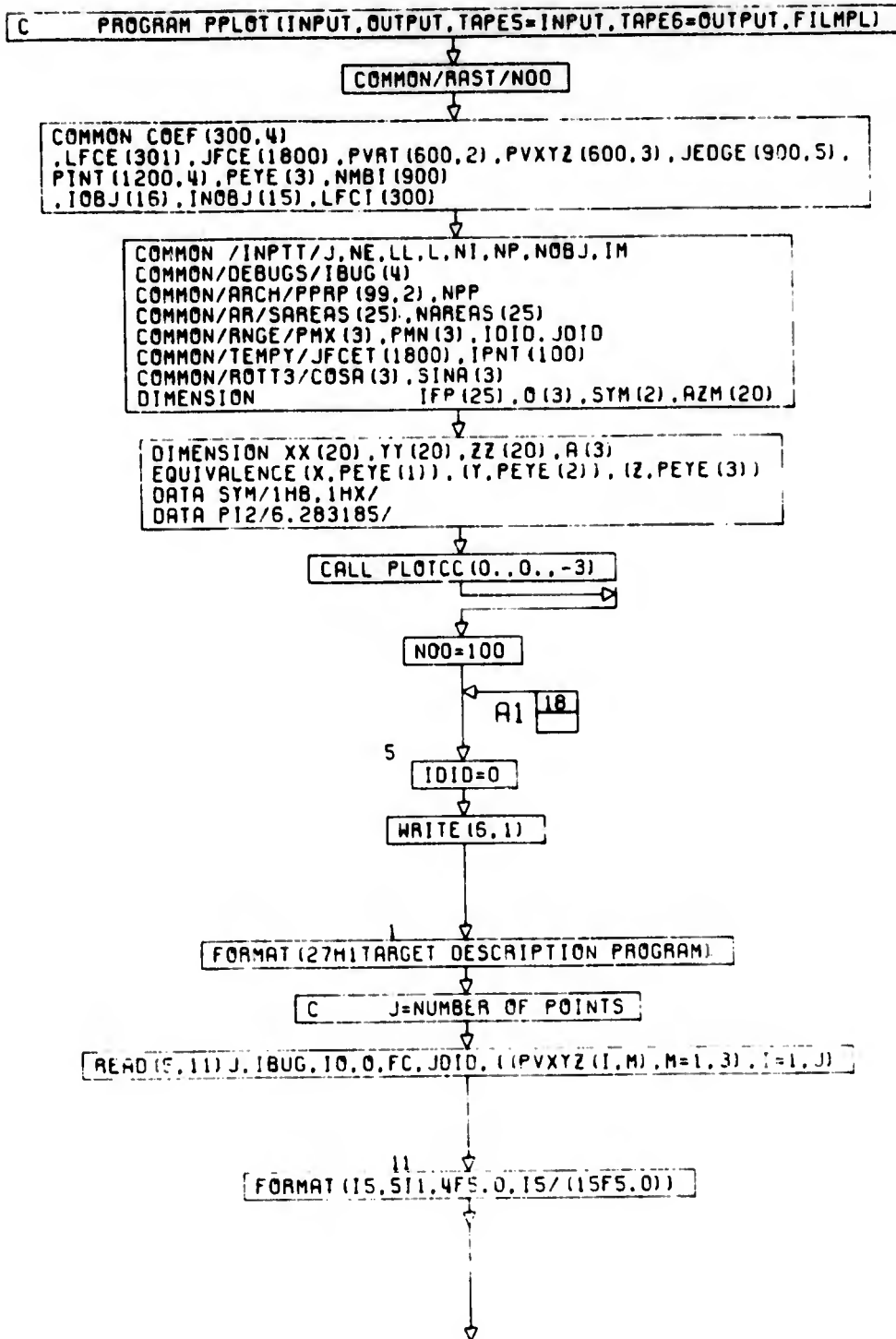
ITERATION NUMBER	VIEWING ANGLE, θ , (DEGREES) AZIMUTH (All θ 's are increased by .1 radians*) (NO SYMMETRY)
1	0, 90, 180, 270
2	45, 135, 225, 315
3	22.5, 67.5, 112.5, 157.5, 202.5, 247.5, 292.5, 337.5 etc.

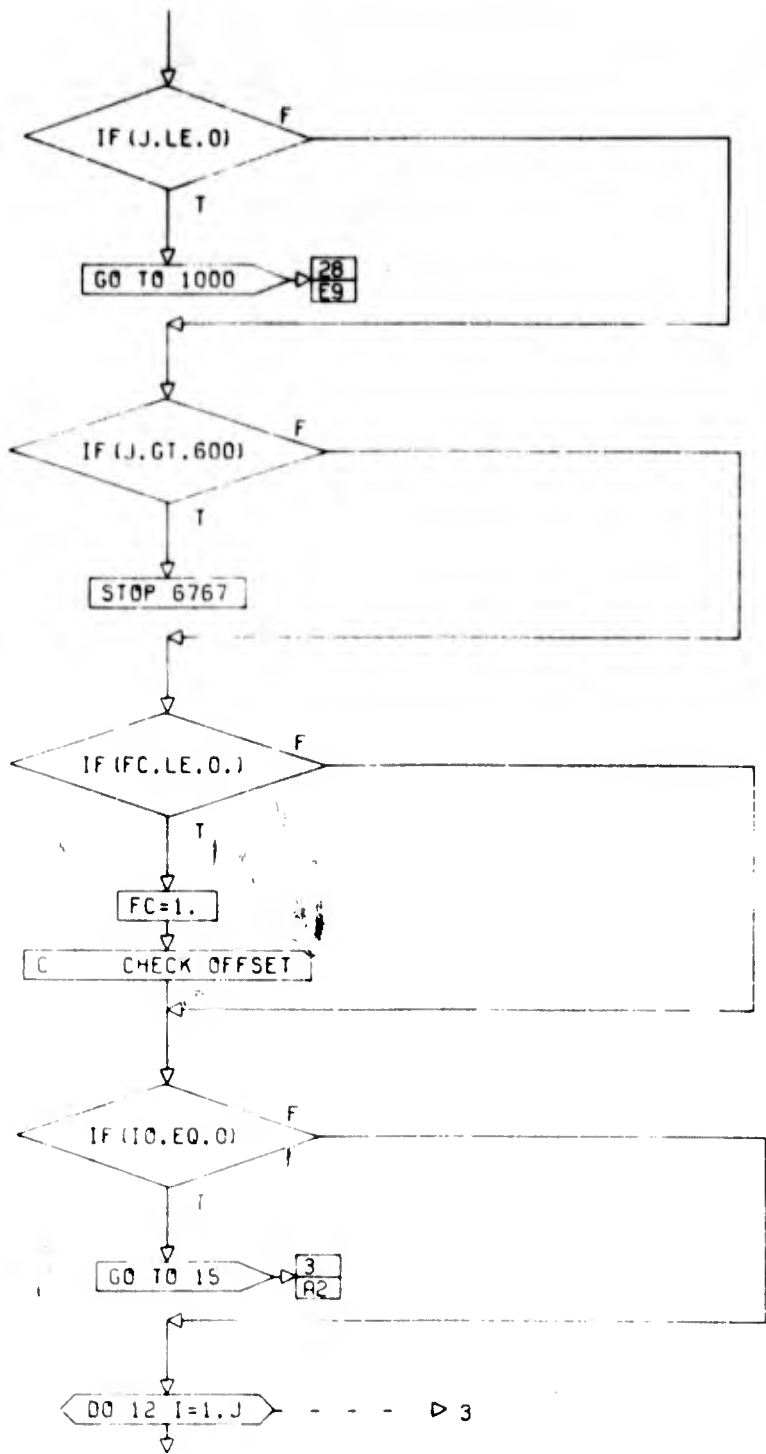
*To possibly avoid parallelism problems.

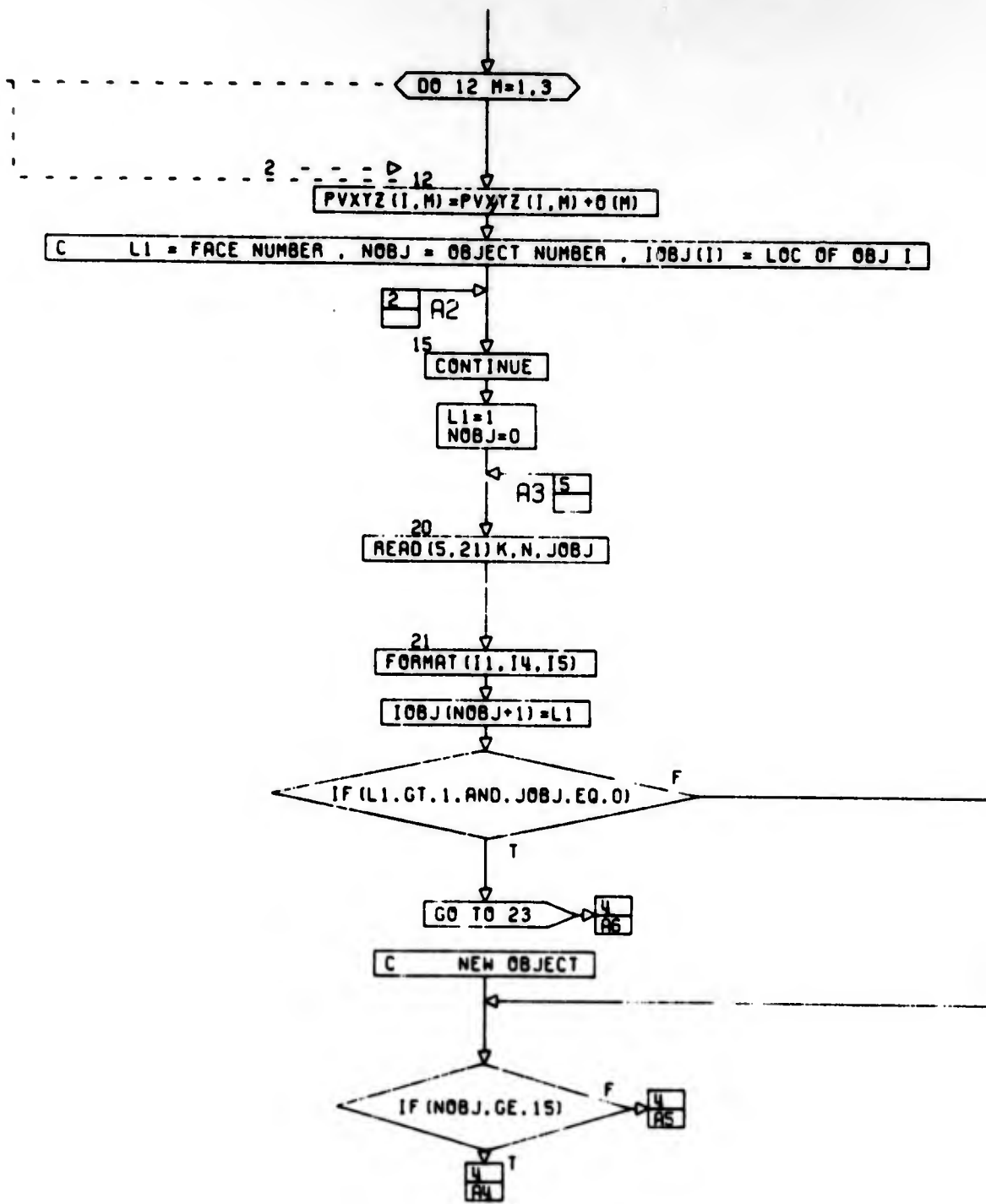
APPENDIX II

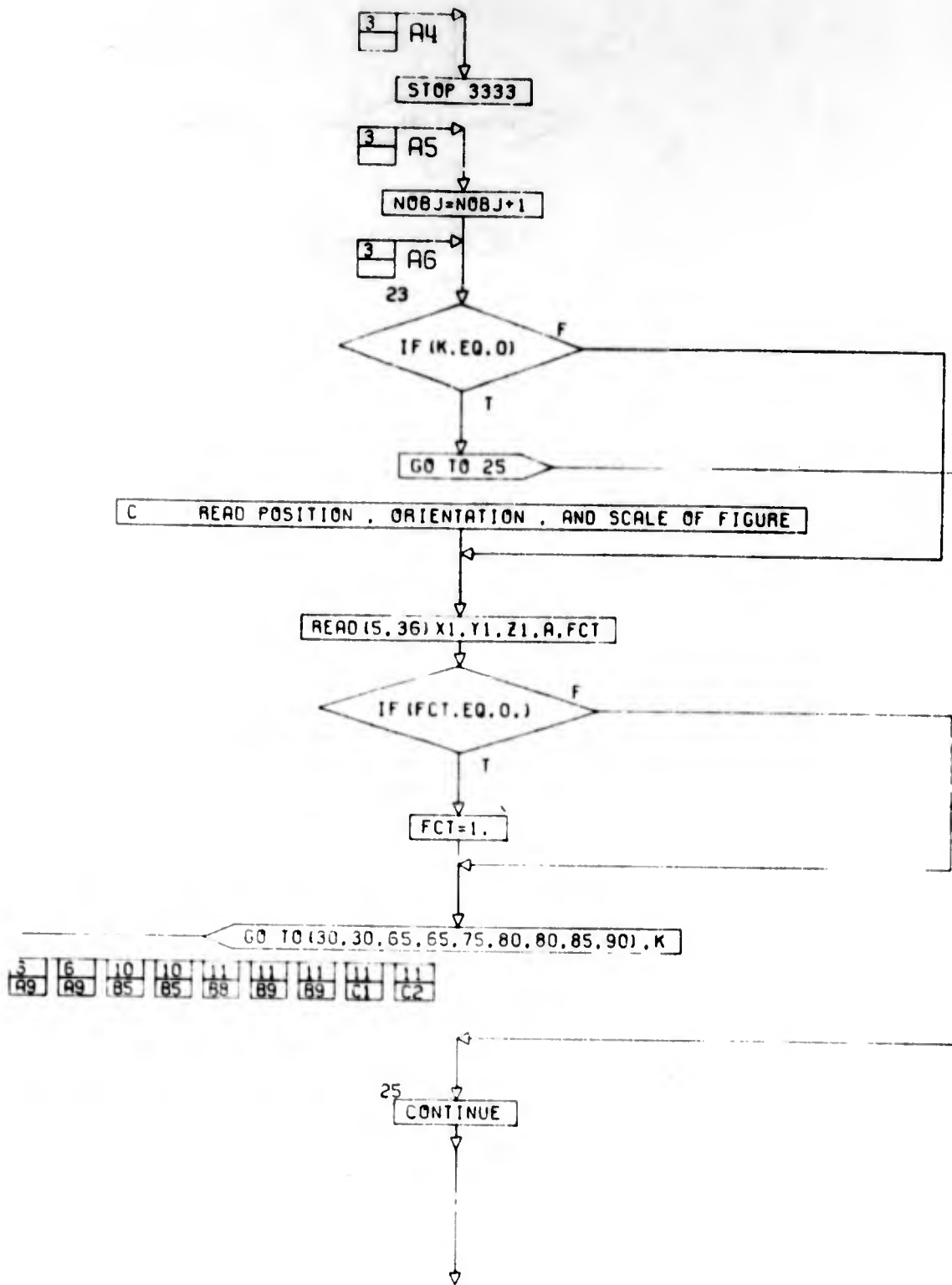
DETAILED FLOW CHARTS

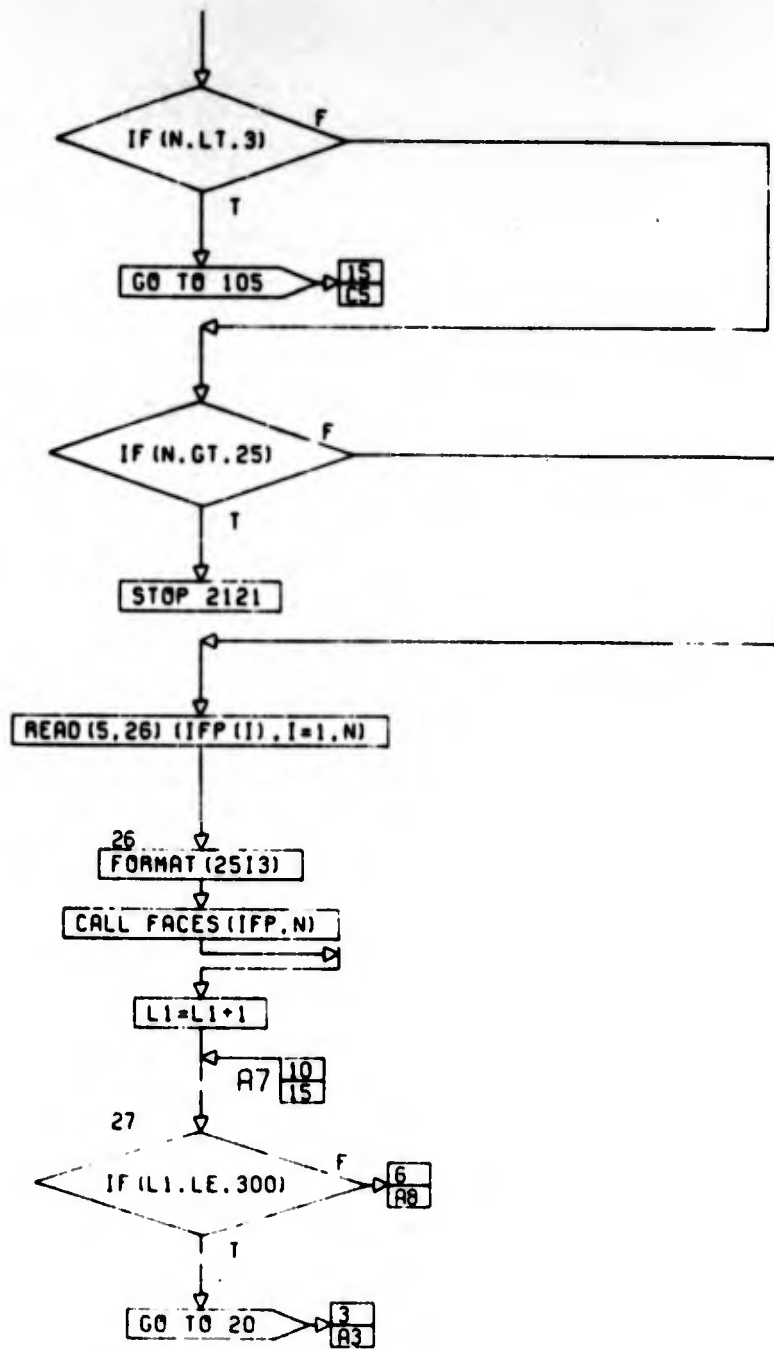
PROGRAM PLOT

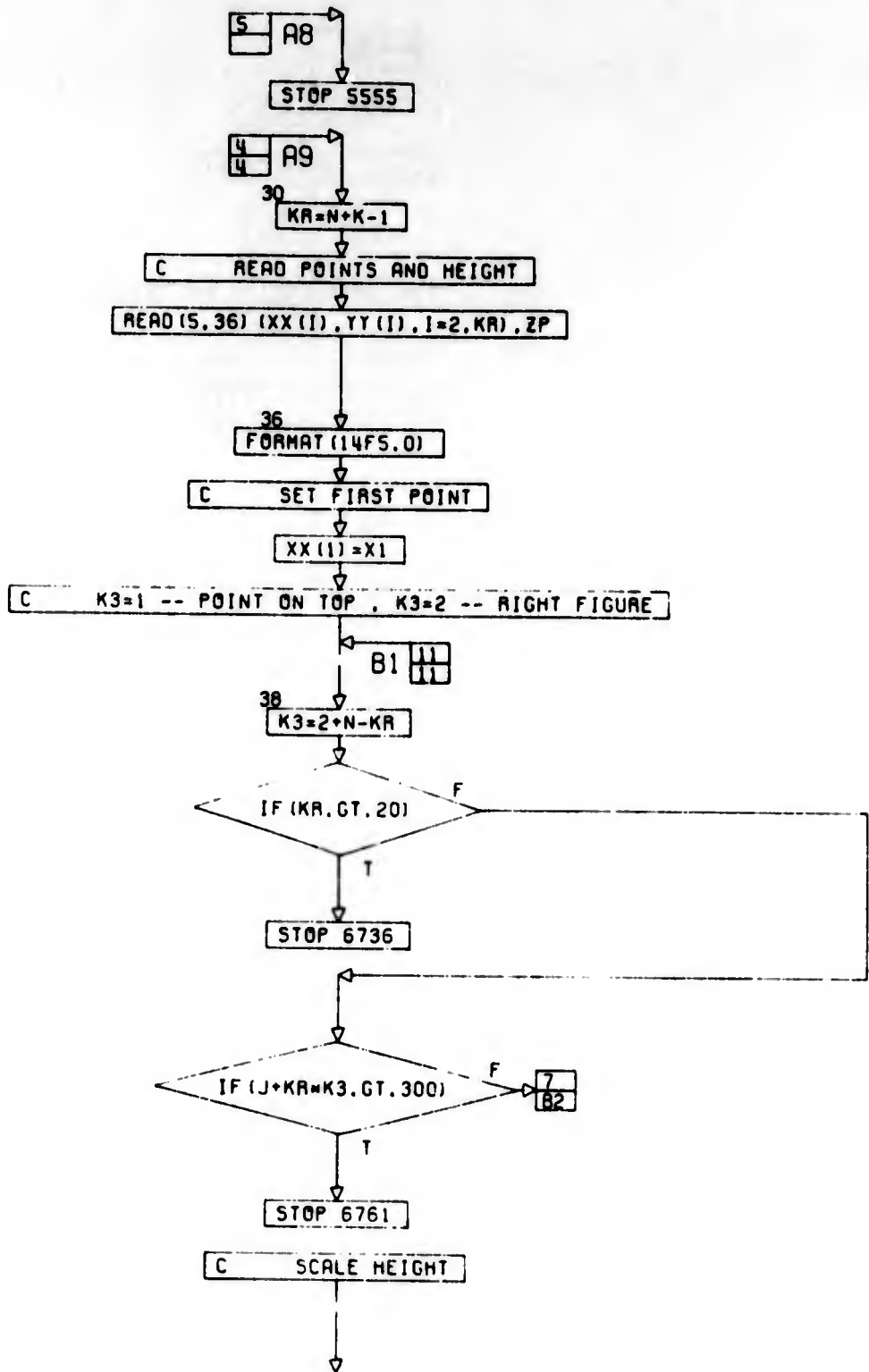


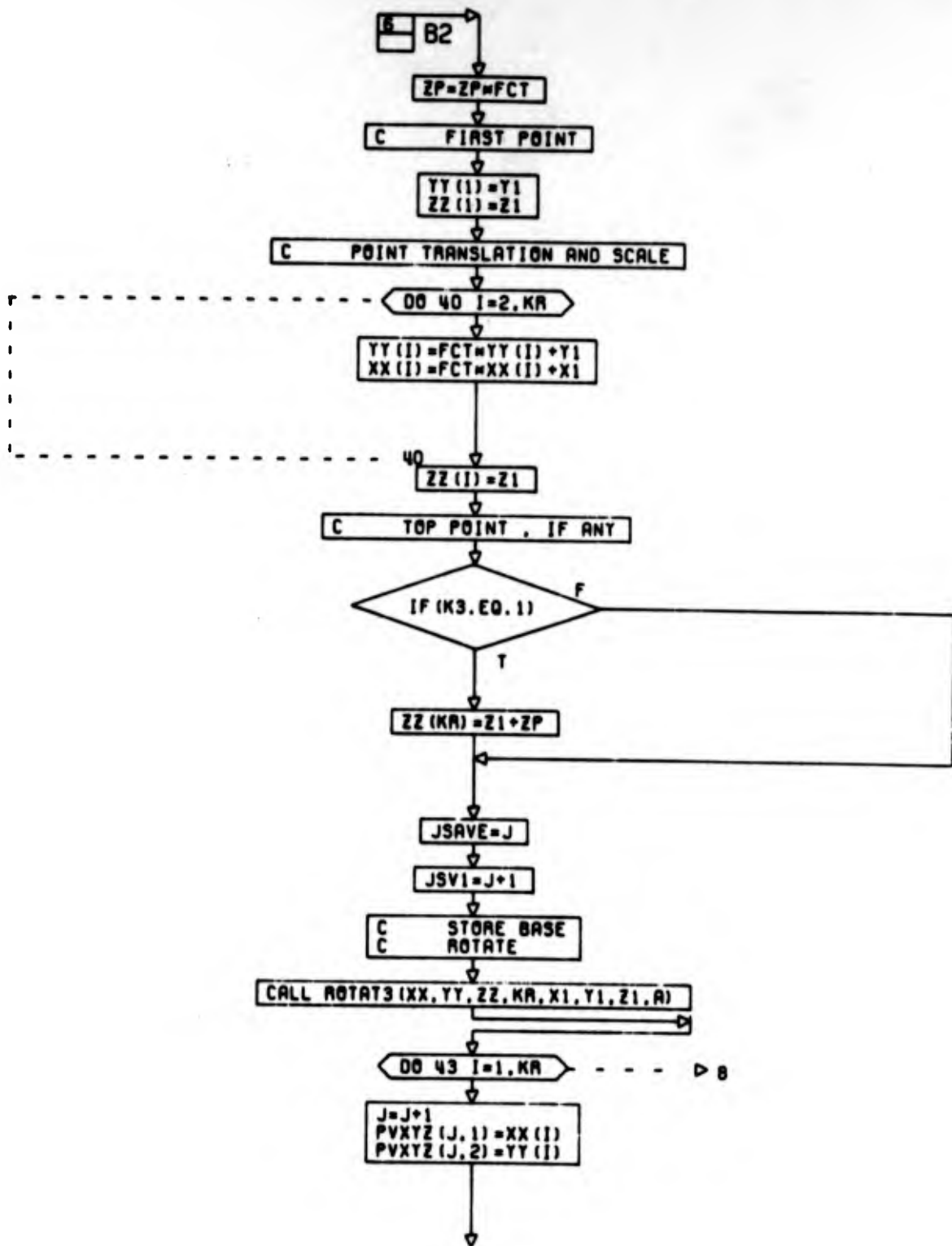


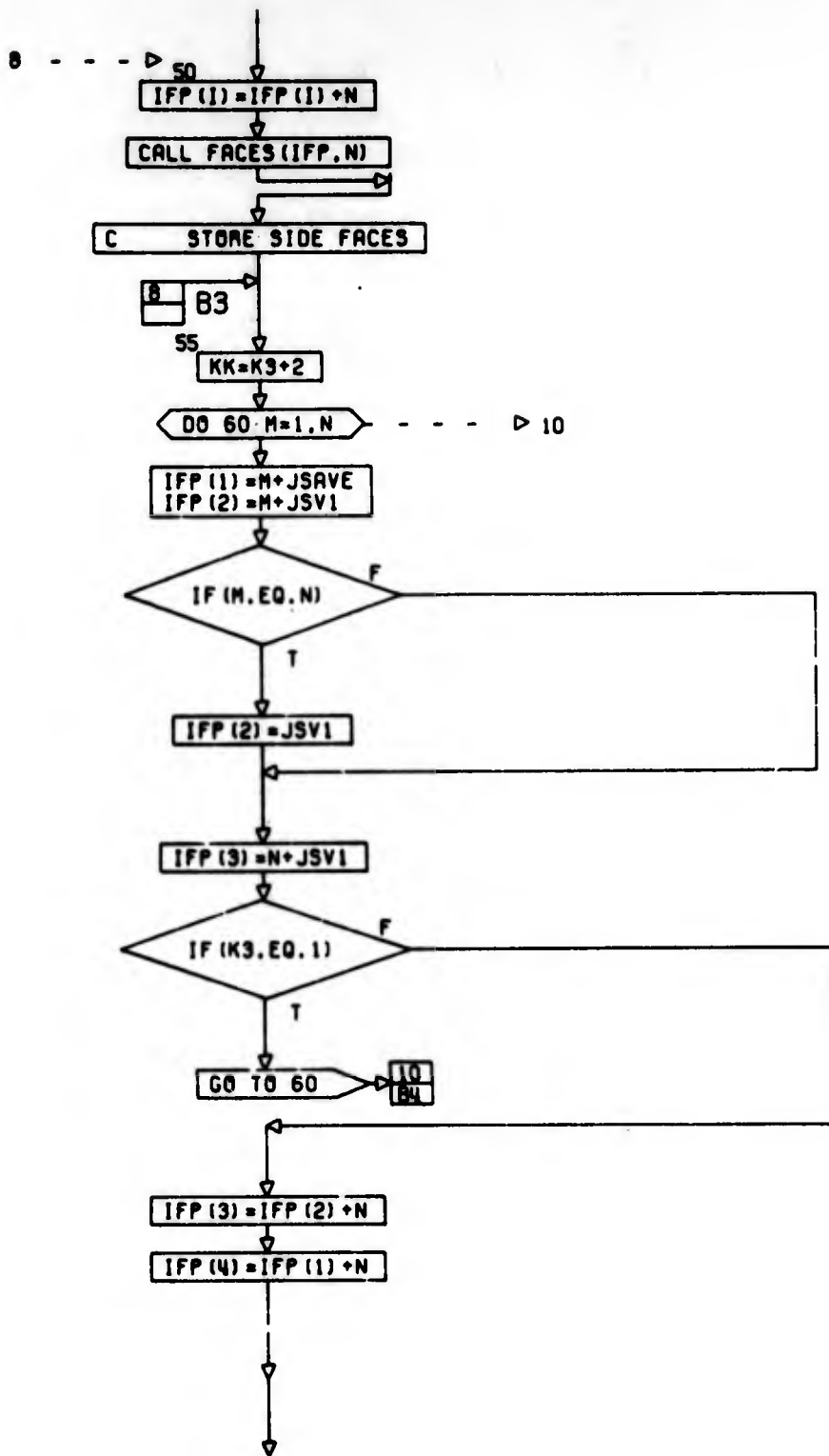


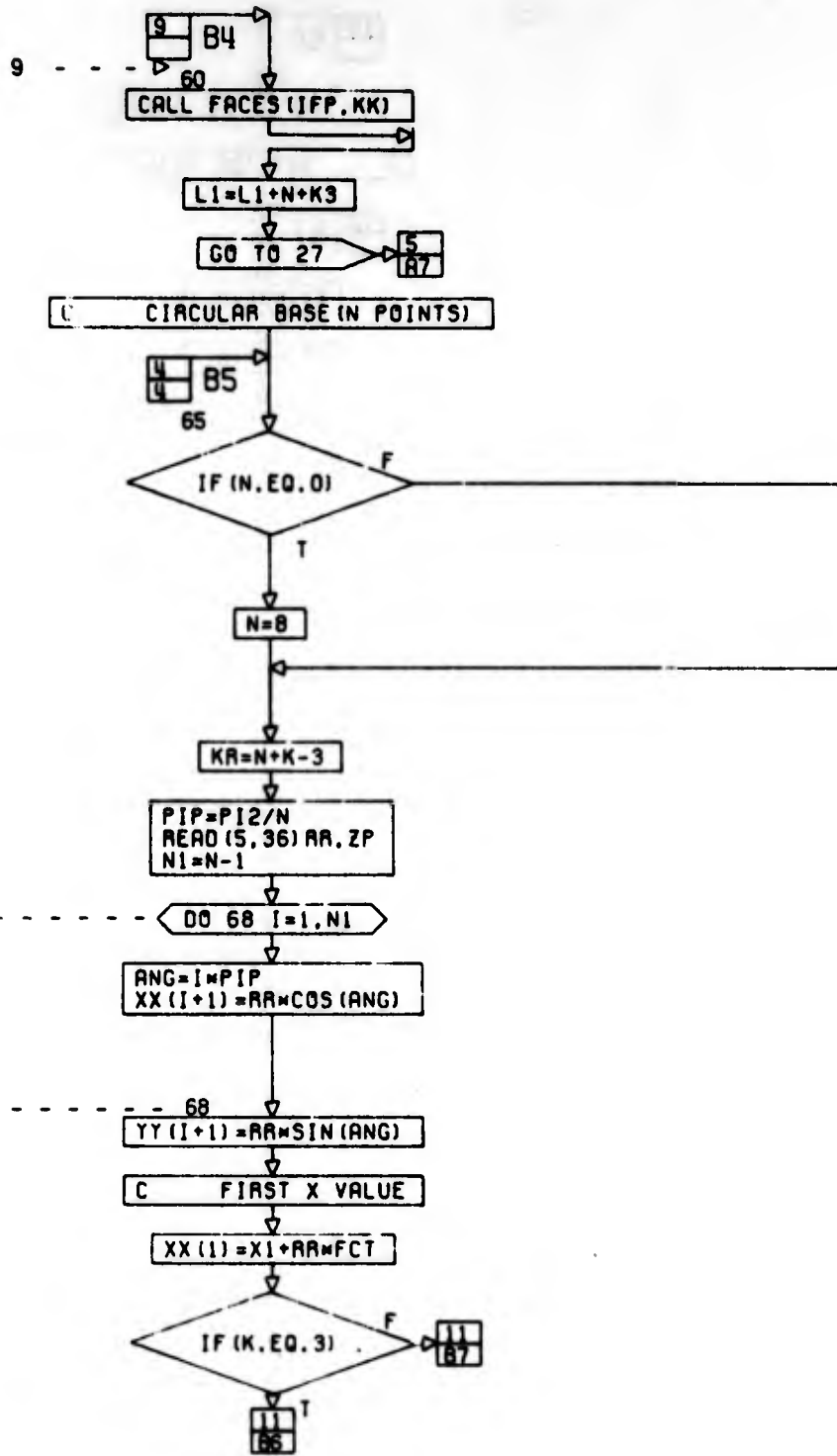


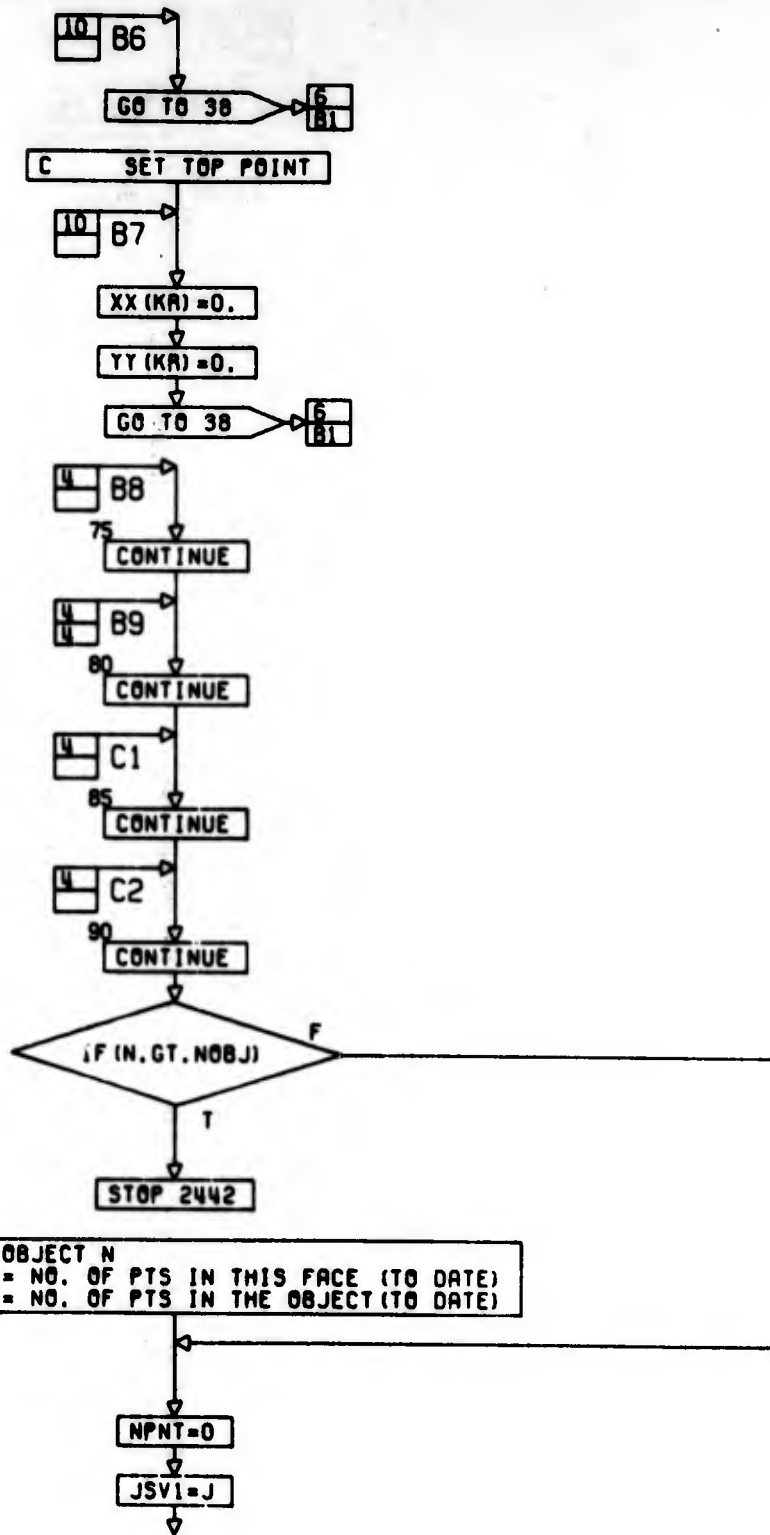


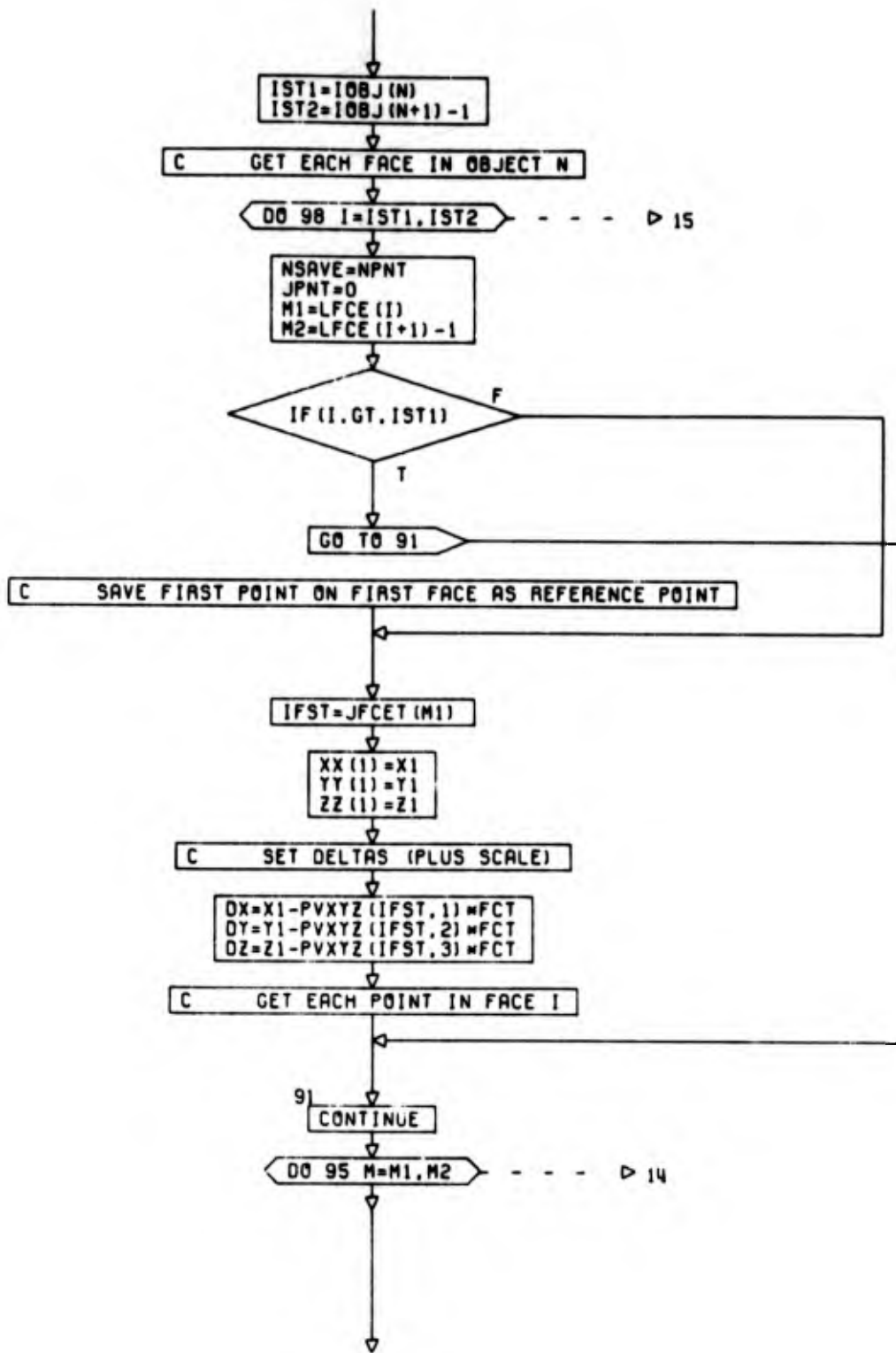


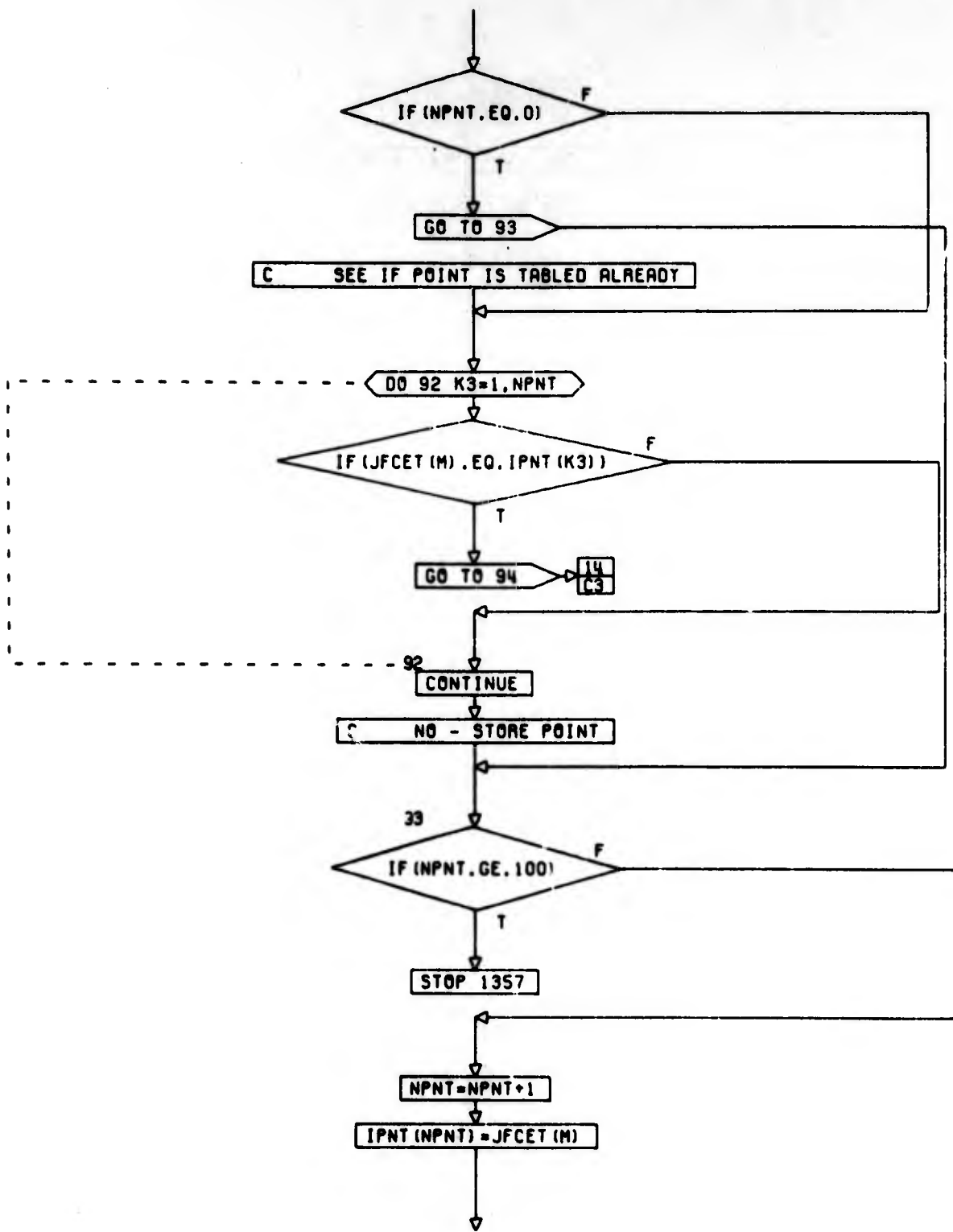


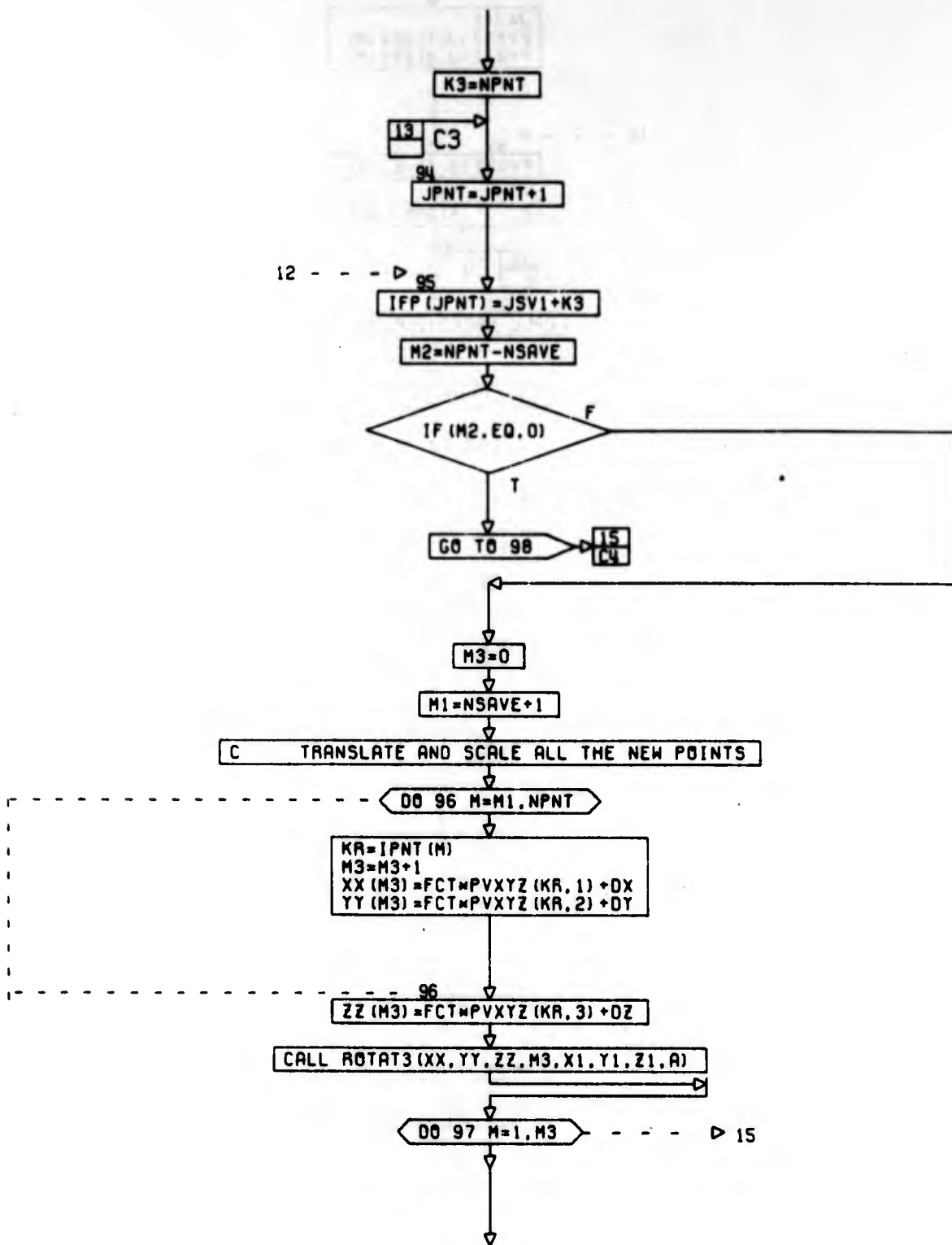


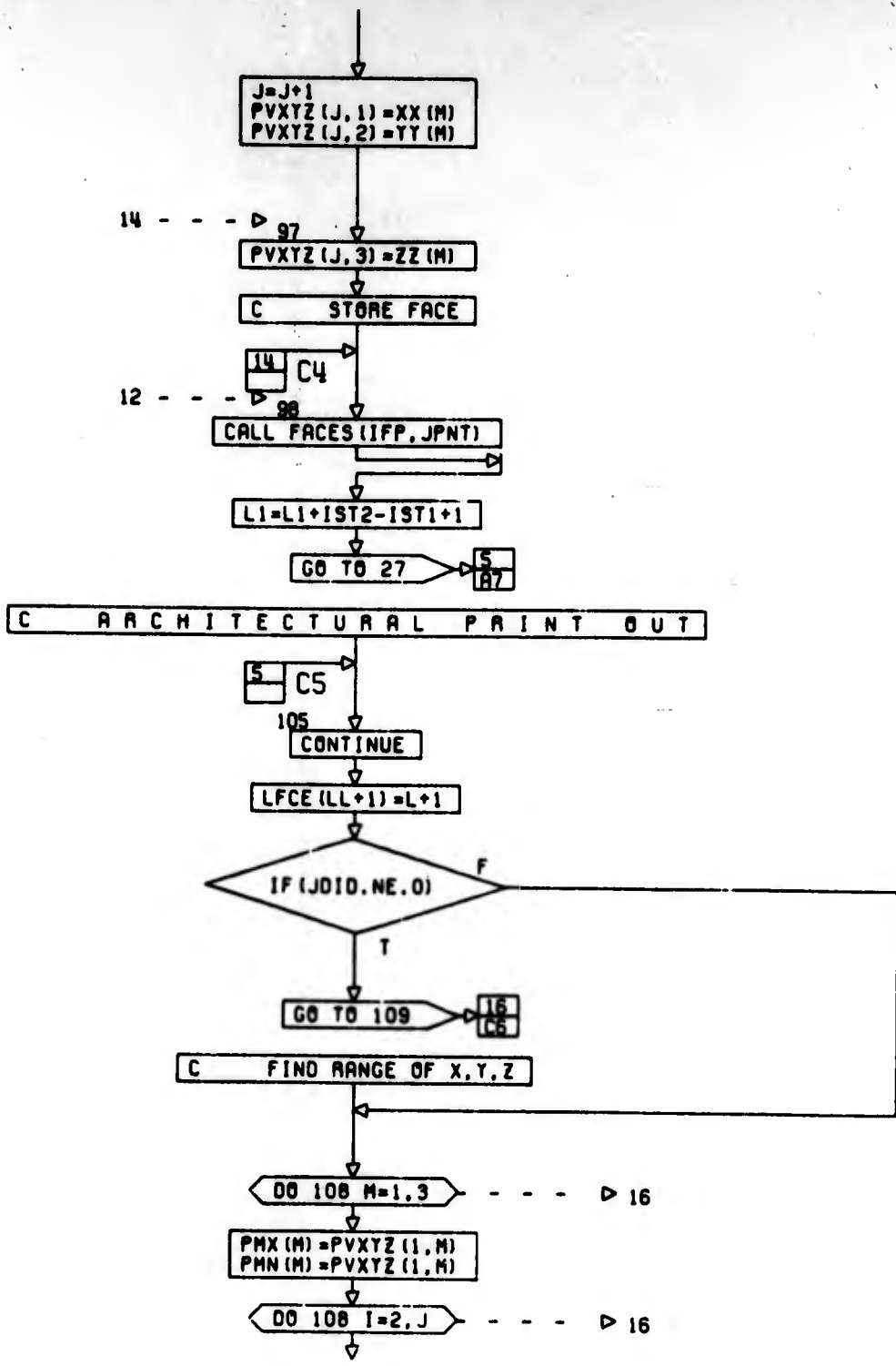


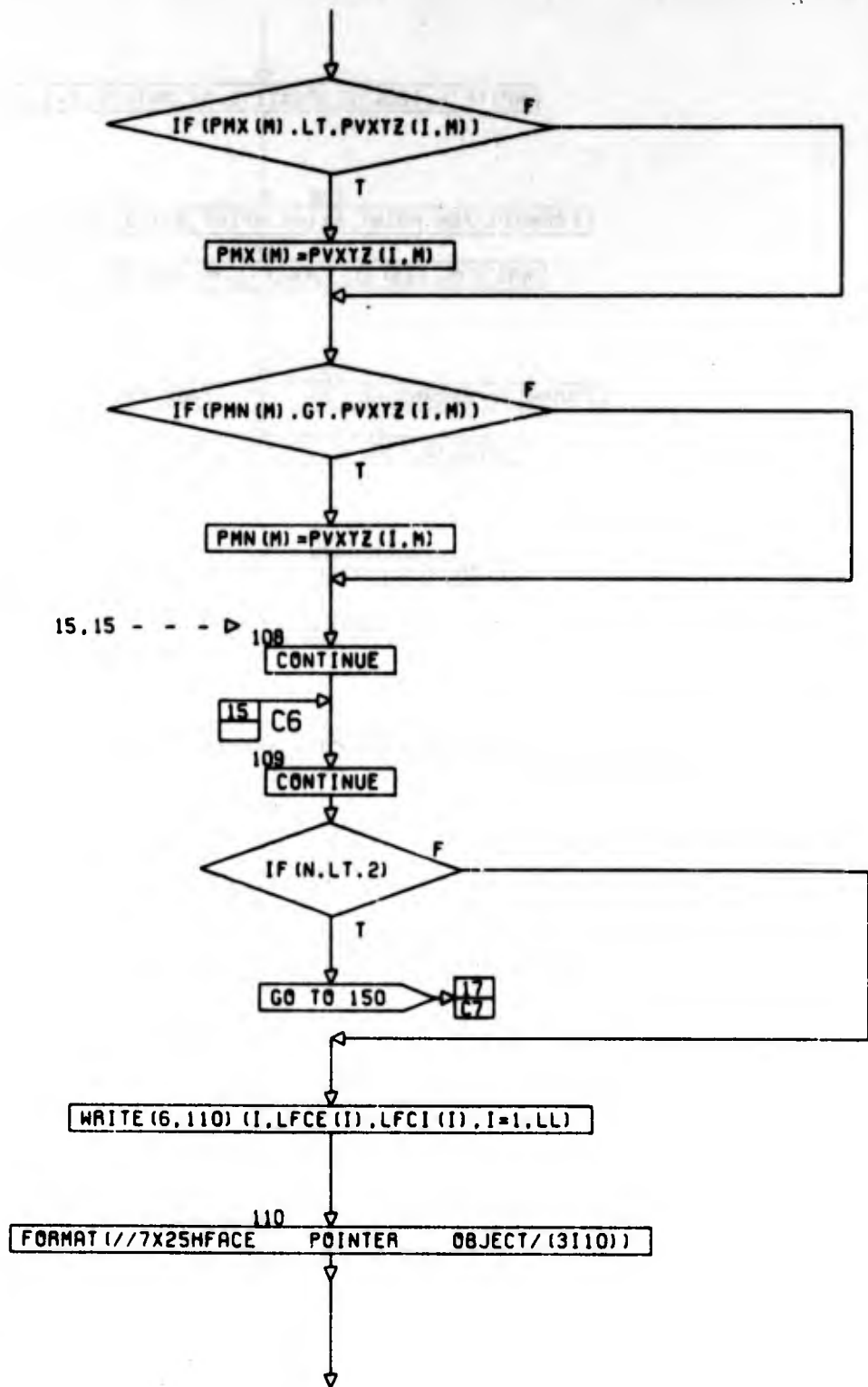


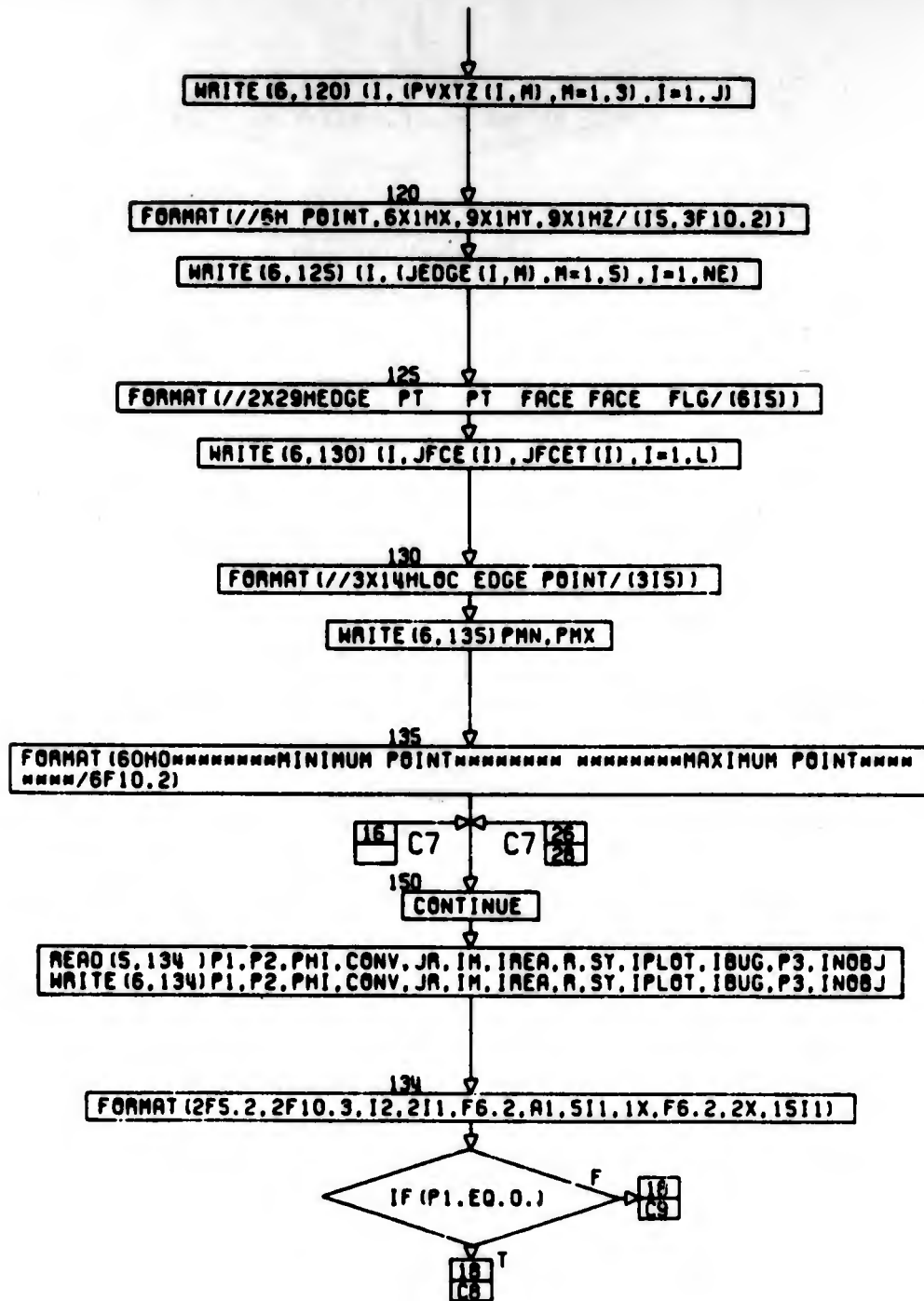


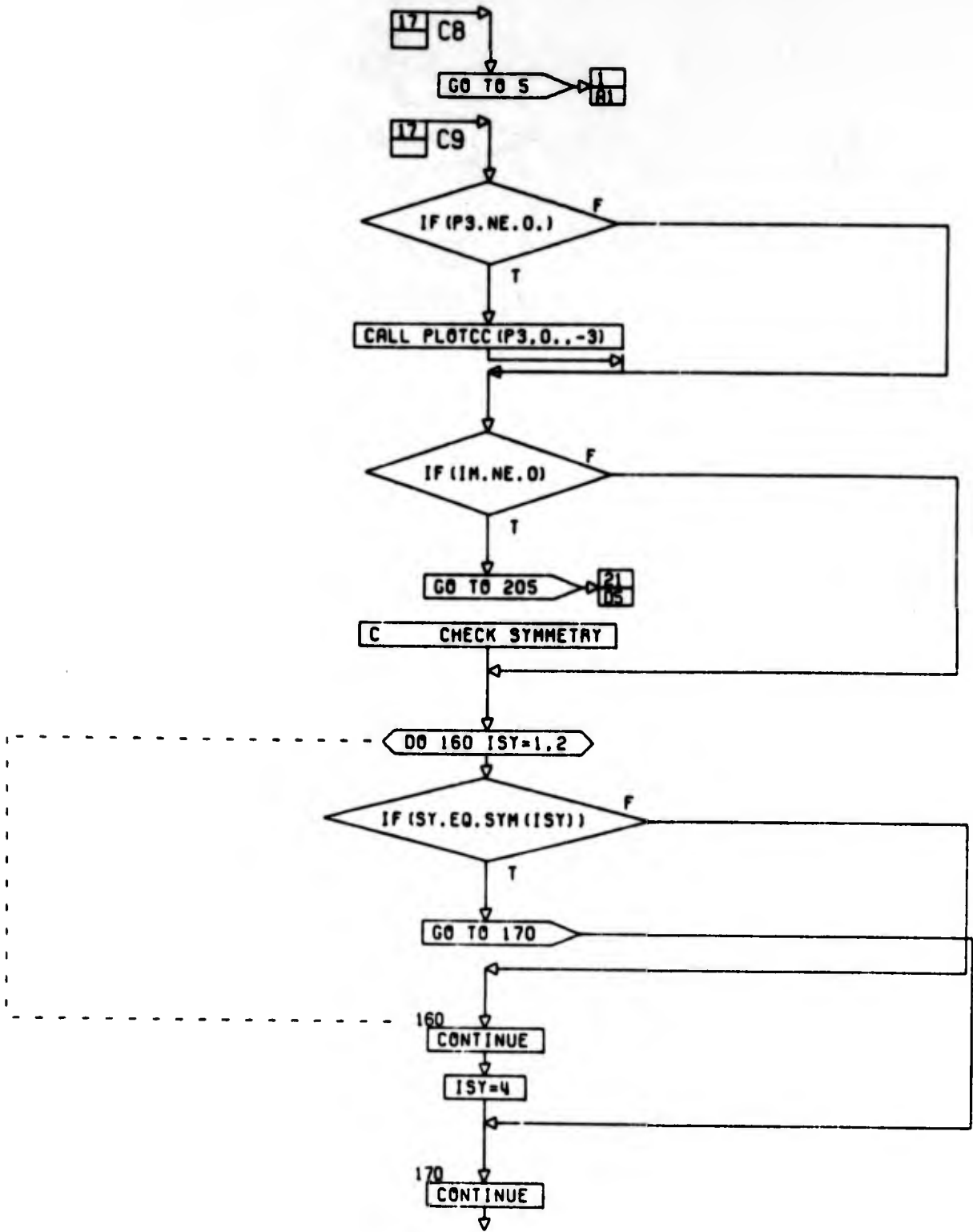


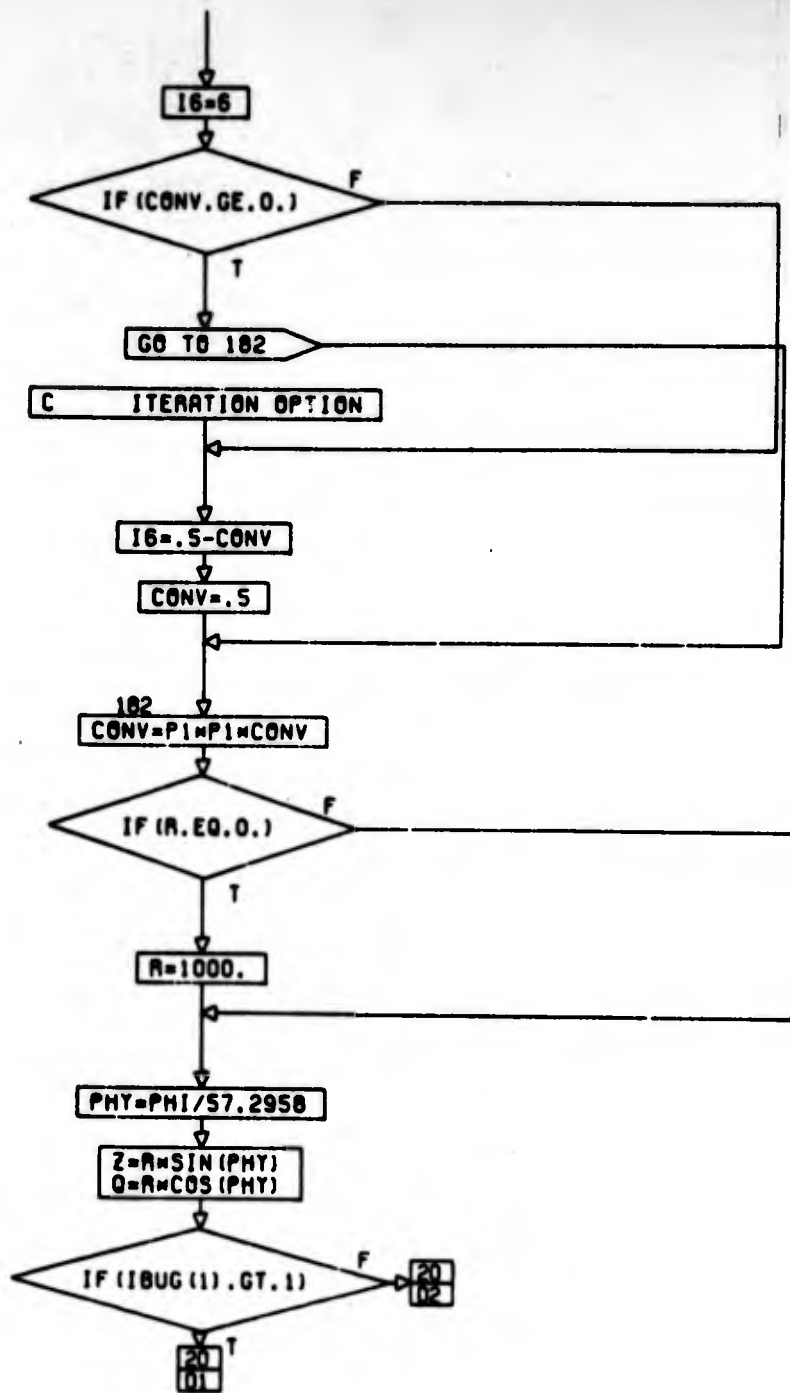


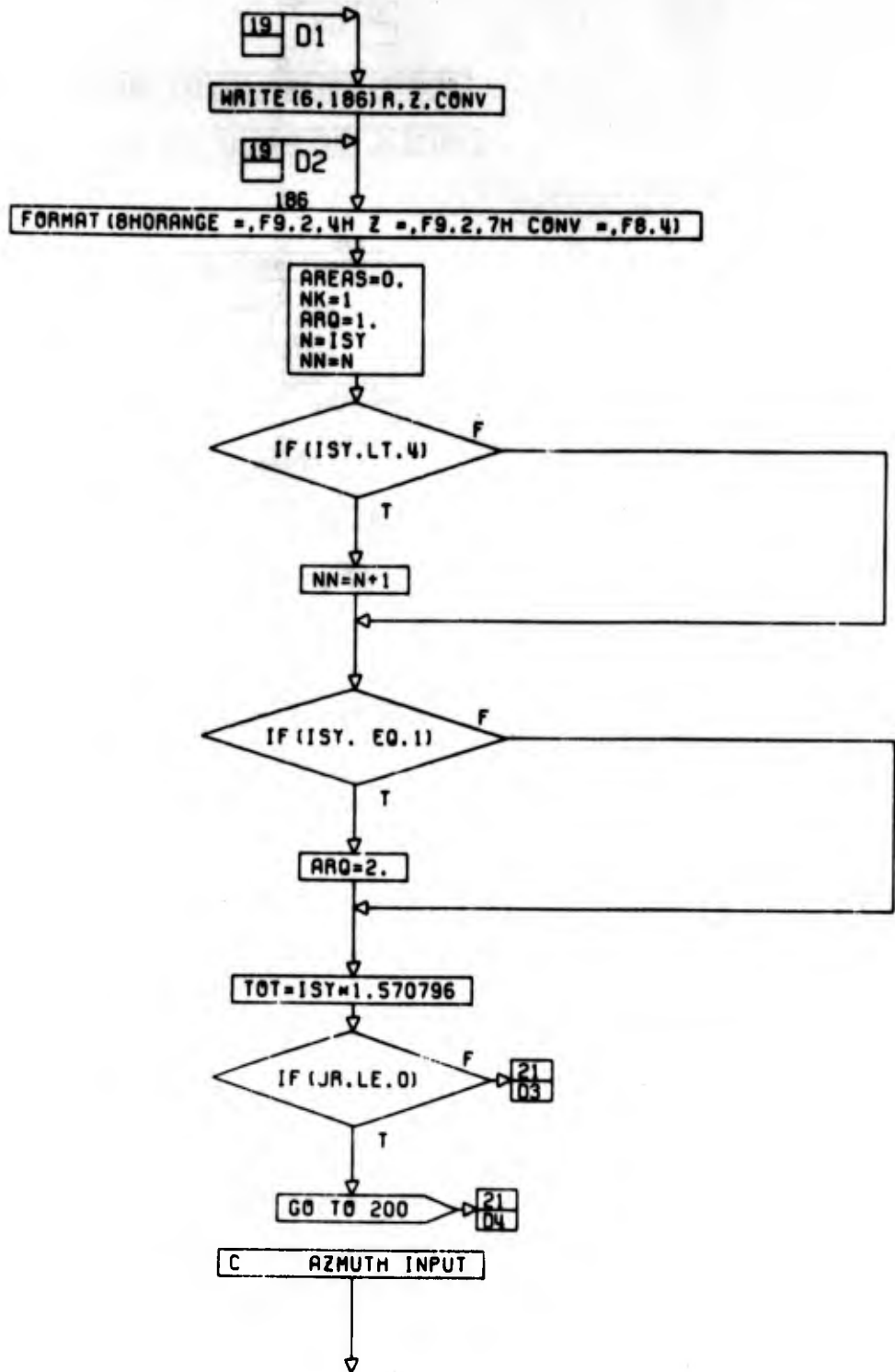


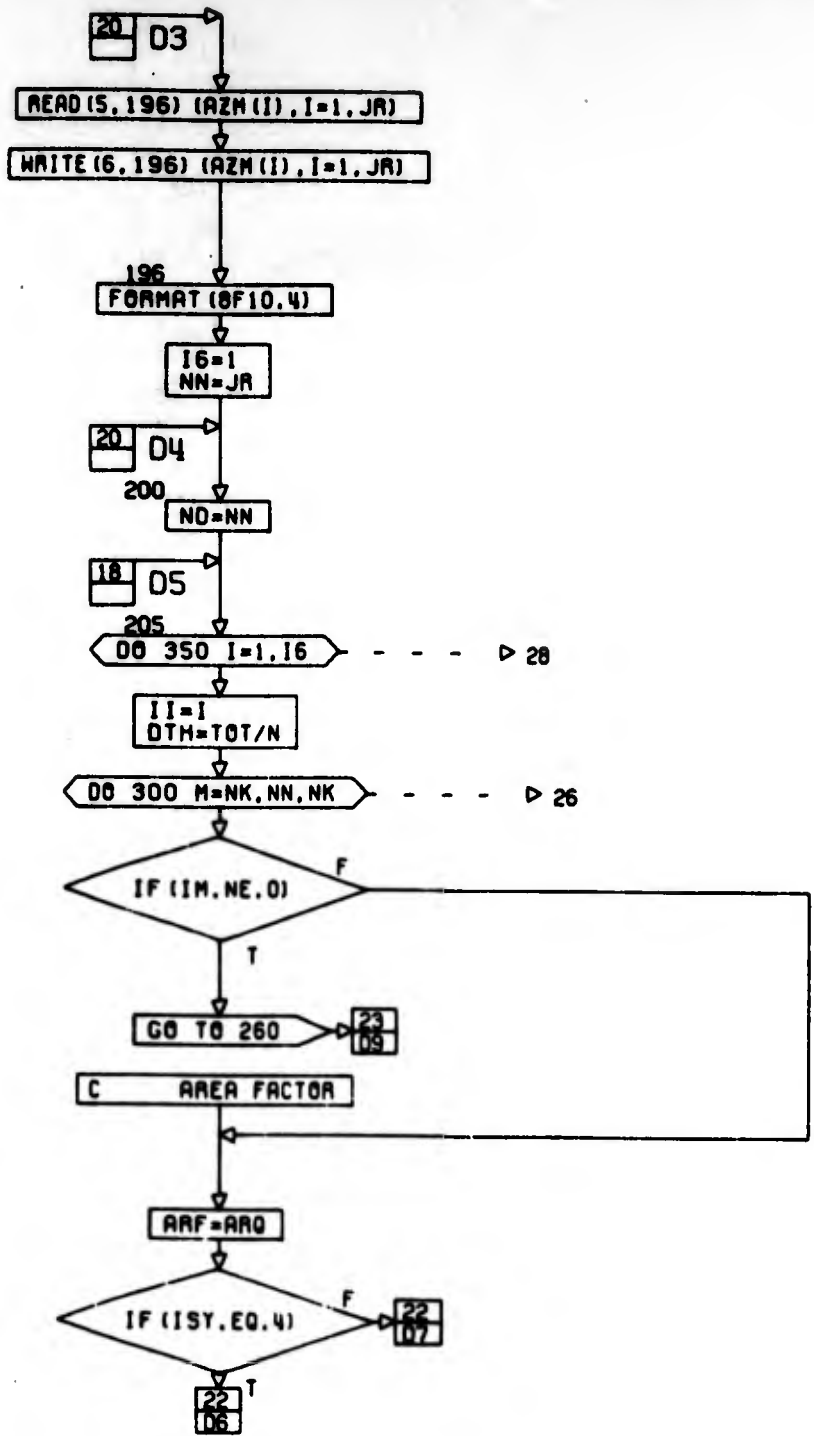


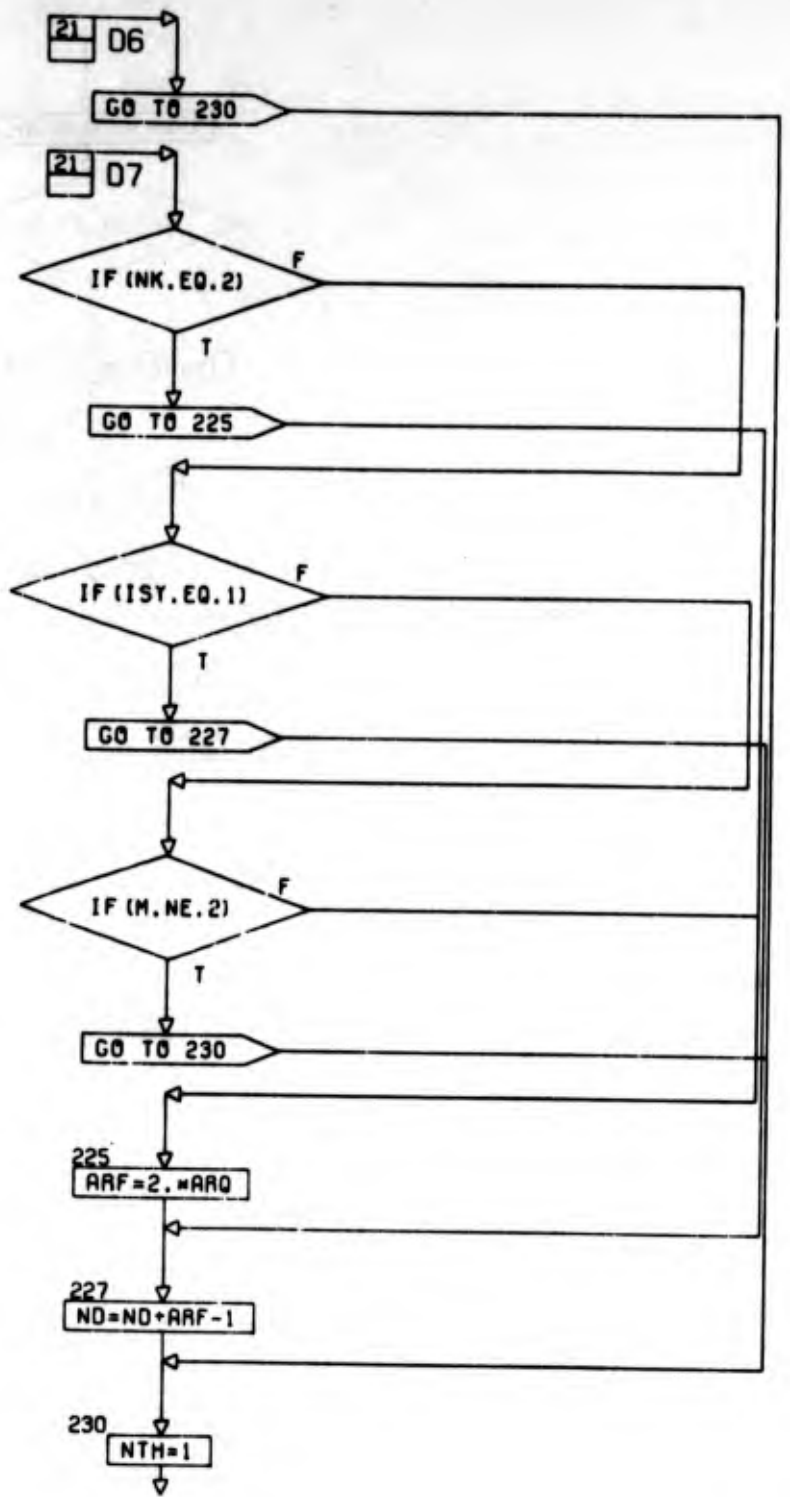


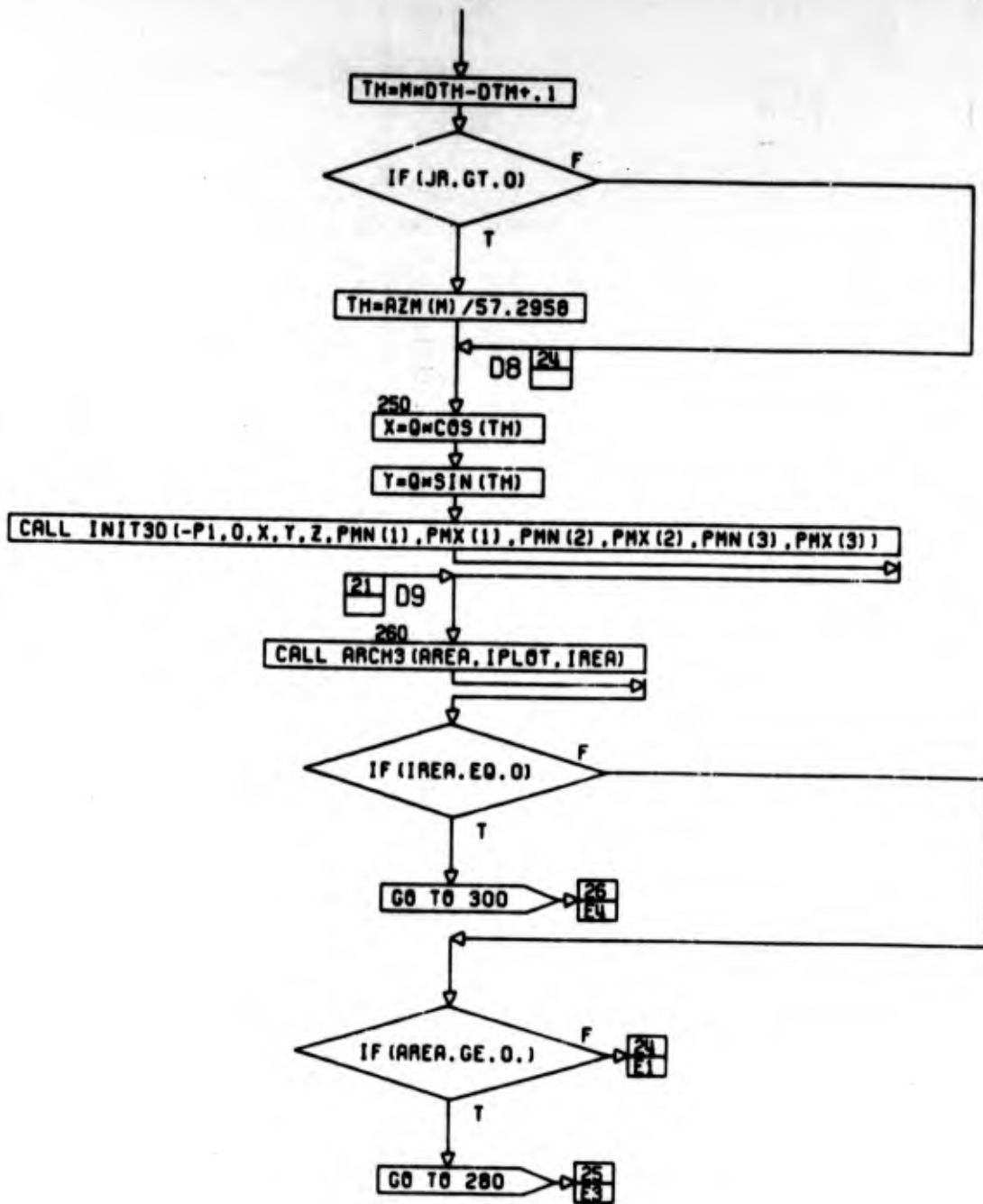


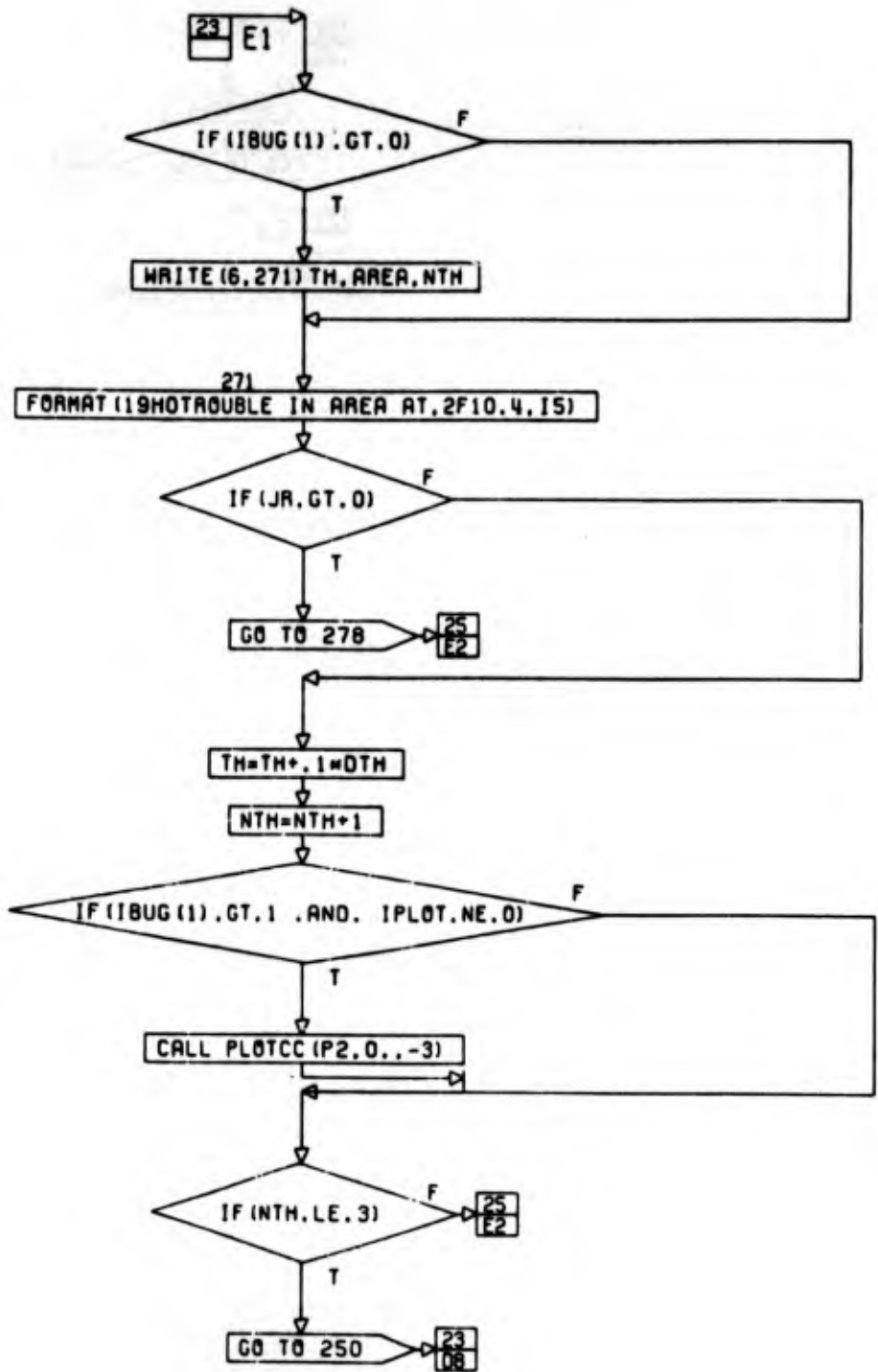


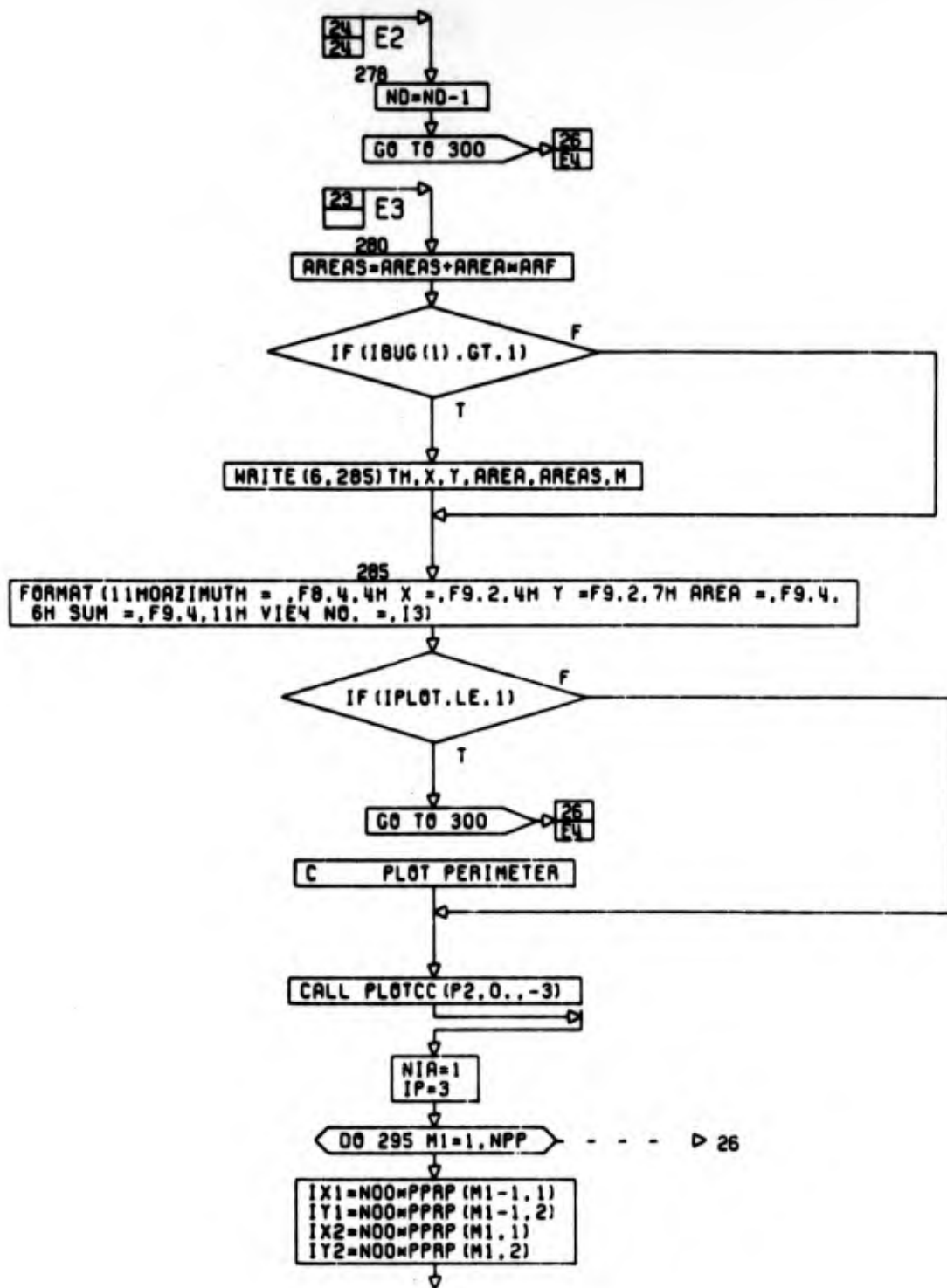


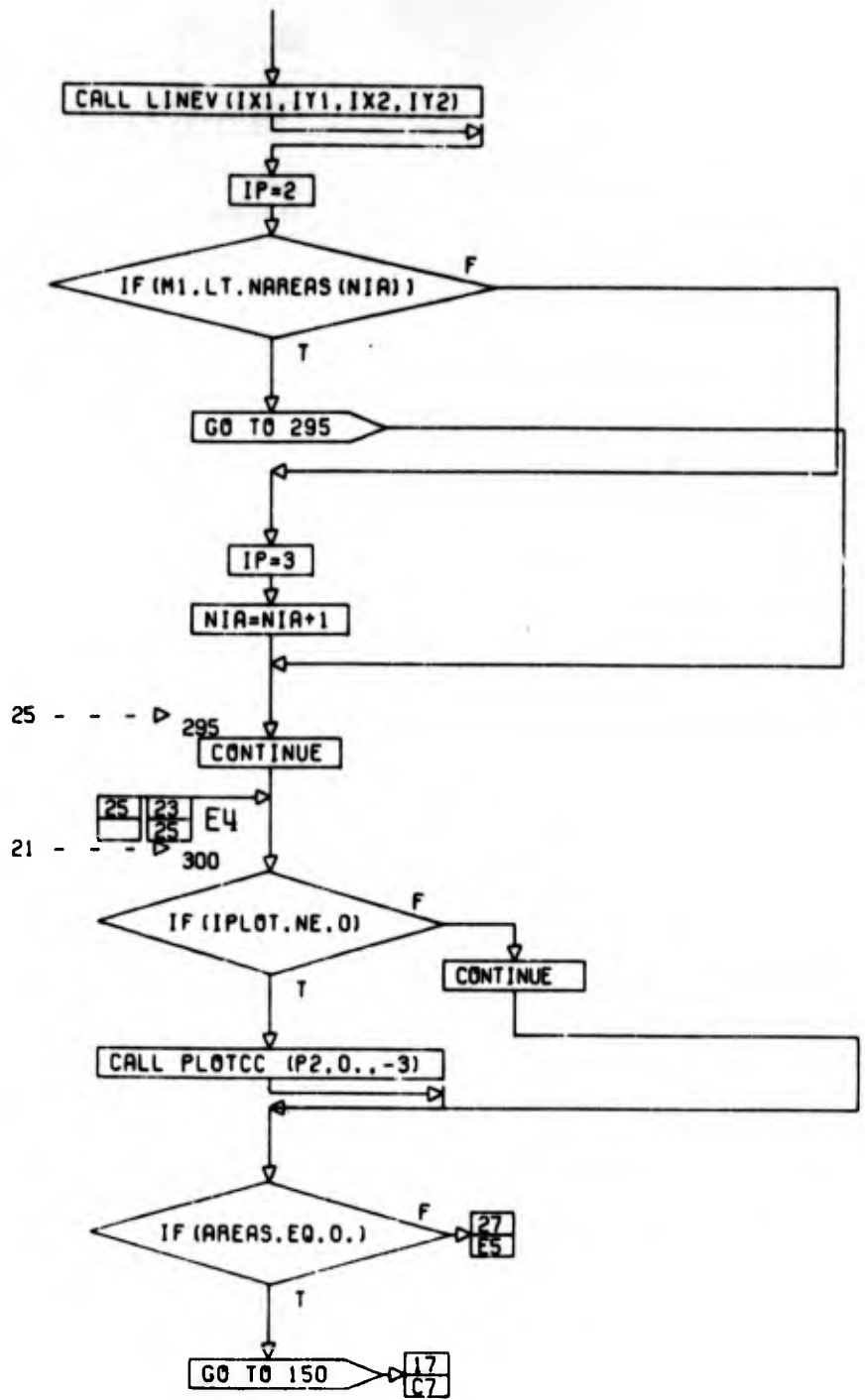


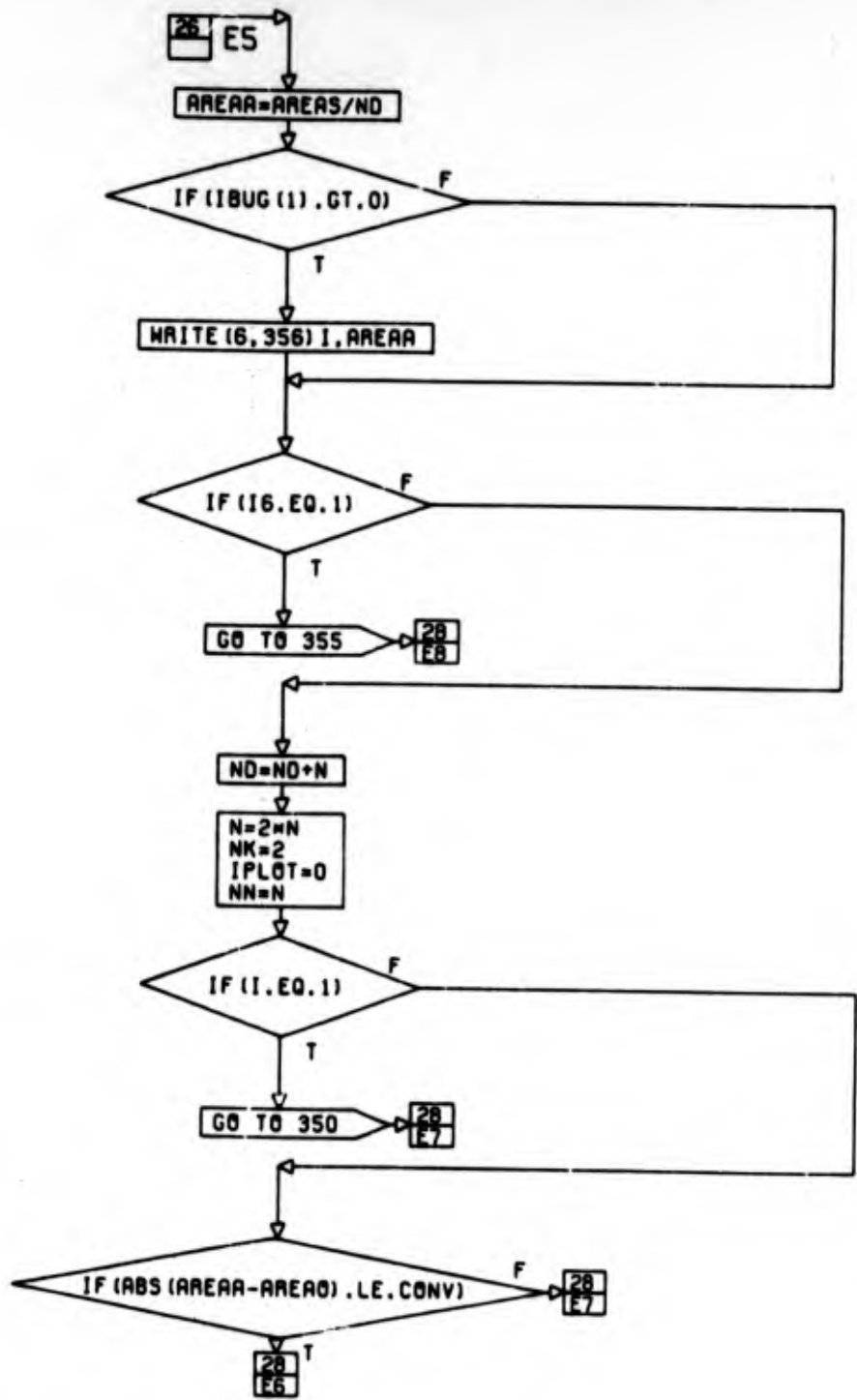


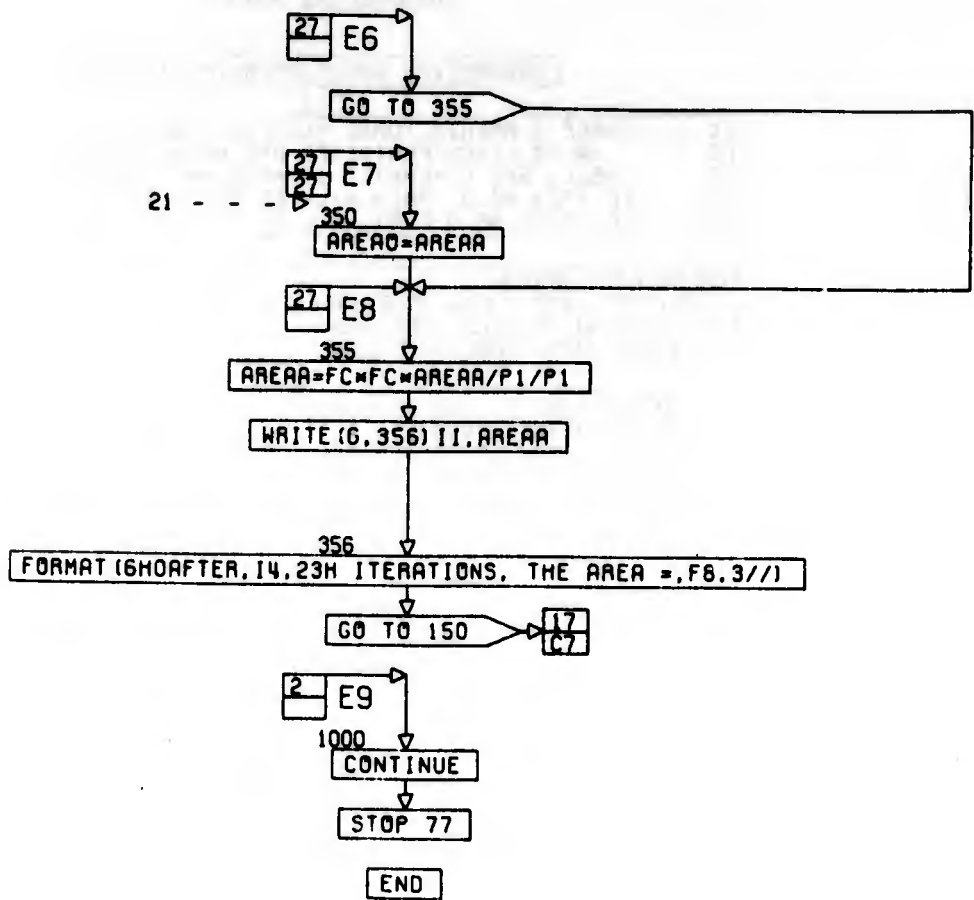












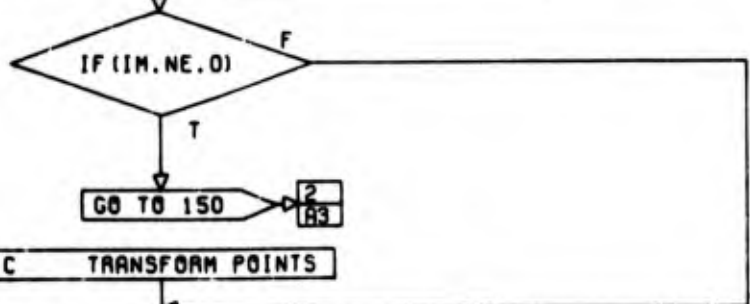
SUBROUTINE ARCH3

SUBROUTINE ARCH3 (AREA, IPLOT, IREA)

C THREE D ARCHITCTURAL PLOTTING ROUTINE
 C (ALSO FINDS PERIMETER AND AREA SEEN)
 C TABLES ARE GENERATED IN MAIN AND PASSED THRU COMMON
 C IF IREA.NE.0, AREA WILL BE CALCULATED.
 C IF IPLOT.NE.0 PLOT WILL BE MADE

COMMON COEF (300,4)
 .,LFCE (301),JFCE (1800),PVRT (600,2),PVXYZ (600,3),JEDGE (900,5),
 PINT (1200,4),PEYE (3),NMBI (900)
 .,IOBJ (16),INOBJ (15),LFCI (300)

COMMON /INPTT/J,NE,LL,L,NI,NP,NOBJ,IM
 COMMON/DEBUGS/IBUG (4)
 COMMON /ANSW/ITYPE,ICR,ICL,TYP
 COMMON/ARCH/PPAP (99,2),NPP
 COMMON/AR/SAREAS (25),NAREAS (25)
 DIMENSION PC (3),AL (3),BL (3),PP (2),PPM (199,2),P (50,2)
 NSEG=0

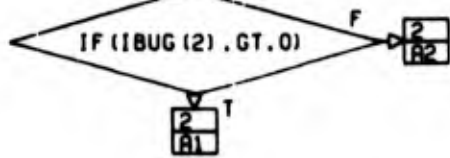


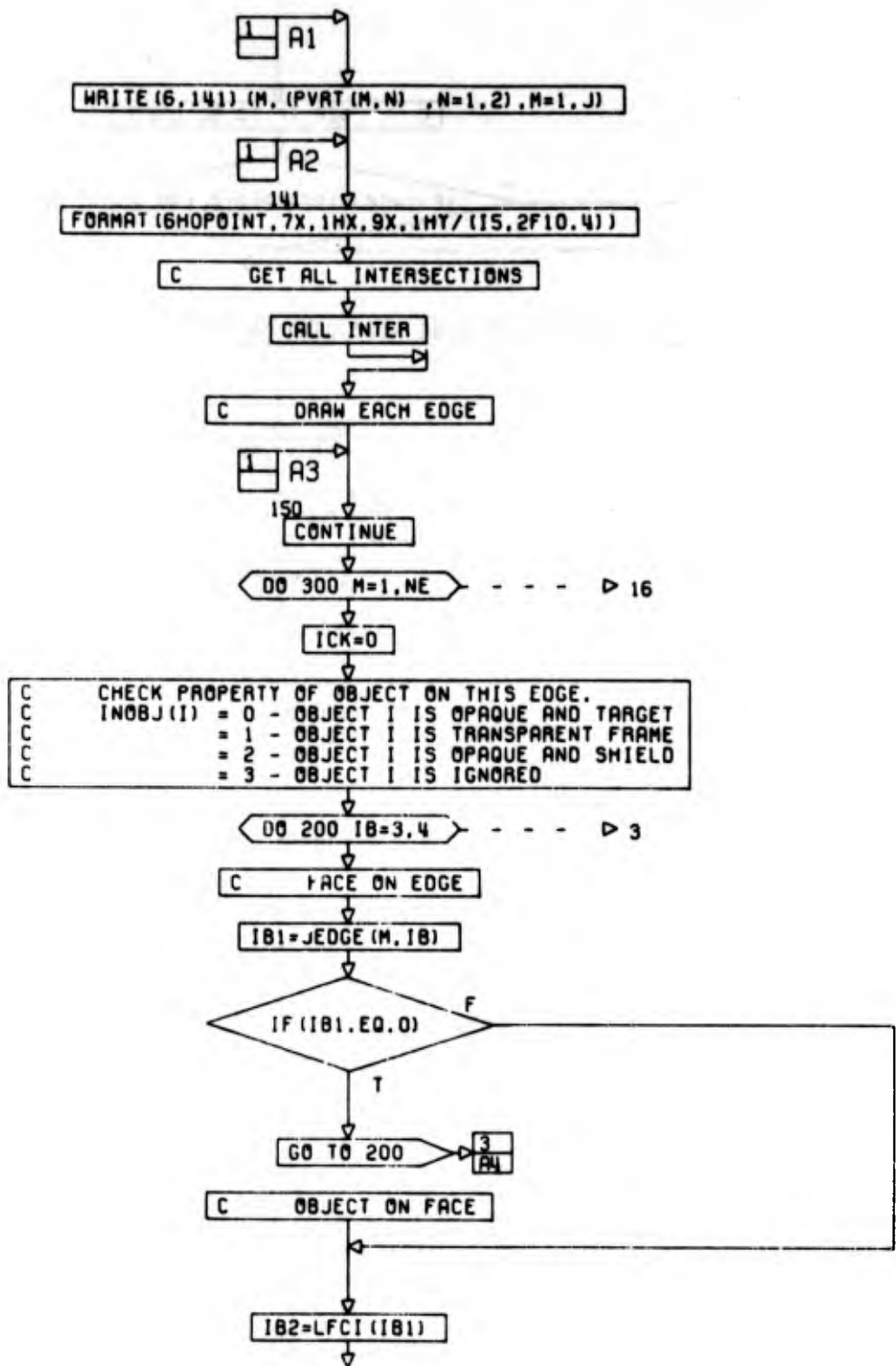
C TRANSFORM POINTS

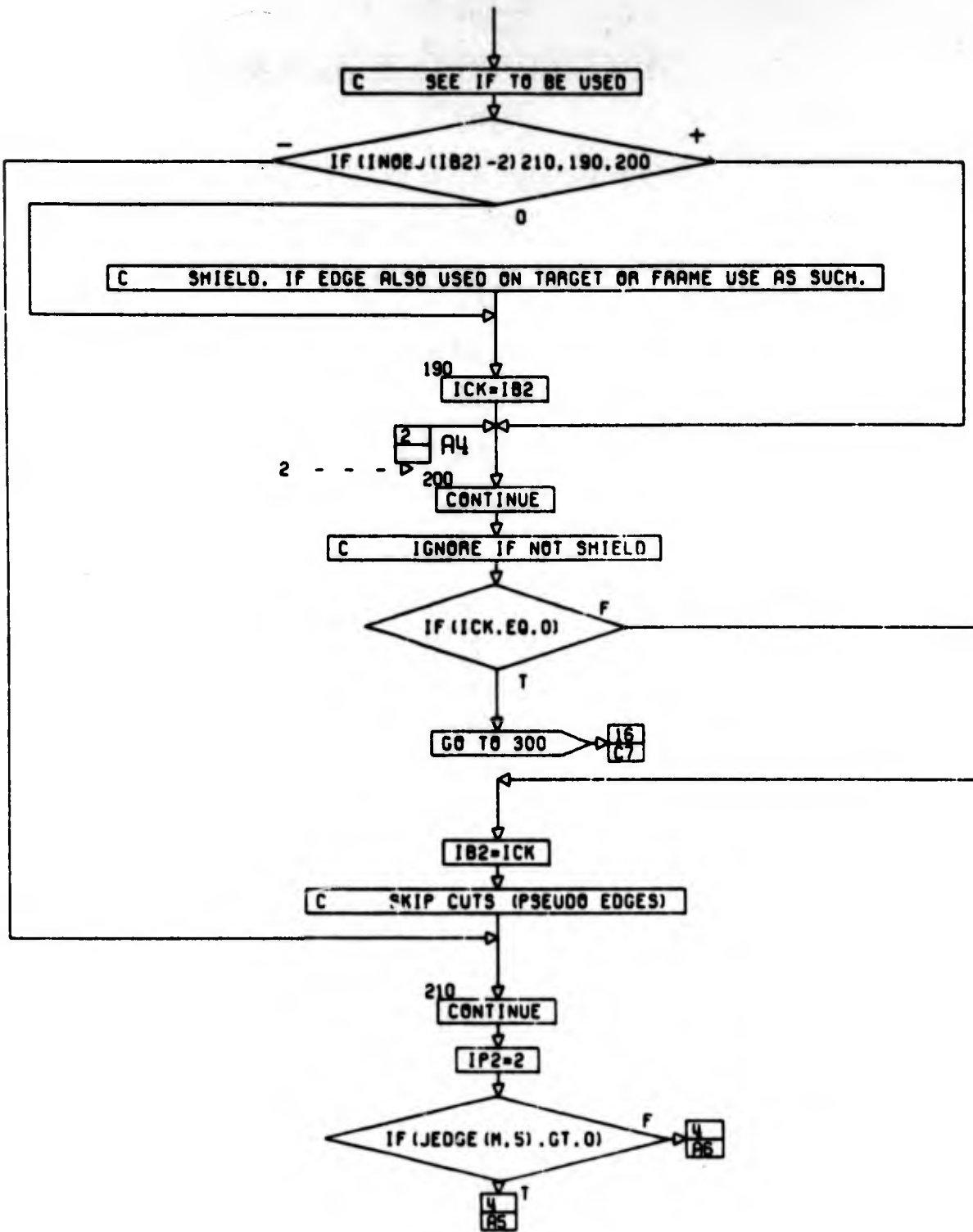
DO 136 M=1,J

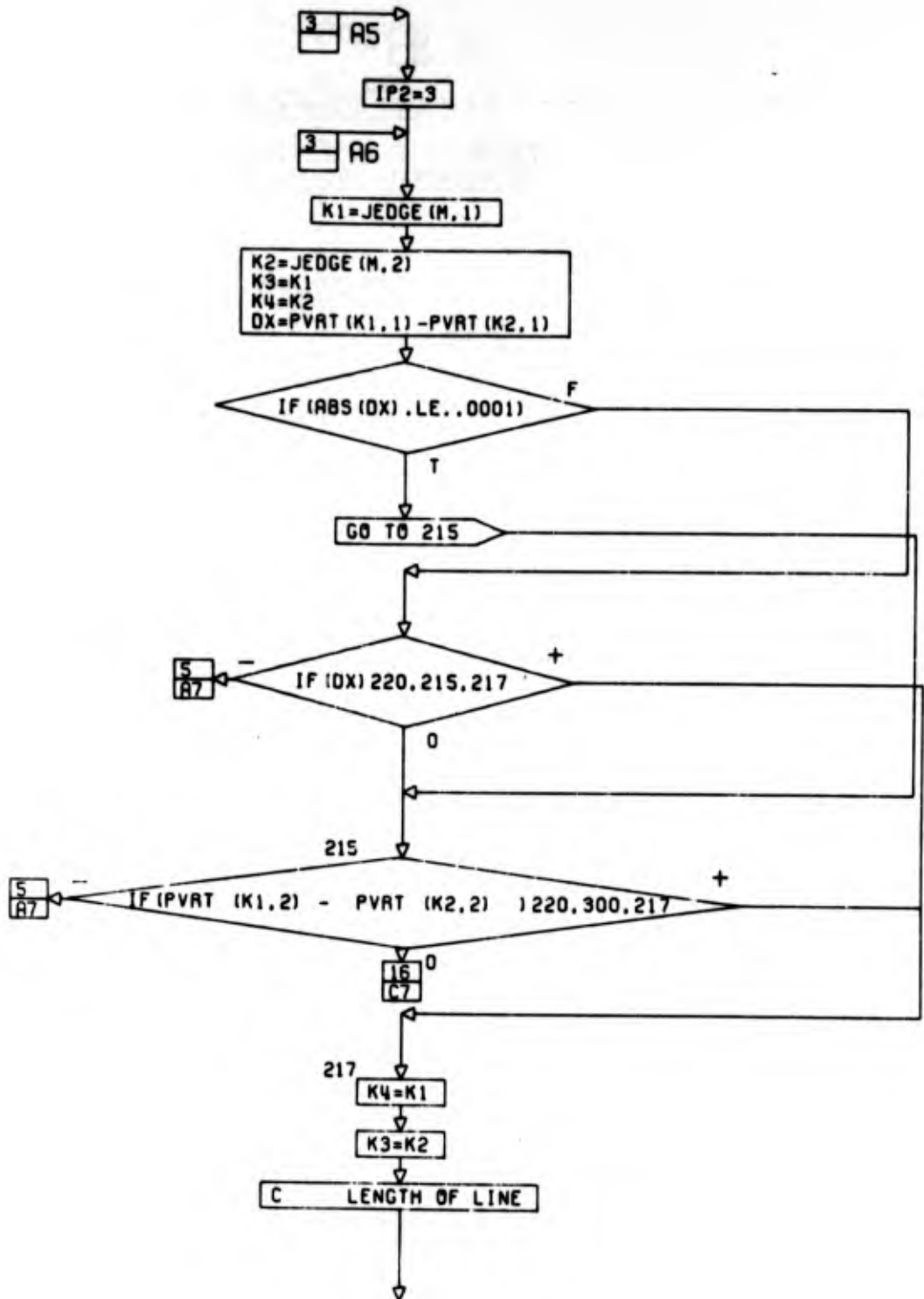
CALL XFORM (PVXYZ (M,1),PVXYZ (M,2),PVXYZ (M,3),PVRT (M,1),PVRT (M,2))

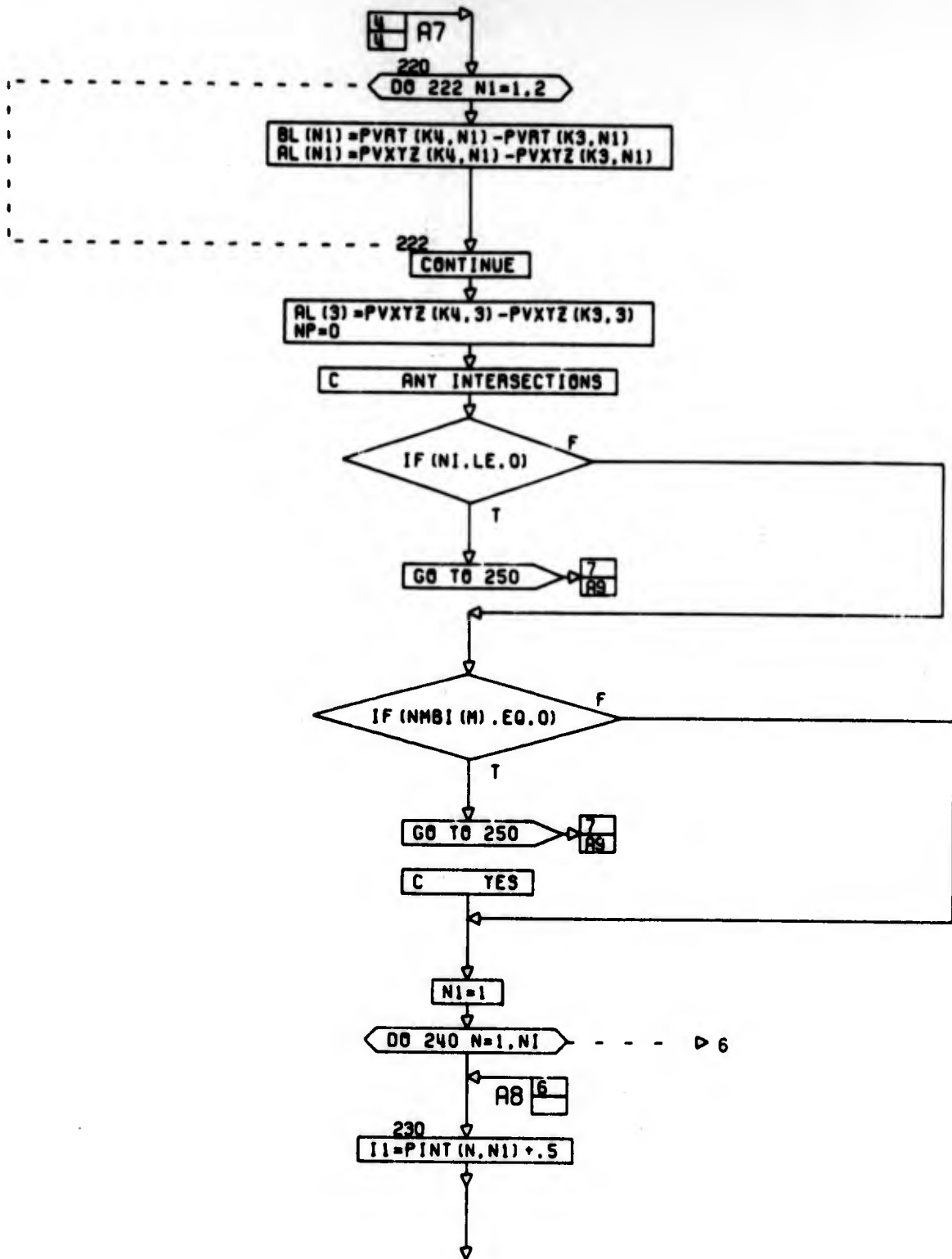
136 CONTINUE

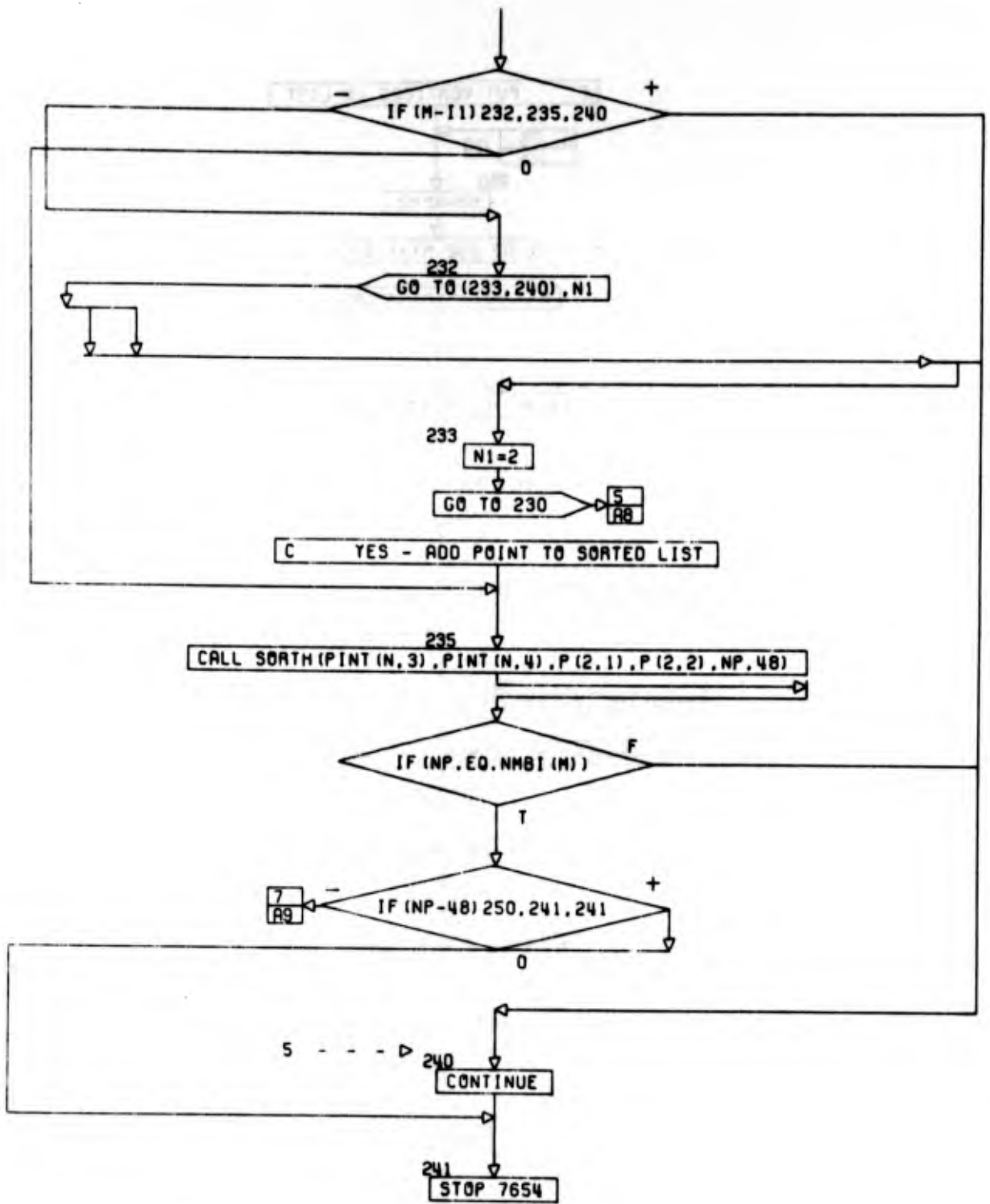


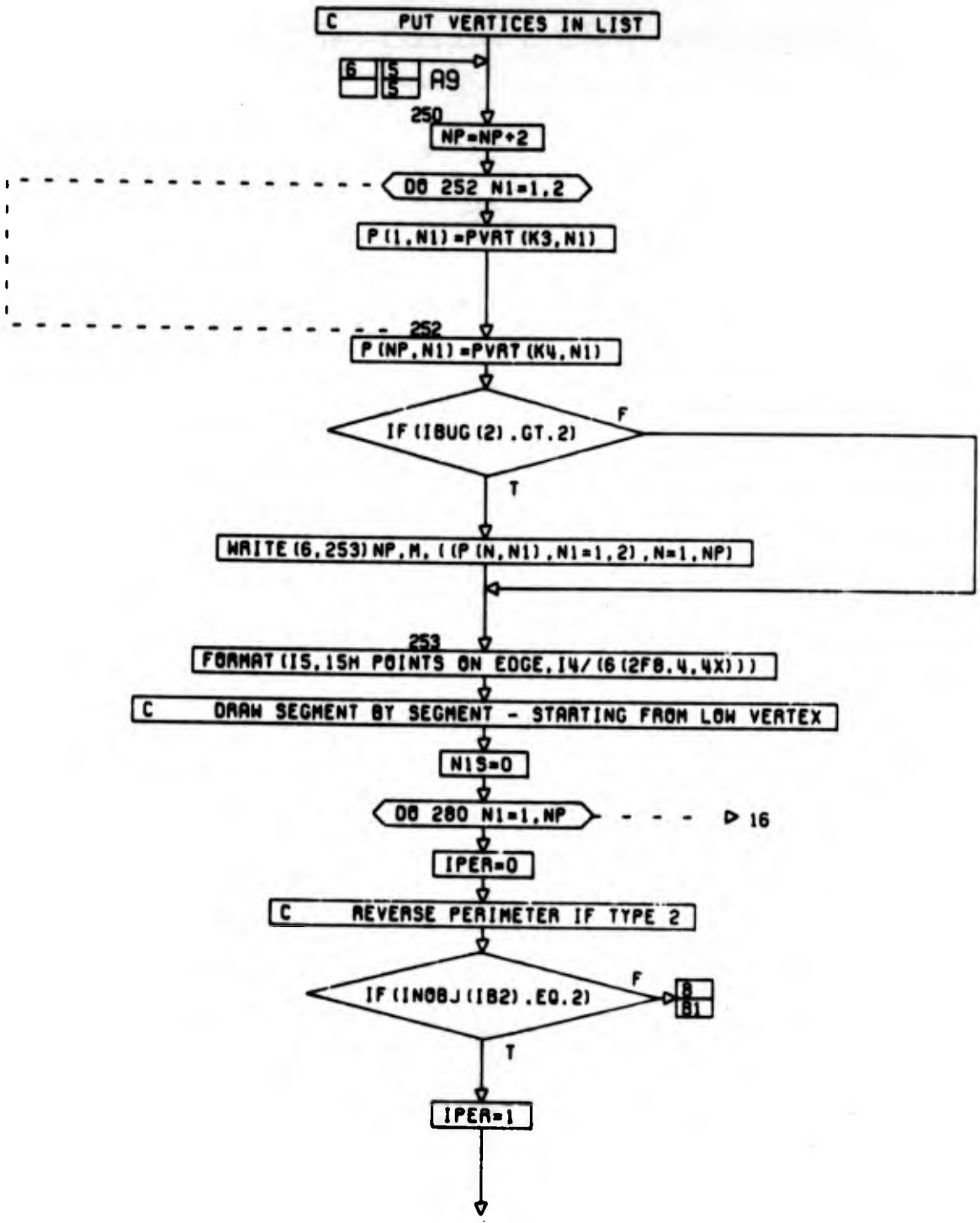


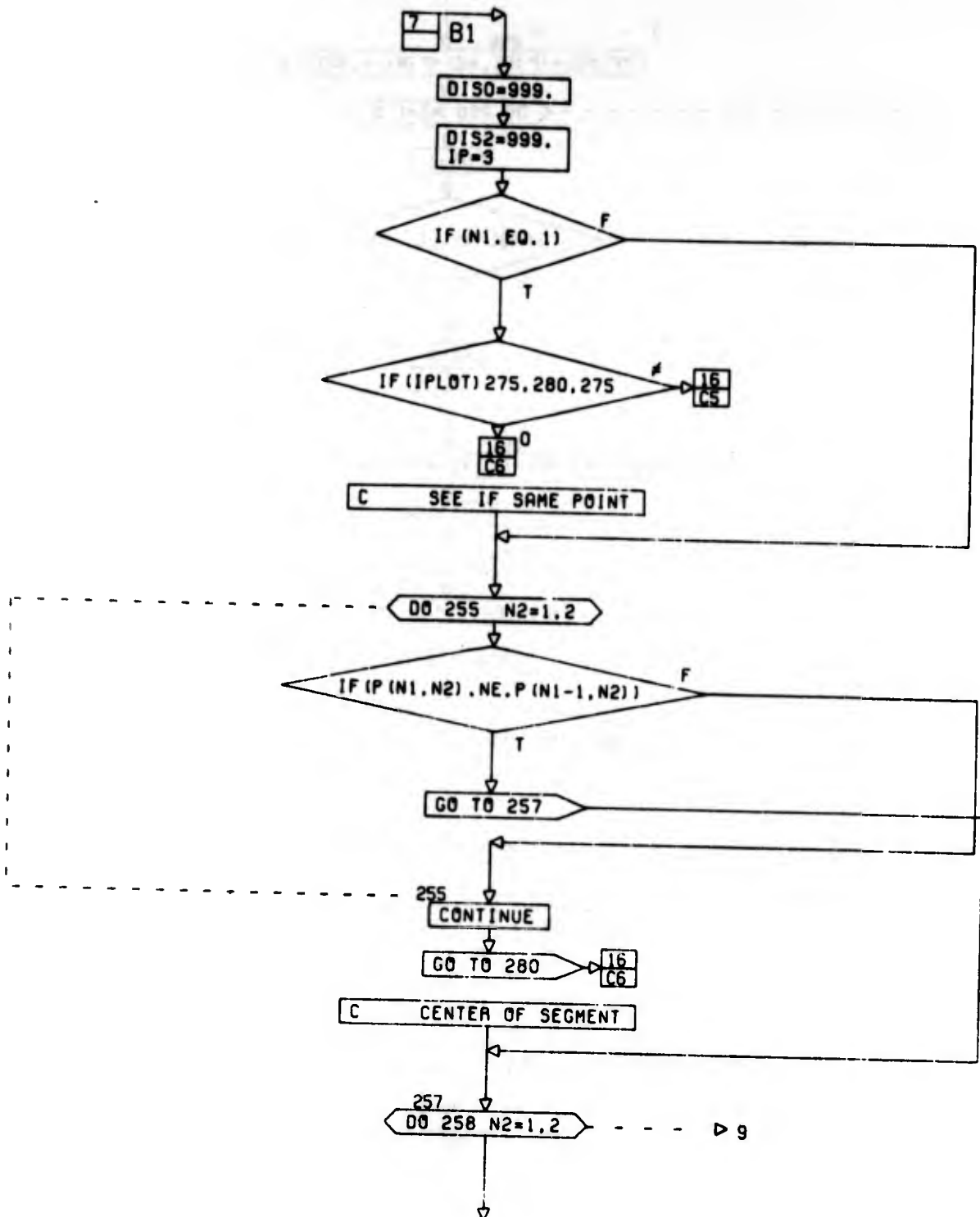


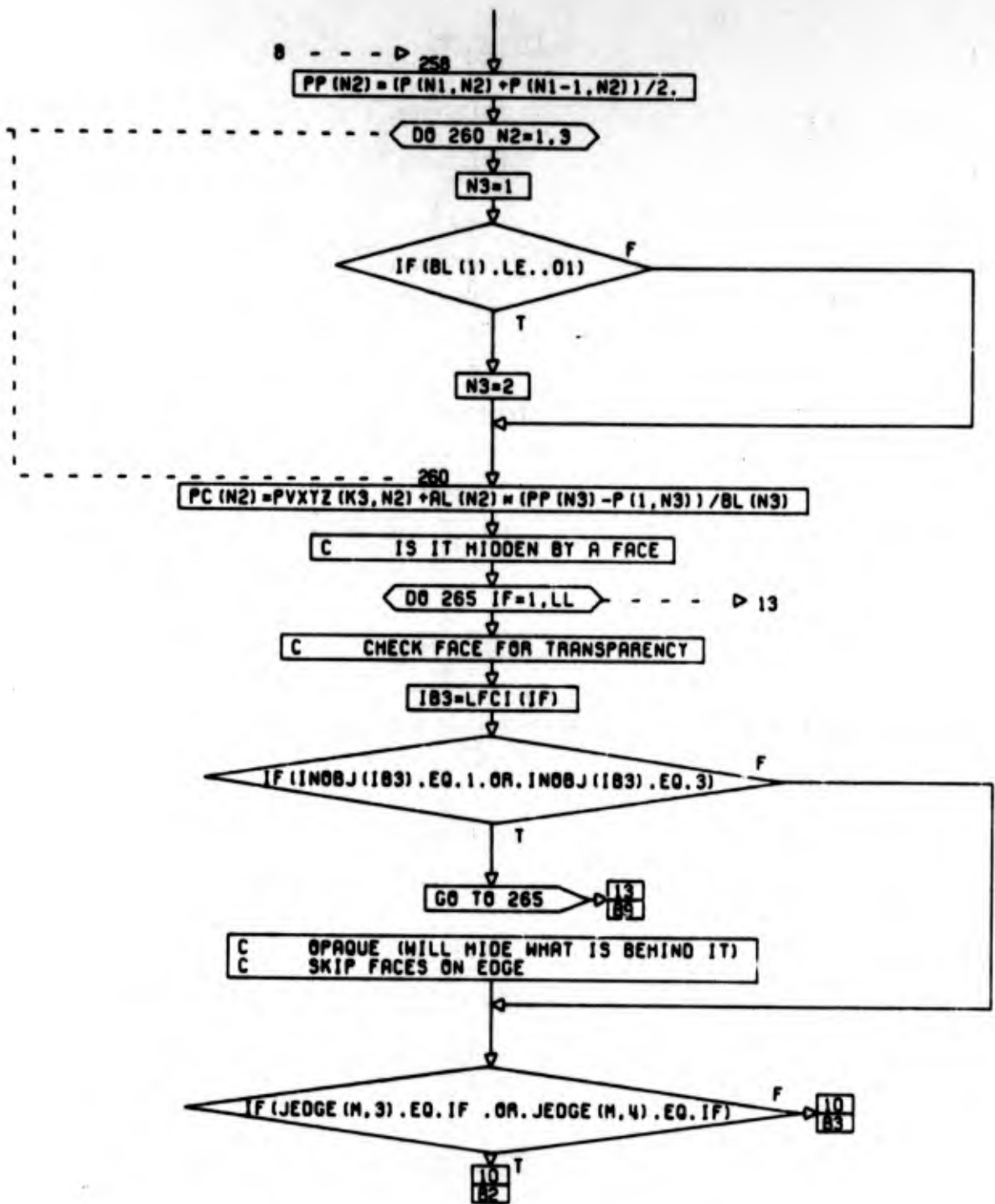


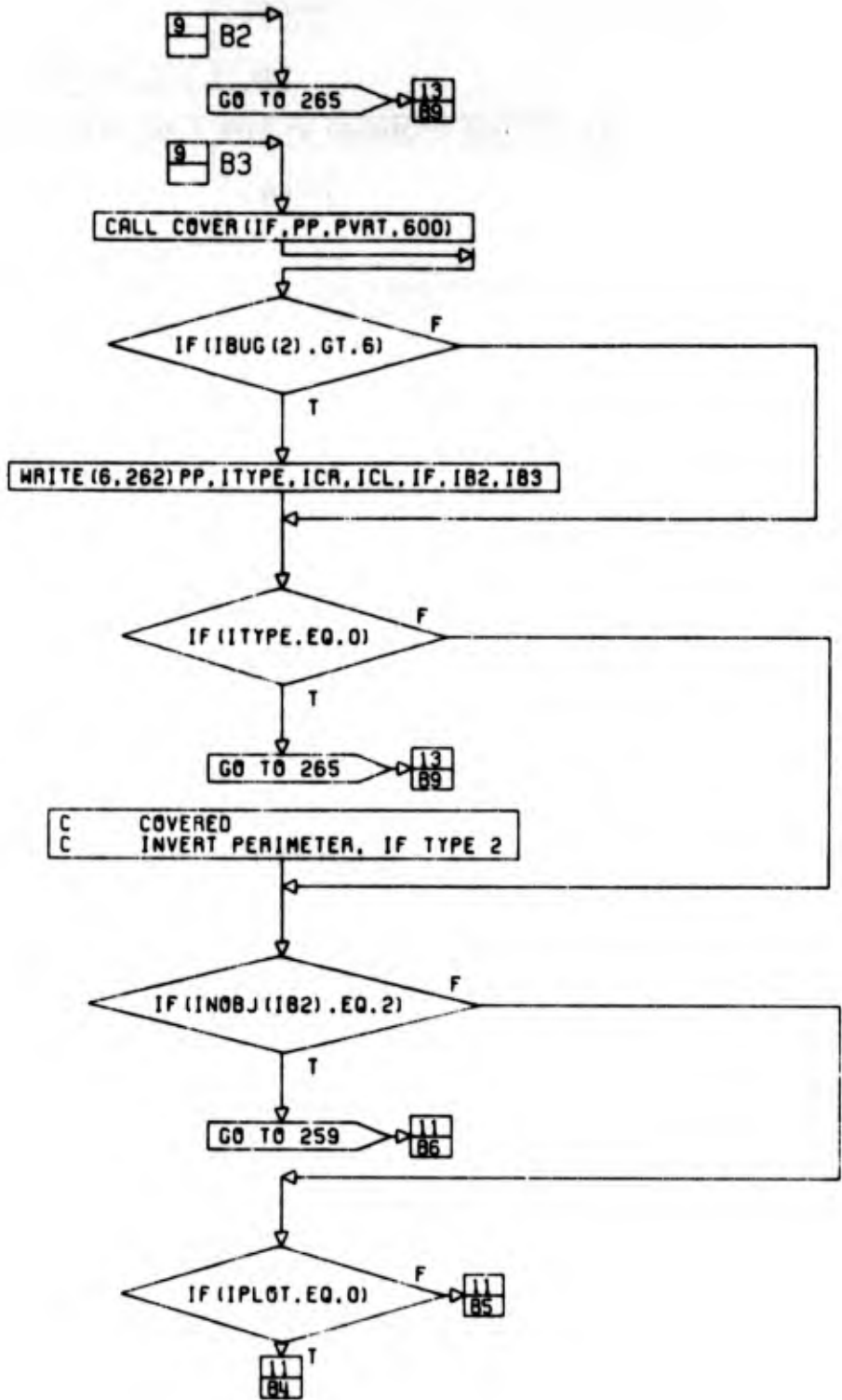


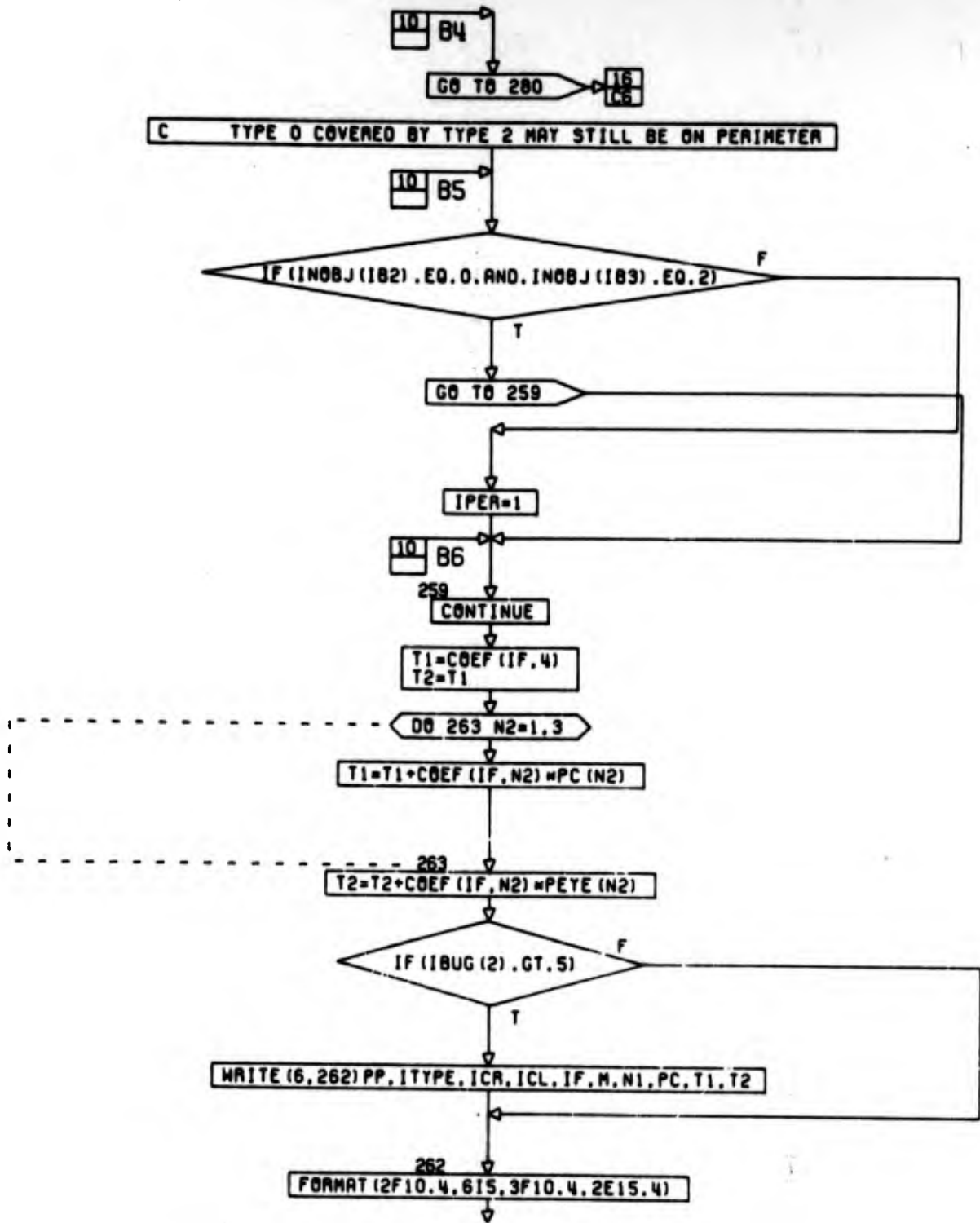


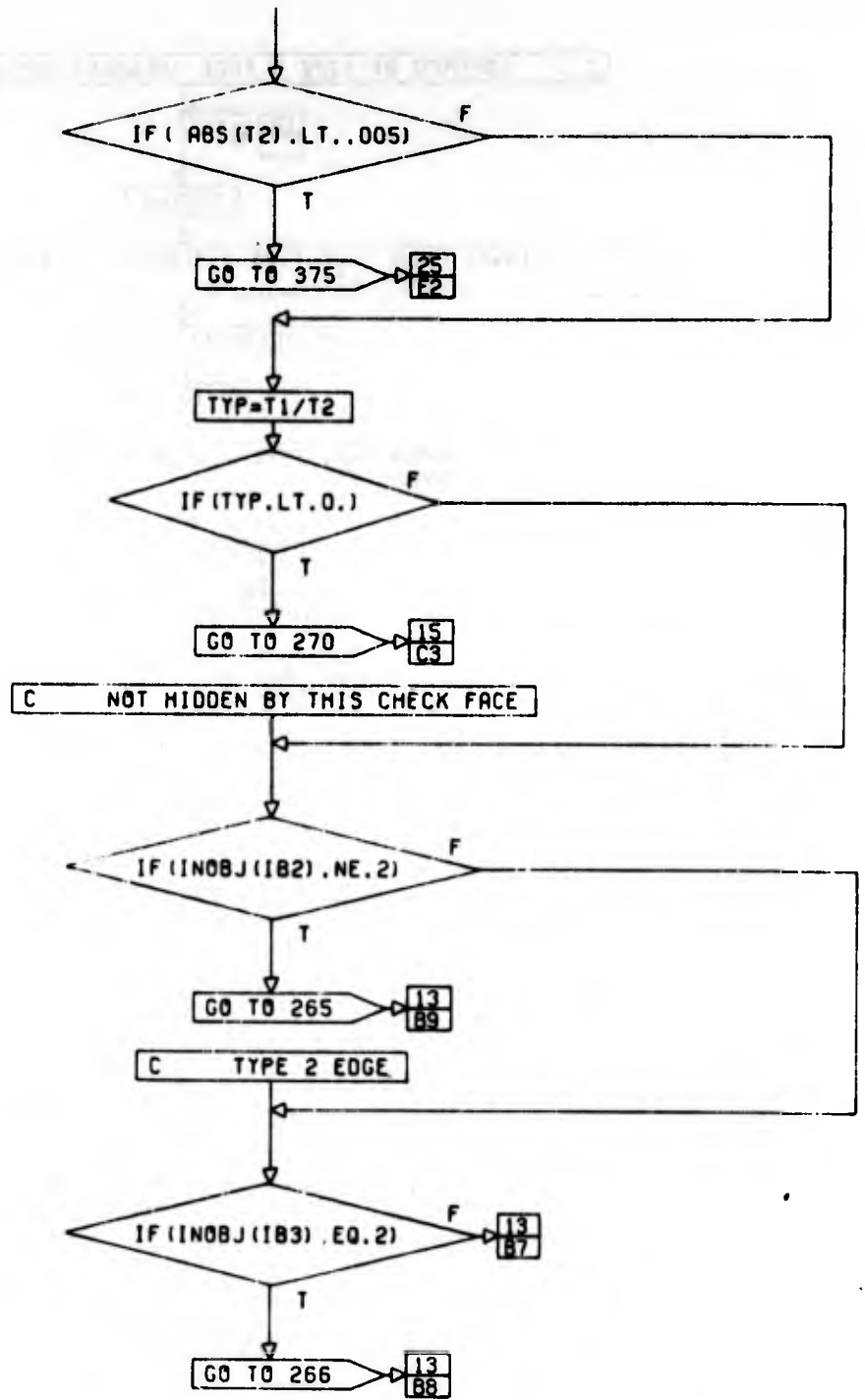


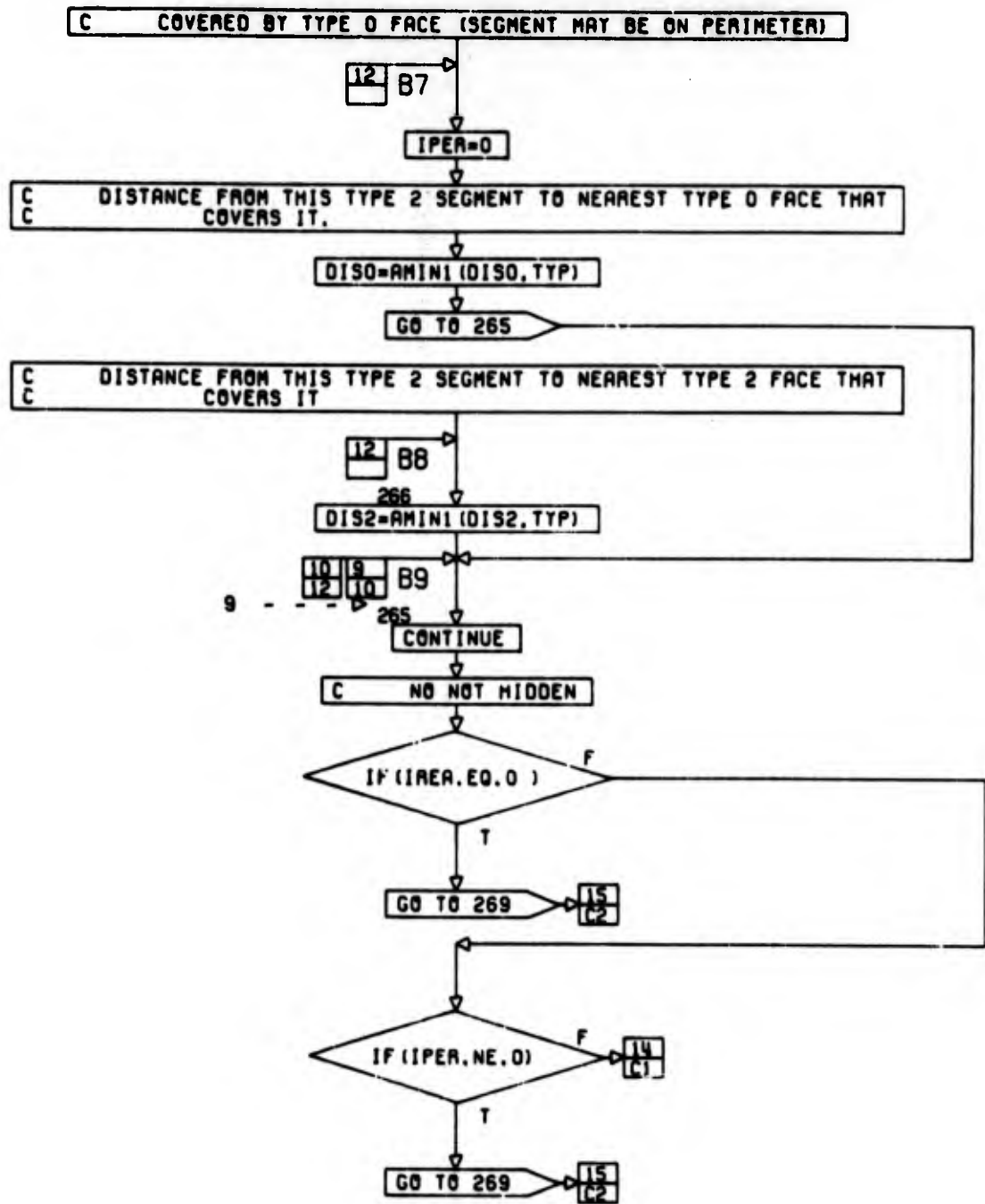


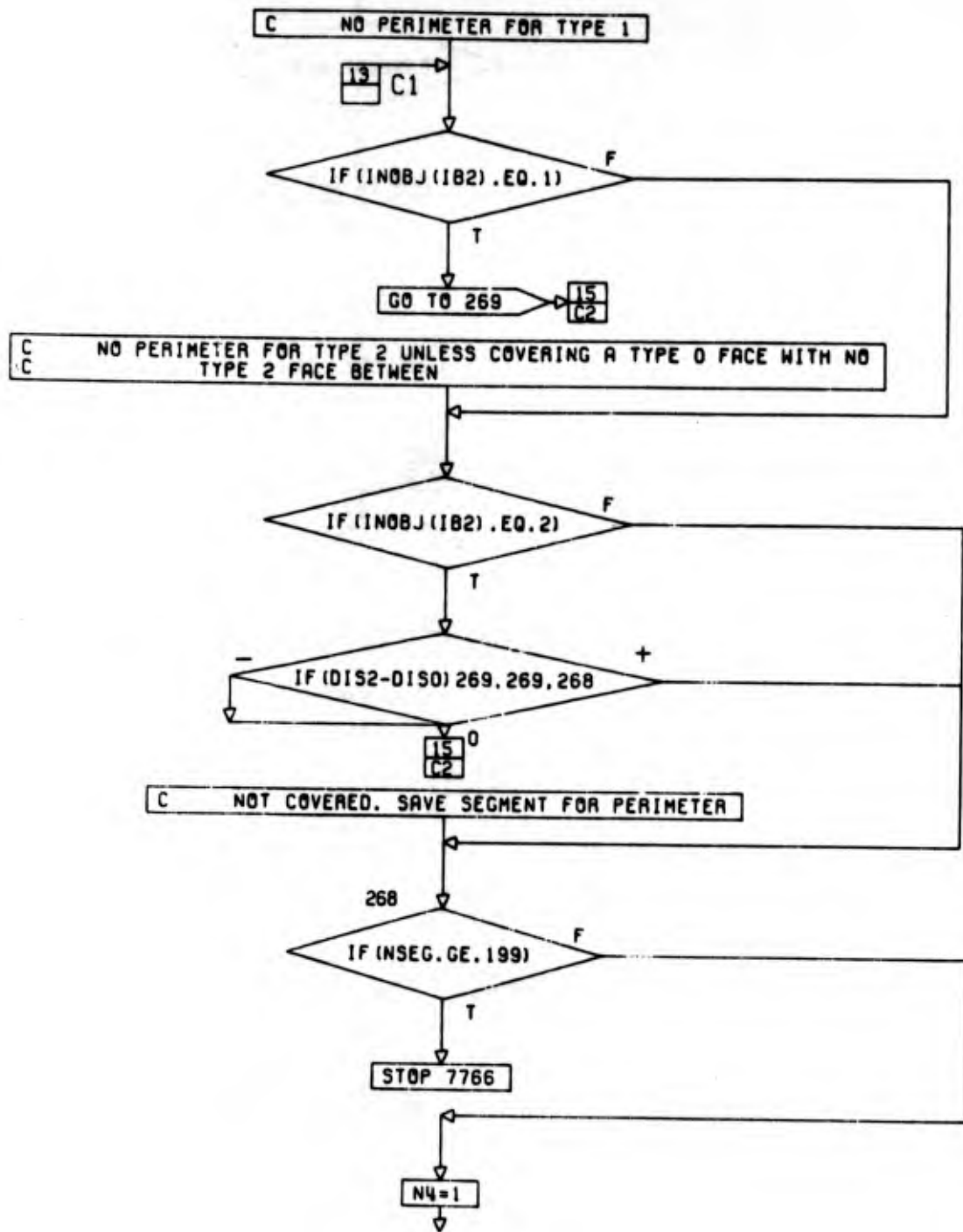


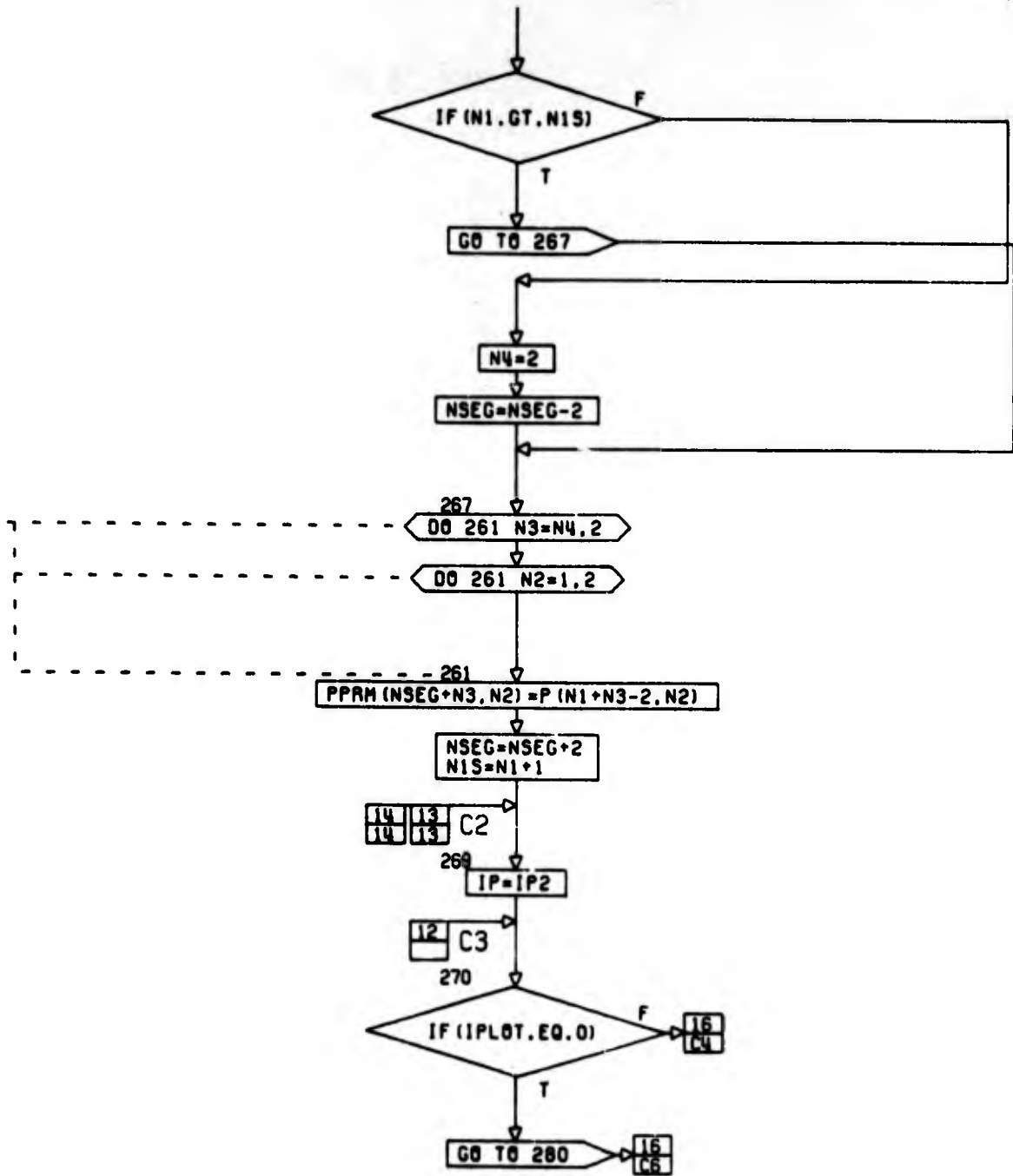


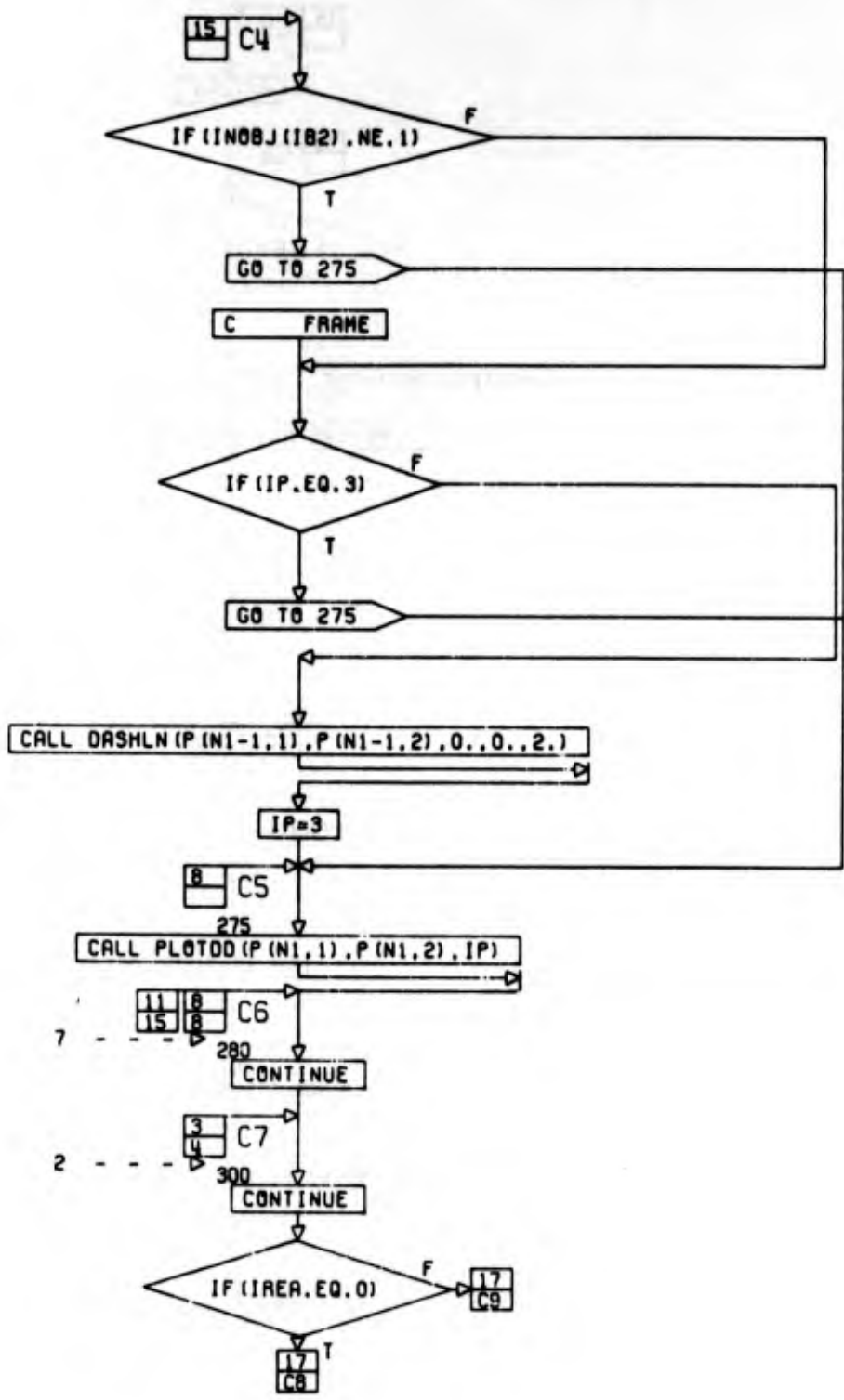


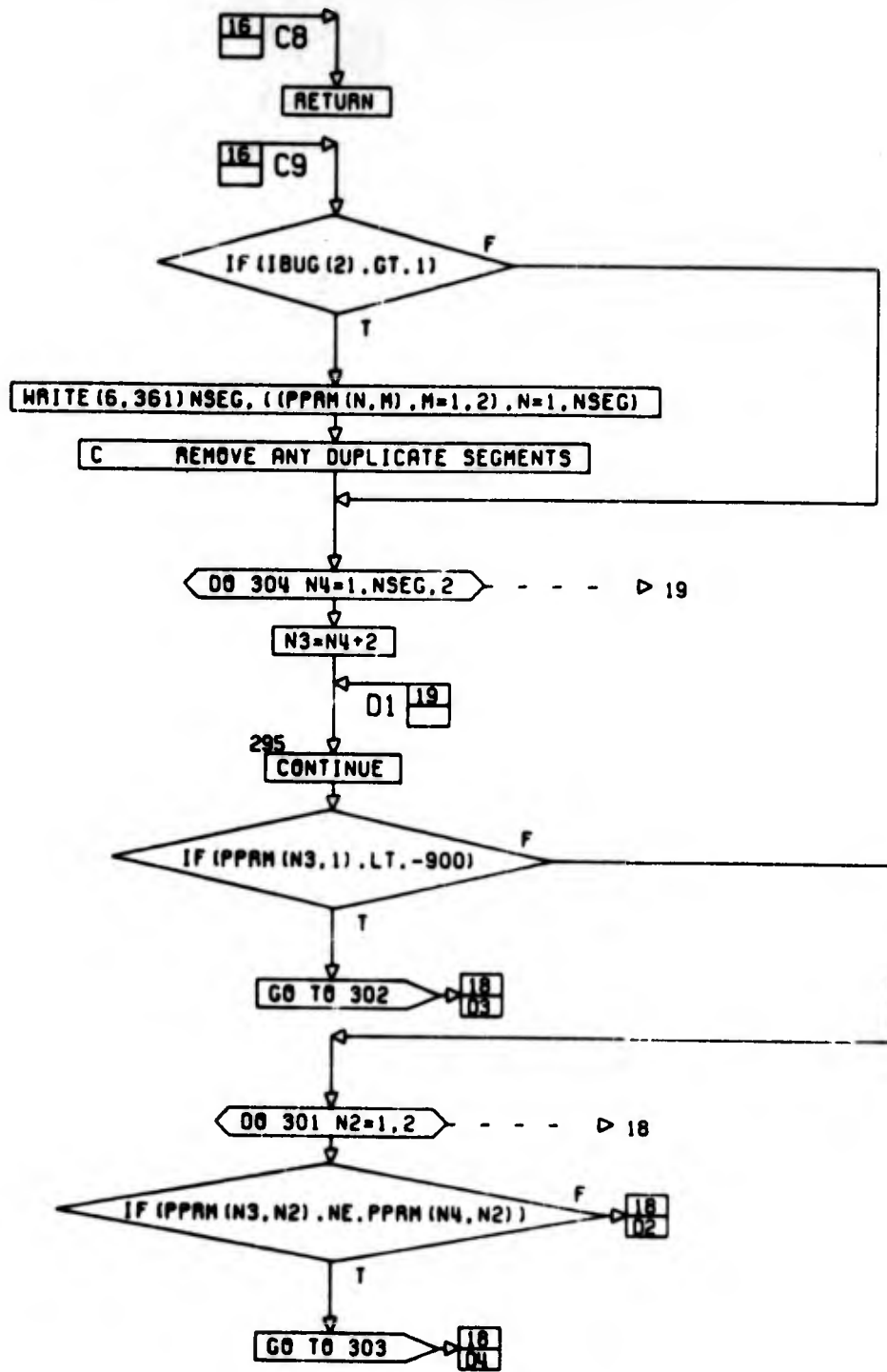


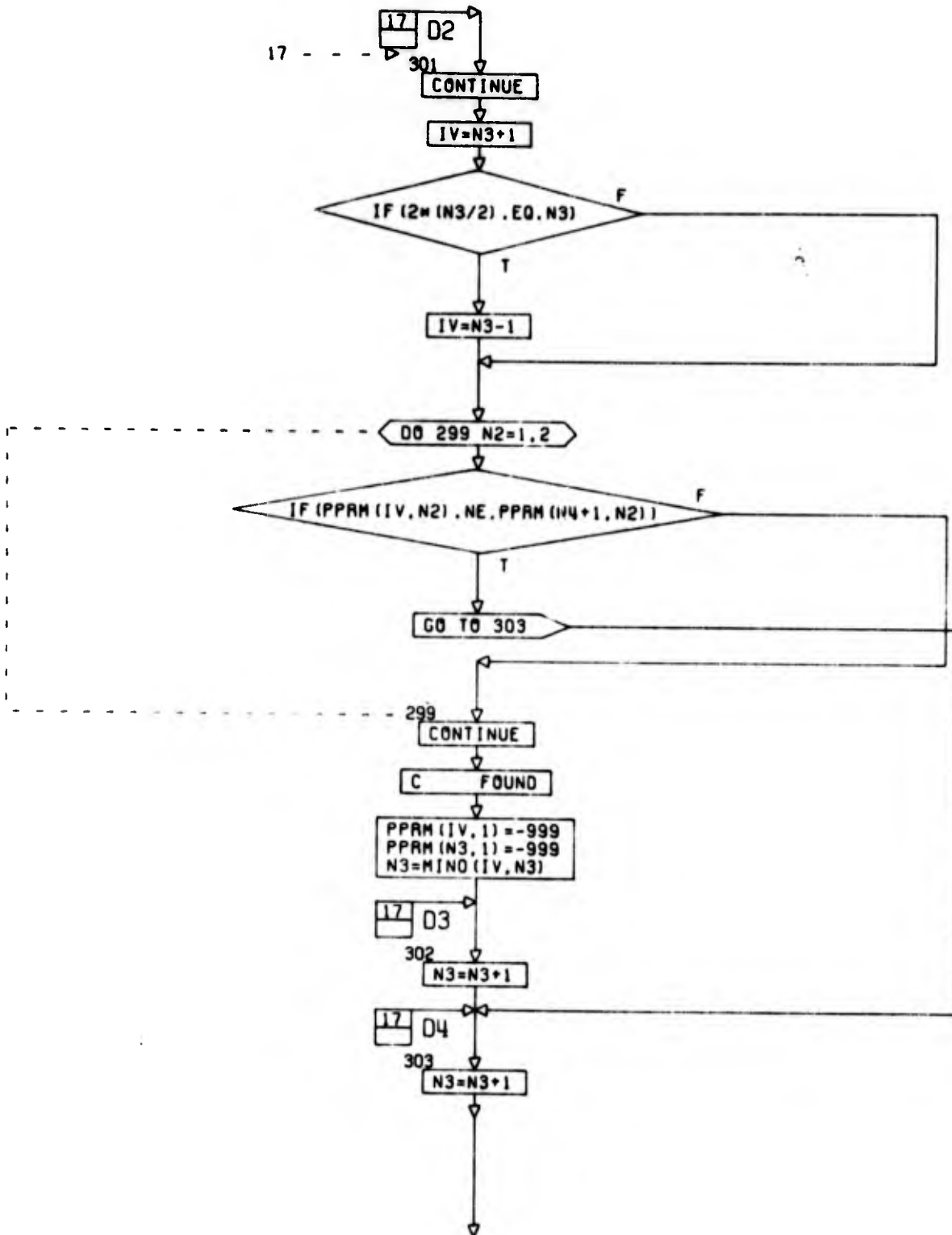


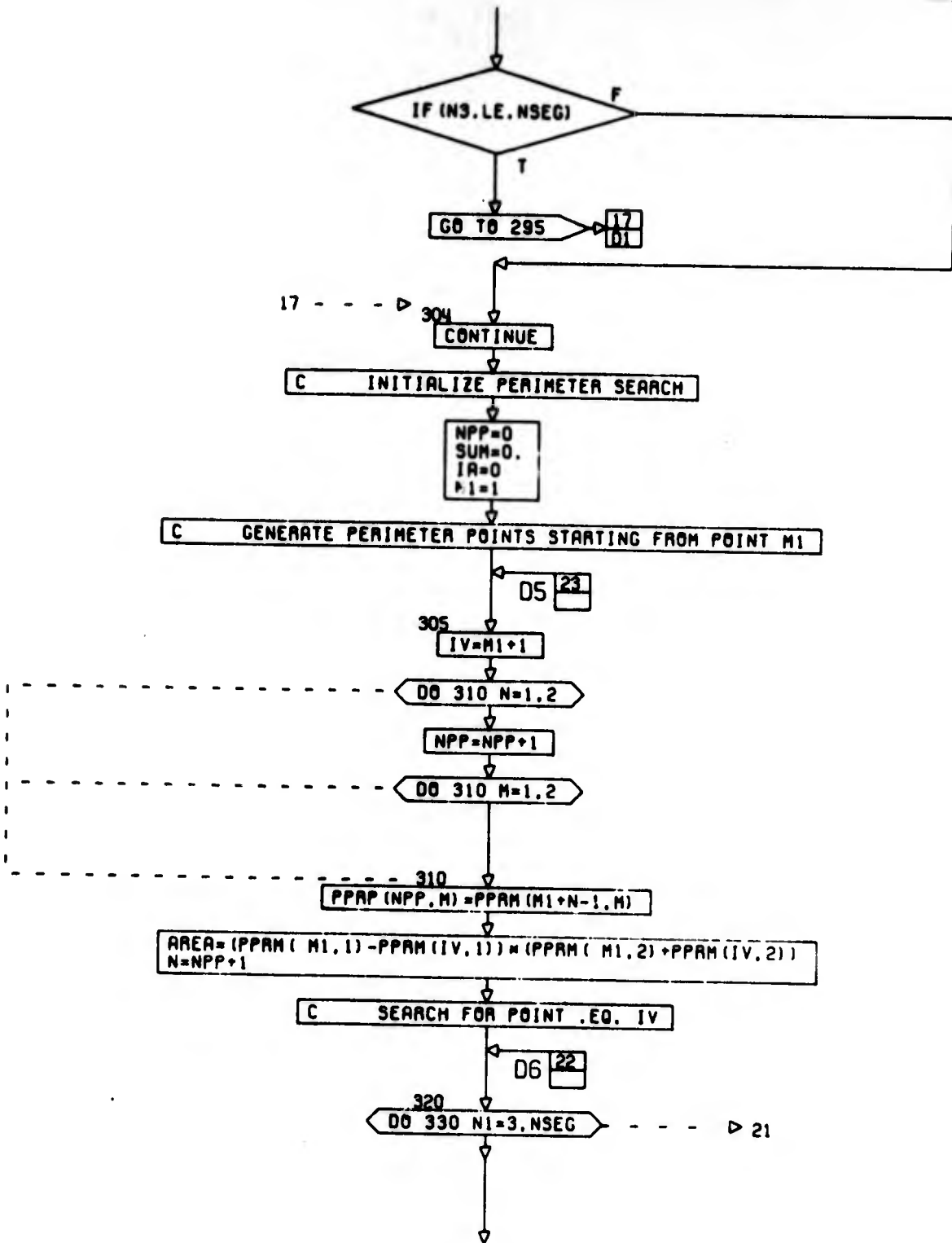


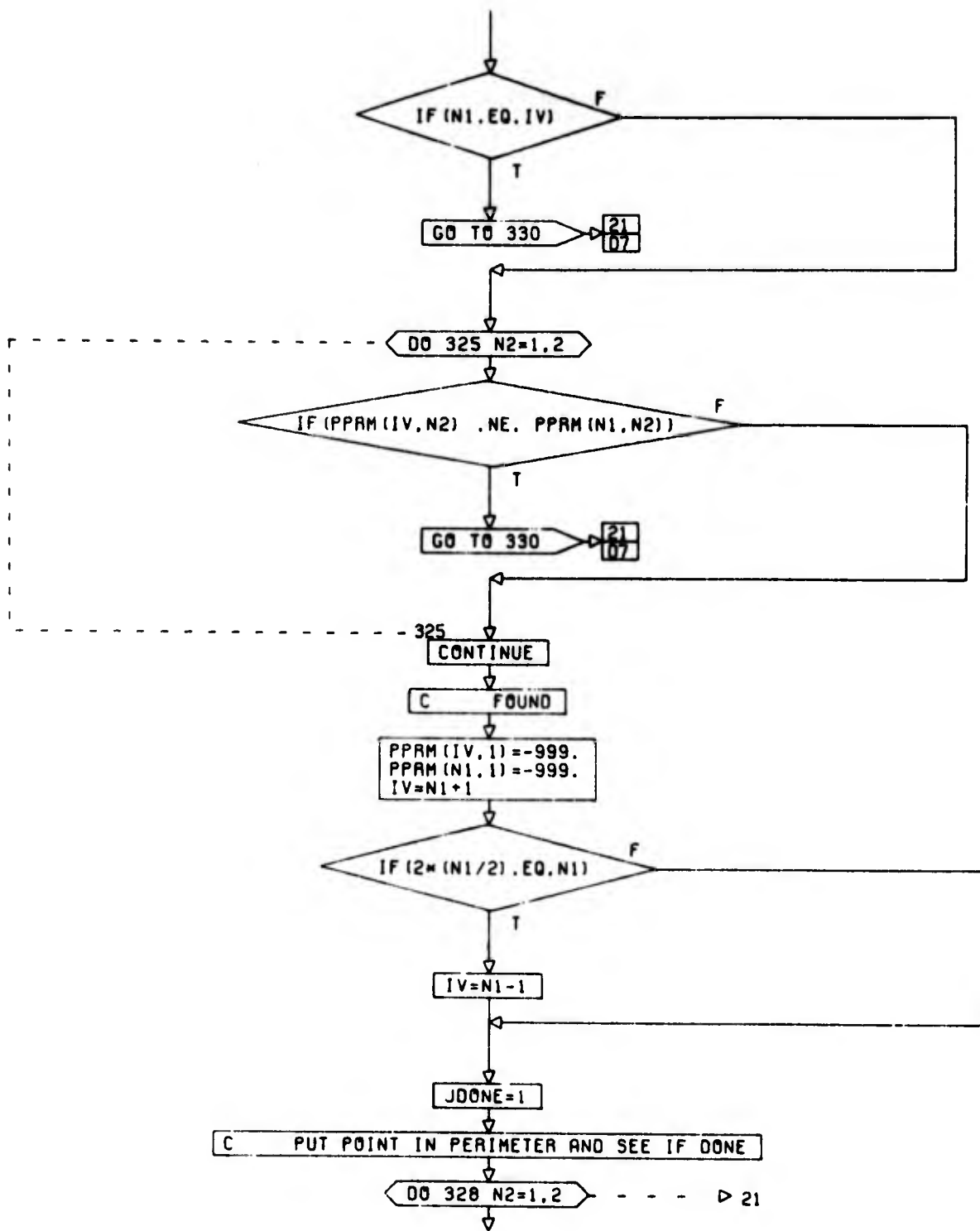


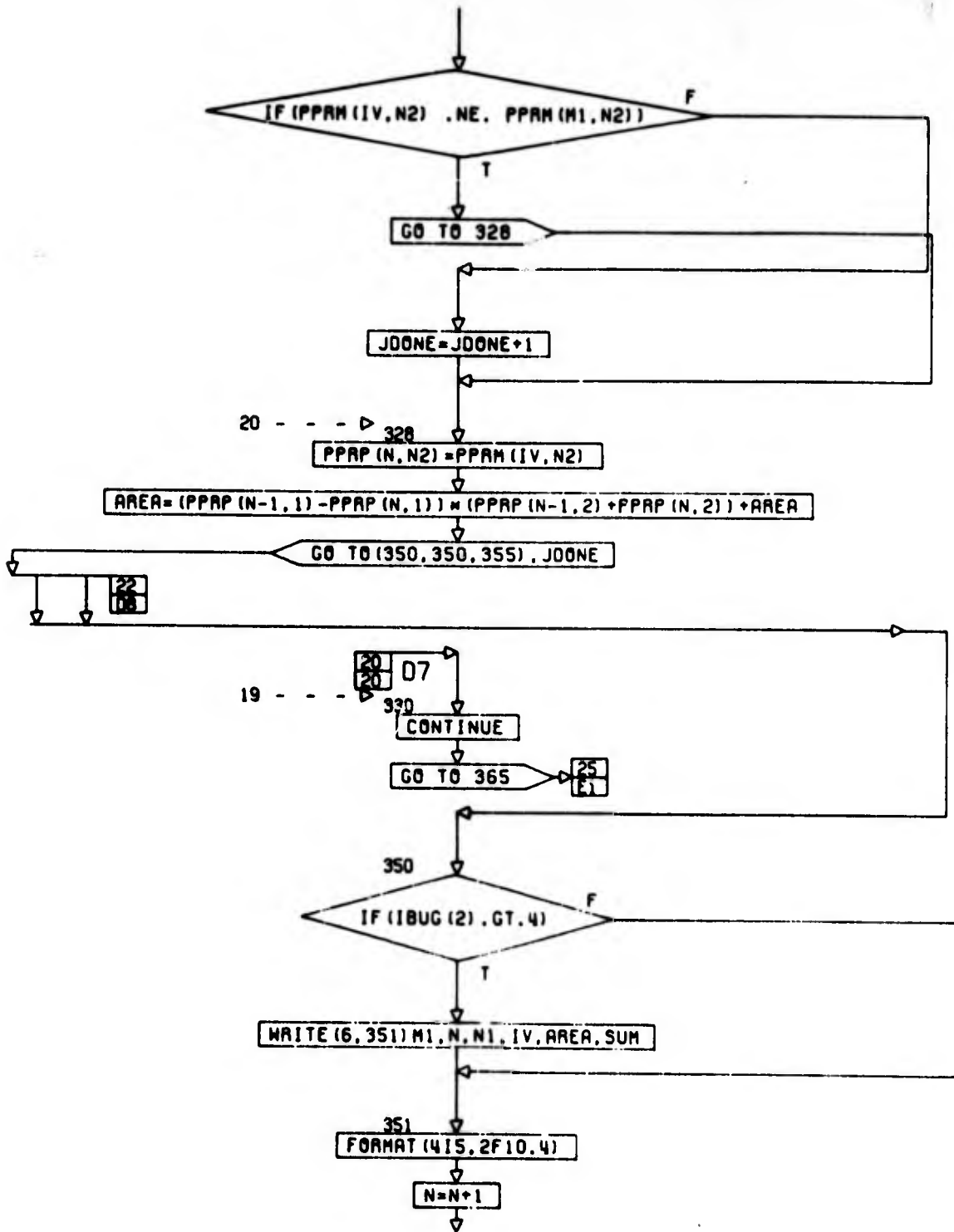


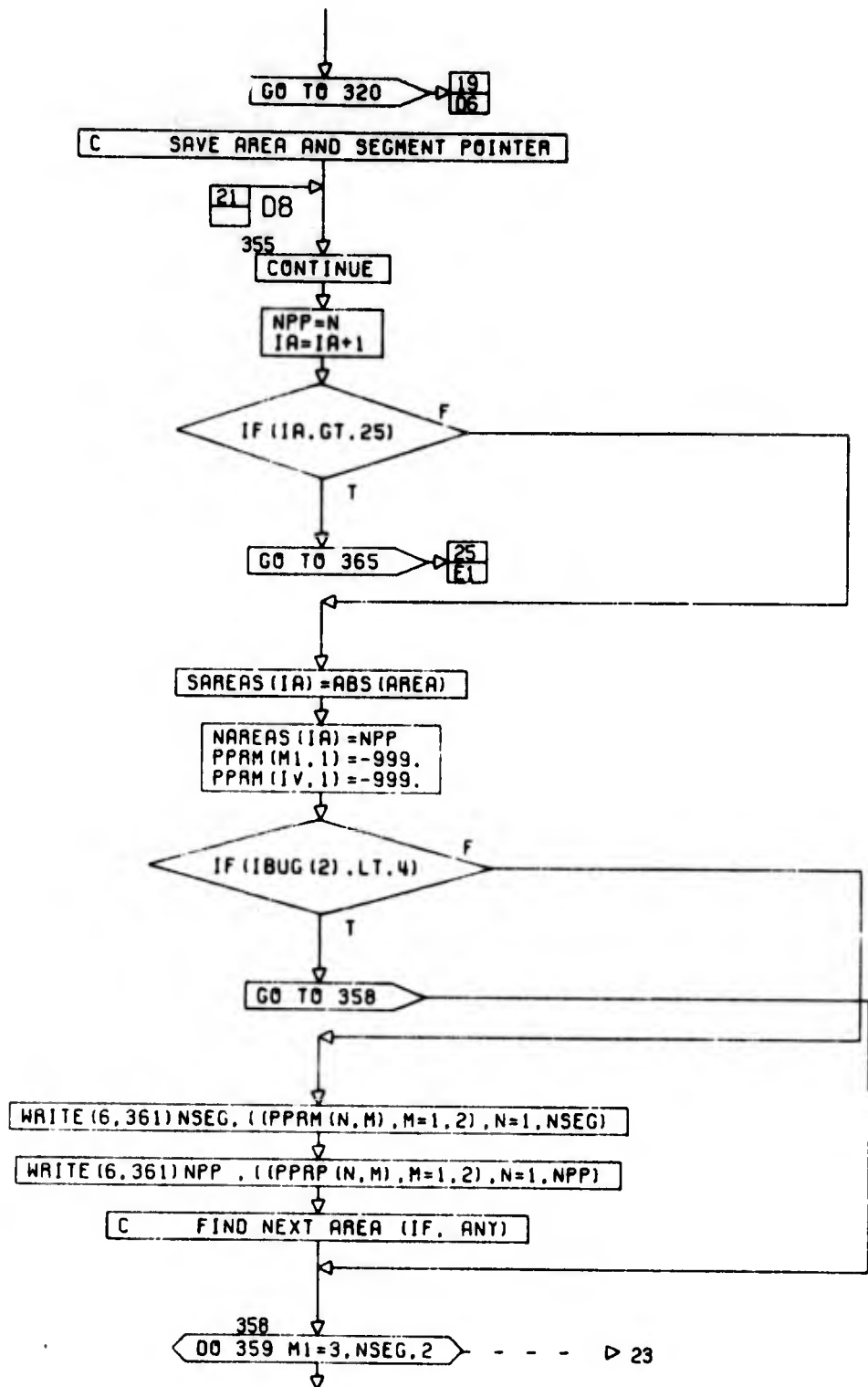


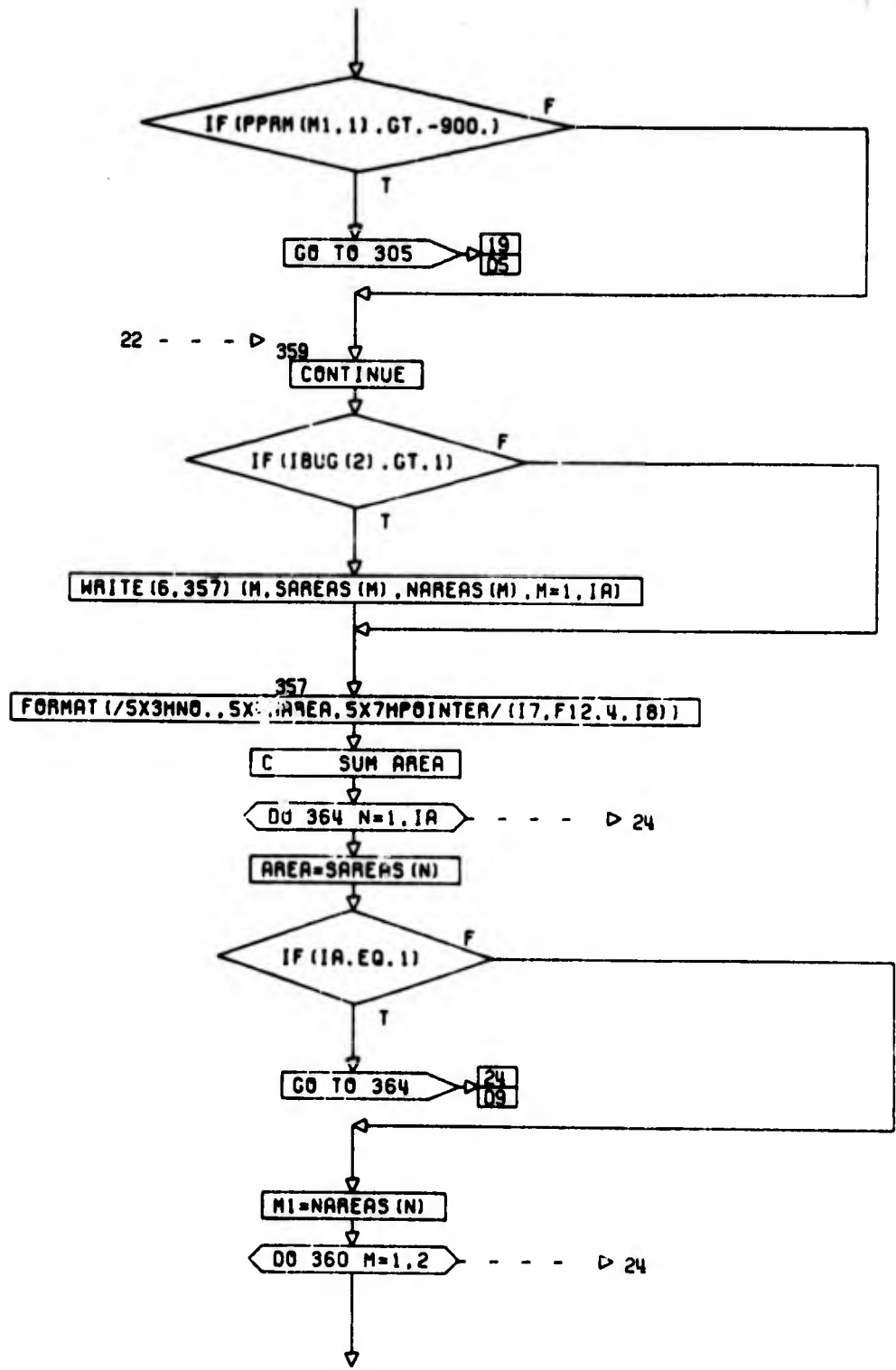


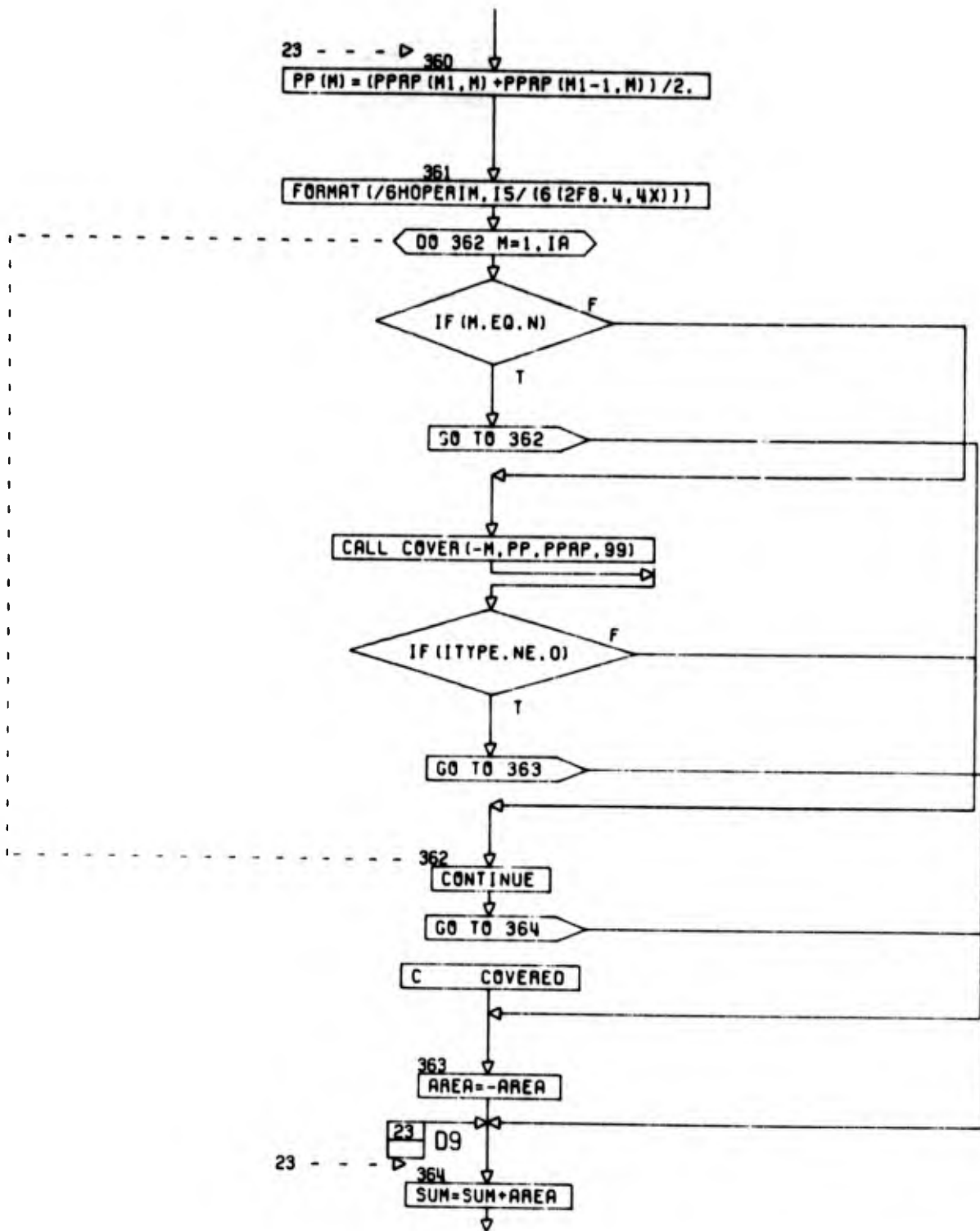


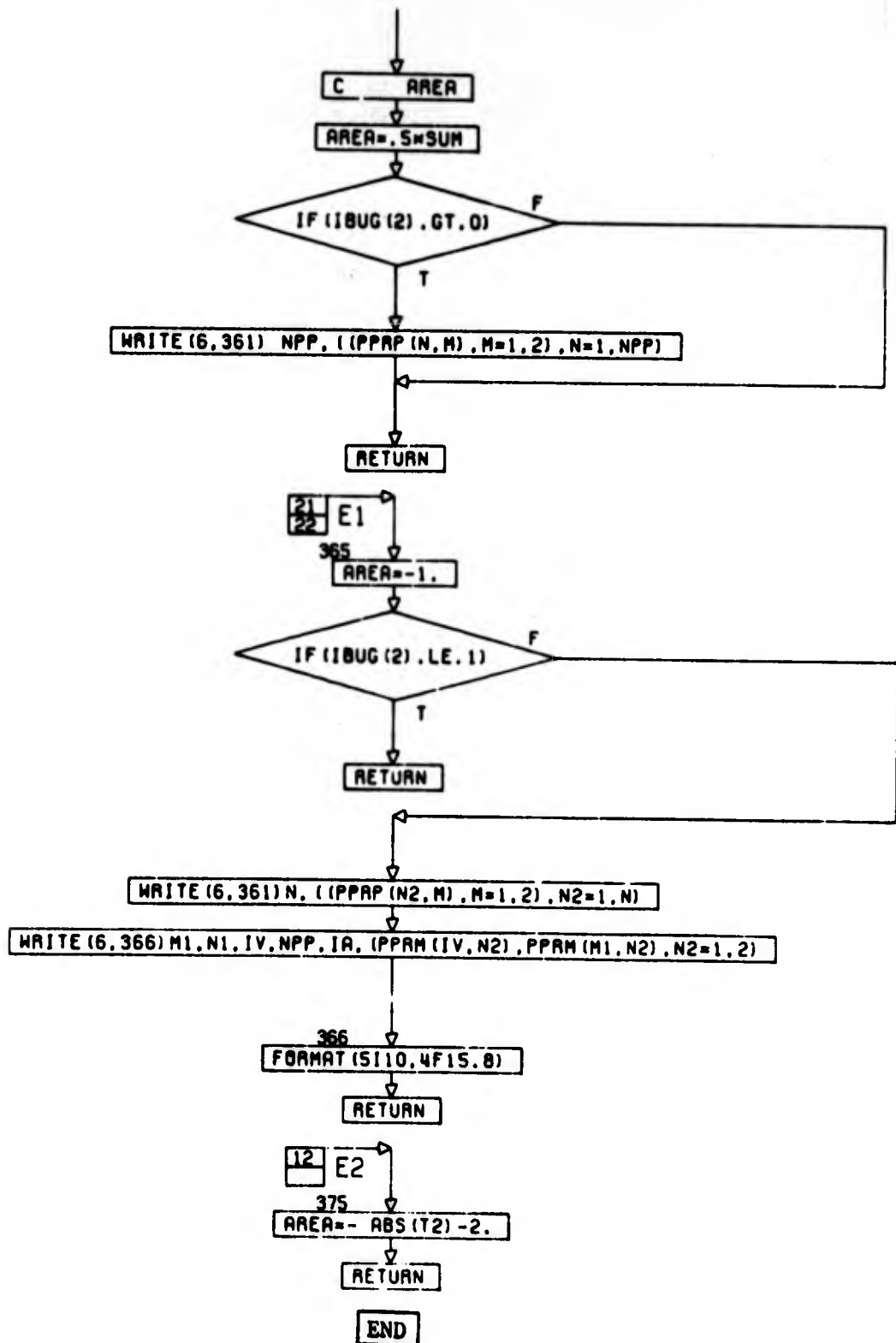












SUBROUTINE INTER

SUBROUTINE INTER

COMMON COEF (300, 4)
 , LFCE (301), JFCE (1800), PVAT (600, 2), PVXYZ (600, 3), JEDGE (900, 5),
 PINT (1200, 4), PEYE (3), NMBI (900)
 , IOBJ (16), INOBJ (15), LFCI (300)

COMMON /INPTT/J, NE, LL, L, NI, NP, NOBJ, IM
 COMMON/DEBUGS/IBUG (4)
 COMMON /ANSH/ITYPE, ICA, ICL, TYP

C J - NUMBER OF POINTS
 C NE - NUMBER OF EDGES
 C LL - NUMBER OF FACES
 C L - LENGTH OF JFCE TABLE
 C NI - NUMBER OF INTERSECTIONS
 C PINT (NI, 1) = EDGE NUMBER I
 C PINT (NI, 2) = EDGE NUMBER K
 C PINT (NI, 3) = X INTERSECT

C PINT (NI, 4) = Y INTERSECT
 C NMBI (I) = NUMBER OF INTERSECTIONS ON EDGE I

IF (IBUG (4) .GT. 0)

WRITE (6, 20)

20
 FORMAT (//5X1HX7X1HY6X3HX115X3HY115X3HX125X3HY125X3HSL15X3HXK15X
 3HYK15X3HXK25X3HYK25X3HSLK4X3H1GG3X1H14X1HK4X1HN)

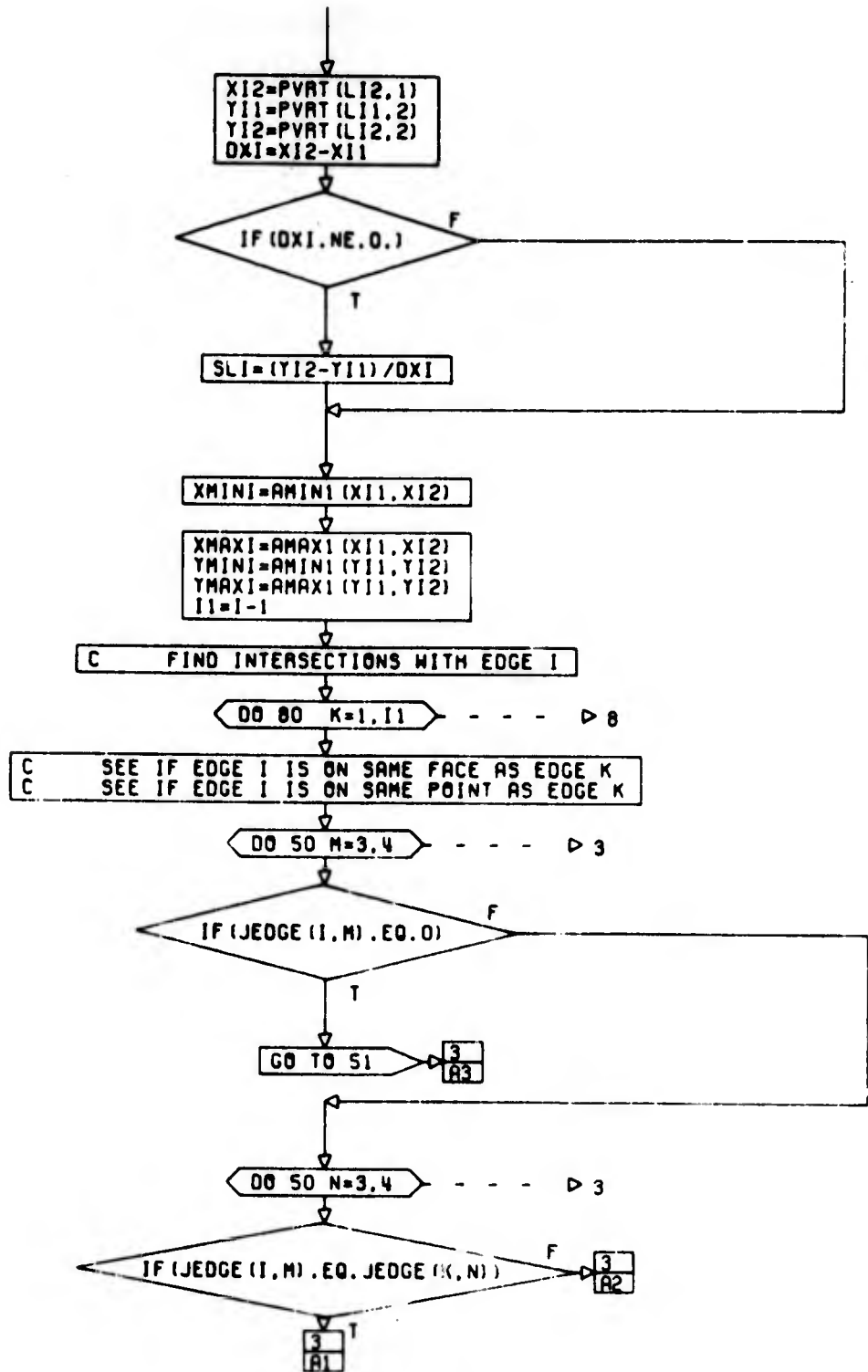
NI=0

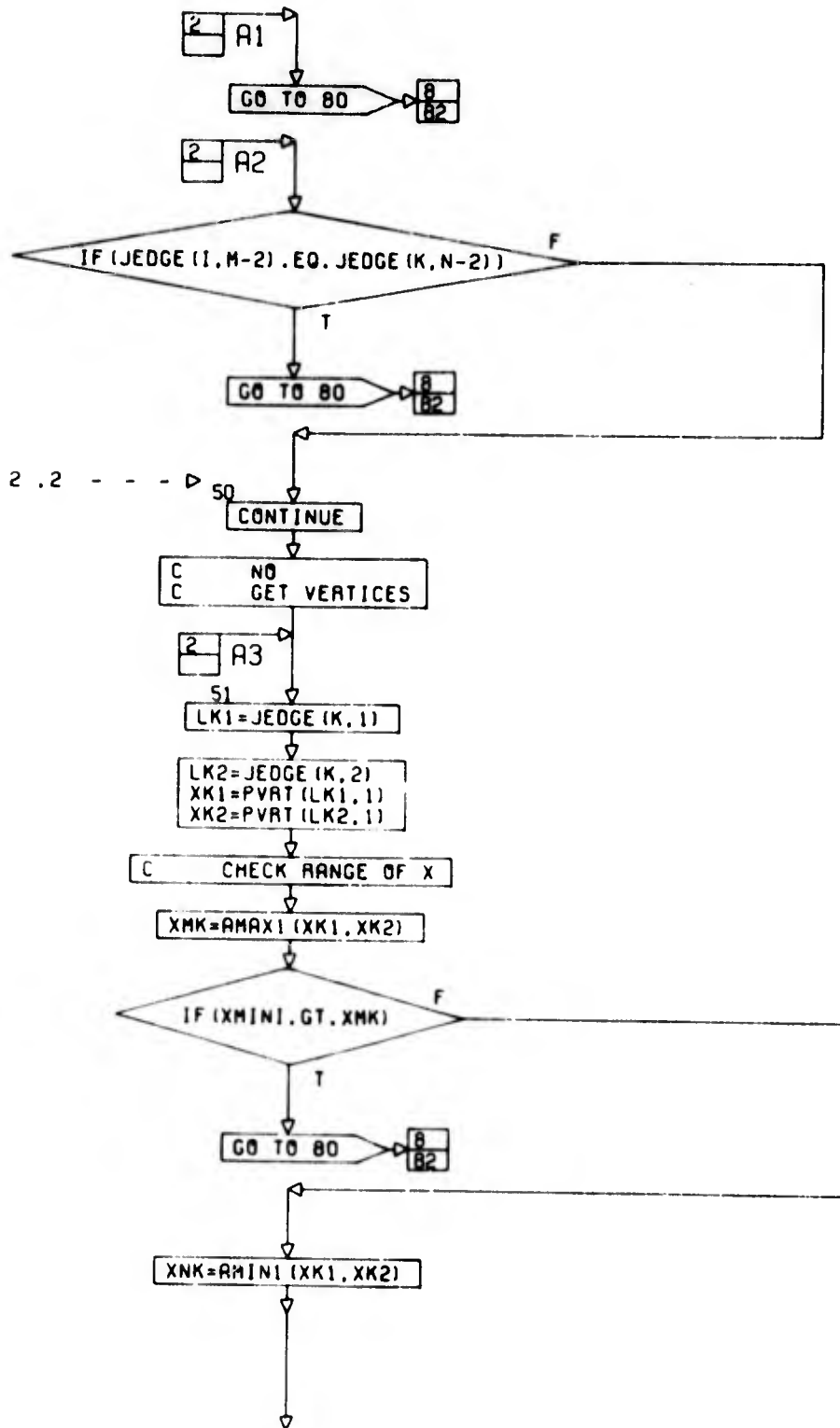
DO 30 I=1, NE

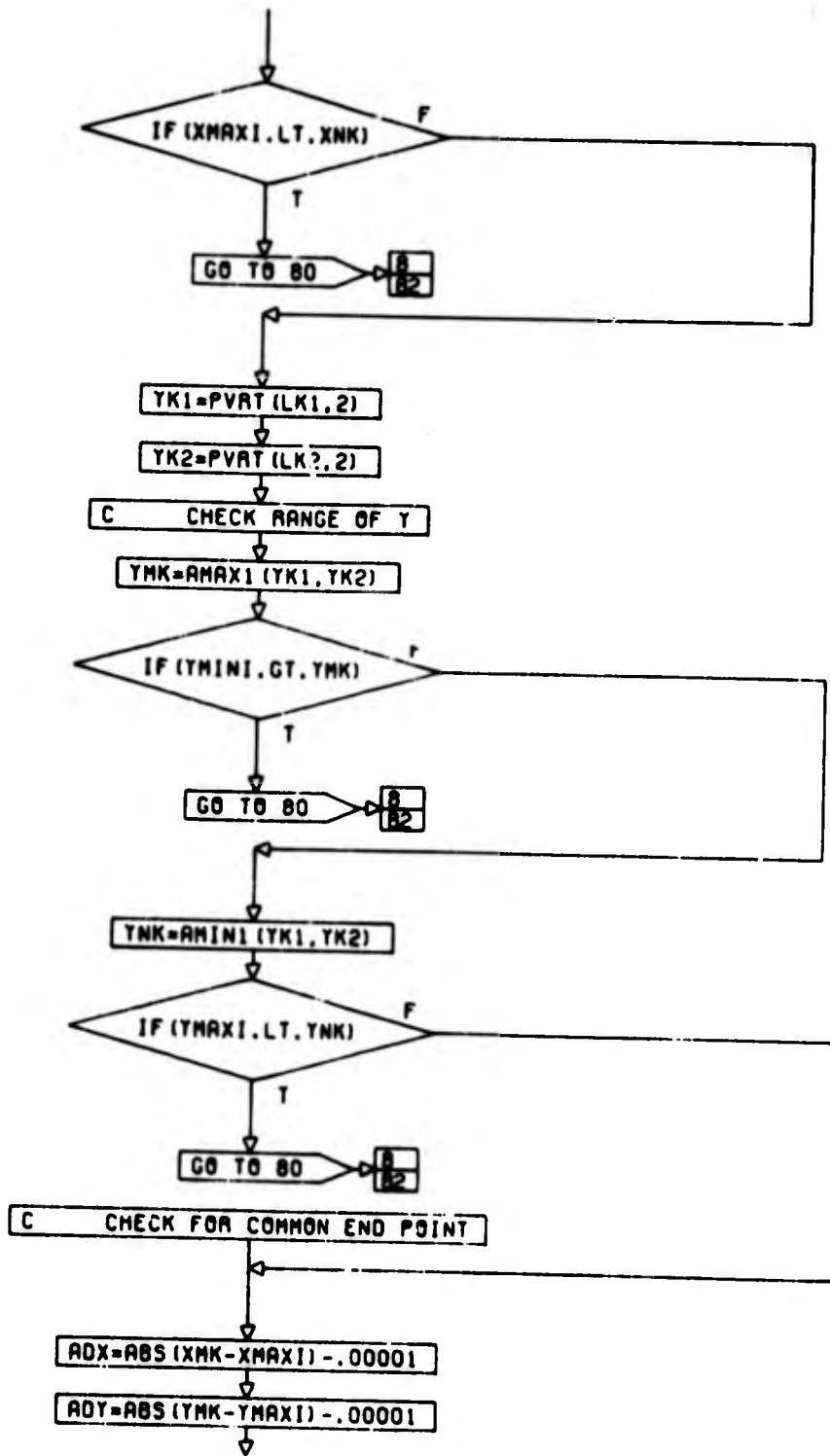
30
 NMBI (I) = 0

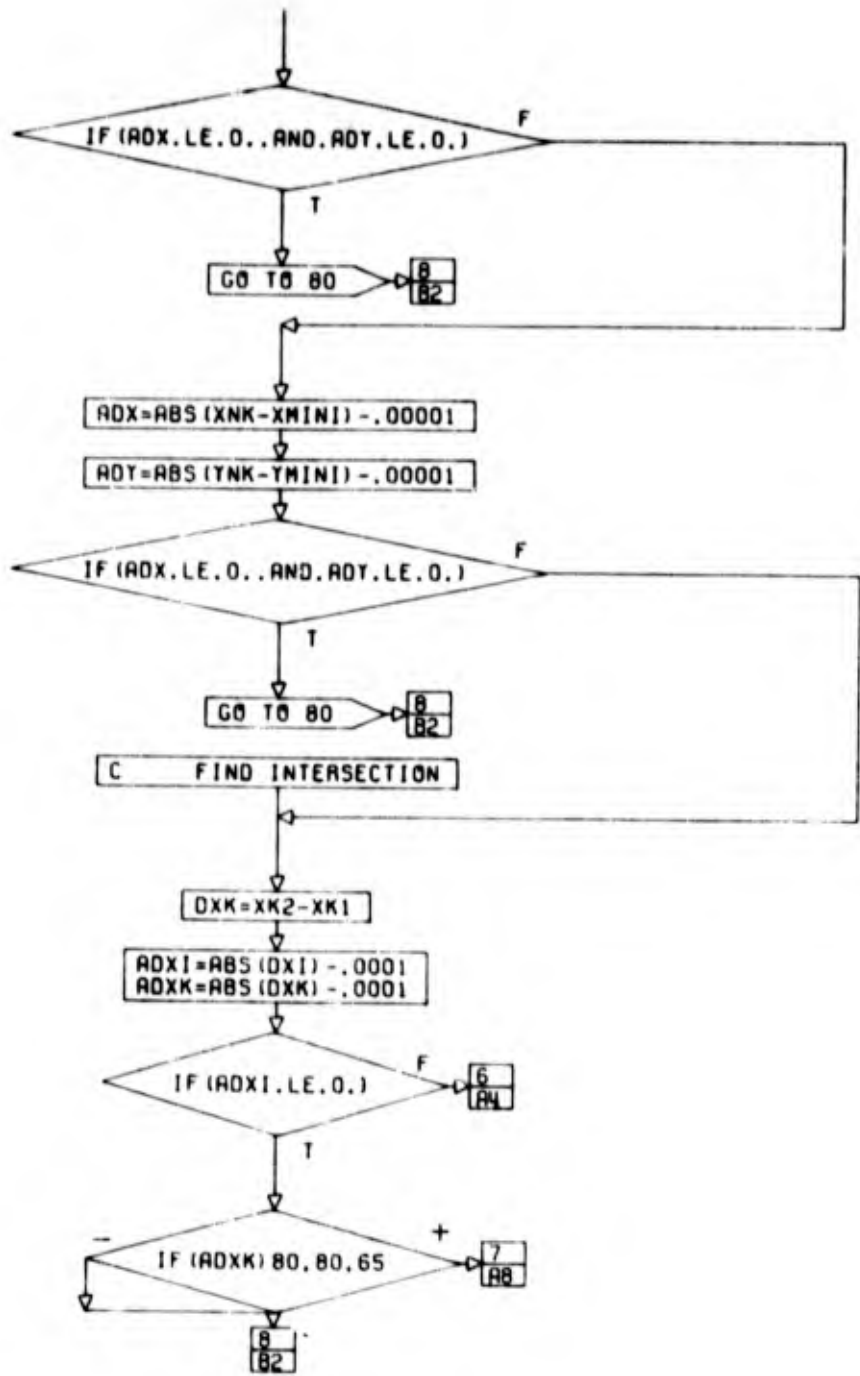
DO 90 I=2, NE

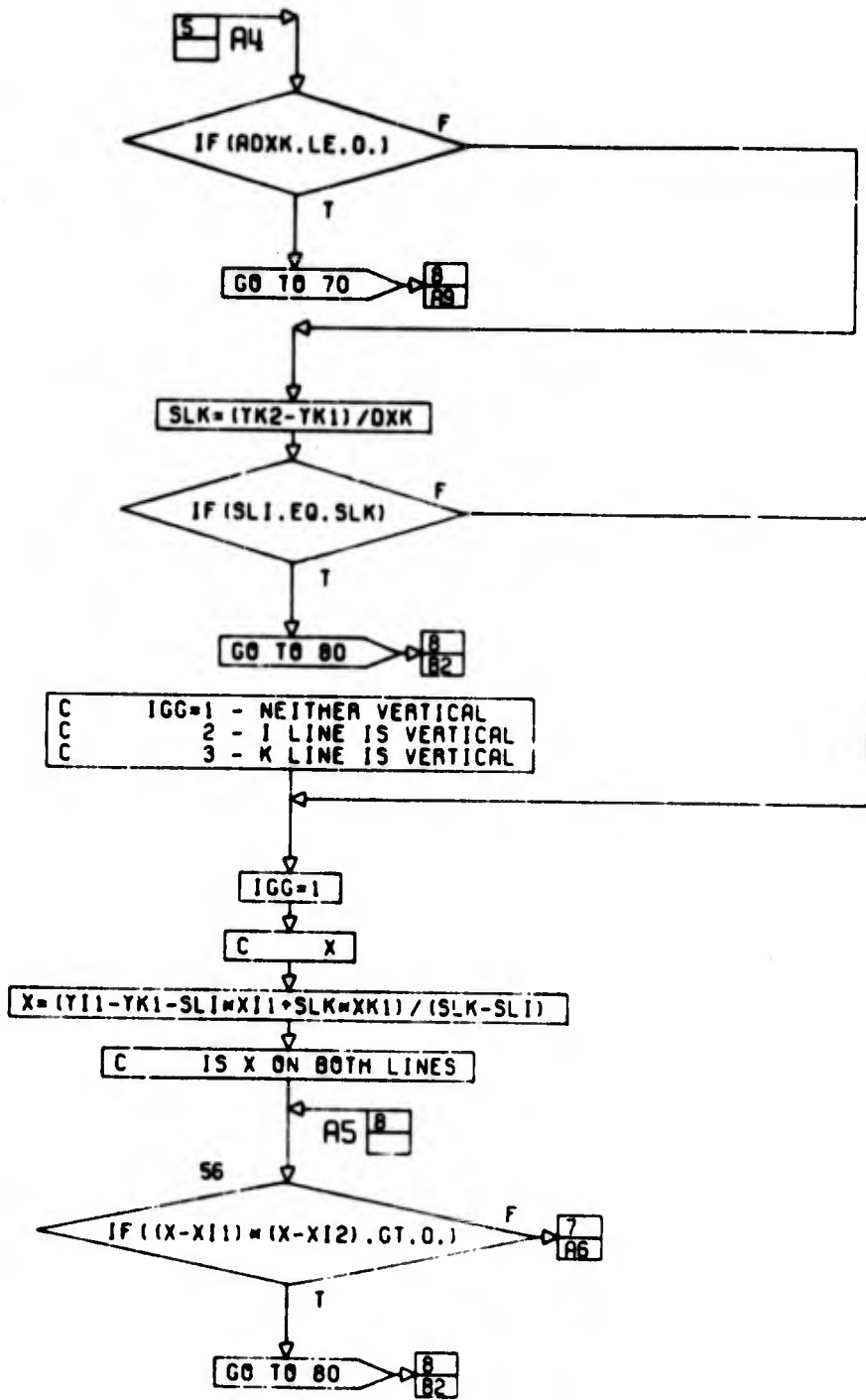
L11=JEDGE (I, 1)
 L12=JEDGE (I, 2)
 X11=PVAT (L11, 1)

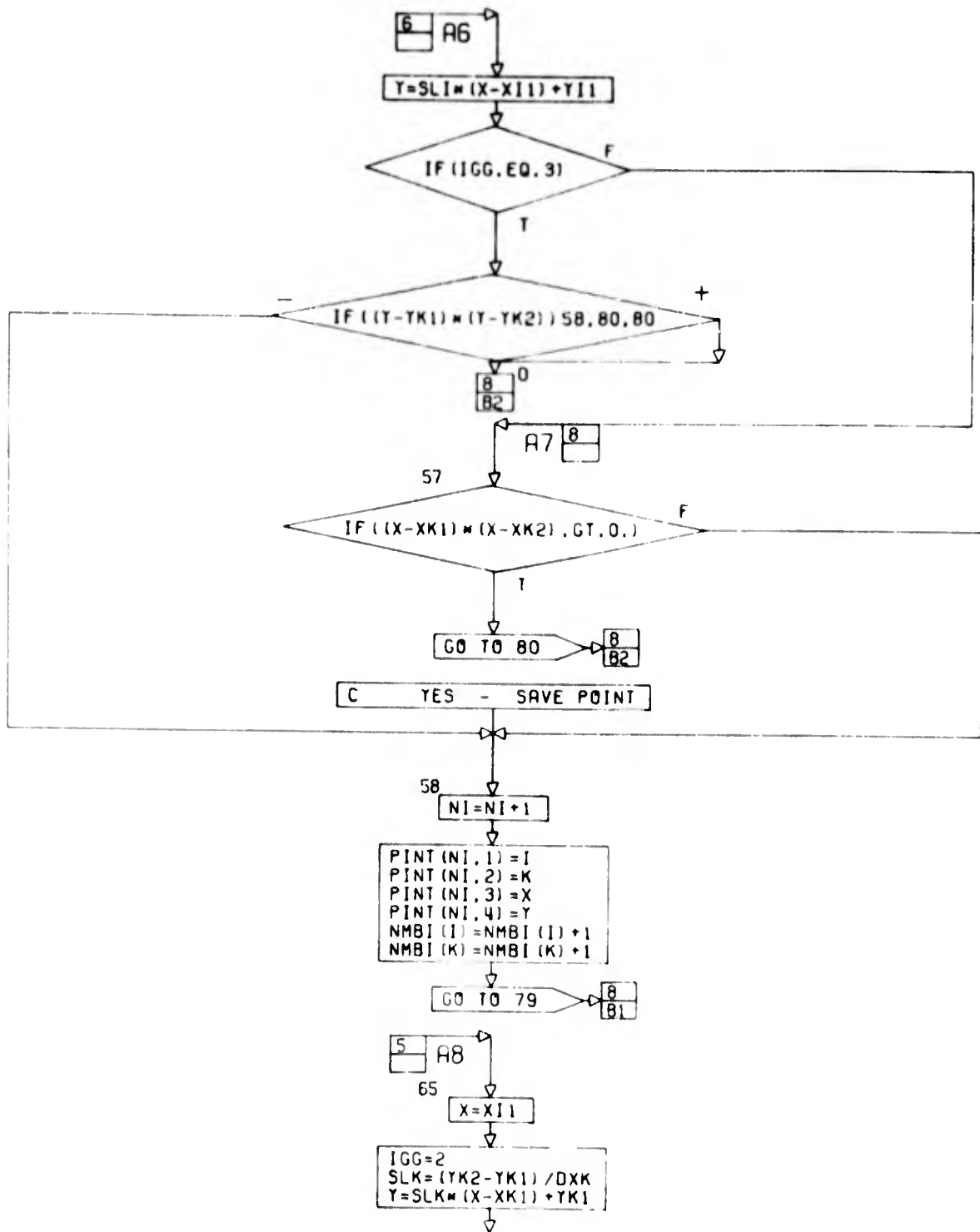


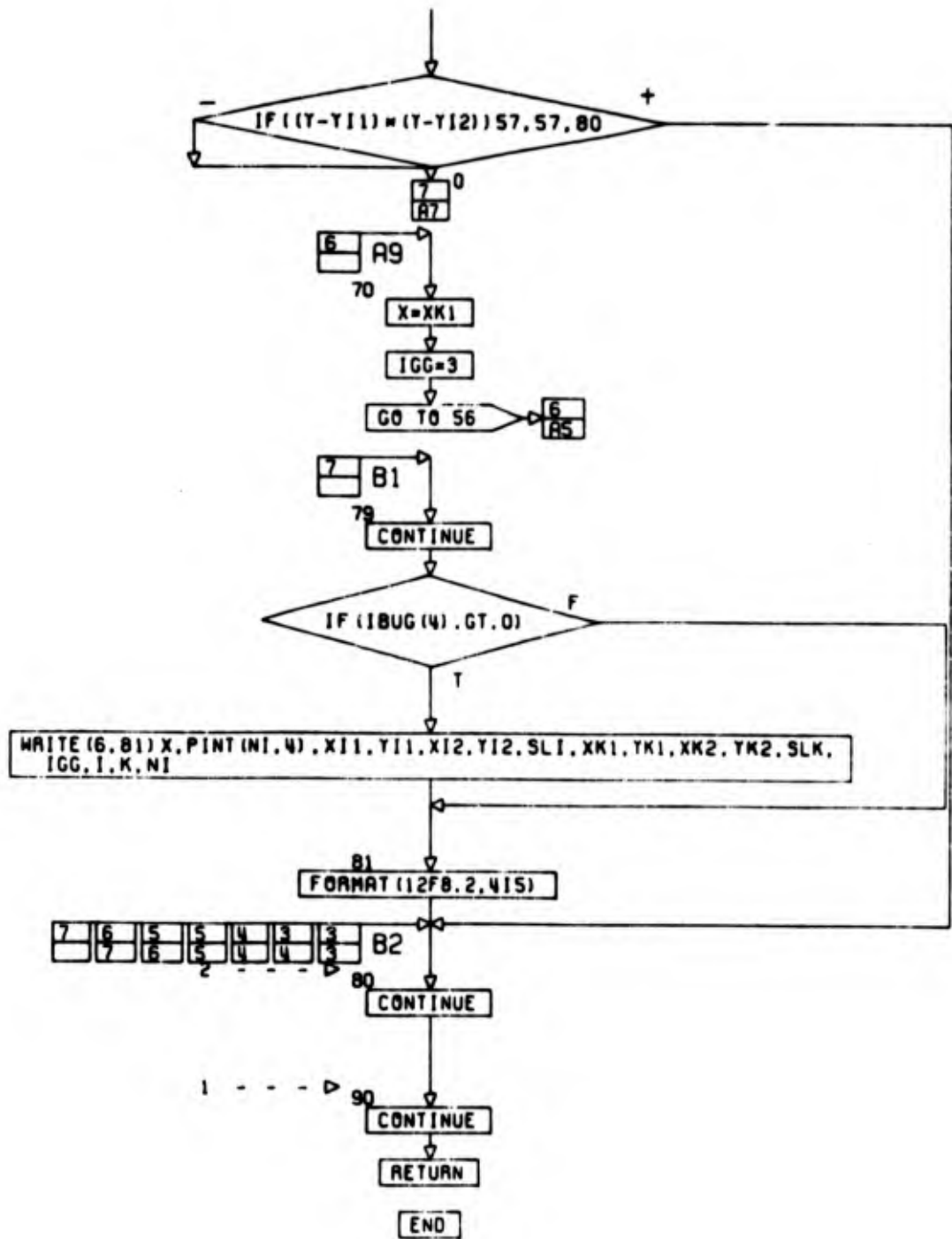












SUBROUTINE ROTAT3

```

SUBROUTINE ROTAT3(X, Y, Z, N, XZ, YZ, ZZ, A)
DIMENSION X(1), Y(1), Z(1), A(3)
COMMON/ROTT3/COSA(3), SINA(3)
    
```

DO 10 I=1,3

```

B=A(I)/57.29578
COSA(I)=COS(B)
    
```

10 SINA(I)=SIN(B)

```

T11=COSA(1)*COSA(2)
T21=SINA(1)*COSA(3)+COSA(1)*SINA(2)*SINA(3)
T31=SINA(1)*SINA(3)-COSA(1)*SINA(2)*COSA(3)
T12=-SINA(1)*COSA(2)
T22=COSA(1)*COSA(3)-SINA(1)*SINA(2)*SINA(3)
T32=COSA(1)*SINA(3)+SINA(1)*SINA(2)*COSA(3)
T13=SINA(2)
T23=-COSA(2)*SINA(3)
    
```

T33=COSA(2)*COSA(3)

DO 20 I=1,N

```

X1=X(I)-XZ
Y1=Y(I)-YZ
Z1=Z(I)-ZZ
X(I)=X1*T11+Y1*T12+Z1*T13+XZ
Y(I)=X1*T21+Y1*T22+Z1*T23+YZ
Z(I)=X1*T31+Y1*T32+Z1*T33+ZZ
    
```

20 CONTINUE

RETURN

END

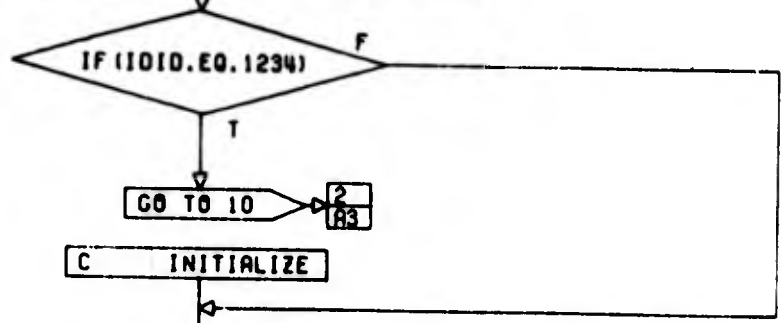
SUBROUTINE FACES

SUBROUTINE FACES (IFP, N)

C DEVELOPE TABLES FOR FACE L CONSISTING OF THE N POINTS INDICATED BY
C IFP

COMMON COEF (300, 4)
 , LFCE (301), JFCE (1800), PVAT (600, 2), PVXYZ (600, 3), JEDGE (900, 5),
 PINT (1200, 4), PEYE (3), NMBI (900)
 , IOBJ (16), INOBJ (15), LFCI (300)

COMMON /INPTT/J, NE, LL, L, NI, NP, NOBJ, IA
 COMMON/DEBUGS/IBUG (4)
 COMMON/RNGE/PMX (3), PMN (3), IDIO, JDIO
 COMMON/TEMPY/JFCET (1800), IPNT (100)
 DIMENSION IC (3), CF (2, 3), IFP (1)



IDIO=1234

C K=FACE POINTER

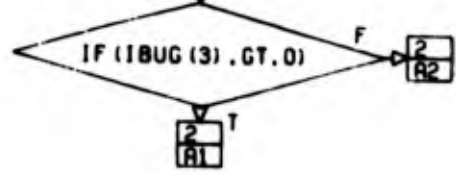
K=1

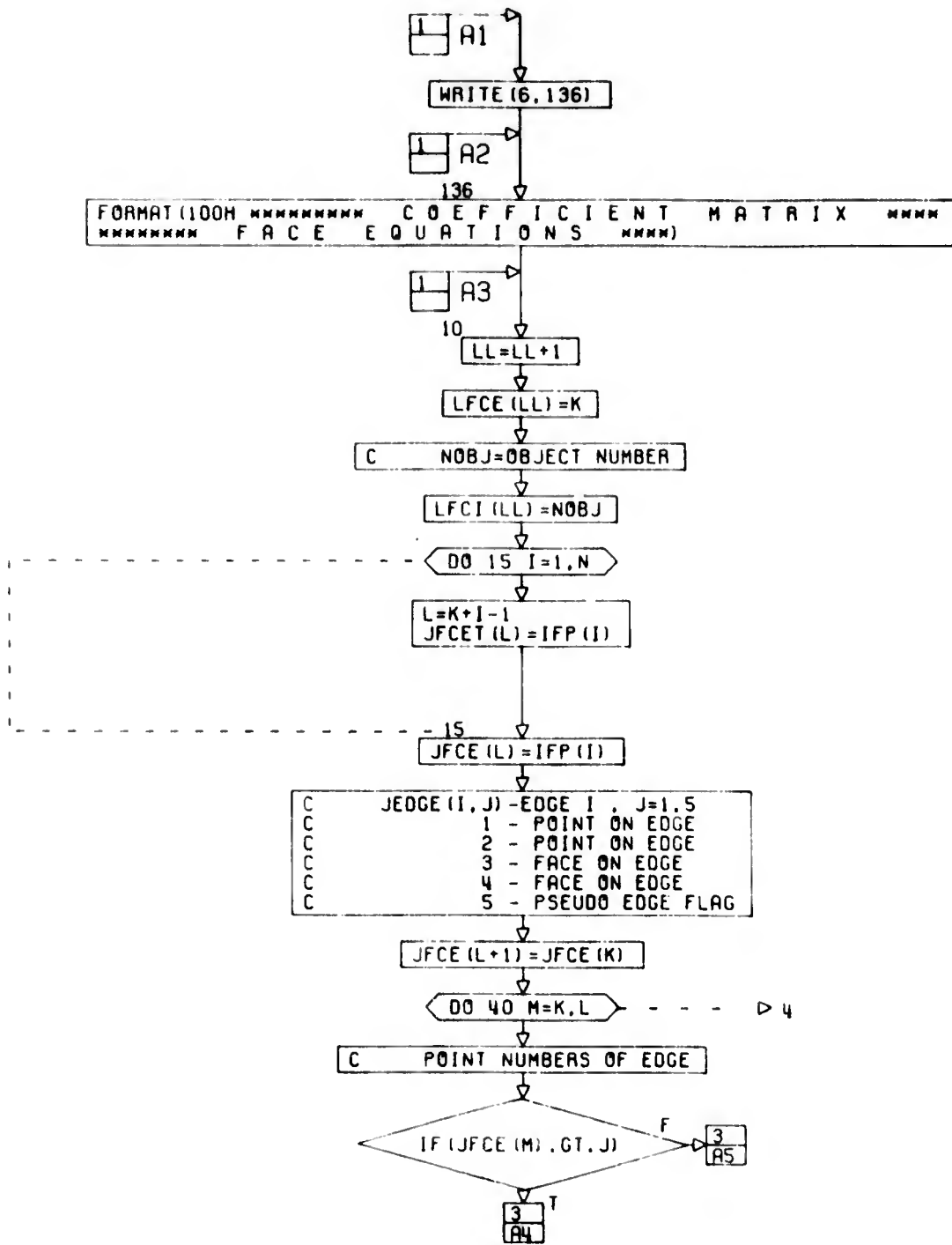
C NE=NUMBER OF EDGES

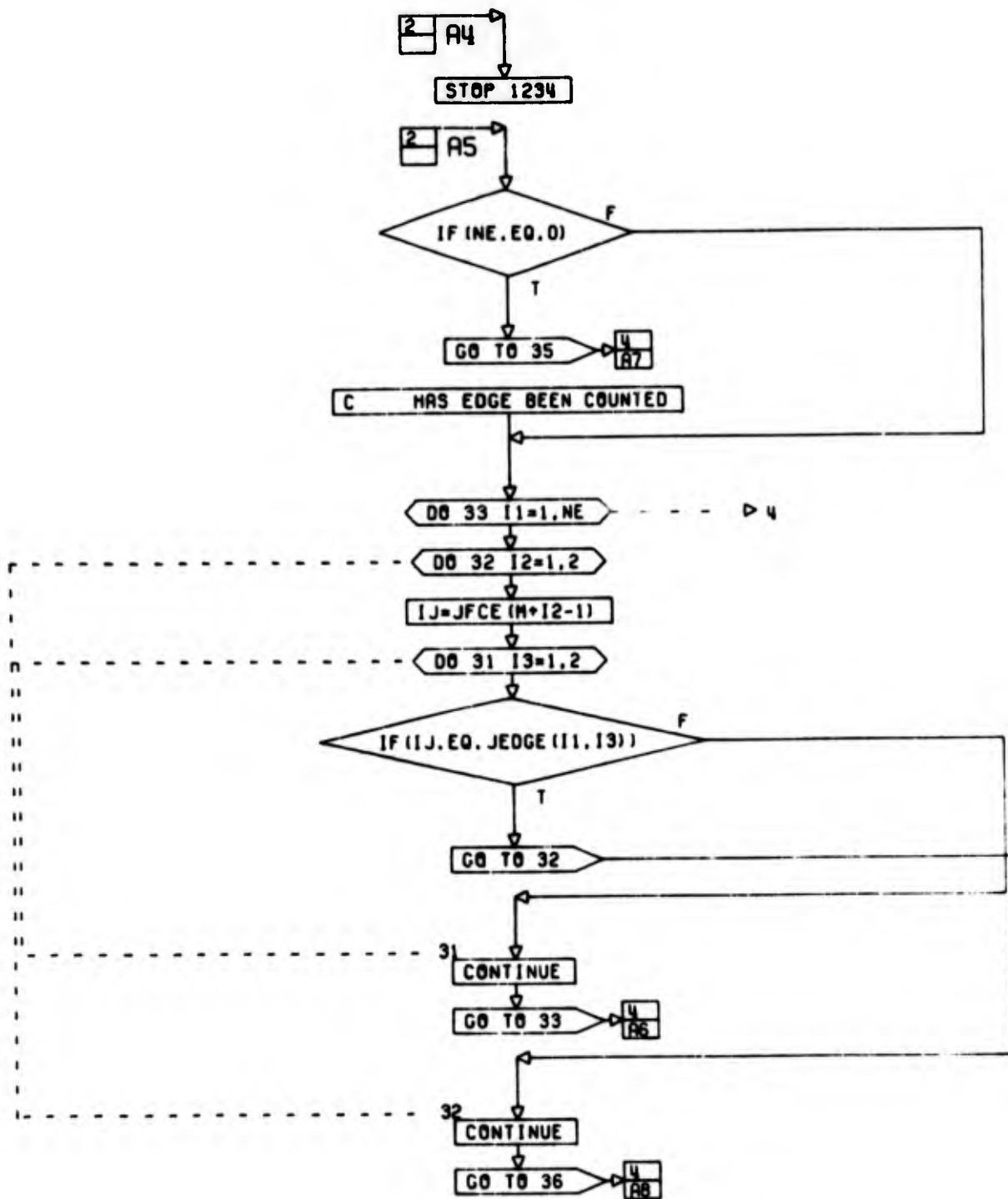
NE=0

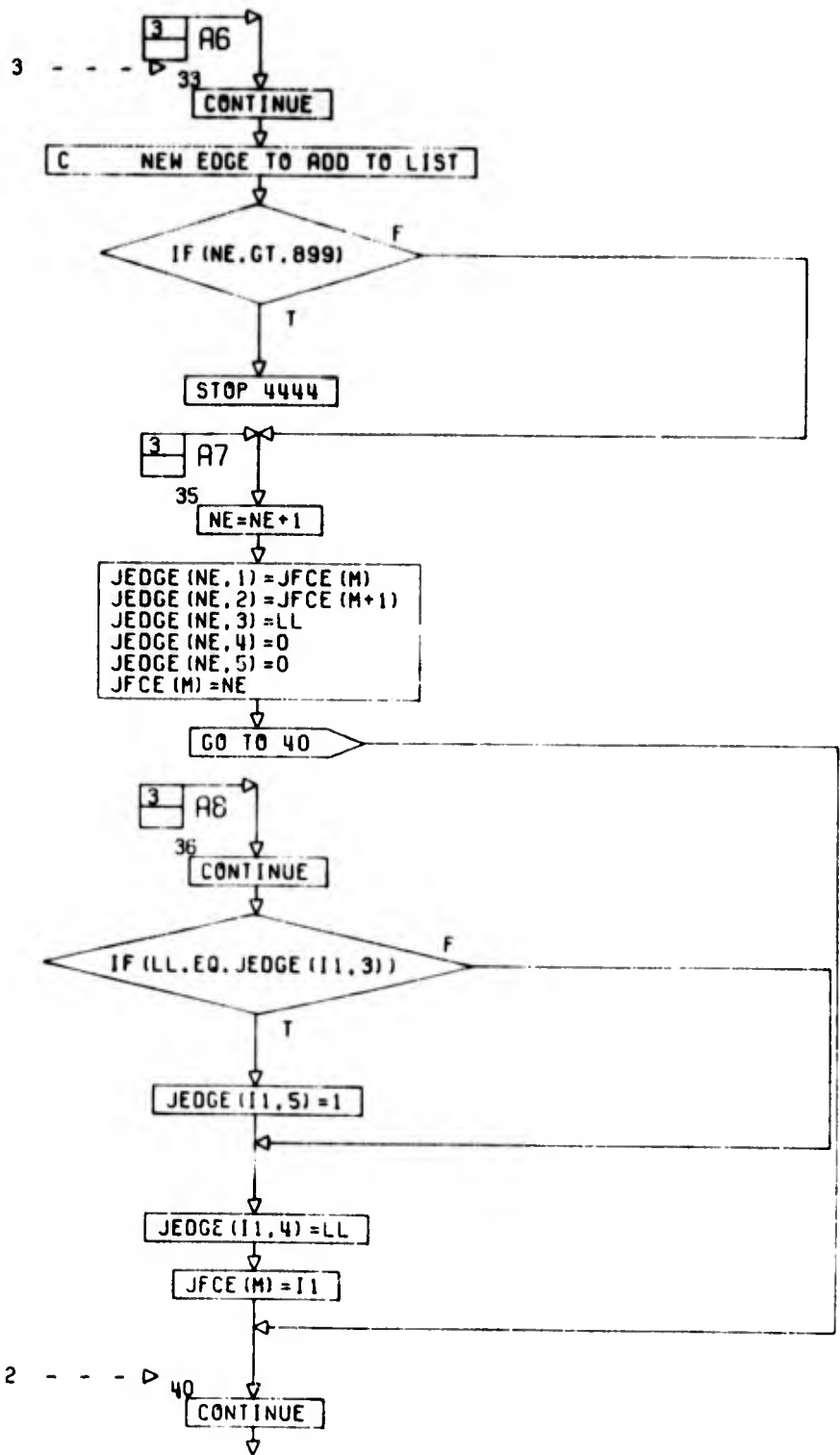
C LL=FACE NUMBER

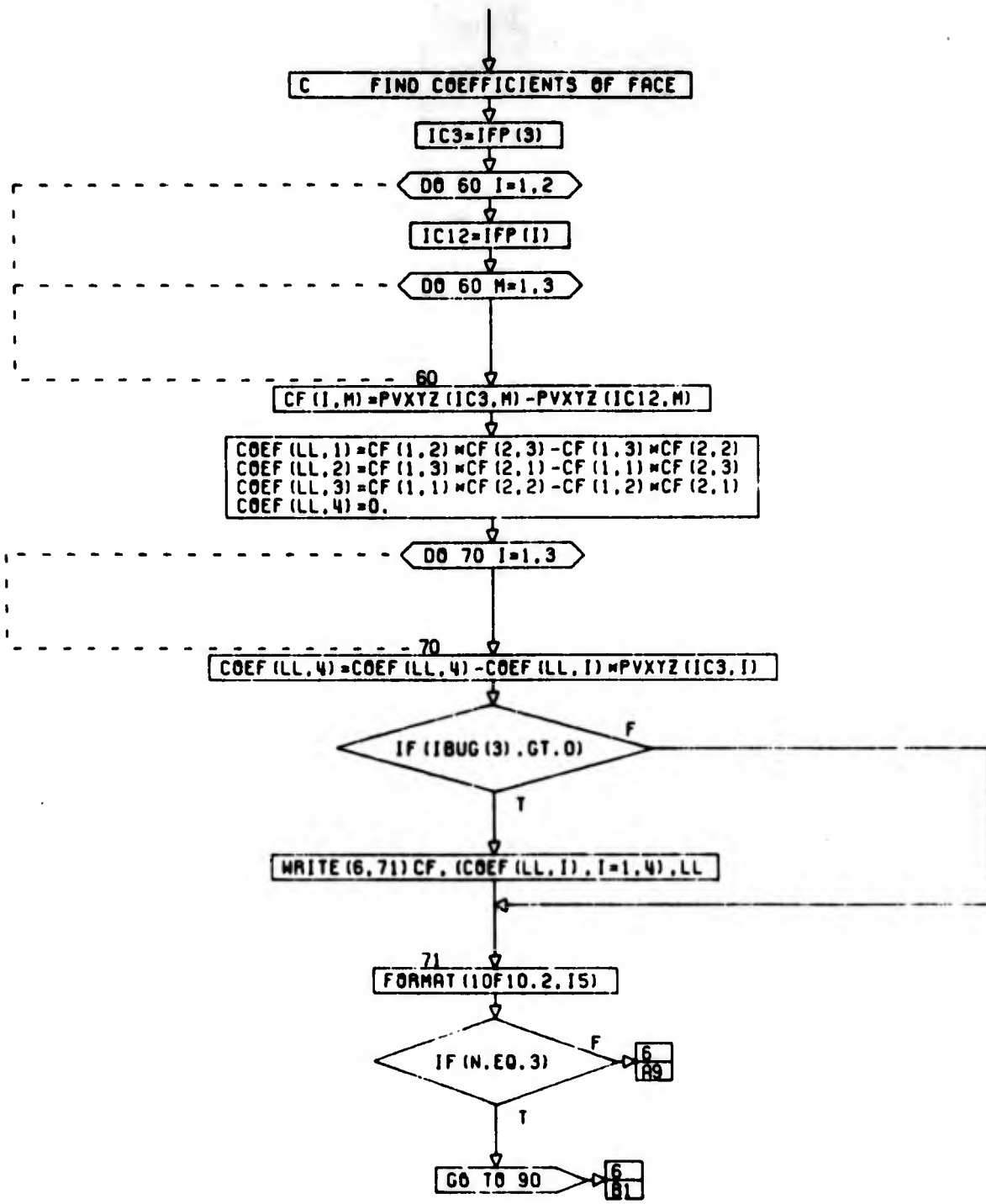
LL=0











C CHECK EACH POINT ON FACE FOR COPLANARITY

5 A9

DO 80 KL=4,N

IP4=IFP(KL)
T1=COEF(LL,4)

DO 75 M=1,3

75 T1=T1+COEF(LL,M)*PVXYZ(IP4,M)

IF (ABS(T1).LT..005)

F

GO TO 80

WRITE(6,77)LL,IP4,T1

77 FORMAT(15H ERROR IN PLANE,13,7H, POINT,14,F10.4)

80 CONTINUE

5 B1

90 K=L+1

LFCE(LL+1)=K

RETURN

END

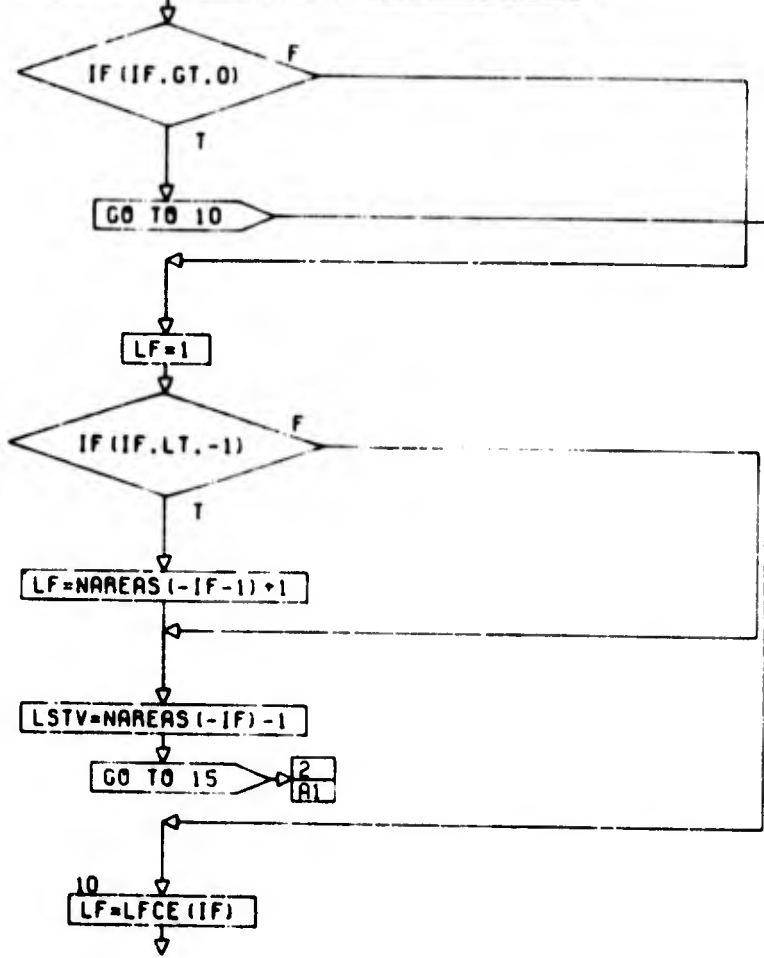
SUBROUTINE COVER

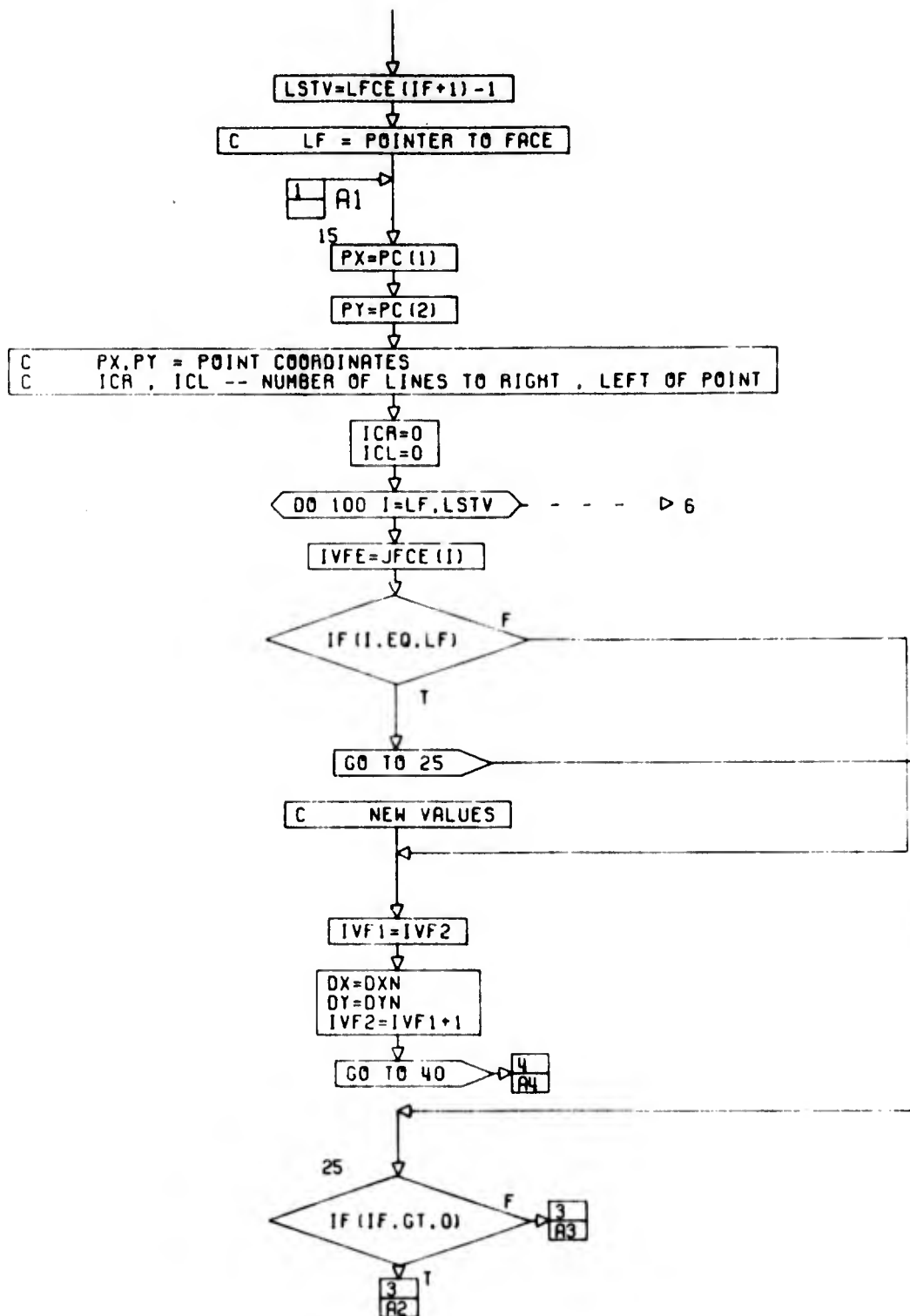
SUBROUTINE COVER (IF, PC, PVRT, JJ)
 DIMENSION PC (1), PVRT (JJ, 2)

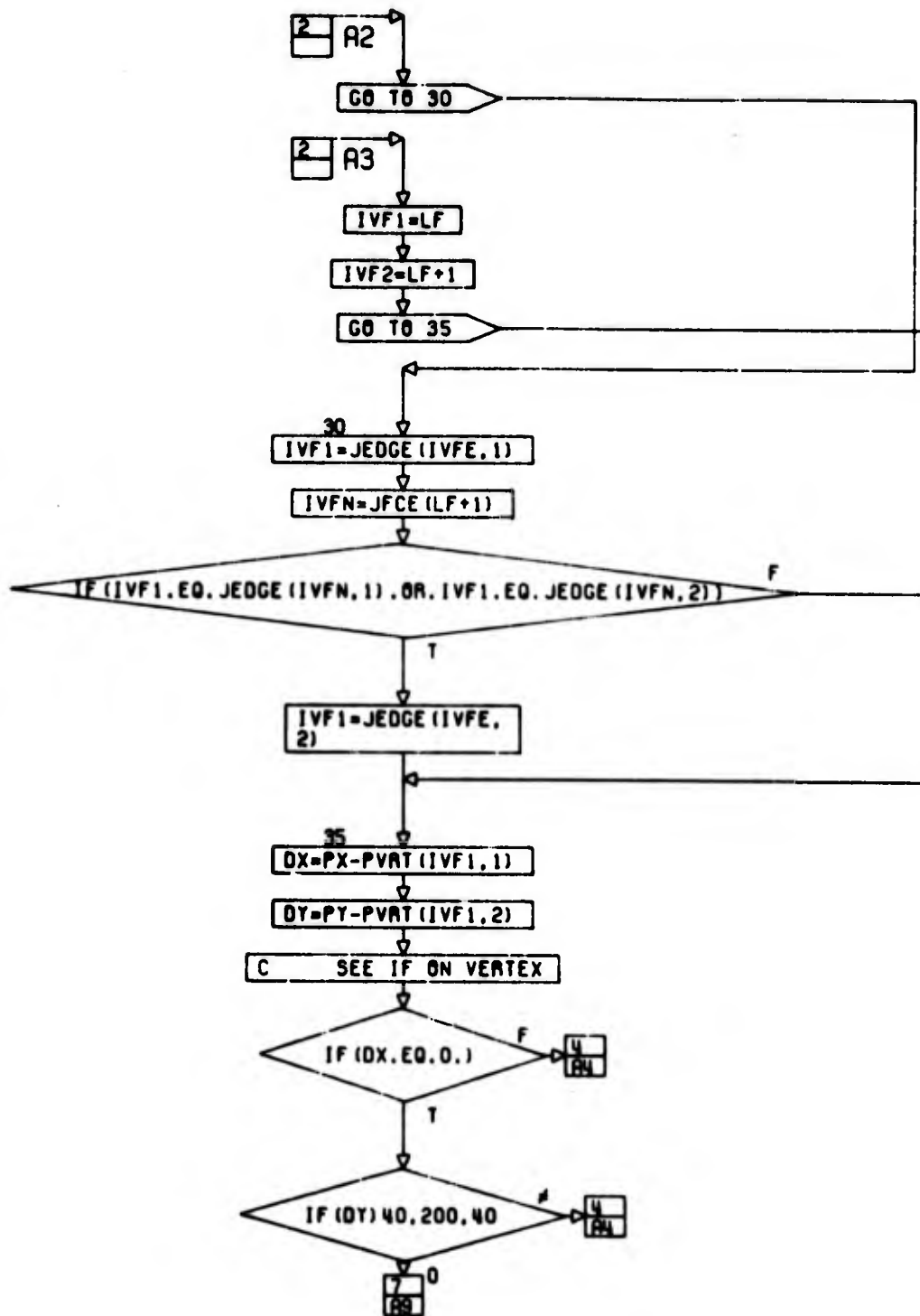
COMMON COEF (300, 4)
 , LFCE (301), JFCE (1800), DUMY (600, 2), PVXYZ (600, 3), JEDGE (900, 5),
 PINT (1200, 4), PEYE (3), NMB1 (900)
 , IOBJ (16), INOBJ (15), LFCI (300)

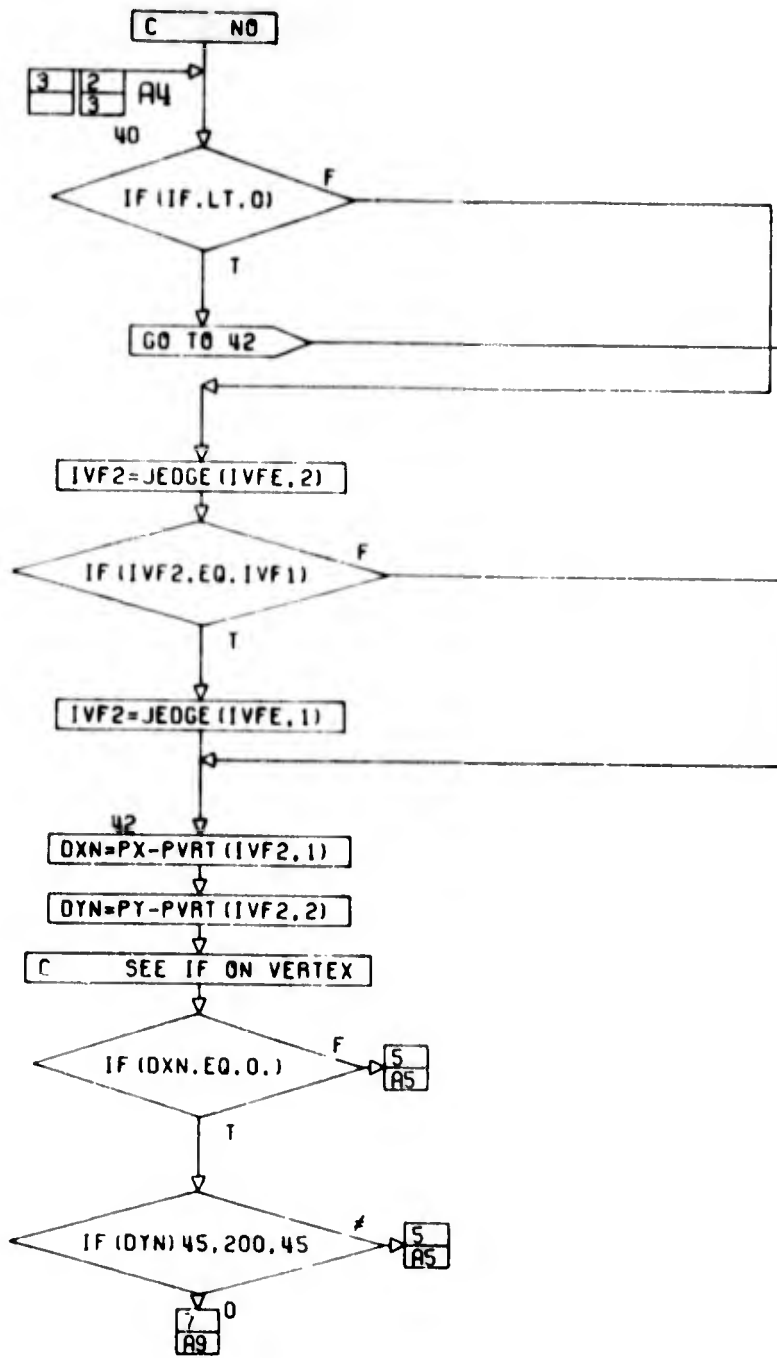
COMMON/DEBUGS/IBUG (4)
 COMMON /ANSW/ITYPE, ICR, ICL, TYP
 COMMON/AR/SAREAS (25), NAREAS (25)

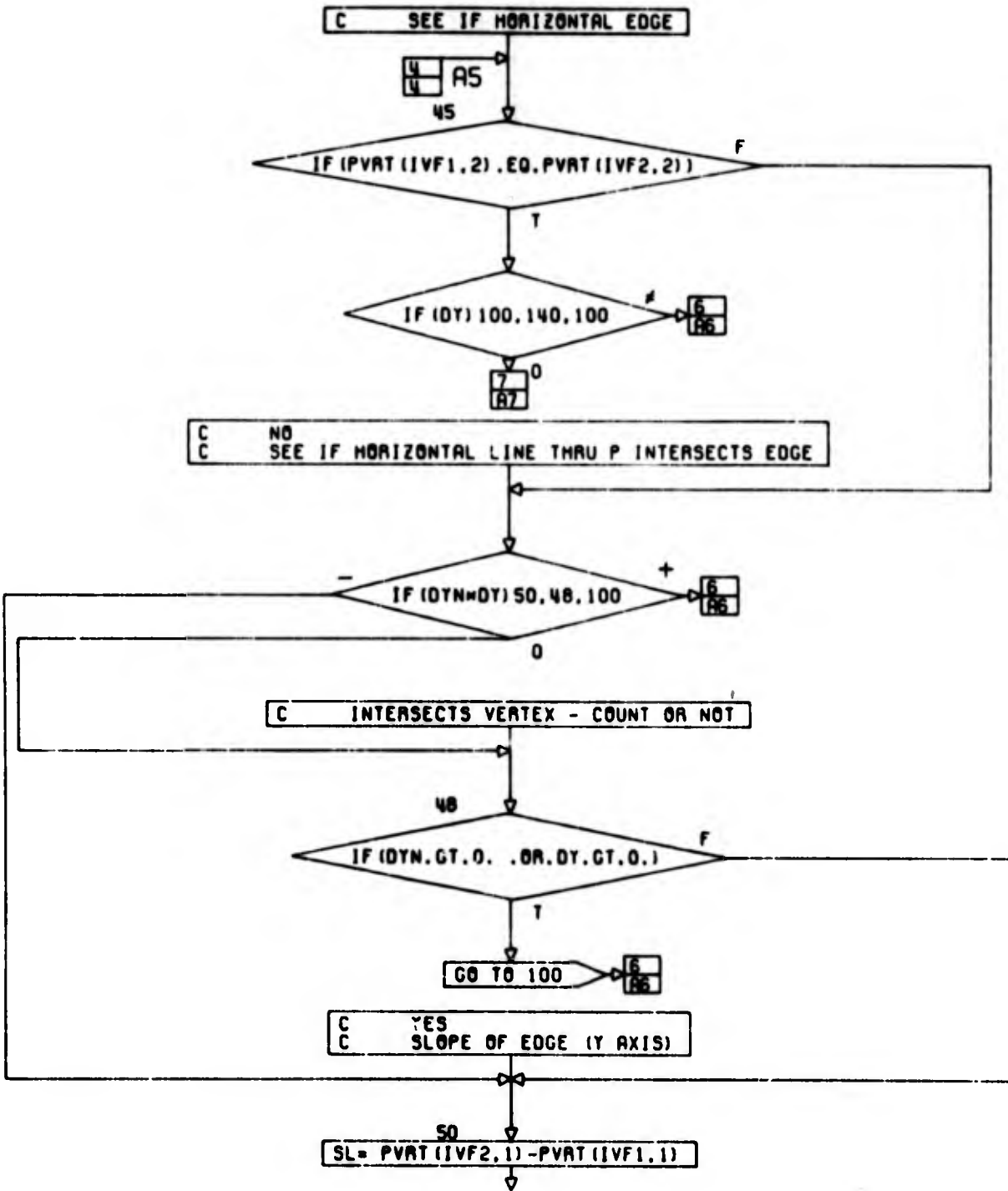
C CHECK TO SEE IF FACE (IF) COVERS POINT (PC)
 C IF .LT. 0 INDICATES PROJECTION -IF RATHER THAN FACE
 C ITYPE = 0 - NOT COVERED
 C = 1 - ON VERTEX
 C = 2 - ON EDGE
 C = 3 - COVERED

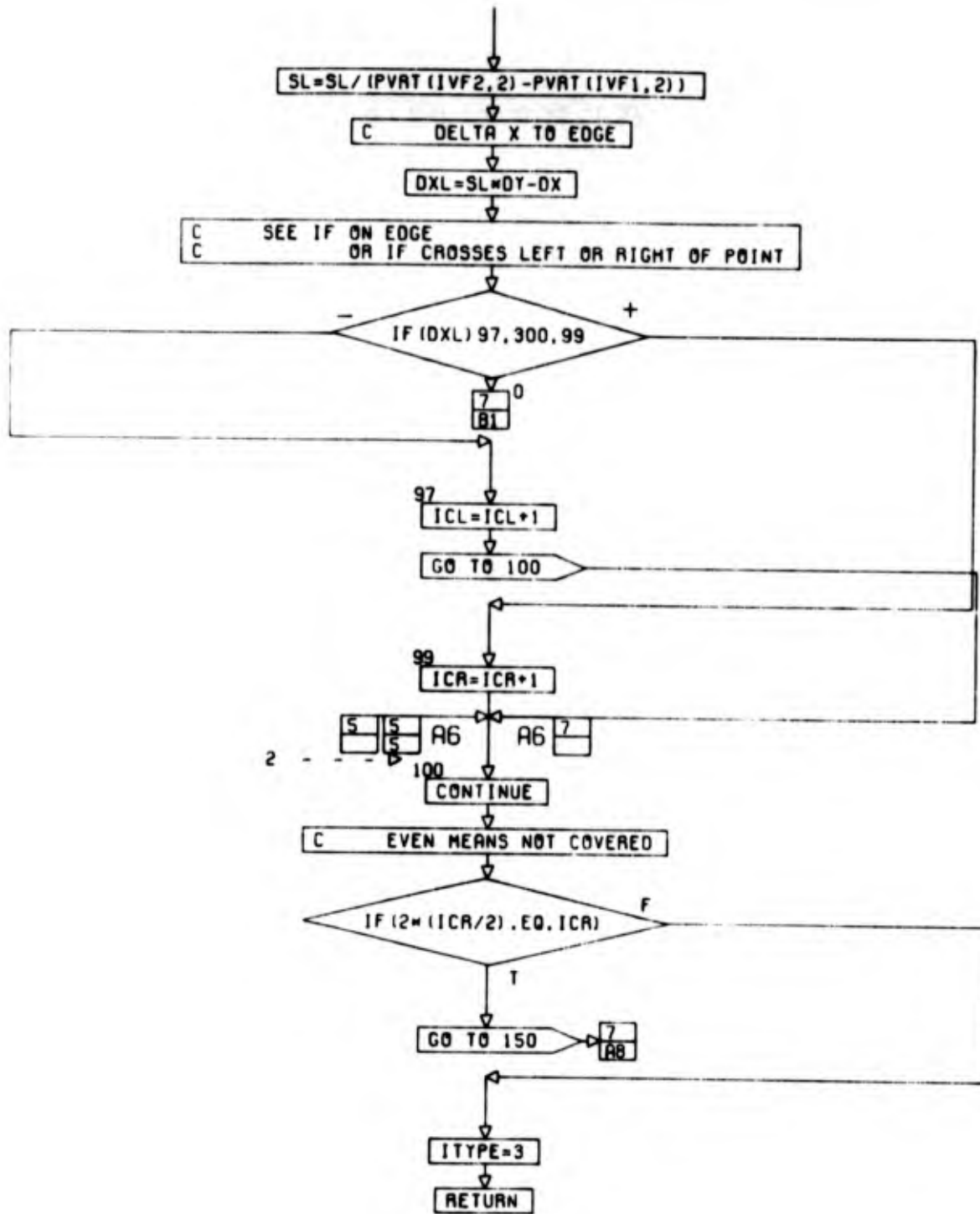


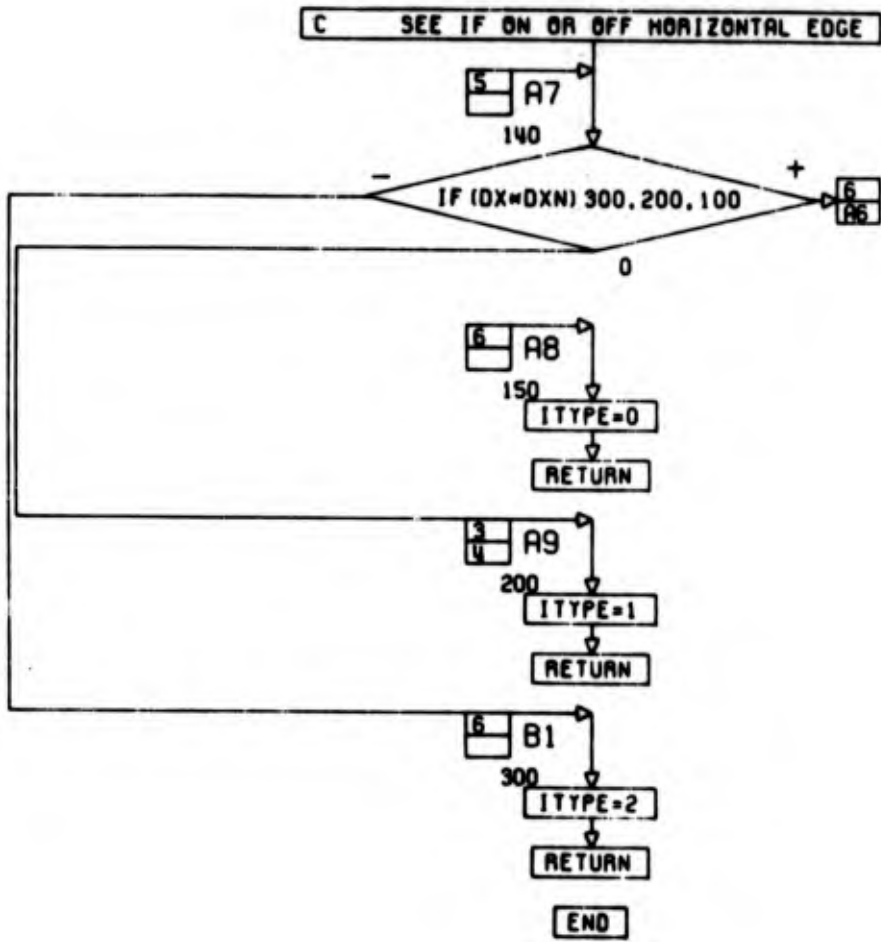




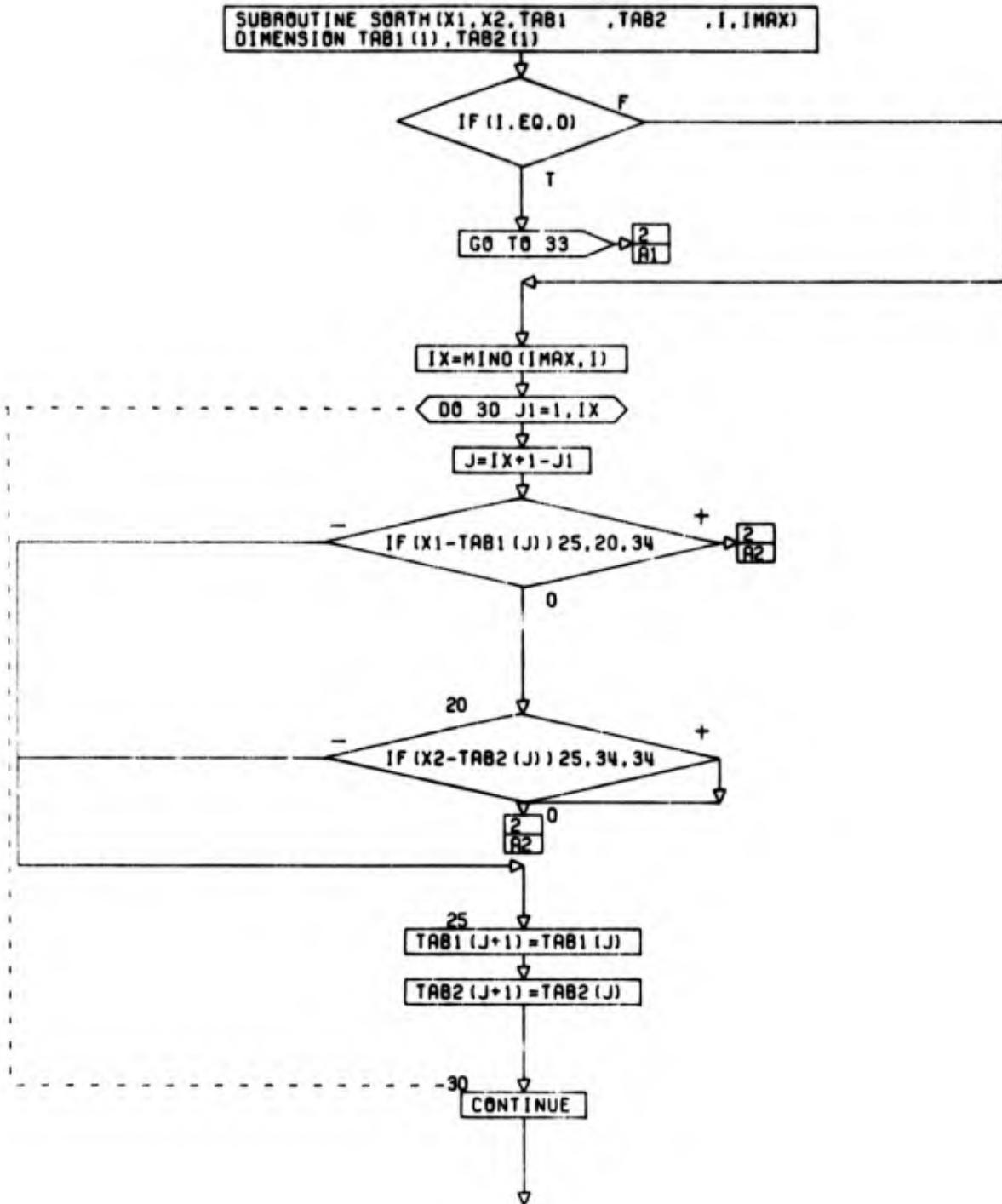


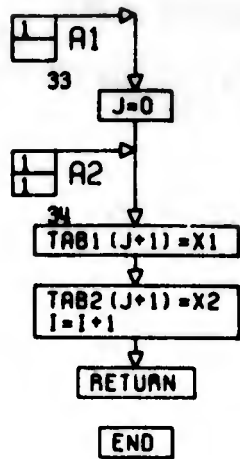






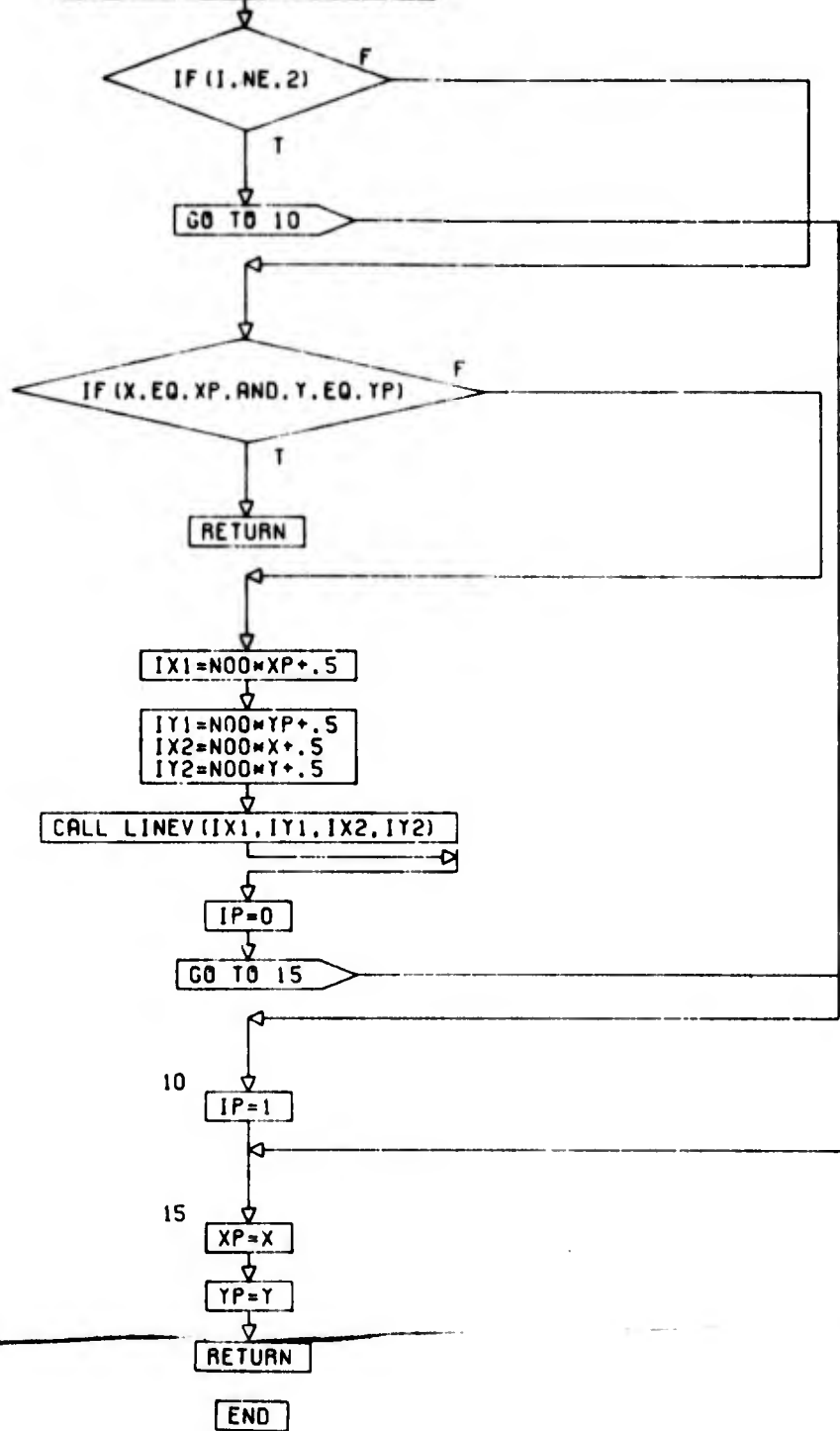
SUBROUTINE SORTH



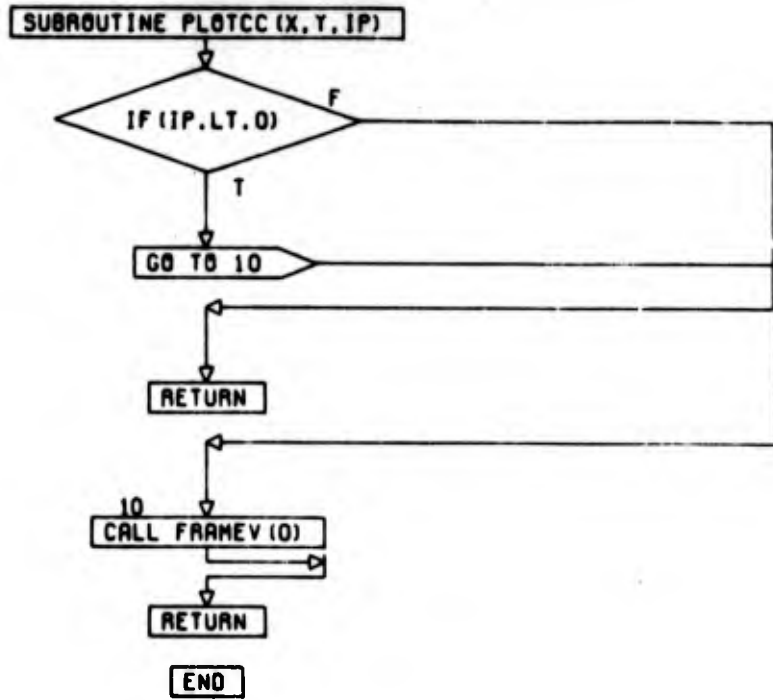


SUBROUTINE PLOTDD

SUBROUTINE PLOTDD(X,Y,I)
COMMON/RAST/NOO
DATA XP,YP,IP/0.,0.,0/



SUBROUTINE PLOTCC



SUBROUTINE LINEV

SUBROUTINE LINEV



RETURN

END

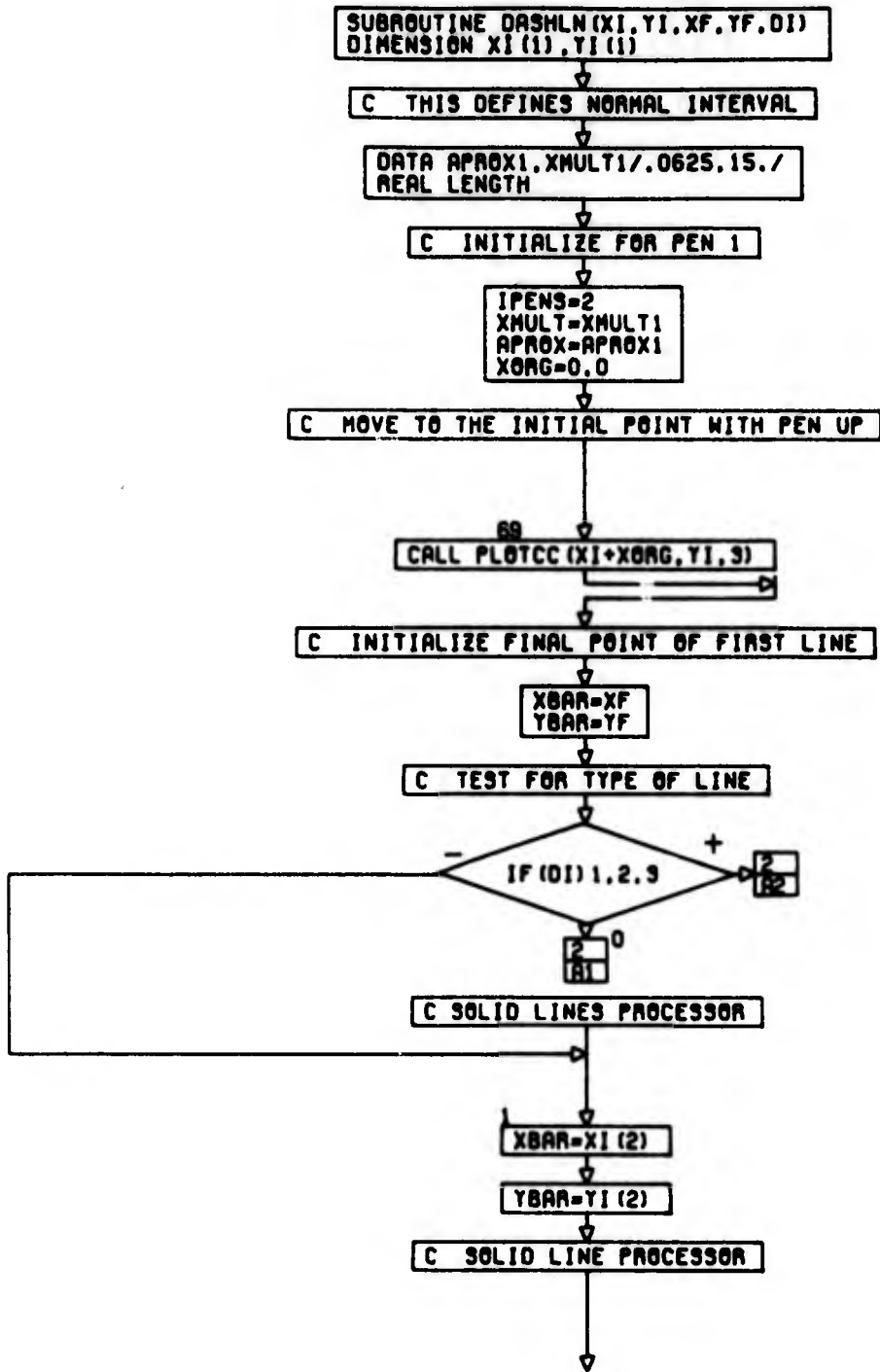
SUBROUTINE FRAMEV

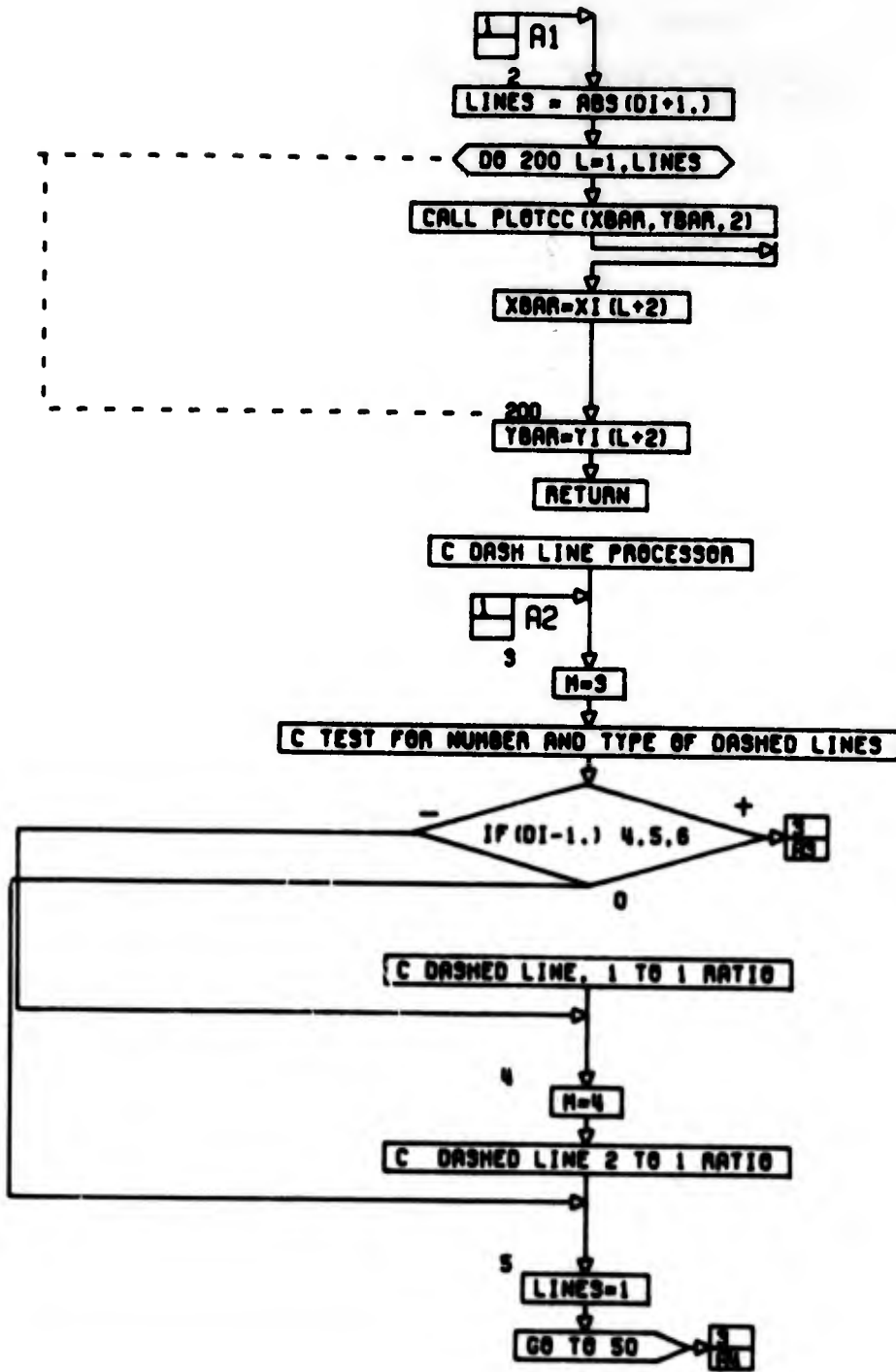
SUBROUTINE FRAMEV

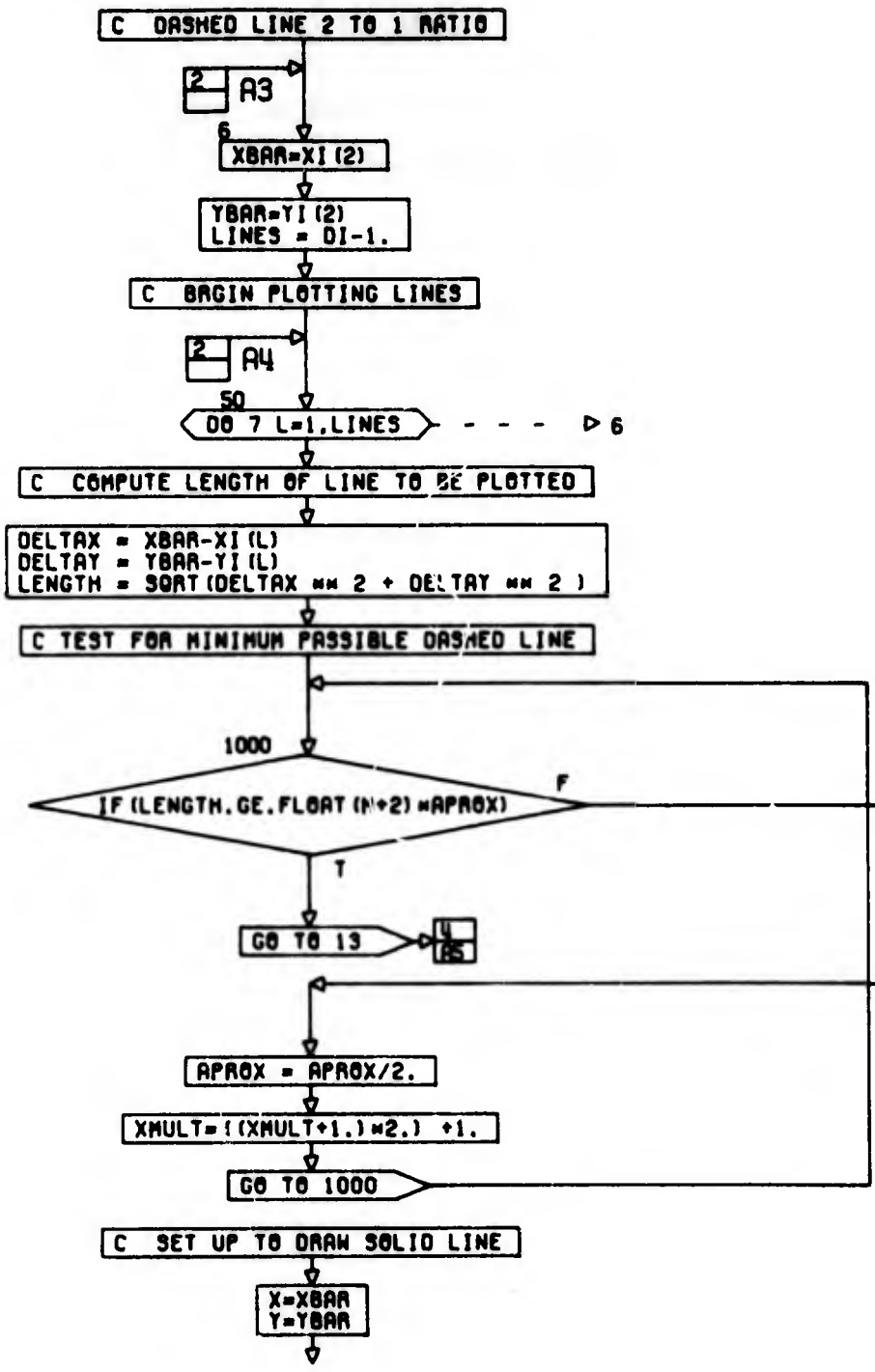
RETURN

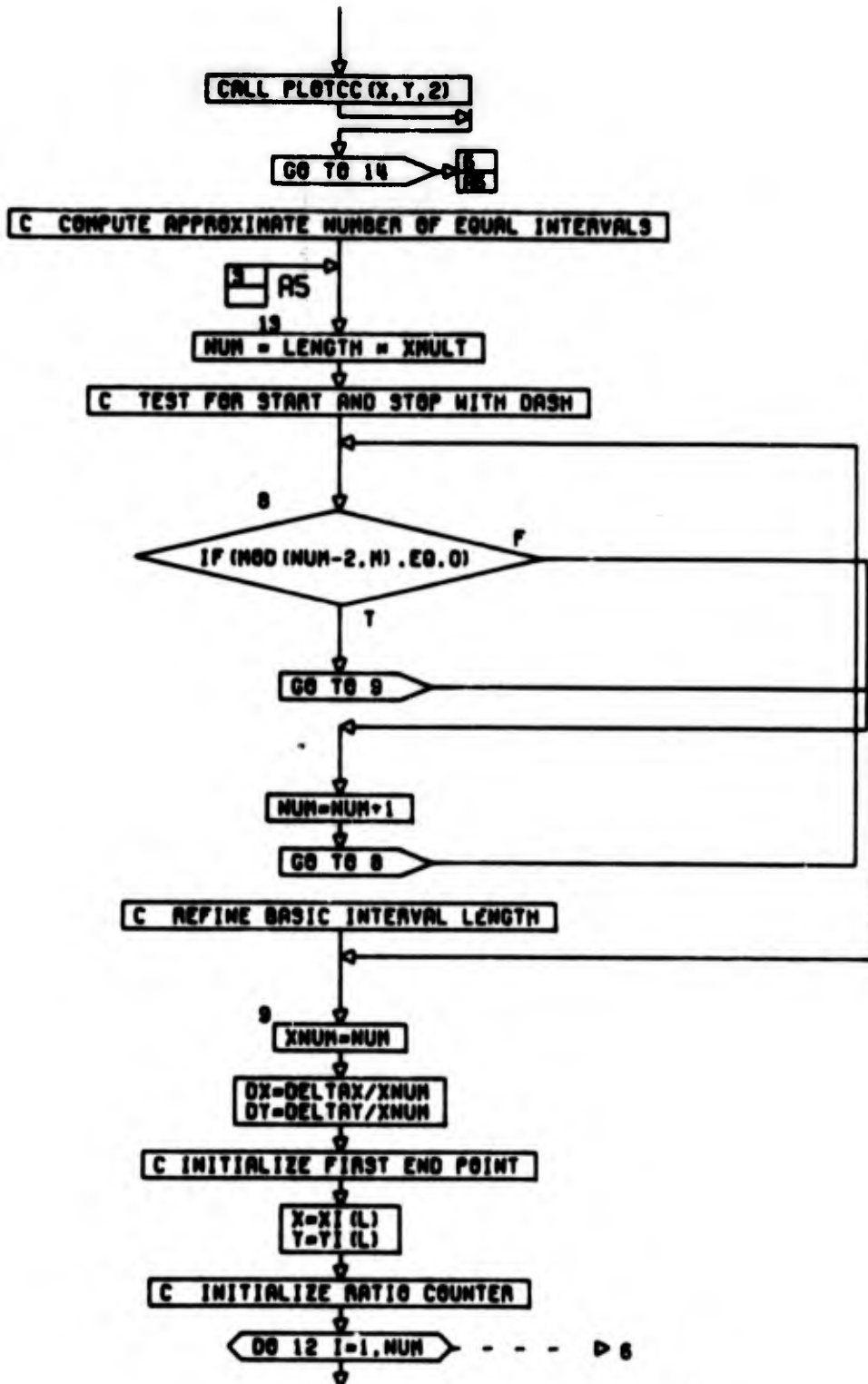
END

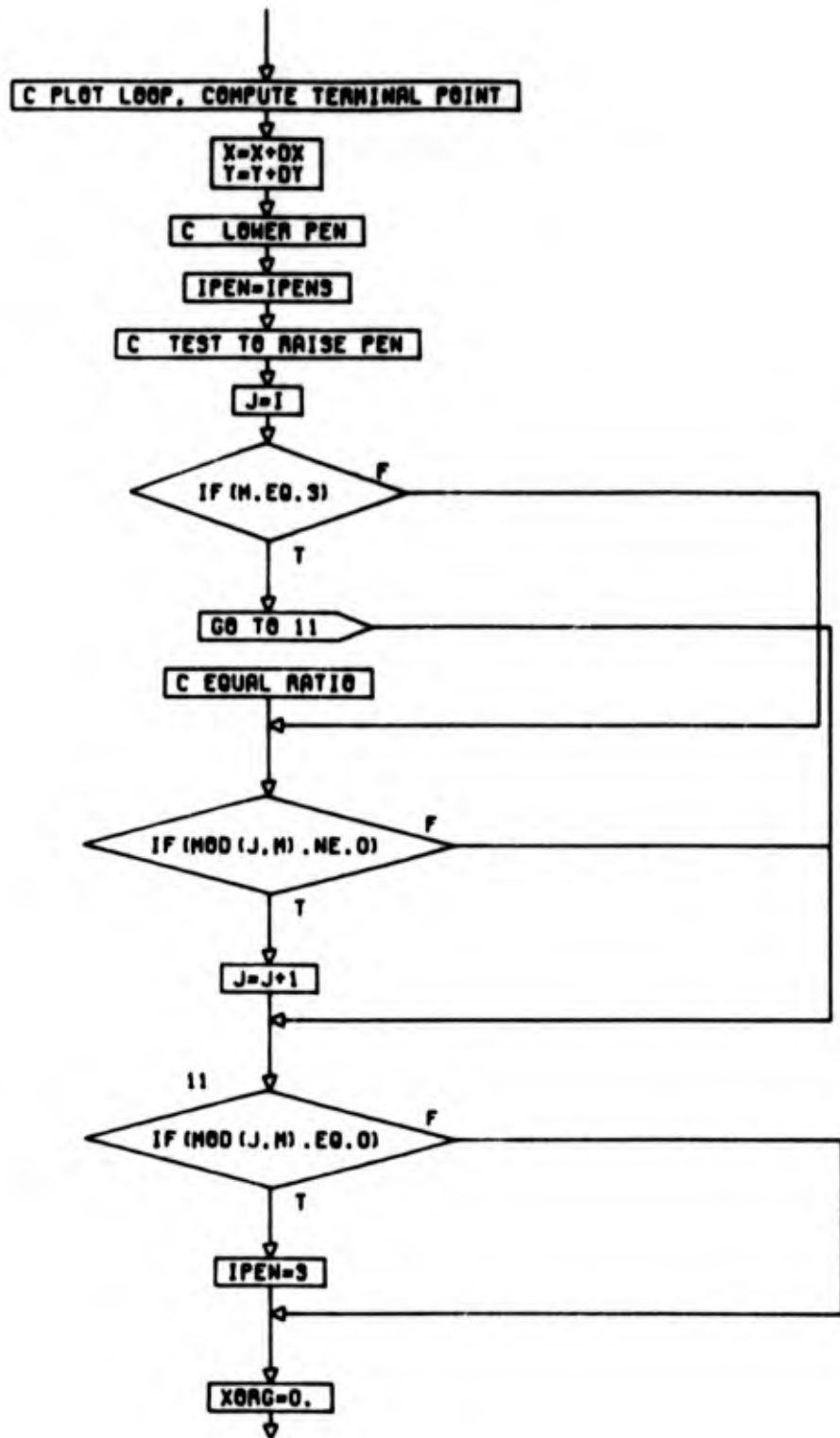
SUBROUTINE DASHLN

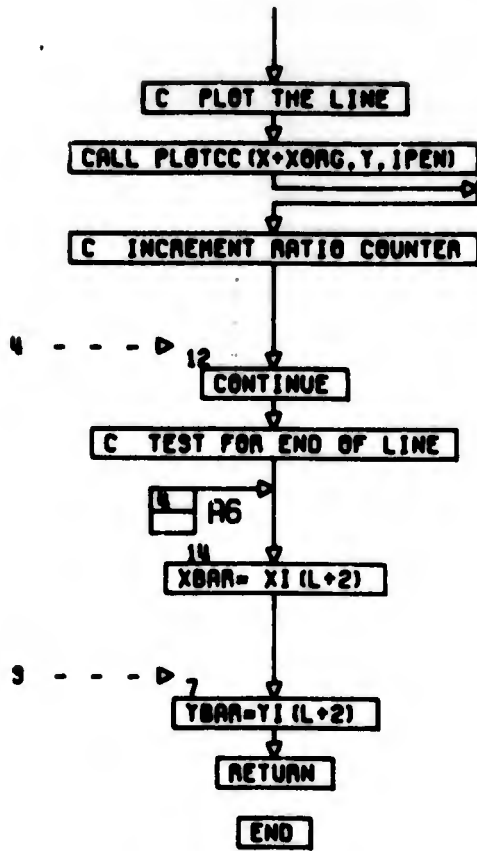












SUBROUTINE INIT3D

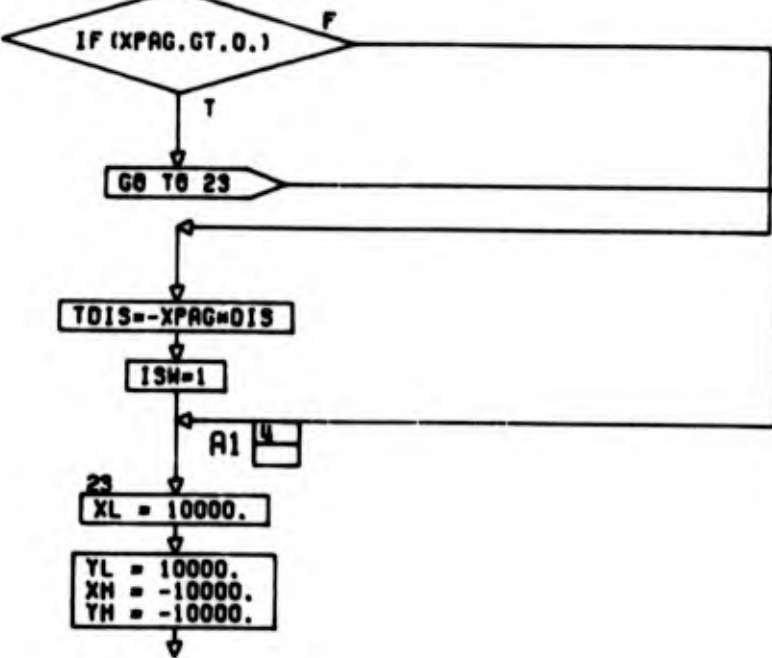
SUBROUTINE INIT3D (XPAG, YPAG, X0, Y0, Z0, XM, XMAX, YN, YMAX, ZMIN, ZMAX)

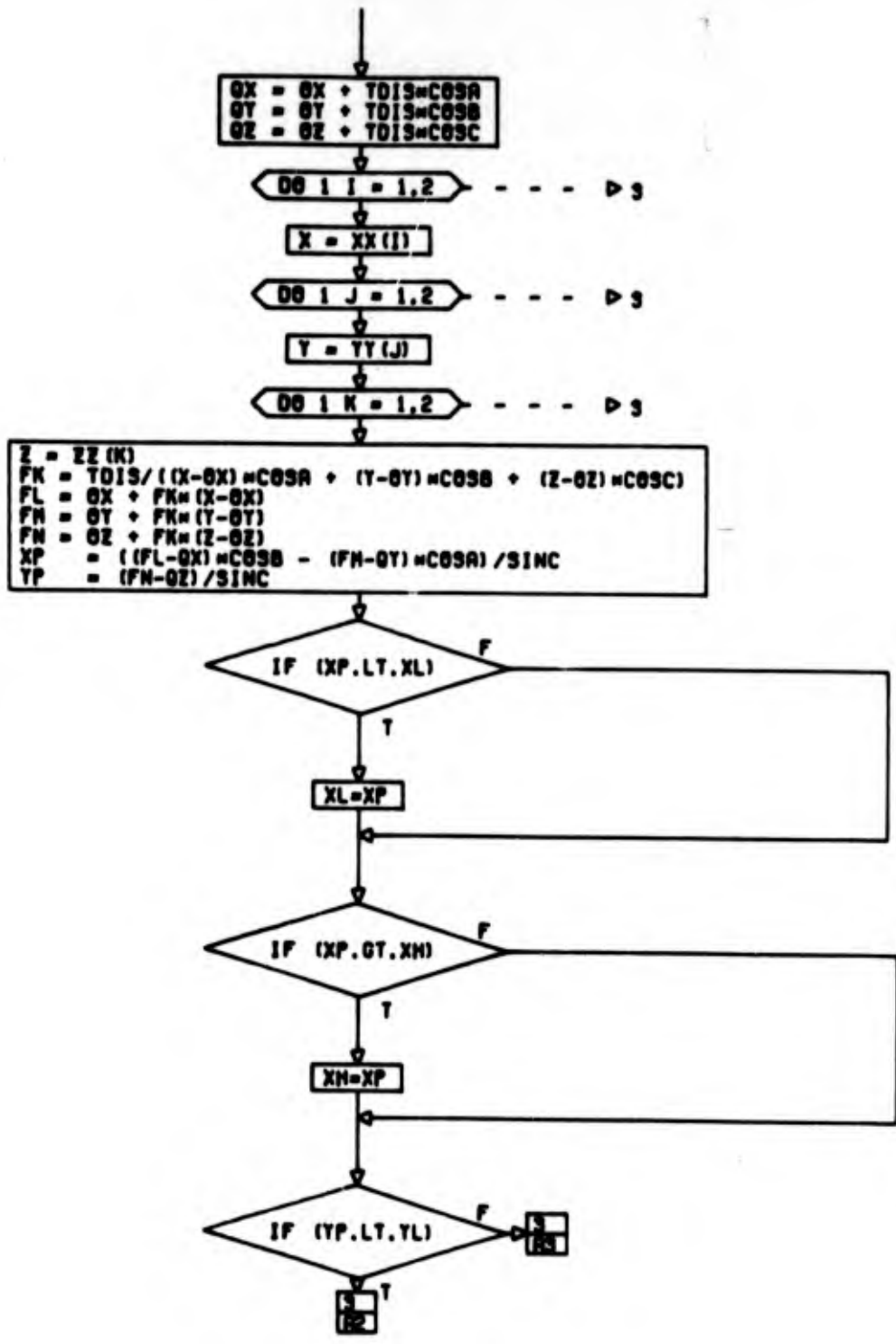
COMMON/PARAM/XL, YL, XMIN, YMIN, TDIS, DIS, OX, OY, OZ, COSA, COSB, COSC,
OX, OY, OZ, SINC, PX, PY, IQUAD, OUM, XLEN, YLEN

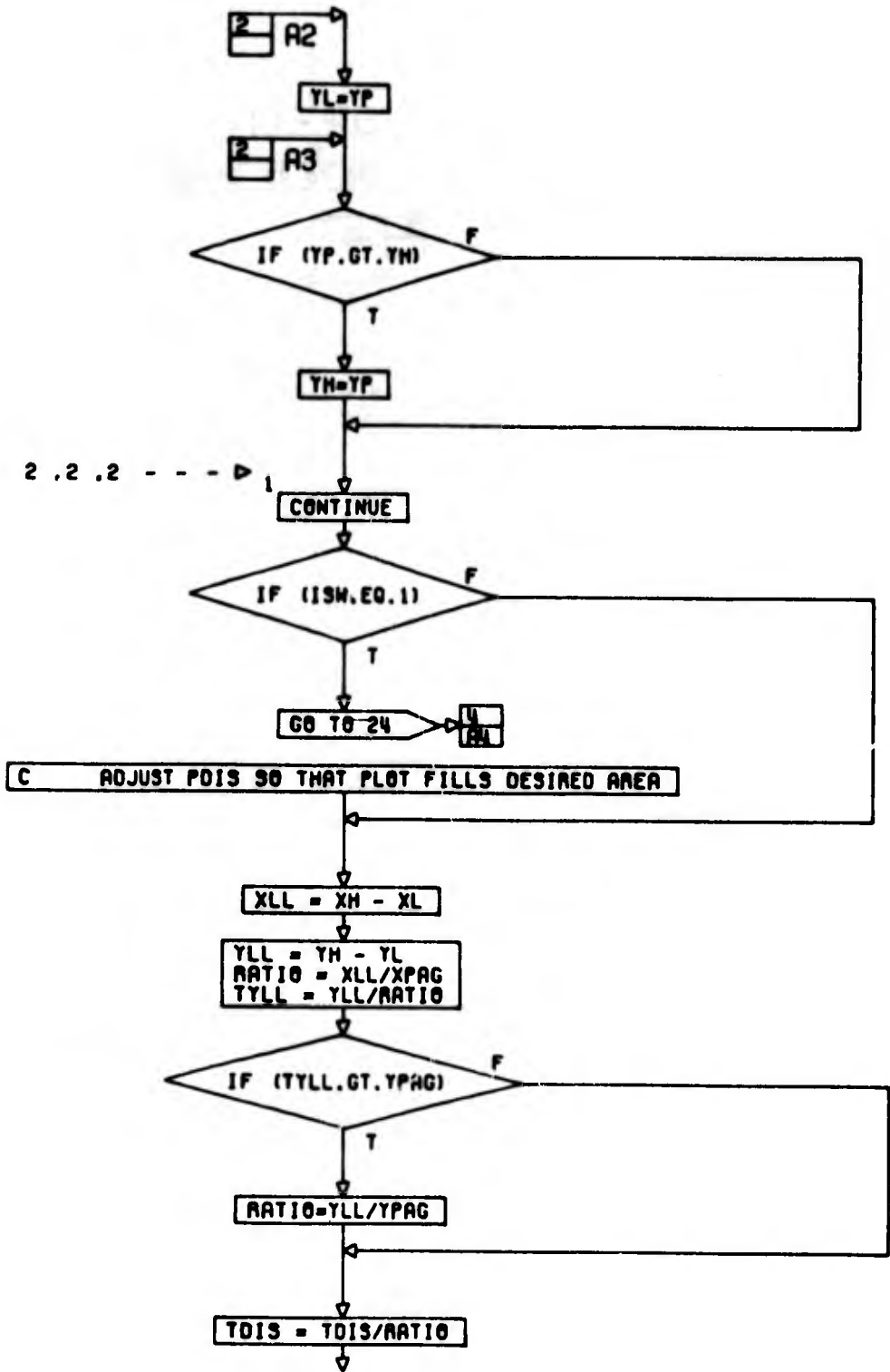
DIMENSION XX (2), YY (2), ZZ (2)
ISM = 0
OX=X0
OY=Y0
OZ=Z0
XMIN=XM
YMIN=YN
XX (1) = XMIN

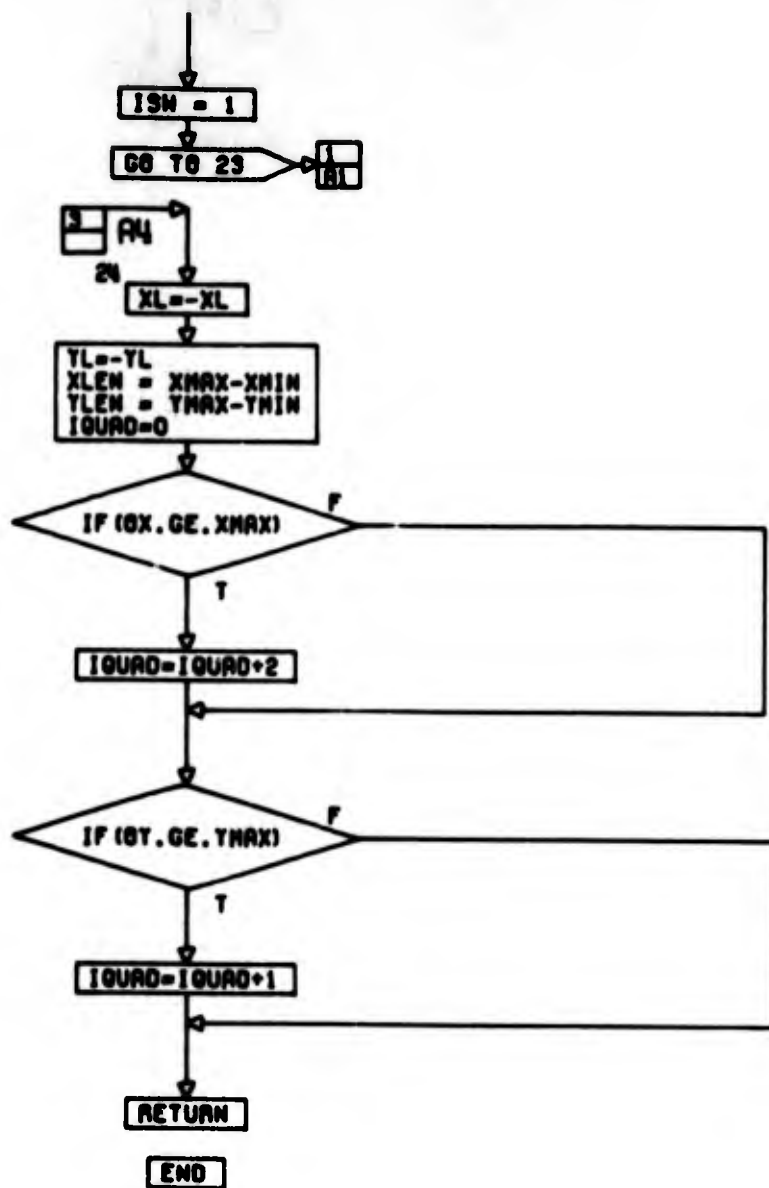
XX (2) = XMAX
YY (1) = YMIN
YY (2) = YMAX
ZZ (1) = ZMIN
ZZ (2) = ZMAX
PX = XMIN+.5*(XMAX-XMIN)
PY = YMIN+.5*(YMAX-YMIN)
PZ = ZMIN+.5*(ZMAX-ZMIN)

DIS = SQRT ((PX-OX)**2 + (PY-OY)**2 + (PZ-OZ)**2)
COSA = (PX-OX)/DIS
COSB = (PY-OY)/DIS
COSC = (PZ-OZ)/DIS
SINC = SQRT (1.-COSC**2)
TDIS = DIS/2.

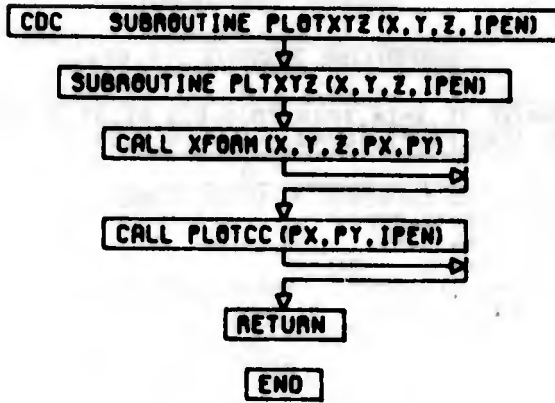








SUBROUTINE PLOTXYZ



SUBROUTINE XFORM

SUBROUTINE XFORM (X, Y, Z, DX, DY)

COMMON/PARAM/XL, YL, XMIN, YMIN, TDIS, DIS, OX, OY, OZ, COSA, COSB, COSC,
OX, OY, OZ, SINC, PX, PY, IQUAD, DIM, XLEN, YLEN

FK = TDIS / ((X-OX) * COSA + (Y-OY) * COSB + (Z - OZ) * COSC)
FL = OX + FK * (X-OX)
FM = OY + FK * (Y-OY)
FN = OZ + FK * (Z - OZ)
OX = ((FL-OX) * COSB - (FM-OY) * COSA) / SINC + XL
OY = (FN-OZ) / SINC + YL

RETURN

END

APPENDIX III

COMMON AND DIMENSION BLOCKS

/Blank/CØEF (m, 4), LFCE (m + 1), JFCE (3n), PVRT (n,2),
PVXYZ (n,3), JEDGE (3n/2, 5), PINT (2n, 4), PEYE (3),
NMBI (3n/2), IØBJ (k + 1), INØBJ (k), LFCI (m)

where m = maximum number of faces allowed (300)

n = maximum number of points allowed (600)

k = maximum number of objects allowed (15)

CØEF - Coefficients for each face

(,1) - X

(,2) - Y

(,3) - Z

(,4) - Distance of viewing point to plane of face

LFCE - Face pointer to edges

JFCE - Edge numbers for each face

PVRT - Projected coordinates of each point (in inches)

(,1) - X

(,2) - Y

PVXYZ - Three space coordinates of each point (in input units)

(,1) - X

(,2) - Y

(,3) - Z

JEDGE - Pointers for each edge

(,1) - First point number on edge

(,2) - Second point number on edge

- (,3) - First face on edge
- (,4) - Second face on edge
- (,5) - Pseudo edge flag

PINT - Intersection coordinates of the projected edges

- (,1) - First edge number on intersection
- (,2) - Second edge number on intersection
- (,3) - X value of intersection
- (,4) - Y value of intersection

PEYE - Three space coordinates of the viewing point

- (,1) - X
- (,2) - Y
- (,3) - Z

NMBI - Number of intersections on each edge

IØBJ - Pointer to first face in object

INØBJ - Type code for each object

LFCI - Object number of each face

/TEMPY/JFCET (3n), IPNT (j)

where n = (see before)

j = maximum number of points on any object (100)

JFCET - point numbers for each face

IPNT - point numbers for each object

/RNGE/PMX(3), PMN(3), IDID, JDID

PMX - maximum input coordinates

(1) - X

(2) - Y

(3) - Z

PMN - minimum input coordinates

(1) - X

(2) - Y

(3) - Z

IDID - internal flat for initialization of faces

JDID - special run flag (see input card A)

/INPTT/J, NE, LL, L, NI, NP, NØBJ, IM

J - Number of points ≤ 600

NE - Number of edges ≤ 900

LL - Number of faces ≤ 300

L - Number of points on faces ≤ 1800

NI - Number of intersection points ≤ 1200

NP - Number of intersection points on any one edge ≤ 48

NØBJ - Number of objects (object numbers) ≤ 15

IM - Special run flag (see input card F)

/ARCH/PPRP (p, 2), NPP

where p = maximum number of points in perimeter (99)

PPRP - Coordinates of perimeter points

(,1) - X

(,2) - Y

NPP - Number of perimeter points ≤ 99

DIMENSION PPRM (2p,2), P (q+2, 2)

Where q = maximum number of intersection points on one line (48)

PPRM - Coordinates of segments on perimeter

(2i-1, 1) - First X of segment i

(2i-1, 2) - First Y of segment i

(2i, 1) - Second X of segment i

(2i, 2) - Second Y of segment i

P - Sorted coordinates of points on a line

(1, 1) - low vertex X

(1, 2) - low vertex Y

(i, 1) - intersection Xi

(i, 2) - intersection Yi

(NP+2, 1) - high vertex X

(NP+2, 2) - high vertex Y

DIMENSION XX (s), YY (s), ZZ (s), A (3)

where s = maximum number of points in a solid's base (20)

XX }
YY } Coordinates of points in a solid's base.
ZZ }

A - Rotation angles of solid (see input card D)

(1) - Azimuth

(2) - Pitch

(3) - Roll

DIMENSION IFP (f), \emptyset (3), SYM (2), AZM (a)

where f = maximum number of points in a face (25)

a = maximum number of input azimuths (card G) (20)

IFP - Point numbers describing a face (card B)

Ø - Offset for input points (card A)

(1) - X

(2) - Y

(3) - Z

SYM - Program Symmetry controls

AZM - Input azimuths (optional, see card G)

/RØTT3/CØSA (3), SINA (3)

CØSA - Cosines of the angles in A

SINA - Sines of the angles in A

/AR/SAREAS (b), NAREAS (b)

where b = maximum number of perimeters in a projection (25)

SAREAS - 2 times area of perimeter

NAREAS - Pointer to first segment in a perimeter

/DEBUGS/IBUG(4)

IBUG - The debug flags (see debug output and cards A and F)

/INSW/ITYPE, ICR, ICL, TYP

(Results from subroutine COVER)

ITYPE - 0 = not covered

1 = on vertex

2 = on edge

3 = covered

} assumed covered

ICR - Number of edge crosses to right of point

ICL - Number of edge crosses to left of point

TYP - Determines if point is hidden (not from cover)

<0, means point is hidden

EXPANSION OF ARRAYS

In order to expand the limits in the program, the dimensions on the arrays given above must be changed. In addition, several program statements must be changed. These statements are listed below.

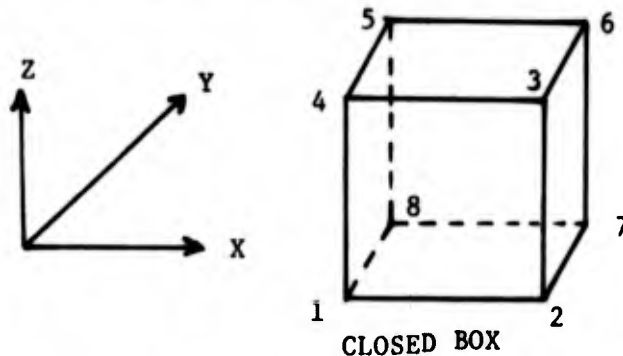
<u>Statement</u>	<u>Sequence</u>
IF(J.GT.600) STØP 6767	270
IF(NØBJ.GE.15) STØP 3333	460
IF(N.GT.25) STØP 2121	560
27 IF(L1.LE.300) GØ TØ 20	630
IF(KR.GT.20) STØP 6736	770
IF(J+KR*K3.GT. 600) STØP 6761	780
CALL COVER (IF, PP, PVRT, 600)	5340
IF (NE.GT.899) STØP 4444	9630

APPENDIX IV

SAMPLE PROBLEMS

(See Following Coding Sheets)

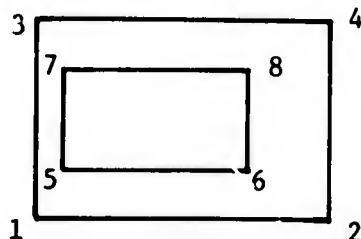
1. This case describes the closed box shown below, using faces only for illustration purposes. The box could have been described by one solid card.



- Run F1: Plot at half scale, the perspective and perimeters of the above box rotated and viewed from an elevation of 45 degrees. Calculate areas and converge to .5 square unit. Print intermediate results for each view.
- Run F2: Plot at twice scale, the perspectives (only) of the above box rotated and viewed from an elevation of 10 degrees. Calculate areas for two iterations. Print intermediate results for each view.
- Run F3: Plot at input scale, three perspectives and perimeters of the above box viewed from an elevation of 30 degrees and at a distance of 250 units (from figure origin). Use azimuth angle of 45, 60, and 330 degrees, respectively, for the three views. Print intermediate results for each view.

In describing the box if the origin was placed so that symmetry was involved, column 41 of card F could be set to X or B. Input is shown in Figure IV-1.

2. This case describes an object with a window, as illustrated below.



FORTRAN CODING FORM

FORM 7065
APR 68

TITLE

JOB NO. **31 - FACES ONLY**

DATE

BY

ADDRESS	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40										
CARD A	B	1																																																
B1	A.	D.	D.	S.	D.	D.	D.	D.	S.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.	D.		
B2	S.	S.	A.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	S.	
C1	A																																																	
D1	1	2	3	4																																														
C2	A																																																	
D2	3	4	5	6																																														
C3	A																																																	
D3	1	2	7	8																																														
C4	A																																																	
D4	1	8	5	9																																														
C5	A																																																	
D5	2	7	6	3																																														
C6	A																																																	
D6	5	6	7	8																																														
E	A																																																	
F1	.5																																																	
F2	2.																																																	
F3	11.																																																	
G	45.																																																	
H																																																		
I																																																		
J																																																		

Figure IV-1. Input Data - Faces Only

Card C - Columns 4 - 5 : 10

Card D - Columns 1 - 30: 3 4 2 1 5 6 8 7 5 1

Since the edge that connects points 1 and 5 is given twice, it is considered a pseudo-edge and is not drawn. In effect, it cuts into the hole to connect the hole to the outside.

3. This case demonstrates the use of solids (see plot, Figure IV-2). Input is shown in Figure IV-3.

4. This case demonstrates the use of object types as shown in Figure IV-4. Input is shown in Figure IV-5.

Run F1 defines object 5 (the large solid) to be the target with objects 1 through 4 being shields. Object 6 is a frame.

Run F2 defines objects 2 and 4 as the target with objects 1, 3, and 5 being shields. Object 6 is a frame.

If card E contains a 2 in column 5, the geometry output shown in Figure IV-6 is obtained.

Depending upon the type of input used, the following output is printed.

1 For each face, the following is printed:

Face number (i), Pointer (LFCE), Object number (LFCI).
LFCE (i) points to table LOC (j) (see 4 below).

2 For each point, the following is printed:

Point number (i), Input X, Input Y, Input Z (PVXYZ)

3 For each edge, the following is printed:

Edge number (i), point numbers, face numbers, flag (JEDGE)

4 The following face table is printed:

LOC(j), edge number (JFCE), point number (JFCET).
If FACE i points to j1, and FACE i +1 to j2 (see 1 above),
all entries between LOC j1 and LOC j2 - 1 describe FACE i.

5 Minimum and maximum points are printed which describe the extreme corners of a rectangular solid (in input coordinates) which would enclose all the geometry.

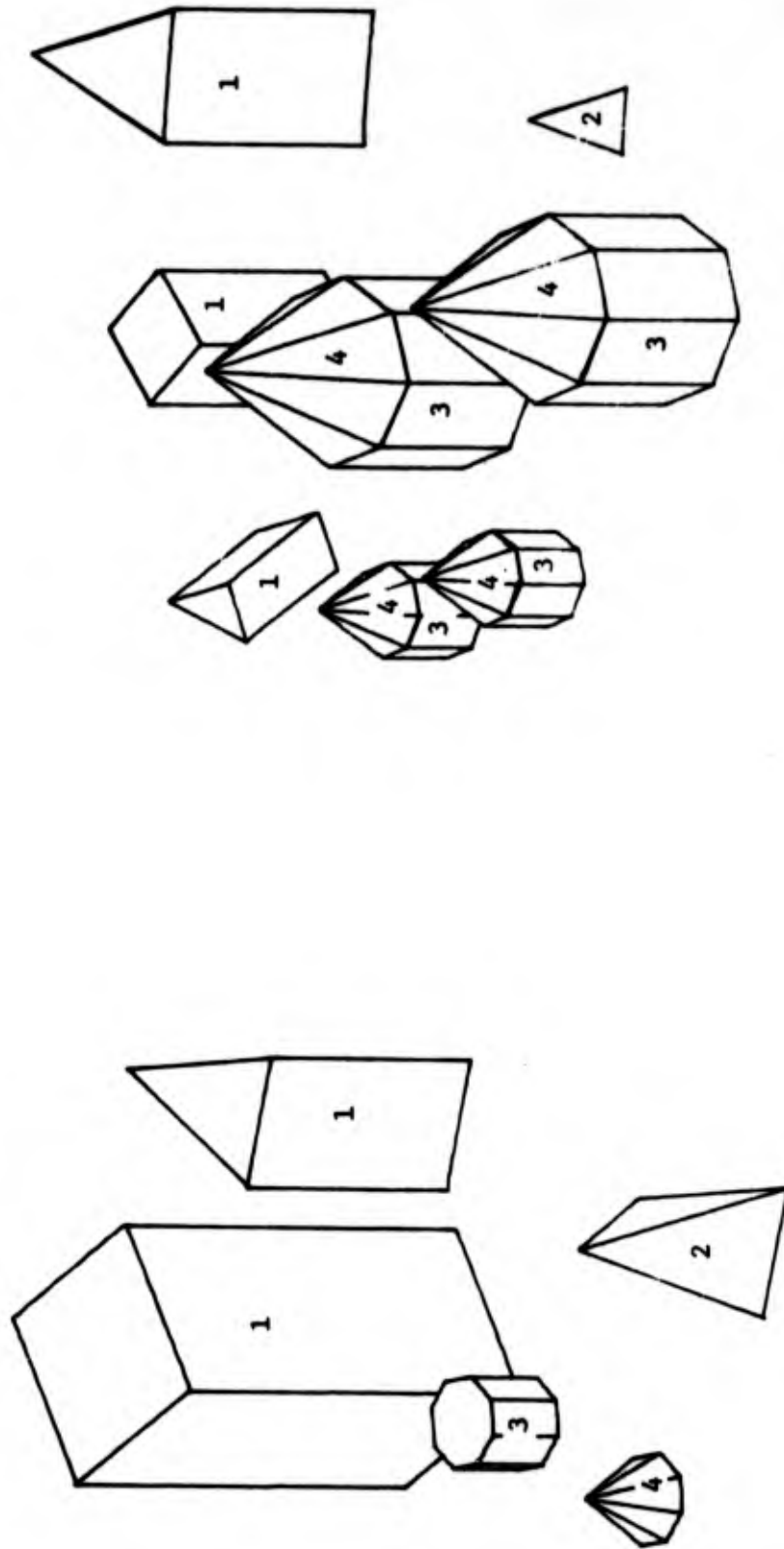


Figure IV-2. Standard Geometrical Shapes

FORTRAN CODING FORM

SHEET _____ OF _____

TITLE _____

JOB NO. **#3 - SOLIDS ONLY**

CARD NO.	CARD A	CARD B	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
	CARD A	B	1	1																		
	C1	1	3	1																		
	D1	1	2	3	45.	0.	0.															
	D'1	2	1	1	2.	3.																
	C2	1	4	2																		
	D2	1	1	1	45.	0.	0.	0.	.5													
	D'2	2	0	2	2.	0.	2.		5.													
	C3	2	3	3																		
	D3	1	7	3	45.	0.	0.	0.	.5													
	D'3	2	1	1	2.	1.5	1.5	3.														
	C4	3	4	4																		
	D4	1	5	2	0.	0.	0.	2.														
	D'4	2	1																			
	C5	4	5	4																		
	D5	1	5	4	0.	0.	0.	2.														
	D'5	2	1																			
	C6	9	4	8																		
	D6	1	8	2	0.	0.	0.	0.														
	C7	9	5	5																		
	D7	1	5	2	0.	0.	0.	.5														
	C8	9	1	6																		
	D8	6	2	2	0.	0.	30.	0.	.5													
	E		2																			
	F	.5			45.	-1.		1	22													

Figure IV-3. Input Data - Solids Only

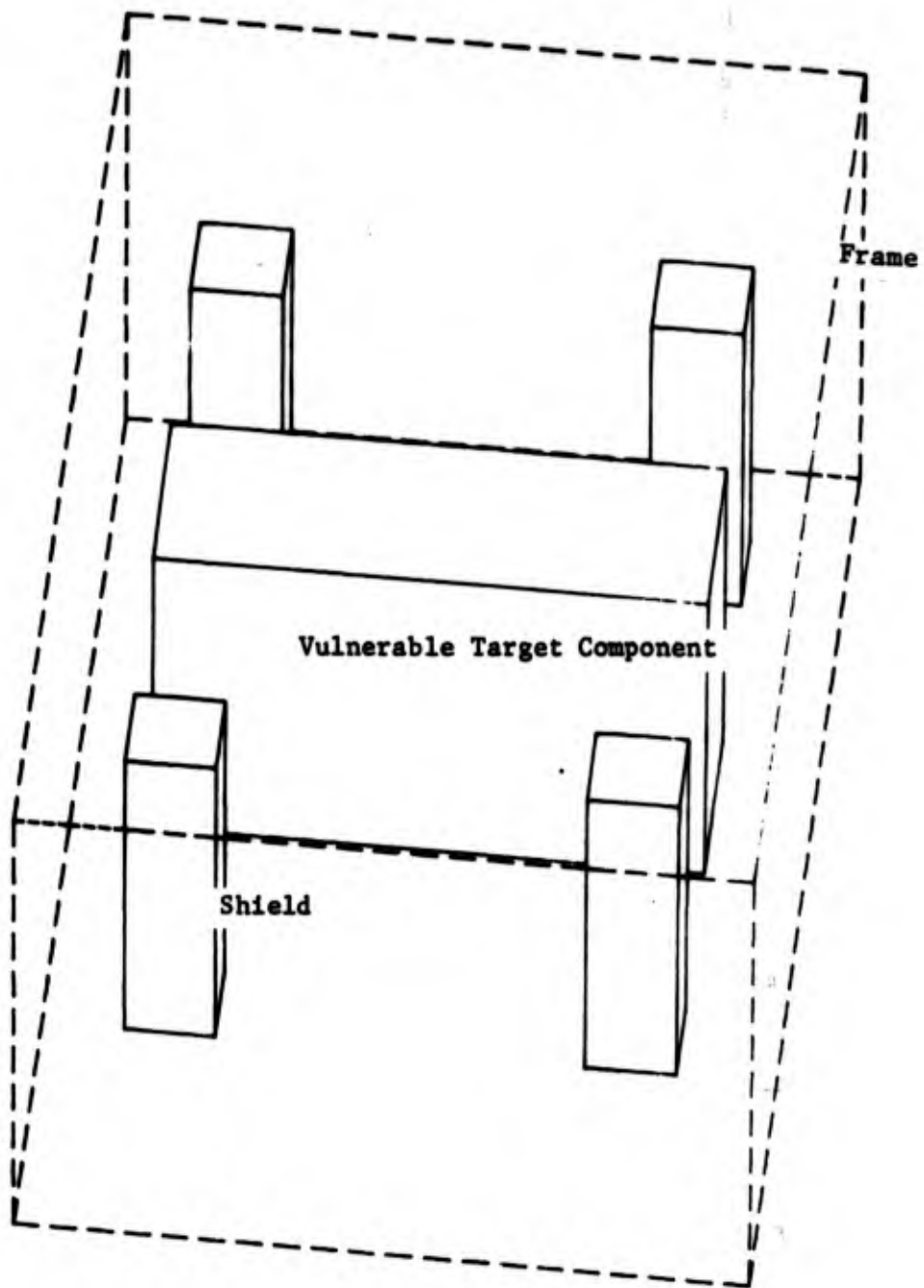


Figure IV-4. Shielding and Identifiable Component Example

FORTRAN CODING FORM

CARD NO.	CARD	TOTAL										PAGE	OF	
		1	2	3	4	5	6	7	8	9	0			
#4 - TEST PROBLEM														
1	A	1	1											
2	B													
3	C1	1												
4	D1	1												
5	D'1	0		1		0		1						
6	C2	1		2										
7	D2	1		3										
8	C3	1		1										
9	D3	1		1										
10	C4	1		1										
11	D4	1		1										
12	C5	1		5										
13	D5	1		1										
14	D'5	0		2		6		0		6				
15	C6	1		6										
16	D6	0		0										
17	D'6	0		12		8		0		8				
18	E	2												
19	F1	5				15				-1		1		
20	F2	5				15				-1		1		
21	H													
22	I													
23	J													
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99														
100														

Figure IV-5. Input Data - Test Problems

```

1
1 3 1
1. 2. 3. 45.
2. 1. 1. 2. 3.
2 3 2
3. 4. 3. 45.
2. 1. .5 2.5 3.
2

```

FACE	POINTER	OBJECT
1	1	1
2	4	1
3	7	1
4	11	1
5	15	1
6	19	2
7	22	2
8	25	2
9	28	2

POINT	X	Y	Z
1	0.0	0.0	0.0
2	1.00	2.00	3.00
3	1.71	4.12	3.00
4	0.20	4.12	3.00
5	1.00	2.00	6.00
6	1.71	4.12	6.00
7	0.20	4.12	6.00
8	3.00	4.00	3.00
9	4.41	5.00	1.50
10	3.35	6.50	2.65
11	5.12	4.00	0.65

EDGE	PT	PT	FACE	FACE	FLG
1	2	3	1	3	0
2	3	4	1	4	0
3	4	2	1	5	0
4	5	6	2	3	0
5	6	7	2	4	0
6	7	5	2	5	0
7	3	6	3	4	0
8	5	2	3	5	0
9	4	7	4	5	0
10	8	9	6	7	0
11	9	10	6	8	0
12	10	8	6	9	0
13	9	11	7	8	0
14	11	8	7	9	0
15	10	11	8	9	0

Figure IV-6. Geometry Output

LOC	EDGE	POINT
1	1	2
2	2	3
3	3	4
4	4	5
5	5	6
6	6	7
7	1	2
8	7	3
9	4	6
10	8	5
11	2	3
12	9	4
13	5	7
14	7	6
15	3	4
16	8	2
17	6	5
18	9	7
19	10	8
20	11	9
21	12	10
22	10	8
23	13	9
24	14	11
25	11	9
26	15	10
27	13	11
28	12	10
29	14	8
30	15	11

*****MINIMUM POINT***** *****MAXIMUM POINT*****

0.0	0.0	0.0	5.12	6.50	6.00
-----	-----	-----	------	------	------

Figure IV-6. (Concluded)

APPENDIX V

TARGET DESCRIPTION AND VULNERABILITY PROGRAM

```

PROGRAM PLOT(INPUT,OUTPUT,TAPES=INPUT,TAPE6=OUTPUT,FILHPL)
C PROGRAM PLOT(INPUT,OUTPUT,TAPES=INPUT,TAPE6=OUTPUT,FILHPL)
COMMON/RAST/NOB
5 COMMON/COEF(300,4) 10100210
* LFCF(100),JFCF(100),PVRT(600,2),PVXYZ(600,3),JEDGE(900,5), 10100220
* PINT(1200,4),PEYE(3),NM0I(900) 10100230
* IOBJ(10),INOBJ(15),LFCI(300) 10100240
COMMON /IMPRT/J,NE,LL,L,NI,NP,NOBJ,IN 10100250
COMMON/JEBUGS/IBUG(4) 10100260
10 COMMON/ARCH/PPRP(30,2),NPP 10100270
COMMON/AR/SAREAS(25),NAREAS(25) 10100280
COMMON/RNGE/PX(3),PMN(3),IDID,JOID 10100290
COMMON/TEMPY/JFCET(1000),IPNT(100) 10100300
15 COMMON/ROTT3/COSA(3),SINA(3) 10100310
DIMENSION IFF(25),O(3),SYM(2),AZH(20) 10100320
DIMENSION XX(20),YY(20),ZZ(20),A(3) 10100330
EQUIVALENCE(X,PEYE(1)),(Y,PEYE(2)),(Z,PEYE(3)) 10100340
DATA SYH/3M0,1Mx/ 10100350
DATA PI2/6.283185/ 10100360
20 C 10100370
CALL PLOTCC(0.,0.,-3) 10100380
NOB=100 10100390
5 IDIJ=0 10100400
WRITE(6,1) 10100410
25 1 FORMAT(27M1TARGET DESCRIPTION PROGRAM)
C
C J=NUMBER OF POINTS 10100210
C 10100220
C 10100230
30 READ(5,11) J,IBUG,IO,O,FC,JOID,(PVXYZ(I,M),M=1,3),I=1,J)
11 FORMAT(15,5I1,4F5.0,15/(15F5.0))
IF(I.LT.8)GO TO 1000
IF(I.GT.600)STOP 6767
IF(FC.LT.0.1)FC=1.
C CHECK OFFSET
35 IF(10.EQ.0)GO TO 15
DO 12 I=1,J 10100290
DO 12 M=1,3 10100300
12 PVXYZ(I,M)=PVXYZ(I,M)+O(M) 10100320
C 10100330
C 10100340
40 C 10100350
L1 = FACE NUMBER , NOBJ = OBJECT NUMBER , IOBJ(I) = LOC OF OBJ I
15 CONTINUE 10100360
I=1 10100370
NOBJ=0 10100380
45 C 10100390
20 HEAD(5,21)K,N,NOBJ 10100400
21 FORMAT(11,I4,15) 10100410
IOBJ(1) = I 10100420
IF(I.GT.1.AND.NOBJ.EQ.0)GO TO 23 10100430
C NEW OBJECT 10100440
IF(10.EQ.15)STOP 3333 10100450
NOBJ=NOBJ+1 10100460
30 C 10100470
23 IF(K.EQ.0)GO TO 25 10100480
C READ POSITION , ORIENTATION , AND SCALE OF FIGURE 10100490
55 READ(5,36) X1,Y1,Z1,A,FC 10100500

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      IF (FCT.EQ.0.) FCT=1.
      GO TO (30,30,65,65,75,80,30,65,90),K
C
25 CONTINUE
      IF (N.LT.J) GO TO 105
      IF (N.GT.25) STOP 2121
      READ (5,26) (IFP(I),I=1,N)
26 FORMAT (25I3)
C
      CALL FACES (IFP,N)
C
      L1=L1+1
27 IF (L1.LE.300) GO TO 20
C
      STOP 5555
C
30 KR=N+K-1
      READ POINTS AND HEIGHT
      READ (5,36) (XX(I),YY(I),I=2,KR),ZP
75 36 FORMAT (14F5.0)
      SET FIRST POINT
      XX(1)=X1
C
      K3=1 -- POINT ON TOP , K3=2 -- RIGHT FIGURE
C
80 38 K3=2+N-KR
      IF (KR.GT.20) STOP 6736
      IF (J+KR*K3.GT.300) STOP 6761
      SCALE HEIGHT
      ZP=ZP*FCT
      FIRST POINT
      YY(1)=Y1
      ZZ(1)=Z1
C
90 POINT TRANSLATION AND SCALE
      DO 40 I=2,KR
      YY(I)=FCT*YY(I)+Y1
      XX(I)=FCT*XX(I)+X1
      ZZ(I)=Z1
95 C
      TOP POINT , IF ANY
      IF (K3.EQ.1) ZZ(KR)=Z1+ZP
      JSAVE=J
      JSV1=J+1
100 C
      STORE BASE
      ROTATE
      CALL ROTATJ (XX,YY,ZZ,KR,X1,Y1,Z1,A)
      DO 43 I=1,KR
      J=J+1
      PVXYZ (J,1)=XX(I)
      PVXYZ (J,2)=YY(I)
      PVXYZ (J,3)=ZZ(I)
105 43
C
      STORE BOTTOM FACE
      DO 45 I=1,N
110 45 IFP(I)=I+JSAVE

```

```

10100510
10100520
10100530
10100540
10100550
10100560
10100570
10100580
10100590
10100600
10100610
10100620
10100630
10100640
10100650
10100660
10100670
10100680
10100690
10100700
10100710
10100720
10100730
10100740
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10100760
10100770
10100780
10100790
10100800
10100810
10100820
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10100880
10100890
10100900
10100910
10100920
10100930
10100940
10100950
10100960
10100970
10100980
10100990
10101000
10101010
10101020
10101030
10101040
10101050

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PROGRAM	PPLLOT	COC 6600 FTM V3.0-PE06 OPT=1 04/05/72 12.56.44. PAGE 3
	C	10101060
	C	10101070
	C	10101080
115	C	10101090
	C	10101100
	C	10101110
	C	10101120
	C	10101130
120	C	10101140
	C	10101150
	C	10101160
	C	10101170
	C	10101180
125	C	10101190
	C	10101200
	C	10101210
	C	10101220
	C	10101230
	C	10101240
	C	10101250
	C	10101260
130	C	10101270
	C	10101280
	C	10101290
	C	10101300
	C	10101310
	C	10101320
	C	10101330
	C	10101340
	C	10101350
	C	10101360
	C	10101370
	C	10101380
	C	10101390
	C	10101400
	C	10101410
135	C	10101420
	C	10101430
	C	10101440
	C	10101450
	C	10101460
	C	10101470
140	C	10101480
	C	10101490
	C	10101500
	C	10101510
	C	10101520
145	C	10101530
	C	10101540
	C	10101550
	C	10101560
	C	10101570
150	C	10101580
	C	10101590
	C	10101600
	C	10101610
	C	10101620
	C	10101630
155	C	10101640
	C	10101650
	C	10101660
	C	10101670
160	C	10101680
	C	10101690
	C	10101700
	C	10101710
	C	10101720
165	C	10101730
	C	10101740


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C
/ TRANSLATE AND SCALE ALL THE NEW POINTS 10102300
DO 96 M=1,MPNT 10102310
NR=IPNT(M) 10102320
NS=NS+1 10102330
NK(M)=FCT*PVXYZ(NR,1)+BX 10102340
VY(M)=FCT*PVXYZ(NR,2)+BY 10102350
96 ZZ(M)=FCT*PVXYZ(NR,3)+BZ 10102360
C 10102370
230 CALL ROTATJ(NX,VY,ZZ,NS,N1,V1,Z1,A) 10102380
C 10102390
DO 97 M=1,NS 10102400
J=J+1 10102410
PVYZ(J,1)=NK(M) 10102420
235 PVYZ(J,2)=VY(M) 10102430
97 PVYZ(J,3)=ZZ(M) 10102440
C 10102450
G STORE FACE 10102460
98 CALL FACES(IPP,JPNT) 10102470
240 C 10102480
C 10102490
L1=L1+ISTZ-IST1+1 10102500
GO TO 27 10102510
C 10102520
245 C 10102530
C 10102540
C 10102550
ARCHITECTURAL PRINT OUT 10102560
C 10102570
C 10102580
250 105 CONTINUE 10102590
LFCE(LL+1)=L+1 10102600
IF(JOID.NE.0)GO TO 109 10102610
C FIND RANGE OF X,Y,Z 10102620
DO 108 M=1,J 10102630
255 PNX(M)=PVYZ(1,M) 10102640
PNM(M)=PVYZ(1,M) 10102650
DO 108 I=2,J 10102660
IF(PNX(I).LT.PVYZ(1,M))PNX(M)=PVYZ(1,M) 10102670
IF(PNM(I).GT.PVYZ(1,M))PNM(M)=PVYZ(1,M) 10102680
260 108 CONTINUE 10102690
109 CONTINUE 10102700
IF(M.LT.2)GO TO 150 10102710
WRITE(6,110)(I,LFCE(I),LFC(I),I=1,LL) 10102720
265 110 FORMAT(//7A25#FACE POINTER OBJECT/(3I10)) 10102730
WRITE(6,120)(I,(PVYZ(I,I),M=1,3),I=1,J) 10102740
120 FORMAT(//6H POINT,6X1M,6X1M,6X1MZ/(15,4F10.2)) 10102750
WRITE(6,125)(I,(JEDGE(I,M),M=1,3),I=1,NE) 10102760
270 125 FORMAT(//2X20#EDGE PT PT FACE FACE FLG/(16I5)) 10102770
WRITE(6,130)(I,JFCE(I),JFCE(I),I=1,L) 10102780
130 FORMAT(//3X14#LOC EDGE POINT/(3I5)) 10102790
WRITE(6,135)IPNM,PNK 10102800
275 135 FORMAT(6#H*****MINIMUM POINT***** *****MAXIMUM POINT***** 10102810
1****/6F10.2) 10102820
C 10102830
150 CONTINUE 10102840

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READ(5,134) P1,P2,PHI,CONV,JR,IN,IREA,R,SY,IPLOT,IBUG,P3,INOBJ 10102050
WRITE(6,133) P1,P2,PHI,CONV,JR,IN,IREA,R,SY,IPLOT,IBUG,P3,INOBJ 10102060
130 FORMAT(2F5.2,2F10.3,12Z11,F6.2,A1,5I1,1X,F6.2,2X,15I1) 10102070
IF(P1.EQ.0) GO TO 5 10102080
IF(P3.NE.0) CALL PLOTCC(P3,0,-3) 10102090
IF(IM.NE.0) GO TO 205 10102100
C CHECK SYMMETRY 10102110
DO 160 ISY=1,2 10102120
IF(ISY.EQ.2) SYM=ISY GO TO 170 10102130
160 CONTINUE 10102140
ISY=4 10102150
170 CONTINUE 10102160
I0=6 10102170
IF(CONV.GE.0) GO TO 182 10102180
C ITERATION OPTION 10102190
I0=5-CONV 10102200
CONV=5 10102210
182 CONV=1+P1*CONV 10102220
IF(IREQ.0) I0=1000 10102230
PHI=PHI/57.2958 10102240
Z=R*SIN(PHY) 10102250
J=R*COS(PHY) 10102260
IF(IBUG(1).GT.1) WRITE(6,106) R,Z,CONV 10102270
190 FJMMAT(5M0XANUC =,F9.2,4M Z =,F9.2,7M CONV =,F8.4) 10102280
ARLAS=0 10102290
NK=1 10102300
ARJ=1 10102310
N=ISY 10102320
NN=N 10102330
IF(ISY.LT.4) NN=N+1 10102340
IF(ISY.EQ.1) ARJ=2 10102350
I0=ISY*1.570796 10102360
IF(JR.LT.0) GO TO 200 10102370
C AZH01M INPJ 10102380
HEAD(5,136) (AZH(I),I=1,JR) 10102390
WRITE(6,136) (AZH(I),I=1,JR) 10102400
130 FOMAT(3F10.4) 10102410
I0=1 10102420
NN=JR 10102430
C 10102440
C 10102450
200 NJ=NN 10102460
205 DO 300 I=1,16 10102470
I1=1 10102480
OT=TOT/N 10102490
C 10102500
DO 300 I=NN,NN,NK 10102510
IF(IM.NE.0) GO TO 260 10102520
C AREA FACTOR 10102530
ARF=ARQ 10102540
IF(ISY.EQ.4) GO TO 230 10102550
IF(NK.EQ.2) GO TO 225 10102560
IF(ISY.EQ.1) GO TO 227 10102570
IF(IM.NE.2) GO TO 230 10102580
300 225 ARF=2.*ARQ 10102590

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227 ND=NG+AMP-1
230 NTH=1
      TTH=DTM-DTH+.1
      IF(JR.GT.0)TTH=AZINI/97.2996
335 250 X=Q*CSITH
      Y=Q*SINTH
      CALL INIT33(-P1.0,X,Y,Z,PNH(1),PNH(2),PNH(3),PNH(4),PNH(5),PNH(6))
260 CALL ARCH3(AREA,IPLT,AREA)
      IF(INEA.EQ.0)GO TO 300
340 IF(INEA.GE.3)GO TO 280
      IF(IBUG(1).GT.0)WRITE(6,271)TTH,AREA,NTH
271 FORMAT(1YH'TROUBLE IN AREA AT,2F10.4,I5)
      IF(JR.GT.0)GO TO 270
      TTH=TTH+.1*DTM
      NTH=NTH+1
345 IF(IBUG(1).GT.1 .AND. (IPLT.NE.0))CALL PLOTCC(P2,0.,-3)
      IF(NTH.LE.3)GO TO 250
270 ND=ND-1
      GO TO 300
350 280 AREAS=AREAS+AREA*ARF
      IF(IBUG(1).GT.1)WRITE(6,285)TTH,X,Y,AREA,AREAS,M
285 FORMAT(11M0AZIMUTH = ,F8.4,M X =,F9.2,M Y =F9.2,M AREA =,F9.4,
      * 6M SUM =,F9.4,11M VIEW NO. =,I3)
355 IF(IPLT.LE.1)GO TO 300
      C PLOT PERIMETER
      CALL PLOTCC(P2,0.,-3)
      NIA=1
      IP=3
      DO 295 NI=1,NPP
360 IF(IP.EQ.3)GO TO 291
      IX1=N00*PPR(NI-1,1)
      IY1=N00*PPR(NI-1,2)
      IX2=N00*PPR(NI,1)
      IY2=N00*PPR(NI,2)
365 CALL LINEV(IX1,IY1,IX2,IY2)
291 CONTINUE
      IP=2
      IF(NI.LT.NANEAS(NIA))GO TO 295
      IP=3
370 NIA=NIA+1
295 CONTINUE
      C
380 IF(IPLT.NE.0)CALL PLOTCC (P2,0.,-3)
      IF(INEA.EQ.0)GO TO 190
375 C
      AREAS=AREAS/ND
      IF(IBUG(1).GT.0)WRITE(6,350)I,AREAS
      IF(IG.EQ.1)GO TO 355
      ND=ND+M
      N=2*M
      NK=2
      IPLT=0
      NN=M
380 IF(I.EQ.1)GO TO 350
      IF(ABS(AREAS-AREAD).LE.CONV)GO TO 355

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PROGRAM

MPLOT

CDC 6600 FTH V3.0-P204 OPT=1 04/05/72 12.54.44.

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	350	AREA0=AREA	10103740
C			10103750
	355	AREA=FC*FC*AREA/P1/P1	10103760
		WRITE(6,356)II,AREA	10103770
390	355	FORMAT(5MDAFTEr,14,23H ITERATIONS, THE AREA =,F8.3//)	10103780
		GO TO 150	10103790
C			10103800
	1000	CONTINUE	10103810
		STOP 77	10103820
395		END	10103840

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SUBROUTINE ARCH3(AREA,IPLOT,IREA)
THREE D ARCHITCTURAL PLOTTING ROUTINE
(ALSO FINDS PERIMETER AND AREA SEEN)
10103850
10103860
10103870
5 C TABLES ARE GENERATED IN MAIN AND PASSED THRU COMMON
10103880
10103890
10103900
10103910
10103920
C IF IREA.NE.0, AREA WILL BE CALCULATED.
C IF IPLOT.NE.0 PLOT WILL BE MADE
COMMON COEF(300,4)
10 C
10 LFCI(300),JFCE(1000),PVRT(600,2),PVXYZ(600,3),JEDGE(900,5),
PINT(1200,4),PEYE(3),MMOI(900)
10 IOBJ(16),INOBJ(15),LFCI(300)
COMMON /INPT/J,NE,LL,L,NI,NP,NOBJ,IN
COMMON/JEBUGS/JBUG(4)
15 COMMON /ANSM/ITYPE,ICR,ICL,TYP
COMMON/ARCH/PPRP(19,2),NPP
COMMON/AR/SAREAS(25),NAREAS(25)
JIMENS(IJN PC(3),AL(3),BL(3),PP(2),PPRM(19,2),P(9,2)
NSEG=0
20 IF(IEN.NE.0)GO TO 150
C
C TRANSFORM POINTS
DO 136 M=1,J
10104000
10104010
10104020
10104030
10104040
10104050
10104060
10104070
10104080
10104090
25 C CALL XFORM(PVXYZ(M,1),PVXYZ(M,2),PVXYZ(M,3),PVRT(M,1),PVRT(M,2))
130 CONTINUE
10104100
10104110
10104120
10104130
141 FORMAT(6NDPOINT,7X,1HX,9X,1HY/15,2F10.4))
C
C GET ALL INTERSECTIONS
CALL INTER
10104140
10104150
10104160
10104170
10104180
10104190
30 C DRAW EACH EDGE
C
C
C
150 CONTINUE
10104200
10104210
10104220
10104230
10104240
10104250
10104260
10104270
10104280
10104290
10104300
45 C DO 200 I0=J,4
FACE ON EDGE
I01=JEDGE(I0,I0)
IF(I01.EQ.0)GO TO 200
OBJECT ON FACE
I02=LFCI(I01)
10104310
10104320
10104330
10104340
50 C SEE IF TO BE USED
IF(INOBJ(I02)-2)210,190,200
SHIELD. IF EDGE ALSO USEJ ON TARGET OR FRAME USE AS SUCH.
10104350
10104360
10104370
10104380
10104390
10104400
55 C 190 ICK=I02
200 CONTINUE
IGNORE IF NOT SHIELD
IF(ICK.EQ.0)GO TO 300
10104410

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      I02=IOK
      SKIP CUTS (PSEUDO EDGES)
210 CONTINUE
      IP2=2
      IF (JEDGE(M,5).GT.0) IP2=3
      K1=JEDGE(M,1)
      K2=JEDGE(M,2)
      K3=K1
      K4=K2
      O1=PVRT(K1,1)-PVRT(K2,1)
      IF (ABS(O1)-LE.1.0001) GO TO 215
      IF (O1) 220,215,217
215 IF (PVRT(K1,2) - PVRT(K2,2)) 220,300,217
217 K4=K1
      K3=K2
      C
      C LENGTH OF LINE
      C
220 DO 222 N1=1,2
      BL(N1)=PVRT(K4,N1)-PVRT(K3,N1)
      AL(N1)=PVXYZ(K4,N1)-PVXYZ(K3,N1)
222 CONTINUE
      AL(3)=PVXYZ(K4,3)-PVXYZ(K3,3)
      C
      C
      C NP=0
      C ANY INTERSECTIONS
      IF (N1.LE.0) GO TO 250
      IF (NMBI(M).EQ.0) GO TO 250
      C YES
      N1=1
      DO 240 N=1,N1
230 I1=PINT(N,N1)+.5
      IF (M-I1) 232,235,240
232 GO TO (233,240),N1
233 N1=2
      GO TO 230
      C
      C YES - ADD POINT TO SORTED LIST
      C
235 CALL SORTM(PINT(N,3),PINT(N,4),P(2,1),P(2,2),NP,40)
      IF (NP.EQ.NMBI(M)) IF (NP-49) 250,241,241
240 CONTINUE
241 STOP 7654
      C
      C PUT VERTICES IN LIST
      C NP=NP+2
      DO 252 N1=1,2
      P(1,N1)=PVRT(K3,N1)
252 P(NP,N1)=PVRT(K4,N1)
      IF (IBUG(2).GT.2) WRITE (6,253) NP,M,((P(N,N1),N1=1,2),N=1,NP)
253 FORMAT(15,15H POINTS ON EDGE,14/(612F8.4,6X))
      C
      C

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	C	DRAW SEGMENT BY SEGMENT - STARTING FROM LOW VERTEX	10104970
	C	NIS=0	10104980
		DO 206 N1=1,NP	10104990
115		IPER=0	10105000
	C	REVERSE PERIMETER IF TYPE 2	10105010
		IF(INOBJ(IJ2).EQ.2)IPER=1	10105020
		DIS=999.	10105030
		DIS2=999.	10105040
120		IP=3	10105050
		IF(N1.EQ.1)IF(IPL0T)275,200,275	10105060
	C	SEE IF SAME POINT	10105070
	C	DO 255 N2=1,2	10105080
125		IF(P(N1,N2).NE.P(N1-1,N2))GO TO 257	10105090
		255 CONTINUE	10105100
		GO TO 280	10105110
	C		10105120
	C		10105130
130	C	CENTER OF SEGMENT	10105140
		257 DO 258 N2=1,2	10105150
		258 PP(N2)=(P(N1,N2)+P(N1-1,N2))/2.	10105160
	C		10105170
		DO 260 N2=1,3	10105180
135		N3=1	10105190
		IF(ML(1).LE..01)N3=2	10105200
		260 PC(N2)=PVXYZ(K3,N2)+AL(N2)*(PP(N3)-P(1,N3))/BL(N3)	10105210
	C		10105220
140	C	IS IT HIDDEN BY A FACE	10105230
	C		10105240
	C		10105250
		DO 265 IF=1,LL	10105260
	C	CHECK FACE FOR TRANSPARENCY	10105270
		IB3=LFCI(IF)	10105280
145		IF(INOBJ(IB3).EQ.1.OR.INOBJ(IB3).EQ.3)GO TO 265	10105290
	C	OPAQUE (WILL HIDE WHAT IS BEHIND IT)	10105300
		SKIP FACES ON EDGE	10105310
	C	IF(JEDGE(M,J).EQ.1.OR.JEDGE(M,J).EQ.4)GO TO 265	10105320
		CALL COVER(IF,PP,PVRT,600)	10105330
150		IF(INJG(2).GT.0)WRITE(6,262)PP,ITYPE,ICR,ICL,IF,IB2,IB3	10105340
		IF(ITYPE.EQ.0)GO TO 265	10105350
	C		10105360
	C	COVERED	10105370
	C		10105380
	C		10105390
155		INVERT PERIMETER, IF TYPE 2	10105400
		IF(INOBJ(IJ2).EQ.2)GO TO 259	10105410
		IF(IPL0T.EQ.0)GO TO 280	10105420
	C	TYPE 0 COVERED BY TYPE 2 MAY STILL BE ON PERIMETER	10105430
		IF(INOBJ(IJ2).EQ.0.AND.INOBJ(IJ3).EQ.2)GO TO 259	10105440
160		IPER=1	10105450
		259 CONTINUE	10105460
		T1=CDEF(IF,6)	10105470
		T2=T1	10105480
		DO 263 N2=1,3	10105490
165		T1=T1+CDEF(IF,N2)*PC(N2)	10105500
		263 T2=T2+CDEF(IF,N2)*PEVE(N2)	10105510

	IF (IBUG(2).GT.5)WRITE(6,262)PP,ITYPE,ICR,ICL,IF,M,N1,PC,T1,T2	10105520
262	FORMAT(2F10.4,6I5,3F10.4,2E15.4)	10105530
	IF (ABS(T2).LT..005)GO TO 375	10105540
	TYP=T1/T2	10105550
170	IF (TYP.LT.0.)GO TO 270	10105560
	C	10105570
	C NOT HIDDEN BY THIS CHECK FACE	10105580
	IF (INOBJ(I02).NE.2)GO TO 265	10105590
	C TYPE 2 EDGE	10105600
175	IF (INOBJ(I03).EQ.2)GO TO 266	10105610
	C COVERED BY TYPE 0 FACE (SEGMENT MAY BE ON PERIMETER)	10105620
	IPER=0	10105630
	C DISTANCE FROM THIS TYPE 2 SEGMENT TO NEAREST TYPE 0 FACE THAT	10105640
	C COVERS IT	10105650
180	DIS0=AMIN1(DIS0,TYP)	10105660
	GO TO 265	10105670
	C DISTANCE FROM THIS TYPE 2 SEGMENT TO NEAREST TYPE 2 FACE THAT	10105680
	C COVERS IT	10105690
185	266 DIS2=AMIN1(DIS2,TYP)	10105700
	C	10105710
	265 CONTINUE	10105720
	C	10105730
	C NO NOT HIDDEN	10105740
	C	10105750
190	IF (IREA.EQ.0)GO TO 269	10105760
	IF (IPER.NE.1)GO TO 269	10105770
	C NO PERIMETER FOR TYPE 1	10105780
	IF (INOBJ(I02).EQ.1)GO TO 269	10105790
195	C NO PERIMETER FOR TYPE 2 UNLESS COVERING A TYPE 0 FACE WITH NO	10105800
	C TYPE 2 FACE BETWEEN	10105810
	IF (INOBJ(I02).EQ.2)IF (DIS2-DIS0)269,269,268	10105820
	C NOT COVERED. SAVE SEGMENT FOR PERIMETER	10105830
	268 IF (NSEG.GE.199)STOP 7766	10105840
	N4=1	10105850
200	IF (N1.GT.N15)GO TO 267	10105860
	N4=2	10105870
	NSEG=NSC0-2	10105880
	C	10105890
205	267 DO 261 N3=N4,2	10105900
	DO 261 N2=1,2	10105910
	261 P<<M(NSEG+N3,N2)=P(N1+N3-2,N2)	10105920
	NSEG=NSEG+2	10105930
	N15=N1+1	10105940
	C	10105950
210	269 IP=IP2	10105960
	270 IF (IPL0T.EQ.0)GO TO 280	10105970
	IF (INOBJ(I02).NE.1)GO TO 275	10105980
	C FRAME	10105990
215	IF (IP.EQ.3)GO TO 275	10106000
	CALL DASHLN(P(N1-1,1),P(N1-1,2),0.,0.,2.)	10106010
	IP=3	10106020
	275 CALL PLJTDJ(P(N1,1),P(N1,2),IP)	10106030
	C	10106040
220	280 CONTINUE	10106050
		10106060

	C		10106070
	C	300 CONTINUE	10106080
	C		10106090
	C		10106100
225		IF (AREA.EQ.0) RETURN	10106110
		IF (IBUG(2).GT.1) WRITE(6,361) NSEG, ((PPRM(N,M), M=1,2), N=1, NSEG)	10106120
	C		10106130
	C	REMOVE ANY DUPLICATE SEGMENTS	10106140
		DO 304 N=1, NSEG, 2	10106150
230		NJ=N+2	10106160
		295 CONTINUE	10106170
		IF (PPRM(NJ,1).LT.-999) GO TO 302	10106180
		DO 301 N2=1, 2	10106190
		IF (PPRM(NJ, N2).NE.PPRM(N, N2)) GO TO 303	10106200
235		301 CONTINUE	10106210
		IV=N3+1	10106220
		IF (2*(N3/2).EQ.N3) IV=N3-1	10106230
		DO 299 N2=1, 2	10106240
		IF (PPRM(IV, N2).NE.PPRM(N+1, N2)) GO TO 303	10106250
240		299 CONTINUE	10106260
	C	FOUND	10106270
		PPRM(IV, 1)=-999	10106280
		PPRM(NJ, 1)=-999	10106290
		N3=MIN0(IV, NJ)	10106300
245		302 N3=N3+1	10106310
		303 N3=N3+1	10106320
		IF (N3.LE.NSEG) GO TO 295	10106330
		304 CONTINUE	10106340
250	C		10106350
	C	INITIALIZE PERIMETER SEARCH	10106360
			10106370
		NPP=0	10106380
		SUM=0.	10106390
		IA=0	10106400
		M1=1	10106410
255		GENERATE PERIMETER POINTS STARTING FROM POINT M1	10106420
	C		10106430
		305 IV=M1+1	10106440
		DO 310 N=1, 2	10106450
		NPP=NPP+1	10106460
260		DO 310 N=1, 2	10106470
		310 PPRM(NPP, M)=PPRM(M1+N-1, M)	10106480
		AREA=(PPRM(M1, 1)-PPRM(IV, 1))*(PPRM(M1, 2)+PPRM(IV, 2))	10106490
265			10106500
		N=NPP+1	10106510
	C	SEARCH FOR POINT .EQ. IV	10106520
		DO 330 N1=3, NSEG	10106530
		IF (N1.EQ.IV) GO TO 330	10106540
		DO 325 N2=1, 2	10106550
270		IF (PPRM(IV, N2).NE.PPRM(N1, N2)) GO TO 331	10106560
		325 CONTINUE	10106570
	C	FOUND	10106580
		PPRM(IV, 1)=-999.	10106590
		PPRM(N1, 1)=-999.	10106600
275		IV=N1+1	10106610

	IF(2*(M1/2).EQ.N1)IV=N1-1	10106620
	JDONE=1	10106630
	PUT POINT IN PERIMETER AND SEE IF DONE	10106640
280	DO 328 N2=1,2	10106650
	IF(PPRM(IV,N2).NE.PPRM(M1,N2))GO TO 328	10106660
	JDONE=JDONE+1	10106670
285	328 PPRP(N,N2)=PPRM(IV,N2)	10106680
	AREA=(PPRP(N-1,1)-PPRP(N,1))*(PPRP(N-1,2)+PPRP(N,2))+AREA	10106690
	GO TO(350,350,355),JDONE	10106700
	CONTINUE	10106710
	GO TO 305	10106720
	350 IF(IUGG(2).GT.4)WRITE(6,351)M1,N,N1,IV,AREA,SUM	10106730
	351 FORMAT(4I5,2F10.4)	10106740
290	N=N+1	10106750
	GO TO 320	10106760
	C	10106770
	C	10106780
	C	10106790
295	305 CONTINUE	10106800
	NPP=N	10106810
	IA=IA+1	10106820
	IF(IA.GT.25)GO TO 365	10106830
	SAREAS(IA)=ABS(AREA)	10106840
	NAREAS(IA)=NPP	10106850
300	PPRM(M1,1)=-999.	10106860
	PPRM(IV,1)=-999.	10106870
	IF(IUGG(2).LT.4)GO TO 358	10106880
	WRITE(6,361)NSEG,(PPRM(N,M),M=1,2),N=1,NSEG)	10106890
305	WRITE(6,361)NPP,(PPRP(N,M),M=1,2),N=1,NPP)	10106900
	FIND NEXT AREA (IF ANY)	10106910
	C	10106920
	C	10106930
	358 DO 359 N1=3,NSEG,2	10106940
	IF(PPRM(M1,1).GT.-900.)GO TO 305	10106950
	359 CONTINUE	10106960
310	C	10106970
	IF(IUGG(2).GT.1)WRITE(6,357)(M,SAREAS(M),NAREAS(M),M=1,IA)	10106980
	357 FORMAT(/>X3HNO.,5X4HAREA,5X7HPOINTER/(17,F12.4,I8))	10106990
	C	10107000
	C	10107010
315	C	10107020
	SUM AREA	10107030
	DO 364 N=1,IA	10107040
	AREA=SAREAS(N)	10107050
	IF(IA.EQ.1)GO TO 364	10107060
	M1=NAREAS(N)	10107070
320	DO 360 M=1,2	10107080
	360 PP(M)=(PPRP(M1,M)+PPRP(M1-1,M))/2.	10107090
	361 FORMAT(/>HOPERIM,I5/(6(2F8.4,4X)))	10107100
	DO 362 A=1,IA	10107110
	IF(M.EQ.N)GO TO 362	10107120
325	CALL COVER(-M,PP,PPRP,99)	10107130
	IF(ITYPE.NE.0)GO TO 363	10107140
	362 CONTINUE	10107150
	GO TO 304	10107160
330	C	10107170
	COVERED	10107180
	363 AREA=-AREA	10107190

SUBROUTINE ARCH3

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	364	SUM=SUM+AREA	10107170
	C		10107180
	C	AREA	10107190
335	C	AREA=.5*SUM	10107200
	C		10107210
		IF (IBUG(2).GT.0) WRITE(6,361) NPP, ((PPR(N,N), N=1,2), N=1, NPP)	10107220
		RETURN	10107230
	365	AREA=-1.	10107240
340		IF (IBUG(2).LE.1) RETURN	10107250
		WRITE(6,361) N, ((PPR(N2,N), N=1,2), N2=1, N)	10107260
		WRITE(6,366) M1, N1, IV, NPP, IA, (PPR(IV, N2), PPR(N1, N2), N2=1,2)	10107270
	366	FORMAT(5I10,4F15.0)	10107280
		RETURN	10107290
345	375	AREA= ADS(72)-2.	10107300
		RETURN	10107310
		END	10107320
			10107340

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SUBROUTINE INTER                                10107350
COMMON COEF(300,4)
* LFCE(331),JFCE(1800),PVRT(600,2),PVXYZ(600,3),JEDGE(900,5),
5 * PINT(1200,4),PEYE(3),NMBI(900)
* IOBJ(10),INOBJ(15),LFCI(300)
COMMON /INPT/J,NE,LL,L,NI,NP,NOBJ,IM                                10107410
COMMON/JEBUGS/IBUG(4)                                              10107420
COMMON /ANSW/ITYPE,ICR,ICL,TYP                                    10107430
C                                                                    10107440
C                                                                    10107450
C J = NUMBER OF POINTS                                           10107460
C NE = NUMBER OF EDGES                                           10107470
C LL = NUMBER OF FACES                                           10107480
C L = LENGTH OF JFCE TABLE                                       10107490
C NI = NUMBER OF INTERSECTIONS                                    10107500
15 C                                                                    10107510
C PINT(NI,1) = EDGE NUMBER I                                       10107520
C PINT(NI,2) = EDGE NUMBER K                                       10107530
C PINT(NI,3) = X INTERSECT                                       10107540
C PINT(NI,4) = Y INTERSECT                                       10107550
20 C                                                                    10107560
C NMBI(I) = NUMBER OF INTERSECTIONS ON EDGE I                    10107570
C                                                                    10107580
C IF (IBUG(4).GT.0)WRITE(6,20)                                     10107590
25 C FORMAT(/5X1HX7X1HY6X3HX15X3HY[15X3HX125X3HY125X3HSL15X3HXK15X
* 3HYK15X3HXK25X3HYK25X3HSLK4X3HIGG3X1HI4X1HK4X1HN)            10107600
C NI=0                                                            10107610
C DO 35 I=1,NE                                                    10107620
30 C NMBI(I)=0                                                    10107630
C                                                                    10107640
35 C DO 90 I=2,NE                                                  10107650
C LI1=JEDGE(I,1)                                                  10107660
C LI2=JEDGE(I,2)                                                  10107670
C XI1=PVRT(LI1,1)                                                 10107680
C XI2=PVRT(LI2,1)                                                 10107690
35 C YI1=PVRT(LI1,2)                                              10107700
C YI2=PVRT(LI2,2)                                                 10107710
C DXI=XI2-XI1                                                      10107720
C IF (DXI.NE.0.)SLI=(YI2-YI1)/DXI                                  10107730
C XMINI=AMIN1(XI1,XI2)                                             10107740
40 C XMAXI=AMAX1(XI1,XI2)                                          10107750
C YMINI=AMIN1(YI1,YI2)                                             10107760
C YMAXI=AMAX1(YI1,YI2)                                             10107770
C                                                                    10107780
C I1=I-1                                                            10107790
45 C                                                                    10107800
C FIND INTERSECTIONS WITH EDGE I                                  10107810
C DO 80 K=1,I1                                                    10107820
C                                                                    10107830
50 C SEE IF EDGE I IS ON SAME FACE AS EDGE K                      10107840
C SEE IF EDGE I IS ON SAME POINT AS EDGE K                      10107850
C DO 50 M=3,4                                                     10107860
C IF (JEDGE(I,M).EQ.0)GO TO 51                                    10107870
C DO 50 M=3,4                                                     10107880
55 C IF (JEDGE(I,M).EQ.2,JEDGE(K,M))GO TO 80                      10107890
C IF (JEDGE(I,M-2).EQ.JEDGE(K,M-2))GO TO 80                    10107900

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	50 CONTINUE	10107910
C	NO	10107920
C	GET VERTICES	10107930
60	51 LK1=JEDGE(K,1)	10107940
	LK2=JEDGE(K,2)	10107950
C		10107960
	KK1=PVRT(LK1,1)	10107970
	KK2=PVRT(LK2,1)	10107980
C	CHECK RANGE OF X	10107990
65	XMK=AMAX1(XK1, XK2)	10108000
	IF(XMIN1.GT.XMK)GO TO 80	10108010
	XNK=AMIN1(XK1, XK2)	10108020
	IF(XMAX1.LT.XNK)GO TO 80	10108030
C		10108040
70	YK1=PVRT(LK1,2)	10108050
	YK2=PVRT(LK2,2)	10108060
C	CHECK RANGE OF Y	10108070
	YMK=AMAX1(YK1, YK2)	10108080
	IF(YMIN1.GT.YMK)GO TO 80	10108090
75	YNK=AMIN1(YK1, YK2)	10108100
	IF(YMAX1.LT.YNK)GO TO 80	10108110
C		10108120
C	CHECK FOR COMMON END POINT	10108130
80	ADY=ABS(XMK-XMAX1)-.00001	10108140
	ADY=ABS(YMK-YMAX1)-.00001	10108150
	IF(ADX.LE.0..AND.ADY.LE.0.)GO TO 80	10108160
	ADX=ABS(XNK-XMIN1)-.00001	10108170
	ADY=ABS(YNK-YMIN1)-.00001	10108180
85	IF(ADX.LE.0..AND.ADY.LE.0.)GO TO 80	10108190
C		10108200
C	FIND INTERSECTION	10108210
C		10108220
	DXK=XK2-XK1	10108230
90	ADX1=ABS(DX1)-.0001	10108240
	ADXK=ABS(DXK)-.0001	10108250
	IF(ADX1.LE.0.)IF(ADXK)80,80,65	10108260
	IF(ADXK.LE.0.)GO TO 70	10108270
C		10108280
95	SLK=(YK2-YK1)/DXK	10108290
	IF(SLI.EQ.SLK)GO TO 80	10108300
C	IGG=1 - NEITHER VERTICAL	10108310
C	2 - I LINE IS VERTICAL	10108320
C	3 - K LINE IS VERTICAL	10108330
100	IGG=1	10108340
C	X	10108350
	X=(Y11-YK1-SLI*X11+SLK*XK1)/(SLK-SLI)	10108360
C	IS X ON BOTH LINES	10108370
105	56 IF((X-X11)*(X-X12).GT.0.)GO TO 80	10108380
	Y=SLI*(X-X11)+Y11	10108390
	IF(IGG.EQ.3)IF((Y-YK1)*(Y-YK2))80,80,80	10108400
C		10108410
	57 IF((X-XK1)*(X-XK2).GT.0.)GO TO 80	10108420
C	YES - SAVE POINT	10108430
110	58 NI=NI+1	10108440
		10108450

		PINT(NI,1)X1	10100660
		PINT(NI,2)X4	10100670
		PINT(NI,3)X4	10100680
		PINT(NI,4)X4	10100690
10		NM1(I1)NM2(I1)+1	10100500
		NM2(I1)NM2(I1)+1	10100510
		GO TO 71	10100520
	C		10100530
	65	X=X1	10100540
		Y=Y2	10100550
		SLA=(Y2-YK1)/DK	10100560
		YSLA*(Z-XK1)+YK1	10100570
		IF(Y-Y11)*(Y-Y12)157,57,60	10100580
			10100590
125		70 X=X1	10100600
		Y=Y3	10100610
		GO TO 53	10100620
			10100630
	C		10100640
	79	CONTINUE	10100650
		IF (IBUGIN).GT.0)	10100660
130		WRITE(1,1)X,PINT(NI,4),X1,Y11,X12,Y12,SL1,XK1,YK1,XK2,YK2,SLK,	10100670
		• IGG,1,K,NI	10100680
		81 FORMAT(12F9.2,-15)	10100690
			10100700
135		80 CONTINUE	10100710
		90 CONTINUE	10100720
		RETURN	10100730
		END	10100730

	SUBROUTINE ROTAT3(X,Y,Z,M,X2,Y2,Z2,A)	1010070
	DIMENSION K(1),Y(1),Z(1),A(3)	1010075
	COMMON/ROT3/COSA(3),SINA(3)	1010080
	DO 10 I=1,3	1010085
5	B=A(I)/57.29578	1010090
	COSA(I)=COS(B)	1010095
	SINA(I)=SIN(B)	1010100
10	T1=COSA(1)*COSA(2)	1010105
	T2=SINA(1)*COSA(3)+COSA(1)*SINA(2)*SINA(3)	1010110
10	T3=SINA(1)*SINA(3)-COSA(1)*SINA(2)*COSA(3)	1010115
	T12=-SINA(1)*COSA(2)	1010120
	T22=COSA(1)*COSA(3)-SINA(1)*SINA(2)*SINA(3)	1010125
	T32=COSA(1)*SINA(3)+SINA(1)*SINA(2)*COSA(3)	1010130
15	T13=SINA(2)	1010135
	T23=-COSA(2)*SINA(3)	1010140
	T33=COSA(2)*COSA(3)	1010145
	DO 20 I=1,M	1010150
	X1=X(I)-XZ	1010155
20	Y1=Y(I)-YZ	1010160
	Z1=Z(I)-ZZ	1010165
	K(I)=X1*T1+Y1*T12+Z1*T13+XZ	1010170
	Y(I)=X1*T21+Y1*T22+Z1*T23+YZ	1010175
25	Z(I)=X1*T31+Y1*T32+Z1*T33+ZZ	1010180
	CONTINUE	1010185
	RETURN	1010190
	END	1010195

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SUBROUTINE FACES(IFP,N)                                10109000
DEVELOPE TABLES FOR FACE L CONSISTING OF THE N POINTS INDICATED BY 10109010
IFP                                                    10109020
COMMON COEF(1304,4)
*LFGE(1311),JFGE(1800),PVRT(600,2),PVXYZ(600,3),JEDGE(900,5),
*PNT(1230,4),PEYE(3),NMBI(900)
*IDBJ(10),INQBJ(15),LFCI(300)
COMMON /INPTT/J,NE,LL,L,NI,NP,NOBJ,IM                10109000
COMMON /JEBUGS/JBUG(4)                               10109100
COMMON /NGE/PH(13),PMN(3),IJID,JID                 10109110
COMMON /TEMPY/JFDET(1800),IPNT(100)
DIMENSION IC(3),CF(2,3),IFP(1)
IF(IJID.EQ.1234)GO TO 10
INITIALIZE
IJID=1234
K=FACE POINTER
K=1
NE=NUMBER OF EDGES
N=0
L=FACE NUMBER
LL=0
IF(NE.EQ.0)WRITE(6,136)
136 FORMAT(1J0H '***** COEFFICIENT MATRIX *****'
1***** I A C E EQUATIONS *****)
10 LL=LL+1
LFCI(LL)=K
NBJ=OBJECT NUMBER
LFCI(LL)=NBJ
DO 15 I=1,N
L=K+I-1
JFGE(L)=IFP(I)
15 JFGE(L)=IFP(I)
JEDGE(1,J)=EDGE I , J=1,5
1 - POINT ON EDGE
2 - POINT ON EDGE
3 - FACE ON EDGE
4 - FACE ON EDGE
5 - PSEUDO EDGE FLAG
JFGE(LL)=JFGE(K)
JD 40 M=K,L
POINT NUMBERS OF EDGE
IF(JFGE(M).GT.J)STOP 1234
IF(NE.EQ.0)GO TO 35
HAS EDGE BEEN COUNTED
JJ 35 I1=1,NE
JJ 32 I2=1,2
IJ=JFGE(I1+I2-1)
JJ 31 I3=1,2
IF(IJ.EQ.JEDGE(I1,I3))GO TO 32
31 CONTINUE

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      GO TO 33
32 CONTINUE
      GO TO 36
33 CONTINUE
60      C
      C      NEW EDGE TO ADD TO LIST
      IF (ME.GT.099) STOP 4444
35      ME=ME+1
      JEDGE(ME,1)=JFCE(M)
65      JEDGE(ME,2)=JFCE(M+1)
      JEDGE(ME,3)=LL
      JEDGE(ME,4)=0
      JEDGE(ME,5)=0
      JFCE(M)=ME
70      GO TO 43
      C
      C
36 CONTINUE
      IF (LL.EQ.JEDGE(I1,3)) JEDGE(I1,5)=1
75      JEDGE(I1,4)=LL
      JFCE(M)=I1
40 CONTINUE
      C
      C      FIND COEFFICIENTS OF FACE
80      C
      IC3=IFP(3)
      DO 60 I=1,2
      IC12=IFP(I)
      DO 60 M=1,3
85      C
      C      60 CF(I,M)=PVXYZ(IC3,M)-PVXYZ(IC12,M)
      COEF(LL,1)=CF(1,2)*CF(2,3)-CF(1,3)*CF(2,2)
      COEF(LL,2)=CF(1,3)*CF(2,1)-CF(1,1)*CF(2,3)
      COEF(LL,3)=CF(1,1)*CF(2,2)-CF(1,2)*CF(2,1)
      COEF(LL,4)=0
90      DO 70 I=1,3
      C
      C      70 COEF(LL,4)=COEF(LL,4)-COEF(LL,I)*PVXYZ(IC3,I)
      IF (IMAG(3).GT.0) WRITE(6,7) CF.(COEF(LL,I),I=1,4), LL
95      C
      C      71 FORMAT(10F10.2,15)
      IF (N.EQ.3) GO TO 90
      C
      C      CHECK EACH POINT ON FACE FOR COPLANARITY
      DO 80 KL=4,N
      IP4=IFP(KL)
      T1=COEF(LL,4)
100      DO 75 M=1,3
      C
      C      75 T1=T1+COEF(LL,M)*PVXYZ(IP4,M)
      IF (ABS(T1).LT.005) GO TO 80
      WRITE(6,7) LL, IP4, T1
105      C
      C      77 FORMAT(15H ERROR IN PLANE, I3,7M, POINT, I4, F10.4)
      80 CONTINUE
      C
      C
110      90 K=L+1
      LFCE(LL+1)=K
      RETURN
      END

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10109580
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		SUBROUTINE COVER(IF,PC,PVRT,JJ)	10110130
		DIMENSION PC(1),PVRT(JJ,2)	10110130
		COMMON COEF(300,4)	
5		*,LFCE(1331),JFCE(1400),OU4Y(600,2),PVXYZ(600,3),JEDGE(900,5),	
		*PIHT(1230,4),PEYE(3),NMBI(900)	
		*,IOBJ(10),INOBJ(15),LFCE(1300)	
		COMMON/JEBUGS/ISUG(4)	10110200
		COMMON /ANSW/ITYPE,ICR,ICL,TYP	10110210
		COMMON/AR/SAREAS(25),NAREAS(25)	10110220
10	C		10110230
		CHECK TO SEE IF FACE (IF) COVERS POINT (PC)	10110240
		IF.LT.0 INDICATES PROJECTION -IF RATHER THAN FACE	10110250
		ITYPE = 0 - NOT COVERED	10110260
15		= 1 - ON VERTEX	10110270
		= 2 - ON EDGE	10110280
		= 3 - COVERED	10110290
			10110300
		IF(IF.GT.0)GO TO 10	10110310
		LF=1	10110320
20		IF(IF.LT.-1)LF=NAREAS(-IF-1)+1	10110330
		LSTV=NAREAS(-IF)-1	10110340
		GO TO 15	10110350
	C		10110360
25		10 LF=LFCE(IF)	10110370
		LSTV=LFCE(IF+1)-1	10110380
	C		10110390
	C	LF = POINTER TO FACE	10110400
	C		10110410
30		15 PX=PC(1)	10110420
		PY=PC(2)	10110430
	C		10110440
	C	PX,PY = POINT COORDINATES	10110450
	C		10110460
	C	ICR , ICL -- NUMBER OF LINES TO RIGHT , LEFT OF POINT	10110470
35		ICR=0	10110480
		ICL=0	10110490
	C		10110500
	C		10110510
40		DO 100 I=LF,LSTV	10110520
		IVFE=JFCE(I)	10110530
		IF(I.EQ.LF)GO TO 25	10110540
	C	NEW VALJES	10110550
		IV=1+IVF2	10110560
45		IX=OAN	10110570
		OY=DYN	10110580
		IVF2=IVF1+1	10110590
		GO TO 43	10110600
	C		10110610
50		25 IF(IF.GT.0)GO TO 30	10110620
		IVF1=LF	10110630
		IVF2=LF+1	10110640
		GO TO 33	10110650
	C		10110660
55		30 IVF1=JEDGE(IVFE,1)	10110670
		IVFN=JFCE(LF+1)	10110680

```

      IF (IVF1.EQ.JEDGE(IVFN,1).OR.IVF1.EQ.JEDGE(IVFN,2)) IVF1=JEDGE(IVFE,10110600
      * 2) 10110700
35  DX=PX-PVRT(IVF1,1) 10110710
      DY=PY-PVRT(IVF1,2) 10110720
80  C  SEE IF JN VERTEX 10110730
      IF (DX.EQ.0.) IF (DY) 40,200,40 10110740
      C  NO 10110750
      C  10110760
85  40  IF (IF.LT.0) GO TO 42 10110770
      IVF2=JEDGE(IVFE,2) 10110780
      IF (IVF2.EQ.IVF1) IVF2=JEDGE(IVFE,1) 10110790
      42  DX=PX-PVRT(IVF2,1) 10110800
      DY=PY-PVRT(IVF2,2) 10110810
70  C  SEE IF JN VERTEX 10110820
      IF (DX.EQ.0.) IF (DY) 45,200,45 10110830
      C  10110840
      C  SEE IF HORIZONTAL EDGE 10110850
      45  IF (PVRT(IVF1,2).EQ.PVRT(IVF2,2)) IF (DY) 100,140,100 10110860
      C  NO 10110870
75  C  SEE IF HORIZONTAL LINE THRU P INTERSECTS EDGE 10110880
      IF (DYM*JY) 50,40,100 10110890
      C  INTERSECTS VERTEX - COUNT OR NOT 10110900
      40  IF (DYM*GT.0. .OR.DY*GT.0.) GO TO 100 10110910
      C  YES 10110920
80  C  SLOPE OF EDGE (Y AXIS) 10110930
      50  SL= PVRT(IVF2,1)-PVRT(IVF1,1) 10110940
      SL=SL/(PVRT(IVF2,2)-PVRT(IVF1,2)) 10110950
      C  DELTA X TO EDGE 10110960
      DXL=SL*JY-DX 10110970
85  C  SEE IF JN EDGE 10110980
      C  JR IF CROSSES LEFT OR RIGHT OF POINT 10110990
      C  10111000
      IF (DXL) 77,100,99 10111010
      77  ICL=ICL+1 10111020
      GO TO 100 10111030
      79  ICM=ICR+1 10111040
      100 CONTINUE 10111050
      C  10111060
      C  10111070
95  C  EVEN MEANS NOT COVERED 10111080
      IF (2*(ICR/2).EQ.ICR) GO TO 150 10111090
      ITYPE=3 10111100
      RETURN 10111110
      C  10111120
100  C  SEE IF JN ON OFF HORIZONTAL EDGE 10111130
      140  IF (DX*DYN) 130,200,100 10111140
      C  10111150
      150  ITYPE=0 10111160
      RETURN 10111170
105  C  10111180
      200  ITYPE=1 10111190
      RETURN 10112200
      C  10112210
110  300  ITYPE=2 10112220
      RETURN 10112230
      END 10112240

```

```

SUBROUTINE SORTM(X1,X2,TAB1 ,TAB2 ,I,IMAX)      10111250
DIMENSION TAB1(I),TAB2(I)                      10111260
IF(I.EQ.0) GO TO J3                            10111270
IX=MIN0(IMAX,I)                                10111280
DO 30 J1=1,IX                                   10111290
  J=IX+1-J1                                     10111300
  IF(X1-TAB1(J))25,20,34                        10111310
20 IF(X2-TAB2(J))25,34,34                       10111320
25 TAB1(J+1)=TAB1(J)                            10111330
  TAB2(J+1)=TAB2(J)                             10111340
30 CONTINUE                                     10111350
J3 J=0                                          10111360
34 TAB1(J+1)=X1                                  10111370
  TAB2(J+1)=X2                                  10111380
  I=I+1                                         10111390
RETURN                                          10111400
END                                             10111410
```

SUBROUTINE PLOTDD

CDC 6600 FTN V3.0-P286 OPT=1 06/05/72 12.96.66. PAGE 1

	SUBROUTINE PLOTDD(X,Y,I)	
	COMMON/RAST/N80	10111420
	JATA XP,YP,IP/0.,0.,0/	
	IF(I.NE.2)GO TO 10	10111430
5	IF(X.EQ.XP.AND.Y.EQ.YP)RETURN	10111440
	IX1=N80*XP+.5	10111450
	IY1=N80*YP+.5	10111460
	IX2=N80*X+.5	
	IY2=N80*Y+.5	
10	CALL LINEV(IX1,IY1,IX2,IY2)	
	IP=0	10111470
	GO TO 15	10111480
10	IP=1	10111490
15	XP=X	10111900
	YP=Y	10111910
	RETURN	10111920
	END	10111930
		10111940

SUBROUTINE PLOTCC

CDC 6600 FTH V3.0-P284 OPT=1 04/05/72 12.54.44.

PAGE 1

```
      SUBROUTINE PLOTCC(X,Y,IP)
      IF(IP.LT.0)GO TO 10
      RETURN
10    CALL FRAMEV(0)
      RETURN
      END
```

5

```

SUBROUTINE DASHLN(XI,YI,XP,YF,DI)
REAL LENGTH
DIMENSION XI(1),YI(1)
C THIS DEFINES NORMAL INTERVAL
5 DATA APROX1,XMULT1/.0625,15./
C INITIALIZE FOR PEN 1
  IPENS=2
  XMULT=XMULT1
  APROX=APROX1
10 XORG=3.0
C MOVE TO THE INITIAL POINT WITH PEN UP
  69 CALL PL3YD(XI(1)+XORG,YI(1),3)
C INITIALIZE FINAL POINT OF FIRST LINE
  XBAR=XF
15 YBAR=YF
C TEST FOR TYPE OF LINE
  IF(DI)1,2,3
C SOLID LINES PROCESSOR
  1 XBAR=XI(2)
  YBAR=YI(2)
20 C SOLID LINE PROCESSOR
  2 LINES = ABS(DI+1.)
  DO 200 L=1,LINES
  CALL PLOTDD(XBAR,YBAR,2)
  XBAR=XI(L+2)
25 200 YBAR=YI(L+2)
  RETURN
C DASH LINE PROCESSOR
  3 M=3
30 C TEST FOR NUMBER AND TYPE OF DASHED LINES
  IF(DI-1.) 4,5,6
C DASHED LINE, 1 TO 1 RATIO
  4 M=4
35 C DASHED LINE 2 TO 1 RATIO
  5 LINES=1
  GO TO 50
C DASHED LINE 2 TO 1 RATIO
  6 XBAR=XI(2)
  YBAR=YI(2)
40 LINES = DI-1.
C BEGIN PLOTTING LINES
  50 DO 7 L=1,LINES
C COMPUTE LENGTH OF LINE TO BE PLOTTED
  DELTAX = XBAR-XI(L)
  DELTAY = YBAR-YI(L)
45 LENGTH = SQRT(DELTAX ** 2 + DELTAY ** 2 )
C TEST FOR MINIMUM POSSIBLE DASHED LINE
  1000 IF(LENGTH.GE.FLOAT(M*2)*APROX) GO TO 13
  APROX = APROX/2.
  XMULT=(XMULT*1.)*2. +1.
50 GO TO 1000
C SET UP TO DRAW SOLID LINE
  9999 CONTINUE
  X=XBAR
55 Y=YBAR

```

```
      CALL PLJTD0(X,Y,2)
      GO TO 14
C COMPUTE APPROXIMATE NUMBER OF EQUAL INTERVALS
13 NUM = LENGTH * XMULT
58 C TEST FOR START AND STOP WITH DASH
      5 IF(MOD(NUM-2,M).EQ.0) GO TO 9
      NUM=NUM+1
      GO TO 8
65 C REFINE BASIC INTERVAL LENGTH
      9 XNUM=NUM
      DX=DELTA X/XNUM
      DY=DELTA Y/XNUM
C INITIALIZE FIRST END POINT
73 X=XI(L)
      Y=YI(L)
C INITIALIZE RATIO COUNTER
      DD 12 I=1,NJM
C PLOT LOOP, COMPUTE TERMINAL POINT
75 X=X+DX
      Y=Y+DY
C LOWER PEN
      IPEN=IPENS
C TEST TO RAISE PEN
      J=I
80 IF(M.EQ.3) GO TO 11
C EQUAL RATIO
      IF(MOD(J,M).NE.0) J=J+1
11 IF(MOD(J,M).EQ.0) IPEN=3
      XORG=0.
55 C PLOT THE LINE
      CALL PLJTD0(X+XORG,Y,IPEN)
C INCREMENT RATIO COUNTER
12 CONTINUE
C TEST FOR END OF LINE
90 14 XBAR=XI(L+2)
      7 YBAR=YI(L+2)
      RETURN
      END
```

```

SUBROUTINE INIT30(XPAG,YPAG,XO,YO,ZO,XM,XMAX,YM,YMAX,ZMIN,ZMAX)
COMMON/PARAM/XL,YL,XMIN,YMIN,TOIS,DIS,QX,QY,QZ,COSA,COSB,COSC,
1  OX,OY,OZ,SINC,PX,PY,IQUAD,DUM,XLEN,YLEN
DIMENSION XX(2),YY(2),ZZ(2)
5  ISM = 0
   OX=XO
   OY=YO
   OZ=ZO
10  XMIN=XM
   YMIN=YM
   XX(1) = XMIN
   XX(2) = XMAX
   YY(1) = YMIN
   YY(2) = YMAX
15  ZZ(1) = ZMIN
   ZZ(2) = ZMAX
   PX = XMIN+.5*(XMAX-XMIN)
   PY = YMIN+.5*(YMAX-YMIN)
   PZ = ZMIN+.5*(ZMAX-ZMIN)
20  DIS = SJRT((PX-OX)**2+(PY-OY)**2+(PZ-OZ)**2)
   COSA = (PX-OX)/DIS
   COSB = (PY-OY)/DIS
   COSC = (PZ-OZ)/DIS
   SINC = SJRT(1.-COSC**2)
25  TOIS = DIS/2.
   IF(XPAG.GT.0.)GO TO 23
   TOIS=-XPAG*DIS
   ISM=1
23  XL = 10000.
   YL = 10000.
30  XM = -10000.
   YM = -10000.
   QX = OX + TOIS*COSA
   QY = OY + TOIS*COSB
35  QZ = OZ + TOIS*COSC
   DO 1 I = 1,2
   X = XX(I)
   DO 1 J = 1,2
   Y = YY(J)
40  DO 1 K = 1,2
   Z = ZZ(K)
   FK = TOIS/((X-OX)*COSA + (Y-OY)*COSB + (Z-OZ)*COSC)
   FL = OX + FK*(X-OX)
   FN = OY + FK*(Y-OY)
45  FO = OZ + FK*(Z-OZ)
   XP = ((FL-QX)*COSB - (FN-QY)*COSA)/SINC
   YP = (FN-QZ)/SINC
   IF (XP.LT.XL) XL=XP
   IF (XP.GT.XM) XM=XP
50  IF (YP.LT.YL) YL=YP
   IF (YP.GT.YM) YM=YP
1  CONTINUE
   IF (ISM.EQ.1) GO TO 24
C
C  ADJUST POIS SO THAT PLOT FILLS DESIRED AREA
55

```

```
      C
      XLL = XM - XL
      YLL = YM - YL
      RATIO = XLL/XPAG
60      TYLL = YLL/RATIO
      IF (TYLL.GT.YPAG) RATIO=YLL/YPAG
      YDIS = YDIS/RATIO
      ISW = 1
      GO TO 23
65      C
      C
      24 XL=XL
      YL=YL
      XLEN = XMAX-XMIN
      YLEN = YMAX-YMIN
      IQUAD=0
      IF (IX.GE.XMAX) IQUAD=IQUAD+2
      IF (IY.GE.YMAX) IQUAD=IQUAD+1
      RETURN
75      END
```

CDC SUBROUTINE PLOTXYZ(X,Y,Z,IPEN)
SUBROUTINE PLTXYZ(X,Y,Z,IPEN)
CALL XFORM(X,Y,Z,PX,PY)
CALL PLOTCC(PX,PY,IPEN)
RETURN
END

5

```
      SUBROUTINE XFORM(X,Y,Z,DX,DY)
      COMMON/PAHAM/XL,YL,XMIN,YMIN,TDIS,DIS,OX,OY,OZ,COSA,COSB,COSC,
1     DX, OY, OZ, SINC, PX, PY, IQUAD, DUM, XLEN, YLEN
      FK = TDIS/(IX-OX)*COSA + (Y-OY)*COSB + (Z - OZ)*COSC
      FL = OX + FK*(X-OX)
      FN = OY + FK*(Y-OY)
      FM = OZ + FK*(Z - OZ)
      DX = (IFL-DXI)*COSB - (FM-OY)*COSA/SINC + XL
      DY = (FN-OZ)/SINC + YL
      RETURN
      END
```

10

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<p>This program provided the Air Force an existing target description computer program which was demonstrated on the Eglin Air Force Base CDC 6600 computer by completing two check runs. The subsequent formulation, coding, and incorporation of two improvements in the program which provided a shielding capability and the input of standard geometrical shapes resulted in a modified program being adopted for use with the Eglin Air Force Base computer. The revised program was demonstrated by computing the presented area of the fuel tanks of a generic fighter aircraft, and making perspective plots of the target with hidden lines removed, using the SC4020 plotter. This target description and vulnerability program also provides the Air Force with a unique tool for making rapid descriptive and vulnerability assessments of targets through the use of high speed computers and automatic plotting equipment.</p>			

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