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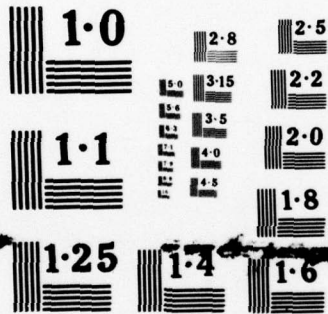
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MULTIPLE SURFACE SCATTERING FROM THE ICE COVERED ARCTIC OCEAN. (U)  
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**LEVEL** #

**MULTIPLE SURFACE SCATTERING FROM THE ICE COVERED ARCTIC OCEAN**

by

(12)

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March 1979

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ABSTRACT

The range dependent boundary condition imposed by a rough ice surface serves to couple the normal modes of an underwater acoustic field. Beginning with the parabolic wave equation, the solution is expanded in terms of normal-mode depth functions modulated by random amplitudes. A system of master equations for the quantities  $\langle a_n(r)a_n^*(r) \rangle$  is derived, where the  $a_n(r)$  are the normal-mode amplitudes, and the brackets indicate an ensemble average. The master equations determine the mean power in each mode as a function of range, describing the transfer of energy between modes. Explicit relations for the coupling coefficients are obtained in terms of the spectrum of the rough surface. Transmission loss, intensity redistribution and the approach to equipartition of energy as functions of range and depth are obtained numerically.

## I. INTRODUCTION

The problem of acoustic scattering from the rough ice cover of the Arctic Ocean has been of considerable interest for a long time because the effect is unavoidable. To the present, the multiple scattering phenomenon has not been considered with the exception of recent work by Kryazhev, et al<sup>1</sup>. The present work will be compared in detail with the Soviet work in a future report.

The present calculation makes use of the method of parabolic equations (forward scattering, long range,  $k_0 r \gg 1$ ) introduced to underwater acoustics by F. D. Tappert<sup>2</sup> to study long-range propagation. The medium we consider is the Arctic Ocean whose sound speed profile is taken to be bilinear<sup>3</sup>. The shape of the interface between the under-ice cover and the water is  $n(r)$ , where  $n(r)$  is a random ice roughness function represented by its wavenumber distribution. The integral of this wavenumber distribution is the r.m.s. under-ice amplitude squared. The form of the wavenumber distribution is motivated by previous research carried out by Hibler, et al<sup>4</sup> and is taken here to be Gaussian.

The rough surface causes the initial acoustic intensity to be redistributed as a function of depth. It is also found that the energy per mode approaches equipartition as the observation range approaches long ranges.

The reader is referred to Ref. 5 to obtain further details to the calculations shown below. It is noted here that this is a preliminary report to be followed by a report including comparison to experimental data.

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## II. Theory.

Consider a point source at point  $(0, z_0)$  in a cylindrical coordinate system, emitting an acoustic signal at angular frequency  $\omega$ . The problem is to describe the average effect of a randomly distributed rough surface on the distribution of energy within the ocean waveguide. Of particular interest is the average intensity as a function of range and depth  $I(r, z) = \langle p(r, z)p^*(r, z) \rangle$  where  $p(r, z)$  is the pressure amplitude.

We begin with the equation satisfied by the envelope modulating the cylindrical plane wave, i.e. the parabolic wave equation:

$$2ik_0 \partial \psi(r, z) / \partial r + \partial^2 \psi(r, z) / \partial z^2 + k_0^2 (n^2(z) - 1) \psi(r, z) = 0, \quad (1)$$

where the envelope function  $\psi(r, z)$  satisfies the following boundary conditions:

$$\psi(r, \eta(r)) = 0, \quad (1a)$$

$$\partial \psi(r, z) / \partial z \Big|_{z=H} = 0, \quad (1b)$$

$$\psi(0, z) = (8\pi k_0)^{-1/2} \delta(z - z_0), \quad (1c)$$

where  $\eta(r)$  represents the randomly distributed boundary between the water and under-ice surface, and  $H$  is the ocean depth.

Performing the coordinate transformation<sup>5</sup>

$$r' = r , \tag{2}$$

$$z' = z - \eta(r) ,$$

and rewriting  $\psi(r, z)$  as  $\tilde{\psi}(r', z') \exp(i\theta(r', z'))$ , Eq. (1) becomes (dropping the primes, suppressing the arguments for convenience and imposing conditions on  $\theta(r', z')$ )

$$i\partial\tilde{\psi}/\partial r + (1/2k_0)\partial^2\tilde{\psi}/\partial z^2 + (k_0/2)(n^2(z) - 1)\tilde{\psi} - k_0 z \partial^2\eta/\partial r^2 \tilde{\psi} = 0 , \tag{3}$$

$$\tilde{\psi}(r, 0) = 0 , \tag{3a}$$

$$\partial\tilde{\psi}/\partial z|_{z=H} = 0 , \tag{3b}$$

$$\tilde{\psi}(0, z) = (8\pi k_0)^{-1/2} \delta(z - \bar{z}_0) , \tag{3c}$$

where  $\bar{z}_0 = z_0 - \eta(0)$ . The random boundary condition (Eq. (1a)) becomes a "flat surface" boundary condition at the expense of introducing an additional perturbative term in the parabolic wave equation.

The envelope function,  $\tilde{\psi}$ , is expanded in terms of a complete set of "states" or normal modes, defined by the unperturbed sound-speed profile. Each normal mode is modulated by a random amplitude indicating the effect of the surface on acoustic propagation:

$$\Psi(r, z) = \sum_n a_n(r) \phi_n(z) \exp[i(\lambda_n - k_0/2)r] , \quad (4)$$

where

$$[(1/2k_0) \partial^2 / \partial z^2 + (k_0/2) n^2(z)] \phi_n(z) = \lambda_n \phi_n(z) ,$$

$$\int_0^H \phi_n(z) \phi_m(z) dz = \delta_{nm} .$$

Inserting Eq. (4) into Eq. (3) and using the orthonormality of the normal-mode depth function, one finds, upon equating the coefficients of  $\phi_n(z) \exp[i(\lambda_n - k_0/2)r]$ , that the random amplitudes satisfy the coupled mode equations,

$$da_n(r)/dr = i \sum_m c_{mn}(r) \exp(i\lambda_{mn}r) a_m(r) , \quad (5)$$

where

$$\lambda_{mn} = \lambda_m - \lambda_n ,$$

$$c_{mn}(r) = \int_0^H \phi_m(z) H(r, z) \phi_n(z) dz$$

$$= -k_0 z_{mn} \partial^2 \eta(r) / \partial r^2 ,$$

with

$$H(r, z) = -k_0 z \partial^2 \eta(r) / \partial r^2 ,$$

$$z_{mn} = z_{nm} = \int_0^H \phi_m(z) z \phi_n(z) dz ,$$

is the "dipole moment". The coupling coefficients,  $c_{mn}(r)$ , are real and symmetric. The coupling coefficients are

expressed in terms of a Fourier integral representation. Imposing the conditions that the mean amplitude of the surface roughness is zero and that correlations of coupling coefficients be spatially stationary, we obtain specific conditions on the Fourier amplitudes. Integrating Eq. (5) from  $r$  to  $r + \Delta r$ , where  $\Delta r \ll r$ , to second order in the coupling coefficients and anticipating use of the above mentioned statistical properties of the Fourier amplitudes, an approximate expression for the  $a_n(r)$  is obtained. One then constructs the average correlation amplitude between modes  $n$  and  $m$  applying the random phase approximation (this quantity appears in the average intensity):

$$\begin{aligned} A_{nm}(r) &= \langle a_n(r) a_m^*(r) \rangle = \langle |a_n(r)|^2 \rangle \delta_{nm} \\ &= A_n(r) \delta_{nm} . \end{aligned} \quad (6)$$

Using the expression for  $a_n(r)$  obtained by integrating the coupled mode equations, we obtain the master equations governing the evolution of  $A_n(r)$  as one steps out in range:

$$dA_n(r)/dr = \sum_{m \neq n} \Gamma_{nm}^s [A_m(r) - A_n(r)] , \quad (7)$$

where

$$\Gamma_{nm}^s = \Gamma_{mn}^s = 2\pi k_0^2 |Z_{nm}|^2 k^4 P_1(k) \Big|_{k=\lambda_{nm}}$$

with  $P_1(k)$  being the under-ice surface wavenumber distribution whose integral over all wavenumbers is the r.m.s. surface height squared.

Eq. (7) is amenable to physical interpretation. If mode  $n$  has the largest energy content at some range, then Eq. (7) tells us that as we step out in range, mode  $n$  will lose energy to the other modes of the system ( $dA_n/dr < 0$ ). If in the process of releasing this energy, mode  $n' \neq n$  obtains a larger share of the energy than the other modes, then a mode  $n'$  will release energy to the other modes ( $dA_{n'}/dr < 0$ ). This mixing of energy continues as one marches out in range until sufficient multiple scattering has occurred such that the energy becomes equipartitioned. In that case  $A_m(r) \rightarrow A_n(r)$  or  $dA_n(r)/dr \rightarrow 0$ . From Eq. (7), summing over all modes, one finds

$$\frac{d}{dr} \left[ \sum_n A_n(r) \right] = 0 ,$$

or

$$\sum_n A_n(r) = \text{constant} = \sum_n A_n(0) . \quad (8)$$

In view of Eq. (8) and the interpretation of Eq. (7) we conclude

$$A_n(r) \xrightarrow{r \rightarrow \infty} \frac{1}{N} \quad \text{for all } n = 1, N , \quad (8a)$$

where  $N$  is the total number of modes in the system (restricted to include all propagating modes).

Eq. (8) is a statement of energy conservation, which should be expected since we are considering initially a medium with no loss mechanisms.

### III. CALCULATIONS

We begin with the master equations

$$dA_n(r)/dr = \sum_{m \neq n} \Gamma_{nm}^S (A_m(r) - A_n(r)). \quad (9)$$

Defining

$$\Lambda_{nm} = (1 - \delta_{nm}) \Gamma_{nm}^S - \delta_{nm} \sum_{l \neq n} \Gamma_{nl}^S \quad (10)$$

where  $l$  is a dummy index, Eq. (9) can be rewritten as

$$dA_n(r)/dr = \sum_m \Lambda_{nm} A_m(r) \quad (11)$$

or in matrix notation

$$dA(r)/dr = \Lambda A(r) . \quad (11a)$$

Defining  $P$  to be the matrix whose columns are comprised of the eigenvectors of  $\Lambda$  with eigenvalues  $d$ , we define the quantity

$$B(r) = P^T A(r) . \quad (12)$$

Employing the orthogonality of  $P$  ( $P^T P = P P^T = 1$ ),

Eq. (11a) becomes

$$dB(r)/dr = D B(r) \quad (13)$$

where  $D = P^T \Lambda P$  is diagonal, the diagonal elements being

the eigenvalues of  $\Lambda$ . If we rewrite Eq. (13) as

$$dB_m(r)/dr = \sum_n D_{mn} B_n(r) \quad (13a)$$

using  $D_{mn} = -|d_m| \delta_{mn}$  (Gerschgorin's Theorem<sup>6</sup>), each element of Eq. (13a) can be solved

$$B_m(r) = \exp(-|d_m|r) B_m(0) \quad (13b)$$

Inverting the transformation Eq. (12), Eq. (13b) yields

$$A_n(r) = \sum_{k,l} P_{nk} \exp(-|d_k|r) P_{kl} A_l(0) \quad (14)$$

Calculating  $A_n(r+R)$  we find

$$A_n(r+R) = \sum_{k,l} P_{nk} \exp(-|d_k|R) P_{kl} A_l(r) \quad (15)$$

Note that Eq. (15) is an exact relation,  $R$  is not limited in magnitude. Eq. (15) describes how to advance the average correlation amplitude to range  $r+R$  knowing its value at range  $r$ . In particular, if we know the initial value of  $A_n$ , i.e.  $A_n(0)$ , we can calculate  $A_n(r)$  for any range  $r > 0$  using Eq. (15).

Numerically, in order to avoid recalculating a double summation, which is time consuming and uses unnecessary storage, we define the matrix  $C_{nl}(R)$  by

$$C_{nl}(R) = \sum_k P_{nk} \exp(-|d_k|R) P_{kl} \quad (16)$$

This matrix can be calculated once for each roughness setting and stored. Eq. (15) is recast into the form

$$A_n(r+R) = \sum_l C_{nl}(R) A_l(r) \quad (17)$$

In Eq. (17), C can be regarded as a "translation operator".

The quantity of interest here is

$$I(r,z) = \langle |p(r,z,t)|^2 \rangle = J(r,z)/r \quad (18)$$

where

$$J(r,z) = \sum_n A_n(r) \phi_n^2(z) / \sum_n A_n(r) \quad (18a)$$

$I(r,z)$  is called the average intensity and does not depend on  $t$  within the context of our model. Removing the cylindrical spreading factor,  $1/r$ ,  $J(r,z)$  shows how the rough surface affects the propagation of the acoustic signal. We make use of the initial condition to find

$$a_n(0) = ((2\pi/k_0)^{1/2}/4\pi) \phi_n(z_0) \quad (19a)$$

and thus

$$A_n(0) = (1/8\pi k_0) \phi_n^2(z_0) \quad (19b)$$

Knowing this initial condition completely determines the average intensity.

We now discuss calculation of the normal-mode depth functions,  $\phi_n(z)$ . The depth functions are calculated by a multiple shooting method. The computer code that we use was developed by L. B. Dozier<sup>7,8</sup>

applied to the ocean waveguide. Similar techniques were used before in solving one dimensional radial Schroedinger equations. Boundary conditions are imposed at  $z = 0, H$ , then the normal mode depth equations are integrated (by a Numerov scheme) from the surface into the deep ocean and simultaneously from the ocean floor upward. The integrations continue to a matching point somewhere in between. In the process of integrating a trial eigenvalue is used (it is initially estimated using a WKB approach). A comparison of the solution at the matching point is performed to properly match the upward and downward integrations. This also allows one to improve the initial guess made for the eigenvalue for that particular mode. The improvement of the eigenvalue estimate is carried out by an iterative process and continues until convergence to some preset error is reached.

The diagonalization of the matrix  $A$  and calculation of its eigenvalues are performed by subroutines developed by the Argonne National Laboratory in a program package called EISPACK. The subroutines are called TRED2 and IMTQL2. TRED2 reduces a real symmetric matrix into a symmetric tridiagonal matrix. IMTQL2 takes the tridiagonal matrix and calculates its eigenvalues and eigenvectors. It forms the orthogonal matrix  $P$  whose columns are the eigenvectors of  $A$ .

The above subroutines (TRED2 and IMTQL2) are employed in a computer code to perform the manipulations leading to the construction of  $A$  and the subsequent implementations of Eqs. (17) and (18). The results of the calculations of the normal modes are read in from an external tape.

## IV. APPLICATION TO ARCTIC ICE SCATTERING

## A. MODELS

We represent the velocity profile as bilinear:

$$\begin{aligned} c(z)/c_0 &= a + bz, \quad 0 \leq z \leq z_m \\ &= c + dz, \quad z_m \leq z \leq H, \end{aligned} \quad (20)$$

where  $a = 1$ ,  $b = 3.48765 \times 10^{-5} \text{ m}^{-1}$ ,  $c = 1.006106525$   
and  $d = 1.67741 \times 10^{-5} \text{ m}^{-1}$ ,  $z_m$  is the depth at which the two positive gradients  $b$  and  $d$  meet;  $z_m = 337.332 \text{ m}$ .  $H$  is the Arctic Ocean depth, taken to be 4 kilometers.

The multiple shooting method developed to calculate normal modes in the non-ice covered ocean has been adapted to calculate the normal modes for the bilinear profile. Because of the structure of the Arctic velocity profile, there are only RSR modes (RSRBR modes again will not be considered). Therefore the scattering will cause more rapid energy transfer among the RSR modes than in the nonpolar oceans. Thus equipartition is reached sooner as compared with nonpolar ocean scattering.

An important point to be made is that due to the nature of the bilinear profile, it is necessary to use a different initial guess for the eigenvalues from the one used for the canonical profile of the deep sound channel. To estimate the initial eigenvalue we use the fact that the gradients are very small for the bilinear profile and approximate the profile as linear. We then go through the WKB analysis for this initial guess, using the con-

nection formulas, and obtain for our guess,

$$\mu_n^{(0)} = (3b\pi/2k_0)^{2/3} (2n + 3/2)^{2/3} \quad (21)$$

A fundamental difference between Arctic ice scattering and ocean surface scattering is the surface wavenumber spectrum. We take the under-ice surface wavenumber distribution (keel distribution) to be Gaussian<sup>4</sup> with r.m.s. wave height  $\sigma$  and correlation length  $L$ :

$$P_1(k) = (\sigma^2 L / \pi^{1/2}) \exp(-k^2 L^2) \quad (22)$$

The value of  $L$  is based on experimental observation made by O. I. Diachok.<sup>9</sup> He measured the order of 10 ice ridges per kilometer. Thus we take  $L$  to be of order 100 meters.

The corresponding master equations are

$$dA_n(r)/dr = \sum_{m \neq n} \Gamma_{nm} (A_m(r) - A_n(r)) \quad (23)$$

where now

$$\Gamma_{nm}^s = \Gamma_{nm} = 2\pi (k_0^2 \sigma^2 L \lambda_{nm}^4 / \pi^{1/2}) \exp(-\lambda_{nm}^2 L^2) |z_{nm}|^2 \quad (24)$$

where  $\lambda_{nm}$  and  $z_{nm}$  have the same meaning as before.

Before going to the results, we mention the similarities and differences between our formalism and that given by Kryazhev, et al.<sup>1</sup> They assume a fixed boundary, allow for volume attenuation in the ice and bottom, formally consider 2-D transverse phenomena

and their integral "transport equation", satisfied by  $A_n(r)$ , must be calculated at every range point  $r$ . In our formalism, the surface can be moving or fixed. The moving surface application allows us to calculate long-range power spectra. We have not yet described dissipative mechanisms in our formalism, but this has in fact been done as explained below. Our formalism is much more efficient when it comes to calculating  $A_n(r)$ . Finally, they calculate a quantity called the propagation anomaly (PA) related to our transmission loss (TL) by

$$PA = TL + 20 \log (r/r_1) \quad (25)$$

where  $r_1 = 1$  yd.

Attenuation due to surface scattering has been studied by Marsh, Schulkin and Kneale<sup>10</sup>. The factor

$$\sin \theta / r_1$$

in the attenuation constant is evaluated for a limiting ray whose vertex depth is 1 km.

Since

$$\sin \theta = (1 - (C_0/C(z))^2)^{1/2}$$

and

$$C_0/C(z) = (1 + dz)^{-1}$$

with  $r_1$  being determined by ray theory

$$(r_1 = 2\theta_0/d, \theta_0 \text{ initial ray direction})$$

it is found that

$$\sin\theta/r_1 = \theta_0/r_1 = d/2 ,$$

which is independent of  $r_1$ . Thus an empirical relation expressing ice scattering per unit distance (dB/km) is obtained, which depends upon the source frequency,  $f$ , and the r.m.s. surface roughness,  $\sigma$  :

$$\beta_{MSK} = 9.3373 \times 10^{-6} f^{3/2} \sigma^{8/5} \text{ dB/km} . \quad (26)$$

For a frequency of 90 Hz with r.m.s. surface roughness of 3 meters,  $\beta_{MSK} = .0462$  dB/km. Ref. 1, Fig. 6 (curve 3) indicates that the attenuation is approximately .043 dB/km. Thus to compare the propagation anomaly of Kryazhev et al<sup>1</sup> with the present calculation we need to evaluate:

$$P.A. = TL + 20 \log_{10}(r/r_1) - 9.3373 \times 10^{-6} f^{3/2} \sigma^{8/5} r . \quad (27)$$

## B. RESULTS

Figure 1 describes the quantity  $J(r,z)$  (see Eq.(18a)) as a function of depth for two particular ranges. The function  $J(r,z)$  explicitly indicates the effect of the rough surface (through the amplitude  $A_n(r)$ ). One concludes from this figure that the rough surface serves to redistribute the initial ( $r = 0$  km) intensity distribution as one steps out to long

( $r = 200$  km) ranges. It is clear from Fig. 1 that the intensity distribution approaches uniformity in the sense that it is no longer possible to distinguish the source position relative to other depths. Figure 2 numerically verifies equipartition (Eq. (8a) ) for two particular modes, mode 1 and mode 51. Comparing the approach to equipartition in the deep ocean (Atlantic or Pacific) one notes that the approach to equipartition in the Arctic occurs at a more rapid rate. The reason is that in the Arctic Ocean all modes are RSR modes . Figure 3 displays transmission loss as a function of range for various surface roughnesses. A source with frequency 50 Hz (60 modes are calculated to include all RSR modes) is placed 267 m below the surface. The receiver is at a depth of 260 m. As the roughness of the surface increases, so does transmission loss. For a surface of r.m.s. height 10 meters there is an additional loss at 200 km from the source of 5-6 dB relative to a surface of r.m.s. height 3 meters. Comparison of our theoretical predictions with experimental observations shown by H. W. Kutschale<sup>3</sup> explicitly indicate the need to include surface and bottom loss. If Eq. (26) is employed to account for ice attenuation, then the additional transmission loss corresponding to r.m.s. height of 3 meters at 50 Hz is approximately 20 dB at 1000 km, in closer agreement with experimental observation. The remaining discrepancy can be attributed to the bottom loss not accounted for in our model.

Figure 4 compares the result of our formalism to the work done by Kryazhev, et al<sup>1</sup>. The r.m.s. roughness is 3 meters. The correlation length of the surface fluctuations is 50 meters. The source depth is 50 meters and the receiver is located 100 meters below the surface. The source frequency is 90 Hz. The solid line represents the propagation anomaly by our model. The crosses correspond to the work of Kryazhev, et al<sup>1</sup>.

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FIGURE CAPTIONS

- Figure 1. Mean intensity at two specific ranges (0, 200 km) as a function of depth, with the cylindrical spreading factor removed. The source frequency is 50 Hz, the r.m.s. roughness is 10 m., the source depth is 267 m.
- Figure 2. Verifies the approach to equipartition of energy (Eq.8a). Same frequency, source depth and r.m.s. roughness as for Figure 1.
- Figure 3. Transmission loss as a function of range for 3 r.m.s. roughnesses. Source depth 267 m., receiver depth 260 m, frequency 50 Hz.
- Figure 4. Propagation anomaly (see Eqs. 25 and 27). Source frequency is 90 Hz, source depth is 50 m. r.m.s. roughness 3 m, correlation length 50 m., receiver depth 100 m.

F= 50.0

SD= 267.0

SIG 10.0

R(KM)=0.0

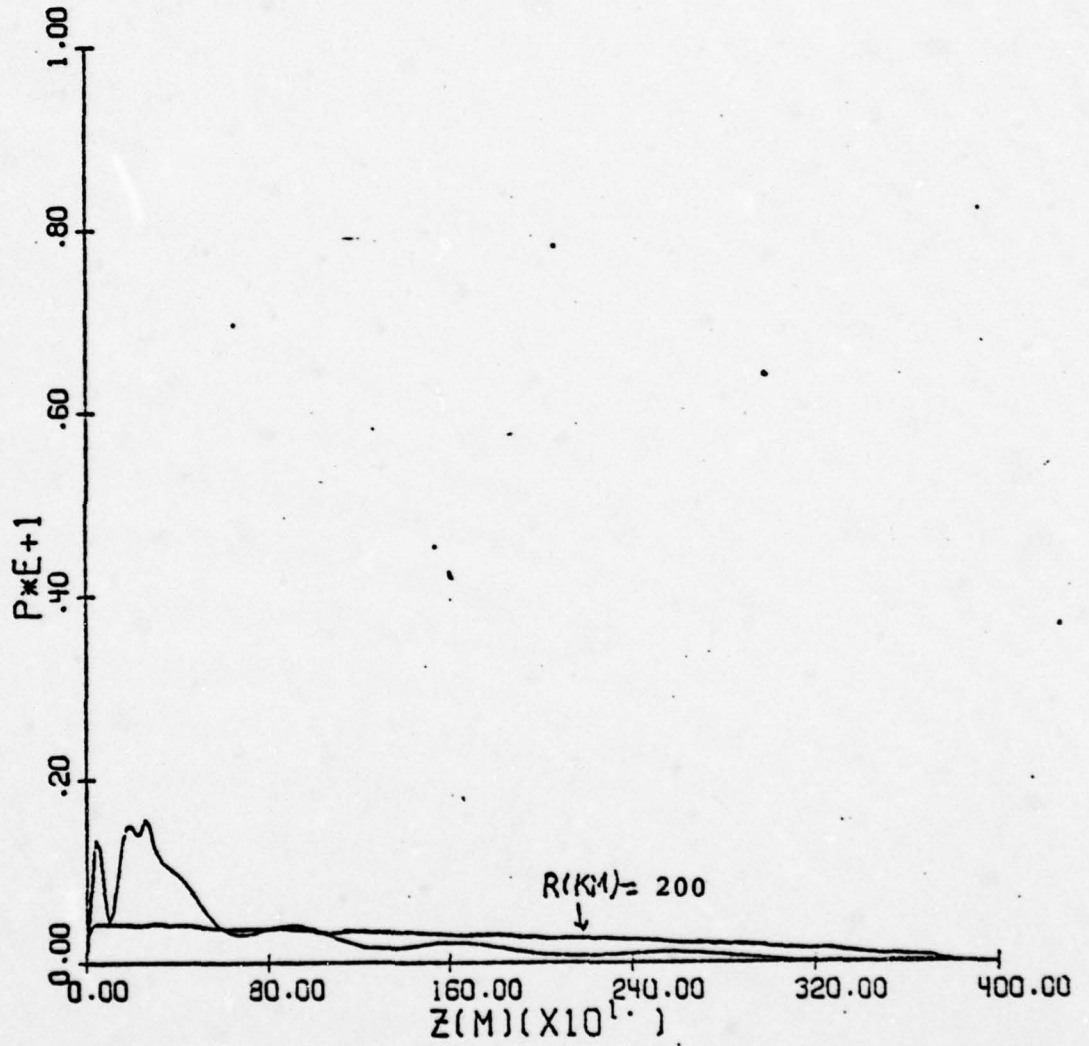


FIGURE 1

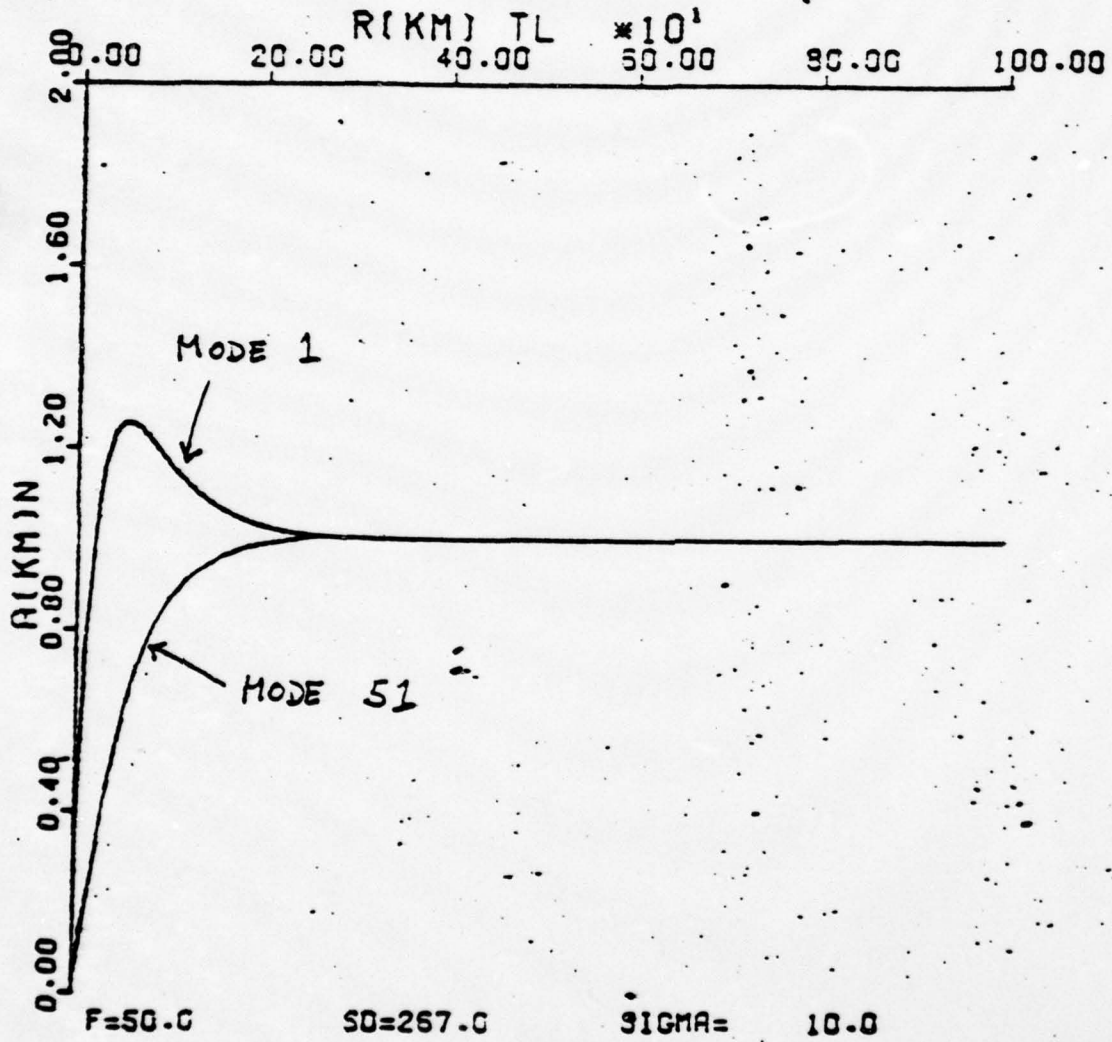


FIGURE 2

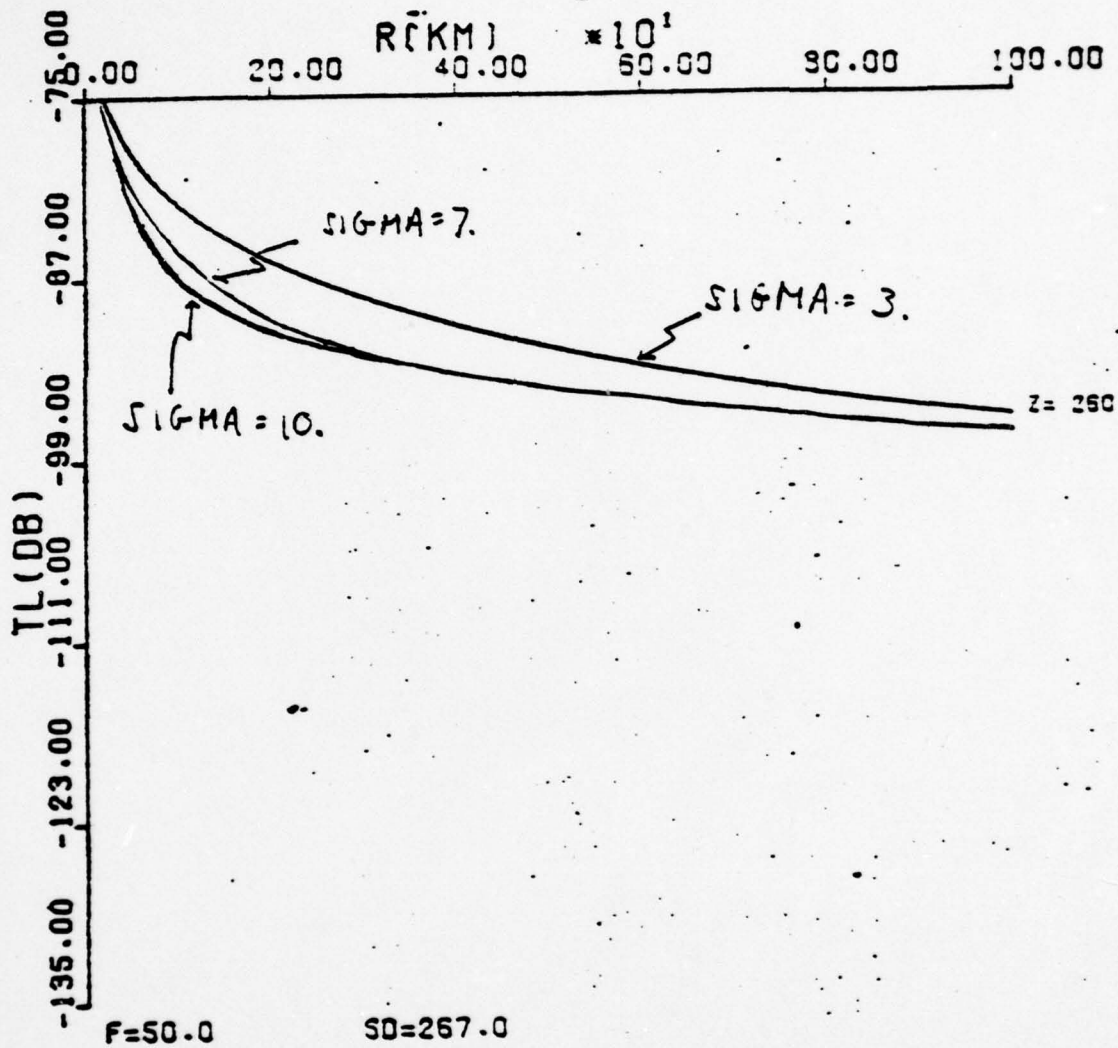


FIGURE 3

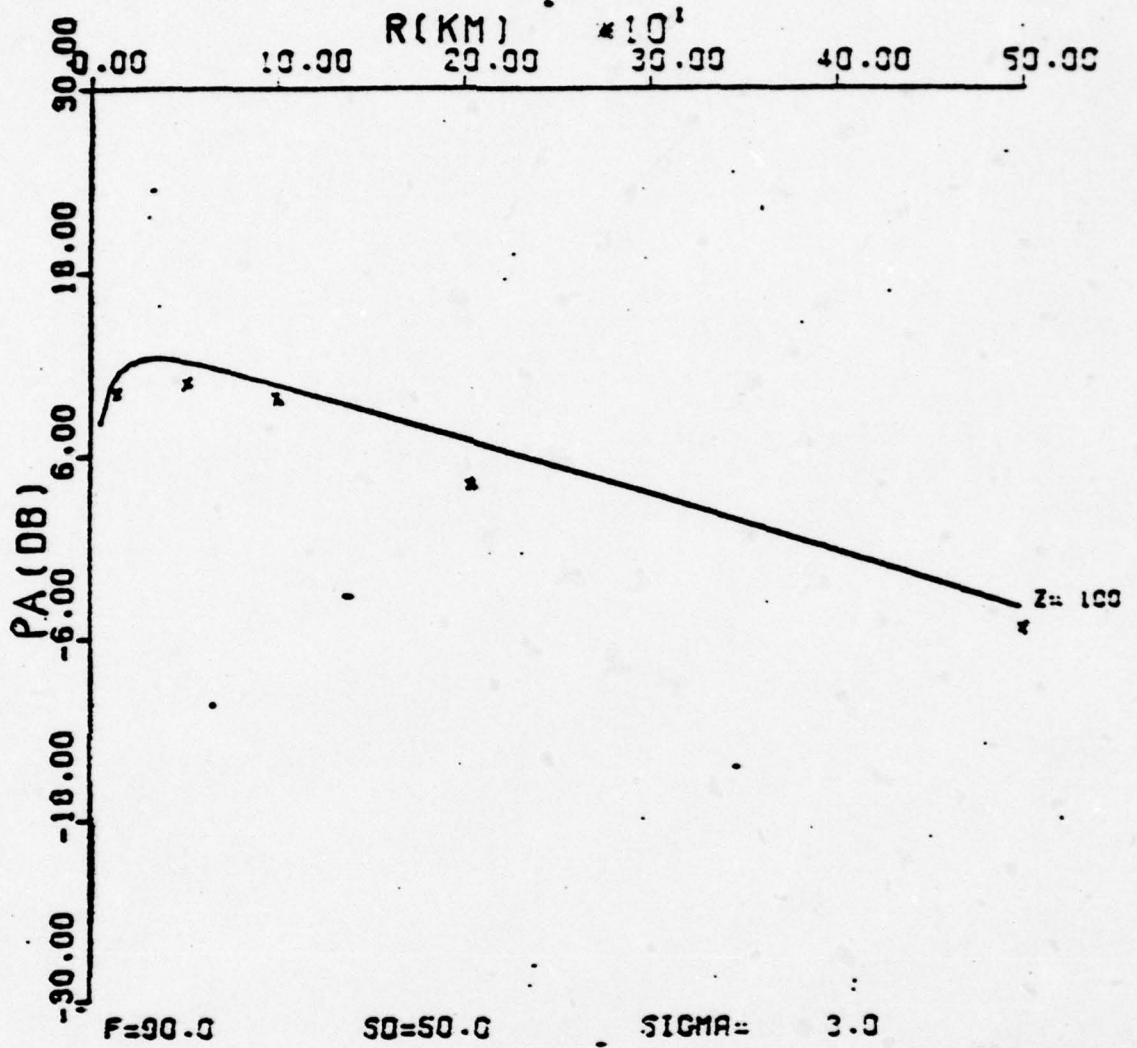


FIGURE 4

APPENDIX A  
DOCUMENTATION OF WIND  
AND PROGRAM LISTING

$$dA_n(r)/dr = \sum_{m \neq n} \Gamma_{nm}^S (A_m(r) - A_n(r))$$

GAMA

Matrix in master equations (meter)<sup>-1</sup>

P

Matrix whose columns are the eigenvectors of GAMA

DG

Elements are the eigenvalues of GAMA

XKPA

Elements are the eigenvalues corresponding to the normal-mode depth functions.

PHIN, PHIM

Normal-mode depth functions

ZZ

Depth variable, meters

AX

Amplitudes,  $A_n(r)$

POWR

Used to calculate various quantities, such as, intensity, transmission loss, equipartition, etc.

XR

Range variable in kilometers

CO

Sound speed at ocean surface, meters/sec.

NM

Number of modes

DELTR

Range increment in meters

NR

Number of points in total range (NR-1 is the number  
of divisions of total range)

SD

Source depth in meters

KO

Acoustic wavenumber, meters<sup>-1</sup> (Real)

SIGMA

r.m.s. surface roughness, meters

CL

Surface roughness correlation length, meters

FREQ

Acoustic source frequency, Hz

ALPHA

Ice attenuation constant (dB/km)

```

PROGRAM WIND(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,TAPE7,TAPE10)
THIS PROGRAM PLOTS LOG OF RATIO OF INTENSITY TO POINT
SOURCE INTENSITY AT 1 METER
PLOTS RANGE TIMES INTENSITY
PHI IS TO BE IN RADIANS
COMMON/A/FREQ,SD,SIGMA
REAL KOSQ,KO
COMMON GAMA(114,114),P(114,114),DG(114),XKPA(114),DN(114),DE(114),
IPHIN(201),PHIM(201),ZZ(201),E(114),AX(101,114),POWR(101),XR(101)
DIMENSION PHINB(114,201)
DATA H/L/8HR(KM) /,VTL/10H IL(DB) /,VTL1/7HA(KM)=N/
*,VTL2/7H P=E+1 /,RTL3/4HZ(M)/,VTL3/6HP/PMAX/,
*H/L4/3H N /,VTL4/8H-LOG/DG//
NAMELIST/VAL/SIGMA,THRESH,CL
DATA CO/1434./,PI/3.1415926535/,NM/114/,NPREV,NMM/-2.0/
DATA DELTR/1.5E+4/,NR/101/,SD/50./,BETA/1.6774E-5/
RE=IND 9
5 NPREV=NPREV+NM+2
C SKIP OVER LAST (N=VNO) RECORD OF PREV FREQUENCY
IF(NPREV.GT.0) READ(9)
READ(9)B,H,NZ,KOSQ,NMM
IF(EOF(9))77.7
7 FREQ=CO/ SQRT(KOSQ)
IF(NM.GT.NMM)GO TO 76
C SKIP OVER THE EIGENFUNCTIONS
NZI=NZ-1
KO=SQR(KOSQ)
DO 40 I=1,NMM
40 READ(9)
READ(9)(XKPA(I),I=1,NM)
DO 65 I=1,NM
65 XKPA(I)=XKPA(I)**2/(2.*KO)
UZ=N/NZI
DO 50 I=1,NZ
50 ZZ(I)=(I-1)*UZ
4 READ VAL
IF(EOF(5))77.51
51 PRINT VAL
IF(PHI.EQ.90.)PHI=ASIN(1.)
ALPHA=-9.3373E-6*FREQ**(1.5)*SIGMA**(1.6)
NMM1=NMM-1
A4=1./(1.+BETA*PHI)**3
DO 2 N=1,NMM1
RE=IND 9
IF(NPREV.LE.0) GO TO 9
DO 8 I=1,NPREV
8 READ(9)
DO 10 I=1,N
10 READ(9)
READ(9) PHIN
J1=N+1
DO 3 M=N1,NM
3 X1=XKPA(N)-XKPA(M)
A=AS(X1)
XX=X**2
READ(9)PHIM
SUM=0.5*PHIN(NZ)*PHIM(NZ)+H
SUMA=0.5*PHIN(NZ)*PHIM(NZ)*A4
DO 60 I=2,NZ1
60 A=1./(1.+BETA*ZZ(I))**3
SUMA=SUMA+PHIN(I)*PHIM(I)*A4
SUM=SUM+PHIN(I)*PHIM(I)*ZZ(I)
ZM=SUM+DZ

```

```

      ZMNI=SUMA*JZ
C      WRITE(6,1000)N,M,ZMN
C1000  FORMAT(1X,ZMN(*,I3,*,*,I3,*)**,E11.4)
      Z2=ZMN**2
      R=XX*CL**2
      IF(R.LE.1.E-8)GO TO 22
      IF(R.GE.350.)GO TO 23
      DD=EXP(-R)
      GO TO 12
22     DD=1.-R
      GO TO 12
23     DD=0.
12     GAMA(N,M)=CL*SIGMA**2*DD*Z2*(X**2*K0SQ/SORT(PI)
      GAMA(N,M)=(2.*PI)*GAMA(N,M)*(1.-(BETA*ZMNI/(XX*ZMN)))**2
      GAMA(M,N)=GAMA(N,M)
3     CONTINUE
2     CONTINUE
      DO 57 I=1,NM
      GSUM=0.
      DO 58 J=1,NM
      IF(J.EQ.I)GO TO 58
      GSUM=GSUM+GAMA(J,I)
58     CONTINUE
57     GAMA(I,I)=-GSUM
      DO 80 I=1,NM
C      80  WRITE(6,1060)(GAMA(I,J),J=1,I)
C *****CALCULATE COHERENT DECAY LENGTHS*****
      CALL PLOFSOL(275.9HA, BEILIS)
      DO 15 I=1,NM
15     DE(I)=-ALOG10(ABS(GAMA(I,I)))
      DO 16 J=1,NM
16     DN(J)=FLOAT(J)
      EMAX=DE(I)
      DO 115 I=1,NM
115    IF(DE(I).GE.EMAX)EMAX=DE(I)
      EMIN=DE(I)
      DO 116 J=1,NM
116    IF(DE(J).LE.EMIN)EMIN=DE(J)
      NH4=3
      NV4=8
      XI=PI
      CALL GFX(DN,DE,NM,DN(1),DN(NM),4.,6.,XI,
      +DE(NM),HTL4,NH4,VTL4,NV4)
      DO 17 I=1,NM
17     DE(I)=0.
      CALL FRAME
C *****
      GMAX=0.
      NMMI=NM-1
      DO 55 I=1,NMMI
      JMIN=I+1
      DO 56 J=JMIN,NM
      TEMP=ABS(GAMA(J,I))
      IF(TEMP.GT.GMAX)GMAX=TEMP
56     CONTINUE
55     CONTINUE
      WRITE(6,600)GMAX
600    FORMAT(*O GMAX=*,E11.4)
C MUST PRINT GAMA ARRAY NOW SINCE MAY BE DESTROYED BY TRED2
C      WRITE(6,1062)
C 1062  FORMAT(*OTHE LOWER TRIANGLE OF THE GAMMA MATRIX FOLLOWS*)
      DO 571 I=1,NM
      DO 581 J=1,NM
      IF(ABS(GAMA(J,I)).LT.THRESH*GMAX)GAMA(J,I)=0.
581    CONTINUE
571    CONTINUE

```

```

CALL TRED2(NM,NM,GAMA,DG,E,P)
CALL INTOL2(NM,NM,DG,E,P,IERR)
IF(IERR.NE.0)GO TO 500
WRITE(6,1059)FREQ
C1059 FORMAT(*THESE ARE THE EIGENVECTORS CORRESPONDING TO ACOUSTIC
C IFREQUENCY *,F6.2)
C DO 70 I=1,NM
C70 WRITE(6,1060)(P(J,I),J=1,NM)
1060 FORMAT(*0*,10E11.4)
WRITE(6,2223)FREQ,NM,SD
2223 FORMAT(* FREQ=*,F6.2,* # MODES=*,I4,* SDEPTH=*,F7.3)
WRITE(6,1061)
1061 FORMAT(*THE EIGENVALUES ARE *)
WRITE(6,1060)(DG(I),I=1,NM)
DO 18 I=1,NM
DE(I)=-ALOG10(ABS(DG(I)))
18 IF(I.EQ.NM)DE(I)=DE(I-1)
NH4=3
NV4=8
XI=PI
CALL GFX(DN,DE,NM,DN(1),DN(NM),4..6..XI,
*DE(NM),HTL4,NH4,VTL4,NV4)
CALL FRAME
DO 101 I=1,NM
DO 101 K=1,NM
SUMB=0.
DO 103 J=1,NM
X1=DG(J)*DELTR
IF(ABS(X1).GE.675.84)GO TO 103
Y1=P(I,J)*P(K,J)*EXP(X1)
SUMB=SUMB+Y1
103 CONTINUE
C DX IS REPLACED BY GAMA TO MIN. SPACE USED.
101 GAMA(I,K)=SUMB
C WRITE(6,1060)(GAMA(I,K),K=1,NM)
NZX=INT((SD/DZ)+1)
N=SD/DZ-FLOAT(NZX)+1.
RE=IND 9
READ(9)
SUMC=0.
DO 20 J=1,NM
READ(9)PHIN
PHINT=N*PHIN(NZX+1)+(1.-N)*PHIN(NZX)
AX(1,J)=PHIN[*2
20 SUMC=SUMC+PHINT[*2
CONST=1./SUMC
WRITE(6,3333)CONST
3333 FORMAT(* CONST=*,E11.4)
C WRITE(6,3334)AX(1,1),AX(1,50),AX(1,100)
DO 30 I=1,NM
30 AX(1,I)=AX(1,I)*CONST
C WRITE(6,3334)AX(1,1),AX(1,50),AX(1,100)
C3334 FORMAT(* AX(1,1,50,100)=*,3E11.4)
DO 82 L=2,NR
LMI=L-1
DO 81 I=1,NM
SUMA=0.
DO 83 K=1,NM
83 SUMA=SUMA+GAMA(I,K)*AX(LMI,K)
AX(L,I)=SUMA
C IF(MOD(L,10).EQ.1)WRITE(6,2222)LMI,I,AX(L,I)
C222 FORMAT(* AX(*,I4,*,*,I4,*)=*,E11.4)
81 CONTINUE
82 CONTINUE
C DO 701 L=2,NR
C ENCUN=0.

```

```

C      DO 711 I=1,NM
C711  ENCON=ENCON+AX(L,I)
C701  WRITE(6,9999)ENCON,L
C9999  FORMAT(* ENCON=*,E11.4,* RANGE=40TIMES*,I4,*KM*)
      DO 605 J=1,NR
605    XR(J)=FLOAT(J-1)*DELTR/1.E+3
      NH=8
      RE=IND 9
      READ(9)
      DO 27 N=1,NM
27     READ(9)(PHINB(N,I),I=1,NZ)
      XA=2.*ALOG10(12./13.)
      XB1=ALOG10(2.*I/(K0*CONST))
      DO 501 M=1,6
      DOD=100.*FLOAT(M-1)+100.
      NZY=INT(DOD/DZ)+1
      N1=DOD/DZ-FLOAT(NZY)+1.
      SUMP1=0.
      DO 817 N=1,NM
      PHINA=N1*PHINB(N,NZY+1)+(1.-N1)*PHINB(N,NZY)
817    SUMP1=SUMP1+AX(1,N)*PHINA**2
      POWR(1)=SUMP1
C      WRITE(6,503)POWR(1)
C503  FORMAT(* POWER(1,2)=*,E11.4)
      POWR(1)=10.*(ALOG10(POWR(1)*13./12.))+XA+XB1
      WRITE(6,98)POWR(1)
98    FORMAT(I4,*LOG(I/S)(1)=*,E11.4)
      IF(ABS(POWR(1)).LT.80.)POWR(1)=-80.
      IF(ABS(POWR(1)).GT.130.)POWR(1)=-130.
      DO 63 I=2,NR
      SUMP=0.
      DO 307 N=1,NM
      PHINX=N1*PHINB(N,NZY+1)+(1.-N1)*PHINB(N,NZY)
807    SUMP=SUMP+AX(I,N)*PHINX**2
      POWR(I)=SUMP
      POWR(I)=10.*(ALOG10(SUMP/(XR(I)*1.E+3))+XA+XB1)
C      POWR(I)=POWR(I)+ALPHA*XR(I)
C      POWR(I)=POWR(I)+20.*ALOG10(XR(I)*1.E+3*13./12.)
      WRITE(6,99)I,POWR(I)
99    FORMAT(I4,*LOG(I/S)(*,I4,*)=*,E11.4)
      IF(ABS(POWR(I)).GT.80.)POWR(I)=-80.
      IF(ABS(POWR(I)).GT.130.)POWR(I)=-130.
C      IF(ABS(POWR(I)).GT.15.)POWR(I)=15.
C      WRITE(6,2323)I,DOD,SUMP,POWR(I)
C2323  FORMAT(* P(*,I2,*,*,F7.2,*)=*,E11.4,* LOG(P)=*,E11.4)
63    CONTINUE
C      YMAX=0.
C      DO 827 I=1,NR
C827  IF(POWR(I).GE.YMAX)YMAX=POWR(I)
C      YMIN=YMAX
C      DO 837 I=1,NR
C837  IF(POWR(I).LT.YMIN)YMIN=POWR(I)
      IF(A.GT.1)NH=-8
      XQ=J.3
      XMQ=0.
      CALL YFX(XR,POWR,NR,XR(1),XR(NR),-130.,-80.,HTL,NH,VTL,10,M,XQ,
      *XMQ)
501  CONTINUE
      CALL FRAME
      NH=8
      DO 601 M=1,6
      DOD=100.*FLOAT(M-1)+100.
      NZY=INT(DOD/DZ)+1
      N1=DOD/DZ+1.-FLOAT(NZY)
      SUMP1=0.
      DO 917 N=1,NM

```

```

PHINA=N*PHINB(N,NZY+1)+(1.-N)*PHINB(N,NZY)
917 SUMP=SUMP+AX(I,N)*PHINA**2
POWR(I)=SUMP*1.E+2
C WRITE(6,603)DOO,POWR(I)
C603 FORMAT(* P(I,*,F7.2,*)=*,E11.4)
DO 73 I=2,NR
SUMP=0.
DO 907 N=1,NA
PHINX=N*PHINB(N,NZY+1)+(1.-N)*PHINB(N,NZY)
907 SUMP=SUMP+AX(I,N)*PHINX**2
POWR(I)=SUMP*1.E+2
C WRITE(6,4343)I,DOO,SUMP
C4343 FORMAT(* P(*,I3,*,*,F7.2,*)=*,E11.4)
73 CONTINUE
C YMA=0.
C DO 847 I=1,NR
C847 IF(POWR(I).GT.YMX)YMX=POWR(I)
C WRITE(6,4000)YMX
C4000 FORMAT(* P4AX=*,E11.4)
C DO 857 I=1,NR
C857 POWR(I)=POWR(I)/YMX
IF(A.GT.1)NH=-8
XQ=6.5
XMQ=0.
CALL YFX(XR,POWR,NR,XR(1),XR(NR),0.,1.,HTL,NH,VTL2,7,M,XQ,XMQ)
601 CONTINUE
CALL FRAME
XMQ=1.
DOO=500.
NZY=INT(DOO/DZ)+1.
NX=DOO/DZ+1.-FLOAT(NZY)
DO 791 N=1,NA,15
NH=8
C PHINX=N*PHINB(N,NZY+1)+(1.-N)*PHINB(N,NZY)
DO 792 I=1,NR
POWR(I)=AX(I,N)*FLOAT(NM)
IF(POWR(I).GT.2.)WRITE(6,26)I,N,POWR(I)
26 FORMAT(I X,*,POWR(*,I3,*,*,I3,*)=*,E11.4)
792 IF(POWR(I).GT.2.)POWR(I)=2.
CALL YFX(XR,POWR,NR,XR(1),XR(NR),0.,2.,HTL,NH,VTL1,7,N,XQ,XMQ)
791 CALL FRAME
DO 793 I=1,NR,10
XI=FLOAT(I-1)*DELTR/1.E+3
IX=XI
IF(I.EQ.NR)GO TO 666
IF(IX.GT.450.AND.(MOD(IX,300).NE.0))GO TO 793
666 DO 794 J=1,NZ
SUMX=0.
DO 795 N=1,NA
795 SUMX=SUMX+AX(I,N)*PHINB(N,J)**2
794 PHIN(J)=SUMX
YMIK=0.
DO 89 J=1,NZ
89 IF(PHIN(J).GE.YMIK)YMIK=PHIN(J)
DO 91 J=1,NZ
91 PHIN(J)=PHIN(J)*1.E+2
NH3=4
NV3=6
CALL GFX(ZZ,PHIN,NZ,ZZ(1),ZZ(NZ),0.,1.,XI,YMIK,
+HTL3,NH3,VTL2,NV3)
CALL FRAME
793 CONTINUE
CALL PLOT(0.0,0.0,999)
GO TO 4
500 WRITE(6,1050)IERR
1050 FORMAT(*OIRR= *,I20)

```

```

IERR=IERR-1
IF(IERR.GE.1.AND.IERR.LT.251)WRITE(6,1060)(DG(I),I=1,IERR)
GO TO 5
76 WRITE(6,1080)NMM
1080 FORMAT(*OERROR,ONLY*,I5,*MODES ON DISK*)
77 STOP
END
C
SUBROUTINE IATOL2(NM,N,D,E,Z,IERR)
INIEGER I,J,K,L,M,N,II,NM,MML,IERR
REAL D(N),E(N),Z(NM,N)
REAL B,C,F,G,P,R,S,MACHEP
MACHEP = 2.**(-47)
C
IERR = 0
IF (N .EQ. 1) GO TO 1001
C
DO 100 I = 2, N
100 E(I-1) = E(I)
C
E(N) = 0.0
C
DO 240 L = 1, N
J = 0
C
***** LOOK FOR SMALL SUB-DIAGONAL ELEMENT *****
105 DO 110 M = L, N
IF (M .EQ. N) GO TO 120
IF (ABS(E(M)) .LE. MACHEP * (ABS(D(M)) + ABS(D(M+1))))
GO TO 120
110 CONTINUE
C
120 P = D(L)
IF (M .EQ. L) GO TO 240
IF (J .EQ. 30) GO TO 1000
J = J + 1
C
***** FORM SHIFT *****
G = (D(L+1) - P) / (2.0 * E(L))
R = SQRT(G*G+1.0)
G = D(M) - P + E(L) / (G + SIGN(R,G))
S = 1.0
C = 1.0
P = 0.0
MML = M - L
C
***** FOR I=M-1 STEP -1 UNTIL L DO -- *****
DO 200 II = 1, MML
I = M - II
F = S * E(I)
B = C * E(I)
IF (ABS(F) .LT. ABS(G)) GO TO 150
C = G / F
R = SQRT(C*C+1.0)
E(I+1) = F * R
S = 1.0 / R
C = C * S
GO TO 160
150 S = F / G
R = SQRT(S*S+1.0)
E(I+1) = G * R
C = 1.0 / R
S = S * C
160 G = D(I+1) - P
R = (D(I) - G) * S + 2.0 * C * B
P = S * R
D(I+1) = G + P
G = C * R - B
C
***** FORM VECTOR *****

```

```

      DO 180 K = 1, N
        F = Z(K,I+1)
        Z(K,I+1) = S * Z(K,I) + C * F
        Z(K,I) = C * Z(K,I) - S * F
180    CONTINUE
C
C 200    CONTINUE
      D(L) = D(L) - P
      E(L) = 3
      E(M) = 0.0
      GO TO 105
C 240    CONTINUE
C ***** ORDER EIGENVALUES AND EIGENVECTORS *****
      DO 300 II = 2, N
        I = II - 1
        K = I
        P = D(I)
C
      DO 260 J = II, N
        IF (D(J) .GE. P) GO TO 260
        K = J
        P = D(J)
C 260    CONTINUE
C
      IF (K .EQ. I) GO TO 300
      D(K) = D(I)
      D(I) = P
C
      DO 280 J = 1, N
        P = Z(J,I)
        Z(J,I) = Z(J,K)
        Z(J,K) = P
C 280    CONTINUE
C
C 300    CONTINUE
C
      GO TO 1001
C ***** SET ERROR -- NO CONVERGENCE TO AN
C ***** EIGENVALUE AFTER 30 ITERATIONS *****
C 1000 IERR = L
      WRITE(5,2050)L
C 2050 FORMAT(*OL= *,I20)
C 1001 RETURN
C ***** LAST CARD OF INTQL2 *****
      END
C
      SUBROUTINE TRED2(NM,N,A,D,E,Z)
C
      INTEGER I,J,K,L,N,II,NM,JPI
      REAL A(NM,N),D(N),E(N),Z(NM,N)
      REAL F,G,H,HH,SCALE
      REAL SJRT,ABS,SIGN
C
      THIS SUBROUTINE IS A TRANSLATION OF THE ALGOL PROCEDURE TRED2,
      NUM. MATH. 11, 181-195(1968) BY MARTIN, REINSCH, AND WILKINSON.
      HANDBOOK FOR AUTO. COMP., VOL.II-LINEAR ALGEBRA, 212-226(1971).
C
      THIS SUBROUTINE REDUCES A REAL SYMMETRIC MATRIX TO A
      SYMMETRIC TRIDIAGONAL MATRIX USING AN ACCUMULATING
      ORTHOGONAL SIMILARITY TRANSFORMATIONS.
C
      ON INPUT-
C
      NM MUST BE SET TO THE ROW DIMENSION OF TWO-DIMENSIONAL
      ARRAY PARAMETERS AS DECLARED IN THE CALLING PROGRAM

```

```

C      DIMENSION STATEMENT,
C
C      N IS THE ORDER OF THE MATRIX.
C
C      A CONTAINS THE REAL SYMMETRIC INPUT MATRIX. ONLY THE
C      LOWER TRIANGLE OF THE MATRIX NEED BE SUPPLIED.
C
C      ON OUTPUT-
C
C      D CONTAINS THE DIAGONAL ELEMENTS OF THE TRIDIAGONAL MATRIX.
C
C      E CONTAINS THE SUBDIAGONAL ELEMENTS OF THE TRIDIAGONAL
C      MATRIX IN ITS LAST N-1 POSITIONS. E(1) IS SET TO ZERO.
C
C      Z CONTAINS THE ORTHOGONAL TRANSFORMATION MATRIX
C      PRODUCED IN THE REDUCTION.
C
C      A AND Z MAY COINCIDE. IF DISTINCT, A IS UNALTERED.
C
C      QUESTIONS AND COMMENTS SHOULD BE DIRECTED TO B. S. GARROW,
C      APPLIED MATHEMATICS DIVISION, ARGONNE NATIONAL LABORATORY
C
C-----
C
C      DO 100 I = 1, N
C
C          DO 100 J = 1, I
C              Z(I,J) = A(I,J)
C
C      100 CONTINUE
C
C      IF (N .EQ. 1) GO TO 320
C      ***** FOR I=N STEP -1 UNTIL 2 DO --- *****
C      DO 300 II = 2, N
C          I = II + 2 - II
C          L = I - 1
C          H = 0.0
C          SCALE = 0.0
C          IF (L .LT. 2) GO TO 130
C          ***** SCALE ROW (ALGOL TOL THEN NOT NEEDED) *****
C          DO 120 K = 1, L
C      120      SCALE = SCALE + ABS(Z(I,K))
C
C          IF (SCALE .NE. 0.0) GO TO 140
C      130      E(I) = Z(I,L)
C              GO TO 290
C
C      140      DO 150 K = 1, L
C          Z(I,K) = Z(I,K) / SCALE
C          H = H + Z(I,K) * Z(I,K)
C      150      CONTINUE
C
C          F = Z(I,L)
C          G = -SIGN(SQRT(H),F)
C          E(I) = SCALE * G
C          H = H - F * G
C          Z(I,L) = F - G
C          F = 0.0
C
C          DO 240 J = 1, L
C          Z(J,I) = Z(I,J) / (SCALE * H)
C          G = 0.0
C          ***** FORM ELEMENT OF A*U *****
C          DO 180 K = 1, J
C      180      G = G + Z(J,K) * Z(I,K)
C
C          JPI = J + 1

```

```

      IF (L .LT. JPI) GO TO 220
C
      DO 200 K = JPI, L
200    G = G + Z(K,J) * Z(I,K)
C      ***** FORM ELEMENT OF P *****
220    E(J) = G / H
      F = F + E(J) * Z(I,J)
240    CONTINUE
C
      HH = F / (H + H)
C      ***** FORM REDUCED A *****
      DO 260 J = 1, L
      F = Z(I,J)
      G = E(J) - HH * F
      E(J) = G
C
      DO 260 K = 1, J
      Z(J,K) = Z(J,K) - F * E(K) - G * Z(I,K)
260    CONTINUE
C
      DO 280 K = 1, L
280    Z(I,K) = SCALE * Z(I,K)
C
290    D(I) = H
300    CONTINUE
C
320    D(I) = 0.0
      E(I) = 0.0
C      ***** ACCUMULATION OF TRANSFORMATION MATRICES *****
      DO 500 I = 1, N
      L = I - 1
      IF (D(I) .EQ. 0.0) GO TO 380
C
      DO 360 J = 1, L
      G = 0.0
C
      DO 340 K = 1, L
340    G = G + Z(I,K) * Z(K,J)
C
      DO 360 K = 1, L
      Z(K,J) = Z(K,J) - G * Z(K,I)
360    CONTINUE
C
380    D(I) = Z(I,I)
      Z(I,I) = 1.0
      IF (L .LT. 1) GO TO 500
C
      DO 400 J = 1, L
      Z(I,J) = 0.0
      Z(J,I) = 0.0
400    CONTINUE
C
500    CONTINUE
C
      RETURN
C      ***** LAST CARD OF FRED2 *****
      END
      SUBROUTINE YFX(X,Y,N,XMIN,XMAX,YMIN,YMAX,HTL,NH,VTL,NV,M,XQ,XMQ)
      DIMENSION TEXT(7),X(I),Y(N)
      COMMON/A/FREQ,SD,SIGMA
      DATA (TEXT(I),I=1,7)/10H0= 100.00,10H0= 200.00,
+10H0= 300.00,10H0= 400.00,10H0= 500.00,10H0= 600.00,
+10H0= 700.00/
      WRITE(5,2014)(X(I),I=1,N)
      WRITE(5,2014)(Y(J),J=1,N)
2014  FORMAT(1X,10E11.4)

```

```

IF(.NH.LE.0)GO TO 10
DX=(XMAX-XMIN)/5.
DY=(YMAX-YMIN)/5.
XB=0.5
IF(XQ.EQ.0.3)XB=5.5
IF(XB.EQ.0.5)NH=-NH
CALL AXIS(0.5,XB,HIL,NH,5.,0.,XMIN,DX)
CALL AXIS(0.5,0.5,VTL,NV,5.,90.,YMIN,DY)
CALL SYMBOL(0.5,XQ,.1,3H F=,0.0,3)
CALL NUMBER(0.8,XQ,.1,FREQ,0.0,1)
CALL SYMBOL(2.0,XQ,.1,3HSD=,0.0,3)
CALL NUMBER(2.3,XQ,.1,SD,0.0,1)
CALL SYMBOL(3.5,XQ,.1,6HSIGMA=,0.0,3)
CALL NUMBER(3.8,XQ,.1,SIGMA,0.0,1)
IF(XMQ.EQ.1.)Z=M
IF(XMQ.EQ.1.)CALL SYMBOL(3.5,6.0,.1,5HMODE ,0.0,5)
IF(XMQ.EQ.1.)CALL NUMBER(4.0,6.0,.1,Z,0.0,1)
10 CALL LINE(X,Y,N,1,0,0,XMIN-DX/2.,DX,YMIN-DY/2.,DY)
ZETA=(Y(N)-YMIN)/DY+.5
IF(Y(N).LT.0.)ZETA=XB-ABS(Y(N)-YMAX)/DY
C ZETA DEPENDS ON CHOICE OF AXIS
C RE-ADJUST AS REQUIRED
IF(XMQ.EQ.1.)GO TO 12
CALL SYMBOL(X(N)/DX+.6,ZETA,.08,TEXT(M),0.,10)
12 RETURN
END
SUBROUTINE GFX(X,Y,N,XMIN,XMAX,YMIN,YMAX,XI,YMIX,
+HTL3,NH3,VTL3,NV3)
DIMENSION X(N),Y(N)
COMMON/A/FREQ,SD,SIGMA
WRITE(6,4014)(X(I),I=1,N)
WRITE(6,4014)(Y(J),J=1,N)
4014 FORMAT(1X,10E11.4)
IF(XI.NE.PI)WRITE(6,4024)XI,YMIX
4024 FORMAT(1X,#PMAX(*,F6.1,* KM)=*,E11.4)
IF(.NH3.LE.0)GO TO 10
DX=(XMAX-XMIN)/5.
DY=(YMAX-YMIN)/5.
CALL AXIS(0.5,0.5,HTL3,-NH3,5.,0.,XMIN,DX)
CALL AXIS(0.5,0.5,VTL3,NV3,5.,90.,YMIN,DY)
CALL SYMBOL(0.5,6.5,.1,3H F=,0.0,3)
CALL NUMBER(0.8,6.5,.1,FREQ,0.0,1)
CALL SYMBOL(2.0,6.5,.1,3HSD=,0.0,3)
CALL NUMBER(2.3,6.5,.1,SD,0.0,1)
CALL SYMBOL(3.5,6.5,.1,6HSIGMA=,0.0,3)
CALL NUMBER(3.8,6.5,.1,SIGMA,0.0,1)
IF(XI.NE.PI)CALL SYMBOL(2.0,6.0,.1,6HR(KM)=,0.0,6)
IF(XI.NE.PI)CALL NUMBER(2.5,6.0,.1,XI,0.0,1)
10 CALL LINE(X,Y,N,1,0,0,XMIN-DX/2.,DX,YMIN-DY/2.,DY)
RETURN
END
-END OF FILE-

```

APPENDIX B  
 DOCUMENTATION OF NORMAL MODE  
 PROGRAM FOR THE BILINEAR PROFILE  
 AND PROGRAM LISTING

P Normal modes  $\phi_n$  as a function of depth

U Eigenvalues  $\mu_n$

STK Related to eigenvalues via  $STK = k_0 \sqrt{1 - \mu_n^2}$   
 where  $k_0$  is the source wavenumber

ZM Depth coordinate (variable)

ZMAT Depth coordinate at which up and down integrations meet

ZMEET Depth coordinate where the two velocity gradients meet

EN Index of refraction,  $n(z)$ , as a function of depth

VM The potential,  $1 - n^2(z)$ , in the normal-mode equation

DELZ Depth increment

KO Source wavenumber

KOSQ Source wavenumber squared

BC Boundary condition value for eigenfunction

SLOPE Slope of eigenfunction at the boundary

TPT Turning point where eigenfunctions turn from oscillatory  
 (exponentially decay) to exponentially decaying (oscillatory)

H  
 -----  
 Ocean depth (m)

FBGN Source frequency (HZ)

IM First mode calculated (also equals the number of zero crossings in the mode)

NM Last mode calculated (equals number of zero crossings in the mode)

NMINC Increment of successive modes to be calculated between IM and NM.

NZW Number of depth points (spaced at DELZ) at which the normal mode depth functions are calculated and stored

USER NUMBER: edit  
 BEGIN TEXT EDITING.

? 11\*

```

PROGRAM MAIN(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,TAPE9)
C-----INSTRUCTIONS FOR CHANGING DIMENSIONS
C CHANGE THE DIM IN U AND STK TO # OF MODES REQ
C STEP 1. SELECT NEW DIM FOR P, =15 TO 20 PCT ABOVE ZM, VM
C STEP 2. RS /OLD DIM/,/NEW DIM/12
C STEP 3. SELECT NEW DIM FOR ZM, VM = 2**N+1 FOR SOME N
C STEP 4. RS /OLD/,/NEW/110
C STEP 5. RS /OLD*9/,/NEW*9/
DIMENSION U(20),P(9601),STK(20)
COMMON/GEN/UG,ZM(8001),ZMAT,FACT,DELZ,KO,DIVCK,SQB,SUB,KOSO,VM(
+8001),H12,H16,EXPMAX,OSCMAX,BC,TPT,SLOPE,EPS,B
REAL KO,KOSO
DATA CO,ZO,B,G/1434.,0.,1300.,.017/,EXPCT,OSPCT/1.,.1/
DATA ZMAT/105.,/ZMEET/337.3323427/
DATA NPTS,PI,DIVCK,UTEST/ 8001,3.14159265358979,1.E-40,1.E-44/
DATA H,WK,PCTERR,NPMX/4000.,0.5,0.01,9601/,SLINIT/1.E-100/
NAMELIST/VAL/FBGN,FMAG,NFG,IM,NI,NM,MMINC,NZN
C EN(Z)=1./((1.+EPS*(2.*(Z-ZO)/B-1.+EXP(2.*(ZO-Z)/B)))
EN(Z)=1./((1.006106525+1.67741E-5*Z)
V(Z)=1.-EN(Z)**2
REWIND 9
EPS=8*G/CO*0.5
EPSQ=SQRT(EPS)
DELZ=H/(NPTS-1)
H12=DELZ**2/12.
H16=16./21./DELZ
SQB=.9
FACT=PCTERR*240./H
DO 10 I=1,NPTS
ZM(I)=DELZ*(I-1)
IF(ZM(I).GT.ZMEET)GO TO 300.
VM(I)=1.-((1./((1.+3.48765E-5*ZM(I)))**2
GO TO 10
300 VM(I)=V(ZM(I))
10 CONTINUE
IMID=FLOAT(NPTS)*ZMAT/H
IF(ZM(IMID+1)-ZMAT.LI.ZMAT-ZM(IMID)) IMID=IMID+1
NMID=NPTS-IMID+1
IMID=IMID
NMID=NMID
IFLAG=0
IMD1=IMID+1
NMD1=NMID-1
KSHFT=NPMX-NPTS
VLEFT=VM(1)
VRT=V(H)
WRITE(6,81)VLEFT,VRT
81 FORMAT(1X,*,VLEFT=*,F10.5,*,VRT=*,F10.5)
KOSO=1.
1 READ VAL
IF(EOF(5))100,2
2 PRINT VAL
IF(FBGN.LI.0.) STOP
NSKP=(NPTS-1)/(NZN-1)
IM=IM+1
NM=NM+1
FRAT=10.**((1./FMAG)
IF(FBGN.EQ.0.) GO TO 23
F=FBGN/FRAT
C 23 DO 22 II=1,NFG
F=F*FRAT

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```

n=2.*PI*F
OLDKSO=KOSO
KO=n/CO
KOSO=KO*KO
WRITE(9) B,H,NZW,KOSO,NM
WRITE(6,3545)
3545 FORMAT(*WRITE HEADER*)
RATIO=KOSO/OLDKSO
DO 11 K=1,NPTS
11 VM(K)=RATIO*VM(K)
A=BB*ZMAT
NRR=0
KNTM=0
DO 20 I=1,M,NM,NMINC
M=I-1
IF(IFLAG.EQ.0) GO TO 15
IMID=I+IDD
NMID=NM+IDD
IMD1=IMID+1
NMD1=NMID-1
IFLAG=0
15 MKB=(MK+M)*PI
IF(KNTM-1) 16,17,18
16 UG=((3.*PI*3.48765E-5/(2.*KO))*(FLOAT(2*M)+1.5))**(2./3.)
IF(3.48765E-5.LT.DIVCK) UG=(FLOAT(2*M+1)*PI*.5/H/KO)**2
UINC=UG
GO TO 13
17 UINC=U(1)*(((FLOAT(2*M)+1.5)/(FLOAT(2*IM)-.5))**(2./3.))-1.)
GO TO 19
18 UINC=U(KNTM)-U(KNTM-1)
19 UG=U(KNTM)+UINC
13 UGL=0.
IF(KNTM.GT.0) UGL=U(KNTM)
DO 50 LL=1,10
A=1.E50
BB=1.E50
WRITE(6,72)ZMAT,H,BB
IF(UG.LT.VLEFT) CALL TURN(0.,ZO,A)
IF(UG.LT.VRT) CALL TURN(ZO,H,BB)
C 72 FORMAT(1X,*ZMAT,H,BB**,.3F10.5)
IF(UG.GE.VLEFT.OR.UG.GE.VRT) GO TO 60
XINT=0.
UDER=0.
KL=FLOAT(NPTS-1)*A/H+1.
KU=FLOAT(NPTS-1)*BB/H+1.
DO 40 KK=KL,KU
ARG=UG-VM(KK)/KOSO
IF(ARG.LT.0.)WRITE(6,26)ARG
C 26 FORMAT(1X,*ARG**,.E11.4)
IF(ARG.LE.DIVCK) GO TO 40.
SQ=SQRT(ARG)
UDER=UDER+0.5/SQ
XINT=XINT+SQ
C 40 CONTINUE
XINC=KO*XINT*DELZ
UDER=KO*UDER*DELZ
IF(ABS(XINC-MKB).LE.0.01*MKB) GO TO 60
C WRITE(6,25)UDER
C 25 FORMAT(1X,*UDER**,.E11.4)
UINC=(MKB-XINT)/UDER.
UG=UG+UINC
50 IF(UG.LE.UGL) UG=UGL+.1*ABS(UINC)
WRITE(6,1002) M,XINT,MKB
C 1002 FORMAT(*ONO MKB CONV FOR MODE*,I6,*ACTION**,.E11.4,*MKB**,.E11.4)
60 UGH=4.,UG-3.,UGL

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DO 70 KK=1,50
SUB=KOSQ=UG
IF(KK.EQ.1) GO TO 51
A=-1.E50
BB=1.E50
IF(UG.LT.VLEFT) CALL TURN(O.,ZO,A)
IF(UG.LT.VRT) CALL TURN(ZU,H,BB)
WRITE(6,72) ZMAT,H,BB
51 ZL=AMAXI(O.,A)
ZR=AMINI(BB,H)
OSCMAX=(ZR-ZL)/FLOAT(1)*OSPCT
EXPMAX=O.
IPT=A
IF(A.NE.-1.E50) EXPMAX=ZL*EXPCT
52 BC=O.
SLOPE=SLINIT*(-1.)*M
CALL NUMER(P,NPMX,1,KM,PINT1,NOD1,IMID)
EXPMAX=O.
IPT=BB
IF(BB.NE.1.E50) EXPMAX=(H-ZR)*EXPCT
56 BC=SLINIT
SLOPE=O.
CALL NUMER(P(KM+1),NPMX-KM,NPTS,KDUM,PINT2,NOD2,NMID)
IREF=KM+NMID
IAB=KM+KDUM
CALL INTERP(IMID+NMID-KDUM,KM,P,NPMX,O)
CALL INTERP(IREF+IMID-KM,IAB,P,NPMX,KM+NPTS+1)
SUM=O.
DO 63 K=IMD1,KM
IF(P(K)≠P(K-1).LT.O..OR.P(K).EQ.O.) NOD1=NOD1-1
63 SUM=SUM-P(K)**2
PINT1=PINT1+DELZ*(SUM-O.5*(P(IMID)**2-P(KM)**2))
IRF1=IREF+1
SUM=O.
DO 66 K=IRF1,IAB
SUM=SUM-P(K)**2
66 IF(P(K)≠P(K-1).LT.O..OR.P(K).EQ.O.) NOD2=NOD2-1
NOD1=NOD1+NOD2
PINT2=PINT2+DELZ*(SUM-O.5*(P(IREF)**2-P(IAB)**2))
IF(P(IMID)≠P(IREF).GT.O.) GO TO 67
IFLAG=IFLAG+1
C IF(A.EQ.O) WRITE(6,247) M,IFLAG
C 247 FORMAT(*ITERS. FOR CONVERG. MODE *,I3,*,*,I3)
IF(IFLAG.GT.50) GO TO 78
KL=OSCMAX/DELZ
IF(IMD1.GT.KM) GO TO 249
DO 240 K=IMD1,KM
IF(P(K)≠P(IREF+IMID-K).GT.DIVCK) GO TO 260
240 CONTINUE
249 IF(IRF1.GT.IAB) GO TO 252
DO 250 K=IRF1,IAB
IF(P(K)≠P(IMID+IREF-K).GT.DIVCK) GO TO 270
250 CONTINUE
252 IF(NOD1.EQ.M) GO TO 994
GO TO 67
260 IMID=K
IF(K+KL.GT.KM) KL=KM-K
IF(P(K+KL)≠P(IREF+IMID-K-KL).GT.DIVCK) IMID=IMID+KL
GO TO 280
270 IMID=IMID-K+IREF
IF(K+KL.GT.IAB) KL=IAB-K
IF(P(K+KL)≠P(IREF+IMID-K-KL).GT.DIVCK) IMID=IMID-KL
280 NMID=NPTS-IMID+1
IMD1=IMID+1
NMID=NMID-1
GO TO 51

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67 IF(NOD1-N1 71,68,75
68 RATIO=P(IMID)/P(IREF)
CALL DERIV(P,IMID,IMID,1,DERL)
CALL DERIV(P,IREF,IMID,-1,DERR)
UINC=P(IMID)*(DERL/RATIO-DERR)/((PINT1/RATIO+PINT2*RATIO)*KOSQ)
IF(UG+UINC.GT.UGH) UINC=0.5*(UGH-UG)
IF(UG+UINC.LF.UGL) UINC=0.5*(UGL-UG)
GO TO 79
71 UGL=AMAX1(UGL,UG)
GO TO 77
75 UGH=AMIN1(UGH,UG)
77 UINC=0.5*(UGL+UGH)-UG
IF(M.LE.0.OR.NOD1.LE.0) GO TO 79
UDER=UG*(FLOAT(M)/FLOAT(NOD1)-1.)
IF(ABS(UINC).GT.2.*ABS(UDER)) UINC=UDER
79 UG=UG+UINC
IF(ABS(UINC).LE.UTEST*UG) GO TO 80
70 CONTINUE
78 WRITE(6,1170) M,KK,IFLAG
1170 FORMAT(IX,CONV FAILURE FOR*,I3,* EVALUE*,*KK*,I3,* IFLAG*,I3)
STOP
80 DO 82 K=1,NMD1
PP=P(K+NMID-K)
IF(PP.EQ.1.E60) P(NPMX-K+1)=PP
82 IF(PP.NE.1.E60) P(NPMX-K+1)=PP*RATIO
KL=IMD1
83 KU=MIN0(KL+KSHFT-1,NPTS)
DO 84 K=KL,KU
84 P(K)=P(NPMX-K+KL)
IF(KU.GE.NPTS) GO TO 90
KMOV=NPTS-KU
DO 86 K=1,KMOV
86 P(NPMX-K+1)=P(NPTS-K+1)
KL=KU+1
GO TO 83
90 IF(UG.GE.1.0) GO TO 21
CALL INTERP(1,NPTS,P,NPTS,0)
PINT1=0.
DO 92 K=1,NPTS,NSKP
92 PINT1=PINT1+P(K)**2
PINT1=SQRT(DELZ*FLOAT(NSKP)*(PINT1-0.5*(P(1)**2+P(NPTS)**2)))
DO 91 K=1,NPTS,NSKP
91 P(K)=P(K)/PINT1
IF(NZ.NE.1) GO TO 94
WRITE(9) (P(K),K=1,NPTS,NSKP)
WRITE(6,3546) NZ,I,A,88
3546 FORMAT(*ORROTE EFCT*,I6,I5,* IPTS**,2F10.1)
94 KNTM=KNTM+1
U(KNTM)=UG
IF(UG.LI.VLEFT.AND.UG.LI.VRE) NRR=NRR+1
STK(KNTM)=KO*SQRT(1.-UG)
WRITE(6,7070)KNTM,STK(KNTM)
7070 FORMAT(IX,*STK(*,I4,*),F10.7)
20 CONTINUE
21 WRITE(9) (STK(I),I=1,KNTM)
WRITE(6,6668) F,NRR,KNTM,(STK(I),I=1,KNTM)
6668 FORMAT(F8.3,2I3,10E11.5)
22 CONTINUE
C DIF23=STK(2)-STK(3)
C DIF2526=STK(25)-STK(26)
C DIF9091=STK(90)-STK(91)
C DIF2021=STK(120)-STK(121)
C WRITE(6,263)DIF23,DIF2526,DIF9091,DIF2021
C263 FORMAT(4E11.5)
GO TO 1
991 WRITE(6,1001) K

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1991 FORMAT(*SIGN CHANGE AT NE* MATCH PT. MODE*,I4)
GO TO 666
994 WRITE(6,1994) P(IMID),P(IREF),IMID,IREF,KM,IAB
1994 FORMAT(*PROBLEM. NODE AT MID*,2E11.3,4I6)
666 WRITE(6,666) F,NRR,KNTM,(STK(I),I=1,KNTM)
100 STOP
END
SUBROUTINE NUMER(P,NP,IS,KMAX,PINT,NODES,IMID)
DIMENSION P(1)
REAL KO,KOSO
COMMON/GEN/UG,ZM(8001),ZO,FACT,DELZ,KO,DIYCK,S08,SUB,
* KOSQ,VM(8001),H12,H16,EXPMAX,OSCMAX,PS,TPT,SLOPE,EPS,B
NODES=0
DO 10 I=1,NP
10 P(I)=1.E60
PINT=0.
ZS=ZM(IS)
F1=VM(IS)-SUB
IF(OSCMAX.LT.DELZ)WRITE(6,161)OSCMAX,DELZ
161 FORMAT(IX,*OSCMAX=*,F10.5,* DELZ=*,F10.5,* 11*)
IF(OSCMAX.LT.DELZ) GO TO 500
HMAX=AMAX1(EXPMAX,DELZ)
IF(HMAX.EQ.OSCMAX) OSCMAX=1.00001*OSCMAX
IF(ABS(TPT).EQ.1.E50) HMAX=OSCMAX
IF(ABS(F1).LE.DIYCK) HTST=HMAX
IF(ABS(F1).GT.DIYCK) HTST=AMINI(S08*EXP(.2*ALOG(FACT/ABS(F1))
* ),HMAX)
IF(HTST.LT.DELZ)WRITE(6,162)HTST,DELZ
162 FORMAT(IX,*HTST=*,F10.5,* DELZ=*,F10.5,* 18*)
IF(HTST.LT.DELZ) GO TO 500
ZZ=DELZ
DO 120 NSK=1,100
ZZ=2.*ZZ
IF(HTST.LT.ZZ) GO TO 130
120 CONTINUE
WRITE(6,1020) HTST
1020 FORMAT(*MAX STEP SIZE=*,E10.3,* TOO BIG*)
STOP
130 HH=ZZ/2.
NASK=2*(NSK-1)
FF=HH*HH/12.
NSK=NASK*SIGN(1.0,ZO-ZS)
P(1)=PS
K=IS+NSK
KA=1+NASK
FO=VM(K)-SUB
IF(HMAX.NE.OSCMAX.AND.SLOPE.EQ.1.E50)
* P(KA)=PS*EXP(HH/2.*(SQRT(F1)+SQRT(FO))+0.25*ALOG(F1/FO))
IF(HMAX.EQ.OSCMAX.OR.SLOPE.NE.1.E50) P(KA)=PS*SLOPE*(ZM(K)-ZM(IS))
IF(P(KA)*P(1).LT.0..OR.P(KA).EQ.0.) NODES=NODES+1
IF((ZM(K+NSK)-TPT)*(TPT-ZM(K)).GE.0.) HMAX=AMINI(HMAX,OSCMAX)
PINT=HH*0.5*PS**2
HTST=AMINI(HTST,HMAX)
GO TO 150
140 K=K+NSK
KA=KA+NASK
IF(KA.GT.NP) GO TO 700
FO=VM(K)-SUB
IF(ABS(1.-FF*FO).LE.DIYCK) GO TO 600
P(KA)=(P(KA-NASK)*(2.+10.*FF*F1)-P(KA-2*NASK)*(1.-FF*F2))/
* (1.-FF*FO)
KMAX=KA
IF(P(KA)*P(KA-NASK).LT.0..OR.P(KA).EQ.0.) NODES=NODES+1
IF((ZM(K+NSK)-TPT)*(TPT-ZM(K)).GE.0.) HMAX=AMINI(HMAX,OSCMAX)
IF(ABS(FO).LE.DIYCK) HTST=HMAX
IF(ABS(FO).GT.DIYCK) HTST=AMINI(S08*EXP(.2*ALOG(FACT/ABS(FO))
* )

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      *      ),HMAX)
      IF(HH.GT.0.5*HTST) GO TO 150
      IF(KA.LE.2*NASK.OR.KA>2*NASK.GT.NP.OR.KA+NASK.GT.IMID+1) GO TO 160
      IF((ZM(K+2*NSK)-TPT)*(TPT-ZM(K)).LT.0.) GO TO 147
      HMAX=AMINI(HMAX,OSCMAX)
      HTST=AMINI(HTST,HMAX)
      IF(HH.GT.0.5*HTST) GO TO 150
      147 PINT=PINT+1.5*HH*P(KA)**2
          HH=HH*2.
          FF=FF*4.
          NSK=NSK*2
          NASK=NASK*2
          *WRITE(6,164),NASK
      C 164 FORMAT(IX,=NASK=,15,= 67*)
          GO TO 170
      150 IF(HH.LE.HTST.OR.KA-IMID.GE.4) GO TO 160.
          PINT=PINT+.5*HH*P(KA)**2
      152 IF(NASK.LT.2) GO TO 500
          HH=HH/2.
          FF=FF/4.
          NSK=NSK/2
          NASK=NASK/2
          F2=VM(K-NSK)-SUB
          IF(ABS(2.+10.*FF*F2).LE.DIVCK) GO TO 600
          P(KA-NASK)=(P(KA)*(1.-FF*FO)+P(KA-2*NASK)*(1.-FF*F1))/
          * (2.+10.*FF*F2)
          IF(HH.LE.HTST) GO TO 155
          F1=F2
          IF(NASK.LT.2.)WRITE(6,163),NASK
      163 FORMAT(IX,=NASK=,15,= 81*)
          GO TO 152
      155 PINT=PINT+.5*HH*P(KA)**2
          GO TO 170.
      160 F2=F1
          PINT=PINT+HH*P(KA)**2
      170 F1=FO
          IF(KA-IMID.LT.4) GO TO 140
          PINT=PINT-0.5*HH*P(KA)**2
          RETURN
      500 *WRITE(6,1500) HTST,K,ZM(K)
      1500 FORMAT(=MAX STPSIZ=,F14.6,= TOO SMALL, K=,I6,= Z=,F8.2)
          STOP
      600 *WRITE(6,1600) K,ZM(K)
      1600 FORMAT(=DIV BY 0 AT K=,I3,= Z=,F8.2)
          STOP
      700 *WRITE(6,1700) K
      1700 FORMAT(=OVERFLOWED STORAGE, K=,I6)
          STOP
      END
      SUBROUTINE INTERP(IL,IU,P,NPMX,KOFF)
      DIMENSION P(1)
      REAL KO,KOSQ
      COMMON/GEN/UG,ZM(8001),ZO,FACT,DELZ,KO,DIVCK,SOS,SUB,KOSQ,VM( 80
      *10)
      DO 80 K=1,IL
      IF(P(IL-K+1).NE.1.E60) GO TO 84
      80 CONTINUE
      GO TO 98
      84 I1=IL-K+1
      DO 85 K=IU,NPMX
      IF(P(K).NE.1.E60) GO TO 87
      85 CONTINUE
      GO TO 98
      87 I2=K
      IF(KOFF.EQ.0) KC=1
      IF(KOFF.NE.0) KC=1

```

```

NSK=1
DO 90 KK=11,12
IF(NSK.GT.1.AND.P(KK).NE.1.E60) GO TO 92
IF(P(KK).EQ.1.E60) NSK=NSK+1
GO TO 90
92 KL=KK-NSK
KU=KK-1
FF=(DELZ*NSK)**2/12.
94 NSK=NSK/2
FF=FF/4.
DO 93 K=KL,KU,NSK
IF(P(K).NE.1.E60) GO TO 93
L=KC*K+KOFF
F2=2.+10.*(VM(L)-SUB)*FF
IF(ABS(F2).LE.DIVCK) GO TO 97
P(K)=(P(K+NSK)*(1.-FF*(VM(L+NSK)-SUB))
+P(K-NSK)*(1.-FF*(VM(L-NSK)-SUB)))/F2
93 CONTINUE
IF(NSK.GT.1) GO TO 94
90 CONTINUE
RETURN
97 WRITE(6,1097) K,ZM(K)
1097 FORMAT(*DIV CHECK IN INTERP AT K=*,I3,* Z=*,F8.2)
STOP
98 WRITE(6,1098) K
1098 FORMAT(*TOO MANY BLANKS FOR INTERP, K=*,I3)
STOP
END
SUBROUTINE DERIV(P,I,IA,ISGN,DER)
DIMENSION P(1)
COMMON/GEN/UG,ZM(8001),ZO,FACT,DELZ,KO,DIVCK,S08,SUB,KOSO,VM( 80
*01),H12,H16,QUM(7)
I2=ISGN+ISGN
A1=0.5*(P(I+ISGN)-P(I-ISGN))
B1=H12*((VM(IA+1)-SUB)*P(I+ISGN)-(VM(IA-1)-SUB)*P(I-ISGN))
A2=0.5*(P(I+I2)-P(I-I2))
B2=H12*((VM(IA+2)-SUB)*P(I+I2)-(VM(IA-2)-SUB)*P(I-I2))
DER=H16*(-A1+1.15625*A2-7.4*B1-.425*B2)
RETURN
END
SUBROUTINE TURN(ZLL,ZRR,ZI)
COMMON/GEN/UG,ZM(8001),ZO,FACT,DELZ,KO,DIVCK,S08,SUB,KOSO,
* VM(8001),H12,H16,EXPMAX,OSCMAX,BC,TPT,SLOPE,EPS,B
REAL KO,KOSO
DATA ZMEET/337.3323427/
E1(Z)=1./(1.006106525+1.67741E-5*Z)
V1(Z)=1.-E1(Z)**2
E2(Z)=1./(1.+3.48765E-5*Z)
V2(Z)=1.-E2(Z)**2
ZL=ZLL
ZR=ZRR
IF(ZL.LE.ZMEET)GO TO 25
VL=V1(ZL)
GO TO 22
25 VL=V2(ZL)
22 IF(ZR.LE.ZMEET)GO TO 27
VR=V1(ZR)
GO TO 28
27 VR=V2(ZR)
28 DO 10 I=1,40
ZI=.5*(ZL+ZR)
IF(ZI.LE.ZMEET)GO TO 29
VT=V1(ZI)
GO TO 30
29 VT=V2(ZI)
30 LE(ABS(VT-UG)/T.E-5*UG) RETURN

```

```
C      IF((VL-UG)*(UG-VT).GE.0.) GO TO 5
      VL=VI
      ZL=ZI
      GO TO 10
C      5  VR=VI
      ZR=ZI
C      10  CONTINUE
      WRITE(6,1000) UG,VL,VT,VR
      1000 FORMAT(*IX,COULDNT FIND V=U, UG,VL,VT,VR* 4E13.6)
      STOP
      END
      -END OF FILE-
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CONT

mode amplitudes, and the brackets indicate an ensemble average. The master equations determine the mean power in each mode as a function of range, describing the transfer of energy between modes. Explicit relations for the coupling coefficients are obtained in terms of the spectrum of the rough surface. Transmission loss, intensity redistribution and the approach to equipartition of energy as functions of range and depth are obtained numerically.

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