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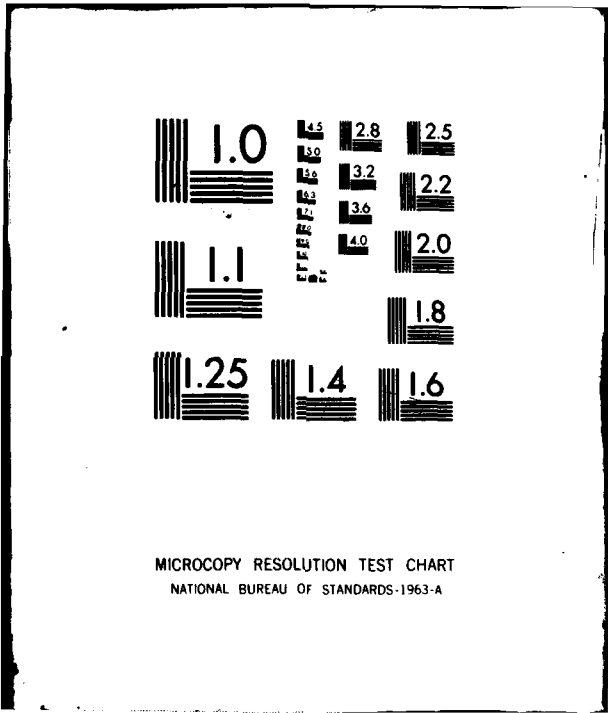
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DIRTRAN-I USER'S MANUAL

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Prepared by
DAVID DVORE

Aerodyne Research, Inc.
Crosby Drive
Bedford, MA 01730

Under Contract DAAK20-79-Q-0043
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US Army Electronics Research and Development Command
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| Artillery | Infrared | Buoyancy | |
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| The DIRTRAN-I Code is a computer-implemented model for predicting the optical effects of an explosion-produced dust cloud as it disperses in the lower atmosphere. This model is based on first principles of fluid dynamics, atmospheric, and optics. The model has been validated using cloud dimension and line-of-sight optical transmission data from the DIRT I and Graf II-Winter Army dust obscuration field trials. The DIRTRAN-I Code exploits information available about crater sizes produced by explosions in conjunction | | | |

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with distinct models for coupling of energy to the ground for artillery projectiles versus bare charges. The model recognizes that dust ejecta are partitioned into a buoyantly rising fireball and a non-buoyant "dust skirt" which is subject to diffusion in the vertically sheared wind field. The DIRTRAN-I Code solves separately for these two clouds. The solutions are based on atmospheric diffusion theory and take into account the effects of wind and temperature profiles in the constant shear stress layer of the lower atmosphere for different atmospheric stability categories. Separate treatment is given to particles of different sizes, the larger ones being allowed to settle out. Outputs of the code include dust cloud displacement and dimensions for both the non-buoyant wind-dominated skirt and the initial buoyant fireball as it is wind blown and eventually also becomes subject to wind diffusion. Line-of-sight transmittances at several wavelength bands (visible: 0.4 - 0.7 μm ; infrared: 0.8 - 1.1, 3.5 - 4.0, and 8.5 - 12 μm ; mm wave: 94 - 140 GHz) are also output options. Because of the analytic solutions derived from first-principle physics, the DIRTRAN-I Code has been designed to keep both storage and computation time to a minimum. In order to be machine transportable, the code has been written in ANSI FORTRAN IV with no system specific enhancements.

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1. INTRODUCTION

The DIRTRAN-I Code is a computer-implemented model for predicting the optical effects of an explosion-produced dust cloud as it disperses in the lower atmosphere. This model is based on first principles of fluid dynamics, atmospheric, and optics. The model has been validated using cloud dimension and line-of-sight optical transmission data from the DIRT I and Graf II-Winter Army dust obscuration field trials. The DIRTRAN-I Code exploits information available about crater sizes produced by explosions in conjunction with distinct models for coupling of energy to the ground for artillery projectiles versus bare charges. The model recognizes that dust ejecta are partitioned into a buoyantly rising fireball and a non-buoyant "dust skirt" which is subject to diffusion in the vertically sheared wind field. The DIRTRAN-I Code solves separately for these two clouds. The solutions are based on atmospheric diffusion theory and take into account the effects of wind and temperature profiles in the constant shear stress layer of the lower atmosphere for different atmospheric stability categories. Separate treatment is given to particles of different sizes, the larger ones being allowed to settle out. Outputs of the code include dust cloud displacement and dimensions for both the non-buoyant wind-dominated skirt and the initial buoyant fireball as it is wind blown and eventually also becomes subject to wind diffusion. Line-of-sight transmittances at several wavelength bands (visible: 0.4 - 0.7 μm ; infrared: 0.8 - 1.1, 3.5 - 4.0, and 8.5 - 12 μm ; mm wave: 94 - 140 GHz) are also output options.

Because of the analytic solutions derived from first-principle physics, the DIRTRAN-I Code has been designed to keep both storage and computation time to a minimum. In order to be machine transportable, the code has been written in ANSI FORTRAN IV with no system specific enhancements.

2. FUNCTIONS AND SUBROUTINES

There is a great deal of internal documentation in the code listed in Section 5. In Figs. 2.1 through 2.5 are box diagrams illustrating the structure of the code.

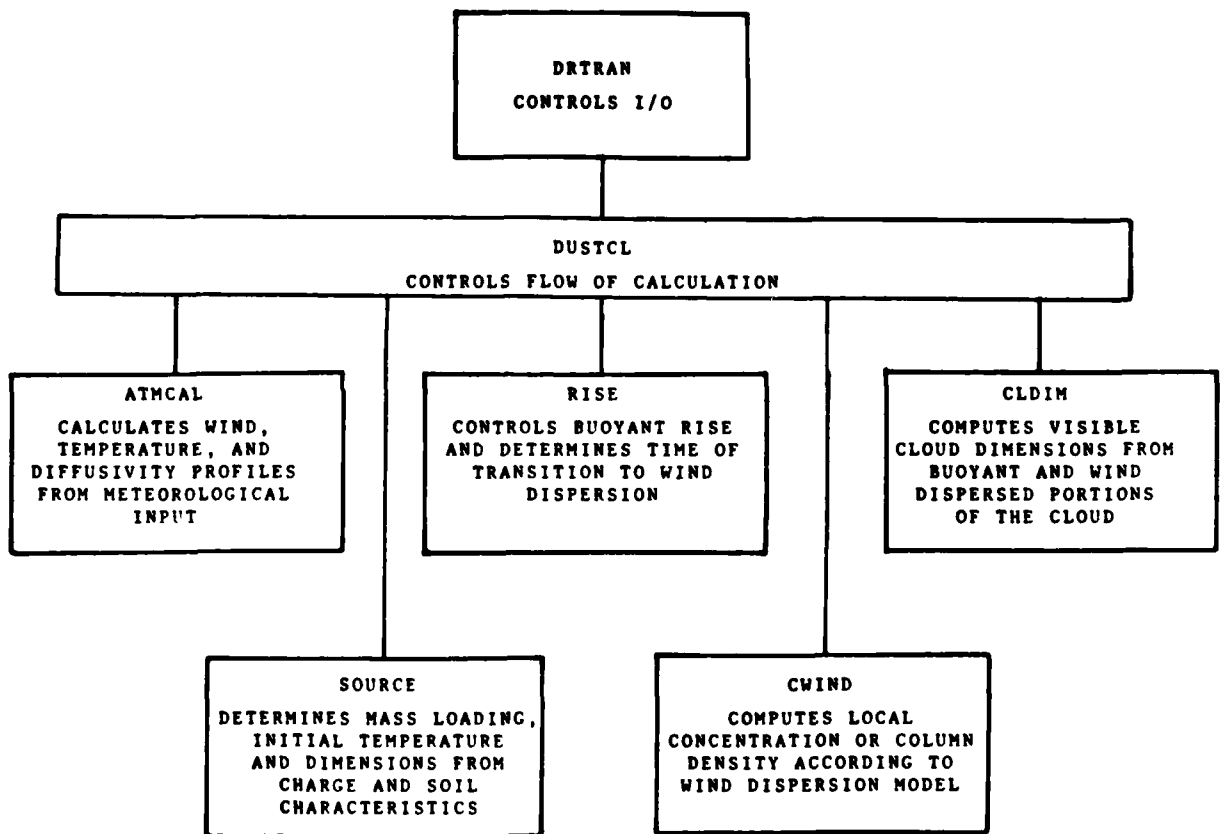


Figure 2.1 Controlling Routines.

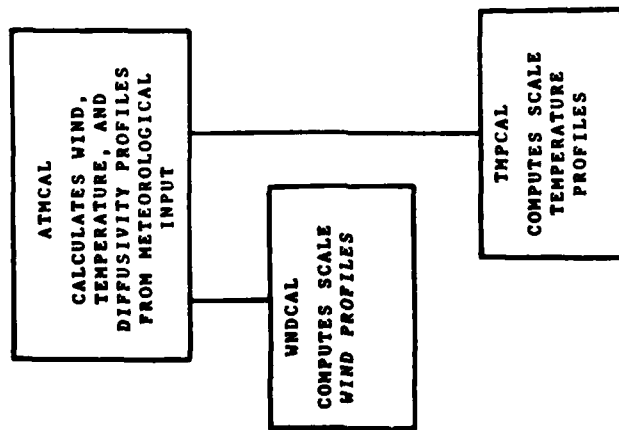


Figure 2.2 Routines for Interpreting Meteorological Data.

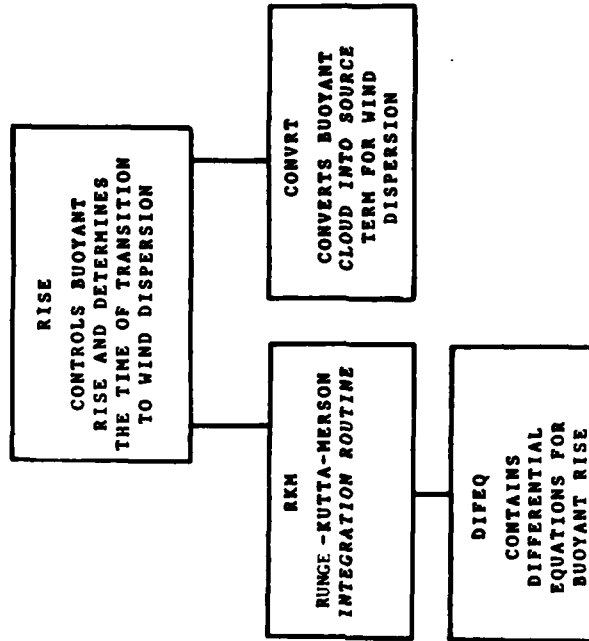


Figure 2.3 Routines for Buoyant Rise Model

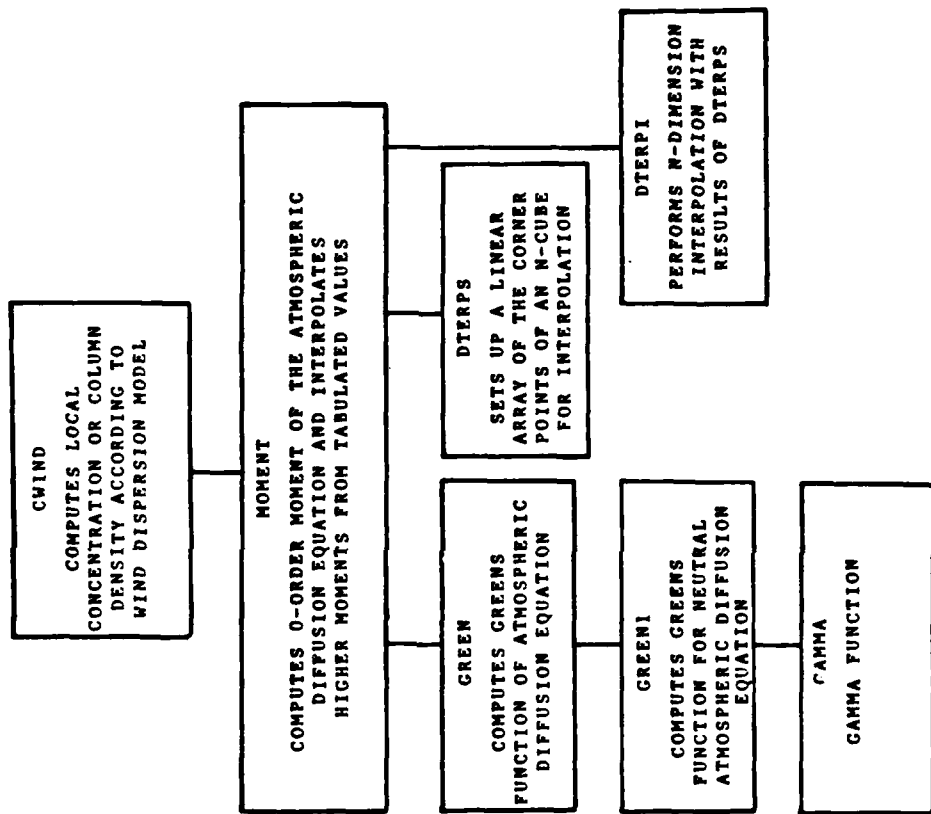


Figure 2.4 Routines for Wind Dispersion Model.

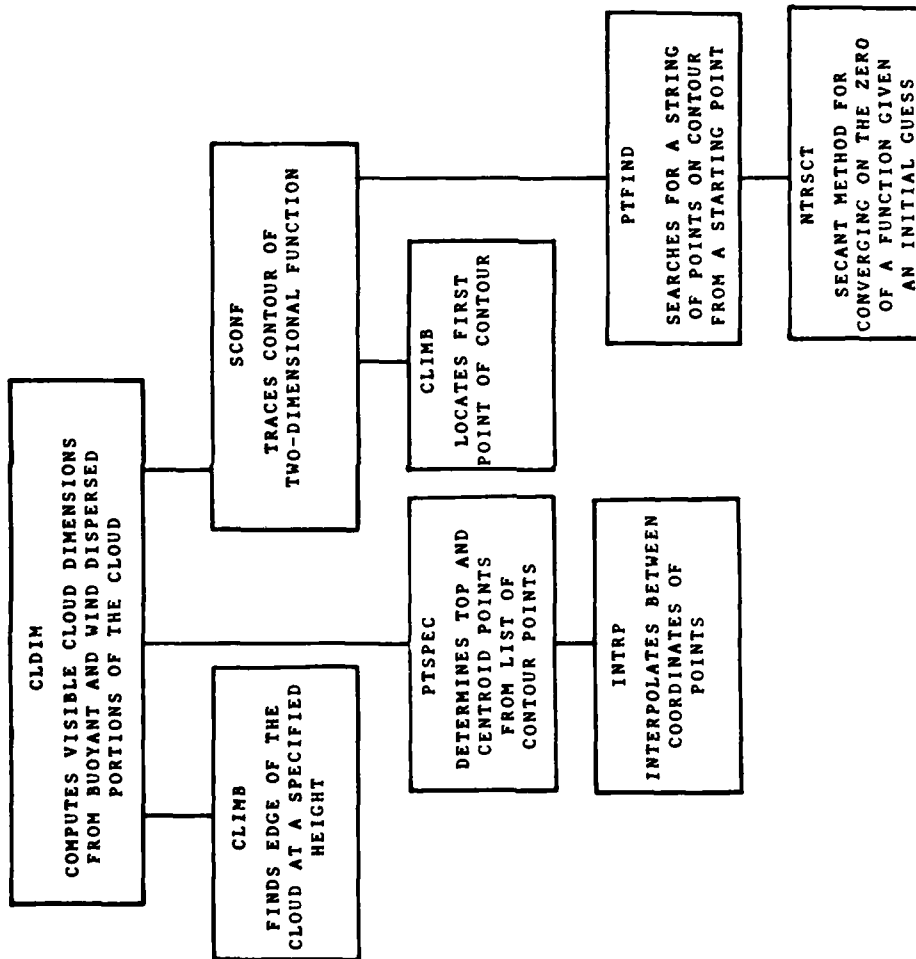


Figure 2.5 Routines for Determining Cloud Dimensions.

Miscellaneous Routines

- FUNCT Two-dimensional function which provides optically weighted column densities for visible contour tracing.
- GRAD2 Computes the two-dimensional gradient vector of a function.
- GFUN The restriction of a function of two variables to a line specified by a base point and direction vector.
- PERP Computes a vector rotated 90° counterclockwise from a given vector.
- UNIT Computes the length of a vector and a unit vector in the same direction as a given vector.
- VSUM Adds a given scalar multiple of one given vector to another.

3. USAGE

The user accesses the DIRTRAN-I Code via Subroutine DRTRAN.

```
CALL DRTRAN (WAVE1, ICLMAT, TRNLOS, IERR)
```

where:

WAVE1 is the wavelength in micrometers. Valid ranges are:

| | |
|----------|--------------------|
| 0.4 - | 0.7 micrometers |
| 0.8 - | 1.1 micrometers |
| 3.5 - | 4.0 micrometers |
| 8.5 - | 12.0 micrometers |
| 2100.0 - | 3200.0 micrometers |

ICLMAT is an integer index which is 0 if meteorological data is read from an external unit with other inputs and is 1 if passed in COMMON /CLYMAT/.

TRNLOS is the returned value of the transmittance along the line-of-sight between the transmitter and the receiver.

IERR is an integer error code which is returned one if a fatal error occurs and zero otherwise.

3.1 Common Blocks Used to Pass Information to DIRTRAN-I

There are two common blocks which communicate information to DIRTRAN-I: /IOUNIT/ and /CLYMAT/.

3.1.1 COMMON /IOUNIT/ IOIN, IOOUT, ISPTPE, LOUNIT, NDIRTU, NBSCAT

Of the variables in /IOUNIT/ only IOIN, IOOUT, and NDIRTU are used by DIRTRAN-I.

IOIN The Fortran logical unit from which DIRTRAN-I reads input data to be described in Subsection 3.2.

IOOUT The Fortran logical unit onto which DIRTRAN-I writes output and error messages.

NDIRTU The Fortran logical unit from which DIRTRAN-I reads the data file containing tabulated values for the moments of the atmospheric diffusion equation.

3.1.2 COMMON /CLYMAT/ TEMP, PRESS, RH, AH, DP, VIS, CLDAMT, CLDHYT, FOGPRB, IPASCT, WNDVEL, WNDDIR

DIRTRAN-I uses only TEMP, IPASCT, WNDVEL, and WNDDIR.

TEMP Temperature in degrees C taken at approximately two meters above ground.

IPASCT Integer 1 - 6 corresponding to Pasquill Categories A - F.

WNDVEL The wind speed in meters per second measured at approximately two meters above ground.

WNDDIR The wind direction (in degrees clockwise from true north) from which the wind is blowing. With this option the user's coordinate system must have the positive x-axis pointing east and positive y-axis pointing north. (Thus 0° corresponds to a wind blowing from the north to the south; 90° is a wind blowing from the east to the west; etc.)

3.2 Input from FORTRAN Logical Unit IOIN

The input read from logical unit, IOIN, provides the user with a variety of ways to use DIRTRAN-I. There are seven types of records to be distinguished on the input file. They are listed here with the names of variables contained on each record and the format type.

RECORD

| | | | | | | | | | | | | |
|---|--------|--------|--------|--------|--------|--------|--------|---------|------|--------|------|-------|
| 1 | NAME | NEWATM | NEWSRC | LOSTRN | EDGE | NEWTIM | | | | | | |
| | FORMAT | L1 | L1 | L1 | L1 | L1 | | | | | | |
| 2 | NAME | NATMOS | ZTMP | TMPMES | ZWND | WNDMES | ZTMP | TEMPMES | ZWND | WNDMES | ZINV | THWND |
| | FORMAT | I1,1X | F7.2 | F7.2 | F7.2 | F7.2 | F7.2 | F7.2 | F7.2 | F7.2 | F7.2 | F7.2 |
| 3 | NAME | NSOIL | NCHRG | CHWT | DETDEP | DSOD | SRCCOR | SRCCOR | | | | |
| | FORMAT | I1,1X | I1,1X | F7.2 | F7.2 | F7.2 | F7.2 | F7.2 | | | | |
| 4 | NAME | TRNCOR | TRNCOR | TRNCOR | RECCOR | RECCOR | RECCOR | | | | | |
| | FORMAT | F7.2 | F7.2 | F7.2 | F7.2 | F7.2 | F7.2 | | | | | |
| 5 | NAME | OBSCOR | OBSCOR | SPCHT | | | | | | | | |
| | FORMAT | F7.2 | F7.2 | F7.2 | | | | | | | | |
| 6 | NAME | TIME | | | | | | | | | | |
| | FORMAT | F7.2 | | | | | | | | | | |
| 7 | NAME | CNTNU | | | | | | | | | | |
| | FORMAT | L1 | | | | | | | | | | |

The description of the variables is in the comments in subroutine DRTRAN and appears on Pages 5-1 - 5-6 in this manual. Additional descriptions for some of the variables appears in Section 4.

The input file contains one or several sequences of these records each of which must begin with record 1, end with record 7, and contain a subset of records 2 - 6 corresponding to the entries in record 1. In each sequence, each of records 2 through 6 must appear if and only if the corresponding control variable entered in record 1 is .TRUE..

If NEWATM is .TRUE. then record 2 must appear.

If NEWSRC is .TRUE. then record 3 must appear.

If LOSTRN is .TRUE. then record 4 must appear.

If EDGE is .TRUE. then record 5 must appear.

If NEWTIM is .TRUE. then record 6 must appear.

On the first record of the input file NEWATM, NEWSRC, and NEWTIM must all be .TRUE.. This initializes the meteorological conditions, the charge and soil characteristics, and time after blast for the first observation. After that, DIRTRAN-I assumes that:

- Meteorological data are unchanged until NEWATM is .TRUE. again.
- Charge and Soil Characteristics are unchanged until NEWSRC is .TRUE. again.
- Time after blast is unchanged until NEWTIM is .TRUE. again.

The first time that NEWATM is .TRUE., if ICLMAT = 1 (see arguments of DRTRAN in Section 2), then record 2 should not appear following record 1. This is the only time that a control variable in record 1 may be .TRUE. without the corresponding record 2 - 6 following.

Record 7 contains the control variable, CNTNU, which is .TRUE. if another sequence of records 1 - 7 is to be read on this call of DRTRAN and .FALSE. is DRTRAN is to return control to the calling routine. An example follows.

3.3 Example

```

TTTTT
3 1 1. 271.30 1. 2.30 0. 090.
1 1 15. 0. .15 000. 0. 1.8
175.00-1148.0 1.8 -173.0 1135.0 1.8
175.0-1148.0 1.8
1.

T
FFTTT
175.00-1148.9 1.8 -173.0 1135.0 1.8
175.0-1148.0 1.8
2.

T
FFTTT
175.00-1148.9 1.8 -173.0 1135.0 1.8
175.0-1148.0 1.8
5.

T
FFTTT
175.00-1148.9 1.8 -173.0 1135.0 1.8
175.0-1148.0 1.8
10.

T
FFTTT
175.00-1148.9 1.8 -173.0 1135.0 1.8
175.0-1148.0 1.8
20.

T
FFTTT
175.00-1148.9 1.8 -173.0 1135.0 1.8
175.0-1148.0 1.8
30.

T
FFTTT
175.00-1148.9 1.8 -173.0 1135.0 1.8
175.0-1148.0 1.8
40.

T
FFTTT
175.00-1148.9 1.8 -173.0 1135.0 1.8
175.0-1148.0 1.8
60.

F

```

The results from the above input file follow.

DIRTRAN-I DUST CLOUD INFRARED TRANSMISSION CALCULATION

ALL UNITS ARE MKS UNLESS OTHERWISE SPECIFIED.

PASQUILL CATEGORY 3
 HT 1.00 TEMP 271.30 HT 1.00 WIND 2.30
 WIND DIRECTION 90.00

SOIL INDEX 1
 CHARGE INDEX 1
 WEIGHT OF CHARGE 15.00
 DETONATION DEPTH 0.00
 DEPTH OF SOD 0.15
 SOURCE COORDINATES 0.00 0.00

TIME AFTER BLAST 1.00

WAVELENGTH 0.55 MICROMETERS
 TRANSMITTER COORDINATES 175.00 -1148.00 1.80
 RECEIVER COORDINATES -173.00 1135.00 1.80
 TRANSMITTANCE ALONG THE LINE-OF-SIGHT 0.149E-02

OBSERVER COORDINATES 175.00 -1148.00
 THE HEIGHT OF THE CLOUD IS 8.39 METERS
 THE CENTROID COORDINATES ARE 0.41 4.79
 THE WIDTH AT THE CENTROID IS 7.19 METERS
 THE WIDTH AT 1.80 METERS IS 14.06 METERS

5 CONTOUR POINTS HAVE BEEN DETERMINED

-6.654 1.800
 -3.184 4.794
 0.410 8.388
 4.003 4.794
 7.408 1.800

TIME AFTER BLAST 2.00

WAVELENGTH 0.55 MICROMETERS
 TRANSMITTER COORDINATES 175.00 -1148.90 1.80
 RECEIVER COORDINATES -173.00 1135.00 1.80
 TRANSMITTANCE ALONG THE LINE-OF-SIGHT 0.296E-02

OBSERVER COORDINATES 175.00 -1148.00
 THE HEIGHT OF THE CLOUD IS 12.83 METERS
 THE CENTROID COORDINATES ARE 0.83 8.34

THE WIDTH AT THE CENTROID IS 8.97 METERS
 THE WIDTH AT 1.80 METERS IS 14.69 METERS
 5 CONTOUR POINTS HAVE BEEN DETERMINED
 -6.590 1.800
 -3.650 8.345
 0.832 12.827
 5.315 8.345
 8.098 1.800

TIME AFTER BLAST 5.00

WAVELENGTH 0.55 MICROMETERS
 TRANSMITTER COORDINATES 175.00 -1148.90 1.80
 RECEIVER COORDINATES -173.00 1135.00 1.80
 TRANSMITTANCE ALONG THE LINE-OF-SIGHT 0.156E-01

OBSERVER COORDINATES 175.00 -1148.00
 THE HEIGHT OF THE CLOUD IS 23.46 METERS
 THE CENTROID COORDINATES ARE 2.21 16.85
 THE WIDTH AT THE CENTROID IS 13.23 METERS
 THE WIDTH AT 1.80 METERS IS 16.56 METERS
 5 CONTOUR POINTS HAVE BEEN DETERMINED
 -6.396 1.800
 -4.409 16.845
 2.208 23.462
 8.825 16.845
 10.166 1.800

TIME AFTER BLAST 10.00

WAVELENGTH 0.55 MICROMETERS
 TRANSMITTER COORDINATES 175.00 -1148.90 1.80
 RECEIVER COORDINATES -173.00 1135.00 1.80
 TRANSMITTANCE ALONG THE LINE-OF-SIGHT 0.107E 00

OBSERVER COORDINATES 175.00 -1148.00
 THE HEIGHT OF THE CLOUD IS 36.10 METERS
 THE CENTROID COORDINATES ARE 4.71 26.94
 THE WIDTH AT THE CENTROID IS 18.32 METERS
 THE WIDTH AT 1.80 METERS IS 19.37 METERS
 5 CONTOUR POINTS HAVE BEEN DETERMINED
 -5.762 1.800
 -4.453 26.943
 4.709 36.105
 13.871 26.943
 13.613 1.800

TIME AFTER BLAST 20.00
 WAVELENGTH 0.55 MICROMETERS
 TRANSMITTER COORDINATES 175.00 -1148.90 1.80
 RECEIVER COORDINATES -173.00 1135.00 1.80
 TRANSMITTANCE ALONG THE LINE-OF-SIGHT 0.508E 00
 OBSERVER COORDINATES 175.00 -1148.00
 THE HEIGHT OF THE CLOUD IS 59.23 METERS
 THE CENTROID COORDINATES ARE 9.98 40.06
 THE WIDTH AT THE CENTROID IS 42.01 METERS
 THE WIDTH AT 1.80 METERS IS 24.06 METERS
 5 CONTOUR POINTS HAVE BEEN DETERMINED
 -4.179 1.800
 -11.030 40.057
 10.032 59.232
 30.983 40.057
 19.883 1.800

TIME AFTER BLAST 30.00
 WAVELENGTH 0.55 MICROMETERS
 TRANSMITTER COORDINATES 175.00 -1148.90 1.80
 RECEIVER COORDINATES -173.00 1135.00 1.80
 TRANSMITTANCE ALONG THE LINE-OF-SIGHT 0.789E 00
 OBSERVER COORDINATES 175.00 -1148.00
 THE HEIGHT OF THE CLOUD IS 67.78 METERS
 THE CENTROID COORDINATES ARE 15.89 40.18
 THE WIDTH AT THE CENTROID IS 69.05 METERS
 THE WIDTH AT 1.80 METERS IS 27.81 METERS
 5 CONTOUR POINTS HAVE BEEN DETERMINED
 -2.285 1.800
 -18.638 40.178
 17.039 67.779
 50.413 40.178
 25.528 1.800

TIME AFTER BLAST 40.00
 WAVELENGTH 0.55 MICROMETERS
 TRANSMITTER COORDINATES 175.00 -1148.90 1.80
 RECEIVER COORDINATES -173.00 1135.00 1.80
 TRANSMITTANCE ALONG THE LINE-OF-SIGHT 0.909E 00

| | | | |
|------------------------------|----------------|--------|--------------|
| OBSERVER | COORDINATES | 175.00 | -1148.00 |
| THE HEIGHT OF THE CLOUD IS | | | 72.35 METERS |
| THE CENTROID COORDINATES ARE | | 21.67 | 40.70 |
| THE WIDTH AT THE CENTROID IS | | | 83.14 METERS |
| THE WIDTH AT | 1.80 METERS IS | | 30.63 METERS |

5 CONTOUR POINTS HAVE BEEN DETERMINED

| | |
|---------|--------|
| 0.235 | 1.800 |
| -19.906 | 40.703 |
| 20.352 | 72.355 |
| 63.238 | 40.703 |
| 30.860 | 1.800 |

TIME AFTER BLAST 60.00

| | |
|---------------------------------------|----------------------|
| WAVELENGTH | 0.55 MICROMETERS |
| TRANSMITTER COORDINATES | 175.00 -1148.90 1.80 |
| RECEIVER COORDINATES | -173.00 1135.00 1.80 |
| TRANSMITTANCE ALONG THE LINE-OF-SIGHT | 0.977E 00 |

| | | | |
|------------------------------|----------------|--------|--------------|
| OBSERVER | COORDINATES | 175.00 | -1148.00 |
| THE HEIGHT OF THE CLOUD IS | | | 77.53 METERS |
| THE CENTROID COORDINATES ARE | | 33.99 | 48.28 |
| THE WIDTH AT THE CENTROID IS | | | 99.13 METERS |
| THE WIDTH AT | 1.80 METERS IS | | 36.56 METERS |

5 CONTOUR POINTS HAVE BEEN DETERMINED

| | |
|---------|--------|
| 4.962 | 1.800 |
| -15.571 | 48.284 |
| 34.569 | 77.535 |
| 83.556 | 48.284 |
| 41.524 | 1.800 |

4. DIRTRAN-I GEOMETRY

4.1 User Coordinates

A top view of the (x,y) user coordinate plane for the DIRTRAN-I geometry is shown in Fig. 4.1. All inputs are in this user coordinate plane. Negative coordinates are allowed.

4.2 Wind Geometry

THWND is the angle in degrees that the wind velocity vector makes with the user's positive x-axis and is measured counter-clockwise. If the x-axis points east, then the following relationship holds between THWND and WINDIR (which is the standard meteorological wind direction as discussed in Sub-Section 3.1.2):

$$\text{THWND} = 270 - \text{WINDIR}$$

4.3 Transmission Geometry

The height above ground of the transmitter and receiver, TRNCOR(3) and RECCOR(3), must be equal and must be between 0 and 5 meters. The transmitter height will be used as a default for the receiver height.

4.4 Observer Geometry

A local coordinate system, x' , y' , z' is used for viewing geometry. The x' -axis is aligned from the detonation point with coordinates, SRCCOR(I), to the observer position with coordinates, OBSCOR(I). The y' -axis is rotated 90° counterclockwise from the x' -axis, and the z' -axis is vertical so as to make a right-handed coordinate system. The visible cloud is projected along the observer's line-of-sight, the x' -axis. The visible cloud contour thus appears on the y' - z' coordinate plane, shown in Fig. 4.2. Five contour points are reported by DIRTRAN-I:

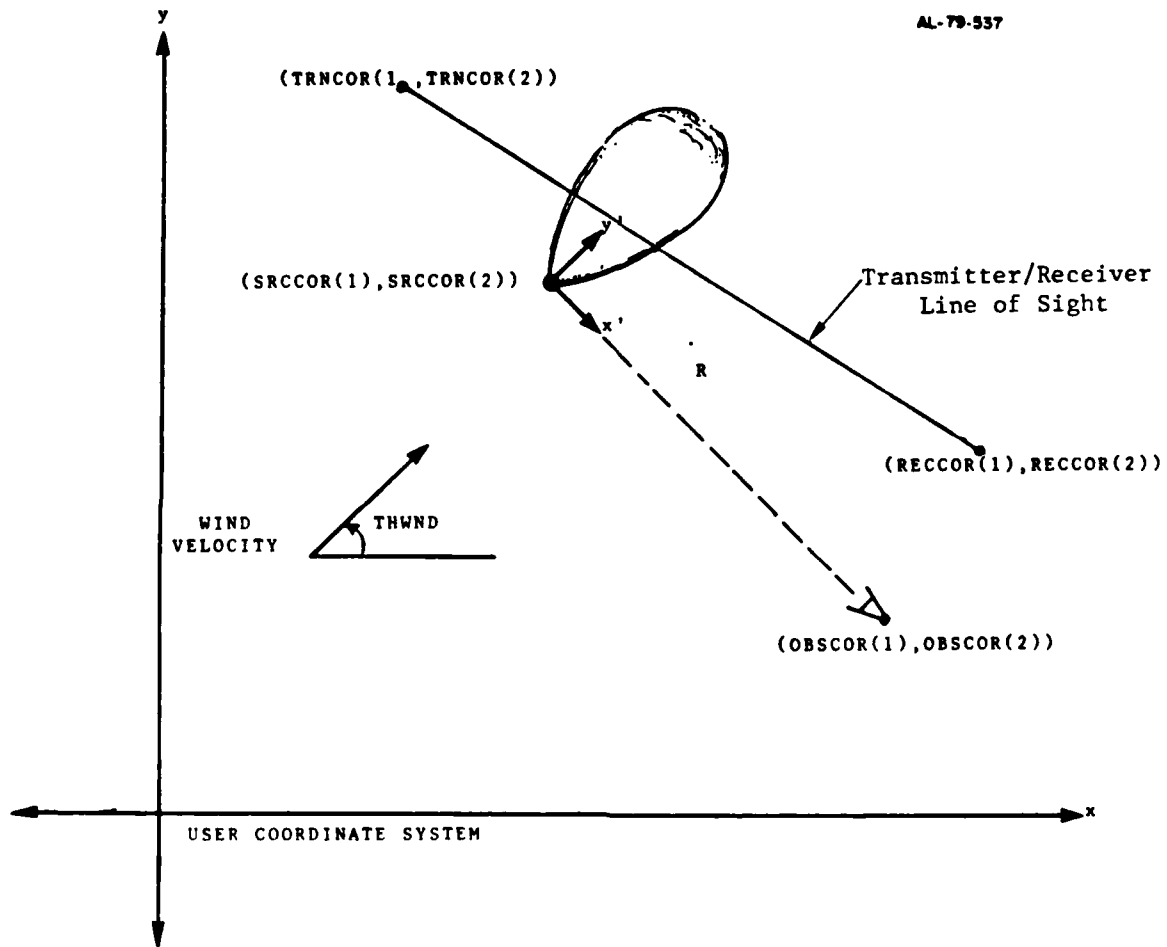


Figure 4.1 Top View of DIRTRAN-I Geometry.

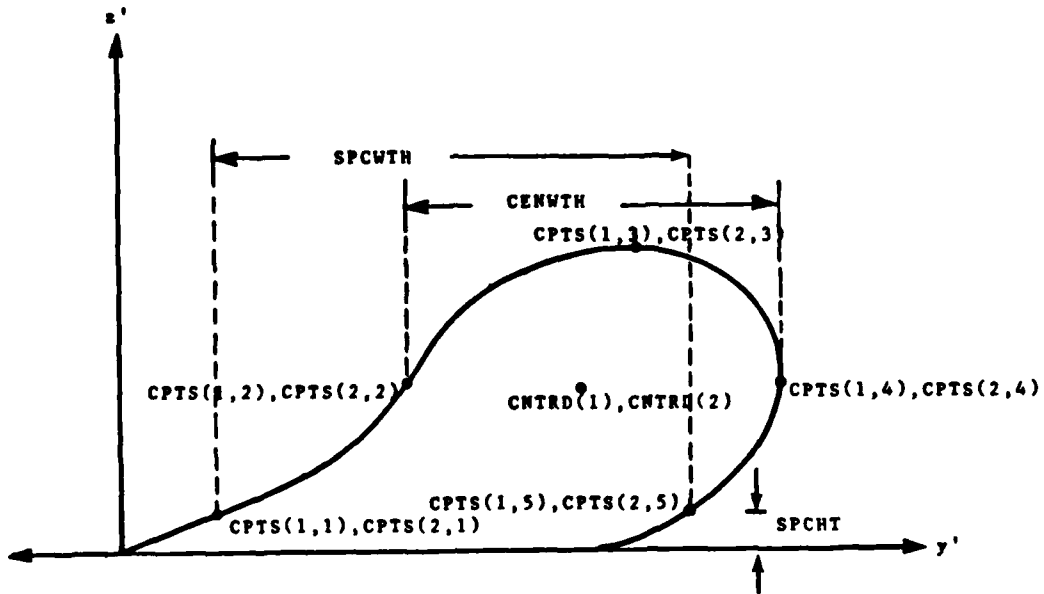


Figure 4.2 Observer's View.

- The left and right edges of the cloud at a specified height, SPCHT,
- The left and right edges of the cloud at the centroid height, and
- The top of the cloud.

The centroid is determined by first locating the leading edge of the cloud which is $(CPTS(1,4), CPTS(2,4))$ in Fig. 4.2. A horizontal line is drawn across the cloud to determine $(CPTS(1,2), CPTS(2,2))$ in Fig. 4.2. The centroid is defined to be the midpoint of these two.

5. LISTING OF DIRTRAN-I CODE

```

C           DIRTRAN-I CODE
C
C           TEST CALLING ROUTINE
C
C           COMMON /IOUNIT/ IOIN, IOOUT, ISPTPF, LOUNIT, NDIRTU, NBSCAT
C           DATA IOIN, IOOUT, NDIRTU/5, 1, 7/
C           WAVE1=.55
C           ICLMAT=0
C           CALL DRTRAN(WAVE1, ICLMAT, TRNLOS, IERR)
C           STOP
C           END
C           UTILITY ROUTINE FOR INTERFACING DIRTRAN-I WITH EC-SAEL
C
C           ***** SUBFILE 1 *****
C
C           SUBROUTINE DRTRAN(WAVE1, ICLMAT, TRNLOS, IERR)
C           IMPLICIT INTEGER*4 (1-N)
C           LOGICAL NEWATM, NEWSRC, LOSTRN, EDGE, NEWTIM, CNTNU, CLMRED
C           DIMENSION ZTMP(2), TMPMES(2), ZWND(2), WNDMES(2), SRCCOR(2), TRNCOR(3)
C           I , RECCOR(3), CPTS(2, 200), CNTRD(2), OBSCOR(2)
C           COMMON /IOUNIT/ IOIN, IOOUT, ISPTPF, LOUNIT, NDIRTU, NBSCAT
C           COMMON /CLYMAT/ TEMP, PRESS, RH, AH, DP, VIS, CLDAMT, CLDHYT,
C           I FOGPRB, IPASCT, WNDVEL, WINDIR
C           *****
C
C           DAVID DVORE
C           AERODYNE RESEARCH, INC.
C           (617)275-9400 X127
C
C           PURPOSE
C
C           DRTRAN CALCULATES DUST CLOUD DIMENSIONS AND TRANSMITTANCES
C           THROUGH DUST CLOUDS FOR GIVEN METEOROLOGICAL DATA, SOIL TYPE,
C           BOMB CHARACTERISTICS, AND WAVELENGTH.
C
C           INPUT
C
C           NEWATM      A LOGICAL VARIABLE WHICH IS .TRUE. IF NEW ATMOSPHERIC
C                     CONDITIONS ARE TO BE SPECIFIED AND .FALSE. IF PREVIOUS
C                     VALUES ARE TO BE ASSUMED. IF .TRUE. THEN NATMOS, ZTMP,
C                     TMPMES, ZWND, WNDMES, HTINV, AND THWND MUST BE
C                     SPECIFIED

```


| | | | |
|---|--------|---|--|
| C | | 3 | 30 DEGREE TILTED TIP AT 0.3 METER DEPTH |
| C | | 4 | 30 DEGREE TILTED TIP AT 0.6 METER DEPTH |
| C | | 5 | HORIZONTAL PROJECTILE ON SURFACE |
| C | | | DEFAULT VALUE IS 1 IF NCHRG IS NOT BETWEEN 1 AND 5. |
| C | | | |
| C | DETDEP | | THE DEPTH OF DETONATION IN METERS. VALID RANGE: 0.0 - 2.0 M. |
| C | | | |
| C | NSOIL | | INTEGER INDEX OF SOIL TYPE. NSOIL IS 1 FOR EUROPEAN SOIL 2 FOR DESERT SOIL |
| C | | | |
| C | DSOD | | DEPTH OF SOD IN METERS VALID RANGE: 0.0 - 1.0 M. |
| C | | | |
| C | WAVE1 | | WAVELENGTH IN MICROMETERS. USED TO DETERMINE NWL. VALID RANGES: |
| C | | | |
| C | NWL | | INTEGER INDEX FOR WAVELENGTH 1 FOR 0.4 - 0.7 MICROMETER (VISIBLE) 2 FOR 0.8 - 1.1 MICROMETER 3 FOR 3.5 - 4.0 MICROMETER 4 FOR 8.5 - 12.0 MICROMETER 5 FOR 2100 - 3200 MICROMETER |
| C | | | |
| C | SRCCOR | | A SINGLY DIMENSIONED ARRAY CONTAINING THE X AND Y COORDINATES OF THE DETONATION POSITION. VALID RANGE: -9999.9 - 9999.99 M. |
| C | | | |
| C | LOSTRN | | A LOGICAL VARIABLE WHICH IS .TRUE. IF THE TRANSMITTANCE ALONG A LINE-OF-SIGHT IS DESIRED AND .FALSE. IF NOT. IF .TRUE. THEN TRNCOR AND RECCOR MUST BE SPECIFIED. |
| C | | | |
| C | TRNCOR | | A SINGLY DIMENSIONED ARRAY CONTAINING THE THREE COORDINATES OF THE TRANSMITTER. THE COORDINATE SYSTEM MUST BE IN METERS. THE THIRD COORDINATE IS RESTRICTED TO BE BETWEEN 1 AND 5 METERS (HEIGHT). VALID RANGE: -9999.9 - 9999.99 M. |
| C | | | |
| C | RECCOR | | A SINGLY DIMENSIONED ARRAY CONTAINING THE THREE COORDINATES OF THE RECEIVER. (METERS) THE THIRD COORDINATE MUST BE THE SAME AS THE THIRD COORDINATE OF TRNCOR. VALID RANGE: -9999.9 - 9999.99 M. |
| C | | | |
| C | EDGE | | A LOGICAL VARIABLE WHICH .TRUE. IF CLOUD DIMENSIONS |

C ARE TO BE CALCULATED AND .FALSE. IF NOT. IF .TRUE.
 C THEN OBSCOR AND SPCHT MUST BE SPECIFIED.
 C
 C OBSCOR A SINGLY DIMENSIONED ARRAY CONTAINING THE X AND Y
 C COORDINATES, RESP., OF THE OBSERVER. (METERS)
 C VALID RANGE: -9999.9 - 9999.99
 C
 C SPCHT A SPECIFIED HEIGHT IN METERS AT WHICH THE WIDTH OF
 C THE CLOUD AS VIEWED FROM POSITION OBSCOR IS DESIRED.
 C MUST BE BETWEEN 1 AND 5 METERS.
 C
 C NEWTIM A LOGICAL VARIABLE WHICH IS .TRUE. IF ONE WISHES TO
 C ADVANCE THE TIME AND FALSE IF MORE RESULTS ARE
 C REQUIRED AT THE CURRENT TIME. IF .TRUE. THEN TIME
 C MUST BE SPECIFIED.
 C
 C TIME TIME MEASURED IN SECONDS AFTER DETONATION.
 C SUCCESSIVE CALLS OF DRTRAN MAY KEEP THE TIME UNCHANGED
 C FROM PREVIOUS CALL (NEWTIM = .FALSE.) OR SPECIFY A
 C NEW TIME GREATER THAN IN THE PREVIOUS CALL. WHEN
 C A NEW SOURCE IS SPECIFIED (NEWSRC=.TRUE.) A NEW TIME
 C MUST ALSO BE SPECIFIED (NEWTIM=.TRUE.) AND ONLY IN
 C THIS CASE MAY A TIME LESS THAN THE PREVIOUS CALL
 C BE SPECIFIED.
 C VALID RANGE: 0.5 - 1000.0 SECONDS.
 C
 C
 C OUTPUT
 C
 C TRNLOS THE TRANSMITTANCE ALONG THE LINE-OF-SIGHT BETWEEN
 C THE TRANSMITTER AND THE RECEIVER.
 C
 C IERR INTEGER ERROR CODE WHICH EQUALS 1 IF A FATAL ERROR
 C OCCURS AND 0 OTHERWISE
 C
 C CNTRD A SINGLY DIMENSIONED ARRAY CONTAINING THE HORIZONTAL
 C COORDINATE AND THE VERTICAL COORDINATE OF THE
 C CENTROID OF THE CLOUD.
 C
 C HEIGHT THE HEIGHT OF THE CLOUD IN METERS.
 C
 C CENWTH THE WIDTH OF THE CLOUD IN METERS AT THE CENTROID
 C HEIGHT
 C
 C SPCWTH THE WIDTH OF THE CLOUD IN METERS AT THE SPECIFIED
 C HEIGHT
 C


```

C      CONBYN      CONVERTS CLOUD DIMENSIONS AS SPECIFIED BY VARIABLES
C      USED IN RISE TO OUTPUT VARIABLES DESCRIBING CLOUD
C      DIMENSIONS
C
C      WIND        COMPUTES WIND VELOCITY AS A FUNCTION OF HEIGHT
C
C      SCNF        DETERMINES A SET OF POINTS DEFINING THE OBSERVABLE
C      CONTOUR OF THE CLOUD AS VIEWED FROM A DISTANCE AT A
C      GIVEN ANGLE TO THE WIND VELOCITY.
C
C      PTSPEC      USES THE SET OF COORDINATE POINTS DETERMINED BY SCNF
C      TO CALCULATE OUTPUT VARIABLES DESCRIBING CLOUD
C      DIMENSIONS
C
C      FUNCTIONS CALLED
C
C      CWIND       COMPUTES THE OPTICALLY WEIGHTED CONCENTRATION
C      FOR TIMES AFTER THE TRANSITION FROM BUOYANT RISE
C      TO WIND BLOWN
C
C *****
C      IERR=0
C      CLMRED=.FALSE.
C      WRITE(IOOUT,900)
C 900 FORMAT(49H1      DIRTRAN-I DUST CLOUD INFRARED TRANSMISSION ,
C      1          12HCALCULATION //
C      2          46H ALL UNITS ARE MKS UNLESS OTHERWISE SPECIFIED.//)
C 100 READ(IOIN,701)NEWATM,NEWSRC,LOSTRN,EDGE,NEWTIM
C      IF(.NOT.NEWATM) GO TO 10
C      IF(ICLMAT.EQ.1.AND..NOT.CLMRED)GO TO 5
C      READ(IOIN,702)NATMOS,(ZTMP(I),TMPMES(I),ZWND(I),
C      +WNDMES(I),I=1,2),ZINV,THWND
C      GO TO 6
C
C      IPASCT      PASQUILL CATEGORY
C      WNDVEL      WIND VELOCITY IN M/S MEASURED AT 2 METERS ABOVE GROUND
C      WINDIR      WIND DIRECTION IN DEGREES CLOCKWISE FROM TRUE NORTH
C      TEMP        TEMPERATURE IN DEGREES C MEASURED AT 2 METERS HEIGHT
C
C      5 NATMOS=IPASCT
C      ZWND(1)=2.
C      ZTMP(1)=2.
C      WNDMES(1)=WNDVEL
C      TMPMES(1)=TEMP+273.0
C
C      NOTE THAT POSITIVE X AXIS IS ASSUMED TO BE EAST.
C      NOTE THAT WINDIR IS THE DIRECTION OF ORIGIN OF THE WIND.

```

C

```
THWND=270.-WINDIR
ZINV=150.0
CLMRED=.TRUE.
6 CONTINUE
950 FORMAT(1X)
WRITE(IOOUT,950)
WRITE(IOOUT,951)NATMOS
NIO=1
IF(NATMOS.EQ.0)NIO=2
WRITE(IOOUT,952)(ZTMP(I),TMPMES(I),ZWND(I),WNDMES(I),I=1,NIO)
WRITE(IOOUT,953)THWND
951 FORMAT(30H PASQUILL CATEGORY ,I2)
952 FORMAT(8H HT ,F7.2,7H TEMP ,F7.2,7H HT,F7.2,7H WIND ,
1 F7.2)
953 FORMAT(22H WIND DIRECTION ,F7.2)
10 CONTINUE
IF(.NOT.NEWSRC)GO TO 20
READ(IOIN,703)NSOIL,NCHRG,CHWT,DETDEP,DSOD,SRCCOR(1),
1 SRCCOR(2)
WRITE(IOOUT,950)
WRITE(IOOUT,955)NSOIL
WRITE(IOOUT,954)NCHRG
WRITE(IOOUT,956)CHWT
WRITE(IOOUT,957)DETDEP
WRITE(IOOUT,958)DSOD
WRITE(IOOUT,959)(SRCCOR(I),I=1,2)
WRITE(IOOUT,950)
954 FORMAT(15H CHARGE INDEX ,I2)
955 FORMAT(15H SOIL INDEX ,I2)
964 FORMAT(30H WAVELENGTH ,F7.2,13H MICROMETERS )
956 FORMAT(30H WEIGHT OF CHARGE ,F7.2)
957 FORMAT(30H DETONATION DEPTH ,F7.2)
958 FORMAT(30H DEPTH OF SOD ,F7.2)
959 FORMAT(30H SOURCE COORDINATES ,2F10.2)
20 CONTINUE
IF(.NOT.LOSTRN)GO TO 30
READ (IOIN,704)(TRNCOR(I),I=1,3),(RECCOR(J),J=1,3)
IF(WAVE1.LT.0.4)GO TO 29
IF(WAVE1.GT.0.7)GO TO 21
NWL=1
GO TO 30
21 IF(WAVE1.LT.0.8)GO TO 29
IF(WAVE1.GT.1.1)GO TO 22
NWL=2
GO TO 30
22 IF(WAVE1.LT.3.5)GO TO 29
IF(WAVE1.GT.4.0)GO TO 23
```

```

NWL=3
GO TO 30
23 IF(WAVE1.LT.8.5)GO TO 29
   IF(WAVE1.GT.12.0)GO TO 24
   NWL=4
   GO TO 30
24 IF(WAVE1.LT.2100)GO TO 29
   IF(WAVE1.GT.3200)GO TO 29
   NWL=5
   GO TO 30
29 WRITE(IOOUT,25)
25 FORMAT(42H *** DIRTRAN-I ERROR - WAVE1 OUT OF RANGE )
   IERR=1
   GO TO 999
30 IF (EDGE) READ (IOIN,704) (OBSCOR(IO),IO=1,2),SPCHT
   TIMTST=TIME
   IF (NEWTIM) READ (IOIN,704) TIME
   IF(.NOT.NEWSRC.AND.TIME.LT.TIMTST)GO TO 997
   WRITE(IOOUT,960)TIME
960 FORMAT(//30H TIME AFTER BLAST ,F7.2)
   NERR=0
   CALL DUSTCL (NEWATM,NATMOS,ZTMP,TMPMES,ZWND,WNDMES,ZINV,THWND,
1  NEWSRC,CHWT,NCHRG,DETDEP,NSOIL,DSOD,NWL,SRCCOR,
2  LOSTRN,TRNCOR,RECCOR,EDGE,OBSCOR,SPCHT,NEWTIM,TIME,
3  TRNLOS,CNTRD,HEIGHT,CENWTH,SPCWTH,NCPTS,CPTS,NERR)
C   IF (NERR.EQ.0)GO TO 600
C   WRITE(IOOUT,969)NERR
C 969  FORMAT(20H ***** ERROR NUMBER ,I2)
C   GO TO 800
600 IF(.NOT.LOSTRN)GO TO 700
   WRITE(IOOUT,950)
   WRITE(IOOUT,964)WAVE1
   WRITE(IOOUT,961)(TRNCOR(I),I=1,3)
   WRITE(IOOUT,962)(RECCOR(I),I=1,3)
961  FORMAT(30H TRANSMITTER COORDINATES ,3F10.2)
962  FORMAT(30H RECEIVER COORDINATES ,3F10.2)
   WRITE(IOOUT,970)TRNLOS
970  FORMAT(40H TRANSMITTANCE ALONG THE LINE-OF-SIGHT ,E10.3)
700 IF(.NOT.EDGE)GO TO 800
   WRITE(IOOUT,950)
   WRITE(IOOUT,963)(OBSCOR(I),I=1,2)
963  FORMAT(30H OBSERVER COORDINATES ,2F10.2)
   WRITE(IOOUT,971)HEIGHT
971  FORMAT(28H THE HEIGHT OF THE CLOUD IS ,10X,F10.2,7H METERS)
C
C 990  FORMAT((1X,2F10.2))
C   WRITE(IOOUT,972)(CNTRD(IO),IO=1,2)

```

```

972  FORMAT(30H THE CENTROID COORDINATES ARE ,8X,2F10.2)
      WRITE(IOOUT,973)CENWTH
973  FORMAT(30H THE WIDTH AT THE CENTROID IS ,8XF10.2, 7H METERS)
      WRITE(IOOUT,974)SPCHT,SPCWTH
974  FORMAT(14H THE WIDTH AT ,F8.2,11H METERS IS ,5X,F10.2,7H METERS)
      WRITE(IOOUT,975)NCPTS
975  FORMAT(1X,I3,37H CONTOUR POINTS HAVE BEEN DETERMINED )
      WRITE(IOOUT,708)((CPTS(10,IPT),IO=1,2),IPT=1,NCPTS)
800  READ(IOIN,701)CNTNU
      IF(CNTNU)GO TO 100
701  FORMAT (5L1)
702  FORMAT (11,1X,10F7.2)
703  FORMAT (2(11,1X),5F7.2)
704  FORMAT (6F7.2)
705  FORMAT (I2)
708  FORMAT ((1X,2(F10.3,2X)))
709  FORMAT (2(I2,1X),2F7.2)
      GO TO 999
997  WRITE(IOOUT,998)
998  FORMAT(54H *** DIRTRAN ERROR - TIMES ARE NOT IN INCREASING ORDER)
      IERR=1
999  RETURN
      END

```

C CONTROLLING ROUTINE FOR DIRTRAN-I CODE

C ***** SUBFILE 2 *****

```

SUBROUTINE DUSTCL(NEWATM,NATMOS,ZTMP,TMPMES,ZWND,WNDMES,HTINV,
1 THWND,NEWSRC,CHWT,NCHRG,DETDEP,NSOIL,DSOD,NWL,SRCCOR,
2 LOSTRN,TRNCOR,RECCOR,EDGE,OBSCOR,SPCHT,NEWTIM,
3 TIME,TRNLOS,CNTRD,HEIGHT,CENWTH,SPCWTH,NCPTS,CPTS,NERR)
  IMPLICIT INTEGER*4 (1-N)
  LOGICAL NEWATM,NEWSRC,LOSTRN,EDGE,NEWTIM,HORIZ,ERR
  DIMENSION ZTMP(2),TMPMES(2),ZWND(2),WNDMES(2),SRCCOR(2),TRNCOR(3)
1 ,RECCOR(3),CPTS(2,200),ORIG(2),TRNFRM(2,2),TRN(3),REC(3)
2 ,PNT(3),DELS(3),CNTRD(2),OBSCOR(2),DIR(2),SCRN(2)
  DIMENSION OWF(5,2)
  COMMON /GEOM/COSTH2,SINTH,SINTH2,VISEXT,RTP1
  COMMON /MODE/ HORIZ
  COMMON /WNDPRM/ DXZO,DYXO,DZO,UO,UM,DN,ZINV
  COMMON /CLOCK/ FTIME,TWIND
  COMMON /SEPRIN/ SEP1(2),SEP2(2),PRSEP1,PRSEP2,NUM1,NUM2
  COMMON /IOUNIT/ IOIN,IOOUT,ISPTPF,LOUNIT,NDIRTU,NBSCAT
  EXTERNAL FUNCT
  DATA PI/3.1415927/,VISEXT,ZMIN,RES,TANT/.1,0.,1.,.1/
  DATA ONEM/-1./,RTP1/1.77245/
  DATA OWF/1.,.93,.52,.44,7.E-4,1.,.93,.66,.52,7.E-4/

```

C *****

C DAVID DVORE
C AERODYNE RESEARCH, INC.
C (617)275-9400 X127
C

C PURPOSE

C DUSTCL CALCULATES DUST CLOUD DIMENSIONS AND TRANSMITTANCES
C THROUGH DUST CLOUDS FOR GIVEN METEOROLOGICAL DATA, SOIL TYPE,
C BOMB CHARACTERISTICS, AND WAVELENGTH.
C

C SEE COMMENTS IN DRTRAN FOR DETAILS.
C

C *****

IF(LOSTRN.OR.EDGE)GO TO 100
NERR=4
GO TO 999
100 IF(.NOT.NEWATM) GO TO 200
IF(NEWSRC) GO TO 150
NERR =5
GO TO 999
150 CONTINUE
ZINV=HTINV
CALL ATMCAL(NATMOS,ZTMP,TMPMES,ZWND,WNDMES,ERR)
IF(.NOT.ERR)GO TO 155
NERR=7
GO TO 999
155 CONTINUE

C COMPUTE THE ROTATION TRANSFORMATION MATRIX TO CONVERT USER
C DEFINED COORDINATES INTO LOCAL COORDINATES WITH X AXIS IN
C THE WIND DIRECTION.
C

THETAX=THWND*PI/180.
TRNFRM(1,1)=COS(THETAX)
TRNFRM(2,2)=TRNFRM(1,1)
TRNFRM(1,2)=SIN(THETAX)
TRNFRM(2,1)=-TRNFRM(1,2)
200 CONTINUE
IF(.NOT.NEWSRC) GO TO 300
TWIND=1.E5
TPRES=0.
DEL=.001
CALL SOURCE(CHWT,NCHRG,DETDEP,NSOIL,DSOD)
DO 250 I=1,2
ORIG(I)=SRCCOR(I)
250 CONTINUE
OVLAP=SPACNG/2.
SEP1(1)=SPACNG*COS(THARRY-THETAX)

```

SEP1(2)=SPACNG*SIN(THARRY-THETAX)
CALL PERP(SEP1,SEP2)
300 CONTINUE
IF(.NOT.LOSTRN) GO TO 400
C
C CONVERT TRNCOR AND RECCOR TO LOCAL COORDINATES WITH ORIGIN AT
C DETONATION POINT AND X AXIS IN WIND DIRECTION.
C
TRN(3)=TRNCOR(3)
REC(3)=RECCOR(3)
DO 320 I=1,2
TRN(I)=0.
REC(I)=0.
DO 310 J=1,2
TRN(I)=TRN(I)+TRNFRM(I,J)*(TRNCOR(J)-ORIG(J))
REC(I)=REC(I)+TRNFRM(I,J)*(RECCOR(J)-ORIG(J))
310 CONTINUE
320 CONTINUE
400 CONTINUE
IF(.NOT.EDGE) GO TO 500
C
C COMPUTE SIN AND COS OF THE ANGLE BETWEEN THE OBSERVERS VIEWING
C ANGLE AND THE LOCAL POSITIVE X AXIS WHICH IS IN THE WIND
C DIRECTION.
C
CALL VSUM(ORIG,OBSCOR,ONEM,DIR)
CALL UNIT(DIR,DIR,RANGE)
COSTH=0.
SINTH=0.
DO 410 J=1,2
COSTH=COSTH+TRNFRM(1,J)*DIR(J)
SINTH=SINTH+TRNFRM(2,J)*DIR(J)
410 CONTINUE
SINTH2=SINTH*SINTH
COSTH2=COSTH**2
SCRN(1)=SINTH
SCRN(2)=-COSTH
500 CONTINUE
IF(NEWTIM) CALL RISE(TPRES,TIME,DEL)
600 IF(.NOT.EDGE) GO TO 650
FTIME=TIME
CALL CLDIM(CNTRD,HEIGHT,CENWTH,SPCHT,SPCWTH,NCPTS,CPTS,
1 NERR)
IF(.NOT.ERR)GO TO 650
NERR=6
GO TO 999
650 CONTINUE
IF(.NOT.LOSTRN)GO TO 999

```

C
C
C
C
C

DETERMINE THE OPTICALLY WEIGHTED CL VALUE
ALONG THE LINE CONNECTING THE TRANSMITTER AND RECIEVER

CALL VSUM(REC,TRN,ONEM,DIR)
CALL UNIT(DIR,DIR,RANGE)
COSTH=DIR(1)
SINTH=DIR(2)
SINTH2=SINTH*SINTH
COSTH2=COSTH**2
SCRN(1)=SINTH
SCRN(2)=-COSTH
X=DOTPRD(SCRN,TRN)
HORIZ=.TRUE.
TRNLOS=EXP(-CWIND(X,Y,TRN(3),TIME)*OWF(NWL,NSOIL))
999 RETURN
END

C CALCULATION OF ATMOSPHERIC PARAMETERS FOR DIRTRAN-I CODE

C
C
C
C

***** SUBFILE 3 *****

SUBROUTINE ATMCAL(NATM,ZT,TMES,ZU,UMES,ERR)
IMPLICIT INTEGER*4 (I-N)
REAL M,N
LOGICAL ERR
DIMENSION ZT(2),TMES(2),ZU(2),UMES(2),ZLO(6)
COMMON /WNDPRM/ DXZO,DYXO,DZO,UO,M,N,ZINV
COMMON /TMPPRM/TO,TI,TM
COMMON /IOUNIT/ IOIN,IOOUT,ISPTPF,LOUNIT,NDIRTU,NBSCAT
DATA ZLO/-2.5,-4.5,-13.5,1000.,55.,20./

C *****

C
C
C

PURPOSE

C
C
C

TO FIT THE BEST POWER-LAW PROFILES OF WINDSPEED,
DIFFUSIVITY, AND TEMPERATURE CONSISTENT WITH KNOWN RELATIONS
GOVERNING THE CONSTANT SHEAR STRESS LAYER TO GIVEN
MEASUREMENTS AT TWO HEIGHTS.

C
C
C

C
C
C

INPUTS

C
C
C

NATM INTEGER WHICH IS 0 IF WINDSPEED AND TEMPERATURE
ARE AVAILABLE AT TWO HEIGHTS AND EQUAL TO THE
PASQUILL CATEGORY OTHERWISE.

C
C

```

C      ZT      SINGLY DIMENSIONED ARRAY CONTAINING TWO HEIGHTS
C      (IN METERS) AT WHICH TEMPERATURES WILL BE GIVEN.
C      MUST BE IN ASCENDING ORDER.
C
C      TMES     SINGLY DIMENSIONED ARRAY CONTAINING THE TWO
C      TEMPERATURE MEASUREMENTS IN DEGREES KELVIN
C      AT HEIGHTS ZT.
C
C      ZU      SINGLY DIMENSIONED ARRAY CONTAINING ONE OR TWO
C      HEIGHTS (METERS) AT WHICH WIND SPEEDS WILL BE
C      GIVEN.  MUST BE IN ASCENDING ORDER.
C
C      UMES     SINGLY DIMENSIONED ARRAY CONTAINING THE ONE OR
C      TWO WIND SPEED MEASUREMENTS (M/S) AT HEIGHTS UMES.
C
C      ZINV     INVERSION HEIGHT IN METERS.
C
C
C      OUTPUTS
C
C      ERR      A LOGICAL WHICH IS TRUE IF AN ERROR IS INCURED
C      DURING THE CALCULATION.
C
C      DXZO     THE RATIO OF THE DIFFUSIVITY IN THE X DIRECTION
C      TO THE DIFFUSIVITY IN THE Z DIRECTION.  RETURNED
C      IN COMMON /WNDPRM/.
C
C      DYXO     THE RATIO OF THE DIFFUSIVITY IN THE Y DIRECTION
C      TO THE DIFFUSIVITY IN THE X DIRECTION.  RETURNED
C      IN COMMON /WNDPRM/.
C
C      DZO      THE COEFFICIENT OF Z**N IN THE VERTICAL PROFILE
C      OF VERTICAL DIFFUSIVITY.  RETURNED IN COMMON
C      /WNDPRM/.
C
C      UO       THE COEFFICIENT OF Z**M IN THE VERTICAL PROFILE
C      OF HORIZONTAL WIND SPEED.  RETURNED IN COMMON
C      /WNDPRM/.
C
C      M        THE EXPONENT OF Z IN THE HORIZONTAL WIND SPEED
C      PROFILE.  RETURNED IN COMMON /WNDPRM/.
C
C      N        THE EXPONENT OF Z IN THE VERTICAL DIFFUSIVITY
C      PROFILE.  RETURNED IN COMMON /WNDPRM/.
C
C      TO, T1, TM  CONSTANTS FOR THE TEMPERATURE PROFILE SUCH THAT

```

```

C           T=T0+T1*Z**TM.  RETURNED IN COMMON /TMPPRM/.
C
C
C
C   CALLED FROM DUSTCL
C
C   NEEDED FUNCTIONS AND SUBROUTINES
C           TMPCAL   CALCULATES SCALED TEMPERATURE PROFILES
C           WNDCAL   CALCULATES SCALED WIND SPEED PROFILES
C
C *****
C
C   ERR=.FALSE.
C
C   DELTH IS THE DIFFERENCE IN POTENTIAL TEMPERATURE BETWEEN THE
C   TWO HEIGHTS WHERE TEMPERATURE IS GIVEN.
C
C   Z0=0.02
C   IF(NATM.EQ.0)GO TO 100
C
C   ASSIGN ATMOSPHERIC PROFILE ACCORDING TO SPECIFIED PASQUILL
C   CATEGORY
C
C   Z0      FRICTION HEIGHT
C   ZL      MOMIN-OBUKOV LENGTH
C   USTAR   THE FRICTION VELOCITY
C   TSTAR   THE SCALING TEMPERATURE
C
C   ZL=ZLO(NATM)
C   NP=IFIX(SIGN(1.,ZL))
C   USTAR=UMES(1)/WNCAL(Z0,ZL,ZU(1))
C   TSTAR=TMES(1)*USTAR**2/1.568/ZL
C   IF(NATM-4)200,300,210
100 CONTINUE
C
C   USE ITERATIVE PROCEDURE TO CONVERGE ON BEST ATMOSPHERIC PROFILE
C   TO MATCH DATA AT TWO HEIGHTS
C
C   DELTH=TMES(2)-TMES(1)+.0098*(ZT(2)-ZT(1))
C   NP=SIGN(1.,DELTH)
C   DELU=UMES(2)-UMES(1)
C   ZULOG=ALOG(ZU(2)/ZU(1))
C   ZTLOG=ALOG(ZT(2)/ZT(1))
C   USTAR=(UMES(2)-UMES(1))/ZULOG
C   TSTAR=DELTH/ZTLOG
C   ZL=.638*TMES(1)*USTAR**2/TSTAR

```

```

IF(ABS(ZL).GE.1000.)GO TO 300
DO 110 ITER=1,100
USTAR=DELU/(WDCAL(Z0,ZL,ZU(2))-WDCAL(Z0,ZL,ZU(1)))
TSTAR=DELTH/(TMPAL(Z0,ZL,ZT(2))-TMPAL(Z0,ZL,ZT(1)))
ZLP=ZL
ZL=.638*TMES(1)*USTAR**2/TSTAR
IF(ABS((ZL-ZLP)/ZLP).LT..01)GO TO 120
110 CONTINUE
ERR=.TRUE.
GO TO 999
120 CONTINUE
Z0=EXP(.4*(WDCAL(Z0,ZL,ZU(1))-UMES(1)/USTAR))*Z0
IF(NP)200,300,210
200 CONTINUE
C
C UNSTABLE ATMOSPHERE
C
DZ0=3.15*.4*USTAR/ABS(ZL)**(1./3.)
DXZ0=2.
M=1./7.
N=4./3.
GO TO 430
210 CONTINUE
C
C STABLE ATMOSPHERE
C
DXZ0=6.
M=1./7.
N=1.
DZ0=.4*USTAR/(1.+47./ZL)
GO TO 430
300 CONTINUE
C
C NEUTRAL ATMOSPHERE
C
DZ0=.4*USTAR
DXZ0=5.
NP=0
N=1.
M=1./7.
430 CONTINUE
C
C COMMON CALCULATION TO UNSTABLE, NEUTRAL, AND STABLE ATMOSPHERES
C
IF(ZINV.LE.10.)ZINV=200.
U0=UMES(1)/ZU(1)**M
DYX0=1.
IF(NATM.EQ.0)U0=(U0+UMES(2)/ZU(2)**M)/2.

```



```

C          LOGARITHMIC WIND VELOCITY BOUNDARY LAYER PROFILE IN AN
C          UNSTABLE ATMOSPHERE
C          PSIMS      THE SAME AS PSIM FOR A STABLE ATMOSPHERE
C

```

```

          IF(ABS(ZL).LE.1.E3)GO TO 100
          WNDCAL=ALOG(1.+Z/Z0)
          GO TO 999
100 CONTINUE
          P=SIGN(1.,ZL)
          LOW=.TRUE.
          S=Z/ZL
          IF(S.LE.1.5.AND.S.GE.-2.)GO TO 10
          S=AMIN1(S,1.5)
          S=AMAX1(S,-2.)
          LOW=.FALSE.
          10 CONTINUE
             IF(P)120,130,130
120 S=1./PHIM(S)
          PSI=PSIM(S)
          GO TO 52
130 CONTINUE
          PSI=PSIMS(S)
          52 CONTINUE
             WNDCAL=ALOG(1.+Z/Z0)-PSI
             IF(LOW)GO TO 999
             IF(P)53,53,54
          53 WNDCAL=WNDCAL+.75-.95*(-ZL/Z)**(1./3.)
             GO TO 999
          54 WNDCAL=WNDCAL-15.+10.*Z/ZL
999 WNDCAL=WNDCAL/.4
          RETURN
          END

```

```

C
C ***** SUBFILE 5 *****
C

```

```

          FUNCTION TMPCAL(Z0,ZL,Z)
          IMPLICIT INTEGER*4 (I-N)

```

```

C *****
C
C
C
C

```

```

          PURPOSE

```

```

          TO CALCULATE THE POTENTIAL TEMPERATURE SCALED BY THE SCALE
          TEMPERATURE, T*, FROM GIVEN FRICTION HEIGHT AND MONIN-OBUKHOV
          LENGTH AT A SPECIFIED HEIGHT.

```

```

C

```

```

C      INPUTS
C
C      Z0      THE FRICTION HEIGHT IN METERS.
C      ZL      THE MONIN-OBUKHOV LENGTH IN METERS.
C      Z       THE HEIGHT AT WHICH THE SCALED VELOCITY IS DESIRED
C              IN METERS
C
C      RETURNS SCALED TEMPERATURE
C
C      CALLED BY ATMCAL
C
C *****
C      LOGICAL LOW
C      PHIM(Z)=(1.-16.*Z)**(-.25)
C      PSIH(S)=-2.*ALOG((S*S+1.)/2.)
C      PSIHS(Z)=-11.*Z
C
C      PHIM     THE SHEAR OF MOMENTUM
C      PSIH     THE UNIVERSAL FUNCTION FOR DEVIATION FROM LOGARITHMIC
C              POTENTIAL TEMPERATURE PROFILE IN THE BOUNDARY LAYER
C              OF AN UNSTABLE ATMOSPHERE
C      PHIHS    THE SAME AS PHIH EXCEPT FOR STABLE ATMOSPHERE
C
C      IF(ABS(ZL).LE.1.E3)GO TO 100
C      TPCAL=ALOG(1.+Z/Z0)
C      GO TO 999
100  CONTINUE
C      P=SIGN(1.,ZL)
C      LOW=.TRUE.
C      S=Z/ZL
C      IF(S.LE.1.5.AND.S.GE.-2.)GO TO 10
C      S=AMIN1(S,1.5)
C      S=AMAX1(S,-2.)
C      LOW=.FALSE.
10   CONTINUE
C      IF(P)120,130,130
120  S=1./PHIM(S)
C      PSI=PSIH(S)
C      GO TO 52
130  CONTINUE
C      PSI=PSIHS(S)
52   CONTINUE
C      TPCAL=ALOG(1.+Z/Z0)-PSI
C      IF(LOW)GO TO 999
C      IF(P)53,53,54

```



```

C *****
LOGICAL HORIZ
DIMENSION CR(5,4),CD(5,4),OWML(3,4),OWSV(3,4),PRTTN(4)
DIMENSION S(3),BURHTR(5),WTRAT(5)
COMMON/PRTINF/ RO,VGRAV(3),NPRTS
COMMON/BUOYCL/ RSPH,DELT,VXSPH,VZSPH,XCMSPH,ZCMSPH,
* SPHNS(3),RISTIM
COMMON /TMPPRM/ TO,T1,TM
COMMON /WNDPRM/ DXZO,DYXO,DZO,UO,UM,DN,ZINV
COMMON /BURST/ ACCEL,TBURST
COMMON /GEOM/COSTH2,SINTH,SINTH2,VISEXT,RTPI
COMMON /MODE/ HORIZ
COMMON/DISCS/NDSCS,TDSC(10),XDSC(10),ZDSC(10),R2DSC(10),
1 QDSC(10,3)
C
C CR IS THE CRATER RADIUS INDEXED BY COEFFICIENT AND SOIL TYPE
DATA CR/.483,-.328,.0319,.0536,0.,.386,-.291,.0543,.057,11*0./
C CD IS THE CRATER DIAMETER INDEXED BY COEFFICIENT AND SOIL TYPE
DATA CD/.261,-.453,.0681,.224,.055,.198,-.355,.0582,.215,.0586,
1 10*0./
C OWML IS THE OPTICALLY WEIGHTED MASS LOADING COEFFICIENT INDEXED BY
C BIN SIZE AND SOIL TYPE
DATA OWML/1.3E4,2*0.,2.61E4,8*0./
C OWSV IS THE OPTICALLY WEIGHTED PARTICLE SETTLING VELOCITY (CM/SEC)
C INDEXED BY BIN SIZE AND SOIL TYPE
DATA OWSV/12*0./
C PRTTN IS THE PARTITIONING RATIO INDEXED ON SOIL TYPE
DATA PRTTN/4*.9/
C BURHTR IS THE RATIO OF BURST HEIGHT TO INITIAL RADIUS AND WTRAT
C IS THE FRACTION OF THE TOTAL WEIGHT WHICH IS EFFECTIVE IN THE CLOUD
DATA BURHTR/0.,4.,2.,4.,3./,WTRAT/.6,1.,.8,1.,.6/
C
C
RISTM=0.
XCMSPH=0.
NPRTS=1
W3=(W*WTRAT(NCHRG))**.3333333
RO=1.535*W3
TAMB=TO+T1*RO**TM
DELT=.57*TAMB
RSPH=RO
ZCMSPH=RO
VXSPH=UO*ZCMSPH**UM
BURHT=BURHTR(NCHRC)*RO
BURVZ=1.3*SQRT(RO)
TBURST=.15*RO
VZSPH= 2.*BURHT/TBURST-BURVZ
ACCEL=(BURVZ-VZSPH)/TBURST

```

```

      CLAM=DD/W3
C
C  CALCULATE CRATER RADIUS AND DEPTH
C
      RC=CR(1,NSOIL)
      DC=CD(1,NSOIL)
      IF (CLAM.LT.1.E-30) GO TO 98
      TERM=1.
      DO 100 I=2,5
      TERM=TERM*CLAM
      RC=RC + CR(I,NSOIL)*TERM
      DC=DC + CD(I,NSOIL)*TERM
100  CONTINUE
      98  CONTINUE
      RC=RC*W3
      DC=DC*(W*WTRAT(NCHRG))**.3
C
C  GET CRATER VOLUME
C
      VC=(3.1415926/3.) * (RC/DC)**2 * (DC - DSOD)**3
C
C  CALCULATE OPTICALLY WEIGHTED PARAMETERS
C
      NDSCS=MAX0(5,IFIX(5.*W3/2.4))
      DO 101 L=1,NPRTS
      S(L)=OWML(L,NSOIL) * VC
      VGRAV(L)=CWSV(L,NSOIL)
      SPHNS(L)=PRITN(NSOIL) * S(L)
      QDSC(1,L) = (1.-PRITN(NSOIL)) * S(L)/FLOAT(NDSCS)
101  CONTINUE
      DELH=2.*RO/FLOAT(NDSCS)
      Z=-DELH/2.
      DO 200 I=1,NDSCS
      Z=Z+DELH
      ZDSC(I)=Z
      DO 201 J=1,NPRTS
      QDSC(I,J)=QDSC(1,J)
201  CONTINUE
      CON=ALOG(QDSC(1,1)/VISEXT/DELH/(2.*RO)/3.14159)
      IF(CON.GT.1.)GO TO 210
      D=1.
      GO TO 230
210  D=CON
      DO 220 IT=1,5
      D=(CON-1.+ALOG(D))*D/(D-1)
220  CONTINUE
230  R2DSC(I)=4.*RO*RO/D
      TDSC(I)=-DELH*DELH/D/(DZO*Z**DN)/4.

```

```

      SIGZ=DELH*DELH/D
C     WRITE(1,777)SIGZ
      XDSC(1)=U0*Z**UM * TDSC(1)
C     WRITE(1,777)TDSC(1),XDSC(1),ZDSC(1),R2DSC(1),QDSC(1,1)
777  FORMAT(1X,5(1PE10.3))
200  CONTINUE
      RETURN
      END

C           WIND DISPERSION OF DUST CLOUD FOR DIRTRAN-I CODE
C
C ***** SUBFILE 7 *****
C
      FUNCTION FUNCT(X,Z)
      IMPLICIT INTEGER*4 (I-N)
      COMMON /CLOCK/ TIME,TWIND
C *****
C
C     PURPOSE
C
C     TO SUPPLY A TRANSMITTANCE FUNCTION FOR THE CONTOUR TRACING
C     ROUTINE IN ORDER TO DETERMINE THE CLOUD EDGE.
C
C     INPUT
C
C     X   THE HORIZONTAL COORDINATE IN METERS
C     Z   THE VERTICAL COORDINATE IN METERS
C
C     OUTPUT
C
C     RETURNS THE LOG OF THE OPTICALLY WEIGHTED CL VALUE FOR THE
C     LINE-OF-SIGHT SPECIFIED BY X,Z
C
C     FUNCTIONS CALLED
C
C     CWIND
C
C     CALLED BY GFUN, CLIMB, GRAD2
C *****
      Y=0.
C     WRITE(1,1)X,Z,TIME
1    FORMAT(1X,3(1PE10.2))
      IF(Z.LE.0.)GO TO 100
      EXT=CWIND(X,Y,Z,TIME)
      IF(EXT.LE.1.E-30)GO TO 100
      FUNCT=ALOG(EXT)
      GO TO 999

```



```

C
C *****
C
C COMMON /PRTINF/
C
C RO INITIAL RADIUS OF THE CLOUD IN METERS
C VGRAV SINGLY DIMENSIONED ARRAY. VGRAV(I) IS THE OPTICALLY
C WEIGHTED AVERAGE SETTLING VELOCITY FOR PARTICLES IN THE
C I SIZE RANGE
C NPRTS THE NUMBER OF PARTICLE SIZE RANGES
C
C COMMON /DISCS/
C
C NDSCS THE NUMBER OF DISC SOURCES
C TDSC SINGLY DIMENSIONED ARRAY CONTAINING THE TIME OF RELEASE
C OF THE DISC SOURCES
C XDSC SINGLY DIMENSIONED ARRAY CONTAINING THE X COORDINATE
C OF THE CENTER OF THE DISC SOURCES
C ZDSC SINGLY DIMENSIONED ARRAY CONTAINING THE Z COORDINATE
C OF THE CENTER OF THE DISC SOURCES
C R2DSC SINGLY DIMENSIONED ARRAY CONTAINING THE SQUARE OF THE
C RADII OF THE DISC SOURCES
C QDSC DOUBLY DIMENSIONED ARRAY. QDSC(I,J) IS THE NUMBER OF
C PARTICLES OF THE J SIZE RANGE IN THE I DISC.
C
C SUM THE CONTRIBUTIONS OF THE DISC SOURCES TO THE
C OPTICALLY WEIGHTED CONCENTRATION AT X,Y,Z,T
C
C CWIND=0.
C DO 211 I=1,NDSCS
C TOF=T-TDSC(I)
C REFO(1)=XDSC(I)
C REFO(2)=0.
C ROH2=R2DSC(I)
C H=ZDSC(I)
C IF(HORIZ) REFO(1)=REFO(1)*SINTH
C DO 210 J=1,NPRTS
C
C DETERMINE MOMENTS FOR CURRENT SOURCE DISC AT Z
C
C CALL MOMENT(VGRAV(J),Z,H,TOF,Q,XBAR,SIGW2,SIGP2)
C IF(Q.GT.1.E-20) GO TO 113
C
C IF Q IS TOO SMALL, ITS CONTRIBUTION IS INGORED
C
C CWNDS=0.
C GO TO 210

```

```

113 CONTINUE
  RX2=ROH2+2.*SIGW2
  RY2=ROH2+2.*SIGP2
  IF(HORIZ)GO TO 120

```

```

C
C ***** COMPUTE CONCENTRATION AT (X,Y,Z,T)
C

```

```

  ARG=-(X-REF0(1)-XBAR)**2/RX2
  IF(ABS(ARG).GT.30.)GO TO 150
  CWNDSC (Q/RTPI/SQRT(RX2))*EXP(ARG)
  ARG=-(Y-REF0(2))**2/RX2
  IF(ABS(ARG).GT.30.)GO TO 150
  CY=EXP(ARG )/RTPI/SQRT(RY2)
  CWNDSC=QDSC(I,J)*CWNDSC*CY
  GO TO 150

```

```

C
C COMPUTE CONCENTRATION ALONG LINE-OF-SIGHT SPECIFIED BY X,Z
C

```

```

120 CONTINUE
  REF(1)=REF0(1)
  REFF2=RX2*SINTH2+RY2*COSTH2
  ARG=-(X-REF(1)-XBAR*SINTH)**2/REFF2
  IF(ABS(ARG).GT.30.)GO TO 150
  CWNDSC=EXP(ARG) /SQRT(REFF2)/RTPI
  CWNDSC=CWNDSC*Q*QDSC(I,J)

```

```

150 CONTINUE
  CWIND=CWIND+CWNDSC
210 CONTINUE
211 CONTINUE
  RETURN
  END

```

```

C
C ***** SUBFILE 9 *****
C

```

```

  SUBROUTINE CONVRT(T)
  IMPLICIT INTEGER*4 (I-N)
  REAL M,N
  LOGICAL HORIZ
  COMMON/BUOYCL/RSPH,DELT,VXS,1,VZSPH,XCMSPH,ZCMSPH,
  1 SPHNS(3),RISTIM
  COMMON/PRTINF/ RO,VGRAV(?),NPRTS
  COMMON /WNDPRM/DXZO,DYXO,DZO,UG,M,N,ZINV
  COMMON /GEOM/COSTH2,SINTH,SINTH2,VISEXT,RTPI
  COMMON /MODE/ HORIZ
  COMMON/DISCS/NDSCS,TDSC(10),XDSC(10),ZDSC(10),R2DSC(10),
  1 QDSC(10,3)
  COMMON /CLOCK/ TIME,TWIND

```

```

C *****

```

```

C
C
C   PURPOSE
C
C   TO CONVERT THE CURRENT BUOYANT CLOUD INTO DISC SOURCES FOR
C   USE BY THE WIND DISPERSION MODEL
C
C   INPUT
C
C   T           THE TIME IN SECONDS AFTER DETONATION
C
C   OUTPUT
C
C   SUBROUTINES CALLED
C
C   MOMENT      COMPUTES ZERO ORDER MOMENT AND INTERPOLATES FROM
C               TABLE OF HIGHER ORDER MOMENTS.
C
C   CALLED BY FUNCT,DUSTCL
C
C *****
C
C   COMMON /BUOYCL/
C
C   RSPH        RADUIS OF THE SPHERICAL BUOYANT CLOUD IN METERS
C   DELT        TEMPERATURE EXCESS OF CLOUD OVER AMBIENT ATMOSPHERE
C               AT SAME HEIGHT IN DEGREES KELVIN
C   VXSPH       X COMPONENT OF CLOUD VELOCITY IN METERS/SEC
C   VZSPH       Z COMPONENT OF CLOUD VELOCITY IN METERS/SEC
C   XCMSPH      X COORDINATE OF CENTER OF SPHERE IN METERS
C   ZCMSPH      Z COORDINATE OF CENTER OF SPHERE IN METERS
C   SPHNS       SINGLY DIMENSIONED ARRAY.  SPHNS(I) IS THE NUMBER
C               OF PARTICLES OF THE I SIZE RANGE IN THE SPHERE.
C   RISTIM      THE TIME IN SECONDS AFTER DETONATION THAT THE CLOUD
C               HAS RISEN BUOYANTLY
C
C   COMMON /PRTINF/
C
C   RO          INITIAL RADIUS OF THE CLOUD IN METERS
C   VGRAV       SINGLY DIMENSIONED ARRAY.  VGRAV(I) IS THE OPTICALLY
C               WEIGHTED AVERAGE SETTLING VELOCITY FOR PARTICLES IN THE
C               I SIZE RANGE
C   NPTS        THE NUMBER OF PARTICLE SIZE RANGES
C
C   COMMON /DISCS/

```

```

C      NDSCS   THE NUMBER OF DISC SOURCES
C      TDSC    SINGLY DIMENSIONED ARRAY CONTAINING THE TIME OF RELEASE
C             OF THE DISC SOURCES
C      XDSC    SINGLY DIMENSIONED ARRAY CONTAINING THE X COORDINATE
C             OF THE CENTER OF THE DISC SOURCES
C      ZDSC    SINGLY DIMENSIONED ARRAY CONTAINING THE Z COORDINATE
C             OF THE CENTER OF THE DISC SOURCES
C      R2DSC   SINGLY DIMENSIONED ARRAY CONTAINING THE SQUARE OF THE
C             RADII OF THE DISC SOURCES
C      QDSC    DOUBLY DIMENSIONED ARRAY.  QDSC(I,J) IS THE NUMBER OF
C             PARTICLES OF THE J SIZE RANGE IN THE I DISC.
C

```

```

      NSPH=5
      DEL=2./FLOAT(NSPH)
      A2=3./FLOAT(NSPH)**2
      A3=2./FLOAT(NSPH)**3
      DELZ=DEL*RSPPH
      HREF=ZCMSPPH-RSPH-.5*DELZ
      R2=RSPH*RSPPH
      DO 50 I=1, NSPH
      IDSC=NDSCS+I
      ZDSC(IDSC)=HREF+FLOAT(I)*DELZ
      HMZ=ZDSC(IDSC)-ZCMSPPH
      RD2=R2-HMZ*HMZ
      VFRAC=A2*(FLOAT(2*I-1))-A3*FLOAT(3*I*(I-1)+1)
      DO 5 IPRT=1, NPRTS
      QDSC(IDSC, IPRT)=VFRAC*SPHNS(IPRT)
5    CONTINUE
      A=ALOG(QDSC(IDSC,1)/VISEXT/DELZ/SQRT(RD2)/RTPI**2)
      IF(A.GT.1.)GO TO 210
      D=1.
      GO TO 230
210  D=A
      DO 220 IT=1, 5
      D=(A-1.+ALOG(D))*D/(D-1)
220  CONTINUE
230  R2DSC(IDSC)=RD2/D
      GAPTIM=-DELZ*DELZ/D/4./(DZO*ZDSC(IDSC)**N)
      XDSC(IDSC)=UO*ZDSC(IDSC)**M * GAPTIM +XCMSPPH
      TDSC(IDSC)=T+GAPTIM
50   CONTINUE
      NDSCS=NDSCS+NSPH
      TWIND=T
      RETURN
      END

```

```

C      BUOYANTLY RISING DUST CLOUD FOR DIRTRAN-I CODE
C

```

```

C ***** SUBFILE 10 *****

```



```

IF(T2.LE.0.)T2=.5
IF(T2.GT.TNEXT)T2=TNEXT
IF(Y(1)+Y(6).GE.ZINV)GO TO 200
IF (DEL.LT.HMIN)DEL=HMIN
CALL RKM(N,T1,T2,Y,HMIN,DEL,ACCURC,WK,ND)

```

```

C
C CHECK TO SEE IF CLOUD GROWTH IS DOMINATED BY WIND DIFFUSION
C OVER BUOYANT RISE BY COMPARING WIND DIFFUSIVITY, DIFW, TO
C THE EFFECTIVE BUOYANT DIFFUSIVITY, DIFB.
C

```

```

5 DIFB=ABS(.25*Y(1)*Y(4))
DIFW=DZO*(Y(6)+Y(1))*NDIF
IF(DIFB.GT.DIFW)GO TO 15
CALL CONVRT(T2)
GO TO 200
15 CONTINUE
IF(T2.GE.TNEXT)GO TO 200
IF(T2.GT.300.)GO TO 99
20 CONTINUE
99 WRITE(100OUT,98)
98 FORMAT(55H *** DIRTRAN-I ERROR - 5 MINUTE CUT-OFF ON BUOYANT RISE
1)
STOP
200 TPRES=T2
RISTIM=TPRES
999 RETURN
END

```

```

C
C ***** SUBFILE 11 *****
C

```

```

SUBROUTINE DIFEQ(N,T,Y,YP)
IMPLICIT INTEGER*4 (I-N)
DIMENSION Y(N),YP(N)
COMMON/PRTINF/ROCL,VGRAV(3),NPRTS
COMMON /TMPPRM/TO,T1,TM
COMMON/WNDPRM/DXZO,DYXO,DZO,UC,UM,DN,ZINV
COMMON /BURST/ ACCEL,TBURST
DATA ALPHA/.25/

```

```

C *****

```

```

C
C
C
C
C
C
C
C
C

```

PURPOSE

DIFEQ CONTAINS THE PARTIAL DIFFERENTIAL EQUATIONS FOR THE RISE OF A BUOYANT CLOUD WHICH ARE USED BY SUBROUTINE RKM.

INPUT

```

C
C   N           THE NUMBER OF DEPENDENT VARIABLES
C   T           THE INDEPENDENT VARIABLE, I.E. TIME
C   Y(1)        RADIUS OF CLOUD
C   Y(2)        CLOUD TEMPERATURE MINUS SURROUNDING TEMPERATURE
C   Y(3)        CLOUD VELOCITY IN WIND DIRECTION
C   Y(4)        VERTICAL VELOCITY OF CLOUD
C   Y(5)        X-COORDINATE OF CENTER OF MASS FOR THE CLOUD
C   Y(6)        THE HEIGHT OF THE CLOUD C.O.M.
C
C
C   OUTPUT
C
C   YP   AN ARRAY CONTAINING COMPUTED DERIVATIVES OF THE DEPENDENT
C         VARIABLES WITH RESPECT TO THE INDEPENDENT VARIABLE.
C
C
C   REQUIRED FUNCTIONS
C
C         NONE
C
C   CALLED BY RKM
C
C *****
C   IF(T.LT.TBURST)GO TO 200
C   DELT=T1*Y(6)**TM
C   TA=T0+DELT
C   DTADZ=TM*DELT/Y(6)
C   VW=U0*Y(6)**UM
C   VR=SQRT((Y(3)-VW)*(Y(3)-VW)+Y(4)*Y(4))
C
C   TA           THE AMBIENT ATMOSPHERIC TEMPERATURE AT CLOUD HEIGHT
C   DTADZ       THE TEMPERATURE GRADIENT AT CLOUD HEIGHT
C   VW          THE WIND VELOCITY AT CLOUD HEIGHT
C   VR          THE RELATIVE VELOCITY OF THE CLOUD WITH RESPECT TO WIND
C   TR          THE RATIO OF CLOUD TEMPERATURE TO AMBIENT TEMPERATURE
C
C   TR=Y(2)/TA
C
C   CALCULATE ARVOL, THE SURFACE AREA TO VOLUME RATIO
C   WHICH DEPENDS ON THE NUMBER AND PLACEMENT OF CHARGES
C
C   ARVOL=3./Y(1)
10  CONTINUE
C   YP(1)=ALPHA*VR
C   YP(2)=- (1.+TR)*ARVOL*Y(2)*YP(1)-Y(4)*(DTADZ)

```

```

      YP(3)=ARVOL*(VW-Y(3))*YP(1)
      YP(4)=9.8*TR-ARVOL*Y(4)*YP(1)
      YP(5)=Y(3)
      YP(6)=Y(4)
      GO TO 999
200  N=6
      DO 210 I=1,N
        YP(I)=0.
210  CONTINUE
      YP(4)=ACCEL
      YP(5)=Y(3)
      YP(6)=Y(4)
999  RETURN
      END

```

```

C
C ***** SUBFILE 12 *****
C
      SUBROUTINE CLDIM(CNTRD, HEIGHT, CENWTH, SPCHT, SPCWTH, NCPTS, CPTSS,
1 NERR)
      IMPLICIT INTEGER*4 (I-N)
C *****
C
C
C      PURPOSE
C
C      CLDIM CALCULATES FIVE CONTOUR POINTS AND CLOUD DIMENSIONS AS
C      SEEN FROM THE SPECIFIED OBSERVER POSITION. CLDIM REQUIRES CLOUD
C      PARAMETERS FROM THE BUOYANT RISE STAGE OF CLOUD DEVELOPMENT WHICH
C      ARE SUPPLIED IN COMMON STORAGE /BUOYCL/ AND /PRTINF/ AS WELL AS
C      VIEWING GEOMETRY WHICH IS SUPPLIED IN COMMON /GEOM/. SPCHT IS
C      REQUIRED INPUT IN THE ARGUMENTS. ALL OUTPUTS ARE ARGUMENTS.
C
C
C      INPUT
C
C      SPCHT      THE SPECIFIED HEIGHT AT WHICH THE WIDTH OF THE CLOUD
C                 IS DESIRED. (METERS)
C
C
C      OUTPUT
C
C      CNTRD      A SINGLY DIMENSIONED ARRAY OF LENGTH 2 WHICH CONTAINS
C                 THE HORIZONTAL AND VERTICAL COORDINATES, RESP., OF THE
C                 CLOUD CENTROID. (METERS)
C
C      HEIGHT     THE HEIGHT OF THE CLOUD IN METERS
C
C      CENWTH     THE WIDTH OF THE CLOUD AT THE CENTROID HEIGHT IN METERS
C
C      SPCWTH     THE WIDTH OF THE CLOUD AT THE SPECIFIED HEIGHT (METERS)

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C      NCPTS      THE NUMBER OF CONTOUR POINTS (=5)
C      CPTS       A DOUBLY DIMENSIONED ARRAY OF SIZE (2,N),N.GE.5, WHICH
C                CONTAINS THE HORIZONTAL AND VERTICAL COORDINATES OF
C                THE FIVE CONTOUR POINTS. (METERS)

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C      REQUIRED SUBROUTINES

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C          SCONF      MAIN ROUTINE FOR CONTOUR TRACING ALGORITHM.  USED
C                    WITH WIND MODEL.

```

```

C      CALLED BY DUSTCL

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C *****
C      DIMENSION CNTRD(2),CPTS(2,200),CPTS5(2,5)
C      LOGICAL HORIZ,NOCONT
C      COMMON /BUOYCL/RSPH,DELT,VX,VZ,XCM,ZCM,SPHNS(3),TIM
C      COMMON /PRTINF/RO,VGRAV(3),NPRTS
C      COMMON /GEOM/COSTH2,SINTH,SINTH2,VISEXT,RTPI
C      COMMON /MODE/ HORIZ
C      COMMON /CLOCK/ T,TWIND
C      COMMON/WNDPR:/DXZO,DYXO,DZO,UO,UM,DN,ZINV
C      COMMON/DISCS/NDSCS,TDSC(10),XDSC(10),ZDSC(10),R2DSC(10),
C      1 QDSC(10,3)
C      COMMON /SPECS/ RES,STEP,TANT,CON
C      EXTERNAL FUNCT,GFUN
C      DATA      VISEXT,ZMIN,RES,TANT /.1,0.,.4,.1/
C      HORIZ=.TRUE.
C      CON=ALOG(VISEXT)
C      CPTS5(2,1)=SPCHT
C      CPTS5(2,5)=SPCHT
C      U=UO*CPTS5(2,1)**UM
C      CPTS5(1,1)=T*U*SINTH
C      CPTS5(1,5)=CPTS5(1,1)
C      NSERCH=-1
C      STEP=20.
C      CALL CLIMB(FUNCT,GFUN,CPTS5,FP1,NSERCH,NOCONT)
C      NSERCH=1
C      STEP=20.
C      CALL CLIMB(FUNCT,GFUN,CPTS5(1,5),FP1,NSERCH,NOCONT)
C      SPCWTH=CPTS5(1,5)-CPTS5(1,1)
C      NCPTS=5
C      IF(T.LE.TWIND)GO TO 50
C      IND=NDSCS-2
C      CPTS(2,1)=ZDSC(IND)
C      CPTS(1,1)=(XDSC(IND)+(T-TDSC(IND))*UO*ZDSC(IND)**UM)*SINTH
C      STEP=20.
C      CALL SCONF(FUNCT,ZMIN,NCPTS,CPTS,NERR)

```

```

C      IF(NERR.NE.0) GO TO 999
      CALL PTSPEC(NCPTS,CPTS,XHIGH,HEIGHT,XC1,CNTRD,XC2,CENWTH)
      GO TO 100
50    CNTRD(1)=XCM*SINTH
      CNTRD(2)=ZCM
      XHIGH=CNTRD(1)
      HEIGHT=ZCM+RSPH
      CENWTH=2.*(RSPH)
100   CPTS5(1,2)=CNTRD(1)-CENWTH/2.
      CPTS5(1,4)=CNTRD(1)+CENWTH/2.
      CPTS5(1,3)=XHIGH
      CPTS5(2,2)=CNTRD(2)
      CPTS5(2,3)=HEIGHT
      CPTS5(2,4)=CNTRD(2)
      NCPTS=5
999   RETURN
      END

```

C ROUTINE FOR TRACING A CONTOUR OF A FUNCTION OF TWO VARIABLES

C ***** SUBFILE 13 *****

C SCONF IS THE CONTROLLING ROUTINE FOR THE CONTOUR TRACING
C ALGORITHM. THE FUNCTION WHOSE CONTOUR IS DESIRED MUST BE A
C CONTINUOUS, REAL VALUED FUNCTION OF TWO VARIABLES.
C THE CONTOUR FOUND IS ONE CONTINUOUS CLOSED CONTOUR OR
C ONE CONTINUOUS CURVE BEGINNING AND ENDING ON THE SPECIFIED
C BOUNDARY. THERE MAY BE OTHER PIECES TO THE CONTOUR.

C INPUT

| | | |
|---|--------|--|
| C | FUNCT | THE FUNCTION WHOSE CONTOUR IS TO BE FOUND |
| C | CON | THE CONTOUR LEVEL. |
| C | YMN | LOWER BOUND FOR THE SECOND COORDINATE |
| C | RES | THE RESOLUTION LENGTH. |
| C | DELTA | THE INITIAL STEP SIZE WHEN LOOKING ALONG THE |
| C | | GRADIENT TO FIND A POINT ON THE CONTOUR. |
| C | THETAN | THE TANGENT OF THE MAXIMUM ALLOWABLE ROTATION ANGLE |
| C | | BETWEEN SUCCESSIVE LINE SEGMENTS OF THE POLYGONAL |
| C | | CONTOUR. |
| C | MAXDIM | THE NUMBER OF POINTS FOR WHICH STORAGE HAS BEEN |
| C | | ALLOCATED IN THE ARRAY CP. |
| C | CP | A DOUBLY DIMENSIONED ARRAY TO BE FILLED WITH THE |
| C | | COORDINATES OF THE CONTOUR POINTS. CP(I,J) IS THE |
| C | | I-TH COORDINATE, I=1,2 , OF THE J-TH POINT OF THE |
| C | | CONTOUR. UPON CALLING SCONF, CP(1,1),I=1,2 , SHOULD |
| C | | BE THE COORDINATES OF THE BEST GUESS AS TO WHERE THE |

```

C          CONTOUR IS LOCATED.
C
C
C  OUTPUT
C
C      CP      A DOUBLY DIMENSIONED ARRAY FILLED WITH THE
C              COORDINATES OF THE CONTOUR POINTS.  CP(I,J) IS THE
C              I-TH COORDINATE, I=1,2 , OF THE J-TH POINT OF THE
C              CONTOUR.
C
C      MAXDIM  THE NUMBER OF POINTS REPORTED IN CP.
C
C      ERROR   A NUMERICAL FLAG TELLING WHAT TYPE OF ERROR
C              OCCURRED WHILE RUNNING, IF ANY.
C              MEANING OF ERROR CODE-
C              -1=>ARRAY FILLED COMPLETELY
C              0=>CONTOUR CLOSED OR MET BOUNDARIES, NO PROBLEM.
C              1=>NO CONTOUR FOUND
C              2=>PTFIND UNABLE TO FIND NEXT POINT.  CHECK FOR
C                  KINK OR DISCONTINUITY OF THE FUNCTION.
C
C
C  CALLED SUBROUTINES.
C
C      CLIMB   LOCATES FIRST POINT OF CONTOUR OR THAT CONTOUR
C              DOESN'T EXIST.
C
C      PTFIND  FINDS ADDITIONAL POINTS ON THE CONTOUR GIVEN AT LEAST
C              ONE.
C
C
C  LOCAL VARIABLES
C
C      LEFT   A LOGICAL WHICH IS .TRUE. FOR COUNTERCLOCKWISE CONTOUR
C              SEARCH AND .FALSE. FOR CLOCKWISE SEARCH
C
C      TMP    TEMPORARY STORAGE USED FOR SWAPPING POSITIONS IN
C              THE ARRAY OF CONTOUR POINTS.
C
C      NOCONT A LOGICAL ERROR FLAG MEANING EITHER THE CONTOUR
C              DOES NOT EXIST OR IS TOO SMALL TO BE TRACED
C
C      ENDCON A NUMERICAL FLAG INDICATING THE STATUS OF THE
C              CONTOUR POINTS TRACED WITH VALUES:
C              -1    THE ARRAY CP IS FILLED
C              0    THE CONTOUR IS CLOSED
C              1    THE CONTOUR HAS MET A BOUNDARY
C              2    THE REQUIRED STEP SIZE HAS BECOME LESS
C                  THAN THE RESOLUTION
C
C *****
C      SUBROUTINE SCONF(FUNCT,YMN,MAXDIM,CP,ERROR)
C      IMPLICIT INTEGER*4 (I-N)
C      EXTERNAL FUNCT,GFUN

```

```

INTEGER ENDCON, ERROR
LOGICAL NOCONT, ERR, LEFT
DIMENSION          TMP(2)
DIMENSION CP(2, 200)
COMMON/LINE/BASE(2), DIR(2), DFDS/SPECS/RES, DELTA, THETAN, CON
COMMON/LIMIT/YMIN, FMIN
COMMON /IOUNIT/ IOIN, IOOUT, ISPTPF, LOUNIT, NDIRTU, NBSCAT
DATA FMIN/-29./
MAXDIM=200
ERROR=0
YMIN=YMN

C
C FINDING THE POINT ON THE CONTOUR, OR IF A CONTOUR EVEN EXISTS.
C
      NSERCH=0
      CALL CLIMB(FUNCT, GFUN, CP, FCP, NSERCH, NOCONT)
C *** APPROPRIATE ACTION IF THE CONTOUR DOES NOT EXIST,
      IF(NOCONT)GO TO 99
      L=1
      LEFT=.TRUE.
      CALL PTFIND(LEFT, GFUN, MAXDIM, CP, L, ENDCON)

C
C ** THE NEXT TWO DO LOOPS ARE FOR SWITCHING THE POSITIONS
C OF THE POINTS IN THE ARRAY AROUND FOR EASE IN
C WORKING WITH LATER ON.
C
      MID=L/2
      DO 17 I=1, MID
        J=L-I+1
        DO 19 K=1, 2
          TMP(K)=CP(K, I)
          CP(K, I)=CP(K, J)
          CP(K, J)=TMP(K)
        19 CONTINUE
      17 CONTINUE
C ** IS THE CONTOUR CLOSED OR IS THE ARRAY FILLED
      IF(ENDCON)97, 76, 27
      27 IF(ENDCON.EQ.2)ERROR=2
      IF(ENDCON.EQ.2)WRITE(IOOUT, 796)
      LEFT=.FALSE.
      CALL PTFIND(LEFT, GFUN, MAXDIM, CP, L, ENDCON)
      MAXDIM=L
      IF(ENDCON)97, 76, 95
      76 CONTINUE
      MAXDIM=L+1
      CP(1, MAXDIM)=CP(1, 1)
      CP(2, MAXDIM)=CP(2, 1)
      GO TO 98

```

```

95 IF(ENDCON.EQ.1)GO TO 98
96 ERROR=2
   MAXDIM=L
   WRITE(IOOUT,796)
796 FORMAT(53H *** DIRTRAN-I ERROR - CONTOUR TRACING ROUTINE STUCK /
1      56H                                CHECK FOR DISCONTINUITY OF FUNCTION )
   GO TO 999
97 ERROR=-1
   WRITE(IOOUT,797)
797 FORMAT(51H *** DIRTRAN-I ERROR - ARRAY CPTS NOT LARGE ENOUGH )
   GO TO 999
98 ERROR=0
   GO TO 999
99 ERROR=1
   WRITE(IOOUT,799)
799 FORMAT(51H *** DIRTRAN-I WARNING - CLOUD CONTOUR NOT FOUND /
1      49H                                MAY HAVE DISSIPATED )
999 RETURN
   END

```

```

C
C ***** SUBFILE 14 *****
C

```

```

FUNCTION GFUN(S)
  IMPLICIT INTEGER*4 (I-N)

```

```

C
C   GFUN IS THE RESTRICTION OF THE TWO DIMENSIONAL FUNCTION, F, TO
C   A LINE. I.E. FORM  $G(S)=F(X,Y)$ , WHERE  $(X,Y)=BASE+S*DIR$ .
C

```

```

EXTERNAL FUNCT
DIMENSION          P(2)
COMMON/LINE/BASE(2),DIR(2),DFDS/SPECS/RES,DELTA,THETA,CON
CALL VSUM(BASE,DIR,S,P)
GFUN=FUNCT(P(1),P(2))
RETURN
END

```

```

C
C ***** SUBFILE 15 *****
C

```

```

C   THIS MODULE IS A SUBROUTINE THAT FINDS A POINT ON A CONTOUR
C BY FINDING THE GRADIENT VECTOR AT THAT POINT AND MARCHING ALONG
C IT UNTIL IT FINDS ITSELF IN A REGION GREATER THAN THE CONTOUR LEVEL.
C AT WHICH POINT IT MARCHES HORIZONTALLY, HALVING THE STEP SIZE
C UNTIL THE CONTOUR IS REACHED WITHIN SPECIFIED RESOLUTION.
C   IN ADDITION IT WILL DETERMINE IF A CONTOUR EXISTS.
C

```

```

C
C   ARGUMENTS PASSED.
C

```

```

C      INPUT
C      FUNCT-THE FUNCTION(X,Y) ALSO GIVEN IN EXTERNAL.
C      P1-THE STARTING POINT.
C
C      OUTPUT
C
C      P1      - THE POINT ON THE CONTOUR OR THE POINT AT WHICH
C              THE FUNCTION REACHES A MAXIMUM BELOW THE CONTOUR
C              LEVEL
C      FPI     - THE VALUE OF THE FUNCTION AT P
C      NOCONT-THE ERROR FLAG.
C              F-NO PROBLEM
C              T-NO CONTOUR FOUND.
C      ERR-ERROR FLAG RETURNED BY 'NIRSCT'
C              F-NO ERROR
C              T-ITERATION DIVERGED OR MAXIMUM SEARCH AREA EXCEEDED
C
C      IN ADDITION, IN COMMON ARE. .,
C
C      YMIN-THE LOWER LIMIT ON Y.
C      DELTA- THE STEP SIZE, MODIFIED IN THIS SUBROUTINE.
C      CON-THE CONTOUR LEVEL.
C      RES-THE RESOLUTION LENGTH
C
C      OTHER VARIABLES INCLUDE
C      GRAD-THE GRADIENT VECTOR
C      PO-THE CURRENT POINT ON THE GRADIENT.
C      P1-THE POINT ON THE GRADIENT BEING TESTED
C          TO SEE ABOUT CONTOUR EXISTENCE.
C      FPO,FPI-THE FUNCTION VALUES OF PO AND P1.
C
C      CALLED SUBROUTINES
C
C      GRAD2-FINDS THE GRADIENT VECTOR OF A FUNCTION AT
C          A POINT AND THE SLOPE THERE.
C      UNIT-CALCULATES THE NORM AND MAGNITUDE OF A 2 VECTOR.
C      VSUM-VECTOR SUM OF THE FORM C=A+SB WHERE S IS SCALAR
C          MULTIPLIER OF B.
C
C      SUBROUTINE CLIMB(FUNCT,GFUN,P1,FPI,NSERCH,NOCONT)
C      IMPLICIT INTEGER*4 (1-N)
C      EXTERNAL FUNCT,GFUN
C      LOGICAL NOCONT
C      DIMENSION GRAD(2),PO(2),P1(2),P(2)
C      COMMON/LINE/BASE(2),DIR(2),DFDS/SPECS/RES,DELTA,THETA,CON
C      COMMON/LIMIT/YMIN,FMIN
C      NOCONT=.FALSE.

```

```

      ONEM=-1.0
      IF (NSERCH.EQ.0)GO TO 7
      DELTA=SIGN(DELTA,FLOAT(NSERCH))
      FP1=FUNCT(P1(1),P1(2))
      IF(FP1.LT.CON)GO TO 25
      GO TO 22
3     CONTINUE
      PO(1)=P1(1)
      PO(2)=P1(2)
      FP0=FP1
C  ** FINDING THE UNIT GRADIENT AND THE NEXT POINT ALONG IT.
      4 CALL GRAD2(PO,FUNCT,RES,GRAD,DFDS)
      5 CALL VSUM(PO,GRAD,DELTA,P1)
C  ** IS THE POINT HEADING BELOW YMIN **
      IF(P1(2).GE.YMIN)GO TO 7
      P1(2)=YMIN
      CALL VSUM(P1,PO,ONEM,GRAD)
      CALL UNIT(GRAD,GRAD,DELTA)
      IF(ABS(DELTA).LT.RES)GO TO 25
      7 FP1=FUNCT(P1(1),P1(2))
C  ** HAS THE CONTOUR BEEN CROSSED **
      8 IF(FP1.GE.CON)GO TO 22
      IF(FP1.GT.FP0)GO TO 3
      DELTA=DELTA/2.
      IF(ABS(DELTA).LT.RES)GO TO 25
      GO TO 5
      25 NOCONT=.TRUE.
      GO TO 99
      22 CONTINUE
C  BEGIN HORIZONTAL SEARCH
      PO(2)=P1(2)
      31 PO(1)=P1(1)
      FP0=FP1
      40 P1(1)=PO(1)+DELTA
      FP1=FUNCT(P1(1),P1(2))
      IF(ABS(DELTA).LT.RES/2.)GO TO 99
      IF(FP1.GE.CON)GO TO 31
      DELTA=DELTA/2.
      GO TO 40
      99 CONTINUE
      RETURN
      END
C ***** SUBFILE 16 *****
C
C
C
C
C THIS SUBROUTINE CALCULATES THE UNIT GRADIENT VECTOR

```

```

C OF A FUNCTION AT THE GIVEN POINT USING THE FORMULA
C PARTIAL DF/DX = (F(X+R,Y)-F(X,Y))/R WHERE R IS
C SMALL, SIMILARLY FOR PARTIAL DF/DY. IT THEN
C NORMALIZES THE RESULTANT VECTOR FOR THE UNIT GRADIENT
C AND FINDS THE SLOPE, WHICH IS THE MAGNITUDE OF
C OF THE REGULAR GRADIENT.
C
C ARGUMENTS PASSED
C PT-THE POINT AT WHICH THE UNIT GRADIENT IS FOUND.
C FUNCT-THE FUNCTION(X,Y)
C RES-R
C GRAD-THE UNIT GRADIENT
C SLOPE-SLOPE AT PT
C
C OTHER VARIABLES
C COO,C10,C01-THE FUNCTION AT THE POINTS F(X,Y),F(X+R,Y),
C AND F(X,Y+R) RESPECTIVELY.
C
C SUBROUTINES CALLED
C UNIT-NORMALIZES A VECTOR AND FINDS ITS MAGNITUDE.
C
C SUBROUTINE GRAD2(PT,FUNCT,RES,GRAD,SLOPE)
C IMPLICIT INTEGER*4 (I-N)
C DIMENSION PT(2),GRAD(2)
C COO=FUNCT(PT(1),PT(2))
C C10=FUNCT(PT(1)+RES,PT(2))
C C01=FUNCT(PT(1),PT(2)+RES)
C GRAD(1)=(C10-COO)/RES
C GRAD(2)=(C01-COO)/RES
C CALL UNIT(GRAD,GRAD,SLOPE)
C RETURN
C END
C
C ***** SUBFILE 17 *****
C
C THIS SUBROUTINE FINDS THE INTERSECTION OF A LINE SPECIFIED BY
C A BASE POINT, BASE, AND A DIRECTON VECTOR, DIR. THE ROUTINE
C DETERMINES A REAL NUMBER, S, SUCH THAT BASE+S*DIR IS THE
C POINT OF INTERSECTION WITH A CONTOUR THROUGH NEWTON-RAPESON
C ITERATION.
C
C
C INPUT TERMS.
C
C SLIM-THE LIMITING VALUE OF S, TO PREVENT THE INTERPOLATION
C FROM BREAKING DOWN IN UNUSUAL CASES AND GOING INTO AN
C INFINITE LOOP
C GFUN-FUNCTION OF S EQUIVALENT TO FUNCTION(X,Y).

```

```

C
C
C OUTPUT TERMS.
C
C     S-A SCALAR PARAMETER SPECIFYING POINTS ON THE LINE.
C     P-THE POINT OF INTERSECTION.
C     ERR- AN ERROR FLAG.
C         F-NO PROBLEM
C         T-NO INTERSECTION FOUND WITHIN THE SET LIMITATIONS.
C
C TERMS IN COMMON.
C     BASE- A 2-VECTOR CONTAINING THE COORDINATES OF THE BASE
C           POINT OF THE LINE. BASE MUST BE INITIALIZED BEFORE
C           THE CALL TO NTRSCT.
C     DIR- A UNIT DIRECTION 2-VECTOR FOR THE LINE. DIR ALSO MUST
C           BE INITIALIZED PREVIOUS TO THE CALL.
C     CON-THE CONTOUR LEVEL TO BE FOUND.
C     DFDS- DF/DS WITH F=FUNCTION(X,Y), USED AS AN INITIALIZER
C           FOR THE INTERPOLATION. FIRST ONE MUST BE INITIALIZED
C           BEFORE THE CALL.
C     RES-THE RESOLUTION
C
C CALLED SUBROUTINES
C
C     VSUM-VECTOR ADDITION SUBROUTINE OF FORM VSUM(A,B,S,C)=
C           C=A+S*B WHERE A,B,C ARE 2-VECTORS AND S SCALAR.
C
C
C     SUBROUTINE NTRSCT(S,P,GFUN,SLIM,ERR)
C     IMPLICIT INTEGER*4 (I-N)
C     EXTERNAL GFUN,FUNCT
C     LOGICAL ERR
C     DIMENSION F(2)
C     COMMON/LINE/BASE(2),DIR(2),DFDS/SPECS/RES,DELTA,THETAN,CON
C     COMMON/LIMIT/YMIN,FMIN
C     SOLD=0.0
C     ERR=.FALSE.
C
C *** ITER IS THE NUMBER OF ITERATIONS.***
C     ITER=0
C     FSOLD=GFUN(SOLD)
C     IF(FSOLD.LE.FMIN)GO TO 999
C     DS=(CON-FSOLD)/DFDS
C     S=SOLD+DS
C     IF(ABS(S).LT.SLIM)GO TO 110
C     DS=SIGN(SLIM/2.,DS)
C     S=SOLD+DS
C 110 ITER=ITER+1

```

```

FS=GFUN(S)
IF(FS.LE.FMIN)GO TO 999
5 DFDS=(FS-FSOLD)/(S-SOLD)
DS= (CON-FS)/DFDS
SOLD=S
FSOLD=FS
S=S+DS
IF(ABS(DS).LT.RES)GO TO 998
IF(ABS(S).GT.SLIM)GO TO 999
IF(ITER.GT.9)GO TO 999
GO TO 110
998 CALL VSUM(BASE,DIR,S,P)
GO TO 1000
999 ERR=.TRUE.
1000 RETURN
END

```

```

C
C ***** SUBFILE 18 *****
C

```

```

C PTFIND DETERMINES A STRING OF POINTS ON THE CONTOUR MARCHING
C EITHER CLOCKWISE (.NOT.LEFT) OR COUNTERCLOCKWISE (LEFT) UNTIL
C THE CONTOUR CLOSES, A BOUNDARY IS MET, THE ARRAY CPTS IS FILLED,
C OR AN ERROR OCCURS. A STARTING POINT MUST BE PROVIDED. PTFIND
C BEGINS BY CALCULATING THE TANGENT TO THE CONTOUR WHICH IS
C PERPENDICULAR TO THE GRADIENT. SUBSEQUENT POINTS ARE FOUND BY
C EXTENDING THE TANGENT THROUGH THE TWO MOST RECENTLY DETERMINED
C POINTS AND SEARCHING IN THE PERPENDUCULAR DIRECTION. IN CASE
C OF ERROR, ONE RESTART IS ALLOWED.
C THE STEP SIZE, DELTA, IS HALVED WHEN THE EXTRAPOLATED POINT
C EXCEDES BOUNDARY OR THE SEARCH IN THE PERPENDICULAR DIRECTION
C DID NOT YIELD A POINT WITHIN LIMITS DETERMINED BY CURVATURE.
C DELTA IS LENGTHENED INVERSELY AS THE LOCAL CURVATURE OF THE CURVE.
C

```

C INPUT TERMS

```

C GFUN-THE ONE VARIABLE EQUIVALENT TO THE FUNCTION
C RESTRICTED TO A LINE THROUGH POINT, BASE, IN DIRECTION,DIR
C MAXDIM-THE MAXIMUM NUMBER OF POINTS IN THE ARRAY.
C CP-THE ARRAY OF CONTOUR POINTS AS IT INITIALLY IS.
C L-THE INDEX OF HOW MANY POINTS HAD BEEN FOUND BEFORE.
C

```

C OUTPUT TERMS

```

C CP-CURRENT ARRAY OF CONTOUR POINTS
C L-CURRENT INDEX OF POINTS. ON RETURN, L IS
C THE NUMBER OF POINTS FOUND.
C ENDCON-A NUMERICAL FLAG THAT TELLS
C WHY THE SUBROUTINE IS ENDING THE SEARCH.
C ENDCON EQUALS.
C

```

```

C          -1=>THE ARRAY CP IS FILLED.
C          0=>THE CONTOUR IS CLOSED.
C          1=>THE CONTOUR HAS MET A BOUNDARY.
C          2=>REQUIRED STEP SIZE BECAME LESS THAN RESOLUTION
C
C OTHER PERTINENT VARIABLES IN COMMON...
C   CON-THE CONTOUR LEVEL
C   BASE-THE POINT ALONG THE TANGENT.
C   DFDS-THE SLOPE OF THE CURVE.  MODIFIED IN 'NTRSCT'
C   RES-THE RESOLUTION LENGTH
C   DELTA-THE STEP SIZE ALONG THE TANGENT,MODIFIED HERE.
C   THETAN-THE TANGENT OF THETA, THE ANGLESPREAD OF PERMISSIBLE
C           SEARCH AREA. THE SMALLER THETAN IS, THE SMOOTHER THE
C           POLYGON OF CALCULATED POINTS WILL BE.
C   YMIN-LOWER BOUND FOR SECOND COORDINATE
C
C OTHER VARIABLES
C   P1-CURRENT POINT ON CONTOUR
C   PNEXT-NEXT POINT ON CONTOUR,NOT YET APPROVED BY 'ENDTST'.
C   FULTAN-THE APPROXIMATION OF THE TANGENT AT PNEXT BY
C           THE VECTOR FROM P1 TO PNEXT.
C   TAN-THE UNIT VECTOR OF FULTAN
C   DIST-THE MAGNITUDE OF FULTAN,USED IN 'ENDTST'.
C   S-THE DISTANCE ALONG THE GRADIENT FROM BASE TO
C       A POINT ON THE CONTOUR.
C   SMAX-THE LARGEST ALLOWABLE VALUE OF S.
C
C
C SUBROUTINES CALLED.
C
C   VSUM(A,B,S,C)-VECTOR ADDITION OF THE FORM  $C=A+S*B$  WHERE
C           A,B,C ARE 2-VECTORS AND S IS SCALAR.
C   PERP(A,B)-A ,B ARE 2-VECTORS AND B IS A VECTOR ROTATED
C           90 DEGREES COUNTERCLOCKWISE.
C   NTRSCT(S,P,GFUN,SLIM,IC,ERR)-FINDS THE INTERSECTION OF A
C           LINE DRAWN FROM BASE(IN COMMON) ALONG DIR,THE DIRECTION
C           VECTOR(IN COMMON), WITH THE CONTOUR LEVEL (IN COMMON).
C           S IS THE DISTANCE FROM BASE TO THE CONTOUR,P IS THE
C           POINT OF INTERSECTION, GFUN IS GFUN(S) AND IS A ONE
C           VARIABLE EQUIVALENT OF THE FUNCTION WHOSE CONTOUR
C           IS BEING SOUGHT, SLIM IS THE MAXIMUM ALLOWABLE
C           VALUE OF S, AND ERR IS THE ERROR FLAG(LOGICAL).
C           IC IS A LOGICAL VARIABLE WHERE T MEANS FOR
C           NTRSCT TO STOP AFTER 5 ITERATIONS.
C   ENDTST-F(PO,P,TAN,DIST,SMAX,I,M,ENDCON)-FINDS IF
C           THE CONTOUR IS CLOSED, HAS RUN INTO THE Y BOUNDARY
C           OR IF THE ARRAY OF CONTOUR POINTS IS FILLED.

```

```

C      UNIT(A,B,S)-A,B ARE 2-VECTORS AND B IS THE NNORM OF A
C      AND S IS THE MAGNITUDE OF A.
C
C
C
C      SUBROUTINE PTFIND(LEFT,GFUN,MAXDIM,CP,L,ENDCON)
C      IMPLICIT INTEGER*4 (I-N)
C      EXTERNAL GFUN,FUNCT
C      INTEGER ENDCON
C      LOGICAL ERR,ONCE,LEFT
C      DIMENSION CHORD(2),TAN(2)
C      DIMENSION CP(2,MAXDIM)
C      COMMON/LINE/BASE(2),DIR(2),DFDS/SPECS/RES,DELTA,THETA,CON
C      COMMON/LIMIT/YMIN,FMIN
C      ERR=.FALSE.
C      RES2=RES/2.
C
C      INITIALIZE SEARCH FOR CONTOUR POINTS MAKING USE OF THE FACT
C      THAT THE TANGENT TO THE CONTOUR IS PERPENDICULAR TO THE
C      GRADIENT OF THE FUNCTION.
C
C      9  ONCE=.TRUE.
C      CALL GRAD2(CP(1,L),FUNCT,5.*RES,DIR,DFDS)
C      CALL PERP(DIR,TAN)
C      IF(.NOT.LEFT)GO TO 31
C      TAN(1)=-TAN(1)
C      TAN(2)=-TAN(2)
C      DFDS =-DFDS
C      31 DELTA=10.
C      TANTH=1.
C      *** STEPPING DELTA ALONG THE TANGENT ***
C      10 CALL VSUM(CP(1,L),TAN,DELTA,BASE)
C      *** IS BASE BELOW THE MINIMUM PERMISSIBLE Y***
C      IF(BASE(2).GT.YMIN)GO TO 29
C      DELTA=DELTA/2.
C      IF(ABS(DELTA).LT.RES2)GO TO 91
C      GO TO 10
C
C      DETERMINE THE RANGE OF SEARCH PERPENDICULAR TO THE EXTENDED
C      TANGENT, SMAX, AND CALL NTR SCT TO LOCATE THE CONTOUR POINT
C
C      29 SMAX=AMINI(ABS(DELTA*TANTH+RES),ABS((BASE(2)-YMIN)/DIR(2)))
C      DFDSO=DFDS
C      30 CALL NTR SCT(S,CP(1,L+1),GFUN,SMAX,ERR)
C      *** HAS THE CONTOUR BEEN FOUND WITHIN LIMITING CONDITIONS**
C      IF(.NOT.ERR)GO TO 32
C      DFDS=DFDSO
C      DELTA=DELTA/2.

```

```

C
C CHECK TO SEE IF STEP SIZE, DELTA, IS BELOW MINIMUM, RES2.
C IF SO, ALLOW ONE RESTART THEN ABORT
C
C IF(ABS(DELTA).GE.RES2)GO TO 10
C IF(ONCE)GO TO 92
C GO TO 9
C DETERMINE TANGENT FOR NEWLY FOUND POINT
32 CALL VSUM(CP(1,L+1),CP(1,L),-1.,TAN)
C CALL UNIT(TAN,TAN,DIST)
C CALL PERP(TAN,DIR)
C ** IS THE CONTOUR CLOSED **
C WHAT THIS NEXT CHECK DOES IS TO LOOK WITHIN A BOX
C DELTA BY 2*SMAX, WHERE P AND THE PREVIOUS POINT ARE AT EACH
C END OF THE LINE SEGMENT BETWEEN THE MIDPOINTS OF THE TWO
C OPPOSITE SIDES 2*SMAX LONG, TO SEE IF THE STARTING POINT
C IS WITHIN.
C CALL VSUM(CP,CP(1,L),-1.,CHORD)
C VAR1=DOTPRD(DIR,CHORD)
C VAR2=DOTPRD(TAN,CHORD)
C IF(ABS(VAR1).GE.RES*2.)GO TO 35
C IF((VAR2.LT.DIST).AND.(VAR2.GT.0.0))GO TO 90
C BEGIN SEARCH FOR NEXT POINT
35 L=L+1
C IF(CP(2,L).LT.RES2+YMIN)GO TO 91
C IF(L.GE.MAXDIM)GO TO 89
C DELTA=AMINI(10.,DELTA*(SMAX+2.*RES)/((ABS(S)+RES)*2.),DELTA*2.)
C ONCE=.FALSE.
C TANTH=THE TAN
C GO TO 10
89 ENDCON=-1
C GO TO 99
90 ENDCON=0
C L=L+1
C GO TO 99
91 ENDCON=1
C GO TO 99
92 ENDCON=2
99 RETURN
C END

C
C *****~***** SUBFILE 19 *****
C
C SUBROUTINE VSUM(A,B,S,C)
C IMPLICIT INTEGER*4 (I-N)
C DIMENSION A(2),B(2),C(2)
C *** C=A+S*B WHERE A,B,C ARE VECTORS AND S IS SCALAR
C DO 14 J=1,2

```

```
14 C(J)=A(J)+S*B(J)
RETURN
END
```

```
C
C ***** SUBFILE 20 *****
C
```

```
    SUBROUTINE PERP(A,B)
    IMPLICIT INTEGER*4 (I-N)
    DIMENSION A(2),B(2)
C *** B IS ROTATED 90 DEGREES COUNTERCLOCKWISE FROM A
    B(1)=-A(2)
    B(2)=A(1)
    RETURN
    END
```

```
C
C ***** SUBFILE 21 *****
C
```

```
    SUBROUTINE UNIT(A,B,XNORM)
    IMPLICIT INTEGER*4 (I-N)
    DIMENSION A(2),B(2)
C *** B IS THE NORM OF A, AND XNORM IS THE MAGNITUDE
    XNORM=SQRT(A(1)**2+A(2)**2)
    B(1)=A(1)/XNORM!
    B(2)=A(2)/XNORM!
    RETURN
    END
```

```
C
C ***** SUBFILE 22 *****
C
```

```
    FUNCTION DOTPRD(A,B)
    IMPLICIT INTEGER*4 (I-N)
    DIMENSION A(2),B(2)
C
C    DOTPRD IS THE SCALAR PRODUCT OF A AND B
C
    DOTPRD=A(1)*B(1)+A(2)*B(2)
    RETURN
    END
```

```
C
C ***** SUBFILE 23 *****
C
```

```
    THIS SUBROUTINE TAKES AN ARRAY OF POINTS OF A CONTOUR
    AND FINDS THE HIGHEST POINT, THE TWO POINTS ALONG A
    LINE OF SIGHT (THESE TWO MAY NOT BE IN THE ARRAY AND WILL
    BE FOUND BY INTERPOLATION FROM RATIOS) AND THEIR CENTROID,
    THE CENTROID AND THE TWO POINTS WITH THE SAME Y VALUE, THE LENGTH
    OF THE LINE OF SIGHT, AND THE SHEAR DISTANCE. NOTE- THE POINT ON
    THE CENTROID LINE WITH THE GREATER X VALUE IS THE LEADING
```

```

C   EDGE POINT.
C
C   INPUT TERMS
C
C       SPCHT-A SPECIFIED HEIGHT AT WHICH THE WIDTH IS DESIRED
C       CP-THE ARRAY OF CONTOUR POINTS
C       L-THE NUMBER OF POINTS IN CP.
C
C
C   OUTPUT TERMS
C
C       ZHI- Z COORDINATE OF HIGHEST POINT ON CONTOUR.
C       XHI- X COORDINATE OF HIGHEST POINT ON CONTOUR.
C       XCL- X COORDINATE OF LEFTMOST POINT ON CONTOUR.
C       XCR- X COORDINATE OF RIGHTMOST POINT ON CONTOUR.
C       CNTRD-THE CENTROID
C       CENWTH- WIDTH AT THE CENTROID HEIGHT
C       XSPCL- X COORDINATE OF LEFTMOST POINT OF CONTOUR AT THE
C               SPECIFIED HEIGHT, SPCHT
C       XSPCR- X COORDINATE OF RIGHTMOST POINT OF CONTOUR AT THE
C               SPECIFIED HEIGHT
C       SPCWTH- THE WIDTH OF THE CONTOUR AT THE SPECIFIED HEIGHT
C
C   SUBROUTINES CALLED
C
C       INTRP-PERFORMS A SIMPLE INTERPOLATION BY RATIO TO FIND
C           A POINT WITH A GIVEN Y COORDINATE, GIVEN A POINT
C           ON EITHER SIDE. THE CALL IS
C           CALL INTRP(P1,P2,Y,P) WHERE P1,P2 ARE THE GIVEN
C           POINTS, Y THE GIVEN Y COORD., AND P THE POINT RETURNED.
C
C       IN INTRP... VSUM(A,B,S,C) WHERE A,B,S ARE GIVEN AND
C           C=A+S*B. A,B,C ARE 2-VECTORS AND S, A SCALAR.
C
C
C   SUBROUTINE PTSPEC(L,CP,XHI,ZHI,XCL,CNTRD,XCR,CENWTH)
C   IMPLICIT INTEGER*4 (1-N)
C   DIMENSION CNTRD(2),CP(2,L)
C   LOGICAL ERR,BTWN
C   BTWN(A,B,C)=(A.LE.B.AND.B.LT.C).OR.(A.GE.B.AND.B.GT.C)
C   ERR=.FALSE.
C   NHI=1
C   NLO=1
C   NL=1
C   NR=1
C   DO 10 J=1,L
C   IF(CP(2,J).GT.CP(2,NHI))NHI=J
C   IF(CP(2,J).LT.CP(2,NLO))NLO=J

```

```

      IF(CP(1,J).LT.CP(1,NL))NL=J
      IF(CP(1,J).GT.CP(1,NR))NR=J
10  CONTINUE
      XHI=CP(1,NHI)
      ZHI=CP(2,NHI)
      CNTRD(2)=AMAX1(CP(2,NL),CP(2,NR))
      NCR=NL
      NCL=NR
      DO 20 J=1,L
      IF(.NOT.BTWN(CP(2,J),CNTRD(2),CP(2,J+1)))GO TO 20
      IF(CP(1,J).LT.CP(1,NCL))NCL=J
      IF(CP(1,J).GT.CP(1,NCR))NCR=J
20  CONTINUE
      CALL INTRP(CP(1,NCL),CP(1,NCL+1),CNTRD(2),XCL)
      CALL INTRP(CP(1,NCR),CP(1,NCR+1),CNTRD(2),XCR)
      CNTRD(1)=(XCL+XCR)/2.
      CENWTH=XCR-XCL
C      IF(.NOT.BTWN(ZLO,SPCHT,ZHI))GO TO 99
C      NCR=NL
C      NCL=NR
C      DO 30 J=1,L
C      IF(.NOT.BTWN(CP(2,J),SPCHT,CP(2,J+1)))GO TO 30
C      IF(CP(1,J).LT.CP(1,NCL))NCL=J
C      IF(CP(1,J).GT.CP(1,NCR))NCR=J
C 30  CONTINUE
C      CALL INTRP(CP(1,NCL),CP(1,NCL+1),SPCHT,XSPCL)
C      CALL INTRP(CP(1,NCR),CP(1,NCR+1),SPCHT,XSPCR)
C      SPCWTH=XSPCR-XSPCL
C      GO TO 999
C 999 ERR=.TRUE.
C      XSPCL=0.0
C      XSPCR=0.0
C      SPCWTH=0.0
999  RETURN
      END

C
C ***** SUBFILE 24 *****
C
      SUBROUTINE INTRP(P1,P2,Y,X)
      IMPLICIT INTEGER*4 (I-N)
C *****
C
C      GIVEN POINTS P1 AND P2 AND SECOND COORDINATE, Y,
C      INTRP DETERMINES THE FIRST COORDINATE, X, OF A POINT, (X,Y),
C      WHICH IS ON A LINE DRAWN THROUGH P1 AND P2
C
C *****
      DIMENSION P1(2),P2(2),P(2),DIF(2)

```

```

IF(ABS(P2(2)-P1(2)).LT.1.E-30)GO TO 89
RATIO=(Y-P1(2))/(P2(2)-P1(2))
ONEM=-1.
CALL VSUM(P2,P1,ONEM,DIF)
CALL VSUM(P1,DIF,RATIO,P)
X=P(1)
GO TO 99
89 X=P1(1)
99 RETURN
END

```

C CALCULATION OF 0-ORDER AND INTERPOLATION OF HIGHER ORDER MOMENTS

C
C
C
C

***** SUBFILE 25 *****

```

SUBROUTINE MOMENT(VGRAV,ZIN,H,TIN,Q,XBAR,SIGW2,SIGP2)
IMPLICIT INTEGER*4 (I-N)
REAL M,N,NM
DIMENSION AL(9),Z(9),T(9),XB(81,4,4),SW(81,4,4),SP(81,4,4),NM(9)
DIMENSION VAL(16),XVAL(8),W(8),XI(4),IB(4),NTC(4),II(4),X(9,4)
LOGICAL FIRST
COMMON /WDPDM/DXZO,DYXO,DZO,UO,M,N,ZINV
COMMON /IUNIT/ IOIN,IOOUT,ISPTPF,LOUNIT,NDIRTU,NBSCAT
EQUIVALENCE (Z(1),X(1,1)),(T(1),X(1,2)),(AL(1),X(1,3))
EQUIVALENCE (NM(1),X(1,4))
DATA FIRST/.TRUE./,IB/4,4,1,3/,ITC/11/,HREF/1./

```

C *****

C
C
C

PURPOSE

C
C
C
C
C

TO CONVERT PARAMETERS TO NONDIMENSIONAL FORM AND THEN COMPUTE
THE ZERO ORDER MOMENT AND INTERPOLATE FROM TABULATED VALUES OF
THE HIGHER ORDER MOMENTS

C
C

INPUT

C
C
C
C
C
C

VGRAV THE GRAVITATIONAL SETTLING VELOCITIES OF THE PARTICLE
IN METERS / SEC
ZIN THE HEIGHT (METERS) AT WHICH THE MOMENTS ARE DESIRED
H THE HEIGHT OF RELEASE OF THE PARTICLES IN METERS
TIN THE TIME IN SECONDS AFTER RELEASE

C
C

OUTPUT

C
C
C
C
C

Q THE VERTICAL CONCENTRATION OF PARTICLES IN PARTS/METER
AT HEIGHT Z
XBAR THE DISPLACEMENT (METERS) IN THE X (IE WIND) DIRECTION
OF THE CENTER OF MASS OF PARTICLES AT HEIGHT Z

```

C      SIGW2  THE SQUARE OF THE STANDARD DEVIATION OF THE WINDWARD
C      DISPLACEMENT OF THE PARTICLES AT HEIGHT Z IN METERS**2
C      SIGP2  THE SQUARE OF THE STANDARD DEVIATION OF THE CROSS-WIND
C      DISPLACEMENT OF THE PARTICLES AT HEIGHT Z IN METERS**2
C
C
C      SUBROUTINES CALLED
C
C      DTERPS  PUTS THE NEEDED VALUES OF THE TABULATED MOMENTS
C      INTO A ONE DIMENSIONAL ARRAY
C      DTERPI  A FUNCTION WHICH RETURNS THE INTERPOLATED VALUE
C      FOR GIVEN ARGUMENTS AND ARRAYS
C      GREEN   CALCULATES THE GREENS FUNCTION WHICH IS THE
C      0-ORDER MOMENT
C
C      CALLED BY CWIND
C
C      *****
C      IF(.NOT.FIRST)GO TO 5
C
C      READ IN THE TABLE OF MOMENTS ON THE FIRST CALL OF MOMENT
C
C      Z      LOG OF NON-DIMENSIONAL HEIGHTS AT WHICH MOMENTS ARE TABULATED
C      T      LOG OF NON-DIMENSIONAL TIMES   AT WHICH MOMENTS ARE TABULATED
C      AL     NON-DIMENSIONAL SETTLING VELOCITIES AT WHICH MOMENTS ARE
C      TABULATED
C      NM     DIFFUSIVITY POWER LAW EXPONENTS AT WHICH MOMENTS ARE
C      TABULATED
C
C      XB     TABULATED VALUES OF LOGS OF FIRST ORDER MOMENTS (RELATED
C      TO MEAN HORIZONTAL DISPLACEMENT)
C      SW     TABULATED VALUES OF LOGS OF WIND SHEAR COMPONENT OF SECOND
C      ORDER MOMENT (CONTRIBUTES TO VARIANCE IN WIND DIRECTION)
C      SP     TABULATED VALUES OF LOGS OF SECOND ORDER MOMENT COMMON TO
C      WIND AND CROSS-WIND VARIANCES
C
C      READ(NDIRTU,1) NZ,NT,NA,NN
C      1 FORMAT(4I3)
C      NTC(1)=NZ-1
C      NTC(2)=NT-1
C      NTC(3)=NA-1
C      NTC(4)=NN-1
C      READ(NDIRTU,2) (Z(I),I=1,NZ)
C      2 FORMAT(6E13.5)
C      READ(NDIRTU,2) (T(I),I=1,NT)
C      READ(NDIRTU,2) (AL(I),I=1,NA)
C      READ(NDIRTU,2) (NM(I),I=1,NN)
C      NZT=NZ*NT

```

```

DO 3 L=1,NN
READ(NDIRTU,2) ((XB(IJ,K,L),IJ=1,NZT),K=1,NA)
READ(NDIRTU,2) ((SW(IJ,K,L),IJ=1,NZT),K=1,NA)
READ(NDIRTU,2) ((SP(IJ,K,L),IJ=1,NZT),K=1,NA)
3 CONTINUE
FIRST=.FALSE.
REWIND NDIRTU
5 CONTINUE

C
C CONVERT INPUT PARAMETERS TO NONDIMENSIONAL FORM
C
SCLU=DZO*H**(N-1.)
XI(1)=ZIN/H
XI(2)=SCLU*TIN/H
XI(3)=VGRAV/SCLU
XI(4)=N
CALL GREEN(XI(1),HREF,XI(2),XI(3),Q,IER)
Q=Q/H
IF(Q .LE. 1.E-20) GO TO 999

C
C TAKE LOGS FOR LOGARITHMIC INTERPOLATION
C
XI(1)=ALOG(XI(1))
XI(2)=ALOG(XI(2))

C
C DETERMINE INDICES OF LOWEST CORNER POINT OF THE CUBE TO
C BE USED IN INTERPOLATION MAKING SURE THAT ENOUGH CORNER POINTS
C OF THE CUBE HAVE TABULATED VALUES
C
DO 100 I=1,4
II(I)=IB(I)
100 CONTINUE
DO 101 III=1,4
I=5-III
6 IA=II(I)
IF(XI(I) .GE. X(IA,I) .AND. X(IA,I) .LE. X(IA+1,I)) GO TO 101
IF(XI(I) .LT. X(IA,I) .AND. IA .EQ. 1) GO TO 101
IF(XI(I) .GT. X(IA,I) .AND. IA .EQ. NTC(I)) GO TO 101
ISAV=II(I)
II(I)=IA + IFIX(SIGN(1.,XI(I)-X(IA,I)))
IT=0
DO 102 JI=1,2
JIX=JI + II(1) - 1
DO 102 IJ=1,2
IJX=JIX + (IJ + II(2) - 2)*NZ
DO 102 K=1,2
KX=K-1 + II(3)
DO 102 L=1,2

```

```

LX=L-1 + II(4)
IF(XB(IJX,KX,LX) .GT. -100.) IT=IT+1
102 CONTINUE
IF(IT .GT. ITC) GO TO 6
II(I)=ISAV
101 CONTINUE
C
C   PERFORM THE INTERPOLATION WITH DETERMINED CUBE OF POINTS
C
DO 103 I=1,4
I2=I*2
I1=I2-1
IA=II(I)
XVAL(I1)=X(IA,I)
XVAL(I2)=X(IA+1,I)
103 CONTINUE
CALL DTERPS(I1,XB,VAL,NZ)
XBAR=DTERPI(4,XI,XVAL,VAL,-100.,W)
CALL DTERPS(I1,SW,VAL,NZ)
SIGW2=DTERPI(-4,XI,XVAL,VAL,-100.,W)
CALL DTERPS(I1,SP,VAL,NZ)
SIGP2=DTERPI(-4,XI,XVAL,VAL,-100.,W)
C
C   CONVERT THE LOG OF THE NONDIMENSIONAL VALUES INTERPOLATED
C   TO THE USUAL DIMENSIONAL FORM
C
SCL=UO*H**(M+1.)/SCLU
XBAR=SCL*EXP(XBAR)
SIGW2=SCL*SCL*EXP(SIGW2)
SIGP2=2.*DXZO*H*H*EXP(SIGP2)
SIGW2=SIGW2+SIGP2
SIGP2=DYXO*SIGP2
999 RETURN
END
C
C ***** SUBFILE 26 *****
C
SUBROUTINE DTERPS(II,X,VAL,NZ)
IMPLICIT INTEGER*4 (I-N)
DIMENSION X(81,4,4),VAL(1),II(1)
C *****
C
C   PURPOSE
C
C   TO SET UP A ONE DIMENSIONAL ARRAY OF THE VALUES CORRESPONDING
C   TO THE CORNERS OF THE CUBE WITHIN A TABULATED ARRAY WITH
C   LOWEST CORNER INDICES GIVEN

```

```

C
C INPUT
C
C II SINGLY DIMENSIONED ARRAY CONTAINING THE INDICES OF THE
C LOWEST CORNER OF THE CUBE
C X A TRIPLY DIMENSIONED ARRAY CONTAINING THE TABULATED
C V^201ALUES TO BE SET UP. THE FIRST INDEX IS THE COLLAPSED
C INDEX FOR THE FIRST TWO INDICES OF A FOUR DIMENSIONAL
C ARRAY
C NZ THE RANGE OF THE FIRST INDEX OF THE FOUR DIMENSIONAL
C ARRAY
C
C OUTPUT
C
C VAL SINGLY DIMENSIONED ARRAY CONTAINING THE VALUES OF X
C FOR THE 16 CORNER POINTS OF THE CUBE
C
C CALLED BY MOMENT
C
C *****
C M=0
C DO 104 L=1,2
C LX=L + II(4) - 1
C DO 103 K=1,2
C KX=K + II(3) - 1
C DO 102 JI=1,2
C JIX=(JI + II(2) - 2)*NZ
C DO 101 IJ=1,2
C IJX=JIX + IJ + II(1) -1
C M=M+1
C VAL(M)=X(IJX,KX,LX)
101 CONTINUE
102 CONTINUE
103 CONTINUE
104 CONTINUE
C RETURN
C END
C
C ***** SUBFILE 27 *****
C
C FUNCTION DTERPI (NDIM,XI,XVAL,VAL,VMIN,WORK)
C IMPLICIT INTEGER*4 (I-N)
C *****
C
C PURPOSE
C

```

```

C PERFORMS AN N-DIMENSIONAL LINEAR INTERPOLATION
C
C
C INPUT
C
C NDIM - THE NUMBER OF DIMENSIONS. (- DONT RECALCUALTE WEIGHTS)
C XI - THE POINT IN THE HYPERSPACE AT WHICH THE INTERPOLATED
C VALUE IS DESIRED. XI MUST BE A VECTOR OF ATLEAST NDIM
C IN LENGTH.
C XVAL - THE COORDINATE VALUES AT THE CORNERS OF THE HYPERCUBE.
C THE VECTOR MUST BE SET UP LIKE A TWO-DIMENSIONAL ARRAY
C (2 X NDIM), WHERE THE FIRST SUBSCRIPT REFERS TO THE
C HYPERCUBE COORDINATES IN THE SECOND SUBSCRIPTS
C DIRECTION.
C VAL - THE FUNCTIONAL VALUES AT THE CORNERS OF THE HYPERCUBE
C SURROUNDING XI. THIS VECTOR MUST BE FILLED EQUIVALENT
C TO AN NDIM ARRAY WITH EACH DIMENSION AS 2. THE SIZE
C OF VAL SHOULD BE ATLEAST 2**NDIM.
C VMIN - A MINIMUM VALUE OF VAL FOR WHICH THE INTERPOLATION
C WILL USE A CORNER VALUE.
C WORK - A WORK VECTOR OF ATLEAST NDIM*2. USE TO STORE COOR-
C DINATE WEIGHTS.
C
C
C OUTPUT
C
C RETURNS INTERPOLATED VALUE OF VAL AT XI
C
C CALLED BY MOMENT
C
C *****
C DIMENSION XI(1),XVAL(1),VAL(1),WORK(1)
C
C SET UP THE COORDINATE WEIGHTS
C
C NDI=IABS(NDIM)
C IF(NDIM .LT. 0) GO TO 1
C DO 100 I=1,NDI
C I2=I*2
C I1=I2-1
C WORK(I2)=(XI(I)-XVAL(I1))/(XVAL(I2)-XVAL(I1))
C WORK(I1)=1. - WORK(I2)
100 CONTINUE
C
C INTERPOLATE - USE BINARY COUNTER FOR COORDINATE LOCATION
C
1 DTERPI=0.
SUM=0.

```

```

ND=2**NDI
DO 201 I=1,ND
IF(VAL(I) .LT. VMIN) GO TO 201
L=I-1
WEIGHT=1.
DO 200 J=1,NDI
N=MOD(L,2) + J*2 - 1
WEIGHT=WEIGHT*WORK(N)
L=L/2
200 CONTINUE
SUM=SUM + WEIGHT
DTERPI=DTERPI + WEIGHT*VAL(I)
201 CONTINUE
IF(SUM .EQ. 0.) GO TO 202
DTERPI=DTERPI/SUM
RETURN
C
202 STOP
END

C
C ***** SUBFILE 28 *****
C
SUBROUTINE GREEN(Z,Z1,I,ALPHA,TO,IER)
IMPLICIT INTEGER*4 (I-N)
C *****
C
C PURPOSE
C
C TO COMPUTE THE GENERALIZED GREENS FUNCTION
C
C USES GREEN1
C
C SEE GREEN1 FOR ARGUMENT LIST
C
C *****
C REAL N,M
COMMON /WNDPRM/DXZO,DYXO,DZO,UO,M,N,ZINV
C
IF(N .EQ. 1.) GO TO 2
X2=2.-N
AT=ALPHA*T
T0=0.
IF(AT .GE. Z1) RETURN
CALL GREEN1((Z+AT)**X2,Z1**X2,X2*X2*T,(N-1.)/X2,T1,IER)
T1=T1*X2*Z1**(1.-N)
U=1.
T2=0.
IF(ABS(ALPHA) .LT. 1.E-4) GO TO 1
ZM2=Z-Z1+AT
X2=N+1.
AN1=ALPHA*X2
ZMZN=Z1**X2 - (Z1-AT)**X2
ARG=(-AN1*ZM2*ZM2)/(4.*ZMZN)
IF(ARG .LT. -70.) GO TO 3
T2=SQRT(AN1/(4.*3.1415926*ZMZN))*EXP(ARG)

```



```

C          UNCHANGED.  BESI IS IN THE IBM SYSTEM/360 SCIENTIFIC SUBROUTINE
C          PACKAGE.  MODIFICATIONS MADE BY D. DWORE, AERODYNE RESEARCH,
C          INC. JANUARY 15,1979.
C
C          SUBROUTINES AND FUNCTIONS REQUIRED
C          GAMMA WHICH COMPUTES THE GAMMA FUNCTION
C
C          METHOD
C          COMPUTES I BESSEL FUNCTION USING SERIES OR ASYMPTOTIC
C          APPROXIMATION DEPENDING ON THE RANGE OF THE ARGUMENT.
C
C          CALLED BY MOMENT
C
C          .....
C          SUBROUTINE GREEN1(Z,Z1,T,NU,BI,IER)
C          IMPLICIT INTEGER*4 (I-N)
C          REAL NU
C          X=2.*SQRT(Z*Z1)/T
C
C          CHECK FOR ERRORS IN NU AND X AND EXIT IF ANY ARE PRESENT
C
C          IER=0
C          BI=1.0
C          IF(NU)10,15,10
C          10 IF(X)160,20,20
C          15 IF(X)160,17,20
C          17 ARG=-(Z+Z1)/T
C          IF(ARG .LT. -80.) GO TO 170
C          BI=EXP(ARG)/T
C          RETURN
C
C          DEFINE TOLERANCE
C
C          20 TOL=1.E-3
C
C          IF ARGUMENT GT 12 AND GT NU, USE ASYMPTOTIC FORM
C
C          IF(X-12.)40,40,30
C          30 IF(X-ABS(NU))40,40,110
C
C          COMPUTE FIRST TERM OF SERIES AND SET INITIAL VALUE OF THE SUM
C
C          40 XX=X/2.
C          N=INT(NU)
C          FN=N
C          R=NU-FN
C          CALL GAMMA(1.+NU,GR,IER)
C          IF(IER .EQ. 0) GO TO 60
C          50 BI=0.0
C          RETURN
C          60 TERM=1./GR
C          70 BI=TERM!
C          XX=XX*XX
C
C          COMPUTE TERMS, STOPPING WHEN ABS(TERM!) LE ABS(SUM OF TERMS)*TOLERANCE
C
C          DO 90 K=1,1000
C          IF(ABS(TERM)-ABS(BI*TOL))95,95,80
C          80 FK=K
C          FK=FK*(NU+FK)
C          TERM=TERM*(XX/FK)
C          90 BI=BI+TERM!
C          95 ARG=-(Z+Z1)/T

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IF(ARG .LT. -80.) GO TO 170
BI=BI*(Z1/T)**NU*EXP(ARG)/T
C
C
C
RETURN BI AS ANSWER
C
100 RETURN
C
C
X GT 12 AND X GT NU, SO USE ASYMPTOTIC APPROXIMATION
C
110 FN=4.*NU*NU
115 XX=1./(8.*X)
TERM=1.
BI=1.
DO 130 K=1,30
IF(ABS(TERM)-ABS(BI*TOL)) 140,140,120
120 FK=(2*K-1)**2
TERM=TERM*XX*(FK-FN)/FLOAT(K)
130 BI=BI+TERM
C
C
SIGNIFICANCE LOST AFTER 30 TERMS, TRY SERIES
C
GO TO 40
140 PI=3.141592653
ARG=X-(Z+Z1)/T
IF(ARG .LT. -80.) GO TO 170
BI=BI*(Z1/Z)**(NU/2.)*EXP(ARG)/SQRT(2.*PI*X)/T
GO TO 100
160 IER=5
GO TO 100
170 BI=0.C
GO TO 50
END
C
***** SUBFILE 30 *****
C
C
C
.....
C
SUBROUTINE GAMMA
C
PURPOSE
COMPUTES THE GAMMA FUNCTION FOR A GIVEN ARGUMENT
C
USAGE
CALL GAMMA(XX,GX,IER)
C
DESCRIPTION OF PARAMETERS
XX -THE ARGUMENT FOR THE GAMMA FUNCTION
GX -THE RESULTANT GAMMA FUNCTION
IER -THE RESULTANT ERROR CODE WHERE
IER=0 NO ERROR
IER=1 XX IS WITHIN .000001 OF BEING A NEGATIVE INTEGER
IER=2 XX GT 57, OVERFLOW, GX SET TO 1.E22
C
COMMENTS
NONE
C
SUBROUTINES AND FUNCTIONS
NONE
C
METHOD
THE RECURSION RELATION AND POLYNOMIAL APPROXIMATION
BY C. HASTINGS, JR., 'APPROXIMATIONS FOR DIGITAL COMPUTERS',
PRINCETON UNIVERSITY PRESS, 1955
C

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C
C .....
C
SUBROUTINE GAMMA(XX, GX, IER)
  IMPLICIT INTEGER*4 (I-N)
  IF(XX-57.) 6,6,4
4  IER=2
  GX=1.E32
  RETURN
6  X=XX
  ERR=1.0E-6
  IER=0
  GX=1.0
  IF(X-2.0) 50,50,15
10 IF(X-2.0) 110,110,15
15 X=X-1.0
  GX=GX*X
  GO TO 10
50 IF(X-1.0) 60,120,110
C
C   SEE IF X IS NEAR NEGATIVE INTEGER OR ZERO
C
60 IF(X-ERR) 62,62,80
62 Y=FLOAT(INT(X))-X
  IF(ABS(Y)-ERR) 130,130,70
C
C   X NOT NEAR A NEGATIVE INTEGER OR ZERO
C
70 IF(X-1.0)80,80,110
80 GX=GX/X
  X=X+1.0
  GO TO 70
110 Y=X-1.0
  GY=1.0+Y*(-0.5771017+Y*(0.9858540+Y*(-0.8764218+Y*(0.8328212+
  1Y*(-0.5684729+Y*(0.2548205+Y*(-0.0514993C))))))
  GX=GX*GY
120 RETURN
130 IER=1
  RETURN
  END
SUBROUTINE RKM(N, XL, XU, Y, HMIN, DEL, ACCURC, WK, ND)
  IMPLICIT INTEGER*4 (I-N)
C
C NUMERICAL INTEGRATION ROUTINE FOR SYSTEMS OF ODE'S
C   USING THE RUNGE-KUTTA-MERSON TECHNIQUE
C
C INPUT PARAMETERS
C
C   N - NUMBER OF FIRST ORDER DIFFERENTIAL EQUATIONS
C   XL - INITIAL ABCISSA OF THE INTERVAL
C   XU - THE FINAL ABCISSA OF THE INTEGRATION INTERVAL
C   Y - A SINGLY DIMENSIONED ARRAY OF LENGTH N. WHEN
C       RKM IS CALLED IT MUST CONTAIN THE VALUES OF
C       THE DEPENDENT VARIABLES AT XL. UPON RETURN
C       TO THE CALLING PROGRAM Y CONTAINS THE VALUES
C       OF THE DEPENDENT VARIABLES AT XU.
C   HMIN - THE MINIMUM STEP SIZE THAT WILL BE USED FOR THE
C          INTEGRATION
C   DEL - THE INITIAL ESTIMATE OF THE STEP SIZE AND UPON
C         RETURN TO THE CALLING PROGRAM DEL CONTAINS THE
C         FINAL STEP SIZE USED. THIS VALUE SHOULD BE USED
C         IN THE NEXT CALL TO PRODUCE AN EFFICIENT INTEGRATION.

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C          DEL IS RETURNED WITH THE VALUE ZERO IF IT HAS
C          BEEN HALVED BELOW HMIN.
C ACCURC - PREASSIGNED ACCURACY WHICH IS ALSO USED IN ADJUSTING
C          THE STEP SIZE.
C WK - AT LEAST A BLOCK OF N BY 6 FLOATING POINT LOCATIONS
C          USED FOR A WORK ARRAY.
C ND - THE DIMENSION OF ARRAYS Y AND WK.
C
C          IT IS REQUIRED THAT THE USER OF RKM WRITE A SUBROUTINE
C          DEFINING THE DIFFERENTIAL EQUATIONS. THE SUBROUTINE
C          STATEMENT SHOULD LOOK LIKE - SUBROUTINE DIFEQ(N,X,Y,YP) .
C
C WHERE
C N - THE NUMBER OF EQUATIONS
C X - THE INDEPENDENT VARIABLE
C Y - SINGLY DIMENSIONED ARRAY OF DEPENDENT VARIABLES
C YP - SINGLY DIMENSIONED ARRAY OF THE RATES OF Y AT X
C           $YP(I) = D Y(I)/DX$ 
C
C          DIMENSION Y(ND),WK(ND,6)
C          LOGICAL FIRST,QUIT
C
C          SET UP NEEDED VARIABLES UPON ENTRY
C
C          XN=XL
C          H=DEL
C          FIRST=.TRUE.
C          QUIT=.FALSE.
C
C          CHECK IF XN IS CLOSE TO XU
C
C          20 IF(XN+H .LT. XU) GO TO 30
C          DEL=H
C          H=XU-XN
C          QUIT=.TRUE.
C          IF(FIRST) DEL=H
C
C          MAKE FIRST CALL TO DIFEQ AT THE BEGINNING OF INTERVAL
C
C          30 CALL DIFEQ(N,XN,Y,WK(1,1))
C
C          PERFORM THE RUNGE-KUTTA-MERSON ALGORITHM
C
C          40 H3=H/3.
C          DO 50 I=1,N
C          WK(I,3)=H3*WK(I,1)
C          50 WK(I,6)=Y(I)+WK(I,3)
C          CALL DIFEQ(N,XN+H3,WK(I,6),WK(I,2))
C          DO 60 I=1,N
C          60 WK(I,6)=Y(I)+(WK(I,3)+H3*WK(I,2))/2.
C          CALL DIFEQ(N,XN+H3,WK(I,6),WK(I,2))
C          DO 70 I=1,N
C          WK(I,4)=H3*WK(I,2)
C          70 WK(I,6)=Y(I)+(3.*WK(I,3)+9.*WK(I,4))/8.
C          CALL DIFEQ(N,XN+H/2.,WK(I,6),WK(I,2))
C          DO 80 I=1,N
C          WK(I,5)=H3*WK(I,2)
C          80 WK(I,6)=Y(I)+(3.*WK(I,3)-9.*WK(I,4)+12.*WK(I,5))/2.
C          CALL DIFEQ(N,XN+H,WK(I,6),WK(I,2))
C
C          FIND THE LARGEST RELATIVE ERROR
C
C

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TEST=0.
DO 90 I=1,N
YX=Y(I)
IF(YX .EQ. 0.) YX=ACCURC
E=((WK(I,3)-9.*WK(I,4))/2.+4.*WK(I,5)-H3*WK(I,2)/2.)/5.)/YX
90 TEST=AMAX1(TEST,ABS(E))
FIRST=.FALSE.
IF(TEST .LT. ACCURC) GO TO 100
C
C IF THE LARGEST ERROR IS GREATER THAN ACCURC HALF THE STEP
C SIZE AND TRY AGAIN.
C
H=H/2.
IF(H .LT. HMIN) GO TO 10
QUIT=.FALSE.
GO TO 40
C
C TRUNCATION ERROR LESS THAN ACCURC, RESET THE Y ARRAY TO
C SET UP FOR THE NEXT INTERVAL
C
100 XN=XN-H
DO 110 I=1,N
110 Y(I)=Y(I)+(WK(I,3)+4.*WK(I,5)+H3*WK(I,2))/2.
C
C CHECK FOR STEP SIZE DOUBLING. DOUBLE IF LARGEST RELATIVE
C ERROR IS 32 TIMES LESS THAN ACCURC.
C
IF(.NOT.(TEST .GE. ACCURC/32. .OR. QUIT)) H=H*H
IF(.NOT. QUIT) GO TO 20
RETURN
C
C THE VALUE OF H (DEL) IS LESS THAN THE SPECIFIED MINIMUM.
C REPORT THIS AND ERROR OUT.
C
10 CONTINUE
DEL=0.
RETURN
END
BOTTLE

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