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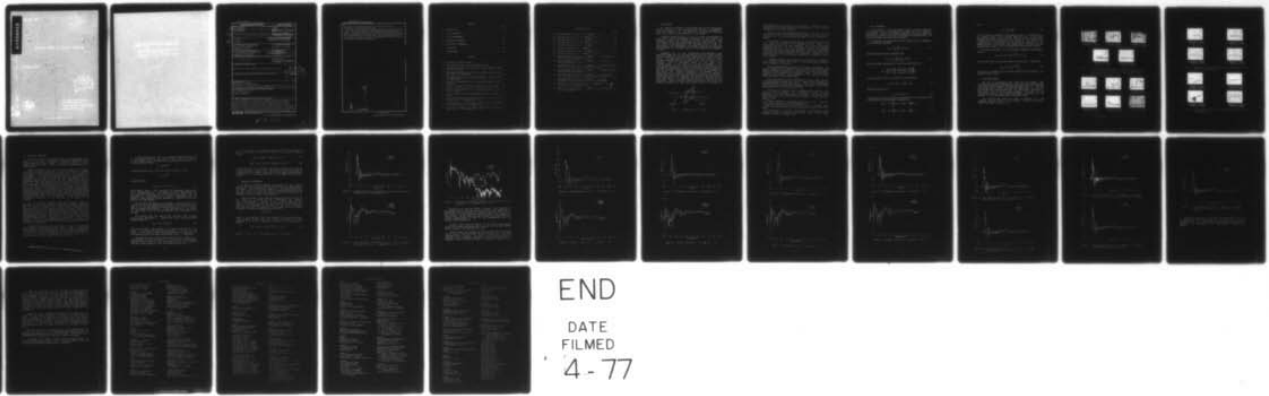
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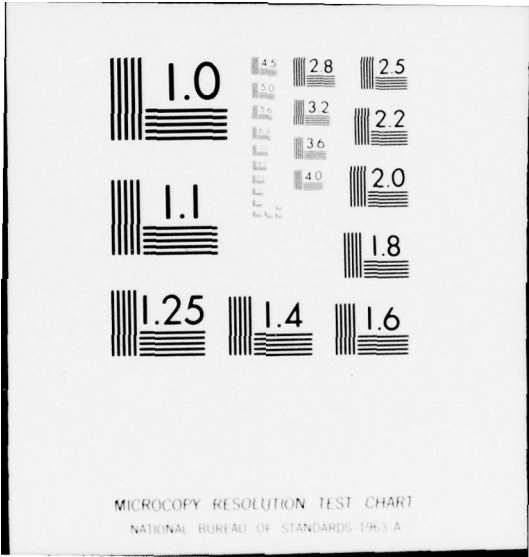
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Simulator Fields and Ground Constants

February 1977

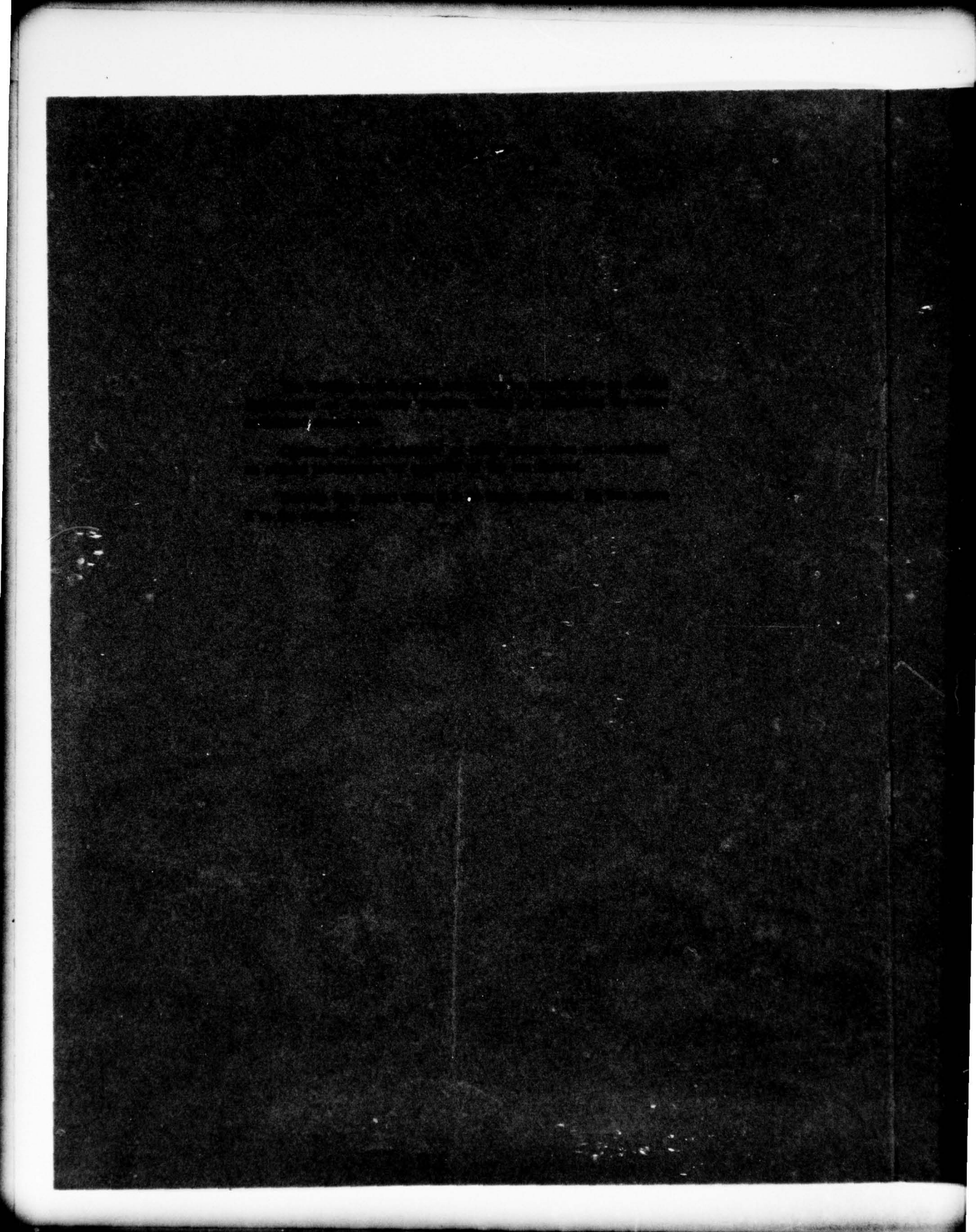
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## 1. INTRODUCTION

The problem considered in this report concerns the relationship between components of the measured fields due to an electromagnetic pulse (EMP) simulator and the possibility of extracting information about the conductivity and permittivity of the ground.

Radiation fields emitted by a pulser can locally be approximated by plane waves, and the monochromatic components of the incident and reflected pulses are related by Fresnel's coefficients. These coefficients involve the ground parameters; when they are known, the free field can be computed from the resultant fields in the air. Alternatively, two measurements of different fields for the same pulse can be compared for different values of the parameters until agreement is found.

Simulators such as the Transportable Electromagnetic Pulse Simulator (TEMPS) and the Army EMP Simulator Operation (AESOP) produce mainly horizontally polarized fields, especially on the center line (see fig. 1). For these fields, the reflected electric field is almost 180 deg out of phase with the incident field, and the peak of the resultant field is determined mostly by the delay time, returning quickly to zero after that. The vertical component of the resultant magnetic field is strictly proportional to the electric field. Simultaneous measurements of these two fields can be used to determine that the respective probes produce traces that are in agreement with each other. The horizontal component of the magnetic field is proportional to the difference (essentially the sum of the magnitudes) between the incident and reflected fields and shows much more detail of the incident pulse. This component can be used to determine the free field and then the resultant electric field, by using the Fresnel coefficient. When the correct values of the ground conductivity and dielectric constant are used, this procedure serves to verify both the

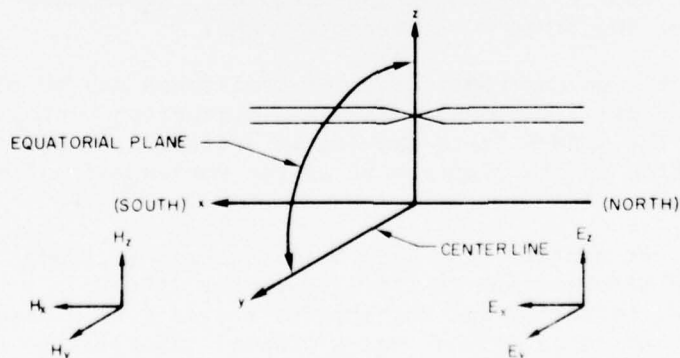


Figure 1. The TEMPS coordinate system.

ground parameters and the agreement of the probes. Furthermore, precise measurements of the field would allow a determination of the frequency dependence of the ground parameters.

Two sets of field measurements were used in this work. One was taken with the sensor box on the ground; the other, at a height of 5 m. The quality of the photographs was acceptable, but much improvement is needed.

The electric field was computed from the radial magnetic field, and this curve was compared to the measured electric field. The corresponding spectra also were compared. The values of the ground parameters were varied to find what effect they have on the agreement between both sets of curves, and reasonable values of the parameters were found that produced acceptable matching of the curves. Other input parameters, such as the height and the calibration constants of the probe, were varied, but no significant improvement was found to justify such a change.

A somewhat different way of comparing the curves also is presented, and it should be tried in future work. It could avoid some difficulties with the numerical computations.

Similar considerations are valid for "vertical" polarization. The vertical component of the resultant electric field and the horizontal magnetic field are proportional to each other, and they can be used to compute the radial component of the electric field. Field mapping has shown that the electric field produced by the TEMPS has a sizable vertical component off the center line.

Once this procedure is well established, it can be used to map the ground parameters at a given site and to observe their variation with the water content and other local changes. More refined measurements also could be used to determine the frequency dependence of the ground parameters for the range of interest for EMP.

Information on numerical Fourier transforms can be found,<sup>1</sup> and the theory of pulses incident on a conducting ground has been published.<sup>2</sup> The TEMPS field mapping is available,<sup>3</sup> and details about the digitization of the traces will be the subject of a future report by Thomas V. Noon.

<sup>1</sup>Alfred G. Brandstein and Egon Marx, *Numerical Fourier Transform*, Harry Diamond Laboratories TR-1748 (September 1976).

<sup>2</sup>Egon Marx, *Reflected and Transmitted Fields for a Plane-wave Pulse Incident on Conducting Ground*, Harry Diamond Laboratories TR-1740 (April 1976).

<sup>3</sup>E. Patrick and S. Soo Hoo, *Transportable Electromagnetic Pulse Simulator (TEMPS) Preliminary Field Mapping Report*, Harry Diamond Laboratories TM-74-15 (October 1974).

## 2. FIELD COMPONENTS

An EMP simulator, such as the TEMPS or AESOP, produces a pulse that on the center line is horizontally polarized to a good degree of approximation. Locally, the fields correspond to those of a plane wave, and Fresnel's formulas can be used to determine the reflected wave. The ground is assumed to be plane and homogeneous.

To determine the reflected field, the incident field is decomposed into its Fourier components,

$$E(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} E_{\omega} e^{i\omega t} d\omega ; \quad (1)$$

then the reflected field is obtained from

$$E'(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} E_{\omega} R_h(\omega) e^{i\omega t} d\omega , \quad (2)$$

where the Fresnel coefficient for horizontal polarization is

$$R_h = \frac{\sin \psi - [\kappa - i(\sigma/\epsilon_0 \omega) - \cos^2 \psi]^{\frac{1}{2}}}{\sin \psi + [\kappa - i(\sigma/\epsilon_0 \omega) - \cos^2 \psi]^{\frac{1}{2}}} . \quad (3)$$

The total field in the air at height  $h$  is then given by

$$E_y(t) = E_h(t) + E'_h(t - t_D) , \quad (4)$$

where the time delay is

$$t_D = 2h \sin \psi / c . \quad (5)$$

The magnetic field of each pulse is perpendicular to the electric field, and the vertical and horizontal components are

$$H_x(t) = Z_0^{-1} [E_h(t) - E'_h(t - t_D)] \sin \psi , \quad (6)$$

$$H_z(t) = Z_0^{-1} [E_h(t) + E'_h(t - t_D)] \cos \psi , \quad (7)$$

where

$$Z_0 = (\mu_0/\epsilon_0)^{1/2}. \quad (8)$$

Thus, the vertical component of the magnetic field is proportional to the electric field. For a perfect conductor,  $R_h = -1$ , and these components follow the free field until time  $t_D$  and then rapidly return to zero, due to the cancellation of the fields of the incident and reflected pulses. On the other hand, the horizontal component of the magnetic field is proportional to the delayed sum of the two pulses and approximates the shape of the free field when the time delay is small.

The Fourier transform of the horizontal component of the magnetic field is

$$H_{x\omega} = Z_0^{-1} (1 - R_h e^{-i\omega t_D}) \sin \psi E_\omega, \quad (9)$$

and the free field can be obtained from the measured  $H_x$ . Furthermore,

$$E_{y\omega} = (1 + R_h e^{-i\omega t_D}) E_\omega \quad (10)$$

also can be computed, and its Fourier transform should reproduce the measured electric field.

### 3. FIELD MEASUREMENTS

Two sets of measurements were taken for this report. They consisted of simultaneous measurements of  $E_x$  and  $H_y$  with different faces of the same Stanford Research Institute dome-type sensor box. Different sweep speeds were recorded during separate shots; that is, only two pictures were obtained from each shot. The measurements were taken on the center line, at 100 m from the simulator. The first set was obtained from a sensor on the ground with AESOP; the second set, at a height of 5 m with the TEMPS pulser in the AESOP frame.

The time-amplitude traces are shown in figures 2 to 5. The composite digitized traces of the magnetic field and the frequency spectra are shown in figures 6 to 9.

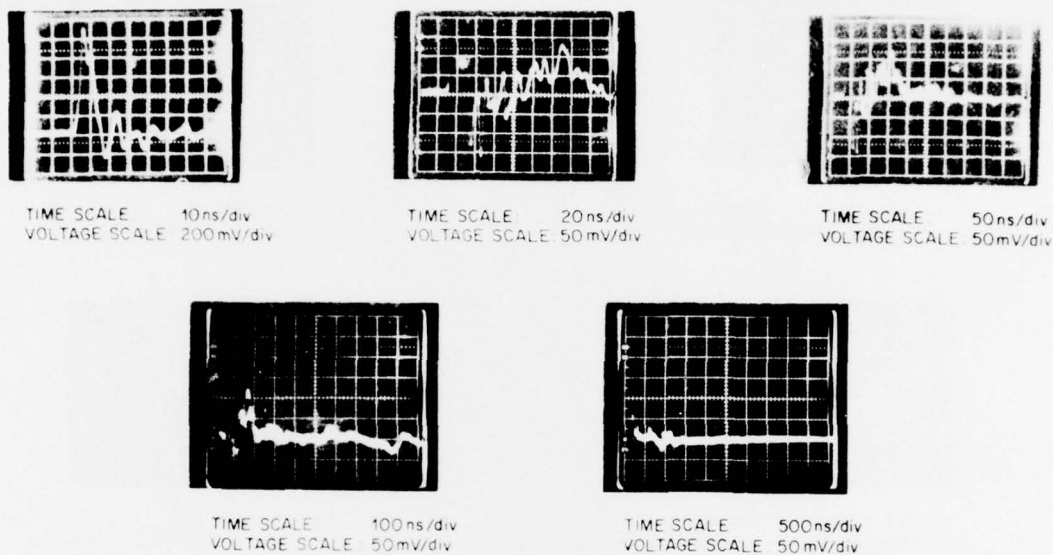


Figure 2. Time-amplitude traces that form composite trace for horizontal electric field (parallel to Pulsar) on center line at 100 m from antenna and with sensor box on ground (sensor height at 0.65 m).

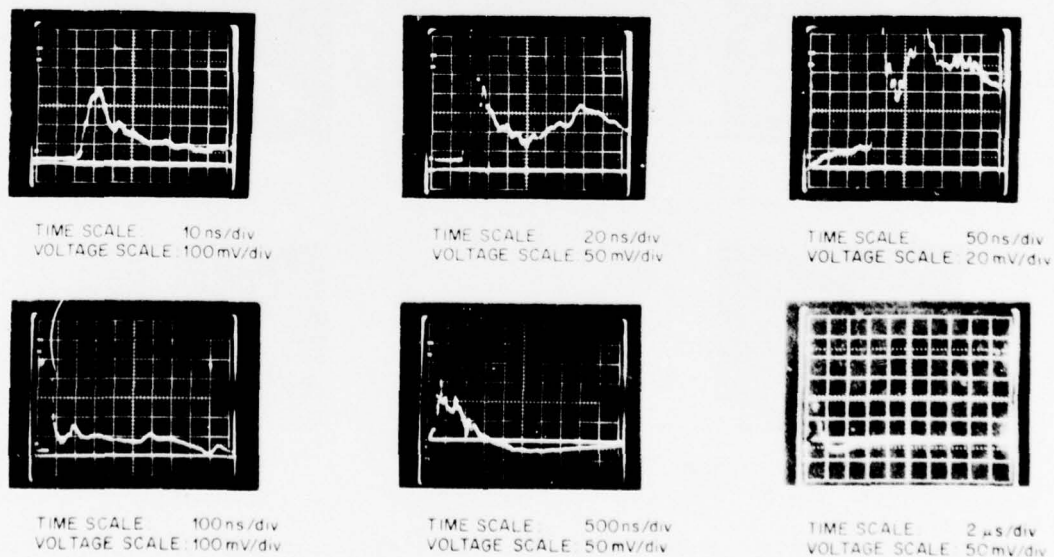
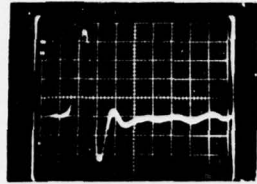
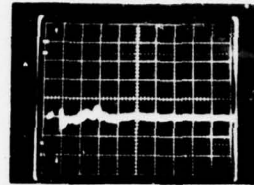


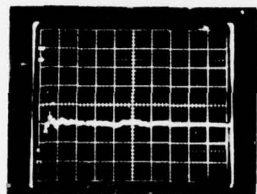
Figure 3. Time-amplitude traces for horizontal (radial) magnetic field at 100 m on ground.



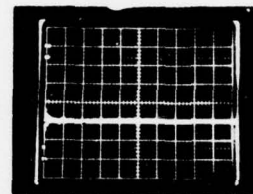
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VOLTAGE SCALE: 100 mV/div



TIME SCALE: 50 ns/div  
VOLTAGE SCALE: 100 mV/div

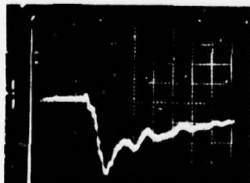


TIME SCALE: 200 ns/div  
VOLTAGE SCALE: 50 mV/div

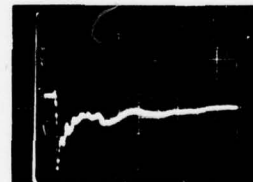


TIME SCALE: 1 μs/div  
VOLTAGE SCALE: 50 mV/div

Figure 4. Time-amplitude traces for horizontal electric field at 100 m with sensor 5 m aboveground.



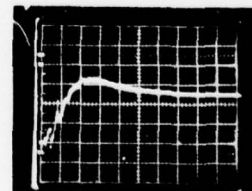
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TIME SCALE: 50 ns/div  
VOLTAGE SCALE: 100 mV/div



TIME SCALE: 200 ns/div  
VOLTAGE SCALE: 50 mV/div



TIME SCALE: 1 μs/div  
VOLTAGE SCALE: 50 mV/div

Figure 5. Time-amplitude traces for horizontal magnetic field at 100 m 5 m aboveground.

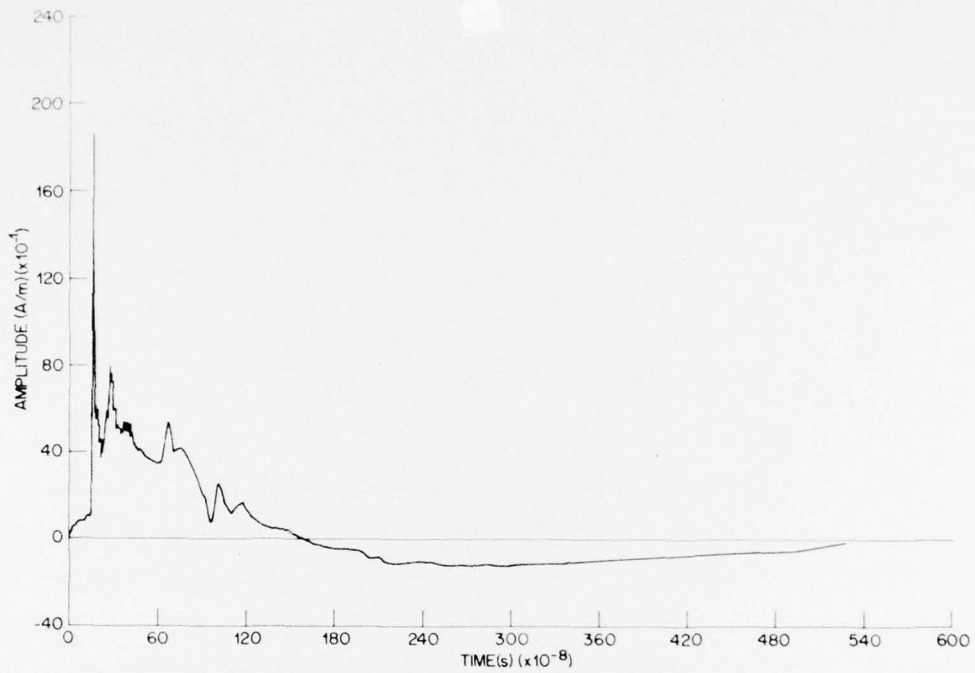


Figure 6. Composite time-amplitude trace of horizontal magnetic field on ground.

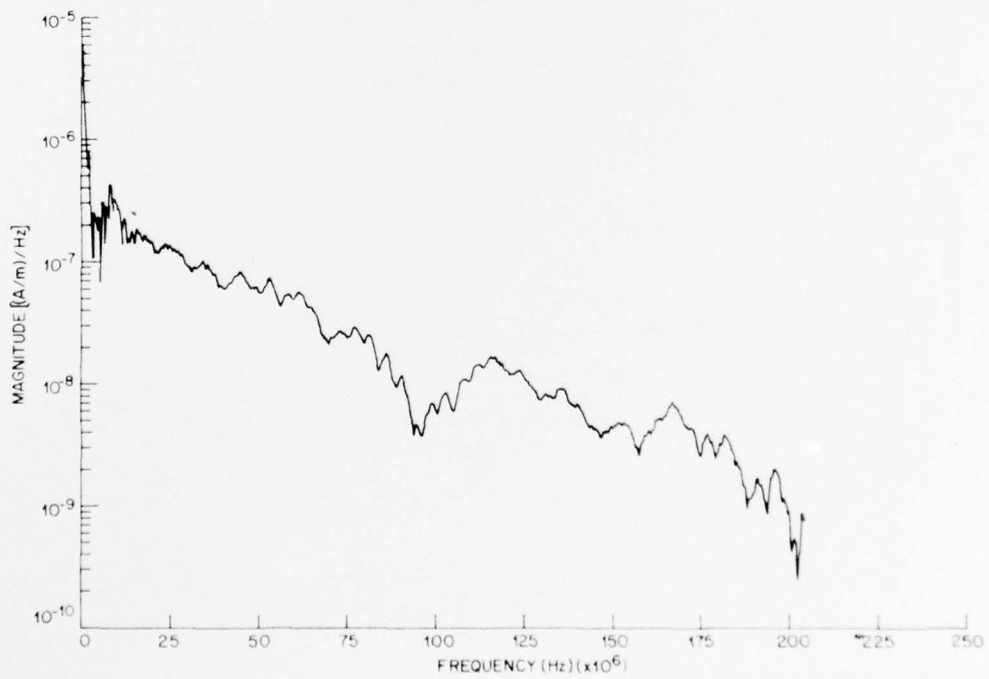


Figure 7. Frequency spectrum of horizontal magnetic field on ground.

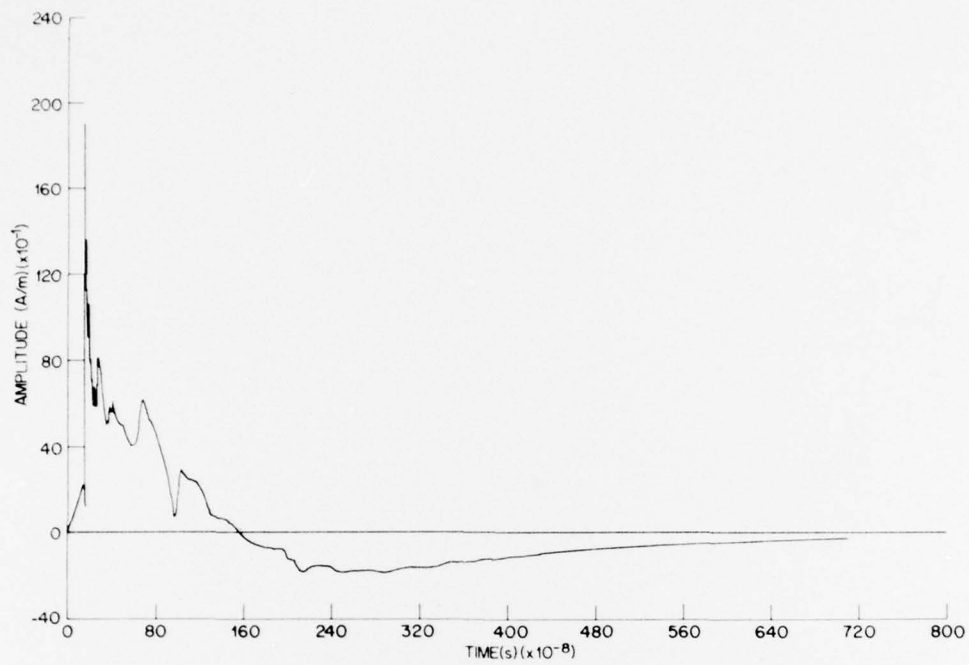


Figure 8. Composite time-amplitude trace of horizontal magnetic field 5 m aboveground.

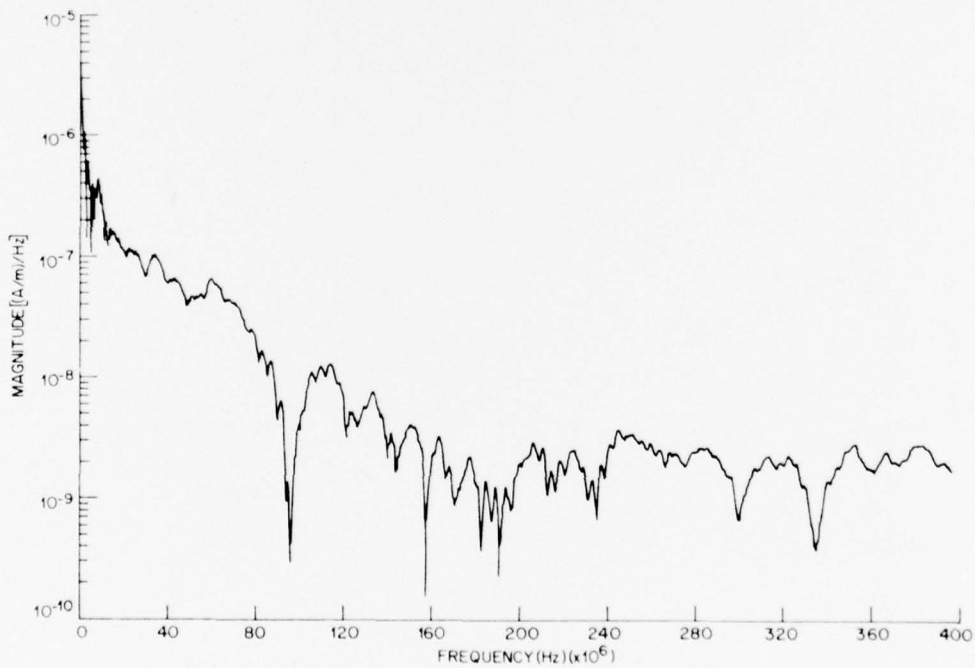


Figure 9. Frequency spectrum of horizontal magnetic field 5 m aboveground.

#### 4. NUMERICAL PROCEDURES

For use as input to the computer program, the time-amplitude traces have to be digitized. Each trace is digitized separately, and a computer program, TRANS, developed by Thomas V. Noon, at the Harry Diamond Laboratories (HDL), gives a single set of coordinates for the entire curve.

Several problems are associated with this procedure. It is assumed that pulses in a set are identical, but they are not really; normally, deviations are small enough so that no severe errors are introduced in this manner. A point has to be identified in each picture that corresponds to the end of the previous trace; this identification is sometimes difficult, but an error that was inadvertently made was discovered through discrepancies in the two curves for the electric field. The ramp that precedes the actual pulse is difficult to obtain for the magnetic field and essentially impossible for the electric field; this ramp was digitized from the third picture in the first set, and it was assumed to be the same for the second set. Another problem related to the ramp is the lack of a precise time when the pulse starts; when comparing the two pulses in the output, one pulse had to be shifted until the leading edges coincided. More generally, the quality of the pictures obtained from the oscilloscopes is such that there is considerable uncertainty in the definition of the points on the digitizer.

Once an acceptable composite trace of the magnetic field was obtained, the points were linearly interpolated to obtain an equispaced set of points suitable for a Fast Fourier Transform (FFT). Then equations (9) and (10) were used to obtain the Fourier transform of the electric field, and an inverse FFT produced a computed trace for the electric field, which was plotted with the measured field. Since this field goes quickly back to zero, only the initial portion of the trace was considered of interest, and most of the resulting ramp also was eliminated from the plots. Alternatively, the absolute values of the Fourier transforms of the computed and measured electric fields were plotted on a semilog plot either for the full range given by the FFT or for only the initial part.

A decision that has to be made is what the number of interpolated points will be. The number 8192 was chosen, because it samples the curve adequately in the region with the largest density of points when the final time is chosen about the end of the magnetic field pulse, at 7.5 or 10  $\mu$ s. Doubling or quadrupling this number of points did not introduce any significant change in the resulting trace.

A serious problem that arose was a large oscillation superimposed on the computed trace of the electric field. With the help of William T. Wyatt of HDL, the reason for this oscillation was found to be the division by the factor

$$1 - R_h e^{-i\omega t_D}$$

to obtain the free field. The value of  $R_h$  is close to -1, and

$$1 + e^{-i\omega t_D}$$

vanishes whenever

$$\omega t_D = k\pi, \quad k = 1, 3, 5, \dots, \quad (11)$$

which causes a peak in the computed  $E_\omega$  for frequencies close to this value. The numerator,  $H_{x(\omega)}$ , also should vanish for these frequencies, but recording, digitization, and computation errors account for the appearance of a large peak in  $E_\omega$ . Similar computations done for analytic curves (such as a double exponential), displaced in time, show basically the same behavior.

For the box on the ground, the time delay is 0.85 ns, and the first frequency at which this peak occurs is 589 MHz. With 8192 points and a time of 7.5  $\mu$ s, the significant frequency limit for an FFT is 546 MHz, and this problem barely shows up. On the other hand, for a 5-m height, the time delay is 4.9 ns, and the frequency of the first peak is only 101 MHz.

The solution that was used for this difficulty was a filter function that multiplied  $E_\omega$ . Several were tried, and the function finally chosen was

$$F(\omega) = \left| \sin \omega t_D / \omega t_D \right|^n, \quad (12)$$

which is 1 for small  $\omega$  and vanishes if  $\omega$  is given by equation (11). The value  $n = 2$  was used for the box on the ground;  $n = 1$ , for the 5-m height. If this filter is used, the frequency spectrum around the first zero and after that is virtually ignored, due to the  $\omega^{-n}$  dependence.

Another method that could be tried, especially for a height of 5 m, would be based on the clear time of 4.9  $\mu$ s to obtain the corresponding reflected field, subtract it from the measured trace, and proceed in this way to obtain the free field. This method was not tried.

It is possible also, following a procedure used by Janis Klebers of HDL, to use equations (4) and (6) to separate the incident and reflected fields,

$$E_h(t) = E_y(t)/2 + Z_o H_x(t)/(2 \sin \psi) , \quad (13)$$

$$E'_h(t - t_D) = -E_y(t)/2 + Z_o H_x(t)/(2 \sin \psi) . \quad (14)$$

Then the matching of the Fresnel coefficient can be done from the Fourier transforms of  $E_h$  and  $E'_h$ . One difficulty with this approach is the need to know a common initial time for the traces, which knowledge is difficult to get because the ramp is not recorded for the electric field.

#### 5. VARIATION OF PARAMETERS

A number of different parameters can be varied in this computer program. The main concern of this work related to the conductivity of the ground,  $\sigma$ , and the dielectric constant,  $\kappa$ . The height of the sensor also was varied, as were the probe calibration constants, but the measured values were found to be adequate. The angle of incidence was determined from the geometry of the experiment.

A good coincidence of the computed and measured electric fields for the sensor at a height of 0.65 m aboveground was obtained with  $\sigma = 20$  mmho/m and  $\kappa = 25$  (fig. 10, 11). Figure 12 shows the full range of the frequency spectrum that is obtained from an 8192-point FFT. There is good agreement in the shape of the Fourier transforms throughout the range, even though the high-frequency end of the computed transform is incorrectly enhanced by the division by

$$1 + R_h e^{-i\omega t_D}.$$

There is an unexplained dip in the transform of the measured electric field at about 280 MHz, where the computed spectrum has a peak. Agreement in the traces is improved by filtering out this frequency, by using

$$F(\omega) = (\sin \omega t_1 / \omega t_1)^{1/2} (\sin \omega t_D / \omega t_D)^{3/2}, \quad (15)$$

where  $t_1 = 1.732 \times 10^{-9}$  s, very nearly twice the time delay.

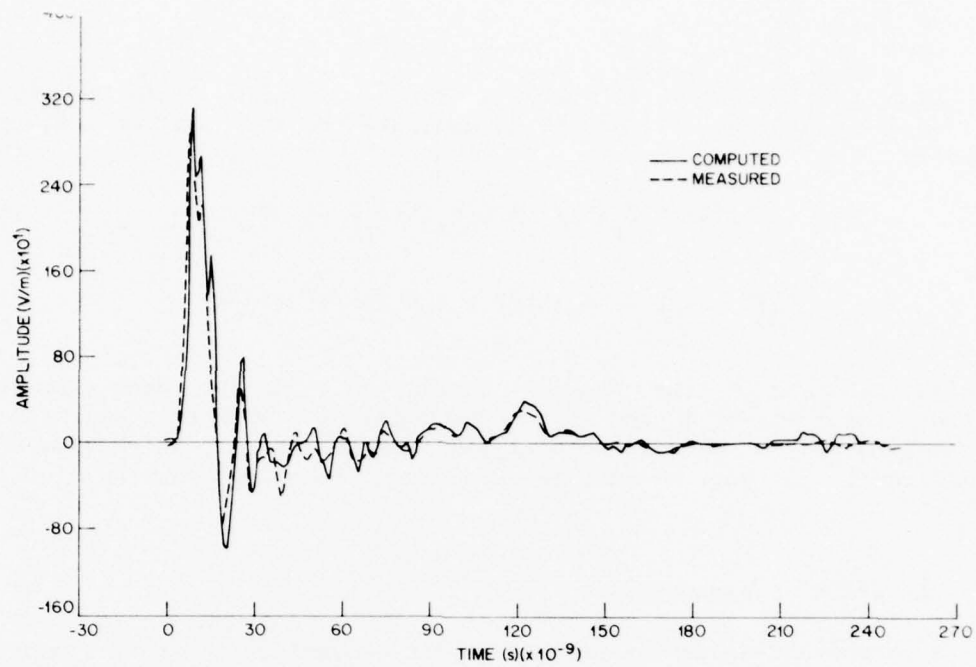


Figure 10. Computed and measured time-amplitude traces of electric field on ground for  $\sigma = 20$  mmho/m and  $\kappa = 25$ .

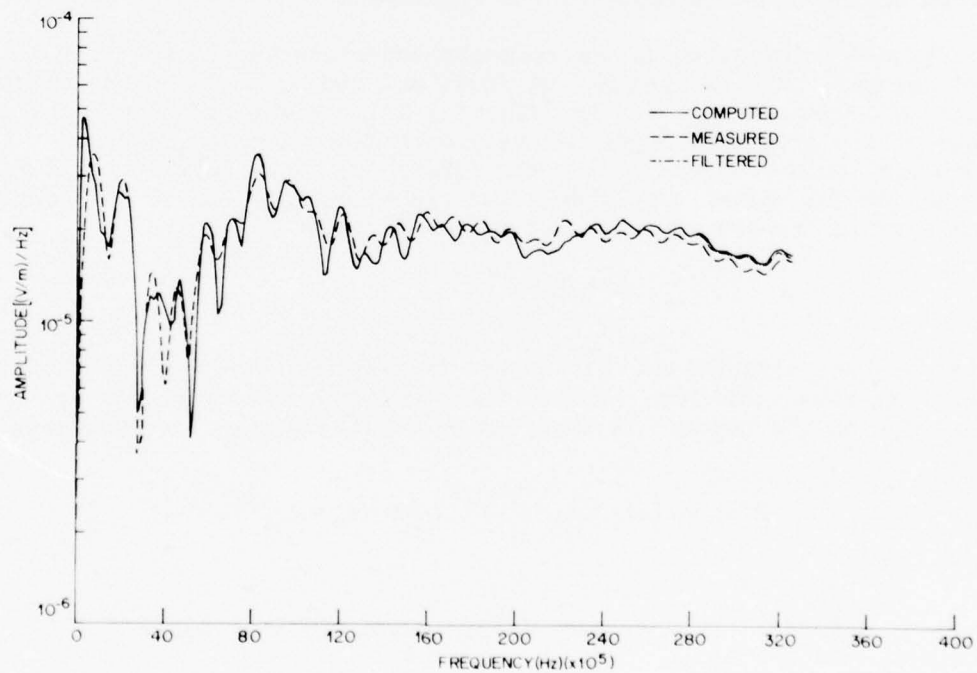


Figure 11. Low-frequency part of spectrum of electric field, as computed from both fields, for  $\sigma = 20$  mmho/m and  $\kappa = 25$ .

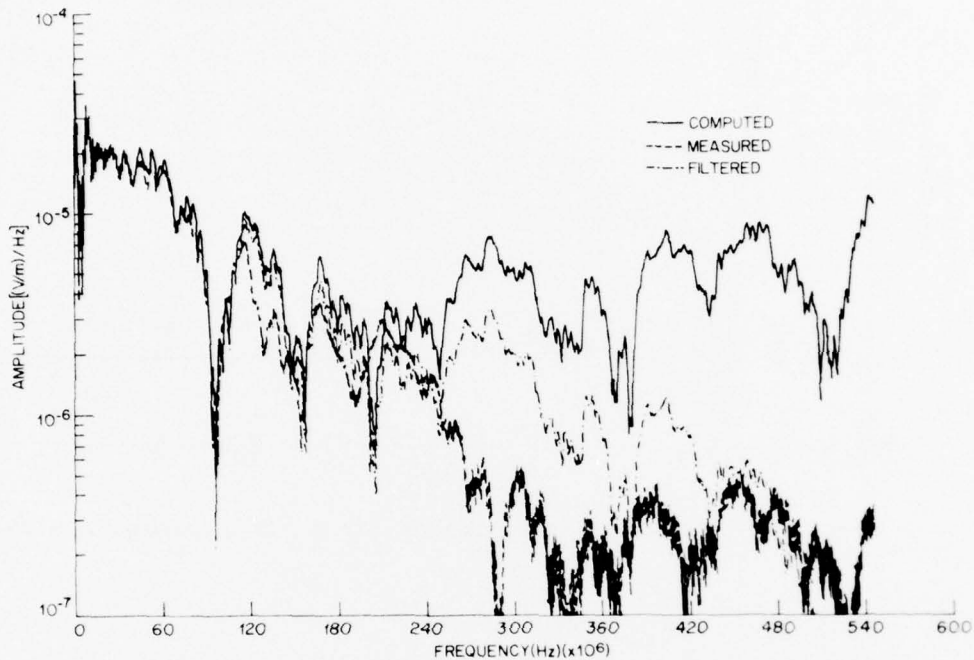


Figure 12. Full range of frequency spectrum as provided by Fast Fourier Transform, for  $\sigma = 20$  mmho/m and  $\kappa = 25$ .

Figures 13 to 20 show the effects of varying  $\sigma$  and  $\kappa$  to values at the extremes that can be expected for the ground. The conductivity is changed from 0.5 to 100 mmho/m; the dielectric constant, from 1 to 100. The effects of these changes are quite noticeable; the conductivity affects mainly the late times and low frequencies, while the dielectric constant changes mainly the peak of the time-amplitude trace and somewhat higher frequencies.

Figures 21 and 22 show the effects of the change in the assumed height of the sensor aboveground, which through the time delay affects mainly the peak in the time-amplitude trace.

Figure 23 shows the computed trace that is obtained by this method when no filter is used, and figure 24 shows the trace for a 4096-point transform with no filter. The latter is less accurate, but is not affected by the "resonance," because it does not go as high in frequency. Figure 25 shows the effect of the filter in equation (15).

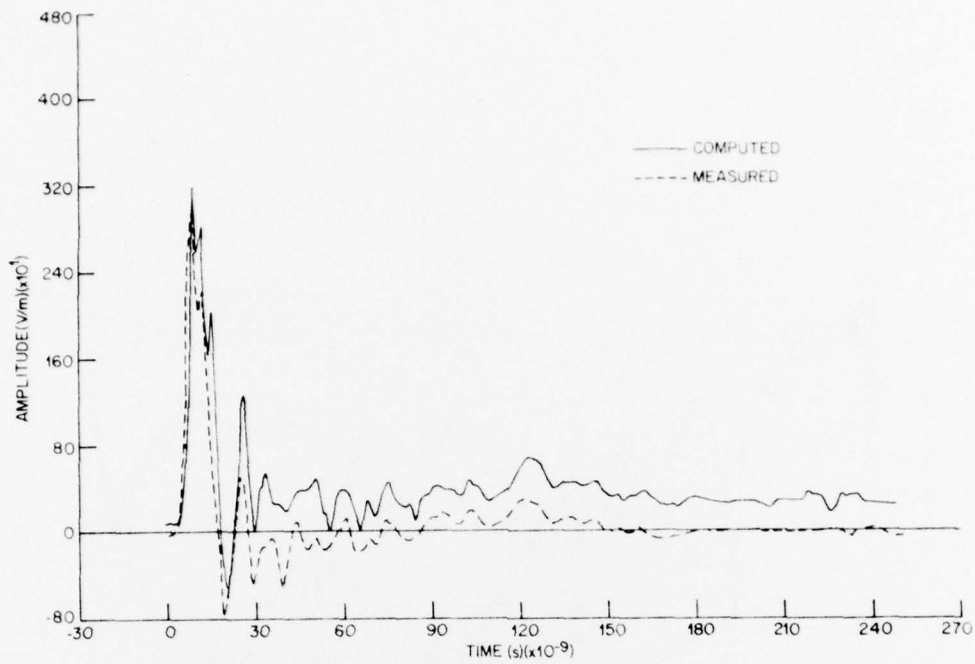


Figure 13. Time-amplitude traces for  $\sigma = 0.5$  mmho/m,  $\kappa = 25$ .

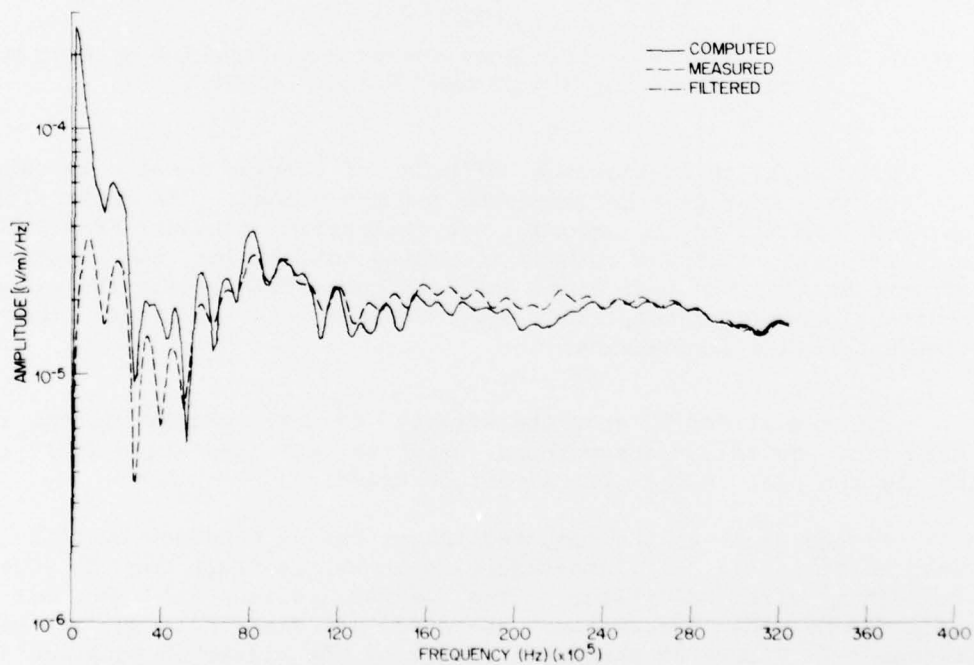


Figure 14. Frequency spectra for  $\sigma = 0.5$  mmho/m,  $\kappa = 25$ .

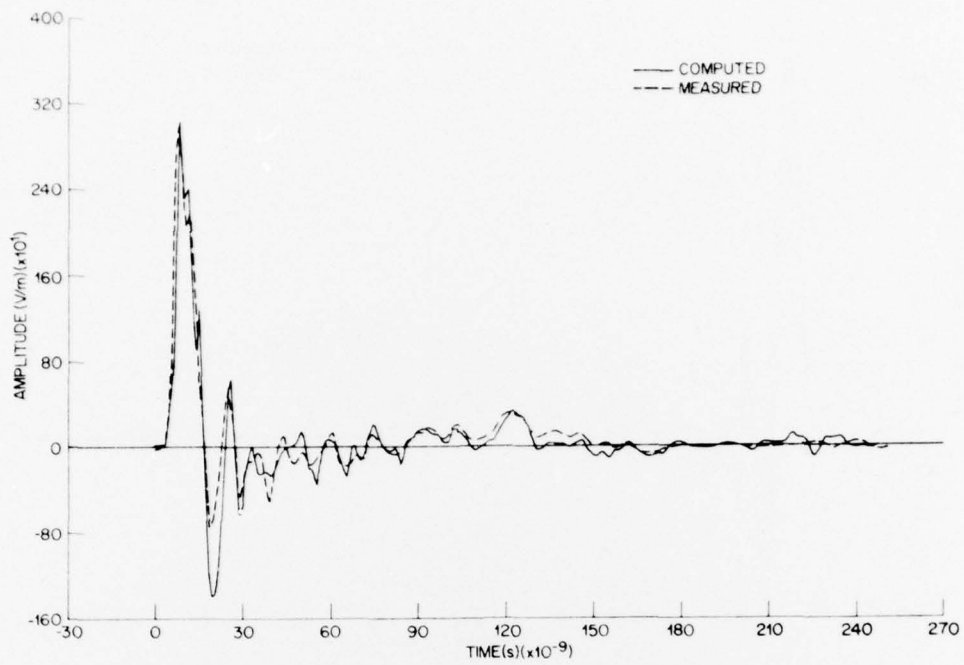


Figure 15. Time-amplitude traces for  $\sigma = 100$  mmho/m,  $\kappa = 25$ .

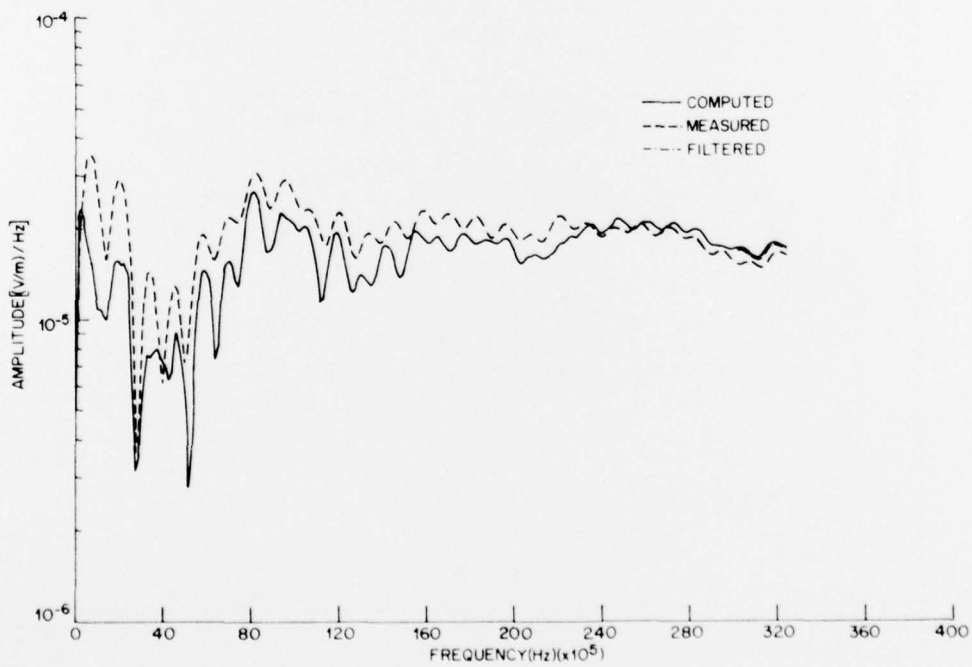


Figure 16. Frequency spectra for  $\sigma = 100$  mmho/m,  $\kappa = 25$ .

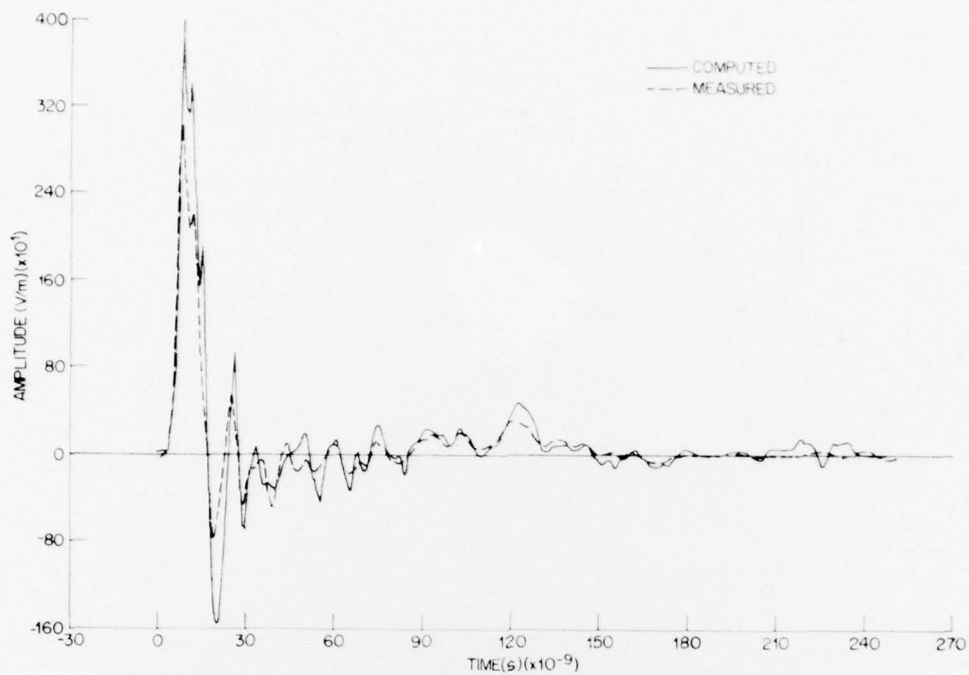


Figure 17. Time-amplitude traces for  $\sigma = 20$  mmho/m,  $\kappa = 1$ .

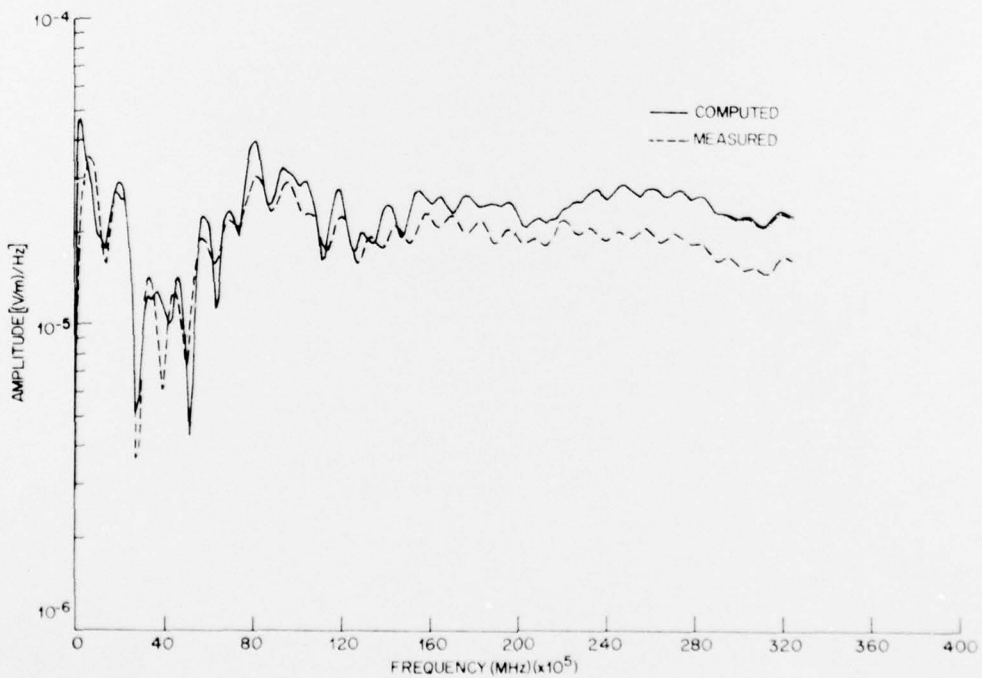


Figure 18. Frequency spectra for  $\sigma = 20$  mmho/m,  $\kappa = 1$ .

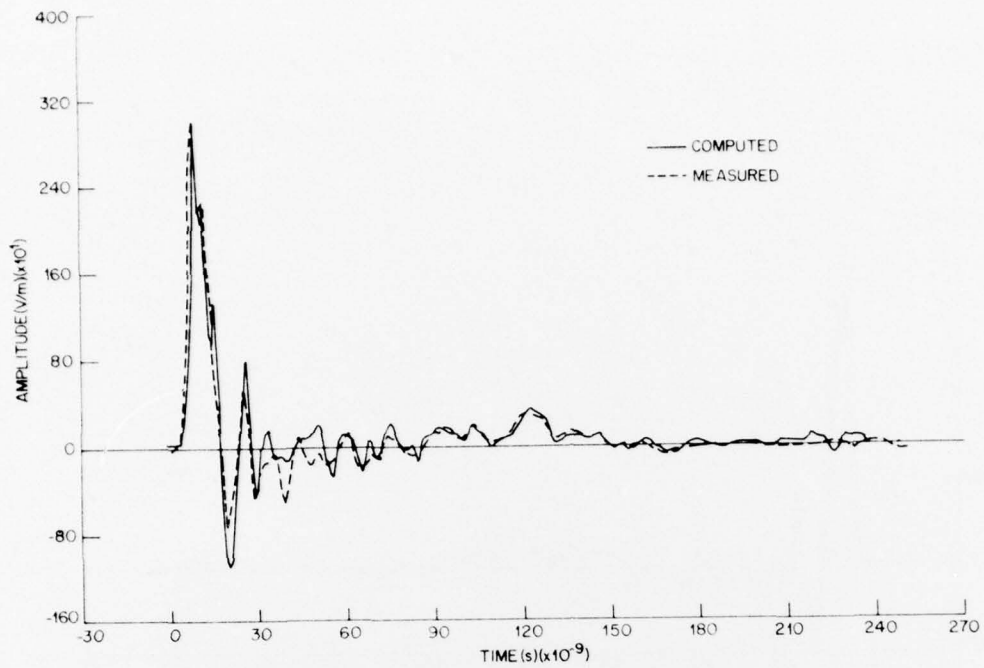


Figure 19. Time-amplitude traces for  $\sigma = 20$  mmho/m,  $\kappa = 100$ .

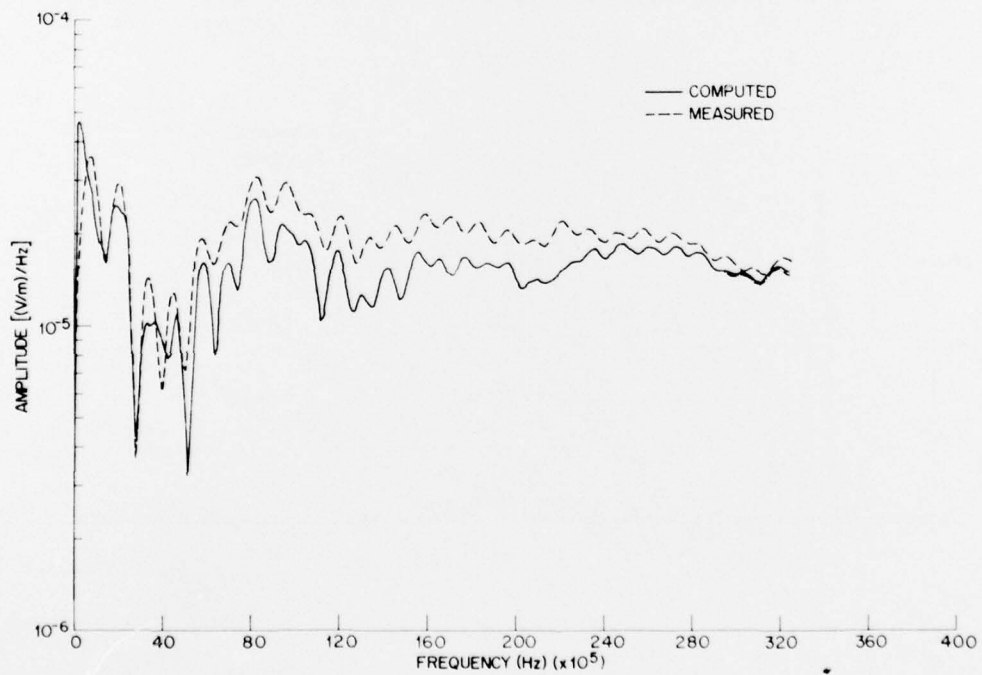


Figure 20. Frequency spectra for  $\sigma = 20$  mmho/m,  $\kappa = 100$ .

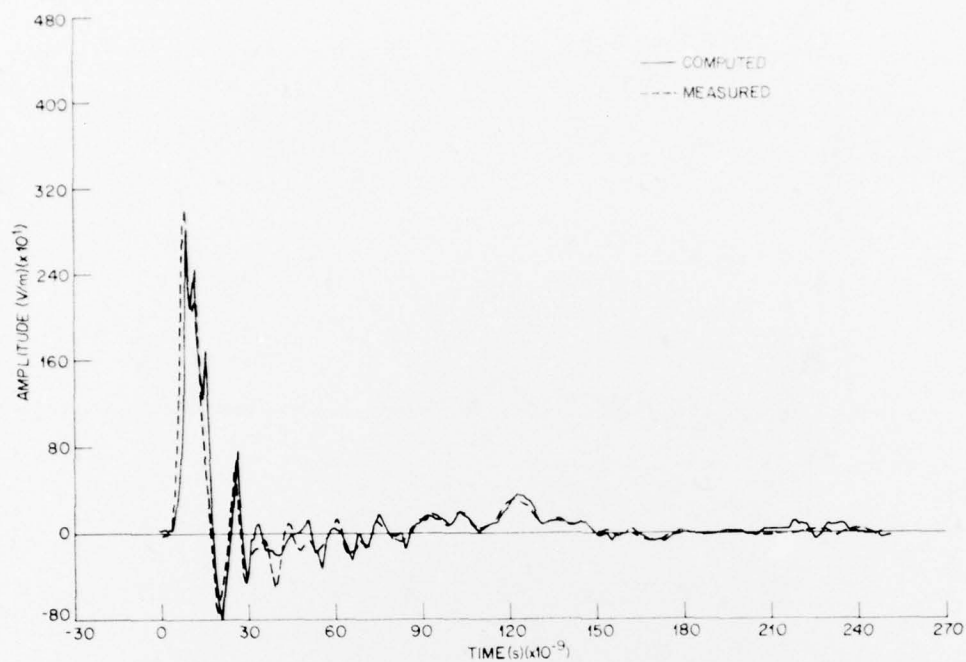


Figure 21. Time-amplitude traces for  $\sigma = 20$  mmho/m,  $\kappa = 25$ , assuming that height of sensor aboveground is 0.55 m.

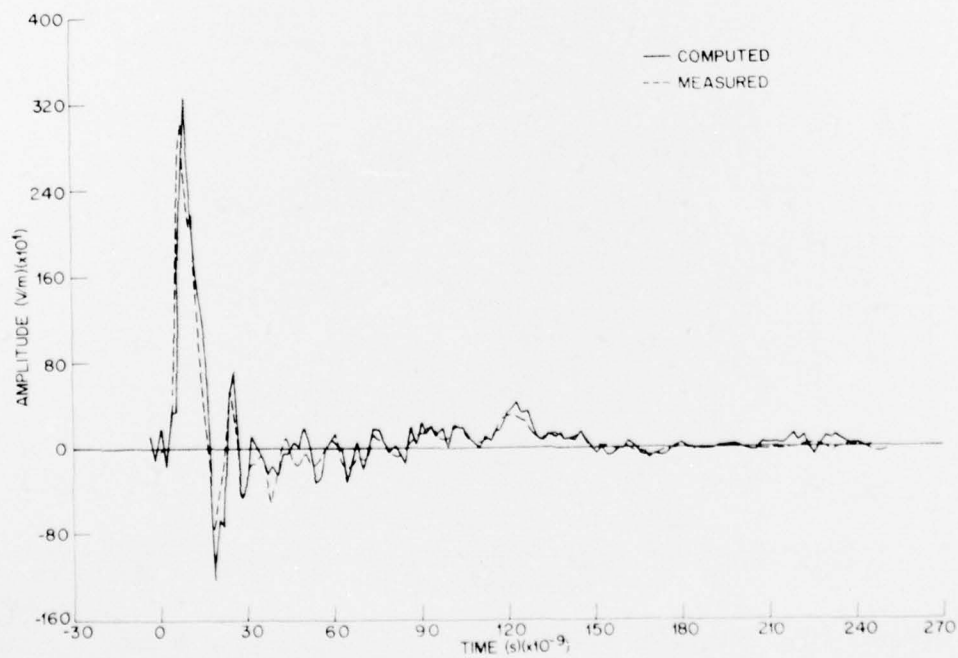


Figure 22. Time-amplitude traces for  $\sigma = 20$  mmho/m,  $\kappa = 25$ , height of sensor aboveground = 0.75 m.

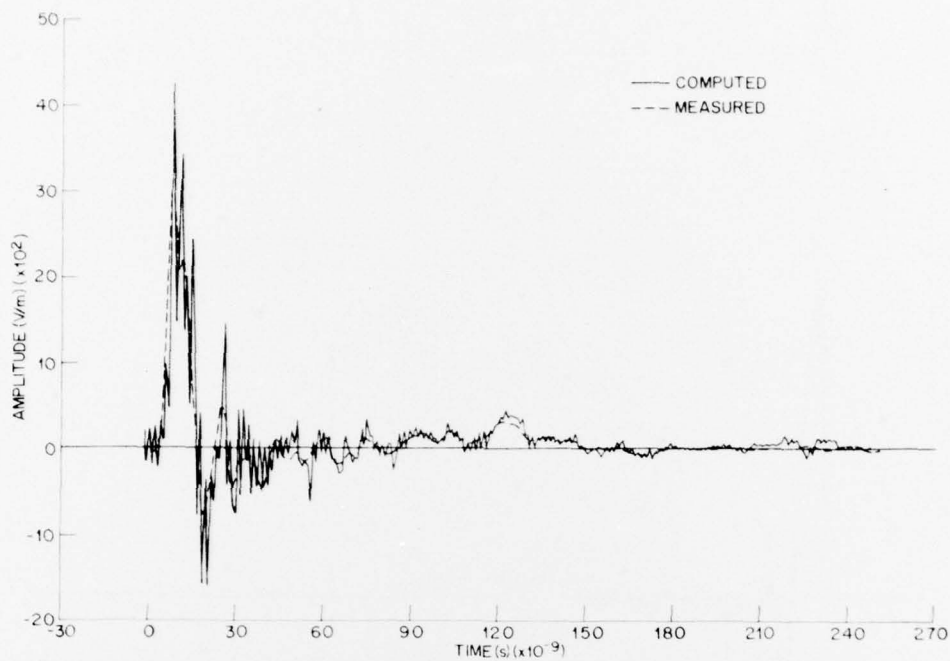


Figure 23. Time-amplitude traces for  $\sigma = 20$  mmho/m,  $\kappa = 25$ , showing spikes when filter is not used with 8192-point transform.

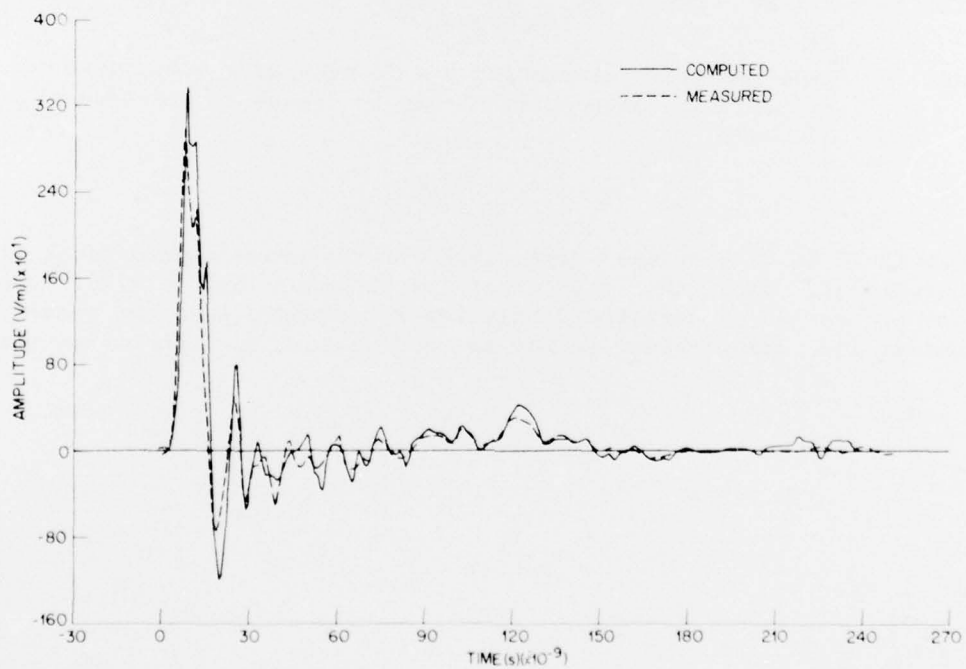


Figure 24. Time-amplitude traces for  $\sigma = 20$  mmho/m,  $\kappa = 25$ , without filter and with 4096-point transform.

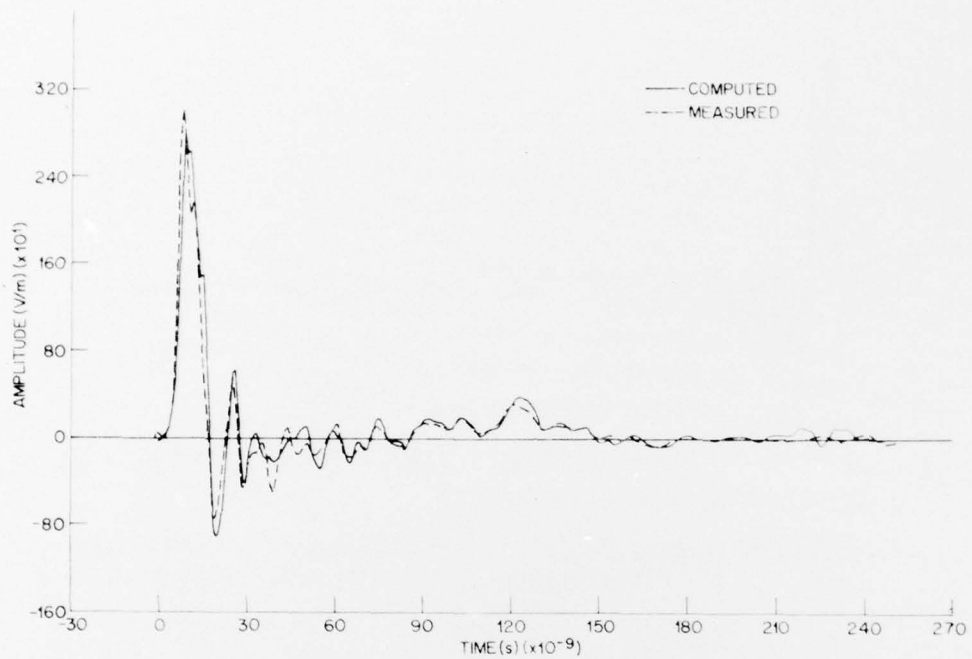


Figure 25. Time-amplitude traces for  $\sigma = 20$  mmho/m,  $\kappa = 25$ , with filter that corresponds to dip in frequency spectrum at 280 MHz.

Figures 26 to 28 show the same graph for the measurements taken at 5 m aboveground, with the values of  $\sigma = 30$  mmho/m and  $\kappa = 25$ . The resonance occurs at a correspondingly lower frequency, and the general agreement at low frequencies is not so good as that for the box on the ground.

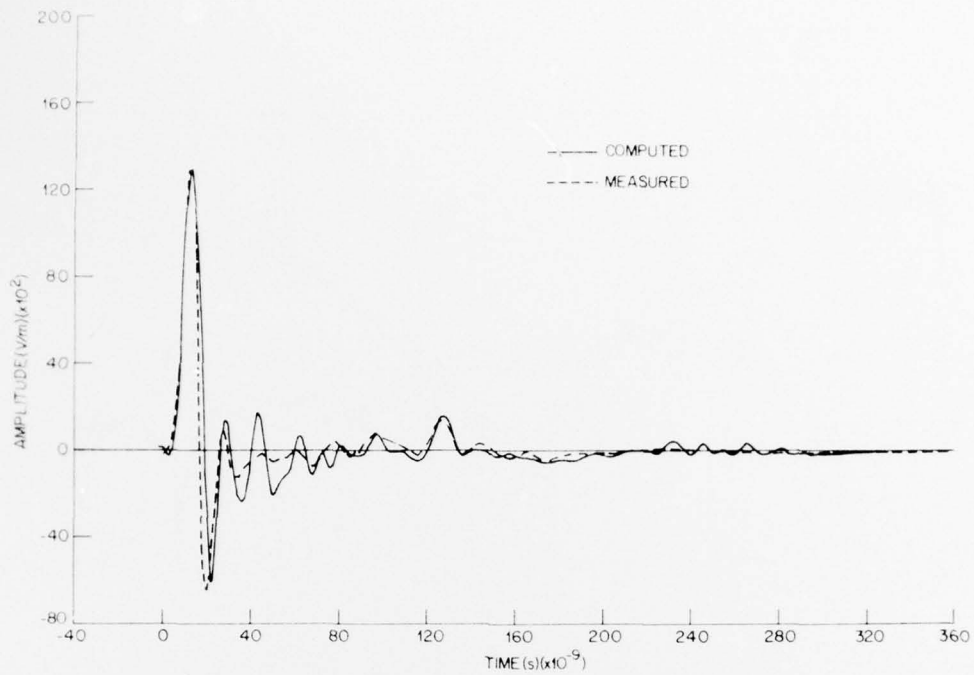


Figure 26. Time-amplitude traces for  $\sigma = 30$  mmho/m,  $\kappa = 25$ , when measurements are taken with sensors at 5 m aboveground.

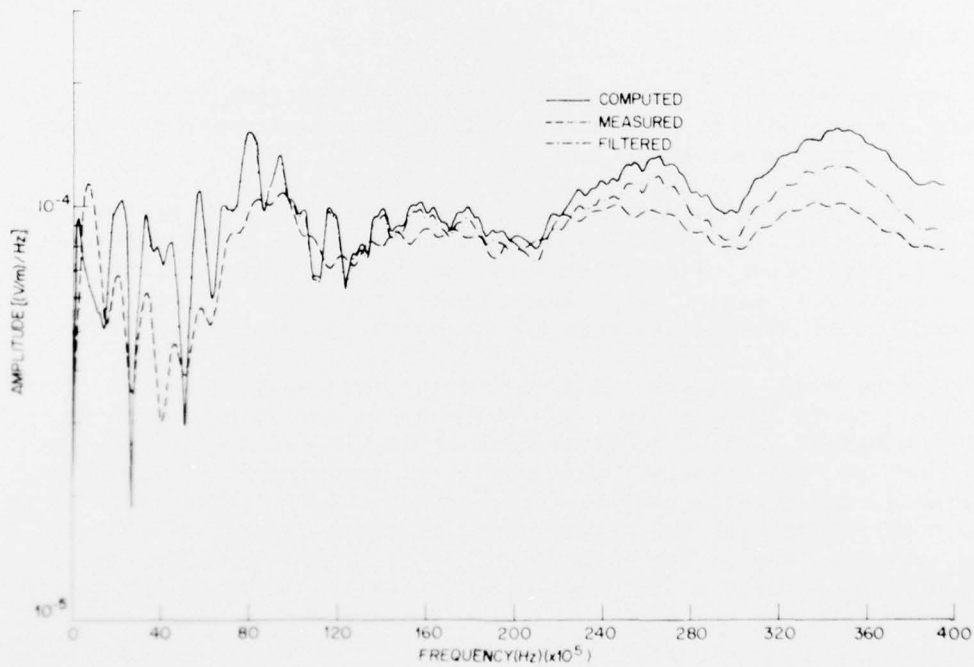


Figure 27. Low-frequency part of spectra for  $\sigma = 30$  mmho/m,  $\kappa = 25$ , and height of sensor aboveground = 5 m.

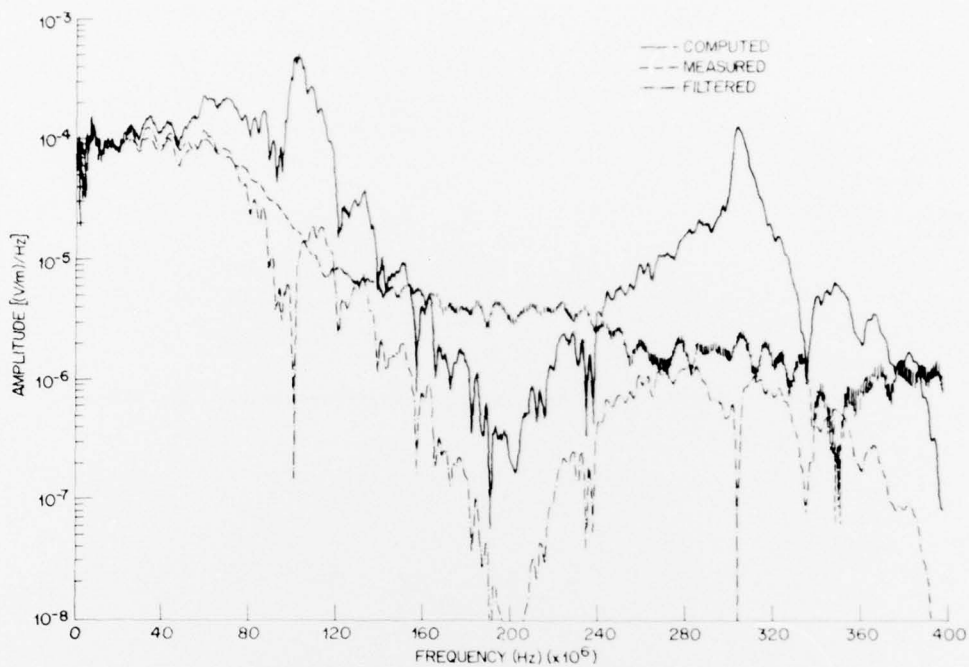


Figure 28. Full range of spectra for  $\sigma = 30 \text{ } \mu\text{ho/m}$ ,  $\kappa = 25$ , and height of sensor aboveground = 5 m.

## 6. CONCLUSIONS

A good agreement was obtained for the time-amplitude traces and the frequency spectra for the chosen best values of the parameters; however, considerable improvement is needed.

For both sets of measurements, on the ground and at 5 m, the peaks in the electric field could be matched quite well. The agreement was inferior in the following oscillations, to improve again at later times before the field essentially went back to zero. There was no significant qualitative difference in the matching for the two sets.

The frequency spectra showed good agreement also at lower frequencies, up to 200 MHz for the box on the ground and up to 50 MHz for the 5-m height. The wide divergence at higher frequencies was found to be due to the limited accuracy of numerical computations. Surprisingly, the general shapes of the curves agree quite well up to the limit of 550 MHz for the measurements on the ground, except that a dip in the spectrum of the electric field at about 280 MHz was not explained. The quality of the agreement is significantly better for the measurements taken on the ground than for those taken at 5 m.

A number of factors that limited the accuracy of these comparisons can be improved without much difficulty. The different sweep speeds for the oscilloscopes can be taken simultaneously when the instrumentation van is available. The quality of the photographs can be improved to show more detail in rapidly varying portions of the curve and less intensity for the slowly varying parts. The amplifications can be increased to show more detail at late times. Time delays can be used in the triggering circuit to obtain a picture with a high sweep speed at later times, to obtain more detail where necessary. Other numerical techniques can be tried to avoid some of the difficulties with false resonances.

Comparison of the measured and "computed" fields shows that the probes for the electric and magnetic fields agree quite well and are probably accurate in an absolute sense within the range of interest. Also, the calibration constants for the probes were used without modifications, so at least their ratio is correct. The assumptions that the pulse was a plane wave over a homogeneous plane infinite ground in the radiation zone for the field also did not introduce any large errors.

That the wave comes from different parts of the simulator and not from a point source at a large distance might explain some of the discrepancies observed after the first few peaks. Also, the effect of the metal box on the measured field was not taken into account.

In summary, this method provides useful information about the sensors and the ground constants, and it can be extended to fields off the center line and other combinations of components.

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