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WIND DRIFT OF SEA ICE: A SUPPLEMENT TO THE NAVAL OCEANOGRAPHIC --ETC(U)
SEP 76 D J GERSON, L S SIMPSON

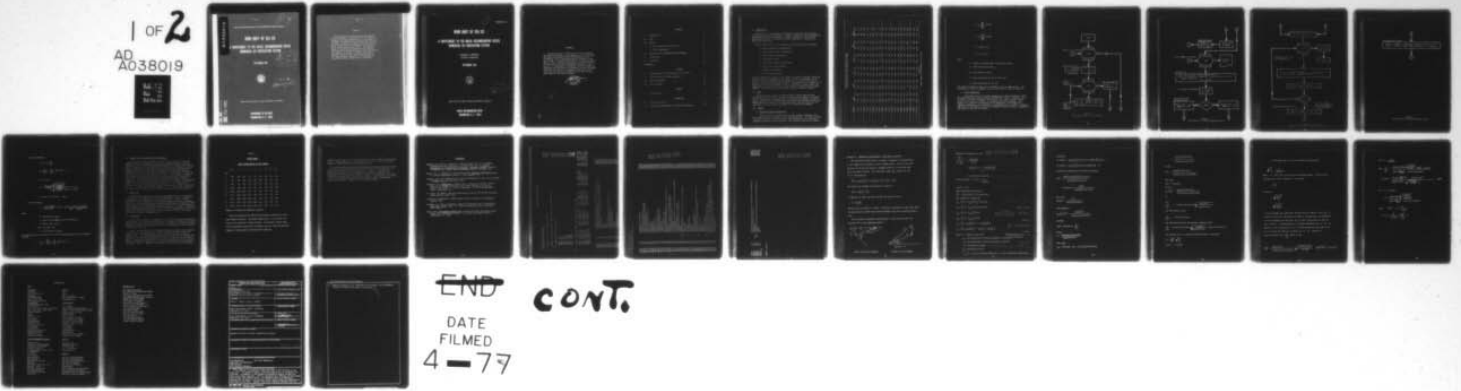
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NAVAL OCEANOGRAPHIC OFFICE REFERENCE PUBLICATION 8 - 5

WIND DRIFT OF SEA ICE

A SUPPLEMENT TO THE NAVAL OCEANOGRAPHIC OFFICE
NUMERICAL ICE FORECASTING SYSTEM

SEPTEMBER 1976

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ABSTRACT

The numerical ice prediction system described in RP 8 has been in use since 1971. Its outputs, however, have been related only to ice growth, not ice drift. An addition to the system now provides an output of daily ice drift at 62 arctic stations. Drift is calculated as a function of wind stress, water stress, and Coriolis force. The computer output is sufficiently accurate for ice drift in the locality of the station whose wind observations were input to the model. However, more recent research indicates that for greater accuracy and for computations of divergence and convergence interaction between floes must be considered.

①

NOO RP 8 - 5

WIND DRIFT OF SEA ICE

A SUPPLEMENT TO THE NAVAL OCEANOGRAPHIC OFFICE NUMERICAL ICE FORECASTING SYSTEM

DONALD J. GERSON
LLOYD S. SIMPSON

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I. INTRODUCTION

Since July 1971 a numerical ice prediction system has been operated by the Naval Oceanographic Office to compute various sea ice characteristics and forecasting aids of importance to arctic operations. Gerson (1975) completely describes the system as of 1975; therefore, it will only be briefly discussed here.

The original outputs of the prediction system include the following:

- * present degree-day accumulations
- * forecast degree-day accumulations
- * daily synoptic temperatures
- * temperature trends
- * selected sea surface temperatures
- * initial freezeup forecasts
- * reported snow depths
- * ice thickness forecasts

All this information relates to ice formation, growth, thickness, and decay in-situ without consideration of ice drift. Since the knowledge of ice drift is extremely important to the forecaster, its inclusion as part of the daily output was considered desirable. The purpose of this report is to describe this significant update to the ice prediction system, namely the computation of wind drift of ice at each of the 62 stations in the present network. An example of a typical output listing is shown in figure 1.

II. DATA

The data are the same as used for the basic system, and are fully described in Gerson (1975). A slight revision in the heading is discussed in U. S. Department of Commerce (1973). The data base remains the entire world's synoptic weather observations collected by the National Oceanic and Atmospheric Administration, but observations for each day now are on one tape rather than two and are processed on its IBM 360/195 computer.

III. METHOD

A. Mean Wind Speed and Direction

The wind drift is derived entirely from values of synoptic wind speed and direction as reported by the network stations. The four (or fewer if reports are missing) daily synoptic wind observations are vectorially averaged to produce a mean wind speed. The equations used are as follows:

WIND SPEED (KTS) AND DIRECTION (DEG)
AND WIND DRIFT OF ICE FOR SEP 8, 1974

STATION NO	00Z		06Z		12Z		18Z		MEAN		DRIFT	
	SPD	DIR	SPD	DIR	SPD	DIR	SPD	DIR	SPD	DIR	SPD	DIR
21504	8.0	200	12.0	140	8.0	110	.0	360	5.8	148	.21	171
21647	16.0	90	14.0	110	18.0	140	18.0	140	15.9	122	.58	142
21824	12.0	160	12.0	160	4.0	270	4.0	200	6.6	175	.24	197
21965	16.0	70	12.0	50	10.0	50	12.0	50	12.3	56	.45	78
21982	14.0	340	20.0	360	10.0	290	22.0	340	15.3	340	.56	0
25173	12.0	320	16.0	320	14.0	290	20.0	320	15.1	314	.56	334
25399	14.0	200	4.0	200	12.0	360	18.0	360	3.6	336	.13	2
25594	10.0	200	10.0	20	14.0	50	.0	360	3.5	50	.13	76
70026	10.0	160	10.0	90	8.0	70	10.0	60	7.4	94	.27	116
70086	10.0	80	10.0	130	7.0	110	12.0	90	9.2	102	.34	123
70133	4.0	90	99.0	990	17.0	360	16.0	320	10.0	349	.27	10
70200	7.0	320	9.0	300	6.0	350	8.0	10	6.6	334	.24	356
70218	99.0	990	99.0	990	99.0	990	99.0	990	99.0	990	9.90	990
70273	11.0	300	6.0	130	6.0	90	4.0	360	1.4	11	.05	47
70308	20.0	330	99.0	990	20.0	290	99.0	990	18.8	311	.70	330
70316	21.0	340	22.0	310	18.0	310	99.0	990	19.7	321	.74	340
70326	4.0	280	.0	360	3.0	280	4.0	250	2.7	269	.10	297
70350	10.0	120	14.0	40	9.0	330	9.0	290	4.3	16	.16	40
72815	7.0	280	12.0	210	12.0	220	5.0	330	6.8	239	.26	241
72816	12.0	360	13.0	340	11.0	320	10.0	310	10.9	335	.41	355

Figure 1.
Sample output of wind velocity and ice drift

$$I = \frac{1}{k} \sum_{i=1}^k V_i \sin D_i \quad ,$$

$$J = \frac{1}{k} \sum_{i=1}^k V_i \cos D_i \quad ,$$

$$\bar{D} = \arctan (I/J) \quad ,$$

$$\bar{V} = (I^2 + J^2)^{\frac{1}{2}} \quad ;$$

where

k = number of observations (1-4) during the day,

D_i = wind direction at time i ,

V_i = wind speed at time i ,

\bar{D} = mean wind direction for the day, and

\bar{V} = mean wind speed for the day.

The computer program accounts for the quadrant in these computations. This subroutine is listed in appendix A, and a flow chart is shown in figure 2.

B. Drift Computation

The method used for ice drift computation is that of Shuleikin (1953). This method has been used by Wittmann and MacDowell (1964) to produce a set of curves for manual computation of ice drift. In order to obtain a daily output for 62 stations, however, an automated method is necessary. The equations as presented by Shuleikin do not immediately lend themselves to computer programming, and considerable transformation was required. A complete derivation of the equations used in the computer program is given in appendix B. The equations used are as follows:

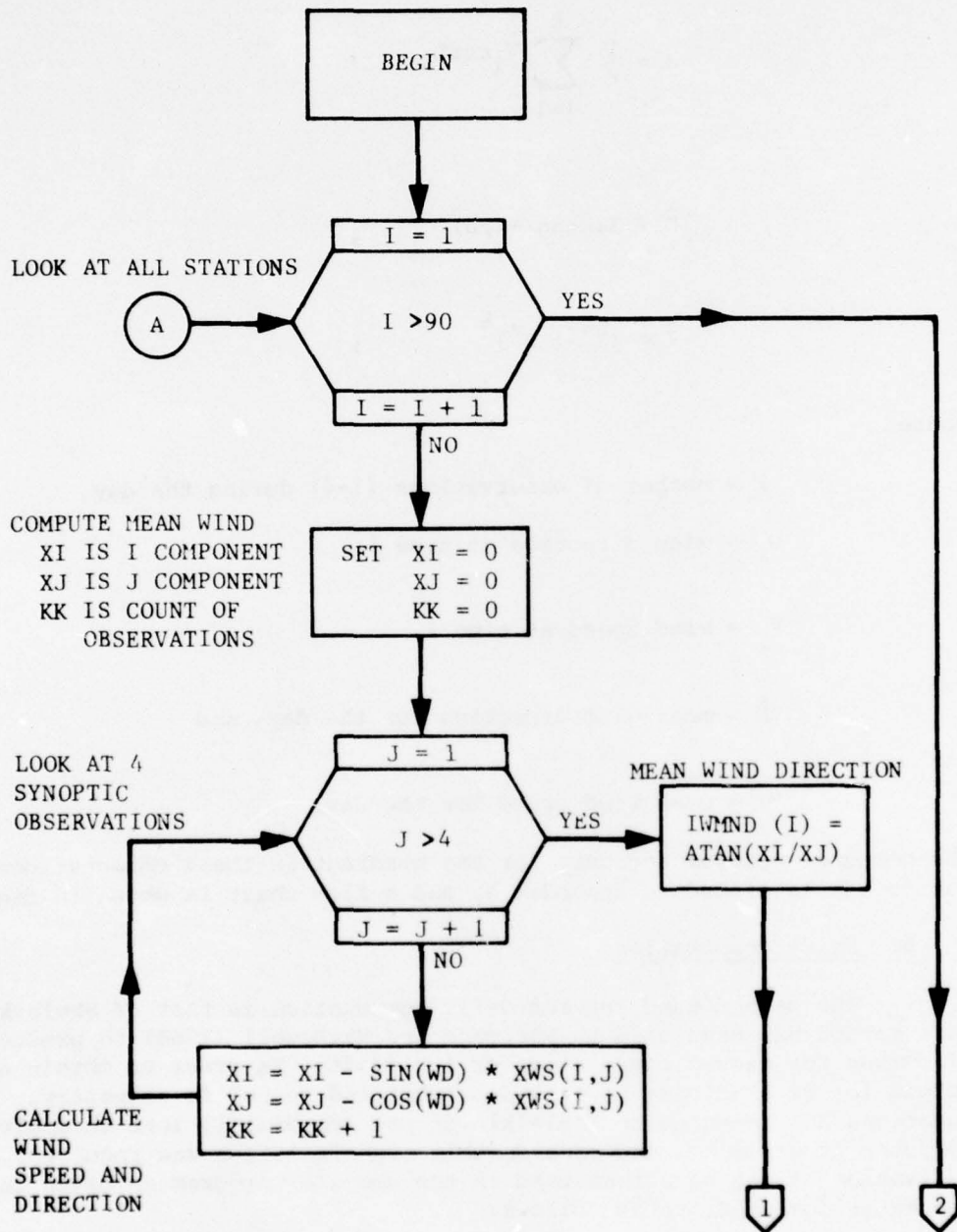


Figure 2.
Flow chart of ice drift subroutine

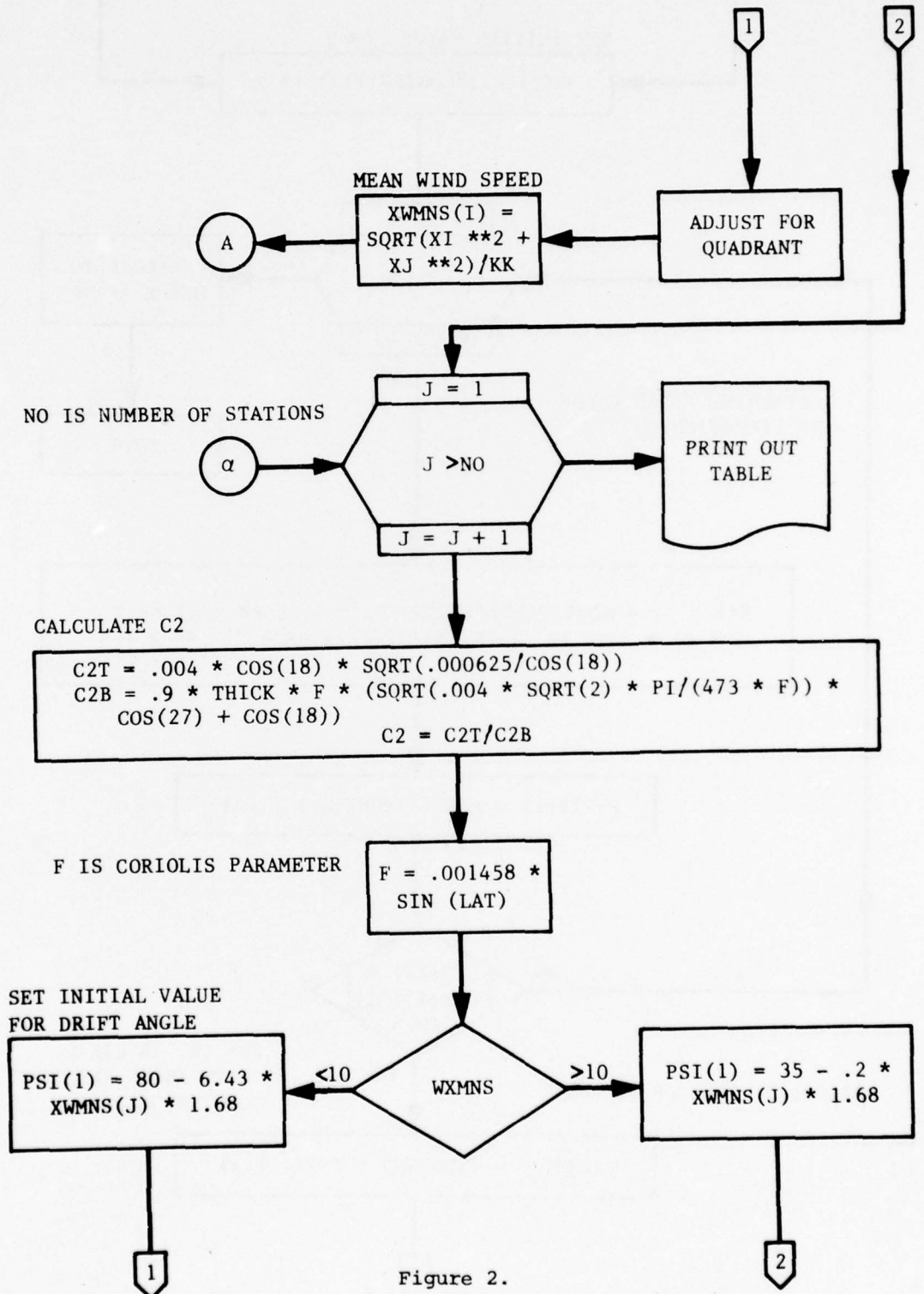


Figure 2.
Flow chart of ice drift subroutine (con.)

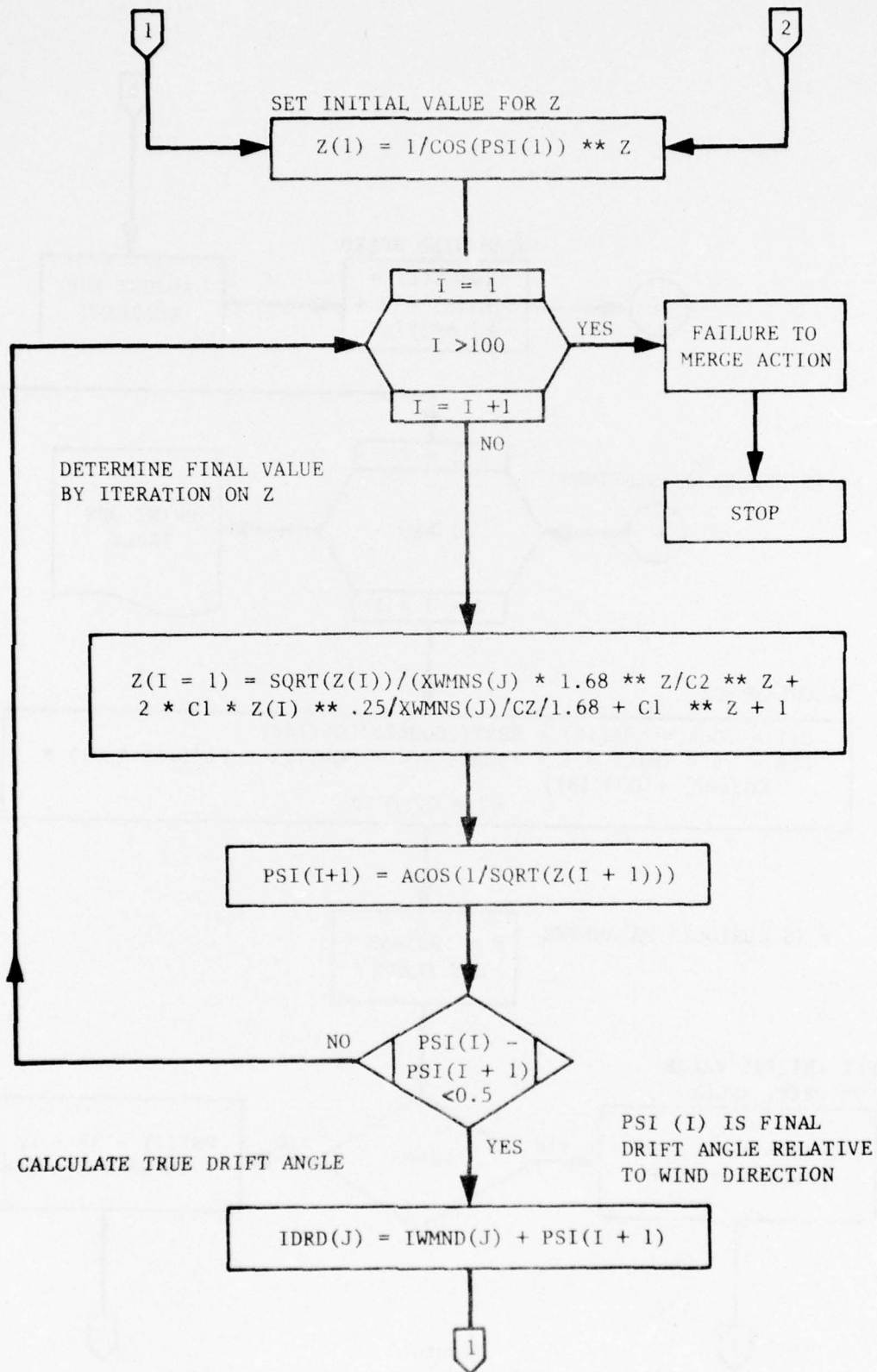


Figure 2.
Flow chart of ice drift subroutine (con.)

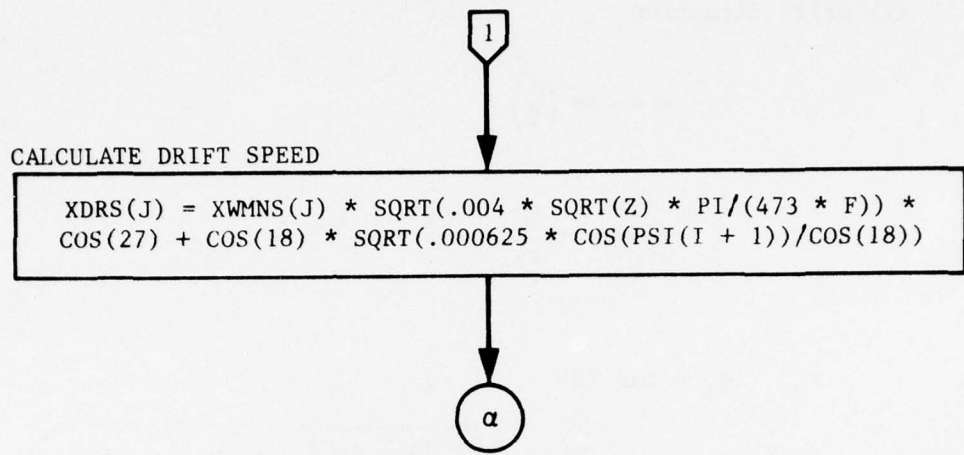


Figure 2.
Flow chart of ice drift subroutine (con.)

(1) drift direction

$$\psi = \arccos \left(\frac{1}{Z} \right) ,$$

$$Z = \frac{Z_n^{\frac{1}{2}}}{V^2 C_2^2} + \frac{2C_1}{VC_2} Z_n^{\frac{1}{2}} + C_1^2 + 1 ,$$

$$C_1 = \tan 18^\circ ,$$

$$C_2 = \frac{.004 \cos 18^\circ \sqrt{\frac{6.25 \times 10^{-4}}{\cos 18^\circ}}}{0.9fI \left[\sqrt{\frac{.004 \sqrt{2\pi}}{473f} \cos 27^\circ + \cos 18^\circ} \right]} ,$$

$$f = 1.458 \times 10^{-4} \sin(\text{lat}) ; \text{ and}$$

(2) drift speed

$$u = V \left[\sqrt{\frac{.004 \sqrt{2\pi}}{473f} \cos 27^\circ + \cos 18^\circ} \right] \sqrt{\frac{6.25 \times 10^{-4} \cos \psi}{\cos 18^\circ}} ;$$

where

V = wind speed (ft/sec),

ψ = drift to the right of the wind direction

u = drift speed (ft/sec)

lat = latitude, and

I = ice thickness (inches)

The equation for Z is required to be in an iterative form, thus it is used as follows:

$$Z_{n+1} = \frac{Z_n^{\frac{1}{2}}}{V^2 C_2^2} + \frac{2C_1}{VC_2} Z_n^{\frac{1}{2}} + C_1^2 + 1$$

IV. VARIATION FOR CONCENTRATION AND ROUGHNESS

The Shuleikin equations assume a single ice floe and do not consider surface roughness. An empirical table of wind factors (Zubov, 1945) was compiled by P.A. Gordienko from many observations of ice drift in the Soviet Arctic. Comparison of this table with the output of the Shuleikin equations shows a match at 0.5 oktas and 4 tenths extent of ridging and hummocking. A factor table (table 1) was then constructed for use in correcting the computer output to the applicable concentration and roughness. Instructions for using the table are given beneath the table. As an example, suppose we have a mean wind speed and direction of 9.2 kn and 102 deg, which produce an ice drift and direction of .34 kn and 123 deg (see station 70086 in figure 1). If the concentration were 0.5 oktas and the extent of ridging and hummocking 4 tenths, then, referring to table 1, the ice drift speed would remain .34 kn since the multiplicative factor is 1. If, however, the concentration was 6 oktas and the ridging 3 tenths, the ice drift speed would be .10 kn since the multiplicative factor is .3. In either case, the drift direction remains 123 deg, since this table only relates to drift speed.

V. CONCLUSIONS

The methods described above have been programmed and are now operational on the UNIVAC 1108 computer at the Naval Oceanographic Office. Ice drift information is now regularly produced, together with the other products described in the Introduction. The outputs have been evaluated by comparing them first with the manual computation method of Wittmann and MacDowell (1964) and second with manual calculations accomplished with the original equations. These comparisons have proved the computer program to be reliable. Evaluation with actual observed drift conditions has not been accomplished, but since the curves from Wittmann and MacDowell have been used successfully for years, the computer output is assumed accurate.

VI. DISCUSSION

As previously stated, this computation of ice drift is based on Shuleikin's work of 1953. This model was chosen since it had been used manually for years and had been found to give accurate results. In addition, it was most easily adapted to estimating wind drift from station observations that were available in the existing system.

A basic problem exists with the Shuleikin model in that it only considers the motion of a single floe as it results from wind and water stress and Coriolis force. No consideration is given to the effect of interaction between floes. In the program herein described, the effects of concentration and ridging are considered empirically but are not input to the theoretical model. Considerable research has been done since Shuleikin's work. Many of the recent papers are published in the extensive AIDJEX series (University of Washington, 1972-). Campbell and Rasmussen (1972) begin with an excellent

Table 1

FACTOR TABLETOTAL CONCENTRATION OF ICE (OKTAS)

	0.5	1	2	3	4	5	6	7.0	7.5
E*									
1	.26	.24	.20	.17	.13	.10	.09	.07	.07
2	.51	.47	.40	.34	.28	.22	.18	.15	.12
3	.75	.71	.63	.55	.47	.39	.30	.22	.19
4	1.00	.96	.84	.72	.62	.51	.39	.29	.24
5	1.26	1.19	1.06	.92	.79	.65	.52	.38	.31
6	1.51	1.43	1.26	1.10	.94	.80	.63	.46	.38
7	1.75	1.66	1.47	1.29	1.10	.92	.73	.55	.46
8	2.01	1.90	1.69	1.49	1.28	1.07	.85	.64	.53
9	2.26	2.13	1.90	1.64	1.40	1.17	.94	.71	.60

*Extent of ridging and hummocking (tenths)

Table of multiplicative factors for estimating speed of ice drift from computer printout. The drift speeds given in the printout are true for 0.5 oktas and 4 tenths ridging. To determine correct speed enter concentration and extent of ridging into this table and multiply computer's drift speed by the factor thus obtained.

summary of ice dynamics up to 1972 and proceed to give a model that considers ice as a viscous material. Rothrock (1975) considers sea ice as a plastic material. Additional papers are expected shortly.

Ice drift estimates, computed by the model discussed in sections III and IV of this paper, are sufficiently accurate for use in the locality of the station whose wind reports are used in the calculation. They are not sufficiently accurate for the calculation of areas of convergence and divergence or for interpolation between stations or extrapolation into areas lacking wind observations. To add these features to the system in the future, it will be necessary to implement one of the more sophisticated models, requiring more specific inputs not now readily available.

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APPENDIX A. SUBROUTINE LISTING

FOR A=AMCCKLCSIM=MCALC
FOR U0E3-09/07/76-15.54:17 (11)

SUBROUTINE MCALC ENTRY POINT 001045

STORAGE USED: CODE(1) 001121; DATA(0) 000567; BLANK COMMON(2) 000000

EXTERNAL REFERENCES (BLOCK, NAME)

- 0003 SIN
- 0004 COS
- 0005 ATAN
- 0006 SQRT
- 0007 TAN
- 0010 APRK
- 0011 ACOS
- 0012 MDOUS
- 0013 NI025
- 0014 NI015
- 0015 NERR35

STORAGE ASSIGNMENT (BLOCK, TYPE, RELATIVE LOCATION, NAME)

```

0001 000253 10L 0000 000347 1000F 0000 000354 101JF 0000 000423 1020F 0000 000070 1056
0002 000570 110L 0000 000336 1100F 0001 000074 1139 0001 000560 120L 0001 000341 151G
0003 000471 1756 0001 000137 20L 0001 000660 2268 0001 000762 2475 0001 000770 254G
0004 000644 90L 0000 R 000324 C1 0000 R 000323 C10 0000 R 000330 C28 0000 R 000330 C28
0005 000327 C21 0000 R 000324 C27 0000 R 000317 VE9 0000 I 000310 I 0000 I 000310 I
0006 000320 IDEG 0000 000471 INAPS 0000 000335 IPAGE 0000 I 000332 J 0000 I 000332 JDRD
0007 000333 JJ 0000 I 000334 JK 0000 I 000313 KK 0000 R 000321 PI 0000 R 000144 PSI
0008 000326 THICK 0000 R 000315 KD 0000 R 000311 AI 0000 R 000316 KRAND
0009 R 000000 Z
    
```

```

C0101 1* SUBROUTINE MCALC(IM,IRAMS,IMNS,IMNU,ADRS,IP,IN,NU,NU,
C0101 2* IMONTH,DATE,ITYEAR,ITRICK,ALAT)
C0103 3* DIMENSION IMD(Y0,4),AMS(Y0,4),ARMS(Y0),IMNU,IMDI,ADRS(9),JDRD
C0104 4* I(Y0),ANIS(0),AMC(12),JTRICK(Y0),ALAT(Y0),ZILUU),PSI(100)
C0104 5* DU 10 I=1,9C
C0107 6* XTRU=
C0110 7* XJEO=
C0111 8* KKEU=
C0112 9* DU 20 J=1,4
C0115 10* IF(IMNU(I),J)GT=500,OK=AMNS(I),G1,Y0,100 10 K0
C0117 11* AME3,141572654*(IM(I,10))/1E5
C0140 14* XTRAI=J*(IMNU)*AMS(I,10)
C0141 15* XJEAU=CS(IMNU)*AMS(I,10)
C0142 16* KKEK=1
C0143 17* CONTINUE
C0145 18* IF(ABS(G1)GT=100 10 AL
C0147 19* AMMP=ATRIAI/AJ
    
```


000762
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001013
001013
001013
001120

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00251 750
00251 760
00265 770
00270 780
00271 790
00272 800
END FOR

WRITE(6,102J)N(J),(X+S(J,1),IWD(J,1),I=1,4),X+MNS(J),
I+MVD(J),AORS(J),IDRJ(J)
30 CONTINUE
1020 FORMAT(1H0,10X,A5,1X,5(4X,F4.1,3X,13),4X,F4.2,3X,13)
RETURN
END

SCRIPT PRINTS

APPENDIX B. THEORETICAL DEVELOPMENT OF WIND DRIFT EQUATIONS

The frictional stress between two media is assumed to be proportional to the square of the relative velocity between them. Let \vec{V}_a be the wind velocity, \vec{V}_i be the ice velocity, assumed to move in +x direction and \vec{V}_w be the water velocity. The frictional stress (\vec{T}_a) between air and ice is then given by:

$$|\vec{T}_a| = k_a \rho_a |\vec{V}_a - \vec{V}_i|^2 = k_a \rho_a |\vec{V}_a|^2 \text{ since } |\vec{V}_a| \gg |\vec{V}_i|$$

The stress (\vec{T}_i) between ice and water is given by:

$$|\vec{T}_i| = k_w \rho_w |\vec{V}_i - \vec{V}_w|^2$$

In addition to these two forces we have the Coriolis force:

$$\vec{C} = f(\vec{V}_i \times \vec{k})$$

acting on the ice where $f = 2\omega \sin\theta$. The motion is assumed to take place under the equilibrium of these three forces therefore they must vectorially add to zero.

We now choose a coordinate system whose X - axis coincides with the direction of \vec{V}_i thus producing figure 3.

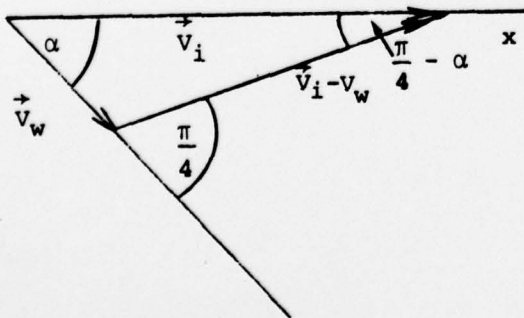


Figure 3a Velocity diagram

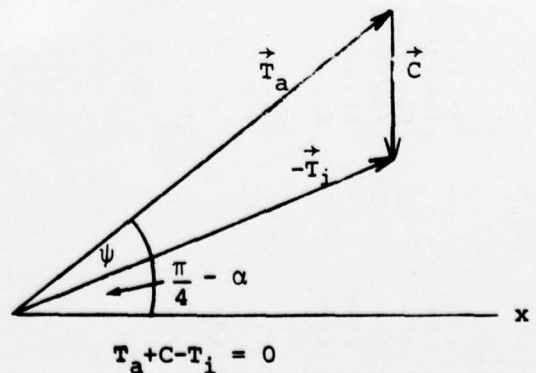


Figure 3b Force diagram

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Referring to figure 3a we see:

$$\frac{|\vec{v}_w|}{|\vec{v}_i - \vec{v}_w|} = \frac{\sin(\pi/4 - \alpha)}{\sin(\alpha)}$$

$$= \frac{\sin(\pi/4) \cos(\alpha) - \sin(\alpha) \cos(\pi/4)}{\sin(\alpha)}$$

$$= \sin(\pi/4) \cot(\alpha) - \cos(\pi/4) = \zeta$$

$$\cot(\alpha) - \cot(\pi/4) = \cos(\alpha) - 1 = \frac{\zeta}{\sin(\pi/4)}$$

$$\cot(\alpha) = 1 + 2\zeta$$

again from figure 3a we have:

$$|\vec{v}_i| = |\vec{v}_w| \cos(\alpha) + |\vec{v}_i - \vec{v}_w| \cos(\pi/4 - \alpha)$$

Now referring to figure 3b:

$$T_{ix} = \vec{T}_i \cdot \vec{i} = k_w \rho_w |\vec{v}_i - \vec{v}_w|^2 \cos(\pi/4 - \alpha)$$

$$T_{iy} = \vec{T}_i \cdot \vec{j} = k_w \rho_w |\vec{v}_i - \vec{v}_w|^2 \sin(\pi/4 - \alpha)$$

$$T_{ax} = \vec{T}_v \cdot \vec{i} = k_a \rho_a |\vec{v}_a|^2 \cos \Psi$$

$$T_{ay} = \vec{T}_v \cdot \vec{j} = k_a \rho_a |\vec{v}_a|^2 \sin \Psi$$

$$C_x = \vec{C} \cdot \vec{i} = -mf(kxV_i) \cdot \vec{i} = -mf(V_i xk) \cdot \vec{i}$$

$$C_y = \vec{C} \cdot \vec{j} = -mf(kxV_i) \cdot \vec{j} = -mf|\vec{v}_i| = f(V_i xk) \cdot \vec{j}$$

where: m = mass per unit area

k_w = the coefficient of friction between ice and water

k_a = the coefficient of friction between air and ice

ρ_w = the density of water

ρ_a = the density of air

$\vec{i}, \vec{j}, \vec{k}$ = the unit vectors along the x, y, and z directions respectively

therefore:

$$\Sigma Y \text{ forces} = -k_w \rho_w |\vec{V}_i - \vec{V}_w|^2 \sin(\pi/4 - \alpha) - mf |\vec{V}_i| + |\vec{T}_v| \sin \Psi = 0$$

$$\Sigma X \text{ forces} = -k_w \rho_w |\vec{V}_i - \vec{V}_w|^2 \cos(\pi/4 - \alpha) + |\vec{T}_v| \cos \Psi = 0$$

Solving for $\sin \Psi$ and $\cos \Psi$ and taking the ratio:

$$\begin{aligned} \tan \Psi &= \frac{mf |\vec{V}_i| + k_w \rho_w |\vec{V}_i - \vec{V}_w|^2 \sin(\pi/4 - \alpha)}{k_w \rho_w |\vec{V}_i - \vec{V}_w|^2 \cos(\pi/4 - \alpha)} \\ &= \tan(\pi/4 - \alpha) + \frac{mf |\vec{V}_i|}{k_w \rho_w |\vec{V}_i - \vec{V}_w|^2 \cos(\pi/4 - \alpha)} \end{aligned}$$

Now since:

$$|\vec{V}_i - \vec{V}_w| = \frac{|\vec{V}_i|}{\zeta \cos(\alpha) + \cos(\pi/4 - \alpha)}$$

and therefore:

$$k_w \rho_w |\vec{V}_i - \vec{V}_w|^2 = \frac{k_w \rho_w |\vec{V}_i|^2}{[\zeta \cos(\alpha) + \cos(\pi/4 - \alpha)]^2}$$

we have:

$$\tan \Psi = \tan(\pi/4 - \alpha) + \frac{B}{|\vec{V}_i|}$$

where:

$$B = \frac{mf [\zeta \cos \alpha + \cos(\pi/4 - \alpha)]^2}{k_w \rho_w \cos(\pi/4 - \alpha)}$$

Now since:

$$T_{vx} = |\vec{T}_v| \cos \Psi = T_{ix} = k_w \rho_w |\vec{V}_i - \vec{V}_w|^2 \cos(\pi/4 - \alpha)$$

$$= \frac{k_w \rho_w |\vec{V}_i|^2 \cos(\pi/4 - \alpha)}{[\zeta \cos(\alpha) + \cos(\pi/4 - \alpha)]^2}$$

we get:

$$|\vec{T}_v| = \frac{k_w \rho_w |\vec{V}_i|^2 \cos(\pi/4 - \alpha)}{[\zeta \cos(\alpha) + \cos(\pi/4 - \alpha)]^2 \cos \Psi}$$

Now since:

$$|\vec{T}_v| = k_a \rho_a |\vec{V}_a|^2$$

we get:

$$k_a \rho_a |\vec{V}_a|^2 = \frac{k_w \rho_w |\vec{V}_i|^2 \cos(\pi/4 - \alpha)}{[\zeta \cos(\alpha) + \cos(\pi/4 - \alpha)]^2 \cos \Psi}$$

or:

$$\frac{|\vec{V}_i|}{|\vec{V}_a|} = [\zeta \cos(\alpha) + \cos(\pi/4 - \alpha)] \sqrt{\frac{k_a \rho_a \cos(\Psi)}{k_w \rho_w \cos(\pi/4 - \alpha)}}$$

Now from above we have:

$$\frac{B}{|\vec{V}_i|} = \tan(\Psi) - \tan(\pi/4 - \alpha)$$

and multiplying this by the previous equation we get:

$$\frac{B}{|\vec{V}_a|} = [\zeta \cos(\alpha) + \cos(\pi/4 - \alpha)] \sqrt{\frac{k_a \rho_a \cos \Psi}{k_w \rho_w \cos(\pi/4 - \alpha)}} [\tan(\Psi) - \tan(\pi/4 - \alpha)]$$

The equation for ζ is derived from Ekman theory, as follows:

$$v_w = \frac{k_w \gamma^2}{\sqrt{f}} \sqrt{\frac{\rho_w}{\mu}}$$

$$\text{where: } \gamma = |\vec{V}_i - \vec{V}_w|$$

μ = the coefficient of viscosity between ice and water

$$\sqrt{\frac{\rho_w}{\mu}} = \frac{\pi}{N|\vec{v}_w|\sqrt{f}}$$

Where: $N = D/|\vec{v}_i|$ and is the depth of frictional mixing. This has been evaluated as $N = 473$, (Shuleikin). Now since:

$$\zeta = \frac{|\vec{v}_i|}{\gamma}$$

we derive:

$$\begin{aligned} \zeta &= \sqrt{\frac{\pi k_w \sqrt{2}}{Nf}} \\ &= \sqrt{\frac{\pi k_w \sqrt{2}}{473f}} \end{aligned}$$

It can be assumed with sufficient accuracy that the density of air (ρ_a) is 1.25×10^{-3} gm per cm^3 , the density of water is 1 gm per cm^3 , the coefficient of friction between ice and water (k_w) is 4×10^{-3} and between air and ice (k_a) is 2×10^{-3} . From observations it has been determined that $\alpha = 27^\circ$. In addition, since the density of ice is .9 and the mass per unit area of ice (m) is the density times the thickness (L), $m = .9L$. Therefore:

from the equation for $\frac{B}{|\vec{v}_a|}$ above, we get:

$$\frac{1}{|\vec{v}_a|} = \frac{\rho_w k_w \cos(18^\circ)}{.9Lf[\zeta \cos(27^\circ) + \cos(18^\circ)]} \sqrt{\frac{6.25 \times 10^{-4} \cos(\Psi)}{\cos(18^\circ)}} \quad [\sqrt{\sec^2(\Psi) - 1} - \tan(18^\circ)]$$

$$\text{let: } Z = \frac{1}{\cos^2(\Psi)}$$

$$\text{then } \frac{1}{|\vec{V}_a|} = \frac{.004 \cos(18^\circ) \frac{1}{Z^{\frac{1}{2}}} \sqrt{\frac{6.25 \times 10^{-4}}{\cos 18^\circ}} [\sqrt{Z-1} - \tan 18^\circ]}{.9 \text{Lf} \left[\frac{.004}{473f} \frac{2\pi}{\cos(27^\circ) + \cos(18^\circ)} \right]}$$

$$\tan(18^\circ) = \frac{Z^{\frac{1}{2}} \cdot .9 \text{Lf} \left[\frac{.004}{473f} \frac{2\pi}{\cos 27^\circ + \cos 18^\circ} \right]}{|\vec{V}_a| \left[.004 \cos 18^\circ \sqrt{\frac{6.25 \times 10^{-4}}{\cos 18^\circ}} \right]} = \sqrt{Z-1}$$

$$\text{let: } C_1 = \tan(18^\circ)$$

$$C_2 = \frac{.004 \cos(18^\circ) \sqrt{\frac{6.25 \times 10^{-4}}{\cos(18^\circ)}}}{.9 \text{Lf} \left[\frac{.004}{473f} \frac{2\pi}{\cos(27^\circ) + \cos(18^\circ)} \right]}$$

$$\text{then: } \sqrt{Z-1} = C_1 + \frac{Z^{\frac{1}{2}}}{C_2 |\vec{V}_a|}$$

$$Z = C_1^2 + \frac{Z^{\frac{1}{2}}}{C_2^2 |\vec{V}_a|^2} + \frac{2C_1 Z^{\frac{1}{2}}}{C_2 |\vec{V}_a|} + 1$$

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20. greater accuracy and for computations of divergence and convergence interaction between floes must be considered.

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p. 16	figure 3a	change	$\vec{V}_i - V_w$	to	$\vec{V}_i - \vec{V}_w$
p. 17	line 5	"	$\cos(\alpha) - 1$	to	$\cot(\alpha) - 1$
"	" 6	"	$1 + 2\zeta$	to	$1 + \sqrt{2}\zeta$
"	" 12	"	\vec{T}_v	to	\vec{T}_a
"	" 13	"	\vec{T}_v	to	\vec{T}_a
p. 18	" 2	"	$ \vec{T}_v $	to	$ \vec{T}_a $
"	" 3	"	$\cos(\pi/4 - \alpha) \vec{T}_v $	to	$\cos(\pi/4 - \alpha) + \vec{T}_a $
"	" 16	"	T_{vx}	to	T_{ax}
"	" "	"	$ \vec{T}_v $	to	$ \vec{T}_a $
p. 19	" 3	"	$ \vec{T}_v $	to	$ \vec{T}_a $
"	" 5	"	$ \vec{T}_v $	to	$ \vec{T}_a $
p. 21	" 2	"	$\sqrt{\frac{6.25 \times 10^4}{\cos 18^\circ}}$	to	$\sqrt{\frac{6.25 \times 10^{-4}}{\cos 18^\circ}}$
"	" 3	"	$\tan(18^\circ) =$	to	$\tan(18^\circ) +$
"	" "	"	$\sqrt{\frac{6.25 + 10^{-4}}{\cos 18^\circ}}$	to	$\sqrt{\frac{6.25 + 10^{-4}}{\cos 18^\circ}}$