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THESIS

AN INTERACTIVE COMPUTER PROGRAM
FOR THE PRELIMINARY DESIGN AND
ANALYSIS OF MARINE REDUCTION GEARS

by

Joseph Louis Paquette

March, 1982

Thesis Advisor: G. Cantin

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The objective of this project was to develop an interactive computer program providing flexibility in the design and analysis of marine propulsion gears. The program, Reduction Gear Analysis and Design (REGAD), will handle conventional parallel axis and simple epicyclic reduction gears. It is capable of

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An Interactive Computer Program
for the Preliminary Design and
Analysis of Marine Reduction Gears

by

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B.S.S.E., United States Naval Academy, 1976

Submitted in partial fulfillment of the
requirements for the degree of

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from the

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March, 1982

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ABSTRACT

The objective of this project was to develop an interactive computer program providing flexibility in the design and analysis of marine propulsion gears. The program, Reduction Gear Analysis and Design (REGAD), will handle conventional parallel axis and simple epicyclic reduction gears. It is capable of generating preliminary designs of new gear sets or providing analyses of existing or proposed gear sets. Program development, organization, and operation are discussed.

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I. INTRODUCTION

In the conceptual stage of ship design, many parameters and options are considered. This is especially true with respect to the propulsion plant. Changes in hull design, displacement, and numbers of propellers all affect changes in the requirements for the propulsion plant. There are also various options under consideration in the propulsion plant: turbines or internal combustion engines, the number of engines, the auxiliaries required for support, etc. All of these will affect the initial design of the reduction gears. It is, therefore, important to be able to produce preliminary designs of reduction gears for the options under consideration.

Preliminary designs provide useful information on feasible arrangements and size without going into the specific design details dependent upon manufacturing. Since any number of preliminary designs may be required due to perturbations discussed above, it is important to be able to automate the design process. An interactive computer program providing various options would free the engineer from tedious, time consuming, and often error prone number manipulation and allow him to produce multiple designs for consideration. It would also provide a quick means of checking the effects of various parameters in addition to the ability to analyze proposed designs or configurations.

Reduction Gear Analysis and Design (REGAD) was developed to fill this need. It is an interactive computer program offering close user control through numerous options. Being interactive, it provides a rapid means of designing or analyzing a gear set, thereby reducing the turn-around time inherent in the use of batch systems. The program was kept modularized and well documented for ease of maintenance and modification. The modularized construction also provides an additional benefit of being able to use this program on smaller computers by using an overlay scheme.

II. PROGRAM CAPABILITIES

A. SCOPE

REGAD was written to provide preliminary designs or analyses of marine propulsion reduction gears. It is incapable of providing detailed designs or performing detailed analyses since specifics of manufacturing are not required for input. The program does not consider shafting, bearings, lubrication, couplings, casings, or other auxiliaries. It will provide sizing information in the form of pitch diameters, effective facewidths, gear ratios, and numbers of teeth per gear. In addition, the program will provide estimates of loadings and stress levels. Estimated weight and dimensions of the gear set are also provided.

All computations are based primarily on the American Gear Manufacturers Association's standards [Ref. 1, 2, 3] using appropriate constants for marine propulsion gears [Ref. 4, 5]. As an option in the program, these constants can be replaced by the user to enable him to investigate other applications such as reduction gears for ships service or emergency generators.

B. LIMITATIONS AND OPTIONS

Program application is limited to marine reduction gears with a maximum of three reduction stages. Conventional parallel axis and simple epicyclic arrangements with helical gears are possible. When dealing with epicyclics, it is assumed that load sharing of the planets is achieved and that the ring gear is suitably flexible. Efficiencies of the gear sets are not provided since power losses are not computed. While estimates of bending and contact stresses are provided, scoring can not be estimated since lubrication is not considered. REGAD does not require the K-factor as input as in previous programs since hardness ranges for the pinions and gears are required. However, the K-factors are computed and displayed for reference purposes. The weight estimates are based on actual designs and do not include turning gears, attached lubrication oil pumps, or other auxiliaries.

The following is a list of major options provided by the program:

(1) brief, on-line program description

(2) choice of design or analysis

(3) listing of preprogrammed constants and an ability to change selected constants of the user's choice

(4) choice of single, double, or triple reductions

(5) choice of single or double helical gears

(6) choice of six hardness ranges for gears and pinions

(7) conventional parallel axis arrangements (see Figures 1, 2, and 3)

(a) one or two power inputs

(b) single power path (articulated) or dual power paths (locked train)

(8) simple epicyclic arrangements (see Figure 4)

(a) choice of planetary or star arrangements

(b) single power input

(c) choice of three, four, or five planet/star gears.

III. PROGRAM ORGANIZATION AND OPERATION

A. REGAD FLOWPATHS

As stated previously, the program was designed in modular form with each module consisting of a number of subprograms. These modules are just conceptual groupings of associated subprograms, and are not related to actual program implementation on any specific computer. Figure 5 shows the basic flow paths of the program. Module One is for program initialization and problem set up. Module Two performs calculations for conventional parallel axis gear sets, while Module Three handles epicyclic gear sets. Module Four is a grouping of all the computational subprograms required by the other modules.

B. MODULE IDENTIFICATION AND DESCRIPTION

This section provides a brief description of each subprogram in each module.

1. Module One : Initialization and Set-up

Module One contains the subprograms necessary for initialization, execution, and initial data entry. It is, basically, the control module for the program. The following is a grouping of the subprograms in Module One.

a. REGAD

REGAD is the main program. It provides the options for either design or analysis and either parallel axis or epicyclic arrangements and controls the flow to the proper module. It then calls the required subprograms for execution of Modules One, and Two or Three.

b. BLOCK DATA

The BLOCK DATA subprogram initializes variables in each of the common blocks.

c. SUBROUTINE DSCRPT

This subroutine is called by REGAD after an affirmative response to a user option to provide a brief description of the REGAD package. It contains an option to stop the program if only a program description is desired.

d. SUBROUTINE INPUT

All options and initial design parameters are entered via this subroutine which is called by REGAD.

e. SUBROUTINE AGMA

The constants for marine propulsion gears required by various AGMA formulations are initialized in the BLOCK DATA subprogram, and can be listed as an option in REGAD. REGAD calls this subroutine after an affirmative user response to display the preprogrammed values. This subroutine then allows the user to selectively change any constant desired.

2. Module Two : Parallel Axis

This module contains all the major subprograms called by REGAD to provide an initial design or to perform an analysis of convential parallel axis reduction gears. The following is a grouping of the subprograms in Module Two.

a. SUBROUTINE PRLDES

This subroutine will produce a design of a parallel axis gear set. All pinion and gear diameters, effective facewidths, and gear ratios are computed using a basic random search optimization technique to find a feasible design by attempting to minimize a function of gear pair volume. It should be noted that, while attempting to minimize gear volume, the design is not necessarily optimized for minimum weight. The optimization technique is used here only to produce a feasible design in terms of dimension and power constraints by minimizing a function of gear pair volume. To produce a truly optimized design for minimum weight, a full optimization must include many more design variables such as helix and pressure angles, pitches, and hardnesses in addition to the dimensions. Additional constraints such as stress and unit load levels would need to be incorporated. All of this would require a more sophisticated and efficient optimization technique than is used here.

b. SUBROUTINE PRLANL

To analyze a proposed or existing design, REGAD will call this subroutine. It will request, as user-supplied input, the basic information calculated in PRLDES, i.e., pitch diameters and effective facewidths. Using this information, PRLANL will compute other parameters such as gear ratios, power and speed splits, and numbers of teeth per gear.

c. SUBROUTINE PRLRES

Immediately following a call to PRLDES or PRLANL, REGAD will call PRLRES to compute all remaining information such as expected loadings and stress levels. The user should be aware that the stress levels are computed according to AGMA formulations [Ref. 2 and 3] and take into account load distribution and overloads. This will produce levels that may seem high but are actually closer to actual levels to be expected in service.

d. SUBROUTINE PRLSIZ

REGAD calls this subroutine after PRLRES to compute estimates of gear set weight and gearbox dimensions. These estimates are determined by empirical relationships obtained from a rather limited data base of actual designs.

e. SUBROUTINE PRLOUT

This is the last subroutine called by REGAD in the parallel axis path. It provides a detailed output of the results obtained from the design or analysis including design parameters entered by the user, the dimensions of each component, expected loadings and stress levels, and configuration information.

3. Module Three : Epicyclic

Module Three contains all the major subprograms called by REGAD to design or analyze simple epicyclic reduction gears. Subroutines EPCDES, EPCANL, EPCRES, EPCSIZ, and EPCOUT are all analogous to those in Module Two. They perform the same functions, but for simple epicyclic gears. Therefore, individual descriptions will not be repeated here.

4. Module Four : Computational Subprogram Library

This module is an organizational grouping of all the subprograms called by those in Modules One, Two, and Three.

a. Subroutine Subprograms

The following are the subroutines used:

(1) GFI - subroutine to compute the AGMA durability geometry factor, I

(2) GFJ - subroutine to compute the AGMA strength geometry factor, J.

b. Real Function Subprograms

The following are the real function subprograms used:

(1) ARCCOS - computes the arc cosine of two arguments

(2) ARCSIN - computes the arc sine of two arguments

(3) AGMAE1 - uses LaGrangian interpolation of Table E-1 [Ref. 1] to compute the constants required for the stress concentration factor formulation

(4) CKDATA - called by SUBROUTINE AGMA to allow the user to change the preprogrammed constants

(5) POWERB - computes allowable service power based on AGMA strength rating [Ref. 3]

(6) POWERH - computes allowable service power based on AGMA durability rating [Ref. 2]

(7) RTFNDR - a modified version of FUNCTION ZEROIN [Ref. 6] used to find a zero of a function in a specified interval

(8) FALFA - the function required by SUBROUTINE GPJ and the zero of which is computed in FUNCTION RTFNDR

(9) SHRLD - computes the load sharing ratio, m_N

(10) THICK - computes tooth thickness at any diameter given a known thickness at a different diameter.

C. DATA TRANSFER

All data transfer between subprograms in Modules One, Two, and Three is via combinations of seven common blocks. Data transfer to and from subprograms in Module Four is via argument lists and common blocks as required. The following is a list of the common blocks used:

(1) /AGMAB/ : constants for AGMA strength formulations

(2) /AGMAH/ : constants for AGMA durability formulations

(3) /DESDAT/ : design parameters and options

(4) /DESPRL/ : parallel axis design information

(5) /RESPRL/ : parallel axis computational results

(6) /DESEPC/ : epicyclic design information

(7) /RESEPC/ : epicyclic computational results.

The variables in each common block along with their definitions can be found in Appendix B.

D. PROGRAM OPERATION

REGAD is an interactive program designed to allow the user to solve his problem at a terminal. Being interactive, the program has many options that control program execution, in addition to requests for data necessary for the execution of the program. Each request for information will contain the necessary guidelines needed by the the user to respond. This may take the form of a mini-table containing information on each option choice, the range of values when a specific quantity is requested, or units, where applicable, of the requested data.

All option parameters are integer values and should not be entered with a decimal. Option codes entered by the user are checked for validity to ensure they fall within the allowed range. If two options are offered, enter a 1 or a 2. Any value entered less than one will automatically default to one, and any value greater than two will automatically default to two. In those cases where there are more than two options, the response is checked to see if it falls within the allowed range. If it does not, a message alerts the user to this fact and allows him to re-enter the correct code. Some questions require affimative or negative responses. To reply, use a Y for yes or an N for no. Use of other values may give undesirable results.

Every attempt has been made to anticipate possible error conditions. If one of these is encountered, a message is generated to inform the user. If the error encountered is a terminal error, the message will also indicate that the program run was aborted under program control.

A detailed development of this package is provided in Appendix A where specifics can be found. Appendix B provides a cross-reference of the variables used in Appendix A with those used in the program. It also contains detailed information on the common blocks. Sample runs of the program can be found in Appendix C, and a complete listing of the program is in Appendix D.

IV. CONCLUSIONS AND RECOMMENDATIONS

Computer aided design (CAD) is an important and useful tool for engineers. As computer technology continues to expand, CAD will become increasingly available for the practicing engineer, allowing him to use his initiative in design instead of being a slave to the numbers involved. REGAD is such a tool for use in the preliminary design of marine reduction gears during the conceptual stages of propulsion plant design.

REGAD could become even more useful if additional options are provided. A module to perform sensitivity analyses of a given design would greatly enhance the use of this program. This option would allow the user to start with any design and vary a selected variable over a specified range to determine its impact on the design. It could also be used to "fine tune" a design by modifying selected parameters to produce the results desired without having to rerun the program for each modification. Graphics would add another dimension by providing graphical displays of the gear arrangements and of certain data such as the results of a sensitivity analysis. A module to handle various composite designs of parallel axis and epicyclic gears would be an important addition. Also, it is recommended that a larger data base be collected to provide more accurate empirical constants for the weight and gearbox size estimates.

APPENDIX A

PROGRAM DEVELOPMENT

With the exception of several general conversion relationships, all computations are accomplished in Modules Two and Three with calls to subprograms in Module Four. The analytical relationships used in the program will be examined, however, most of the relations used can be easily found in the literature and in various texts, so background developments will not be given.

I. GENERAL RELATIONSHIPS

The following relationships are used in Module One and in various other subprograms. The transverse diametral pitch of any gear is the ratio of its number of teeth to its pitch diameter;

$$P_d = \frac{N}{d} \tag{1}$$

The normal and transverse diametral pitches are related by;

$$P_d = P_{nd} \cos \psi \tag{2}$$

and the pressure angles by;

$$\tan \phi_n = \tan \phi_t \cos \psi \qquad (3)$$

Axial pitch is defined as;

$$p_x = \frac{\pi}{P_{nd} \sin \psi} = \frac{\pi}{P_d \tan \psi} \qquad (4)$$

II. CONVENTIONAL PARALLEL AXIS FORMULATIONS

Subroutines PRLANL and PRLDES each provide the pitch diameters of the pinions and gears, the effective facewidths, the stage reduction ratios, the numbers of teeth per gear, speed and power splits, and the geometry factors to subroutines PRLRES and PRLSIZ to compute all further information. The speed splits are the actual speeds of the individual gears and a power split is the actual power transferred by a gear. The strength and durability geometry factors are computed in separate subroutines in Module Four and will be discussed later.

A. COMMON RELATIONSHIPS

Power splits are determined from the configuration. For a single power path configuration, the power is transferred equally from the pinion to the gear, where in a dual power path configuration, the pinion transfers one half its power to each of two gears. These splits are computed exactly since losses are neglected.

Speed splits and stage reduction ratios are based on;

$$m_G = \frac{D}{d} = \frac{n_G}{n_p} \qquad (5)$$

Numbers of teeth on each gear are computed from the equation below and are rounded to the nearest integer.

$$N = d \times P_d \qquad (6)$$

B. DETERMINATION OF DIAMETERS AND FACEWIDTHS

All diameters and facewidths are entered by the user in subroutine PRLANL. Stage gear ratios, power and speed splits and numbers of teeth per gear are computed as discussed in the previous section.

In subroutine PRLDES, the diameters, facewidths, and stage gear ratios are determined by using a basic local random search optimization technique to produce a feasible design. This algorithm requires an initial design to start.

The initial design is based on Dudley's [Ref. 7] formulation for preliminary estimates of gear size;

$$C^2F = \frac{31500}{K} \frac{Pwr}{n_p} \frac{(m_G+1)^3}{m_G} \qquad (7)$$

$$C = \frac{d}{2}(m_G + 1) \qquad (8)$$

By substituting equation 8 into equation 7, a formula for estimating pinion diameter is obtained;

$$d^3 = \frac{126000}{n_p\ K}\ \frac{Pwr}{(F/d)}\ \frac{(m_G + 1)}{m_G} \qquad (9)$$

where F/d = 1.0 for single helical gears and F/d = 2.25 for double helical gears. The term K is the K-factor which is an indication of durability. An expression for estimating K is provided by Thoma [Ref. 4];

$$K \leq \left(\frac{S_{ac}\ x\ 10^{-4}}{C_R}\right)^2 x \left(\frac{2.80}{C_o\ \ C_m}\right) \qquad (10)$$

where the constants used are the AGMA durability constants. The K-factor in equation 10 is for the second reduction. For the first reduction, multiply K from equation 10 by 1.20. The initial estimates for the stage gear ratios are:

(1) single reduction $m_G = M_o$

(2) double reduction $m_{G_2} = \sqrt{M_o} + 3$ dual power path

$m_{G_2} = \sqrt{M_o} - 1$ single power path

$m_{G_1} = \sqrt{M_o} / m_{G_2}$

(3) triple reduction $m_{G_2} = \sqrt[3]{M_o}$

$m_{G_3} = \sqrt[3]{M_o} + 3$

$m_{G_1} = \sqrt[3]{M_o} / m_{G_2} m_{G_3}$.

The initial facewidths used are:

(1) single helical gears $F = d$

(2) double helical gears $F = 2.25\ d$.

With this initial design as a starting point for the random search algorithm, successive designs are determined by randomly adding small amounts of between +1.0 and -1.0 to the diameters, facewidths, and stage gear ratios. These small amounts are scaled to take into account the difference in range of values for each variable. This process will attempt to find a feasible design in which all specified constraints are satisfied. If the initial design violates one or more constraints, the design that violates them the least in succeeding iterations will be kept until a design satisfying all constraints is found. Once a feasible design is found, an attempt to improve this design is made by trying to reduce the size of the gears by minimizing a function of gear pair volume;

$$\text{Volume} = \sum\sum C^2 F = \sum\sum \left[\tfrac{1}{4}(m_G + 1)^2 d^2 F \right] \tag{11}$$

The interior summation is over the number of reduction stages, and the exterior summation is over the number of power inputs. The constraints imposed which determine the limits on each of the designs are:

(1) actual transmitted power is less than or equal to the allowable service power in accordance with references 2 and 3

(2) maximum gear diameter of 200 inches due to manufacturing limitations

(3) minimum facewidth greater than four axial pitches to ensure proper helical action

(4) maximum facewidth less than the pinion pitch diameter for a single helical gear or 2.25 times the pinion pitch diameter for a double helical gear

(5) pinions and gears in succeeding reduction stages are to be larger than those in the previous stage due to the greater amounts of torque carried

(6) in dual power path arrangements, the gear ratio for each reduction stage is greater than the preceeding stage due to the torque carried.

The design obtained can than be adjusted by the user as desired by changing parameters with the analysis option.

III. EPICYCLIC FORMULATIONS

As in Module Two, the pitch diameters, effective face-widths, stage reduction ratios, numbers of teeth, speed and power splits, and the geometry factors are all entered or computed in the analysis or design subroutines (EPCANL or EPCDES) for use in the final computations subroutines (EPCRES and EPCSIZ). Here, the speed splits are the rotational speeds of the sun and planet gears and of either the ring gear or the carrier, depending on the configuration. Planetary arrangements have fixed ring gears while star arrangements have fixed carriers. Also, the direction of rotation must be considered. Star arrangements reverse the direction of rotation of the input and the planetary arrangements will maintain direction of rotation. Assuming equal load sharing of the planets and neglecting losses, power splits are straightforward. The input and output powers are equal while each planet carries an equal share of the total power. Load sharing is an important consideration in the design of epicyclic gears, and must be assured in marine reduction gears due to the high power levels experienced. Equal load sharing of the planets can be reasonably achieved in several different ways. One method requires the sun gear to float, supported only by the planet gears, with a relatively flexible ring gear to allow for inaccuracies in the teeth. There are also mechanical devices available to assist in achieving an equal division of the load. Experience has shown, for marine applications, that three to five planets with stage ratios in the range of two to eight work best.

A. COMMON RELATIONSHIPS

Unlike conventional parallel axis arrangements, there are specific numerical rules governing the proper assembly and operation of an epicyclic gear set. These involve the selection of the numbers of teeth and planets along with computing the various speed ratios. Mesh frequencies are also configuration dependent as seen in a following section.

There are basically three relationships that must be satisfied to ensure proper assembly and operation. The first is a relationship defining the speed ratio of the epicyclic stage since it is not merely the ratio of numbers of teeth or diameters as in a conventional parallel axis gear set. The second relationship requires the ring gear diameter to be equal to the sum of the sun gear diameter and twice a planet gear's diameter. This ensures the planets' ability to fit between the sun and ring gear. For the final relationship, it can be shown geometrically that the sum of the numbers of teeth on the sun gear and ring gear must be an integral multiple of the number of planets in the gear set to ensure proper alignment and meshing of all teeth. It should be noted that these relationships are based on equally spaced planets around the sun gear. The above relationships are conveniently expressed in terms of numbers of teeth on each gear as seen in references 7 and 8. The speed ratio for a planetary arrangement is;

$$m_G = \frac{n_o}{n_i} = \frac{N_R}{N_S} + 1 \tag{12}$$

and for a star arrangement;

$$m_G = \frac{-n_o}{n_i} = \frac{-N_R}{N_S} \tag{13}$$

where the negative sign indicates the star arrangement's reversal of rotational direction of the input. The rotational speed of the planet gears is required for the design of their bearings and can be determined by;

$$n_{PLN} = \frac{N_R}{N_{PLN}} n_o \tag{14}$$

where n_o in each equation above is the speed of the carrier for a planetary arrangement or is the ring gear's speed for a star arrangement. The assembly and meshing relations in terms of tooth numbers are;

$$N_R = N_S + 2\ N_{PLN} \tag{15}$$

and;

$$N_R + N_S = k\ NP \tag{16}$$

where k is an integer and NP is the number of planets.

B. DETERMINATION OF DIAMETERS AND FACEWIDTHS

The random search technique discussed for conventional parallel axis gears is used to provide the epicyclic diameters, facewidths, and stage gear ratios. Equation 9 is used to provide an initial estimate of sun gear diameters where m_G is replaced by the ratio of the planet's pitch diameter to the sun's pitch diameter. This value is usually in the range of 1.5 to 3; therefore, a random number in this range is used to start the problem. Once the sun gear diameter is estimated, the other diameters can be found using the relationships in equations 12 to 16. The initial estimates for the stage gear ratio are the roots of the overall ratio corresponding to the number of reduction stages. For example, m_{G_1} and m_{G_2} for a double reduction gear set would be the square root of the overall ratio. Initial facewidths are chosen as before. The initial estimates of the diameters, facewidths, and the gear ratios provide a starting point for the random search algorithm discussed previously. Again, the method will attempt to improve feasible designs by minimizing a function of gear volume;

$$\text{Volume} = \sum (NP \cdot d^2_{PLN} + d^2_S + d^2_R) \cdot F \qquad (17)$$

where the summation is over the number of reduction stages. The constraints imposed are similar to those for the parallel axis gears:

(1) actual transmitted power is less than or equal to the allowable service power in accordance with references 2 and 3

(2) maximum ring gear diameter of 150 inches due to manufacturing limitations

(3) minimum facewidth greater than four axial pitches to ensure proper helical action

(4) maximum facewidth less than the sun's pitch diameter for a single helical gear or 2.25 times the sun's pitch diameter for a double helical gear

(5) planet gears are to be larger than sun gears due to the greater amounts of torque carried

(6) stage gear ratios are to be between 2 and 8 for each reduction stage.

As before, once a design is obtained, the user can utilize the analysis option to obtain the desired results.

IV. COMPUTATIONAL RESULTS AND DESIGN INFORMATION

Once the geometry is determined in the analysis or design subroutines, the computational results subroutine (PRLRES or EPCRES) and the size estimates subroutine (PRLSIZ or EPCSIZ) are called to provide design information concerning tooth loads, stresses, and other configuration, geometry, and size information. This section describes the formulations used.

The facewidth to diameter ratio is computed using the effective facewidth and the pitch diameter of the pinion for parallel axis gears or the sun gear for epicyclics. Center distance is taken as the average of the pinion and gear pitch diameters. A center distance is computed for epicyclics by finding the average of the sun and a planet gears' pitch diameters.

Pitchline velocity, V, is determined by;

$$V = \frac{\pi \, d \, n_p}{12} \qquad (18)$$

where V is in feet per minute, d is in inches, and n_p is in revolutions per minute. The tangential component of tooth load, W_t, is computed from;

$$W_t = \frac{126000\ Pwr}{n_p\ d} \tag{19}$$

where W_t is in pounds-force, Pwr is in horsepower, and d and n_p are as before. Tooth loading per inch of facewidth is computed from;

$$\text{Tooth Load per Inch} = W_t / F \tag{20}$$

and the unit load, a normalized value of the load per inch above, is;

$$\text{Unit Load} = \frac{W_t\ P_{nd}}{F} \tag{21}$$

where the unit load is expressed in pounds-force per square inch.

Mesh frequencies provide information on how often a tooth is loaded. Mesh frequencies for parallel axis gears are determined by;

$$f = \frac{N_p\ n_p}{60} \tag{22}$$

with f expressed in Hertz. For epicyclic gears, the following are used:

$$\text{(a)}\quad f_S = \frac{NP \quad N_R}{N_R + N_S}\, n_S \qquad\qquad \text{(d)}\quad f_S = NP\; n_S$$

$$\text{(b)}\quad f_P = \frac{N_R}{N_{PLN}}\;\frac{N_S}{N_R + N_S}\, n_S \qquad\qquad \text{(e)}\quad f_P = 2\,\frac{N_S}{N_{PLN}}\, n_S \tag{23}$$

$$\text{(c)}\quad f_R = \frac{NP \quad N_S}{N_R + N_S}\, n_S \qquad\qquad \text{(f)}\quad f_R = NP\,\frac{N_S}{N_R}\, n_S$$

where (a) through (c) are for planetary arrangements and (d) through (f) are for star arrangements.

The K-factor is computed for reference purposes by;

$$K = \frac{W_t}{F\ d}\;\frac{(m_G + 1)}{m_G} \tag{24}$$

The contact stresses are computed according to reference 2 by;

$$s_c = C_p\sqrt{\frac{W_t \quad C_o}{C_v}\;\frac{C_s}{d\ F}\;\frac{C_m \quad C_f}{I}} \tag{25}$$

Bending stresses are computed according to reference 3 by;

$$s_t = \frac{W_t \quad K_o}{K_v}\;\frac{P_d}{F}\;\frac{K_s \quad K_m}{J} \tag{26}$$

Individual torques, T, are found by;

$$T = \frac{W_t \ d}{2000} \tag{27}$$

while the total output torque is computed by;

$$T = \frac{63 \ SHP}{n_p} \tag{28}$$

where T has the units of thousands of inch-pounds-force in both cases. Shaft horsepower, SHP, is the total power transferred to the output shaft.

Weight and size estimates are based on empirical relations obtained from a limited number of actual designs. The relations used are;

$$\begin{aligned} \text{Weight} &= C1 \cdot [\textstyle\sum (d^2 F)]^{C2} \\ \text{Length} &= C3 \cdot \textstyle\sum F \\ \text{Width} &= C4 \cdot D \\ \text{Height} &= C5 \cdot D \end{aligned} \tag{29}$$

where the constants used are found in Table 1. All dimensions are in inches and the weight is in pounds-force rounded to three significant figures.

Table 1: Empirical Constants for Weight and Size Formulations

Constant	Parallel Axis	Epicyclic
C1	1196.0	0.905
C2	0.34	0.89
C3	2.26	2.85
C4	1.20	1.30
	1.37	--
C5	1.28	1.20
D	Bull Gear Diameter	Ring Gear Diameter

first C4: for single power inputs
second C4: for double power inputs

V. COMPUTATIONAL SUBPROGRAMS LIBRARY FORMULATIONS

The formulations provided below are for the major computational subprograms in Module Four. Those that are self-explanatory or are not computational in nature are only described in general.

A. ARCCOS AND ARCSIN

These function subprograms find the arc cosine and arc sine, respectively, for any two arguments. They were added for convenience since not all compilers have them as internal functions.

B. AGMAE1

This function subprogram returns the value of the constants H, L, and M required for the determination of the stress concentration factor, K_t, according to reference 1, for use in computing the strength geometry factor, J. Table E-1 in reference 1 provides the tabulated data necessary to perform a LaGrangian interpolation for each constant for a specified normal pressure angle in degrees. The interpolation formula used is:

$$F(\phi_n) = \frac{(\phi_n - 20)(\phi_n - 14.5)}{57.75} F_1 + \frac{(\phi_n - 14.5)(\phi_n - 25)}{-27.50} F_2 + \frac{(\phi_n - 14.5)(\phi_n - 20)}{52.50} F_3 \qquad (30)$$

where F represents the appropriate values of H, L, or M.

C. CKDATA

FUNCTION CKDATA is called by subroutine AGMA to allow the user to selectively change the preprogrammed constants by checking if the value entered is zero. If it is zero, the current value of the specified constant is not changed. This provides for flexibility in changing constants with multiple values, and it guards against inadvertantly entering a value of zero.

D. POWERB AND POWERH

These function subprograms are used to compute the maximum allowed service power, in horsepower, that can be transmitted by a gear according to references 2 and 3. The formulation based on the strength rating is;

$$P = \frac{n \quad d \quad K_v}{126000 \ SF \ K_o} \ \frac{F}{K_m} \ \frac{J}{K_s \ P_d} \ \frac{S_{ac} \ K_L}{K_R \ K_T} \qquad (31)$$

and the durability rating formulation is;

$$P = \frac{n \quad d}{126000 \ SF} \ \frac{I \ C_v}{C_s \ C_f \ C_o \ C_m} \left[\frac{S_{at} \ d}{C_p} \ \frac{C_L \ C_H}{C_R \ C_T} \right]^2 \qquad (32)$$

where J and I are the respective geometry factors, F is the effective facewidth, n is the speed of d in revolutions per minute, and d is the pinion pitch diameter for parallel axis or is the sun pitch diameter for epicyclics. All other values are the preprogrammed constants.

E. RTFNDR AND FALFA

The function subprogram RTFNDR, a slightly modified version of FUNCTION ZEROIN [Ref. 6], is used to find the value of the root of the equation programmed in function FALFA. This root is required by the subroutine GFJ for the computation of the strength geometry factor, J.

F. SHRLD

This function subprogram computes the load sharing ratio used in computing the geometry factors. The load sharing ratio, m_N, is determined by;

$$m_N = \frac{p_N}{.95\ Z} = \frac{\pi \cos \phi_n}{.95\ Z\ P_{nd}} \tag{33}$$

where Z is the length of action defined as;

$$Z = \frac{1}{2}\left(\sqrt{D_o^2 - D_b^2} + \sqrt{d_o^2 - d_b^2} - \sqrt{D^2 - D_b^2} - \sqrt{d^2 - d_b^2}\right) \tag{34}$$

The subscripts on the pitch diameters are:

(1) o : outside diameter; $d_o = d + (2/P_d)$

(2) b : base diameter; $d_b = d \cos \phi_t$

For epicyclics, replace the outside diameters is equation 34 with inside diameters : $d_i = d - (2/P_d)$.

G. THICK

FUNCTION THICK returns the value of the normal arc thickness of a tooth at a specified diameter given a thickness at another diameter. For external gears;

$$t_2 = d_2((t_1/d_1) + \text{inv}\,\phi_1 - \text{inv}\,\phi_2) \tag{35}$$

and for internal gears;

$$t_2 = d_2((t_1/d_1) - \text{inv}\,\phi_1 + \text{inv}\,\phi_2) \tag{36}$$

where the subscript 2 represents the desired point and subscript 1 represents the known point. The involute function is defined as;

$$\text{inv } x = \tan x - x \tag{37}$$

The arguments of the involute functions in equations 35 and 36 are the transverse pressure angles at the points under consideration. The pressure angle at the desired point is defined as;

$$\cos \phi_2 = \frac{d_1 \cos \phi_1}{d_2} \tag{38}$$

The known point is usually taken at the pitch circle where $d_1 = d$, $\phi_1 = \phi_n$, and t_1 is defined as

$$t = \frac{p_n}{2} = \frac{\pi}{2\,P_d} \cos \psi \tag{39}$$

H. GFI

This subroutine is used to compute the AGMA durability geometry factor, I, in accordance with reference 2. The geometry factor is defined as;

$$I = \frac{\cos \phi_t \, \sin \phi_t}{2\, m_N} \; \frac{m_G}{(m_G \pm 1)} \tag{40}$$

where m_N is computed by function *SHRLD* described above. The plus sign applies to external gears and the minus sign applies to internal gears.

I. GFJ

SUBROUTINE GFJ is used to compute the AGMA strength geometry factor, J, in accordance with reference 1 with one major difference: the values used are from analytical developments and are not scaled to a normal diametral pitch of one as are the values used in a graphical layout discussed in reference 1. The strength geometry factor is defined as;

$$J = \frac{Y_C \cos^2 \psi}{K_f \quad m_N} \tag{41}$$

The load sharing ratio, m_N, is computed in FUNCTION SHRLD. The stress concentration factor, K_f, is determined from;

$$K_f = H + \left(\frac{t}{r_f}\right)^L \cdot \left(\frac{t}{h}\right)^M \tag{42}$$

where H, L, and M are determined in FUNCTION AGMAE1. The value of the root fillet radius, r_f, is;

$$r_f = r_T + \frac{(b - r_T)^2}{(d/2\cos^2 \psi) + (b - r_T)} \tag{43}$$

with the dedendum, $b = 1.25/P_d$, and the root tip radius,

$r_T \cong 0.28/P_{nd}$. The values of t and h are determined from the anlytical geometry of the tooth form layout described below.

The tooth form factor, Y , is defined as;

$$Y_C = P_{nd}\left[\frac{\cos \phi_{Ln}}{\cos \phi_n}\left(\frac{1.5}{x\ C_h} - \frac{\tan \phi_{Ln}}{t}\right)\right]^{-1} \qquad (44)$$

where t and x are also from the tooth form layout mentioned previously. The helical factor, C_h, is defined as;

$$C_h = \left[1 - \frac{\nu}{100}\left(1 - \frac{\nu}{100}\right)\right]^{-1} \qquad (45)$$

where $\tan \nu = \tan \psi \sin \phi_n$ for $\psi \leq 50°$. The normal load pressure angle at the tip of the tooth, ϕ_{Ln}, can be seen in figures 6 and 7 and is given by;

$$\phi_{Ln} = \cos^{-1}\left(\frac{d_b}{d_o}\right) \pm \frac{t_o}{d_o} \qquad (46)$$

where the subscript o pertains to the point on the outside diameter and subscript b pertains to the base circle. The plus sign applies to internal gears and the minus, to external. The thickness, t_o, at the outside diameter is determined by function THICK. For internal gears, replace the outside values with the inside values as before.

The graphical tooth form layout is a method by which the variables h, t, and x can be determined from actual measurements of a tooth form drawn and scaled for a normal diametral pitch of one for the case where tooth loading is at the tip. Loading at the tip of the tooth is the general practice for considering loads on helical gears. Refer to Figure 7 for the meanings of h, x, and T where t = 2T. Before determining h, x, and T analytically, several reference parameters must be determined as suggested by McIntire and Lyon [Ref. 9]. The first is the radius from the center of the gear to the tip of the inscribed Lewis stress parabola which is point E in Figure 7. This point is the intersection of the line of action of the tip load, tangent to the base circle, with the tooth centerline. The radius to this point is;

$$r_v = \frac{d_v}{2} = \frac{d_b}{2\cos \phi_{Ln}} \tag{47}$$

An additional reference point is required to fix the geometry. The center of of the root fillet is taken as this point which can be obtained by a very close approximation. To locate this point, the gear center is taken as the origin of a cartesian coordinate system with the tooth centerline as the vertical axis. Two possible cases exist for the location of this point with respect to the base circle. Figure 8 shows the case where the point is inside the base circle and Figure 9 shows the case where it is outside. The coordinates of this point, (XC,YC), can be found from Figures 8 and 9. For both cases it can be seen in Figures 8 and 9 that;

$$HYP = d_R + r_f \tag{48}$$

where $d_R = d - 2b = d - (2.5/P_d)$. From Figure 6, the angle, ϵ, is;

$$\epsilon = \text{inv}\,\phi + \sin^{-1}\frac{t_c}{d} \tag{49}$$

where t_c is the chordal tooth thickness given by;

$$t_c = t - \frac{t^3 \cos^2 \psi}{6 \quad d^3} \tag{50}$$

and t is the normal arc tooth thickness defined earlier.
For the case in Figure 8;

$$\begin{aligned} XX &= (HYP)\sin\epsilon \\ XC &= XX + r_f \qquad (a) \\ YC &= \sqrt{HYP^2 - XC^2} \qquad (b) \end{aligned} \tag{51}$$

and for the case in Figure 9;

$$\phi_1 = \cos^{-1} \frac{(d_b/2)}{HYP}$$

$$OPP_1 = (HYP) \sin \phi_1$$

$$OPP_2 \cong OPP_1 - r_f$$

$$HYP_1 = \sqrt{OPP^2 + (d_b/2)^2}$$

$$\phi_2 = \cos^{-1} \frac{(d_b/2)}{HYP_1}$$

$$\lambda = \phi_1 \pm \text{inv}\,\phi_2 - \phi_2$$

"-" for external gears
"+" for internal gears (see Figure 11)

$$\delta = \lambda + \epsilon$$

$$XC = (HYP) \sin \delta \quad \text{(a)}$$

$$YC = (HYP) \cos \delta \quad \text{(b)} \qquad (52)$$

With the reference values of r_f, XC, and YC determined, the values of h, t=2T, and x can be analytically determined. From Figure 7;

$$XT = r_f \cos \alpha \qquad (53)$$

$$YH = r_f \sin \alpha \qquad (54)$$

$$h = r_v - YC + YH = r_v - YC + r_f \sin \alpha \qquad (55)$$

$$T = (t/2) = XC - XT = XC - r_f \cos \alpha \qquad (56)$$

$$YK = \frac{T}{\tan \alpha} \tag{57}$$

where α must be determined such that;

$$YK = 2h \quad \text{or} \quad YK - 2h = 0 \tag{58}$$

Substituting equations 53 through 57 into 58 yields;

$$F(\alpha) = XC - r_f \cos \alpha - 2\tan \alpha \; (r_v - YC + r_f \sin \alpha) = 0 \tag{59}$$

Equation 59 is the function in FALFA called by RTFNDR to solve for α. Once α is determined, h can be determined from equation 55 and T and t from equation 56. To obtain x, observe the following;

$$\gamma = \tan^{-1} (h/T)$$

$$\gamma_1 = (\pi/2) - \gamma$$

and

$$x = T \tan \gamma_1 \tag{60}$$

While not precise, the identical methodology is used for internal gears. Figures 10 and 11 apply. The expressions for internal gears are given without further development;

$$
\begin{aligned}
h &= -r_v + YC + r_f \sin\alpha \\
T &= XC - r_f \cos\alpha \\
t &= 2T \\
\gamma &= \tan^{-1}(h/T) \\
\gamma_1 &= (\pi/2) - \gamma \\
x &= T \tan\gamma_1
\end{aligned}
\tag{61}
$$

The values for h, t, and x are now used to determine the stress concentration factor, equation 42, and the tooth form factor, equation 44, required to compute the strength geometry factor, J, in equation 41.

APPENDIX B

LIST OF PARAMETERS

While it is not practical to list all variables used in the formulations or the program, it is useful to provide a list of the major variables with a cross-reference between the analytical names and the FORTRAN names. A detailed listing of each common block is also useful when studying the program.

I. PARAMETER CROSS-REFERENCE

This section provides a listing of parameters with both their analytical and FORTRAN names.

Math Symbol	FORTRAN Name	Variable Definition
K_L	AKL	life factor
K_m	AKM	load distribution factor
K_o	AKO	overload factor
K_R	AKR	reliability factor
K_s	AKS	size factor
K_T	AKT	temperature factor
K_v	AKV	dynamic factor
SF	SFB	service factor
C	CDE	center distance (theoretical) (in)

	CDP	(E=epicyclic, P=parallel axis)
C_f	CF	surface finish factor
C_H	CH	hardness factor
C_L	CL	life factor
C_m	CM	load distribution factor
C_o	CO	overload factor
C_p	CP	elastic properties factor
C_R	CR	reliability factor
C_s	CS	size factor
C_T	CT	temperature factor
C_v	CV	dynamic factor
SF	SFH	service factor
ψ	DHELIX	helix angle (deg)
	HELIX	helix angle (rad)
ϕ_t	DPHI	transverse pressure angle (deg)
	PHI	transverse pressure angle (rad)
ϕ_n	DPHIN	normal pressure angle (deg)
	PHIN	normal pressure angle (rad)
D	DG	diameter of gear (in)
d	DP	diameter of pinion (in)
d_{PLN}	DPLN	diameter of planet gears (in)
d_R	DR	diameter of ring gear (in)
		root diameter of a gear (in)
d_S	DS	diameter of sun gear (in)
F	FACEE	facewidth (in)
	FACEP	(E=epicyclic, P=parallel axis)

F/d	FBYDE	f/d ratio (facewidth/diameter)
	FBYDP	(E=epicyclic, P=parallel axis)
I	GEOMI	duribility geometry factor (pinion)
	GI	durability geometry factor (sun)
J	GEOMJG	strength geometry factor (gear)
	GEOMJP	strength geometry factor (pinion)
	GJS	strength geometry factor (sun)
	GJPL	strength geometry factor (planet)
K	KFCTRE	computed k-factor
	KFCTRP	(E=epicyclic, P=parallel axis)
f	MFE	mesh frequency (Hz)
	MFP	(E=epicyclic, P=parallel axis)
M_o	MGOE	overall reduction ratio
	MGOP	(E=epicyclic, P=parallel axis)
m_G	MGE	stage reduction ratio
	MGP	(E=epicyclic, P=parallel axis)
N_G	NG	number of teeth, gear
N_P	NP	number of teeth, pinion
NP	NPLNT	number of planet gears in epicyclic set
N_{PLN}	NPLN	number of teeth, planet
N_R	NR	number of teeth, ring
N_S	NS	number of teeth, sun
P_d	PD	transverse diametral pitch
P_{nd}	PND	normal diametral pitch
V	PLVE	pitch line velocity (fpm)
	PLVP	(E=epicyclic, P=parallel axis)

Pwr	PWRE	power split per gear pair (hp)
	PWRP	(E=epicyclic, P=parallel axis)
n_{in}	RPMIN	source speed input (rpm)
n_{out}	RPMOUT	output shaft/propeller speed (rpm)
n_i	RPMI	stage input speed, epicyclic (rpm)
n_o	RPMO	stage output speed, epicyclic (rpm)
n_{PLN}	RPMPL	planet speed, epicyclic (rpm)
n_P, n_G	RPMP	stage pinion and gear speed, parallel axis (rpm)
s_{ac}	SAC	allowable contact stress number
s_{at}	SAT	allowable bending stress number
SHP	SHP	shaft horsepower, output (hp)
s_t	SIGBE	bending stress (psi)
	SIGBP	(E=epicyclic, P=parallel axis)
s_c	SIGHE	contact stress (psi)
	SIGHP	(E=epicyclic, P=parallel axis)
T	TORQE	torque (k in-lb)
	TORQP	(E=epicyclic, P=parallel axis)
W_t	WTE	tangential tooth load (lb)
	WTP	(E=epicyclic, P=parallel axis)

II. COMMON BLOCK DETAILS

The following provides information concerning the variables in each common block. The numbers in parentheses are the size of the array where applicable.

COMMON BLOCK AGMAB (FOR STRENGTH RATING)

SFB	:	R*4 (2,2);	service factor
AKV	:	R*4;	dynamic factor
AKS	:	R*4;	size factor
AKM	:	R*4;	load distribution factor
AKO	:	R*4 (2);	overload factor
SAT	:	R*4 (6);	allowable bending stress number
AKL	:	R*4 (2);	life factor
AKR	:	R*4 (6);	reliability factor
AKT	:	R*4;	temperature factor

COMMON BLOCK AGMAH (FOR DURABILITY RATING)

SFH	:	R*4 (2,2);	service factor
CV	:	R*4 (3);	dynamic factor
CS	:	R*4;	size factor
CM	:	R*4 (2);	load distribution factor
CF	:	R*4;	surface finish factor
CO	:	R*4 (2);	overload factor
SAC	:	R*4 (6);	allowable contact stress number
CP	:	R*4;	elastic properties factor
CL	:	R*4 (2);	life factor
CH	:	R*4;	hardness factor
CT	:	R*4;	temperature factor
CR	:	R*4 (6);	reliability factor

COMMON BLOCK DESDAT (DESIGN PARAMETERS, INPUT)

PWRIN : R*4 (2);	source power input (hp)
RPMIN : R*4 (2);	source speed input (rpm)
RPMOUT: R*4;	output shaft/propeller speed (rpm)
DHELIX: R*4 (3);	helix angle (deg)
HELIX : R*4 (3);	helix angle (rad)
PD : R*4 (3);	transverse diametral pitch
PND : R*4 (3);	normal diametral pitch
DPHI : R*4 (3);	transverse pressure angle (deg)
PHI : R*4 (3);	transverse pressure angle (rad)
DPHIN : R*4 (3);	normal pressure angle (deg)
PHIN : R*4 (3);	normal pressure angle (rad)
NDIFP : I*4;	number of different power sources
IARR : I*4;	arrangement code (1=parallel axis, 2=epicyclic)
IEPIC : I*4 (3);	epicyclic code (1=planetary, 2=star)
IHARD : I*4 (3,2);	hardness range code (1-6, see SUBR. AGMA)
IOPRO : I*4;	operational profile code (1=naval profile full power 5% max; 2=other, max power continuous)
NPWRIN: I*4;	number of power sources (inputs)
IPWRSR: I*4 (2);	power source code (1=turbine or motor, 2=multicylinder internal combustion engine)
NRED : I*4;	number of reduction stages

```
NPATH : I*4;         number of power paths (1=single,2=dual)
NPLNT : I*4 (3);     number of planet gears in epicyclic set
NHELX : I*4;         number of helicies (1=single, 2=double)
```

COMMON BLOCK DESEPC (EPICYCLIC DESIGN PARAMETERS)

```
MGOE  : R*4;         overall reduction ratio
MGE   : R*4 (3);     stage reduction ratio
RPMI  : R*4 (3);     stage input speed (rpm)
RPMPL : R*4 (3);     planet speed (rpm)
RPMO  : R*4 (3);     stage output speed (rpm)
PWRE  : R*4 (3);     stage power split per planet (hp)
DS    : R*4 (3);     diameter of sun gear (in)
DPLN  : R*4 (3);     diameter of planet gears (in)
DR    : R*4 (3);     diameter of ring gear (in)
FACEE : R*4 (3);     facewidth (in)
GI    : R*4 (3);     durability geometry factor (sun/planet)
GJS   : R*4 (3);     strength geometry factor (sun)
GJPL  : R*4 (3);     strength geometry factor (planet)
NS    : I*4 (3);     number of teeth, sun
NPLN  : I*4 (3);     number of teeth, planet
NR    : I*4 (3);     number of teeth, ring
```

COMMON BLOCK DESPRL (PARALLEL AXIS DESIGN PARAMETERS)

```
PWRFAC: R*4 (2,3);   stage power split factor
MGOP  : R*4 (2);     overall reduction ratio
MGP   : R*4 (3,2);   stage reduction ratio
```

```
RPMP   : R*4 (6,2); stage pinion and gear speed (rpm)
PWRP   : R*4 (6,2); stage power split per gear (hp)
DP     : R*4 (3,2); diameter of pinion (in)
DG     : R*4 (3,2); diameter of gear (in)
FACEP  : R*4 (3,2); facewidth (in)
GEOMI  : R*4 (3,2); duribility geometry factor
GEOMJG : R*4 (3,2); strength geometry factor (gear)
GEOMJP : R*4 (3,2); strength geometry factor (pinion)
NP     : I*4 (3,2); number of teeth, pinion
NG     : I*4 (3,2); number of teeth, gear
```

COMMON BLOCK RESEPC (EPICYCLIC PARAMETERS, RESULTS)

```
PLVE   : R*4 (3);   pitch line velocity (fpm)
FBYDE  : R*4 (3);   f/d ratio (facewidth/sun diameter)
CDE    : R*4 (3);   center distance (theoretical) (in)
WTE    : R*4 (3);   tangential tooth load (lb)
TLPIE  : R*4 (3);   tooth load per in (lb/in)
UNTLDE : R*4 (3);   unit load (psi)
MFE    : R*4 (3,3); mesh frequency (Hz)
KFCTRE : R*4 (3);   computed k-factor
SIGHE  : R*4 (3);   contact stress (psi)
SIGBE  : R*4 (3);   bending stress (psi)
TORQE  : R*4 (3,3); torgue (k in-lb)
RPME   : R*4 (3,3); gear speeds (rpm)
PDIAME : R*4 (3,3); pitch diameters (in)
WGHTE  : R*4;       gear set weight estimate (lb)
```

```
SPCWTE: R*4;         specific weight (lb/hp)
MTHE  : I*4 (3,3);   tooth numbers
ISIZEE: I*4 (3);     length, width, height estimates (in)
```

<u>COMMON BLOCK RESPRL</u> (<u>PARALLEL AXIS PARAMETERS</u>, <u>RESULTS</u>)

```
PLVP  : R*4 (3,2);   pitch line velocity (fpm)
FBYDP : R*4 (3,2);   f/d ratio (facewidth/pinion diameter)
CDP   : R*4 (3,2);   center distance (theoretical) (in)
WTP   : R*4 (6,2);   tangential tooth load (lb)
TLPIP : R*4 (6,2);   tooth load per inch (lb/in)
UNTLDP: R*4 (6,2);   unit load (psi)
MFP   : R*4 (3,2);   mesh frequency (Hz)
KFCTRP: R*4 (6,2);   computed k-factor
SIGHP : R*4 (3,2);   contact stress (psi)
SIGBP : R*4 (6,2);   bending stress (psi)
TORQP : R*4 (6,2);   torque (k in-lb)
PDIAMP: R*4 (6,2);   pitch diameters (in)
SCDMIN: R*4;         minimum source center distance (in)
SCDMAX: R*4;         maximum source center distance (in)
SHP   : R*4;         shaft horsepower, output (hp)
WGHTP : R*4;         gear set weight estimate (lb)
SPCWTP: R*4;         specific weight (lb/hp)
TRQOUT: R*4;         torque, output (k in-lb)
MTHP  : I*4 (6,2);   tooth numbers
ISIZEP: I*4 (3);     length, width, height estimates (in)
```

APPENDIX C

REGAD SAMPLE RUNS

This appendix contains samples of actual terminal sessions using REGAD. For the sake of brevity, only two complete sessions are included. However, a number of analysis and design runs were made using a full range of options and configurations, and they compared favorably to actual designs. The comparisons are not shown here due to the proprietary nature of the designs used for verification. The first example is an analysis run for a locked train, double reduction gear set with two different inputs. Following it, is the results section from a design run using the identical parameters as the analysis run. The second example is a double reduction epicyclic gear set with the complete analysis session followed by the results section of a design run as before. The analysis and design sessions are identical with one exception. A seed for a random number generator is requested in the design option instead of diameters and facewidths as in the analysis option. For those cases where an infeasible design is generated, a message will alert the user and the program will continue. To obtain a feasible design, or just a different one, rerun the program and provide a different seed for the random number generator. This method was used on several occasions to obtain the desired results. Once a feasible design is obtained, the user can then use the analysis option to obtain a design that more closely suits his needs.

I. PARALLEL AXIS GEAR SET
Analysis Session

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****************************************************************************
**                                                                        **
**                               REGAD                                    **
**                 REDUCTION GEAR ANALYSIS AND DESIGN                     **
**                                                                        **
****************************************************************************


   DO YOU DESIRE A PROGRAM DESCRIPTION? (Y OR N):
y

**********************************************************************
     THIS PROGRAM IS CAPABLE OF PERFORMING PRELIMINARY DESIGN
   OR ANALYSIS OF MULTIREDUCTION, PARALLEL AXIS AND EPICYCLIC
   REDUCTION GEARS.  THE CAPABILITIES AND FEATURES OF THE PRO-
   GRAM ARE AS FOLLOWS:

        1) MAXIMUM OF THREE REDUCTION STAGES ALLOWED
        2) CHOICE OF SINGLE OR DOUBLE HELICALS
        3) WEIGHT AND SIZE ESTIMATES PROVIDED
        4) FOR PARALLEL AXIS GEARS:
           - ONE OR TWO POWER SOURCES ALLOWED
           - SINGLE OR DUAL POWER PATHS ALLOWED
        5) FOR EPICYCLIC GEARS:
           - ONLY ONE POWER SOURCE ALLOWED
           - LIMITED TO 3, 4, OR 5 PLANET GEARS
           - ONLY SIMPLE EPICYCLICS PER REDUCTION STAGE
           - PLANETARY OR STAR ARRANGEMENTS POSSIBLE

     THE STANDARDS OF THE AMERICAN GEAR MANUFACTURING ASSOCI-
   ATION WERE USED AS A BASIS FOR THIS PROGRAM.  THE CONSTANTS
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   USED IN THE AGMA FORMULATIONS ARE BASED ON THOSE PUBLISHED
   BY F. A. THOMA, OF DELAVAL TURBINE, FOR MARINE PROPULSION
   GEARS.  AN OPTION IS PROVIDED DURING EXECUTION OF THE PRO-
   GRAM TO OBTAIN A LISTING OF THESE CONSTANTS, AND TO CHANGE
   ANY OF THEM FOR OTHER POSSIBLE APPLICATIONS.
     IT SHOULD BE NOTED THAT THE STRESSES LISTED IN THE OUTPUT
   ARE THOSE COMPUTED FROM THE AGMA FORMULATIONS AND ARE NOT
   FROM A DETAILED STRESS ANALYSIS.


   FOR MORE SPECIFIC INFORMATION, SEE THE USERS MANUAL OR
   OBTAIN A LISTING OF THE PROGRAM.
*****************************************************************


   DO YOU WISH THE PROGRAM TO CONTINUE INTO THE ANALYSIS
   AND DESIGN SEGMENTS? (Y OR N):
Y


   YOU WILL NOW BE ASKED TO PROVIDE THE PARAMETERS REQUIRED
FOR THE ANALYSIS OR DESIGN IN THIS RUN.


** ENTER PROGRAM OPTION CODE (1=DESIGN, 2=ANALYSIS):
?
2

** ENTER ARRANGEMENT CODE (1=PARALLEL AXIS, 2=EPICYCLIC):
?
1


   CHOOSE OPERATIONAL PROFILE CODE BELOW:
   OPERATIONAL MODE    SERVICE PROFILE    CODE
```

```
     FULL POWER         5 PERCENT MAX         1
    MAXIMUM LOAD          CONTINUOUS          2

** ENTER OPERATIONAL PROFILE CODE:
?
1

** ENTER NUMBER OF REDUCTIONS (1, 2, OR 3):
?
2


   CHOOSE DESIRED HELIX TYPE BELOW:
        TYPE      ANGLE     CODE
       SINGLE     15-25       1
       DOUBLE     25-50       2

** ENTER HELIX CODE:
?
2

** ENTER NUMBER OF POWER PATHS (1=SINGLE, 2=DUAL):
?
2

** ENTER NUMBER OF POWER SOURCES (1 OR 2):
?
2

   WILL ANY POWER SOURCE BE A MULTICYLINDER I. C. ENGINE? (Y OR N):
n

** ENTER POWER AND SPEED OF HIGH POWER SOURCE (HP,RPM):
?
21250,6990
```

```
** ENTER POWER AND SPEED OF LOW POWER SOURCE (HP,RPM):
?
21250,5980

** ENTER OUTPUT SHAFT/PROPELLER SPEED (RPM):
?
300

   WHICH DIAMETRAL PITCH WILL YOU SPECIFY?
   (1=TRANSVERSE, 2=NORMAL):
?
1

   WHICH PRESSURE ANGLE WILL YOU SPECIFY?
   (1=TRANSVERSE, 2=NORMAL):
?
2

   THE FOLLOWING PARAMETERS ARE REQUESTED FOR STAGE 1 :

** ENTER HELIX ANGLE (DEGREES):
?
35

** ENTER TRANSVERSE DIAMETRAL PITCH:
?
4.5

** ENTER NORMAL PRESSURE ANGLE (DEGREES):
?
20
```

```
   CHOOSE GEAR HARDNESS RANGE BELOW:
        BHN          CODE
     160 - 200         1
     200 - 240         2
     240 - 300         3
     300 - 360         4
     360 - 400         5
     400 - 640         6

** ENTER HARDNESS CODES FOR PINION AND GEAR (HCPIN,HCGEAR):
?
2,1


   THE FOLLOWING PARAMETERS ARE REQUESTED FOR STAGE 2 :

** ENTER HELIX ANGLE (DEGREES):
?
35

** ENTER TRANSVERSE DIAMETRAL PITCH:
?
3.5

** ENTER NORMAL PRESSURE ANGLE (DEGREES):
?
20


   CHOOSE GEAR HARDNESS RANGE BELOW:
        BHN          CODE
     160 - 200         1
     200 - 240         2
     240 - 300         3
     300 - 360         4
     360 - 400         5
```

```
    400 - 640       6

** ENTER HARDNESS CODES FOR PINION AND GEAR (HCPIN,HCGEAR):
?
2,1


   TO MAKE CORRECTIONS TO DATA JUST ENTERED, THE PROGRAM MUST BE
   ABORTED AND RE-STARTED.  DO YOU WISH TO ABORT THIS RUN? (Y OR N):
n


   DO YOU DESIRE A LISTING OF THE PRE-PROGRAMMED CONSTANTS USED
IN THE AGMA FORMULATIONS? (Y OR N):
y

    THE FOLLOWING IS A LISTING OF THE PRE-PROGRAMMED CONSTANTS
   USED IN THE AGMA FORMULATIONS WITH APPROPRIATE NOTES ON
   THEIR APPLICATION.  NOTE: THOSE STARTING WITH A 'C' ARE
   DURABILITY CONSTANTS AND THOSE WITH A 'K' ARE STRENGTH
   CONSTANTS.  SERVICE FACTOR APPLIES TO BOTH FORMULATIONS.

   ID    CONST     VALUE(S)   NOTES
    1   SF(1,1)      1.00     SERVICE FACTOR; A1,B1
        SF(1,2)      1.50                     A1,B2
        SF(2,1)      1.50                     A2,B1
        SF(2,2)      1.75                     A2,B2

    2    CV(1)       1.00     DYNAMIC FACTOR; C1
         CV(2)       0.83                     C2
         CV(3)       0.69                     C3

    3     CS         1.00     SIZE FACTOR

    4    CM(1)       1.25     LOAD DISTRIBUTION FACTOR; A1
         CM(2)       1.35                               A2
```

5	CF	1.00	SURFACE CONDITION FACTOR
6	CO(1)	1.15	OVERLOAD FACTOR; A1
	CO(2)	1.14	A2
7	CP	2300.0	ELASTIC PROPERTIES FACTOR
8	CL(1)	0.80	LIFE FACTOR; A1
	CL(2)	0.68	A2
9	CH	1.00	HARDNESS RATIO FACTOR
10	CT	1.00	TEMPERATURE FACTOR
11	CR(1)	1.16	RELIABILITY FACTOR; D1
	CR(2)	1.19	D2
	CR(3)	1.22	D3
	CR(4)	1.27	D4
	CR(5)	1.31	D5
	CR(6)	1.35	D6
12	SAC(1)	95000.	ALLOWABLE CONTACT STRESS; D1
	SAC(2)	108000.	D2
	SAC(3)	125000.	D3
	SAC(4)	146000.	D4
	SAC(5)	165000.	D5
	SAC(6)	182000.	D6
13	KV	0.70	DYNAMIC FACTOR
14	KS	1.00	SIZE FACTOR
15	KM	1.10	LOAD DISTRIBUTION FACTOR
16	KO(1)	1.21	OVERLOAD FACTOR; E1

	KO(2)	1.28	E2
17	KL(1)	0.80	LIFE FACTOR; A1
	KL(2)	0.68	A2
18	KT	1.00	TEMPERATURE FACTOR
19	KR(1)	1.16	RELIABILITY FACTOR; D1
	KR(2)	1.18	D2
	KR(3)	1.23	D3
	KR(4)	1.29	D4
	KR(5)	1.31	D5
	KR(6)	1.33	D6
20	SAT(1)	32900.	ALLOWABLE MATERIAL STRESS; D1
	SAT(2)	38100.	D2
	SAT(3)	44500.	D3
	SAT(4)	51750.	D4
	SAT(5)	54250.	D5
	SAT(6)	61000.	D6

DEFINITIONS OF CODED NOTES FROM ABOVE:

A1 NAVAL PROFILE - FULL POWER, 5 PERCENT MAX
A2 OTHER - MAXIMUM LOAD, CONTINUOUS

B1 POWER SOURCE - TURBINE OR MOTOR
B2 POWER SOURCE - MULTICYLINDER I. C. ENGINE

C1 FIRST REDUCTION STAGE
C2 SECOND REDUCTION STAGE
C3 THIRD REDUCTION STAGE

D1 HARDNESS RANGE: 160 - 200 BHN
D2 HARDNESS RANGE: 200 - 240 BHN
D3 HARDNESS RANGE: 240 - 300 BHN
D4 HARDNESS RANGE: 300 - 360 BHN

```
    D5  HARDNESS RANGE: 360 - 400 BHN
    D6  HARDNESS RANGE: 400 - 640 BHN

    E1  SINGLE POWER PATH
    E2  DOUBLE POWER PATH


  DO YOU DESIRE TO CHANGE ANY OF THE ABOVE VALUES? (Y OR N):
Y


  TO CHANGE A CONSTANT ABOVE, ENTER THE ID NUMBER WHEN PROMTED.
  USE ID NUMBER 99 WHEN NO FURTHER CHANGES ARE TO BE MADE.
  NOTE: WHEN ASKED FOR THE NEW VALUE OF THE CONSTANT, ENTERING
  A ZERO WILL CAUSE THE ORIGINAL VALUE TO REMAIN UNCHANGED.
  THIS IS USEFUL WHEN A CONSTANT HAS MULTIPLE VALUES, BUT NOT
  ALL OF THEM ARE TO BE CHANGED.


  ** ENTER THE CONSTANT ID NUMBER (1-20, 99 TO STOP):
?
16

  ** ENTER KO(1):
?
1.14

  ** ENTER KO(2):
?
0


  ** ENTER THE CONSTANT ID NUMBER (1-20, 99 TO STOP):
?
99
```

THE FOLLOWING IS A LISTING OF THE PRE-PROGRAMMED CONSTANTS USED IN THE AGMA FORMULATIONS WITH APPROPRIATE NOTES ON THEIR APPLICATION. NOTE: THOSE STARTING WITH A 'C' ARE DURABILITY CONSTANTS AND THOSE WITH A 'K' ARE STRENGTH CONSTANTS. SERVICE FACTOR APPLIES TO BOTH FORMULATIONS.

ID	CONST	VALUE(S)	NOTES
1	SF(1,1)	1.00	SERVICE FACTOR; A1,B1
	SF(1,2)	1.50	A1,B2
	SF(2,1)	1.50	A2,B1
	SF(2,2)	1.75	A2,B2
2	CV(1)	1.00	DYNAMIC FACTOR; C1
	CV(2)	0.83	C2
	CV(3)	0.69	C3
3	CS	1.00	SIZE FACTOR
4	CM(1)	1.25	LOAD DISTRIBUTION FACTOR; A1
	CM(2)	1.35	A2
5	CF	1.00	SURFACE CONDITION FACTOR
6	CO(1)	1.15	OVERLOAD FACTOR; A1
	CO(2)	1.14	A2
7	CP	2300.0	ELASTIC PROPERTIES FACTOR
8	CL(1)	0.80	LIFE FACTOR; A1
	CL(2)	0.68	A2
9	CH	1.00	HARDNESS RATIO FACTOR
10	CT	1.00	TEMPERATURE FACTOR
11	CR(1)	1.16	RELIABILITY FACTOR; D1

	CR(2)	1.19	D2
	CR(3)	1.22	D3
	CR(4)	1.27	D4
	CR(5)	1.31	D5
	CR(6)	1.35	D6
12	SAC(1)	95000.	ALLOWABLE CONTACT STRESS; D1
	SAC(2)	108000.	D2
	SAC(3)	125000.	D3
	SAC(4)	146000.	D4
	SAC(5)	165000.	D5
	SAC(6)	182000.	D6
13	KV	0.70	DYNAMIC FACTOR
14	KS	1.00	SIZE FACTOR
15	KM	1.10	LOAD DISTRIBUTION FACTOR
16	KO(1)	1.14	OVERLOAD FACTOR; E1
	KO(2)	1.28	E2
17	KL(1)	0.80	LIFE FACTOR; A1
	KL(2)	0.68	A2
18	KT	1.00	TEMPERATURE FACTOR
19	KR(1)	1.16	RELIABILITY FACTOR; D1
	KR(2)	1.18	D2
	KR(3)	1.23	D3
	KR(4)	1.29	D4
	KR(5)	1.31	D5
	KR(6)	1.33	D6
20	SAT(1)	32900.	ALLOWABLE MATERIAL STRESS; D1
	SAT(2)	38100.	D2

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     SAT(3)    44500.                              D3
     SAT(4)    51750.                              D4
     SAT(5)    54250.                              D5
     SAT(6)    61000.                              D6

DEFINITIONS OF CODED NOTES FROM ABOVE:
 A1  NAVAL PROFILE - FULL POWER, 5 PERCENT MAX
 A2  OTHER - MAXIMUM LOAD, CONTINUOUS

 B1  POWER SOURCE - TURBINE OR MOTOR
 B2  POWER SOURCE - MULTICYLINDER I. C. ENGINE

 C1  FIRST REDUCTION STAGE
 C2  SECOND REDUCTION STAGE
 C3  THIRD REDUCTION STAGE

 D1  HARDNESS RANGE: 160 - 200 BHN
 D2  HARDNESS RANGE: 200 - 240 BHN
 D3  HARDNESS RANGE: 240 - 300 BHN
 D4  HARDNESS RANGE: 300 - 360 BHN
 D5  HARDNESS RANGE: 360 - 400 BHN
 D6  HARDNESS RANGE: 400 - 640 BHN

 E1  SINGLE POWER PATH
 E2  DOUBLE POWER PATH


THE INFORMATION REQUESTED BELOW IS FOR REDUCTION STAGE 1
IN POWER TRAIN 1.

ENTER DIAMETERS OF PINION AND GEAR, INCHES (DP,DG):
?
9.31,29.35
```

```
** ENTER FACEWIDTH OF GEAR PAIR, INCHES:
?
16.62

   THE INFORMATION REQUESTED BELOW IS FOR REDUCTION STAGE 2
   IN POWER TRAIN 1.

** ENTER DIAMETERS OF PINION AND GEAR, INCHES (DP,DG):
?
14.24,105.25

** ENTER FACEWIDTH OF GEAR PAIR, INCHES:
?
25.97

   THE INFORMATION REQUESTED BELOW IS FOR REDUCTION STAGE 1
   IN POWER TRAIN 2.

** ENTER DIAMETERS OF PINION AND GEAR, INCHES (DP,DG):
?
10.01,26.98

** ENTER FACEWIDTH OF GEAR PAIR, INCHES:
?
18.02

   THE INFORMATION REQUESTED BELOW IS FOR REDUCTION STAGE 2
   IN POWER TRAIN 2.

** ENTER ONLY DIAMETER OF PINION, INCHES (DP):
?
14.24
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******************************************************************

POWER SOURCE 1:  TURBINE OR MOTOR
    INPUT POWER (HP):  21250.     INPUT SPEED (RPM):  6990.

ARRANGEMENT: PARALLEL AXIS, 2 INPUT(S), 2 POWER PATH(S), 2 REDUCTION(S)
    OUTPUT POWER (HP):  42500.0   OUTPUT SPEED (RPM):  300.
    RATIO: 23.301                 OUTPUT TORQUE (K IN-LB):   8925.0

SOURCE CENTER DISTANCE (IN): MIN=  38.8   MAX=  49.4

SIZING ESTIMATES FOR THE ENTIRE REDUCTION SET:
    WEIGHT (LB):  93200.     SPECIFIC WEIGHT (LB/HP):   2.19
    LENGTH (IN):  99   WIDTH (IN): 135   HEIGHT (IN): 144
```

		REDUCTION 1		REDUCTION 2	
		PINION	GEAR	PINION	GEAR
POWER SPLIT	HP	21250.	10625.	10625.	21250.
SPEED	RPM	6990.	2217.	2217.	300.
NUMBER OF TEETH		42	132	50	368
NORMAL DIAMETRAL PITCH		5.493		4.273	
TRANS. DIAMETRAL PITCH		4.500		3.500	
NORMAL PRESSURE ANGLE		20.0		20.0	
TRANS. PRESSURE ANGLE		24.0		24.0	
HELIX ANGLE		35.0		35.0	
GEAR RATIO		3.153		7.391	
PITCH DIAMETER	IN	9.31	29.35	14.24	105.25
EFFECTIVE FACEWIDTH	IN	16.62		25.97	
F/DP		1.79		1.82	
CENTER DISTANCE	IN	19.33		59.74	
PITCHLINE VELOCITY	FPM	17037.		8266.	
TANGENTIAL LOAD	LB	41160.	20580.	42417.	84835.
TOOTH LOAD/IN	LB/IN	2477.	1238.	1633.	3267.
UNIT LOAD	PSI	13605.	6802.	6979.	13957.

		Reduction 1 Pinion	Reduction 1 Gear	Reduction 2 Pinion	Reduction 2 Gear
MESH FREQRENCY	HZ	4893.		1848.	
K FACTOR (COMPUTED)		350.	175.	130.	260.
CONTACT STRESS	PSI	89094.		59079.	
BENDING STRESS	PSI	37381.	17155.	18416.	33846.
TORQUE	K IN-LB	191.6	302.0	302.0	4464.4
HARDNESS RANGE	BHN	200-240	160-200	200-240	160-200

****

POWER SOURCE 2: TURBINE OR MOTOR
INPUT POWER (HP): 21250. INPUT SPEED (RPM): 5980.

ARRANGEMENT: PARALLEL AXIS, 2 INPUT(S), 2 POWER PATH(S), 2 REDUCTION(S)
OUTPUT POWER (HP): 42500.0 OUTPUT SPEED (RPM): 300.
RATIO: 19.921 OUTPUT TORQUE (K IN-LB): 8925.0

SOURCE CENTER DISTANCE (IN): MIN= 38.8 MAX= 49.4

SIZING ESTIMATES FOR THE ENTIRE REDUCTION SET:
WEIGHT (LB): 93200. SPECIFIC WEIGHT (LB/HP): 2.19
LENGTH (IN): 99 WIDTH (IN): 135 HEIGHT (IN): 144

		REDUCTION 1		REDUCTION 2	
		PINION	GEAR	PINION	GEAR
POWER SPLIT	HP	21250.	10625.	10625.	21250.
SPEED	RPM	5980.	2219.	2219.	300.
NUMBER OF TEETH		45	121	50	368
NORMAL DIAMETRAL PITCH		5.493		4.273	
TRANS. DIAMETRAL PITCH		4.500		3.500	
NORMAL PRESSURE ANGLE		20.0		20.0	
TRANS. PRESSURE ANGLE		24.0		24.0	
HELIX ANGLE		35.0		35.0	
GEAR RATIO		2.695		7.391	
PITCH DIAMETER	IN	10.01	26.98	14.24	105.25

EFFECTIVE FACEWIDTH IN	18.02		25.97	
F/DP	1.80		1.82	
CENTER DISTANCE IN	18.49		59.74	
PITCHLINE VELOCITY FPM	15671.		8271.	
TANGENTIAL LOAD LB	44747.	22374.	42390.	84781.
TOOTH LOAD/IN LB/IN	2483.	1242.	1632.	3265.
UNIT LOAD PSI	13641.	6821.	6974.	13949.
MESH FREQRENCY HZ	4485.		1849.	
K FACTOR (COMPUTED)	340.	170.	130.	260.
CONTACT STRESS PSI	87718.		59060.	
BENDING STRESS PSI	37061.	17230.	18404.	33824.
TORQUE K IN-LB	224.0	301.8	301.8	4461.6
HARDNESS RANGE BHN	200-240	160-200	200-240	160-200

****

Results from Design Session

```
** ENTER SEED FOR RANDOM NUMBER GENERATOR (X.XX):
?
0.76

****************************************************************************

 POWER SOURCE 1:  TURBINE OR MOTOR
     INPUT POWER (HP):  21250.    INPUT SPEED (RPM):  6990.

 ARRANGEMENT: PARALLEL AXIS, 2 INPUT(S), 2 POWER PATH(S), 2 REDUCTION(S)
     OUTPUT POWER (HP):  42500.0   OUTPUT SPEED (RPM):  300.
     RATIO: 23.300                OUTPUT TORQUE (K IN-LB):   8925.0

 SOURCE CENTER DISTANCE (IN): MIN=  57.7   MAX=  57.7

 SIZING ESTIMATES FOR THE ENTIRE REDUCTION SET:
     WEIGHT (LB): 125000.     SPECIFIC WEIGHT (LB/HP):   2.94
     LENGTH (IN): 143   WIDTH (IN): 165   HEIGHT (IN): 177
```

		REDUCTION 1		REDUCTION 2	
		PINION	GEAR	PINION	GEAR
POWER SPLIT	HP	21250.	10625.	10625.	21250.
SPEED	RPM	6990.	2411.	2411.	300.
NUMBER OF TEETH		72	209	56	452
NORMAL DIAMETRAL PITCH		5.493		4.273	
TRANS. DIAMETRAL PITCH		4.500		3.500	
NORMAL PRESSURE ANGLE		20.0		20.0	
TRANS. PRESSURE ANGLE		24.0		24.0	
HELIX ANGLE		35.0		35.0	
GEAR RATIO		2.899		8.037	
PITCH DIAMETER	IN	15.99	46.35	16.06	129.07
EFFECTIVE FACEWIDTH	IN	30.91		32.19	

P/DP		1.93		2.00	
CENTER DISTANCE	IN	31.17		72.57	
PITCHLINE VELOCITY	FPM	29258.		10137.	
TANGENTIAL LOAD	LB	23968.	11984.	34587.	69174.
TOOTH LOAD/IN	LB/IN	775.	388.	1074.	2149.
UNIT LOAD	PSI	4259.	2130.	4591.	9182.
MESH FREQRENCY	HZ	8388.		2250.	
K FACTOR (COMPUTED)		65.	33.	75.	150.
CONTACT STRESS	PSI	37970.		44786.	
BENDING STRESS	PSI	10804.	5176.	11900.	22092.
TORQUE	K IN-LB	191.6	277.7	277.7	4464.3
HARDNESS RANGE	BHN	200-240	160-200	200-240	160-200

****

POWER SOURCE 2: TURBINE OR MOTOR
INPUT POWER (HP): 21250. INPUT SPEED (RPM): 5980.

ARRANGEMENT: PARALLEL AXIS, 2 INPUT(S), 2 POWER PATH(S), 2 REDUCTION(S)
OUTPUT POWER (HP): 42500.0 OUTPUT SPEED (RPM): 300.
RATIO: 19.933 OUTPUT TORQUE (K IN-LB): 8925.0

SOURCE CENTER DISTANCE (IN): MIN= 57.7 MAX= 57.7

SIZING ESTIMATES FOR THE ENTIRE REDUCTION SET:
WEIGHT (LB): 125000. SPECIFIC WEIGHT (LB/HP): 2.94
LENGTH (IN): 143 WIDTH (IN): 165 HEIGHT (IN): 177

		REDUCTION 1		REDUCTION 2	
		PINION	GEAR	PINION	GEAR
POWER SPLIT	HP	21250.	10625.	10625.	21250.
SPEED	RPM	5980.	1851.	1851.	300.
NUMBER OF TEETH		76	247	73	452
NORMAL DIAMETRAL PITCH		5.493		4.273	

TRANS. DIAMETRAL PITCH	4.500		3.500	
NORMAL PRESSURE ANGLE	20.0		20.0	
TRANS. PRESSURE ANGLE	24.0		24.0	
HELIX ANGLE	35.0		35.0	
GEAR RATIO	3.231		6.169	
PITCH DIAMETER IN	16.97	54.82	20.92	129.07
EFFECTIVE FACEWIDTH IN	27.14		27.14	
F/DP	1.60		1.30	
CENTER DISTANCE IN	35.89		75.00	
PITCHLINE VELOCITY FPM	26562.		10137.	
TANGENTIAL LOAD LB	26400.	13200.	34587.	69174.
TOOTH LOAD/IN LB/IN	973.	486.	1274.	2548.
UNIT LOAD PSI	5343.	2672.	5444.	10889.
MESH FREQRENCY HZ	7575.		2252.	
K FACTOR (COMPUTED)	75.	38.	71.	142.
CONTACT STRESS PSI	40667.		43269.	
BENDING STRESS PSI	13453.	6452.	13701.	25995.
TORQUE K IN-LB	224.0	361.8	361.8	4464.3
HARDNESS RANGE BHN	200-240	160-200	200-240	160-200

II. EPICYCLIC GEAR SET
Analysis Session

```
*****************************************************************
**                                                             **
**                           REGAD                             **
**              REDUCTION GEAR ANALYSIS AND DESIGN             **
**                                                             **
*****************************************************************


   DO YOU DESIRE A PROGRAM DESCRIPTION? (Y OR N):
n


   YOU WILL NOW BE ASKED TO PROVIDE THE PARAMETERS REQUIRED
FOR THE ANALYSIS OR DESIGN IN THIS RUN.


** ENTER PROGRAM OPTION CODE (1=DESIGN, 2=ANALYSIS):
?
2

** ENTER ARRANGEMENT CODE (1=PARALLEL AXIS, 2=EPICYCLIC):
?
2


   CHOOSE OPERATIONAL PROFILE CODE BELOW:
   OPERATIONAL MODE    SERVICE PROFILE    CODE
      FULL POWER       5 PERCENT MAX        1
     MAXIMUM LOAD        CONTINUOUS         2
```

```
** ENTER OPERATIONAL PROFILE CODE:
?
1

** ENTER NUMBER OF REDUCTIONS (1, 2, OR 3):
?
2


   CHOOSE DESIRED HELIX TYPE BELOW:
        TYPE      ANGLE     CODE
       SINGLE     15-25       1
       DOUBLE     25-50       2

** ENTER HELIX CODE:
?
2

   WILL ANY POWER SOURCE BE A MULTICYLINDER I. C. ENGINE? (Y OR N):
n

** ENTER POWER AND SPEED OF THE POWER SOURCE (HP,RPM):
?
8250,3600

** ENTER OUTPUT SHAFT/PROPELLER SPEED (RPM):
?
155


   WHICH DIAMETRAL PITCH WILL YOU SPECIFY?
   (1=TRANSVERSE, 2=NORMAL):
?
2
```

```
   WHICH PRESSURE ANGLE WILL YOU SPECIFY?
   (1=TRANSVERSE, 2=NORMAL):
?
2


   THE FOLLOWING PARAMETERS ARE REQUESTED FOR STAGE 1 :

** ENTER HELIX ANGLE (DEGREES):
?
25

** ENTER NORMAL DIAMETRAL PITCH:
?
8

** ENTER NORMAL PRESSURE ANGLE (DEGREES):
?
20

** ENTER EPICYCLIC CODE (1=PLANETARY, 2=STAR):
?
1

** ENTER NUMBER OF PLANET GEARS (3 TO 5):
?
4


   CHOOSE GEAR HARDNESS RANGE BELOW:
       BHN         CODE
     160 - 200       1
     200 - 240       2
     240 - 300       3
     300 - 360       4
     360 - 400       5
```

```
   400 - 640       6

** ENTER HARDNESS CODES FOR SUN/PLANETS AND RING (HCSUN,HCRING):
?
4,2

   THE FOLLOWING PARAMETERS ARE REQUESTED FOR STAGE 2 :

** ENTER HELIX ANGLE (DEGREES):
?
25

** ENTER NORMAL DIAMETRAL PITCH:
?
6

** ENTER NORMAL PRESSURE ANGLE (DEGREES):
?
20

** ENTER EPICYCLIC CODE (1=PLANETARY, 2=STAR):
?
1

** ENTER NUMBER OF PLANET GEARS (3 TO 5):
?
5


   CHOOSE GEAR HARDNESS RANGE BELOW:
       BHN          CODE
    160 - 200         1
    200 - 240         2
    240 - 300         3
    300 - 360         4
```

```
     360 - 400        5
     400 - 640        6

** ENTER HARDNESS CODES FOR SUN/PLANETS AND RING (HCSUN,HCRING):
?
4,2


   TO MAKE CORRECTIONS TO DATA JUST ENTERED, THE PROGRAM MUST BE
   ABORTED AND RE-STARTED.  DO YOU WISH TO ABORT THIS RUN? (Y OR N):
n


   DO YOU DESIRE A LISTING OF THE PRE-PROGRAMMED CONSTANTS USED
IN THE AGMA FORMULATIONS? (Y OR N):
n


   THE INFORMATION REQUESTED BELOW IS FOR REDUCTION STAGE 1.

** ENTER DIAMETERS, IN INCHES, OF SUN, PLANET, AND RING GEARS
   (DS, DPLN, DR):
?
12.55,18.76,50.34

** ENTER FACEWIDTH OF GEARS, IN INCHES:
?
19.13


   THE INFORMATION REQUESTED BELOW IS FOR REDUCTION STAGE 2.

** ENTER DIAMETERS, IN INCHES, OF SUN, PLANET, AND RING GEARS
   (DS, DPLN, DR):
?
22.99,30.16,83.67
```

```
** ENTER FACEWIDTH OF GEARS, IN INCHES:
?
27.57

**************************************************************************

 POWER SOURCE:  TURBINE OR MOTOR
     INPUT POWER (HP):    8250.     INPUT SPEED (RPM):   3600.

 ARRANGEMENT: EPICYCLIC, 2 REDUCTION(S)
     OUTPUT POWER (HP):    8250.    OUTPUT SPEED (RPM):   155.
     RATIO: 23.226                  OUTPUT TORQUE (K IN-LB):    3356.5

 SIZING ESTIMATES FOR THE ENTIRE REDUCTION SET:
     WEIGHT (LB):  65400.     SPECIFIC WEIGHT (LB/HP):   7.93
     LENGTH (IN): 133   WIDTH (IN): 109   HEIGHT (IN): 100


**************************************************************************
```

REDUCTION 1	SUN	PLANETS	RING-CAGE
GEAR ARRANGEMENT		PLANETARY	
NUMBER OF PLANETS		4	
POWER SPLIT HP	8250.	2063.	8250.
SPEED RPM	3600.	1928.	718.
NUMBER OF TEETH	91	136	365
NORMAL DIAMETRAL PITCH		8.000	
TRANS. DIAMETRAL PITCH		7.250	
NORMAL PRESSURE ANGLE		20.0	
TRANS. PRESSURE ANGLE		21.9	

HELIX ANGLE		25.0	
GEAR RATIO		5.011	
PITCH DIAMETER IN	12.55	18.76	50.34
EFFECTIVE FACEWIDTH IN		19.13	
F/DP		1.52	
CENTER DISTANCE IN		15.65	
PITCHLINE VELOCITY FPM		11828.	
TANGENTIAL LOAD LB		23017.	
TOOTH LOAD/IN LB/IN		1203.	
UNIT LOAD PSI		9626.	
MESH FREQRENCY HZ	11526.	1928.	2874.
K FACTOR (COMPUTED)		160.	
CONTACT STRESS PSI		62354.	
BENDING STRESS PSI		26284.	
TORQUE K IN-LB	144.4	215.9	723.5
HARDNESS RANGE BHN	300 - 360	300 - 360	200 - 240

****

		REDUCTION 2	
	SUN	PLANETS	RING-CAGE
GEAR ARRANGEMENT		PLANETARY	
NUMBER OF PLANETS		5	
POWER SPLIT HP	8250.	1650.	8250.
SPEED RPM	718.	430.	155.
NUMBER OF TEETH	125	164	455
NORMAL DIAMETRAL PITCH		6.000	
TRANS. DIAMETRAL PITCH		5.438	
NORMAL PRESSURE ANGLE		20.0	
TRANS. PRESSURE ANGLE		21.9	
HELIX ANGLE		25.0	
GEAR RATIO		4.639	
PITCH DIAMETER IN	22.99	30.16	83.67
EFFECTIVE FACEWIDTH IN		27.57	

F/DP			1.20	
CENTER DISTANCE	IN		26.57	
PITCHLINE VELOCITY	FPM		4324.	
TANGENTIAL LOAD	LB		62964.	
TOOTH LOAD/IN	LB/IN		2284.	
UNIT LOAD	PSI		13703.	
MESH FREQRENCY	HZ	2818.	430.	774.
K FACTOR (COMPUTED)			175.	
CONTACT STRESS	PSI		64864.	
BENDING STRESS	PSI		36504.	
TORQUE	K IN-LB	723.8	949.5	3356.5
HARDNESS RANGE	BHN	300 - 360	300 - 360	200 - 240

****

Results from Design Session

```
** ENTER SEED FOR RANDOM NUMBER GENERATOR (X.XX):
?
0.076

*************************************************************************

 POWER SOURCE:  TURBINE OR MOTOR
     INPUT POWER (HP):   8250.    INPUT SPEED (RPM):  3600.

 ARRANGEMENT: EPICYCLIC, 2 REDUCTION(S)
     OUTPUT POWER (HP):   8250.   OUTPUT SPEED (RPM):  155.
     RATIO: 23.093                OUTPUT TORQUE (K IN-LB):   3334.1

 SIZING ESTIMATES FOR THE ENTIRE REDUCTION SET:
     WEIGHT (LB):  66300.     SPECIFIC WEIGHT (LB/HP):   8.04
     LENGTH (IN): 154   WIDTH (IN):  92   HEIGHT (IN):  85

*************************************************************************

                                        REDUCTION 1
                        |     SUN      |    PLANETS    |   RING-CAGE   |
                        |--------------|---------------|---------------|
GEAR ARRANGEMENT        |               PLANETARY                      |
NUMBER OF PLANETS       |                   4                          |
POWER SPLIT          HP |     8250.    |     2063.     |     8250.     |
SPEED               RPM |     3600.    |     1786.     |      684.     |
NUMBER OF TEETH         |      98      |      160      |      418      |
NORMAL DIAMETRAL PITCH  |                 8.000                        |
TRANS. DIAMETRAL PITCH  |                 7.250                        |
NORMAL PRESSURE ANGLE   |                 20.0                         |
```

TRANS. PRESSURE ANGLE		21.9	
HELIX ANGLE		25.0	
GEAR RATIO		5.265	
PITCH DIAMETER IN	13.54	22.07	57.65
EFFECTIVE FACEWIDTH IN		14.52	
F/DP		1.07	
CENTER DISTANCE IN		17.80	
PITCHLINE VELOCITY FPM		12762.	
TANGENTIAL LOAD LB		21333.	
TOOTH LOAD/IN LB/IN		1470.	
UNIT LOAD PSI		11756.	
MESH FREQRENCY HZ	11665.	1786.	2735.
K FACTOR (COMPUTED)		175.	
CONTACT STRESS P5I		59881.	
BENDING STRESS PSI		32049.	
TORQUE K IN-LB	144.4	235.4	760.2
HARDNESS RANGE BHN	300 - 360	300 - 360	200 - 240

****

REDUCTION 2

	SUN	PLANETS	RING-CAGE
GEAR ARRANGEMENT		PLANETARY	
NUMBER OF PLANETS		5	
POWER SPLIT HP	8250.	1650.	8250.
SPEED RPM	684.	442.	156.
NUMBER OF TEETH	114	136	386
NORMAL DIAMETRAL PITCH		6.000	
TRANS. DIAMETRAL PITCH		5.438	
NORMAL PRESSURE ANGLE		20.0	
TRANS. PRESSURE ANGLE		21.9	
HELIX ANGLE		25.0	
GEAR RATIO		4.386	
PITCH DIAMETER IN	21.03	25.01	70.98

EFFECTIVE FACEWIDTH IN		39.42	
F/DP		1.87	
CENTER DISTANCE IN		23.02	
PITCHLINE VELOCITY FPM		3764.	
TANGENTIAL LOAD LB		72331.	
TOOTH LOAD/IN LB/IN		1835.	
UNIT LOAD PSI		11009.	
MESH FREQRENCY HZ	2639.	442.	779.
K FACTOR (COMPUTED)		161.	
CONTACT STRESS PSI		53704.	
BENDING STRESS PSI		30069.	
TORQUE K IN-LB	760.5	904.5	3334.1
HARDNESS RANGE BHN	300 - 360	300 - 360	200 - 240

****

APPENDIX D

PROGRAM LISTING

Module One

```
C*****************************************************************************
C*                              REGAD                                        *
C*                REDUCTION GEAR ANALYSIS AND DESIGN                         *
C*****************************************************************************
C     CODED BY:  LT J.L. PAQUETTE, USN           JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C        THIS IS THE MAIN PROGRAM FOR THE  REGAD  PACKAGE OF SUBROUTINES
C     FOR THE PRELIMINARY DESIGN OR ANALYSIS OF MULTIREDUCTION, PARALLEL
C     AXIS AND EPICYCLIC GEARING FOR MARINE APPLICATIONS.  A BRIEF DE-
C     SCRIPTION AND LISTING OF CAPABILITIES CAN BE OBTAINED AS AN OPTION
C     DURING THE EXECUTION OF THE PROGRAM.  THIS PACKAGE HAS BEEN DE-
C     SIGNED IN MODULAR FORM FOR EASE OF MAINTENANCE AND MODIFICATION.
C     WITH THE EXCEPTION OF FREE FORMATTED INPUT, EVERY ATTEMPT WAS MADE
C     TO ENSURE PORTABILITY BY USING ANSI FORTRAN (FORTRAN IV).
C
      REAL MGOP,MGP,MGOE,MGE,MFP,MFE,KFCTRP,KFCTRE
C
C        SEVEN COMMON BLOCKS ARE USED FOR DATA TRANSFER WITHIN THE PRO-
C     GRAM.  TWO CONTAIN THE PRE-PROGRAMMED AGMA CONSTANTS.  A LISTING
C     OF THESE CONSTANTS AND THEIR VALUES CAN BE OBTAINED AND SELECTIVE-
C     LY CHANGED AS AN OPTION DURING THE EXECUTION OF THE PROGRAM.
C
```

```
      COMMON /AGMAB/ SFB(2,2),AKV,AKS,AKM,AKO(2),SAT(6),AKL(2),AKR(6),AK1MOD0240
     1T                                                                 1MOD0250
C                                                                       1MOD0260
C *** COMMON BLOCK AGMAB  (FOR STRENGTH RATING)                          1MOD0270
C     AKL   : R*4 ARRAY (2);    LIFE FACTOR                             1MOD0280
C     AKM   : R*4;              LOAD DISTRIBUTION FACTOR                1MOD0290
C     AKO   : R*4 ARRAY (2);    OVERLOAD FACTOR                         1MOD0300
C     AKR   : R*4 ARRAY (6);    RELIABILITY FACTOR                      1MOD0310
C     AKS   : R*4;              SIZE FACTOR                             1MOD0320
C     AKT   : R*4;              TEMPERATURE FACTOR                      1MOD0330
C     AKV   : R*4;              DYNAMIC FACTOR                          1MOD0340
C     SAT   : R*4 ARRAY (6);    ALLOWABLE BENDING STRESS NUMBER         1MOD0350
C     SFB   : R*4 ARRAY (2,2);  SERVICE FACTOR                          1MOD0360
C                                                                       1MOD0370
      COMMON /AGMAH/ SFH(2,2),CV(3),CS,CM(2),CF,CO(2),SAC(6),CP,CL(2),CH1MOD0380
     1,CT,CR(6)                                                         1MOD0390
C                                                                       1MOD0400
C *** COMMON BLOCK AGMAH  (FOR DURABILITY RATING)                        1MOD0410
C     CF    : R*4;              SURFACE FINISH FACTOR                   1MOD0420
C     CH    : R*4;              HARDNESS FACTOR                         1MOD0430
C     CL    : R*4 ARRAY (2);    LIFE FACTOR                             1MOD0440
C     CM    : R*4 ARRAY (2);    LOAD DISTRIBUTION FACTOR                1MOD0450
C     CO    : R*4 ARRAY (2);    OVERLOAD FACTOR                         1MOD0460
C     CP    : R*4;              ELASTIC PROPERTIES FACTOR               1MOD0470
C     CR    : R*4 ARRAY (6);    RELIABILITY FACTOR                      1MOD0480
C     CS    : R*4;              SIZE FACTOR                             1MOD0490
C     CT    : R*4;              TEMPERATURE FACTOR                      1MOD0500
C     CV    : R*4 ARRAY (3);    DYNAMIC FACTOR                          1MOD0510
C     SAC   : R*4 ARRAY (6);    ALLOWABLE CONTACT STRESS NUMBER         1MOD0520
C     SFH   : R*4 ARRAY (2,2);  SERVICE FACTOR                          1MOD0530
C                                                                       1MOD0540
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),1MOD0550
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(31MOD0560
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX              1MOD0570
C                                                                       1MOD0580
C *** COMMON BLOCK DESDAT  (DESIGN PARAMETERS, INPUT)                    1MOD0590
```

AD-A117 828 NAVAL POSTGRADUATE SCHOOL MONTEREY CA F/G 9/2
AN INTERACTIVE COMPUTER PROGRAM FOR THE PRELIMINARY DESIGN AND --ETC(U)
MAR 82 J L PAQUETTE

UNCLASSIFIED NL

2 OF 2

AD A117828

END
DATE
FILMED
8-82
DTIC

```
C     DHELIX: R*4 ARRAY (3);   HELIX ANGLE (DEG)                          1MOD0600
C     DPHI  : R*4 ARRAY (3);   TRANSVERSE PRESSURE ANGLE (DEG)            1MOD0610
C     DPHIN : R*4 ARRAY (3);   NORMAL PRESSURE ANGLE (DEG)                1MOD0620
C     HELIX : R*4 ARRAY (3);   HELIX ANGLE (RAD)                          1MOD0630
C     IARR  : I*4;             ARRANGEMENT CODE (1=PARALLEL AXIS, 2=EPI-1MOD0640
C                              CYCLIC)                                    1MOD0650
C     NDIFP : I*4;             NUMBER OF DIFFERENT POWER SOURCES          1MOD0660
C     IEPIC : I*4 ARRAY (3);   EPICYCLIC CODE (1=PLANETARY, 2=STAR)       1MOD0670
C     IHARD : I*4 ARRAY (3,2); HARDNESS RANGE CODE (1-6, SEE SUBR. AGMA) 1MOD0680
C     IOPRO : I*4;             OPERATIONAL PROFILE CODE (1=NAVAL PROFILE1MOD0690
C                              FULL POWER 5% MAX; 2=OTHER, MAX POWER      1MOD0700
C                              CONTINUOUS)                                1MOD0710
C     IPWRSR: I*4 ARRAY (2);   POWER SOURCE CODE (1=TURBINE OR MOTOR, 2=1MOD0720
C                              MULTICYLINDER INTERNAL COMBUSTION ENGINE) 1MOD0730
C     NHELX : I*4;             NUMBER OF HELICIES (1=SINGLE, 2=DOUBLE)    1MOD0740
C     NPATH : I*4;             NUMBER OF POWER PATHS (1=SINGLE, 2=DUAL)   1MOD0750
C     NPLNT : I*4 ARRAY (3);   NUMBER OF PLANET GEARS IN EPICYCLIC SET    1MOD0760
C     NPWRIN: I*4;             NUMBER OF POWER SOURCES (INPUTS)           1MOD0770
C     NRED  : I*4;             NUMBER OF REDUCTION STAGES                 1MOD0780
C     PD    : R*4 ARRAY (3);   TRANSVERSE DIAMETRAL PITCH                 1MOD0790
C     PHI   : R*4 ARRAY (3);   TRANSVERSE PRESSURE ANGLE (RAD)            1MOD0800
C     PHIN  : R*4 ARRAY (3);   NORMAL PRESSURE ANGLE (RAD)                1MOD0810
C     PND   : R*4 ARRAY (3);   NORMAL DIAMETRAL PITCH                     1MOD0820
C     PWRIN : R*4 ARRAY (2);   SOURCE POWER INPUT (HP)                    1MOD0830
C     RPMIN : R*4 ARRAY (2);   SOURCE SPEED INPUT (RPM)                   1MOD0840
C     RPMOUT: R*4;             OUTPUT SHAFT/PROPELLER SPEED (RPM)         1MOD0850
C                                                                         1MOD0860
      COMMON /DESPRL/ PWRFAC(2,3),MGOP(2),MGP(3,2),RPMP(6,2),PWRP(6,2),D1MOD0870
     1P(3,2),DG(3,2),FACEP(3,2),GEOMI(3,2),GEOMJP(3,2),GEOMJG(3,2),NP(3,1MOD0880
     22),NG(3,2)                                                          1MOD0890
C                                                                         1MOD0900
C *** COMMON BLOCK DESPRL  (PARALLEL AXIS DESIGN PARAMETERS)              1MOD0910
C     DG    : R*4 ARRAY (3,2); DIAMETER OF GEAR (IN)                      1MOD0920
C     DP    : R*4 ARRAY (3,2); DIAMETER OF PINION (IN)                    1MOD0930
C     FACEP : R*4 ARRAY (3,2); FACEWIDTH (IN)                             1MOD0940
C     GEOMI : R*4 ARRAY (3,2); DURIBILITY GEOMETRY FACTOR                 1MOD0950
```

```
C     GEOMJG: R*4 ARRAY (3,2); STRENGTH GEOMETRY FACTOR (GEAR)
C     GEOMJP: R*4 ARRAY (3,2); STRENGTH GEOMETRY FACTOR (PINION)
C     MGOP  : R*4 ARRAY (2);   OVERALL REDUCTION RATIO
C     MGP   : R*4 ARRAY (3,2); STAGE REDUCTION RATIO
C     NG    : I*4 ARRAY (3,2); NUMBER OF TEETH, GEAR
C     NP    : I*4 ARRAY (3,2); NUMBER OF TEETH, PINION
C     PWRFAC: R*4 ARRAY (2,3); STAGE POWER SPLIT FACTOR
C     PWRP  : R*4 ARRAY (6,2); STAGE POWER SPLIT PER GEAR (HP)
C     RPMP  : R*4 ARRAY (6,2); STAGE PINION AND GEAR SPEED (RPM)
C
      COMMON /RESPRL/ PLVP(3,2),FBYDP(3,2),CDP(3,2),WTP(6,2),TLPIP(6,2),
     1UNTLDP(6,2),MFP(3,2),KFCTRP(6,2),SIGHP(3,2),SIGBP(6,2),TORQP(6,2),
     2PDIAMP(6,2),SCDMIN,SCDMAX,SHP,WGHTP,SPCWTP,MTHP(6,2),ISIZEP(3)
C
C *** COMMON BLOCK RESPRL  (PARALLEL AXIS PARAMETERS, RESULTS)
C     CDP   : R*4 ARRAY (3,2); CENTER DISTANCE (THEORETICAL) (IN)
C     FBYDP : R*4 ARRAY (3,2); F/D RATIO (FACEWIDTH/PINION DIAMETER)
C     ISIZEP: I*4 ARRAY (3);   LENGTH, WIDTH, HEIGHT ESTIMATES (IN)
C     KFCTRP: R*4 ARRAY (6,2); COMPUTED K-FACTOR
C     MFP   : R*4 ARRAY (3,2); MESH FREQUENCY (HZ)
C     MTHP  : I*4 ARRAY (6,2); TOOTH NUMBERS
C     PDIAMP: R*4 ARRAY (6,2); PITCH DIAMETERS (IN)
C     PLVP  : R*4 ARRAY (3,2); PITCH LINE VELOCITY (FPM)
C     SCDMAX: R*4;             MAXIMUM SOURCE CENTER DISTANCE (IN)
C     SCDMIN: R*4;             MINIMUM SOURCE CENTER DISTANCE (IN)
C     SHP   : R*4;             SHAFT HORSEPOWER, OUTPUT (HP)
C     SIGBP : R*4 ARRAY (6,2); BENDING STRESS (PSI)
C     SIGHP : R*4 ARRAY (3,2); CONTACT STRESS (PSI)
C     SPCWTP: R*4;             SPECIFIC WEIGHT (LB/HP)
C     TLPIP : R*4 ARRAY (6,2); TOOTH LOAD PER INCH (LB/IN)
C     TORQP : R*4 ARRAY (6,2); TORQUE (K IN-LB)
C     UNTLDP: R*4 ARRAY (6,2); UNIT LOAD (PSI)
C     WGHTP : R*4;             GEAR SET WEIGHT ESTIMATE (LB)
C     WTP   : R*4 ARRAY (6,2); TANGENTIAL TOOTH LOAD (LB)
C
      COMMON /DESEPC/ MGOE,MGE(3),RPMI(3),RPMPL(3),RPMO(3),PWRE(3),DS(3)
```

```
     1,DPLN(3),DR(3),FACEE(3),GI(3),GJS(3),GJPL(3),NS(3),NPLN(3),NR(3)
C
C *** COMMON BLOCK DESEPC  (EPICYCLIC DESIGN PARAMETERS)
C     DPLN  : R*4 ARRAY (3);   DIAMETER OF PLANET GEARS (IN)
C     DR    : R*4 ARRAY (3);   DIAMETER OF RING GEAR (IN)
C     DS    : R*4 ARRAY (3);   DIAMETER OF SUN GEAR (IN)
C     FACEE : R*4 ARRAY (3);   FACEWIDTH (IN)
C     GI    : R*4 ARRAY (3);   DURABILITY GEOMETRY FACTOR (SUN/PLANETS)
C     GJS   : R*4 ARRAY (3);   STRENGTH GEOMETRY FACTOR (SUN)
C     GJPL  : R*4 ARRAY (3);   STRENGTH GEOMETRY FACTOR (PLANET)
C     MGE   : R*4 ARRAY (3);   STAGE REDUCTION RATIO
C     MGOE  : R*4;             OVERALL REDUCTION RATIO
C     NPLN  : I*4 ARRAY (3);   NUMBER OF TEETH, PLANET
C     NR    : I*4 ARRAY (3);   NUMBER OF TEETH, RING
C     NS    : I*4 ARRAY (3);   NUMBER OF TEETH, SUN
C     PWRE  : R*4 ARRAY (3);   STAGE POWER SPLIT PER GEAR PAIR (HP)
C     RPMI  : R*4 ARRAY (3);   STAGE INPUT SPEED (RPM)
C     RPMO  : R*4 ARRAY (3);   STAGE OUTPUT SPEED (RPM)
C     RPMPL : R*4 ARRAY (3);   PLANET SPEED (RPM)
C
      COMMON /RESEPC/ PLVE(3),FBYDE(3),CDE(3),WTE(3),TLPIE(3),UNTLDE(3),
     1MFE(3,3),KFCTRE(3),SIGHE(3),SIGBE(3),TORQE(3,3),RPME(3,3),PDIAME(3
     2,3),WGHTE,SPCWTE,MTHE(3,3),ISIZEE(3)
C
C *** COMMON BLOCK RESEPC  (EPICYCLIC PARAMETERS, RESULTS)
C     CDE   : R*4 ARRAY (3);   CENTER DISTANCE (THEORETICAL) (IN)
C     FBYDE : R*4 ARRAY (3);   F/D RATIO (FACEWIDTH/SUN DIAMETER)
C     ISIZEE: I*4 ARRAY (3);   LENGTH, WIDTH, HEIGHT ESTIMATES (IN)
C     KFCTRE: R*4 ARRAY (3);   COMPUTED K-FACTOR
C     MFE   : R*4 ARRAY (3,3); MESH FREQUENCY (HZ)
C     MTHE  : I*4 ARRAY (3,3); TOOTH NUMBERS
C     PDIAME: R*4 ARRAY (3,3); PITCH DIAMETERS (IN)
C     PLVE  : R*4 ARRAY (3);   PITCH LINE VELOCITY (FPM)
C     RPME  : R*4 ARRAY (3,3); GEAR SPEEDS (RPM)
C     SIGBE : R*4 ARRAY (3);   BENDING STRESS (PSI)
C     SIGHE : R*4 ARRAY (3);   CONTACT STRESS (PSI)
```

```
C     SPCWTE: R*4;               SPECIFIC WEIGHT (LB/HP)             1MOD1680
C     TLPIE : R*4 ARRAY (3);     TOOTH LOAD PER IN  (LB/IN)          1MOD1690
C     TORQE : R*4 ARRAY (3,3);  TORGUE (K IN-LB)                     1MOD1700
C     UNTLDE: R*4 ARRAY (3);     UNIT LOAD (PSI)                     1MOD1710
C     WGHTE : R*4;               GEAR SET WEIGHT ESTIMATE (LB)       1MOD1720
C     WTE   : R*4 ARRAY (3);     TANGENTIAL TOOTH LOAD (LB)          1MOD1730
C                                                                    1MOD1740
C                                                                    1MOD1750
C     EXECUTE REGAD                                                  1MOD1760
C                                                                    1MGD1770
      DATA YES/1HY/                                                  1MOD1780
      WRITE (6,90)                                                   1MOD1790
      WRITE (6,100)                                                  1MOD1800
      READ (5,130) REP                                               1MOD1810
      IF (REP.EQ.YES) CALL DSCRPT                                    1MOD1820
      WRITE (6,120)                                                  1MOD1830
C                                                                    1MOD1840
C     DESIGN / ANALYSIS OPTION SELECTION                             1MOD1850
C                                                                    1MOD1860
      WRITE (6,70)                                                   1MOD1870
      READ (5,*) ICODE                                               1MOD1880
      IF (ICODE.LT.1) ICODE=1                                        1MOD1890
      IF (ICODE.GT.2) ICODE=2                                        1MOD1900
C                                                                    1MOD1910
C     CONFIGURATION SELECTION                                        1MOD1920
C                                                                    1MOD1930
      WRITE (6,80)                                                   1MOD1940
      READ (5,*) IARR                                                1MOD1950
      IF (IARR.LT.1) IARR=1                                          1MOD1960
      IF (IARR.GT.2) IARR=2                                          1MOD1970
      CALL INPUT                                                     1MOD1980
      WRITE (6,110)                                                  1MOD1990
      READ (5,130) REP                                               1MOD2000
      IF (REP.EQ.YES) CALL AGMA                                      1MOD2010
      L=ICODE+(IARR-1)*2                                             1MOD2020
      GO TO (10,20,40,50), L                                         1MOD2030
```

```
C                                                                 1MOD2040
C     PARALLEL AXIS REDUCTION GEARS                               1MOD2050
C                                                                 1MOD2060
C                                                                 1MOD2070
C     DESIGN                                                      1MOD2080
C                                                                 1MOD2090
10    CALL PRLDES                                                 1MOD2100
      GO TO 30                                                    1MOD2110
C                                                                 1MOD2120
C     ANALYSIS                                                    1MOD2130
C                                                                 1MOD2140
20    CALL PRLANL                                                 1MOD2150
C                                                                 1MOD2160
C     COMPLETE PARALLEL AXIS COMPUTATIONS                         1MOD2170
C                                                                 1MOD2180
30    CALL PRLRES                                                 1MOD2190
      CALL PRLSIZ                                                 1MOD2200
      CALL PRLOUT                                                 1MOD2210
      STOP                                                        1MOD2220
C                                                                 1MOD2230
C     EPICYCLIC REDUCTION GEARS                                   1MOD2240
C                                                                 1MOD2250
C                                                                 1MOD2260
C     DESIGN                                                      1MOD2270
C                                                                 1MOD2280
40    CALL EPCDES                                                 1MOD2290
      GO TO 60                                                    1MOD2300
C                                                                 1MOD2310
C     ANALYSIS                                                    1MOD2320
C                                                                 1MOD2330
50    CALL EPCANL                                                 1MOD2340
C                                                                 1MOD2350
C     COMPLETE EPICYCLIC COMPUTATIONS                             1MOD2360
C                                                                 1MOD2370
60    CALL EPCRES                                                 1MOD2380
      CALL EPCSIZ                                                 1MOD2390
```

```
      CALL EPCOUT                                                       1MOD2400
      STOP                                                              1MOD2410
C                                                                       1MOD2420
C     FORMAT STATMENTS                                                  1MOD2430
C                                                                       1MOD2440
C                                                                       1MOD2450
70    FORMAT (/,1X,52H** ENTER PROGRAM OPTION CODE (1=DESIGN, 2=ANALYSIS1MOD2460
     1):)                                                               1MOD2470
80    FORMAT (/,1X,57H** ENTER ARRANGEMENT CODE (1=PARALLEL AXIS, 2=EPIC1MOD2480
     1YCLIC):)                                                          1MOD2490
90    FORMAT (1H1,72(1H*),/,1X,2H**,68(1H ),2H**,/,1X,2H**,32(1H ),5HREG1MOD2500
     1AD,31(1H ),2H**,/,1X,2H**,17(1H ),34HREDUCTION GEAR ANALYSIS AND D1MOD2510
     2ESIGN,17(1H ),2H**,/,1X,2H**,68(1H ),2H**,/,1X,72(1H*),////)      1MOD2520
100   FORMAT (4X,46HDO YOU DESIRE A PROGRAM DESCRIPTION? (Y OR N):)     1MOD2530
110   FORMAT (//,4X,60HDO YOU DESIRE A LISTING OF THE PRE-PROGRAMMED CON1MOD2540
     1STANTS USED,/,1X,35HIN THE AGMA FORMULATIONS? (Y OR N):)          1MOD2550
120   FORMAT (//,4X,56HYOU WILL NOW BE ASKED TO PROVIDE THE PARAMETERS R1MOD2560
     1EQUIRED,/,1X,39HFOR THE ANALYSIS OR DESIGN IN THIS RUN.,//)       1MOD2570
130   FORMAT (1A1)                                                      1MOD2580
      END                                                               1MOD2590
C***********************************************************************1MOD2600
C     *     *     *     *     *     *     *     *     *     *     *     *1MOD2610
C***********************************************************************1MOD2620
      BLOCK DATA                                                        1MOD2630
      REAL MGOP,MGP,MGOE,MGE,MFP,MFE,KFCTRP,KFCTRE                      1MOD2640
      COMMON /AGMAH/ SFH(2,2),CV(3),CS,CM(2),CF,CO(2),SAC(6),CP,CL(2),CH1MOD2650
     1,CT,CR(6)                                                         1MOD2660
      COMMON /AGMAB/ SFB(2,2),AKV,AKS,AKM,AKO(2),SAT(6),AKL(2),AKR(6),AK1MOD2670
     1T                                                                 1MOD2680
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),1MOD2690
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(31MOD2700
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX              1MOD2710
      COMMON /DESPRL/ PWRFAC(2,3),MGOP(2),MGP(3,2),RPMP(6,2),PWRP(6,2),D1MOD2720
     1P(3,2),DG(3,2),FACEP(3,2),GEOMI(3,2),GEOMJP(3,2),GEOMJG(3,2),NP(3,1MOD2730
     22),NG(3,2)                                                        1MOD2740
      COMMON /RESPRL/ PLVP(3,2),FBYDP(3,2),CDP(3,2),WTP(6,2),TLPIP(6,2),1MOD2750
```

```
     1UNTLDP(6,2),MFP(3,2),KFCTRP(6,2),SIGHP(3,2),SIGBP(6,2),TORQP(6,2),
     2PDIAMP(6,2),SCDMIN,SCDMAX,SHP,WGHTP,SPCWTP,TRQOUT,MTHP(6,2),ISIZEP
     3(3)
      COMMON /DESEPC/ MGOE,MGE(3),RPMI(3),RPMPL(3),RPMO(3),PWRE(3),DS(3)
     1,DPLN(3),DR(3),FACEE(3),GI(3),GJS(3),GJPL(3),NS(3),NPLN(3),NR(3)
      COMMON /RESEPC/ PLVE(3),FBYDE(3),CDE(3),WTE(3),TLPIE(3),UNTLDE(3),
     1MFE(3,3),KFCTRE(3),SIGHE(3),SIGBE(3),TORQE(3,3),RPME(3,3),PDIAME(3
     2,3),WGHTE,SPCWTE,MTHE(3,3),ISIZEE(3)
      DATA SFH/1.,1.5,1.5,1.75/,CV/1.,.83,.69/,CS/1./,CM/1.25,1.35/,CF/1
     1./,CO/1.15,1.14/,SAC/95000.,108000.,125000.,146000.,165000.,182000
     2./,CP/2300./,CL/.80,.68/,CH/1./,CT/1./,CR/1.160,1.185,1.224,1.273,
     31.312,1.350/
      DATA SFB/1.,1.5,1.5,1.75/,AKV/.7/,AKS/1./,AKM/1.1/,AKO/1.21,1.28/,
     1SAT/32900.,38100.,44500.,51750.,54250.,61000./,AKL/.80,.68/,AKR/1.
     2160,1.180,1.230,1.288,1.313,1.330/,AKT/1./
      DATA IPWRSR/1,1/,PWRFAC/1.,1.,1.,.5,.5,.25/,MGOP/2*1./,MGOE/1./,PW
     1RIN/2*0./,RPMIN/2*0.0/
      END
C***********************************************************************
C    *     *     *     *     *     *     *     *     *     *     *     *
C***********************************************************************
      SUBROUTINE DSCRPT
C
C     CODED BY:  LT J.L. PAQUETTE, USN          JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C
C     SUBPROGRAM TO PROVIDE A GENERAL DESCRIPTION OF THE REGAD PACKAGE
C     AND AN OPTION TO STOP THE RUN IF ONLY THE DESCRIPTION IS DESIRED.
C
      DATA YES/1HY/
      WRITE (6,10)
      WRITE (6,20)
      WRITE (6,30)
      WRITE (6,40)
      WRITE (6,50)
```

```
      WRITE (6,60)                                                      1MOD3120
      READ (5,80) REP                                                   1MOD3130
      IF (REP.EQ.YES) RETURN                                            1MOD3140
C                                                                       1MOD3150
C     STOP BY USER                                                      1MOD3160
C                                                                       1MOD3170
      WRITE (6,70)                                                      1MOD3180
      STOP                                                              1MOD3190
C                                                                       1MOD3200
C     FORMAT STATEMENTS                                                 1MOD3210
C                                                                       1MOD3220
C                                                                       1MOD3230
10    FORMAT (1H1,65(1H*),/4X,59H  THIS PROGRAM IS CAPABLE OF PERFORMING1MOD3240
     1 PRELIMINARY DESIGN /4X,59HOR ANALYSIS OF MULTIREDUCTION, PARALLEL1MOD3250
     2 AXIS AND EPICYCLIC /4X,59HREDUCTION GEARS.  THE CAPABILITIES AND 1MOD3260
     3FEATURES OF THE PRO-/4X,20HGRAM ARE AS FOLLOWS:)                  1MOD3270
20    FORMAT (/9X,44H1) MAXIMUM OF THREE REDUCTION STAGES ALLOWED/9X,38H1MOD3280
     12) CHOICE OF SINGLE OR DOUBLE HELICALS/9X,37H3) WEIGHT AND SIZE ES1MOD3290
     2TIMATES PROVIDED/9X,27H4) FOR PARALLEL AXIS GEARS:/12X,34H- ONE OR1MOD3300
     3 TWO POWER SOURCES ALLOWED/12X,36H- SINGLE OR DUAL POWER PATHS ALL1MOD3310
     4OWED)                                                             1MOD3320
30    FORMAT (9X,23H5) FOR EPICYCLIC GEARS:/12X,31H- ONLY ONE POWER SOUR1MOD3330
     1CE ALLOWED/12X,36H- LIMITED TO 3, 4, OR 5 PLANET GEARS/12X,44H- ON1MOD3340
     2LY SIMPLE EPICYCLICS PER REDUCTION STAGE/12X,41H- PLANETARY OR STA1MOD3350
     3R ARRANGEMENTS POSSIBLE)                                          1MOD3360
40    FORMAT (/4X,59H  THE STANDARDS OF THE AMERICAN GEAR MANUFACTURING 1MOD3370
     1ASSOCI- /4X,59HATION WERE USED AS A BASIS FOR THIS PROGRAM.  THE C1MOD3380
     2ONSTANTS/4X,59HUSED IN THE AGMA FORMULATIONS ARE BASED ON THOSE PU1MOD3390
     3BLISHED /4X,59HBY F. A. THOMA, OF DELAVAL TURBINE, FOR MARINE PROP1MOD3400
     4ULSION  /4X,59HGEARS.  AN OPTION IS PROVIDED DURING EXECUTION OF T1MOD3410
     5HE PRO- /4X,59HGRAM TO OBTAIN A LISTING OF THESE CONSTANTS, AND TO1MOD3420
     6 CHANGE /4X,44HANY OF THEM FOR OTHER POSSIBLE APPLICATIONS./4X,59H1MOD3430
     7  IT SHOULD BE NOTED THAT THE STRESSES LISTED IN THE OUTPUT/4X,59H1MOD3440
     8ARE THOSE COMPUTED FROM THE AGMA FORMULATIONS AND ARE NOT  /4X,32H1MOD3450
     9FROM A DETAILED STRESS ANALYSIS.)                                 1MOD3460
50    FORMAT (//,4X,54HFOR MORE SPECIFIC INFORMATION, SEE THE USERS MANU1MOD3470
```

```
     1AL OR,/,4X,32HOBTAIN A LISTING OF THE PROGRAM.,/,1X,65(1H*))      1MOD3480
60    FORMAT (//,4X,53HDO YOU WISH THE PROGRAM TO CONTINUE INTO THE ANAL1MOD3490
     1YSIS,/,4X,30HAND DESIGN SEGMENTS? (Y OR N):)                      1MOD3500
70    FORMAT (///,5X,35H***** PROGRAM STOPPED BY USER *****)            1MOD3510
80    FORMAT (1A1)                                                      1MOD3520
      END                                                               1MOD3530
C*********************************************************************1MOD3540
C    *    *    *    *    *    *    *    *    *    *    *    *    *    * 1MOD3550
C*********************************************************************1MOD3560
      SUBROUTINE INPUT                                                  1MOD3570
C                                                                       1MOD3580
C     CODED BY:  LT J.L. PAQUETTE, USN          JAN 1982                1MOD3590
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940          1MOD3600
C                                                                       1MOD3610
C     SUBPROGRAM TO PROVIDE USER INPUT OF ALL USER-SPECIFIED DESIGN     1MOD3620
C     VARIABLES AND OPTIONS                                             1MOD3630
C                                                                       1MOD3640
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),1MOD3650
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(31MOD3660
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX              1MOD3670
C                                                                       1MOD3680
C     INITIALIZE                                                        1MOD3690
C                                                                       1MOD3700
      DATA YES/1HY/                                                     1MOD3710
      DEGRAD=4.*ATAN(1.)/180.                                           1MOD3720
C                                                                       1MOD3730
C     COMMON DATA                                                       1MOD3740
C                                                                       1MOD3750
      WRITE (6,230)                                                     1MOD3760
      READ (5,*) IOPRO                                                  1MOD3770
      IF (IOPRO.LT.1) IOPRO=1                                           1MOD3780
      IF (IOPRO.GT.2) IOPRO=2                                           1MOD3790
10    WRITE (6,240)                                                     1MOD3800
      READ (5,*) NRED                                                   1MOD3810
      IF ((NRED.GE.1).AND.(NRED.LE.3)) GO TO 20                         1MOD3820
      WRITE (6,250) NRED                                                1MOD3830
```

```
      GO TO 10                                                          1MOD3840
   20 WRITE (6,260)                                                     1MOD3850
      READ (5,*) NHELX                                                  1MOD3860
      IF (NHELX.LT.1) NHELX=1                                           1MOD3870
      IF (NHELX.GT.2) NHELX=2                                           1MOD3880
      GO TO (30,40), IARR                                               1MOD3890
C                                                                       1MOD3900
C     PARALLEL AXIS DATA                                                1MOD3910
C                                                                       1MOD3920
   30 WRITE (6,270)                                                     1MOD3930
      READ (5,*) NPATH                                                  1MOD3940
      IF (NPATH.LT.1) NPATH=1                                           1MOD3950
      IF (NPATH.GT.2) NPATH=2                                           1MOD3960
      GO TO 50                                                          1MOD3970
C                                                                       1MOD3980
C     EPICYCLIC DATA                                                    1MOD3990
C                                                                       1MOD4000
   40 NPWRIN=1                                                          1MOD4010
      NPATH=2                                                           1MOD4020
      GO TO 60                                                          1MOD4030
C                                                                       1MOD4040
C     COMMON DESIGN DATA                                                1MOD4050
C                                                                       1MOD4060
C                                                                       1MOD4070
C     POWER SOURCE DATA                                                 1MOD4080
C                                                                       1MOD4090
   50 WRITE (6,280)                                                     1MOD4100
      READ (5,*) NPWRIN                                                 1MOD4110
      IF (NPWRIN.LT.1) NPWRIN=1                                         1MOD4120
      IF (NPWRIN.GT.2) NPWRIN=2                                         1MOD4130
   60 WRITE (6,290)                                                     1MOD4140
      READ (5,550) REP1                                                 1MOD4150
      GO TO (70,80), NPWRIN                                             1MOD4160
C                                                                       1MOD4170
C     SINGLE POWER SOURCE                                               1MOD4180
C                                                                       1MOD4190
```

```
70    IF (REP1.EQ.YES) IPWRSR(1)=2                                         1MOD4200
      WRITE (6,300)                                                        1MOD4210
      READ (5,*) PWRIN(1),RPMIN(1)                                         1MOD4220
      GO TO 110                                                            1MOD4230
C                                                                          1MOD4240
C     DUAL POWER SOURCES                                                   1MOD4250
C                                                                          1MOD4260
80    IF (REP1.NE.YES) GO TO 100                                           1MOD4270
      WRITE (6,310)                                                        1MOD4280
      READ (5,*) IENG                                                      1MOD4290
      IF ((IENG.GE.1).AND.(IENG.LE.3)) GO TO 90                            1MOD4300
      WRITE (6,320) IENG                                                   1MOD4310
      GO TO 80                                                             1MOD4320
90    IF ((IENG.EQ.1).OR.(IENG.EQ.3)) IPWRSR(1)=2                          1MOD4330
      IF ((IENG.EQ.2).OR.(IENG.EQ.3)) IPWRSR(2)=2                          1MOD4340
100   WRITE (6,330)                                                        1MOD4350
      READ (5,*) PWRIN(1),RPMIN(1)                                         1MOD4360
      WRITE (6,340)                                                        1MOD4370
      READ (5,*) PWRIN(2),RPMIN(2)                                         1MOD4380
C                                                                          1MOD4390
C     OUTPUT SPEED OF REDUCTION SET                                        1MOD4400
C                                                                          1MOD4410
110   NDIFP=NPWRIN                                                         1MOD4420
      IF ((NPWRIN.EQ.2).AND.(PWRIN(1).EQ.PWRIN(2)).AND.(RPMIN(1).EQ.RPMI1MOD4430
     1N(2))) NDIFP=1                                                       1MOD4440
      WRITE (6,350)                                                        1MOD4450
      READ (5,*) RPMOUT                                                    1MOD4460
C                                                                          1MOD4470
C     DESIGN PARAMETER DATA                                                1MOD4480
C                                                                          1MOD4490
      WRITE (6,360)                                                        1MOD4500
      READ (5,*) IPD                                                       1MOD4510
      IF (IPD.LT.1) IPD=1                                                  1MOD4520
      IF (IPD.GT.2) IPD=2                                                  1MOD4530
      WRITE (6,370)                                                        1MOD4540
      READ (5,*) IPHI                                                      1MOD4550
```

```
      IF (IPHI.LT.1) IPHI=1                                             1MOD4560
      IF (IPHI.GT.2) IPHI=2                                             1MOD4570
      DO 220 I=1,NRED                                                   1MOD4580
      WRITE (6,380) I                                                   1MOD4590
  120 WRITE (6,390)                                                     1MOD4600
      READ (5,*) DHELIX(I)                                              1MOD4610
      IF ((NHELX.EQ.1).AND.(DHELIX(I).GE.15.0).AND.(DHELIX(I).LE.25.0)) 1MOD4620
     1GO TO 130                                                         1MOD4630
      IF ((NHELX.EQ.2).AND.(DHELIX(I).GE.25.0).AND.(DHELIX(I).LE.50.0)) 1MOD4640
     1GO TO 130                                                         1MOD4650
      WRITE (6,400) DHELIX(I),NHELX                                     1MOD4660
      GO TO 120                                                         1MOD4670
  130 HELIX(I)=DHELIX(I)*DEGRAD                                         1MOD4680
      GO TO (140,150), IPD                                              1MOD4690
  140 WRITE (6,410)                                                     1MOD4700
      READ (5,*) PD(I)                                                  1MOD4710
      PND(I)=PD(I)/COS(HELIX(I))                                        1MOD4720
      GO TO 160                                                         1MOD4730
  150 WRITE (6,420)                                                     1MOD4740
      READ (5,*) PND(I)                                                 1MOD4750
      PD(I)=PND(I)*COS(HELIX(I))                                        1MOD4760
  160 GO TO (170,180), IPHI                                             1MOD4770
  170 WRITE (6,430)                                                     1MOD4780
      READ (5,*) DPHI(I)                                                1MOD4790
      PHI(I)=DPHI(I)*DEGRAD                                             1MOD4800
      ARG=TAN(PHI(I))*COS(HELIX(I))                                     1MOD4810
      PHIN(I)=ATAN(ARG)                                                 1MOD4820
      DPHIN(I)=PHIN(I)/DEGRAD                                           1MOD4830
      GO TO 190                                                         1MOD4840
  180 WRITE (6,440)                                                     1MOD4850
      READ (5,*) DPHIN(I)                                               1MOD4860
      PHIN(I)=DPHIN(I)*DEGRAD                                           1MOD4870
      ARG=TAN(PHIN(I))/COS(HELIX(I))                                    1MOD4880
      PHI(I)=ATAN(ARG)                                                  1MOD4890
      DPHI(I)=PHI(I)/DEGRAD                                             1MOD4900
  190 IF (IARR.EQ.1) GO TO 210                                          1MOD4910
```

```
      WRITE (6,450)
      READ (5,*) IEPIC(I)
      IF (IEPIC(I).LT.1) IEPIC(I)=1
      IF (IEPIC(I).GT.2) IEPIC(I)=2
200   WRITE (6,460)
      READ (5,*) NPLNT(I)
      IF ((NPLNT(I).GE.3).AND.(NPLNT(I).LE.5)) GO TO 210
      WRITE (6,470) NPLNT(I)
      GO TO 200
210   WRITE (6,480)
      IF (IARR.EQ.1) WRITE (6,490)
      IF (IARR.EQ.2) WRITE (6,500)
      READ (5,*) IHARD(I,1),IHARD(I,2)
      IF ((IHARD(I,1).GE.1).AND.(IHARD(I,1).LE.6).AND.(IHARD(I,2).GE.1).
     1AND.(IHARD(I,2).LE.6)) GO TO 220
      IF (IARR.EQ.1) WRITE (6,510) IHARD(I,1),IHARD(I,2)
      IF (IARR.EQ.2) WRITE (6,520) IHARD(I,1),IHARD(I,2)
      GO TO 210
220   CONTINUE
C
C     DATA CORRECTION
C
      WRITE (6,530)
      READ (5,550) REP
      IF (REP.NE.YES) RETURN
      WRITE (6,540)
      STOP
C
C     FORMAT STATEMENTS
C
C
230   FORMAT (//,4X,38HCHOOSE OPERATIONAL PROFILE CODE BELOW:,/,4X,16HOP
     1ERATIONAL MODE,4X,15HSERVICE PROFILE,4X,4HCODE,/,7X,10HFULL POWER,
     28X,13H5 PERCENT MAX,7X,1H1,/,6X,12HMAXIMUM LOAD,9X,10HCONTINUOUS,8
     3X,1H2,//,1X,34H** ENTER OPERATIONAL PROFILE CODE:)
240   FORMAT (/,1X,43H** ENTER NUMBER OF REDUCTIONS (1, 2, OR 3):)
```

```
250   FORMAT (4X,I2,42H IS NOT A LEGITIMATE NUMBER OF REDUCTIONS.)       1MOD5280
260   FORMAT (//,4X,32HCHOOSE DESIRED HELIX TYPE BELOW:,/,8X,6H TYPE ,4X1MOD5290
     1,5HANGLE,4X,4HCODE,/,8X,6HSINGLE,4X,5H15-25,6X,1H1,/,8X,6HDOUBLE,41MOD5300
     2X,5H25-50,6X,1H2,//,1X,20H** ENTER HELIX CODE:)                   1MOD5310
270   FORMAT (/,1X,50H** ENTER NUMBER OF POWER PATHS (1=SINGLE, 2=DUAL):1MOD5320
     1)                                                                  1MOD5330
280   FORMAT (/,1X,42H** ENTER NUMBER OF POWER SOURCES (1 OR 2):)       1MOD5340
290   FORMAT (/,4X,64HWILL ANY POWER SOURCE BE A MULTICYLINDER I. C. ENG1MOD5350
     1INE? (Y OR N):)                                                    1MOD5360
300   FORMAT (/,1X,54H** ENTER POWER AND SPEED OF THE POWER SOURCE (HP,R1MOD5370
     1PM):)                                                              1MOD5380
310   FORMAT (//,4X,52HCHOOSE WHICH SOURCE(S) WILL BE AN I.C. ENGINE BEL1MOD5390
     1OW:,/,20X,12HPOWER SOURCE,4X,4HCODE,/,21X,10HHIGH POWER,7X,1H1,/,21MOD5400
     21X,10HLOW  POWER,7X,1H2,/,24X,4HBOTH,10X,1H3,//,1X,26H** ENTER I.C1MOD5410
     3. ENGINE CODE:)                                                    1MOD5420
320   FORMAT (4X,I2,38H IS NOT A LEGITIMATE I.C. ENGINE CODE.)          1MOD5430
330   FORMAT (/,1X,55H** ENTER POWER AND SPEED OF HIGH POWER SOURCE (HP,1MOD5440
     1RPM):)                                                             1MOD5450
340   FORMAT (/,1X,54H** ENTER POWER AND SPEED OF LOW POWER SOURCE (HP,R1MOD5460
     1PM):)                                                              1MO^5470
350   FORMAT (/,1X,44H** ENTER OUTPUT SHAFT/PROPELLER SPEED (RPM):)     1MCD5480
360   FORMAT (//,4X,39HWHICH DIAMETRAL PITCH WILL YOU SPECIFY?,/,4X,25H(1MOD5490
     11=TRANSVERSE, 2=NORMAL):)                                          1MOD5500
370   FORMAT (//,4X,38HWHICH PRESSURE ANGLE WILL YOU SPECIFY?,/,4X,25H(11MOD5510
     1=TRANSVERSE, 2=NORMAL):)                                           1MOD5520
380   FORMAT (//,4X,48HTHE FOLLOWING PARAMETERS ARE REQUESTED FOR STAGE,1MOD5530
     1I2,2H :)                                                           1MOD5540
390   FORMAT (/,1X,31H** ENTER HELIX ANGLE (DEGREES):)                  1MOD5550
400   FORMAT (//,4X,24HTHE HELIX ANGLE ENTERED,,F5.1,25H, DOES NOT AGREE1MOD5560
     1 WITH THE,/,4X,11HHELIX TYPE=,I2,36H CHOSEN.  TYPE=1, SINGLE: 15-21MOD5570
     25DEG.,,/,4X,26HTYPE=2, DOUBLE: 25-50 DEG.)                         1MOD5580
410   FORMAT (/,1X,36H** ENTER TRANSVERSE DIAMETRAL PITCH:)             1MOD5590
420   FORMAT (/,1X,32H** ENTER NORMAL DIAMETRAL PITCH:)                 1MOD5600
430   FORMAT (/,1X,45H** ENTER TRANSVERSE PRESSURE ANGLE (DEGREES):)    1MOD5610
440   FORMAT (/,1X,41H** ENTER NORMAL PRESSURE ANGLE (DEGREES):)        1MOD5620
450   FORMAT (/,1X,46H** ENTER EPICYCLIC CODE (1=PLANETARY, 2=STAR):)   1MOD5630
```

```
460   FORMAT (/,1X,41H** ENTER NUMBER OF PLANET GEARS (3 TO 5):)        1MOD5640
470   FORMAT (//,4X,I2,39H IS NOT A LEGITIMATE NUMBER OF PLANETS.)      1MOD5650
480   FORMAT (//,4X,33HCHOOSE GEAR HARDNESS RANGE BELOW:,/,9X,3HBHN,8X,41MOD5660
     1HCODE,/,6X,9H160 - 200,7X,1H1,/,6X,9H200 - 240,7X,1H2,/,6X,9H240 -1MOD5670
     2 300,7X,1H3,/,6X,9H300 - 360,7X,1H4,/,6X,9H360 - 400,7X,1H5,/,6X,91MOD5680
     3H400 - 640,7X,1H6)                                                1MOD5690
490   FORMAT (/,1X,59H** ENTER HARDNESS CODES FOR PINION AND GEAR (HCPIN1MOD5700
     1,HCGEAR):)                                                        1MOD5710
500   FORMAT (/,1X,64H** ENTER HARDNESS CODES FOR SUN/PLANETS AND RING (1MOD5720
     1HCSUN,HCRING):)                                                   1MOD5730
510   FORMAT (//,4X,25HTHE PINION HARDNESS CODE,,I2,31H AND/OR THE GEAR 1MOD5740
     1HARDNESS CODE,,/,4X,I2,26H ARE NOT LEGITIMATE CODES.)             1MOD5750
520   FORMAT (//,4X,29HTHE SUN/PLANET HARDNESS CODE,,I2,25H AND/OR THE R1MOD5760
     1ING HARDNESS,/,4X,5HCODE,,I2,26H ARE NOT LEGITIMATE CODES.)       1MOD5770
530   FORMAT (//,4X,61HTO MAKE CORRECTIONS TO DATA JUST ENTERED, THE PRO1MOD5780
     1GRAM MUST BE,/,4X,65HABORTED AND RE-STARTED.  DO YOU WISH TO ABORT1MOD5790
     2 THIS RUN? (Y OR N):)                                             1MOD5800
540   FORMAT (///,5X,44H***** RUN ABORTED BY USER --- RE-START *****)   1MOD5810
550   FORMAT (1A1)                                                      1MOD5820
      END                                                               1MOD5830
C***********************************************************************1MOD5840
C     *     *     *     *     *     *     *     *     *     *     *     *1MOD5850
C***********************************************************************1MOD5860
      SUBROUTINE AGMA                                                   1MOD5870
C                                                                       1MOD5880
C     CODED BY:  LT J.L. PAQUETTE, USN           JAN 1982               1MOD5890
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940          1MOD5900
C                                                                       1MOD5910
C     SUBPROGRAM TO LIST AND OPTIONALLY CHANGE THE PRE-PROGRAMMED       1MOD5920
C     AGMA CONSTANTS                                                    1MOD5930
C                                                                       1MOD5940
C     EXTERNAL SUBPROGRAM(S) REQUIRED: FUNCTION CKDATA                  1MOD5950
C                                                                       1MOD5960
      COMMON /AGMAB/ SFB(2,2),AKV,AKS,AKM,AKO(2),SAT(6),AKL(2),AKR(6),AK1MOD5970
     1T                                                                 1MOD5980
      COMMON /AGMAH/ SFH(2,2),CV(3),CS,CM(2),CF,CO(2),SAC(6),CP,CL(2),CH1MOD5990
```

```
      1,CT,CR(6)
C
C      INITIALIZATION
C
       DATA YES/1HY/,EP/30.E06/,EG/30.E06/,VP/.3/,VG/.3/
       ID=0
C
C      PROVIDE LISTING OF CONSTANTS AND THEIR VALUES
C
10     WRITE (6,340)
       WRITE (6,350) SFB(1,1),SFB(1,2),SFB(2,1),SFB(2,2)
       WRITE (6,360) (CV(I),I=1,3),CS,CM(1),CM(2),CF
       WRITE (6,370) CO(1),CO(2),CP,CL(1),CL(2),CH,CT
       WRITE (6,380) (CR(I),I=1,6)
       WRITE (6,390) (SAC(I),I=1,6)
       WRITE (6,400) AKV,AKS,AKM,AKO(1),AKO(2),AKL(1),AKL(2)
       WRITE (6,410) AKT,(AKR(I),I=1,6)
       WRITE (6,420) (SAT(I),I=1,6)
       WRITE (6,430)
       WRITE (6,440)
       IF (ID.EQ.99) RETURN
       WRITE (6,450)
       READ (5,700) REP
       IF (REP.NE.YES) RETURN
C
C      CHANGE SELECTED CONSTANTS
C
       WRITE (6,460)
20     WRITE (6,470)
       READ (5,*) ID
       IF (ID.EQ.99) GO TO 10
       IF ((ID.LT.1).OR.(ID.GT.20)) GO TO 20
       GO TO (30,50,70,80,100,110,130,140,160,170,180,200,220,230,240,250
      1,270,290,300,320), ID
30     DO 40 I=1,2
       DO 40 J=1,2
```

```
      WRITE (6,480) I,J                                          1MOD6360
      SFB(I,J)=CKDATA(SFB(I,J))                                  1MOD6370
      SFH(I,J)=SFB(I,J)                                          1MOD6380
40    CONTINUE                                                   1MOD6390
      GO TO 20                                                   1MOD6400
50    DO 60 I=1,3                                                1MOD6410
      WRITE (6,490) I                                            1MOD6420
      CV(I)=CKDATA(CV(I))                                        1MOD6430
60    CONTINUE                                                   1MOD6440
      GO TO 20                                                   1MOD6450
70    WRITE (6,500)                                              1MOD6460
      CS=CKDATA(CS)                                              1MOD6470
      GO TO 20                                                   1MOD6480
80    DO 90 I=1,2                                                1MOD6490
      WRITE (6,510) I                                            1MOD6500
      CM(I)=CKDATA(CM(I))                                        1MOD6510
90    CONTINUE                                                   1MOD6520
      GO TO 20                                                   1MOD6530
100   WRITE (6,520)                                              1MOD6540
      CF=CKDATA(CF)                                              1MOD6550
      GO TO 20                                                   1MOD6560
110   DO 120 I=1,2                                               1MOD6570
      WRITE (6,530) I                                            1MOD6580
      CO(I)=CKDATA(CO(I))                                        1MOD6590
120   CONTINUE                                                   1MOD6600
      GO TO 20                                                   1MOD6610
130   WRITE (6,540) EP,EG,VP,VG                                  1MOD6620
      WRITE (6,550)                                              1MOD6630
      READ (5,*) VAL1,VAL2                                       1MOD6640
      IF (VAL1.NE.0.0) EP=VAL1                                   1MOD6650
      IF (VAL2.NE.0.0) EG=VAL2                                   1MOD6660
      WRITE (6,560)                                              1MOD6670
      READ (5,*) VAL1,VAL2                                       1MOD6680
      IF (VAL1.NE.0.0) VP=VAL1                                   1MOD6690
      IF (VAL1.NE.0.0) VG=VAL2                                   1MOD6700
      AP=(1.-VP*VP)/EP                                           1MOD6710
```

```
      AG=(1.-VG*VG)/EG                                              1MOD6720
      A=4.*ATAN(1.)*(AP+AG)                                         1MOD6730
      CP=SQRT(1./A)                                                 1MOD6740
      GO TO 20                                                      1MOD6750
  140 DO 150 I=1,2                                                  1MOD6760
      WRITE (6,570) I                                               1MOD6770
      CL(I)=CKDATA(CL(I))                                           1MOD6780
  150 CONTINUE                                                      1MOD6790
      GO TO 20                                                      1MOD6800
  160 WRITE (6,580)                                                 1MOD6810
      CH=CKDATA(CH)                                                 1MOD6820
      GO TO 20                                                      1MOD6830
  170 WRITE (6,590)                                                 1MOD6840
      CT=CKDATA(CT)                                                 1MOD6850
      GO TO 20                                                      1MOD6860
  180 DO 190 I=1,6                                                  1MOD6870
      WRITE (6,600) I                                               1MOD6880
      CR(I)=CKDATA(CR(I))                                           1MOD6890
  190 CONTINUE                                                      1MOD6900
      GO TO 20                                                      1MOD6910
  200 DO 210 I=1,6                                                  1MOD6920
      WRITE (6,610) I                                               1MOD6930
      SAC(I)=CKDATA(SAC(I))                                         1MOD6940
  210 CONTINUE                                                      1MOD6950
      GO TO 20                                                      1MOD6960
  220 WRITE (6,620)                                                 1MOD6970
      AKV=CKDATA(AKV)                                               1MOD6980
      GO TO 20                                                      1MOD6990
  230 WRITE (6,630)                                                 1MOD7000
      AKS=CKDATA(AKS)                                               1MOD7010
      GO TO 20                                                      1MOD7020
  240 WRITE (6,640)                                                 1MOD7030
      AKM=CKDATA(AKM)                                               1MOD7040
      GO TO 20                                                      1MOD7050
  250 DO 260 I=1,2                                                  1MOD7060
      WRITE (6,650) I                                               1MOD7070
```

```
      AKO(I)=CKDATA(AKO(I))                                             1MOD7080
260   CONTINUE                                                          1MOD7090
      GO TO 20                                                          1MOD7100
270   DO 280 I=1,2                                                      1MOD7110
      WRITE (6,660) I                                                   1MOD7120
      AKL(I)=CKDATA(AKL(I))                                             1MOD7130
280   CONTINUE                                                          1MOD7140
      GO TO 20                                                          1MOD7150
290   WRITE (6,670)                                                     1MOD7160
      AKT=CKDATA(AKT)                                                   1MOD7170
      GO TO 20                                                          1MOD7180
300   DO 310 I=1,6                                                      1MOD7190
      WRITE (6,680) I                                                   1MOD7200
      AKR(I)=CKDATA(AKR(I))                                             1MOD7210
310   CONTINUE                                                          1MOD7220
      GO TO 20                                                          1MOD7230
320   DO 330 I=1,6                                                      1MOD7240
      WRITE (6,690) I                                                   1MOD7250
      SAT(I)=CKDATA(SAT(I))                                             1MOD7260
330   CONTINUE                                                          1MOD7270
      GO TO 20                                                          1MOD7280
C                                                                       1MOD7290
C     FORMAT STATEMENTS                                                 1MOD7300
C                                                                       1MOD7310
C                                                                       1MOD7320
340   FORMAT (1H1,4X,58HTHE FOLLOWING IS A LISTING OF THE PRE-PROGRAMMED1MOD7330
     1 CONSTANTS,/,4X,55HUSED IN THE AGMA FORMULATIONS WITH APPROPRIATE 1MOD7340
     2NOTES ON,/,4X,55HTHEIR APPLICATION.  NOTE: THOSE STARTING WITH A '1MOD7350
     3C' ARE,/,4X,54HDURABILITY CONSTANTS AND THOSE WITH A 'K' ARE STREN1MOD7360
     4GTH,/,4X,56HCONSTANTS.  SERVICE FACTOR APPLIES TO BOTH FORMULATION1MOD7370
     5S.,/)                                                             1MOD7380
350   FORMAT (4X,2HID,4X,5HCONST,4X,8HVALUE(S),3X,5HNOTES,/4X,12H 1    SF1MOD7390
     1(1,1),5X,F4.2,5X,21HSERVICE FACTOR; A1,B1,/4X,12H     SF(1,2),5X,F1MOD7400
     24.2,5X,21H                  A1,B2,/4X,12H     SF(2,1),5X,F4.2,5X,21H1MOD7410
     3                  A2,B1,/4X,12H     SF(2,2),5X,F4.2,5X,21H            1MOD7420
     4         A2,B2,/)                                                 1MOD7430
```

```
360   FORMAT (4X,12H 2    CV(1) ,5X,F4.2,5X,18HDYNAMIC FACTOR; C1,/4X,121MOD7440
     1H      CV(2) ,5X,F4.2,5X,18H                     C2,/4X,12H      CV(3) 1MOD7450
     2,5X,F4.2,5X,18H                     C3,//4X,12H 3      CS   ,5X,F4.2,5X,1MOD7460
     311HSIZE FACTOR,//4X,12H 4    CM(1) ,5X,F4.2,5X,28HLOAD DISTRIBUTIO1MOD7470
     4N FACTOR; A1,/4X,12H      CM(2) ,5X,F4.2,5X,28H                    1MOD7480
     5      A2,//4X,12H 5      CF   ,5X,F4.2,5X,24HSURFACE CONDITION FAC1MOD7490
     6TOR,/)                                                            1MOD7500
370   FORMAT (4X,12H 6    CO(1) ,5X,F4.2,5X,19HOVERLOAD FACTOR; A1,/4X,11MOD7510
     12H      CO(2) ,5X,F4.2,5X,19H                    A2,//4X,12H 7      C1MOD7520
     2P  ,4X,F6.1,4X,25HELASTIC PROPERTIES FACTOR,//4X,12H 8    CL(1) ,51MOD7530
     3X,F4.2,5X,15HLIFE FACTOR; A1,/4X,12H      CL(2) ,5X,F4.2,5X,15H   1MOD7540
     4          A2,//4X,12H 9      CH   ,5X,F4.2,5X,21HHARDNESS RATIO FAC1MOD7550
     5TOR,//4X,12H10      CT   ,5X,F4.2,5X,18HTEMPERATURE FACTOR,/)      1MOD7560
380   FORMAT (4X,12H11    CR(1) ,5X,F4.2,5X,22HRELIABILITY FACTOR; D1,/41MOD7570
     1X,12H      CR(2) ,5X,F4.2,5X,22H                    D2,/4X,12H     1MOD7580
     2  CR(3) ,5X,F4.2,5X,22H                    D3,/4X,12H      CR(4) ,1MOD7590
     35X,F4.2,5X,22H                    D4,/4X,12H      CR(5) ,5X,F4.2,51MOD7600
     4X,22H                    D5,/4X,12H      CR(6) ,5X,F4.2,5X,22H     1MOD7610
     5                D6,/)                                             1MOD7620
390   FORMAT (4X,12H12    SAC(1),4X,F7.0,3X,28HALLOWABLE CONTACT STRESS;1MOD7630
     1 D1,/4X,12H      SAC(2),4X,F7.0,3X,28H                           D21MOD7640
     2,/4X,12H      SAC(3),4X,F7.0,3X,28H                           D3,/41MOD7650
     3X,12H      SAC(4),4X,F7.0,3X,28H                           D4,/4X,11MOD7660
     42H      SAC(5),4X,F7.0,3X,28H                           D5,/4X,12H 1MOD7670
     5      SAC(6),4X,F7.0,3X,28H                           D6,/)        1MOD7680
400   FORMAT (4X,12H13      KV   ,5X,F4.2,5X,14HDYNAMIC FACTOR,//4X,12H141MOD7690
     1      KS   ,5X,F4.2,5X,11HSIZE FACTOR,//4X,12H15      KM   ,5X,F4.2,1MOD7700
     25X,24HLOAD DISTRIBUTION FACTOR,//4X,12H16    KO(1) ,5X,F4.2,5X,19H1MOD7710
     3OVERLOAD FACTOR; E1,/4X,12H      KO(2) ,5X,F4.2,5X,19H            1MOD7720
     4      E2,//4X,12H17    KL(1) ,5X,F4.2,5X,15HLIFE FACTOR; A1,/4X,12H1MOD7730
     5      KL(2) ,5X,F4.2,5X,15H             A2,/)                     1MOD7740
410   FORMAT (4X,12H18      KT   ,5X,F4.2,5X,18HTEMPERATURE FACTOR,//4X,11MOD7750
     12H19    KR(1) ,5X,F4.2,5X,22HRELIABILITY FACTOR; D1,/4X,12H      K1MOD7760
     2R(2) ,5X,F4.2,5X,22H                    D2,/4X,12H      KR(3) ,5X,1MOD7770
     3F4.2,5X,22H                    D3,/4X,12H      KR(4) ,5X,F4.2,5X,21MOD7780
     42H                    D4,/4X,12H      KR(5) ,5X,F4.2,5X,22H       1MOD7790
```

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     5           D5,/4X,12H      KR(6) ,5X,F4.2,5X,22H                1MOD7800
     6    D6,/)                                                        1MOD7810
420   FORMAT (4X,12H20    SAT(1),4X,F6.0,4X,29HALLOWABLE MATERIAL STRESS1MOD7820
     1; D1,/4X,12H      SAT(2),4X,F6.0,4X,29H                           1MOD7830
     2D2,/4X,12H      SAT(3),4X,F6.0,4X,29H                          D31MOD7840
     3,/4X,12H      SAT(4),4X,F6.0,4X,29H                          D4,/1MOD7850
     44X,12H      SAT(5),4X,F6.0,4X,29H                          D5,/4X1MOD7860
     5,12H      SAT(6),4X,F6.0,4X,29H                          D6,/)   1MOD7870
430   FORMAT (5X,38HDEFINITIONS OF CODED NOTES FROM ABOVE:,/6X,45HA1  MA1MOD7880
     1VAL PROFILE - FULL POWER, 5 PERCENT MAX,/6X,36HA2  OTHER - MAXIMUM1MOD7890
     2 LOAD, CONTINUOUS,//6X,35HB1  POWER SOURCE - TURBINE OR MOTOR,/6X,1MOD7900
     345HB2  POWER SOURCE - MULTICYLINDER I. C. ENGINE,//6X,25HC1  FIRST1MOD7910
     4 REDUCTION STAGE,/6X,26HC2  SECOND REDUCTION STAGE,/6X,25HC3  THIR1MOD7920
     5D REDUCTION STAGE,/)                                             1MOD7930
440   FORMAT (6X,33HD1  HARDNESS RANGE: 160 - 200 BHN,/6X,33HD2  HARDNES1MOD7940
     1S RANGE: 200 - 240 BHN,/6X,33HD3  HARDNESS RANGE: 240 - 300 BHN,/61MOD7950
     2X,33HD4  HARDNESS RANGE: 300 - 360 BHN,/6X,33HD5  HARDNESS RANGE: 1MOD7960
     3360 - 400 BHN,/6X,33HD6  HARDNESS RANGE: 400 - 640 BHN,//6X,21HE1 1MOD7970
     4 SINGLE POWER PATH,/6X,21HE2  DOUBLE POWER PATH,//)              1MOD7980
450   FORMAT (4X,58HDO YOU DESIRE TO CHANGE ANY OF THE ABOVE VALUES? (Y 1MOD7990
     1OR N):)                                                          1MOD8000
460   FORMAT (//,4X,61HTO CHANGE A CONSTANT ABOVE, ENTER THE ID NUMBER W1MOD8010
     1HEN PROMTED.,/,4X,56HUSE ID NUMBER 99 WHEN NO FURTHER CHANGES ARE 1MOD8020
     2TO BE MADE.,/,4X,60HNOTE: WHEN ASKED FOR THE NEW VALUE OF THE CONS1MOD8030
     3TANT, ENTERING,/,4X,57HA ZERO WILL CAUSE THE ORIGINAL VALUE TO REM1MOD8040
     4AIN UNCHANGED.,/,4X,59HTHIS IS USEFUL WHEN A CONSTANT HAS MULTIPLE1MOD8050
     5 VALUES, BUT NOT,/,4X,30HALL OF THEM ARE TO BE CHANGED.)         1MOD8060
470   FORMAT (//,4X,51H** ENTER THE CONSTANT ID NUMBER (1-20, 99 TO STOP1MOD8070
     1):)                                                              1MOD8080
480   FORMAT (/,4X,12H** ENTER SF(,I1,1H,,I1,2H):)                     1MOD8090
490   FORMAT (/,4X,12H** ENTER CV(,I1,2H):)                            1MOD8100
500   FORMAT (/,4X,12H** ENTER CS:)                                    1MOD8110
510   FORMAT (/,4X,12H** ENTER CM(,I1,2H):)                            1MOD8120
520   FORMAT (/,4X,12H** ENTER CP:)                                    1MOD8130
530   FORMAT (/,4X,12H** ENTER CO(,I1,2H):)                            1MOD8140
540   FORMAT (/,4X,31HCURRENT YOUNG'S MODULI ARE: EP=,2PE9.1,6H,  EG=,E91MOD8150
```

```
     1.1,/,4X,33HCURRENT POISSON'S RATIOS ARE: VP=,0PF5.3,6H,  VG=,F5.3)1MOD8160
550   FORMAT (/,4X,52H** ENTER YOUNG'S MODULI FOR PINION AND GEAR (EP,EG1MOD8170
     1):)                                                              1MOD8180
560   FORMAT (/,4X,53H** ENTER POISONN'S RATIO FOR PINION AND GEAR (VP,V1MOD8190
     1G):)                                                             1MOD8200
570   FORMAT (/,4X,12H** ENTER CL(,I1,2H):)                            1MOD8210
580   FORMAT (/,4X,12H** ENTER CH:)                                    1MOD8220
590   FORMAT (/,4X,12H** ENTER CT:)                                    1MOD8230
600   FORMAT (/,4X,12H** ENTER CR(,I1,2H):)                            1MOD8240
610   FORMAT (/,4X,13H** ENTER SAC(,I1,2H):)                           1MOD8250
620   FORMAT (/,4X,12H** ENTER KV:)                                    1MOD8260
630   FORMAT (/,4X,12H** ENTER KS:)                                    1MOD8270
640   FORMAT (/,4X,12H** ENTER KM:)                                    1MOD8280
650   FORMAT (/,4X,12H** ENTER KO(,I1,2H):)                            1MOD8290
660   FORMAT (/,4X,12H** ENTER KL(,I1,2H):)                            1MOD8300
670   FORMAT (/,4X,12H** ENTER KT:)                                    1MOD8310
680   FORMAT (/,4X,12H** ENTER KR(,I1,2H):)                            1MOD8320
690   FORMAT (/,4X,13H** ENTER SAT(,I1,2H):)                           1MOD8330
700   FORMAT (1A1)                                                     1MOD8340
      END                                                              1MOD8350
```

Module Two

```
      SUBROUTINE PRLANL
C
C     CODED BY:  LT J.L. PAQUETTE, USN           JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO PERFORM AN ANALYSIS OF A GIVEN PARALLEL
C     AXIS GEAR SET
C
C     EXTERNAL SUBPROGRAM(S) REQUIRED: SUBROUTINE GFI, SUBROUTINE GFJ,
C     FUNCTION AGMAE1, FUNCTION ARCCOS, FUNCTION ARCSIN, FUNCTION FALFA,
C     FUNCTION RTFNDR, FUNCTION SHRLD, FUNCTION THICK
C
      REAL MGOP,MGP
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(3
     22,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX
      COMMON /DESPRL/ PWRFAC(2,3),MGOP(2),MGP(3,2),RPMP(6,2),PWRP(6,2),D
     1P(3,2),DG(3,2),FACEP(3,2),GEOMI(3,2),GEOMJP(3,2),GEOMJG(3,2),NP(3,
     22),NG(3,2)
C
C     INITIALIZATION
C
      NRED2=NRED*2
C
C     ENTER REQUIRED INFORMATION: DIAMETERS AND FACEWIDTHS
C
      DO 20 J=1,NDIFP
      DO 20 I=1,NRED
      WRITE (6,70) I,J
      IF ((J.EQ.2).AND.(I.EQ.NRED)) GO TO 10
      WRITE (6,80)
      READ (5,*) DP(I,J),DG(I,J)
      MGP(I,J)=DG(I,J)/DP(I,J)
```

```
      NP(I,J)=INT(PD(I)*DP(I,J)+.5)                                      2MOD0340
      NG(I,J)=INT(PD(I)*DG(I,J)+.5)                                      2MOD0350
      WRITE (6,90)                                                       2MOD0360
      READ (5,*) FACEP(I,J)                                              2MOD0370
      GO TO 20                                                           2MOD0380
10    WRITE (6,100)                                                      2MOD0390
      READ (5,*) DP(NRED,2)                                              2MOD0400
      NP(NRED,2)=INT(PD(I)*DP(NRED,2)+.5)                                2MOD0410
      NG(NRED,2)=NG(NRED,1)                                              2MOD0420
      DG(NRED,2)=DG(NRED,1)                                              2MOD0430
      FACEP(NRED,2)=FACEP(NRED,1)                                        2MOD0440
      MGP(NRED,2)=DG(NRED,2)/DP(NRED,2)                                  2MOD0450
20    CONTINUE                                                           2MOD0460
C                                                                        2MOD0470
C     COMPUTE RATIOS, SPEED AND POWER SPLITS, AND GEOMETRY FACTORS       2MOD0480
C                                                                        2MOD0490
      DO 30 J=1,NDIFP                                                    2MOD0500
      L=1                                                                2MOD0510
      RPMP(1,J)=RPMIN(J)                                                 2MOD0520
      RPMP(2,J)=RPMP(1,J)/MGP(L,J)                                       2MOD0530
      IF (NRED.EQ.1) GO TO 30                                            2MOD0540
      DO 30 I=3,NRED2,2                                                  2MOD0550
      L=L+1                                                              2MOD0560
      IM1=I-1                                                            2MOD0570
      IP1=I+1                                                            2MOD0580
      RPMP(I,J)=RPMP(IM1,J)                                              2MOD0590
      RPMP(IP1,J)=RPMP(I,J)/MGP(L,J)                                     2MOD0600
30    CONTINUE                                                           2MOD0610
      DO 50 J=1,NDIFP                                                    2MOD0620
      PWR1=PWRIN(J)                                                      2MOD0630
      L=0                                                                2MOD0640
      DO 40 I=1,NRED2,2                                                  2MOD0650
      IP1=I+1                                                            2MOD0660
      L=L+1                                                              2MOD0670
      PWRP(I,J)=PWR1*PWRFAC(NPATH,L)                                     2MOD0680
      PWRP(IP1,J)=PWRP(I,J)/FLOAT(L*NPATH)                               2MOD0690
```

```
40    CONTINUE
      PWRP(NRED2,J)=PWR1
50    CONTINUE
      DO 60 J=1,NDIFF
      MGOP(J)=1.
      DO 60 I=1,NRED
      MGOP(J)=MGOP(J)*MGP(I,J)
      CALL GFI  (GEOMI(I,J),I,MGP(I,J),DP(I,J),DG(I,J),0)
      CALL GFJ  (GEOMJP(I,J),I,DP(I,J),DG(I,J),1,0)
      CALL GFJ  (GEOMJG(I,J),I,DP(I,J),DG(I,J),2,0)
60    CONTINUE
      RETURN
C
C     FORMAT STATEMENTS
C
C
70    FORMAT (//,4X,54HTHE INFORMATION REQUESTED BELOW IS FOR REDUCTION
     1STAGE,I2,/,4X,14HIN POWER TRAIN,I2,1H.)
80    FORMAT (/,1X,54H** ENTER DIAMETERS OF PINION AND GEAR, INCHES (DP,
     1DG):)
90    FORMAT (/,1X,40H** ENTER FACEWIDTH OF GEAR PAIR, INCHES:)
100   FORMAT (/,1X,46H** ENTER ONLY DIAMETER OF PINION, INCHES (DP):)
      END
C*********************************************************************
C   *     *     *     *     *     *     *     *     *     *     *     *     *     *
C*********************************************************************
      SUBROUTINE PRLDES
C
C     CODED BY:  LT J.L. PAQUETTE, USN            JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO PERFORM DESIGN CALCULATIONS FOR PARALLEL AXIS
C     REDUCTION GEARS USING A BASIC RANDOM SEARCH OPTIMIZATION
C     TECHNIQUE TO FIND THE GEAR DIMENSIONS SUBJECT TO SIZE AND
C     POWER CONSTRAINTS.
C
```

```
C     THE VARIABLES ENDING IN A 'Q' ARE LOCAL TO THIS SUBROUTINE AND    2MOD1060
C     REPRESENT THE VALUES OF THE REAL VARIABLE DURING A SPECIFIC       2MOD1070
C     ITERATION.  IF ALL CONSTRAINTS ARE MET (DESIGN IS FEASIBLE) THE   2MOD1080
C     GLOBAL VARIABLES WILL TAKE ON THESE VALUES.                       2MOD1090
C                                                                       2MOD1100
C     EXTERNAL SUBPROGRAM(S) REQUIRED: FUNCTION POWERB, FUNCTION POWERH,2MOD1110
C     SUBROUTINE GFI, SUBROUTINE GFJ, FUNCTION AGMAE1, FUNCTION ARCCOS, 2MOD1120
C     FUNCTION ARCSIN, FUNCTION RTFNDR, FUNCTION FALFA, FUNCTION SHRLD, 2MOD1130
C     FUNCTION THICK, FUNCTION RNDGEN                                   2MOD1140
C                                                                       2MOD1150
      REAL MGOP,MGP,MGO,MGQ,KK                                          2MOD1160
      LOGICAL FLAG,FLAGG                                                2MOD1170
      DIMENSION G(10,3,2),SPDP(3,2),SPDG(3,2),HPP(3,2),HPG(3,2)         2MOD1180
      DIMENSION DPQ(3,2),DGQ(3,2),MGQ(3,2),FACEQ(3,2),SCALE(3)          2MOD1190
      DIMENSION GI(3,2),GJP(3,2),GJG(3,2),REDFAC(3),S(20),IGG(3)        2MOD1200
      COMMON /AGMAB/ SFB(2,2),AKV,AKS,AKM,AKO(2),SAT(6),AKL(2),AKR(6),AK2MOD1210
     1T                                                                 2MOD1220
      COMMON /AGMAH/ SFH(2,2),CV(3),CS,CM(2),CF,CO(2),SAC(6),CP,CL(2),CH2MOD1230
     1,CT,CR(6)                                                         2MOD1240
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),2MOD1250
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(32MOD1260
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX              2MOD1270
      COMMON /DESPRL/ PWRFAC(2,3),MGOP(2),MGP(3,2),RPMP(6,2),PWRP(6,2),D2MOD1280
     1P(3,2),DG(3,2),FACEP(3,2),GEOMI(3,2),GEOMJP(3,2),GEOMJG(3,2),NP(3,2MOD1290
     22),NG(3,2)                                                        2MOD1300
C                                                                       2MOD1310
C     INITIALIZATION                                                    2MOD1320
C                                                                       2MOD1330
      DATA REDFAC/1.2,1.,.83/,IQMAX/7500/,IQ/0/,M/0/,BB/.5/,FDP/1./     2MOD1340
      DATA ALPHA/1./,SCALE/65.,5.,65./,IGG/6,8,10/,FLAG/.FALSE./,IK/0/  2MOD1350
      FOURPI=16.*ATAN(1.)                                               2MOD1360
      LL=NPATH+(NRED-1)*2                                               2MOD1370
      E=1./3.                                                           2MOD1380
      NDV=6*NRED-4                                                      2MOD1390
      NDVP=NRED*NDIFP                                                   2MOD1400
      NDVP3=3*NDVP                                                      2MOD1410
```

```
      MM=10*NDV                                                         2MOD1420
      IF (NHELX.EQ.2)  FDP=2.25                                         2MOD1430
      IF (NHELX.EQ.2)  SCALE(3)=150.                                    2MOD1440
      IRET=1                                                            2MOD1450
      WRITE (6,440)                                                     2MOD1460
      READ  (5,*) RND                                                   2MOD1470
C                                                                       2MOD1480
C     COMPUTE THE STAGE GEAR RATIOS FOR THE INITIAL DESIGN              2MOD1490
C                                                                       2MOD1500
      DO 60 J=1,NDIFP                                                   2MOD1510
      MGOP(J)=RPMIN(J)/RPMOUT                                           2MOD1520
      MGO=MGOP(J)                                                       2MOD1530
      GO TO (10,20,30,40,50,50), LL                                     2MOD1540
10    IF ((MGO.LE.1.0).OR.(MGO.GT.10.0))  GO TO 370                     2MOD1550
      MGQ(1,J)=MGO                                                      2MOD1560
      GO TO 60                                                          2MOD1570
20    IF ((MGO.LE.2.24).OR.(MGO.GT.10.0))  GO TO 370                    2MOD1580
      MGQ(1,J)=MGO                                                      2MOD1590
      GO TO 60                                                          2MOD1600
30    IF ((MGO.LE.2.0).OR.(MGO.GT.20.0))  GO TO 370                     2MOD1610
      MGQ(2,J)=SQRT(MGO)-1.                                             2MOD1620
      MGQ(1,J)=MGO/MGQ(2,J)                                             2MOD1630
      GO TO 60                                                          2MOD1640
40    IF ((MGO.LE.2.9).OR.(MGO.GT.48.4))  GO TO 370                     2MOD1650
      MGQ(2,J)=SQRT(MGO)+3.                                             2MOD1660
      MGQ(1,J)=MGO/MGQ(2,J)                                             2MOD1670
      GO TO 60                                                          2MOD1680
50    IF (MGO.LT.5) GO TO 370                                           2MOD1690
      MGQ(2,J)=MGO**E                                                   2MOD1700
      MGQ(3,J)=MGQ(2,J)+3.                                              2MOD1710
      MGQ(1,J)=MGO/(MGQ(2,J)*MGQ(3,J))                                  2MOD1720
60    CONTINUE                                                          2MOD1730
C                                                                       2MOD1740
C     COMPUTE POWER AND SPEED SPLITS FOR THE INITIAL DESIGN             2MOD1750
C                                                                       2MOD1760
      DO 80 J=1,NDIFP                                                   2MOD1770
```

```
      RPM1=RPMIN(J)                                                     2MOD1780
      PWR1=PWRIN(J)                                                     2MOD1790
      DO 70 I=1,NRED                                                    2MOD1800
      SPDP(I,J)=RPM1                                                    2MOD1810
      SPDG(I,J)=RPM1/MGQ(I,J)                                           2MOD1820
      RPM1=SPDG(I,J)                                                    2MOD1830
      HPP(I,J)=PWR1*PWRFAC(NPATH,I)                                     2MOD1840
      HPG(I,J)=PWR1/FLOAT(NPATH*I)                                      2MOD1850
70    CONTINUE                                                          2MOD1860
      HPG(NRED,J)=PWR1                                                  2MOD1870
80    CONTINUE                                                          2MOD1880
C                                                                       2MOD1890
C     ESTIMATE INITIAL DESIGN AS START POINT FOR OPTIMIZATION           2MOD1900
C                                                                       2MOD1910
      DO 90 J=1,NDIFP                                                   2MOD1920
      DO 90 I=1,NRED                                                    2MOD1930
      IH=IHARD(I,1)                                                     2MOD1940
      BRAC=SAC(IH)*1.E-04/CR(IH)                                        2MOD1950
      KK=BRAC*BRAC*REDFAC(I)*2.80/(CO(IOPRO)*CM(IOPRO))                 2MOD1960
      ANUM=126050.*HPP(I,J)*(MGQ(I,J)+1.)                               2MOD1970
      DEN=SPDP(I,J)*FDP*KK*MGQ(I,J)                                     2MOD1980
      DPQ(I,J)=(ANUM/DEN)**E                                            2MOD1990
      FACEQ(I,J)=FDP*DPQ(I,J)                                           2MOD2000
90    CONTINUE                                                          2MOD2010
C                                                                       2MOD2020
C     COMPUTE VALUES OF DEPENDENT VARIABLES                             2MOD2030
C                                                                       2MOD2040
100   GO TO (110,120,130), NRED                                         2MOD2050
C *** SINGLE REDUCTION                                                  2MOD2060
110   MGQ(1,1)=MGOP(1)                                                  2MOD2070
      DGQ(1,1)=MGQ(1,1)*DPQ(1,1)                                        2MOD2080
      IF (NDIFP.EQ.1) GO TO 150                                         2MOD2090
      MGQ(1,2)=MGOP(2)                                                  2MOD2100
      DGQ(1,2)=DGQ(1,1)                                                 2MOD2110
      DPQ(1,2)=DGQ(1,2)/MGQ(1,2)                                        2MOD2120
      FACEQ(1,2)=FACEQ(1,1)                                             2MOD2130
```

```
      GO TO 150
C *** DOUBLE REDUCTION
120   MGQ(1,1)=MGOP(1)/MGQ(2,1)
      DGQ(1,1)=MGQ(1,1)*DPQ(1,1)
      DGQ(2,1)=MGQ(2,1)*DPQ(2,1)
      IF (NDIFP.EQ.1) GO TO 150
      DGQ(2,2)=DGQ(2,1)
      MGQ(2,2)=DGQ(2,2)/DPQ(2,2)
      MGQ(1,2)=MGOP(2)/MGQ(2,2)
      DGQ(1,2)=MGQ(1,2)*DPQ(1,2)
      FACEQ(2,2)=FACEQ(1,2)
      GO TO 150
C *** TRIPLE REDUCTION
130   MGQ(1,1)=MGOP(1)/(MGQ(2,1)*MGQ(3,1))
      DO 140 I=1,3
140   DGQ(I,1)=MGQ(I,1)*DPQ(I,1)
      IF (NDIFP.EQ.1) GO TO 150
      DGQ(3,2)=DGQ(3,1)
      MGQ(3,2)=DGQ(3,2)/DPQ(3,2)
      MGQ(1,2)=MGOP(2)/(MGQ(2,2)*MGQ(3,2))
      DGQ(2,2)=MGQ(2,2)*DPQ(2,2)
      DGQ(1,2)=MGQ(1,2)*DPQ(1,2)
      FACEQ(3,2)=FACEQ(3,1)
C
C     COMPUTE CONSTRAINTS AND OBJECTIVE FUNCTION
C
150   VQ=0.0
      FLAGG=.FALSE.
      DO 190 J=1,NDIFP
      DO 190 I=1,NRED
      CALL GFI (GI(I,J),I,MGQ(I,J),DPQ(I,J),DGQ(I,J),0)
      APWRH=POWERH(SPDP(I,J),FACEQ(I,J),DPQ(I,J),I,J,GI(I,J))
      CALL GFJ (GJP(I,J),I,DPQ(I,J),DGQ(I,J),1,0)
      APWRBP=POWERB(SPDP(I,J),FACEQ(I,J),DPQ(I,J),I,J,1,GJP(I,J))
      CALL GFJ (GJG(I,J),I,DPQ(I,J),DGQ(I,J),2,0)
      APWRBG=POWERB(SPDP(I,J),FACEQ(I,J),DPQ(I,J),I,J,2,GJG(I,J))
```

```
      FLB=FOURPI/(PD(I)*TAN(HELIX(I)))                                   2MOD2500
      IF (FDP.EQ.2.25) FLB=DPQ(I,J)                                      2MOD2510
      FUB=FDP*DPQ(I,J)                                                   2MOD2520
      G(1,I,J)=HPP(I,J)/APWRH-1.0                                        2MOD2530
      G(2,I,J)=HPP(I,J)/APWRBP-1.0                                       2MOD2540
      G(3,I,J)=HPG(I,J)/APWRBG-1.0                                       2MOD2550
      IF ((G(1,I,J).GT.0.).OR.(G(2,I,J).GT.0.).OR.(G(3,I,J).GT.0.)) FLAG2MOD2560
     1G=.TRUE.                                                           2MOD2570
      G(4,I,J)=DGQ(I,J)/200.-1.0                                         2MOD2580
      G(5,I,J)=FLB/FACEQ(I,J)-1.0                                        2MOD2590
      G(6,I,J)=FACEQ(I,J)/FUB-1.0                                        2MOD2600
      GO TO (180,160,170), NRED                                          2MOD2610
  160 IF (NPATH.EQ.1) G(7,I,J)=DGQ(1,J)/DGQ(2,J)-1.0                     2MOD2620
      IF (NPATH.EQ.2) G(7,I,J)=MGQ(1,J)/MGQ(2,J)-1.0                     2MOD2630
      G(8,I,J)=DPQ(1,J)/DPQ(2,J)-1.0                                     2MOD2640
      GO TO 180                                                          2MOD2650
  170 G(7,I,J)=MGQ(1,J)/MGQ(2,J)-1.0                                     2MOD2660
      G(8,I,J)=MGQ(2,J)/MGQ(3,J)-1.0                                     2MOD2670
      G(9,I,J)=DPQ(1,J)/DPQ(2,J)-1.0                                     2MOD2680
      G(10,I,J)=DPQ(2,J)/DPQ(3,J)-1.0                                    2MOD2690
  180 VQ=VQ+.25*(MGQ(I,J)+1.)*(MGQ(I,J)+1.)*DPQ(I,J)*DPQ(I,J)*FACEQ(I,J) 2MOD2700
  190 CONTINUE                                                           2MOD2710
C                                                                        2MOD2720
C     CHECK FOR CONSTRAINT VIOLATIONS  (CONSTRAINTS VIOLATED IF AT       2MOD2730
C     LEAST ONE HAS A VALUE GREATER THAN ZERO)                           2MOD2740
C                                                                        2MOD2750
      GMAX=-1.0E+20                                                      2MOD2760
      IG=IGG(NRED)                                                       2MOD2770
      DO 200 K=1,IG                                                      2MOD2780
      DO 200 I=1,NRED                                                    2MOD2790
      DO 200 J=1,NDIFP                                                   2MOD2800
      GMAX=AMAX1(GMAX,G(K,I,J))                                          2MOD2810
  200 CONTINUE                                                           2MOD2820
      GO TO (210,300), IRET                                              2MOD2830
C                                                                        2MOD2840
C     SAVE THIS ITERATION'S DESIGN                                       2MOD2850
```

```
C                                                                       2MOD2860
210   GMXSTR=GMAX                                                       2MOD2870
220   FLAG=.FALSE.                                                      2MOD2880
      IF (GMAX.GT.0.0) FLAG=.TRUE.                                      2MOD2890
      VSTR=VQ                                                           2MOD2900
      KS=1                                                              2MOD2910
      DO 230 J=1,NDIFP                                                  2MOD2920
      L=0                                                               2MOD2930
      DO 230 I=1,NRED                                                   2MOD2940
      MGP(I,J)=MGQ(I,J)                                                 2MOD2950
      DP(I,J)=DPQ(I,J)                                                  2MOD2960
      DG(I,J)=DGQ(I,J)                                                  2MOD2970
      FACEP(I,J)=FACEQ(I,J)                                             2MOD2980
      NP(I,J)=INT(DP(I,J)*PD(I)+.5)                                     2MOD2990
      NG(I,J)=INT(DG(I,J)*PD(I)+.5)                                     2MOD3000
      GEOMI(I,J)=GI(I,J)                                                2MOD3010
      GEOMJP(I,J)=GJP(I,J)                                              2MOD3020
      GEOMJG(I,J)=GJG(I,J)                                              2MOD3030
      L=L+1                                                             2MOD3040
      RPMP(L,J)=SPDP(I,J)                                               2MOD3050
      PWRP(L,J)=HPP(I,J)                                                2MOD3060
      L=L+1                                                             2MOD3070
      RPMP(L,J)=SPDG(I,J)                                               2MOD3080
      PWRP(L,J)=HPG(I,J)                                                2MOD3090
230   CONTINUE                                                          2MOD3100
      IF (IRET.EQ.2) GO TO 280                                          2MOD3110
C                                                                       2MOD3120
C     PERFORM LOCAL RANDOM SEARCHES NEAR INITIAL/MOST RECENT DESIGN     2MOD3130
C                                                                       2MOD3140
      IRET=2                                                            2MOD3150
240   M=M+1                                                             2MOD3160
      IF (M.LT.MM) GO TO 250                                            2MOD3170
      ALPHA=BB*ALPHA                                                    2MOD3180
      IF (ALPHA.LT.1.E-04) GO TO 340                                    2MOD3190
      M=0                                                               2MOD3200
250   SMAX=-1.E+10                                                      2MOD3210
```

```
      IS=0                                                              2MOD3220
      DO 260 JJ=1,NDVP                                                  2MOD3230
      DO 260 II=1,3                                                     2MOD3240
      IS=IS+1                                                           2MOD3250
      RND=RNDGEN(RND)                                                   2MOD3260
      S(IS)=(2.*RND-1.)*SCALE(II)                                       2MOD3270
  260 SMAX=AMAX1(SMAX,ABS(S(IS)))                                       2MOD3280
      DO 270 IS=1,NDVP3                                                 2MOD3290
  270 S(IS)=S(IS)/SMAX                                                  2MOD3300
      KS=0                                                              2MOD3310
  280 L=0                                                               2MOD3320
      DO 290 JJ=1,NDIFP                                                 2MOD3330
      DO 290 II=1,NRED                                                  2MOD3340
      L=L+1                                                             2MOD3350
      IF (FLAGG) S(L)=ABS(S(L))                                         2MOD3360
      DPQ(II,JJ)=DP(II,JJ)+ALPHA*S(L)                                   2MOD3370
      L=L+1                                                             2MOD3380
      IF (FLAGG) S(L)=ABS(S(L))                                         2MOD3390
      MGQ(II,JJ)=MGP(II,JJ)+ALPHA*S(L)                                  2MOD3400
      L=L+1                                                             2MOD3410
  290 FACEQ(II,JJ)=FACEP(II,JJ)+ALPHA*S(L)                              2MOD3420
      GO TO 100                                                         2MOD3430
  300 IQ=IQ+1                                                           2MOD3440
      IF (IQ.GT.IQMAX) GO TO 340                                        2MOD3450
      IF (GMAX.GT.0.0) GO TO 330                                        2MOD3460
      IK=IK+1                                                           2MOD3470
      IF (IK.EQ.1) APLHA=1.0                                            2MOD3480
      IF (VQ.LT.VSTR) GO TO 220                                         2MOD3490
  310 IF (KS.EQ.1) GO TO 240                                            2MOD3500
      DO 320 IS=1,NDVP3                                                 2MOD3510
  320 S(IS)=-S(IS)                                                      2MOD3520
      KS=1                                                              2MOD3530
      GO TO 280                                                         2MOD3540
  330 IF (GMAX.GT.GMXSTR) GO TO 310                                     2MOD3550
      GMXSTR=GMAX                                                       2MOD3560
      GO TO 220                                                         2MOD3570
```

```
C                                                                       2MOD3580
C     COMPUTE ACTUAL OVERALL GEAR RATIOS AND SPEEDS TO BE USED          2MOD3590
C                                                                       2MOD3600
340   DO 350 J=1,NDIPP                                                  2MOD3610
      MGOP(J)=1.                                                        2MOD3620
      RPM1=RPMIN(J)                                                     2MOD3630
      L=0                                                               2MOD3640
      DO 350 I=1,NRED                                                   2MOD3650
      MGOP(J)=MGOP(J)*MGP(I,J)                                          2MOD3660
      L=L+1                                                             2MOD3670
      RPMP(L,J)=RPM1                                                    2MOD3680
      L=L+1                                                             2MOD3690
      RPMP(L,J)=RPM1/MGP(I,J)                                           2MOD3700
      RPM1=RPMP(L,J)                                                    2MOD3710
350   CONTINUE                                                          2MOD3720
C                                                                       2MOD3730
C     END OF DESIGN ITERATIONS                                          2MOD3740
C                                                                       2MOD3750
      IF (FLAG) GO TO 360                                               2MOD3760
      RETURN                                                            2MOD3770
C                                                                       2MOD3780
C     ERROR CONDITION HANDLING                                          2MOD3790
C                                                                       2MOD3800
360   WRITE (6,430)                                                     2MOD3810
      RETURN                                                            2MOD3820
370   GO TO (380,390,400,410,420,420), L                                2MOD3830
380   WRITE (6,450) MGO                                                 2MOD3840
      WRITE (6,500)                                                     2MOD3850
      STOP                                                              2MOD3860
390   WRITE (6,460) MGO                                                 2MOD3870
      WRITE (6,500)                                                     2MOD3880
      STOP                                                              2MOD3890
400   WRITE (6,470) MGO                                                 2MOD3900
      WRITE (6,500)                                                     2MOD3910
      STOP                                                              2MOD3920
410   WRITE (6,480) MGO                                                 2MOD3930
```

```
      WRITE (6,500)
      STOP
420   WRITE (6,490) MGO
      WRITE (6,500)
      STOP
C
C     FORMAT STATEMENTS
C
C
430   FORMAT (//,4X,23H******  WARNING  ******,/,4X,54HSIZE AND/OR ALLOW
     1ABLE POWER CONSTRAINTS WERE VIOLATED.,/,4X,32HTHIS DESIGN MAY NOT
     2BE FEASIBLE.,/,4X,34H******  PROGRAM CONTINUING  ******,//)
440   FORMAT (//,2X,49H** ENTER SEED FOR RANDOM NUMBER GENERATOR (X.XX):
     1)
450   FORMAT (//,4X,F7.3,48H IS NOT IN THE REQUIRED RANGE OF 1.0 TO 10.0
     1 FOR,/,4X,47HSINGLE REDUCTION GEARS WITH SINGLE POWER PATHS.)
460   FORMAT (//,4X,F7.3,48H IS NOT IN THE REQUIRED RANGE OF 2.2 TO 10.0
     1 FOR,/,4X,45HSINGLE REDUCTION GEARS WITH DUAL POWER PATHS.)
470   FORMAT (//,4X,F7.3,48H IS NOT IN THE REQUIRED RANGE OF 2.0 TO 20.0
     1 FOR,/,4X,47HDOUBLE REDUCTION GEARS WITH SINGLE POWER PATHS.)
480   FORMAT (//,4X,F7.3,48H IS NOT IN THE REQUIRED RANGE OF 2.9 TO 48.4
     1 FOR,/,4X,45HDOUBLE REDUCTION GEARS WITH DUAL POWER PATHS.)
490   FORMAT (//,4X,F7.3,45H IS TOO SMALL FOR AN OVERALL RATIO FOR TRIPL
     1E,/,4X,16HREDUCTION GEARS.)
500   FORMAT (///,5X,63H*****  RUN ABORTED BY PROGRAM -- ARRANGEMENT NOT
     1 ALLOWED  *****)
      END
C***********************************************************************
C   *     *     *     *     *     *     *     *     *     *     *     *
C***********************************************************************
      SUBROUTINE PRLRES
C
C     CODED BY:  LT J.L. PAQUETTE, USN          JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO COMPUTE ALL OUTPUT PARAMETERS FOR PARALLEL
```

```
C     AXIS GEAR SETS
C
C     EXTERNAL SUBPROGRAM(S) REQUIRED: FUNCTION ARCSIN
C
      REAL MGOP,MGP,MFP,KFCTRP
      COMMON /AGMAB/ SFB(2,2),AKV,AKS,AKM,AKO(2),SAT(6),AKL(2),AKR(6),AK
     1T
      COMMON /AGMAH/ SFH(2,2),CV(3),CS,CM(2),CF,CO(2),SAC(6),CP,CL(2),CH
     1,CT,CR(6)
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(3
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX
      COMMON /DESPRL/ PWRFAC(2,3),MGOP(2),MGP(3,2),RPMP(6,2),PWRP(6,2),D
     1P(3,2),DG(3,2),FACEP(3,2),GEOMI(3,2),GEOMJP(3,2),GEOMJG(3,2),NP(3,
     22),NG(3,2)
      COMMON /RESPRL/ PLVP(3,2),FBYDP(3,2),CDP(3,2),WTP(6,2),TLPIP(6,2),
     1UNTLDP(6,2),MFP(3,2),KFCTRP(6,2),SIGHP(3,2),SIGBP(6,2),TORQP(6,2),
     2PDIAMP(6,2),SCDMIN,SCDMAX,SHP,WGHTP,SPCWTP,TRQOUT,MTHP(6,2),ISIZEP
     3(3)
C
C     INITIALIZE
C
      PI=4.*ATAN(1.)
      L=NPATH+(NRED-1)*2
C
C     COMPUTE ALL OUTPUT PARAMETERS
C
      SHP=PWRIN(1)+PWRIN(2)
      TRQOUT=63.*SHP/RPMOUT
      DO 10 J=1,NDIFP
      M=0
      DO 10 I=1,NRED
      M=M+1
      DEN=FACEP(I,J)*DP(I,J)*MGP(I,J)/(MGP(I,J)+1.)
      PLVP(I,J)=PI*DP(I,J)*RPMP(M,J)/12.
      FBYDP(I,J)=FACEP(I,J)/DP(I,J)
```

```
      CDP(I,J) = (DP(I,J)+DG(I,J))/2.
      MFP(I,J) =NP(I,J)*RPMP(M,J)/60.
      WTP(M,J) = 126050.*PWRP(M,J)/(RPMP(M,J)*DP(I,J))
      C1=WTP(M,J)*CO(IOPRO)/CV(I)
      C2=CS/(FACEP(I,J)*DP(I,J))
      C3=CM(IOPRO)*CF/GEOMI(I,J)
      SIGHP(I,J) =CP*SQRT(C1*C2*C3)
      NPTH=NPATH
      IF ((NRED.EQ.3) .AND. (I.GE.2)) NPTH=2
      C1=AKO(NPTH)/AKV
      C2=PD(I)/FACEP(I,J)
      C3=AKS*AKM
      SIG=C1*C2*C3
      SIGBP(M,J) =WTP(M,J)*SIG/GEOMJP(I,J)
      TORQP(M,J) =WTP(M,J)*DP(I,J)/2000.
      TLPIP(M,J) =WTP(M,J)/FACEP(I,J)
      UNTLDP(M,J) =TLPIP(M,J)*PND(I)
      KFCTRP(M,J) =WTP(M,J)/DEN
      MTHP(M,J) =NP(I,J)
      PDIAMP(M,J) =DP(I,J)
      M=M+1
      WTP(M,J) = 126050.*PWRP(M,J)/(RPMP(M,J)*DG(I,J))
      SIGBP(M,J) =WTP(M,J)*SIG/GEOMJG(I,J)
      TORQP(M,J) =WTP(M,J)*DG(I,J)/2000.
      TLPIP(M,J) =WTP(M,J)/FACEP(I,J)
      UNTLDP(M,J) =TLPIP(M,J)*PND(I)
      KFCTRP(M,J) =WTP(M,J)/DEN
      MTHP(M,J) =NG(I,J)
      PDIAMP(M,J) =DG(I,J)
   10 CONTINUE
      IF (NPWRIN.EQ.1) RETURN
C
C     COMPUTE SOURCE CENTERLINE DISTANCE LIMITS
C       A MINIMUM 12.0 INCH CLEARANCE IS USED BETWEEN EACH POWER
C       TRAINS' FIRST REDUCTION GEARS' PITCH DIAMETERS.
C
```

```
      GO TO (20,30,40,50,60,70), L
C *** SINGLE REDUCTION, SINGLE POWER PATH
20    SCDMIN=DP(1,1)/2.+6.
      SCDMAX=SQRT(CDP(1,1)*CDP(1,1)-SCDMIN*SCDMIN)
      RETURN
C *** SINGLE REDUCTION, DUAL POWER PATH
30    A=DP(1,1)/2.+6.
      A1=ARCSIN(A,CDP(1,1))
      ARG=DP(1,1)/CDP(1,1)
      G1=A1+ATAN(ARG)
      CSTR=SQRT(CDP(1,1)*CDP(1,1)+DP(1,1)*DP(1,1))
      SCDMIN=CSTR*SIN(G1)
      SCDMAX=CSTR*COS(G1)
      RETURN
C *** DOUBLE REDUCTION, SINGLE POWER PATH
40    SCDMIN=DG(1,1)/2.+6.
      A1=ARCSIN(SCDMIN,CDP(2,1))
      SCDMAX=CDP(1,1)+CDP(2,1)*COS(A1)
      RETURN
C *** DOUBLE REDUCTION, DUAL POWER PATH
50    A=DG(1,1)/2.+6.
      A1=ARCSIN(A,CDP(2,1))
      ARG=CDP(1,1)/CDP(2,1)
      G1=A1+ATAN(ARG)
      CSTR=SQRT(CDP(1,1)*CDP(1,1)+CDP(2,1)*CDP(2,1))
      SCDMIN=CSTR*SIN(G1)
      SCDMAX=CSTR*COS(G1)
      IF (G1.GE.ATAN(1.)) SCDMAX=SCDMIN
      RETURN
C *** TRIPLE REDUCTION, FIRST RED. HAS SINGLE POWER PATH
60    A=DP(1,1)/2.+6.
      B=DG(1,1)/2.+6.
      B1=ARCSIN(B,CDP(3,1))
      ARG=CDP(2,1)/CDP(3,1)
      G1=B1+ATAN(ARG)
      CSTR=SQRT(CDP(2,1)*CDP(2,1)+CDP(3,1)*CDP(3,1))
```

```
      A1=CSTR*SIN(G1)-CDP(1,1)                                          2MOD5380
      SCDMIN=AMAX1(A1,A)                                                2MOD5390
      SCDMAX=CDP(1,1)+CSTR*COS(G1)                                      2MOD5400
      RETURN                                                            2MOD5410
C *** TRIPLE REDUCTION, FIRST RED. HAS DUAL POWER PATH                   2MOD5420
70    A=AMAX1(DG(2,1),DP(3,1))/2.+6.                                    2MOD5430
      A1=ARCSIN(A,CDP(3,1))                                             2MOD5440
      ARG=CDP(2,1)/CDP(3,1)                                             2MOD5450
      B1=ATAN(ARG)                                                      2MOD5460
      CSTR1=SQRT(CDP(2,1)*CDP(2,1)+CDP(3,1)*CDP(3,1))                   2MOD5470
      ARG=CDP(1,1)/CSTR1                                                2MOD5480
      C1=ATAN(ARG)                                                      2MOD5490
      D1=A1+B1+C1                                                       2MOD5500
      CSTR2=SQRT(CDP(1,1)*CDP(1,1)+CSTR1*CSTR1)                         2MOD5510
      SCDMIN=CSTR2*SIN(D1)                                              2MOD5520
      SCDMAX=CSTR2*COS(D1)                                              2MOD5530
      IF (D1.GE.ATAN(1.)) SCDMAX=SCDMIN                                 2MOD5540
      RETURN                                                            2MOD5550
      END                                                               2MOD5560
C***********************************************************************2MOD5570
C     *     *     *     *     *     *     *     *     *     *     *     *2MOD5580
C***********************************************************************2MOD5590
      SUBROUTINE PRLSIZ                                                 2MOD5600
C                                                                       2MOD5610
C     CODED BY:  LT J.L. PAQUETTE, USN           JAN 1982               2MOD5620
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940          2MOD5630
C                                                                       2MOD5640
C     SUBPROGRAM TO PROVIDE ESTIMATES ON WEIGHT (LBS) AND DIMENSIONS    2MOD5650
C     (IN) OF PARALLEL AXIS MARINE PROPULSION REDUCTION GEARS           2MOD5660
C        ALL RELATIONS ARE EMPIRICAL AND BASED ON ONLY A LIMITED        2MOD5670
C        NUMBER OF ACTUAL DESIGNS.  OVERALL WEIGHT, NEGLECTING THE      2MOD5680
C        WEIGHT OF AUXILIARY EQUIPMENT, IS BASED ON THE SUM OF ALL      2MOD5690
C        GEAR BLANK VOLUMNS (F*D*D).  OVERALL DIMENSIONS ARE BASED      2MOD5700
C        ON BULL GEAR DIAMETER AND SUM OF EACH REDUCTION STAGE'S        2MOD5710
C        FACEWIDTH.                                                     2MOD5720
C                                                                       2MOD5730
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      REAL MGOP,MGP                                                     2MOD5740
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),2MOD5750
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(32MOD5760
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX              2MOD5770
      COMMON /DESPRL/ PWRFAC(2,3),MGOP(2),MGP(3,2),RPMP(6,2),PWRP(6,2),D2MOD5780
     1P(3,2),DG(3,2),FACEP(3,2),GEOMI(3,2),GEOMJP(3,2),GEOMJG(3,2),NP(3,2MOD5790
     22),NG(3,2)                                                        2MOD5800
      COMMON /RESPRI/ PLVP(3,2),FBYDP(3,2),CDP(3,2),WTP(6,2),TLPIP(6,2),2MOD5810
     1UNTLDP(6,2),M[illegible]P(3,2),KFCTRP(6,2),SIGHP(3,2),SIGBP(6,2),TORQP(6,2),2MOD5820
     2PDIAMP(6,2),SCDMIN,SCDMAX,SHP,WGHTP,SPCWTP,TRQOUT,MTHP(6,2),ISIZEP2MOD5830
     3(3)                                                               2MOD5840
C                                                                       2MOD5850
C     INITIALIZATION                                                    2MOD5860
C                                                                       2MOD5870
      D2F=0.0                                                           2MOD5880
      SF=0.0                                                            2MOD5890
      FNP=FLOAT(NPATH)                                                  2MOD5900
C                                                                       2MOD5910
C     COMPUTE WEIGHT ESTIMATE                                           2MOD5920
C                                                                       2MOD5930
      GO TO (10,30,50), NRED                                            2MOD5940
   10 DP1=1.                                                            2MOD5950
      IF (NPATH.EQ.2) DP1=3.                                            2MOD5960
      DO 20 J=1,NPWRIN                                                  2MOD5970
   20 D2F=D2F+DP1*DP(1,J)*DP(1,J)*FACEP(1,J)                            2MOD5980
      D2F=D2F+DG(1,1)*DG(1,1)*FACEP(1,1)                                2MOD5990
      GO TO 70                                                          2MOD6000
   30 DO 40 J=1,NPWRIN                                                  2MOD6010
      D2F1=DP(1,J)*DP(1,J)*FACEP(1,J)                                   2MOD6020
      D2F2=FNP*DG(1,J)*DG(1,J)*FACEP(1,J)                               2MOD6030
      D2F3=FNP*DP(2,J)*DP(2,J)*FACEP(2,J)                               2MOD6040
   40 D2F=D2F+D2F1+D2F2+D2F3                                            2MOD6050
      D2F=D2F+DG(2,1)*DG(2,1)*FACEP(2,1)                                2MOD6060
      GO TO 70                                                          2MOD6070
   50 DO 60 J=1,NPWRIN                                                  2MOD6080
      D2F1=DP(1,J)*DP(1,J)*FACEP(1,J)                                   2MOD6090
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      D2F2=FNP*DG(1,J)*DG(1,J)*FACEP(1,J)                               2MOD6100
      D2F3=2.*DP(2,J)*DP(2,J)*FACEP(2,J)                                2MOD6110
      D2F4=4.*DG(2,J)*DG(2,J)*FACEP(2,J)                                2MOD6120
      D2F5=4.*DP(3,J)*DP(3,J)*FACEP(3,J)                                2MOD6130
60    D2F=D2F+D2F1+D2F2+D2F3+D2F4+D2F5                                  2MOD6140
      D2F=D2F+DG(3,1)*DG(3,1)*FACEP(3,1)                                2MOD6150
70    WGHTP=1196.*(D2F)**0.34                                           2MOD6160
      IP=INT(ALOG10(WGHTP))-2                                           2MOD6170
      WGHTP=AINT(WGHTP/(10.**IP))*(10**IP)                              2MOD6180
      SPCWTP=WGHTP/SHP                                                  2MOD6190
C                                                                       2MOD6200
C     DIMENSIONS ESTIMATE                                               2MOD6210
C                                                                       2MOD6220
      DO 80 I=1,NRED                                                    2MOD6230
      IF (NPWRIN.EQ.1) SF=SF+FACEP(I,1)                                 2MOD6240
      IF (NPWRIN.EQ.2) SF=SF+AMAX1(FACEP(I,1),FACEP(I,2))               2MOD6250
80    CONTINUE                                                          2MOD6260
      ISIZEP(1)=INT(2.26*SF+.5)                                         2MOD6270
      ISIZEP(2)=INT(1.28*DG(NRED,1)+.5)                                 2MOD6280
      WC=1.20                                                           2MOD6290
      IF (NPWRIN.EQ.2) WC=1.37                                          2MOD6300
      ISIZEP(3)=INT(WC*DG(NRED,1)+.5)                                   2MOD6310
      RETURN                                                            2MOD6320
      END                                                               2MOD6330
C***********************************************************************2MOD6340
C    *    *    *    *    *    *    *    *    *    *    *    *    *    *  2MOD6350
C***********************************************************************2MOD6360
      SUBROUTINE PRLOUT                                                 2MOD6370
C                                                                       2MOD6380
C     CODED BY:  LT J.L. PAQUETTE, USN          JAN 1982                2MOD6390
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940          2MOD6400
C                                                                       2MOD6410
C     SUBPROGRAM TO PRESENT ALL RESULTS FROM THE DESIGN/ANALYSIS        2MOD6420
C     FOR PARALLEL AXIS GEARS                                           2MOD6430
C                                                                       2MOD6440
      REAL MGOP,MGP,MFP,KFCTRP                                          2MOD6450
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```
      DIMENSION KHARD(6,2),MHARD(12)                                    2MOD6460
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),2MOD6470
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(32MOD6480
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX              2MOD6490
      COMMON /DESPRL/ PWRFAC(2,3),MGOP(2),MGP(3,2),RPMP(6,2),PWRP(6,2),D2MOD6500
     1P(3,2),DG(3,2),FACEP(3,2),GEOMI(3,2),GEOMJP(3,2),GEOMJG(3,2),NP(3,2MOD6510
     22),NG(3,2)                                                        2MOD6520
      COMMON /RESPRL/ PLVP(3,2),FBYDP(3,2),CDP(3,2),WTP(6,2),TLPIP(6,2),2MOD6530
     1UNTLDP(6,2),MFP(3,2),KFCTRP(6,2),SIGHP(3,2),SIGBP(6,2),TORQP(6,2),2MOD6540
     2PDIAMP(6,2),SCDMIN,SCDMAX,SHP,WGHTP,SPCWTP,TRQOUT,MTHP(6,2),ISIZEP2MOD6550
     3(3)                                                               2MOD6560
C                                                                       2MOD6570
C     INITIALIZATION                                                    2MOD6580
C                                                                       2MOD6590
      DATA KHARD/160,200,240,300,360,400,200,240,300,360,400,640/,M/0/  2MOD6600
      NRED2=2*NRED                                                      2MOD6610
      NRED4=4*NRED                                                      2MOD6620
      DO 10 II=1,NRED                                                   2MOD6630
      DO 10 JJ=1,2                                                      2MOD6640
      M=M+1                                                             2MOD6650
      I=IHARD(II,JJ)                                                    2MOD6660
      MHARD(M)=KHARD(I,1)                                               2MOD6670
      M=M+1                                                             2MOD6680
10    MHARD(M)=KHARD(I,2)                                               2MOD6690
C                                                                       2MOD6700
C     PRINT OUTPUT                                                      2MOD6710
C                                                                       2MOD6720
      DO 20 J=1,NDIFP                                                   2MOD6730
      WRITE (6,30)                                                      2MOD6740
      IF ((NPWRIN.EQ.2).AND.(NDIFP.EQ.1)) WRITE (6,70)                  2MOD6750
      IF (IPWRSR(J).EQ.1) WRITE (6,40) J                                2MOD6760
      IF (IPWRSR(J).EQ.2) WRITE (6,50) J                                2MOD6770
      WRITE (6,60) PWRIN(J),RPMIN(J)                                    2MOD6780
      WRITE (6,80) NPWRIN,NPATH,NRED                                    2MOD6790
      WRITE (6,90) SHP,RPMOUT,MGOP(J),TRQOUT                            2MOD6800
      IF (NPWRIN.EQ.2) WRITE (6,100) SCDMIN,SCDMAX                      2MOD6810
```

```
      WRITE (6,110) WGHTP,SPCWTP,(ISIZEP(I),I=1,3)                   2MOD6820
      IF (NRED.EQ.1) WRITE (6,120)                                    2MOD6830
      IF (NRED.EQ.2) WRITE (6,130)                                    2MOD6840
      IF (NRED.EQ.3) WRITE (6,140)                                    2MOD6850
      WRITE (6,150) (PWRP(I,J),I=1,NRED2)                             2MOD6860
      WRITE (6,160) (RPMP(I,J),I=1,NRED2)                             2MOD6870
      WRITE (6,170) (MTHP(I,J),I=1,NRED2)                             2MOD6880
      WRITE (6,180) (PND(I),I=1,NRED)                                 2MOD6890
      WRITE (6,190) (PD(I),I=1,NRED)                                  2MOD6900
      WRITE (6,200) (DPHIN(I),I=1,NRED)                               2MOD6910
      WRITE (6,210) (DPHI(I),I=1,NRED)                                2MOD6920
      WRITE (6,220) (DHELIX(I),I=1,NRED)                              2MOD6930
      WRITE (6,230) (MGP(I,J),I=1,NRED)                               2MOD6940
      WRITE (6,240) (PDIAMP(I,J),I=1,NRED2)                           2MOD6950
      WRITE (6,250) (FACEP(I,J),I=1,NRED)                             2MOD6960
      WRITE (6,260) (FBYDP(I,J),I=1,NRED)                             2MOD6970
      WRITE (6,270) (CDP(I,J),I=1,NRED)                               2MOD6980
      WRITE (6,280) (PLVP(I,J),I=1,NRED)                              2MOD6990
      WRITE (6,290) (WTP(I,J),I=1,NRED2)                              2MOD7000
      WRITE (6,300) (TLPIP(I,J),I=1,NRED2)                            2MOD7010
      WRITE (6,310) (UNTLDP(I,J),I=1,NRED2)                           2MOD7020
      WRITE (6,320) (MFP(I,J),I=1,NRED)                               2MOD7030
      WRITE (6,330) (KFCTRP(I,J),I=1,NRED2)                           2MOD7040
      WRITE (6,340) (SIGHP(I,J),I=1,NRED)                             2MOD7050
      WRITE (6,350) (SIGBP(I,J),I=1,NRED2)                            2MOD7060
      WRITE (6,360) (TORQP(I,J),I=1,NRED2)                            2MOD7070
      WRITE (6,370) (MHARD(I),I=1,NRED4)                              2MOD7080
20    CONTINUE                                                        2MOD7090
      WRITE (6,30)                                                    2MOD7100
      RETURN                                                          2MOD7110
C                                                                     2MOD7120
C     FORMAT STATEMENTS                                               2MOD7130
C                                                                     2MOD7140
C                                                                     2MOD7150
30    FORMAT (/,1X,72(1H*),/)                                         2MOD7160
40    FORMAT (2X,12HPOWER SOURCE,I2,19H:  TURBINE OR MOTOR)           2MOD7170
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50    FORMAT (2X,12HPOWER SOURCE,I2,43H:  MULTICYLINDER INTERNAL COMBUST2MOD7180
     1ION ENGINE)                                                       2MOD7190
60    FORMAT (6X,18HINPUT POWER (HP): ,F7.0,4X,19HINPUT SPEED (RPM): ,F62MOD7200
     1.0,/)                                                             2MOD7210
70    FORMAT (2X,57HNOTE: POWER SOURCES 1 AND 2 ARE IDENTICAL, THEREFORE2MOD7220
     1, THE,/,2X,56HTABULATED INFORMATION BELOW APPLIES TO EACH POWER TR2MOD7230
     2AIN.,/)                                                           2MOD7240
80    FORMAT (2X,27HARRANGEMENT: PARALLEL AXIS,,I2,10H INPUT(S),,I2,15H 2MOD7250
     1POWER PATH(S),,I2,13H REDUCTION(S))                               2MOD7260
90    FORMAT (6X,19HOUTPUT POWER (HP): ,F8.1,3X,20HOUTPUT SPEED (RPM): ,2MOD7270
     1F5.0,/,6X,7HRATIO: ,F6.3,16X,25HOUTPUT TORQUE (K IN-LB): ,F8.1,/) 2MOD7280
100   FORMAT (2X,34HSOURCE CENTER DISTANCE (IN): MIN= ,F5.1,3X,5HMAX= ,F2MOD7290
     15.1,/)                                                            2MOD7300
110   FORMAT (2X,46HSIZING ESTIMATES FOR THE ENTIRE REDUCTION SET:,/,6X,2MOD7310
     113HWEIGHT (LB): ,F7.0,5X,25HSPECIFIC WEIGHT (LB/HP): ,F6.2,/,6X,132MOD7320
     2HLENGTH (IN): ,I3,3X,12HWIDTH (IN): ,I3,3X,13HHEIGHT (IN): ,I3,//)2MOD7330
120   FORMAT (27X,11HREDUCTION 1,/,24X,17H|PINION | GEAR  |,/,24X,1H|,152MOD7340
     1(1H-),1H|)                                                        2MOD7350
130   FORMAT (27X,11HREDUCTION 1,5X,11HREDUCTION 2,/,24X,33H|PINION | GE2MOD7360
     1AR  |PINION | GEAR  |,/,24X,1H|,15(1H-),1H|,15(1H-),1H|)          2MOD7370
140   FORMAT (27X,11HREDUCTION 1,5X,11HREDUCTION 2,5X,11HREDUCTION 3,/,22MOD7380
     14X,49H|PINION | GEAR  |PINION | GEAR  |PINION | GEAR  |,/,24X,1H|,2MOD7390
     215(1H-),1H|,15(1H-),1H|,15(1H-),1H|)                              2MOD7400
150   FORMAT (1X,24HPOWER SPLIT          HP |,6(F7.0,1H|))              2MOD7410
160   FORMAT (1X,24HSPEED               RPM |,3(F6.0,1X,1H|,1X,F6.0,1H|))2MOD7420
170   FORMAT (1X,24HNUMBER OF TEETH         |,6(2X,I4,1X,1H|))          2MOD7430
180   FORMAT (1X,24HNORMAL DIAMETRAL PITCH |,3(5X,F6.3,4X,1H|))         2MOD7440
190   FORMAT (1X,24HTRANS. DIAMETRAL PITCH |,3(5X,F6.3,4X,1H|))         2MOD7450
200   FORMAT (1X,24HNORMAL PRESSURE ANGLE  |,3(6X,F4.1,5X,1H|))         2MOD7460
210   FORMAT (1X,24HTRANS. PRESSURE ANGLE  |,3(6X,F4.1,5X,1H|))         2MOD7470
220   FORMAT (1X,24HHELIX ANGLE             |,3(6X,F4.1,5X,1H|))        2MOD7480
230   FORMAT (1X,24HGEAR RATIO              |,3(5X,F6.3,4X,1H|))        2MOD7490
240   FORMAT (1X,24HPITCH DIAMETER       IN |,3(F6.2,1X,1H|,1X,F6.2,1H|))2MOD7500
250   FORMAT (1X,24HEFFECTIVE FACEWIDTH IN |,3(5X,F5.2,5X,1H|))         2MOD7510
260   FORMAT (1X,24HF/DP                    |,3(6X,F4.2,5X,1H|))        2MOD7520
270   FORMAT (1X,24HCENTER DISTANCE      IN |,3(5X,F6.2,4X,1H|))        2MOD7530
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280   FORMAT (1X,24HPITCHLINE VELOCITY FPM |,3(5X,F6.0,4X,1H|))           2MOD7540
290   FORMAT (1X,24HTANGENTIAL LOAD      LB |,3(F6.0,1X,1H|,1X,F6.0,1H|))2MOD7550
300   FORMAT (1X,24HTOOTH LOAD/IN     LB/IN |,6(1X,F5.0,1X,1H|))          2MOD7560
310   FORMAT (1X,24HUNIT LOAD           PSI |,3(F6.0,1X,1H|,1X,F6.0,1H|))2MOD7570
320   FORMAT (1X,24HMESH FREQRENCY       HZ |,3(5X,F6.0,4X,1H|))          2MOD7580
330   FORMAT (1X,24HK FACTOR (COMPUTED)     |,6(1X,F5.0,1X,1H|))          2MOD7590
340   FORMAT (1X,24HCONTACT STRESS      PSI |,3(4X,F7.0,4X,1H|))          2MOD7600
350   FORMAT (1X,24HBENDING STRESS      PSI |,6(F7.0,1H|))                2MOD7610
360   FORMAT (1X,24HTORQUE          K IN-LB |,6(F7.1,1H|))                2MOD7620
370   FORMAT (1X,24HHARDNESS RANGE      BHN |,6(I3,1H-,I3,1H|))           2MOD7630
      END                                                                 2MOD7640
```

Module Three

```
      SUBROUTINE EPCANL
C
C     CODED BY:  LT J.L. PAQUETTE, USN           JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO PERFORM AN ANALYSIS OF A GIVEN EPICYCLIC GEAR SET
C
C     EXTERNAL SUBPROGRAM(S) REQUIRED: SUBROUTINE GFI, SUBROUTINE GFJ,
C     FUNCTION AGMAE1, FUNCTION ARCCOS, FUNCTION ARCSIN, FUNCTION FALFA,
C     FUNCTION RTFNDR, FUNCTION SHRLD, FUNCTION THICK
C
      REAL MGOE,MGE,MG1
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(3
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX
      COMMON /DESEPC/ MGOE,MGE(3),RPMI(3),RPMPL(3),RPMO(3),PWRE(3),DS(3)
     1,DPLN(3),DR(3),FACEE(3),GI(3),GJS(3),GJPL(3),NS(3),NPLN(3),NR(3)
C
C     ENTER REQUIRED INFORMATION: TOOTH NUMBERS, DIAMETERS, FACEWIDTHS
C
      DO 10 I=1,NRED
      WRITE (6,30) I
      WRITE (6,40)
      READ (5,*) DS(I),DPLN(I),DR(I)
      WRITE (6,50)
      READ (5,*) FACEE(I)
10    CONTINUE
C
C     COMPUTE RATIOS, SPEED AND POWER SPLITS, AND GEOMETRY FACTORS
C
      RPM1=RPMIN(1)
      MGOE=RPMIN(1)/RPMOUT
      DO 20 I=1,NRED
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```
      NS(I)=INT(PD(I)*DS(I)+.5)
      NPLN(I)=INT(PD(I)*DPLN(I)+.5)
      NR(I)=INT(PD(I)*DR(I)+.5)
      MGE(I)=DR(I)/DS(I)
      IF (IEPIC(I).EQ.1) MGE(I)=MGE(I)+1.
      RPMI(I)=RPM1
      RPMO(I)=RPM1/MGE(I)
      RPM1=RPMO(I)
      RPMPL(I)=RPM1*DR(I)/DPLN(I)
      PWRE(I)=PWRIN(1)/NPLNT(I)
      MG1=DPLN(I)/DS(I)
      CALL GFI  (GI(I),I,MG1,DS(I),DPLN(I),0)
      CALL GFJ  (GJS(I),I,DS(I),DPLN(I),1,0)
      CALL GFJ  (GJPL(I),I,DS(I),DPLN(I),2,0)
20    CONTINUE
      RETURN
C
C     FORMAT STATEMENTS
C
C
30    FORMAT (//,4X,54HTHE INFORMATION REQUESTED BELOW IS FOR REDUCTION
     1STAGE,I2,1H.)
40    FORMAT (/,1X,61H** ENTER DIAMETERS, IN INCHES, OF SUN, PLANET, AND
     1 RING GEARS,/,1X,18H   (DS, DPLN, DR):)
50    FORMAT (/,1X,39H** ENTER FACEWIDTH OF GEARS, IN INCHES:)
      END
C*********************************************************************
C     *     *     *     *     *     *     *     *     *     *     *     *     *
C*********************************************************************
      SUBROUTINE EPCDES
C
C     CODED BY:  LT J.L. PAQUETTE, USN          JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO PERFORM DESIGN CALCULATIONS FOR EPICYCLIC
C     REDUCTION GEARS USING A BASIC RANDOM SEARCH OPTIMIZATION
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C     TECHNIQUE TO FIND THE GEAR DIMENSIONS SUBJECT TO SIZE AND
C     POWER CONSTRAINTS.
C
C     THE VARIABLES ENDING IN A 'Q' ARE LOCAL TO THIS SUBROUTINE AND
C     REPRESENT THE VALUES OF THE REAL VARIABLE DURING A SPECIFIC
C     ITERATION.  IF ALL CONSTRAINTS ARE MET (DESIGN IS FEASIBLE) THE
C     GLOBAL VARIABLES WILL TAKE ON THESE VALUES.
C
C     EXTERNAL SUBPROGRAM(S) REQUIRED: FUNCTION POWERB, FUNCTION POWERH,
C     SUBROUTINE GFI, SUBROUTINE GFJ, FUNCTION AGMAE1, FUNCTION ARCCOS,
C     FUNCTION ARCSIN, FUNCTION RTFNDR, FUNCTION FALFA, FUNCTION SHRLD,
C     FUNCTION THICK, FUNCTION RNDGEN
C
      REAL MGOE,MGE,MG1,MGQ,KK
      LOGICAL FLAG,FLAGG
      DIMENSION G(9,3),SPD(3),HP(3,2),SCALE(3)
      DIMENSION DSQ(3),DRQ(3),DPLNQ(3),MGQ(3),FACEQ(3)
      DIMENSION GFIS(3),GFJS(3),GFJP(3),S(10),NSQ(3),NRQ(3),NPLNQ(3)
      COMMON /AGMAB/ SFB(2,2),AKV,AKS,AKM,AKO(2),SAT(6),AKL(2),AKR(6),AK
     1T
      COMMON /AGMAH/ SFH(2,2),CV(3),CS,CM(2),CF,CO(2),SAC(6),CP,CL(2),CH
     1,CT,CR(6)
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(3
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX
      COMMON /DESEPC/ MGOE,MGE(3),RPMI(3),RPMPL(3),RPMO(3),PWRE(3),DS(3)
     1,DPLN(3),DR(3),FACEE(3),GI(3),GJS(3),GJPL(3),NS(3),NPLN(3),NR(3)
C
C     INITIALIZATION
C
      DATA IQMAX/7500/,IQ/0/,M/0/,BB/.5/,FDP/1./,ALPHA/1./
      DATA SCALE/30.,5.,30./,FLAG/.FALSE./,IK/0/
      FOURPI=16.*ATAN(1.)
      E3=1./3.
      E=1./FLOAT(NRED)
      NRED3=3*NRED
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      NDV=NRED3                                                         3MOD1060
      MM=10*NDV                                                         3MOD1070
      IF (NHELX.EQ.2)  FDP=2.25                                         3MOD1080
      IF (NHELX.EQ.2)  SCALE(3)=75.                                     3MOD1090
      IRET=1                                                            3MOD1100
      WRITE (6,340)                                                     3MOD1110
      READ (5,*) RND                                                    3MOD1120
      RND=RNDGEN(RND)                                                   3MOD1130
C                                                                       3MOD1140
C     COMPUTE THE OVERALL GEAR RATIO, INITIAL STAGE GEAR RATIOS,        3MOD1150
C     AND POWER AND SPEED SPLITS                                        3MOD1160
C                                                                       3MOD1170
      MGOE=RPMIN(1)/RPMOUT                                              3MOD1180
      MGMAX=8.**NRED                                                    3MOD1190
      IF (MGOE.GT.MGMAX) GO TO 320                                      3MOD1200
10    RPM1=RPMIN(1)                                                     3MOD1210
      DO 20 I=1,NRED                                                    3MOD1220
      MGQ(I)=MGOE**E                                                    3MOD1230
      SPD(I)=RPM1                                                       3MOD1240
      RPM1=SPD(I)/MGQ(I)                                                3MOD1250
      HP(I,1)=PWRIN(1)                                                  3MOD1260
      HP(I,2)=HP(I,1)/NPLNT(I)                                          3MOD1270
20    CONTINUE                                                          3MOD1280
C                                                                       3MOD1290
C     ESTIMATE INITIAL DESIGN AS START POINT FOR OPTIMIZATION           3MOD1300
C                                                                       3MOD1310
      DO 30 I=1,NRED                                                    3MOD1320
      MG1=(1.+RND)*1.5                                                  3MOD1330
      IH=IHARD(I,1)                                                     3MOD1340
      BRAC=SAC(IH)*1.E-04/CR(IH)                                        3MOD1350
      KK=BRAC*BRAC*3.36/(CO(IOPRO)*CM(IOPRO))                           3MOD1360
      ANUM=126050.*HP(I,1)*(MG1+1.)                                     3MOD1370
      DEN=SPD(I)*FDP*KK*MG1                                             3MOD1380
      DSQ(I)=(ANUM/DEN)**E3                                             3MOD1390
      FACEQ(I)=FDP*DSQ(I)                                               3MOD1400
30    CONTINUE                                                          3MOD1410
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C
C      COMPUTE VALUES OF DEPENDENT VARIABLES
C
40     GO TO (50,60,70), NRED
C ***  SINGLE REDUCTION
50     MGQ(1)=MGOE
       GO TO 80
C ***  DOUBLE REDUCTION
60     MGQ(1)=MGOE/MGQ(2)
       GO TO 80
C ***  TRIPLE REDUCTION
70     MGQ(1)=MGOE/(MGQ(2)*MGQ(3))
80     RPM1=RPMIN(1)
       DO 130 I=1,NRED
       PNSQ=PD(I)*DSQ(I)
       NSQ(I)=INT(PNSQ+.5)
       IEP=IEPIC(I)
       GO TO (90,100), IEP
C ***  PLANETARY GEAR CONFIGURATION
90     PNRQ=FLOAT(NSQ(I))*(MGQ(I)-1.)
       NRQ(I)=INT(PNRQ+.5)
       PKCON=FLOAT(NRQ(I))*MGQ(I)/(FLOAT(NPLNT(I))*(MGQ(I)-1.))
       KCON=INT(PKCON+.5)
       GO TO 110
C ***  STAR GEAR ARRANGEMENT
100    PNRQ=FLOAT(NSQ(I))*MGQ(I)
       NRQ(I)=INT(PNRQ+.5)
       PKCON=FLOAT(NRQ(I))*(MGQ(I)+1.)/(MGQ(I)*FLOAT(NPLNT(I)))
       KCON=INT(PKCON+.5)
110    NRQ(I)=KCON*NPLNT(I)-NSQ(I)
       PLNTQ=(FLOAT(NRQ(I))-FLOAT(NSQ(I)))/2.
       IF (PLNTQ.EQ.AINT(PLNTQ)) GO TO 120
       KCON=KCON+1
       GO TO 110
120    NPLNQ(I)=INT(PLNTQ)
       MGQ(I)=FLOAT(NRQ(I))/FLOAT(NSQ(I))
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      IF (IEPIC(I).EQ.1) MGQ(I)=MGQ(I)+1.                               3MOD1780
      SPD(I)=RPM1                                                       3MOD1790
      RPM1=SPD(I)/MGQ(I)                                                3MOD1800
      DPLNQ(I)=FLOAT(NPLNQ(I))/PD(I)                                    3MOD1810
      DRQ(I)=FLOAT(NRQ(I))/PD(I)                                        3MOD1820
  130 CONTINUE                                                          3MOD1830
C                                                                       3MOD1840
C     COMPUTE CONSTRAINTS AND OBJECTIVE FUNCTION                        3MOD1850
C                                                                       3MOD1860
      VQ=0.0                                                            3MOD1870
      FLAGG=.FALSE.                                                     3MOD1880
      DO 140 I=1,NRED                                                   3MOD1890
      DPLN7=.7*DPLNQ(I)                                                 3MOD1900
      CALL GFI (GFIS(I),I,MG1,DSQ(I),DPLN7,0)                           3MOD1910
      APWRH=POWERH(SPD(I),FACEQ(I),DSQ(I),I,1,GFIS(I))                  3MOD1920
      CALL GFJ (GFJS(I),I,DSQ(I),DPLN7,1,0)                             3MOD1930
      APWRBP=POWERB(SPD(I),FACEQ(I),DSQ(I),I,1,1,GFJS(I))               3MOD1940
      CALL GFJ (GFJP(I),I,DSQ(I),DPLN7,2,0)                             3MOD1950
      APWRBG=POWERB(SPD(I),FACEQ(I),DPLN7,I,1,1,GFJP(I))                3MOD1960
      FLB=FOURPI/(PD(I)*TAN(HELIX(I)))                                  3MOD1970
      IF (FDP.EQ.2.25) FLB=DSQ(I)                                       3MOD1980
      FUB=FDP*DSQ(I)                                                    3MOD1990
      G(1,I)=HP(I,1)/APWRH-1.0                                          3MOD2000
      G(2,I)=HP(I,1)/APWRBP-1.0                                         3MOD2010
      G(3,I)=HP(I,2)/APWRBG-1.0                                         3MOD2020
      IF ((G(1,I).GT.0.).OR.(G(2,I).GT.0.).OR.(G(3,I).GT.0.)) FLAGG=.TRU3MOD2030
     1E.                                                                3MOD2040
      G(4,I)=DRQ(I)/150.-1.0                                            3MOD2050
      G(5,I)=FLB/FACEQ(I)-1.0                                           3MOD2060
      G(6,I)=FACEQ(I)/FUB-1.0                                           3MOD2070
      G(7,I)=DSQ(I)/DPLNQ(I)-1.0                                        3MOD2080
      G(8,I)=MGQ(I)/8.-1.0                                              3MOD2090
      G(9,I)=2./MGQ(I)-1.0                                              3MOD2100
      VQ=VQ+FACEQ(I)*(NPLNT(I)*DPLN(I)*DPLN(I)+DSQ(I)*DSQ(I)+DRQ(I)*DRQ(3MOD2110
     1I))                                                               3MOD2120
  140 CONTINUE                                                          3MOD2130
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C                                                                       3MOD2140
C     CHECK FOR CONSTRAINT VIOLATIONS  (CONSTRAINTS VIOLATED IF AT      3MOD2150
C     LEAST ONE HAS A VALUE GREATER THAN ZERO)                          3MOD2160
C                                                                       3MOD2170
      GMAX=-1.0E+20                                                     3MOD2180
      DO 150 K=1,9                                                      3MOD2190
      DO 150 I=1,NRED                                                   3MOD2200
      GMAX=AMAX1(GMAX,G(K,I))                                           3MOD2210
150   CONTINUE                                                          3MOD2220
      GO TO (160,250), IRET                                             3MOD2230
C                                                                       3MOD2240
C     SAVE THIS ITERATION'S DESIGN                                      3MOD2250
C                                                                       3MOD2260
160   GMXSTR=GMAX                                                       3MOD2270
170   FLAG=.FALSE.                                                      3MOD2280
      IF (GMAX.GT.0.0) FLAG=.TRUE.                                      3MOD2290
      VSTR=VQ                                                           3MOD2300
      KS=1                                                              3MOD2310
      RPM1=RPMIN(1)                                                     3MOD2320
      DO 180 I=1,NRED                                                   3MOD2330
      MGE(I)=MGQ(I)                                                     3MOD2340
      DS(I)=DSQ(I)                                                      3MOD2350
      DPLN(I)=DPLNQ(I)                                                  3MOD2360
      DR(I)=DRQ(I)                                                      3MOD2370
      FACEE(I)=FACEQ(I)                                                 3MOD2380
      NS(I)=NSQ(I)                                                      3MOD2390
      NPLN(I)=NPLNQ(I)                                                  3MOD2400
      NR(I)=NRQ(I)                                                      3MOD2410
      GI(I)=GFIS(I)                                                     3MOD2420
      GJS(I)=GFJS(I)                                                    3MOD2430
      GJPL(I)=GFJP(I)                                                   3MOD2440
      RPMI(I)=RPM1                                                      3MOD2450
      RPMO(I)=RPM1/MGE(I)                                               3MOD2460
      RPM1=RPMO(I)                                                      3MOD2470
      RPMPL(I)=RPM1*DR(I)/DPLN(I)                                       3MOD2480
      PWRE(I)=HP(I,2)                                                   3MOD2490
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180   CONTINUE                                                          3MOD2500
      IF (IRET.EQ.2) GO TO 230                                          3MOD2510
C                                                                       3MOD2520
C     PERFORM LOCAL RANDOM SEARCHES NEAR INITIAL/MOST RECENT DESIGN     3MOD2530
C                                                                       3MOD2540
      IRET=2                                                            3MOD2550
190   M=M+1                                                             3MOD2560
      IF (M.LT.MM) GO TO 200                                            3MOD2570
      ALPHA=BB*ALPHA                                                    3MOD2580
      IF (ALPHA.LT.1.E-04) GO TO 290                                    3MOD2590
      M=0                                                               3MOD2600
200   SMAX=-1.E+10                                                      3MOD2610
      IS=0                                                              3MOD2620
      DO 210 JJ=1,NRED                                                  3MOD2630
      DO 210 II=1,3                                                     3MOD2640
      IS=IS+1                                                           3MOD2650
      RND=RNDGEN(RND)                                                   3MOD2660
      S(IS)=(2.*RND-1.)*SCALE(II)                                       3MOD2670
210   SMAX=AMAX1(SMAX,ABS(S(IS)))                                       3MOD2680
      DO 220 IS=1,NRED3                                                 3MOD2690
220   S(IS)=S(IS)/SMAX                                                  3MOD2700
      KS=0                                                              3MOD2710
230   L=0                                                               3MOD2720
      DO 240 II=1,NRED                                                  3MOD2730
      L=L+1                                                             3MOD2740
      IF (FLAGG) S(L)=ABS(S(L))                                         3MOD2750
      DSQ(II)=DS(II)+ALPHA*S(L)                                         3MOD2760
      L=L+1                                                             3MOD2770
C     IF(FLAGG) S(L)=ABS(S(L))                                          3MOD2780
      MGQ(II)=MGE(II)+ALPHA*S(L)                                        3MOD2790
      L=L+1                                                             3MOD2800
240   FACEQ(II)=FACEE(II)+ALPHA*S(L)                                    3MOD2810
      GO TO 40                                                          3MOD2820
250   IQ=IQ+1                                                           3MOD2830
      IF (IQ.GT.IQMAX) GO TO 290                                        3MOD2840
      IF (GMAX.GT.0.0) GO TO 280                                        3MOD2850
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      IK=IK+1
      IF (IK.EQ.1) APLHA=1.0
      IF (VQ.LT.VSTR) GO TO 170
  260 IF (KS.EQ.1) GO TO 190
      DO 270 IS=1,NRED3
  270 S(IS)=-S(IS)
      KS=1
      GO TO 230
  280 IF (GMAX.GT.GMXSTR) GO TO 260
      GMXSTR=GMAX
      GO TO 170
C
C     COMPUTE ACTUAL OVERALL GEAR RATIOS AND SPEEDS TO BE USED
C
  290 MGOE=1.
      DO 300 I=1,NRED
  300 MGOE=MGOE*MGE(I)
C
C     END OF DESIGN ITERATIONS
C
      IF (FLAG) GO TO 310
      RETURN
C
C     ERROR CONDITION HANDLING
C
  310 WRITE (6,330)
      RETURN
  320 NP1=NRED+1
      WRITE (6,350) MGOE,NRED,NP1
      NRED=NP1
      GO TO 10
C
C     FORMAT STATEMENTS
C
C
  330 FORMAT (//,4X,23H******  WARNING  ******,/,4X,54HSIZE AND/OR ALLOW
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```
      1ABLE POWER CONSTRAINTS WERE VIOLATED.,/,4X,32HTHIS DESIGN MAY NOT 3MOD3220
      2BE FEASIBLE.,/,4X,34H******  PROGRAM CONTINUING  ******,//)       3MOD3230
  340  FORMAT (//,2X,49H** ENTER SEED FOR RANDOM NUMBER GENERATOR (X.XX):3MOD3240
      1)                                                                 3MOD3250
  350  FORMAT (//,4X,28HTHE OVERALL REDUCTION RATIO,,F7.3,17H, IS TO LARG3MOD3260
      1E FOR,I2,/,4X,30HREDUCTION STAGE(S); THEREFORE,,I2,33H REDUCTION S3MOD3270
      2TAGE(S) WILL BE USED.)                                            3MOD3280
       END                                                               3MOD3290
C*********************************************************************3MOD3300
C   *     *     *     *     *     *     *     *     *     *     *     *     *     *  3MOD3310
C*********************************************************************3MOD3320
       SUBROUTINE EPCRES                                                 3MOD3330
C                                                                        3MOD3340
C      CODED BY:  LT J.L. PAQUETTE, USN            JAN 1982              3MOD3350
C                 NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940          3MOD3360
C                                                                        3MOD3370
C      SUBPROGRAM TO COMPUTE ALL OUTPUT PARAMETERS FOR EPICYCLIC GEARS   3MOD3380
C                                                                        3MOD3390
       REAL MGOE,MGE,MFE,KFCTRE,MG1                                      3MOD3400
       COMMON /AGMAB/ SFB(2,2),AKV,AKS,AKM,AKO(2),SAT(6),AKL(2),AKR(6),AK3MOD3410
      1T                                                                 3MOD3420
       COMMON /AGMAH/ SFH(2,2),CV(3),CS,CM(2),CF,CO(2),SAC(6),CP,CL(2),CH3MOD3430
      1,CT,CR(6)                                                         3MOD3440
       COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),3MOD3450
      1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(33MOD3460
      2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX              3MOD3470
       COMMON /DESEPC/ MGOE,MGE(3),RPMI(3),RPMPL(3),RPMO(3),PWRE(3),DS(3) 3MOD3480
      1,DPLN(3),DR(3),FACEE(3),GI(3),GJS(3),GJPL(3),NS(3),NPLN(3),NR(3)  3MOD3490
       COMMON /RESEPC/ PLVE(3),FBYDE(3),CDE(3),WTE(3),TLPIE(3),UNTLDE(3),3MOD3500
      1MFE(3,3),KFCTRE(3),SIGHE(3),SIGBE(3),TORQE(3,3),RPME(3,3),PDIAME(33MOD3510
      2,3),WGHTE,SPCWTE,MTHE(3,3),ISIZEE(3)                              3MOD3520
C                                                                        3MOD3530
C      INITIALIZE                                                        3MOD3540
C                                                                        3MOD3550
       PI=4.*ATAN(1.)                                                    3MOD3560
C                                                                        3MOD3570
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C     COMPUTE ALL OUTPUT PARAMETERS                                    3MOD3580
C                                                                      3MOD3590
      DO 40 I=1,NRED                                                   3MOD3600
      PLVE(I)=PI*DS(I)*RPMI(I)/12.                                     3MOD3610
      FBYDE(I)=FACEE(I)/DS(I)                                          3MOD3620
      CDE(I)=(DS(I)+DPLN(I))/2.                                        3MOD3630
      WTE(I)=126050.*PWRIN(1)/(RPMI(I)*DS(I))                          3MOD3640
      TLPIE(I)=WTE(I)/FACEE(I)                                         3MOD3650
      UNTLDE(I)=TLPIE(I)*PND(I)                                        3MOD3660
      ANPLNT=FLOAT(NPLNT(I))                                           3MOD3670
      ANR=FLOAT(NR(I))                                                 3MOD3680
      ANPLN=FLOAT(NPLN(I))                                             3MOD3690
      ANS=FLOAT(NS(I))                                                 3MOD3700
      IE=IEPIC(I)                                                      3MOD3710
      GO TO (10,20), IE                                                3MOD3720
10    ANRPNS=ANR+ANS                                                   3MOD3730
      MFE(I,1)=ANPLNT*ANR*RPMI(I)/ANRPNS                               3MOD3740
      MFE(I,2)=(ANR/ANPLN)*ANS*RPMI(I)/ANRPNS                          3MOD3750
      MFE(I,3)=ANPLNT*ANS*RPMI(I)/ANRPNS                               3MOD3760
      GO TO 30                                                         3MOD3770
20    MFE(I,1)=ANPLNT*RPMI(I)                                          3MOD3780
      MFE(I,2)=2.*ANS*RPMI(I)/ANPLN                                    3MOD3790
      MFE(I,3)=ANPLNT*ANS*RPMI(I)/ANR                                  3MOD3800
30    MG1=DPLN(I)/DS(I)                                                3MOD3810
      KFCTRE(I)=WTE(I)*(MG1+1.)/(FACEE(I)*DS(I)*MG1)                   3MOD3820
      C1=WTE(I)*CO(IOPRO)/CV(1)                                        3MOD3830
      C2=CS/(DS(I)*FACEE(I))                                           3MOD3840
      C3=CM(IOPRO)*CF/GI(I)                                            3MOD3850
      SIGHE(I)=CP*SQRT(C1*C2*C3)                                       3MOD3860
      C1=WTE(I)*AKO(2)/AKV                                             3MOD3870
      C2=PD(I)/FACEE(I)                                                3MOD3880
      C3=AKS*AKM/AMIN1(GJS(I),GJPL(I))                                 3MOD3890
      SIGBE(I)=C1*C2*C3                                                3MOD3900
      TW=WTE(I)/2000.                                                  3MOD3910
      TORQE(I,1)=TW*DS(I)                                              3MOD3920
      TORQE(I,2)=TW*DPLN(I)                                            3MOD3930
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      TORQE(I,3)=63.*PWRIN(1)/RPMO(I)
      RPME(I,1)=RPMI(I)
      RPME(I,2)=RPMPL(I)
      RPME(I,3)=RPMO(I)
      MTHE(I,1)=NS(I)
      MTHE(I,2)=NPLN(I)
      MTHE(I,3)=NR(I)
      PDIAME(I,1)=DS(I)
      PDIAME(I,2)=DPLN(I)
      PDIAME(I,3)=DR(I)
40    CONTINUE
      RETURN
      END
C***********************************************************************
C     *     *     *     *     *     *     *     *     *     *     *     *
C***********************************************************************
      SUBROUTINE EPCSIZ
C
C     CODED BY:  LT J.L. PAQUETTE, USN           JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO PROVIDE ESTIMATES ON WEIGHT (LBS) AND DIMENSIONS
C     (IN) OF EPICYCLIC MARINE PROPULSION REDUCTION GEARS
C        ALL RELATIONS ARE EMPIRICAL AND BASED ON ONLY A LIMITED
C        NUMBER OF ACTUAL DESIGNS.  OVERALL WEIGHT, NEGLECTING THE
C        WEIGHT OF AUXILIARY EQUIPMENT, IS BASED ON THE SUM OF ALL
C        GEAR BLANK VOLUMNS (F*D*D).  OVERALL DIMENSIONS ARE BASED
C        ON RING GEAR DIAMETER AND SUM OF EACH REDUCTION STAGE'S
C        FACEWIDTH.
C
      REAL MGOE,MGE,MFE,KFCTRE
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(3
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX
      COMMON /DESEPC/ MGOE,MGE(3),RPMI(3),RPMPL(3),RPMO(3),PWRE(3),DS(3)
     1,DPLN(3),DR(3),FACEE(3),GI(3),GJS(3),GJPL(3),NS(3),NPLN(3),NR(3)
```

```
      COMMON /RESEPC/ PLVE(3),FBYDE(3),CDE(3),WTE(3),TLPIE(3),UNTLDE(3),3MOD4300
     1MFE(3,3),KFCTRE(3),SIGHE(3),SIGBE(3),TORQE(3,3),RPME(3,3),PDIAME(33MOD4310
     2,3),WGHTE,SPCWTE,MTHE(3,3),ISIZEE(3)                              3MOD4320
C                                                                       3MOD4330
C     INITIALIZATION                                                    3MOD4340
C                                                                       3MOD4350
      D2F=0.0                                                           3MOD4360
      SF=0.0                                                            3MOD4370
      FNP=FLOAT(NPATH)                                                  3MOD4380
      DRMAX=-1.E-04                                                     3MOD4390
C                                                                       3MOD4400
C     COMPUTE WEIGHT ESTIMATE                                           3MOD4410
C                                                                       3MOD4420
      DO 10 I=1,NRED                                                    3MOD4430
      DRMAX=AMAX1(DRMAX,DR(I))                                          3MOD4440
      SF=SF+FACEE(I)                                                    3MOD4450
      D2F1=DS(I)*DS(I)*FACEE(I)                                         3MOD4460
      D2F2=NPLNT(I)*DPLN(I)*DPLN(I)*FACEE(I)                            3MOD4470
C *** USE 0.7 DR TO ACCOUNT FOR THE CARRIER                             3MOD4480
      D2F3=.49*DR(I)*DR(I)*FACEE(I)                                     3MOD4490
10    D2F=D2F+D2F1+D2F2+D2F3                                            3MOD4500
      WGHTE=.905*(D2F)**0.89                                            3MOD4510
      IP=INT(ALOG10(WGHTE))-2                                           3MOD4520
      WGHTE=AINT(WGHTE/(10.**IP))*(10**IP)                              3MOD4530
      SPCWTE=WGHTE/PWRIN(1)                                             3MOD4540
C                                                                       3MOD4550
C     DIMENSIONS ESTIMATE                                               3MOD4560
C                                                                       3MOD4570
      ISIZEE(1)=INT(2.85*SF+.5)                                         3MOD4580
      ISIZEE(2)=INT(1.30*DRMAX+.5)                                      3MOD4590
      ISIZEE(3)=INT(1.20*DRMAX+.5)                                      3MOD4600
      RETURN                                                            3MOD4610
      END                                                               3MOD4620
C***********************************************************************3MOD4630
C     *     *     *     *     *     *     *     *     *     *     *     * 3MOD4640
C***********************************************************************3MOD4650
```

```
      SUBROUTINE EPCOUT
C
C     CODED BY:  LT J.L. PAQUETTE, USN           JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO PRESENT ALL RESULTS FROM THE DESIGN/ANALYSIS
C     FOR EPICYCLIC GEARS
C
      REAL MGOE,MGE,MFE,KFCTRE
      DIMENSION KHARD(6,2),MHARD(4)
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(3
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX
      COMMON /DESEPC/ MGOE,MGE(3),RPMI(3),RPMPL(3),RPMO(3),PWRE(3),DS(3)
     1,DPLN(3),DR(3),FACEE(3),GI(3),GJS(3),GJPL(3),NS(3),NPLN(3),NR(3)
      COMMON /RESEPC/ PLVE(3),FBYDE(3),CDE(3),WTE(3),TLPIE(3),UNTLDE(3),
     1MFE(3,3),KFCTRE(3),SIGHE(3),SIGBE(3),TORQE(3,3),RPME(3,3),PDIAME(3
     2,3),WGHTE,SPCWTE,MTHE(3,3),ISIZEE(3)
C
C     INITIALIZATION
C
      DATA KHARD/160,200,240,300,360,400,200,240,300,360,400,640/
C
C     PRINT OUTPUT
C
      WRITE (6,30)
      IF (IPWRSR(1).EQ.1) WRITE (6,40)
      IF (IPWRSR(1).EQ.2) WRITE (6,50)
      WRITE (6,60) PWRIN(1),RPMIN(1)
      WRITE (6,70) NRED
      WRITE (6,80) PWRIN(1),RPMOUT,MGOE,TORQE(NRED,3)
      WRITE (6,90) WGHTE,SPCWTE,(ISIZEE(I),I=1,3)
      DO 20 I=1,NRED
      WRITE (6,30)
      M=0
      DO 10 J=1,2
```

```
      IH=IHARD(I,J)                                                    3MOD5020
      M=M+1                                                            3MOD5030
      MHARD(M)=KHARD(IH,1)                                             3MOD5040
      M=M+1                                                            3MOD5050
10    MHARD(M)=KHARD(IH,2)                                             3MOD5060
      WRITE (6,100) I                                                  3MOD5070
      IF (IEPIC(I).EQ.1) WRITE (6,110)                                 3MOD5080
      IF (IEPIC(I).EQ.2) WRITE (6,120)                                 3MOD5090
      WRITE (6,130) NPLNT(I)                                           3MOD5100
      WRITE (6,140) PWRIN(1),PWRE(I),PWRIN(1)                          3MOD5110
      WRITE (6,150) (RPME(I,J),J=1,3)                                  3MOD5120
      WRITE (6,160) (MTHE(I,J),J=1,3)                                  3MOD5130
      WRITE (6,170) PND(I)                                             3MOD5140
      WRITE (6,180) PD(I)                                              3MOD5150
      WRITE (6,190) DPHIN(I)                                           3MOD5160
      WRITE (6,200) DPHI(I)                                            3MOD5170
      WRITE (6,210) DHELIX(I)                                          3MOD5180
      WRITE (6,220) MGE(I)                                             3MOD5190
      WRITE (6,230) (PDIAME(I,J),J=1,3)                                3MOD5200
      WRITE (6,240) FACEE(I)                                           3MOD5210
      WRITE (6,250) FBYDE(I)                                           3MOD5220
      WRITE (6,260) CDE(I)                                             3MOD5230
      WRITE (6,270) PLVE(I)                                            3MOD5240
      WRITE (6,280) WTE(I)                                             3MOD5250
      WRITE (6,290) TLPIE(I)                                           3MOD5260
      WRITE (6,300) UNTLDE(I)                                          3MOD5270
      WRITE (6,310) (MFE(I,J),J=1,3)                                   3MOD5280
      WRITE (6,320) KFCTRE(I)                                          3MOD5290
      WRITE (6,330) SIGHE(I)                                           3MOD5300
      WRITE (6,340) SIGBE(I)                                           3MOD5310
      WRITE (6,350) (TORQE(I,J),J=1,3)                                 3MOD5320
      WRITE (6,360) (MHARD(J),J=1,2),(MHARD(J),J=1,4)                  3MOD5330
20    CONTINUE                                                         3MOD5340
      WRITE (6,30)                                                     3MOD5350
      RETURN                                                           3MOD5360
C                                                                      3MOD5370
```

```
C     FORMAT STATEMENTS                                                 3MOD5380
C                                                                       3MOD5390
C                                                                       3MOD5400
30    FORMAT (//,1X,72(1H*),/)                                          3MOD5410
40    FORMAT (2X,31HPOWER SOURCE:  TURBINE OR MOTOR)                    3MOD5420
50    FORMAT (2X,55HPOWER SOURCE:  MULTICYLINDER INTERNAL COMBUSTION ENG3MOD5430
     1INE)                                                              3MOD5440
60    FORMAT (6X,18HINPUT POWER (HP): ,F7.0,4X,19HINPUT SPEED (RPM): ,F63MOD5450
     1.0,/)                                                             3MOD5460
70    FORMAT (2X,23HARRANGEMENT: EPICYCLIC,,I2,13H REDUCTION(S))        3MOD5470
80    FORMAT (6X,19HOUTPUT POWER (HP): ,F7.0,3X,20HOUTPUT SPEED (RPM): ,3MOD5480
     1F5.0,/,6X,7HRATIO: ,F6.3,16X,25HOUTPUT TORQUE (K IN-LB): ,F8.1,/) 3MOD5490
90    FORMAT (2X,46HSIZING ESTIMATES FOR THE ENTIRE REDUCTION SET:,/,6X,3MOD5500
     113HWEIGHT (LB): ,F7.0,5X,25HSPECIFIC WEIGHT (LB/HP): ,F6.2,/,6X,133MOD5510
     2HLENGTH (IN): ,I3,3X,12HWIDTH (IN): ,I3,3X,13HHEIGHT (IN): ,I3,//)3MOD5520
100   FORMAT (43X,9HREDUCTION,I2,/,24X,1H|,6X,3HSUN,6X,1H|,4X,7HPLANETS,3MOD5530
     14X,1H|,3X,9HRING-CAGE,3X,1H|,/,24X,1H|,15(1H-),1H|,15(1H-),1H|,15(3MOD5540
     21H-),1H|)                                                         3MOD5550
110   FORMAT (1X,24HGEAR ARRANGEMENT        |,19X,9HPLANETARY,19X,1H|)  3MOD5560
120   FORMAT (1X,24HGEAR ARRANGEMENT        |,22X,4HSTAR,21X,1H|)       3MOD5570
130   FORMAT (1X,24HNUMBER OF PLANETS       |,23X,I1,23X,1H|)           3MOD5580
140   FORMAT (1X,24HPOWER SPLIT           HP |,3(4X,F7.0,4X,1H|))       3MOD5590
150   FORMAT (1X,24HSPEED                RPM |,3(4X,F7.0,4X,1H|))       3MOD5600
160   FORMAT (1X,24HNUMBER OF TEETH         |,3(6X,I4,5X,1H|))          3MOD5610
170   FORMAT (1X,24HNORMAL DIAMETRAL PITCH |,20X,F6.3,21X,1H|)          3MOD5620
180   FORMAT (1X,24HTRANS. DIAMETRAL PITCH |,20X,F6.3,21X,1H|)          3MOD5630
190   FORMAT (1X,24HNORMAL PRESSURE ANGLE  |,21X,F4.1,22X,1H|)          3MOD5640
200   FORMAT (1X,24HTRANS. PRESSURE ANGLE  |,21X,F4.1,22X,1H|)          3MOD5650
210   FORMAT (1X,24HHELIX ANGLE             |,21X,F4.1,22X,1H|)         3MOD5660
220   FORMAT (1X,24HGEAR RATIO              |,20X,F6.3,21X,1H|)         3MOD5670
230   FORMAT (1X,24HPITCH DIAMETER       IN |,3(4X,F6.2,5X,1H|))        3MOD5680
240   FORMAT (1X,24HEFFECTIVE FACEWIDTH IN |,21X,F5.2,21X,1H|)          3MOD5690
250   FORMAT (1X,24HF/DP                    |,21X,F4.2,22X,1H|)         3MOD5700
260   FORMAT (1X,24HCENTER DISTANCE      IN |,20X,F6.2,21X,1H|)         3MOD5710
270   FORMAT (1X,24HPITCHLINE VELOCITY FPM |,20X,F6.0,21X,1H|)          3MOD5720
280   FORMAT (1X,24HTANGENTIAL LOAD      LB |,20X,F6.0,21X,1H|)         3MOD5730
```

```
290   FORMAT (1X,24HTOOTH LOAD/IN    LB/IN |,21X,F5.0,21X,1H|)
300   FORMAT (1X,24HUNIT LOAD          PSI |,20X,F6.0,21X,1H|)
310   FORMAT (1X,24HMESH FREQRENCY      HZ |,3(4X,F6.0,5X,1H|))
320   FORMAT (1X,24HK FACTOR (COMPUTED)    |,21X,F5.0,21X,1H|)
330   FORMAT (1X,24HCONTACT STRESS     PSI |,20X,F7.0,20X,1H|)
340   FORMAT (1X,24HBENDING STRESS     PSI |,20X,F7.0,20X,1H|)
350   FORMAT (1X,24HTORQUE          K IN-LB |,3(4X,F7.1,4X,1H|))
360   FORMAT (1X,24HHARDNESS RANGE     BHN |,3(2X,I3,5H  -   ,I3,2X,1H|))
      END
```

Module Four

```
      FUNCTION AGMAE1 (PHIN,II)
C
C     CODED BY:  LT J.L. PAQUETTE, USN           JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO PROVIDE INTERPOLATION OF TABLE E-1 IN
C     AGMA 226.01, AUG 1970 FOR VALUES OF H, L, AND M USED
C     TO COMPUTE KF -- LAGRANGE INTERPOLATION USED
C
C     PHIN   NORMAL PRESSURE ANGLE IN RADIANS
C     II=1   INTERPOLATION OF H -- F(1)  TO F(3)
C     II=2   INTERPOLATION OF L -- F(4)  TO F(6)
C     II=3   INTERPOLATION OF M -- F(7)  TO F(9)
C
      DIMENSION F(9),A(3)
C
C     INITIALIZATION:
C     ARRAY F CONTAINS THE VALUES OF H, L, M FROM TABLE E-1
C
      DATA F/0.22,0.18,0.14,0.20,0.15,0.11,0.40,0.45,0.50/
      SUM=0.0
      L=0
C
C     CONVERT PHIN TO DEGREES FOR USE IN INTERPOLATION
C
      X=PHIN*180./(4.*ATAN(1.))
      A(1)=(X-20.)*(X-25.)/57.75
      A(2)=(X-14.5)*(X-25.)/(-27.5)
      A(3)=(X-14.5)*(X-20.)/52.5
      I=(II-1)*3+1
      J=3*II
      DO 10 K=I,J
      L=L+1
```

```
10    SUM=SUM+A(L)*F(K)
      AGMAE1=SUM
      RETURN
      END
C*****************************************************************
C     *     *     *     *     *     *     *     *     *     *     *
C*****************************************************************
      FUNCTION ARCCOS (A,B)
      RATIO=A/B
      ARG=SQRT(1.-RATIO*RATIO)/RATIO
      ARCCOS=ATAN(ARG)
      RETURN
      END
C*****************************************************************
C     *     *     *     *     *     *     *     *     *     *     *
C*****************************************************************
      FUNCTION ARCSIN (A,B)
      RATIO=A/B
      ARG=RATIO/SQRT(1.-RATIO*RATIO)
      ARCSIN=ATAN(ARG)
      RETURN
      END
C*****************************************************************
C     *     *     *     *     *     *     *     *     *     *     *
C*****************************************************************
      FUNCTION CKDATA (A)
C
C     CODED BY:  LT J.L. PAQUETTE, USN            JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM USED BY SUBROUTINE AGMA TO CHECK AND/OR MODIFY THE
C     PRE-PROGRAMMED AGMA CONSTANTS -- A VALUE  OF ZERO (VAL=0.0) WILL
C     CAUSE THE PRE-PROGRAMMED CONSTANT TO REMAIN UNCHANGED.
C
      READ (5,*) VAL
      IF (VAL.NE.0.0) GO TO 10
```

```
      CKDATA=A
      RETURN
10    CKDATA=VAL
      RETURN
      END
C*************************************************************************
C        *     *     *     *     *     *     *     *     *     *     *     *     *
C*************************************************************************
      FUNCTION FALFA (X,CNST)
C
C     CODED BY:  LT J.L. PAQUETTE, USN          JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO EVALUATE THE FUNCTION OF ALPHA FROM THE
C     GEOMETRY OF THE TOOTH LAYOUT
C
C     X     VARIABLE REPRESENTING ALPHA
C     CNST  PARAMETER LIST OF CONSTANTS IN F(ALPHA)
C           CNST(1)=XC   X-COORD OF ROOT FILLET CENTER
C           CNST(2)=YC   Y-COORD OF ROOT FILLET CENTER
C           CNST(3)=RF   ROOT FILLET RADIUS
C           CNST(4)=RV   RADIUS TO TIP OF STRESS PARABOLA
C           CNST(5)=GII  0 FOR EXTERNAL GEARS; 1 FOR INTERNAL GEARS
C
      DIMENSION CNST(5)
      XC=CNST(1)
      YC=CNST(2)
      RF=CNST(3)
      RV=CNST(4)
      GII=CNST(5)
      CONST=RV-YC
      IF (GII.EQ.1.0) CONST=-CONST
      FALFA=XC-RF*COS(X)-2.*TAN(X)*(CONST+RF*SIN(X))
      RETURN
      END
C*************************************************************************
```

```
C      *     *     *     *     *     *     *     *     *     *     *     *     *     *
C*******************************************************************************
      SUBROUTINE GFI (GEOMI,IRED,MG,DP,DG,III)
C
C     CODED BY:  LT J.L. PAQUETTE, USN           JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO COMPUTE THE DURABILITY GEOMETRY FACTOR, I
C
C     OUTPUT VARIABLE:
C     GEOMI  DURABILITY GEOMETRY FACTOR
C
C     INPUT VARIABLES:
C     IRED   REDUCTION STAGE UNDER CONSIDERATION
C     MG     REDUCTION RATIO  (MG .GT. 1.0)
C     DP     DIAMETER OF THE PINION
C     DG     DIAMETER OF THE GEAR
C     III    0 FOR EXTERNAL GEARS; 1 FOR INTERNAL GEARS
C
C     EXTERNAL SUBPROGRAM(S) REQUIRED: FUNCTION SHRLD
C
      REAL MG
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(3
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX
      RATIO=MG/(MG+1.)
      IF (III.EQ.1) RATIO=MG/(MG-1.)
      TWOMN=2.*SHRLD(IRED,DP,DG)
      GEOMI=SIN(PHI(IRED))*COS(PHI(IRED))*RATIO/TWOMN
      RETURN
      END
C*******************************************************************************
C      *     *     *     *     *     *     *     *     *     *     *     *     *     *
C*******************************************************************************
      SUBROUTINE GFJ (GEOMJ,IRED,DP,DG,IPG,III)
C
```

```
C     CODED BY:  LT J.L. PAQUETTE, USN          JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO COMPUTE THE STRENGTH GEOMETRY FACTOR, J,
C     IAW AGMA 226.01, AUG 1970 -- ALL CALCULATIONS ARE BASED
C     ON ACTUAL GEOMETRY WITH NO REQUIREMENT TO SCALE THE
C     PROBLEM TO A NORMAL DIAMETRAL PITCH OF ONE (PND=1).
C     THE AGMA TOOTH FORM FACTOR, BASED ON A SCALE OF PND=1,
C     HAS BEEN APPROPRIATELY MODIFIED.
C
C     OUTPUT VARIABLE:
C     GEOMJ  STRENGTH GEOMETRY FACTOR
C
C     INPUT VARIABLES:
C     IRED   REDUCTION STAGE UNDER CONSIDERATION
C     DP     DIAMETER OF THE PINION
C     DG     DIAMETER OF THE GEAR
C     IPG    GEAR FOR WHICH GEOMJ IS COMPUTED:
C              IPG=1  GEOMJ FOR PINION
C              IPG=2  GEOMJ FOR GEAR
C     III    0 FOR EXTERNAL GEARS; 1 FOR INTERNAL GEARS
C
C     EXTERNAL SUBPROGRAM(S) REQUIRED: FUNCTION AGMAE1, FUNCTION ARCCOS,
C        FUNCTION ARCSIN, FUNCTION FALFA, FUNCTION RTFNDR, FUNCTION
C        SHRLD, FUNCTION THICK
C
      REAL INV,KF,MN
      DIMENSION CNST(5)
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(3
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX
      EXTERNAL FALFA
      INV(Z)=TAN(Z)-Z
C
C     INITIALIZATION
C
```

```
      IF (IPG.EQ.1) III=0                                              4MOD1780
      PI=4.*ATAN(1.)                                                   4MOD1790
      D=DP                                                             4MOD1800
      IF (IPG.EQ.2) D=DG                                               4MOD1810
C                                                                      4MOD1820
C     A=ADDENDUM; B=DEDENDUM; TT=ARC THICKNESS OF THE TOOTH            4MOD1830
C     AT THE PITCH DIAMETER, D                                         4MOD1840
C                                                                      4MOD1850
      A=1./PD(IRED)                                                    4MOD1860
      B=1.25/PD(IRED)                                                  4MOD1870
      TT=PI*COS(HELIX(IRED))/(2.*PD(IRED))                             4MOD1880
C                                                                      4MOD1890
C     RF=ROOT FILLET RADIUS; RT=RADIUS OF TIP OF GENERATING TOOL       4MOD1900
C     (ASSUME AVERAGE VALUE OF 0.28/PND FOR RT)                        4MOD1910
C                                                                      4MOD1920
      RT=.28/PND(IRED)                                                 4MOD1930
      BMRT=B-RT                                                        4MOD1940
      RF=RT+BMRT*BMRT/(D/(2.*COS(HELIX(IRED))*COS(HELIX(IRED)))+BMRT)  4MOD1950
C                                                                      4MOD1960
C     D=PITCH DIAMETER; DR=ROOT DIAMETER; DO=OUTSIDE DIAMETER;         4MOD1970
C     DB=BASE DIAMETER; DI=INSIDE DIAMETER (INTERNAL GEARS ONLY)       4MOD1980
C                                                                      4MOD1990
      DR=D-2.*B                                                        4MOD2000
      DO=D+2.*A                                                        4MOD2010
      DB=D*COS(PHI(IRED))                                              4MOD2020
      DI=D-2.*A                                                        4MOD2030
C                                                                      4MOD2040
C     TC=CHORDAL THICKNESS OF THE TOOTH AT THE PITCH DIAMETER;         4MOD2050
C     EPS=ANGLE FROM THE CENTERLINE OF THE TOOTH TO A POINT WHERE      4MOD2060
C     THE INVOLUTE CURVE CROSSES THE BASE CIRCLE; TTIP=THICKNESS       4MOD2070
C     OF THE TOOTH AT ITS TIP                                          4MOD2080
C                                                                      4MOD2090
      TC=TT-(TT*TT*TT*COS(HELIX(IRED))*COS(HELIX(IRED))/(6.*D*D))      4MOD2100
      EPS=INV(PHI(IRED))+ARCSIN(TC,D)                                  4MOD2110
      IF (III.EQ.1) EPS=ARCSIN(TC,D)-INV(PHI(IRED))                    4MOD2120
      DTIP=DO                                                          4MOD2130
```

```
      IF (III.EQ.1) DTIP=DI                                             4MOD2140
      TTIP=THICK(D,DB,DTIP,TT,III)                                      4MOD2150
C                                                                       4MOD2160
C     PHILN=NORMAL LOAD PRESSURE ANGLE AT THE TIP OF THE TOOTH;         4MOD2170
C     RV=RADIUS TO THE TIP OF THE STRESS PARABOLA ON THE TOOTH          4MOD2180
C     CENTERLINE; XC=X-COORD OF THE CENTER OF THE ROOT FILLET;          4MOD2190
C     YC=Y-COORD OF THE CENTER OF THE ROOT FILLET (BOTH WITH            4MOD2200
C     RESPECT TO THE TOOTH CENTERLINE)                                  4MOD2210
C                                                                       4MOD2220
      PHILN=ARCCOS(DB,DTIP)-(TTIP/DTIP)                                 4MOD2230
      IF (III.EQ.1) PHILN=ARCCOS(DB,DTIP)+(TTIP/DTIP)                   4MOD2240
      RV=DB/(2.*COS(PHILN))                                             4MOD2250
C                                                                       4MOD2260
C     COMPUTE XC AND YC                                                 4MOD2270
C                                                                       4MOD2280
      HYP=(DR/2.)+RF                                                    4MOD2290
      RB=DB/2.                                                          4MOD2300
      IF (HYP-RB) 10,20,20                                              4MOD2310
   10 XC=RF+HYP*SIN(EPS)                                                4MOD2320
      YC=SQRT(HYP*HYP-XC*XC)                                            4MOD2330
      GO TO 30                                                          4MOD2340
   20 PHI1=ARCCOS(RB,HYP)                                               4MOD2350
      OPP1=HYP*SIN(PHI1)                                                4MOD2360
      OPP2=OPP1-RF                                                      4MOD2370
      HYP1=SQRT(OPP2*OPP2+RB*RB)                                        4MOD2380
      PHI2=ARCCOS(RB,HYP1)                                              4MOD2390
      DELTA=EPS+PHI1-PHI2-INV(PHI2)                                     4MOD2400
      IF (III.EQ.1) DELTA=EPS+PHI1-PHI2+INV(PHI2)                       4MOD2410
      XC=HYP*SIN(DELTA)                                                 4MOD2420
      YC=HYP*COS(DELTA)                                                 4MOD2430
C                                                                       4MOD2440
C     SOLVE FOR THE ANGLE ALPHA USED TO COMPUTE VALUES OF T, H,         4MOD2450
C     AND X WHICH ARE 'COMPUTED MEASUREMENTS' FROM THE TOOTH            4MOD2460
C     LAYOUT (NOTE: T=2*CAPT)                                           4MOD2470
C     ARRAY CNST IS A PARAMETER LIST OF CONSTANTS REQUIRED FOR          4MOD2480
C     THE EVALUATION OF THE FUNCTION OF ALPHA                           4MOD2490
```

```
C                                                                      4MOD2500
30    CNST(1)=XC                                                       4MOD2510
      CNST(2)=YC                                                       4MOD2520
      CNST(3)=RF                                                       4MOD2530
      CNST(4)=RV                                                       4MOD2540
      CNST(5)=FLOAT(III)                                               4MOD2550
      ALPHA=RTFNDR(0.,0.7,FALFA,CNST,0.0001)                           4MOD2560
      CAPT=XC-RF*COS(ALPHA)                                            4MOD2570
      T=2.*CAPT                                                        4MOD2580
      H=RV-YC+RF*SIN(ALPHA)                                            4MOD2590
      IF (III.EQ.1)  H=YC-RV+RF*SIN(ALPHA)                             4MOD2600
      ARG=H/CAPT                                                       4MOD2610
      GAMMA1=(PI/2.)-ATAN(ARG)                                         4MOD2620
      X=CAPT*TAN(GAMMA1)                                               4MOD2630
C                                                                      4MOD2640
C     CSMH=AGMA HELICAL FACTOR; ANU=ARGUMENT FOR CSMH IN DEGREES       4MOD2650
C     AND DIVIDED BY 100                                               4MOD2660
C                                                                      4MOD2670
      ARG=TAN(HELIX(IRED))*SIN(PHIN(IRED))                             4MOD2680
      ANU=ATAN(ARG)*1.8/PI                                             4MOD2690
      CSMH=1./(1.-SQRT(ANU*(1.-ANU)))                                  4MOD2700
C                                                                      4MOD2710
C     YSMC=AGMA TOOTH FORM FACTOR                                      4MOD2720
C                                                                      4MOD2730
      ARG=(1.5/(X*CSMH))-(TAN(PHILN)/T)                                4MOD2740
      ARG1=COS(PHILN)/COS(PHIN(IRED))                                  4MOD2750
      YSMC=PND(IRED)/(ARG*ARG1)                                        4MOD2760
C                                                                      4MOD2770
C     KF=THEORETICAL STRESS CORRECTION FACTOR; AH, AL, AND AM ARE      4MOD2780
C     THE H, L, AND M CONSTANTS FROM AGMA 226.01, APPENDIX E, USED     4MOD2790
C     TO COMPUTE KF                                                    4MOD2800
C                                                                      4MOD2810
      AH=AGMAE1(PHIN(IRED),1)                                          4MOD2820
      AL=AGMAE1(PHIN(IRED),2)                                          4MOD2830
      AM=AGMAE1(PHIN(IRED),3)                                          4MOD2840
      RAT1=T/RF                                                        4MOD2850
```

```
      RAT2=T/H
      KP=AH+(RAT1**AL)*(RAT2**AM)
C
C     MN=LOAD SHARING RATIO
C
      MN=SHRLD(IRED,DP,DG)
C
C     GEOMETRY FACTOR J
C
      GEOMJ=YSMC*COS(HELIX(IRED))*COS(HELIX(IRED))/(KF*MN)
      RETURN
      END
C*****************************************************************************
C     *     *     *     *     *     *     *     *     *     *     *     *     *
C*****************************************************************************
      FUNCTION POWERB (RPM,FACE,D,IRED,IPWR,IGR,GEOMJ)
C
C     CODED BY:  LT J.L. PAQUETTE, USN          JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO COMPUTE THE ALLOWABLE SERVICE POWER FOR A GEAR PAIR
C     BASED ON AGMA'S STRENGTH RATING (AGMA 221.02 JUL 1965)
C
C     RPM    PINION SPEED IN RPM
C     FACE   FACEWIDTH OF THE GEAR PAIR IN INCHES
C     D      PITCH DIAMETER OF THE PINION IN INCHES
C     GEOMJ  STRENGTH GEOMETRY FACTOR, J
C     IRED   REDUCTION STAGE UNDER CONSIDERATION
C     IPWR   POWER SOURCE IDENTIFICATION
C     IGR    GEAR IDENTIFICATION (1=PINION, 2=GEAR)
C
      COMMON /AGMAB/ SFB(2,2),AKV,AKS,AKM,AKO(2),SAT(6),AKL(2),AKR(6),AK
     1T
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(3
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX
```

```
C
C     INITIALIZATION
C
      IH=IHARD(IRED,IGR)
      IP=IPWRSR(IPWR)
      NPTH=NPATH
      IF ((NRED.EQ.3).AND.(IRED.GE.2)) NPTH=2
C
C     COMPUTE ALLOWABLE SERVICE POWER
C
      ANUM=RPM*D*AKV*GEOMJ*SAT(IH)*AKL(IOPRO)
      DEN=SFB(IOPRO,IP)*AKO(NPTH)*AKM*AKS*AKR(IH)*AKT*PD(IRED)
      POWERB=FACE*ANUM/(126050.*DEN)
      RETURN
      END
C*****************************************************************
C         *     *     *     *     *     *     *     *     *     *     *     *     *
C*****************************************************************
      FUNCTION POWERH (RPM,FACE,D,IRED,IPWR,GEOMI)
C
C     CODED BY:  LT J.L. PAQUETTE, USN           JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO COMPUTE THE ALLOWABLE SERVICE POWER OF A GEAR PAIR
C     BASED ON AGMA'S DURABILITY RATING (AGMA 211.02 SEPT 1966)
C
C     RPM    PINION SPEED IN RPM
C     FACE   FACEWIDTH OF THE GEAR PAIR IN INCHES
C     D      PITCH DIAMETER OF THE PINION IN INCHES
C     IRED   REDUCTION STAGE UNDER CONSIDERATION
C     IPWR   POWER SOURCE IDENTIFICATION
C     GEOMI  DURABILITY GEOMETRY FACTOR, I
C
      COMMON /AGMAH/ SFH(2,2),CV(3),CS,CM(2),CF,CO(2),SAC(6),CP,CL(2),CH
     1,CT,CR(6)
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),
```

```
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIPP,IARR,IEPIC(3),IHARD(34MOD3580
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX             4MOD3590
C                                                                       4MOD3600
C     INITIALIZATION                                                    4MOD3610
C                                                                       4MOD3620
      IH=IHARD(IRED,1)                                                  4MOD3630
      IP=IPWRSR(IPWR)                                                   4MOD3640
C                                                                       4MOD3650
C     COMPUTE ALLOWABLE SERVICE POWER                                   4MOD3660
C                                                                       4MOD3670
      BRAC=SAC(IH)*D*CL(IOPRO)*CH/(CP*CT*CR(IH))                        4MOD3680
      ANUM=RPM*GEOMI*CV(IRED)*BRAC*BRAC                                 4MOD3690
      DEN=SFH(IOPRO,IP)*CS*CM(IOPRO)*CF*CO(IOPRO)                       4MOD3700
      POWERH=FACE*ANUM/(126050.*DEN)                                    4MOD3710
      RETURN                                                            4MOD3720
      END                                                               4MOD3730
C***********************************************************************4MOD3740
C   *     *     *     *     *     *     *     *     *     *     *     * 4MOD3750
C***********************************************************************4MOD3760
      FUNCTION RNDGEN (RO)                                              4MOD3770
      PI=3.14159286745534                                               4MOD3780
      A=(PI+RO)**5.                                                     4MOD3790
      I=IFIX(A)                                                         4MOD3800
      RNDGEN=A-FLOAT(I)                                                 4MOD3810
      RETURN                                                            4MOD3820
      END                                                               4MOD3830
C***********************************************************************4MOD3840
C   *     *     *     *     *     *     *     *     *     *     *     * 4MOD3850
C***********************************************************************4MOD3860
      FUNCTION RTFNDR (AX,BX,F,CNST,TOL)                                4MOD3870
C                                                                       4MOD3880
C        THIS FUNCTION SUBPROGRAM IS A SLIGHTLY MODIFIED                4MOD3890
C     VERSION OF THE FUNCTION SUBPROGRAM ZEROIN GIVEN IN                4MOD3900
C     FORSYTHE, MALCOLM, AND MOLER, COMPUTER METHODS FOR                4MOD3910
C     MATHEMATICAL COMPUTATIONS, PRENTICE-HALL,INC. (1977).             4MOD3920
C                           LT J.L. PAQUETTE, USN  JAN 1982             4MOD3930
```

```
C                                                                       4MOD3940
C     SUBPROGRAM TO FIND A ROOT OF F(X)  IN THE INTERVAL AX,BX          4MOD3950
C                                                                       4MOD3960
C     AX    LEFT ENDPOINT OF INITIAL INTERVAL                           4MOD3970
C     BX    RIGHT ENDPOINT OF INITIAL INTERVAL                          4MOD3980
C     F     FUNCTION SUBPROGRAM FOR EVALUATION OF F(X)                  4MOD3990
C     CNST  PARAMETER LIST OF CONSTANTS REQUIRED IN F(X)                4MOD4000
C     TOL   DESIRED LENGTH OF INTERVAL OF UNCERTAINTY OF                4MOD4010
C           THE FINAL RESULT                                            4MOD4020
C                                                                       4MOD4030
C     IT IS ASSUMED THAT F(AX)  AND F(BX)  HAVE OPPOSITE SIGNS          4MOD4040
C     WITHOUT A CHECK.  RTFNDR RETURNS A ROOT, X, IN THE                4MOD4050
C     INTERVAL AX,BX TO WITHIN A TOLERANCE OF 4*EPS*ABS(X)+TOL          4MOD4060
C     WHERE EPS IS THE RELATIVE MACHINE PRECISION.                      4MOD4070
C                                                                       4MOD4080
      DIMENSION CNST(5)                                                 4MOD4090
C                                                                       4MOD4100
C     COMPUTE EPS, THE RELATIVE MACHINE PRECISION                       4MOD4110
C                                                                       4MOD4120
      EPS=1.0                                                           4MOD4130
10    EPS=EPS/2.0                                                       4MOD4140
      TOL1=1.0+EPS                                                      4MOD4150
      IF (TOL1.GT.1.0) GO TO 10                                         4MOD4160
C                                                                       4MOD4170
C     INITIALIZATION                                                    4MOD4180
C                                                                       4MOD4190
      A=AX                                                              4MOD4200
      B=BX                                                              4MOD4210
      FA=F(A,CNST)                                                      4MOD4220
      FB=F(B,CNST)                                                      4MOD4230
C                                                                       4MOD4240
C     BEGIN STEP                                                        4MOD4250
C                                                                       4MOD4260
20    C=A                                                               4MOD4270
      FC=FA                                                             4MOD4280
      D=B-A                                                             4MOD4290
```

```
      E=D                                                               4MOD4300
   30 IF (ABS(FC).GE.ABS(FB)) GO TO 40                                  4MOD4310
      A=B                                                               4MOD4320
      B=C                                                               4MOD4330
      C=A                                                               4MOD4340
      FA=FB                                                             4MOD4350
      FB=FC                                                             4MOD4360
      FC=FA                                                             4MOD4370
C                                                                       4MOD4380
C     CONVERGENCE TEST                                                  4MOD4390
C                                                                       4MOD4400
   40 TOL1=2.*EPS*ABS(B)+.5*TOL                                         4MOD4410
      XM=.5*(C-B)                                                       4MOD4420
      IF (ABS(XM).LE.TOL1) GO TO 90                                     4MOD4430
      IF (FB.EQ.0.0) GO TO 90                                           4MOD4440
C                                                                       4MOD4450
C     BISECTION REQUIREMENT TEST                                        4MOD4460
C                                                                       4MOD4470
      IF (ABS(E).LT.TOL1) GO TO 70                                      4MOD4480
      IF (ABS(FA).LE.ABS(FB)) GO TO 70                                  4MOD4490
C                                                                       4MOD4500
C     QUADRATIC INTERPOLATION TEST                                      4MOD4510
C                                                                       4MOD4520
      IF (A.NE.C) GO TO 50                                              4MOD4530
C                                                                       4MOD4540
C     LINEAR INTERPOLATION                                              4MOD4550
C                                                                       4MOD4560
      S=FB/FA                                                           4MOD4570
      P=2.*XM*S                                                         4MOD4580
      Q=1.-S                                                            4MOD4590
      GO TO 60                                                          4MOD4600
C                                                                       4MOD4610
C     INVERSE QUADRATIC INTERPOLATION                                   4MOD4620
C                                                                       4MOD4630
   50 Q=FA/FC                                                           4MOD4640
      R=FB/FC                                                           4MOD4650
```

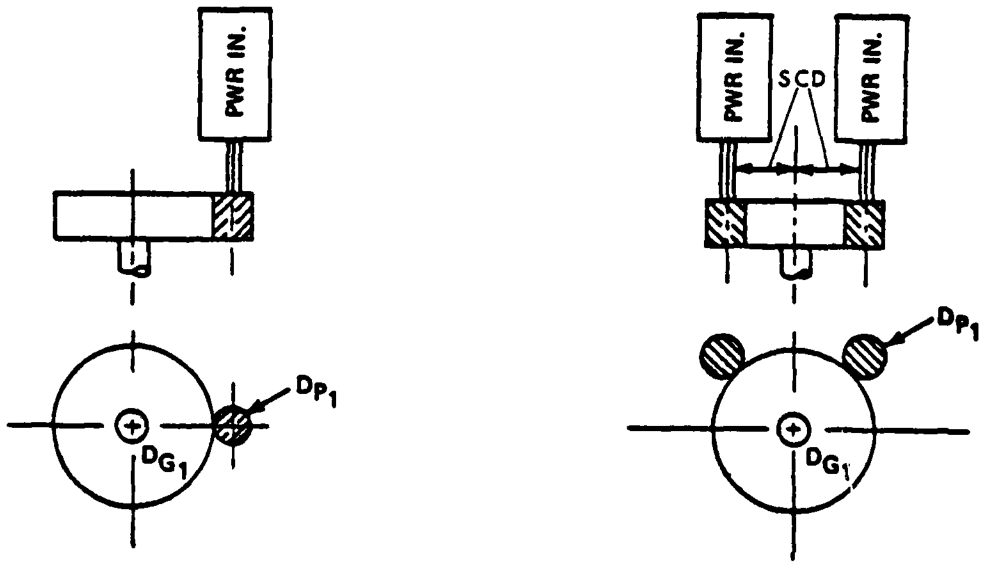
```
      S=FB/FA                                                           4MOD4660
      P=S*(2.*XM*Q*(Q-R)-(B-A)*(R-1.))                                  4MOD4670
      Q=(Q-1.)*(R-1.)*(S-1.)                                            4MOD4680
C                                                                       4MOD4690
C     ADJUST SIGNS                                                      4MOD4700
C                                                                       4MOD4710
60    IF (P.GT.0.0) Q=-Q                                                4MOD4720
      P=ABS(P)                                                          4MOD4730
C                                                                       4MOD4740
C     INTERPOLATION ACCEPTABILITY TEST                                  4MOD4750
C                                                                       4MOD4760
      T1=2.*P                                                           4MOD4770
      T2=3.*XM*Q-ABS(TOL1*Q)                                            4MOD4780
      T3=ABS(.5*E*Q)                                                    4MOD4790
      IF (T1.GE.T2) GO TO 70                                            4MOD4800
      IF (P.GE.T3) GO TO 70                                             4MOD4810
      E=D                                                               4MOD4820
      D=P/Q                                                             4MOD4830
      GO TO 80                                                          4MOD4840
C                                                                       4MOD4850
C     BISECTION                                                         4MOD4860
C                                                                       4MOD4870
70    D=XM                                                              4MOD4880
      E=D                                                               4MOD4890
C                                                                       4MOD4900
C     COMPLETE STEP                                                     4MOD4910
C                                                                       4MOD4920
80    A=B                                                               4MOD4930
      FA=FB                                                             4MOD4940
      IF (ABS(D).GT.TOL1) B=B+D                                         4MOD4950
      IF (ABS(D).LE.TOL1) B=B+SIGN(TOL1,XM)                             4MOD4960
      FB=F(B,CNST)                                                      4MOD4970
      T1=FB*(FC/ABS(FC))                                                4MOD4980
      IF (T1.GT.0.0) GO TO 20                                           4MOD4990
      GO TO 30                                                          4MOD5000
C                                                                       4MOD5010
```

```
C     ROUTINE COMPLETED                                                 4MOD5020
C                                                                       4MOD5030
90    RTFNDR=B                                                          4MOD5040
      RETURN                                                            4MOD5050
      END                                                               4MOD5060
C***********************************************************************4MOD5070
C     *    *    *    *    *    *    *    *    *    *    *    *    *    * 4MOD5080
C***********************************************************************4MOD5090
      FUNCTION SHRLD (IRED,DP,DG)                                       4MOD5100
C                                                                       4MOD5110
C     CODED BY:  LT J.L. PAQUETTE, USN           JAN 1982               4MOD5120
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940          4MOD5130
C                                                                       4MOD5140
C     SUBPROGRAM TO COMPUTE THE LOAD SHARING RATIO, MN=PN/(.95*Z)       4MOD5150
C                                                                       4MOD5160
C     IRED  REDUCTION STAGE UNDER CONSIDERATION                         4MOD5170
C     DP    DIAMETER OF THE PINION                                      4MOD5180
C     DG    DIAMETER OF THE GEAR                                        4MOD5190
C                                                                       4MOD5200
      COMMON /DESDAT/ PWRIN(2),RPMIN(2),RPMOUT,DHELIX(3),HELIX(3),PD(3),4MOD5210
     1PND(3),DPHI(3),PHI(3),DPHIN(3),PHIN(3),NDIFP,IARR,IEPIC(3),IHARD(34MOD5220
     2,2),IOPRO,NPWRIN,IPWRSR(2),NRED,NPATH,NPLNT(3),NHELX              4MOD5230
      PI=4.*ATAN(1.)                                                    4MOD5240
      PN=(PI/PND(IRED))*COS(PHIN(IRED))                                 4MOD5250
      DGB=DG*COS(PHI(IRED))                                             4MOD5260
      DPB=DP*COS(PHI(IRED))                                             4MOD5270
      DGO=DG+(2./PD(IRED))                                              4MOD5280
      DPO=DP+(2./PD(IRED))                                              4MOD5290
      Z=.5*(SQRT(DGO*DGO-DGB*DGB)+SQRT(DPO*DPO-DPB*DPB)-SQRT(DG*DG-DGB*D4MOD5300
     1GB)-SQRT(DP*DP-DPB*DPB))                                          4MOD5310
      SHRLD=PN/(.95*Z)                                                  4MOD5320
      RETURN                                                            4MOD5330
      END                                                               4MOD5340
C***********************************************************************4MOD5350
C     *    *    *    *    *    *    *    *    *    *    *    *    *    * 4MOD5360
C***********************************************************************4MOD5370
```

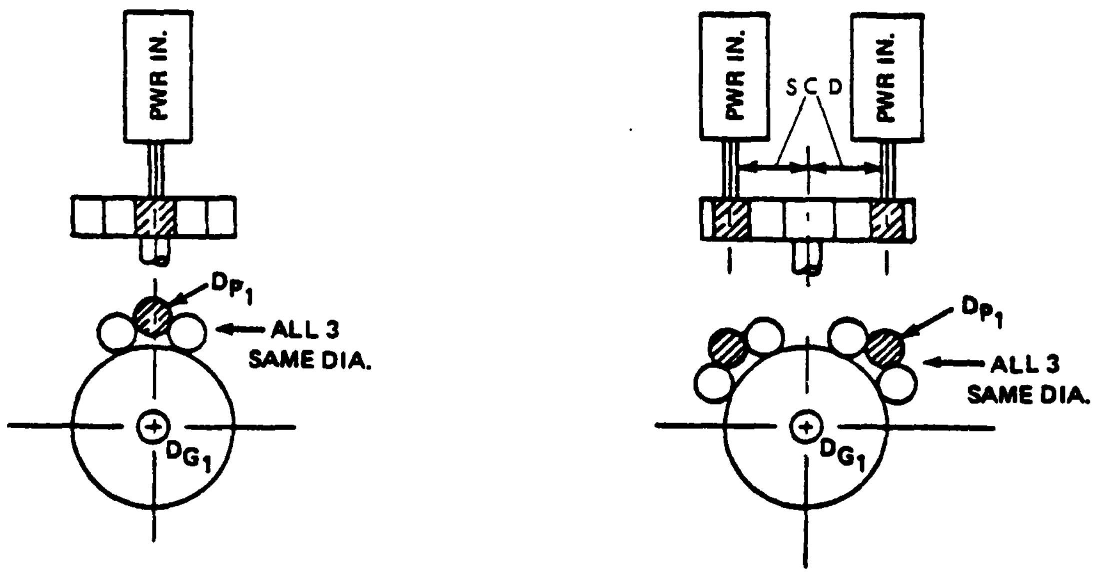
```
      FUNCTION THICK (D,DB,DT,T,III)
C
C     CODED BY:  LT J.L. PAQUETTE, USN           JAN 1982
C                NAVAL POSTGRADUATE SCHOOL  MONTEREY, CA 93940
C
C     SUBPROGRAM TO COMPUTE THE THICHNESS OF A TOOTH BASED ON
C     A THICKNESS KNOWN AT A SPECIFIED DIAMETER
C
C     D    REFERENCE DIAMETER OF KNOWN THICKNESS (USUALLY PITCH DIAM.)
C     DB   BASE DIAMETER OF THE GEAR
C     DT   DIAMETER AT WHICH THE THICKNESS IS TO BE COMPUTED
C     T    KNOWN THICKNESS AT REFERENCE DIAMETER
C     III  0 FOR EXTERNAL GEARS; 1 FOR INTERNAL GEARS
C
C     EXTERNAL SUBPROGRAM(S) REQUIRED: FUNCTION ARCCOS
C
      REAL INV
      INV(X)=TAN(X)-X
      PHI=ARCCOS(DB,D)
      PHIT=ARCCOS(DB,DT)
      IF (III.EQ.1) GO TO 10
      THICK=DT*((T/D)+INV(PHI)-INV(PHIT))
      RETURN
10    THICK=DT*((T/D)-INV(PHI)+INV(PHIT))
      RETURN
      END
```

APPENDIX E

FIGURES

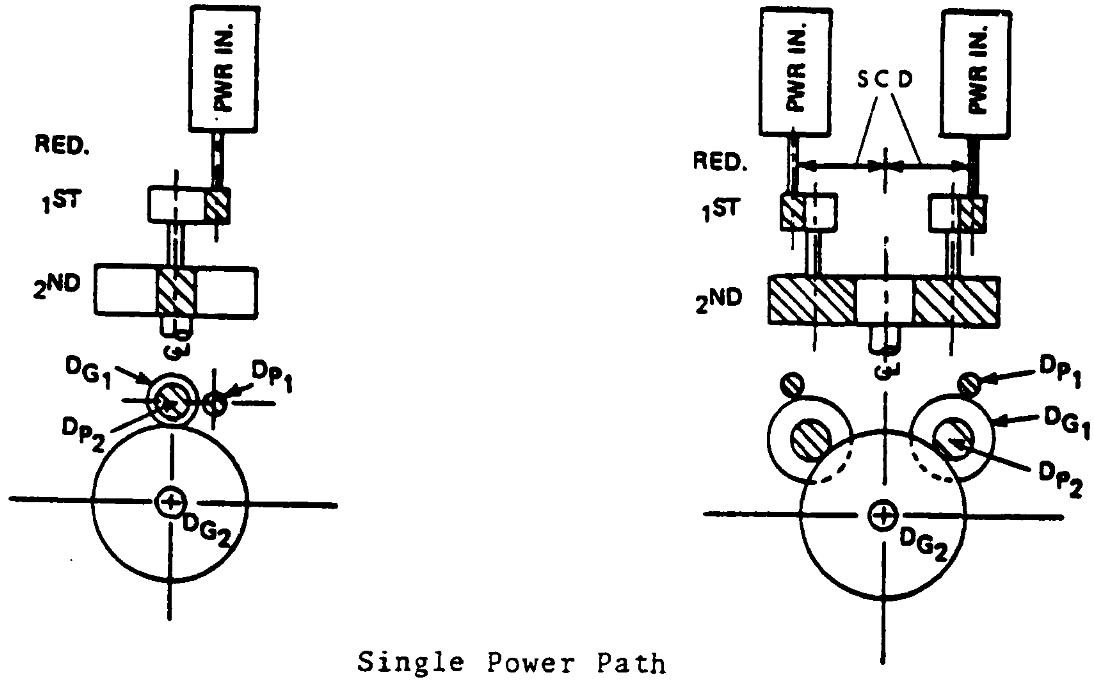


Single Power Path

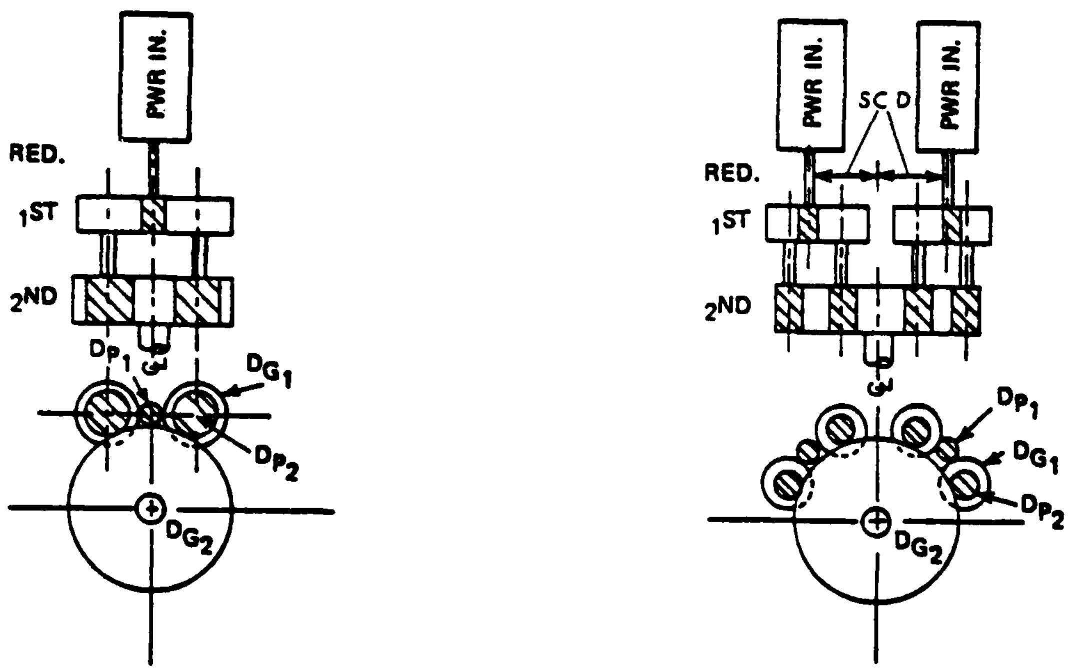


Double Power Paths

Figure 1: Single Reduction Parallel Axis Arrangements

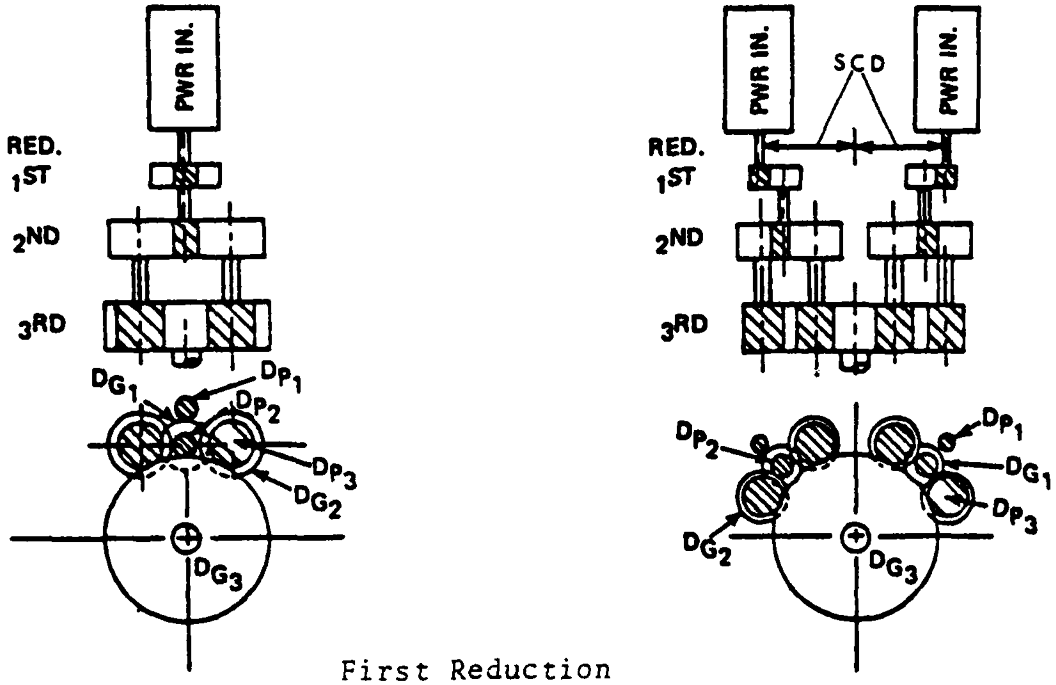


Single Power Path

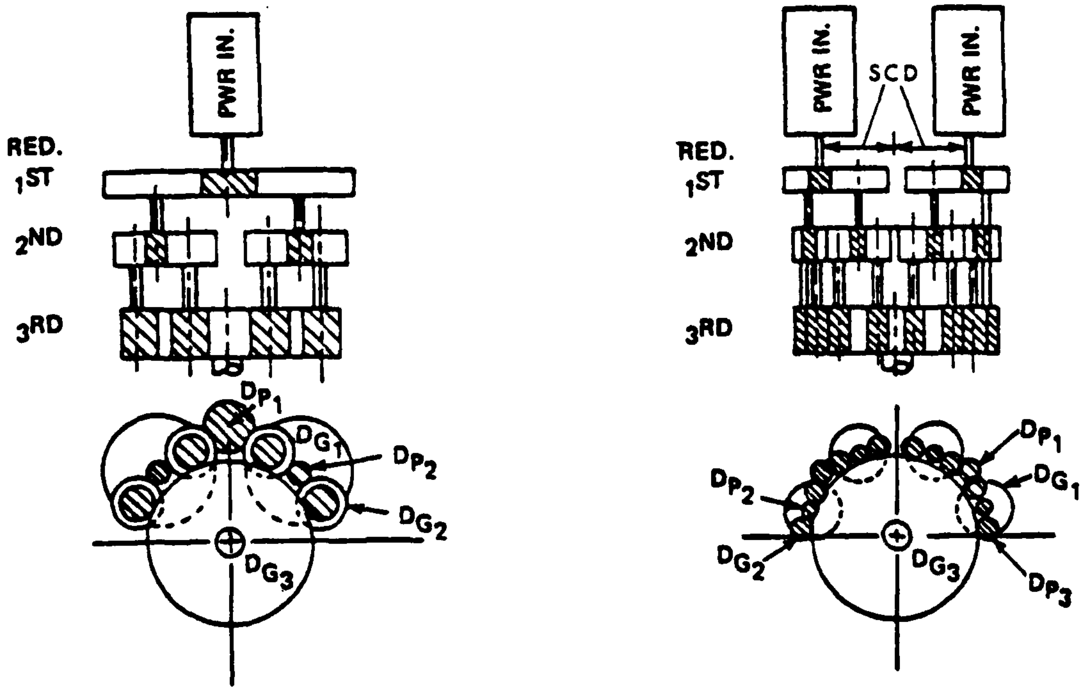


Double Power Path

Figure 2: Double Reduction Parallel Axis Arrangements

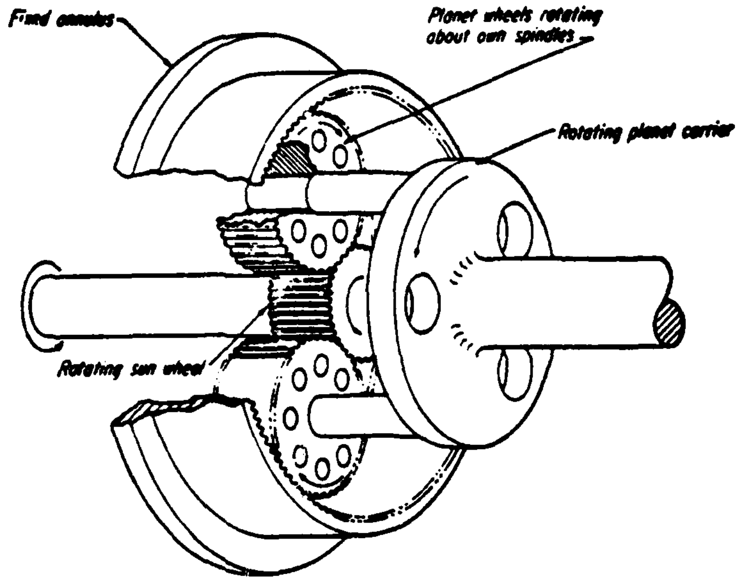


First Reduction
Single Power Path

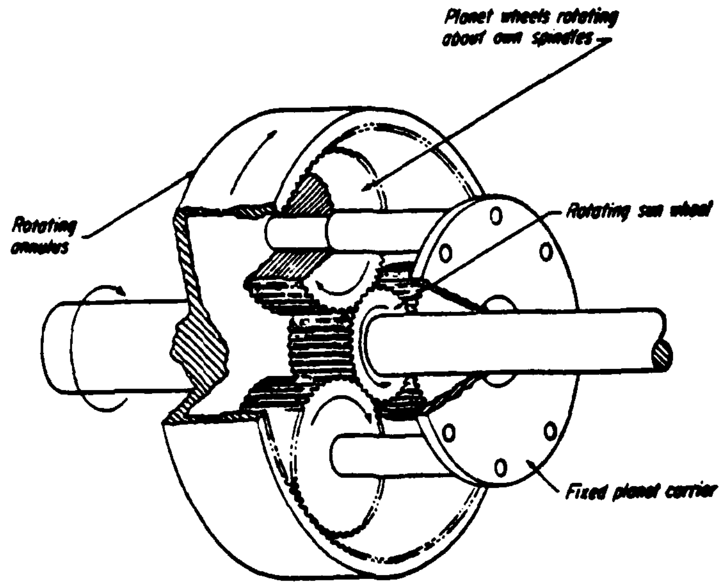


Double Power Paths

Figure 3: Triple Reduction Parallel Axis Arrangements



Planetary



Star

Figure 4: Single Reduction Epicyclic Arrangements
(from Ref. 7)

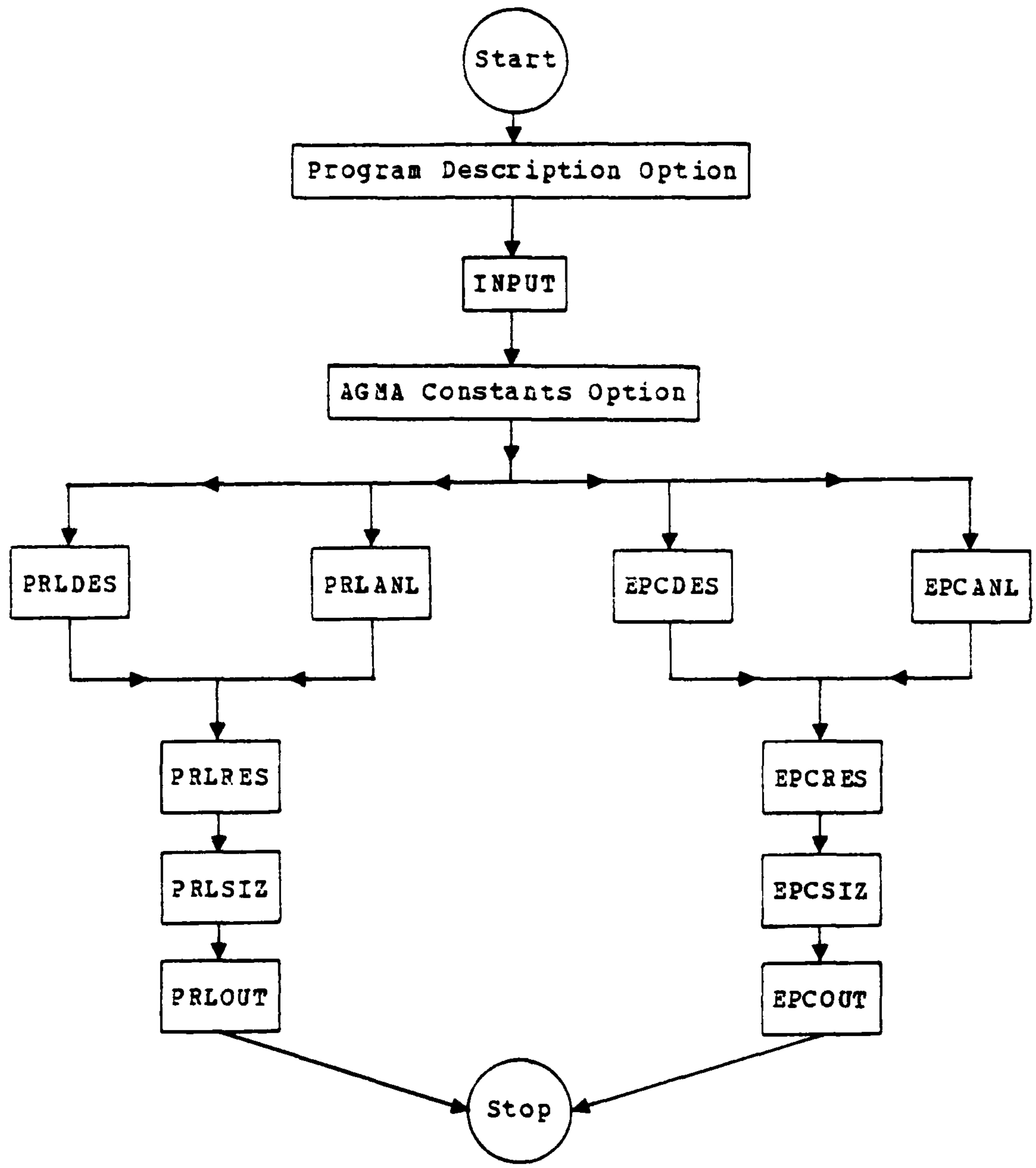


Figure 5: Flow Chart of the REGAD Package

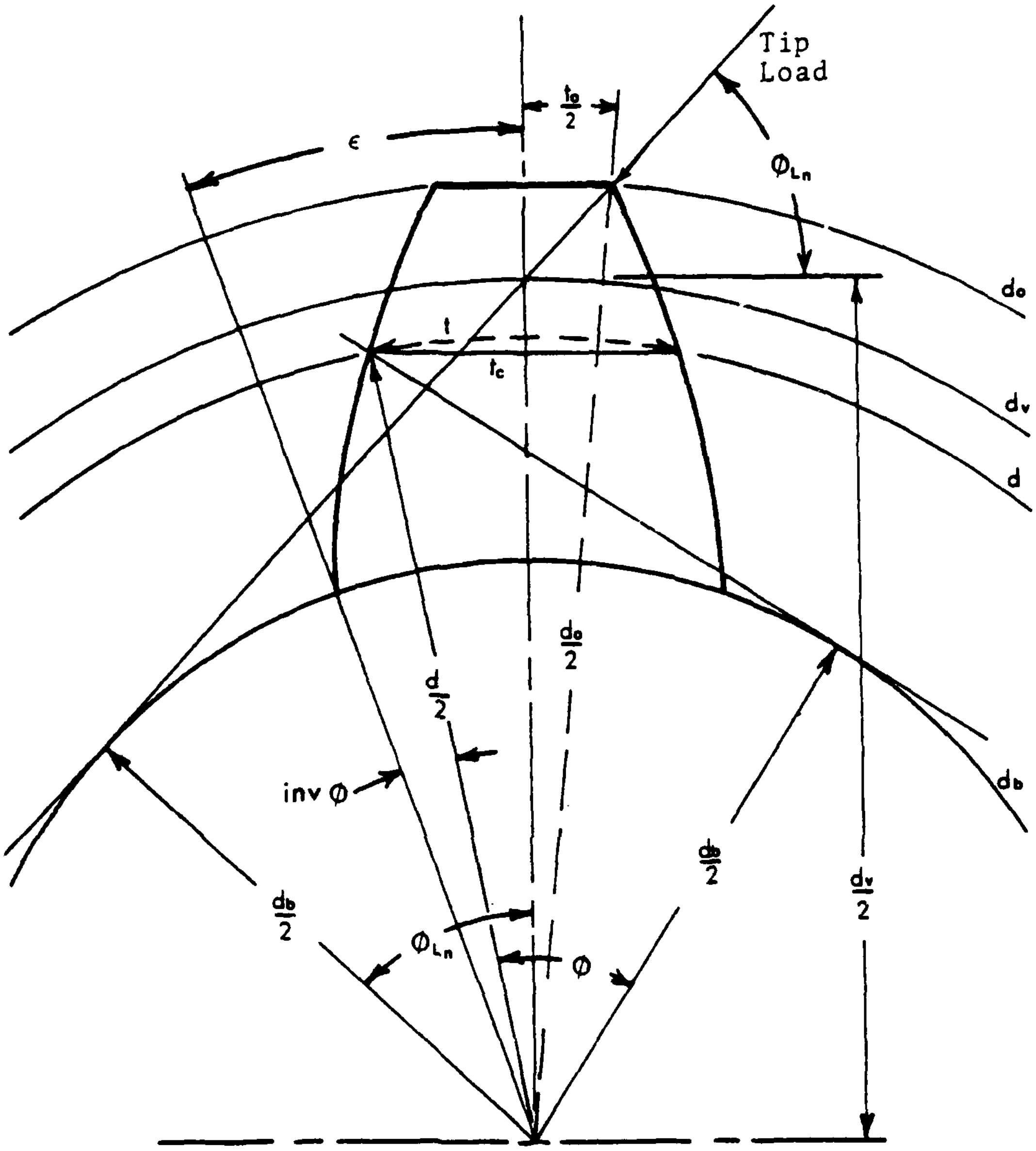


Figure 6: External Tooth Dimensions

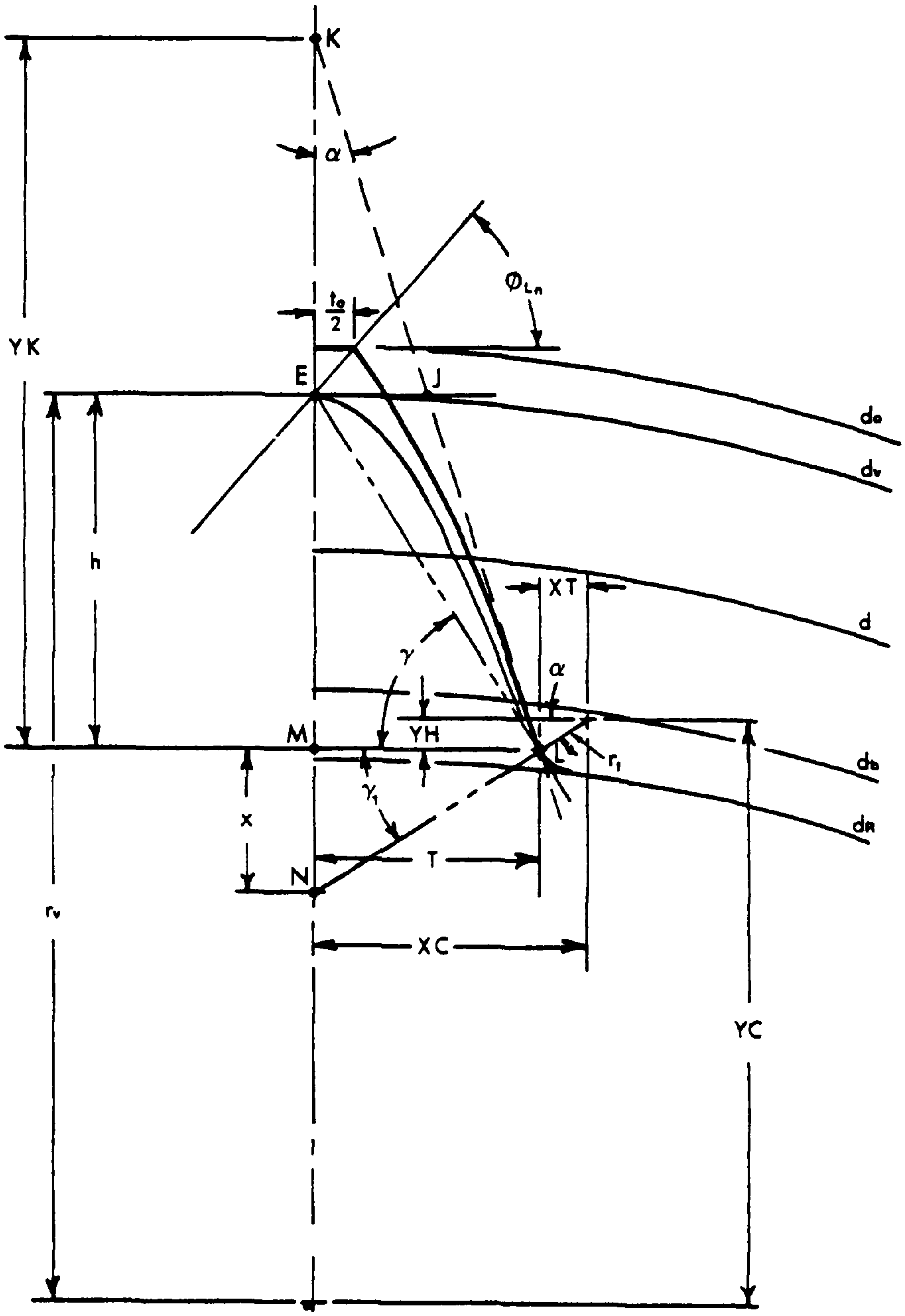


Figure 7: External Tooth Form Layout

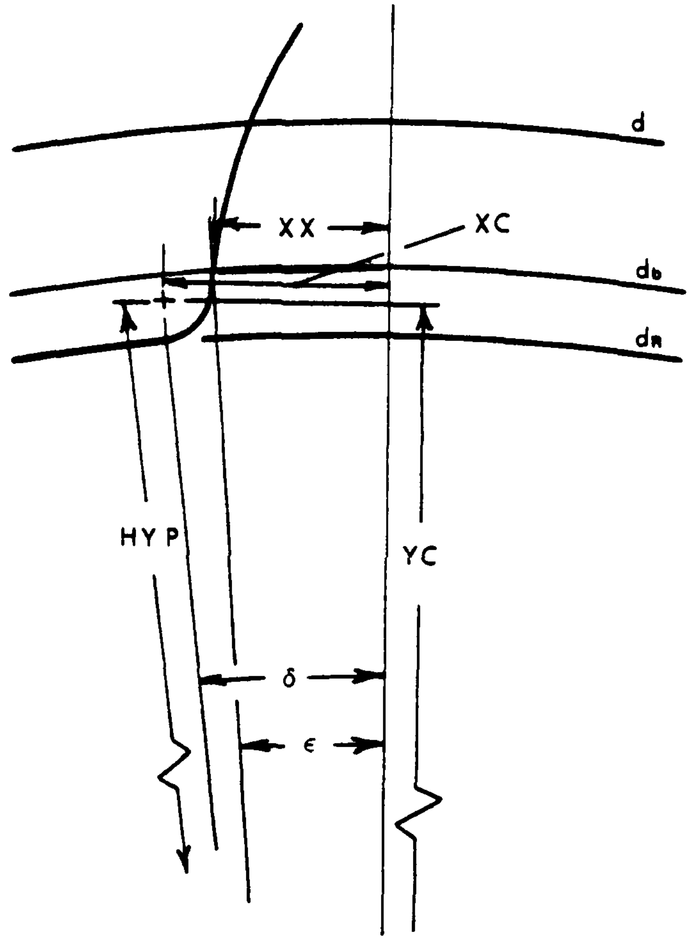


Figure 8: Fillet Center Location - Inside Base Circle

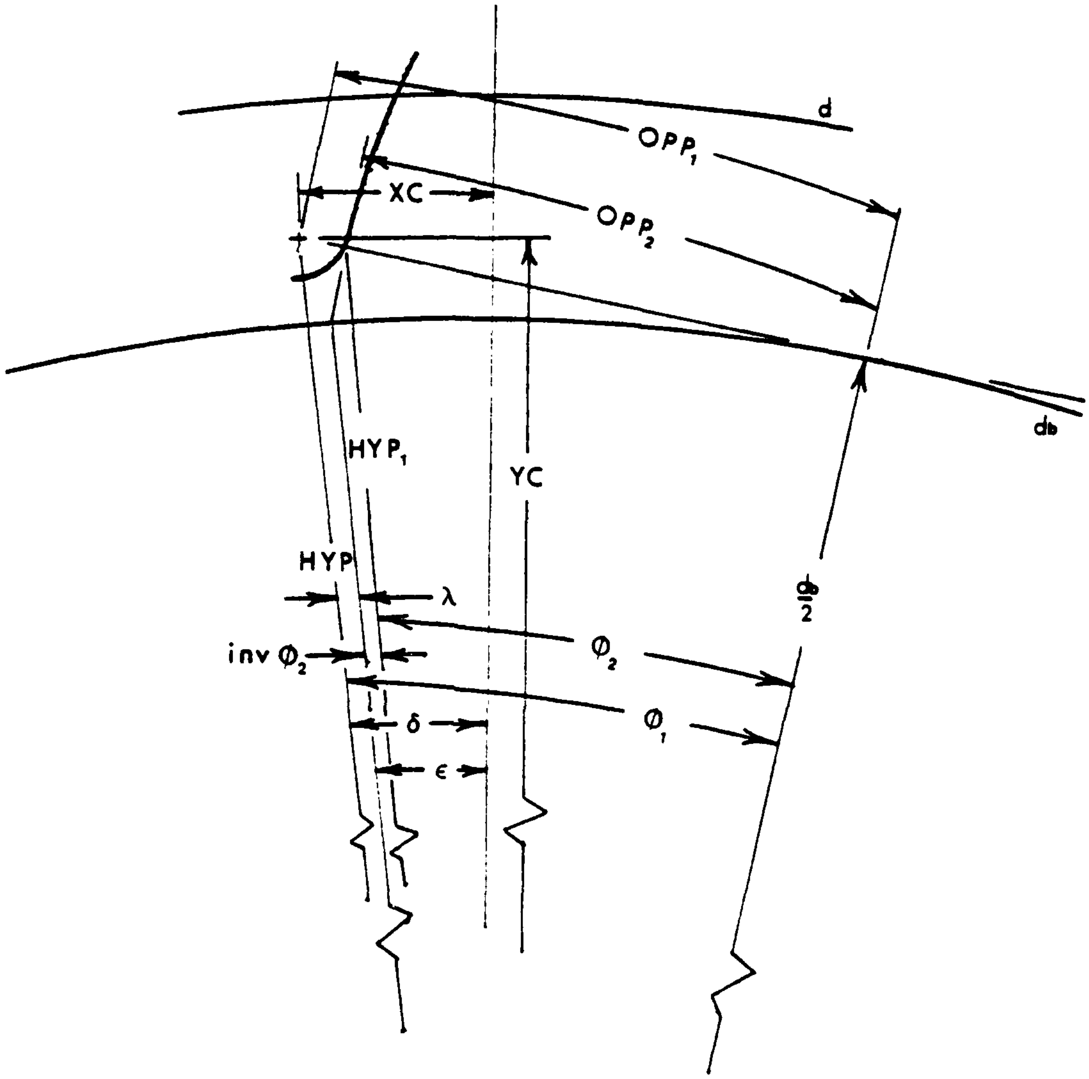


Figure 9: Fillet Center Location - Outside Base Circle

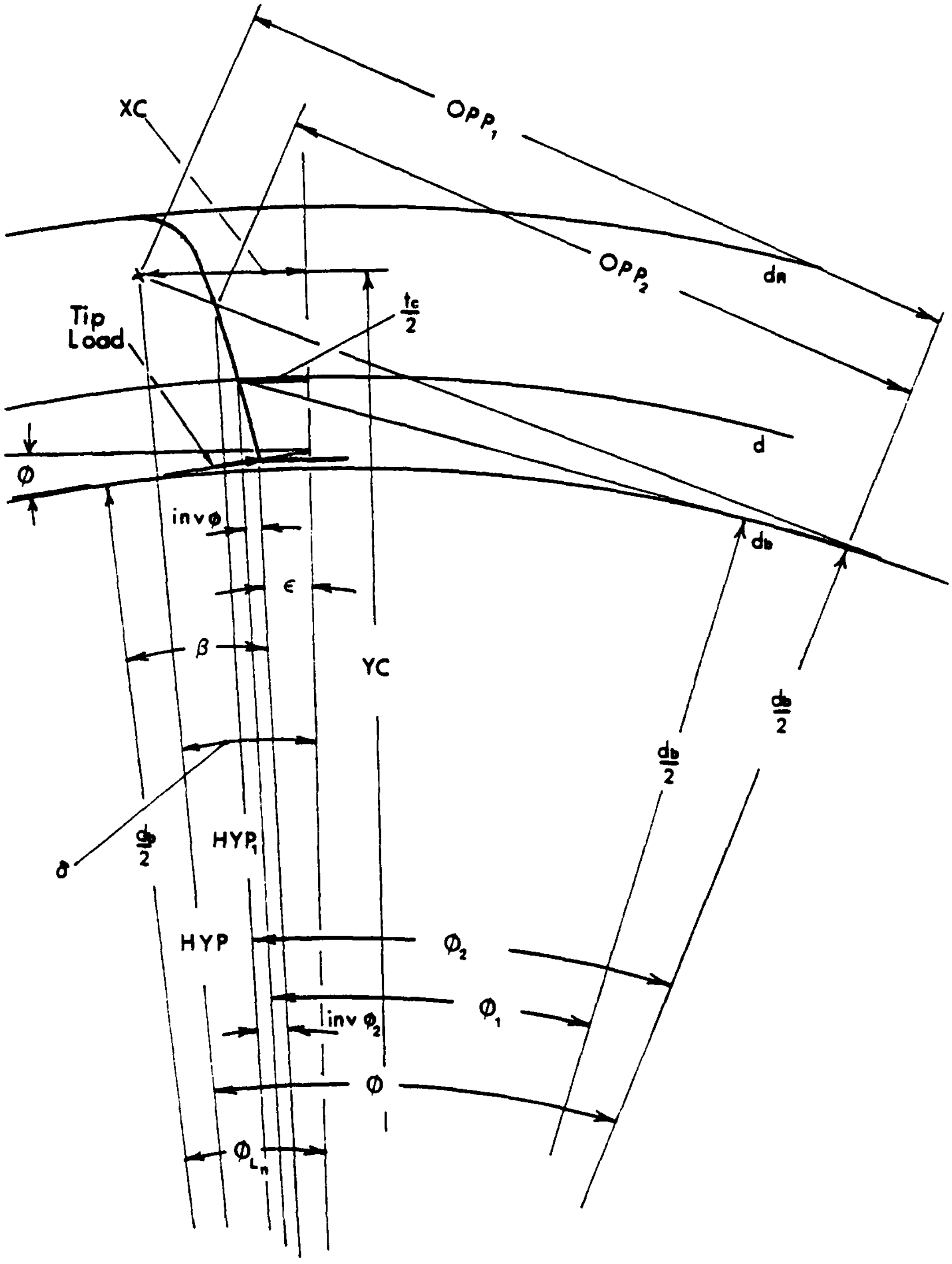


Figure 10: Internal Tooth Dimensions

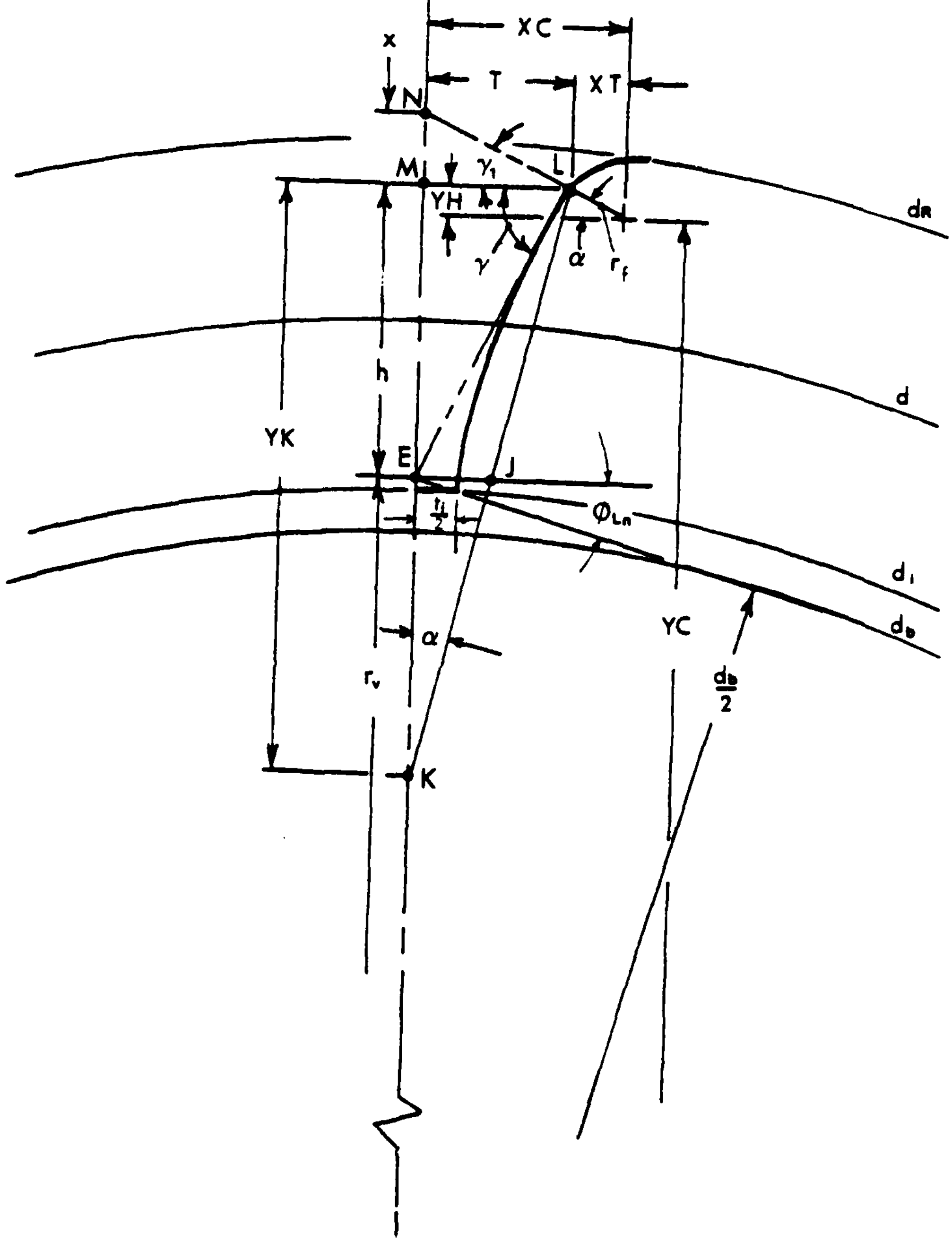


Figure 11: Internal Tooth Form Layout

LIST OF REFERENCES

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2. American Gear Manufacturers Association, AGMA Standard for Surface Durability (Pitting) of Helical and Herringbone Gear Teeth (AGMA 211.02), September, 1966.

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5. Thoma, F.A., Let's Up-Date Marine Gear Tooth Bending Stress Calculations, paper presented at the Mechanisms Conference & International Symposium on Gearing and Transmissions, San Francisco, California, 8-12 October 1972.

6. Forsythe, G.E., Malcolm, M.A., and Moler, C.B., Computer Methods for Mathematical Computations, p. 161-166, Prentice-Hall, Inc., 1977.

7. Dudley, D.W., ed., Gear Handbook, McGraw-Hill Book Company, Inc., 1962.

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