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# Evaluation Framework for Input Layer Preprocessing in a Radial Basis Function Neural Network

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## **ABSTRACT**

The need for immediate situational awareness updates in a military environment can be partially mitigated by employing machine learning (ML) at the edge of the network, where the warfighter operates. Technical challenges for edge computing, like limited power and data, require unique hardware and software implementations for viable solutions. Low power neuromorphic processors running radial basis function artificial neural networks (RBFNN) makes ML at the edge more practical but can introduce limitations in the data throughput. This power and data limitation can be moderated using preprocessing of the input space to magnify the most pertinent data features. This paper presents a framework for evaluating different input space paradigms in a systematic manner. Using a representative small dataset for a pyroshock event, common in the military environment, several input preprocessing paradigms are evaluated.

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# 1 INTRODUCTION

The need for immediate situational awareness updates in a military environment can be partially mitigated by employing machine learning (ML) at the edge of the network, where the warfighter operates. Technical challenges for edge computing, like limited power and data, require unique hardware and software implementations for viable solutions [1]. Low power neuromorphic processors running radial basis function artificial neural networks (RBFNN) makes ML at the edge more practical but can introduce limitations in the data throughput [2, 3, 4, 5]. This power and data limitation can be moderated using pre-processing of the input space that can magnify the most pertinent features.

Architecture development for artificial neural networks (ANN) used for classification often assumes a raw input dataset to maximize the potential learning of the ANN [6, 7, 8]. This approach leads to an ever increasing need for network complexity from added neurons and layers. When employing these algorithms in an edge computing environment, this complexity and resulting data and power consumption can be prohibitive [9]. The RBFNN using a restricted Coulomb energy (RCE) learning method can classify input data in a low power environment by minimizing the number of active neurons [2, 5, 4].

To increase the practical implementation of an RBF for time or image based signals, they are often sent preprocessed data using fast Fourier transform (FFT), wavelets, or other data reduction methods [10, 2, 11, 12, 13, 14]. Time based signals generated from pyroshock events similar to those found in a mining or military environment tend to use frequency transforms like wavelets or the FFT [7]. Often the preprocessing algorithms are chosen through trial and error with the classification accuracy used as the performance metric [8]. The training process for an RCE involves adjusting neuron weights as well as sequentially activating additional neurons to recognize each class as the definition is refined by the training dataset [15, 16]. RCE neuron weights and activations depend on the order and composition of the input data training set [17].

While it is well known that an RBFNN using RCE learning can approximate a function smoothly, the number of committed neurons is not an in-line metric [15, 18, 5]. Generally, attention is focused on the RBFNN learning method [19, 20, 4, 21, 22] or on integration into a deeper network [14]. While preprocessing methods are often critical to the research, it is not viewed in the context of committed neurons [10, 2, 12, 11]. Considering the number of committed neurons relative to the preprocessing method for an RBFNN using RCE learning has been absent from the literature.

This paper proposes a framework for evaluating preprocessing methods to an RBFNN input layer based on the committed neuron count using a simulation of the NM500 neuromorphic chip [1]. The correlation coefficient between the number of committed neurons and the inference accuracy has a highly correlated  $p$ -value across the entire dataset of  $1 \times 10^{-7}$ . Using representative data for a pyroshock event common in the military environment, several input preprocessing methods were evaluated. By using the ANN structure in evaluating the preprocessing method, the potential computational cost and associated power may be mitigated. This research helps to establish a framework whereby preprocessing methods can be evaluated in real-time, which could serve as a precursor for a broader RBFNN design method.

The remainder of this paper is structured as follows. Section 2 details the data description and ANN structure. Section 3 describes the dataset and the manner in which it was used. Section 4 outlines the specifics of the cross-validation and RBFNN chip simulation. Finally, section 5 presents the results, while section 6 outlines the specific conclusions that can be drawn from

this study.

## 2 METHOD

The source data is from pyroshock testing on a military system. Given the typical high operational costs, the dataset is small. Furthermore, the dataset contains collection artifacts as is also common when dealing with military systems in an unpredictable operating environment. The utilization of the data and structure of the ANN must both be tailored to operate under these limitations. Processing this class of data has broad applicability in both military and commercial systems.

### 2.1 DATASET DESCRIPTION

Pyroshock events generate time based signals in various severe environments found in mining, military, and other systems. These events cause a decaying, oscillatory response due to high amplitude and frequency excitation [23]. There are two classes of labeled data with a third noise class as a counter-example to prevent over-fitting. Typical examples for each class are shown in Figure 2.1a. Traditional rule-based classification methods would be difficult with this amount of overlap between classes shown in Figure 2.1a.

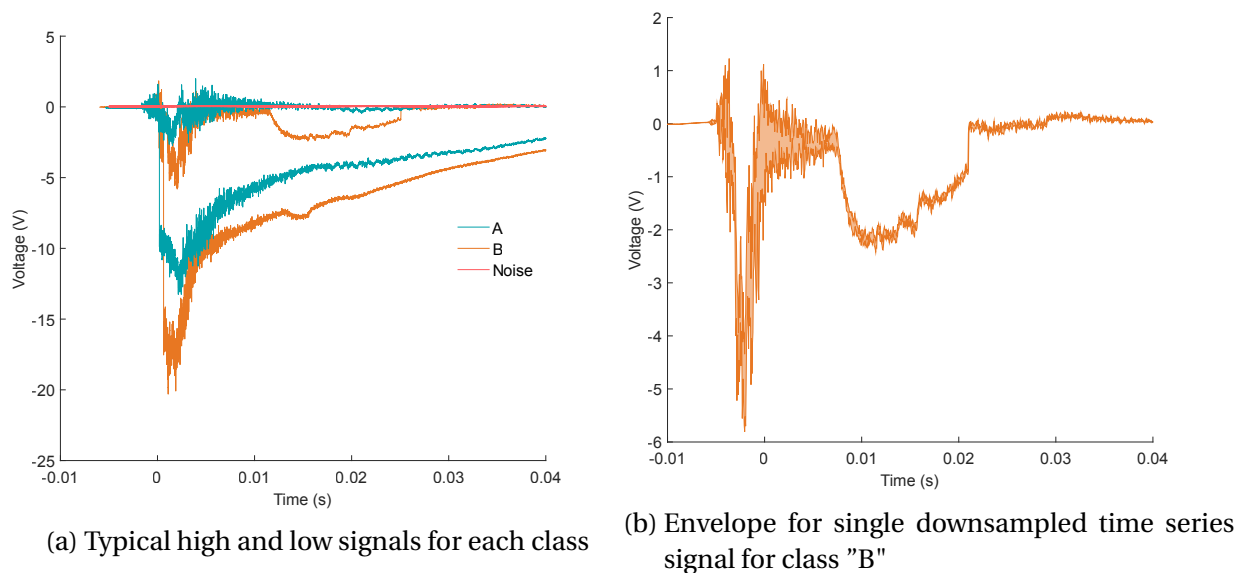


Figure 2.1: Time series data

The noise data files were randomly generated based on the magnitude and frequency content prior to the pyroshock events. Half of the noise examples have a constant 60 Hz sinusoid component. The data rate of the dataset is much higher at 1 MHz than is typically feasible for edge deployed applications. The data was downsampled at a 50:1 ratio and a phase shift of one sample to essentially split each data example into several of the same class and increase the data points for the limited dataset. The envelope defined by a single downsampled example of class "B" is shown in Figure 2.1b, demonstrating the variability introduced by downsampling, especially in the high frequency content portion early in the pyroshock event.

Each set of downsampled examples are treated as a group when placed in either the training or validation sets. All data is the voltage from a single sensor on the same test asset over the course of several days of testing. The allocation for a single training epoch is outlined in Table 2.1.

Table 2.1: Dataset example allocation breakdown for a single epoch

class	Original	50:1 Downsampled	Training	Validation
A	9	450	400	50
B	49	2450	2200	250
Noise	20	1000	900	100
Total	78	3900	3500	400

## 2.2 RBFNN WITH RCE LEARNING

An RBFNN is an artificial neural network with a fully connected input layer, partially connected hidden layer where each hidden layer neuron is connected to only one output layer neuron [24]. Output layer neurons are typically connected to several output hidden layer neurons, as is seen in Figure 2.2. The RBFNN considered in this work uses an RCE learning method to assign the

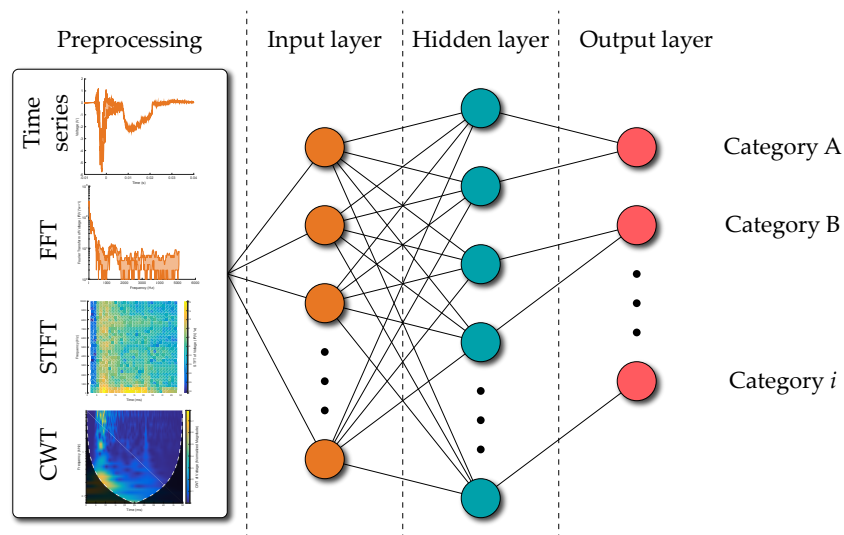


Figure 2.2: RBFNN diagram with representative preprocessing methods

center of each radial basis function referred to as a prototype because it is equal to the scaled input values of the first input vector defining a new area of influence for that class.

The other aspect of the RCE training process is to define the activation distance from a prototype referred to as the active influence field (AIF) [25, 26]. An RBFNN using RCE learning starts with one hidden layer neuron and only adds one neuron at a time during training. The

NM500 architecture has a fixed number of neurons, so when a neuron is added to the RBFNN it is merely committed to using that latest input as the prototype for distance measurements to subsequent inputs. Hidden layer radial basis function neurons are added if the input is outside all AIF radii for the labeled class. If this new neuron conflicts with the AIF radius of another class neuron, that other AIF radius is reduced to deconflict the output layer. The noise class of counter-examples also reduces AIF radii to prevent over generalization.

The RBFNN simulation for the NM500 allows for an input layer of at most 256 neurons for a single ANN context. While the NM500 can use both the  $L_1$  or  $L_\infty$  distance for the distance calculation, this work uses  $L_1$  for training and inference. The distance for a given input,  $i$ , from each committed neuron is,

$$d_i = \sum |w\mathbf{x} - \mathbf{p}_i|, \quad (2.1)$$

where  $w$  scales the input vector  $\mathbf{x}$  and the prototype,  $\mathbf{p}_i$ , is the center of the radial basis function of the  $i^{th}$  hidden layer neuron. The scalar  $w$  is constant and specific to an RBFNN with a preprocessing method.

While there are many possible activation functions like PRelu and Gaussian this RBFNN implementation uses a Step function [27],

$$Activation(d_i) = \begin{cases} 1 & : d_i \leq AIF_i \\ 0 & : d_i > AIF_i \end{cases}. \quad (2.2)$$

The number of neurons that can be committed is limited to the physical number of on-board neuromorphic memory cells in the design. The absolute minimum is the number of labeled example classes input in training and the maximum the total number of examples input during training.

The RBFNN architecture using RCE learning creates a potentially functional inference model in real-time on an objective system without the need for high-power, high-bandwidth off-line training making the RBFNN attractive for edge computing applications. Intrinsic to this architecture is an input dependent increasing number of neurons during training. The number of neurons are determined by both the separation between input classes as well as the neighbor distance within a class. The dependence of neuron growth based on input vector distances is non-linear and order dependent, but still dependent and therefore insightful [27, 5].

### 3 NEURAL NETWORK PREPROCESSING

Often RBFNN architecture definitions focus on methods for AIF determination and activation functions, whereas this work focuses on the input preprocessing [19, 27, 15, 21, 4, 14]. While much attention has been paid to preprocessing methods, it is still worthwhile to consider preprocessing with respect to the number of committed neurons required to classify the input space [10, 2, 12, 14]. Preprocessing the input vector essentially changes the representation and thereby the features within that representation. The purpose is to have features unique to each class be separated by a larger distance while features within a class have a smaller separation.

#### 3.1 TIME SERIES

The time series is raw input voltage with the minimum amount of preprocessing. The data was converted to fixed point to facilitate future hardware implementation. An additional scalar,  $w$ ,

multiplies the signal as part of preprocessing to control the magnitude of the  $L_1$  distance also related to hardware implementation. The envelope for every example in the dataset arranged by class is shown in Figure 3.1. The first 256 data points after a threshold trigger are used as

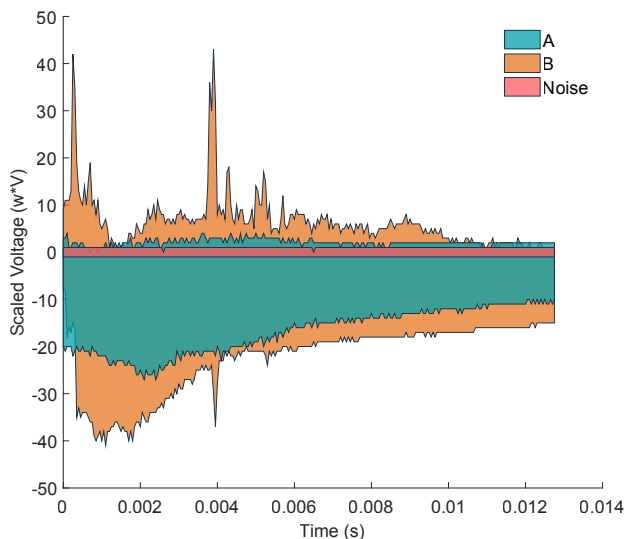


Figure 3.1: Envelope for each class across the entire dataset

the input to the RBFNN. There is a significant amount of overlapping between the envelope of each class. It would be difficult to infer these classes using traditional methods directly based on these time series.

### 3.2 FOURIER TRANSFORM

The FFT represents the input in the frequency domain [28]. This removes all time based information from input and highlights the various frequency components of the pyroshock event. The FFT for the downsampled example in Figure 2.1b is shown in Figure 3.2a. The FFT for a single example in Figure 3.2a shows discretization from the fixed point conversion. To better visually express the fixed point, FFT data in Figure 3.2 is offset by 1 and plotted on a logarithmic scale. While the figure is on the log scale, the RBFNN input is not. As with all the input preprocessing methods, the scalar  $w$  multiplies the input. The envelope for the FFT of every example in the dataset arranged by class is shown in Figure 3.2b. The FFT signals have significant overlap making traditional rules based classification difficult. The first 256 FFT points are used for the RBFNN input.

### 3.3 SPECTROGRAM

The short-time Fourier transform (STFT) combines time and frequency features of the data to produce a spectrogram [29]. This makes any time-separated frequency based data features more prominent. The spectrogram for the downsampled example in Figure 2.1b is shown in Figure 3.3a. Only a subset of the logarithm of the spectrogram data was used for the RBFNN input at one time. The spectrogram input was a set of  $31 \times 8$  contiguous points offset from the

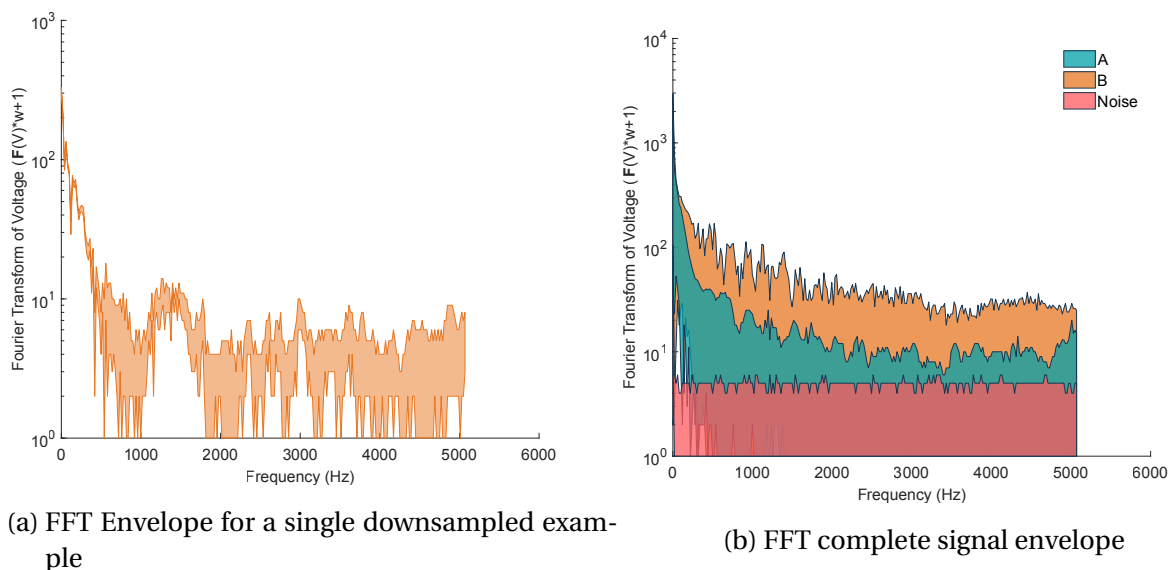


Figure 3.2: FFT data

origin and scaled by  $w$ . The subset of a typical spectrogram used for each class example is shown in Figure 3.3b. For the RBFNN input layer the spectrogram was arranged into a vector.

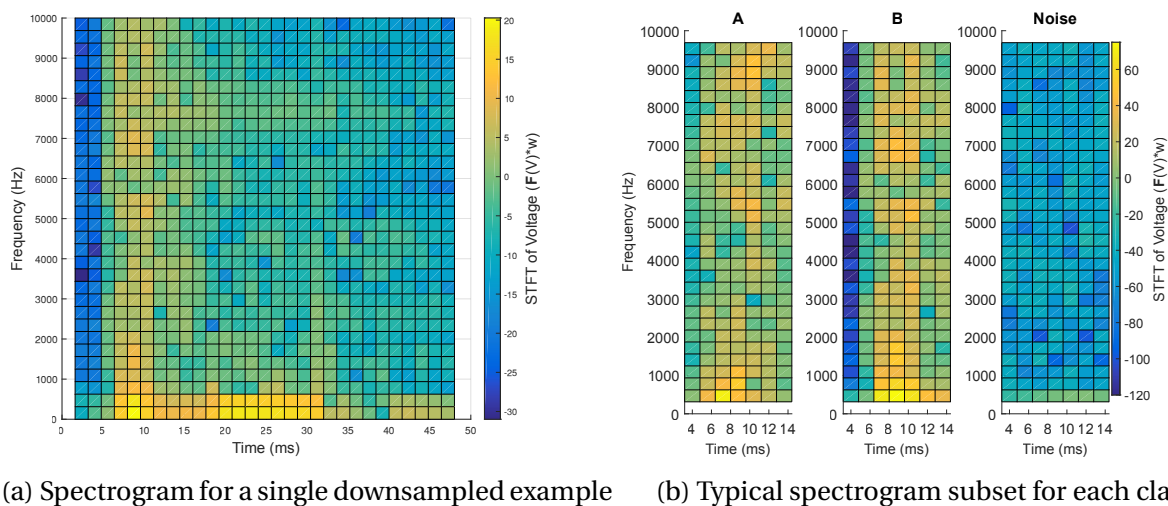


Figure 3.3: Short-time Fourier transform data

### 3.4 SCALOGRAM

The continuous wavelet transform (CWT) in this work used the Morse wavelet with 4 voices per octave to produce a scalogram of the voltage signal. The scalogram for the downsampled example in Figure 2.1b is shown in Figure 3.4a. The CWT uses  $L_1$  normalization by dilating the wavelet so all frequency amplitudes are normalized to the same value [30]. The CWT has a logarithmic frequency distribution. There are many methods to select points from the scalogram to map to the input layer. Input vectors in this work are uniformly distributed and offset from

the scalogram origin to produce an  $18 \times 13$  set of points scaled by  $w$ . The subset of a typical scalogram used for each class example is shown in Figure 3.4b.

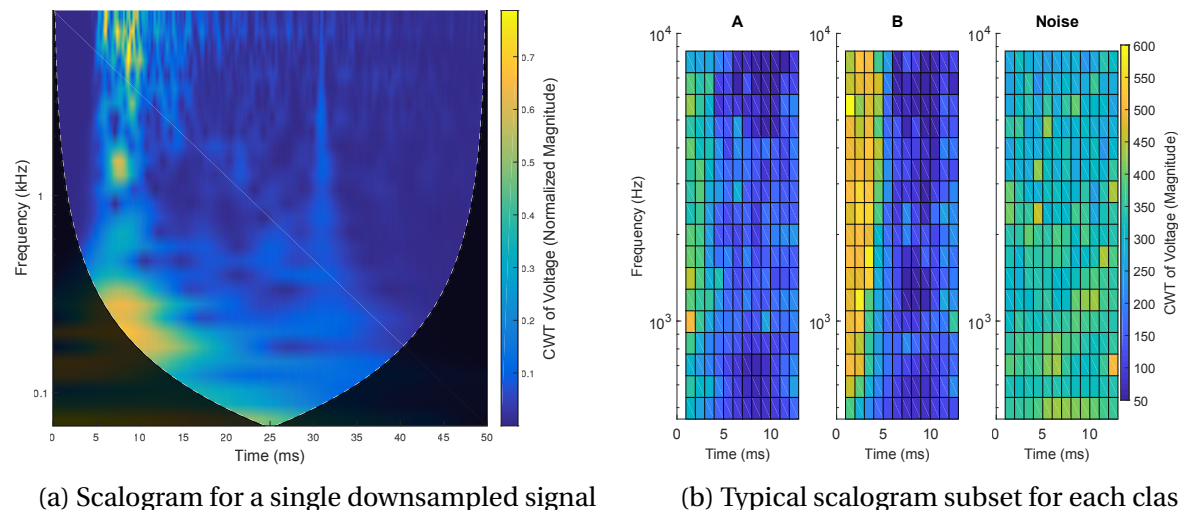


Figure 3.4: Continuous wavelet transform data

## 4 EVALUATION METHODOLOGY

Training and validation was conducted using a simulation of the NM500 neuromorphic chip. Validation data encompassed at least 10% of the data in each class as previously shown in Table 2.1. RCE learning is implemented on the NM500 with a global initial setting for the maximum and minimum AIF radii that determines to what extent the RBFNN will generalize in inference. Each AIF is then reduced as needed during training. Scalar  $w$  was used to maximize the classification accuracy on a subset of the dataset for each preprocessing method. Once found, the scalar  $w$  was constant for a given preprocessing method. This allowed all preprocessing methods to use the same maximum initial neuron AIF.

A non-exhaustive Monte-Carlo cross-validation was used to compare the classification performance of each preprocessing method. The order of the Monte-Carlo training sets was the same for each epoch for every preprocessing method. Since relative performance between methods is of most interest, all four preprocessing methods used the same example ordering during training to allow a reasonable comparison. Each preprocessing method was trained for one epoch before validation. This was to maintain a training methodology that could be implemented in real-time with low memory and bandwidth requirements. Each preprocessing method was used to train and validate 100 RBFNN models.

## 5 RESULTS

The summary statistics are in Figure 5.1a. Bar height shows the mean accuracy across all validation runs. The boxplot center shows the median, while the boxplot top and bottom show the interquartile range (IQR). Boxplot whiskers are 1.5 times the IQR above and below the boxplot. The STFT had both the highest accuracy and lowest skewness. The growth of committed

neurons was recorded for each training set, the envelope of neuron growth over the course of training for each preprocessing method is shown in Figure 5.1b. In this RCE implementation, the number of committed neurons can only increase where the methods are arranged in order from least to most committed neurons in Figure 5.1b.

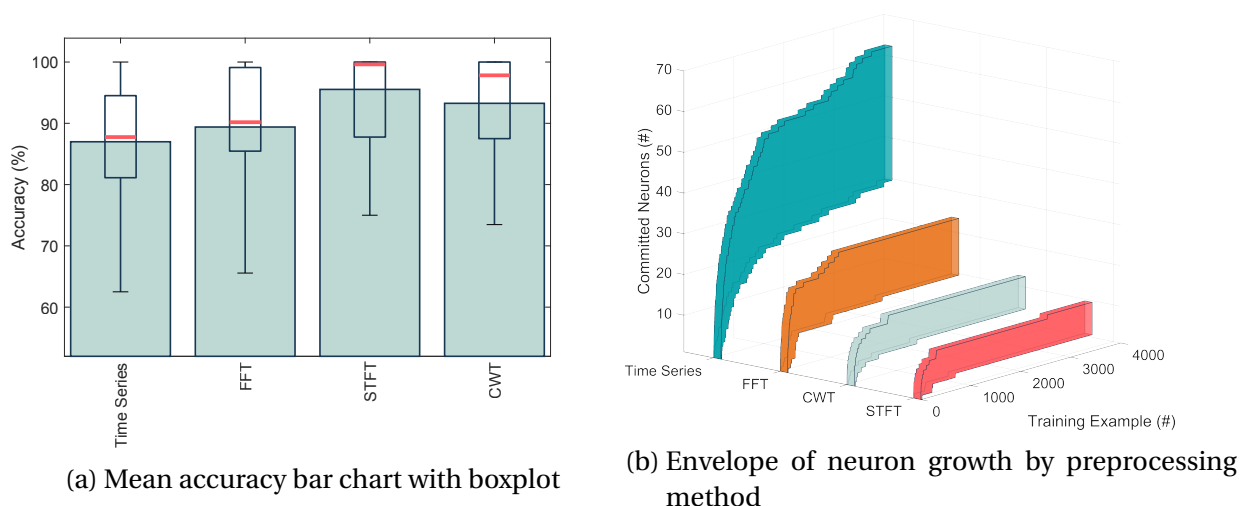


Figure 5.1: Overall results

A Bivariate histogram for each method is shown in Figure 5.2a with the final number of neurons after completing one Monte-Carlo training epoch versus the accuracy of the validation for that model. For a dataset given two different preprocessing methods performing at the same classification accuracy level, the method that uses fewer neurons can be said to more efficiently processing the features of the input space. The time series method had the lowest mean accu-

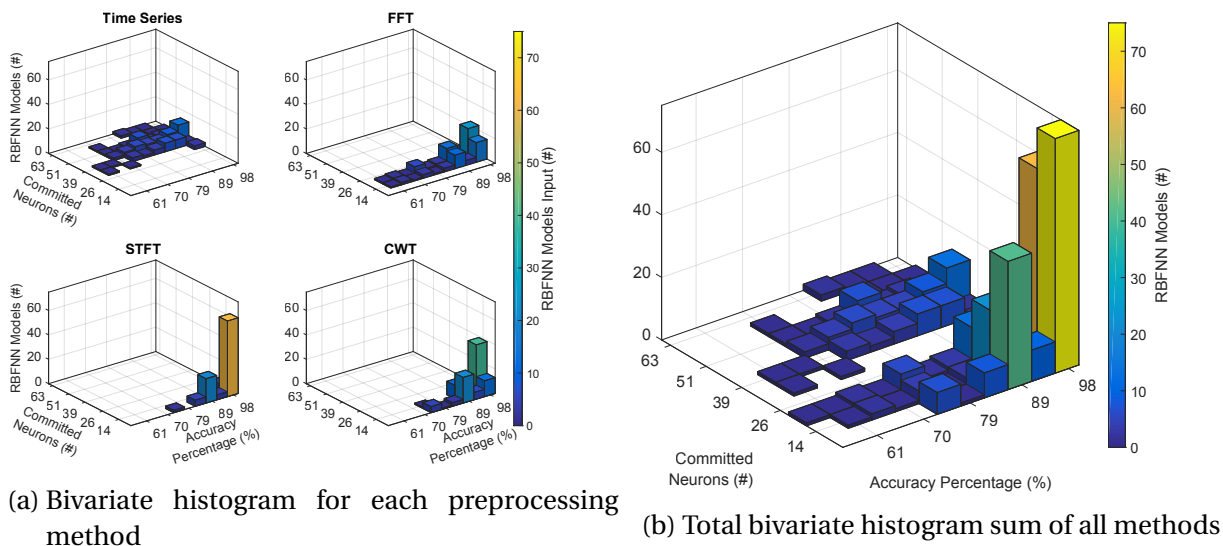


Figure 5.2: Bivariate histogram of accuracy and committed neurons

racy and most neurons committed, while the STFT had the highest mean accuracy and least neurons committed. Similarly, the FFT had the second lowest mean accuracy and second most

neurons committed and the CWT had the second highest mean accuracy and second least neurons committed.

The Pearson bivariate correlation coefficient calculated as the product of the standard scores shows the correlation between the number of committed neurons and accuracy [31],

$$\rho(acc, nn) = \frac{1}{N-1} \sum_{i=1}^N \left( \frac{acc_i - \bar{acc}}{\sigma_{acc}} \right) \left( \frac{nn_i - \bar{nn}}{\sigma_{nn}} \right), \quad (5.1)$$

where  $acc$  is the mean accuracy and  $nn$  is the final number of neurons committed during training,  $\sigma$  is the standard deviation, and  $N$  is the number of trained RBFNN models. Of interest is that the  $p$ -value for both the time series and FFT are not significant, while both the STFT and CWT methods have a  $p < .0001$ . Neuron growth is a feature of the RBFNN and so can be evaluated in the aggregate across all input preprocessing methods. The composite of all methods in Figure 5.2b shows an acute trend where the more neurons are committed during training the lower the accuracy in validation. The composite across all the input preprocessing methods has a  $p < 1 \times 10^{-7}$  demonstrating high correlation between the number of neurons and accuracy. While this correlation is useful, it is non-linear and non-deterministic, making it a useful heuristic for assessing relative accuracy between input preprocessing methods. The NM500 implementation of the RBFNN allows for up to 127 contexts, allowing independent RBFNN models to address different classification tasks sequentially on the same processing hardware. Practically speaking, this would allow all the preprocessing methods from this study to run essentially in parallel, where their relative performance could be assessed in real-time using the neuron growth heuristic as a framework for a higher level decision method. This could allow a priori higher accuracy classification because neuron growth precedes validation.

## 6 CONCLUSION

In this study, the committed neuron count is a useful heuristic for an RBFNN using an RCE neuron learning method that correlates well with the inference accuracy during validation. Since neuron count is intrinsic to the training process before any validation, it can be used to optimize the input preprocessing during training in real-time. It was shown, using the simulation of the NM500 neuromorphic chip, that a combination of neuron count and multiple RBFNN contexts provides a framework for evaluating input layer preprocessing methods. Conceivably, a higher level decision method based on this framework could be developed for real-time optimization of an RBFNN using RCE learning. Future work is planned to implement this work in hardware to investigate power and bandwidth performance.

## ACKNOWLEDGMENTS

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