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SCALING CALCULATIONS FOR A RELATIVISTIC GYROTRON(U) 1/1
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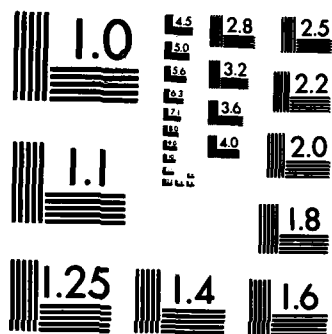
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Scaling Calculations for a Relativistic Gyrotron

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July 31, 1985

This work was supported by the Defense Nuclear Agency under Subtask X99QMXVF, work unit 00007 and work unit title "Gyrotron Development," also by the Lawrence Livermore National Laboratory and the Office of Naval Research.



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<p>The relativistic gyrotron is under development at NRL as an ultra-high power source of millimeter wave radiation. The purpose of the present study is to estimate the optimum operating characteristics of gyrotrons based on multi-kiloampere, mega-electron volt electron beams. Gyrotrons with weakly relativistic, moderate current electron beams have demonstrated very high efficiency and average power at millimeter wavelengths and the possibility of achieving good efficiencies at very high peak powers is of interest. Compared to other high power millimeter wave generators, gyrotrons are relatively insensitive to electron beam velocity spread and thus appear well suited to device configurations based on high current pulseline accelerators. The results of this study indicate that the relativistic gyrotron has potential for achieving high efficiency (15-30%) using relativistic electron beams with $\gamma \sim 2-3$. Optimum efficiency occurs for short interaction lengths; characterized by 4-8 cyclotron periods. Such short interaction lengths lead to the possibility of very high peak power generation using multi-kiloampere</p> <p style="text-align: right;">(Continues)</p>				
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19. ABSTRACT (Continued)

beams: 100-300 MW with a 600 keV beam and 51 GW with a 1 MeV beam. The output power risetime has been estimated to be a few nanoseconds for a low Q oscillator at 35 GHz which implies the gyrotron interaction can be readily investigated using a 20-100 nsec pulseline accelerator.

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SCALING CALCULATIONS FOR A RELATIVISTIC GYROTRON

I. Introduction:

The gyrotron oscillator is under development as a source of high power millimeter-wave radiation. Research in the U. S. to date has emphasized high average power devices based on thermionic cathode technology. Output powers up to a megawatt have been achieved by such devices which are based on high quality moderate voltage (≤ 100 keV) electron beams with currents of ≤ 50 Amps. High efficiencies $\sim 50\%$ have been demonstrated. Future directed energy applications of high power millimeter-wave radiation may require sources with peak power in the gigawatt range. It is therefore of interest to investigate the peak power potential of a relativistic gyrotron with a mega-electronvolt, multi-kilomampere electron beam. Such an electron beam can be generated for short pulse lengths (≤ 100 nsec) using a pulseline accelerator with a field emission (cold) cathode. An important objective of this work is to obtain design parameters for a cold cathode gyrotron experiment based on a 600 kV, 6kA, 55 nsec Febetron pulser. A second objective is to investigate scaling to higher voltage to increase output power.

Section 2 of this report describes scaling parameters and design constraints for a relativistic gyrotron. The results of calculations are given in Section 3. The non-linear, slow-time-scale equations of motion used for these calculations are derived in the Appendix.

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II. Gyrotron Scaling Theory and Design Constraints

This section describes scaling parameters and constraints for a relativistic gyrotron with a megavolt, multi-kiloampere electron beam. The configuration analyzed corresponds to a cylindrical resonator and a thin annular electron beam with the beam radius chosen to coincide with a maximum of the resonator electric field.

The gyrotron is a particular case of the Cyclotron Resonance Maser (CRM). The resonance condition is

$$\omega - k_{\parallel} v_{\parallel} - s\Omega/\gamma = 0 \quad (1)$$

where ω is the rf frequency, Ω is the non-relativistic cyclotron frequency, γ is the relativistic mass ratio, v_{\parallel} is the axial electron velocity, k_{\parallel} is the axial propagation number, and s is the harmonic number. In the gyrotron the electron beam interacts most effectively with a TE type mode which is close to cut-off in the resonator. Thus, the gyrotron corresponds to the case $k_{\parallel} v_{\parallel} \ll \omega \approx s\Omega/\gamma$. The present calculations consider only the fundamental harmonic interaction ($s=1$) as this yields the highest power and is least subject to mode competition.

The basic gyrotron interaction is characterized by five parameters: the e-beam relativistic factor γ , the e-beam pitch ratio $\alpha = v_{\perp}/v_{\parallel}$; the number of cyclotron orbits an electron makes traversing the resonator, N_c ; the applied axial magnetic field, B_0 ; and the amplitude of the rf electric field at the e-beam position, E_b . Gyrotron designs for high power are subject to constraints on the minimum resonator Q, the maximum electric fields at the cavity wall, the space-charge limit on beam current and requirements for stability of single mode operation. To optimize the gyrotron design for a given e-beam energy, characterized by γ_0 , and pitch ratio α , it is convenient to use the number of cyclotron orbits N_c as the scaling parameter. The applied magnetic field, B_0 , and the electric field amplitude at the e-beam are then varied to optimize the efficiency.

In terms of N_C , the interaction length is given by

$$L = \frac{2\pi}{\omega_C} v_{\parallel 0} N_C = (N_C + 1) \lambda \beta_{\parallel 0} \quad (2)$$

where Eq. (5) below has been used and

$$\beta_{\parallel 0} = \left[\frac{1 - 1/\gamma_0^2}{1 + \alpha^2} \right] \quad (3)$$

is the normalized axial velocity, ω_C is the relativistic cyclotron frequency ($\omega_C = \Omega/\gamma_0$), and $\lambda = \frac{c}{f}$ is the free-space wavelength. The rf fields in a cylindrical cavity can be expressed in terms of the axial profile function $h(z)$. The profile function depends on several factors including the interaction itself; however, a reasonable approximation for scaling calculations is to assume a sinusoidal profile:

$$h(z) = \sin k_{\parallel} z \quad (4)$$

where $k_{\parallel} = \pi/L$. The interaction efficiency is optimized when the cyclotron frequency is detuned from the resonance frequency by approximately the interaction bandwidth, i.e.,

$$\omega - \omega_C \approx \frac{\omega_C}{N_C} \quad (5)$$

Thus a good estimate for the optimum magnetic field is given by

$$B_0 = \frac{m}{|e|} \frac{\gamma_0 \omega}{1 + 1/N_C} \quad (6)$$

which was used in these calculations. This leaves the electric field amplitude E_b as the only optimization parameter.

Estimates for the electronic efficiency were obtained by integrating a set of equations of motion for an electron in the cavity and averaging over the initial phase of the electron entering the cavity. A tractable set of non-linear equations based on a slow-time-scale formulation developed previously was used. For this application, the equations derived in reference 1 for a TE circular waveguide mode have been generalized to include the interaction with the rf magnetic field component, which is important at relativistic e-beam energies. A derivation of the equations of motion is given in the Appendix. Electron beam self-field effects and thermal effects are neglected.

As shown in the Appendix, the slow-time-scale equations of motion for a gyrotron interacting at the sth harmonic with a TE circular waveguide mode which is close to cutoff can be written in the form:

$$\frac{du_t}{d\zeta} = -\frac{1}{2} \frac{\gamma}{u_z} \left[J_{s-1} \left(\frac{u_t}{\bar{\Omega}_{z0}} \right) - J_{s+1} \left(\frac{u_t}{\bar{\Omega}_{z0}} \right) \right] \operatorname{Re} \left\{ \bar{E}_s \left(h - \frac{i u_z}{\gamma \bar{\omega}} \frac{dh}{d\zeta} \right) e^{is\Lambda} \right\} + \frac{u_t}{2\bar{\Omega}_{z0}} \frac{d\bar{\Omega}_{z0}}{d\zeta} \quad (7a)$$

$$\frac{d\Lambda}{d\zeta} = -\frac{1}{2} \frac{\gamma}{u_z u_t} \left[J_{s-1} \left(\frac{u_t}{\bar{\Omega}_{z0}} \right) + J_{s+1} \left(\frac{u_t}{\bar{\Omega}_{z0}} \right) \right]$$

$$\operatorname{Re} \left\{ \bar{E}_s \left[i \left(h - \frac{i u_z}{\gamma \bar{\omega}} \frac{dh}{d\zeta} \right) - \frac{u_t^2}{\gamma \bar{\omega}} \frac{h}{\bar{\Omega}_{z0}} \right] e^{is\Lambda} \right\} + \frac{\gamma}{u_z} \left(\frac{\bar{\omega}}{s} - \frac{\bar{\Omega}_{z0}}{\gamma} \right) \quad (7b)$$

$$\frac{du_z}{d\zeta} = -\frac{1}{2} \frac{1}{\bar{\omega}} \frac{u_t}{u_z} \left[J_{s-1} \left(\frac{u_t}{\bar{\Omega}_{z0}} \right) - J_{s+1} \left(\frac{u_t}{\bar{\Omega}_{z0}} \right) \right] \operatorname{Re} \left\{ \bar{E}_s \frac{dh}{d\zeta} e^{is\Lambda} \right\} - \frac{u_t}{u_z} \frac{1}{\bar{\Omega}_{z0}} \frac{d\bar{\Omega}_{z0}}{d\zeta} \quad (7c)$$

In Equations (7) u_t and Λ are slow-time-scale variables for the magnitude and phase of the transverse momentum, and u_z is the axial momentum. ζ is the axial coordinate and γ is the relativistic factor ($\gamma^2 = 1 + u_t^2 + u_z^2$). E_s is the effective electric field at the beam and h is the normalized axial profile function of the electromagnetic mode $\{f = |f_{\max}| h(z)\}$. J_{s-1} is a regular Bessel function.

$\bar{\omega}$ is the normalized wave frequency and $\bar{\Omega}_{z0}$ is the nonrelativistic cyclotron frequency due to the applied axial magnetic field. Equations (7) use the following normalization scheme:

(i) the radial coordinate is normalized to r_{w0} ($\bar{r} = r/r_{w0}$), and the axial coordinate is normalized to r_{w0}/x_{mn} ($\bar{z} = z x_{mn}/r_{w0}$), where x_{mn} is the n th zero of dJ_m/dx ;

(ii) frequencies are normalized to $c/(x_{mn} r_{w0})$ ($\bar{\omega} = \frac{\omega r_{w0}}{c x_{mn}}$);

(iii) velocities are normalized to c and momenta are normalized to $m_0 c$ ($\bar{v} = v/c, u = p/m_0 c$);

(iv) electric and magnetic fields are normalized to $\frac{m_0 c^2}{|e|} \frac{x_{mn}}{r_{w0}}$ and

$\frac{m_0 c}{|e|} \frac{x_{mn}}{r_{w0}}$, respectively ($\bar{E} = \frac{|e|}{m_n c^2} \frac{r_{w0}}{x_{mn}} E, \bar{B} = \frac{|e|}{m_0 c} \frac{r_{w0}}{x_{mn}} B$). Unnormalized

quantities are expressed in mks units unless otherwise stated.

In obtaining Equations (7), the radial scale length r_{w0} is assumed to be equal to the waveguide radius and the axial dependence of the waveguide radius has been neglected except in calculating the axial profile function f .

Equations (7) are independent of the wave frequency. Moreover, geometric factors associated with a particular waveguide mode and the position of the electron beam are contained in the factor E_s .

For a circularly polarized mode with azimuthal dependence $e^{-im\theta}$ (and time dependence $e^{i\omega t}$) E_s is given by

$$\bar{E}_s = C_{mn}^{(c)} \frac{J_{m-s}}{\bar{r}_w} (\bar{k}_{mn} \bar{R}_0) |\bar{r}_{max}| e^{-im\theta} \quad (8)$$

and by

$$E_s = C_{mn}^{(c)} (-1)^s \frac{J_{m+s}(\bar{k}_{mn} \bar{R}_0)}{\bar{r}_w} |f_{\max}| e^{im\Xi_0} \quad (9)$$

for a mode with dependence $e^{+im\theta}$. In Equations (8) and (9) \bar{r}_w is the normalized waveguide radius; \bar{R}_0, Ξ_0 are the polar coordinates of the electron orbit guiding center orbit and

$$C_{mn}^{(c)} = \left[\left[\pi (x_{mn}^2 - m^2) \right]^{1/2} J_m(x_{mn}) \right]^{-1} \quad (10)$$

The profile function f has dimensions of voltage and is normalized according to

$$\bar{f} = \frac{|e|}{m_0 c^2} f. \quad \text{The transverse wave number } \bar{k}_{mn} = x_{mn} / \bar{r}_w.$$

For a linearly polarized mode with azimuthal dependence $\cos m\theta$

$$E_s = C_{mn}^{(l)} \left[\frac{J_{m-s}(\bar{k}_{mn} \bar{R}_0)}{\bar{r}_w} e^{-im\Xi_0} + (-1)^s \frac{J_{m+s}(\bar{k}_{mn} \bar{R}_0)}{\bar{r}_w} e^{im\Xi_0} \right] |f_{\max}| \quad (11)$$

where

$$C_{mn}^{(l)} = \sqrt{2} \left[\left[\pi (x_{mn}^2 - m^2) \right]^{1/2} J_m(x_{mn}) \right]^{-1} \quad (12)$$

The output power is related to the cavity fields according to

$$P_\omega = \frac{\omega W}{Q} \quad (13)$$

where the stored electromagnetic energy

$$W = \frac{\epsilon_0}{2} |f_{\max}|^2 \int dz |h(z)|^2 \quad (14)$$

and Q is the diffraction Q of the cavity. Substituting Eq. (14) into Eq. (13) and transforming to normalized parameters leads to

$$P_{\omega} = \frac{1}{2} \frac{c^3}{\mu_0} \left(\frac{m_0}{e} \right)^2 \frac{\omega}{Q} |\tilde{r}_{\max}|^2 \int dz |h(z)|^2 \quad (15)$$

where c is the speed of light and $\mu_0 = 4\pi \times 10^{-7}$. Eq. (15) shows that the output power is independent of frequency. The electronic efficiency is calculated by integrating Eqs. (7) through the interaction region to obtain the change in electron energy and averaging with respect to the initial momentum phase:

$$\eta = \left[\frac{1}{2\pi} \int_0^{2\pi} d\Lambda_0 [\gamma(z_F, \Lambda_0) - \gamma_0] \right] / (\gamma - 1) \quad (16)$$

For a linearly polarized mode the efficiency must also be averaged with respect to the guiding center angle Ξ_0 . The electron beam power or current are found from the power balance equation:

$$P_b = I_0 V_0 = \frac{P}{\eta} \quad (17)$$

The threshold current for oscillation is given by the small signal limit

$$I_{th} = \lim_{E_s \rightarrow 0} \frac{P_{\omega}(E_s)}{V_0 \eta(E_s)} \quad (18)$$

Calculations of gyrotron efficiency generally assume a circularly polarized rf mode because in this case the interaction efficiency is the same for all beam electrons. When the rf mode is linearly polarized the rf fields have an azimuthal dependence given by $\sin m\theta$ or $\cos m\theta$ and consequently the electronic efficiency varies

with azimuthal angle. As shown in Section 3, the result is a reduction in the optimum efficiency averaged over the beam by a factor of approximately 0.7 compared to a circularly polarized mode. Linear mode polarization is nevertheless of particular interest for relativistic gyrotrons as this polarization occurs when axial slots are used to control mode competition.

In these calculations, a value of twice the diffraction limited θ was assumed. The diffraction limited θ is given by

$$\theta_D = 4\pi \left(\frac{L}{\lambda}\right)^2 = 4\pi(N_C + 1)^2 a_{10}^2 \quad (19)$$

In gyrotrons the space-charge limited electron beam current places a significant restriction on the achievable output power. An estimate for a thin annular gyro-beam has been derived by Ganguly and Chu². Their result for the space-charge limited current is

$$I_{SCL} (\text{kA}) = \frac{8.5 \gamma_0}{\ln(r_w/r_G)} [1 - (1 - a_{10}^2)^{1/3}]^{3/2} \quad (20)$$

where r_w is the cavity wall radius and r_G is the e-beam radius.

III. Results of Calculations

This section presents scaling calculations for the relativistic gyrotron. To show the efficiency potential of the relativistic regime and to calibrate the present calculations, Figure 1 compares efficiencies calculated for 70 keV and 1 MeV electron beams with $\alpha = v_{\perp}/v_{\parallel} = 1.5$ interacting with a circularly polarized TE mode. One notes that the peak efficiency of 30% at 1 MeV is only slightly less than the peak efficiency of 34% at 70 keV. However, there is an order of magnitude difference in the optimum number of cyclotron orbits: peak efficiency at 1 MeV occurs for $N_c = 3-5$ whereas peak efficiency at 70 keV occurs for $N_c = 15-30$. This result is consistent with the gyrotron efficiency scaling relation

$$\eta \sim \frac{1}{N_c(\gamma_0 - 1)} \quad (21)$$

derived by Bratman et al³. The efficiency results for 70 keV are in good agreement with the results of Chu et al⁴. The latter are also shown in Figure 1.

Although the intrinsic efficiency has only a gradual decrease with increase in beam energy other factors limit efficiency at relativistic energies: The efficiency is a sensitive function of the ratio v_{\perp}/v_{\parallel} since as shown by Bratman et al³

$\eta \propto \beta_{10}^2$. Due to lack of experience in the design of high voltage beam formation systems - particularly cold cathode systems - lower values of v_{\perp}/v_{\parallel} can be expected, at least initially. As discussed above, the use of a linearly polarized rf mode also reduces efficiency. Figure 2 shows efficiency as a function of N_c for a 600 keV e-beam for $\alpha = 1.0$ and 1.5 and for linear and circular polarization. For a linearly polarized mode and $\alpha = 1.0 - 1.5$ the peak efficiency is 15% - 22% compared to 21% - 31% for a circularly polarized mode. Similar results for a 1 MeV beam are shown in Figure 3. Effects due to electron beam thermal and self-field effects have not been included. These effects may be significant in a high power, relativistic gyrotron and are under investigation.

Figure 4 shows the optimum electric field vs. N_c both at the electron beam position and at the cavity wall for a linearly polarized mode and a 500 keV beam with $\alpha = 1.5$. The electric field corresponds to the case of a TE_{14} mode with the electron beam placed at the fourth E-field maximum ($r_G/r_w = 0.86$). The curves shown in Figure 4 indicate that the peak cavity field at the wall is reduced an order of magnitude from the field at the beam. Thus peak fields at the beam of ≥ 1 MV/cm, which are needed for high power and peak efficiency, can be achieved with low probability of field induced emission from the cavity wall.

Figure 5 shows the electron beam current corresponding to optimum efficiency as a function of N_c for a 600 keV beam. The cavity Q is assumed to be twice the diffraction limited Q and the beam is placed on the fourth E-field maximum. Results are shown for the TE_{14} mode with $\alpha = 1.0$ and 1.5, and for the TE_{15} mode with $\alpha = 1.0$. Linear polarization is assumed in all cases. The estimated space-charge limiting currents for these configurations are: 2.9 kA for the TE_{15} mode with $\alpha = 1.0$, 3.5 kA for the TE_{14} mode with $\alpha = 1.5$ and 7.4 kA for the TE_{14} mode with $\alpha = 1.0$.

Output power scaling at optimum efficiency for a 600 keV beam is shown in Figure 6. The choices for Q and beam position are the same as in Figure 5. The maximum rf power is limited by the dc space charge effect for the TE_{14} mode, $\alpha = 1.5$ and TE_{15} mode, $\alpha = 1.0$ cases. The maximum power for the TE_{14} , $\alpha = 1.0$ case is limited by the available e-beam current of 6 kA corresponding to a Febetron pulser. Figure 7 compares output power scaling for 1 MeV and 0.6 MeV e-beams. The curves correspond to a TE_{14} linearly polarized mode with $\alpha = 1.5$, the beam on the 4th E-field peak, and $Q = 20Q_0$. The 1 MeV curve reaches a peak power of about 1 GW. The dashed curve indicates that higher powers are possible if partial space-charge neutralization proves feasible.

The present analysis has emphasized the high power regime. The interaction region is very short involving only a few cyclotron orbits, and non-linear effects are strong. In this regime the output power is ultimately limited by the condition that the operating e-beam current be greater than the oscillation threshold current. Figure 8 compares the threshold and optimum efficiency currents for a 600 keV beam with $\alpha = 1.5$ placed on the fourth peak of a TE_{14} mode. The optimum efficiency currents are shown for both linear and circular polarization; the former being 10% - 15% larger than the latter. Both polarizations have the same threshold current. Except at short interaction lengths of less than 3 cyclotron orbits, the optimum efficiency current is approximately twice the threshold current. The same behavior is found for a 1 MeV beam.

In the case of short pulse operation it is necessary to consider the output power risetime. The 10% - 90% power risetime is approximately

$$\tau \approx \frac{2n}{\omega} \left[\frac{I}{I_{thr}} - 1 \right]^{-1} \quad (22)$$

where I is the beam current and I_{thr} is the threshold current.

This expression does not include the effect of finite e-beam risetime.

Figure 9 shows power risetime scaling vs. N_c for 0.6 MeV and 1 MeV beams with $\alpha = 1.5$, $\theta = 20^\circ$. The minimum risetime for a 35 GHz oscillator is shown to be about one nanosecond.

IV. Conclusions

The results of this study indicate that the relativistic gyrotron has potential for achieving high efficiency (15-30%) using relativistic ($\gamma \sim 2-3$) electron beams. Optimum efficiency occurs for short interaction lengths characterized by 4-8 cyclotron periods. Such short interaction lengths lead to the possibility of very high peak power generation using multi-kiloampere beams: 100-300 MW for a 600 keV beam and ~ 1 GW with a 1 MeV beam. These power levels apply to the case of single mode operation in a linearly polarized TE_{14} mode.

The optimum interaction efficiency occurs for electric fields ~ 1 MV/cm at the electron beam. Since the gyrotron is based on a fast-wave interaction, such fields at the beam can be achieved without excessive electric fields at the wall. For example, for a 600 keV beam and a TE_{14} mode the peak field at the wall is ~ 100 kV/cm.

The output power rise time has been estimated to be a few nanoseconds for a low Q oscillator at 35 GHz. Thus the gyrotron interaction can be readily investigated using a 20-100 nsec pulseline accelerator.

The electron beam dc space-charge effect appears to be a significant factor limiting gyrotron power. The possibility of space-charge neutralization via a background plasma should be investigated.

V. Acknowledgments

Many helpful and stimulating discussions with Drs. Ganguly, Manheimer, Read, Gold, Dialetis, and Granatstein are gratefully acknowledged. This work was supported by the Defense Nuclear Agency, Lawrence Livermore National Laboratory and the Office of Naval Research.

GYROTRON EFFICIENCY SCALING

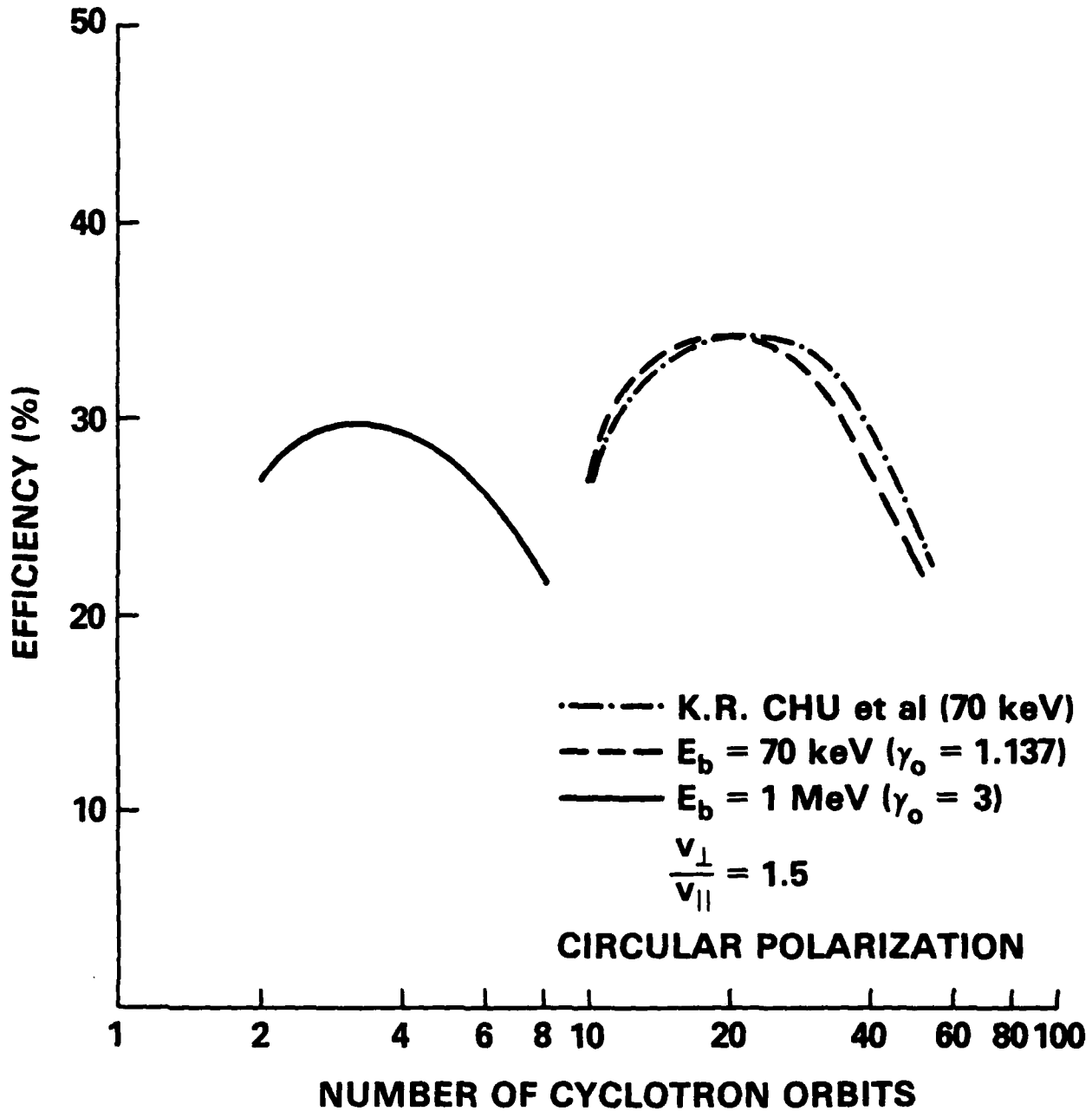


Fig. 1: Optimized Electronic Efficiency as a Function of Interaction Length for a Circularly Polarized TE Mode

OPTIMUM EFFICIENCY vs. NUMBER OF CYCLOTRON ORBITS

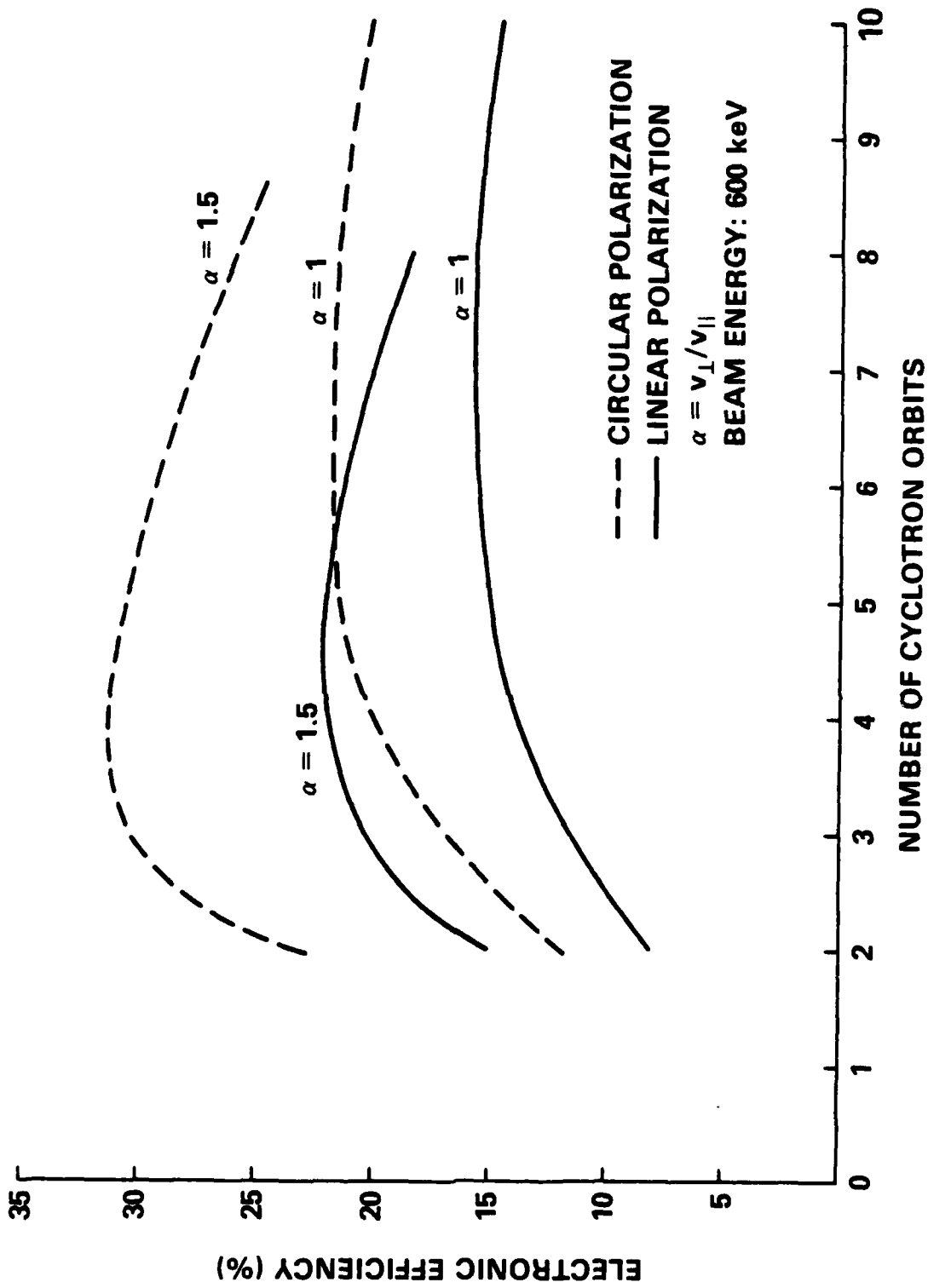


Fig. 2: Optimized Electronic Efficiency for a 600 keV Electron Beam

OPTIMUM EFFICIENCY SCALING

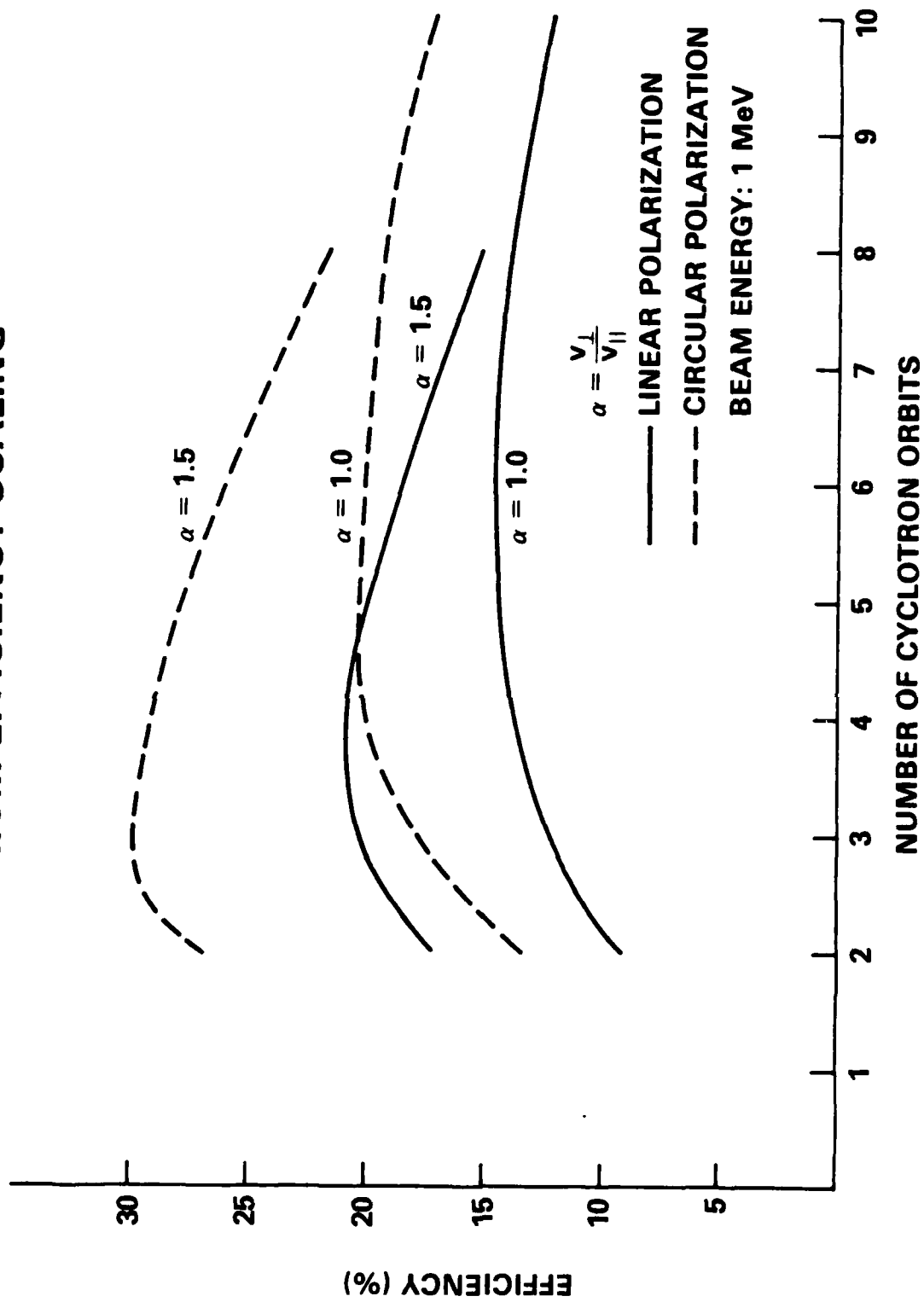


Fig. 3: Optimized Electronic Efficiency for a 1 MeV Electron Beam

OPTIMUM ELECTRIC FIELD

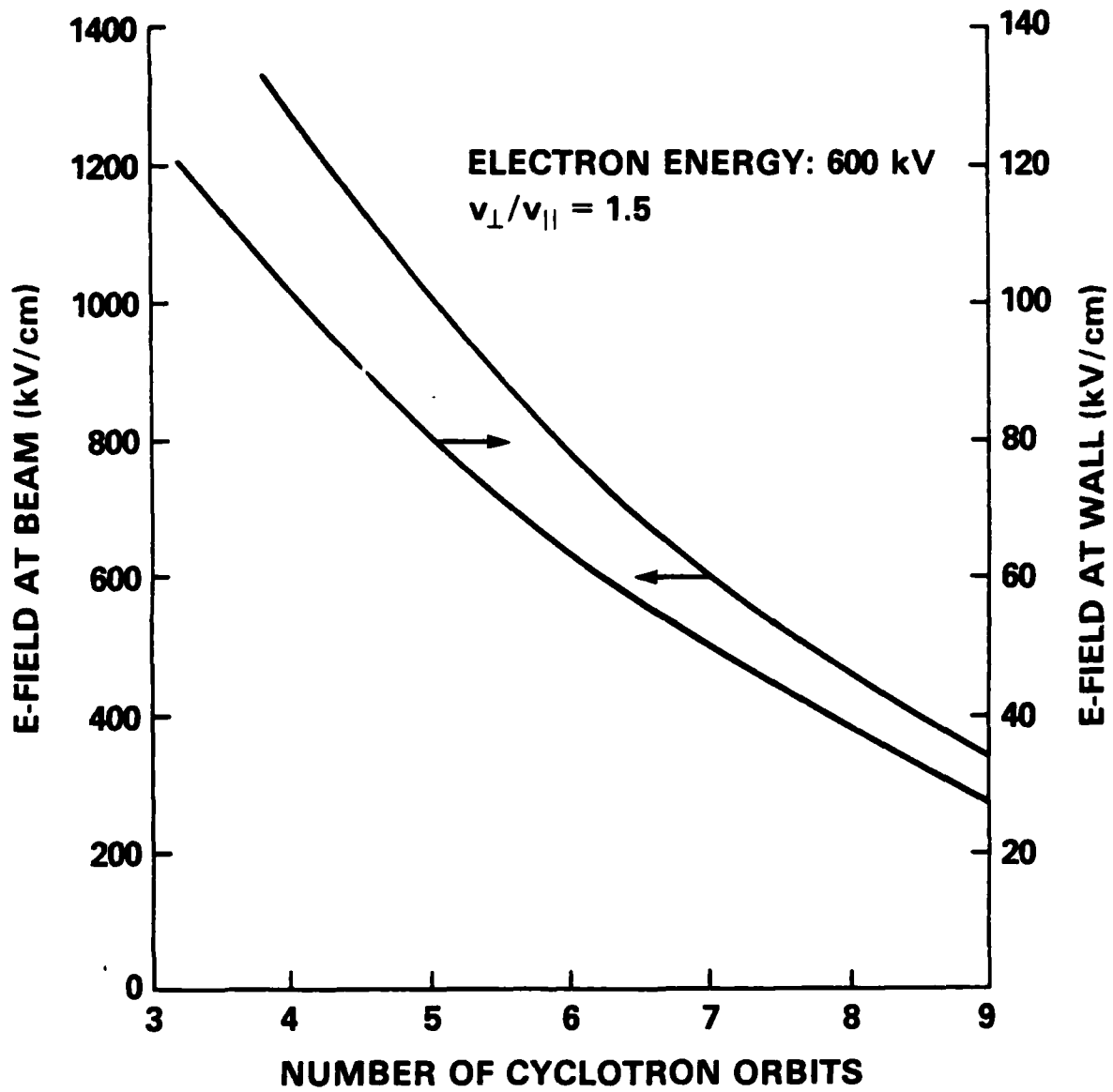


Fig. 4: Optimum Value of the Peak Electric Field at the Electron Beam and at the Cavity Wall for a Linearly Polarized TE_{14} Mode at 35 GHz

BEAM CURRENT AT OPTIMUM EFFICIENCY

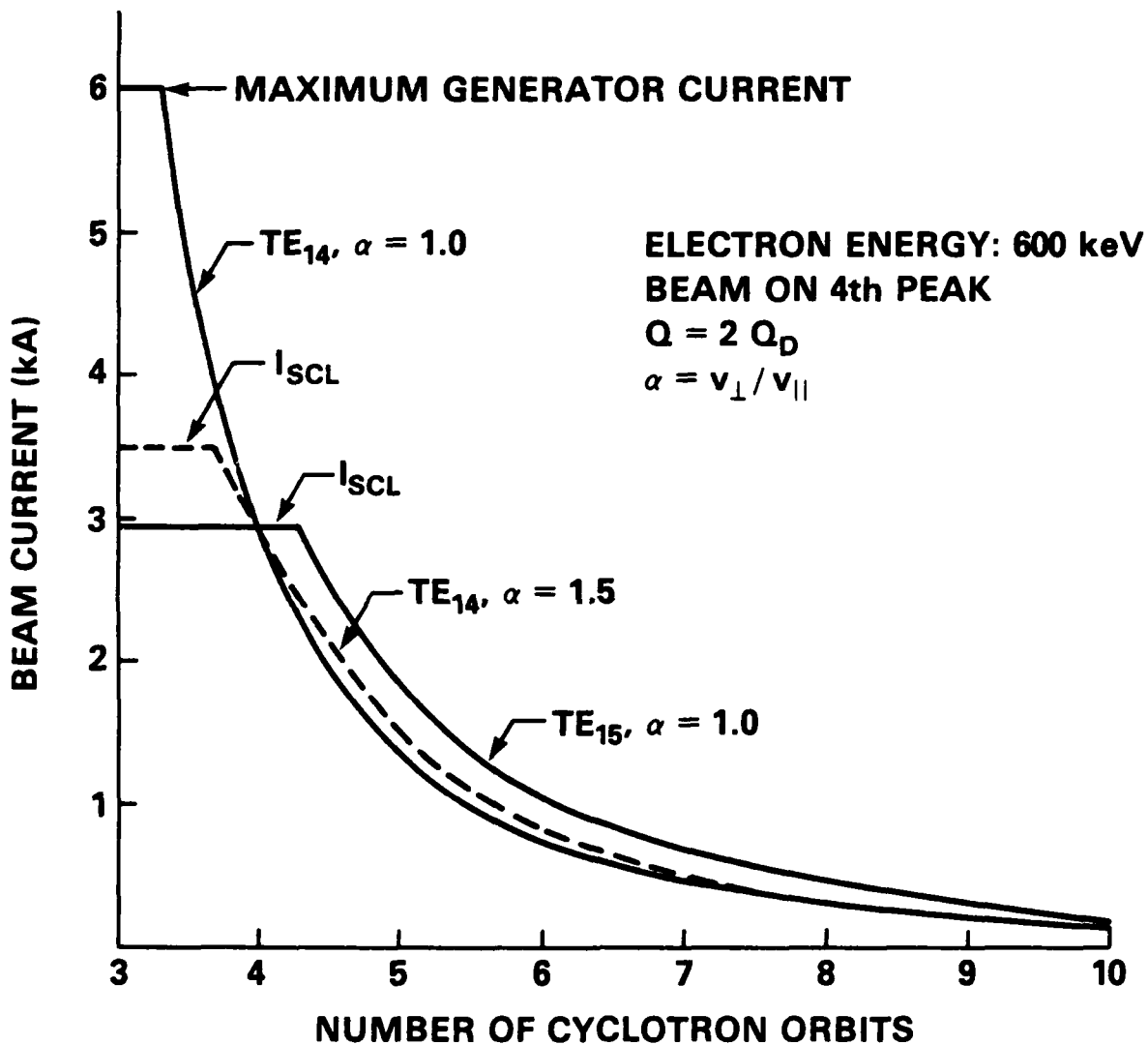


Fig. 5: Electron Beam Current Corresponding to Optimum Efficiency for $Q=2Q_D$ and Linear Polarization. I_{SCL} Denotes the Space-Charge Limited Current. Maximum Generator Current Refers to the NRL 600 kV, 6 kA Febetron Pulser

OUTPUT POWER SCALING

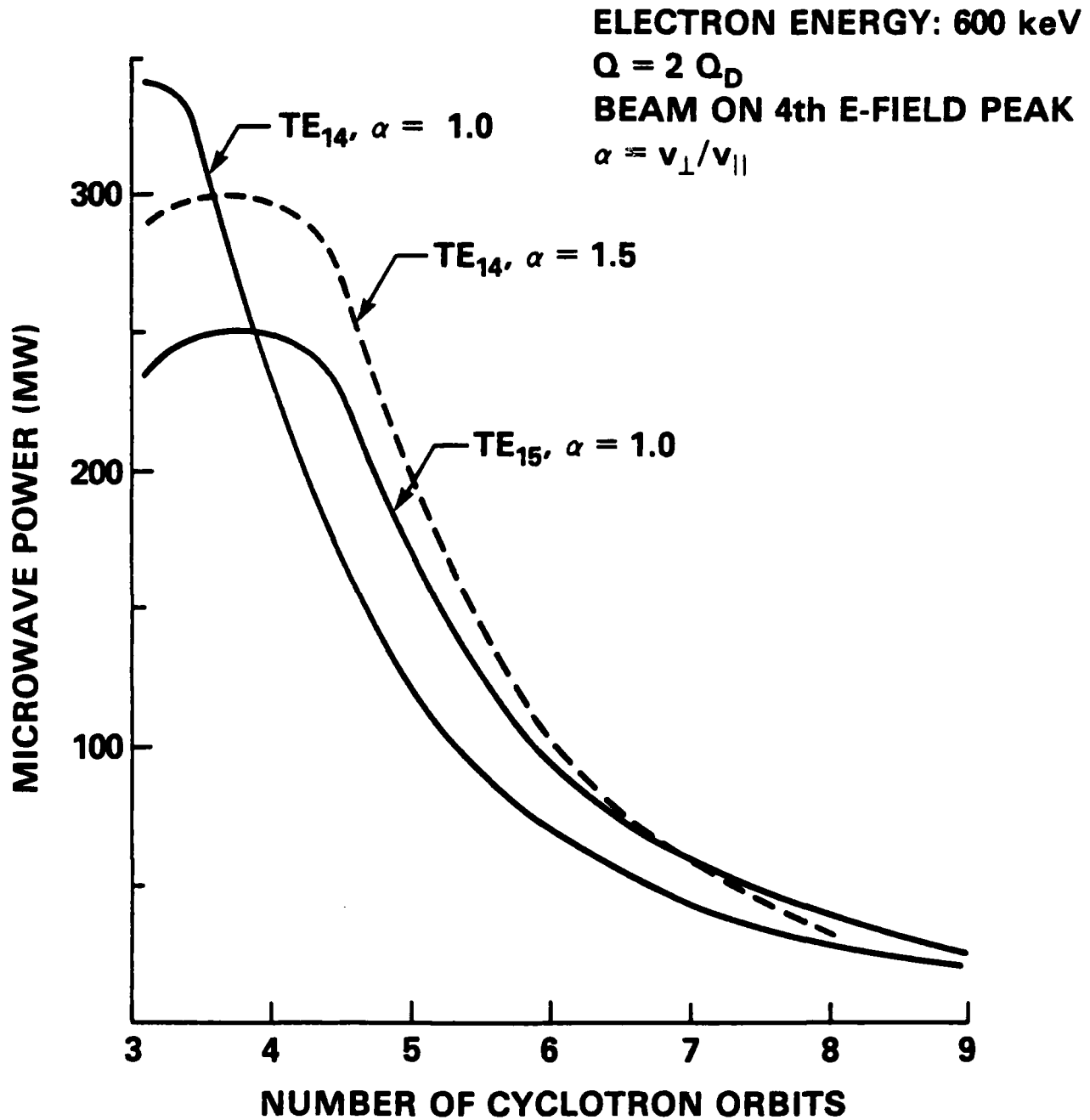


Fig. 6: Output Power Corresponding to Optimum Efficiency Operation for $Q=2Q_D$ and Linear Polarization.

OUTPUT POWER SCALING

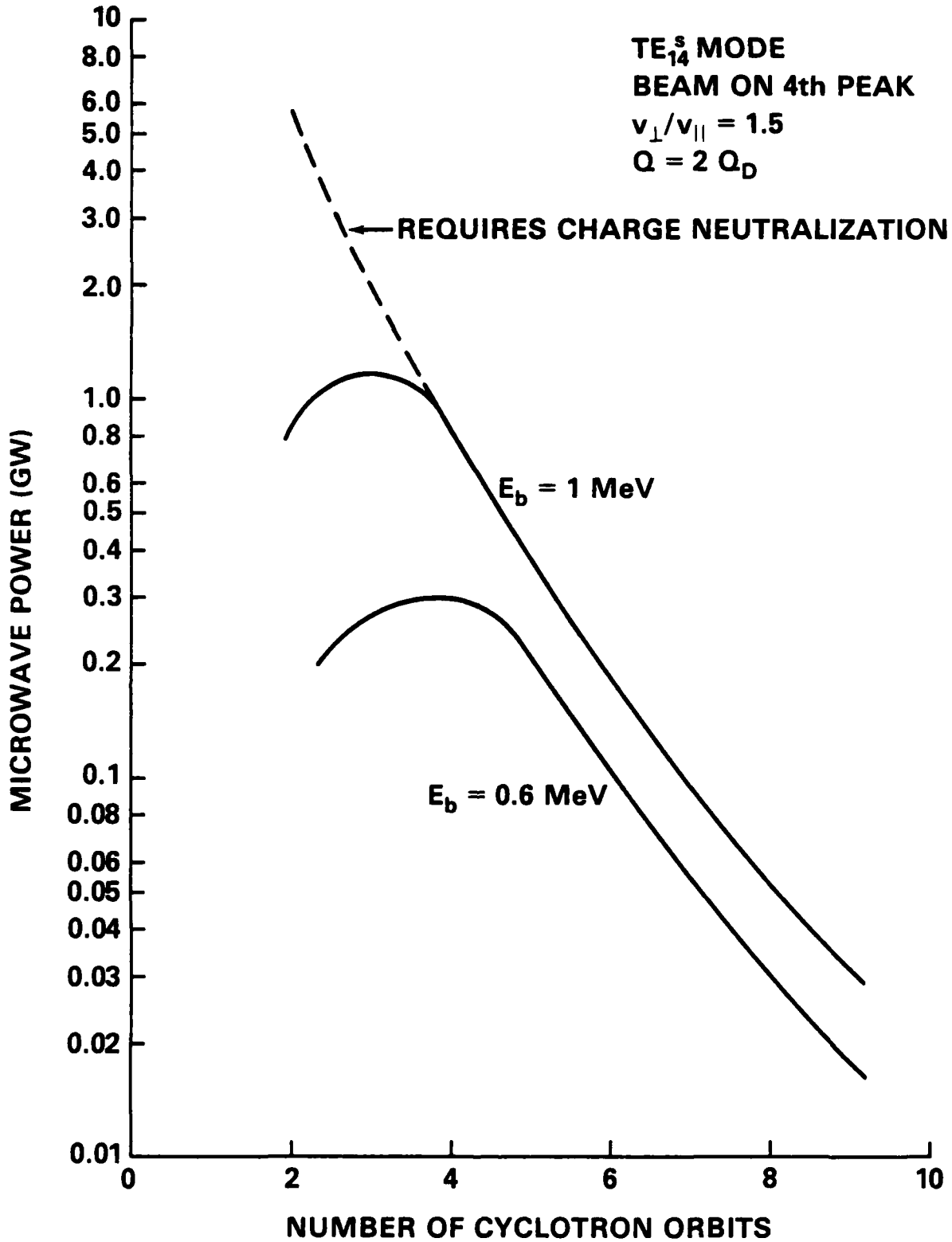


Fig. 7: Output Power for Optimum Efficiency Operation for $Q=2Q_D$ and Linear Polarization. The Dashed Curve Corresponds to Beam Currents Exceeding the Space-Charge Limit and thus not Normally Achievable

THRESHOLD AND OPTIMUM EFFICIENCY ELECTRON BEAM CURRENTS

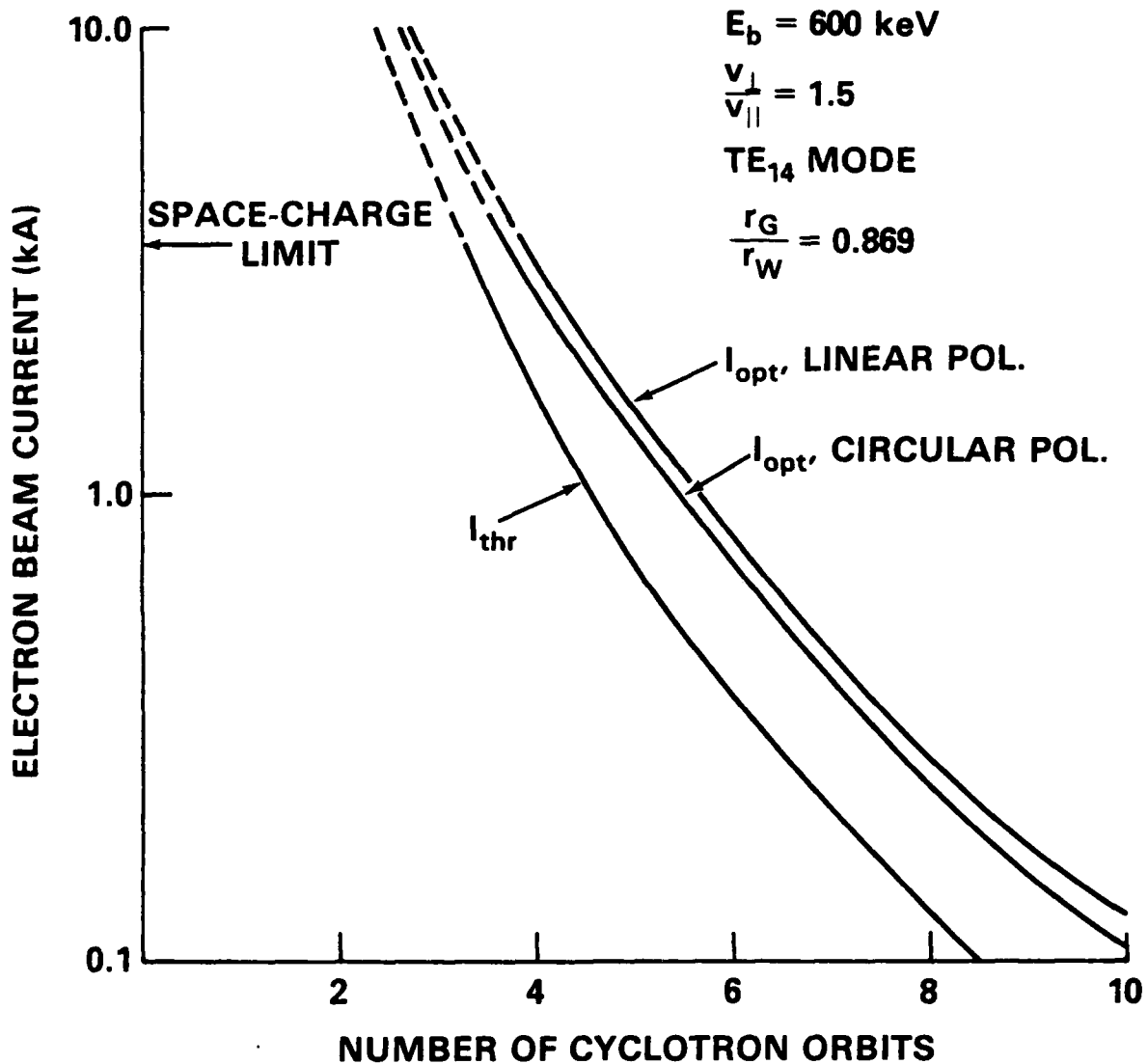


Fig. 8: Comparison of Threshold Beam Current and Current at Optimum Efficiency for Circular and Linear Polarization and $Q=2Q_D$. The Threshold Current is the same for both Polarizations.

GYROTRON RISETIME

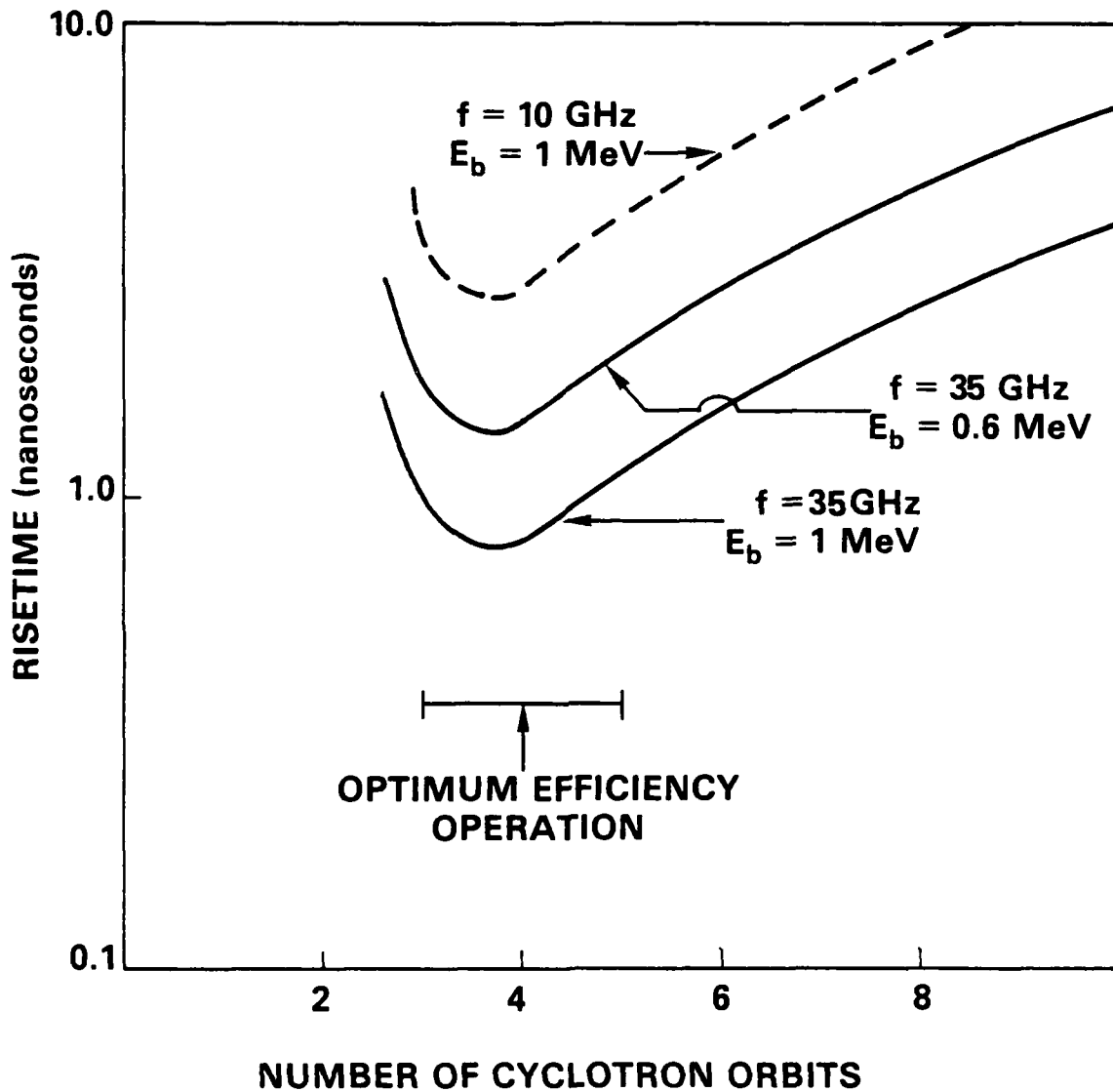


Fig. 9: 10% - 90% Output Power Risetime for a Gyrotron Operating at Optimum Efficiency with $Q=2Q_D$ and $V_{\perp}/V_{\parallel} = 1.5$

Appendix

1. Single-Particle Slow-Time-scale Equations of motion

The starting point is the Lorentz force equation

$$\frac{d}{dt} (\gamma \vec{v}) + \eta (\vec{v} \times \vec{B}_0) = -\eta (\vec{E} + \vec{v} \times \vec{B}) = \vec{a} \quad (1)$$

where \vec{B}_0 is an applied static magnetic field which is predominantly axial

$$\vec{B}_0 = B_{0z} \hat{z} + B_{0r} \hat{r}, \quad B_{0z} \gg B_{0r}, \quad (2)$$

$$\eta = \frac{|e|}{m_0} \quad (3)$$

is the charge to rest mass ratio for an electron, and \vec{E} , \vec{B} are the electromagnetic fields. It is convenient to introduce the normalized momentum variable

$$\vec{u} = \gamma \vec{v} \quad (4)$$

in terms of which the relativistic factor is given by

$$\gamma = [1 + u^2/c^2]^{1/2} \quad (5)$$

To obtain a slow-time-scale formulation the transverse momentum is expressed in the form:

$$u_x + i u_y = i u_t \exp [i (\Omega \tau + \phi)] \quad (6)$$

where

$$\Omega = \frac{\eta B_o}{\gamma_o} = \frac{\eta B_{oz}(z=0)}{\gamma_o} = \frac{\Omega_{zo}}{\gamma_o} \quad (7)$$

and $\tau = t - t_o$ where t_o is the time the electron enters the interaction region.

Using the transformation (6) in Eq. (1) leads to the following equations:

$$\dot{u}_t = \frac{i}{2} [(a_x - i a_y) e^{i(\Omega\tau+\phi)} - (a_x + i a_y) e^{-i(\Omega\tau+\phi)}] + \frac{u_z u_z}{2\gamma} \frac{1}{B} \frac{\partial B}{\partial z} \quad (8.1)$$

$$\dot{\phi} = \frac{-1}{2} \frac{1}{u_t} [(a_x - i a_y) e^{i(\Omega\tau+\phi)} + (a_x + i a_y) e^{-i(\Omega\tau+\phi)}] - \Omega + \frac{\Omega}{\gamma} \quad (8.2)$$

$$\dot{u}_z = a_z - \frac{1}{2} \frac{1}{B} \frac{\partial B}{\partial z} \frac{u_t^2}{\gamma} \quad (8.3)$$

Equations 8.1-8.3 account for electron interactions with all rf-field components and allow for a tapered applied magnetic field.

2. Transverse Electromagnetic modes in a waveguide

In the present theory, the electron beam is assumed to interact with a single TE or TM vacuum waveguide mode with time dependence $e^{i\omega t}$. The transverse field components are given by:

$$\vec{E}_t = \text{Re} \{ f(z) \vec{e}(x, y, z) e^{i\omega t} \} \quad (9.1)$$

$$\vec{B}_t = \text{Re} \{ g(z) \vec{h}(x, y, z) e^{i\omega t} \} \quad (9.2)$$

where \vec{e} and \vec{h} are transverse vector mode functions. These vector functions are related to scalar functions according to

$$\vec{e} = \hat{z} \times \vec{\nabla}_t \psi \quad (10.1)$$

$$\vec{h} = -\vec{\nabla}_t \psi \quad (10.2)$$

for TE modes, and

$$\vec{e} = -\vec{\nabla}_t \psi \quad (11.1)$$

$$\vec{h} = -\hat{z} \times \vec{\nabla}_t \psi \quad (11.2)$$

for TM modes, The scalar functions satisfy the equation

$$(\nabla_t^2 + k_1^2) \psi = 0 \quad (12)$$

and the boundary condition

$$\frac{\partial \psi}{\partial n} = 0 \quad (13.1)$$

on the waveguide boundary for TE modes, or

$$\psi = 0 \quad (13.2)$$

at the waveguide boundary for TM modes. In Eq. (13.1) $\partial/\partial n$ indicates the normal derivative. When integrated over the waveguide cross section the vector functions satisfy the normalization and orthogonality conditions

$$\int_{S(z)} dx dy \vec{v}_i \vec{v}_j = \delta_{ij} \quad (14)$$

($\delta_{ij} = 0$ if $i \neq j$, $\delta_{ij} = 1$ if $i = j$) where \vec{v}_i denotes either \vec{e}_i or \vec{h}_i and $S(z)$ denotes the z -dependent waveguide cross section. The axial field components are given by

$$B_z = \text{Re} \left\{ -i \frac{k^2}{\omega} f(z) \psi(x, y) e^{i\omega t} \right\} \quad (15)$$

for a TE mode, and by

$$E_z = \text{Re} \left\{ -i \frac{c^2}{\omega} k_{\perp}^2 g(z) \psi(x, y) e^{i\omega t} \right\} \quad (16)$$

for a TM mode. The axial profile functions $f(z)$ and $g(z)$ are related according to

$$g(z) = \frac{i}{\omega} \frac{df(z)}{dz} \quad (17)$$

for a TE mode, and

$$f(z) = i \frac{c^2}{\omega} \frac{dg(z)}{dz} \quad (18)$$

for a TM mode. Equations (15-18) are obtained by substitution into the Maxwell curl equation

$$\nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \quad (19)$$

3. Equations of motion for an electron interacting with a waveguide mode

Substituting Equation (9) - (16) into (8) leads to

$$\begin{aligned} \dot{u}_t = & \text{Re} \{ -n (f-v_z g) (L_+ \psi e^{-i(\Omega\tau+\phi)} + L_- \psi e^{i(\Omega\tau+\phi)}) e^{i\omega t} \} \\ & + \frac{u_z u_t}{2\gamma} \frac{1}{B_z} \frac{\partial R_z}{\partial z} \end{aligned} \quad (20.1)$$

$$\begin{aligned} \dot{\phi} = & \frac{1}{u_t} \text{Re} \left\{ \frac{i\eta}{2} [(f-v_z g) (L_+ \psi e^{-i(\Omega\tau+\phi)} - L_- \psi e^{i(\Omega\tau+\phi)}) \right. \\ & \left. - 2 \frac{v_t k_t^2}{\omega} f \psi] e^{i\omega t} \right\} - \Omega + \frac{\Omega_z}{\gamma} \end{aligned} \quad (20.2)$$

$$\begin{aligned} \dot{u}_z = & \text{Re} \left\{ -\frac{\eta v_t}{2} g (L_+ \psi e^{-i(\Omega\tau+\phi)} + L_- \psi e^{i(\Omega\tau+\phi)}) e^{i\omega t} \right\} \\ & - \frac{u_t^2}{2\gamma} \frac{1}{B_z} \frac{\partial R_z}{\partial z} \end{aligned} \quad (20.3)$$

for TE modes, and

$$\begin{aligned} \dot{u}_t = & \text{Re} \{ -in(f-v_z g) (L_+ \psi e^{-i(\Omega\tau+\phi)} - L_- \psi e^{i(\Omega\tau+\phi)}) e^{i\omega t} \} \\ & + \frac{u_z u_t}{2\gamma_z} \frac{1}{B_z} \frac{\partial R_z}{\partial z} \end{aligned} \quad (21.1)$$

$$\dot{\phi} = \frac{1}{u_t} \operatorname{Re} \left\{ -\frac{\eta}{2} (f - v_z g) (L_+ \psi e^{-i(\Omega\tau + \phi)} + L_- \psi e^{i(\Omega\tau + \phi)}) e^{i\omega t} - \Omega + \frac{\Omega z}{\gamma} \right\} \quad (21.1)$$

$$\begin{aligned} \dot{u}_z = \operatorname{Re} \left\{ -\frac{i\eta}{2} g \left[v_t (L_+ \psi e^{-i(\Omega\tau + \phi)} - L_- \psi e^{i(\Omega\tau + \phi)}) \right. \right. \\ \left. \left. + 2 \frac{c^2 k_t^2}{\omega} \psi \right] e^{i\omega t} \right\} - \frac{1}{2B_z} \frac{\partial B_z}{\partial z} \frac{u_t^2}{\gamma} \end{aligned} \quad (21.3)$$

for TM modes, where L_+ and L_- are defined by:

$$L_+ \psi \equiv e^{i\theta} \left(\frac{\partial}{\partial r} + \frac{i}{r} \frac{\partial}{\partial \theta} \right) \psi, \quad (22.1)$$

$$L_- \psi \equiv e^{-i\theta} \left(\frac{\partial}{\partial r} - \frac{i}{r} \frac{\partial}{\partial \theta} \right) \psi. \quad (22.2)$$

3.1 Circular waveguide mode.

For a circular waveguide, the projection of an electron orbit on the cross sectional plane of the resonator forms an annulus with average radius equal to the electron orbit guiding center radius R_0 , and with thickness equal to twice the Larmor radius

$$r_L \equiv u_t / \Omega_z \quad (23)$$

The case of an axis encircling beam ($R_0=0$) is a special case of the analysis.

The scalar function for a circular waveguide mode with circular polarization is

$$\psi_{mn} = C_{mn} J(k_{mn} r) e^{\pm im\theta} \quad (24)$$

where for a TE mode:

$$k_{mn} = \frac{x_{mn}}{r_w}, \quad (25)$$

$$C_{mn} = [[\pi (x_{mn}^2 - m^2)]^{1/2} J_m(x_{mn})]^{-1}, \quad (26)$$

x_{mn} is the n^{th} zero of $J_m'(x)$ (prime denotes differentiation), J_m is a Bessel function, and r_w is the waveguide wall radius. For a TM mode:

$$k_{mn} = \frac{z_{mn}}{r_w}, \quad (27)$$

$$C_{mn} = [\sqrt{\pi} z_{mn} J_m(z_{mn})]^{-1}, \quad (28)$$

and z_{mn} is the n^{th} zero of $J_m(z)$. For definiteness consider the mode with polarization $e^{i(\omega t - m\theta)}$. Substitution of Eq. (24) into (22.1) and (22.2) gives

$$L_{+\psi} = C_{mn} k_{mn} J_{m-1}(k_{mn} r) e^{-i(m-1)\theta} \quad (29.1)$$

$$L_{-\psi} = C_{mn} k_{mn} J_{m+1}(k_{mn} r) e^{-i(m+1)\theta} \quad (29.2)$$

For the case of non-zero guiding center radius, the addition theorem⁵ is used to express Bessel functions of the radial coordinate in terms of Bessel functions with guiding center and Larmor radius arguments; i.e.,

$$J_m(kr) e^{\pm im\theta} = \sum_k J_{m+k}(kR_0) J_k(kr_L) e^{\pm ik[\pi - (\Omega\tau + \phi) \pm (k+m)\Xi_0]} \quad (30)$$

where Ξ_0 is guiding center position angle.

Substitution of Equations (24), (29), and (30) into (20) or (21), and considering

the interaction with the sth harmonic of the applied magnetic field leads to the following slow time-scale equations of motion: For a TE mode:

$$\dot{u}_t = \text{Re} \left\{ -\eta (f - v_z g) C_{mn} J_{m-s} (k_{mn} R_0) \frac{\partial J_s (k_{mn} r_L)}{\partial r_L} \right. \\ \left. e^{i[(\omega - s\Omega)\tau + \omega t_0 - s\phi - (m-s)\Xi_0]} \right\} + \frac{u_z u_t}{2\gamma} \frac{1}{B_z} \frac{\partial B_z}{\partial z} \quad (31.1)$$

$$\dot{\phi} = \frac{1}{u_t} \text{Re} \left\{ i\eta [(f - v_z g) - \frac{k_{mn}^2 u_t}{\gamma s \omega \Omega_z} f] C_{mn} J_{m-s} (k_{mn} R_0) \frac{s}{r_L} J_s (k_{mn} r_L) \right. \\ \left. e^{i[(\omega - s\Omega)\tau + \omega t_0 - s\phi - (m-s)\Xi_0]} \right\} - \Omega + \frac{\Omega z}{\gamma} \quad (31.2)$$

$$\dot{u}_z = \text{Re} \left\{ -\eta g \frac{u_t}{\gamma} C_{mn} J_{m-s} (k_{mn} R_0) \frac{\partial J_s (k_{mn} r_L)}{\partial r_L} \right. \\ \left. e^{i[(\omega - s\Omega)\tau + \omega t_0 - s\phi - (m-s)\Xi_0]} \right\} + \frac{1}{2} \frac{u_t^2}{\gamma} \frac{1}{B_z} \frac{\partial B_z}{\partial z} \quad (31.3)$$

and for a TM mode:

$$\dot{u}_t = \text{Re} \left\{ -i\eta (f - v_z g) C_{mn} J_{m-s} (k_{mn} R_0) \frac{s}{r_L} J_s (k_{mn} r_L) \right. \\ \left. e^{i[(\omega - s\Omega)\tau + \omega t_0 - s\phi - (m-s)\Xi_0]} \right\} + \frac{u_z u_t}{2\gamma} \frac{1}{B_z} \frac{\partial B_z}{\partial z} \quad (32.1)$$

$$\dot{\phi} = \frac{1}{u_t} \text{Re} \left\{ -\eta (f - v_z g) J_{m-s} (k_{mn} R_0) \frac{\partial J_s (k_{mn} r_L)}{\partial r_L} \right. \\ \left. e^{i[(\omega - s\Omega)\tau + \omega t_0 - s\phi - (m-s)\Xi_0]} \right\} - \Omega + \frac{\Omega z}{\gamma} \quad (32.2)$$

$$\dot{u}_z = \text{Re} \left\{ -\eta g \left(\frac{u_t}{\gamma} - \frac{c^2 k_{mn} r_L}{s \omega} \right) C_{mn} J_{m-s} (k_{mn} R_0) \frac{s}{r_L} J_s (k_{mn} r_L) \right. \\ \left. e^{i[(\omega - s\Omega)\tau + \omega t_0 - s\phi - (m-s)\Xi_0]} \right\} + \frac{u_t^2}{2\gamma} \frac{1}{B_z} \frac{\partial B_z}{\partial z} \quad (32.3)$$

In Eqs. (7) in Section 2, above the phase angle ϕ is replaced by

$$\Lambda \equiv (\omega - s\Omega)\tau + \omega\tau_0 - s\phi - (m-s)\Xi_0. \quad (33)$$

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