REPORT DOCUMENTATION PAGE

Form Approved OMB NO. 0704-0188

1. REPORT DATE (DD-MM-YYYY)	2. REPORT TYPE	3. DATES COVERED (From - To)
02-03-2023	Final Report	1-Sep-2013 - 31-Aug-2016

4. TITLE AND SUBTITLE
Final Report: Disciplined Approximate Computing for Energy Efficiency and Resilience

5a. CONTRACT NUMBER
W911NF-13-1-0368

5b. GRANT NUMBER

5c. PROGRAM ELEMENT NUMBER
611102

6. AUTHORS

5d. PROJECT NUMBER

5e. TASK NUMBER

5f. WORK UNIT NUMBER

7. PERFORMING ORGANIZATION NAMES AND ADDRESSES
University of Washington
Office of Sponsored Programs
4333 Brooklyn Ave NE Box 359472
Seattle, WA 98195 -9472

8. PERFORMING ORGANIZATION REPORT NUMBER

9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS (ES)
U.S. Army Research Office
P.O. Box 12211
Research Triangle Park, NC 27709-2211

10. SPONSOR/MONITOR'S ACRONYM(S)
ARO

11. SPONSOR/MONITOR'S REPORT NUMBER(S)
63997-NC.5

12. DISTRIBUTION AVAILIBILITY STATEMENT
Approved for public release; distribution is unlimited.

13. SUPPLEMENTARY NOTES
The views, opinions and/or findings contained in this report are those of the author(s) and should not contrued as an official Department of the Army position, policy or decision, unless so designated by other documentation.

14. ABSTRACT

15. SUBJECT TERMS

16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT	15. NUMBER OF PAGES	19a. NAME OF RESPONSIBLE PERSON
a. REPORT	b. ABSTRACT	c. THIS PAGE			Mark Oskin
UU	UU	UU	UU		19b. TELEPHONE NUMBER 206-685-2237

RPPR Final Report
as of 03-Mar-2023

Agency Code: 21XD

Proposal Number: 63997NC **Agreement Number: W911NF-13-1-0368**
INVESTIGATOR(S):

Name: Luis Ceze
Email: luisceze@cs.washington.edu
Phone Number: 2065431896
Principal: N

Name: Mark H. Oskin
Email: oskin@cs.washington.edu
Phone Number: 2066852237
Principal: Y

Organization: **University of Washington**
Address: Office of Sponsored Programs, Seattle, WA 981959472
Country: USA
DUNS Number: 605799469 EIN: 916001537

Report Date: 30-Nov-2016 Date Received: 02-Mar-2023
Final Report for Period Beginning 01-Sep-2013 and Ending 31-Aug-2016
Title: Disciplined Approximate Computing for Energy Efficiency and Resilience
Begin Performance Period: 01-Sep-2013 **End Performance Period:** 31-Aug-2016
Report Term: 0-Other

Submitted By: Mark Oskin Email: oskin@cs.washington.edu
Phone: (206) 685-2237

STEM Degrees: **STEM Participants:**

Major Goals: The work in the proposed study has four core components: (1) identifying approximation opportunities in the applications in question; (2) mapping out the space of potential approximation techniques; (3) compiling models of accuracy and efficiency trade-offs for each technique; and (4) combining the application model with the approximation technique models and produce quality-versus-efficiency gain plots. Below we list each task and subtask.

In Step 1, we will collect applications and test cases, assess their error resilience, profile them looking for hot code, compute patterns and memory usage. Then in Step 2 we will compile a set of techniques for approximate computing, including deterministic and non-deterministic functional units and approximate accelerators, approximate storage, and approximate communication techniques. Then in Step 3 we will match application opportunities found in Step 1 and match them with Step 2. We will then, in Step 4, derive and build analytical and/or simulation models for the techniques. Finally, in Step 5, we will organize a workshop for the key players in approximate computing write a report on the study.

Accomplishments: Please see the "Training" and "Dissemination" sections where accomplishments are described for each student / paper.

RPPR Final Report
as of 03-Mar-2023

Training Opportunities: This grant funded the following students (whole or in part towards) toward their Ph.D. degrees:

Vincent Lee (Ph.D.), thesis: Towards Stochastic Computing Architectures for Emerging Applications, First employment: Facebook (Research)

Vincent's thesis takes a wide ranging approach to approximate and stochastic computing. Within it he describes a processor-in-memory (PIM) design for efficient image search. This application naturally lends itself to approximate computing techniques. The underlying algorithm (K-means search) lends itself to approximate computing techniques via reduced dimensionality and bit-width computing. High dimensionality feature spaces can be "folded" onto lower dimension metric spaces with limited loss of accuracy, provided sufficient dimensions are provided. Within that reduced metric space distance comparisons can be performed on lower bit width values (even as far as 1 bit). These two techniques can then be embedded into a in-DRAM device for highly power and performance efficient image search.

Amrita Mazunder (Ph.D.), thesis: Perceptual Optimizations for Video Capture, Processing, and Storage Systems

Amrita's thesis describes a hardware and software system for capturing and processing visual data. Video applications are naturally amendable to approximation techniques. One aspect of her thesis that this grant directly funded was a low power staged visual machine learning hardware device. This staged approached applied simple continuous analysis techniques to detect likely faces in real time video. Once detected the higher power compute device was woken up and performed a more thorough analysis. Finally if a face was detect it was sent over air for further processing in the cloud. This staged approach relied on provable guarantees about approximation quality.

Jacob Nelson (Ph.D.), thesis: Latency-Tolerant Distributed Shared Memory for Data-Intensive Applications. First employment: Microsoft Research

Jacob's thesis presents a software system for efficient execution of fine-grained parallel applications. The specific part of this work this grant funded was what we call disciplined approximate computing. This technique provides approximate computing but with programmer specified bounded error. For example, suppose a service like Facebook is built on a distributed system of machines. Computing the number of "Likes" for a post could involve processing across this distributed system. When a result has a handful of "Likes" the exact number is important. But when a post has millions of "Likes" the precise result is often hidden from the page and a more human readable "X million" display is used. Disciplined approximation is a technique that can provide the correct value of "X" in this case with relaxed precision specifiable by the programmer.

Results Dissemination: The grant led to the following key publications:

Michael Ringenburg, Adrian Sampson, Isaac Ackerman, Dan Grossman and Luis Ceze, "Debugging Approximate Programs via Dynamic Analysis", ASPLOS 2015
This paper describes a technique to debug approximate programs. Debugging approximate code is challenging because it is non-deterministic and while the developer has a built in intuition for what values are sampled from the real world and hence, amendable to approximate computing, they don't always do a perfect job of reasoning about the implications of carrying that approximation through the logic of their program. This paper introduces an "online" quality of result monitoring system. A sampling approach is used to periodically assess the value of approximation. Result for various algorithms such as FFT, Sobel filtering and triangle intersection are presented.

Brett Boston, Adrian Sampson, Dan Grossman and Luis Ceze, "Probability Type Inference for Flexible Approximate Programming", SPLASH 2015 OOPSLA
This paper describes a type system for energy-aware approximate computing. Type annotations are added for the developer to indicate which values can be computed appropriately. Formal semantics are presented so the language can be well defined a correct compiler implemented. Finally programs such as fft, LU decomposition, monte carlo simulation and raytracing are modified to use the new approximate keyword and semantics.

Adrian Sampson, Andre Baixo, Benjamin Ransford, Thierry Moreau, Joshua Yip, Luis Ceze and Mark Oskin, "Accept: A Programmer-Guided Compiler Framework for Practical Approximate Computing", UW Tech Report UW-CSE-15-01-01
This paper describes a technique software engineers can use to write approximately correct programs. It introduces a new keyword "approx" which annotates a type. A compiler can then generate code that approximately computes results for those values. The paper demonstrates the value of this approach by augmenting the code for a microcontroller designed for an energy harvesting system.

RPPR Final Report
as of 03-Mar-2023

Honors and Awards: Nothing to Report

Protocol Activity Status:

Technology Transfer: After graduation Amrita won a small Co-Motion grant to explore commercial opportunities of her work. Ultimately she decided her work was best integrated into an existing product rather than forming a startup focused on commercializing just the technology described in her thesis.

PARTICIPANTS:

Participant Type: Graduate Student (research assistant)
Participant: Vincent Lee
Person Months Worked: 3.00 **Funding Support:**
Project Contribution:
National Academy Member: N

Participant Type: Graduate Student (research assistant)
Participant: Jacob Nelson
Person Months Worked: 3.00 **Funding Support:**
Project Contribution:
National Academy Member: N

Participant Type: Graduate Student (research assistant)
Participant: Amrita Mazunder
Person Months Worked: 3.00 **Funding Support:**
Project Contribution:
National Academy Member: N

Participant Type: Co-Investigator
Participant: Luis Ceze
Person Months Worked: 1.00 **Funding Support:**
Project Contribution:
National Academy Member: N

Participant Type: PD/PI
Participant: Mark Oskin
Person Months Worked: 1.00 **Funding Support:**
Project Contribution:
National Academy Member: N

RPPR Final Report
as of 03-Mar-2023

Partners

,

I certify that the information in the report is complete and accurate:
Signature: Mark Oskin
Signature Date: 3/2/23 1:54PM

ACCEPT: A Programmer-Guided Compiler Framework for Practical Approximate Computing

Adrian Sampson André Baixo Benjamin Ransford Thierry Moreau Joshua Yip Luis Ceze Mark Oskin
University of Washington

Abstract

Approximate computing trades off accuracy for better performance and energy efficiency. It offers promising optimization opportunities for a wide variety of modern applications, from mobile vision to data analytics. Recent approaches to approximate computing have relied on either manual program modification, based exclusively on programmer reasoning, or opaque automatic transformations, which sacrifice programmer control. We describe ACCEPT*, a comprehensive framework for approximation that balances automation with programmer guidance. It includes C/C++ type qualifiers for constraining approximation, a compiler analysis library that identifies regions of approximable code, an autotuning system that automatically chooses the best approximation strategies, and a feedback mechanism that explains how annotations can be improved for better approximation opportunities.* ACCEPT *automatically applies a variety of approximation techniques, including hardware acceleration, while ensuring their safety. We apply* ACCEPT *to nine workloads on a standard desktop, an FPGA-augmented mobile SoC, and an energy-harvesting sensor device to evaluate the annotation process. We observe average speedups of 2.3×, 4.8×, and 1.5× on the three platforms, respectively.*

1. Introduction

Recent work on *approximate computing* has exploited the fact that many applications, particularly those whose outputs are meant for human interpretation, can enable more efficient execution at the cost of slightly inaccurate outputs. 3-D rendering, search, and machine learning are examples of the many tasks that tolerate inaccuracy.

Research over the past few years has proposed a variety of software and hardware approaches to approximate computing. Some of these approaches include: producing multiple versions of a program with varying accuracy and choosing at run time which version to use [5, 19]; periodically skipping loop iterations [24, 37]; removing synchronization primitives to reduce overhead and contention [22, 25, 27]; adjusting the precision of floating-point values [30]; using special low-power hardware structures that may be more likely to produce wrong results [15, 21]; and training on-chip hardware neural networks to mimic the behavior of costly functions [2, 16].

These disparate mechanisms for approximation share an important distinction from traditional program optimizations: they have subtle and broad-ranging effects on safety, reliability, and output quality. Some work proposes to rely on programmers for manual reasoning about these complex effects [16, 21, 27, 37], while other work proposes automated transformation based on code patterns or exhaustive search [5, 31, 32]. Manual code editing can be tedious and error-prone, especially since important safety invariants are at stake. Conversely, fully automatic transformations eliminate a crucial element of visibility and control. Programmers must trust the automated system; they have no recourse when opportunities are missed or invariants are broken.

We propose ACCEPT (an Approximate C Compiler for Energy and Performance Trade-offs), a framework for approximation that balances automation with programmer guidance. ACCEPT is *controlled* because it preserves programmer intention expressed via code annotations. A static analysis rules out unintended side effects. The programmer participates in a feedback loop with the analysis and has the opportunity to enable more approximation opportunities. ACCEPT is *practical* because it facilitates a range of approximation techniques that work on currently available hardware. Just as a traditional compiler framework provides common tools to support optimizations, ACCEPT consists of foundational analyses to help implement automatic approximate transformations based on programmer guidance and dynamic feedback.

ACCEPT's architecture combines static and dynamic components. The frontend, built atop LLVM [20], extends the syntax of C and C++ to incorporate an `APPROX` keyword that programmers use to annotate types as in other work [34]. ACCEPT's central analysis, *precise-purity*, identifies code that can affect only approximable values. Individual approximate optimizations use these analysis results to preserve static properties while transforming the code. After compilation, an autotuning component measures program executions and uses heuristics to identify program variants that maximize performance and output quality. To incorporate application insight, ACCEPT furnishes programmers with feedback to guide them toward better annotations that unlock more optimizations.

Contributions. ACCEPT is an end-to-end framework that makes past proposals for approximate program transformations practical and disciplined. Its contributions are:

- A programming model for program relaxation that combines lightweight annotations with compiler analysis feedback to guide programmers toward effective relaxations;
- An autotuning system that efficiently searches for a program's best approximation parameters;
- A core analysis library that identifies code that can be safely relaxed or offloaded to an approximate accelerator;
- A prototype implementation demonstrating both pure-

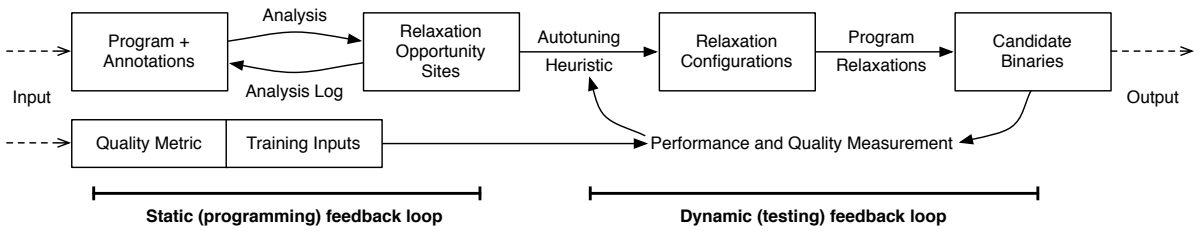


Figure 1: Overview of the ACCEPT compiler workflow.

software optimizations and hardware acceleration using an off-the-shelf FPGA part.

We evaluate ACCEPT across three platforms: a standard Intel-based server; a mobile SoC with an on-chip FPGA, which we use as an approximate accelerator to offload computations from the main core; and an ultra-low-power, energy-harvesting embedded microcontroller where performance is critical to applications' viability. The experiments demonstrate average speedups of 2.3×, 4.8×, and 1.5× on the three platforms, respectively, with quality loss under 10%.

We also report qualitatively on the programming experience. Novice C++ programmers were able to apply ACCEPT to legacy software to obtain new speedups. We plan to open-source the ACCEPT toolchain after publication both as a research tool for implementing new approximation techniques and as an end-to-end system for practitioners to experiment with approximate computing.

2. Overview

To safely and efficiently harness the potential of approximate programs, ACCEPT combines three main techniques: (1) a programmer–compiler feedback loop consisting of source code annotations and an analysis log; (2) a compiler analysis library that enables a range of automatic program relaxations; and (3) an autotuning system that uses dynamic measurements of candidate program relaxations to find the best balances between efficiency and quality. The final output is a set of Pareto-optimal versions of the input program that reflect its efficiency–quality trade-off space.

Figure 1 illustrates how these components make up ACCEPT's workflow. Crucially, two feedback loops control the impact of potentially destructive program relaxations: a *static* feedback loop that offers conservative guarantees and a complementary *dynamic* feedback loop that measures real program behavior to choose the best optimizations empirically. A key hypothesis of this paper is that neither static nor dynamic constraints are sufficient, since dynamic measurements cannot offer guarantees and static constraints do not capture the full complexity of relationships among relaxations, performance, and output quality. Together, however, the two feedback loops make ACCEPT's optimizations both controlled and practical.

Safety constraints and feedback. Because program relaxations can have outsize effects on program behavior, programmers need *visibility* into—and *control* over—the transformations the compiler applies. To give the programmer fine-grained control over relaxations, ACCEPT extends an existing lightweight annotation system for approximate computing based on type qualifiers [34]. ACCEPT gives programmers visibility into the relaxation process via feedback that identifies which transformations can be applied and which annotations are constraining it. Through annotation and feedback, the programmer iterates toward an annotation set that unlocks new performance benefits while relying on an assurance that critical computations are unaffected.

Automatic program transformations. Based on programmer annotations, ACCEPT's compiler passes apply program transformations that involve only approximate data. To this end, ACCEPT provides a compiler analysis library that is shared among relaxation strategies. We leverage existing work that relaxes program correctness in exchange for performance [2,16,22,25,27,28,37] and extend them with ACCEPT's safety analysis and programmer feedback.

Autotuning. While a set of annotations may permit many different safe program relaxations, not all of them are beneficial in the quality–performance trade-off they offer. A practical approximation mechanism must help programmers choose from among many candidate relaxations for a given program to strike an optimal balance between performance and quality. ACCEPT's autotuner heuristically explores the space of possible relaxed programs to identify Pareto-optimal variants.

3. Annotation and Programmer Feedback

This section describes ACCEPT's annotations and feedback, which helps programmers balance safety with approximation.

3.1. Annotation Language

The programmer uses annotations to communicate to the compiler which parts of a program are safe targets for program relaxation. ACCEPT adapts the type system of EnerJ, a language for approximate computing that was originally developed for bounding the effects of unreliable hardware components [34]. As in EnerJ, all types in ACCEPT are qualified as either *approximate* or *precise*, with precise being the default.

Information flow and endorsement. ACCEPT's type system uses a standard information-flow approach to prevent approximate data from affecting precise data. Precise types are strict subtypes of their approximate counterparts, so variables annotated as approximate cannot be assigned to precise ones without explicit programmer intervention. (The opposite

direction, wherein precise data affects approximate data, is permitted.) ACCEPT's type system is directly derived from EnerJ's [34], for which its authors prove a noninterference property ensuring that precise data stays precise. The same noninterference guarantee applies to ACCEPT's type-qualifier extension for type-safe subsets of C and C++. Undefined behavior in C and C++ remains undefined in ACCEPT.

Strict information flow can be too constraining. For example, a program may need to compute an approximate value, where relaxations can apply, but then check the resulting output for integrity while treating it as precise:

```
APPROX int a = expensiveCall();
cheapChecksumPrecise(a); // illegal
```

To permit this pattern, ACCEPT provides an *endorsement* expression that acts as a cast from an approximate type to its precise equivalent. The above program fails to typecheck, but using `ENDORSE(a)` as the argument is legal:

```
APPROX int a = expensiveCall();
cheapChecksumPrecise(ENDORSE(a));
```

Endorsements give programmers explicit control over information flow when dealing with approximate values.

Pointer types. For basic, non-reference types, ACCEPT's dialect of C allows unidirectional information flow: precise values can be assigned into approximate variables but not vice-versa. For pointers and references, however, even precise-to-approximate flow can cause unpredictable results since it creates two aliases for the same data that disagree on its approximateness. Pointer types are therefore invariant in the referent type. The language does not permit approximate pointers—i.e., addresses must be precise.

Implicit flow. Control flow provides an avenue for approximate data to affect precise data without a direct assignment. For example, `if (a) p = 5;` allows the variable `a` to affect the value of `p`. Like EnerJ, ACCEPT prohibits approximate values from being used in conditions—specifically, in `if`, `for`, `do`, `while`, and `switch` statements and in the ternary conditional-expression operator. Programmers can use endorsements to explicitly circumvent this restriction.

Escape hatches. ACCEPT decides whether program relaxations are safe based on the *effects* of the statements involved. Section 4 goes into more detail, but at a high level, code can be relaxed if its externally visible effects are approximate. For example, if `a` is a pointer to an `APPROX int`, then the statement `*a = 5;` has an approximate effect on the heap. Escape hatches from this sound reasoning are critical in a practical system that must handle legacy code. To enable or disable specific optimizations, the programmer can override the compiler's decision about a statement's effects using two additional annotations. The `ACCEPT_PERMIT` annotation forces a statement to be considered approximate and `ACCEPT_FORBID` forces it to be precise, forbidding any relaxations involving it.

These two annotations represent escape hatches from ACCEPT's normal reasoning and thus violate the safety guarantees it normally provides. Qualitatively, when annotating programs, we use these annotations much less frequently than the primary annotations `APPROX` and `ENDORSE`. We find `ACCEPT_PERMIT` to be useful when experimentally exploring program behavior before annotating and in system programming involving memory-mapped registers. Conversely, `ACCEPT_FORBID` is useful for marking parts of the program involved in introspection. Section 7.4 gives more detail on these experiences.

3.2. Programmer Feedback

ACCEPT takes inspiration from parallelizing compilers that use a development feedback loop to help guide the programmer toward parallelization opportunities [18, 29]. It provides feedback through an *analysis log* that describes the relaxations that it attempted to apply. For example, for ACCEPT's synchronization-elision relaxation, the log lists every lexically scoped lock acquire/release pair in the program. For each relaxation opportunity, it reports whether the relaxation is safe—whether it involves only approximate data—and, if it is not, identifies the statements that prevent the relaxation from applying. We call these statements, which carry externally visible precise effects, *blockers*.

ACCEPT reports blockers for each failed relaxation-opportunity site. For example, during the annotation of one program in our evaluation, ACCEPT examined this loop:

```
650  double myhiz = 0;
651  for (long kk=k1; kk<k2; kk++) {
652    myhiz += dist(points->p[kk], points->p[0],
653      ptDimension) * points->p[kk].weight;
654  }
```

The store to the precise (by default) variable `myhiz` prevents the loop from being approximable. The analysis log reports:

```
loop at streamcluster.cpp:651
blockers: 1
 * streamcluster.cpp:652: store to myhiz
```

Examining that loop in context, we found that `myhiz` was a weight accumulator that had little impact on the algorithm, so we changed its type from `double` to `APPROX double`. On its next execution, ACCEPT logged the following message about the same loop, highlighting a new relaxation opportunity:

```
loop at streamcluster.cpp:651
can perforate loop
```

The feedback loop between the programmer's annotations and the compiler's analysis log strikes a balance with respect to programmer involvement: it helps identify new relaxation opportunities while leaving the programmer in control. Consider the alternatives on either end of the programmer-effort spectrum: On one extreme, suppose that a programmer wishes to speed up a loop by manually skipping iterations. The programmer can easily misunderstand the loop's side effects if it indirectly makes system calls or touches shared data. On the other extreme, unconstrained automatic transformations are even more error prone: a tool that removes locks can easily create subtle concurrency bugs. Combining programmer

feedback with compiler assistance balances the advantages of these approaches.

4. Analysis and Relaxations

ACCEPT takes an annotated program and applies a set of program transformations to code that affects only data marked approximate. We call these transformations *relaxations* because they trade correctness for performance. To determine relaxation opportunities from type annotations, ACCEPT uses a an analysis called *precise-purity*. This section describes ACCEPT's implementations of several program relaxations drawn from the literature and how precise-purity analysis makes them safe. As a framework for approximation, ACCEPT is extensible to relaxations beyond those we describe here.

4.1. Precise-Purity Analysis

ACCEPT provides a core program analysis that client optimizations use to verify that program relaxations are appropriately constrained. This analysis must reconcile a fundamental difference between the language's safety guarantees and the transformation mechanisms: the programmer specifies safety in terms of fine-grained annotations on individual data elements, but program relaxations affect coarse-grained regions of code such as loop bodies or entire functions. Rather than resort to opaque and error-prone code-centric annotation, ACCEPT bridges this gap with the data-centric safety guarantees and programmer feedback outlined in the previous section.

ACCEPT's analysis library determines, for a region of interest (e.g., loop body), whether its side effects are exclusively approximate or may include precise data—in our terminology, whether or not the region is *precise pure*. Precise-purity is the key criterion for whether a relaxation can apply. In ACCEPT, every relaxation strategy consults the precise-purity analysis results and may only apply if and only if it affects exclusively precise-pure code. Formally, a region is precise pure if it:

- contains no stores to precise variables that may be read outside the region;
- does not call any functions that are not precise pure; and
- does not include an unbalanced synchronization statement (locking without unlocking or vice versa).

The analysis begins with the conservative assumption that the region is not precise pure and asserts otherwise only if it can prove precise-purity. For example, this code:

```
int p = ...;
APPROX int a = p * 2;
```

is precise pure if and only if the variable `p` is never read outside this code region. External code may, however, read the variable `a` since it is marked as approximate. Together with the information-flow type system, the precise-purity restriction ensures that code transformations only influence approximate data. Since only the approximate value `a` escapes the precise-pure block above, dependent code must also be marked as **APPROX** to obey the typing rules: any precise code that observes `a` is a type error. The block can affect only other approximate computations, so it is safe for relaxations to transform it.

We implement the core precise-purity analysis conservatively using SSA definition–use chains and a simple pointer-escape analysis. Section 6 gives more implementation details.

Algorithm 1: Approximate region selection.

```
   Input: function f
   Output: set of precise-pure regions R in f
1  foreach basic block B in f do
2      foreach block B' strictly post-dominated by B do
3          if B' dominates B then
4              region ← formRegionBetween(B', B)
5              if region is precise-pure then
6                  R ← R ∪ {region}
7              end
8          end
9      end
10 end
```

4.2. Approximate Region Selection

To support accelerator-style program transformations that provide replacements for coarse-grained regions of approximate code, ACCEPT provides an analysis that identifies regions of code as candidates for replacement, an analysis we call *region selection*. A *candidate region* is a set of instructions that is precise pure, forms control flow with a single entry and a single exit, and has enumerable live-ins (inputs) and live-outs (outputs). Client optimizations, such as neural acceleration described in Section 4.3.3, can enumerate the candidate regions in a program to attempt optimization. Precise-purity analysis enables region selection by proving that chunks of code are cleanly separable from the rest of the program.

Region selection meets the needs of accelerators that do not access memory directly and therefore require statically identifiable inputs and outputs; patterns such as dynamic array updates cannot be offloaded. The same analysis can be adapted to superoptimizers and synthesizers that need to operate on delimited subcomputations. For example, an accuracy-aware superoptimizer such as STOKE [35] could use ACCEPT's region selection to search for tractable optimization targets in a large program. Each fragment could be optimized independently and spliced back into the program.

Algorithm 1 shows how ACCEPT enumerates candidate regions. Intuitively, the algorithm uses dominance and post-dominance sets to identify pairs of basic blocks B_1 and B_2 where B_1 dominates B_2 and B_2 post-dominates B_1. The portion of the control-flow graph between these pairs represent all the single-entry, single-exit portions of a function.

Figure 2 demonstrates lines 2–9 for a basic block, labeled O, in an example CFG. Line 2 collects all the blocks post-dominated by block O (Figure 2b) and line 3 discards G, H, K and L because they do not dominate O (2c). Line 4 forms the

(a) One basic block is selected (b) Blocks post-dominated by O (c) Blocks that also dominate O (d) Selected region

Figure 2: Region selection example.

region between D and O (2d). Region formation uses depth-first search to find the blocks along paths from D to O. The algorithm tests the precise-purity of the newly formed region, which involves identifying the region's inputs and outputs.

4.3. Safe Approximate Relaxations

To demonstrate ACCEPT's flexibility as a framework, we implement three approximation strategies from the literature using precise-purity analysis.

4.3.1. Loop Perforation

Sidiroglou et al. propose *loop perforation*, which exploits the fact that many programs tolerate some skipping of loop iterations without significant quality degradation [37]. A perforated loop includes a parameter, the *perforation factor*, that governs how often an iteration can be skipped at run time.

ACCEPT considers a loop safe to perforate if its body is precise pure and free of early exits (i.e., `break` statements), which can cause nontermination if skipped. To perforate a loop, ACCEPT inserts a counter and code to increment and check it in each loop iteration. To minimize the overhead of loop perforation, ACCEPT requires the perforation factor p to be a power of two to enable bitwise tests against the counter. The loop body executes once every p iterations.

4.3.2. Synchronization Elision

In parallel programs, inter-thread synchronization constructs—locks, barriers, semaphores, etc.—are necessary for program predictability but threaten scalability. Recent research has proposed to strategically reduce synchronization in approximate programs [22, 25, 27, 28]. Even though removing synchronization can add data races and other nondeterminism to previously race-free or deterministic programs, this recent work has observed that the "incorrectness" is often benign: the resulting lost updates and atomicity violations can sometimes only slightly change the program's output.

ACCEPT can elide calls to locks (mutexes) and barriers from the pthreads library. To permit the elision of a lock acquire–release pair, ACCEPT requires that the critical section—the code between the acquire and release—be precise pure. To elide `pthread_barrier_wait()` synchronization, ACCEPT looks for pairs of calls whose intervening code is precise pure, in such cases removing the *first* call (the second call remains to delimit the end of the region).

4.3.3. Neural Acceleration

Recent work has shown how to use hardware neural networks as accelerators for approximate programs [6, 11, 38]. *Neural acceleration* trains a neural network to mimic a region of code and replaces the original code with an invocation of an efficient hardware accelerator implementation, the Neural Processing Unit (NPU) [2, 16]. Taking advantage of neural acceleration, however, has required manual identification of candidate code regions and insertion of offloading instructions.

ACCEPT implements an automatic neural acceleration transform that offloads execution to a custom FPGA-based neural network accelerator. While prior work on neural acceleration has used either simulations of specialized hardware [2, 16] or prototype chips [6], we target our optimization to off-the-shelf parts. To this end, we exploit an existing commercial system on a chip (SoC) that incorporates both a general-purpose ARM core and a Xilinx FPGA fabric on a single die [41].

Practical FPGA implementation poses a challenge common to any loosely coupled accelerator design: the interface to the accelerator has high bandwidth but high latency compared to a custom silicon design that incorporates the neural network directly into the CPU's pipeline, as in other work [2, 16]. ACCEPT alleviates the programmability challenge by constructing batched invocations that maximize performance.

ACCEPT uses approximate region selection (§4.2) to identify acceleration targets. It then collects input and output logs for each region to train a neural network, as in prior work on neural acceleration [16]. The interface to our NPU prototype, like many coarse-grained accelerators, requires the application to batch many invocations into a single message for optimal performance. ACCEPT inserts code to build a buffer of argument sets across multiple invocations of the target region, invoke the accelerator with the buffer, and collect output data.

This optimization demonstrates ACCEPT's utility for helping programmers target approximate accelerators without manually writing interface code.

4.3.4. Other Client Relaxations

The three optimizations above demonstrate ACCEPT's breadth as a framework for realizing ideas from approximate-computing research. Though we omit details for space, we have also prototyped two other optimizations using ACCEPT: an approximate alias analysis that unlocks secondary compiler optimizations such as loop-invariant code motion and

vectorization for approximate data, and approximate strength reduction that aggressively replaces expensive arithmetic operations with cheaper shifts and masks that are not exactly equivalent. Other optimizations from the literature are also amenable to ACCEPT's architecture, including approximate parallelization [22], float-to-fixed conversion [1], bit-width reduction [30, 40], GPU pattern replacement [31], and alternate-algorithm selection [3, 5].

5. Autotuning Search

The autotuner is a test harness in which ACCEPT explores the space of possible program relaxations through empirical feedback. We call a particular selection of relaxations and associated parameters (e.g., loop perforation with factor p) a *relaxation configuration*. The autotuner heuristically generates relaxation configurations and identifies the ones that best balance performance and output quality. The programmer also provides multiple inputs to the program. ACCEPT validates relaxation configurations by running them on fresh inputs to avoid overfitting.

Because the definition of quality is application dependent, ACCEPT relies on programmer-provided *quality metrics* that measure output accuracy, as in previous work [5, 8, 15, 16, 24, 34]. The quality metric is another program that (1) reads the outputs from two different executions of the program being transformed and (2) produces an error score between 0.0 (outputs are identical) and 1.0 (outputs are completely different), where the definitions of "identical" and "different" are application dependent.

A naïve method of exploring the space of relaxation configurations is to enumerate all possible configurations. But the space of possible relaxation configurations is exponential in the number of relaxation opportunities and therefore infeasible to even enumerate, let alone evaluate empirically. We instead use a heuristic that prioritizes a limited number of executions that are likely to meet a minimum output quality.

ACCEPT's heuristic configuration search consists of two steps: it vets each relaxation opportunity individually and then composes relaxations to create composites.

Vetting individual relaxations. In the first step, the autotuner separately evaluates each relaxation opportunity ACCEPT's analysis identified. Even with ACCEPT's static constraints, it is possible for some relaxations to lead to unacceptably degraded output or zero performance benefit. When the programmer uses escape hatches such as `ENDORSE` are used incorrectly, approximate data can affect control flow or even pointers and hence lead to crashes. ACCEPT vets each relaxation opportunity to disqualify unviable or unprofitable ones.

For each relaxation opportunity, the autotuner executes the program with only that relaxation enabled. If the output error is above a threshold, the running time averaged over several executions is slower than the baseline, or the program crashes, the relaxation is discarded. Then, among the "surviving" relaxations, the autotuner increases the aggressiveness of any optimizations that have parameters. (In our prototype, only loop perforation has a variable parameter: the perforation factor p.) The autotuner records the range of parameters for which each opportunity site is "good"—when its error is below a threshold and it offers speedup over the original program—along with the running time and quality score. These parameters are used in the next step to create composite configurations.

Composite configurations. After evaluating each relaxation opportunity site individually, ACCEPT's autotuner composes multiple relaxations to produce the best overall program configurations. For a program of even moderate size, it is infeasible to try every possible combination of component relaxations. ACCEPT heuristically predicts which combinations will yield the best performance for a given quality constraint and validates only the best predictions experimentally.

To formulate a heuristic, ACCEPT hypothesizes that relaxations compose linearly. That is, we assume that two program relaxations that yield output error rates e_1 and e_2, when applied simultaneously, result in an error of $e_1 + e_2$ (and that performance will compose similarly). While different relaxations can in practice compose unpredictably, this simplifying assumption represents an approximation that ACCEPT can later test with real executions.

Even under this assumption, the configuration-search problem is inefficient to solve exactly: it is equivalent to the 0/1 Knapsack Problem, which is NP-complete. In the Knapsack formulation, each configuration's output error is its *weight* and its performance benefit $1 - \frac{1}{\text{speedup}}$ is its *value*. The goal is to find the configuration that provides the most total value subject to a maximum weight capacity.

The Knapsack Problem is intractable, even for programs with only a few dozen potential relaxations. Instead, ACCEPT uses a well-known approximation algorithm [13] to sort the configurations by their value-to-weight ratio and greedily selects configurations in rank order up to an error budget. To account for our simplifying assumptions, we use a range of error budgets to produce multiple candidate composites. The algorithm is dominated by the sorting step, so its running time is $O(n \log n)$ in the number of vetted relaxation-opportunity sites (and negligible in practice). Like other candidate configurations, the composites are executed repeatedly to measure their output quality and speedup.

6. Implementation

ACCEPT extends the LLVM compiler infrastructure [20] and has three main components: (1) a modified compiler frontend based on Clang [12] that augments C and C++ with an approximation-aware type system; (2) a program analysis and set of LLVM optimization passes that implement program relaxations; and (3) a feedback and autotuning system that automatically explores quality–efficiency trade-offs.

6.1. Type System

We implemented our approximation-aware type system, along with the syntactic constructs **APPROX** and **ENDORSE**, as an extension to the Clang C/C++ compiler.

Pluggable types layer. We modified Clang to support *pluggable types* in the style of Cqual [17] and Java's JSR-308 with its accompanying Checker Framework [14, 26]. Pluggable types allow a compiler's built-in type system to be overlaid with arbitrary qualifiers and typing rules. Syntactically, we provide a GNU C `__attribute__(())` construct that specifies the type qualifiers for any variable, field, parameter, function, or method definition. Our pluggable type library implements a bottom-up AST traversal with an interface for defining typing rules. Finally, the compiler emits LLVM IR bitcode augmented with per-instruction metadata indicating the qualifiers on the value of each SSA operation. For example, when the result of the expression `a + b` has a type with the **APPROX** qualifier, it emits an `add` instruction reflecting this qualifier. This representation allows LLVM's compiler passes, which have access only to the IR and not to the original source code, to use the programmer-provided qualifier information.

Approximation-aware type system. The primary constructs in our EnerJ-inspired, approximation-aware type system are the **APPROX** type qualifier and the **ENDORSE** explicit type conversion. Both are provided as macros in a C header file. The **APPROX** macro expands to an `__attribute__(())` construct, and **ENDORSE**`(e)` expands to an opaque C comma expression with a magic number that the checker recognizes and interprets as a cast. The type checker itself follows a standard information-flow implementation: most expressions are approximate if any of their subexpressions is approximate; ACCEPT checks types and emits errors in assignments, function calls, function returns, and conditionals.

The escape hatches `ACCEPT_PERMIT` and `ACCEPT_FORBID` are parsed from C-style comments.

6.2. Analysis and Relaxations

Precise-purity (§4.1) and region selection (§4.2) are implemented as LLVM analysis passes. The ACCEPT prototype includes three relaxations, also LLVM passes, that consume the analysis results. The precise-purity analysis offers methods that check whether an individual LLVM IR instruction is approximate, whether an instruction points to approximate memory, and whether a code region (function or set of basic blocks) is precise pure. The region-selection analysis offers methods to enumerate precise-pure regions of the program that can be treated specially, e.g., offloaded to an accelerator.

We special-case the C memory-management intrinsics `memcpy` and `memset` to assign them appropriate effects. For example, `memset(p, v, n)` where `p` has type **APPROX** `float *` is considered precise pure because it behaves as a store to `p`.

The loop-perforation and synchronization-elision relaxations (§4) use precise-purity analysis to determine whether a loop body or critical section can be considered approximate. Loop perforation generates a counter and mask to skip iterations; and synchronization elision deletes lock and barrier call instructions. Neural acceleration uses region selection to identify target code and subsequently generates inline ARM assembly to buffer data and communicate with the FPGA over a coherent bus.

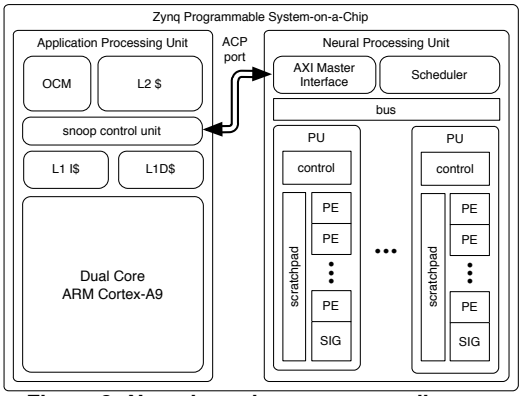


Figure 3: Neural accelerator system diagram.

6.3. Autotuning

ACCEPT's autotuning system is implemented separately from the compiler component. It communicates with the compiler via command-line flags and a pass-generated configuration file that enumerates the program's relaxation opportunities.

The programmer provides a quality metric to the autotuner in the form of a Python script that defines a `score` function, which takes as input two execution outputs and produces an error value between 0.0 and 1.0.

The autotuner's heuristic search consists of many independent program executions, so it is embarrassingly parallel. ACCEPT optionally distributes the work across a cluster of machines to accelerate the process. Workers on each cluster node receive a configuration, compile the program, execute it, and return the output and timing statistics. The master node coordinates the search and reports results.

6.4. Neural Acceleration

We evaluate ACCEPT's approximate region selection using a Neural Processing Unit (NPU) implemented on an on-chip FPGA. Our NPU accelerator design can evaluate multilayer perceptrons of different sizes and topologies without requiring reconfiguration of the underlying FPGA fabric. Its design is based on *systolic arrays* instead of the vector units used in previous work [16]. Systolic arrays excel at exploiting the regular data-parallelism found in neural networks and are amenable to efficient implementation on modern FPGAs. Most of the systolic array's computational datapath can be contained within the dedicated digital signal processing (DSP) slices found in FPGAs, enabling faster clock speeds.

Our design, shown in Figure 3, consists of a cluster of eight processing units (PUs) connected through a bus. Each PU

comprises a control block, a chain of processing elements (PEs), and a sigmoid unit. The PEs are implemented on DSP logic and form a one-dimensional systolic array that feeds into the sigmoid unit. When evaluating a neural network layer, PEs read the synaptic weights from a scratchpad memory. The sigmoid unit implements a nonlinear neuron-activation function using a lookup table. At the core of the PU control block lies a configurable sequencer that orchestrates communication between the PEs and the sigmoid unit. Different PUs can be individually programmed to evaluate either a single or multiple different neural networks.

The NPU communicates with the host processor through the accelerator coherency port (ACP), which reads and writes data to the processor's caches and on-chip memory (OCM). The host processor sends the neural network input sets to a region of the OCM that serves as a buffer. The host processor then signals the FPGA that the data is ready to be read using the dedicated event-signaling instructions in the ARMv7 ISA and transitions to a low-power state until it is awoken by the FPGA. The FPGA reads the inputs and evaluates the neural network. As results are generated, they are written back to the OCM, and once the NPU on the FPGA is done processing the batch, it signals the host CPU that the output is ready.

Full details on the FPGA design are out of the scope of this paper, since our focus is on the programming framework, but will be made available in a technical report after publication.

7. Evaluation

We evaluated ACCEPT's effectiveness at helping programmers to tune programs. We collected applications from domains known to be resilient to approximation, annotated each program using ACCEPT's feedback mechanisms, and applied the autotuner to produce relaxed executables. We examined applications targeting three platforms: a standard x86 server system, a mobile SoC augmented with an FPGA for neural acceleration, and a low-power, embedded sensing device.

7.1. Applications

Table 1 lists the applications we use in this evaluation. Since there is no standard suite of benchmarks for evaluating approximate-computing systems, we collect approximable applications from multiple sources, following the lead of other work in the area [11, 16, 24, 34, 38]. Five programs—canneal, fluidanimate, streamcluster, x264, and zynq-blackscholes—are from the PARSEC parallel benchmark suite [7]. They implement physical simulation, machine learning, video, and financial algorithms. Another program, sobel along with its ARM port zynq-sobel, is an image convolution kernel implementing the Sobel filter, a common component of image processing pipelines. The final program, msp430-activity, is an activity-recognition workload that uses a naïve Bayesian classifier to infer a physical activity from a sequence of accelerometer values on an MSP430 microcontroller [39].

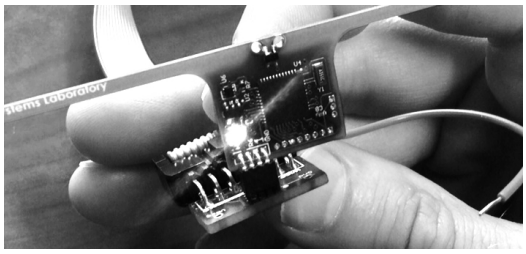


Figure 4: WISP energy-harvesting sensing platform [33].

To evaluate the applications' output accuracy, we develop application-specific quality metrics as in prior work on approximate computing [5, 15, 16, 24, 34]. Table 1 lists the metric for each program. In one case, fluidanimate, the benchmark shipped with an output-comparison tool.

We annotated each benchmark by inserting type annotations and interacting with the compiler's feedback mechanisms to identify fruitful optimizations. Table 1 shows the source code annotation density. We report qualitatively on our experiences with the annotation process in Section 7.4 below.

To validate the generality of ACCEPT's program relaxations, we used one set of inputs (the *training set*) during autotuning and a distinct input set (the *testing set*) to evaluate the final speedup and quality loss.

7.2. Experimental Setup

Each application targets one of three evaluation platforms: an x86 server, an ARM SoC with an integrated FPGA, and an embedded sensing system. The server platform is a dual-socket, 64-bit, 2.8 GHz Intel Xeon machine with two-way simultaneous multithreading and 4 GB memory. During autotuning, we distributed work across a cluster of 20 of these Xeon machines running Red Hat Enterprise Linux 6.5 with kernel version 2.6.32. The FPGA-augmented SoC is included to demonstrate the NPU relaxation, which requires programmable logic. We implemented the neural network design described in Section 6.4 on a Xilinx Zynq-7020 part, which includes a dual-core ARM Cortex-A9 and an FPGA fabric on a single TSMC 28 nm die. Finally, for the embedded msp430-activity workload, we used the WISP [33] device depicted in Figure 4. The WISP incorporates a prototype MSP430FR5969 "Wolverine" microcontroller with 2 KB of SRAM and 64 KB of nonvolatile ferroelectric RAM (FRAM) along with an onboard accelerometer. The WISP can harvest energy from radio waves, but we powered it via its JTAG interface to ensure reliable, repeatable runs connected to our test harness.

We compiled all applications with LLVM's aggressive `-O2` optimizations in addition to ACCEPT's program relaxations. We measured performance by reading the system clock before and after a region of interest that excluded the loading of data files from disk and dumping of results. (This region of interest was already defined for the PARSEC benchmarks.) To obtain accurate time measurements, we ran each configuration five times and averaged the running times.

Application	Description	Quality Metric	LOC	APPROX	ENDORSE
canneal	VLSI routing	Routing cost	3144	91	8
fluidanimate	Fluid dynamics	Particle distance	2138	30	47
streamcluster	Online clustering	Cluster center distance	1122	51	24
x264	Video encoding	Structural similarity	22018	300	69
sobel	Sobel filter	Mean pixel difference	154	7	5
zynq-blackscholes	Investment pricing	Mean relative error	318	50	10
zynq-inversek2j	Inverse kinematics	Euclidean distance	67	6	6
zynq-sobel	Sobel filter	Mean pixel difference	356	16	7
msp430-activity	Activity recognition	Classification rate	587	19	5

Table 1: The approximate applications used in our evaluation. The final two columns show source code annotation counts.

7.3. Results

Figure 5a plots the speedup (versus precise execution) of the best-performing relaxed versions that ACCEPT found for each application with output error under 10%. Speedups in the figure range from 1.3× (canneal) to 17.4× (zynq-inversek2j) with a harmonic mean of 2.3× across all three platforms.

Figure 5 shows the speedup for relaxed versions with only one type of optimization enabled. Not every optimization applies to every benchmark: notably, neural acceleration applies only to the Zynq benchmarks, and synchronization elision applies only to the two benchmarks that use fine-grained lock- and barrier-based synchronization. Loop perforation is the most general relaxation strategy and achieves a 1.9× average speedup across 7 of the benchmarks. Synchronization elision applies to fluidanimate and streamcluster, for which it offers speedups of 3% and 1.2× respectively. The optimization reduces lock contention, which does not dominate the running time of these benchmarks. Neural acceleration offers the largest speedups, ranging from 2.1× for zynq-sobel to 17.4× for zynq-inversek2j.

ACCEPT's feedback system explores a two-dimensional trade-off space between output quality and performance. For each benchmark, ACCEPT reports Pareto-optimal configurations rather than a single "best" relaxed executable; the programmer can select the configuration that strikes the best quality–performance balance for a particular deployment. Table 2 shows the range of output error rates and speedups in the frontiers for our benchmarks. We highlight canneal as an example. For this program, ACCEPT identifies 11 configurations with output error ranging from 1.5% to 15.3% and speedup ranging from 1.1× to 1.7×. Using this Pareto frontier output, the developer can choose a configuration with a lower speedup in error-sensitive situations or a more aggressive 1.7× speedup if higher error is considered acceptable for a deployment.

One benchmark, fluidanimate, exhibits very low error even under aggressive optimization. The configuration with the best speedup for that application, which removed two locks and perforated nine loops, had overall error (change in final particle positions) under 0.00001%. For msp430-activity, error remained at 0% in all acceptable configurations.

Autotuner characterization. Table 2 shows the number of relaxation opportunities (labeled *sites*), the number of composite configurations considered, the total number of configurations explored (including parameter-tuning configurations), and the number of optimal configurations on the output Pareto frontier for each benchmark. For streamcluster, a moderately sized benchmark by code size, exhaustive exploration of the 23 optimizations would have required more than 8 million executions; instead, ACCEPT's search heuristic considered only 14 composites to produce 7 optimal configurations.

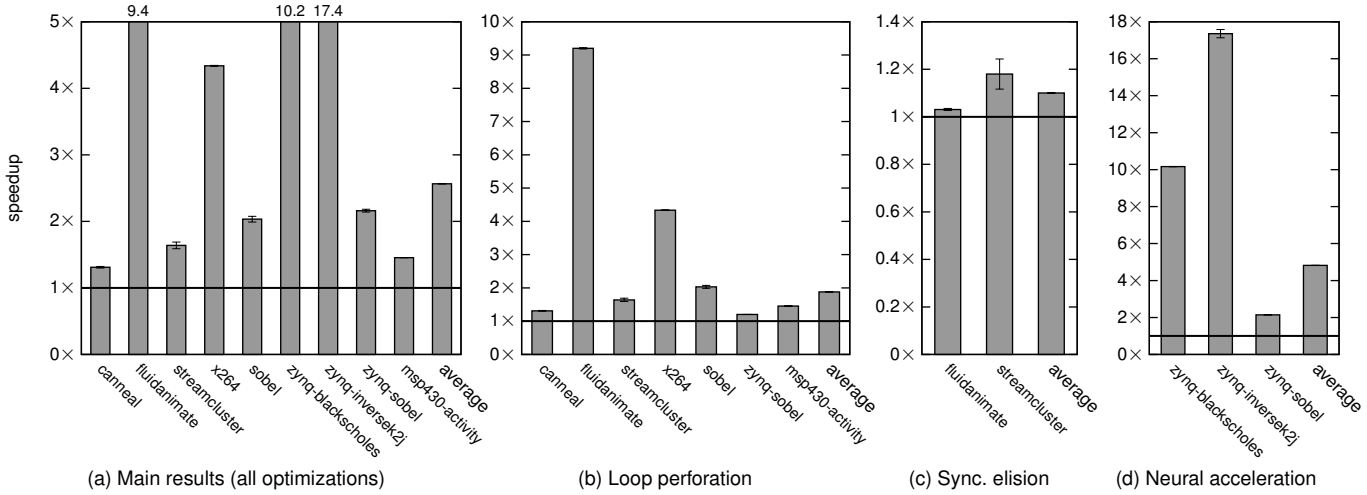
ACCEPT's heuristics help make its profiling step palatable. On our 20-node evaluation cluster for the server applications, the total end-to-end optimization time was typically within a few minutes: times ranged from 14 seconds (sobel) to 11 minutes (x264) with an average of 4 minutes. Tuning for the Zynq and MSP430 platforms was not parallelized and took 19 minutes on average and 5 minutes, respectively.

Accelerator power and energy. We measured power consumption on the Zynq SoC, including its FPGA and DRAM, using a Texas Instruments UCD9240 power supply controller while executing each benchmark in a loop to reach a steady state. Compared to baseline ARM-core–only execution in which the FPGA is not programmed and inactive, power overheads range from from 8.6% (zynq-sobel) to 22.6% (zynq-blackscholes). The zynq-sobel benchmark exhibits lower power overhead because a larger percentage of the program executes on the CPU, putting less load on the FPGA. When we account for the performance gains, energy savings range from 2× (zynq-sobel) to 15.7× (zynq-inversek2j).

7.4. Experiences

This section reports qualitatively on our experiences using ACCEPT to optimize the benchmarks. The programmers included three undergraduate researchers, all of whom were beginners with C and C++ and new to approximate computing, as well as graduate students familiar with the field.

Quality metrics. The first step in tuning a program with ACCEPT is to write a quality metric. In some cases, the program



(a) Main results (all optimizations) (b) Loop perforation (c) Sync. elision (d) Neural acceleration

Figure 5: Speedup for each application, including all optimizations (a) and each optimization in isolation (b–d).

Application	Sites	Composites	Total	Optimal	Error	Speedup
canneal	5	7	32	11	1.5–15.3%	1.1–1.7×
fluidanimate	20	13	82	11	<0.1%	1.0–9.4×
streamcluster	23	14	66	7	<0.1–12.8%	1.0–1.9×
x264	23	10	94	3	<0.1–0.8%	1.0–4.3×
sobel	6	5	21	7	<0.1–26.7%	1.1–2.0×
zynq-blackscholes	2	1	5	1	4.3%	10.2×
zynq-inversek2j	3	2	10	1	8.9%	17.4×
zynq-sobel	6	2	27	4	2.2–6.2%	1.1–2.2×
msp430-activity	4	3	15	5	<0.1%	1.5×

Table 2: Tuning statistics and resulting optimal configurations for each benchmark.

included code to assess output quality. For each remaining case, the programmer wrote a simple Python program (54 lines at most) to parse the program's output and compute the difference between two outputs.

Like any specification, a quality metric can be subtle to write correctly. Although it was not an intended use case, programmers found ACCEPT's dynamic feedback to be helpful in debugging quality metrics. In one instance, ACCEPT reported suspiciously low error for some configurations; these results revealed a quality metric that was ignoring certain missing values in the output and was therefore too permissive.

Initial and iterated annotations. One option when annotating a program for ACCEPT is to first analyze an unannotated program to enumerate all potential optimization sites. However, the programmers preferred to provide an initial annotation set by finding the "core" approximable data in the program—e.g., the vector coordinates in streamcluster or the pixels in sobel. With this data marked as approximate, the type checker reports errors when this data flows into variables that are not yet marked; for each such error, programmers decided whether to add another **APPROX** annotation or to stop the flow of approximation with an **ENDORSE** annotation.

Next, programmers expanded the annotation set to enable more optimizations. Using ACCEPT's analysis log (Section 3.2), they looked for optimizations that could *almost* apply—those that indicated only a small number of blockers.

A persistent consideration was the need to balance effort with potential reward. The programmers focused their attention on parts of the code most likely to provide good quality–efficiency trade-offs. In some cases, it was helpful to take "shortcuts" to program relaxations to test their viability before making them safe. If the programmer was unsure whether a particular lock in a program was contended, for example, it was useful to try eliding that lock to see whether it offered any speedup. Programmers used the `ACCEPT_PERMIT` annotation *temporarily* for an experiment and then, if the optimization proved beneficial, removed the escape-hatch annotation and added the safer **APPROX** and **ENDORSE** annotations.

These experiences highlighted the dual importance of both static and dynamic feedback in ACCEPT. Especially when the programmer is unfamiliar with the application's architecture, the static type errors and conservative precise-purity analysis helped highlight unexpected interactions between components. However, test runs were critical in discovering whether a given subcomputation is important to an algorithm, either in terms of performance or output accuracy.

Code navigation and heuristics. For large programs, programmers reported a need to carefully balance their time between learning the application's architecture and trying new optimizations. (We anticipate that a different strategy would be appropriate when the programmer is already familiar with the code before annotation.) One programmer used a call-graph visualizer to find code closely related to the main computation. In general, more modular code was easier to annotate: when effects are encapsulated, the volume of code related to an optimization is smaller and annotations are more local.

Programmers relied on ACCEPT's analysis feedback for hints about where time would be best spent. They learned to scan for and ignore reports involving memory allocation or system calls, which are rarely fruitful approximation opportunities. Relaxation sites primarily involved with large data arrays were typically good targets.

Encapsulating precise systems programming. The "escape hatches" from ACCEPT's safety analysis were crucial for low-level systems code. In msp430-activity, a routine manipulates memory-mapped registers to read from an accelerometer. The pointers involved in communicating with the memory-mapped peripheral are necessarily precise, but the reading itself is approximate and safe to relax. The `ACCEPT_PERMIT` escape hatch enabled its optimization. This annotation suggests a pattern in systems programming: the language's last-resort annotations can help communicate approximation information about opaque low-level code to ACCEPT.

8. Related Work

ACCEPT builds on a body of prior work on approximate computing. Three main research directions are most relevant to ACCEPT: static safety analyses for approximate programs, program relaxations, and quality-aware autotuners.

One group of proposals seeks to statically analyze approximate programs to prove properties even in the face of unreliable hardware or program transformations. Carbin et al. propose a general proof system for relating baseline executions to relaxed executions [8] and an integrity property checker for loop perforation [9]. Rely [10] is a program analysis that computes the chance that a nondeterministic computation goes wrong. EnerJ [34] provides a simple noninterference guarantee that we adapt in this work. Other recent work [23, 42] uses probabilistic reasoning to prove accuracy bounds on relaxed program transformations as applied to specific patterns in approximate programs. ACCEPT's safety guarantees need to be both general and lightweight, requiring minimal programmer overhead, to be practical. The information-flow types adapted from EnerJ permit straightforward automated compiler reasoning and are not constrained to specific code patterns.

ACCEPT complements specific software approximation strategies that have been previously proposed, such as loop perforation [37], alternate-implementation selection [3, 5], parameter selection [19], synchronization relaxation [22, 25, 27, 28], and pattern substitution [31]. This work contributes a unifying framework to make relaxations controlled and automatic.

ACCEPT's autotuning component resembles other prior work on dynamic measurement of approximate programs. Green [5] samples quality at run time to drive algorithm selection, and Ansel et al. [4] develop an autotuner for the PetaBricks language [3]. Misailovic et al.'s quality-of-service profiler [24] evaluates the results of candidate loop perforations by assessing their performance and quality impacts for reporting to the programmer. Precimonious [30] tunes variables' floating-point widths to adjust overall precision. ACCEPT generalizes these autotuning techniques: it applies to a variety of safety-constrained relaxations and guides the process using a practical search heuristic.

The type-qualifier overlay system we develop for Clang and LLVM is modeled after work on practical pluggable types for Java [14, 26]. Another notable predecessor is Cqual [17], which provided a similar mechanism in GCC for finding bugs (e.g., format-string vulnerabilities [36]). ACCEPT's implementation of type qualifiers adds integration with the rest of the compiler toolchain via IR metadata, which enables program analysis beyond type checking and type-based optimization.

Our neural accelerator design builds on recent work on using hardware neural networks as accelerators [2, 6, 16]. To our knowledge, this is the first work to evaluate neural acceleration on a commodity FPGA part or to demonstrate automated compiler-based offloading to the neural network.

9. Conclusion

Many important classes of applications can tolerate some imprecision. Programs from diverse domains such as imaging, machine learning, vision, physical simulation, and embedded sensing exhibit trade-offs between accuracy and performance. Approximate program relaxations hold the potential to dramatically improve performance and energy usage while only minimally impacting output quality. But these transformations are potentially destructive and can have subtle, far-reaching effects. Programmers need better tools for program relaxation that are safer than manual reasoning but more practical than opaque automatic transformation.

ACCEPT is a compiler framework for approximate programming that balances automation with programmer insight. It supports a wide range of approximate code transformations, including both pure-software relaxations and offloading to hardware accelerators. This paper demonstrates that ACCEPT can yield substantial end-to-end performance benefits with little quality degradation.

Approximate computing research is in its infancy and needs more tools for prototyping and evaluating ideas. The ACCEPT framework can simplify the practical implementation of new optimization strategies and accelerators. We hope to make ACCEPT a common, open-source platform for approximate computing research.

Acknowledgments

This work was supported in part by C-FAR, one of the six SRC STARnet Centers, sponsored by MARCO and DARPA, by NSF grant #1216611, by a Qualcomm Innovation Fellowship, and by gifts from Microsoft.

References

[1] Tor M. Aamodt and Paul Chow. Compile-time and instruction-set methods for improving floating- to fixed-point conversion accuracy. *ACM TECS*, 7(3):26:1–26:27, May 2008.

[2] Renée St. Amant, Amir Yazdanbakhsh, Jongse Park, Bradley Thwaites, Hadi Esmaeilzadeh, Arjang Hassibi, Luis Ceze, and Doug Burger. General-purpose code acceleration with limited-precision analog computation. In *ISCA*, 2014.

[3] Jason Ansel, Cy P. Chan, Yee Lok Wong, Marek Olszewski, Qin Zhao, Alan Edelman, and Saman P. Amarasinghe. PetaBricks: a language and compiler for algorithmic choice. In *PLDI*, 2009.

[4] Jason Ansel, Yee Lok Wong, Cy P. Chan, Marek Olszewski, Alan Edelman, and Saman P. Amarasinghe. Language and compiler support for auto-tuning variable-accuracy algorithms. In *CGO*, 2011.

[5] Woongki Baek and Trishul M. Chilimbi. Green: A framework for supporting energy-conscious programming using controlled approximation. In *PLDI*, 2010.

[6] Bilel Belhadj, Antoine Joubert, Zheng Li, Rodolphe Heliot, and Olivier Temam. Continuous real-world inputs can open up alternative accelerator designs. In *International Symposium on Computer Architecture (ISCA)*, pages 1–12, 2013.

[7] Christian Bienia. *Benchmarking Modern Multiprocessors*. PhD thesis, Princeton University, January 2011.

[8] Michael Carbin, Deokhwan Kim, Sasa Misailovic, and Martin C. Rinard. Proving acceptability properties of relaxed nondeterministic approximate programs. In *PLDI*, 2012.

[9] Michael Carbin, Deokhwan Kim, Sasa Misailovic, and Martin C. Rinard. Verified integrity properties for safe approximate program transformations. In *PEPM*, 2013.

[10] Michael Carbin, Sasa Misailovic, and Martin C. Rinard. Verifying quantitative reliability of programs that execute on unreliable hardware. Technical Report MIT-CSAIL-TR-2013-014, MIT, June 2013.

[11] Tianshi Chen, Yunji Chen, Marc Duranton, Qi Guo, Atif Hashmi, Mikko H. Lipasti, Andrew Nere, Shi Qiu, Michèle Sebag, and Olivier Temam. BenchNN: On the broad potential application scope of hardware neural network accelerators. In *IISWC*, 2012.

[12] Clang: a C language family frontend for LLVM. `http://clang.llvm.org`.

[13] George B. Dantzig. Discrete-variable extremum problems. *Operations Research*, 5(2):266–277, 1957.

[14] Michael D. Ernst. Type annotations specification (JSR 308). `http://types.cs.washington.edu/jsr308/`.

[15] Hadi Esmaeilzadeh, Adrian Sampson, Luis Ceze, and Doug Burger. Architecture support for disciplined approximate programming. In *ASPLOS*, 2012.

[16] Hadi Esmaeilzadeh, Adrian Sampson, Luis Ceze, and Doug Burger. Neural acceleration for general-purpose approximate programs. In *MICRO*, 2012.

[17] Jeffrey S. Foster. *Type Qualifiers: Lightweight Specifications to Improve Software Quality*. PhD thesis, University of California, Berkeley, December 2002.

[18] S. Hiranandani, K. Kennedy, C.-W. Tseng, and S. Warren. The D editor: a new interactive parallel programming tool. In *Supercomputing*, 1994.

[19] Henry Hoffmann, Stelios Sidiroglou, Michael Carbin, Sasa Misailovic, Anant Agarwal, and Martin Rinard. Dynamic knobs for responsive power-aware computing. In *ASPLOS*, 2011.

[20] Chris Lattner and Vikram Adve. LLVM: A compilation framework for lifelong program analysis and transformation. In *CGO*, 2004.

[21] Song Liu, Karthik Pattabiraman, Thomas Moscibroda, and Benjamin G. Zorn. Flikker: Saving refresh-power in mobile devices through critical data partitioning. In *ASPLOS*, 2011.

[22] Sasa Misailovic, Deokhwan Kim, and Martin Rinard. Parallelizing sequential programs with statistical accuracy tests. Technical Report MIT-CSAIL-TR-2010-038, MIT, August 2010.

[23] Sasa Misailovic, Daniel M. Roy, and Martin C. Rinard. Probabilistically accurate program transformations. In *SAS*, 2011.

[24] Sasa Misailovic, Stelios Sidiroglou, Hank Hoffman, and Martin Rinard. Quality of service profiling. In *ICSE*, 2010.

[25] Sasa Misailovic, Stelios Sidiroglou, and Martin C. Rinard. Dancing with uncertainty. In *Workshop on Relaxing Synchronization for Multicore and Manycore Scalability (RACES)*, 2012.

[26] Matthew M. Papi, Mahmood Ali, Telmo Luis Correa Jr., Jeff H. Perkins, and Michael D. Ernst. Practical pluggable types for Java. In *ISSTA*, 2008.

[27] Lakshminarayanan Renganarayanan, Vijayalakshmi Srinivasan, Ravi Nair, and Daniel Prener. Programming with relaxed synchronization. In *Workshop on Relaxing Synchronization for Multicore and Manycore Scalability (RACES)*, 2012.

[28] Martin Rinard. Parallel synchronization-free approximate data structure construction. In *HotPar*, 2013.

[29] Michael Ringenburg and Sung-Eun Choi. Optimizing loop-level parallelism in Cray XMT applications. In *Cray User Group Proceedings*, May 2009.

[30] Cindy Rubio-González, Cuong Nguyen, Hong Diep Nguyen, James Demmel, William Kahan, Koushik Sen, David H. Bailey, Costin Iancu, and David Hough. Precimonious: Tuning assistant for floating-point precision. In *SC*, November 2013.

[31] Mehrzad Samadi, Davoud Anoushe Jamshidi, Janghaeng Lee, and Scott Mahlke. Paraprox: Pattern-based approximation for data parallel applications. In *ASPLOS*, 2014.

[32] Mehrzad Samadi, Janghaeng Lee, D. Anoushe Jamshidi, Amir Hormati, and Scott Mahlke. Sage: Self-tuning approximation for graphics engines. In *MICRO*, 2013.

[33] Alanson P. Sample, Daniel J. Yeager, Pauline S. Powledge, Alexander V. Mamishev, and Joshua R. Smith. Design of an RFID-based battery-free programmable sensing platform. *IEEE Transactions on Instrumentation and Measurement*, 57(11):2608–2615, November 2008.

[34] Adrian Sampson, Werner Dietl, Emily Fortuna, Danushen Gnanapragasam, Luis Ceze, and Dan Grossman. EnerJ: Approximate data types for safe and general low-power computation. In *PLDI*, 2011.

[35] Eric Schkufza, Rahul Sharma, and Alex Aiken. Stochastic optimization of floating-point programs with tunable precision. In *PLDI*, 2014.

[36] Umesh Shankar, Kunal Talwar, Jeffrey S. Foster, and David Wagner. Detecting format string vulnerabilities with type qualifiers. In *USENIX Security Symposium*, August 2001.

[37] Stelios Sidiroglou-Douskos, Sasa Misailovic, Henry Hoffmann, and Martin Rinard. Managing performance vs. accuracy trade-offs with loop perforation. In *FSE*, 2011.

[38] Olivier Temam. A defect-tolerant accelerator for emerging high-performance applications. In *ISCA*, 2012.

[39] Texas Instruments, Inc. MSP430 Ultra-Low Power Microcontrollers. http://www.ti.com/msp430.

[40] Jonathan Ying Fai Tong, David Nagle, and Rob. A. Rutenbar. Reducing power by optimizing the necessary precision/range of floating-point arithmetic. *IEEE Trans. VLSI Syst.*, 8(3):273–286, 2000.

[41] Xilinx, Inc. All programmable SoC.

[42] Zeyuan Allen Zhu, Sasa Misailovic, Jonathan A. Kelner, and Martin Rinard. Randomized accuracy-aware program transformations for efficient approximate computations. In *POPL*, 2012.