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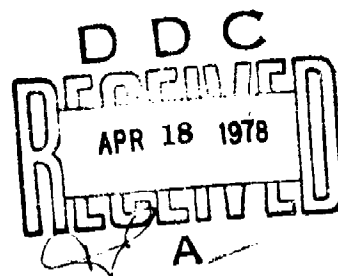
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TECHNICAL REPORT T-78-31

**AN INVESTIGATION OF THE AERODYNAMIC
STABILIZING EFFECTIVENESS OF SEVERAL
SPLIT FLARE AFTERBODY CONFIGURATIONS
IN THE PRESENCE OF AN UNDEREXPANDED
JET PLUME AT TRANSONIC MACH NUMBERS**

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9 January 1978



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20. ABSTRACT (Continue on reverse side if necessary and identify by block number) A study of the stabilizing effectiveness of several folding, split flare afterbodies in the presence of an underexpanded jet plume is presented. Mach number was varied from 0.7 to 1.4 and angle of attack from -4° to 6°. It is shown that the split flare afterbody can be an effective stabilizing device for tube launched missiles. deg		

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I. INTRODUCTION

A common requirement for tube launched missiles is that the aerodynamic stabilizing surfaces be approximately the same diameter as the missile body when in the tube. Several devices have been designed and tested which satisfy this requirement. Among these are: wraparound fins, folding fin configurations, and trailing ring-tails. All of these devices have disadvantages in certain flight conditions. Wraparound fins generally have large induced roll moments which vary with Mach number. Folding fins usually have a high aspect ratio and, therefore, lose much of their stabilizing effectiveness at high supersonic Mach numbers. The effectiveness of trailing ring-tails is greatly reduced by an underexpanded rocket plume; and therefore, they are not suitable for a high acceleration rocket with a motor burning after tube exit.

An alternate to the above stabilizing devices is a split flare which would be folded into a cylindrical shape while in the launch tube and expanded into a partial or split flare upon tube exit. Intuitively, this configuration would have two advantages over the other stabilizing devices suitable for a tube launched, high acceleration, supersonic rocket. Solid flares are more effective than fins as stabilizing devices at high supersonic Mach numbers; therefore, a split flare may also be more effective. Also, a solid flare is an effective device for inhibiting the onset of the adverse effects of an underexpanded rocket plume on rocket static stability; therefore, a split flare may also be effective as a thrust effects inhibitor.

Wind tunnel data were obtained for seven model configurations consisting of solid flares, split flares, and a cylindrical afterbody in the presence of a normal jet plume simulator.

Mach number was varied from 0.7 to 1.4, and the angle of attack range was -4° to 6° . The effect of roll angle on split flare effectiveness was investigated.

II. EXPERIMENTAL PROGRAM

A. Test Facility.

The AEDC-PWT Aerodynamic Wind Tunnel (1T) is a continuous flow, nonreturn facility, with Mach number capability from 0.2 to 1.5. The tunnel total pressure is essentially nonvariant at approximately 2850 psfa with ± 5 percent variation. The total temperature variation can be controlled from 80 to 120 degrees F. The test section is one foot square and 37.5 inches long with 6 percent porosity with all four perforated walls installed.

During the visualization phase the sidewalls were replaced with solid transparent walls.

A more detailed description of the IT facility may be found in the AEDC Test Facility Handbook (reference 1).

B. Model

The model was a sting mounted body of revolution having a diameter of 1.1 inches, Figure 1. It had a 3-caliber, tangent ogive nose and a total length of 10.4 calibers (11.44 in.). A cylindrical afterbody, two solid flare afterbodies, and four split flare afterbodies were tested. All afterbodies were the same length (1.725 in.) with two base diameters used for the solid and split flare configurations (1.705 in. and 2.071 in.). The split flare afterbodies had either 6 or 12 petals, and one of the 6-petal configurations had partially filled slots or skirts. The model assembly is shown in Figure 2, and the afterbodies tested are shown in Figure 3. The plume simulator was located 0.73 in. behind the model base. Effective plume shape was controlled by regulating nitrogen flow through 12 holes, 5/64 in. diameter, equally spaced around the circumference of the simulator. The simulator had a total sonic jet orifice area of 6% of the model cross-sectional area and was 0.815 in. in diameter. Detailed descriptions of the plume simulator and all model parts are contained in MIRADCOM drawings TDK-13900 series.

<u>Model</u>	<u>Nomenclature</u>
C	Cylindrical afterbody
FD1	Small diameter solid flare afterbody
FD2	Large diameter solid flare afterbody
F6D2	Large diameter, 6-petal, split flare afterbody
F6D2S	Large diameter, 6-petal, split flare afterbody, skirt
F12D1	Small diameter, 12-petal, split flare afterbody
F12D2	Large diameter, 12-petal, split flare afterbody

III. TEST PROCEDURE

All configurations were tested at Mach numbers of 0.7, 1.05, 1.25, and 1.4. Data for a single run were obtained by varying angle of attack from -4° to 6° while holding Mach number and plume simulator chamber pressure constant. The plume simulator nitrogen supply was adjusted to give the preselected chamber pressure that gave the desired radial thrust coefficient (CRT) for the tunnel test section conditions. Nominal test conditions are given in Table I, and the values for chamber pressure at specified values of CRT along with the expression for computation is contained in Table II. Zero roll position for the split flare configurations was with a petal flat up. Most of the runs were made at zero roll angle, but the effect of

roll on stability was investigated with the F6D2 configuration.

Shadowgraphs and oil flow photographs were taken at selected test points.

IV. DATA

All balance force coefficients are referenced to the cross-sectional area of the body, 0.95033 sq. in. The moment reference center is located at model station 5.83 inches aft of the nose (5.1 calibers forward of the body base). The moment coefficients are referenced to the body cross-sectional area times the body diameter (1.1 in.). The sign convention is the standard body axis system, positive nose up and right (climbing right turn). The two base pressures were averaged and ratioed to the free stream ambient pressure. Corrections to angle-of-attack were made for sting and balance deflections caused by aerodynamic loads and model weight.

The 2 σ data uncertainties, calculated from the balance calibration, are shown in Table III.

V. DISCUSSION AND RESULTS

There are two primary geometry differences between the split flares and solid flares, and the effects of these differences are qualitatively easy but quantitatively difficult to predict. First, the split flares have less surface area than solid flares of the same length and diameter. Intuitively, the effect of this difference would be reduced stabilizing effectiveness for the split flare, but not a reduction equal to the surface area ratio, because of petal-to-petal interference.

Second, the split flare probably would not inhibit the onset of afterbody flow separation due to an underexpanded jet plume as well as the geometrically similar solid flare because of the high base pressure feeding up through the splits in the afterbody. In this study the effects of base diameter, number of petals, and a partial fill in skirt on split flare stabilizing effectiveness as compared to solid flares are investigated.

The basic longitudinal stability coefficients for all configurations tested are shown in Figure 4. Typical variation of base pressure with CRT is shown in Figure 5. The data in this figure was taken at Mach number 1.25 and zero angle of attack. A comparison of the plateau base pressure of the afterbodies tested gives an indication of their effectiveness in inhibiting flow separation, with a high plateau pressure indicating a good flow separation inhibitor.

As expected, the large diameter, solid flare, FD2, has the highest base pressure plateau and the cylindrical afterbody yields the lowest base pressure plateau. The data shows that the 6-petal configuration is more effective than the 12-petal configuration and that the skirt added to the 6-petal configuration causes little change in base pressure plateau.

Normal force coefficient and pitching moment coefficient versus angle of attack slopes at small angles of attack are shown as a function of CRT in Figure 6. Clearly, the large diameter, solid flare, FD2, is the most effective stabilizing afterbody tested. The 6-petal, large diameter split flare and the addition of the fill-in-skirt to the large diameter split flare increases its stabilizing effectiveness very little. Total axial force coefficients for all configurations tested are shown in Figure 7.

SUMMARY AND CONCLUSIONS

This report is a study of the aerodynamic stabilizing effectiveness of several split flare afterbodies suitable for use in tube launched, free rocket design. The split flares were compared to solid flares with the same base diameter and length in a transonic wind tunnel test. Mach number was varied from 0.7 to 1.4 and angle of attack from -4° to 6° .

The following conclusions were drawn from this study:

- 1) The solid flares are more effective aerodynamic stabilizing devices than the split flares of the same base diameter and length.
- 2) The 6-petal split flare is a more effective aerodynamic stabilizing device than the 12-petal split flare.
- 3) The addition of partial fill-in-skirts to the 6-petal split flare design only caused a slight increase in aerodynamic stabilizing effectiveness.

REFERENCE

1. "Test Facilities Handbook" (Tenth Edition), Propulsion Wind Tunnel Facility, Vol. 4, Arnold Engineering Development Center, May 1974.

NOMENCLATURE

<u>SYMBOL</u>	<u>PLOT SYMBOL</u>	<u>DEFINITION</u>
C_A		total measured axial force coefficient
C_m	C_{LM}	pitching moment coefficient
C_N	C_N	normal force coefficient
C_{m_α}	C_{M_ALPHA}	pitching moment slope at zero angle of attack
C_{N_α}	C_{N_ALPHA}	normal force slope at zero angle of attack
CRT	CRT	radial thrust coefficient
FA		axial force
FN		normal force
FY		side force
l_{ref}	LREF	reference length, in.
M_x		rolling moment
M_m		pitching moment
M_n		yawing moment
M_∞	MACH	tunnel test section Mach number
P_b/P_∞		base to tunnel static pressure ratio
P_t		tunnel stagnation pressure, psfa

NOMENCLATURE (Continued)

<u>SYMBOL</u>	<u>PLOT SYMBOL</u>	<u>DEFINITION</u>
q_{∞}		tunnel test section dynamic pressure, psf
R_N		Reynolds number, per foot
S_{ref}	SREF	reference area used to reduce data to coefficient form, in.
x_{mrp}	XMRP	moment reference point on X axis
α	ALPHA	angle of attack, degrees
ϕ	PHI	angle of roll, degrees

TABLE 1. NOMINAL TEST CONDITIONS.

M_∞	P_t (psfa)	q_∞ (psf)	$R_N \times 10^{-6}$ (per ft.)
0.7	2850	705	4.426
1.05	↓	1090	5.237
1.25		1204	4.999
1.4		1229	4.916

TABLE 2. NOMINAL PLUME SIMULATOR CHAMBER PRESSURE.

MACH	C/T											
	2.5	4.0	5.0	6.1	7.0	9.1	10.2	11.2	14.2	16.6	18.6	25.5
0.7				395			661				1190	1630
1.05	255			615				1120		1630		
1.25	280		557			1005			1580			
1.40	280	460			800			1265				

$$CRT = A_{nj} (0.5283 \times P_c (1.4 \times M_j^2 + 1) - P_s/144) / (A_{ref} \times q/144)$$

where

A_{nj} = Total exit area, 12 orifices

$A_{nj}/A_{ref} = 0.06$

M_j = Sonic jet ($M=1.0$)

q = Free stream dynamic pressure, psf

P_c = Chamber pressure in simulator, psi

P_s = Tunnel static pressure, psf

P_t = 2850 psf -- tunnel total pressure

TABLE 3. DATA UNCERTAINTY.

2σ uncertainties calculated from the balance calibration

	Type of Loading			
	FN	FY	FA	M _L
ΔFN	0.06	0.02	0.06	0.12
ΔFY	0.02	0.03	0.08	0.04
ΔFA	0.03	0.10	0.06	0.05
ΔM_L	0.02	0.02	0.01	0.04
ΔM_m	0.04	0.05	0.08	0.15
ΔM_n	0.04	0.08	0.09	0.09

TABLE 4. DATA SET SUMMARY.

TEST AEDC TM-359			TEST RUN NUMBERS																
Config	Mach No.	α	ϕ	0	2.5	4.0	5.0	6.1	7.0	9.1	10.2	11.2	14.2	16.6	18.6	25.5			
C	0.70	A	0	3				10			9				8	7			
C	1.05	A	0	11	12			18				16		25					
C	1.25	A	0	22	21		20			19			26						
C	1.40	A	0	27	31	30			29			28							
FD1	0.70	A	0	55				59			58				57	56			
FD1	1.05	A	0	53	60			50				49		48					
FD1	1.25	A	0	42	41		40			39			45						
FD1	1.40	A	0	34	38	37			36			35							
FD2	0.70	A	0	64				70			71				72	63			
FD2	1.05	A	0	65	69			68				67		66					
FD2	1.25	A	0	75	79		78			77			76						
FD2	1.40	A	0	80	84	83			82			81							
F6D2S	0.70	A	0	104				108			107				106	105			
F6D2S	1.05	A	0	103	113			112				111		101					
F6D2S	1.25	A	0	97	96		95			94			93						
F6D2S	1.40	A	0	92	91	90			88			87							
F12D1	0.70	A	0	117				125			124				123	116			
F12D1	1.05	A	0	118	122			121				120		119					
F12D1	1.25	A	0	133	132		131			126			129						
F12D1	1.40	A	0	134	138	137			136			135							
F12D2	0.70	A	0	160				164			163				162	151			
F12D2	1.05	A	0	155	152			153				154		159					
F12D2	1.25	A	0	147	151		156			149			148						
F12D2	1.40	A	0	145	144	143			142			141							
F6D2	0.70	A	0	167				171			170				169	168			
F6D2	1.05	A	0	175	174			173				172		173					
F6D2	1.25	A	0	184	183		182			181			180						
F6D2	1.40	A	0	185	185	188			187			186							
F6D2	0.70	A	30	206				210			209				208	207			
F6D2	1.05	A	30	205	213			212				211		204					
F6D2	1.25	A	30	197	198		199			200			203						
F6D2	1.40	A	30	192	196	195			194			193							
F6D2	0.70	A	180	215				218											
F6D2	1.05	A	180	219				220											

A = -4, -2, -1, -0.25, 0, 0.25, 0.5, 1.0, 2.0, 4.0, & 6.0

A = -4, -2, -1, -0.25, 0, 0.25, 0.5, 1.0, 2.0, 4.0, & 6.0

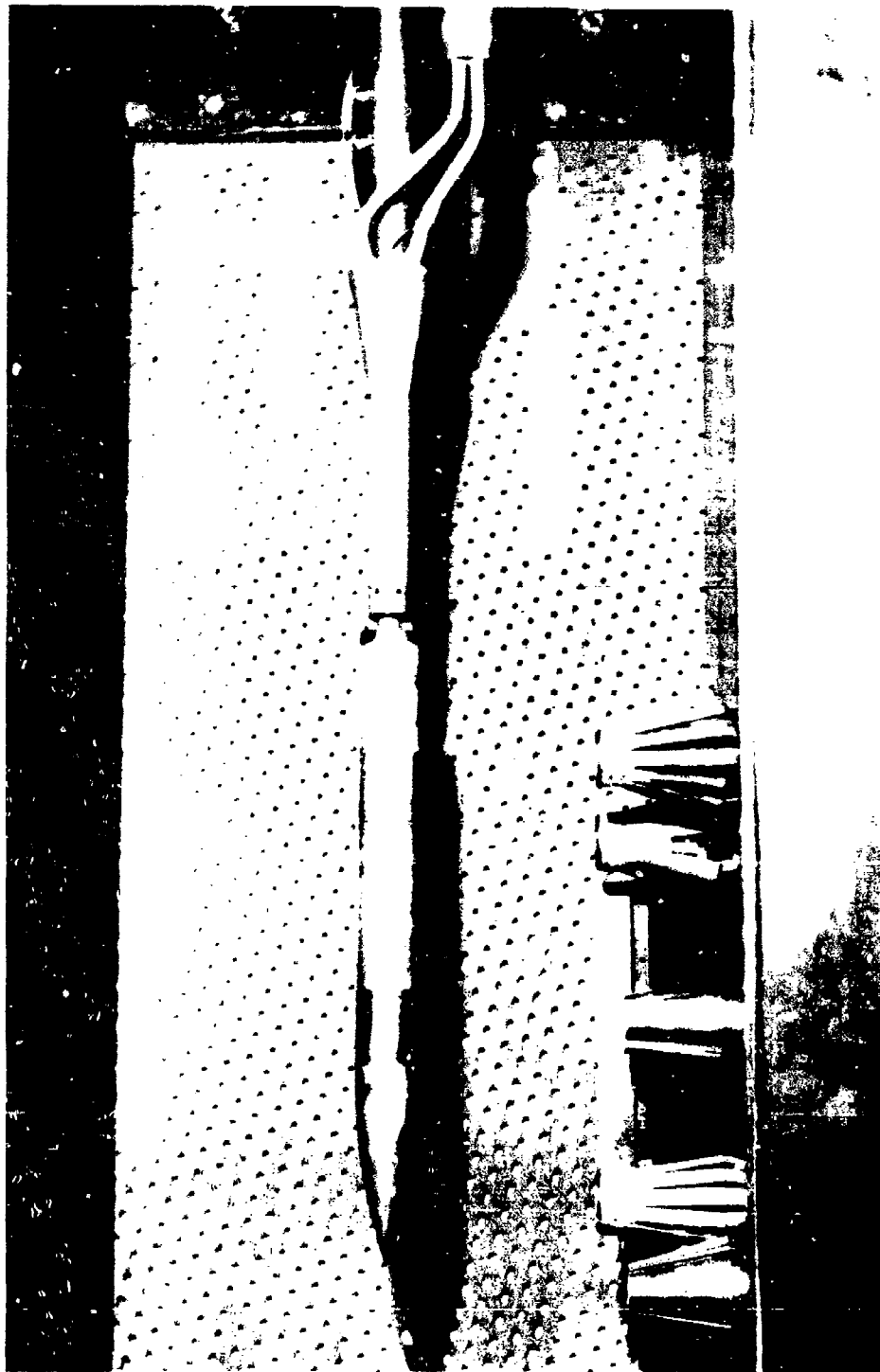


Figure 1. Model installation photograph.

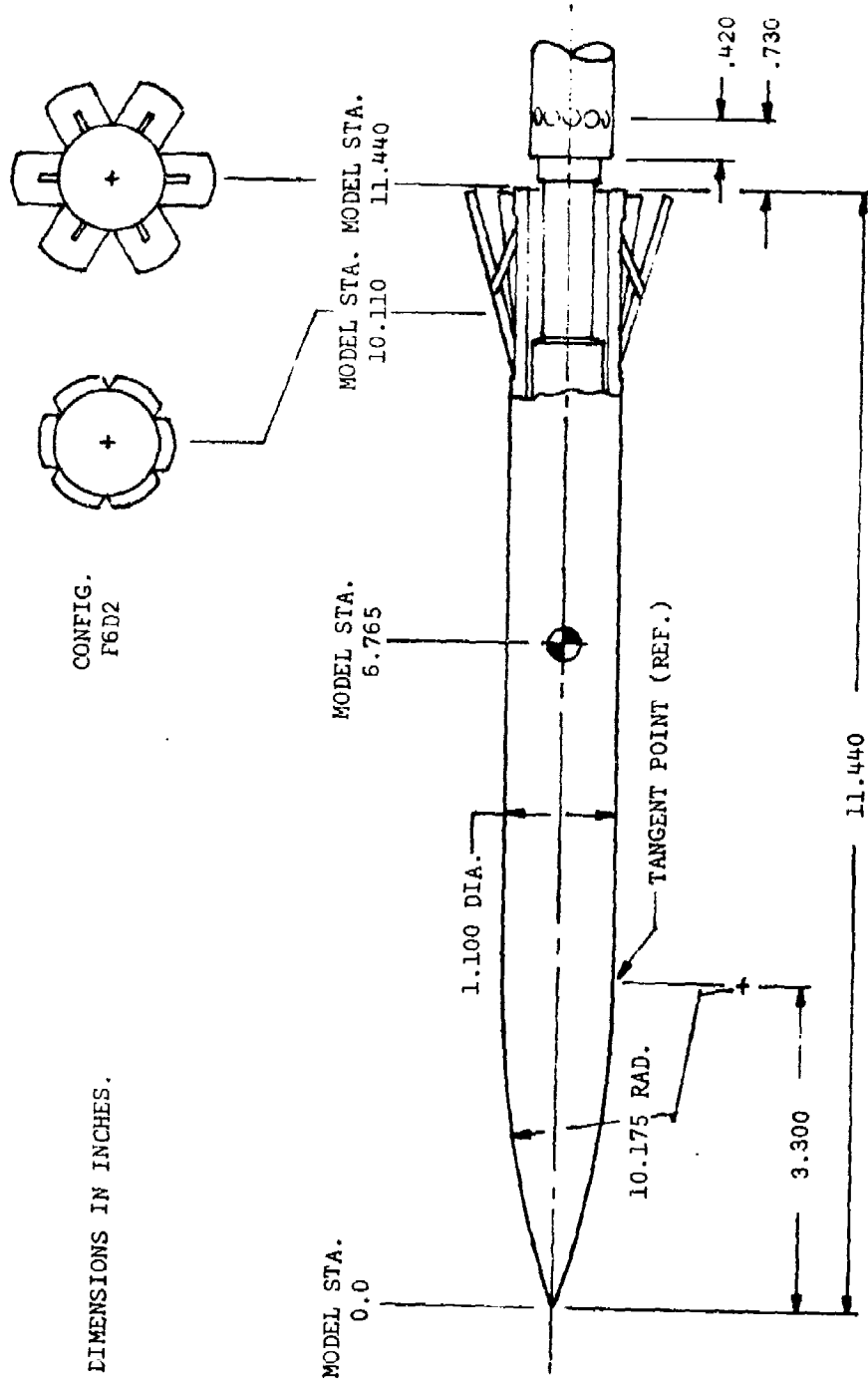


Figure 2. Model assembly.

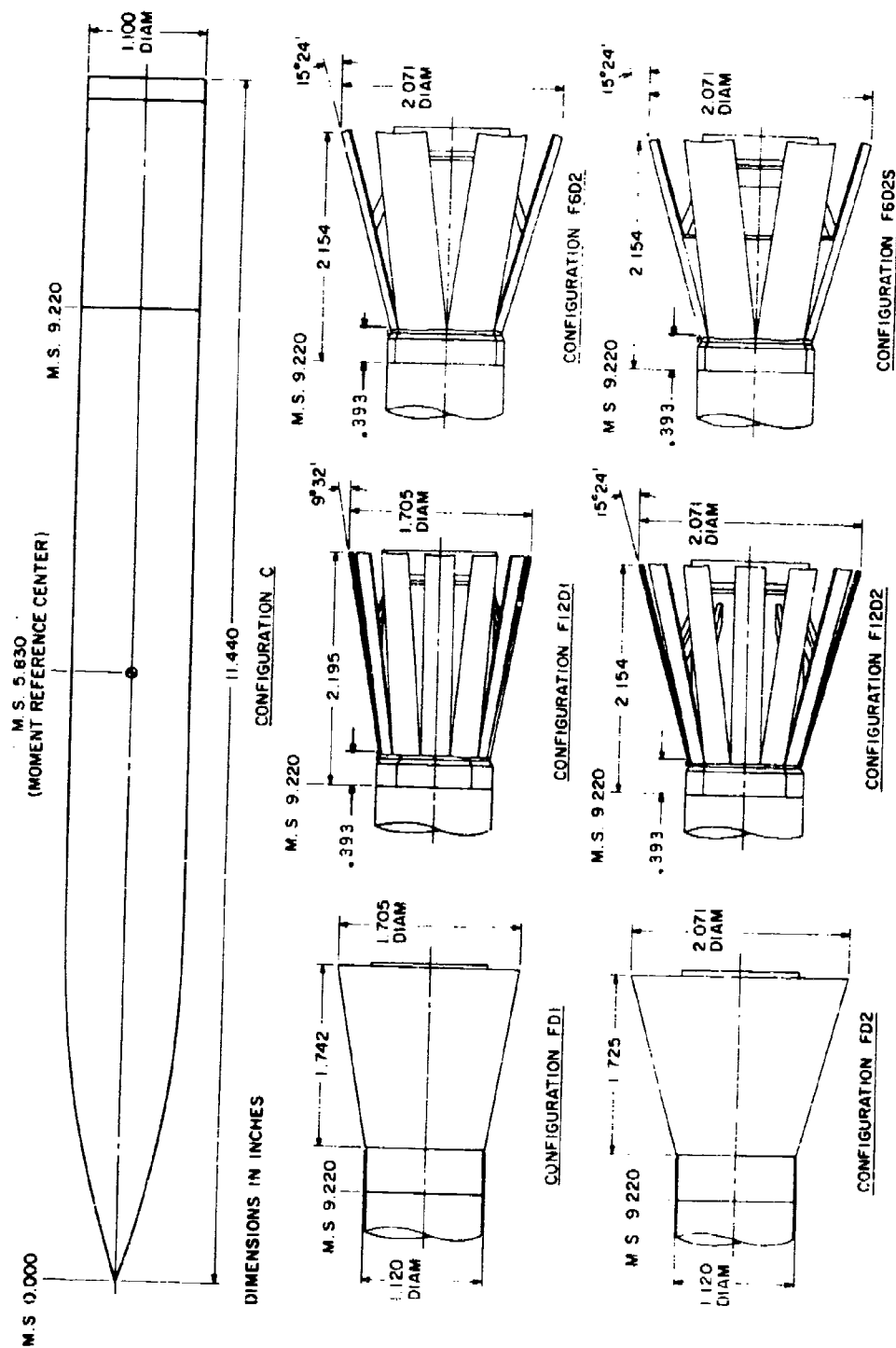


Figure 3. Model details and identification.

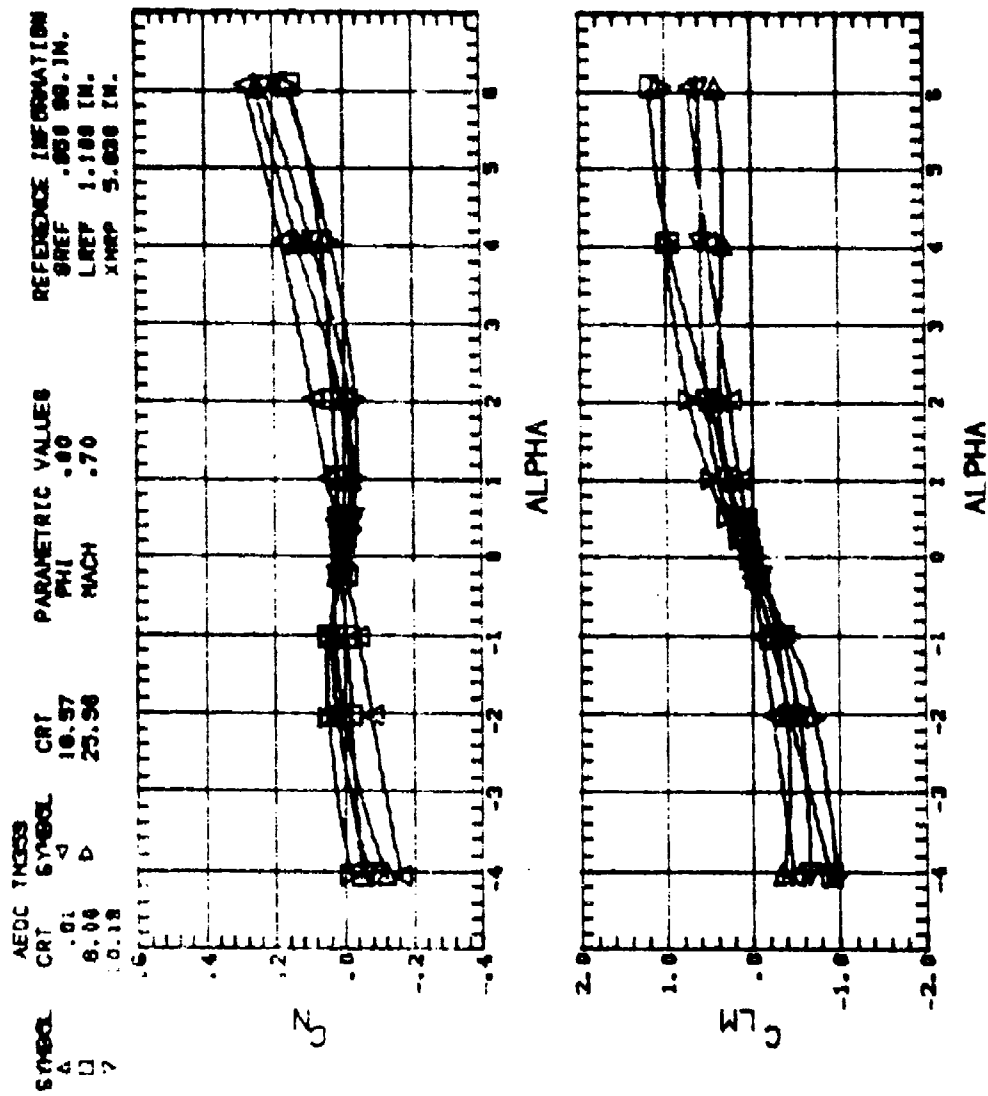


Figure 4. Thrust effects on stability coefficients. C

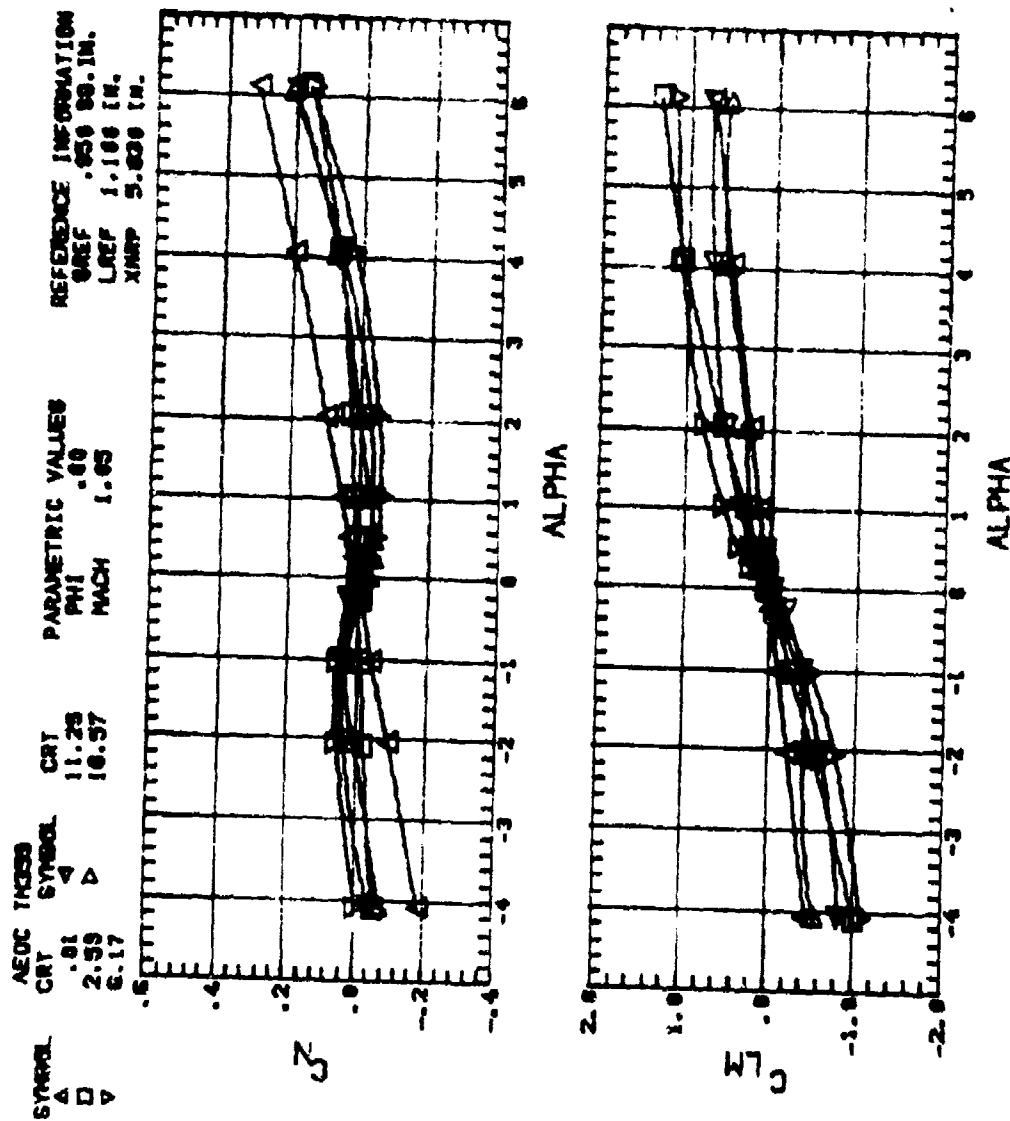


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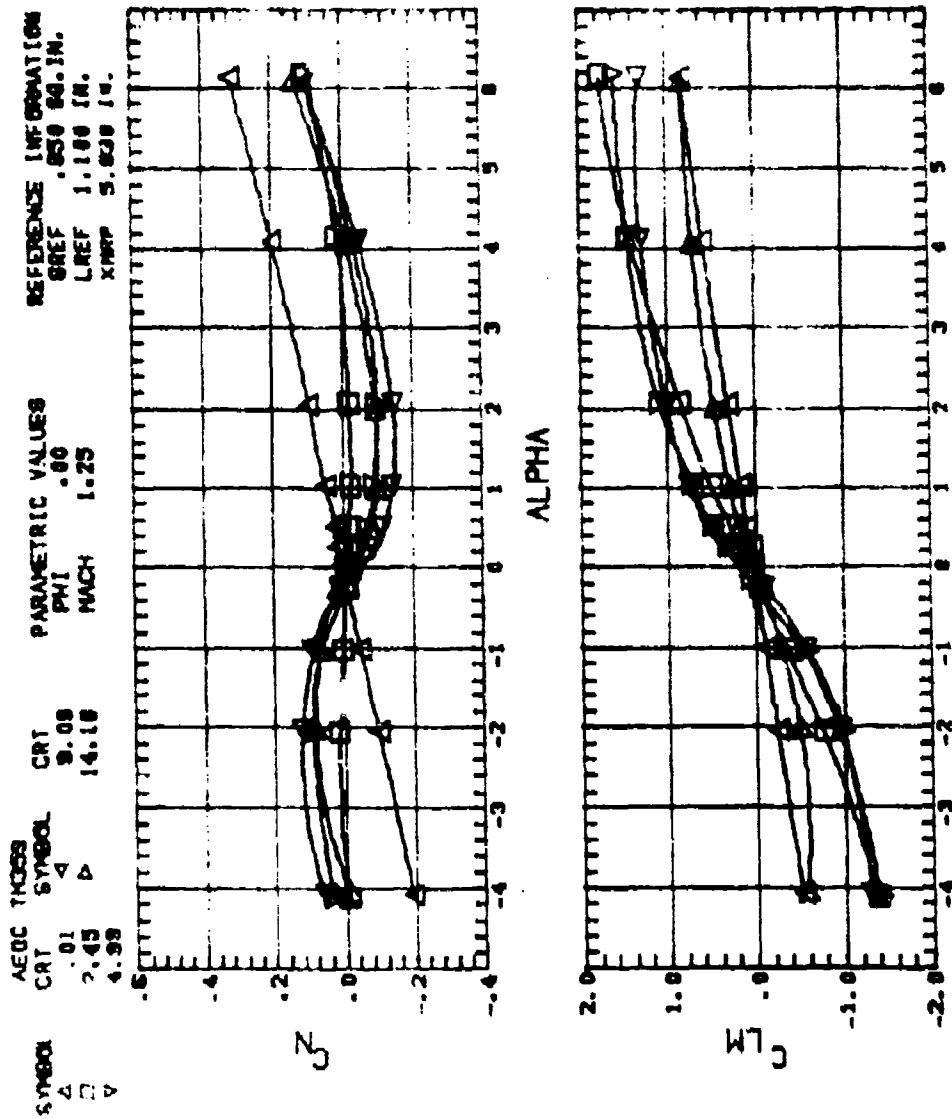


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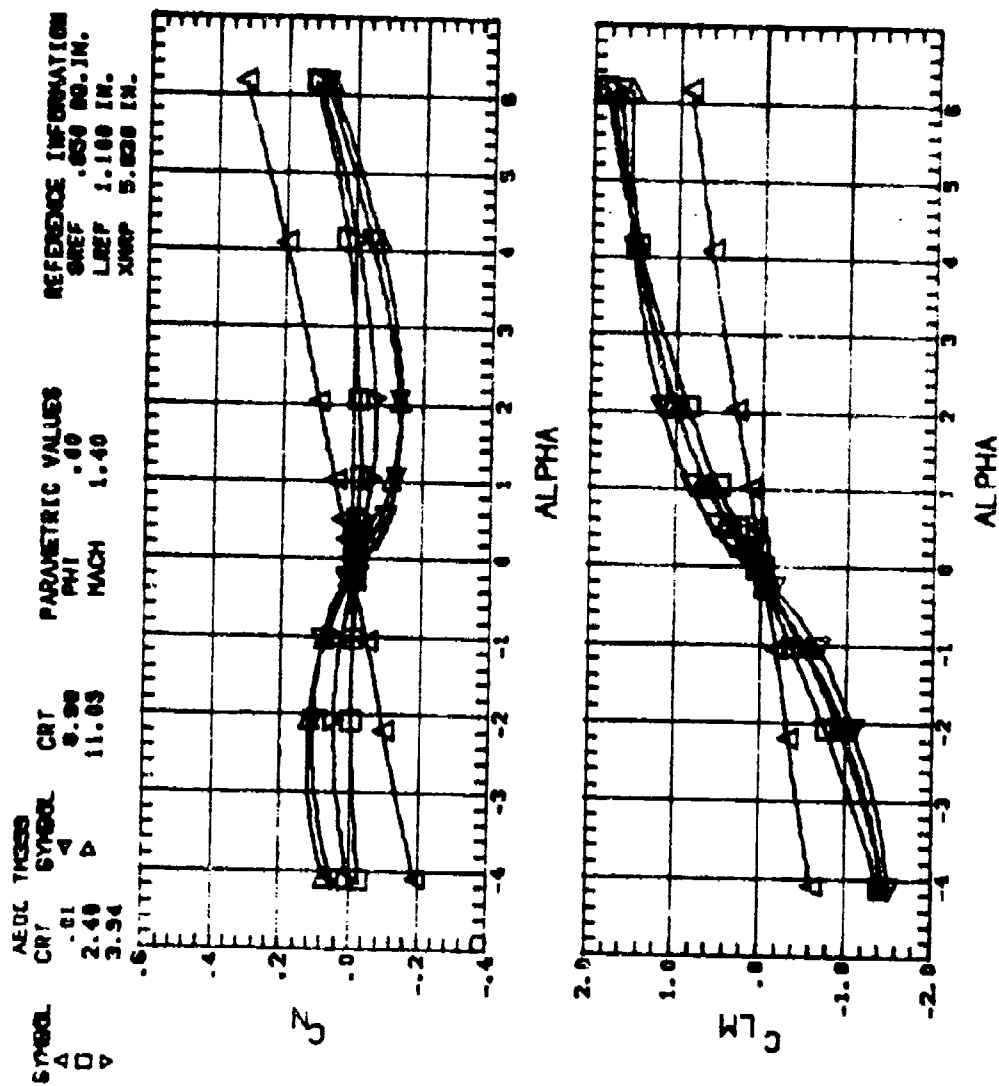


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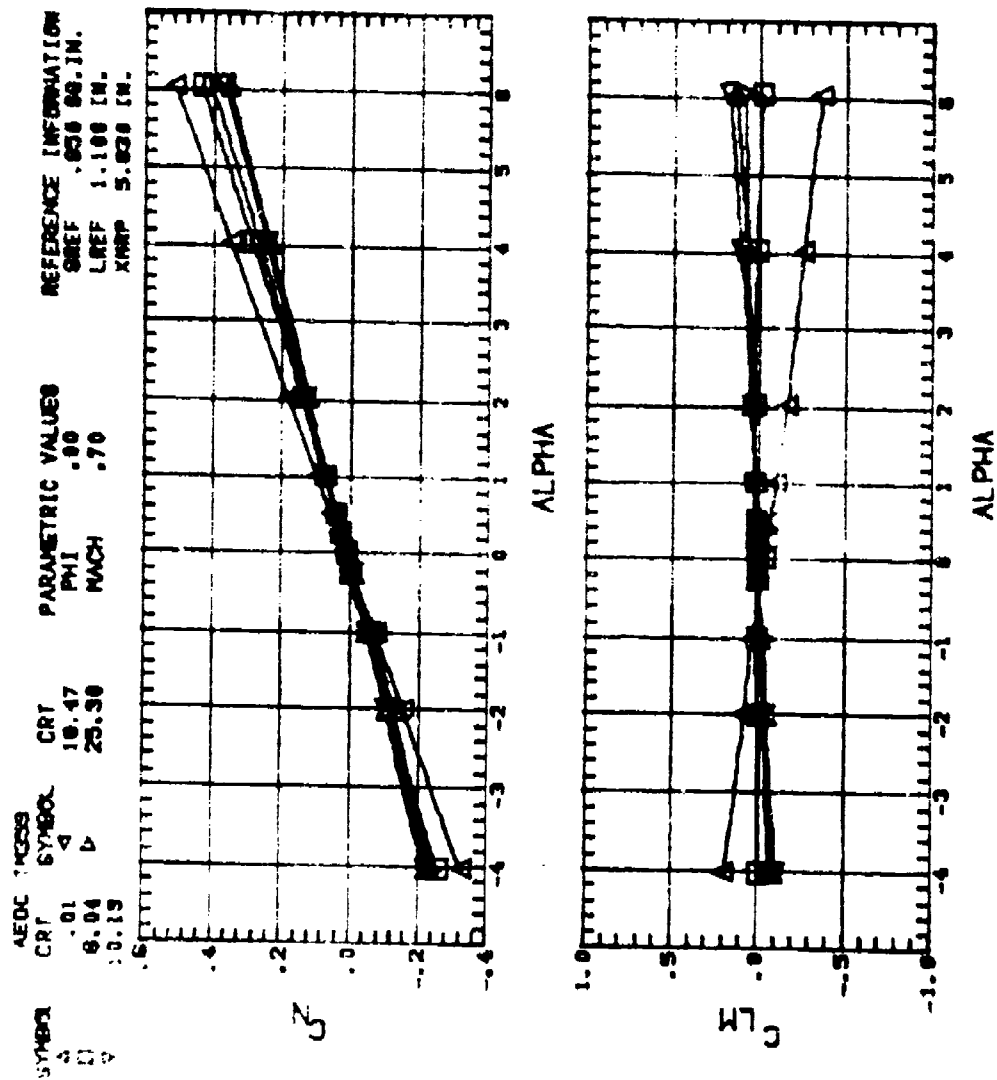


Figure 4. Continued. FD1

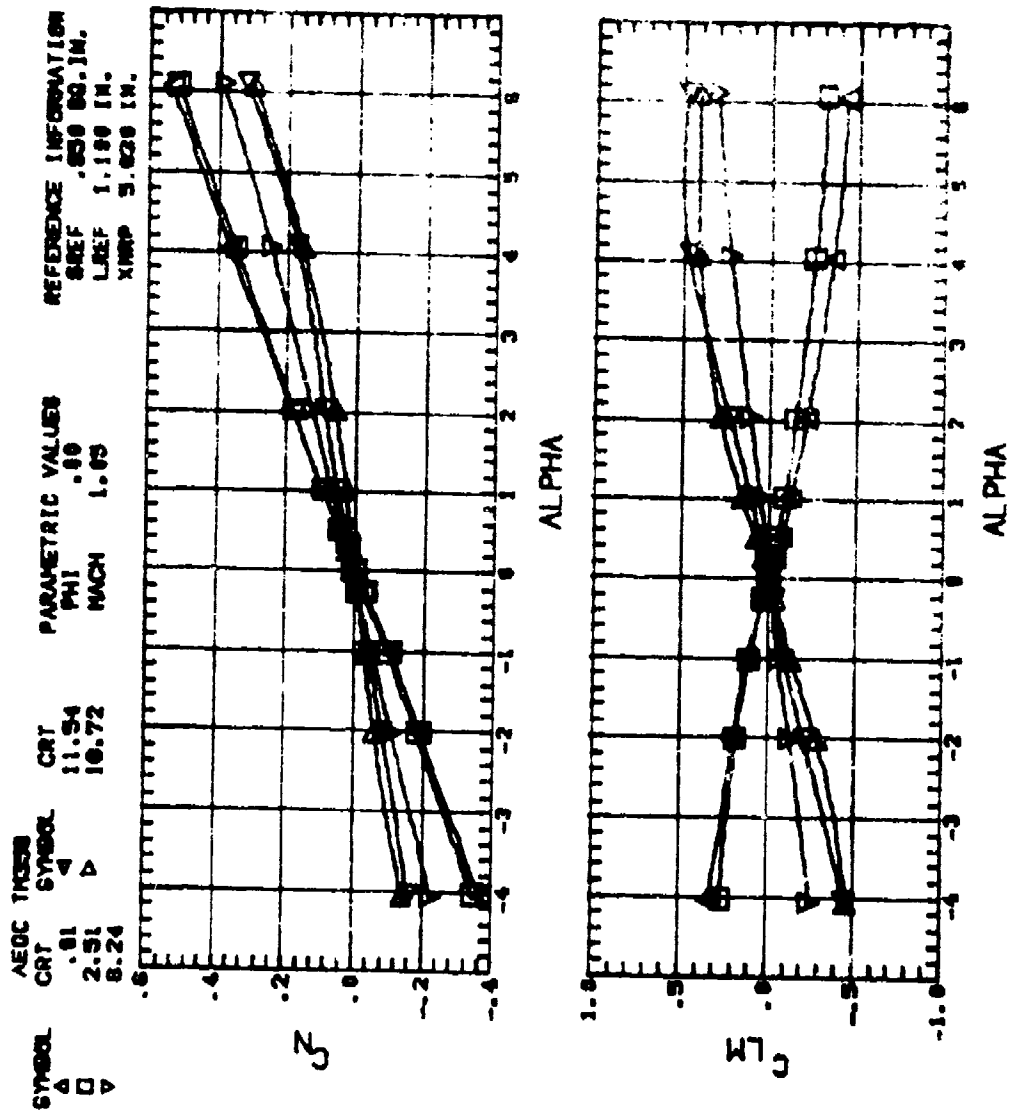


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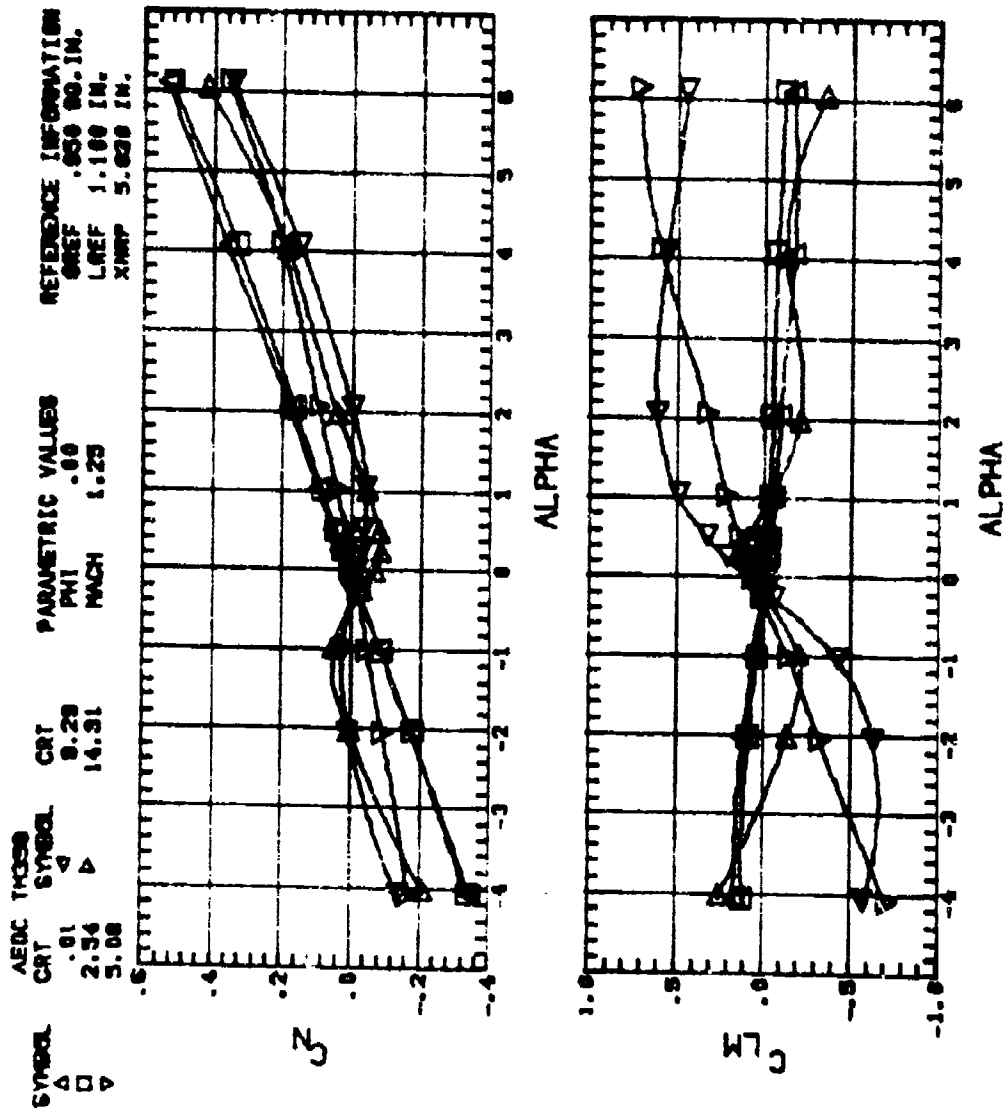


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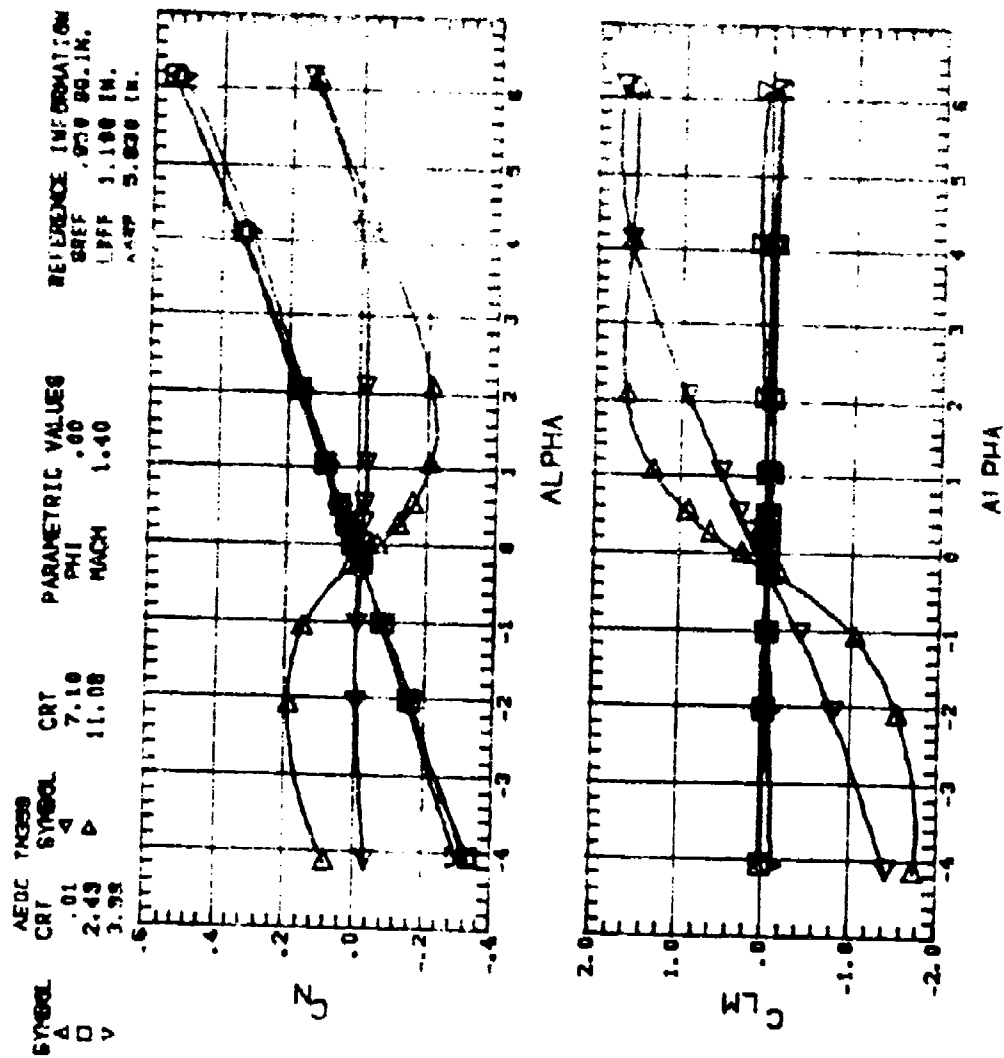


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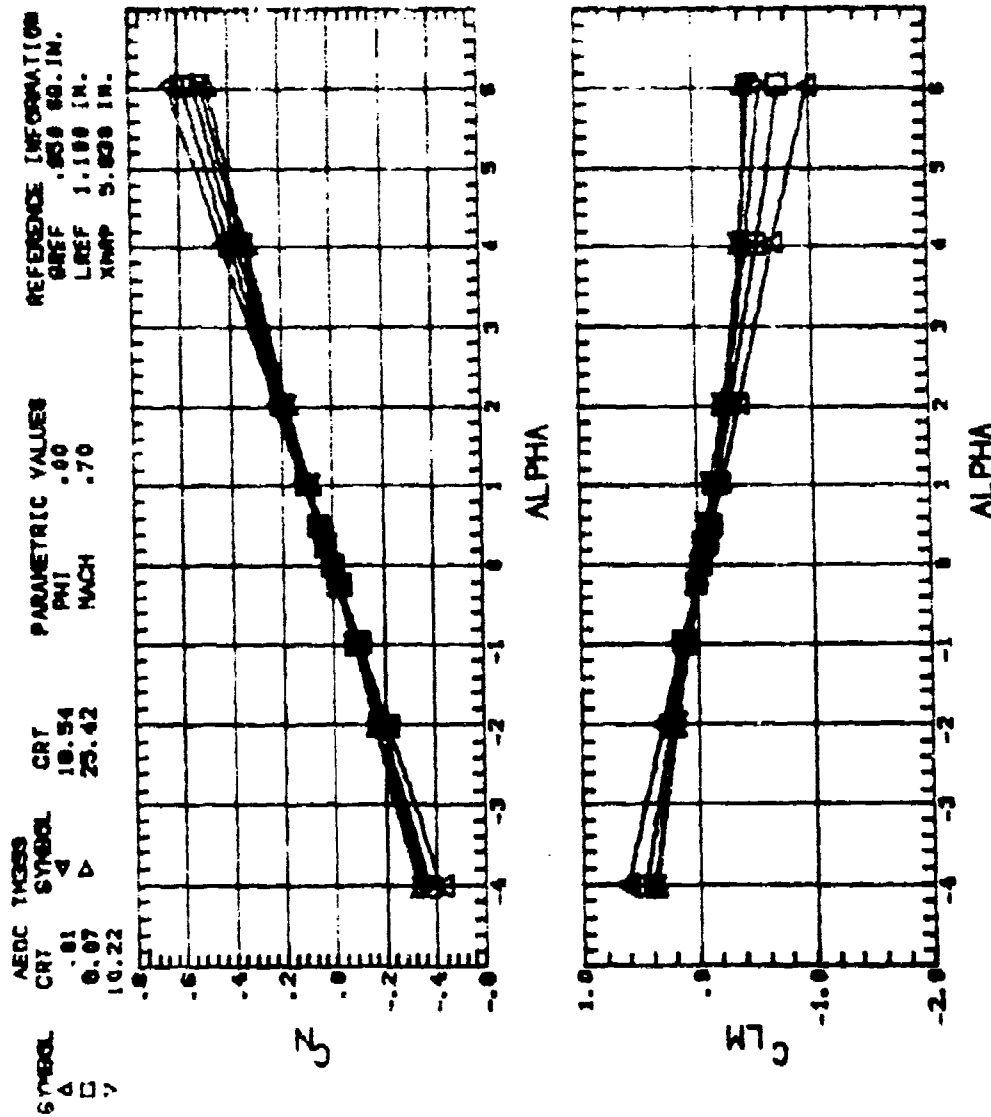


Figure 4. Continued. FD2

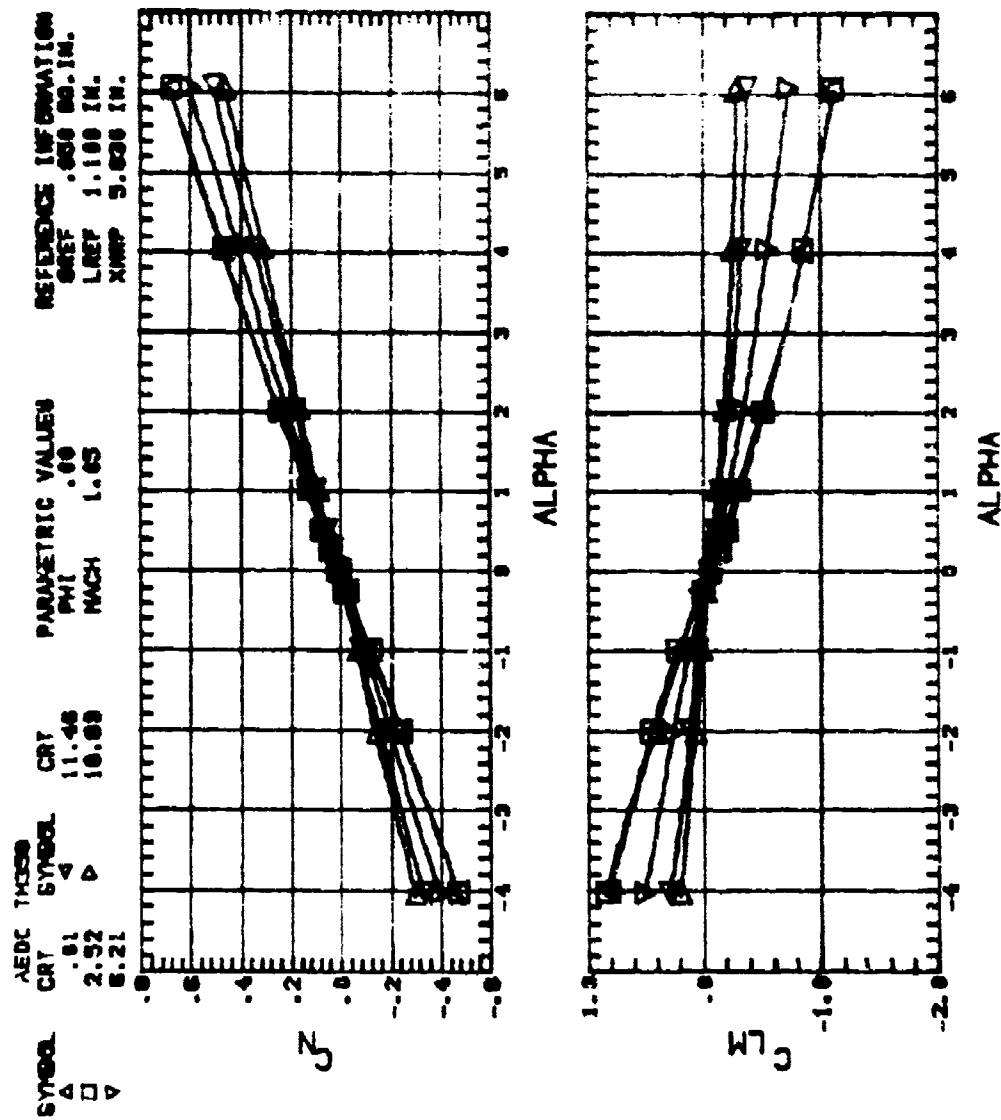


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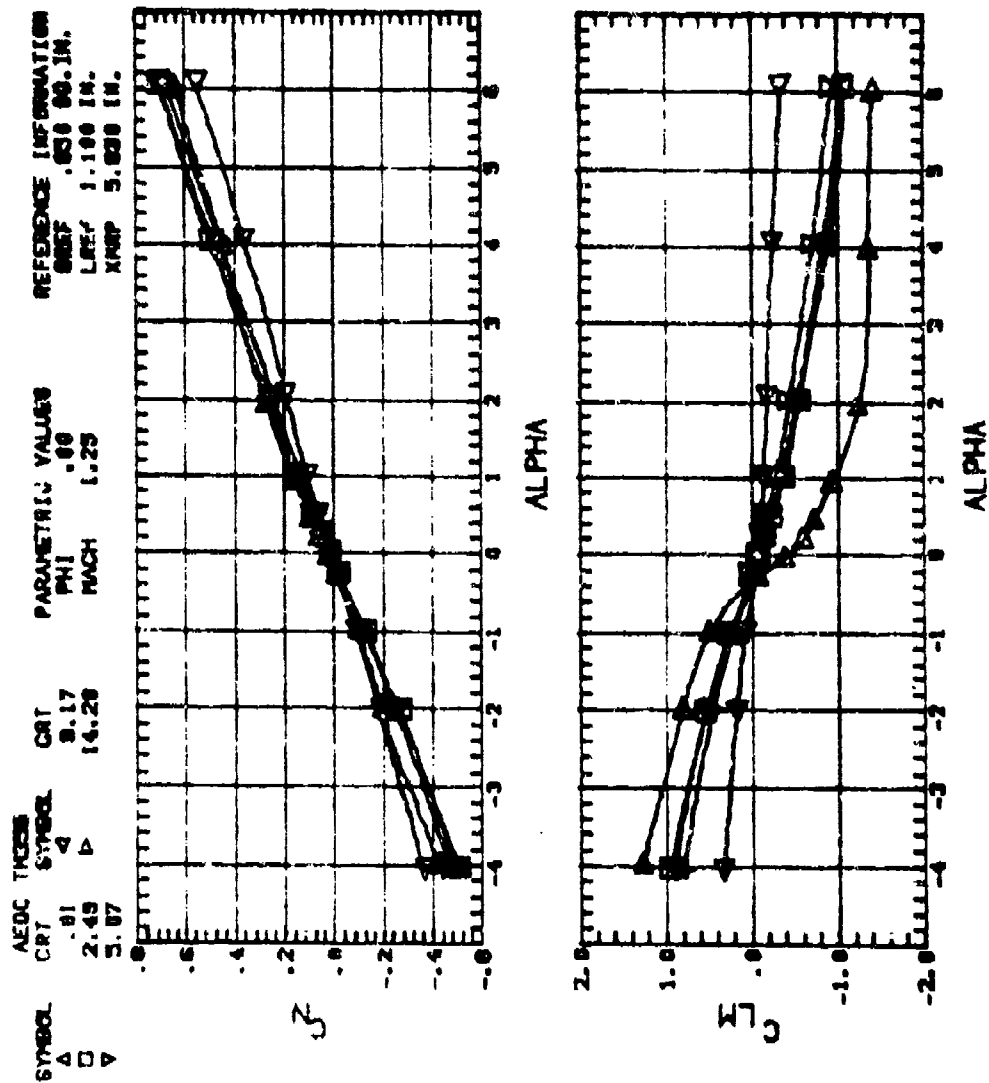


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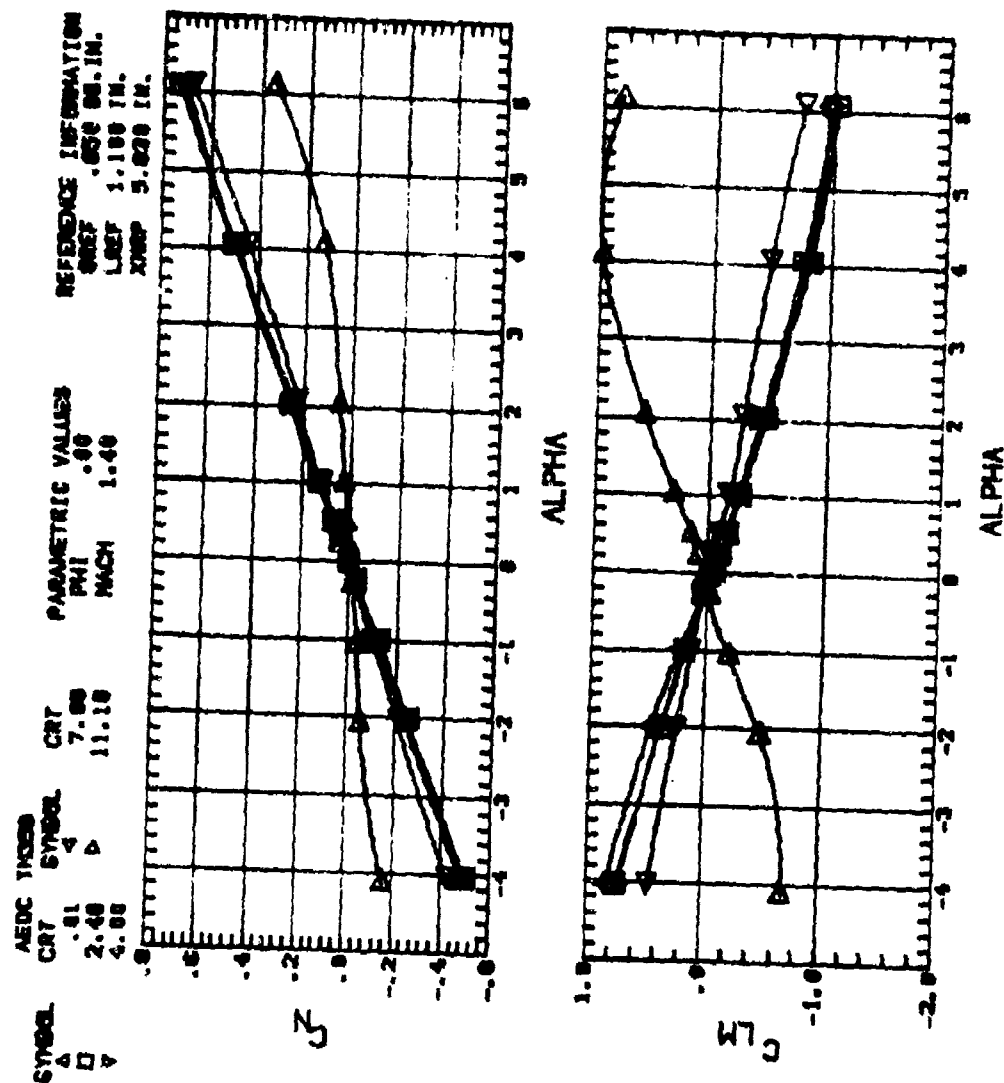


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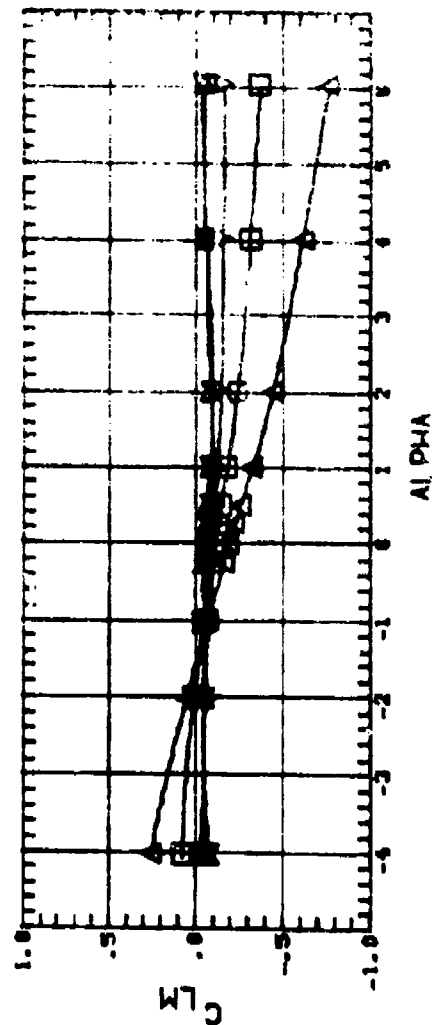
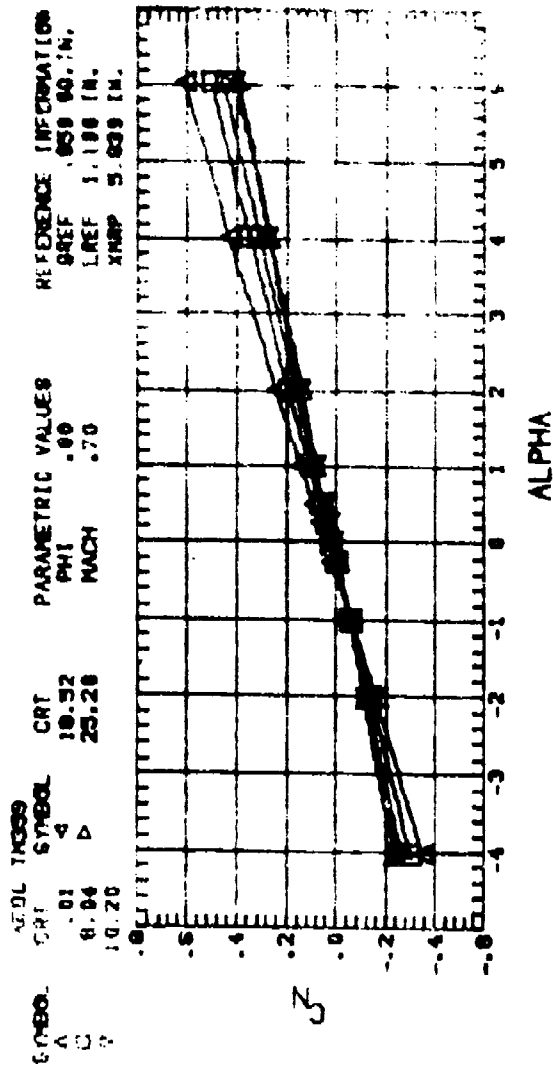


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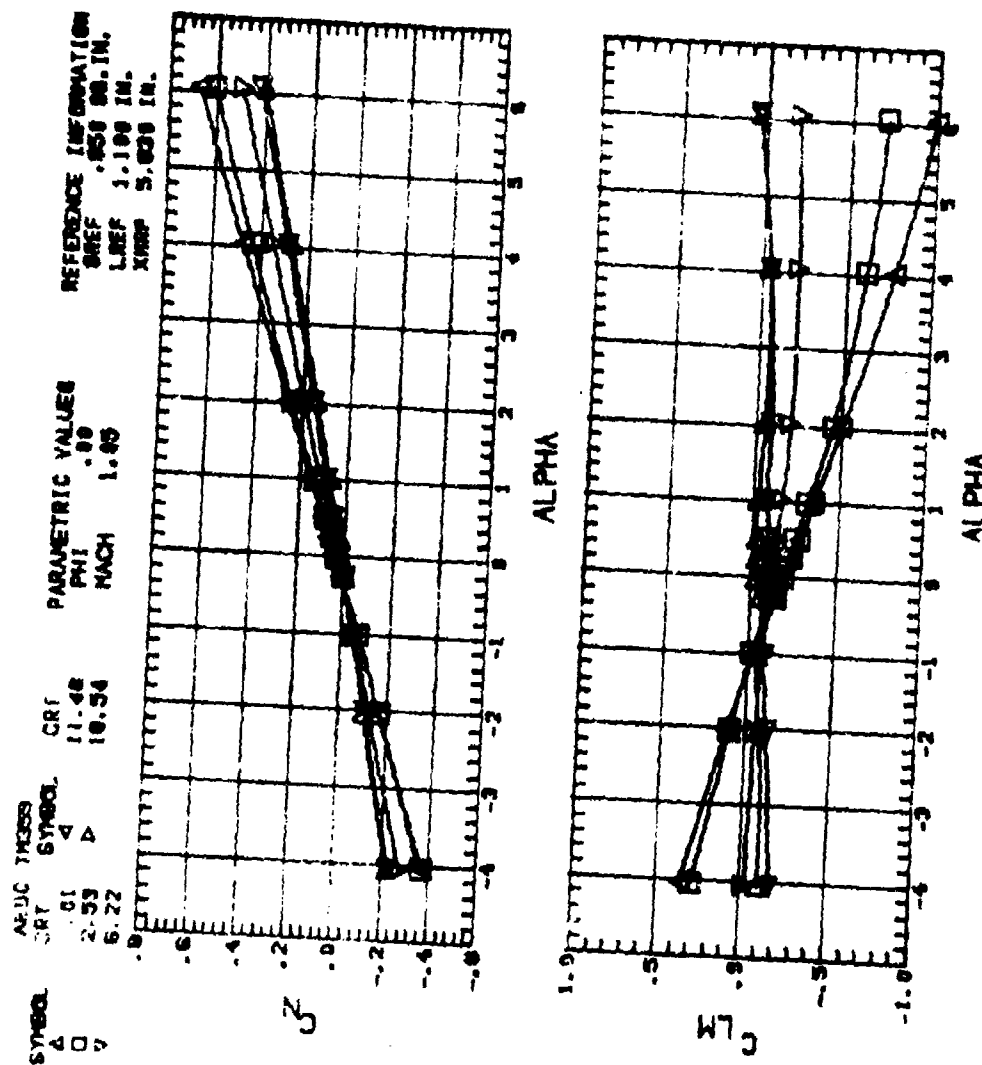


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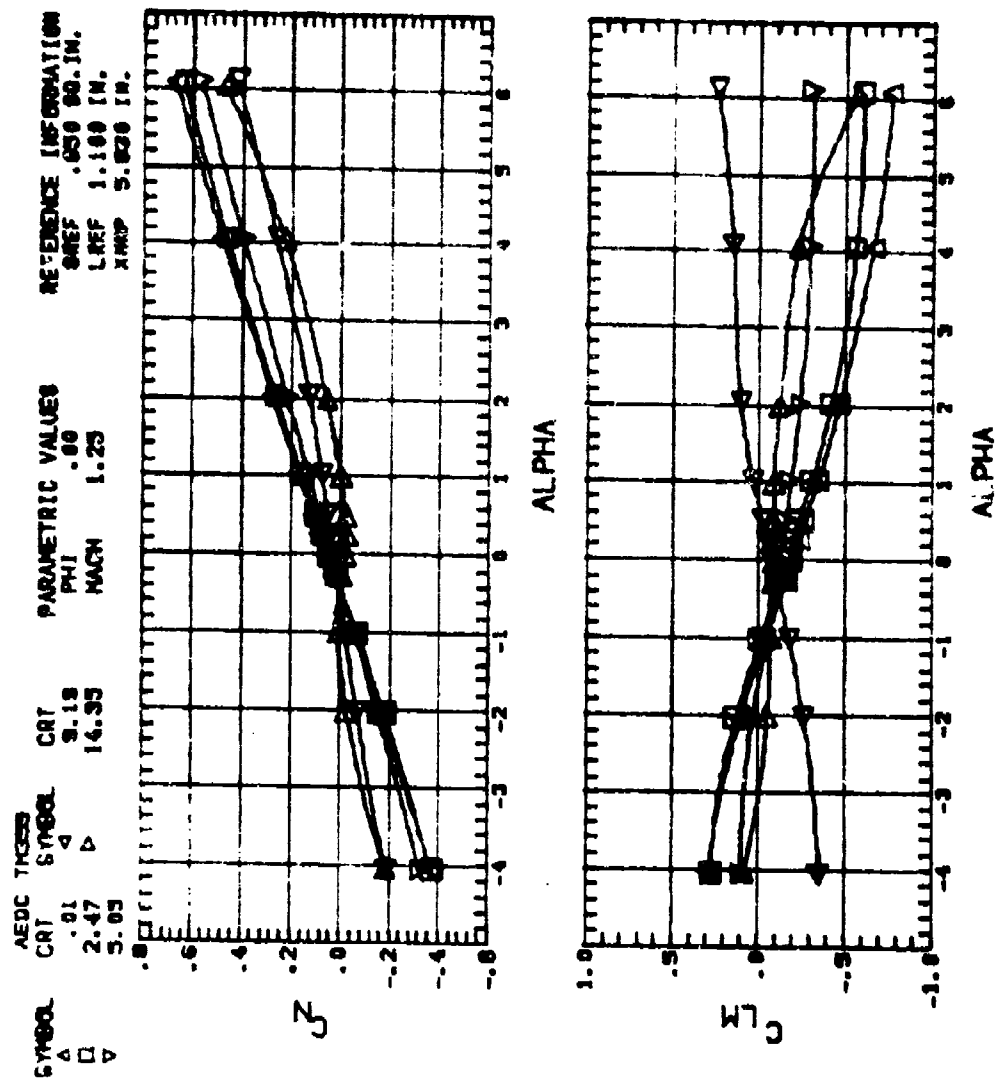


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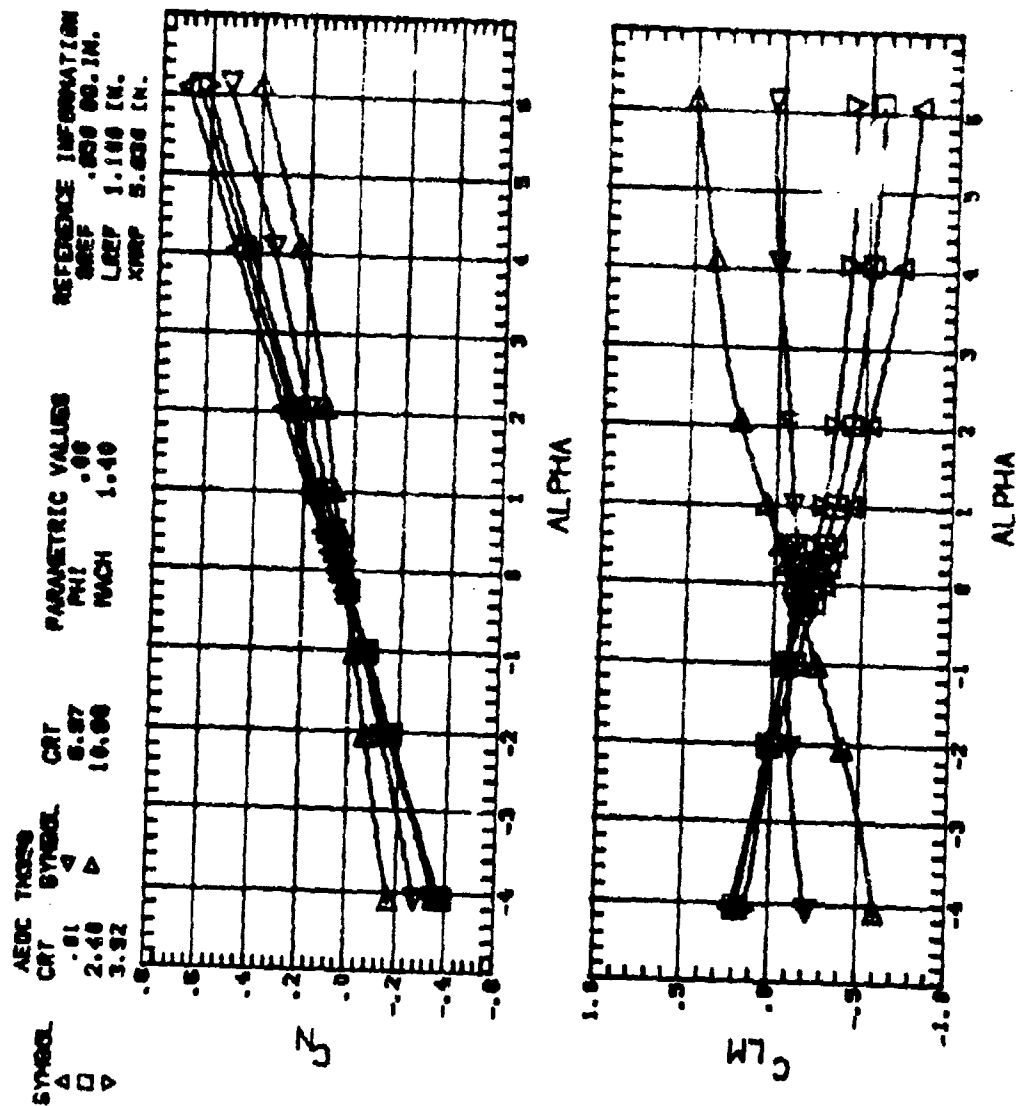


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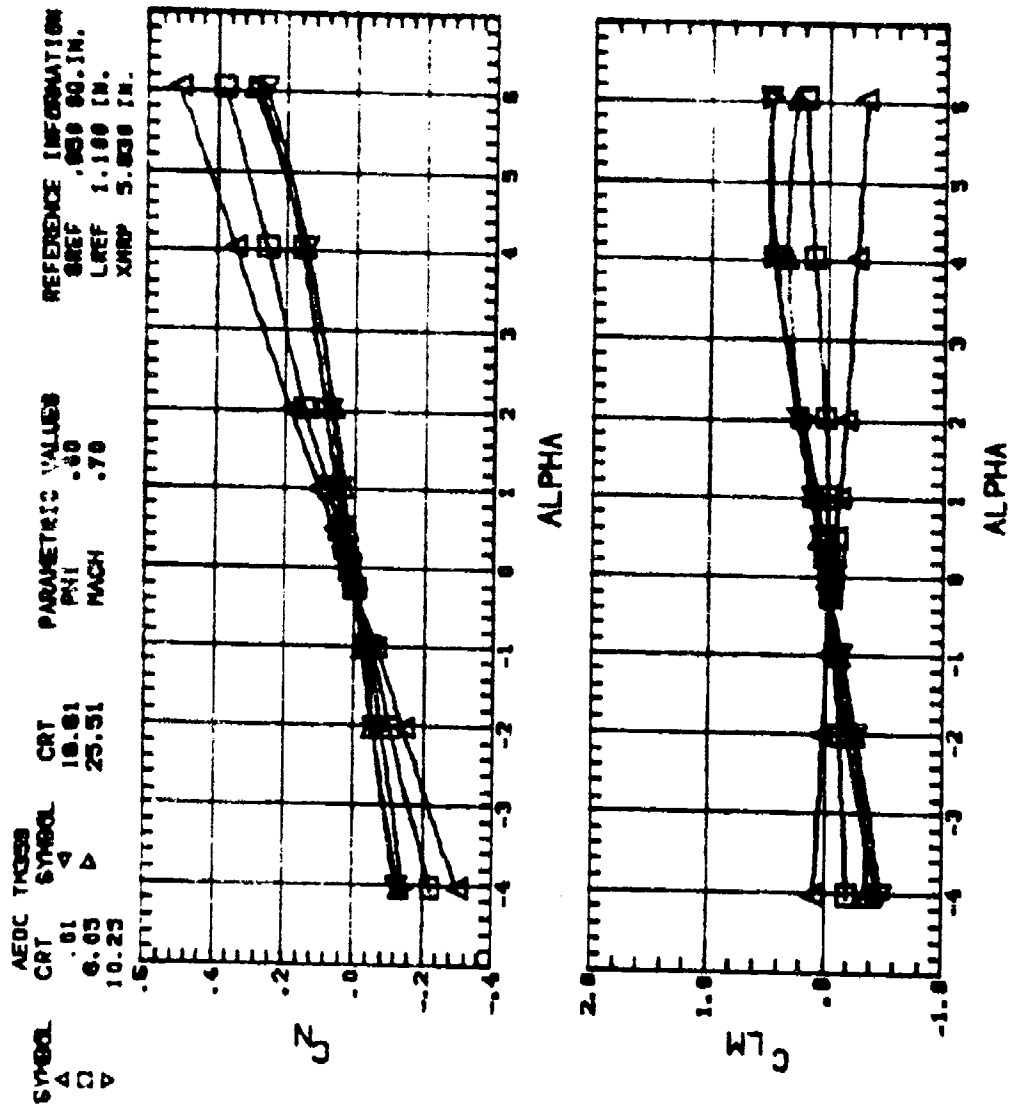


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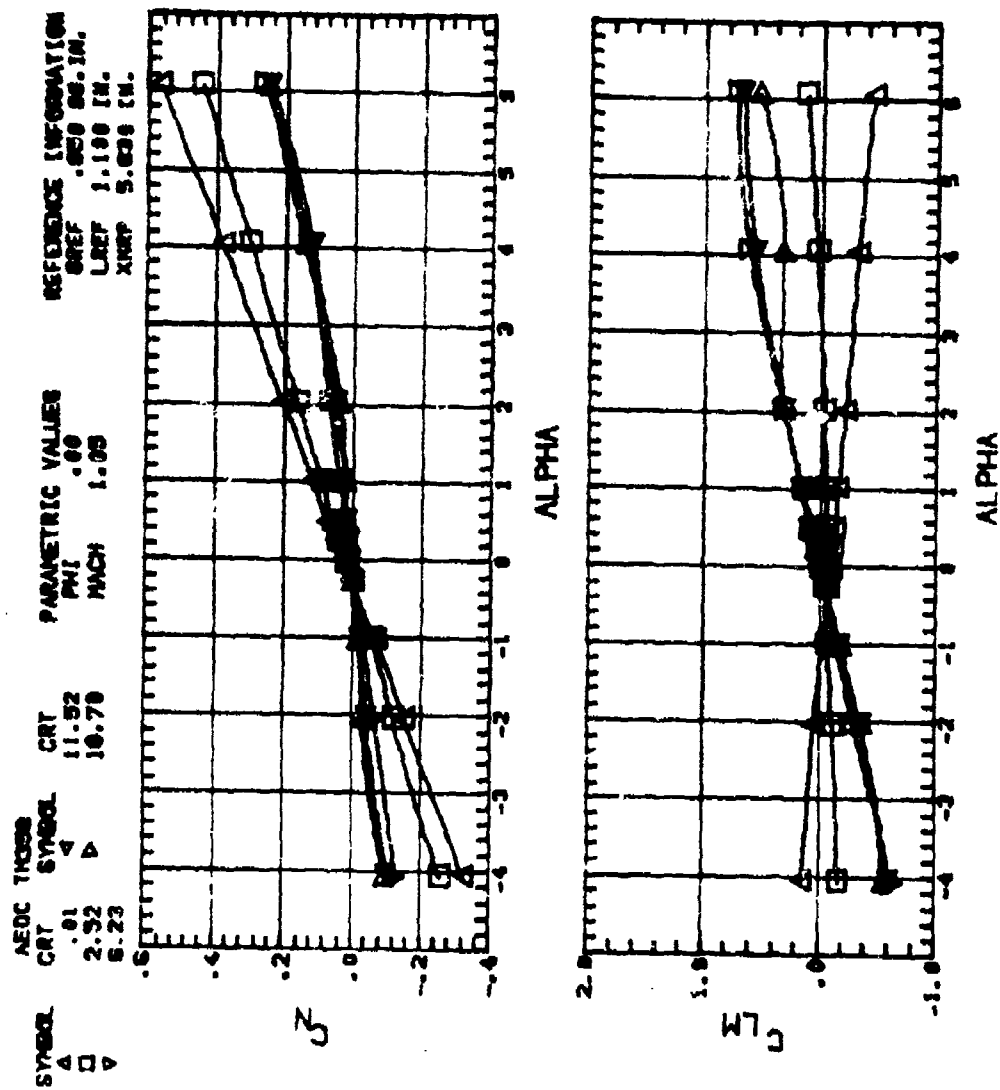


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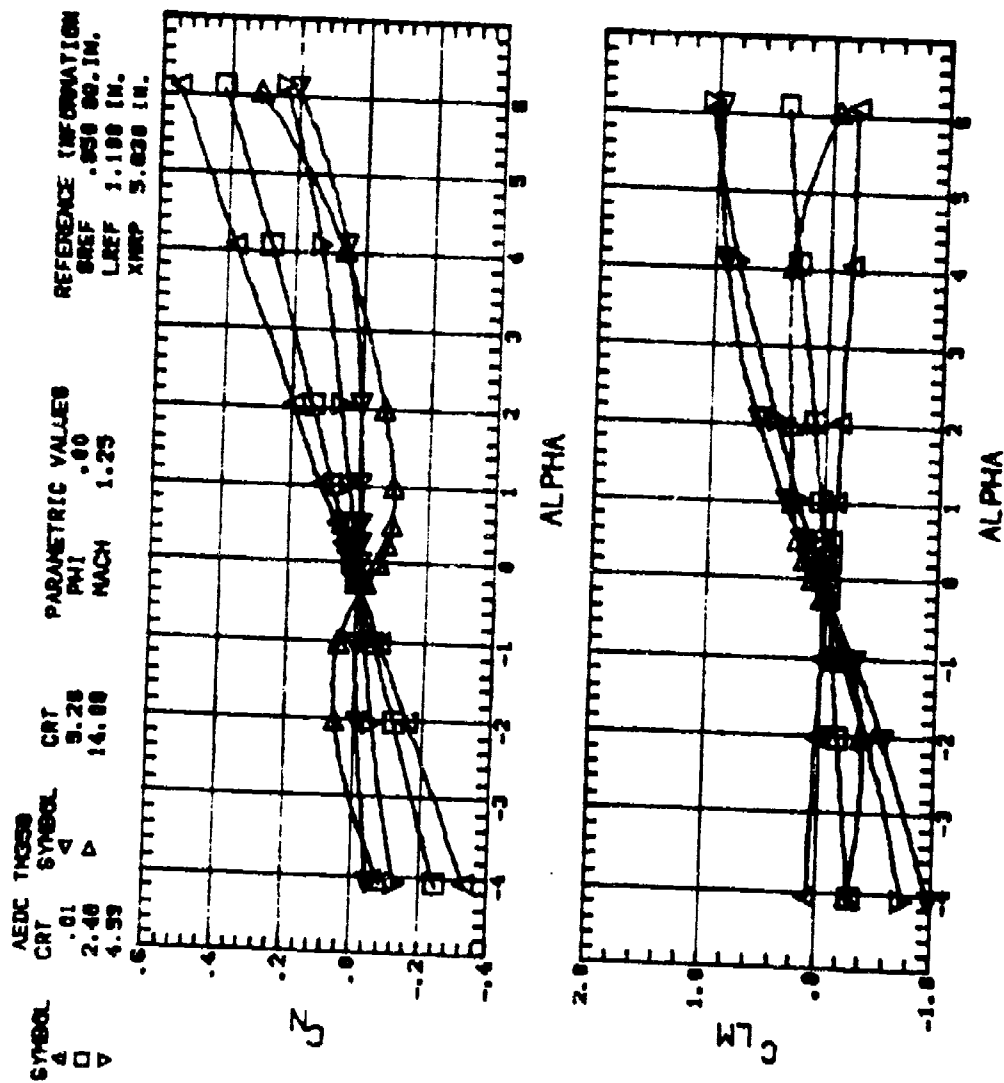


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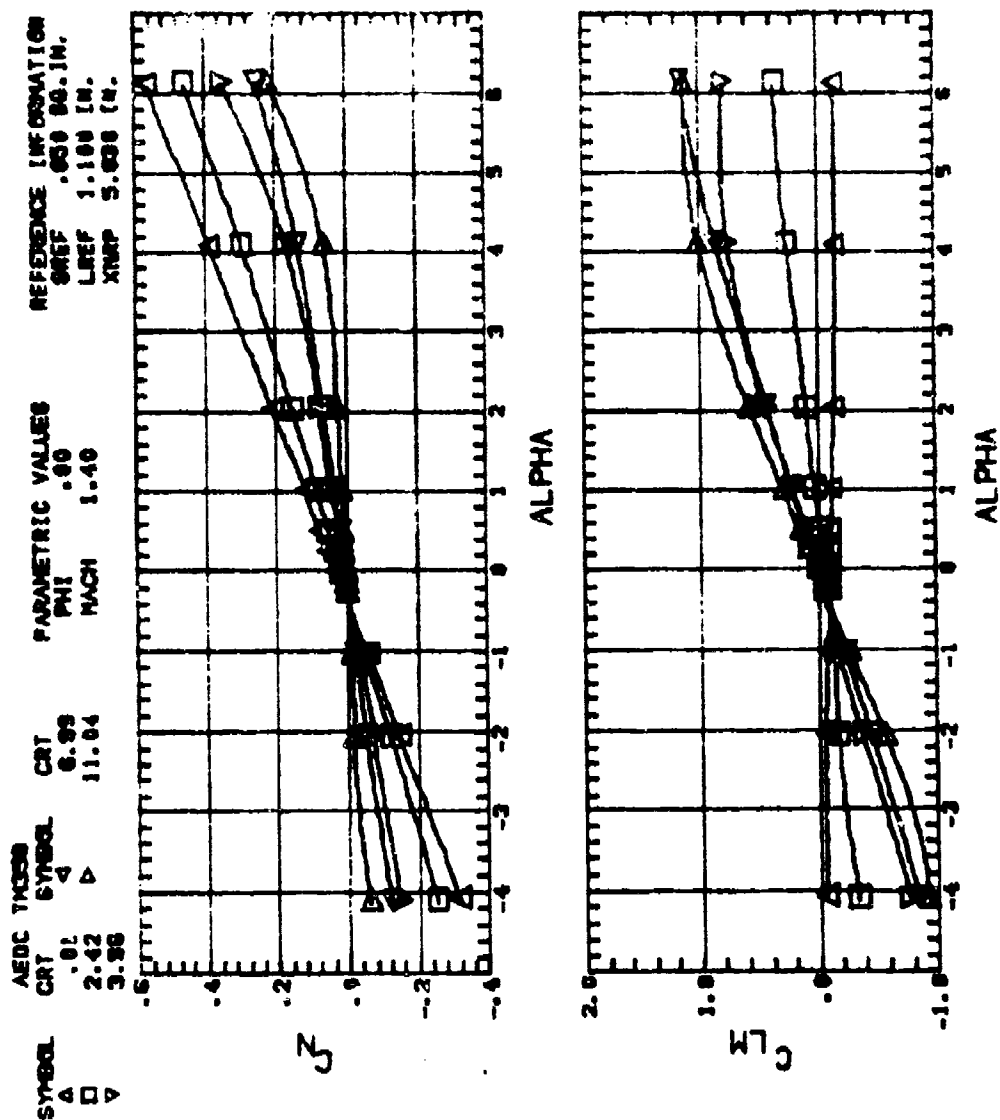


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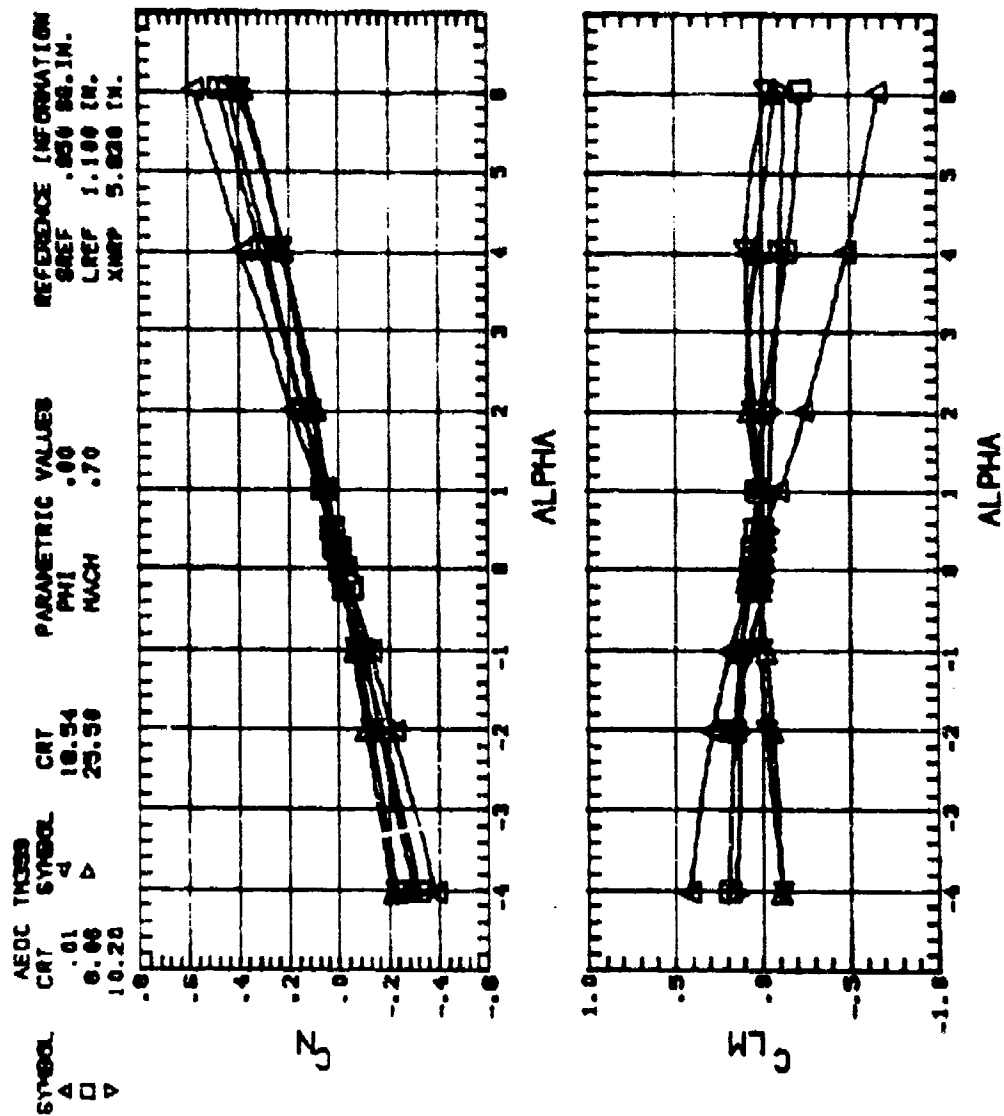


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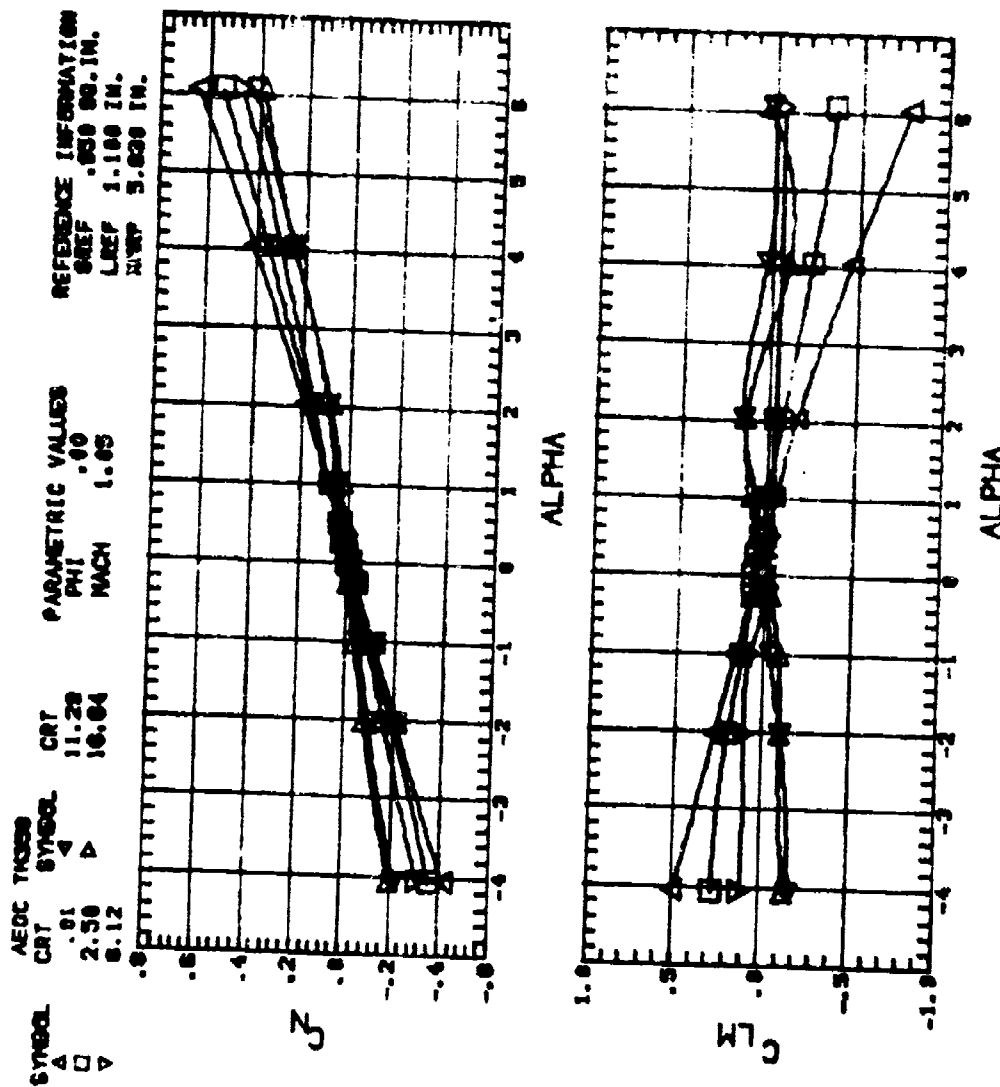


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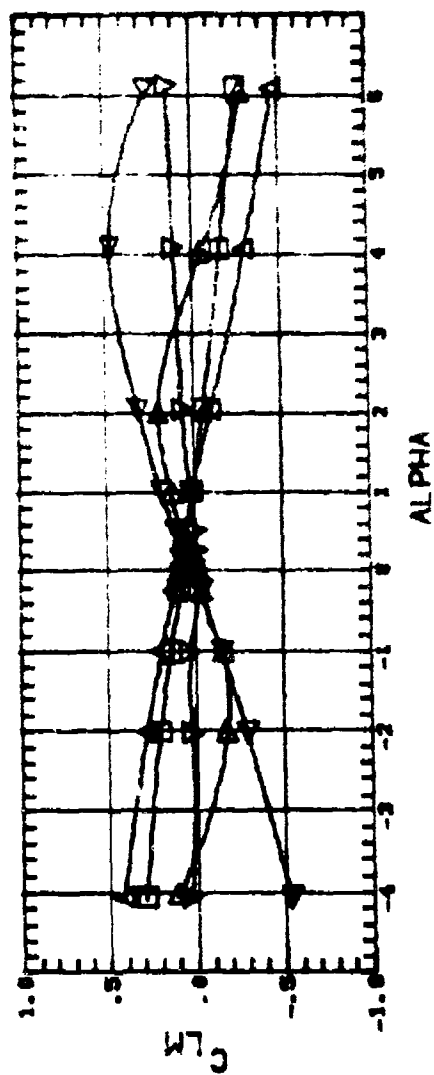
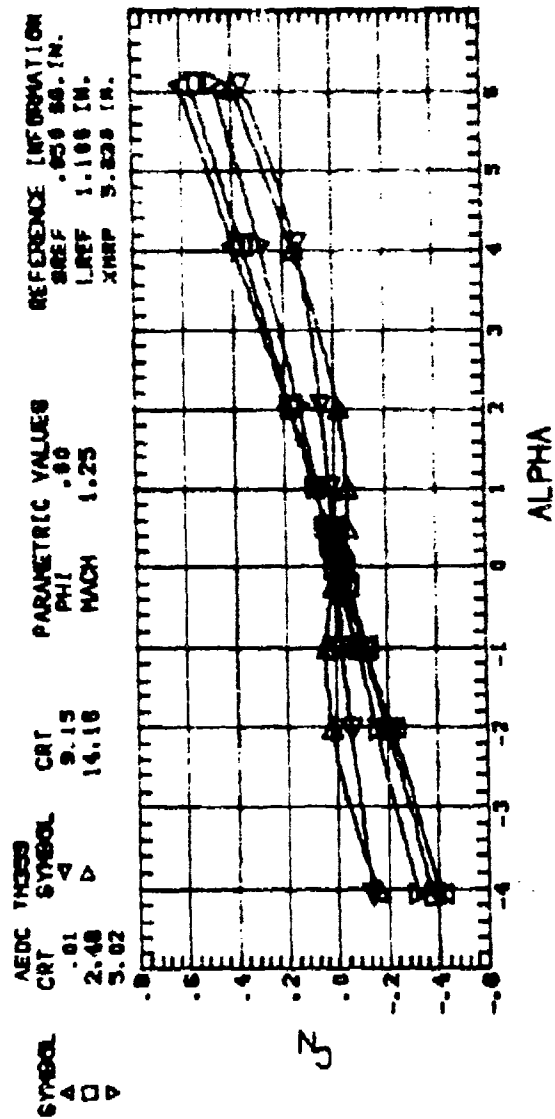


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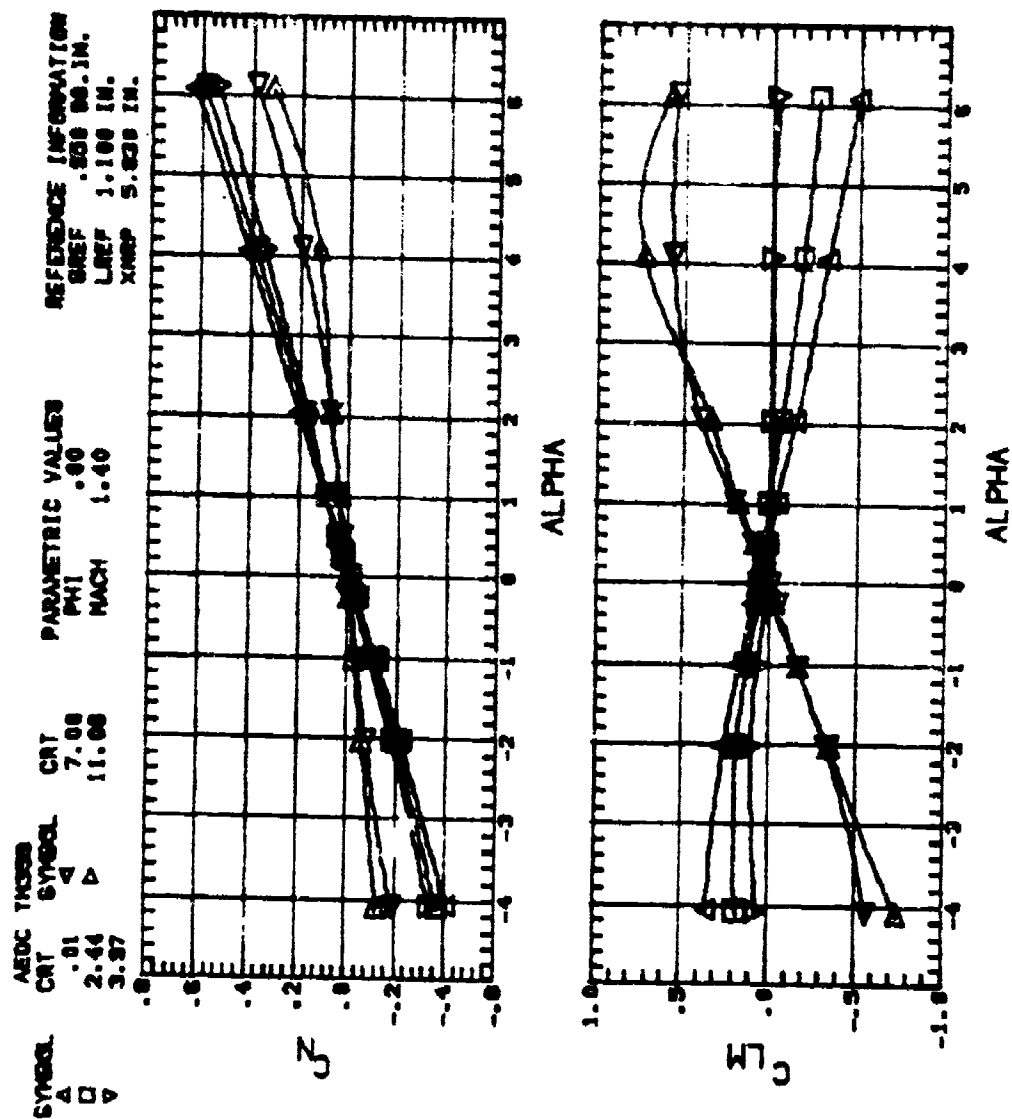


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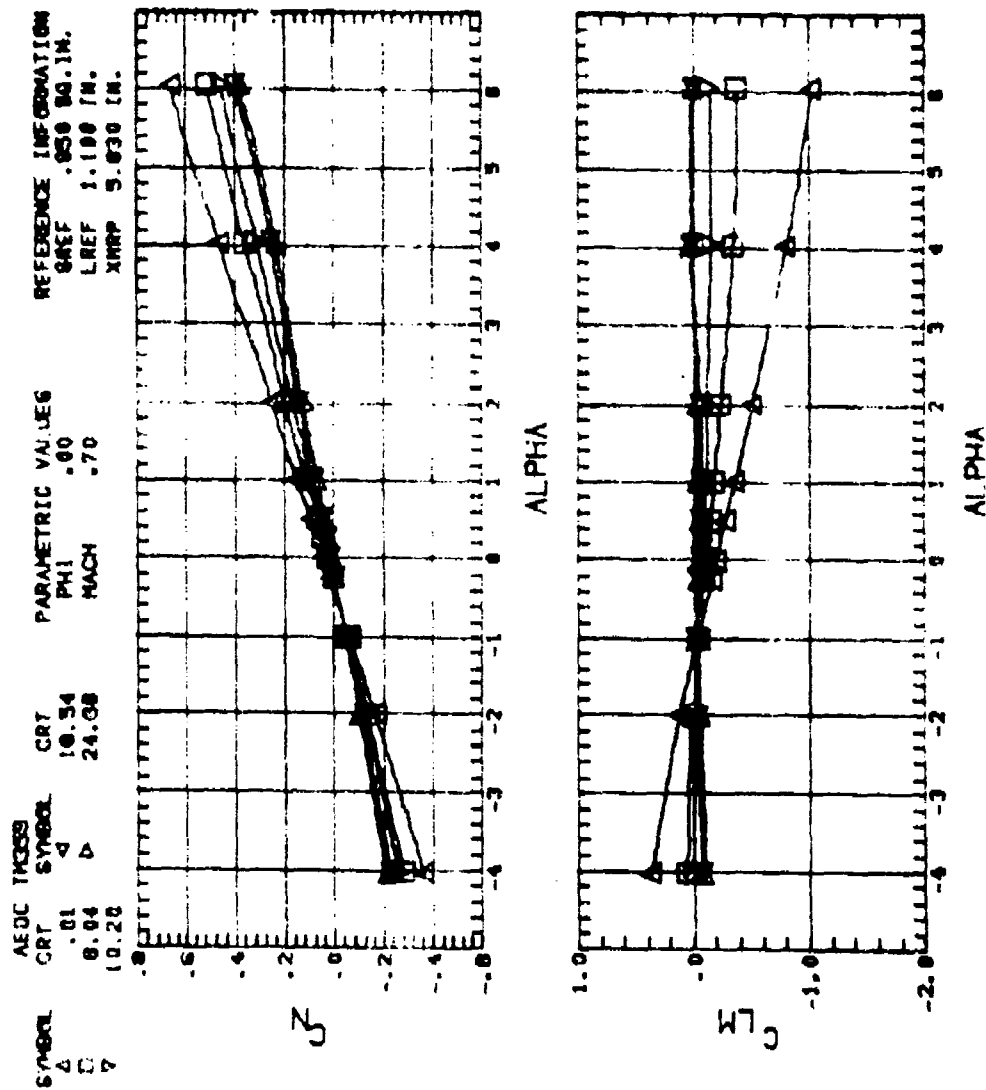


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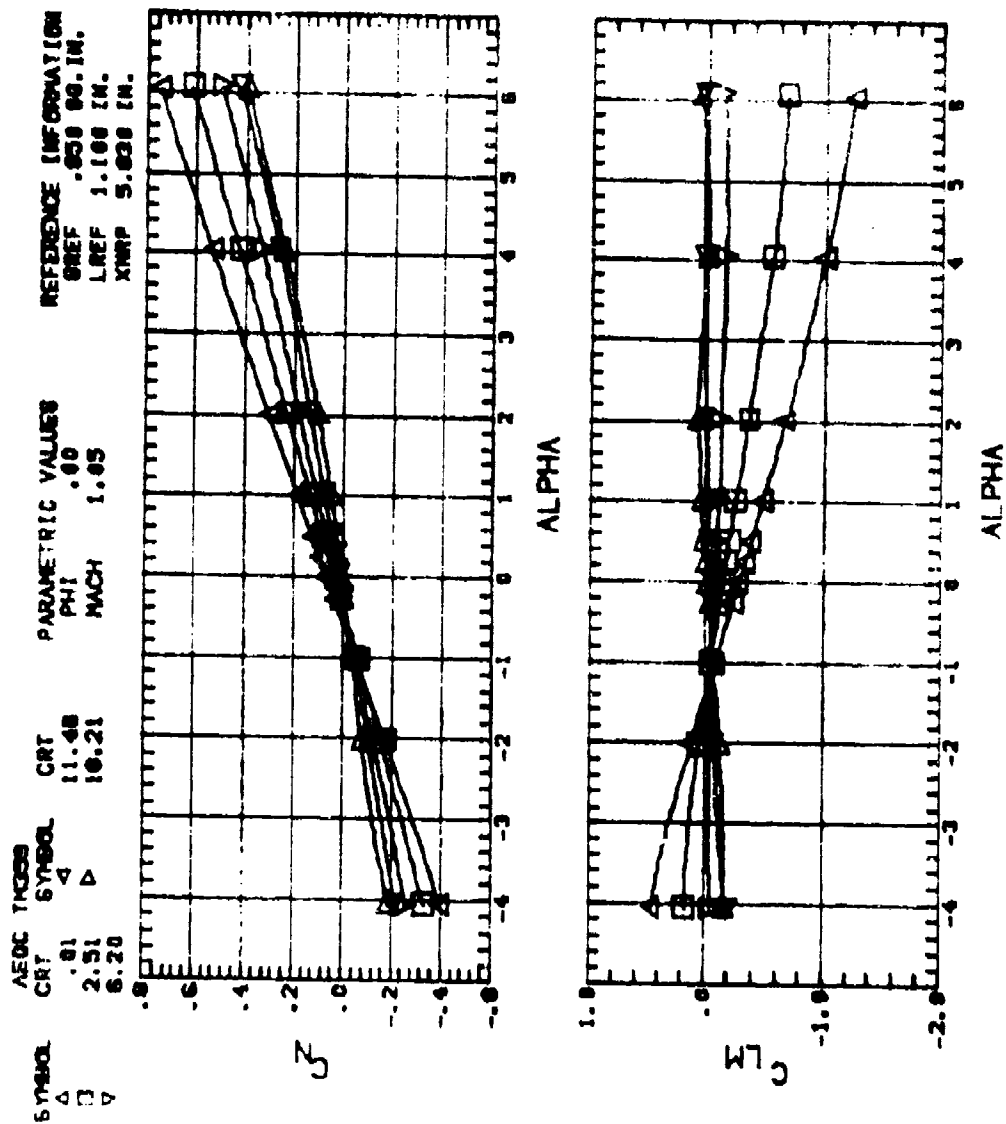
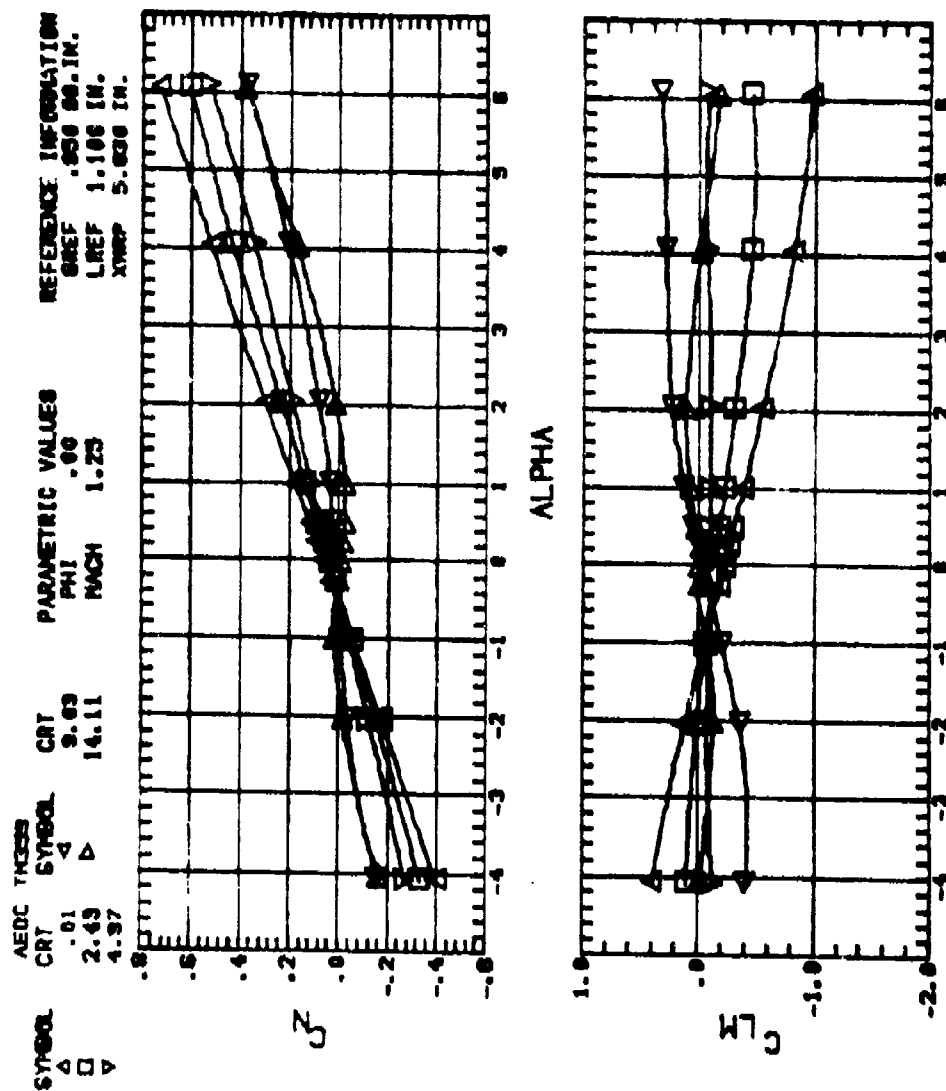


Figure 4. Continued. F6D2



ALPHA

Figure 4. Continued. F6D2

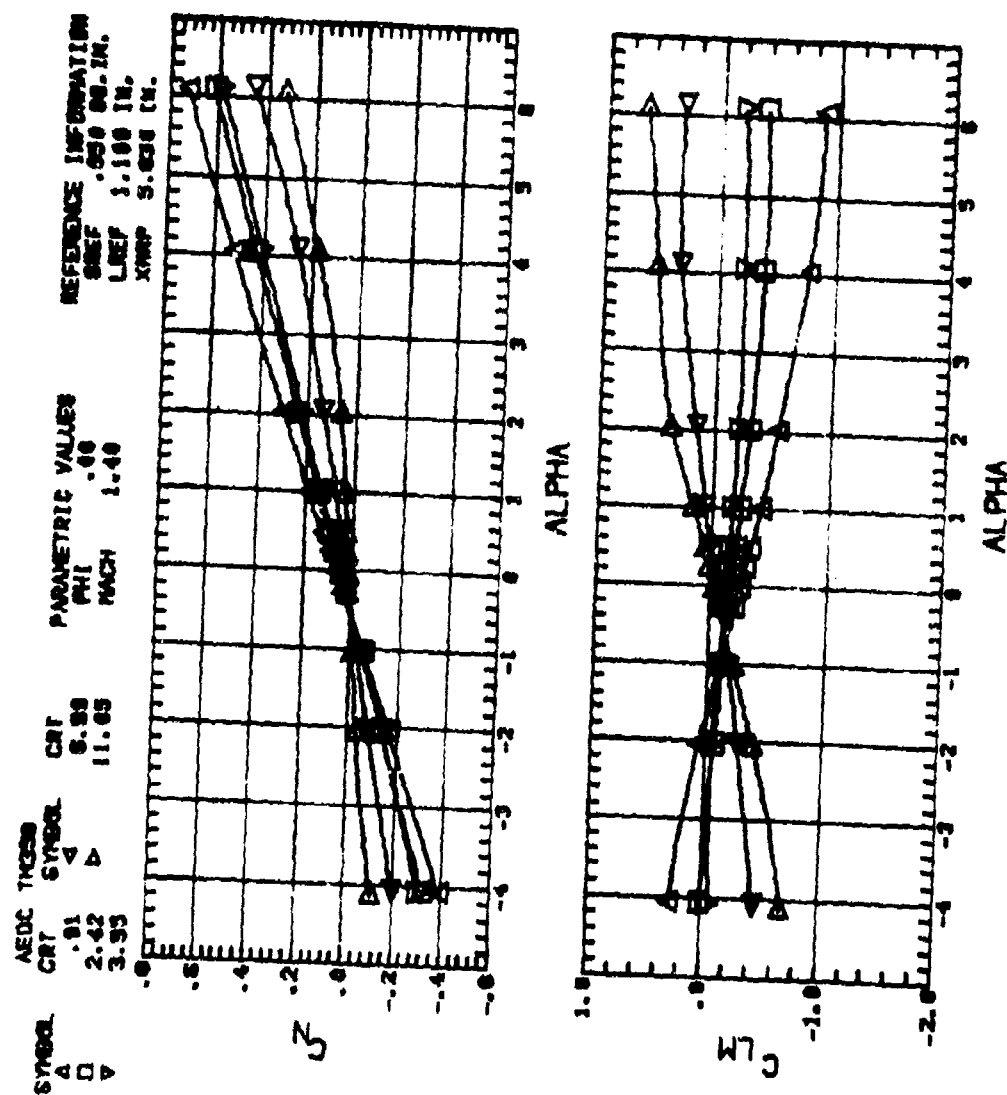


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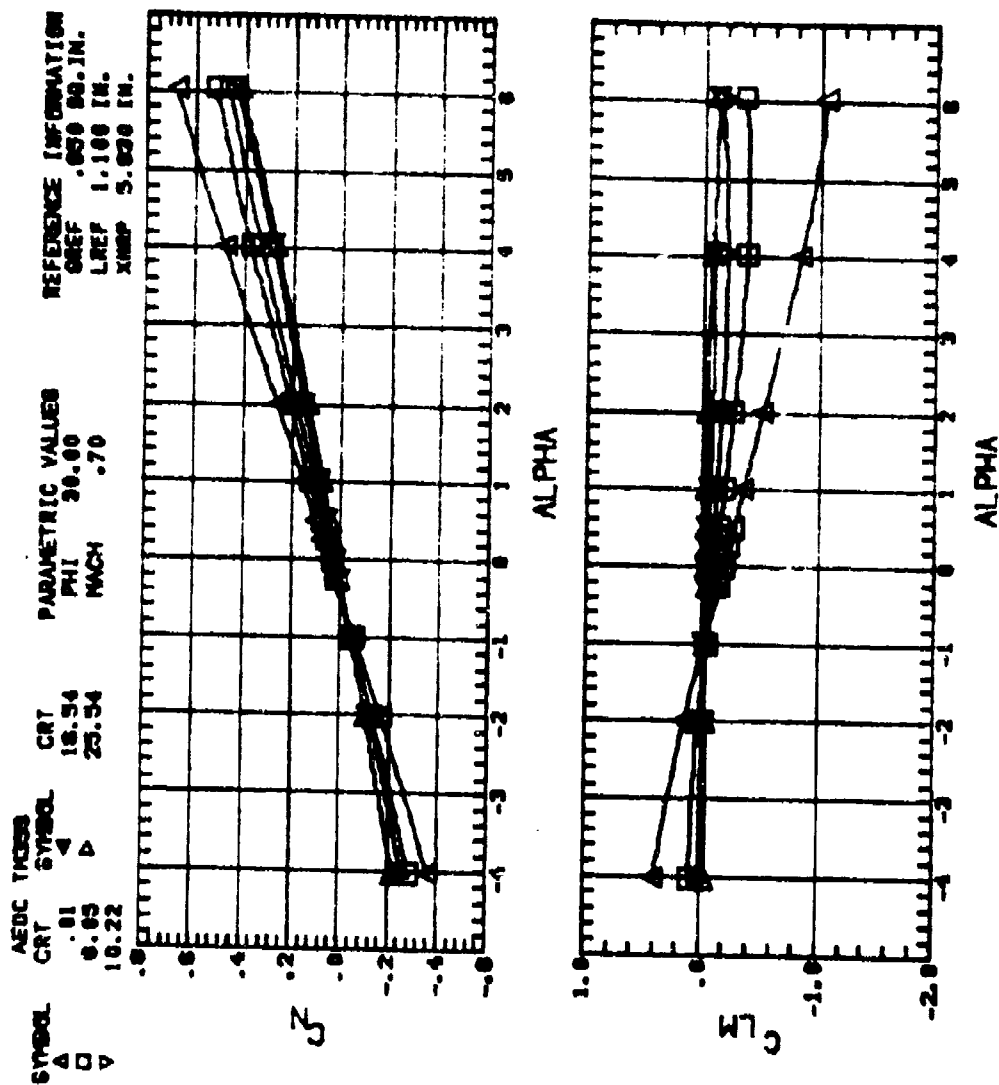


Figure 4. Continued. F6D2, PHI=30 DEG

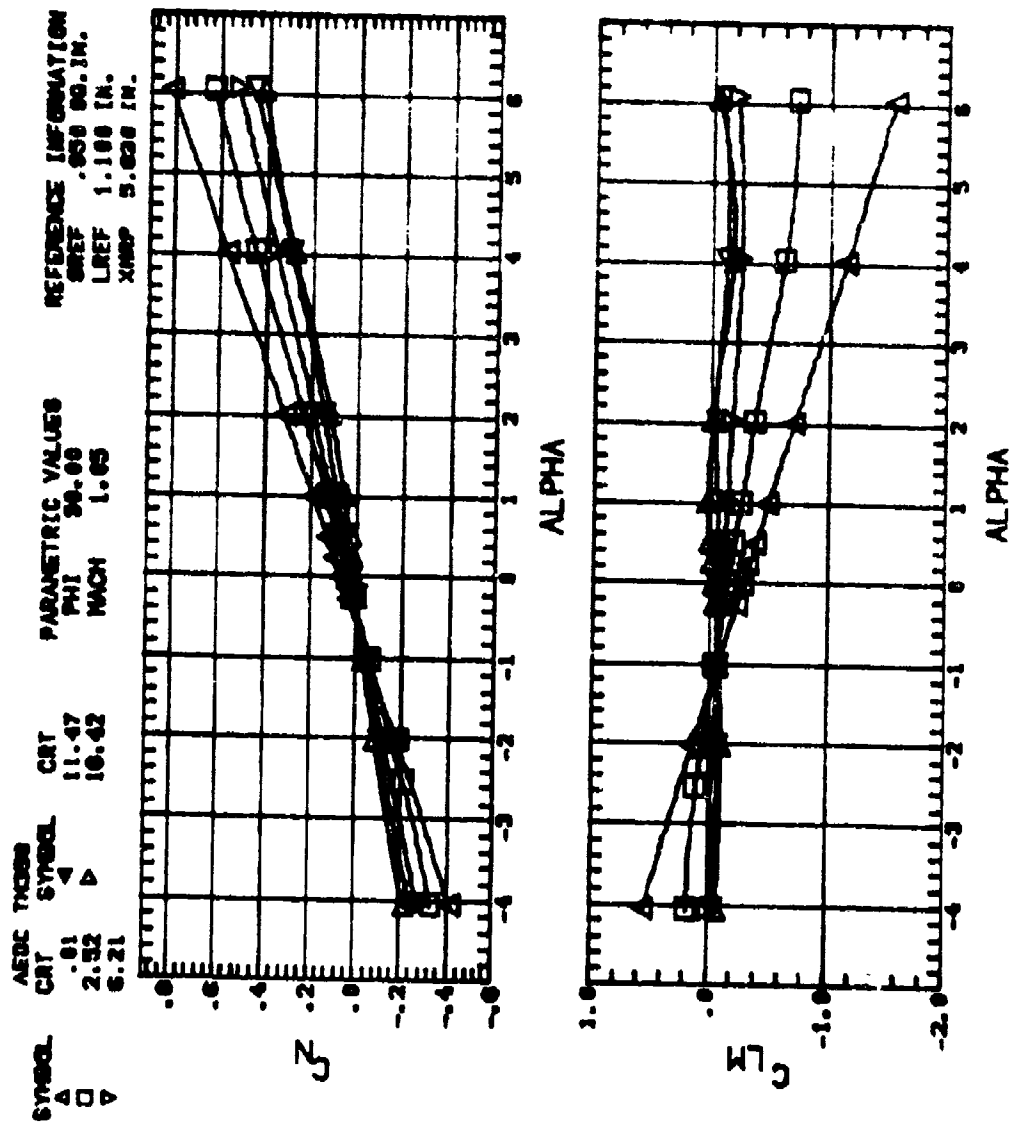


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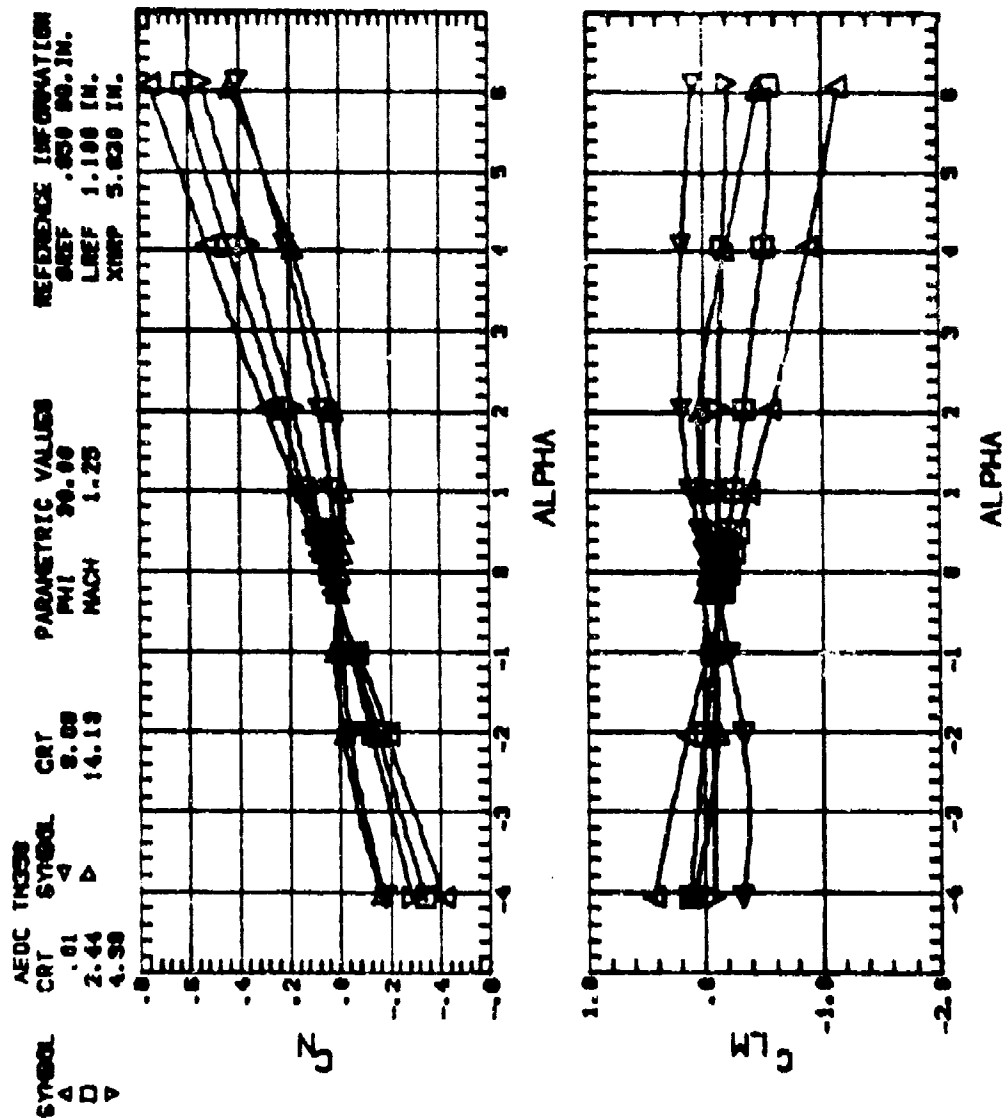


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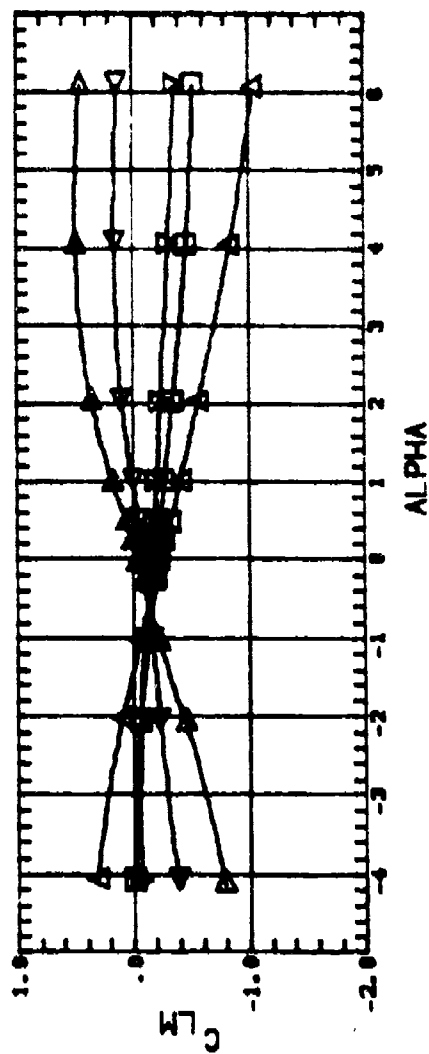
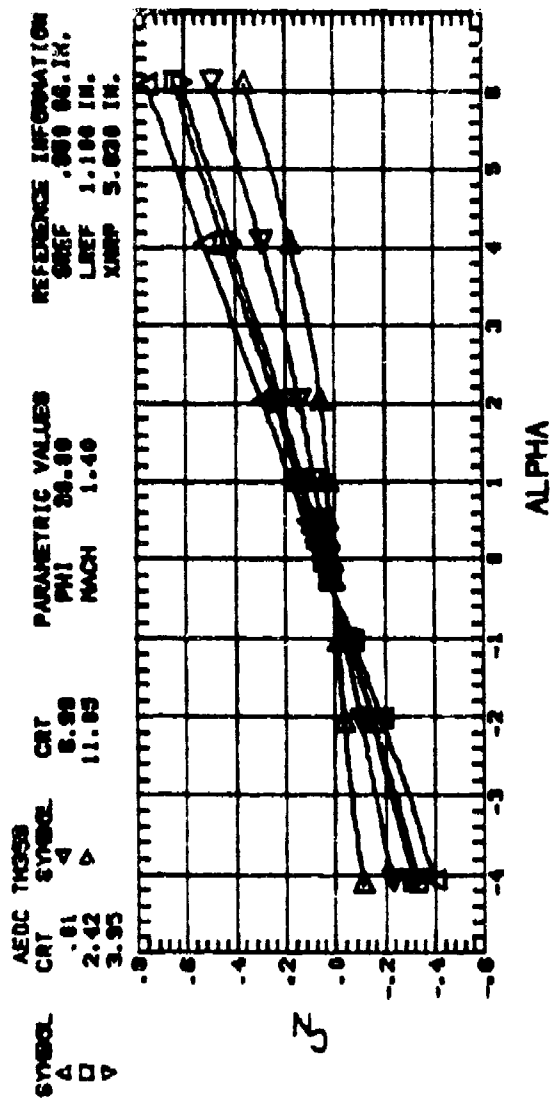


Figure 4. Continued. F6D2, PHI=30 DEG

SYMBOL		CONFIG	REFERENCE INFORMATION	
○		C	SREF	.950 SQ. IN.
□		FD2	LREF	1.100 IN.
△		F6D2	XMRP	5.830 IN.
▽		FL2D2		
◇		F6D2S		

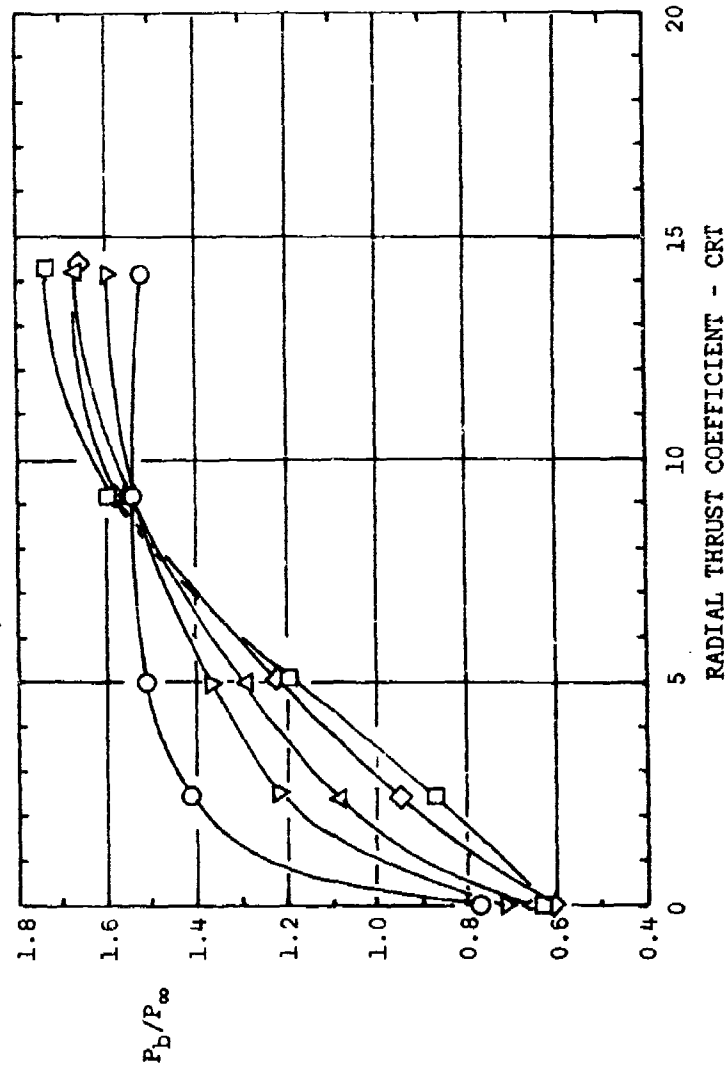


Figure 5. Typical thrust effect on base pressure ratio $-M_\infty = 1.25$, $\alpha = 0^\circ$.

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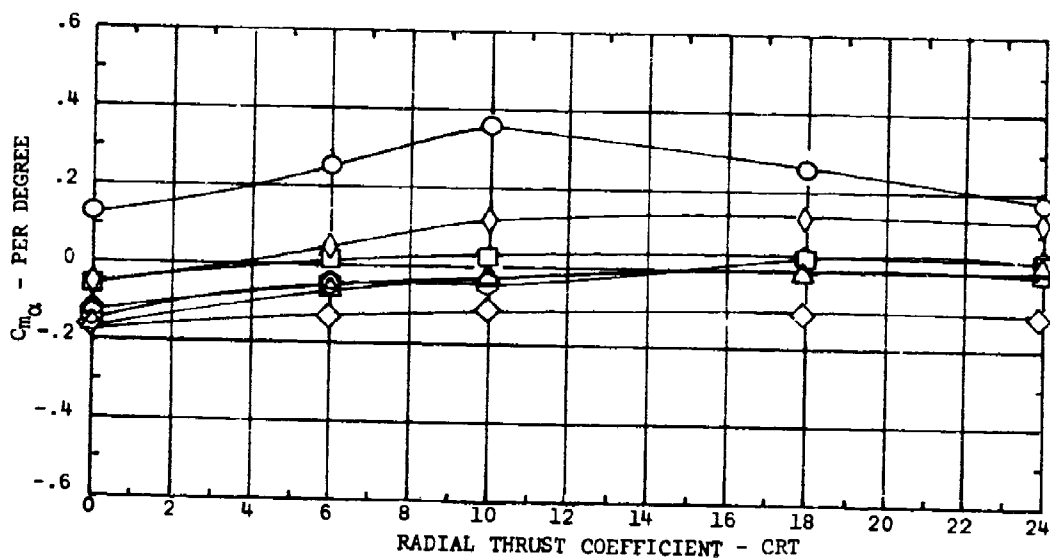
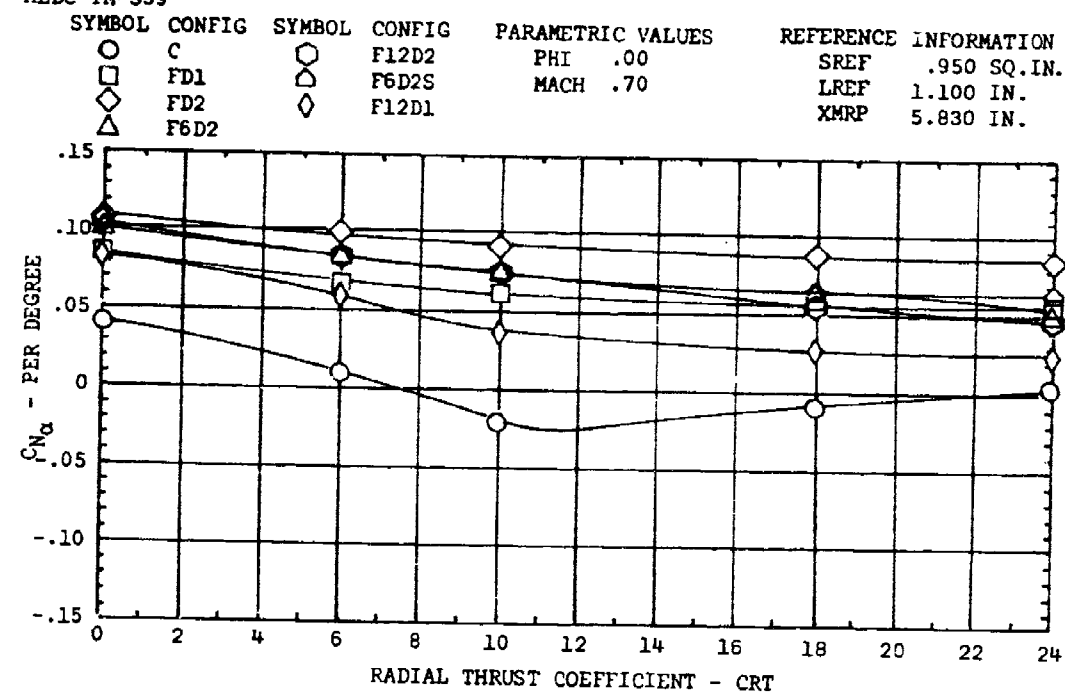


Figure 6. Thrust effects on initial normal force and pitching moment coefficient slopes.

SYMBOL	CONFIG	SYMBOL	CONFIG	PARAMETRIC VALUES	REFERENCE INFORMATION
○	C	○	F12D2	PHI .00	SREF .950 SQ. IN.
□	FD1	□	F6D2S	MACH 1.05	LREF 1.100 IN.
◇	FD2	◇	F12D1		XMR? 5.830 IN.
△	F6D2				

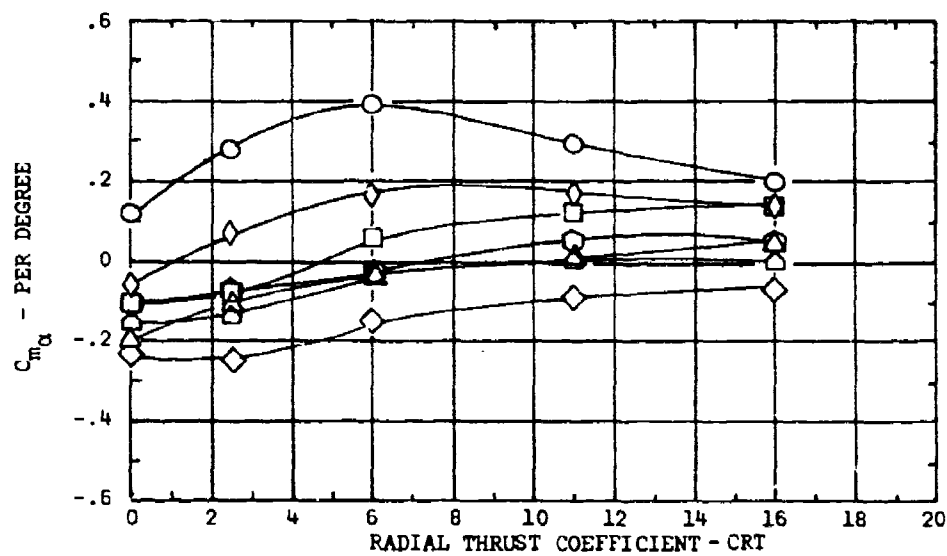
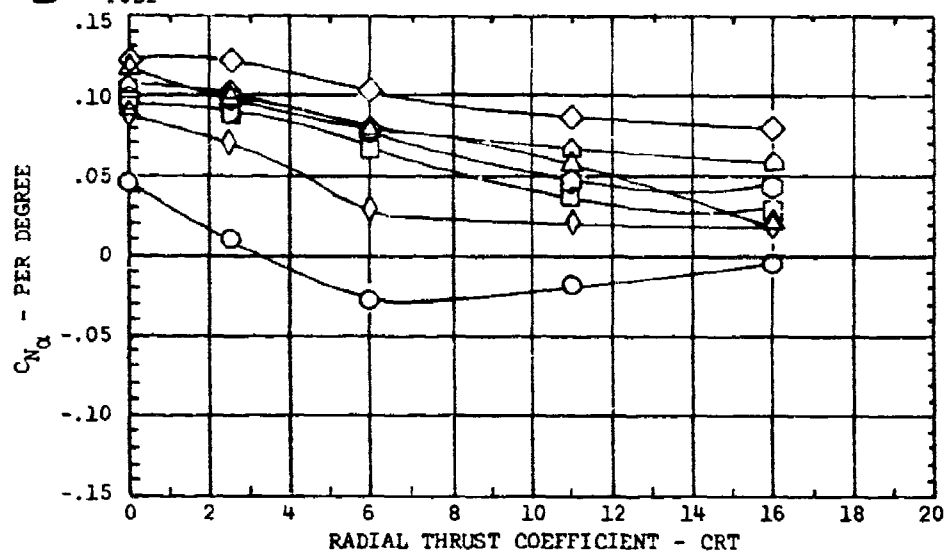


Figure 6. Continued.

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SYMBOL	CONFIG	SYMBOL	CONFIG	PARAMETRIC VALUES	REFERENCE LINE SPACING
○	C	○	F12D2	PHI .00	SRE
□	FD1	△	F6D2S	MACH 1.25	LREF
◇	FD2	◇	F12D1		XMRP 5.830 IN.
△	F6D2				

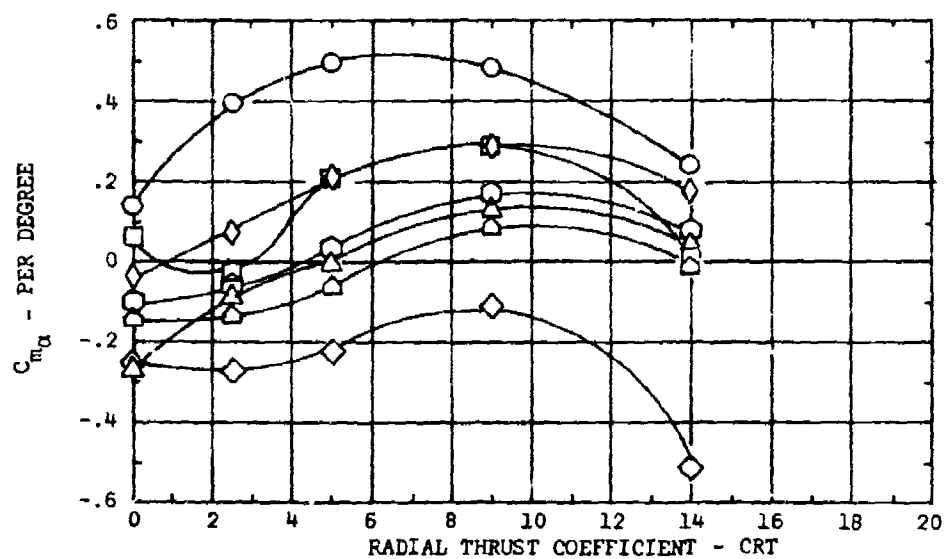
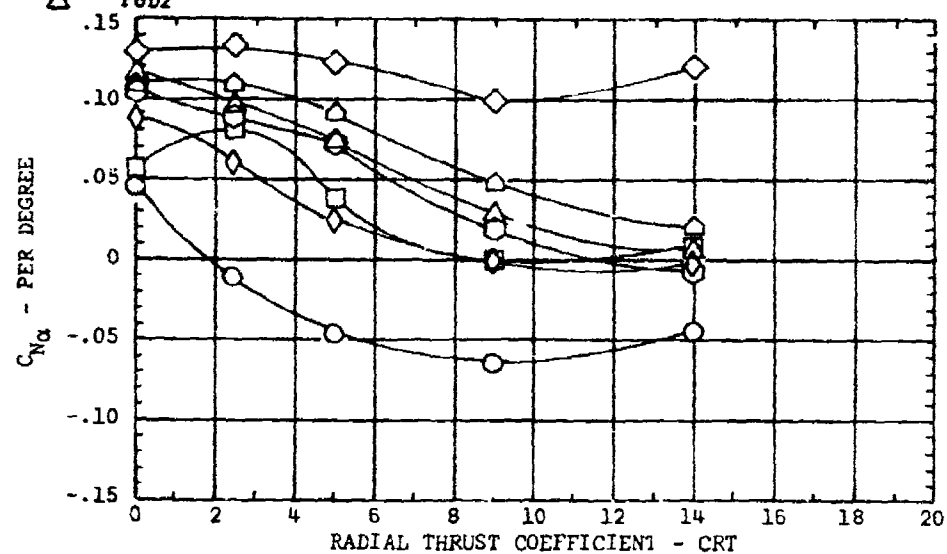


Figure 6. Continued.

PARAMETRIC VALUES

PHI .00

MACH 1.40

REFERENCE INFORMATION

SREF .950 SQ. IN.

LREF 1.100 IN.

XMRP 5.830 IN.

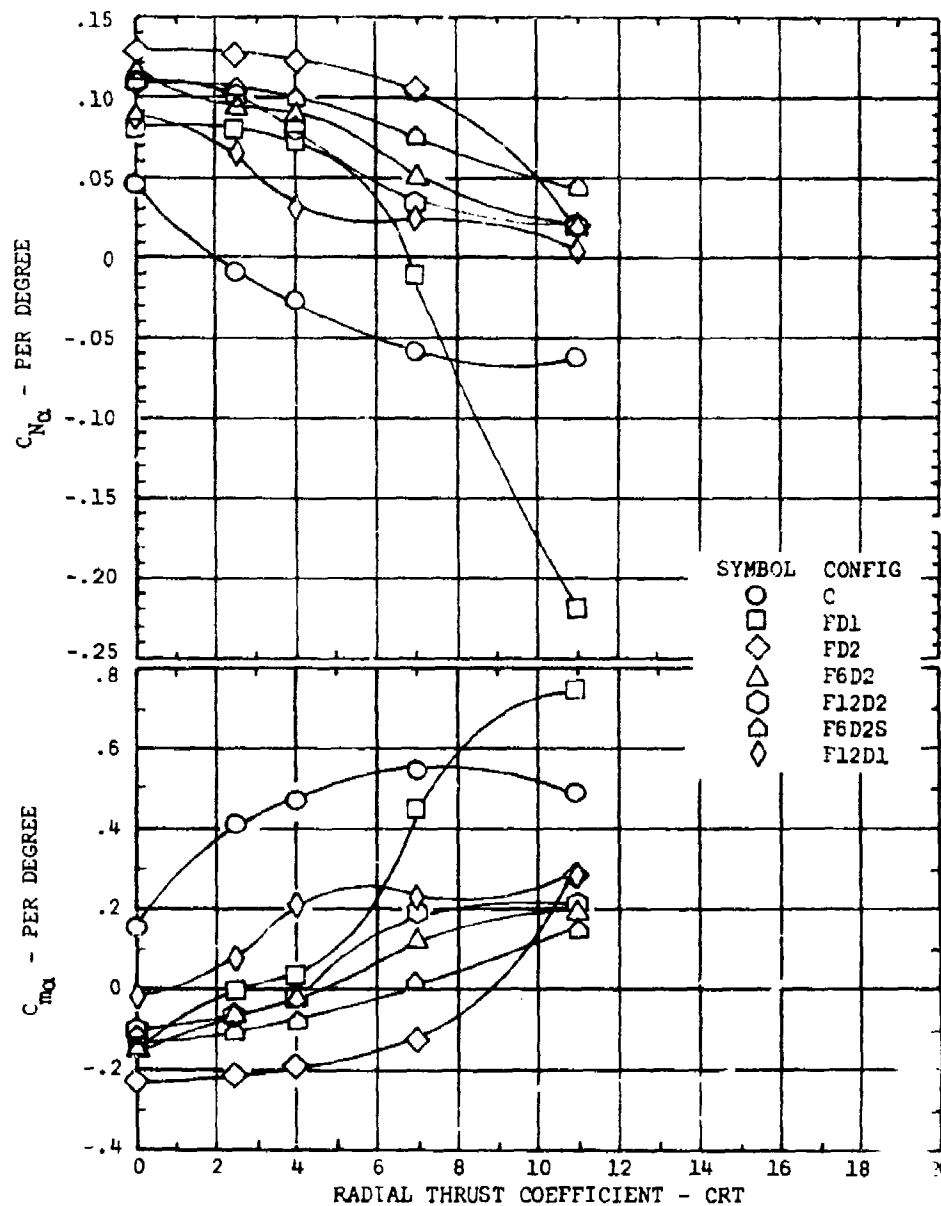


Figure 6. Concluded.

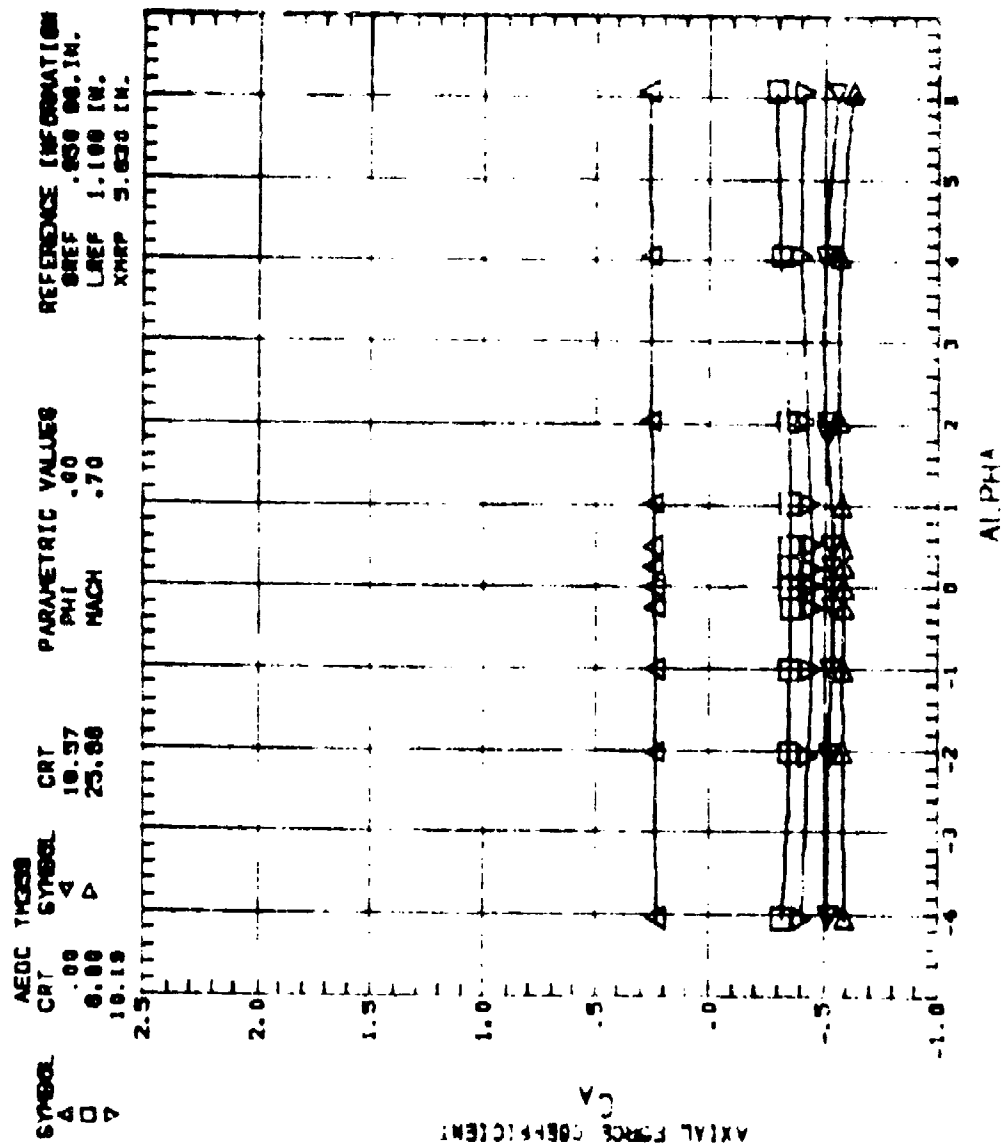


Figure 7. Thrust effects on axial force coefficient. C

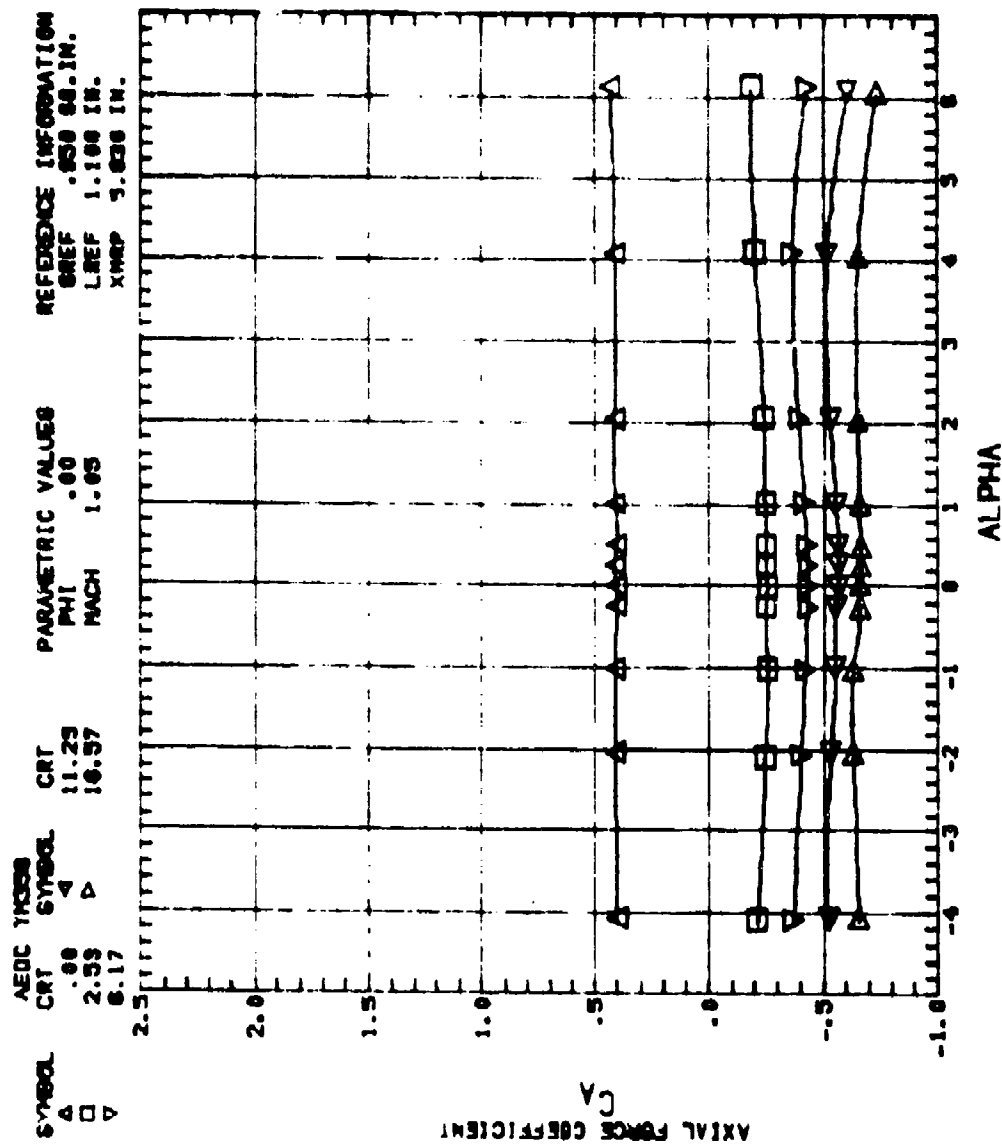


Figure 7. Continued. C

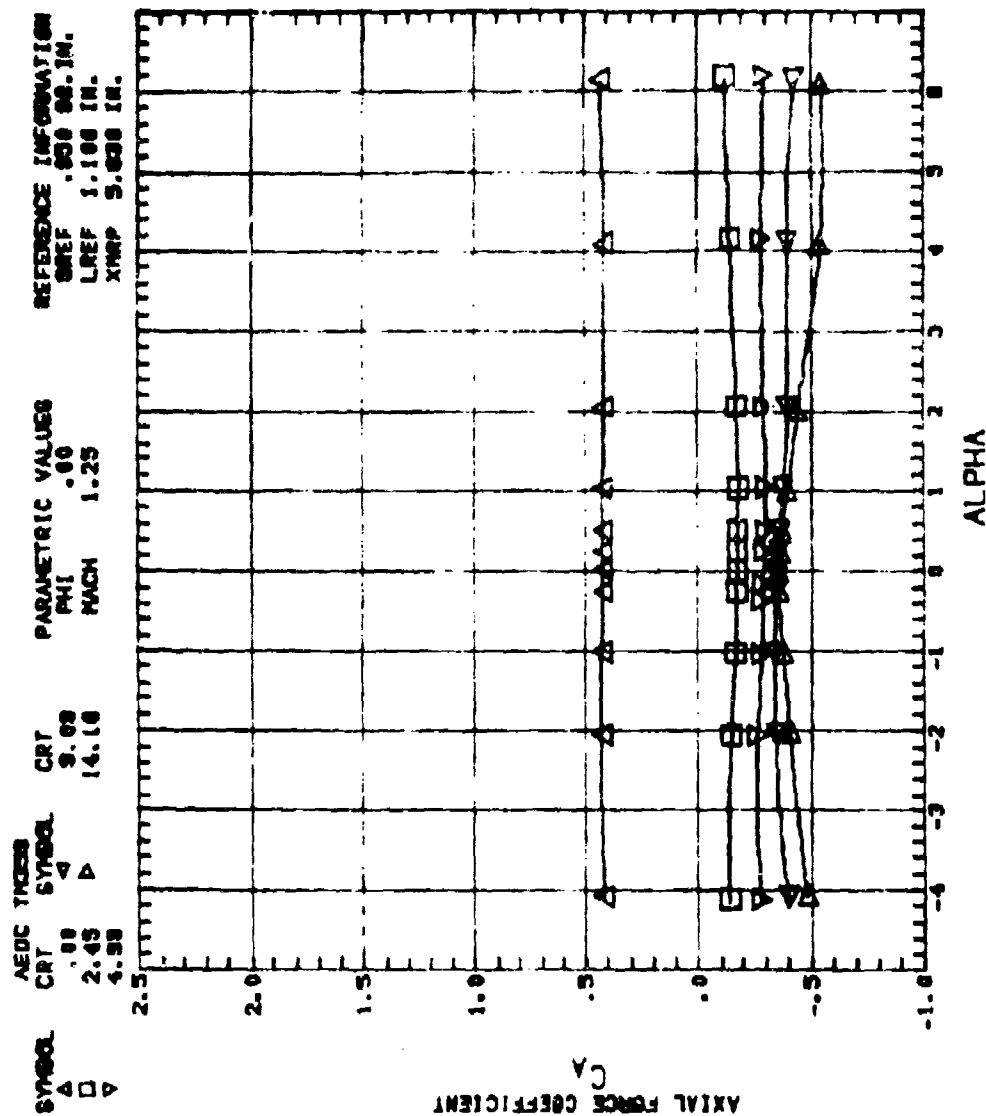


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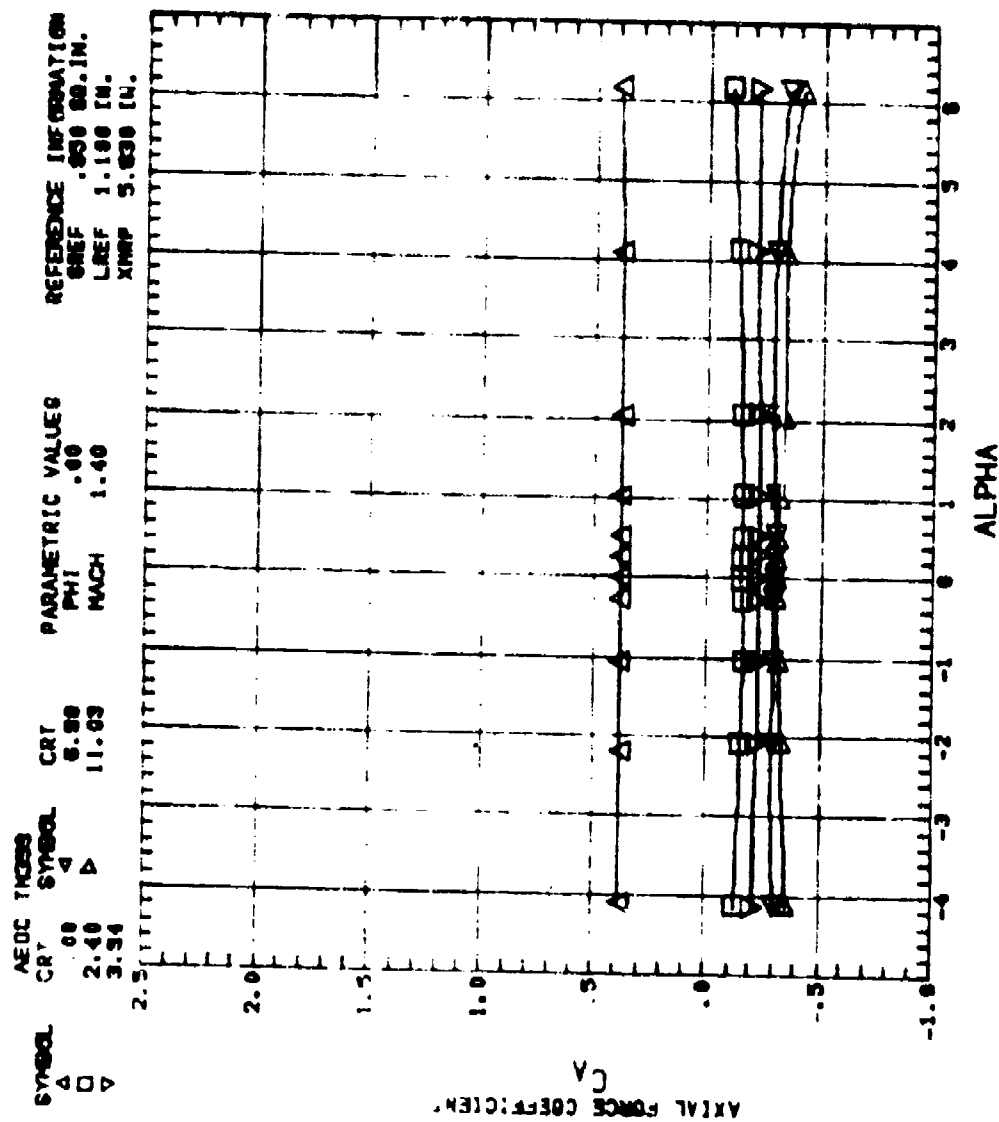


Figure 7. Continued. C

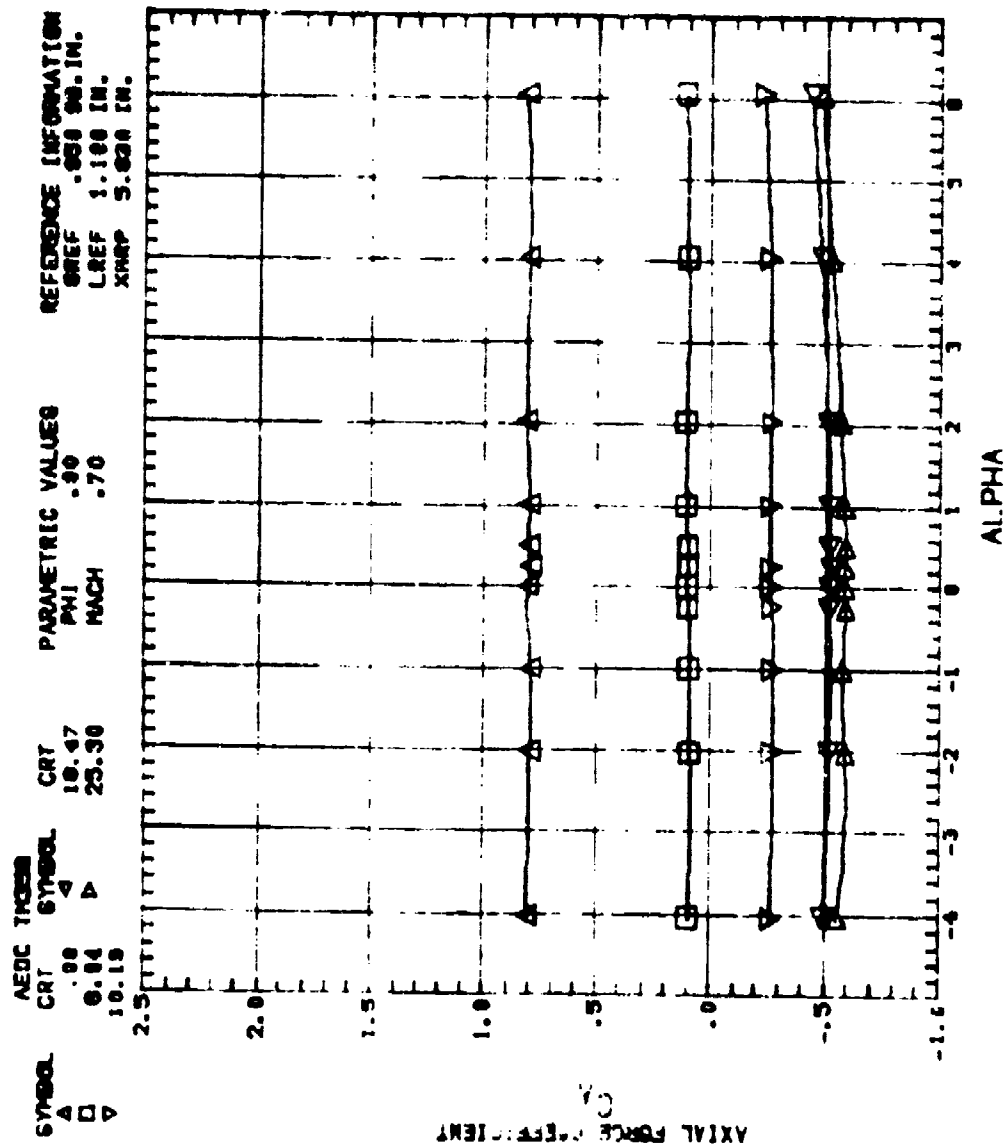


Figure 7. Continued. FDI

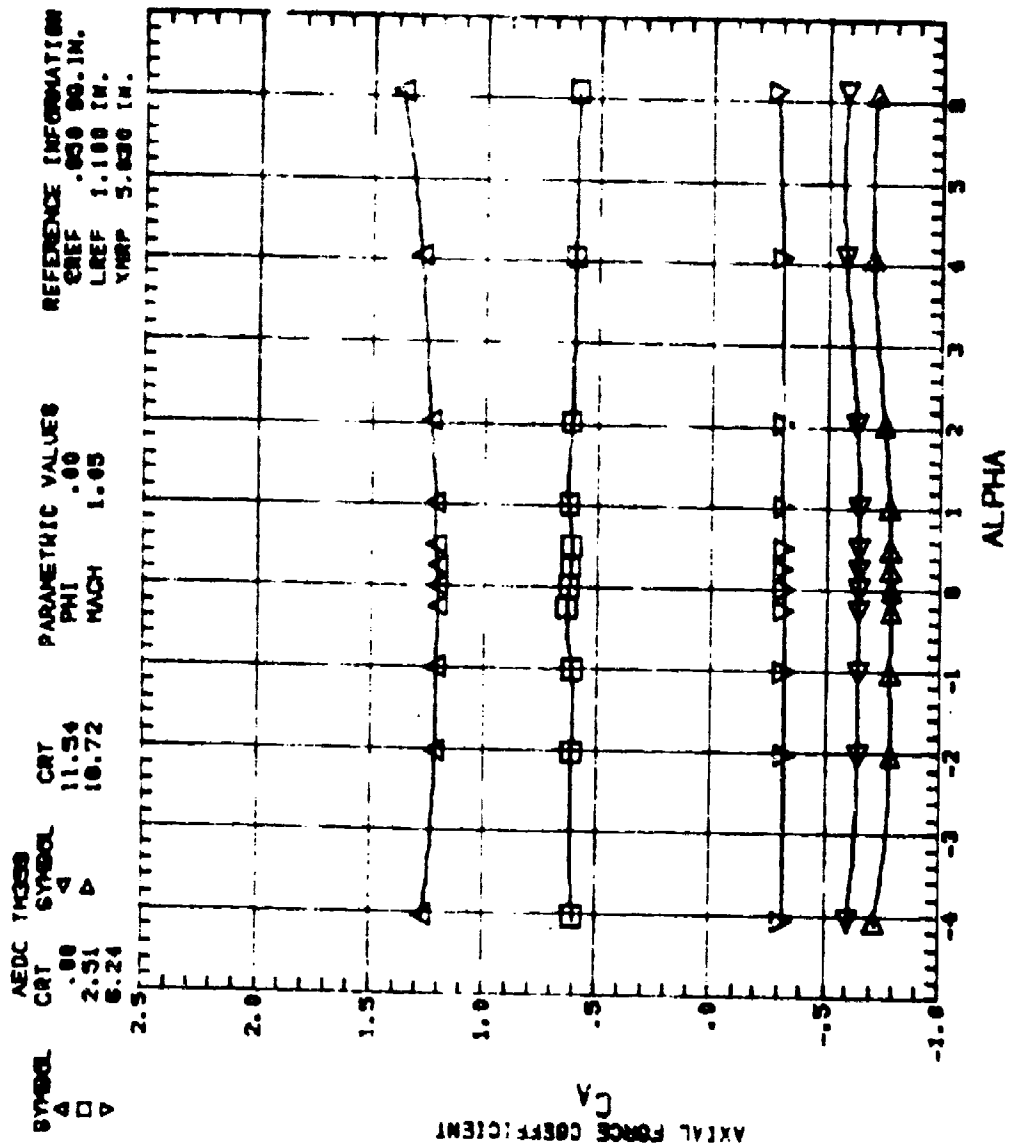


Figure 7. Continued. FD1

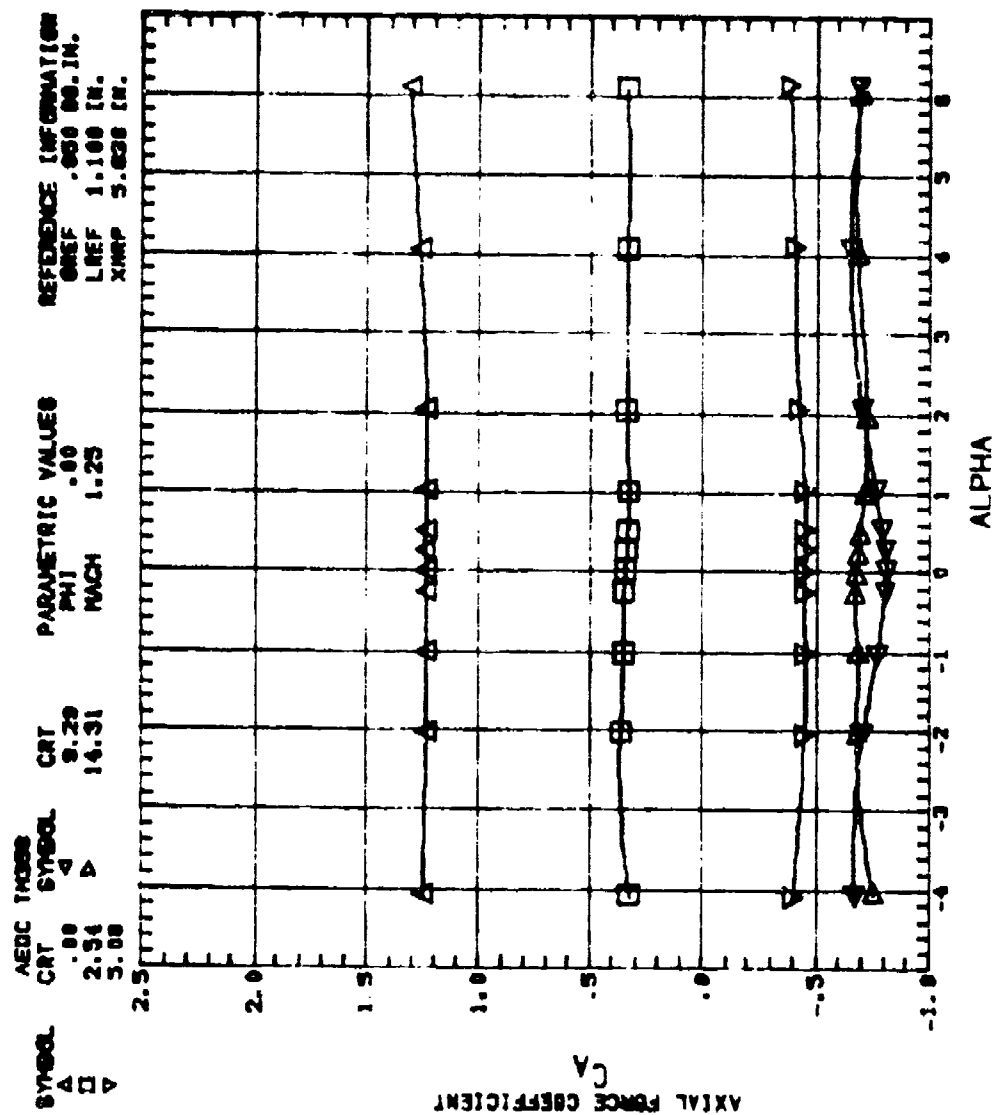


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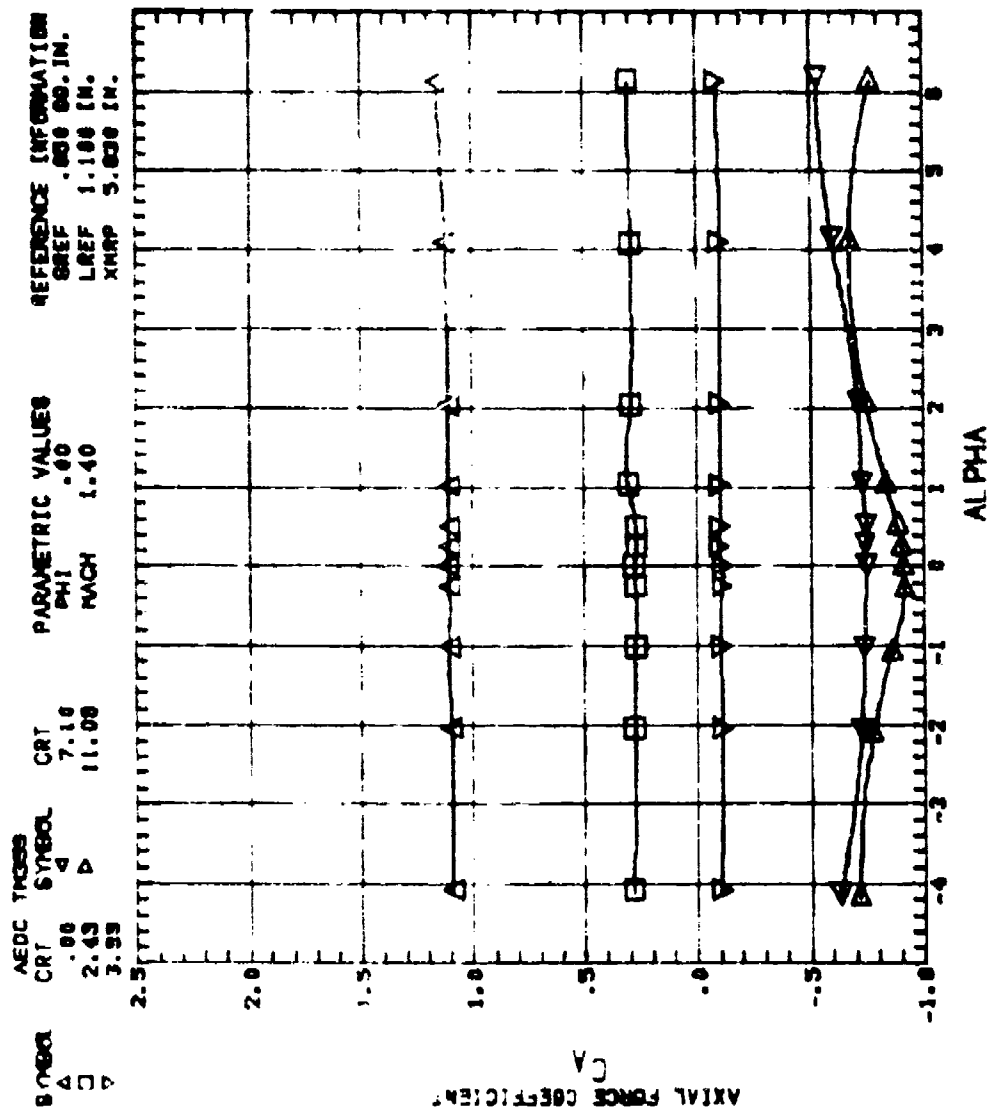


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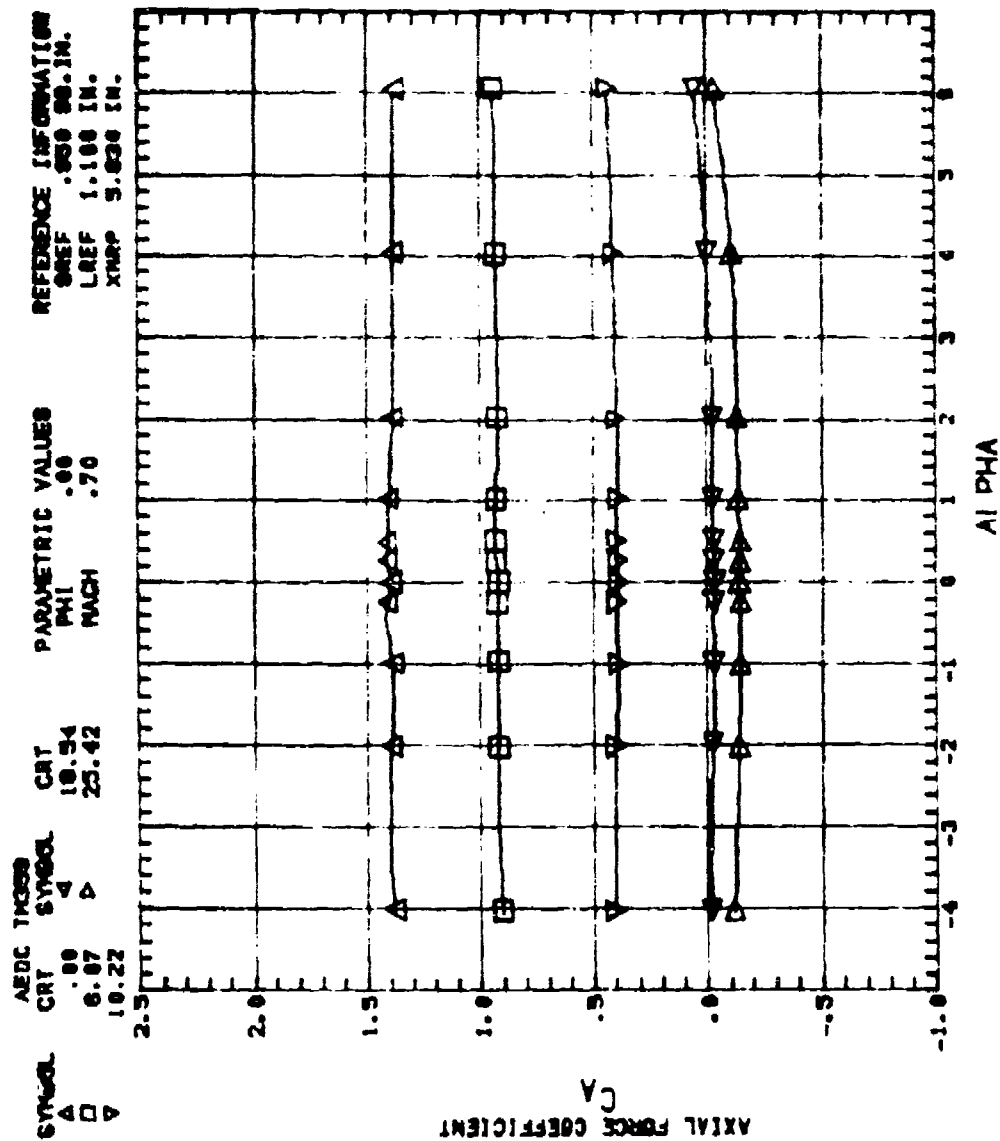


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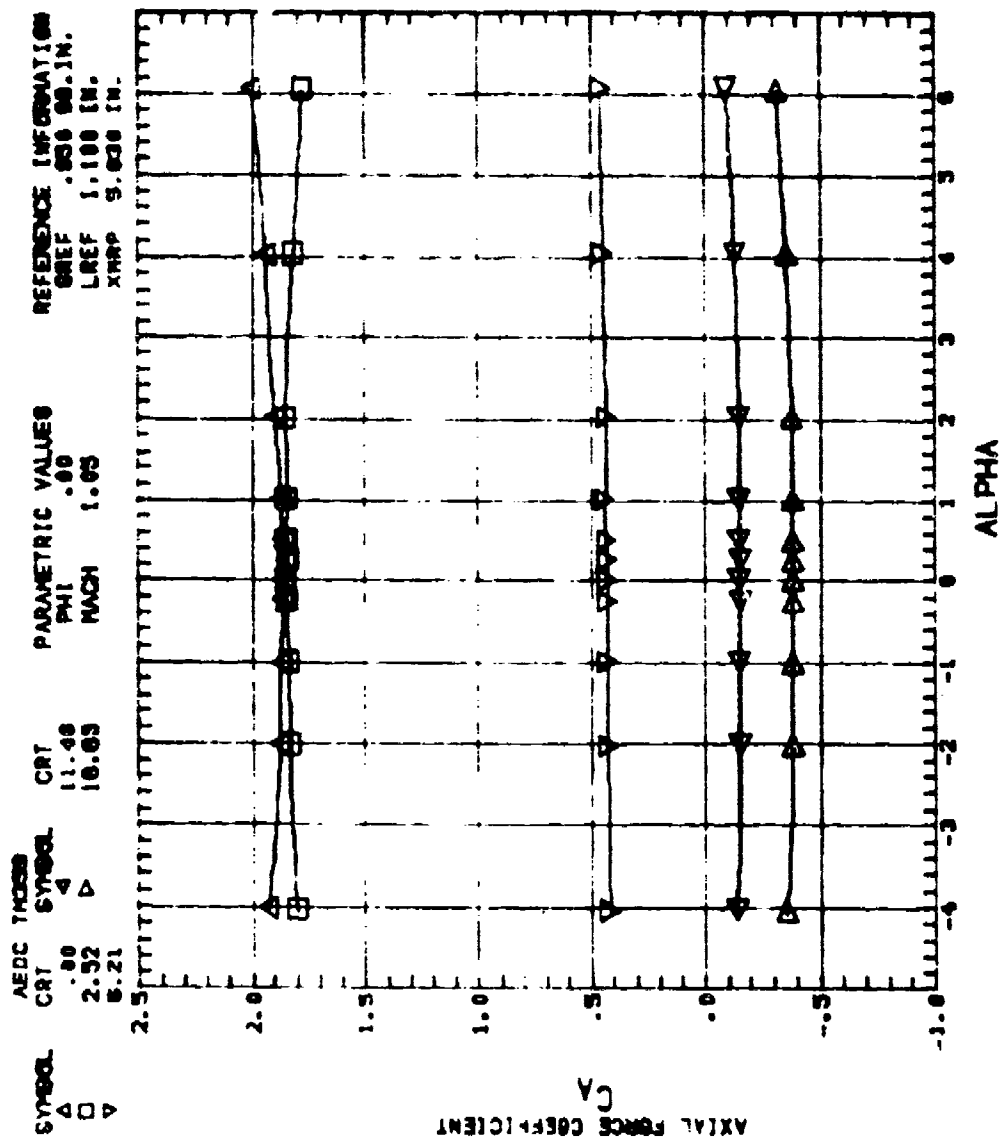


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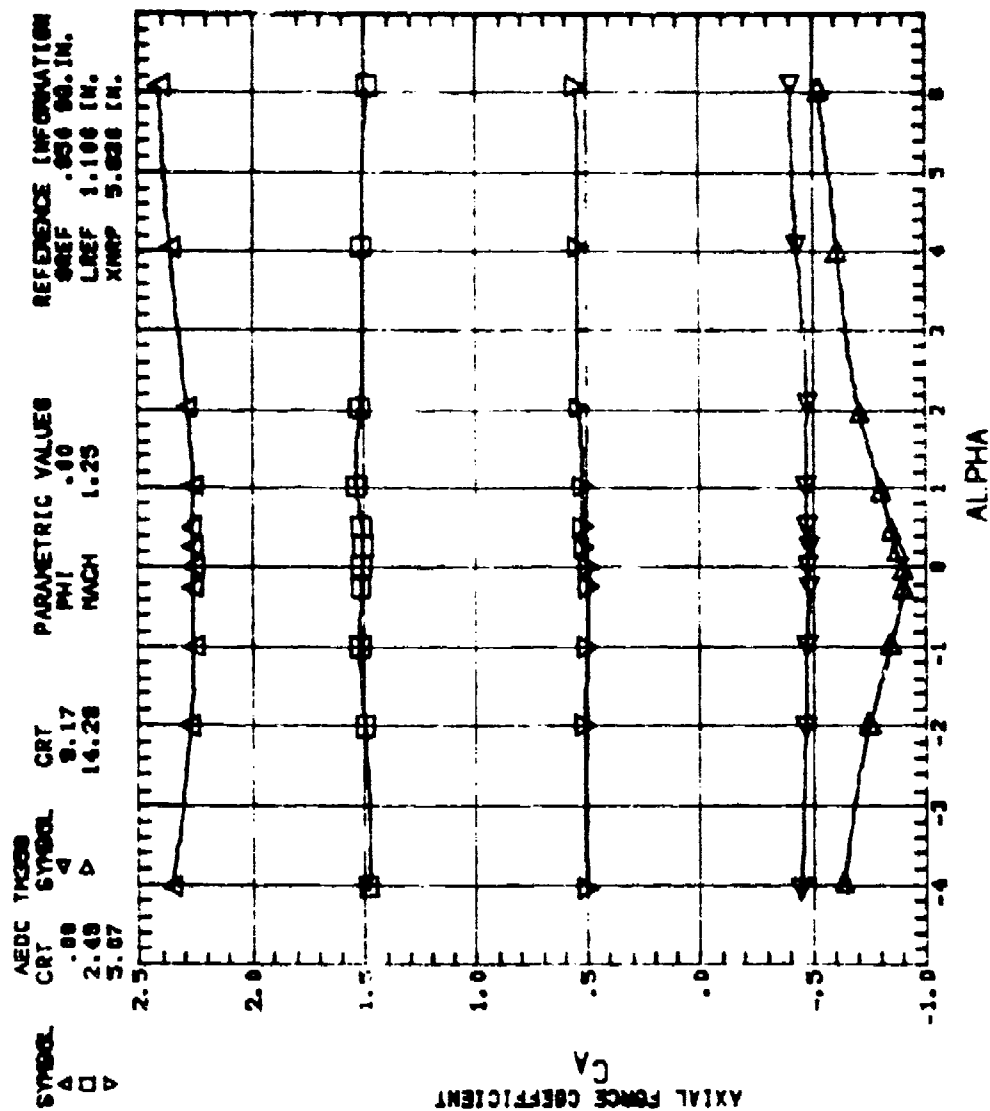


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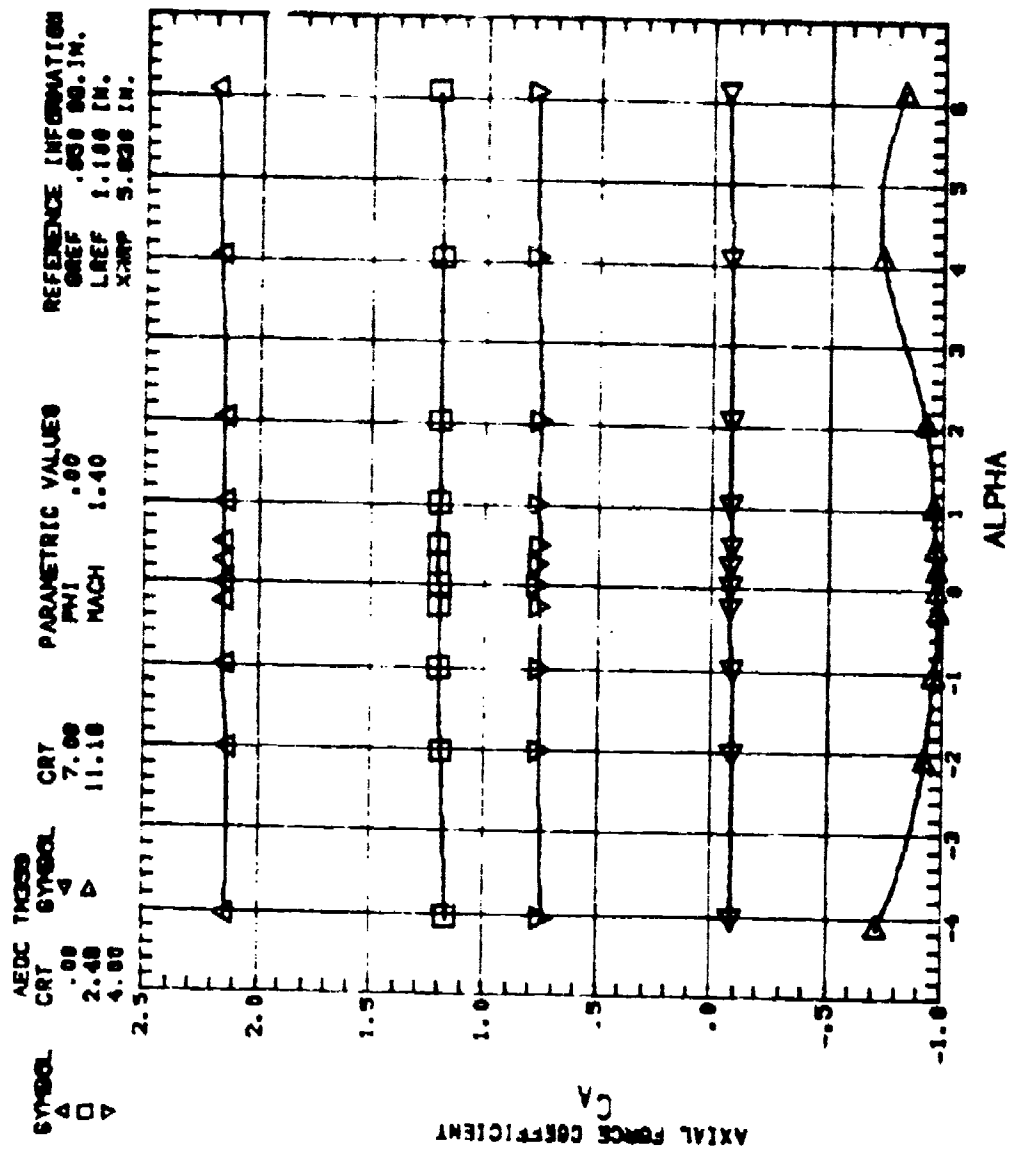


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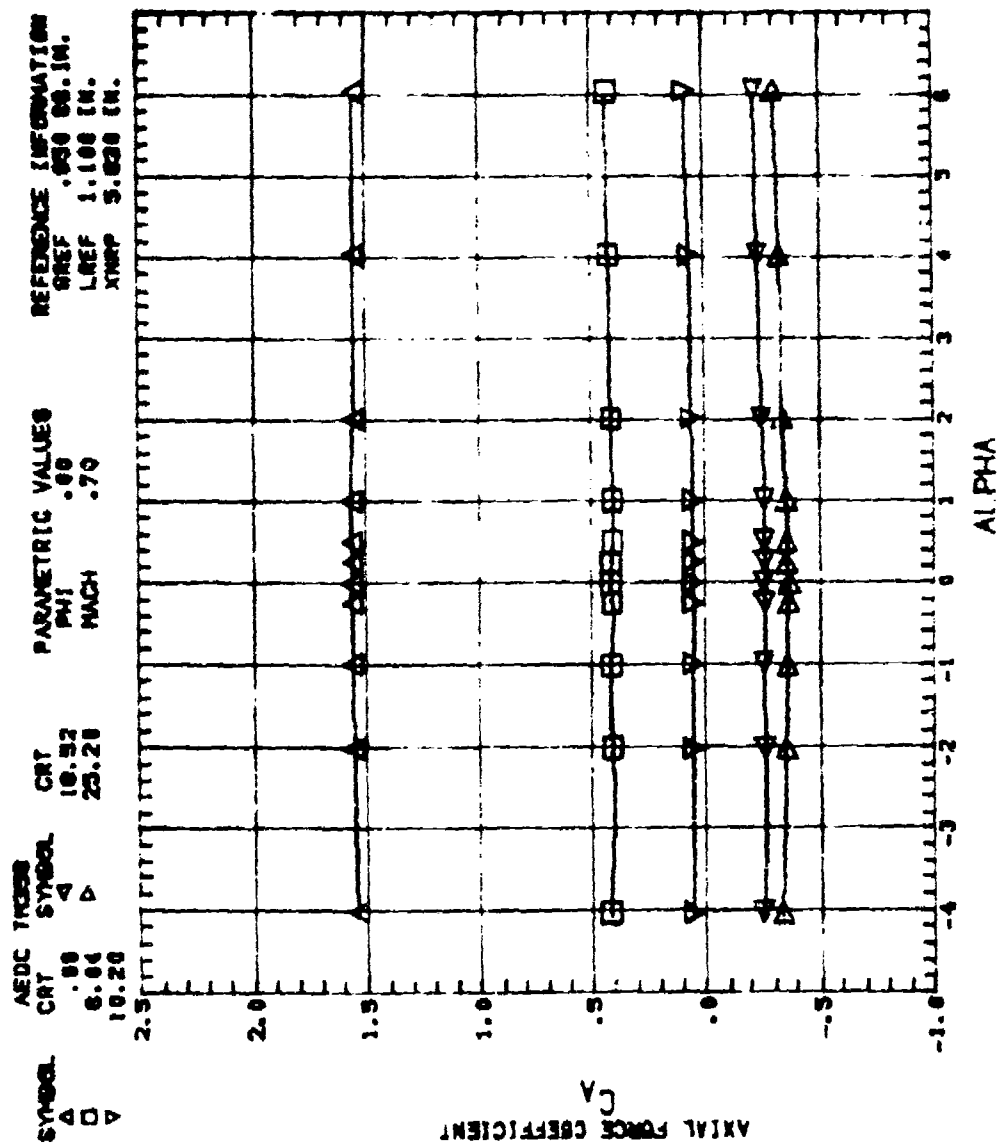


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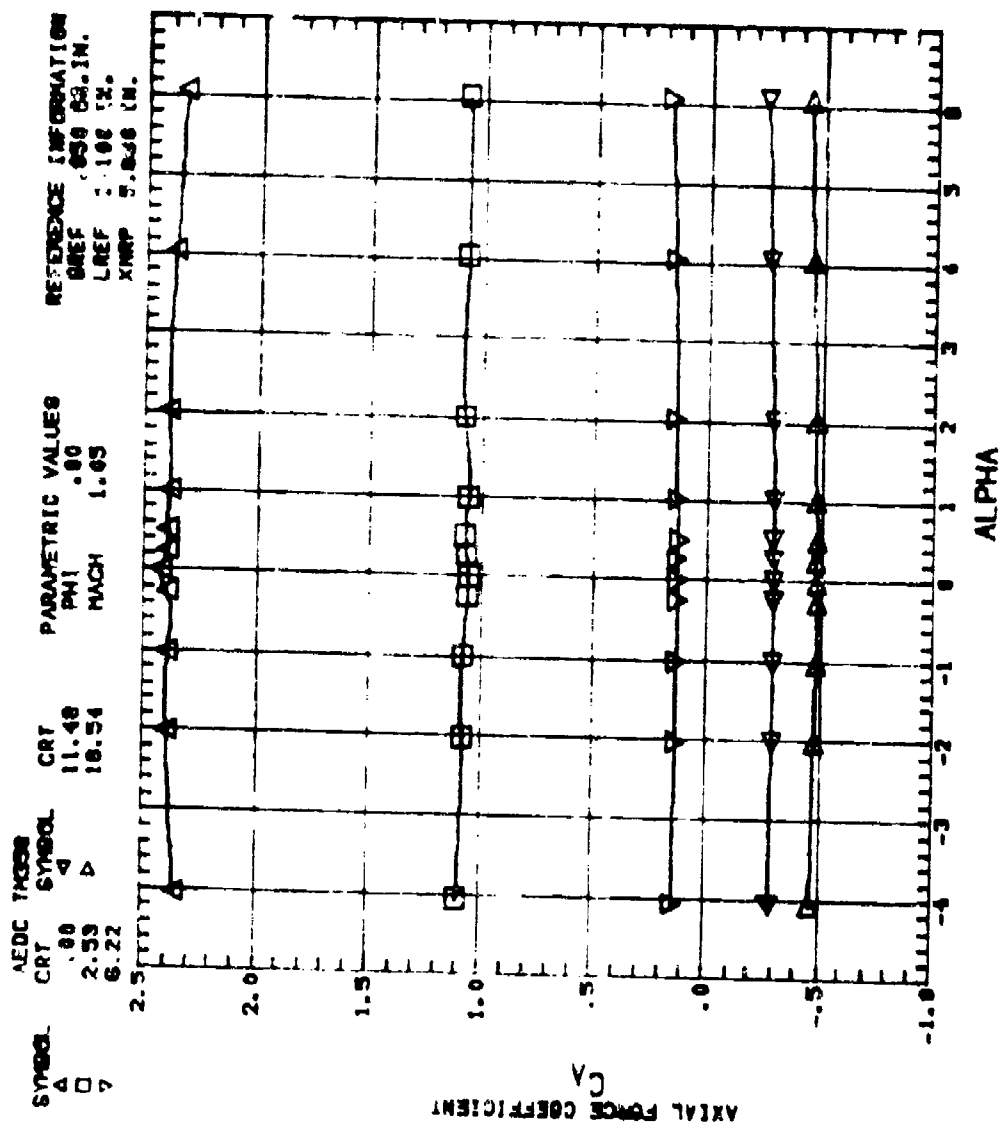


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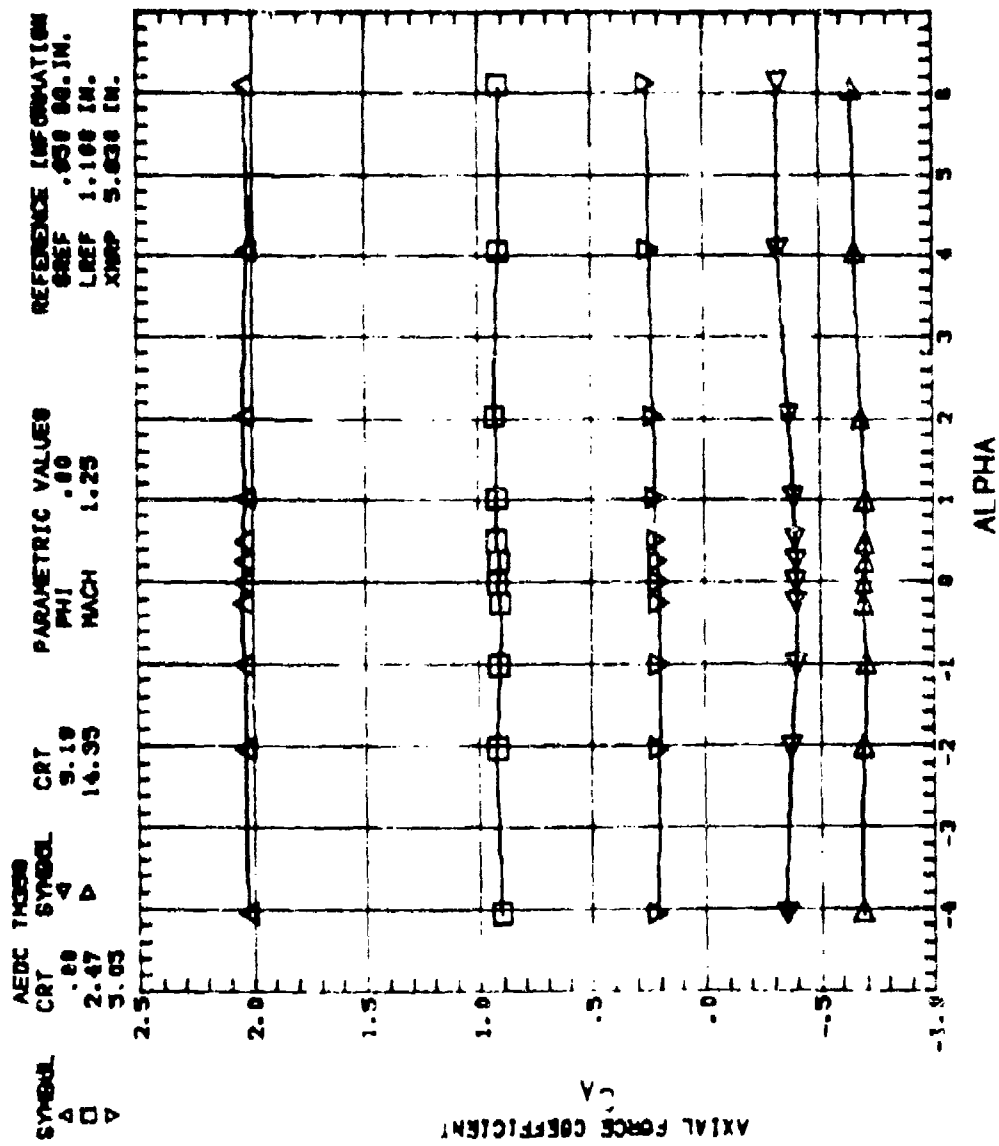


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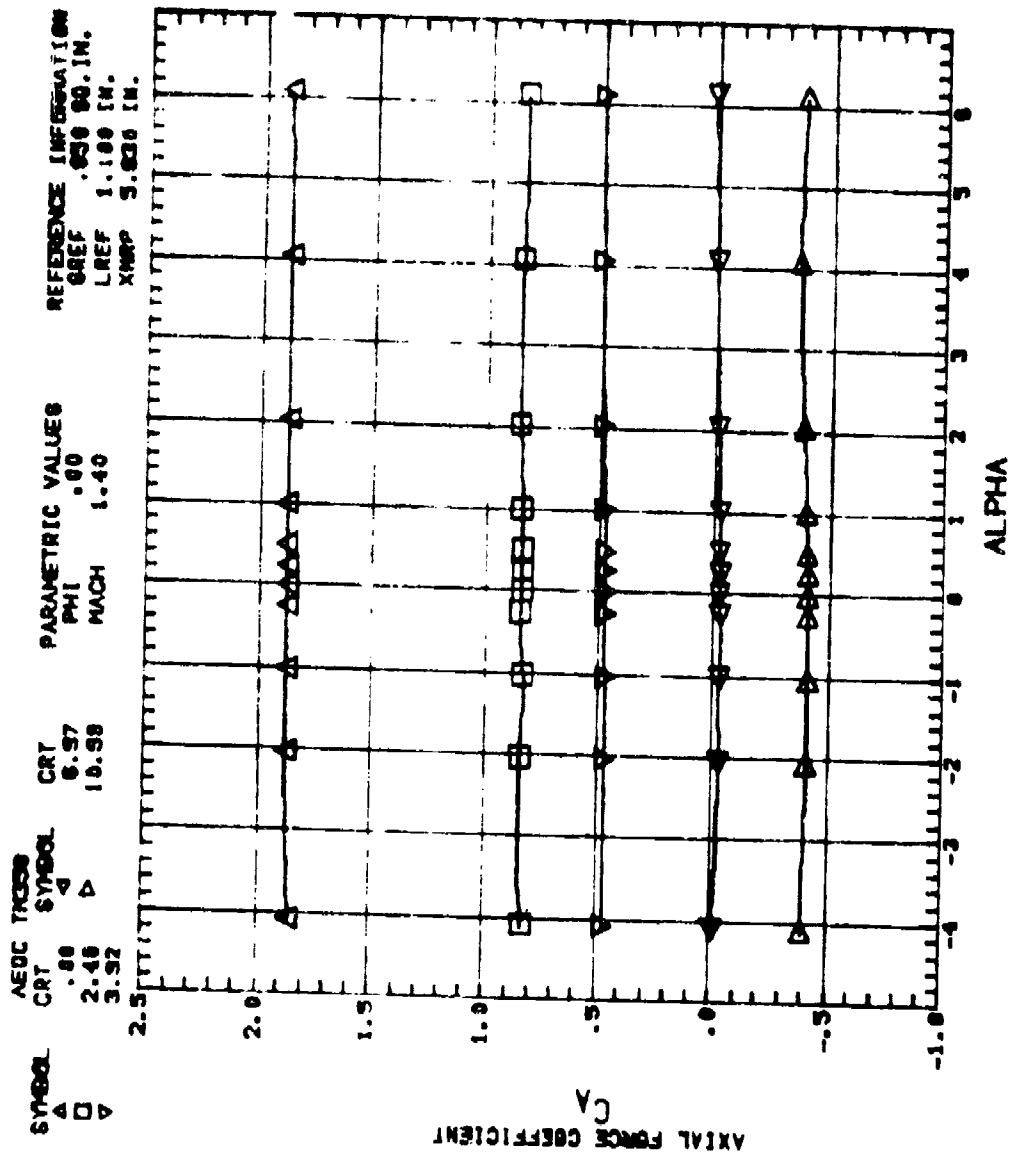


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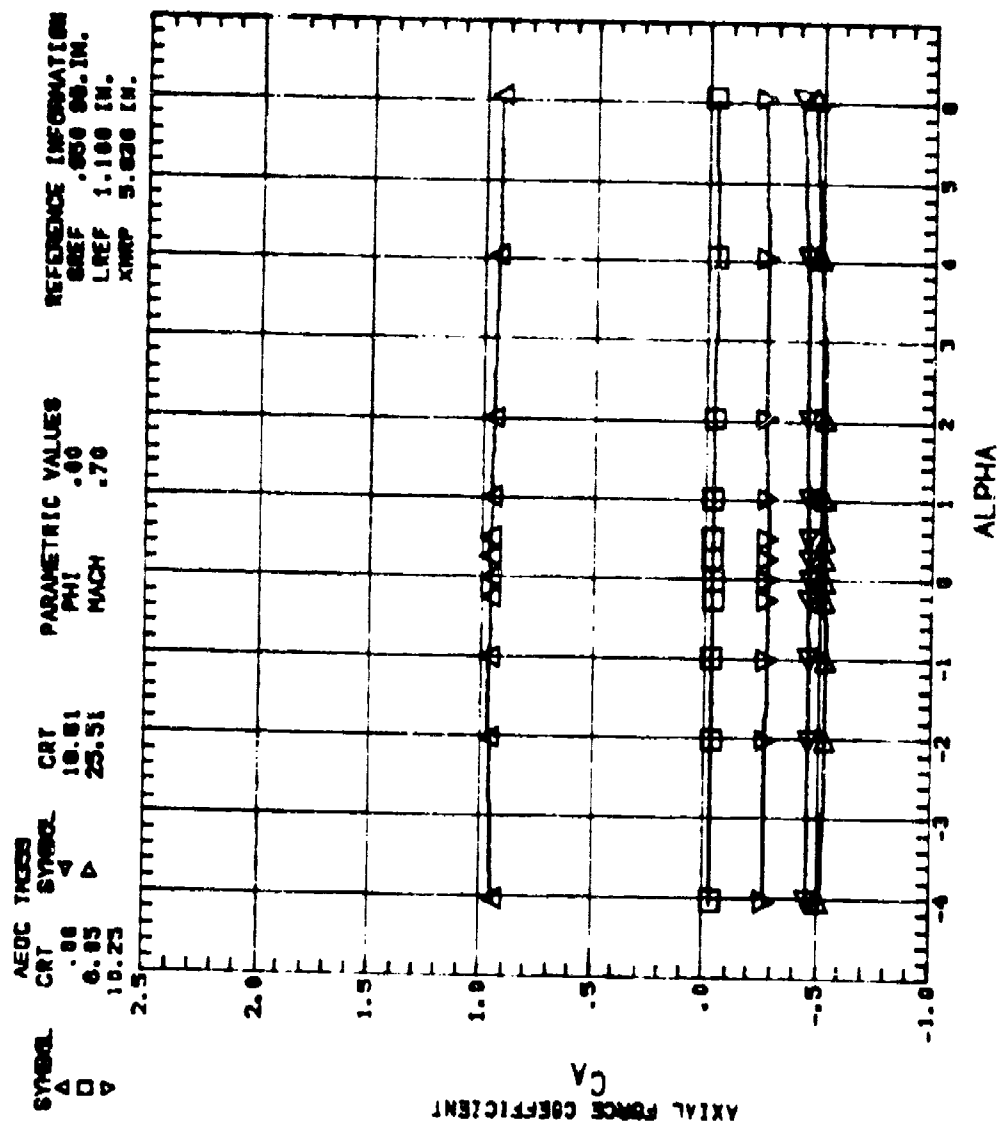


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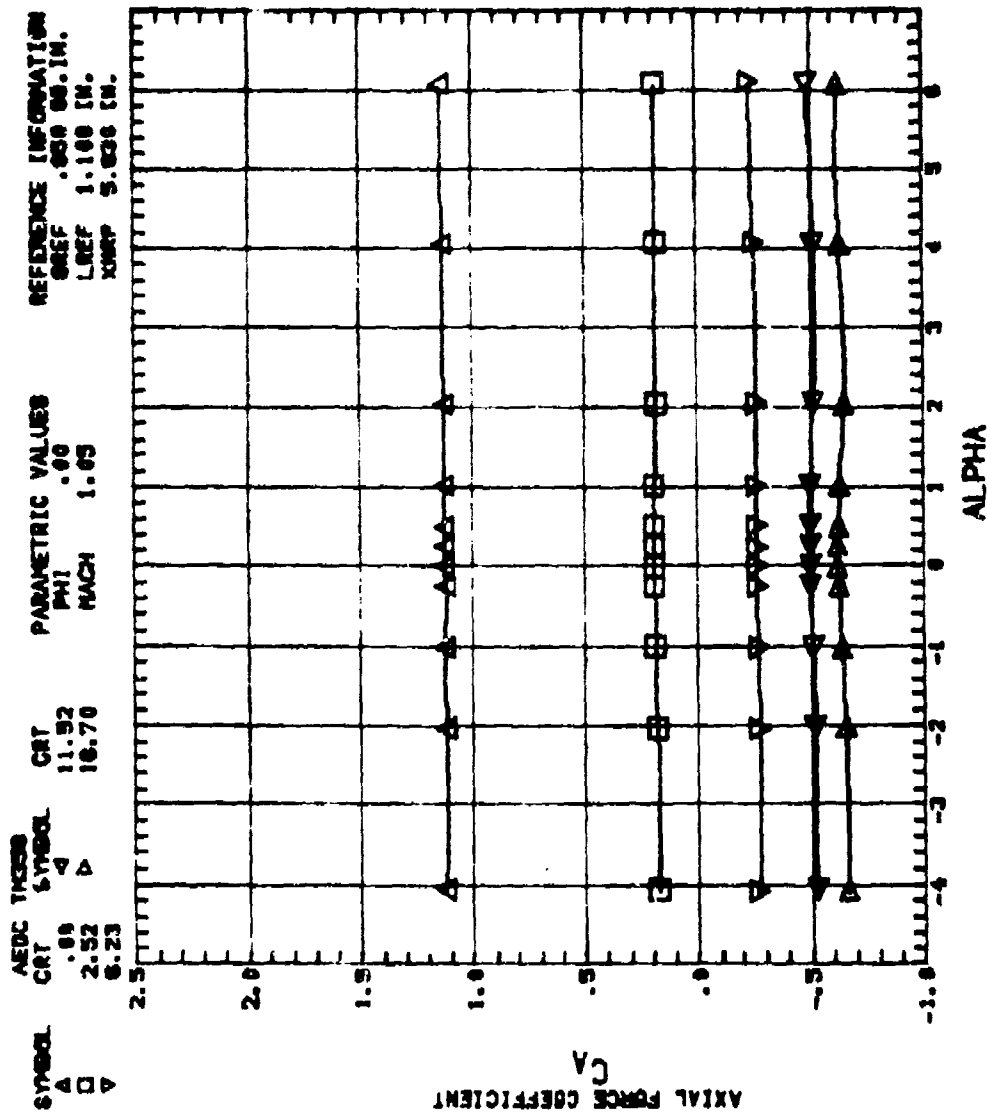


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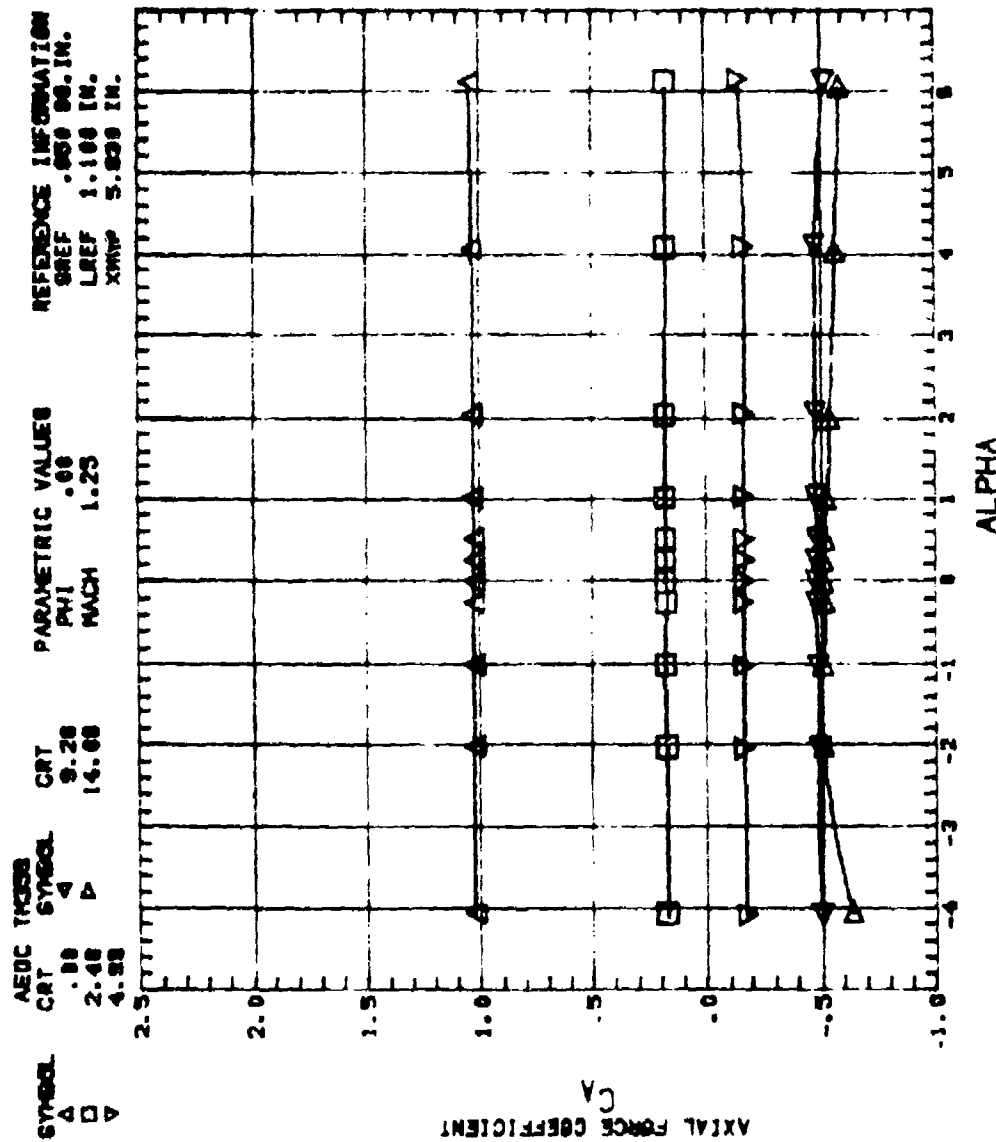


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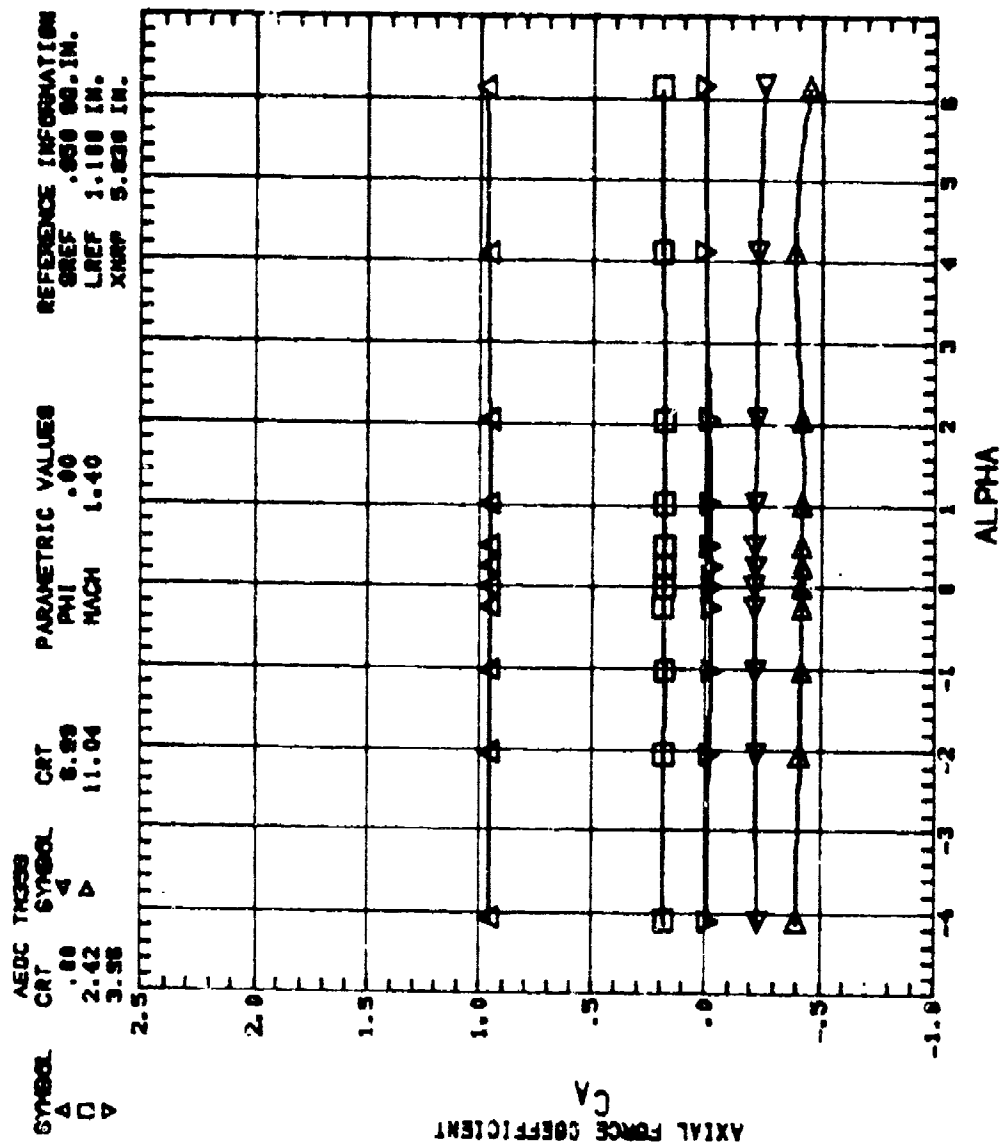
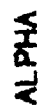
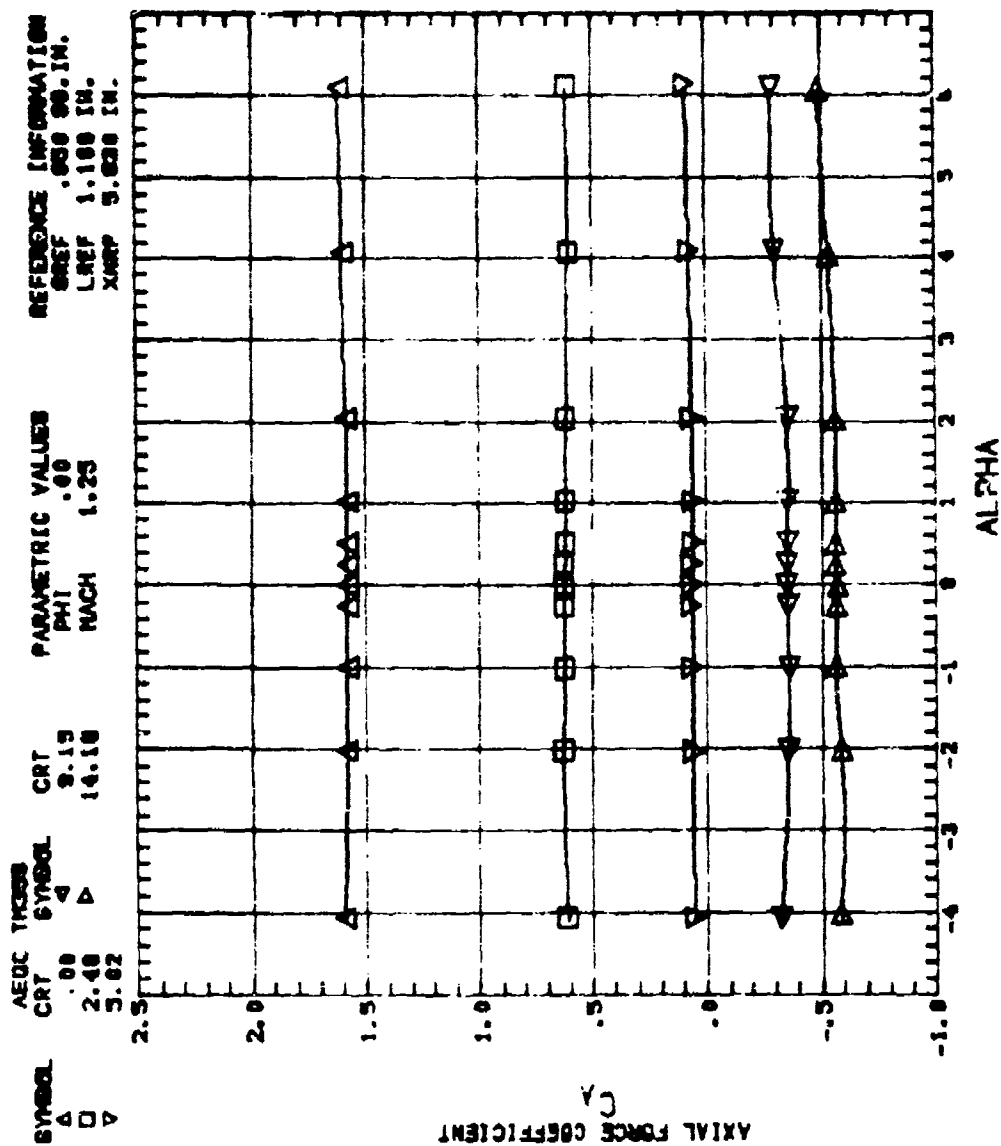


Figure 7. Continued. F12D1



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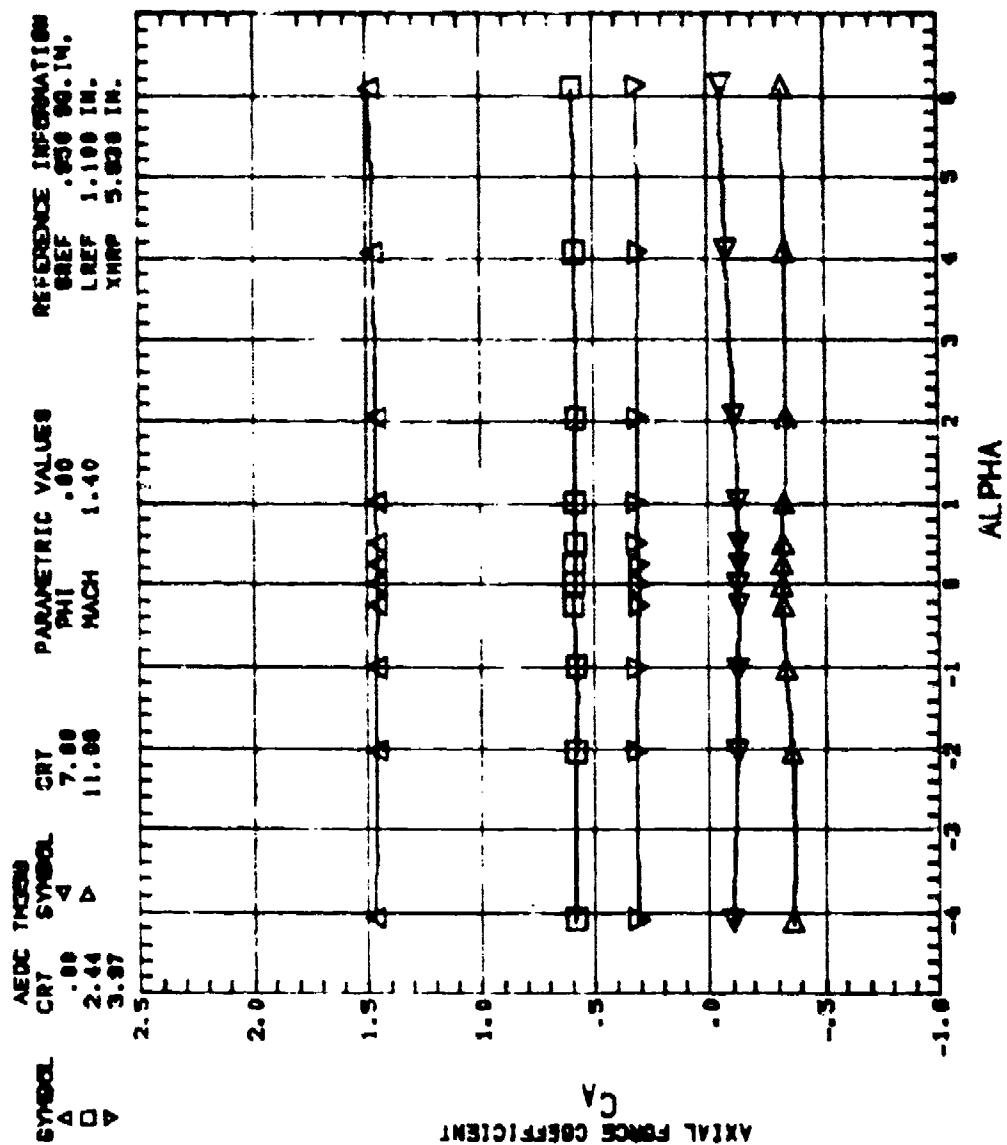


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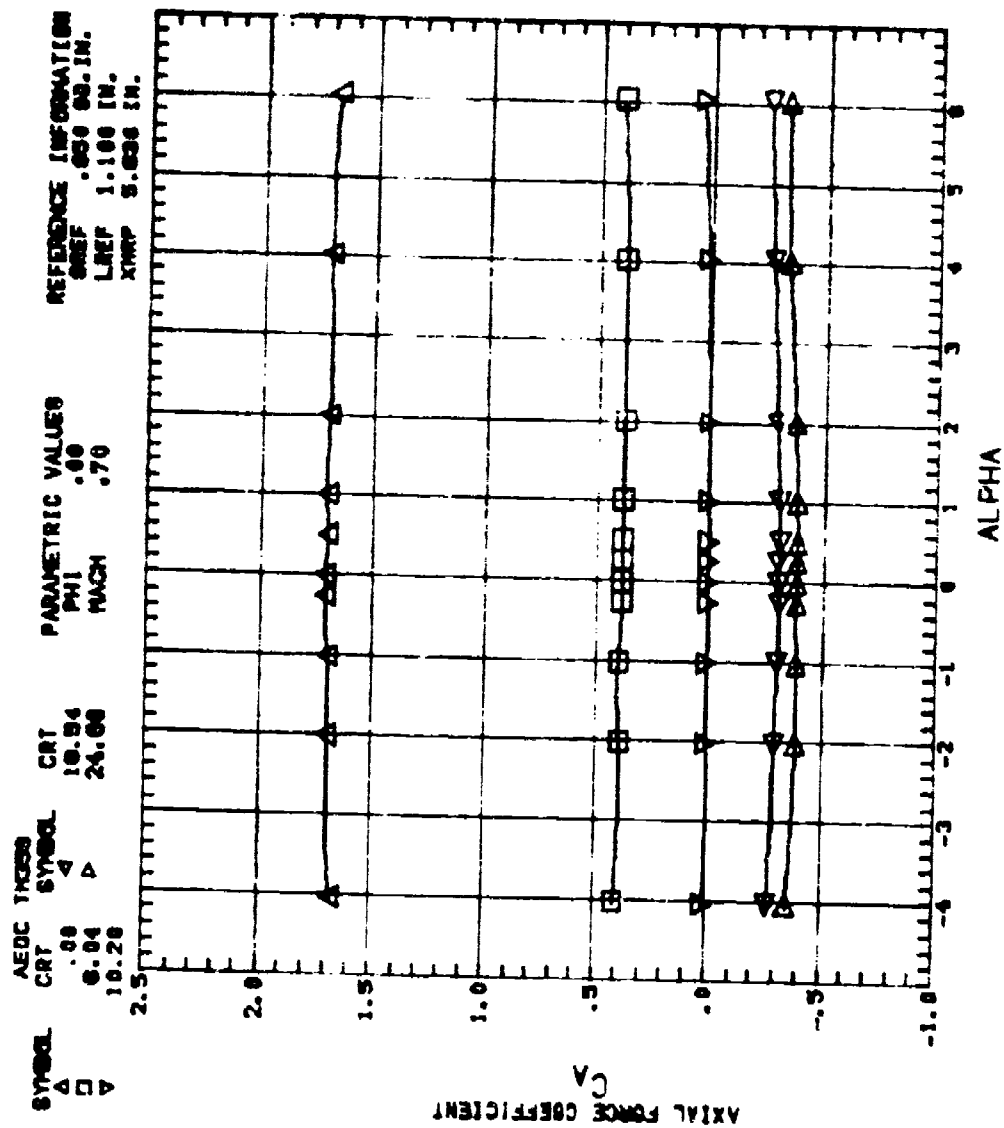


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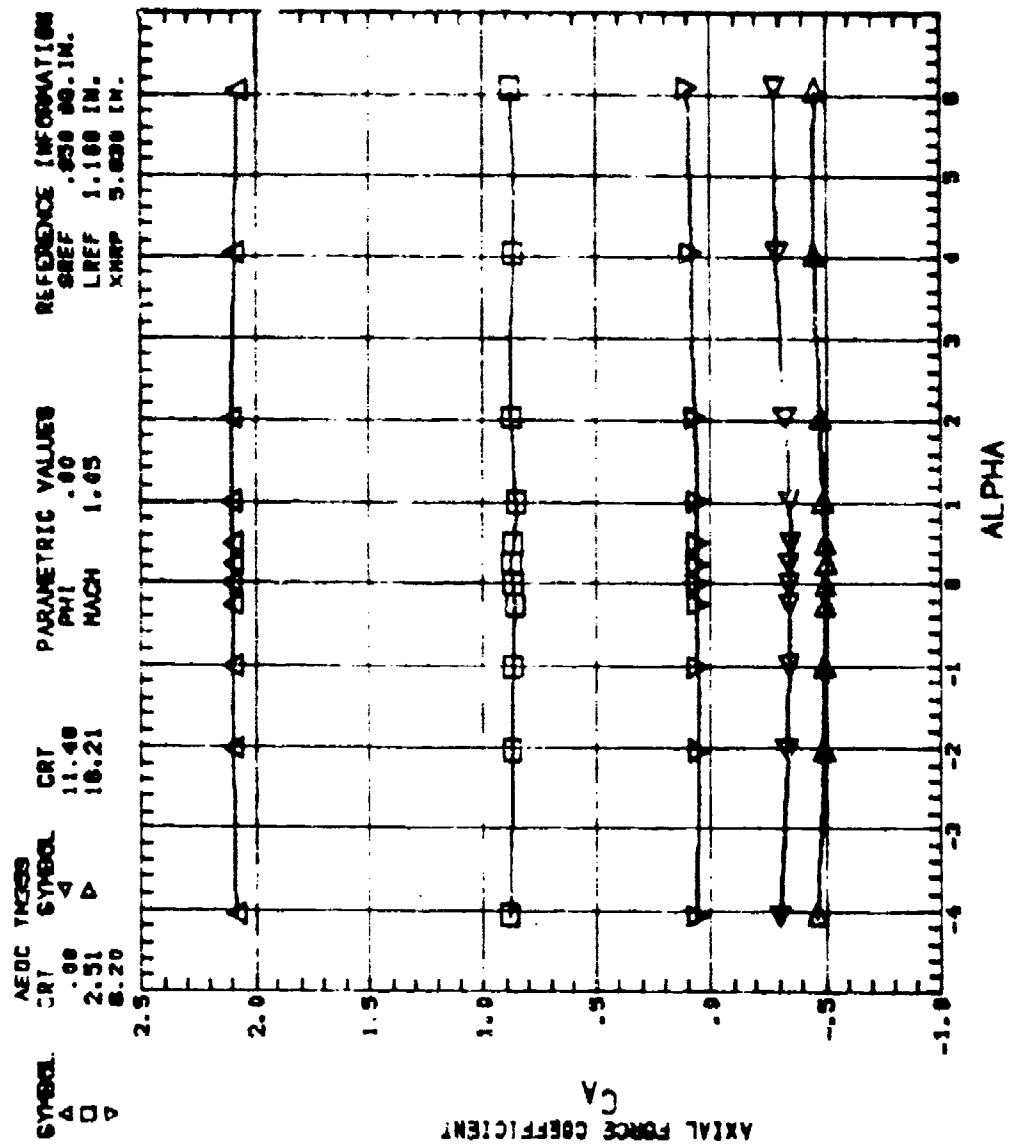
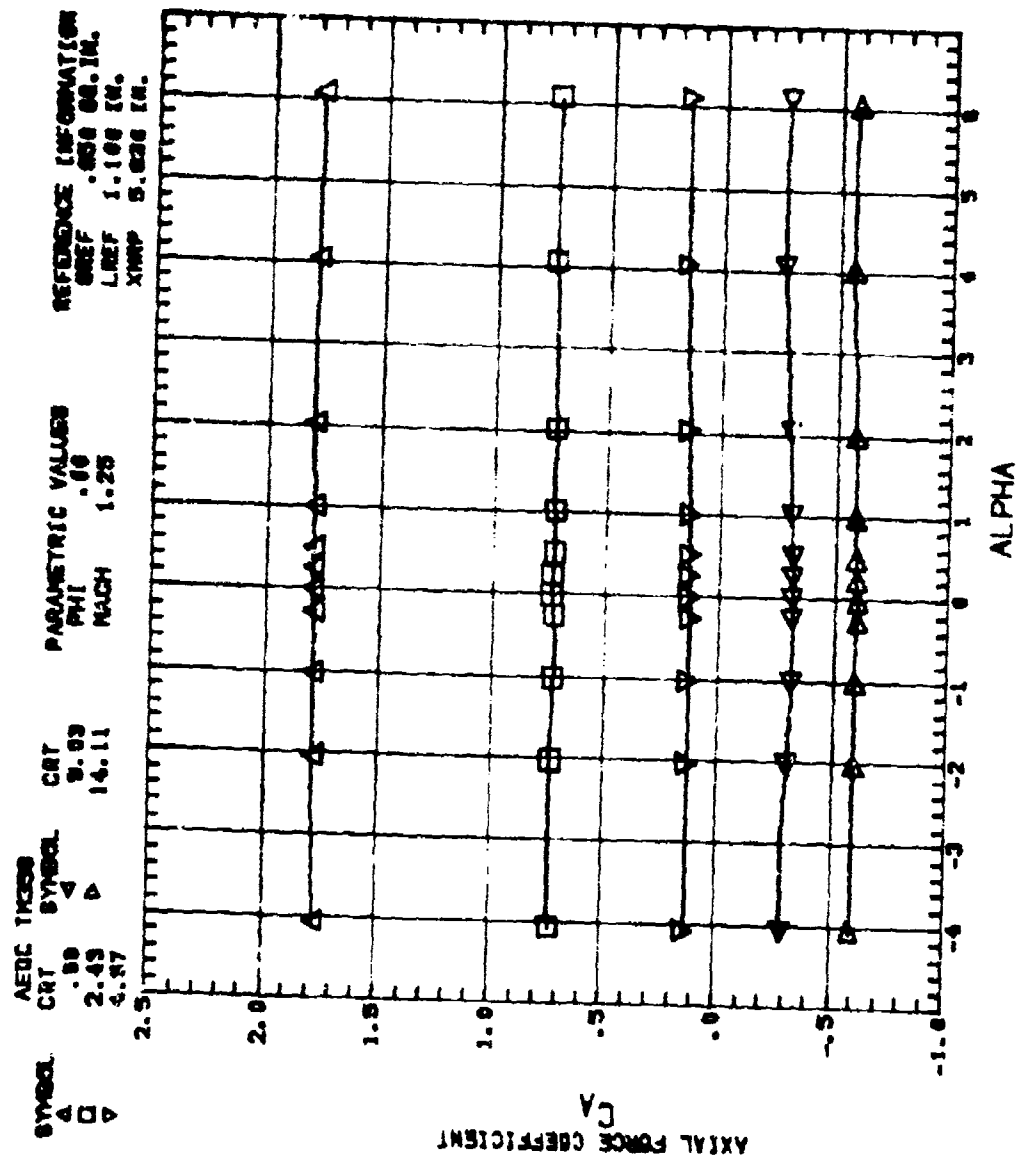


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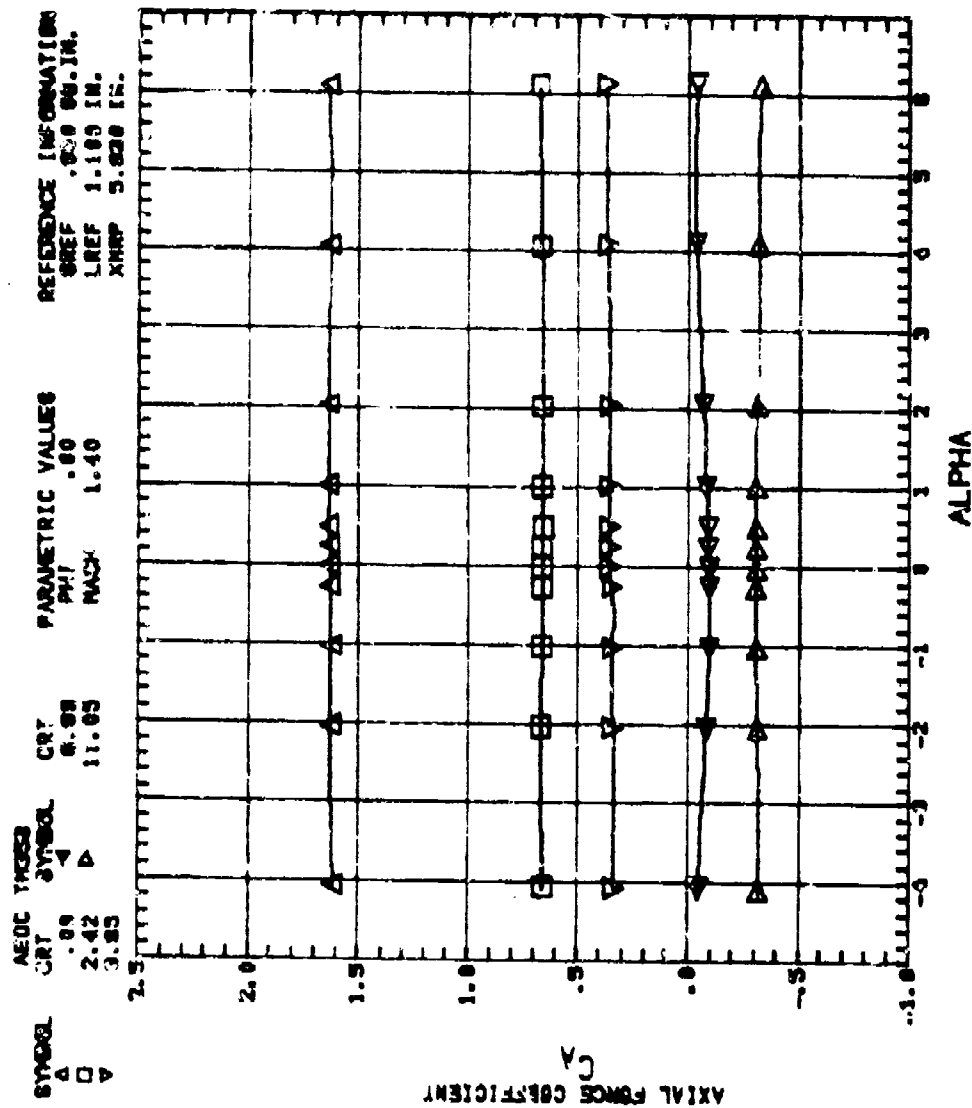


Figure 7. Continued. F6D2

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