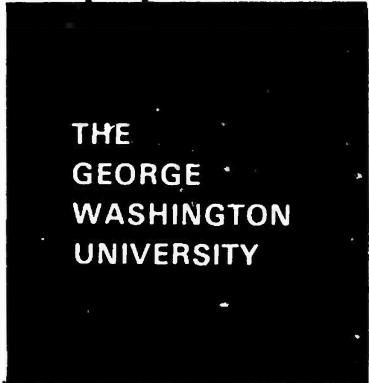


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AND APPLIED SCIENCE

COMPUTATIONAL EXPERIENCE WITH OPTIMAL
VALUE FUNCTION AND LAGRANGE
MULTIPLIER SENSITIVITY
IN NLP

by

Robert L. Armacost

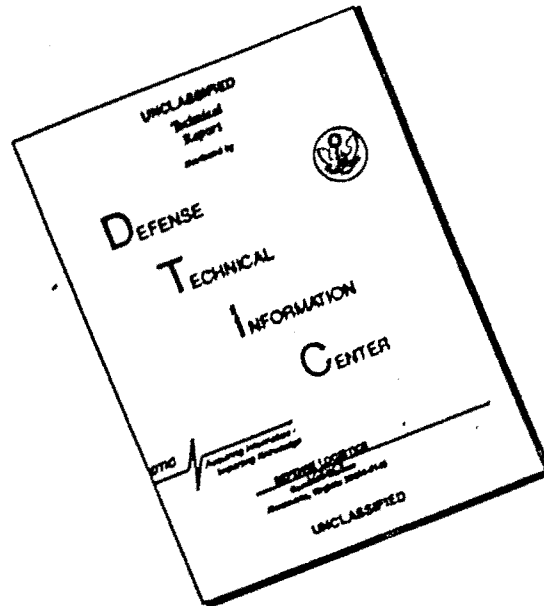
Serial T-335
10 May 1976

The George Washington University
School of Engineering and Applied Science
Institute for Management Science and Engineering

Program in Logistics
Contract N00014-75-C-0729
Project NR 347 020
Office of Naval Research

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SECURITY CLASSIFICATION OF THIS PAGE (When Data Entered)

REPORT DOCUMENTATION PAGE		READ INSTRUCTIONS BEFORE COMPLETING FORM
1 REPORT NUMBER T-335	2 GOVT ACCESSION NO.	3 RECIPIENT'S CATALOG NUMBER
4 TITLE (and Subtitle) COMPUTATIONAL EXPERIENCE WITH OPTIMAL VALUE FUNCTION AND LAGRANGE MULTIPLIER SENSITIVITY IN NLP		5 TYPE OF REPORT & PERIOD COVERED SCIENTIFIC
		6 PERFORMING ORG. REPORT NUMBER
7 AUTHOR(s) ROBERT L. ARMACOST		8 CONTRACT OR GRANT NUMBER(s) N00014-75-C-0729
9 PERFORMING ORGANIZATION NAME AND ADDRESS THE GEORGE WASHINGTON UNIVERSITY PROGRAM IN LOGISTICS WASHINGTON, D.C. 20037		10 PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS N-717-1
11 CONTROLLING OFFICE NAME AND ADDRESS OFFICE OF NAVAL RESEARCH, CODE 430D ARLINGTON, VA. 22217		12 REPORT DATE 10 May
		13 NUMBER OF PAGES 55
14 MONITORING AGENCY NAME & ADDRESS (if different from Controlling Office)		15 SECURITY CLASS. (of this report) NONE
		15a. DECLASSIFICATION/DOWNGRADING SCHEDULE
16 DISTRIBUTION STATEMENT (of this Report) DISTRIBUTION OF THIS REPORT IS UNLIMITED.		
17 DISTRIBUTION STATEMENT (of the abstract entered in Block 20, if different from Report)		
18 SUPPLEMENTARY NOTES		
19 KEY WORDS (Continue on reverse side if necessary and identify by block number) SENSITIVITY ANALYSIS NONLINEAR PROGRAMMING PARAMETRIC SENSITIVITY ANALYSIS PARAMETRIC PROGRAMMING COMPUTATIONAL EXPERIENCE INVENTORY MODELS		
20 ABSTRACT (Continue on reverse side if necessary and identify by block number) Sensitivity analysis in nonlinear programming is examined using the Sequential Unconstrained Minimization Technique. Particular emphasis is placed on the partial derivatives of the Lagrange multipliers and the optimal value function taken with respect to specified problem parameters, the estimation of which is based on recent developments by Armacost and Fiacco. The computational experience complements that previously reported by Armacost and Fiacco. An application of the sensitivity analysis to a		

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20. Abstract

large-scale, multi-item inventory model developed for the U.S. Navy is presented.

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THE GEORGE WASHINGTON UNIVERSITY
School of Engineering and Applied Science
Institute for Management Science and Engineering

Abstract
of
Serial T-335
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COMPUTATIONAL EXPERIENCE WITH OPTIMAL
VALUE FUNCTION AND LAGRANGE
MULTIPLIER SENSITIVITY
IN NLP

by

Robert L. Armacost*

Sensitivity analysis in nonlinear programming is examined using the Sequential Unconstrained Minimization Technique. Particular emphasis is placed on the partial derivatives of the Lagrange multipliers and the optimal value function taken with respect to specified problem parameters, the estimation of which is based on recent developments by Armacost and Fiacco. The computational experience complements that previously reported by Armacost and Fiacco. An application of the sensitivity analysis to a large-scale, multi-item inventory model developed for the U.S. Navy is presented.

*Presently assigned to Coast Guard Headquarters, Washington, D.C. The opinions or assertions contained herein are the private ones of the author and are not to be construed as official or reflecting the views of the Commandant or the Coast Guard at large.

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COMPUTATIONAL EXPERIENCE WITH OPTIMAL VALUE FUNCTION
AND LAGRANGE MULTIPLIER SENSITIVITY IN NLP

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1. Introduction

Several aspects of sensitivity analysis in nonlinear programming have been examined from a computational viewpoint by Armacost and Fiacco (1974). That work was based on the theory developed by Fiacco (1973) and used the computational procedures implemented by Armacost and Mylander (1973) using the SUMT-Version 4 computer code with the logarithmic-quadratic loss penalty function modified to estimate the partial derivatives of the solution point and the objective function taken with respect to certain specified problem parameters. Fiacco (1973) developed the necessary formulas to provide estimates of the partial derivatives of the Lagrange multipliers taken with respect to the problem parameters using the logarithmic-quadratic loss penalty function. Armacost and Fiacco (1975) developed the formulas to obtain first and second order sensitivity information for the optimal value function (a function of the parameters defined by the objective function evaluated at the solution point). Additionally, Armacost and Fiacco (1976) have shown that when the parameters are the right-hand side components of the constraints, the partial derivatives of the Lagrange multipliers are the components of the Hessian of the optimal value function. The supporting theory is addressed in Section 2.

Armacost and Fiacco (1974) focus on the computational experience with four example problems discussing various aspects of the sensitivity analysis procedure and results. They note that for large problems with a large number of parameters, a very large number of partial derivatives will be estimated. This is not only time consuming, but is also burdensome to the user who must evaluate all of them, many of which are zero or very close to zero in value. In addition, it is unlikely that the value of the solution (the value of the objective function evaluated at the solution point) will be sensitive to more than a relatively few parameters. Because of this, the method developed by Armacost and Fiacco (1975) to estimate the first order sensitivity of the optimal value function is incorporated in the computer program here to provide an option for preliminary screening of the parameters to determine which ones affect the optimal value function. Using the formulas developed by Fiacco (1973), a second option is included which permits the calculation of the sensitivity estimates for the Lagrange multipliers. The computer code and options used to accomplish these calculations are discussed in Section 3.

In Section 4, the new computational experience with Lagrange multiplier and optimal value function sensitivity using these options is presented for the four examples of Armacost and Fiacco (1974).

In Section 5, a sensitivity analysis is conducted for a large scale, multi-item inventory model developed by Schrady and Choe (1971) for the U. S. Navy. While the example used is the same small one used by Schrady and Choe, it nonetheless exhibits the value of performing such a sensitivity analysis in real world situations and illustrates the care that must be taken in interpreting the sensitivity results.

2. Supporting Theory

The problems considered here are of the form of Problem $P(\epsilon)$,

$$\begin{aligned} & \text{minimize} && f(x, \epsilon) \\ & \text{subject to} && g_i(x, \epsilon) \geq 0, \quad i=1, \dots, m, && P(\epsilon) \\ & && h_j(x, \epsilon) = 0, \quad j=1, \dots, p. \end{aligned}$$

When certain assumptions are satisfied, Fiacco (1973) and Armacost and Fiacco (1975) have shown the existence of the first order sensitivity of a Kuhn-Tucker triple and the first and second order sensitivity of the optimal value function. Additionally, they provide the means of estimating this sensitivity by way of the logarithmic-quadratic loss penalty function. The following four assumptions are sufficient to establish these results and are assumed to hold throughout this Section.

A1 --The functions defining Problem $P(\epsilon)$ are twice continuously differentiable in (x, ϵ) in a neighborhood of $(x^*, 0)$.

A2 --The second order sufficient conditions for a local minimum of Problem $P(0)$ hold at x^* with associated Lagrange multipliers u^* and w^* .

A3 --The gradients $\nabla_x g_i(x^*, 0)$ for all i such that $g_i(x^*, 0) = 0$, and $\nabla_x h_j(x^*, 0)$, $j=1, \dots, p$ are linearly independent.

A4 --Strict complementary slackness holds at $(x^*, 0)$ (i.e., $u_i^* > 0$ for all i such that $g_i(x^*, 0) = 0$).

The main results are presented without proof and are stated here for completeness. The portion of the theory used in the computational algorithm is made specific. The Lagrangian for Problem $P(\epsilon)$ is

$$L(x, u, w, \epsilon) = f(x, \epsilon) - \sum_{i=1}^m u_i g_i(x, \epsilon) + \sum_{j=1}^p w_j h_j(x, \epsilon)$$

where u_i , $i=1, \dots, m$ and w_j , $j=1, \dots, p$ are the Lagrange multipliers

associated with the inequality and equality constraints respectively.

The first result was proved as Theorem 2.1 by Fiacco (1973).

THEOREM 1: (First order sensitivity of a Kuhn-Tucker triple)

If assumptions A1, A2, A3 and A4 hold for Problem P(ϵ) at $(x^*, 0)$, then

- (a) x^* is a local isolated minimizing point of Problem P(0) and the associated Lagrange multipliers u^* and w^* are unique;
- (b) for ϵ in a neighborhood of 0, there exists a unique, once continuously differentiable vector function $y(\epsilon) = (x(\epsilon), u(\epsilon), w(\epsilon))^T$ satisfying the second order sufficient conditions for a local minimum of Problem P(ϵ) such that $(x(0), u(0), w(0)) = (x^*, u^*, w^*)$ and hence, $x(\epsilon)$ is a locally unique, local minimum of Problem P(ϵ) with associated unique Lagrange multipliers $u(\epsilon)$ and $w(\epsilon)$; and
- (c) for ϵ near 0, the set of binding inequalities is unchanged, strict complementary slackness holds for $u_i(\epsilon)$ for i such that $g_i(x(\epsilon), \epsilon) = 0$, and the binding constraint gradients are linearly independent at $x(\epsilon)$.

Let $y(\epsilon) = (x(\epsilon), u(\epsilon), w(\epsilon))^T$ be a Kuhn-Tucker triple where $x(\epsilon)$ solves Problem P(ϵ), then the optimal value function is defined as $f^*(\epsilon) = f(x(\epsilon), \epsilon)$ and the optimal value Lagrangian is $L^*(\epsilon) = L(x(\epsilon), u(\epsilon), w(\epsilon), \epsilon)$.

The second result was recently established by Armacost and Fiacco (1975) in their Theorem 2, stated here as Theorem 2.

THEOREM 2: (First and second order changes in the optimal value function)

If assumptions A1, A2, A3 and A4 hold for Problem P(ϵ) at $(x^*, 0)$, then

for ϵ near 0,

$$(a) \quad f^*(\epsilon) = L^*(\epsilon);$$

$$(b) \quad \nabla_{\epsilon} f^*(\epsilon) = \nabla_{\epsilon} L(x, u, w, \epsilon) \Big|_{(x, u, w) = (x(\epsilon), u(\epsilon), w(\epsilon))}$$

$$= \nabla_{\epsilon} f(x, \epsilon) - \sum_{i=1}^m u_i \nabla_{\epsilon} g_i(x, \epsilon) + \sum_{j=1}^p w_j \nabla_{\epsilon} h_j(x, \epsilon) \Big|_{(x, u, w) = (x(\epsilon), u(\epsilon), w(\epsilon))} ;$$

$$(c) \nabla_{\epsilon}^2 f^*(\epsilon) = \nabla_{\epsilon} (\nabla_{\epsilon} L(x(\epsilon), u(\epsilon), w(\epsilon), \epsilon))^T .$$

The problems in subsequent Sections are solved using the logarithmic-quadratic loss penalty function $W(x, \epsilon, r)$ defined as

$$W(x, \epsilon, r) = f(x, \epsilon) - r \sum_{i=1}^m \ln g_i(x, \epsilon) + (1/2r) \sum_{j=1}^p h_j(x, \epsilon)^2. \quad (1)$$

The following result was obtained by Fiacco (1973) as Theorem 3.1.

THEOREM 3: (Approximation of first order sensitivity results and determination of estimates from $W(x, \epsilon, r)$)

If assumptions A1, A2, A3 and A4 hold for Problem $P(\epsilon)$, then for (ϵ, r) near $(0, 0)$, there exists a locally unique, once continuously differentiable vector function $y(\epsilon, r) = (x(\epsilon, r), u(\epsilon, r), w(\epsilon, r))^T$ satisfying

$$\begin{aligned} \nabla_x L(x, u, w, \epsilon) &= 0, \\ u_i g_i(x, \epsilon) &= r, \quad i=1, \dots, m, \\ h_j(x, \epsilon) &= w_j r, \quad j=1, \dots, p, \end{aligned}$$

with $(x(0, 0), u(0, 0), w(0, 0)) = (x^*, u^*, w^*)$, and such that for any (ϵ, r) near $(0, 0)$ and $r > 0$, $x(\epsilon, r)$ is a locally unique unconstrained minimizing point of $W(x, \epsilon, r)$, with $\mu_i(x(\epsilon, r), \epsilon) > 0$, $i=1, \dots, m$, and $\nabla_x^2 W(x(\epsilon, r), \epsilon, r)$ is positive definite.

Since the system of equations in Theorem 3 is identically equal to zero at $r = 0$, it follows that $\nabla_{\epsilon} y(\epsilon, r)$ can be calculated for (ϵ, r) near $(0, 0)$. The following result was shown by Fiacco (1973) following his Theorem 3.1.

COROLLARY 3.1: (Convergence of estimates using $W(x, \epsilon, r)$)

If assumptions A1, A2, A3 and A4 hold for Problem $P(\epsilon)$, then for any ϵ

near 0,

- (a) $\lim_{r \rightarrow 0^+} y(\epsilon, r) = y(\zeta, 0) = y(\epsilon)$, the Kuhn-Tucker triple characterized in Theorem 1; and
- (b) $\lim_{r \rightarrow 0^+} \nabla_{\epsilon} y(\zeta, r) = \nabla_{\epsilon} y(\epsilon, 0) = \nabla_{\epsilon} y(\epsilon)$.

Armacost and Fiacco (1974) reported computational experience with sensitivity analysis in four sample nonlinear programming problems. The algorithm uses the fact that the Hessian of the penalty function is positive definite for r small enough and that the gradient of the penalty function is identically zero in a neighborhood of the solution point. Thus, the gradient of the solution point taken with respect to the parameter vector ζ is estimated as

$$\nabla_{\zeta} x(\zeta, r) = -\nabla_x^2 W(x, \epsilon, r)^{-1} \nabla_{\zeta}^2 W(x, \epsilon, r) \Big|_{x=x(\zeta, r)}. \quad (2)$$

Using the fact that $u_i(\epsilon, r) = r/g_i(x(\epsilon, r), \epsilon)$ and $w_j(\epsilon, r) = (1/r)h_j(x(\epsilon, r), \zeta)$, the chain rule can be applied to obtain $\nabla_{\zeta} u_i(\epsilon, r)$ and $\nabla_{\zeta} w_j(\epsilon, r)$ as shown by Fiacco (1973). Convergence was shown by Fiacco (1973) following his Corollary 3.1. The above approach is equivalent to calculating $\nabla_{\zeta} y(\epsilon, r)$ directly from the system of equations in Theorem 3.

The logarithmic-quadratic loss penalty function can also be used to provide estimates of the first and second order sensitivity of the optimal value function. Let the optimal value penalty function be defined as $W^*(\zeta, r) = W(x(\zeta, r), \epsilon, r)$. The first order portion of the sensitivity results developed by Armacost and Fiacco (1975) in their Theorem 4 and Corollary 4.1 follow.

THEOREM 4: (First order sensitivity of $W^*(\zeta, r)$ and estimates for $f^*(\epsilon)$)
If assumptions A1, A2, A3 and A4 hold for Problem $P(\epsilon)$, then for (ζ, r) near $(0, 0)$ and $r > 0$,

- (a) $\lim_{r \rightarrow 0^+} W^*(\epsilon, r) = L^*(\epsilon) = f^*(\epsilon)$;
- (b) $\nabla_{\epsilon} W^*(\epsilon, r) = \nabla_{\epsilon} L(x, u, w, \epsilon) \Big|_{(x, u, w) = (x(\epsilon, r), u(\epsilon, r), w(\epsilon, r))}$; and (3)
- (c) $\lim_{r \rightarrow 0^+} \nabla_{\epsilon} W^*(\epsilon, r) = \nabla_{\epsilon} L(x(\epsilon), u(\epsilon), w(\epsilon), \epsilon) = f^*(\epsilon)$.

Another estimate of the optimal value function is obtained as $f^{\#}(\epsilon, r) \equiv f(x(\epsilon, r), \epsilon)$. Direct application of the chain rule for differentiation then yields an estimate of the first order sensitivity of the optimal value function as

$$\nabla_{\epsilon} f^{\#}(\epsilon, r) = \nabla_x f(x, \epsilon) \nabla_{\epsilon} x(\epsilon, r) + \nabla_{\epsilon} f(x, \epsilon). \quad (4)$$

Under the given assumptions, continuity assures that $f^{\#}(\epsilon, r) \rightarrow f^*(\epsilon)$ and $\nabla_{\epsilon} f^{\#}(\epsilon, r) \rightarrow \nabla_{\epsilon} f^*(\epsilon)$ as $r \rightarrow 0^+$. Thus, both $\nabla_{\epsilon} f^{\#}(\epsilon, r)$ and $\nabla_{\epsilon} W^*(\epsilon, r)$ are estimates of $\nabla_{\epsilon} f^*(\epsilon)$ for r sufficiently small. It is beyond the scope of this Section to explore the relationship between these estimates. It is easily shown, however, that

$$\begin{aligned} \nabla_{\epsilon} W^*(\epsilon, r) = \nabla_{\epsilon} f^{\#}(\epsilon, r) - \sum_{i=1}^m u_i (\nabla_x g_i \nabla_{\epsilon} \lambda(\epsilon, r) + \nabla_{\epsilon} g_i) \\ + \sum_{j=1}^p w_j (\nabla_x h_j \nabla_{\epsilon} x(\epsilon, r) + \nabla_{\epsilon} h_j) \Big|_{x=x(\epsilon, r)}. \end{aligned}$$

It is easily shown that the terms in the summations on the right approach zero as r approaches zero. Armacost and Fiacco (1974) used equations (2) and (4) to examine the trajectory and convergence properties of the gradients of the solution point and the optimal value function from a computational point of view. Here, equation (3) is also used to estimate the first order sensitivity of the optimal value function and has the advantage that $\nabla_{\epsilon} x(\epsilon, r)$ need not be calculated.

3. User Options and Computer Codes

The basic SUMT-Version 4 computer program and instructions for its use are described in Mylander, Holmes and McCormick (1971). The basic sensitivity analysis subroutines, user instructions, and instructions for integrating the sensitivity package with the SUMT-Version 4 code are described in Armacost and Mylander (1973). Briefly, the conduct of a sensitivity analysis is controlled by the variable NEXOP3 which is given a value on the "Second Option Card" in the SUMT input data deck. There are four choices: no sensitivity analysis, a sensitivity analysis at the final subproblem, a sensitivity analysis at each subproblem along the penalty function minimizing trajectory, or a sensitivity analysis at the final subproblem for a range of differencing increments. In conjunction with this option, two additional options are added here and come into play whenever a sensitivity analysis is conducted. The first option (technically Option 4) is controlled by the variable NEXOP4 and determines whether the partial derivatives of the Lagrange multipliers will be calculated. When the calculation is done, the formulas described by Fiacco (1973) are used. The second option added here (Option 5) permits a screening of the parameters to reduce the number of partial derivatives which are estimated by limiting further analysis to those parameters which will affect the optimal value of the objective function by an amount exceeding 0.1 percent of its current value. This option is controlled by the variable NEXOP5. The estimate of sensitivity of the optimal value function with respect to a particular parameter under this option is calculated using the Armacost and Fiacco (1975) result which involves the partial derivative of the Lagrangian taken with respect to the parameter under consideration. Subroutines LMULT and

PRESEN and related coding in Subroutine SENS implement Option 4 and Option 5, respectively. Subroutines SENS, LMULT and PRESEN are listed in Appendix A. Specific instructions for using these two options in conjunction with the "Second Option Card" are given below in Table 1. This information should be added to Table 5 in Mylander, Holmes and McCormick (1971).

TABLE 1
THE SECOND OPTION CARD

Option	Column	Value	Meaning
4	28	-0	Do not estimate the partial derivatives of the estimates of the Lagrange multipliers.
		-1	Estimate the partial derivatives of the estimates of the Lagrange multipliers whenever a sensitivity analysis of the solution point is conducted.
5	35	-0	Estimate the partial derivatives of the optimal value function and eliminate those parameters which do not affect the optimal value function from subsequent sensitivity calculations.
		-1	Estimate the partial derivatives of the optimal value function with respect to all parameters, but continue all subsequent sensitivity calculations with respect to all parameters.
		-2	Do not estimate the partial derivatives of the optimal value function first. Conduct the sensitivity analysis with respect to all parameters.

A potential user of these sensitivity subroutines should be aware that the penalty function coded in SUMT-Version 4 does not have the

factor " $\frac{1}{2}$ " in the quadratic loss term (see equation (1) in Section 2). Therefore, the expressions for the several gradients have an additional factor of "2" in the computer program which does not appear in the supporting theory of Section 2.

4. New Computational Experience

In this Section, the four sample problems of Armacost and Fiacco (1974) are examined. Specifically, the convergence of the partial derivatives of the Lagrange multipliers is examined and the estimates of the gradient of the optimal value function obtained by the chain rule (equation (4)) and by the gradient of the Lagrangian (equation (3)) are compared. The problems are designated by the same letters as in the original paper.

Consider first a simple convex program. The problem is

$$\begin{aligned} \text{minimize} \quad & f(x, \epsilon) = x_1 + \epsilon_2 x_2 \\ \text{subject to} \quad & g_1(x, \epsilon) = \epsilon_1^2 - x_1^2 - x_2^2 \geq 0, \end{aligned} \quad B$$

for $\epsilon_1 > 0$. The analytical solution point and its gradient are given in Armacost and Fiacco (1974) as

$$x(\epsilon) = \begin{bmatrix} x_1(\epsilon) \\ x_2(\epsilon) \end{bmatrix} = \begin{bmatrix} -\frac{\epsilon_1}{\sqrt{1 + \epsilon_2^2}} \\ -\frac{\epsilon_1 \epsilon_2}{\sqrt{1 + \epsilon_2^2}} \end{bmatrix} .$$

$$f^*(\epsilon) = -\epsilon_1 \sqrt{1 + \epsilon_2^2} .$$

$$\nabla_{\epsilon} x(\epsilon) = \frac{1}{\sqrt{1 + \epsilon_2^2}} \begin{bmatrix} -1 & \frac{\epsilon_1 \epsilon_2}{(1 + \epsilon_2^2)} \\ -\epsilon_2 & \frac{-\epsilon_1}{(1 + \epsilon_2^2)} \end{bmatrix},$$

and

$$\nabla_{\epsilon} f^*(\epsilon) = (\partial f^*(\epsilon)/\partial \epsilon_1, \partial f^*(\epsilon)/\partial \epsilon_2)$$

$$= \left(-\sqrt{1 + \epsilon_2^2}, -\epsilon_1 \epsilon_2 / \sqrt{1 + \epsilon_2^2} \right).$$

The Lagrange multiplier and its gradient are analytically determined to be

$$u^*(\epsilon) = \sqrt{1 + \epsilon_2^2} / 2\epsilon_1,$$

and

$$\nabla_{\epsilon} u^*(\epsilon) = \left(-\sqrt{1 + \epsilon_2^2} / 2\epsilon_1^2, \epsilon_2 / (2\epsilon_1 \sqrt{1 + \epsilon_2^2}) \right).$$

The numerical example had $\epsilon_1 = 2$ and $\epsilon_2 = 1$ yielding the following numerical results:

$$\begin{aligned} f^* &= -2\sqrt{2}, & \nabla_{\epsilon} f^* &= (-\sqrt{2}, -\sqrt{2}), \\ x^* &= \begin{bmatrix} -\sqrt{2} \\ -\sqrt{2} \end{bmatrix}, & \nabla_{\epsilon} x^* &= \begin{bmatrix} -\sqrt{2}/2 & \sqrt{2}/2 \\ -\sqrt{2}/2 & -\sqrt{2}/2 \end{bmatrix}, \\ u^* &= \sqrt{2}/4 & \nabla_{\epsilon} u^* &= (-\sqrt{2}/8, \sqrt{2}/8) \\ &\approx 0.353, & &\approx (-.177, .177). \end{aligned}$$

The numerical results obtained by the computer program are included in Table 2 for the optimal value function and Lagrange multiplier sensitivity. The values of the first order optimal value function sensitivity computed both by the chain rule (equation (4)) and by taking partial derivatives of the Lagrangian with respect to the parameters (equation (3))

TABLE 2
TRAJECTORY RESULTS FOR PROBLEM B

Subproblem	f	Lagrangian		Chain rule		u	$\partial u / \partial \epsilon_1$	$\partial u / \partial \epsilon_2$
		$\partial f / \partial \epsilon_1$	$\partial f / \partial \epsilon_2$	$\partial f / \partial \epsilon_1$	$\partial f / \partial \epsilon_2$			
1	-1.9999	-1.9999	-.9999	-1.3333	-1.3333	.4999	-.3333	.1666
2	-2.5393	-1.5440	-1.2947	-1.4087	-1.4088	.3860	-.2100	.1761
3	-2.7765	-1.4439	-1.3833	-1.4139	-1.4139	.3609	-.1844	.1767
4	-2.8128	-1.4243	-1.4064	-1.4142	-1.4142	.3560	-.1790	.1768
5	-2.8245	-1.4127	-1.4123	-1.4142	-1.4142	.3531	-.1768	.1768
6	-2.8274	-1.4137	-1.4137	-1.4142	-1.4142	.3532	-.1767	.1768
7	-2.8282	-1.3899	-1.4141	-1.4142	-1.4142	.3475	-.1737	.1768
Analytical	-2.8282	-1.4142	-1.4142	-1.4142	-1.4142	.3537	-.1769	.1768

are presented in parallel. The results are also plotted in Figure 1 and portray the type of convergence experienced. While the previous results by Arnacost and Fiacco (1974) clearly indicated a stability of the solution point and optimal value function and their gradients taken with respect to the parameters, Table 2 indicates that with the Lagrange multipliers, the same sort of stability is not found. It is well known that with barrier functions, the estimates of the Lagrange multipliers decrease in accuracy as the boundary is approached. The change in the value of u between subproblems 6 and 7 is an indication of this. It is no surprise, therefore, that the estimates of the gradient of the Lagrange multiplier behave in

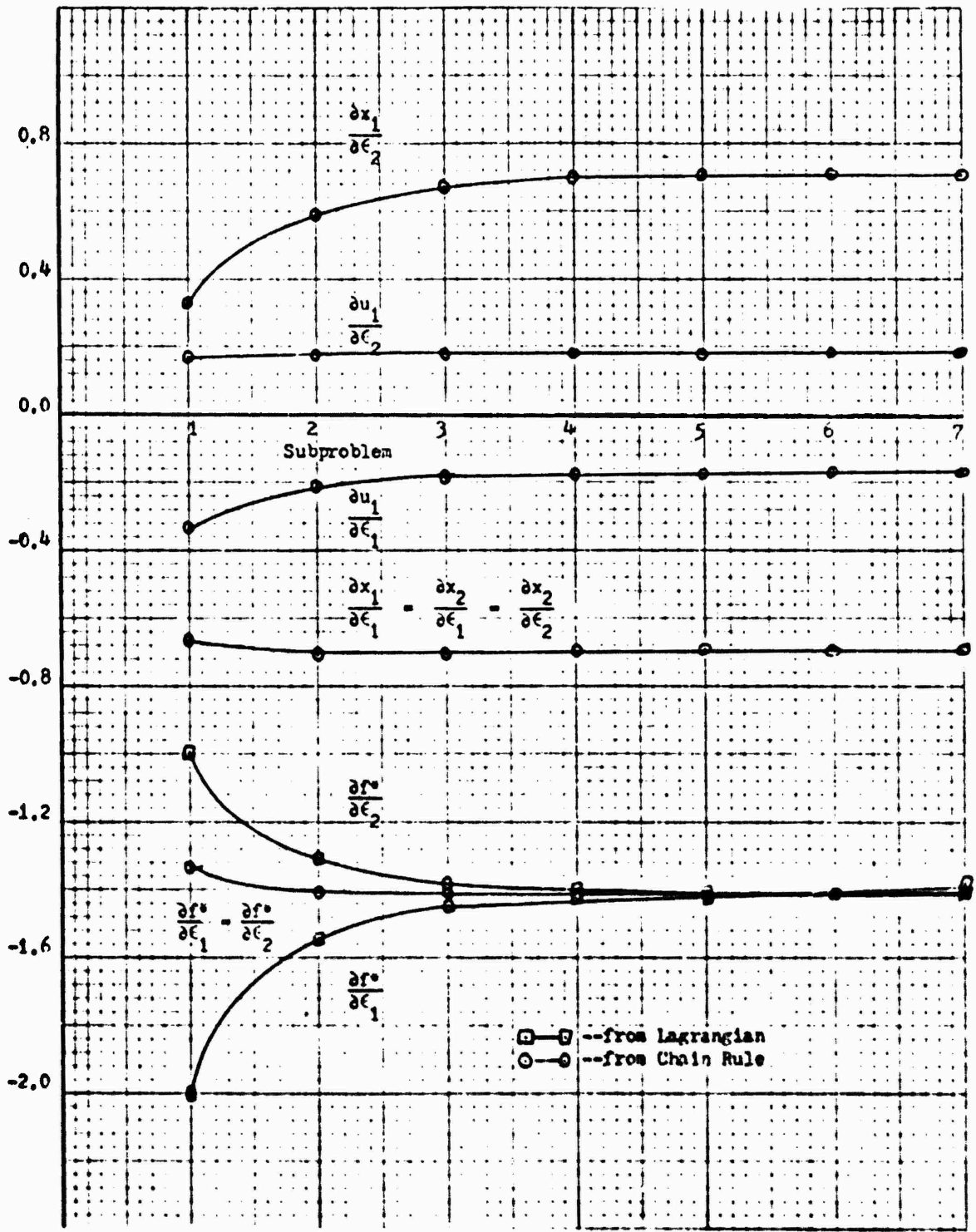


Fig. 1.--partial derivatives for Problem 4.

a similar way. In addition, since the estimate of the gradient of the optimal value function obtained by evaluating the partial derivatives of the Lagrangian taken with respect to the parameters includes the estimates of the Lagrange multipliers, it too will not be as accurate an estimate as the boundary is approached.

The next problem considered is a nonconvex program with an equality constraint. The problem is to

$$\begin{aligned}
 \text{minimize} \quad & f(x, \epsilon) = x_1 + x_2 + \ln x_3 - x_4 \\
 \text{subject to} \quad & g_1(x, \epsilon) = -x_1^2 + x_2 \geq 0, \\
 & g_2(x, \epsilon) = x_1 \geq 0, \\
 & g_3(x, \epsilon) = x_3 - \epsilon_1 \geq 0, \\
 & h_1(x, \epsilon) = x_3^2 + x_4^2 - \epsilon_2^2 = 0,
 \end{aligned}$$

where $\epsilon_2 \geq \epsilon_1 \geq 0$ and $\epsilon_2 > 0$.

The analytical solution is:

$$\begin{aligned}
 f^*(\epsilon) &= \ln \epsilon_1 - \sqrt{\epsilon_2^2 - \epsilon_1^2}, \\
 x_1^*(\epsilon) = x_2^*(\epsilon) &= 0, \quad x_3^*(\epsilon) = 1, \quad x_4^*(\epsilon) = \sqrt{\epsilon_2^2 - \epsilon_1^2}, \\
 u_1^*(\epsilon) = u_2^*(\epsilon) &= 1, \\
 u_3^*(\epsilon) &= 1/\epsilon_1 + \epsilon_1/\sqrt{\epsilon_2^2 - \epsilon_1^2},
 \end{aligned}$$

and

$$w_1^*(\epsilon) = 1/(2\sqrt{\epsilon_2^2 - \epsilon_1^2}).$$

The numerical example used has $\epsilon_1 = 1$ and $\epsilon_2 = 2$. The numerical solution derived analytically for the solution point, Lagrange multipliers and their gradients are:

$$\begin{aligned}
 f^* &\approx -1.732, & \nabla_{\epsilon} f^* &\approx (1.578, -1.157), \\
 x^* &\approx \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1.732 \end{bmatrix}, & \nabla_{\epsilon} x^* &\approx \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ -0.577 & 1.154 \end{bmatrix}.
 \end{aligned}$$

$$u^* \approx \begin{bmatrix} 1 \\ 1 \\ 1.732 \end{bmatrix}, \quad \nabla_{\epsilon} u^* \approx \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ -.231 & -.385 \end{bmatrix},$$

$$w^* \approx .289, \quad \nabla_{\epsilon} w^* \approx (.0962, -.1925).$$

The computed results for a trajectory sensitivity analysis are shown in Table 3.

The partial derivatives of the Lagrange multipliers shown in Table 3 are the only ones which are non-zero. Note that at the fifth and sixth subproblems, the estimates of the gradients of u_3 and w_1 are reasonably close to the true values determined analytically. It is at that point also that the estimates of u_3 and w_1 are the closest to their true values at the solution point. Notice also that the estimate of $\partial f^*/\partial \epsilon_2$ obtained from the partial derivative of the Lagrangian with respect to ϵ_2 is reasonably close to the true value. It is entirely dependent on w_1 and as the estimate for w_1 becomes less accurate, the error will be reflected in the first order sensitivity estimate of the optimal value function taken with respect to ϵ_2 . In the following example, the need for careful attention to the differencing increment is illustrated when the parameters are the right-hand sides of the constraints. For Problem C, a sensitivity analysis was conducted at the final subproblem for a range of differencing increments. The results were that the sensitivity estimates remained fairly constant over the range of differencing increments from 10^{-7} to 10^{-12} . Thus, the source of error in this case is solely the lack of accuracy of the estimates of the Lagrange multipliers for the binding constraints.

Two related problems called the Shell Primal and the Shell Dual were presented by Armacost and Fiacco (1974). However, computational

TABLE 3
TRAJECTORY RESULTS FOR PROBLEM C

Subproblem	Lagrangian		Chain rule		u_1	u_2	u_3	w_1	$\partial u_3 / \partial \epsilon_1$	$\partial u_3 / \partial \epsilon_2$	$\partial w_1 / \partial \epsilon_1$	$\partial w_1 / \partial \epsilon_2$	
	f	$\partial f / \partial \epsilon_1$	$\partial f / \partial \epsilon_2$	$\partial f / \partial \epsilon_2$									
1	.857	1.808	-1.500	1.252	-.948	.999	1.999	1.808	.375	.931	-.891	.222	-.316
2	-1.027	1.568	-1.216	1.538	-1.128	1.000	1.366	1.568	.304	.164	-.512	.128	-.217
3	-1.550	1.571	-1.172	1.573	-1.150	.999	1.123	1.570	.292	-.123	-.416	.104	-.198
4	-1.686	1.575	-1.158	1.576	-1.154	1.001	1.030	1.575	.289	-.203	-.392	.098	-.193
5	-1.720	1.574	-1.161	1.577	-1.154	.996	1.007	1.574	.290	-.219	-.388	.097	-.193
6	-1.729	1.576	-1.168	1.577	-1.154	.996	1.000	1.576	.292	-.219	-.390	.097	-.194
7	-1.731	1.585	-1.109	1.577	-1.154	1.000	1.006	1.585	.277	-.258	-.369	.092	-.184
8	-1.732	1.581	-1.045	1.577	-1.154	1.001	1.002	1.581	.261	-.303	-.348	.087	-.174
Analytical	-1.732	1.578	-1.157	1.578	-1.157	1.000	1.000	1.578	.289	-.231	-.385	.096	-.192

1
2
1

results were presented only for the Shell Dual. (The Shell Dual was developed as a test problem by the Shell Development Company and used by Colville (1968) in his comparative analysis of nonlinear programming codes.) Computational results are presented below for both the Shell Primal and the Shell Dual. The first problem considered is the Shell Primal.

$$\begin{aligned} \text{minimize} \quad & f(x, \epsilon) = \sum_{j=1}^n e_j x_j + \sum_{i=1}^n \sum_{j=1}^n x_i c_{ij} x_j + \sum_{j=1}^n d_j x_j^3 \\ \text{subject to} \quad & g_i(x, \epsilon) = \sum_{j=1}^n a_{ij} x_j - \epsilon_i \geq 0, \quad i=1, \dots, m, \end{aligned} \quad D$$

with $x_j \geq 0$, $j=1, \dots, n$. The dual problem is much more difficult to solve and is the one most often used in computational comparisons. The Shell Dual is to

$$\begin{aligned} \text{maximize} \quad & f(x, \epsilon) = \sum_{j=1}^m \epsilon_j y_j - \sum_{i=1}^n \sum_{j=1}^n x_i c_{ij} x_j - 2 \sum_{i=1}^n d_i x_i^3 \\ \text{subject to} \quad & g_i(x, \epsilon) = e_i + 2 \sum_{j=1}^n c_{ji} x_j + 3d_i x_i^2 \\ & - \sum_{j=1}^n a_{ji} y_j \geq 0, \quad i=1, \dots, n, \end{aligned} \quad E$$

with $x_i \geq 0$, $i=1, \dots, n$, and $y_j \geq 0$, $j=1, \dots, m$. In the numerical example used here, $n = 5$ and $m = 10$. The problem data is given in Table 3 of Armacost and Flacco (1974) and in Appendix C. The parameters of the sensitivity analysis are the variables ϵ_i , $i=1, \dots, 10$, the components of the right-hand sides of the primal constraints.

As a brief aside, the computational solution of the Shell Dual provided the motivation for some of the recent work in parametric sensitivity analysis by Armacost and Flacco. Specifically, Armacost and Flacco (1974) noted that in solving the dual problem, the partial

derivatives of the dual variables with respect to the right-hand sides of the primal constraints were obtained. With the correspondence between the dual variables and Lagrange multipliers and their interpretation as the partial derivatives of the optimal value function with respect to the right-hand sides of the primal constraints, it appeared that the second order partial derivatives of the optimal value function had been obtained. The calculations supported this conjecture since the matrix of partial derivatives of the dual variables with respect to the parameters was symmetric. Armacost and Fiacco (1976) have shown that when the parameters are the components of the right-hand side only, then the gradient of the Lagrange multiplier vector taken with respect to the parameters is the Hessian of the optimal value function. This matrix will be computed using the Shell Primal and then compared with the Hessian obtained by solving the Shell Dual.

In solving all of the sample problems, the option to screen the sensitivity estimates was used resulting in the partial derivatives being computed only for those parameters which affected the optimal value function by more than 0.1 percent of its current value. Annotated computer output for the final subproblem with sensitivity analysis data for the Shell Primal is shown in Figure 2. (The annotation applies to the computer output in Figures 3, 4, 5 and 6 as well.) The parameters are represented by the letter "A" vice "C" in the computer output. Similar output for the Shell Dual is shown in Figure 3. (Compare the sensitivity analysis portion with Figure 4 of Armacost and Fiacco (1974).) The sensitivity estimates for both problems were obtained by conducting a trajectory sensitivity analysis, i.e., a sensitivity analysis performed at each subproblem along the minimizing trajectory. Since the Shell Dual is a maximization problem and SURE is coded to solve a minimization problem, problem 2 is solved

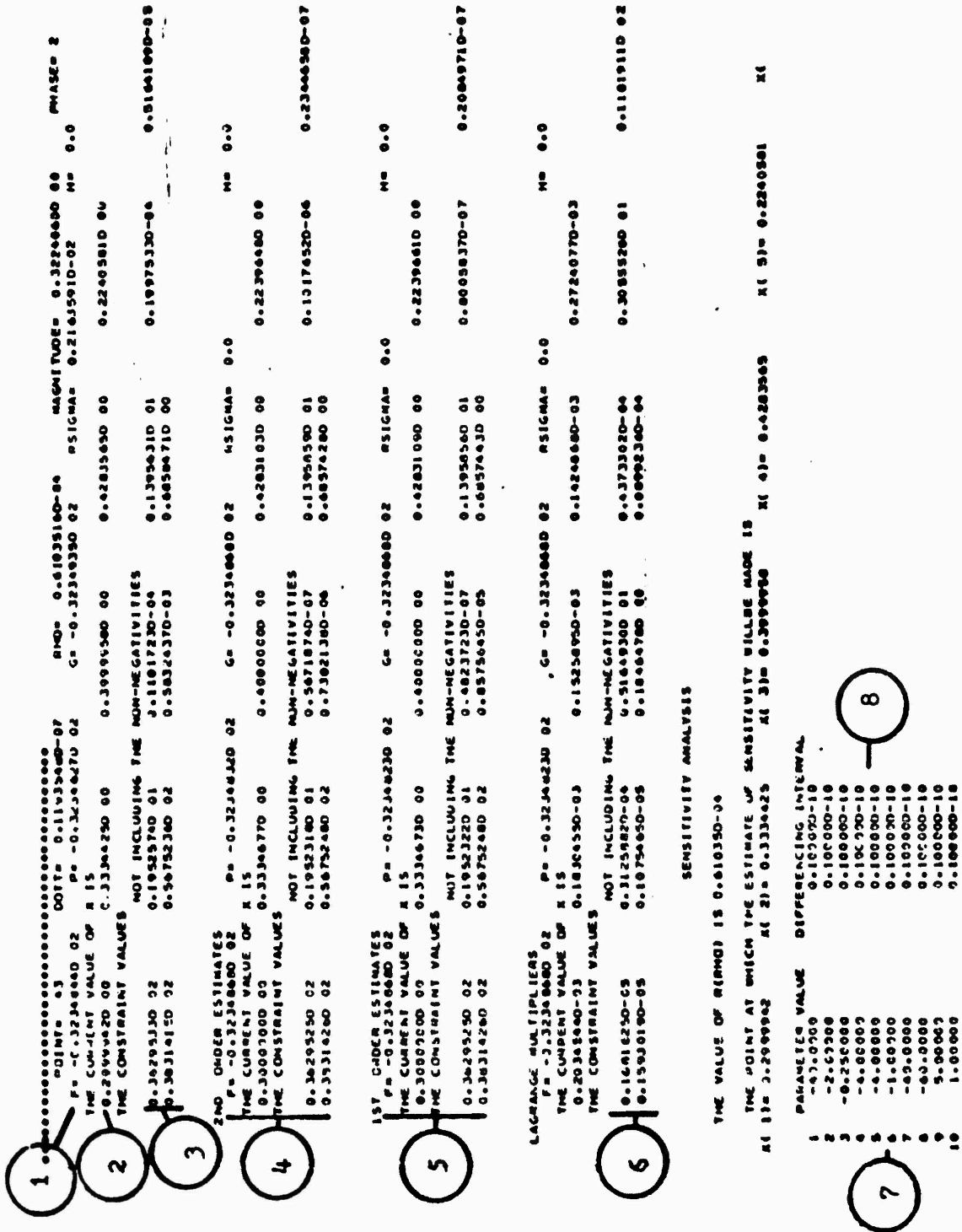


Fig. 2.--Shell Primal subproblem and sensitivity output.

OPTIMAL VALUE FUNCTION SENSITIVITY

9 DF/DAL 11= 0.1010700-05 CF/DAL 21= 0.1120400-04 DF/DAL 31= 5.164927 DF/DAL 41= 0.4373250-04 DF/DAL 51= 3.055494
DF/DAL 61= 11.61909 DF/DAL 71= 0.1542870-05 DF/DAL 81= 0.1075360-05 DF/DAL 91= 0.1043878 DF/DAL 101= 0.6892310-04

DETAILED SENSITIVITY RESULTS FOLLOW FOR PARAMETERS 10
3 . 5 . 6 . 9 .

11 R-DERIVATIVES ARE WITH RESPECT TO PARAMETER . J
DRI 11=C-300050 DRI 21= 0.0733740-01 DRI 31= 0.1909975 DRI 41= 0.2459346 DRI 51= 0.6789670-01 DRI
U-DERIVATIVES WITH RESPECT TO PARAMETER J
DUI 11= 0.3157470-05 DUI 21= 0.3450040-05 DUI 31= 4.071089 DUI 41= 0.30812470-04 DUI 51= 0.5663126 DUI 61= 3.471514
DUI 71= 0.1183370-07 DUI 81= 0.5719450-08 DUI 91= 0.1899914 DUI 101= 0.36930720-04 DUI

DF(DR(1)/DA)= 5.17404
0.000000

12 R-DERIVATIVES ARE WITH RESPECT TO PARAMETER . 5
DRI 11= 0.5722700-06 DRI 21= 0.1471101 DRI 31= 0.35330800-06 DRI 41= 0.49171810-01 DRI 51= 0.98155170-01 DRI
U-DERIVATIVES WITH RESPECT TO PARAMETER 5
DUI 11= 0.15704520-07 DUI 21= 0.75303430-05 DUI 31= 0.5662908 DUI 41= 0.12307150-04 DUI 51= 0.5051511 DUI 61= 0.6190303
DUI 71= 0.4769330-08 DUI 81= 0.55701140-08 DUI 91= 0.23921210-01 DUI 101= 0.12732600-04 DUI

DF(DR(1)/DA)= 3.06108
0.000000

13 R-DERIVATIVES ARE WITH RESPECT TO PARAMETER . 6
DRI 11= 0.1970961 DRI 21= 0.06431100-01 DRI 31= 0.3489971 DRI 41= 0.2281358 DRI 51= 0.27945040-01 DRI
U-DERIVATIVES WITH RESPECT TO PARAMETER 6
DUI 11= 0.16757800-06 DUI 21= 0.66706110-04 DUI 31= 3.471577 DUI 41= 0.35366940-04 DUI 51= 0.6190663 DUI 61= 7.192956
DUI 71= 0.0203990-08 DUI 81= 0.10932490-07 DUI 91= 1.580096 DUI 101= 0.25883760-04 DUI

DF(DR(1)/DA)= 11.0395
0.000000

R-DERIVATIVES ARE WITH RESPECT TO PARAMETER . 9
DRI 11= 0.3127220-C DRI 21= 0.39574130-01 DRI 31= 0.32994070-06 DRI 41= 0.75787080-01 DRI 51= 0.1542692 DRI
U-DERIVATIVES WITH RESPECT TO PARAMETER 9
DUI 11= 0.15506120-09 DUI 21= 0.46916310-05 DUI 31= 0.1699977 DUI 41= 0.11653320-04 DUI 51= 0.23614310-01 DUI 61= 1.589064
DUI 71= 0.79198540-03 DUI 81= 0.4295270-08 DUI 91= 0.634795 DUI 101= 0.24716170-04 DUI

DF(DR(1)/DA)= 9.103099
0.000000

Fig. 2.--Continued.

Identifier	Annotation
	Meaning
1	F = the value of the objective function at the current solution point.
2	The value of the components of the solution point of the current subproblem, here, x_1, \dots, x_5 .
3	The value of the constraints evaluated at the current solution point, i.e., $\epsilon_1, \dots, \epsilon_{10}$.
4	The data corresponding to 1 - 3 above when the solution point is a second order estimate based on the values in 2.
5	The same as 4, but the solution point is a first order estimate based on the values in 2. These values and those in 4 are extrapolations from the current solution estimate.
6	The estimates of the Lagrange multipliers based on the current value of r (RHO) and the current estimates of the solution point, in this case as $u_i = r/\epsilon_i(x, \epsilon)$, $i=1, \dots, 10$.
7	The value of the parameters, ϵ_i , $i=1, \dots, 10$.
8	The value of the differencing increment used in the central differencing formula for each of the parameters.
9	The estimates of the gradient of the optimal value function calculated by equation (3).
10	The parameters whose associated partial derivatives affect the optimal value function by more than 0.001 of its current value.
11	The first order sensitivity of the solution point calculated by equation (2).
12	The first order sensitivity of the Lagrange multipliers calculated using the method described following; equation (2).
13	The partial derivative of the optimal value function taken with respect to the indicated parameter and calculated by equation (4).

FIG. 2.--Continued.

```

*****
PUIVTS OF
F = 0.2734915D 02
THE CURRENT VALUE OF K IS
0.1604622D-05
0.1535861D-05
0.6300385D 00
THE CONSTRAINT VALUES
0.2736177D-03
0.1183384D-03
0.1528849D-03
0.1127815D-03
0.2729410D-03
*****
2ND ORDER ESTIMATES
F = 0.2734915D 02
THE CURRENT VALUE OF K IS
0.3267815D-06
0.3764177D-06
0.3964950D 00
THE CONSTRAINT VALUES
0.4884534D-06
0.3787882D-06
0.3349878D-06
*****
LAGRANGE MULTIPLIERS
F = 0.2734915D 02
THE CURRENT VALUE OF K IS
0.3023770D 02
0.3824541D 02
0.1525845D-03
THE CONSTRAINT VALUES
0.2994402D 00
0.3328260D 00
0.3398275D 00
*****
SENSITIVITY ANALYSIS
THE VALUE OF R(RMO) IS 0.610350-04
THE POINT AT WHICH THE ESTIMATE OF SENSITIVITY WILL BE MADE IS
K( 1) = 0.1604622D-05 K( 2) = 0.1535861D-05 K( 3) = 0.6300385D 00
K( 4) = 0.2736177D-03 K( 5) = 0.1183384D-03 K( 6) = 0.1528849D-03
K( 7) = 0.2729410D-03 K( 8) = 0.3267815D-06 K( 9) = 0.3764177D-06
K(10) = 0.3964950D 00 K(11) = 0.4884534D-06 K(12) = 0.3787882D-06
K(13) = 0.3349878D-06 K(14) = 0.3023770D 02 K(15) = 0.3824541D 02
K(16) = 0.1525845D-03 K(17) = 0.2994402D 00 K(18) = 0.3328260D 00
K(19) = 0.3398275D 00
*****
PARAMETER VALUE DIFFERENTIAL INTERVAL
1 -6C-0200 0.10000D-10
2 -2C-0200 0.10000D-10
3 -0.250000 0.10000D-10
4 -0.333330 0.10000D-10
5 -0.750000 0.10000D-10
6 -1.000000 0.10000D-10
7 -0.250000 0.10000D-10
8 -0.000000 0.10000D-10
9 5.000000 0.10000D-10
10 1.000000 0.10000D-10
*****
PHASE = 2
M = 0.0
MAGNITUDE = 0.5443617D 00
ASIGMA = 0.7054842D-02
RMO = 0.6103510D-04
ASIGMA = 0.7054842D-02
M = 0.0
0.4381135D-04
0.6815031D-04
0.3061097D 01
0.3000026D 00
0.1184054D 02
0.3334450D 00
0.1127815D-03
0.2729410D-03
0.3267815D-06
0.3764177D-06
0.3964950D 00
0.4884534D-06
0.3787882D-06
0.3349878D-06
0.3023770D 02
0.3824541D 02
0.1525845D-03
0.2994402D 00
0.3328260D 00
0.3398275D 00
0.4381135D-04
0.6815031D-04
0.3061097D 01
0.3000026D 00
0.1184054D 02
0.3334450D 00
0.1127815D-03
0.2729410D-03
0.3267815D-06
0.3764177D-06
0.3964950D 00
0.4884534D-06
0.3787882D-06
0.3349878D-06
0.3023770D 02
0.3824541D 02
0.1525845D-03
0.2994402D 00
0.3328260D 00
0.3398275D 00
0.4381135D-04
0.6815031D-04
0.3061097D 01
0.3000026D 00
0.1184054D 02
0.3334450D 00

```

Fig. 3.--Shell Dual subproblem and sensitivity output.

OPTIMAL VALUE FUNCTION SENSITIVITY

DF/DAL J1= 0.0 DF/DAL J1= 0.0 DF/DAL J1= -5.174173 DF/DAL J1= 0.0 DF/DAL J1= -3.061010
DF/DAL J2= -11.04066 DF/DAL J2= 3.0 DF/DAL J2= 0.0 DF/DAL J2= -0.104496 DF/DAL J2= -0.17763370-03

DETAILED SENSITIVITY RESULTS FOLLOW FOR PARAMETERS
J . 5 . 6 . 9 .

X-DERIVATIVES ARE WITH RESPECT TO PARAMETER . 3
DK(1)= 0.31907230-04 DK(2)= 0.36740500-05 DK(3)= 0.066262 DK(4)= 0.39966350-04 DK(5)= 0.5653876 DK(6)= 3.465049
DK(7)= -0.11876600-07 DK(8)= -0.37241330-08 DK(9)= 0.1894743 DK(10)= 0.37037780-04 DK(11)= -0.3993361 DK(12)= 0.97104790-01
DK(13)= -0.1996140 DK(14)= 0.2854635 DK(15)= -0.87701160-01 DK(16)= 0.37037780-04 DK(17)= -0.3993361 DK(18)= 0.97104790-01

U-DERIVATIVES WITH RESPECT TO PARAMETER J
DU(1)= 0.3090959 DU(2)= 0.97360610-01 DU(3)= 0.1999979 DU(4)= 0.2860099 DU(5)= -0.67970100-01 DU(6)= 0.2860099

DF(DER1)/DA= -5.17412
0.0000000

X-DERIVATIVES ARE WITH RESPECT TO PARAMETER . 5
DK(1)= 0.15967700-07 DK(2)= -0.75654290-05 DK(3)= -0.5653876 DK(4)= -0.12354650-04 DK(5)= 0.5043776 DK(6)= -0.6151088
DK(7)= -0.250250-08 DK(8)= -0.54030230-08 DK(9)= 0.23771030-01 DK(10)= 0.12779510-04 DK(11)= -0.9776610-05 DK(12)= -0.1466763
DK(13)= -0.10249670-05 DK(14)= -0.49099900-01 DK(15)= 0.97961440-01 DK(16)= 0.12779510-04 DK(17)= -0.9776610-05 DK(18)= -0.1466763

U-DERIVATIVES WITH RESPECT TO PARAMETER 6
DU(1)= 0.56912250-04 DU(2)= 0.1471216 DU(3)= -0.35180400-06 DU(4)= -0.49199600-01 DU(5)= 0.98181900-01 DU(6)= 0.98181900-01

DF(DER1)/DA= -3.06121
0.0000000

X-DERIVATIVES ARE WITH RESPECT TO PARAMETER . 6
DK(1)= 0.16410230-06 DK(2)= 0.67274700-04 DK(3)= 3.465049 DK(4)= 0.33522310-04 DK(5)= -0.6151072 DK(6)= 7.105064
DK(7)= -0.23229210-08 DK(8)= -0.10949900-07 DK(9)= 1.588282 DK(10)= 0.25973670-04 DK(11)= -0.1994387 DK(12)= 0.94303820-01
DK(13)= -0.3493977 DK(14)= 0.2278306 DK(15)= 0.28173220-01 DK(16)= 0.33522310-04 DK(17)= -0.6151072 DK(18)= 0.94303820-01

U-DERIVATIVES WITH RESPECT TO PARAMETER 6
DU(1)= 0.1649961 DU(2)= 0.94454450-01 DU(3)= -0.3499971 DU(4)= 0.2281903 DU(5)= 0.27081450-01 DU(6)= 0.27081450-01

DF(DER1)/DA= -11.0397
0.0000000

X-DERIVATIVES ARE WITH RESPECT TO PARAMETER . 9
DK(1)= 0.15591490-09 DK(2)= -0.67151480-05 DK(3)= 0.1694744 DK(4)= 0.11096380-04 DK(5)= 0.23771290-01 DK(6)= 1.906583
DK(7)= 0.79408010-08 DK(8)= 0.31141300-08 DK(9)= 0.9343746 DK(10)= -0.24603890-04 DK(11)= 0.93957130-04 DK(12)= -0.39006690-01
DK(13)= -0.28930610-04 DK(14)= 0.75689600-01 DK(15)= 0.1842322 DK(16)= 0.11096380-04 DK(17)= 0.23771290-01 DK(18)= -0.39006690-01

U-DERIVATIVES WITH RESPECT TO PARAMETER 9
DU(1)= 0.31109050-06 DU(2)= -0.39570260-01 DU(3)= 0.32640930-06 DU(4)= 0.75782260-01 DU(5)= 0.1842326 DU(6)= 0.1842326

DF(DER1)/DA= -0.104000
0.0000000

Fig. 3.--Continued.

by minimizing the negative of the objective function and therefore, the results in Fig 3 for the objective function value and the values of its partial derivatives must be multiplied by -1 to obtain the correct results. The variables $X(1) - X(10)$ in the Shell Dual correspond to the Lagrange multipliers in the Shell Primal and the variables $X(11) - X(15)$ in the Dual correspond to $X(1) - X(5)$ in the Primal. The components of the Hessian of the optimal value function then are the partial derivatives of $X(1) - X(10)$ in the Shell Dual and the u -derivatives in the Shell Primal. The dual variables, Lagrange multipliers, the partial derivatives of the optimal value function obtained by means of the Lagrangian, and those obtained using the chain rule are compared in Table 4.

TABLE 4
FIRST ORDER SENSITIVITY COMPARISON

1	Shell Primal			Shell Dual		
	u_1	$\partial f/\partial \epsilon_1$ (Lag.)	$\partial f/\partial \epsilon_1$ (C.R.)	x_1	$\partial f/\partial \epsilon_1$ (Lag.)	$\partial f/\partial \epsilon_1$ (C.R.)
1	$.168 \times 10^{-5}$	$.168 \times 10^{-5}$	-	$.168 \times 10^{-5}$	0.0	-
2	$.312 \times 10^{-4}$	$.312 \times 10^{-4}$	-	$.313 \times 10^{-4}$	0.0	-
3	5.1649	5.1649	5.1740	5.1742	5.1741	5.1741
4	$.437 \times 10^{-4}$	$.437 \times 10^{-4}$	-	$.438 \times 10^{-4}$	0.0	-
5	3.0555	3.0554	3.0610	3.0610	3.0610	3.0612
6	11.8191	11.8190	11.8395	11.8405	11.8406	11.8397
7	$.159 \times 10^{-5}$	$.159 \times 10^{-5}$	-	$.159 \times 10^{-5}$	0.0	-
8	$.107 \times 10^{-5}$	$.107 \times 10^{-5}$	-	$.107 \times 10^{-5}$	0.0	-
9	.1046	.1046	.1038	.1043	.1044	.1040
10	$.889 \times 10^{-4}$	$.889 \times 10^{-4}$	-	$.891 \times 10^{-4}$	$.177 \times 10^{-3}$	-

Since the preliminary screening option was used, detailed sensitivity estimates for the parameters which correspond to the non-binding inequality

constraints were not computed in Figures 2 and 3. In the Shell Primal, the Lagrange multipliers and the partial derivatives obtained by means of the Lagrangian correspond exactly. As noted in the discussions following Problems B and C, the estimates of the Lagrange multipliers for the binding constraints are very sensitive near the boundary of the constraint set. This explains the slight variation between these estimates and the other sensitivity estimates shown in Table 4 for the binding Primal constraints.

Now compare the second order sensitivity estimates with respect to the parameters which are the right-hand sides of the binding Primal constraints. Let H_D and H_P denote the submatrices of the Hessian of the optimal value function for the Dual and Primal respectively, obtained by deleting the rows and columns corresponding to the non-binding Primal inequality constraints. Thus, the components of H_D are $\partial x_1 / \partial \epsilon_j$, $1, j=3,5,6,9$, and the components of H_P are $\partial u_1 / \partial \epsilon_j$, $1, j=3,5,6,9$. From the computer output, these matrices are:

$$H_D = \begin{bmatrix} 4.0642 & -.5653 & 3.4650 & .1894 \\ -.5653 & .5043 & -.6151 & .0237 \\ 3.4650 & -.6151 & 7.1850 & 1.5885 \\ .1894 & .0237 & 1.5885 & .8343 \end{bmatrix}$$

and

$$H_P = \begin{bmatrix} 4.0710 & -.5663 & 3.4715 & .1899 \\ -.5662 & .5051 & -.6158 & .0239 \\ 3.4715 & -.6158 & 7.1929 & 1.5890 \\ .1899 & .0239 & 1.5890 & .8347 \end{bmatrix}$$

Both H_D and H_P are symmetric, and while the agreement is not exact, it is very close as anticipated.

Armacost and Fiacco (1974) indicate that the differencing interval

used in the sensitivity analysis can affect the accuracy of the results. For this reason, an option was provided by Armacost and Mylander (1973) to conduct the sensitivity analysis at the final subproblem for a range of differencing intervals. It is even more important to be cautious when dealing with right-hand side perturbations as the following discussion indicates. The results shown above for the Shell Primal and the Shell Dual were obtained with a trajectory sensitivity analysis and at the final subproblem, the differencing increment used in the central differencing formulas was 10^{-11} . The Hessian submatrices H_P and H_D were found to be very close. When the problems were solved using a sensitivity analysis at the final subproblem only with a differencing increment of 10^{-9} , the diagonal elements of H_P were considerably different from those of H_D . The problems were solved again with a sensitivity analysis performed at the final subproblem for a range of values of the differencing increment, ranging from 10^{-6} to 10^{-11} . The components of H_D remained constant as did the non-diagonal elements of H_P which were equal to the non-diagonal elements of H_D . The diagonal elements of H_P did not remain constant and their variation is depicted in Table 5.

The final example considered in this section is called the cattle feed problem. It was formulated and originally presented by van de Panne and Popp (1963). Armacost and Fiacco (1974) presented the cattle feed problem to illustrate an application of the sensitivity analysis. The additional sensitivity results are presented here for completeness. The problem is a chance-constrained program to determine the mix of inputs to cattle feed that will satisfy nutritive constraints and minimize the cost of the cattle feed. The protein content of the components is a random

TABLE 5
 VARIATION IN THE COMPONENTS OF H_p

Δ	$\partial^2 f / \partial \epsilon_1^2$			
	1=3	1=5	1=6	1=9
10^{-6}	-3148.3	-383.81	-89157.9	.8342
10^{-7}	-27.228	-3.328	-851.345	.8347
10^{-8}	3.758	.466	-1.389	.8347
10^{-9}	4.067	.504	7.107	.8347
10^{-10}	4.071	.505	7.191	.8347
10^{-11}	4.071	.505	7.192	.8347

variable, normally distributed with a mean and variance determined experimentally. The application of the sensitivity analysis included the standard deviations as parameters with the interpretation that if the solution were sensitive to a standard deviation, more sampling would be indicated in order to obtain a sharper estimate. The statement of the problem is

$$\begin{aligned}
 &\text{minimize} && f(x, \epsilon) = c_1 x_1 + c_2 x_2 + c_3 x_3 + c_4 x_4 \\
 &\text{subject to} && g_1(x, \epsilon) = a_1 x_1 + a_2 x_2 + a_3 x_3 + a_4 x_4 - \epsilon_7 \geq 0, \\
 & && g_2(x, \epsilon) = \mu_1 x_1 + \mu_2 x_2 + \mu_3 x_3 + \mu_4 x_4 && F \\
 & && + \epsilon_5 \sqrt{\epsilon_1^2 x_1^2 + \epsilon_2^2 x_2^2 + \epsilon_3^2 x_3^2 + \epsilon_4^2 x_4^2} - \epsilon_6 \geq 0, \\
 & && h_1(x, \epsilon) = x_1 + x_2 + x_3 + x_4 - 1 = 0,
 \end{aligned}$$

with $x_i \geq 0$, $i=1,2,3,4$. The notation is slightly different from Armacost and Fiacco (1974). Here, the parameters in the sensitivity analysis are denoted ϵ_1 . The correspondence with the previous work is $\epsilon_1 = \sigma_1$, $i=1,2,3,4$,

$\epsilon_5 = \phi$, $\epsilon_6 = p_m$ and $\epsilon_7 = o_m$. The problem data from Table 6 of Armacost and Fiacco (1974) are included in Appendix C. The sensitivity results for Problem F are shown in Figure 4. Again, the preliminary screening option was used to avoid calculating sensitivity estimates which did not affect the optimal value function significantly. Here, the components of the gradient of the optimal value function obtained directly from the gradient of the Lagrangian and the estimate of the gradient obtained by application of the chain rule are very close. The values of the Lagrange multipliers estimated in the SUMT program are $u_1 = 0.58037$, $u_2 = -.41005$ and $w_1 = -18.3738$. The multipliers u_1 and u_2 correspond to $\partial f^*/\partial \epsilon_7$ and $\partial f^*/\partial \epsilon_6$ respectively. Also note that second order sensitivity information for ϵ_6 and ϵ_7 is available since they are the right-hand sides of the two inequality constraints. Namely,

$$\partial^2 f^*/\partial \epsilon_7^2 = \partial u_1/\partial \epsilon_7 = .0112929,$$

$$\partial^2 f^*/\partial \epsilon_6 \partial \epsilon_7 = \partial u_1/\partial \epsilon_6 = .45706 \times 10^{-6},$$

$$\partial^2 f^*/\partial \epsilon_7 \partial \epsilon_6 = \partial u_2/\partial \epsilon_7 = .45671 \times 10^{-6},$$

$$\text{and} \quad \partial^2 f^*/\partial \epsilon_6^2 = \partial u_2/\partial \epsilon_6 = .46212 \times 10^{-3}.$$

The results shown in Figure 4 were obtained using a sensitivity analysis at the final subproblem for a range of differencing increments. For other values of the differencing increments not shown here, the optimal value function sensitivity estimates with respect to ϵ_6 and ϵ_7 obtained directly from the gradient of the Lagrangian and the cross-partial of u_1 and u_2 with respect to ϵ_6 and ϵ_7 do vary somewhat while the other sensitivity estimates remain relatively constant. In a practical sense, however, the cross-partial of u_1 and u_2 with respect to ϵ_6 and ϵ_7 are constant since they are of the order of 10^{-6} .

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SENSITIVITY ANALYSIS

THE VALUE OF RHPND IS 0.076900-E3

THE POINT AT WHICH THE PATHWAY OF SENSITIVITY BEGINS IS
 RE 110 0.4107573 RE 210 0.3917040-E2 RE 310 0.3130958 RE 410 0.5306070-E1 RE

PARAMETER	VALUE	DIFFERENCING INTERVAL
1	3.437000	0.100000-E0
2	7.000000	0.100000-E0
3	0.497000	0.100000-E0
4	0.787000	0.100000-E0
5	1.000000	0.100000-E0
6	21.0000	0.100000-E0
7	0.000000	0.100000-E0

OPTIMAL VALUE FUNCTION SENSITIVITY

DF/DAL 110 0.3042050-E1 DF/DAL 210 0.3132100-E2 DF/DAL 310 0.2001000 DF/DAL 410 0.1007000-E2 DF/DAL 510 0.0000000
 DF/DAL 610 0.4107573 DF/DAL 710 0.5003000 DF/DAL

DETAILED SENSITIVITY RESULTS FOLLOW FOR PARAMETERS
 1 2 3 4 5 6 7

U-DERIVATIVES ARE WITH RESPECT TO PARAMETER 1
 DUE 110-0.0000000-E2 DUE 210 0.2347000-E2 DUE 310-0.1300100-E1 DUE 410 0.0000000-E2 DUE

U-DERIVATIVES WITH RESPECT TO PARAMETER 2
 DUE 110-0.0000000-E1 DUE 210-0.0000000-E2 DUE

U-DERIVATIVES WITH RESPECT TO PARAMETER 3
 DUE 110-0.0000000 DUE

DF/DAL 11/DAL 0.0000000-E1
 00000000

U-DERIVATIVES ARE WITH RESPECT TO PARAMETER 4
 DUE 110-0.0000000-E1 DUE 210 0.3000000-E2 DUE 310 0.0000000-E1 DUE 410 0.1000000-E1 DUE

U-DERIVATIVES WITH RESPECT TO PARAMETER 5
 DUE 110 0.0000000-E1 DUE 210 0.0000000-E2 DUE

U-DERIVATIVES WITH RESPECT TO PARAMETER 6
 DUE 110 0.0000000 DUE

DF/DAL 11/DAL 0.0000000
 00000000

U-DERIVATIVES ARE WITH RESPECT TO PARAMETER 7
 DUE 110-0.0000000-E1 DUE 210 0.1000000-E1 DUE 310 0.0000000-E1 DUE 410 0.0000000-E1 DUE

U-DERIVATIVES WITH RESPECT TO PARAMETER 8
 DUE 110 0.0000000 DUE 210 0.0000000-E2 DUE

U-DERIVATIVES WITH RESPECT TO PARAMETER 9
 DUE 110 0.0000000 DUE

DF/DAL 11/DAL 0.0000000
 00000000

U-DERIVATIVES ARE WITH RESPECT TO PARAMETER 10
 DUE 110-0.0000000-E1 DUE 210-0.0000000-E2 DUE 310 0.0000000-E2 DUE 410 0.0000000-E1 DUE

U-DERIVATIVES WITH RESPECT TO PARAMETER 11
 DUE 110 0.0000000-E1 DUE 210 0.0000000-E2 DUE

U-DERIVATIVES WITH RESPECT TO PARAMETER 12
 DUE 110 0.0000000-E2 DUE

DF/DAL 11/DAL 0.0000000
 00000000

U-DERIVATIVES ARE WITH RESPECT TO PARAMETER 13
 DUE 110-0.0000000-E1 DUE 210 0.0000000-E2 DUE 310 0.0000000 DUE 410-0.0000000-E1 DUE

U-DERIVATIVES WITH RESPECT TO PARAMETER 14
 DUE 110 0.1120000-E1 DUE 210 0.0000000-E2 DUE

U-DERIVATIVES WITH RESPECT TO PARAMETER 15
 DUE 110 0.0000000-E1 DUE

DF/DAL 11/DAL 0.0000000
 00000000

Fig. 4.--Sensitivity results for Problem F.

5. Large-scale, Multi-item Inventory Model

Traditionally, inventory models have been formulated to minimize some function of the ordering, holding and shortage (or backorder) costs subject to various constraints. Schrady and Choe (1971) have formulated an inventory model which appears to have much greater relevance for an inventory system such as the U. S. Naval supply system. For the Navy, the costs used in the traditional models may be quite artificial while the real objective of the system is to maximize the service to the Fleet, an objective equivalent to minimization of stockouts. In addition, the stock points of the Naval supply system have investment and reorder workload constraints that are real and binding. Schrady and Choe consider a multi-item inventory system with the specific objective function of minimizing the total time-weighted shortages. The decision variables are the "reorder quantities" and the "reorder points," the decisions of how much to order and when to order, for each item in the inventory. Clearly, it is of interest to know "if" and "by how much" these variables and the value of the objective function will change if certain parameters change. Schrady and Choe solved a small example problem using the SUMT computer code. McCormick (1972) has shown how the special structure of this inventory model can be used to facilitate the use of the SUMT code to solve very large inventory problems. Here, the sensitivity analysis is applied to this model, a large-scale inventory system, and it is illustrated by means of the example used by Schrady and Choe.

The model presented here is due to Schrady and Choe. An extension of the model by McCormick (1972) includes constraints on storage volume and probability of depletion. The sensitivity results are easily applied to the extended model. Several assumptions specify the nature of the model. The

first is that all demand which occurs when the on-hand stock is zero, is back-ordered. The model is probabilistic in that the lead time demand is a random variable. Specifically, for the i^{th} variable, it is assumed that the demand which occurs during the time between the placement of an order and its receipt by the stock point is normally distributed with mean μ_i and variance σ_i^2 .

For the i^{th} item, let

- c_i - item unit cost (in dollars),
- λ_i - mean demand per unit time (in units),
- r_i - reorder point,
- Q_i - reorder quantity,
- $\phi(x)$ - the Normal(0,1) density function, and
- $\Phi(s)$ - the Normal(0,1) complementary cumulative distribution function = $\int_x^{\infty} \phi(x) dx$.

In addition, let K_1 be the investment limit in dollars, let K_2 be the reorder workload limit and let N be the total number of items in the inventory. The detailed development of the model is omitted here and the reader is referred to Schrady and Choe (1971) or McCormick (1972). A function needed from that development for the final model is

$$\beta_i(r_i) = \frac{1}{2}(\sigma_i^2 + (r_i - \mu_i)^2) \phi((r_i - \mu_i)/\sigma_i) - \frac{1}{2}Q_i(r_i - \mu_i) \phi((r_i - \mu_i)/\sigma_i).$$

Then the general multi-item model of Schrady and Choe is

$$\text{minimize } Z(Q,r) = \sum_{i=1}^N \beta_i(r_i)/Q_i$$

S-C

$$\text{subject to } \epsilon_1(Q, r) = K_1 - \sum_{i=1}^N c_i (r_i + Q_i/2 - \mu_i) \geq 0,$$

$$\epsilon_2(Q, r) = K_2 - \sum_{i=1}^N \lambda_i / Q_i \geq 0,$$

with r_i unrestricted, $Q_i \geq 0$, $i=1, \dots, N$, $Q = (Q_1, \dots, Q_N)^T$ and $r = (r_1, \dots, r_N)^T$.

To put the problem in (x, ϵ) notation, make the following identifications for $i=1, \dots, N$:

$$x_{2i-1} = Q_i,$$

$$x_{2i} = r_i,$$

$$\epsilon_{4i-1} = \mu_i,$$

$$\epsilon_{4i} = \sigma_i,$$

$$\epsilon_{4i+1} = c_i,$$

$$\epsilon_{4i+2} = \lambda_i,$$

and $\epsilon_1 = K_1$, $\epsilon_2 = K_2$. Rewrite Problem S-C as

$$\text{minimize } f(x, \epsilon) = \sum_{i=1}^N \beta_i(x_{2i}, \epsilon) / x_{2i-1} \quad \text{S-C}(\epsilon)$$

$$\text{subject to } \epsilon_1(x, \epsilon) = \epsilon_1 - \sum_{i=1}^N \epsilon_{4i+1} (x_{2i} + x_{2i-1}/2 - \epsilon_{4i-1}) \geq 0,$$

$$\epsilon_2(x, \epsilon) = \epsilon_2 - \sum_{i=1}^N \epsilon_{4i+2} / x_{2i-1} \geq 0,$$

$x_{2i-1} \geq 0$, x_{2i} unrestricted, $i=1, \dots, N$, and

$$\beta_i(x_{2i}, \epsilon) = \frac{1}{2} ((\epsilon_{4i}^2 + (x_{2i} - \epsilon_{4i-1})^2) \Phi((x_{2i} - \epsilon_{4i-1}) / \epsilon_{4i}) - \epsilon_{4i} (x_{2i} - \epsilon_{4i-1}) \Phi((x_{2i} - \epsilon_{4i-1}) / \epsilon_{4i})).$$

Schrady and Choe consider a three item example. The problem data and the initial starting point for the SUMT program are shown in Table 6.

TABLE 6
MULTI-ITEM INVENTORY PROBLEM DATA

Item	i=1	i=2	i=3
Data:			
$\mu_1 = \epsilon_{41-1}$	100	200	300
$\sigma_1 = \epsilon_{41}$	100	100	200
$c_1 = \epsilon_{41+1}$	1	10	20
$\lambda_1 = \epsilon_{41+2}$	1,000	1,500	2,000
Starting point:			
$Q_1 = x_{21-1}$	600	270	300
$r_1 = x_{21}$	200	260	400

In addition, $K_1 = \epsilon_1 = \$8,000$ and $K_2 = \epsilon_2 = 15$.

Figure 5 contains the computer output for the final subproblem of a trajectory sensitivity analysis for Problem S-C(ϵ) using the data of Table 6. The results indicate that the optimal value function is sensitive to parameters 2, 5, 8, 9, 12, and 13, i.e., K_2 , c_1 , σ_2 , c_2 , σ_3 and c_3 respectively. The fact that the solution is sensitive to the values of the standard deviations of the lead time demand of two items lets the decision maker know that since these parameters were obtained by sampling, a possible action may be to conduct additional sampling in order to sharpen the estimate of the standard deviation.

The solution value is also very sensitive to all of the item costs. If the structure of Problem S-C is examined, this result is most surprising since the c_1 appear only in the investment constraint and the optimal value function is not very sensitive to the investment limit K_1 . Recall, however,

```

*****
POINTS 35      DDIT= 0.2555000-07      RMS= 0.0103180-04      MAGNITUDE= 0.22017350-02      PHASE= 2
P= 0.1250000 02      P= 0.1250000 02      G= 0.1200000 02      MSIGMA= -0.12010910-02      M= 0.0
THE CURRENT VALUE OF X IS
0.5331710 03      0.25277810 03      0.24555100 03      0.27700770 03      0.28503760 03      0.43661080 03
THE CONSTRAINT VALUES
0.11784680-01      NOT INCLUDING THE NON-NEGATIVES
0.97960500-00

2ND ORDER ESTIMATES
P= 0.1250000 02      P= 0.1250000 02      G= 0.1200000 02      MSIGMA= 0.0      M= 0.0
THE CURRENT VALUE OF X IS
0.5331710 03      0.25277770 03      0.24555060 03      0.27700830 03      0.28503650 03      0.43651220 03
THE CONSTRAINT VALUES
-0.13226120-03      NOT INCLUDING THE NON-NEGATIVES
0.20330000-00

1ST ORDER ESTIMATES
P= 0.1250000 02      P= 0.1250000 02      G= 0.1200000 02      MSIGMA= 0.0      M= 0.0
THE CURRENT VALUE OF X IS
0.5331710 03      0.2527770 03      0.24555060 03      0.27700830 03      0.28503600 03      0.43661230 03
THE CONSTRAINT VALUES
-0.13101900-03      NOT INCLUDING THE NON-NEGATIVES
0.20330000-00

LAGRANGE MULTIPLIERS
P= 0.1250000 02      P= 0.1250000 02      G= 0.1200000 02      MSIGMA= 0.0      M= 0.0
THE CURRENT VALUE OF X IS
0.1100750-06      0.24103780-06      0.24082330-06      0.22033740-06      0.21013020-06      0.13079300-06
THE CONSTRAINT VALUES
0.31778570-02      NOT INCLUDING THE NON-NEGATIVES
0.02202030 00

SENSITIVITY ANALYSIS
THE VALUE OF R(RMS) IS 0.0103180-04
THE POINT AT WHICH THE ESTIMATE OF SENSITIVITY WILL BE MADE IS
R( 1)= 533.1717      R( 2)= 252.7781      R( 3)= 245.5100      R( 4)= 277.0077      R( 5)= 285.0376      R( 6)= 436.6106

PARAMETER VALUE      DIFFERENCING INTERVAL
1  020.000      0.100000-10
2  15.0000      0.100000-10
3  100.000      0.100000-10
4  100.000      0.100000-10
5  100.000      0.100000-10
6  100.000      0.100000-10
7  200.000      0.100000-10
8  100.000      0.100000-10
9  100.000      0.100000-10
10 100.000      0.100000-10
11 100.000      0.100000-10
12 200.000      0.100000-10
13 200.000      0.100000-10
14 200.000      0.100000-10

```

Fig. 5.--Computer output for Schrady-Choe inventory problem.

IMPITAL VALUE FUNCTION SENSITIVITY

DF/DA1 11=-0.51797570-02 DF/DA1 21=-0.022224 DF/DA1 31=-0.2022160-04 DF/DA1 41= 0.11157180-01 DF/DA1 51= 2.171260
DF/DA1 61= 0.11699590-02 DF/DA1 71=-0.2022160-03 DF/DA1 81= 0.89706030-01 DF/DA1 91= 1.3334539 DF/DA1 101= 0.253385080-02
DF/DA1 111=-0.76628340-03 DF/DA1 121= 0.1722345 DF/DA1 131= 1.445152 DF/DA1 141= 0.21657450-02 DF/DA1

DETAILED SENSITIVITY RESULTS FOLLOW FOR PARAMETERS
2 . 3 . 4 . 9 . 12 . 13 .

R-DERIVATIVES ARE WITH RESPECT TO PARAMETER . 2
DA1 11= -07.31873 DA1 21= 5.226528 DA1 31= -10.76101 DA1 41= 0.196130 DA1 51= -14.00654 DA1 61= 9.967083

U-DERIVATIVES WITH RESPECT TO PARAMETER 2
DU1 11=-0.16231410-03 DU1 21=-0.1381545 DU1

DF(X1(1))/DA= -0.425665
00000000

R-DERIVATIVES ARE WITH RESPECT TO PARAMETER . 5
DA1 11= -208.8669 DA1 21= -31.79176 DA1 31= 15.31396 DA1 41= -10.34249 DA1 51= 14.37551 DA1 61= -20.00203

U-DERIVATIVES WITH RESPECT TO PARAMETER 5
DU1 11= 0.06036710-03 DU1 21= 0.1635012 DU1

DF(X1(4))/DA= 2.15929
00000000

R-DERIVATIVES ARE WITH RESPECT TO PARAMETER . 8
DA1 11=-0.866421 DA1 21=-0.122265 DA1 31= 0.2271026 DA1 41= 1.033795 DA1 51=0.1066107 DA1 61=-0.6918837

U-DERIVATIVES WITH RESPECT TO PARAMETER 8
DU1 11= 0.23757780-06 DU1 21= 0.6307420-03 DU1

DF(X1(8))/DA= 0.8053020-01
00000000

R-DERIVATIVES ARE WITH RESPECT TO PARAMETER . 9
DA1 11= 0.180797 DA1 21= -2.678276 DA1 31= -0.971093 DA1 41= -7.267639 DA1 51= 3.652195 DA1 61= -7.106662

U-DERIVATIVES WITH RESPECT TO PARAMETER 9
DU1 11= 0.23822300-03 DU1 21= 0.48914290-01 DU1

DF(X1(9))/DA= 1.22862
00000000

R-DERIVATIVES ARE WITH RESPECT TO PARAMETER . 12
DA1 11= -1.237436 DA1 21=-0.261058 DA1 31=-0.4033268 DA1 41=-0.2639144 DA1 51= 0.5042921 DA1 61= 0.44637070-01

U-DERIVATIVES WITH RESPECT TO PARAMETER 12
DU1 11= 0.2088460-06 DU1 21= 0.19939320-02 DU1

DF(X1(12))/DA= 0.172936
00000000

R-DERIVATIVES ARE WITH RESPECT TO PARAMETER . 13
DA1 11=-0.1609796 DA1 21= -2.307463 DA1 31= 0.0442031 DA1 41= -3.170249 DA1 51=-0.4251138 DA1 61= -12.15228

U-DERIVATIVES WITH RESPECT TO PARAMETER 13
DU1 11= 0.27499190-03 DU1 21= 0.32200950-01 DU1

DF(X1(13))/DA= 1.43768
00000000

Fig. 5. --Continued.

that when the partial derivatives are used as sensitivity estimates, one is effectively saying "how much will the objective function (or solution point) change if the parameter is increased by one unit?" Suppose c_1 (parameter 5) is increased by one unit from one to two. Using a linear estimate, the objective function is expected to increase by 2.16 to 15.15 and Q_1 (variable x_1) is expected to decrease by 208 units to 325. Figure 6 contains the computer output for the perturbed problem with $c_1 = 2$. Note that the value of the optimal value function increased to 14.99 and Q_1 decreased to 411. The changes were quite large and in the directions expected but of course not as large as the linear estimate. Notice, however, that this change in c_1 represented a 100 % increase in the value of the parameter. For purposes of comparison, consider a similar change in the investment constraint K_1 (parameter 1) to which the solution is apparently insensitive. Using the optimal value function sensitivity estimate (-0.00517), a 100% increase in the value of the parameter is 8,000 and consequently, a linear estimate of the expected change in the optimal value function would be $(8,000 \times -0.00517 =)$ -41.36. The above example does not imply that equivalent percentage changes in parameter values is relevant but rather is meant to emphasize that the sensitivity estimates are valid for a small neighborhood of the given parameter values and as such represent instantaneous changes.

The solution values in Figure 5 are slightly different from those presented in Schradly and Choe (1971). This difference is due to the use of

```

*****
POINT= 36
DUTTS 3-1849450D-07      EMO= 0-6103510D-C6      MAGNITUDE= 0-1666201D-02      PHASE= 2
F= -1409577D 02      F= 0-1499587D 02      G= 0-1499580D 02      PSIGMA= -0-1242409D-02      M= 0-0
THE CURRENT VALUE OF R IS
0-018250D 03      0-2205680D 03      0-2574781D 03      0-2684021D 03      0-2965231D 03      0-4197297D 03
THE CONSTRAINT VALUES NOT INCLUDING THE NON-NEGATIVES
0-1078350D-01      0-7436540D-04

2ND ORDER ESTIMATES
F= 0-1499587D 02      F= 0-1499587D 02      G= 0-1499580D 02      PSIGMA= 0-0      M= 0-0
THE CURRENT VALUE OF R IS
0-0110231D 03      0-2205680D 03      0-2574781D 03      0-2684021D 03      0-2965231D 03      0-4197297D 03
THE CONSTRAINT VALUES NOT INCLUDING THE NON-NEGATIVES
0-1091200D-04      0-1400232D-06

1ST ORDER ESTIMATES
F= 0-1499587D 02      F= 0-1499587D 02      G= 0-1499580D 02      PSIGMA= 0-0      M= 0-0
THE CURRENT VALUE OF R IS
0-011820D 03      0-2205680D 03      0-2574781D 03      0-2684021D 03      0-2965231D 03      0-4197297D 03
THE CONSTRAINT VALUES NOT INCLUDING THE NON-NEGATIVES
0-2552402D-04      0-1043250D-06

LAGRANGE MULTIPLIERS
F= 0-1499587D 02      F= 0-1499587D 02      G= 0-1499580D 02      PSIGMA= 0-0      M= 0-0
THE CURRENT VALUE OF R IS
0-1082785D-06      0-2670324D-06      0-2374800D-06      0-2274020D-06      0-2058354D-06      0-1454158D-06
THE CONSTRAINT VALUES NOT INCLUDING THE NON-NEGATIVES
0-5073535D-02      0-7071040D 00

SENSITIVITY ANALYSIS
THE VALUE OF (RMIN) IS 0-01035D-04
THE POINT AT WHICH THE ESTIMATE OF SENSITIVITY WILL BE MADE IS
K( 1)= 611-0250      K( 2)= 228-5583      K( 3)= 257-4793      K( 4)= 268-0021      K( 5)= 296-8241      K( 6)= 419-7285

PARAMETER VALUE DIFFERENCING INTERVAL
1  002-00      0-1710D-10
2  15-0000      0-1030D-10
3  129-000      0-1370D-10
4  122-000      0-13990D-10
5  2-00700      0-1700D-10
6  100-00      0-10007D-10
7  200-00      0-1000D-10
8  173-00      0-1300D-10
9  170-000      0-1070D-10
10 1500-00      0-1000D-10
11 320-000      0-1000D-10
12 203-000      0-1000D-10
13 203000      0-1000D-10
14 2000-00      0-1300D-10

```

Fig. 6.--Computer output for perturbed Schrady-Choe problem.

two different approximations to the complementary cumulative normal distribution. While the solution values vary only slightly with these different estimates of the normal distribution, the variations in the Lagrange multipliers and some sensitivity estimates are greater. For the system library subroutine using the normal distribution error function (erf) to estimate the complementary cumulative distribution, the minimizing trajectory of subproblems showed that the estimate of the Lagrange multipliers deviated from what appeared to be a relatively constant value as the final subproblem was approached. As expected, the optimal value function sensitivity estimates obtained directly from the Lagrangian varied in almost direct proportion with the estimates of the Lagrange multipliers. In Figures 5 and 6, the estimates of the optimal value function sensitivity obtained by the two different methods (chain rule and Lagrangian) are in close agreement. This was not the case using the erf-related subroutine used by Schradly and Choe. This is the same effect experienced in other problems as discussed in Section 4. In this case, however, the x -derivatives are affected to a slight degree. The major source of this error appears to be the lack of necessary precision associated with the erf-related subroutine for the complementary cumulative normal distribution. The conclusion can only be that one must proceed with caution. From this and other examples, however, it appears that convergence of the Lagrange multiplier estimates along the minimizing trajectory is a good indication that the sensitivity estimates will be accurate.

This large-scale inventory example illustrates a potential "real world" application of sensitivity analysis. It also highlights the need for a careful interpretation of the sensitivity information as well as the recurrent call for caution in the use of a numerical algorithm.

6. Conclusions

The purpose of this paper was to present examples of computational implementation of sensitivity analysis with respect to the optimal value function and the Lagrange multipliers using the theoretical results of Fiacco (1973) and Armacost and Fiacco (1975, 1976). All of the problems presented led to new insights into the computational aspects of this type of sensitivity analysis.

The major conclusion is that the sensitivity estimates of the optimal value function obtained directly from the gradient of the Lagrangian, the partial derivatives of the Lagrange multipliers associated with the binding constraints, and to a lesser extent, the partial derivatives of the solution point, are dependent on the accuracy of the estimate of the Lagrange multipliers calculated in the penalty function algorithm and subsequently used in the gradient of the Lagrangian. If the estimates of the Lagrange multipliers along the minimizing trajectory converge to a common value, then it appears that the sensitivity estimates will converge to their true values provided the differencing increment is satisfactory. If, however, the Lagrange multipliers converge and then vary, the sensitivity estimates should be viewed with caution. (Note that the Lagrange multiplier estimates are available in the standard SUMT output and a trajectory analysis is not required.)

Armacost and Fiacco (1974) noted that the differencing increment used in the central differencing formulas was a potential source of error depending on the scaling of the problem. The same caution applies when dealing with Lagrange multiplier and optimal value function sensitivity.

The example problems which included right-hand side parameters indicated that the optimal value function second order sensitivity estimates are themselves very sensitive to the Lagrange multiplier estimates, the differencing increment and the scaling of the problem. It appears that further analysis is needed before this particular program can be used to take advantage of second order sensitivity estimates to improve algorithm performance. This is particularly true for the second partial derivatives of the optimal value function taken with respect to the right-hand side of a binding constraint.

Computer time was provided by The George Washington University Computer Center.

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APPENDIX A

SUBROUTINES SENS, LMULT AND PRESEN

```

0001      SUBROUTINE SENS                                016680
C                                                    016690
C                                                    016700
C              IS MARCH 1972                          016710
C                                                    016720
C THIS VERSION OF THE SENSITIVITY ANALYSIS SUBROUTINE IS USED TO
C COMPUTE THE DIRECTIONAL DERIVATIVES OF X AND F WITH RESPECT TO
C CERTAIN PARAMETERS CODED IN THE ARRAY PAR(20). THE DIRECTIONAL
C DERIVATIVES ARE ESTIMATED FOR ONE PARAMETER AT A TIME WITH NPAP BEING
C THE NUMBER OF PARAMETERS INVOLVED IN THE SENSITIVITY ANALYSIS. THE
C USE OF THE PARAMETERS PAR(20) MUST BE CONSISTENT THROUGHOUT THE
C USER'S SUBROUTINES.                                016730
C THE SUBROUTINE IS USED FOR A SENSITIVITY ANALYSIS AT THE FINAL SUB-
C PROBLEM OR FOR A SENSITIVITY ANALYSIS AT EACH SUBPROBLEM ALONG THE
C MINIMIZING TRAJECTORY. DPAF(20) IS THE ARRAY OF DIFFERENCING
C INTERVALS CORRESPONDING TO THE PARAMETERS PAR(20). DPAH(20) IS
C ASSIGNED VALUES IN SUBROUTINE MARDIP.              016740
C THIS APPROACH TO SENSITIVITY ANALYSIS IS DUE TO A. V. FIACCO. THE
C FIRST VERSION WAS CODED BY M. CAUSEY. THE SECOND VERSION WAS CODED
C BY R. C. NYLANDER. THIS IS THE THIRD VERSION WHICH IS AN EXTENSION
C OF THE SECOND VERSION TO PERMIT SENSITIVITY ANALYSIS ALONG THE
C MINIMIZING TRAJECTORY, AND WAS CODED BY R. L. ARMACOST. 016750
C IMPLICIT REAL*8(A-H,O-Z)                            016760
C REAL*8 ENGIN,PATIO,EPSE,THETA,KEP1,KEP2           016770
C COMMON/ENGIN/ZE(20),DEL(20),A(27,27),N,M,NN,NPI,NMI 016780
C COMMON/OAL/ZH,M,PZ                                   016790
C COMMON/ZENTIN/NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10 015790
C COMMON/VALU/DF,G,DP,RSIGMA,RSIGMA0,UMH            015800
C COMMON/CPST/DEL(20),DEL(20),F(20),F(20),K(20),K(20),X(20),X(20),PP1, 016810
C INTG1,UMIN1,RE(20),R2(20),R3(20),R4(20),R(20),X(20),PP1, 016820
C ZM(20),F1,F1,UM(20),DOTT,INCFAD(20),DIAG(20), 016830
C J(15),ACFL,RSIG,CL,MPHASE,NSATIS                  016840
C COMMON/SEN/PAR(20),IPAR(20),NPAP,ISENS            016850
C COMMON/EXOP/ZE(20),NE(20),NE(20),NE(20),NE(20),NE(20),KEP1,KEP2 016860
C DIMENSION DELT(20),DELT(20),RPH(20),R3M(20)        016870
C DIMENSION DELMUL(40),DM(40),KTEST(20)             016880
C I=0;PA=1                                           016890
C I=0;NS=0                                           016900
C DO 5 I=1,N
C   DELT(I)=DELT(I)
C   S DELT(I)=DELT(I)
C   CALL STMP
C   AVAL=1.0E-10
C   PHM=0.0E+00
C   INNS=ISENS+1
C   CALL PAICP
C   WRITE(4,10) ENO AND PAP.                          016910
C   WRITE(4,10) ENO                                  017020
C 10 FORMAT(//70X,20SENSITIVITY ANALYSIS //         017030
C 15X,20THE VALUE OF PARAMETER IS ,E12.5I
C 20X)
C 20 FORMAT(//40X,80THE POINT AT WHICH THE ESTIMATE OF SENSITIVITY WILL
C 10X MAUT IS )
C   DO 4 I=1,N
C     I=I+1
C     WRITE(4,30) (I,RE(I),J(1,1))
C 30 FORMAT(612X,24E12.2M0,610.7I )
C 40 CONTINUE
C   WRITE(4,50) (I,PAR(I),IPAR(I)), I=1,NPAP)        017040
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016990
017000
017010
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017100
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017120
017130
017140
017150
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017190
017200
017210
017220

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```

0106      130  IF ENCR(FA,FO,CI) GO TO 139
0107      CALL LMULTI2,DELPU,DEM,DUI
0108      139  CALL GRAD(2)
0109      DE(1) = VAL(2) / DEM
0110      DO 142 I=1,N
0111      DEL(1) = DEL(1) + DEL(1) * DEL(1) / DEM
0112      140  CONTINUE
0113      PA(1) = VAL(1)
C HAVING ALREADY FACTORED A, SOLVE AX+Y FOR X.
C WRITE NUMBER AND ORDER/DATA(J).
0114      CALL EMV(1,2)
C PRINT OUT L(1) / A(1)
0115      WRITE(10,12) J
0116      150  FORMAT(17H  A-DERIVATIVES ARE WITH RESPECT TO PARAMETER ,(I2)
0117      DO 170 I=1,N,A
0118      I(1) = MIN(105,M)
0119      WRITE(10,17) ((J,DEL(J)), J=1,I(1))
0120      160  FORMAT(14H  DEL,(I2,2H) =,G10,7) )
0121      170  CONTINUE
0122      IF ENCR(FA,FO,CI) GO TO 175
0123      IF ENCR(FA) GO TO 371
0124      CALL LMULTI3,DELPU,DEM,DUI
0125      DE(1) = VAL(1) / DEM
0126      350  FORMAT(17H  A-U-DERIVATIVES WITH RESPECT TO PARAMETER ,(I2)
0127      DO 370 I=1,N,A
0128      I(1) = MIN(105,M)
0129      WRITE(10,17) ((J,DEL(J)), J=1,I(1))
0130      352  FORMAT(14H  DEL,(I2,2H) =,G10,7) )
0131      360  CONTINUE
0132      IF ENCR(FO,CI) GO TO 375
0133      CALL LMULTI4,DELPU,DEM,DUI
0134      DE(1) = VAL(1) / DEM
0135      360  FORMAT(17H  A-W-DERIVATIVES WITH RESPECT TO PARAMETER ,(I2)
0136      DO 380 I=1,N,A
0137      I(1) = MIN(105,M)
0138      WRITE(10,17) ((J,DEL(J)), J=1,I(1))
0139      362  FORMAT(14H  DEL,(I2,2H) =,G10,7) )
0140      361  CONTINUE
0141      375  CONTINUE
C COMPUTE ORDER/DATA(J).
0142      DO 142 I=1,N
0143      OF = OF + MIN(1) * DEL(1)
0144      180  CONTINUE
C PRINT ORDER/DATA(J).
0145      @ WRITE(10,19) OF
0146      190  FORMAT(17H  ORDER/DATA =,G10,6/10H  *****/)
0147      200  CONTINUE
0148      GO TO 222
0149      201  WRITE(10,19) J
0150      106  FORMAT(17H  TERMINATING PARAMETER,(I3,10H  DUE TO DEAD = 0 /)
0151      GO TO 200
0152      202  RETURN
0153      CALL DIFCTY
0154      DO 205 I=1,N
0155      DEL(1) = DEL(1)
0156      225  DEL(1) = DEL(1)
0157      RETURN
0158      END

```

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```



```

0031      SUBROUTINE PROSENS(DU,KTEST)
0032      IMPLICIT REAL*4(A-H,I-Z)
0033      COMMON/1/MARL(20),DEL(20),A(20,20),N,M,MN,NP1,NM1
0034      COMMON/2/VALU(20),FG,FSIGMA,RJ(40),RHO
0035      COMMON/3/GAL(4),M1,M2
0036      COMMON/4/N/PAK(20),DPAK(20),NPAK,ISENS
0037      DIMENSION GX(40),DU(40),KTEST(20),KLIST(20)
0038      MPMZ = M * M2
0039      FTST = C.C(0) * DABS(F)
0040      DO 100 J=1,NPAK
0041      KTEST(J) = 0
0042      PAK(J) = PAK(J) + DPAK(J)
0043      CALL RESNT(0,DF)
0044      IF(MPMZ.FG.0) GO TO 20
0045      DO 11 I=1,MPMZ
0046      CALL RESNT(I,DU(I))
0047      CONTINUE
0048      DEM = 2. * DPAK(J)
0049      PAK(J) = PAK(J) - DEM
0050      CALL RESNT(0,RF)
0051      IF(MPMZ.FG.0) GO TO 40
0052      DO 30 I=1,MPMZ
0053      CALL RESNT(I,GX(I))
0054      CONTINUE
0055      DFFPS = (DF - RF)/DEM
0056      IF(MPMZ.FG.0) GO TO 60
0057      DO 50 I=1,MPMZ
0058      DU(I) = (DU(I) - GX(I))/DEM
0059      SUM = DFFPS
0060      IF(M.FG.0) GO TO 80
0061      DO 70 I=1,M
0062      SUM = SUM - RHC/RJ(I)*DU(I)
0063      IF(M2.FG.0) GO TO 95
0064      TSUM = 0.
0065      DO 90 I=1,M2
0066      IM = 1+M
0067      TSUM = TSUM + RJ(IM)*DU(IM)
0068      SUM = SUM + TSUM * 2./RMO
0069      DEL(J) = SUM
0070      PAK(J) = PAK(J) + DPAK(J)
0071      DTEST = DABS(DEL(J))
0072      IF(DTEST.GE.FTEST) KTEST(J) = 1
0073      CONTINUE
0074      WRITE(6,600)
0075      600  FORMAT(2X,'34MOPTIMAL VALUE FUNCTION SENSITIVITY  //')
0076      DO 200 I=1,NPAK,5
0077      I1=I+4
0078      WRITE(6,601) (JJ,DEL(JJ)), JJ=I,11)
0079      601  FORMAT(5(7H OF/DAL(12,2H)=,G14.7))
0080      CONTINUE
0081      JJ = 0
0082      DO 250 J=1,NPAK
0083      IF(KTEST(J).EQ.0) GO TO 250
0084      JJ = JJ + 1
0085      KLIST(JJ) = J
0086      CONTINUE
0087      250  IF(JJ.EQ.0) GO TO 300
0088      WRITE(6,602)
0089      602  FORMAT(75H DETAILED SENSITIVITY RESULTS FOLLOW FOR PARAMETERS )
0090      WRITE(6,603) (KLIST(I), I=1,JJ)
0091      603  FORMAT(1H 40(12,2H ),)
0092      WRITE(6,604)
0093      604  FORMAT(/)
0094      RETURN
0095      300  WRITE(6,605)
0096      605  FORMAT(4H THERE ARE NO DETAILED SENSITIVITY RESULTS  //)
0097      RETURN
0098      END
    
```

APPENDIX B

USER SUBROUTINES FOR SCHRADY-CHOE PROBLEM

```

0071      SUBROUTINE READIN
0072      IMPLICIT REAL*8(A-H,O-Z)
0073      COMMON/INV/BETA(20),PHI(20),DENSE(20),IDENT(20),NI
0074      COMMON/SEN/PAR(20),DPAR(20),NPAR,ISENS
0075      901  FORMAT(15,4F12,C)
0076      READ(5,901) NI,PAR(1),PAR(2)
0077      WRITE(6,901) NI,PAR(1),PAR(2)
0078      DO 100 I=1,NI
0079      READ(5,901) IDENT(I), (PAR(4*I-2+J), J=1,4)
0080      WRITE(6,901) IDENT(I), (PAR(4*I-2+J), J=1,4)
0081      100  CONTINUE
0082      NPAR = 4*NI+2
0083      RETURN
0084      END

0001      SUBROUTINE RESTAT(IN,VAL)
0002      IMPLICIT REAL*8(A-H,O-Z)
0003
0004      COMMON/SHAP/X(20),DFL(20),A(20,20),N,M,MN,NP1,NM1
0005      COMMON/INV/BETA(20),PHI(20),DENSE(20),IDENT(20),NI
0006      COMMON/SEN/PAR(20),DPAR(20),NPAR,ISENS
0007      VAL = 0.
0008      IF(IN.EQ.0) GO TO 300
0009      IF(IN.EQ.1) GO TO 100
0010      200  DO 250 I=1,NI
0011          IJ = 2*I-1
0012          Q0 = X(IJ)
0013          IF(Q0.LT.0.) GO TO 180
0014      250  VAL = VAL + PAR(4*I+2)/Q0
0015          VAL = PAR(2) - VAL
0016          RETURN
0017      180  VAL = -1.0
0018          RETURN
0019      100  DO 150 I=1,NI
0020          IJ1 = 2*I
0021          IJ = IJ1 - 1
0022          R0 = X(IJ1)
0023          IF(R0.LT.0.) GO TO 180
0024          Q0 = X(IJ)
0025          IF(Q0.LT.0.) GO TO 180
0026      150  VAL = VAL + PAR(4*I+1)*(R0+Q0/2.-PAR(4*I-1))
0027          VAL = PAR(1) - VAL
0028          RETURN
0029      300  DO 350 I=1,NI
0030          IJ1 = 2*I
0031          IJ = IJ1 - 1
0032          Q0 = X(IJ)
0033          R0 = X(IJ1)
0034          UU = PAR(4*I-1)
0035          SS = PAR(4*I)
0036          DELTA = R0 - UU
0037          ZN = DELTA / SS
0038          CALL ANDTRE(N,F1,UE)
0039          PHI(I) = F1
0040          DENSE(I) = DFN
0041          BETA(I) = 0.5*(SS+SS*DELTA*DELTA+PHI(I)-SS*DELTA*DENSE(I))
0042      350  VAL = VAL + BETA(I)/Q0
0043          RETURN
0044      END

```

```

0001      SUBROUTINE GRAD1(IN)
0002      IMPLICIT REAL*8(A-H,O-Z)
0003      COMMON/SHARE/X(20),DEL(20),A(20,20),N,M,MN,NP1,NM1
0004      COMMON/INV/BETA(20),PHI(20),DENSE(20),IDENT(20),NI
0005      COMMON/SEF/PAF(20),DPAF(20),NPAR,ISENS
0006      IF(IN.EQ.0) GO TO 300
0007      IF(IN.EQ.1) GO TO 100
0008      DO 250 I=1,NI
0009          IJ = 2*I
0010          IJ = IJ - 1
0011          QO = X(IJ)
0012          DEL(IJ) = 0.
0013      250      DEL(IJ) = PAF(4*I+2)/QO/QO
0014          RETURN
0015      100      DO 150 I=1,NI
0016          IJ = 2*I
0017          IJ = IJ - 1
0018          DEL(IJ) = -PAF(4*I+1)
0019      150      DEL(IJ) = DEL(IJ)/2.
0020          RETURN
0021      300      DO 350 I=1,NI
0022          IJ = 2*I
0023          IJ = IJ - 1
0024          QO = X(IJ)
0025          FR = X(IJ)
0026
0027          UU = PAF(4*I-1)
0028
0029          SS = PAF(4*I)
0030
0031          DELTA = FR - UU
0032          ZN = DELTA / SS
0033          CALL ANDT(ZN,FI,DEN)
0034          PHI(I) = FI
0035          DENSE(I) = DEN
0036          DELTA(I) = 0.5*(SS*SS*DELTA*DELTA)*PHI(I)-SS*DELTA*DENSE(I)
0037          DEL(IJ) = (DELTA*PHI(I)-SS*DENSE(I))/QO
0038      350      DEL(IJ) = -DELTA(I)/QO/QO
0039          RETURN
0040      END

0001      SUBROUTINE MATE1(X(IN,IKK)
0002      IMPLICIT REAL*8(A-H,O-Z)
0003      COMMON/SHARE/X(20),DEL(20),A(20,20),N,M,MN,NP1,NM1
0004      COMMON/INV/BETA(20),PHI(20),DENSE(20),IDENT(20),NI
0005      COMMON/SEF/PAF(20),DPAF(20),NPAR,ISENS
0006      IF(IN.EQ.0) GO TO 300
0007      IF(IN.EQ.1) GO TO 100
0008      DO 250 I=1,NI
0009          IJ = 2*I-1
0010          QO = X(IJ)
0011      250      A(IJ,IJ) = -2.*PAF(4*I+2)/QO*QO
0012          RETURN
0013      100      IKK = 1
0014          RETURN
0015      300      DO 350 I=1,NI
0016          IJ = 2*I
0017          IJ = IJ - 1
0018          QO = X(IJ)
0019          FR = X(IJ)
0020
0021          UU = PAF(4*I-1)
0022
0023          SS = PAF(4*I)
0024
0025          DELTA = FR - UU
0026          ZN = DELTA / SS
0027          CALL ANDT(ZN,FI,DEN)
0028          PHI(I) = FI
0029          DENSE(I) = DEN
0030          DELTA(I) = 0.5*(SS*SS*DELTA*DELTA)*PHI(I)-SS*DELTA*DENSE(I)
0031          A(IJ,IJ) = 2.*DELTA(I)/QO*QO
0032          A(IJ,IJ) = -DELTA*PHI(I)-SS*DENSE(I)/QO/QO
0033      350      A(IJ,IJ) = PHI(I)/QO
0034          RETURN
0035      END

0001      SUBROUTINE ANDT(FR,PHI,DENSE)
0002      IMPLICIT REAL*8(A-H,C-Z)
0003      AX = DAYS(FR)
0004      Y = 1.0/(1.0+0.2310419*AX)
0005      DENSE = (0.147422901*FR-0.0000002)
0006      PHI = DENSE*(1.0+((1.330274*Y-1.021254)*Y+1.781478)*Y
0007      I = 0.3706271*Y + 0.3107115)
0008      IF(FR) 1,2,2
0009      1      PHI = 1.0 - PHI
0010      2      RETURN
0011      END

```

APPENDIX C

SHELL PROBLEM DATA

i		j					
		1	2	3	4	5	
c_j		-15	-27	-36	-18	-12	
c_{ij}	1	30	-20	-10	32	-10	
	2	-20	39	-6	-31	32	
	3	-10	-6	10	-6	-10	
	4	32	-31	-6	39	-20	
	5	-10	32	-10	-20	30	
d_j		4	8	10	6	2	b_1
a_{ij}	1	-16	2	0	1	0	-40
	2	0	-2	0	0.4	2	-2
	3	-3.5	0	0	0	0	-0.25
	4	0	-2	0	-4	-1	-4
	5	0	-9	-2	1	-2.8	-4
	6	2	0	-4	0	0	-1
	7	-1	-1	-1	-1	-1	-40
	8	-1	-2	-3	-2	-1	-60
	9	1	2	3	4	5	5
	10	1	1	1	1	1	1

CATTLE FEED PROBLEM DATA

j	c_j	a_j	μ_j	σ_j	
1 Barley	24.55	2.3	12.0	0.53	(parameter 1)
2 Oats	26.75	5.6	11.9	0.44	(parameter 2)
3 Sesame Flakes	39.00	11.1	41.8	4.50	(parameter 3)
4 Groundnut Meal	40.00	1.3	52.1	0.79	(parameter 4)
	ϕ	= -1.645	(parameter 5) corresponds to probability of 0.95		
	p_m	= 21	(parameter 6)		
	o_m	= 5	(parameter 7)		

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Newport
BUPERS Tech Library
FMSO
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Commandant, USMC
Marine Corps School Quantico
Landing Force Dev Ctr
Logistics Officer
Armed Forces Industrial College
Armed Forces Staff College
Army War College Library
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TCMAC, ADST

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IN THE YEAR 2036

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