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DEFORMABLE WING OF HIGH ASPECT RATIO IN A BOUNDED FLUID (DEFORM--ETC(U)  
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## DEFORMABLE WING OF HIGH ASPECT RATIO IN A BOUNDED FLUID

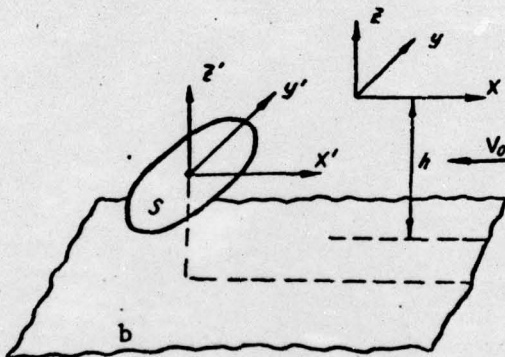
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The aerodynamic characteristics of a lifting element are generally determined by a set of parameters /12\*

$$X = X(\bar{h}, \lambda, Fr, M, P, H, Re, \dots).$$

The group of hydroaerodynamic problems involving studies of characteristics with a small number of parameters (one or two) has now been adequately investigated. Problems involving many parameters are represented by a narrower range of studies.

The present paper, which deals with a three-parameter case, investigates the lift effectiveness of a thin deformable ( $H$ ) surface ( $\lambda$ ) in a bounded fluid ( $\bar{h}$ ).



§1. Let us consider a deformable lifting surface  $S$ , moving steadily at velocity  $V_0$  in an ideal incompressible fluid near some boundary "b" at small local angles of attack. We introduce the right-handed coordinate system  $XYZ$ , fixed in the surface  $S$ , with the  $X$  axis parallel to the undisturbed boundary at a distance  $h$  from the latter and the  $Z$  axis pointing vertically upward (see figure).

In the linear formulation, the problem amounts to solving the equation of a deformable lifting surface,<sup>5,4</sup> having the following form for limiting Froude numbers:

$$\iint_S \gamma(\xi, \eta) \left\{ \frac{d}{dy} \frac{1}{y-\eta} \left[ 1 - \frac{V(x-\xi)^2 + (y-\eta)^2}{x-\xi} \right] + \frac{F}{[(y-\eta)^2 + 4h^2]^2} \times \right. \\ \left. \times \left\{ \frac{(x-\xi)[(y-\eta)^2 < (x-\xi)^2 + (y-\eta)^2 > -4h^2 < (x-\xi)^2 + (y-h)^2 + 8h^2 >]}{V(x-\xi)^2 + (y-\eta)^2 + 4h^2} - \right. \right. \\ \left. \left. - [(y-\eta)^2 - 4h^2] \right\} d\xi d\eta = V_0 [f_{0x}(x, y) + \iint_S C_x(x, y, \xi, \eta) \times \right. \\ \left. \times p(\xi, \eta) d\xi d\eta \right]. \quad (1)$$

\*Numbers in the right margin indicate pagination in the original text.

where  $\gamma(\xi, \eta)$  is the density of doublets;  
 $p(\xi, \eta) = \rho V_0 \gamma(\xi, \eta)$  is the distributed load;  
 $C(x, y, \xi, \eta)$  is a two-dimensional function of the deformability effect.

In the monoaxisymmetric case, we introduce the following transformation of coordinates:

$$y = y' + \frac{y_1 + y_2}{2} = y' + \frac{y_{01} + y_{02}}{2}; \quad y' \in \left( -\frac{y_2 - y_1}{2}, \frac{y_2 - y_1}{2} \right); \quad \bar{y}' = \frac{y'}{b}$$

and similarly for  $\eta$ ; here  $y_{01} \leq y, \eta \leq y_{02}$ ;  $y_{01}, y_{02}$  are the coordinates of the wing tips.

$$x(y) = x'(y) + \frac{x_1(y) + x_2(y)}{2}; \quad x' \in [-a(y), a(y)]; \quad \bar{x}' = \frac{x'}{b}$$

and the same for  $\xi(\eta)$ . Here  $x_1(y) \leq x < x_2(y)$ ;  $\xi_1(\eta) < \xi \leq \xi_2(\eta)$ ;  $x_1(y)$  is the equation of the trailing edge;  $x_2(y)$  is the equation of the leading edge.

We thus obtain a dimensionless form of the equation of a monoaxisymmetric lifting surface in a bounded fluid in an interpretation suitable for an examination of high aspect ratios:

$$\frac{1}{2\pi} \int_{-1}^{+1} \int_{-1}^{+1} \bar{\gamma}(\bar{\xi}', \bar{\eta}') \left\{ \frac{d}{dy'} \frac{1}{\bar{y}' - \bar{\eta}'} \left[ 1 - \frac{\sqrt{\left( \bar{x}' + \frac{x_2 + x_1}{x_2 - x_1} - \bar{\xi}' - \frac{\xi_2 + \xi_1}{x_2 - x_1} \right)^2 + \frac{\xi_2 + \xi_1}{x_2 - x_1}}}{\bar{x}' + \frac{x_2 + x_1}{x_2 - x_1} - \bar{\xi}'} \right. \right. \\
\left. \left. + \lambda^2 \frac{(\bar{y}' - \bar{\eta}')^2}{\frac{\xi_2 + \xi_1}{x_2 - x_1}} \right] + \frac{F}{[(\bar{y}' - \bar{\eta}')^2 + 16\bar{h}^2]^2} \left\{ \left( \bar{x}' + \frac{x_2 + x_1}{x_2 - x_1} - \bar{\xi}' - \frac{\xi_2 + \xi_1}{x_2 - x_1} \right) \times \right. \right. \\
\left. \left. \times [(\bar{y}' - \bar{\eta}')^2 < \frac{1}{\lambda^2} \left( \bar{x}' + \frac{x_2 + x_1}{x_2 - x_1} - \bar{\xi}' - \frac{\xi_2 + \xi_1}{x_2 - x_1} \right)^2 + (\bar{y}' - \bar{\eta}')^2 > -16\bar{h}^2 < \right. \right. \\
\left. \left. - \bar{\xi}' - \frac{\xi_2 + \xi_1}{x_2 - x_1} \right)^2 + (\bar{y}' - \bar{\eta}')^2 + 16\bar{h}^2 \right. \\
\left. \left. < \frac{1}{\lambda^2} \left( \bar{x}' + \frac{x_2 + x_1}{x_2 - x_1} - \bar{\xi}' - \frac{\xi_2 + \xi_1}{x_2 - x_1} \right)^2 + (\bar{y}' - \bar{\eta}')^2 + 32\bar{h}^2 > \right] \times \right. \\
\left. \times [(\bar{y}' - \bar{\eta}')^2 - 16\bar{h}^2] \right\} d\bar{y}' = \frac{1}{a(y)} \left| f_{0x'}(\bar{x}', \bar{y}') + 2Ab^2 \int_{-1}^{+1} C_{\bar{x}'} \times \right. \\
\left. \times (\bar{x}', \bar{y}, \bar{\xi}', \bar{\eta}') \bar{\gamma}(\bar{\xi}', \bar{\eta}') d\bar{\xi}' d\bar{\eta}' \right], \quad (2)$$

where

$$\bar{\gamma}(\bar{\xi}', \bar{\eta}') = \frac{\gamma(\xi', \eta')}{2\lambda(y) V_0}, \quad \lambda = \frac{b}{a(y)} \text{ is the aspect ratio;}$$

$b$  is the semispan;  
 $a(y)$  is the half-chord;

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$\tilde{h} = \frac{h}{2b} = \frac{h}{\ell} = \frac{\bar{h}}{\lambda(y)}$  is the relative distance along the span;  
 $\ell$  is the span;

$\bar{h}$  is the relative distance along the chord;

$f_0(\bar{x}', \bar{y}')$  is the form equation of the initial undeformed surface in dimensionless coordinates;

$f_{0x'}$  is the derivative of the form equation;

$$A = \rho V_0^2;$$

$$F = \begin{cases} 0 & \text{in an unbounded fluid} \\ +1 & \text{under a free surface } \sim F_r = \infty \\ -1 & \text{above a screen. } \sim F_r = 0 \end{cases}$$

52. Because of the impossibility of an analytical solution of the two-dimensional Equation (2), limitations will be introduced for arbitrary planforms: a wing of high aspect ratio will be considered. Then, assuming  $\frac{x_2 + x_1}{2} \approx \frac{\xi_1 + \xi_1}{2}$  and using the approximation

$$\sqrt{\left(\bar{x}' + \frac{x_2 + x_1}{x_2 - x_1} - \bar{\xi}' - \frac{\xi_2 + \xi_1}{x_2 - x_1}\right)^2 + \lambda^2(y) (\bar{y}' - \bar{\eta}')^2} \approx \lambda(y) |\bar{y}' - \bar{\eta}'|.$$

we obtain from Eq. (2)

$$\begin{aligned} & \frac{1}{2\pi} \int_{-1}^{+1} \int_{-1}^{+1} \bar{\gamma}(\bar{\xi}', \bar{\eta}') \left\{ \frac{a}{d\bar{y}'} \frac{1}{\bar{y}' - \bar{\eta}'} \left[ 1 - \frac{\lambda(y) |\bar{y}' - \bar{\eta}'|}{x - \bar{\xi}'} \right] - F \frac{(\bar{y}' - \bar{\eta}')^2 - 16\bar{h}^2}{[(\bar{y}' - \bar{\eta}')^2 + 16\bar{h}^2]^2} \right\} \times \\ & \times d\bar{\xi}' d\bar{\eta}' = \frac{1}{a(y)} \left[ f_{0x'}(\bar{x}', \bar{y}') + 2Ab^2 \int_{-1}^{+1} \int_{-1}^{+1} C_{\bar{x}'}(\bar{x}', \bar{y}', \bar{\xi}', \bar{\eta}') \times \right. \\ & \left. \times \bar{\gamma}(\bar{\xi}', \bar{\eta}') d\bar{\xi}' d\bar{\eta}' \right]. \end{aligned} \quad (3)$$

Assuming  $\bar{\gamma}(\bar{\xi}', \bar{\eta}') = \bar{\gamma}(\bar{\xi}') \bar{\gamma}(\bar{\eta}')$ , we transform Eq. (3) to

$$\begin{aligned} & -\frac{\lambda(y)}{2\pi} \int_{-1}^{+1} \frac{\bar{\gamma}(\bar{\xi}')}{x' - \bar{\xi}'} \frac{a}{d\bar{y}'} \int_{-1}^{+1} \bar{\gamma}(\bar{\eta}') \frac{|\bar{y}' - \bar{\eta}'|}{\bar{y}' - \bar{\eta}'} d\bar{\eta}' d\bar{\xi}' = \frac{1}{a(y)} \left[ f_{0x'}(\bar{x}', \bar{y}') + \right. \\ & \left. + 2Ab^2 \int_{-1}^{+1} \bar{\gamma}(\bar{\eta}') \int_{-1}^{+1} \bar{\gamma}(\bar{\xi}') C_{\bar{x}'}(\bar{x}', \bar{y}', \bar{\xi}', \bar{\eta}') d\bar{\xi}' d\bar{\eta}' \right] - \\ & - \frac{1}{2\pi} \int_{-1}^{+1} \bar{\gamma}(\bar{\xi}') \int_{-1}^{+1} \bar{\gamma}(\bar{\eta}') \frac{a}{d\bar{y}'} \frac{1}{\bar{y}' - \bar{\eta}'} d\bar{\eta}' d\bar{\xi}' + F \frac{1}{2\pi} \times \\ & \times \int_{-1}^{+1} \bar{\gamma}(\bar{\xi}') \int_{-1}^{+1} \bar{\gamma}(\bar{\eta}') \frac{[(\bar{y}' - \bar{\eta}')^2 - 16\bar{h}^2]}{[(\bar{y}' - \bar{\eta}')^2 + 16\bar{h}^2]^2} d\bar{\eta}' d\bar{\xi}'. \end{aligned}$$

Considering

$$\frac{a}{d\bar{y}'} \int_{-1}^{+1} \bar{\gamma}(\bar{\eta}') \frac{|\bar{y}' - \bar{\eta}'|}{\bar{y}' - \bar{\eta}'} d\bar{\eta}' = 2\bar{\gamma}(\bar{y}')$$

and integrating by parts, providing that  $\bar{\gamma}(\bar{\eta}')|_{\bar{\eta}' = \pm 1} = 0$ , when

$$\int_{-1}^{+1} \bar{\gamma}(\bar{\eta}') \frac{d}{d\bar{y}'} \frac{1}{\bar{y}' - \bar{\eta}'} d\bar{\eta}' = \int_{-1}^{+1} \bar{\gamma}(\bar{\eta}') \frac{d\bar{\eta}'}{\bar{y}' - \bar{\eta}'}; \int_{-1}^{+1} \bar{\gamma}(\bar{\eta}') \frac{[(\bar{y}' - \bar{\eta}')^2 - 16h^2]}{[(\bar{y}' - \bar{\eta}')^2 + 16h^2]} d\bar{\eta}' =$$

$$= - \int_{-1}^{+1} \bar{\gamma}(\bar{\eta}') \frac{\bar{y}' - \bar{\eta}'}{(\bar{y}' - \bar{\eta}')^2 + 16h^2} d\bar{\eta}',$$

we have

$$- \frac{2\lambda(y)\bar{\gamma}(\bar{y}')}{2\pi} \int_{-1}^{+1} \frac{\bar{\gamma}(\bar{\xi}') d\bar{\xi}'}{\bar{x}' - \bar{\xi}'} = \frac{1}{a(y)} \left[ f_{0x'}(\bar{x}', \bar{y}') + \right.$$

$$+ 2Ab^2 \int_{-1}^{+1} \bar{\gamma}(\bar{\eta}') \int_{-1}^{+1} \bar{\gamma}(\bar{\xi}') C_{x'}(\bar{x}', \bar{y}', \bar{\xi}', \bar{\eta}') d\bar{\xi}' d\bar{\eta}' \left. \right] -$$

$$- \frac{1}{2\pi} \int_{-1}^{+1} \bar{\gamma}(\bar{\xi}') \int_{-1}^{+1} \bar{\gamma}(\bar{\eta}') \frac{d\bar{\eta}'}{\bar{y}' - \bar{\eta}'} d\bar{\xi}' - F \frac{1}{2\pi} \int_{-1}^{+1} \bar{\gamma}(\bar{\xi}') \int_{-1}^{+1} \bar{\gamma}(\bar{\eta}') \frac{\bar{y}' - \bar{\eta}'}{(\bar{y}' - \bar{\eta}')^2 + 16h^2} \times$$

$$\times d\bar{\eta}' d\bar{\xi}'. \quad (4)$$

After integrating (4) over the chord with a weight factor  $\sqrt{\frac{1-x'}{1+x'}}$  and introducing dimensionless circulation

$$\bar{\Gamma}(\bar{\eta}') = \bar{\gamma}(\bar{\eta}') \int_{-1}^{+1} \bar{\gamma}(\bar{\xi}') d\bar{\xi}' = \frac{\Gamma(\bar{\eta}')}{2bV_0} \quad (5)$$

we obtain an equation for a high-aspect-ratio deformable wing in a bounded fluid, of the same form as the Prandtl equation:

where

$$\bar{\Gamma}(\bar{y}') = \frac{a-\psi}{2\lambda(y)} \left\{ a(\bar{x}', \bar{y}') - \frac{1}{2\pi} \int_{-1}^{+1} \bar{\Gamma}(\bar{\eta}') \left[ \frac{1}{\bar{y}' - \bar{\eta}'} + FG(\bar{y}' - \bar{\eta}') \right] d\bar{\eta}' \right\}, \quad (6)$$

$$a(\bar{x}', \bar{y}') = \frac{\bar{a}(\bar{x}', \bar{y}')}{a(y)} = \frac{\bar{a}(\bar{x}', \bar{y}')}{\pi a(y)}, \quad G(\bar{y}' - \bar{\eta}') = \frac{\bar{y}' - \bar{\eta}'}{(\bar{y}' - \bar{\eta}')^2 + 16h^2};$$

$$\bar{a}(\bar{x}', \bar{y}') = \int_{-1}^{+1} \sqrt{\frac{1-x'}{1+x'}} f_{0x'}(\bar{x}', \bar{y}') d\bar{x}' + 2Ab^2 \int_{-1}^{+1} \bar{\Gamma}(\bar{\eta}') \times$$

$$\times \frac{\int_{-1}^{+1} \sqrt{\frac{1-x'}{1+x'}} \int_{-1}^{+1} \bar{\gamma}(\bar{\xi}') C_{x'}(\bar{x}', \bar{y}', \bar{\xi}', \bar{\eta}') d\bar{\xi}' d\bar{x}'}{\int_{-1}^{+1} \bar{\gamma}(\bar{\xi}') d\bar{\xi}'} d\bar{\eta}'. \quad (7)$$

Assuming the independence of the deformations of the cross sections, we obtain

$$C_{x'}(\bar{x}', \bar{y}', \bar{\xi}', \bar{\eta}') \rightarrow C_x(\bar{x}', \bar{\xi}').$$

In the case of an elastically deformable axisymmetric wing, for an arbitrary position of the projection  $S_p$  of surface  $S$  on the XOY plane, with  $EJ_y = \text{const}$ , we have<sup>3</sup>

$$\begin{aligned}
 x > \xi; C_x^*(\bar{x}', \bar{\xi}') &= \text{sign } R \frac{\sigma^2(y)}{EJ_y} \left\{ \left[ \bar{x}' + \frac{x_1 + x_2}{a(y)} \right] \left[ \bar{\xi}' + \frac{\xi_1 + \xi_2}{a(y)} \right] - \right. \\
 &\quad \left. - \frac{1}{2} \left[ \bar{x}' + \frac{x_1 + x_2}{a(y)} \right]^2 - \left[ \bar{\xi}' + \frac{\xi_1 + \xi_2}{a(y)} + \frac{1}{2} \right] \right\}; \quad (8) \\
 x < \xi; C_x^*(\bar{x}', \bar{\xi}') &= \text{sign } R \frac{\sigma^2(y)}{EJ_y} \left\{ \frac{1}{2} \left[ \bar{\xi}' + \frac{\xi_1 + \xi_2}{a(y)} \right]^2 - \left[ \bar{\xi}' + \frac{\xi_1 + \xi_2}{a(y)} + \frac{1}{2} \right] \right\};
 \end{aligned}$$

where  $\text{sign } R = -1$  corresponds to the built-in end along the leading edge, and  $\text{sign } R = 1$  to the built-in end along the trailing edge.

For a diaxisymmetric wing with a coordinate system located at the center of projection  $S_p$ , formulas (8) become simplified:

$$C_x^*(\bar{x}', \bar{\xi}') = \text{sign } R \frac{\sigma^2(y)}{EJ_y} \left[ (\bar{x}'\bar{\xi}' - \frac{1}{2}\bar{x}'^2) - (\bar{\xi}' - \frac{1}{2}) \right]; \quad (9)$$

$$C_x^*(\bar{x}', \bar{\xi}') = \text{sign } R \frac{\sigma^2(y)}{EJ_y} \left( \frac{1}{2}\bar{\xi}'^2 - \bar{\xi}' + \frac{1}{2} \right).$$

§3. Let us consider a diaxisymmetric elastic wing, planar in the initial undeformed state:  $f_{0x} = \alpha_0$ . Then  $f_{0x'} = \alpha_0 a(y)$ , which gives

$$\bar{\alpha} = \alpha_0 a(y) \pi + \text{sign } R \frac{2Ab^2\sigma^2(y)}{EJ_y} \bar{A}_1 \int_{-1}^{+1} \bar{\Gamma}(\bar{\eta}) d\bar{\eta}, \quad (10)$$

where

$$\bar{A}_1 = \frac{\int_{-1}^{+1} \sqrt{\frac{1-\bar{x}}{1+\bar{x}}} \left\{ \int_{-1}^{\bar{x}} \bar{\gamma}(\bar{\xi}) C_x^*(\bar{x}, \bar{\xi}) d\bar{\xi} + \int_{\bar{x}}^{+1} \bar{\gamma}(\bar{\xi}) C_x^*(\bar{x}, \bar{\xi}) d\bar{\xi} \right\} d\bar{x}}{\int_{-1}^{+1} \bar{\gamma}(\bar{\xi}) d\bar{\xi}}.$$

If  $\bar{\gamma}(\bar{\xi}) = B \sqrt{\frac{1+\bar{\xi}}{1-\bar{\xi}}}$ , then  $\bar{A}_1 \approx 0.75$ .

Thus,

$$\bar{\alpha} = a(y) \pi \left[ \alpha_0 + \text{sign } R \frac{\bar{A}_1 H C_y(y)}{\pi} \right] = a(y) \pi (\alpha_0 + \alpha_p), \quad (11)$$

where

$$\alpha_p = \text{sign } R \frac{\bar{A}_1 H C_y(y)}{\pi}; \quad (12)$$

$$C_y(y) = \lambda(y) \int_{-1}^{+1} \bar{\Gamma}(\bar{\eta}) d\bar{\eta}. \quad (13)$$

$H = \frac{\rho V_0^2 k^2 b}{8EJ_y}$  is the similarity parameter of a statically aerohydroelastic lifting surface.

In this case, Eq. (6) becomes

$$\bar{\Gamma}(\bar{y}) = \frac{\alpha_0 \psi}{2\lambda(y)} \left\{ \alpha_0 + \text{sign } R \frac{\bar{A}_1 H C_y(y)}{\pi} - \frac{1}{2\pi} \int_{-1}^{+1} \bar{\Gamma}(\bar{\eta}) \left[ \frac{1}{\bar{y}-\bar{\eta}} + FG(\bar{y}-\bar{\eta}) \right] d\bar{\eta} \right\}. \quad (14)$$

We seek the solution of Eq. (14) in the form

$$\bar{\Gamma}(\bar{y}) = \alpha A_2 \Gamma_0(\bar{y}), \quad (15)$$

where  $\Gamma_0(\bar{y}) = \sqrt{1 - \bar{y}^2}$ ,  $A_2 = \text{const.}$

Introducing (15) into Eq. (14) and integrating the right- and left-hand parts of the latter equation over the span, we obtain

$$A_2 = \frac{\frac{a_\infty \psi}{\lambda}}{\int_{-1}^{+1} \Gamma_0(\bar{y}) d\bar{y} + \frac{a_\infty \psi}{4\pi\lambda} \int_{-1}^{+1} \int_{-1}^{+1} \Gamma_0(\bar{\eta}) \left[ \frac{1}{\bar{y} - \bar{\eta}} + FG(\bar{y} - \bar{\eta}) \right] d\bar{\eta} d\bar{y}} \quad (16)$$

To calculate  $A_2$ , we expand the regular part of the kernel<sup>5</sup> of the inner integral in the double integral of the denominator of (16) as a series in even

powers of the small parameter  $\tau_2 = \sqrt{4h^2 + 1 - 2h}$ :

$$G(\bar{y} - \bar{\eta}) = \sum_{m=2, 4, \dots} \sum_{n=0}^{\frac{m}{2}-1} \tau_2^m \frac{(m-1-n)! (-1)^{\frac{m}{2}-n+1}}{n! (m-1-2n)!} (\bar{y} - \bar{\eta})^{m-1-2n}.$$

Keeping terms up to  $\tau_2^6$  inclusive in the expansion, we have

$$A_2 = \frac{\frac{a_\infty \psi(\bar{h})}{\lambda}}{\frac{\pi}{2} + \frac{a_\infty \psi(\bar{h})}{2\lambda} \zeta(\bar{h})}, \quad (17)$$

where

$$a_\infty = \frac{dC_{y_\infty}}{d\alpha};$$

$C_{y\bar{h}}$  is the lift coefficient of the thin airfoil near the boundary;

$C_{y_\infty}$  is the lift coefficient of the thin airfoil in an unbounded fluid;

$\psi(\bar{h}) = \frac{a\bar{h}}{a_\infty}$  is the function of the boundary effect in a two-dimensional problem;

$$\zeta(\bar{h}) = 1 + F \frac{1}{2} \left( \tau_2^2 + \frac{1}{4} \tau_2^4 + \frac{1}{8} \tau_2^6 \right) \quad (18)$$

is a function allowing for the effect of finiteness of the span near the boundary.

Thus, using Eq. (13), we arrive at an equation for the lift coefficient of the wing

$$C_y = \frac{\pi\lambda A_2}{2} \left( a_0 + \text{sign } RH + \frac{\lambda_1 C_y}{\pi} \right), \quad (19)$$

which results in

$$C_y = C_{y_{nd}} \psi(\bar{h}, \lambda, H), \quad (20)$$

where  $C_{y_{nd}}$  is the lift coefficient of a planar nondeformable wing of high aspect ratio in a bounded fluid;<sup>5</sup>

$$C_{y_{nd}} = \frac{a_{\infty} \psi(\bar{h})}{1 + \frac{a_{\infty} \psi(\bar{h})}{\pi \lambda} \zeta} a_0; \quad (21)$$

$\psi(\bar{h})$  is the boundary effect function;<sup>5,1</sup>

$$\psi(\bar{h}) = 1 \pm \tau_1^2 + \frac{1}{2} \tau_1^4 \pm \frac{3}{4} \tau_1^6 + \dots$$

where the superscripts correspond to motion above the screen, and the subscripts to motion under the free surface,  $\tau_1 = \sqrt{4\bar{h}^2 + 1 - 2\bar{h}}$ .

$\psi(\bar{h}, \lambda, H)$  is the function of the combined effect of the boundary, aspect ratio and elasticity:

$$\psi(\bar{h}, \lambda, H) = \frac{1}{1 - \text{sign } R H \bar{A}_1 \frac{\lambda}{2} A_2}; \quad (22)$$

or

$$\psi(\bar{h}, \lambda, H) = \frac{1}{1 - \text{sign } R \frac{\bar{A}_1 H \frac{a_{\infty} \psi(\bar{h})}{2}}{\frac{\pi}{2} + \frac{a_{\infty} \psi(\bar{h})}{2\lambda} \zeta}}; \quad (23)$$

In an unbounded fluid, when  $\psi(\bar{h}) = 1$ ,  $\zeta = 1$ , from (23) we set up the relation

$$\psi(\lambda, H) = \frac{1}{1 - \text{sign } R \frac{\frac{1}{2} \bar{A}_1 H a_{\infty}}{\frac{\pi}{2} + \frac{a_{\infty}}{2\lambda}}}; \quad (24)$$

which for  $a_{\infty} = 2\pi$  converts into the formula of Ref. 4:

$$\psi(\lambda, H) \approx \frac{1}{1 - \text{sign } R \frac{0.75H}{\frac{1}{2} + \frac{1}{\lambda}}};$$

and for  $\lambda \rightarrow \infty$  becomes the relation obtained in Ref. 3 for a thin elastic contour:

$$\psi(H) \approx \frac{1}{1 - \text{sign } R \cdot 1.5H}$$

We express Eq. (21) as follows:

$$C_{y_{nd}} = C_{y_{\infty}} \psi(\bar{h}, \lambda); \quad (25)$$

where

$$C_{y_{\infty}} = a_{\infty} a_0,$$

and

$$\psi(\bar{h}, \lambda) = \frac{\psi(\bar{h})}{1 + \frac{a_{\infty} \psi(\bar{h})}{\pi \lambda} \zeta(\bar{h})}; \quad (26)$$

In a bounded fluid for  $\lambda \rightarrow \infty$ , we obtain from formula (23) a representation for the function of the effect of the boundary and elasticity in a two-dimensional problem

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$$\psi(\bar{h}, H) = \frac{1}{1 - \text{sign } R \frac{\bar{A}_1 H a_\infty}{\pi} + F \left( \tau_1^2 - \frac{1}{4} \tau_1^4 + \frac{1}{4} \tau_1^6 \right)}, \quad (27)$$

which for  $a_\infty = 2\pi$  converts into the result of Ref. 3:

$$\psi(\bar{h}, H) \approx \frac{1}{1 - \text{sign } R \cdot 1.5H + F \left( \tau_1^2 - \frac{1}{4} \tau_1^4 + \frac{1}{4} \tau_1^6 \right)}$$

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