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## THESIS

JANUS/ADA SOFTWARE IMPLEMENTATION OF A  
STAR CLUSTER LOCAL AREA NETWORK OF  
PERSONAL COMPUTERS

by

Thomas Victor Works

December 1986

Thesis Advisor:

Uno R. Kodres

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JANUS/Ada Software Implementation of a Star Cluster Local Area  
Network of Personal Computers

by

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Submitted in partial fulfillment of the  
requirements for the degree of

MASTER OF SCIENCE IN INFORMATION SYSTEMS

from the

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December 1986

## ABSTRACT

This thesis describes the detailed design and implementation of a star cluster local area network among multiple Zenith Z-100 microcomputers. The Z-100s are linked together by the Concentrator, a server system consisting of a power supply, an iSBC 86/12A single board computer, and three BLC 8538 eight channel I/O expansion boards, through RS232c USART ports.

The local area network software consists of a server program resident in the Concentrator which provides the communication links between the Z-100s and the utility programs resident in each microcomputer. These utilities include file and message transfer (both point to point and broadcast), directory listing transfer, and online user identification. The program and utilities are written in JANUS/Ada, with assembly language subroutines for machine specific functions, and are designed to run with the CP/M-86 operating system.

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Digital Research Incorporated, Pacific Grove, California:

CP/M-86

National Semiconductor, Santa Clara, California:

PLC 8538

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## I. INTRODUCTION

### A. BACKGROUND

A critical requirement for today's office and laboratory environments is the sharing of expensive data and resources. A network of microcomputer workstations linked together can share data by transmitting files and messages between users and share peripheral resources such as printers by scheduling users in the most efficient manner. In the laboratory environment in particular, it is especially important and desirable to share data, experiments, and software development among lab members and to provide the means to distribute data to all members from a single source such as the professor or laboratory supervisor. Broadcast transmission from one workstation to all workstations of files or messages, or using one workstation as a 'bulletin board' to store messages over a period of time for access by all members, both serve this purpose. A testbed for research in data and resource sharing in the laboratory environment is a MULTIEUS based computer configuration which permits a single board computer to communicate with three input/output boards each containing eight RS-232 ports. This configuration serves as a concentrator for a star cluster local area network, which can connect up to twenty four RS-232 compatible devices.

This thesis is, in many ways, a companion to the thesis done by Lt. Cmdr. Robert Hertman and Capt. Alec Yasinsac,

[Ref. 1]. Their thesis involved the implementation of a prototype star cluster local area network of microcomputers connected to a Vax 11/780 computer over the ETHERNET communications device. The Vax 11/780 system operating under the UNIX operating system provides access to the ARPANET wide area network. Their local area network is operated under the MS-DOS environment and involves the use of various protocols necessary for communications with ARPANET.

The aim of this thesis is to provide an efficient data communications environment limited to the local area network of 2-100 workstations running under the CP/M-86 operating system.

## F. PROJECT DESCRIPTION

### 1. Proposed Capabilities

#### a. Local File Transfer

Any microcomputer should be able to transfer a file to any other microcomputer asynchronously. Additionally, any microcomputer should be able to 'broadcast' files to multiple microcomputers simultaneously.

#### b. Local Message Transfer

Any microcomputer should be able to transfer messages in the same manner as files, with the additional capability of having one microcomputer serve as a 'bulletin board' for the others.

c. Directory Transfer

Any microcomputer should be able to transfer a directory in the same manner as messages and files.

d. Online User Identification

Any microcomputer should be able to obtain a 'net status'; the identities of all currently active workstations in the network, at any given time.

2. Target Hardware

The proposed local area network consists of up to twenty four Z-100 microcomputer workstations connected via RS-232 communications ports to a central MULTIBUS based single board computer, which acts as a central switchboard to provide communications between the workstations.

3. Software

All the applications software for the microcomputers and the processing software for the single board computer acting as a switchboard has been written by the author for this thesis.

C. STRUCTURE OF THE THESIS

The majority of this thesis is the program code that implements the network. The accompanying text provides system description, design decisions, problems encountered, and operating and maintenance procedures. Chapter II describes the hardware of the system, Chapter III details the 8086 CPU, and Chapter IV explains the CP/M-86 operating system. A description of the JANUS/Ada language detailing useful

features, problems encountered, and lessons learned from the prospective of a newcomer to the language with reference to the full ADA language is provided in Chapter V. Chapter VI explains the design methodology and the details of the software implementation with descriptions of each major module.

The appendices provide the program code, user and maintenance manuals, a glossary, and a bibliography.

## II. HARDWARE

### A. THE 86/12A SBC

The 86/12A single board computer is a complete computer system on a single printed circuit board. It includes a 16 bit 8086 CPU, 32K, expandable to 64K, bytes of dynamic RAM, a serial communications interface, three programmable parallel I/O ports, programmable timers, priority interrupt control, MULTIBUS interface control logic, bus expansion drivers for interface with other compatible MULTIBUS expansion boards, and up to 16K bytes of ROM. Table 2.1 lists the possible I/O port addressing assignments.

TABLE 2.1

86/12A I/O ASSIGNMENTS

I/O Address	IC	Function
or 00C0 00C4	8259A Programmable Interrupt Controller	write: ICW1, OCW2 & OCW3 read: Status and Poll
or 00C2 00C6		write: ICW2, ICW3, ICW4, OCW1 read: OCW1 (Mask)
00C8 00CA 00CC 00CF	8255A Programmable Peripheral Interface	write: port A (J1) read: port A (J1) write: port B (J1) read: port B (J1) write: port C (J1) read: port C (J1), Stat write: Control read: none

---

00D0	8253	write: Counter 0
	Programmable	(load cnt/N)
	Interval	read: Counter 0
00D2	Timer	write: Counter 1
		(load cnt/N)
		read: Counter 1
00D4		write: Counter 2
		(load cnt/N)
		read: Counter 2
00D6		write: Control
		read: none

---

or 00D8	8251A	write: Data (J2)
00DC	USART	read: Data (J2)
00DA		write: Mode/Command
or 00DE		read: Status

---

The 8538 Eight Channel Communication Expansion Board is a fully programmable synchronous/asynchronous serial communication channel with RS232C interfaces connected to IC2651 USARTs for serial communications with other devices, and is compatible with the MULTIBUS system. The total address space for each board is 64, or 40 Hex, locations. Each board has a base address that is selectable by DIP switches on the board and is set to 0100 Hex for this implementation. Disregarding the base address for the moment, board 1 would start at 0, board 2 at 40 Hex, and so on. The primary locations of interest are the data register, the status register, the mode register, and the command register. These locations are 0-3 for port 0, 4-7 for port 1, and so on up to 20 Hex for the

eight USARTs. The remaining address locations are for interrupt handling and are not used in this implementation. The port addressing is shown in Table 2.2.

TABLE 2.2  
USART ADDRESSING

Address (Hex)	Function
	R/W: R: Status R/W: R/w:
	Data W: Sync1/Sync2/Dle Mode Command
0-3	" "
4-7	" "
8-B	" "
C-F	" "
10-13	" "
14-17	" "
18-1F	" "
1C-1F	" "
20,28,30,38	Port reset register (write only)
21,29,31,39	N/A
22,2A,32,3A	Transmit interrupt register
23,2B,33,3B	Transmit interrupt requests
24,2C,34,3C	Transmit interrupt mask
25,2D,35,3D	Transmit interrupt requests
26,2F,36,3E	Ring detects
27,2F,37,3F	N/A

### B. THE Z-100

The Zenith Z-100 is a dual processor 8085/8088 computer with either one or two 5.25 inch floppy disk drives and one Winchester hard disk drive providing up to 750K bytes of directly addressable RAM. It is powered by a 5MHZ clock.

The Z-100's main circuit board contains the 8085 and 8088 CPUs and the S-100 IEEE 696 bus. It has the capacity for 192K bytes of memory. Also contained on the main board is

the 8041A keyboard processor, two RS-232 serial interfaces and connectors, one parallel interface and connector, and the video circuit board interface.

The video circuit board contains the CRT controller and supports a bit mapped video system with up to three banks of 32K byte memory devices for red, green, and blue.

The floppy disk drive controller, which can support up to four 5.25 inch and four eight inch drives, and the Winchester disk controller are on separate cards and are each connected to one of the slots of the S-100 bus.

Other hardware features of interest include: the 8259A Programmable Interrupt Controller, the 68A21 Peripheral Interface Adapter, the 8253 Programmable Interval Timer, and the 2661 Enhanced Programmable Communications Interface. The Z-100 has two serial ports, labeled J1, the printer port, and J2, the modem port, both of which are connected through the 2661 interface.

### III. THE CENTRAL PROCESSING UNITS

#### A. THE 8086

The 86/12A single board computer uses the INTEL 8086 microprocessor for its CPU (Central Processing Unit). The 8086 is a high performance, general purpose 16 bit microprocessor. It has a 20 bit address bus, allowing access to a full megabyte of memory. Since the largest register in the 8086 is only 16 bits, it uses segmentation to form 20 bit addresses from the four 16 bit address registers; the CS (Code Segment), the DS (Data Segment), the SS (Stack Segment), and the ES (Extra Segment). These four registers reside in the BIU (Bus Interface Unit).

The EU (Execution Unit) contains nine 16 bit registers interfaced to a 16 bit data bus, four of which are byte or word addressable; the AX (AH, AL), BX, CX, and the DX, and four of which are only word addressable; the SP (Stack Pointer), the BP (Base Pointer), the SI (Source Index), and the DI (Destination Index). The remaining register is the flag register which has nine usable bits; Carry, Parity, Auxiliary Carry, Zero, Sign, Trap, Interrupt, Direction, and Overflow. Lastly, there is one 16 bit IP (Instruction Pointer) register.

The BIU and the EU operate asynchronously in the 8086. Additionally the BIU has an instruction object code queue. These two features combine to virtually eliminate instruction fetch time. By fetching the next instruction, while the

previous is being decoded and executed, and loading it in a queue, the 8086 ensures that there is always an instruction ready the instant it is required. Only when a jump instruction causes the current instruction sequence to be changed, is the instruction queue flushed.

## B. THE 8088

The Z-100 uses both the 8 bit 8085 CPU and the 16 bit 8088 CPU. The 8088 is the processor of interest to this thesis. The 8088 is compatible with the 8086 and is (to the programmer) virtually identical. In particular, the 8088 programmable registers and addressing modes are exactly the same. The significant difference is that it has an 8 bit data bus versus the 16 bit data bus of the 8086.

The differences between the two CPUs are evidenced in execution times. The 8088 has a four byte instruction queue compared to the six byte queue in 8086. This results in more code fetches per instruction and slows down instruction processing. The 8 bit data bus requires the 8088 to take two bus cycles whenever the 8086 would have used only one to fetch 16 bits of data. All other execution time values are identical.

#### IV. THE OPERATING SYSTEM

CP/M-86 is an operating system designed by Digital Research for the 8086 and 8088 sixteen bit microprocessor. It contains three program modules: the CCP, the BDOS, and the BIOS. Entry to the BDOS is provided through the reserved software interrupt #224 (E0 Hex), while entry to the BIOS is provided by either a jump vector located at offset 2500 Hex from the operating system base, or by use of the BDOS function #50. For this implementation, only entry to the BDOS was required. BDOS functions were used for keyboard input, console output, and file operations. Table 4.1 lists each function call used with entry and return parameters indicated.

Access to files in CP/M-86 is achieved by use of the File Control Block (FCB) whose format is shown in Table 4.2. Each FCB is identified by specifying its relative offset from the data segment register. When reading from or writing to a file, BDOS uses sequential 128 byte records to transfer information from the file into memory at the current Direct Memory Address (DMA) and vice-versa. The DMA can be specified by the user as the relative offset from a specified or default DMA base.

CP/M-86 uses one directory entry per 16K bytes of file data, termed an extent. During sequential reads and writes the "cr" field of the FCB is incremented for each 128 byte record until the next extent is required. Unless no more

TABLE 4.1  
BDOS FUNCTIONS

ENTRY	=>	FUNCTION	=>	RETURN
CL: 02H, DI: Ascii Char		Console Output		None
CL: 06H, DI: 0FFH (Input); 0FFH (Status); Char (Output)		Direct Console I/O		AL: Char, Status
CL: 0DH		Reset Disk System		None
CL: 0FH, DI: Selected Disk		Select Disk		None
CL: 0FH, DX: FCB Offset		Open File		AL: Return Code (0-3, 0FFH)
CL: 10H, DX: FCB Offset		Close File		AL: Return Code (0-3, 0FFH)
CL: 11H, DX: FCB Offset		Search For First		AL: Directory Code
CL: 12H,		Search For Next		AL: Directory Code
CL: 13H, DX: FCB Offset		Delete File		AL: Return Code (0, 0FFH)
CL: 14H, DX: FCB Offset		Read Sequential		AL: Return Code (0, 1)
CL: 15H, DX: FCB Offset		Write Sequential		AL: Return Code (0, 1, 2)
CL: 16H, DX: FCB Offset		Make File		AL: Return Code (0, 1, 2, 3, 0FFH)
CL: 1AH, DX: DMA Offset		Set DMA Address		None

TABLE 4.2  
FCE FORMAT

---

dr	f1	f2	/	f8	t1	t2	t3	ex	s1	s2	rc	d0	/	dn	cr	r0	r1	r2
00	01	02	...	08	09	10	11	12	13	14	15	16	...	31	32	33	34	35

where;

```

dr:      drive code (0 - 16)
         0 => default drive
         1 => drive A
         2 => drive B
         ...
         16 => drive P
f1...f8: File name in Ascii upper case
t1 - t3: File type in Ascii upper case
         (t1 high bit = 1 => R/O file)
         (t2 high bit = 1 => Sys file, no DIR)
ex:      Current extent number (0 - 31)
         Set to 0 by user before file I/O
s1:      Internal use
s1:      Internal use, set to 0 on Make, Open,
         and Search
rc:      Record count for ex (0 - 128)
d0...dn: CP/M-86 internal use
cr:      Current record for Read/Write Sequential
         Set to 0 by user
r0 - r2: Optional random record number

```

---

record or directory space exists, the next extent is automatically opened. Then the "cr" field is reset to zero and a new directory entry for the new extent is created.

When directory searches are made, the 128 byte record containing the matched entry is placed in memory at the DMA address. For files with multiple extents, the first directory entry is matched. There are four entries per record.

The location of the matched entry is computed by multiplying the offset returned by the function call by 32 and adding it to the DMA address.

DDT86 proved to be an invaluable tool to the development of this thesis. DDT86, a utility program supplied with CP/M-86, is a dynamic, interactive debug and test program for the CP/M-86 environment. It worked excellently with both the high level JANUS/Ada code and the assembly language sub-routines interfaced with the high level code. DISASM86, the disassembler provided with the JANUS/Ada system, presented the high level code in its post-compiled assembly form which could then be debugged using DDT86. Completion of this thesis would not have been possible without the use of DDT86. Its only drawback was a tendency to 'slow' down a program to the point where it would work under DDT86, but would fail in the real time environment outside DDT86, which caused understandable confusion.

Additional detailed information about CP/M-86 can be found in [Refs. 2 & 3].

## V. THE PROGRAMMING LANGUAGE

ADA is the Department of Defense's mandated language for embedded computer systems. According to DOD directive 5000.31 [Ref. 4], "all mission critical defense systems that enter advanced development status after 1 Jan 84, or that enter full scale development after 1 Jul 84" will be coded in ADA. Introduced in its final form in September 1980, ADA has inspired much activity, discussion, and debate. Due to its large size and complexity, commercial compilers are only now becoming available.

JANUS/Ada, an implementation designed for microcomputers, was chosen for this project because of its availability, and its suitability to systems programming tasks. Although not fully ADA compatible in its treatment of strings, use of inline ASM statements, or the data type Byte, and lacking the capability for exception handling or concurrent tasking, research in the JANUS/Ada implementation should prove invaluable to the effective use of the full language itself; a language destined to be the Department of Defense's standard for embedded systems.

This author's programming experience prior to this project was limited to only the basics of Pascal and Assembly languages. According to Bernard [Ref. 5], my experiences can best be described by:

While people who have a high level language should be able to learn what is referred to as 'the Pascal subset' of ADA with about four weeks of full-time study, many educators report that it takes six months to learn to make effective use of the language.

Also required are a firm knowledge of structured programming and software engineering. It is clear, however, that the ADA designers were correct to base the language syntax on Pascal, a language designed and recognized as the standard to teach students about structured programming.

The most impressive and useful control structure in ADA is the 'Loop' statement. The ability to exit a loop wherever and whenever desired, combined with the traditional constructs of 'For' and 'While', makes the Loop statement applicable to an almost infinite set of design structures and truly supports the concept of structured, easy to read programming. This feature alone separates ADA's control structures from Pascal, Cobol, Fortran, and others.

JANUS/Ada's resident assembly language interface is also extremely useful. Routines that require high speed and efficiency or specific bit/byte manipulation could be coded in assembly language and called from the high level program. This feature answers the traditional systems programmer's need for control of, and access to, the specific machine. The ease with which assembly code could be used in conjunction with high level JANUS/Ada code was very important to this project. Almost all of the I/O and file operations required in the programs were coded in assembly language. This was

partly for speed and efficiency and partly because many of the I/O and file operations built into JANUS/Ada would not work (for reasons undiscovered) after a single call to the CP/M-86 operating system was issued.

ADA's use of packages as the unit of program modularity is an important step in the evolution of structured programming languages. Packages contain data, procedures, and/or functions that for reasons of a particular program's modular design are grouped together to form a unit. A program's various packages are then linked together for execution. Packages support efficient modular design and allow for the effective construction of program libraries of frequently used routines and data structures for programmers to use. Data and routines are made available to users and other packages through Specifications, which provide all the necessary information for their use while hiding the details of the implementation, thus supporting the principle of information hiding.

Packages are also the main instrument of separate compilation, which is becoming a requisite feature of modern programming languages. Unless the vehicle for communication between linked packages, the specification, is changed, modifying a single package requires only its recompilation and not the recompilation of packages referencing it or referenced by it.

Separate compilation is particularly important in JANUS/Ada, and by extension, ADA, because the size and complexity of the language dictates that compilers for it be also large, complex, and relatively slow. This causes software development problems of time and storage.

The compiler itself, while a bit slow, provided helpful compile and run time error checking. Because ADA (and JANUS/Ada) is a strongly typed language, an efficient compiler should be able to detect a majority of errors at compile time, thereby saving development time. The JANUS/Ada compiler does so and even corrected certain syntax errors itself, producing a working program. While it is, in general, difficult to produce simple yet completely explanatory error messages, the JANUS/Ada compiler does a noteworthy job.

[Ref. 6], provided with the JANUS/Ada system, was more than adequate overall. It was not sufficient (and admitted so) to teach the JANUS/Ada language, but its manuals and appendices on the compiler, the assembler, the linker, etc. were first rate. Its description of library packages was also very helpful. [Ref. 7] provided all the necessary information to begin learning ADA in a very practical and concise manner.

## VI. THE IMPLEMENTATION

### A. METHODOLOGY

This author's inexperience with the hardware, the programming language, and software development of this nature (systems programming) and this scope (larger by far than anything attempted before), necessitated complete decomposition and modularization of the problem. The principle of top-down programming was used as the problem was broken into smaller and smaller functional elements until the most basic functions were identified. Such functions as basic input and output, opening and closing files, and interfacing assembly language with JANUS/Ada were coded and tested. These functional entities were combined in a building block manner, until larger and more complex functions such as character transfer and file transfer between two Z-100 were completed. Eventually, interface with the concentrator was achieved as the system began to take shape. The system was finished when the highest levels of the program hierarchy were finally completed and all the decomposed modules of the problem were coded, tested, and linked.

### B. SYSTEMS DESIGN

The problem of designing a star cluster local area network may be decomposed into two parts:

1. Programming the Concentrator.
2. Programming the Z-100.

## 1. The Concentrator

The role of the concentrator is to process network commands from the Z-100s, establish and maintain data communication connections, and route commands and data between Z-100s. The network principle of 'circuit switching' is implemented to route the commands and data. The Concentrator establishes and maintains data communication connections between the source and destination Z-100(s) until the entire user process or 'circuit' is completed.

Within the Concentrator the problem may be further decomposed into two parts. The Concentrator must poll all the ports in the network upon initiation and after each connection is terminated, to determine if any Z-100s are ready to participate in the network, and it must establish and maintain data communication connections.

Currently the Concentrator is equipped with three 8538 BLC expansion boards for a total of 24 available ports. Network expansion can be accomplished by adding more expansion boards and changing the value of the constants 'machno' and 'boardno' accordingly.

The Concentrator polls each port looking for the 'active' signal from a Z-100. If there is no response after a finite period of time, the Concentrator moves on to the next port. If the 'active' signal is received, the Concentrator stops and determines if there are processes waiting for this Z-100 from other Z-100s. If there are no

processes waiting, the Concentrator decodes the subsequent command information from the polled Z-100, and establishes the data communication connection for the requested process.

If there are processes waiting for the Z-100 being polled, the Concentrator decodes the first process in line, contacts the sender of that waiting process, and establishes a data communication connection for the transferral of the waiting process. Upon transfer of the first waiting process, or if the sender is no longer active, the waiting process is destroyed and the Concentrator returns to the polled Z-100 in order to decode the subsequent command information, and establish the data communication connection for the original requested process.

The Concentrator will satisfy at most one waiting process per polling cycle; a polling cycle is one loop around the network of twenty four ports. If there is more than one process waiting in the queue for a particular Z-100, the one which is first in the queue (first come, first served) is serviced during one polling cycle. The next queue element is serviced during the next polling cycle and so on until there are no more waiting processes.

There are two methods of transferring commands and data in this design:

1. Direct Z-100 - to - Z-100.
2. Broadcast to all active Z-100s in the network.

The Z-100 transmits to the Concentrator the transferring method and the Concentrator uses that method for all file, message, or directory transferral.

Once a data communication connection is established, the Concentrator acts as a transparent pathway, transferring commands and data without regard, and looking only for a sequence of four end of process codes (0F1h) from the destination Z-100(s). Receiving this sequence, the Concentrator terminates the connection and resumes polling where it left off. The Concentrator polls in an endless loop, stopping only to process requests from the ports of the network.

For single transferrals, error checking is performed by the sending and receiving terminals. For broadcast transferrals, the Concentrator performs the error checking between itself and the receiving terminals while the sender performs error checking between itself and the Concentrator.

If a data communication connection cannot be established, the record data structure 'connection' containing fields for source, destination, and process is queued in a FIFO queue implemented as an array of records. The queue is limited to one process per source Z-100 per destination Z-100 and is limited to message and file processes. It is this queue that the Concentrator checks after receiving the 'active' signal from any Z-100 during the polling process.

## 2. The Z-100

The role of the Z-100 is to communicate with the user and the Concentrator for the purposes of processing network application programs. Commands are transmitted from the user to the Concentrator, enabling the establishment of the proper data communication connection. Then the source Z-100 transmits commands and data to the destination Z-100(s).

The network applications consist of three Z-100 to Z-100 functions; file transfer, message transfer, and directory transfer, and one Z-100 to Concentrator function; net status. Within each Z-100 to Z-100 function is a sending process and a receiving process. It is these processes that serve as the network unit of execution. The source Z-100 initiates a process, the Concentrator establishes a connection with the destination Z-100(s), and maintains the connection until the process is finished. Then the next process is initiated and so on.

Both the Z-100 and the Concentrator use the record data structure 'connection' to establish data communication connections. 'Connection' contains three fields; 'source', 'destination', and 'process'.

```
TYPE conctn IS
  RECORD
    source: byte;
    destination: byte;
    process: byte;
  END RECORD;
```

The source Z-100 creates the connection record and transmits it to the Concentrator where it is decoded and the proper pathway is established. When the destination Z-100(s) acknowledge the connection, communication begins. If the connection can not be established, the connection record is stored by the Concentrator in the queue. Upon completion of the process, the connection record in the Concentrator and the Z-100 is destroyed.

The Z-100 network application programs are menu driven and implemented in an infinite loop. The Z-100 transmits an 'active' signal to the Concentrator and waits to be polled by the Concentrator. When polled the user is told if there is a process waiting for him/her and is requested to receive that process. Then the user selects a process from the menu and the Z-100 and the Concentrator carry out that process as described above. After process completion, control is returned to the infinite loop which transmits an 'active' signal again, waits to be polled, asks for user input, and so on until the user terminates the loop with "control x".

### 3. Command and Data Communication

A main concern of this thesis is efficient data communications. Fast, error free transmission of commands and data along the data communication connection for both point to point and broadcast, is achieved by an immediate echo method implemented in JANUS/Assembler language for

CP/M-86. The method uses the fact that instruction execution time is much shorter than data transmission time and attempts to minimize wait times as much as possible. All bytes received by any procedure are immediately echoed and the received echoes are then checked for error.

The sending procedure transmits a byte and then waits for an echo from the receiver. It compares the echo with the transmitted byte. If an error is detected, the sending procedure, depending on its function, either retransmits immediately or transmits an error code followed by the retransmitted byte. (For the broadcast method the byte is transmitted to all destination Z-100s before the echoes are received and compared.)

The receiving procedure receives a byte and then immediately echoes it before proceeding to process the received byte. If an error code is received when it returns to receive the next byte, the receiver erases the byte in error and returns to receive the retransmitted byte.

The method is sufficiently general in design to handle more difficult errors than just errors in data bytes transmitted from the sender to the receiver. For instance, the method will detect and correct errors in the echo transmitted back to the sender. This is a particularly insidious error because the receiver actually received the correct data byte, but the sender doesn't think so and sends out an error code or retransmits the data byte. The method

will also correct multiple errors such as when a data byte is transmitted in error and so is the subsequent error code. The sender will stay with the error until it is corrected to its satisfaction and the receiver will always know how many received data bytes are in error and how many to erase. This is true even when a procedure is both a sender and a receiver as in the procedure 'Setup'. Additionally, every receiving procedure has a finite waiting period to ensure the final byte and echo are received properly.

#### 4. Design Considerations

##### a. Assembly Language

JANUS/Assembler combined with CP/M-86 BDOS function calls was used for all I/O subroutines except for the display of non-conditional strings to the user. This was decided because of the need for speed, efficiency, and implementation of the data communication connection. Because of an undiscovered bug in JANUS/Ada, use of CP/M-86 function calls invalidated the perfectly adequate built in JANUS/Ada file operation routines. Thus these functions too were implemented in JANUS/Assembler with CP/M-86 BDOS function calls.

##### b. Memory Management

The Concentrator programs are estimated to occupy 25K of the 64K bytes of memory in the Concentrator. Due to the limited size of the queue for waiting processes, and to the use of message switching as the principle of network

communication, circuit management was deemed not necessary and was not implemented.

c. Process Coordination

The network processes do not use interrupts for coordination. Processes execute sequentially until communication is required. This communication is designed such that when, say, a sender is waiting to transmit specific commands or data, the receiver will eventually 'rendezvous' (although not in the concurrent sense) and the proper receiving procedure will receive and process the transmitted commands or data. When necessary, such as when polling ports, processes will wait a finite period of time and then move on. Occasionally, a process will stop until the receiver tells it to continue. Blocks of data are identified by end of block codes (0FFh), and codes are transmitted to tell the receiver whether or not this was the last block. Special care was exercised in the implementation to ensure that deadlock did not occur ie: both processes expecting to receive or to transmit.

The Concentrator, which is both a receiver and a sender, employs the same design principles when polling ports, checking or updating queues, and establishing data communication connections. Once a connection is established, it treats everything as a block of data, moving on only when a sequence of four end of process codes (0F1h) from the destination Z-100(s) is received.

#### d. The Data Type Byte

Use of the JANUS/Ada predefined data type Byte, which is not ADA standard, was necessitated by the network requirement to transmit all eight bits of each data byte and the method used to transmit and receive commands and data. The data type Character with only seven bits, and the data type Integer, which is not well suited for the manipulations needed for transmission, were not sufficient to represent the data byte used in command and data communication in this implementation.

#### C. SYSTEM EXECUTION

The implemented network application programs are menu and command driven. At program start and after each process, the 'active' signal is transmitted to the Concentrator and the program waits to be polled. When polled the program is informed if there are processes waiting for this Z-100. If there are processes waiting, the user is asked to receive them. Then the user is presented with the following menu:

```
CTRL_S = SEND FILE
CTRL_R = RECEIVE FILE
CTRL_T = SEND MESSAGE (TALK)
CTRL_L = RECEIVE MESSAGE (LISTEN)
CTRL_P = SEND DIRECTORY
CTRL_G = RECEIVE DIRECTORY
CTRL_W = GET NET STATUS (WHO)
CTRL_B = RECEIVE BULLETIN BOARD
OTHERS = RECHECK FOR INCOMING FILE OR MESSAGE
```

The user makes his or her selection and is placed in the appropriate environment. Upon completion of each process,

the user can press any key and be returned to the main menu or pause indefinitely. Upon return to the main menu, the user is given the option of exiting using "CTRL\_X" or continuing "ANY KEY".

To send a file, the user is prompted for the disk drive, file name, and file type of the file he wishes to send. The user's input is displayed as he types and invalid entries (those characters not permitted in file names and file types by CP/M-86) are flagged. A sample entry might look like this:

```
FN.FT: myfil? INVALID ENTRY
myfil_
```

Once entered the file name and type are capitalized in accordance with CP/M-86 format and the user's choice is displayed for confirmation:

```
C: MYFILE.TXT IS SELECTED. PRESS RETURN TO CONFIRM,
ANY OTHER KEY TO RESELECT.
```

Upon confirmation, the user is prompted for the destination terminal (or broadcast) and the source terminal. Then a search is made for the file. If it can not be found an error message is displayed and the user is given the opportunity to reselect. If it is found the file is opened. Then, if the destination is active, the transmission begins. Otherwise, a message indicating that the destination was inactive is displayed and the user is returned to the main menu.

The file is sent in successive 128 byte data blocks until end of file is reached. After each data block, the sender

indicates to the receiver whether or not end of file has occurred and stops until the receiver tells the sender to continue. Once the file is sent, it is closed and the user is returned to the main menu.

To receive a file, the user is prompted as above for drive, file name, and file type. Upon confirmation, the file named by the user is first deleted and then created. This is done to ensure no errors occur during the create operation and has the effect of overwriting the file if the user chooses a file already on the disk. After creating the file, reception begins.

The file is received in 128 byte data blocks and after each block is written to disk, end of file is checked and the sender is told to continue. Once the file is received, it is closed and the user is informed of the number of bytes received. Error messages are displayed if there is no more disk space or directory space on the receiver. The user is then returned to the main menu.

To send a message, the user is prompted to begin typing and told that the maximum message length is 1600 characters. All characters entered except "CTRL\_Z" are sent. The message is organized in a 'page' format of twenty lines with 80 characters each. A limited correction capability is included, consisting of typing "backspace" or "CTRL\_E" and then retyping the character. However, the error, the backspace or CTRL\_H, and the retyped character all count as typed

characters. The message format consists of twenty lines of 80 'keystrokes' each. Users must keep this in mind when typing.

"CTRL\_Z" stops message typing and "CTRL\_S" sends it. Any other key allows the user to retype the message. After "CTRL\_S", the user is prompted for the source and destination (or broadcast) terminals as above. If the destination is active, the message is transmitted as one data block with appropriate end of message codes. The user is returned to the main menu upon completion of the transmission.

To receive a message, the user types "CTRL\_L" from the main menu and reception occurs. The message is displayed and the user is informed of end of message and the number of bytes received. The user is then returned to the main menu.

To send a directory, the user is prompted for the disk drive for which directory he wishes to send. (Presumably in response to a request.) After confirmation, the user is prompted for the source and destination (or broadcast) terminals as above. The directory of the selected drive is then searched for the CP/M-86 wild card file name and type (?????????.???) causing the entire directory to be matched. Each directory entry is placed in the transmission data block until there are eight directory entries for a total of 128 bytes. If the destination is active this data block is then transmitted, preceded by the disk drive, with a code indicating whether or not end of directory has occurred. If there

are no files on the selected disk a "NO FILES ON SELECTED DISK." string is transmitted to the receiver. The user is returned to the main menu upon completion of the transmission.

To receive a directory, the user is prompted as above for drive, file name, and file type in which he wishes to store the incoming directory. Upon confirmation, the file named by the user is first deleted and then created. This is done to ensure no errors occur during the create operation and has the effect of overwriting the file if the user chooses a file already on the disk. After creating the file, reception begins.

The drive of the directory is received first and then the first 128 byte data block. After checking for end of directory, the eight directory entries of the data block are displayed and the user is asked if he wishes to save them on file. Each data block is received the same way. Those data blocks the user wishes to save are written to disk and the rest are discarded. Error messages are displayed if there is no more disk space or directory space on the receiver. When end of directory is reached the reception is ceased, the file closed, and the user returned to the main menu. The file created during this operation should be edited by the user as it may contain characters from each directory entry that are not printable.

To obtain a current net status of the active terminals in the network, the user is prompted for the source and destination terminals as above with the exception that he must enter his terminal for both source and destination. Upon confirmation, a list by number of all active terminals is displayed and the user is returned to the main menu.

Messages are sent the bulletin board, if it is active, by selecting machine #24 when prompted. The bulletin board is 'read' by selecting CTRL\_B at the main menu. If the bulletin board is active, all the current messages are transmitted, in 128 byte blocks, and stored in a user specified file, chosen in the same manner as the receiving of file transfers. This file can then be perused at leisure. The bulletin board can hold up to twenty messages of 1600 bytes each. The twenty-first message replaces the first message and so on.

## VII. CONCLUSIONS

The research objectives of this thesis; coding in JANUS/Ada, allowing single or multiple transfers of files, messages, and directories, and sharing of local resources in a laboratory environment, were satisfactorily completed. However, the complete testing and demonstration of the network in operation was not achieved.

The utilities resident in the Z-100 workstations were completely and satisfactorily tested. So too were the establishment of data communications connections and data transfer through the concentrator of files, messages, and directories from a single Z-100 to another single Z-100 and to multiple (two) Z-100s. The polling mechanism in the concentrator, obtaining net status, and the storing of messages in and retrieval from the bulletin board were also satisfactorily tested.

Remaining to be tested are: the mechanism for the storing of processes for which a connection could not be established and the mechanism for placing and servicing the waiting processes in the queue. Finally, the testing of the entire system of 23 Z-100 workstations and one Bulletin board under all conditions and loads awaits demonstration.

In sum, each module and subroutine was separately compiled and tested, functional integration of parts of the

system were tested and satisfactorily demonstrated, but the complete integration of the entire network was not accomplished.

To achieve final system integration and completion of the network, it is recommended that a two step testing process be conducted. First, set up, under laboratory conditions, a small network consisting of seven Z-100 workstations and a bulletin board using one full 8538 expansion board. In this set up, fully test the package 'Poll' in various experimental situations to ensure that it handles all circumstances as designed and that the queue operations function properly. Second, establish the full network and test it in an operational environment under all conditions of load and function.

The experience of coding this thesis was very challenging and stimulating. Despite my very limited programming background in Pascal, I was able to quickly grasp the fundamentals of Janus/Ada and begin coding small test procedures. As the requirements for the project became clearer, coding intensified and increased in size and scope.

However, I found myself habitually using Pascal or Pascal-like structures. I was tapping very little of the power and richness of Janus/Ada. For instance, I would use

```
IF condition THEN
  EXIT;
END IF;
```

rather than

```
EXIT WHEN condition;
```

to exit loops. Features such as attributes, subtypes, derived types, and ranges were used very little in the beginning. Additionally, the nature of the project precluded working with real or fixed point types and all their features plus many of the built in or provided library subroutines.

It was in the use of the LOOP statement that I began to explore the full power of Janus/Ada over Pascal. I quickly learned to tailor the loop statement to achieve any effect I desired and found it extremely useful in structuring my programs. Gradually, in this and other structures, I began to use Janus/Ada more elegantly and to remove 'Pascal' from my coding, although some always remained.

Surprisingly, the grouping of programs, subroutines, and data into packages and the linking together of these packages into a single program proved very easy to assimilate. The understanding and use of the scope and visibility rules, however, was harder to grasp. As a result, the use of selected components for naming variables in one package while in another package, or the use of private types were not implemented.

The first real problems occurred in the use of input and output, usually the hardest part of any language. For

reasons previously explained, assembly language subroutines interfaced with Janus/Ada programs were used for virtually all input and output. My previous assembly language experience was with 8080 mnemonics, but the use of 8086 mnemonics was easy to learn because I was required to use only those instructions that had counterparts in 8080 and I only had to learn the new register and addressing schemes. However, the interface with Janus/Ada proved extremely difficult to master. It took much trial and error to realize exactly how the parameters were passed and returned from the assembly language subroutine and how the stack was manipulated when the subroutine was called.

Lastly, the requirements of data communication were the hardest to implement. The idea of two programs executing on two different machines and communicating with each other was entirely new. The errors that resulted were difficult to diagnose and correct. In my previous experience, programs very rarely encountered infinite loops; either they didn't work correctly or they produced wrong answers, but they always finished. In data communication, infinite loops were frequent as the programs deadlocked waiting for the other to stop or start communicating. The synchronization of procedures and routines in programs executing in parallel, so that procedures that needed to communicate would 'meet' at the right place and the right time, was the most difficult aspect of coding this thesis.

This thesis demonstrated the following capabilities. First, the ability of JANUS/Ada, and by extension, ADA, to effectively and efficiently perform complex data communication and network functions. Second, the viability of clustering microcomputers for the sharing of resources and the enhancement of data communications and transfer. Finally, the ability of an inexperienced programmer to learn ADA and use it in the solving of complex computer problems.

APPENDIX A  
USER'S MANUAL

A. GETTING STARTED

The system is designed to operate on the Zenith model 100 microcomputer connected to the concentrator in the NPS microcomputer lab. The file Xfermain.cmd should be on the hard disk and the CP/M-86 operating system should be selected.

B. SYSTEMS OPERATION

The command 'xfermain' will place the user in the network. The first message should be:

'WAITING TO BE POLLED.'

Note: System messages are always in uppercase. This means that this Z-100 is waiting to be recognized by the network. A wait of some time may result if the system is busy. If the wait becomes excessive, see the system's maintenance personnel. When recognized, the next message should be:

'CHECKING FOR INCOMING FILE OR MESSAGE.'

If there is an incoming file or message, the user will be asked to receive it prior to continuing with the user's request.

After the incoming data has been received or if there is no data, the following menu will be displayed:

```
CTRL_S = SEND FILE
CTRL_R = RECEIVE FILE
CTRL_T = SEND MESSAGE (TALK)
CTRL_L = RECEIVE MESSAGE (LISTEN)
CTRL_P = SEND DIRECTORY
CTRL_G = RECEIVE DIRECTORY
CTRL_W = GET NET STATUS (WHO)
CTRL_B = RECEIVE BULLETIN BOARD
OTHERS = RECHECK FOR INCOMING FILE OR MESSAGE
```

Selecting the proper entry will place the user in the desired environment.

## C. SENDFILE

Once in Sendfile, the command messages are self explanatory. The program forces the input of a CP/M-86 acceptable file name and file type, but the user must ensure that the file exists on the selected disk. An error message will result otherwise. The next step is selecting the destination machine (numbered 01 through 23) or broadcast to all (number 00). If the requested destination is not presently in the network, the request to send a file will be queued along with the intended destination. Some delay may occur in the sending of a file if the file is very large or the network is very busy. Excessive delay should be referred to the systems maintenance personnel.

## D. RFCFIVEFILE

Once in Receivefile, the command messages are self explanatory. The program prompts for a file name and file type for the incoming data. It forces the input of a CP/M-86 acceptable file name and file type, but the user must ensure that sufficient space exists for the file on the selected disk. An error message will result otherwise. Some delay may occur in the receiving of a file if the file is very large or the network is very busy. Excessive delay should be referred to the systems maintenance personnel.

## E. TALKING

Once in Talking, the command messages are self explanatory. Message length is 1600 characters organized in 20 lines of 80. Errors can be corrected using backspace or 'control h', but each keystroke counts towards the 1600. The next step is selecting the destination machine (numbered 01 through 23), broadcast to all (number 00), or bulletin board (number 24). If the requested destination is not presently in the network, the request to send a message will be queued along with the intended destination. Some delay may occur in the sending of a message if the message is very large or the network is very busy. Excessive delay should be referred to the systems maintenance personnel.

## F. LISTENING

Once in Listening, the message is received immediately and displayed as typed.

## G. WHOS\_THERE

Once in Whos\_there, the user is prompted to enter his machine number as the destination. Then the net status is received.

## H. RECEIVE\_DIR

Once in Receive\_dir, the command messages are self explanatory. The program prompts for a file name and file type for the incoming data. It forces the input of a CP/M-86 acceptable file name and file type, but the user must ensure that sufficient space exists for the file on the selected disk. An error message will result otherwise. The user may save only those directory entries he desires. Some delay may occur in the receiving of a directory if the directory is very large or the network is very busy. Excessive delay should be referred to the systems maintenance personnel.

## I. PRESENT\_DIR

Once in Present\_dir, the command messages are self explanatory. The user is prompted to select the destination machine (numbered 01 through 23) or broadcast to all (number 00). If the requested destination is not presently in the network, the request to send a directory will not be queued and is destroyed. Some delay may occur in the sending of a directory if the directory is very large or the network is very busy. Excessive delay should be referred to the systems maintenance personnel.

## J. BULLBRD

Once in Bullbrd, the command messages are self explanatory. The program prompts for a file name and file type for the incoming data. It forces the input of a CP/M-86 acceptable file name and file type, but the user must ensure that sufficient space exists for the file on the selected disk. An error message will result otherwise. Some delay may occur in the receiving of messages from the bulletin board if the number of messages is very large or the network is very busy. Excessive delay should be referred to the systems maintenance personnel.

## K. FURTHER ACTION

When completing any one of the above tasks, the user is returned to the main menu where he may exit using 'control x' or continue for more tasks. If the user chooses to continue the program returns to the beginning, waits to be recognized again, and so on.

## L. WHEN ERRORS OCCUR

The system is designed to flag most errors and allow user correction without halting execution, however should errors occur which halt the program during data communication, then the system will have to be reset. Otherwise, resetting the user terminal will allow the user to rejoin the network.

MAINTENANCE MANUAL FOR Z-100 PROGRAMS

## A. XFERMAIN

## 1. CONFIGURATION

- a. Language - JANUS/Ada
- b. Compiler Version - 1.47
- c. Linker Version - 1.47
- d. Target Hardware - Zenith Z-100 microcomputer
- e. Operating System - CP/M-86 (version 1.14)
- f. Package description:

The Xfermain package is the main program for the Z-100 workstations. It begins by informing the Concentrator that this particular terminal is active and then waiting to determine if the network has any files or messages waiting for it. Xfermain then presents the user with a menu of selected options: send/receive files, send/receive messages, send/receive directory, and obtain network status. Control code keystrokes then place the user in the desired environment. Xfermain contains an infinite loop that will perform the above functions until the user terminates the session with control x. Upon termination, Xfermain informs the Concentrator it is no longer active.

## 2. SUBROUTINES

- a. Contained: None.
- b. Called:
  - Active
  - Waiting
  - Outconsole
  - Keyin
  - Sendfile
  - Receivefile
  - Talking
  - Listening
  - Whos\_there
  - Receive\_dir
  - Present\_dir
  - Recv\_bulletin
  - Clearscrn
  - Off

## 3. COMMENTS

Xfermain is placed on all terminals of the network, except #24, the Bulletin board, and is invoked by typing the command "xferrain".

## B. XFERFILE

### 1. CONFIGURATION

- a. Language - JANUS/Ada
- b. Compiler Version - 1.47
- c. Linker Version - 1.47
- d. Target Hardware - Zenith Z-100 microcomputer
- e. Operating System - CP/M-86 (version 1.14)
- f. Package description:

The Xferfile package controls the sending and receiving of files from the Z-100 workstations. The user is prompted for the disk drive and file name to send or receive. The package parses and capitalizes the input into eight character filenames and three character file types, in order to conform with the requirements of CP/M-86. When the input has been confirmed by the user, Xferfile either opens an existing file or creates a new one using the file control blocks (FCBs) described in Chapter IV. Files are read and sent or received and written in 128 byte blocks. The sending and receiving processes coordinate with each other and mutually come to a halt when the processes are finished. Xferfile returns to Xfermain after each instance of file transfer.

### 2. SUBROUTINES

#### a. Sendfile

- (1) Type: Procedure
- (2) Purpose: To send a file from one terminal to another terminal or to all active terminals in the network.
- (3) Description of Parameters: None
- (4) Subroutines Called:
  - Clearscrn
  - Reset\_disk
  - Drive\_select
  - Parse\_cap
  - Outconsole
  - Keyin
  - Open\_file
  - Set\_DMA
  - Enter\_machine
  - Set\_up
  - Read\_seq
  - Yes
  - No
  - Send\_block
  - Close\_file
- (5) Process Description:

Sendfile controls the sending of data from a file to the receiving terminal(s). The user specifies the disk, the file name, and the file type and Send\_file creates a file control block (FCB). Then the user specifies the destination terminal(s) and a connection is established. The file specified by the FCB is opened by utilizing CP/M-86 function call

#15 and data is read from the file into a data structure located at the specified direct memory address (DMA) in sequential 128 byte records by utilizing CP/M-86 function call #20. Sendfile tells the user if either an inappropriate file name or type is used, if the file specified is already open, or if the specified file cannot be found on the specified disk. If the receiver is active, the data structure containing the 128 byte record is then transmitted. Sendfile checks after each sequential read to determine if end of file has been reached and sends a yes or a no code accordingly. After the transmission has been completed, the file is closed.

b. Receivefile

(1) Type: Procedure

(2) Purpose: To receive and store a file from a sending terminal.

(3) Description of Parameters: None

(4) Subroutines Called:

Clearscrn  
Reset\_disk  
Drive\_select  
Parse\_cap  
Outconsole  
Keyin  
Delete\_file  
Create\_file  
Set\_DMA  
Endfile  
Write\_seq  
Recv\_block  
Close\_file  
Put\_str  
Put\_int

(5) Process Description:

Receivefile controls the reception of file data from a sending terminal. The user specifies the disk, the file name, and the file type to store the data and a file control block (FCB) is created. The file specified by the FCB is first deleted using CP/M-86 function call #19 to ensure no duplication occurs and then created by utilizing function call #22. 128 bytes of data is received and stored in a data structure located at the specified direct memory address (DMA). The data is written to the file using function call #21 and the the sender is told to send the next 128 bytes of data. Receivefile checks after each block of data is received to determine if end of file has occurred. Receivefile tells the user if either an inappropriate file name or type is used, if directory space is unavailable for the initial filename, if directory space is unavailable for new extents of an existing entry, or if disk space is full. After the

reception has been completed, the file is closed and the number of bytes received is displayed.

c. Parse\_cap

(1) Type: Procedure

(2) Purpose: To parse the file name and file type for invalid characters and to capitalize both to conform to CP/M-86 protocol.

(3) Description of Parameters: A value of type fcb indicating the FCB data structure is one output parameter. A value of type Integer indicating the file name length is the other output parameter.

(4) Subroutines Called:

Outconsole

Keyin

(5) Process Description:

Parse\_cap controls the creation of the user specified file name and file type. The user's input is accepted and displayed. Invalid characters are flagged and the input minus the invalid character is redisplayed for continued input. Parse\_cap then capitalizes the input and stores it in the appropriate fields of FCB.

C. MESSAGES

1. CONFIGURATION

a. Language - JANUS/Ada

b. Compiler Version - 1.47

c. Linker Version - 1.47

d. Target Hardware - Zenith Z-100 microcomputer

e. Operating System - CP/M-86 (version 1.14)

f. Package description:

The Messages package controls the sending and receiving of messages from the Z-100 workstations. A maximum message size of 1600 keystrokes (including error correction) organized in 20 lines of 80 each is implemented. The user types control z to end the message and control s to send it. If the user desires to retype the message entering any character other than control s will erase the first message. After input is confirmed, the message is transmitted and received as a single block of data. The sending and receiving processes coordinate with each other and mutually come to a halt when the processes are finished. Messages returns to Xfermain after each instance of message transfer.

2. SUBROUTINES

a. Talking

(1) Type: Procedure

(2) Purpose: To send a message to one or all of the terminals currently in the network.

(3) Description of Parameters: None

(4) Subroutines Called:

Clearscrn  
Outconsole  
Keyin  
Enter\_machine  
Setup  
Send\_block  
Yes

(5) Process Description:

Talking controls the transmission of message data to receiving terminal(s). The user is prompted to begin typing the message which is displayed simultaneously exactly as typed. Talking then prompts the user for the destination terminal(s) and, after establishing connection with the receiver(s), transmits the message as a single block of data. Messages sent to destination terminal #24 are routed to the bulletin board. Talking indicates end of message by transmitting a sequence of four end of message codes.

b. Listening

(1) Type: Procedure

(2) Purpose: To receive a message from a sending terminal.

(3) Description of Parameters: None

(4) Subroutines Called:

Clearscrn  
Outconsole  
Keyin  
Endmsg  
Recv\_block  
Put\_int

(5) Process Description:

Listening controls the reception of message data from a sending terminal. The message is received as a single block of data and terminated when a sequence of four end of message codes is received. The message is then displayed exactly as the sender typed it along with the number of bytes received.

D. DIRECTORY

1. CONFIGURATION

- a. Language - JANUS/Ada
- b. Compiler Version - 1.47
- c. Linker Version - 1.47
- d. Target Hardware - Zenith Z-100 microcomputer
- e. Operating System - CP/M-86 (version 1.14)
- f. Package description:

The Directory package controls the sending and receiving of directory information from the Z-100 workstations. A FCB is created with question marks (?) in each character of the file name and type. This serves as a wild card and en-

sure that the entire directory will be sent. Directory entries are sent or received in 128 byte blocks. The sending and receiving processes coordinate with each other and mutually come to a halt when the processes are finished. Directory returns to Xfermain after each instance of directory transfer.

## 2. SUBROUTINES

### a. Present\_dir

- (1) Type: Procedure
- (2) Purpose: To send a directory from one terminal to another terminal or to all active terminals in the network.
- (3) Description of Parameters: None
- (4) Subroutines Called:

- Clearscrn
- Reset\_disk
- Drive\_select
- Outconsole
- Keyin
- Enter\_machine
- Set\_up
- Set\_DMA
- Driveout
- Search\_first
- Send\_string
- Send\_dir
- Search\_next
- End\_block
- Yes
- No
- Put\_str

- (5) Process Description:

Present\_dir controls sending of data from a directory to the receiving terminal(s). The user specifies the disk and a file control block (FCB) is created with the wildcard filename and type (?????????.???). Then the user specifies destination terminal(s) and, if they are active, a connection is established. The directory is searched for the first match to the FCB by utilizing CP/M-86 function call #17 and the directory information is placed into a data structure located at the specified direct memory address (DMA) in 128 byte records. An offset is computed to the unique match within this record. Present\_dir transmits the 16 byte match to the receiving terminal(s). Function call #18 is used to obtain all subsequent matches. Present\_dir transmits a total of eight 16 byte segments before transmitting the end of block code, so the receiving terminal(s) receive a full, contiguous 128 byte block. Additionally, Present\_dir indicates end of directory by sending yes or no codes with each 128 bytes. The user is told if there are no files on a selected disk and a message stating such is sent to the receiving terminal(s).

- b. Receive\_dir
  - (1) Type: Procedure
  - (2) Purpose: To receive and store in a file the directory from a sending terminal.
  - (3) Description of Parameters: None
  - (4) Subroutines Called:
    - Clearscrn
    - Reset\_disk
    - Drive\_select
    - Parse\_cap
    - Outconsole
    - Keyin
    - Delete\_file
    - Create\_file
    - Set\_DMA
    - Endfile
    - Write\_seq
    - Recv\_block
    - Drivein
    - Close\_file

(5) Process Description:

Receive\_dir controls the reception of directory data from a sending terminal. The user specifies the disk, the file name, and the file type to store the data and a file control block (FCB) is created. The file specified by the FCB is first deleted using CP/M-86 function call #19 to ensure no duplication occurs and then created by utilizing function call #22. 128 bytes of data is received and stored in a data structure located at the specified direct memory address (DMA). Each 128 bytes of directory data is displayed and the user is given the option of storing the information in the file created. The data is written to the file using function call #21 and the the sender is told to transmit the next 128 bytes of data. Receive\_dir checks after each block of data is received to determine if end of directory has occurred. Receive\_dir tells the user if either an inappropriate file name or type is used, if directory space is unavailable for the initial filename, if directory space is unavailable for new extents of an existing entry, or if disk space is full. After directory reception has been completed, the file is closed.

F. WHO

1. CONFIGURATION

- a. Language - JANUS/Ada
- b. Compiler Version - 1.47
- c. Linker Version - 1.47
- d. Target Hardware - Zenith Z-100 microcomputer
- e. Operating System - CP/M-86 (version 1.14)

f. Package description:  
The Who package controls the inquiry for and reception of net status; which machines are currently active in the network.

## 2. SUBROUTINES

a. Whos\_there  
(1) Type: Procedure  
(2) Purpose: To request and receive net status information.  
(3) Description of Parameters: None  
(4) Subroutines Called:  
Clearscrn  
Recv\_block  
Enter\_machine  
Setup  
Put\_int  
(5) Process Description:  
Whos\_there prompts the user to enter his terminal number for both the source and destination terminals. After a connection has been established, the net status information from the Concentrator is received and displayed.

## G. BULLBRD

### 1. CONFIGURATION

a. Language - JANUS/Ada  
b. Compiler Version - 1.47  
c. Linker Version - 1.47  
d. Target Hardware - Zenith Z-100 microcomputer  
e. Operating System - CP/M-86 (version 1.14)  
f. Package description:  
The Bullbrd package controls the inquiry for receiving the current messages from the bulletin board and storing them on file.

### 2. SUBROUTINES

a. Recv\_bulletin  
(1) Type: Procedure  
(2) Purpose: To receive bulletin board information.  
(3) Description of Parameters: None.  
(4) Subroutines Called:  
Clearscrn  
Enter\_machine  
Setup  
Receivefile  
Keyin  
(5) Process Description:  
Recv\_bulletin prompts the user to enter #24 for the destination terminal. Then, if the bulletin board (terminal #24) is active, Recv\_bulletin establishes a connection. It calls Receivefile which handles the actual file transfer

of the data from the bulletin board and stores it in a user specified file. Error messages are displayed if either an inappropriate file name or type is used, if directory space is unavailable for the initial filename, if directory space is unavailable for new extents of an existing entry, or if disk space is full. After reception of the bulletin board data has been completed, the file is closed.

## H. BULLETIN

### 1. CONFIGURATION

- a. Language - JANUS/Ada
- b. Compiler Version - 1.47
- c. Linker Version - 1.47
- d. Target Hardware - Zenith Z-100 microcomputer
- e. Operating System - CP/M-86 (version 1.14)
- f. Package description:

Bulletin is the package that implements the network bulletin board. It controls the reception of individual messages destined for the bulletin board and the transmission in 128 byte blocks suitable for file transfer of all current messages at a given time. Messages are received in a single block. The bulletin board has the capacity of twenty messages of 1600 bytes each. When the capacity is exceeded, the first one in is the first one out. Messages are stored as an array of records with fields for the message and its length.

### 2. SUBROUTINES

- a. Contained: None.
- b. Called:
  - Clearscrn
  - Active
  - Waiting
  - Recv\_block
  - Endmsg
  - Send\_block
  - No
  - Yes

### 3. COMMENTS

The network bulletin board is 'hard wired' into port #24. It is invoked by typing the command "bulletin". A message is displayed stating that this terminal is the network bulletin board. The program loops endlessly waiting for requests to receive messages or send current message inventory. If another terminal at another port is desired to be the network bulletin board, the package Poll must be changed to reflect the new port. (see Appendix C.) There can be only one bulletin board active at a time.

# I. MYUTIL

## 1. CONFIGURATION

- a. Language - JANUS/Ada
- b. Compiler Version - 1.47
- c. Linker Version - 1.47
- d. Target Hardware - Zenith Z-100 microcomputer
- e. Operating System - CP/M-86 (version 1.14)
- f. Package description:

The Myutil package contains various utility programs in JANUS/Ada.

## 2. SUBROUTINES

### a. Put\_int

- (1) Type: Procedure
- (2) Purpose: To display integers.
- (3) Description of Parameters: A value of type integer to be displayed is the input parameter.
- (4) Subroutines Called:  
My\_put
- (5) Process Description:  
Put\_int takes the input parameter and determines its sign. Then Put\_int strips off each digit, starting from the left and removing leading zeros, and displays it.

### b. Clearscrn

- (1) Type: Procedure
- (2) Purpose: To clear the display screen
- (3) Description of Parameters: None.
- (4) Subroutines Called:  
Outconsole
- (5) Process Description:  
Clearscrn outputs the CP/M-86 clear screen codes.

### c. Enter\_machine

- (1) Type: Procedure
- (2) Purpose: To get the user's input of source and destination machines.
- (3) Description of Parameters: A value of type Integer indicating the source and destination machines are the output parameters.
- (4) Subroutines Called:  
Outconsole  
Keyin
- (5) Process Description:  
Enter\_machine prompts the user for input and then displays it for confirmation. The keyboard input is converted to Integer values which are assigned to the output parameters.

d. Drive\_select  
 (1) Type: Procedure  
 (2) Purpose: To get the user's selection of disk drive.  
 (3) Description of Parameters: A value of type byte indicating the disk drive selection is the output parameter.  
 (4) Subroutines Called:  
     Outconsole  
     Keyin  
     Select\_drive  
 (5) Process Description:  
 Drive\_select prompts the user for input and then displays it for confirmation. Lower case and upper case inputs are treated the same. The appropriate parameter is then passed to the CP/M-86 function call #14, which selects the drive. The drive selection is then returned as an output parameter.

## H. MYASMLIB

### 1. CONFIGURATION

- a. Language - JANUS/Assembler
- b. Compiler Version - 1.50
- c. Linker Version - 1.50
- d. Target Hardware - Zenith Z-100 microcomputer
- e. Operating System - CP/M-86 (version 1.14)
- f. Package description:

The Myasmlib package contains the library of assembly language subroutines for the Z-100 workstations.

### 2. COMMENTS

a. JANUS/Ada parameters for JANUS/Assembler modules are placed on the stack at subroutine call with the last parameter closest to the top and the return address on the very top. Discrete values are passed for parameters of type IN and the address of the parameter is passed for types OUT and IN OUT. Upon return to the calling program OUT and IN OUT parameters are removed from the stack along with the return address.

b. The following subroutines involve input and output to other terminals via the modem port (J2):

```
Send_block
Yes
No
Recv_block
Endfile
Active
Waiting
Setup
Fndmsg
End_block
```

Send\_string  
Send\_dir  
Driveout  
Drivein  
Off

The method of transmission used involves an immediate echo checking procedure. The sending subroutine transmits bytes of data one at a time. The receiving subroutine receives the data bytes and echos each one immediately upon reception. The sending subroutine compares the echo with the transmitted data and checks for error. If an error is detected, the sending subroutine either simply retransmits or sends an error code to tell the receiving subroutine that the data previously received (and processed) was in error, followed by the retransmitted data. All receiving subroutines contain a finite waiting time after the last data was received to ensure that the final echo was received properly.

### 3. SUBROUTINES

#### a. Create\_file

(1) Type: Procedure

(2) Purpose: To create files specified by the FCB.

(3) Description of Parameters: A value of type Integer containing the FCB address is the input parameter. A value of type Integer indicating the result of the CP/M-86 function call is the output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Create\_file implements the CP/M-86 function call #22. It creates (and opens) the file specified by the FCB. It returns a 0, 1, 2, or 3 if the operation was successful and 255 (0FFh) if no more directory space is available.

#### b. Close\_file

(1) Type: Procedure

(2) Purpose: To close files specified by the FCB.

(3) Description of Parameters: A value of type Integer containing the FCB address is the input parameter. A value of type Integer indicating the result of the CP/M-86 function call is the output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Close\_file implements the CP/M-86 function call #16. It closes the file specified by the FCB. It returns a 0, 1, 2, or 3 if the operation was successful and 255 (0FFh) if the file could not be found.

c. Oper\_file

(1) Type: Procedure

(2) Purpose: To open files specified by the FCB.

(3) Description of Parameters: A value of type Integer containing the FCB address is the input parameter. A value of type Integer indicating the result of the CP/M-86 function call is the output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Open\_file implements the CP/M-86 function call #15. It opens the file specified by the FCB. It returns a 0, 1, 2, or 3 if the operation was successful and 255 (0FFh) if the file could not be found.

d. Read\_seq

(1) Type: Procedure

(2) Purpose: To read data from an open file specified by the FCB.

(3) Description of Parameters: A value of type Integer containing the FCB address is the input parameter. A value of type Integer indicating the result of the CP/M-86 function call is the output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Read\_seq implements the CP/M-86 function call #20. It reads sequential 128 byte records from an open file specified by the FCB into memory at the current DMA. It returns a 0 if the operation was successful and a 1 if no data exists at the next record position. Normally this indicates end of file.

e. Write\_seq

(1) Type: Procedure

(2) Purpose: To write data to an open file specified by the FCB.

(3) Description of Parameters: A value of type Integer containing the FCB address is the input parameter. A value of type Integer indicating the result of the CP/M-86 function call is the output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Write\_seq implements the CP/M-86 function call #21. It writes sequential 128 byte records to an open file specified by the FCB from memory at the current DMA. It returns a 0 if the operation was successful and a 1 if there is no more space in the directory for a new extent entry required when the file is larger than 16K (or a multiple of 16K), or a 2 if there is no more space on the disk for new data records.

f. Set\_DMA

(1) Type: Procedure

(2) Purpose: To specify the Direct Memory Address (DMA).

(3) Description of Parameters: A value of type Integer containing the DMA address is the input parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Set\_DMA implements the CP/M-86 function call #26. It sets the DMA to the value of the input parameter, which is normally the address of a specific data structure.

g. Delete\_file

(1) Type: Procedure

(2) Purpose: To delete a file specified by the FCB.

(3) Description of Parameters: A value of type Integer containing the FCB address is the input parameter. A value of type Integer indicating the result of the CP/M-86 function call is the output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Delete\_file implements the CP/M-86 function call #19. It deletes the file specified by the FCB. It returns a 0 if the operation was successful and 255 (0FFh) if the file could not be found.

h. Select\_disk

(1) Type: Procedure

(2) Purpose: To select a specified disk drive.

(3) Description of Parameters: A value of type Integer containing the selected disk drive is the input parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Select\_disk implements the CP/M-86 function call #14. It designates the selected disk (0 = A, 1 = B, etc.) as the default drive for subsequent disk operations.

i. Reset\_disk

(1) Type: Procedure

(2) Purpose: To reset all disk drive systems.

(3) Description of Parameters: None.

(4) Subroutines Called: N/A.

(5) Process Description:

Reset\_disk implements the CP/M-86 function call #13. It restores the file system to reset state where all drives are set to read/write and A is the default drive for subsequent disk operations.

j. Keyin

(1) Type: Procedure

(2) Purpose: To obtain input from the keyboard.

(3) Description of Parameters: A value of type Byte obtained from the keyboard is the output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Keyin implements the CP/M-86 function call #06. It loops infinitely until a key is pressed and then the character obtained is returned as the output parameter.

k. Outconsole

(1) Type: Procedure

(2) Purpose: To display output to the console device.

(3) Description of Parameters: A value of type Byte to be displayed is the input parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Outconsole implements the CP/M-86 function call #02.

l. Send\_block

(1) Type: Procedure

(2) Purpose: To send a block of data to another terminal via the modem port.

(3) Description of Parameters: A value of type Integer indicating the address of the data structure to be sent is one input parameter. A value of the type Integer indicating the size of the data structure is the other input parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Send\_block sends a block of data out the modem port (J2) sequentially one byte at a time, decrementing the size of the data block until it equals zero. Then it transmits a sequence of four end of block codes (0FFh) to indicate that end of block has been reached. Any data structure may be sent using this procedure.

m. Yes

(1) Type: Procedure

(2) Purpose: To indicate to the receiving terminal(s) that an end of process has been reached.

(3) Description of Parameters: None.

(4) Subroutines Called: N/A.

(5) Process Description:

Yes sends out a sequence of four end of process codes (0F1h) when a particular process is finished.

n. No  
(1) Type: Procedure  
(2) Purpose: To indicate to the receiving terminal(s) that a process is still ongoing.  
(3) Description of Parameters: None.  
(4) Subroutines Called: N/A.  
(5) Process Description:  
No sends out a single no code (6Eh) to indicate that a process is not finished.

o. Recv\_block  
(1) Type: Procedure  
(2) Purpose: To receive a block of data from another machine via the modem port.  
(3) Description of Parameters: A value of type Integer indicating the address of the data structure in which the received data will be stored is the input parameter. A value of the type Integer indicating the amount of data received is the output parameter.  
(4) Subroutines Called: N/A.  
(5) Process Description:  
Recv\_block receives a block of data from the modem port (J2) sequentially one byte at a time, incrementing the size of the data block until a sequence of four end of block codes (0FFh) is received indicating that end of block has been reached. Any data structure may be received using this procedure.

p. Endfile  
(1) Type: Procedure  
(2) Purpose: To determine whether or not a file or directory transfer process has finished  
(3) Description of Parameters: A value of the type Boolean indicating finish or not is the output parameter.  
(4) Subroutines Called: N/A.  
(5) Process Description:  
Endfile waits to receive either a single no code (6Eh) or a sequence of four end of process codes (0F1h). If a no code is received the value false is returned to the output parameter, if a sequence of four end of process codes is received a value of true is returned.

q. Active  
(1) Type: Procedure  
(2) Purpose: To indicate to the Concentrator that a particular terminal is in the network.  
(3) Description of Parameters: None.  
(4) Subroutines Called: N/A.  
(5) Process Description:  
Active sends out an active code (0D0h) when the terminal is ready to communicate with the network.

r. Waiting

- (1) Type: Procedure
- (2) Purpose: To receive the status the Concentrator has for an active terminal.
- (3) Description of Parameters: A value of type byte indicating the status.
- (4) Subroutines Called: N/A.
- (5) Process Description:  
Waiting receives the status from the Concentrator that a terminal's active code prompted. A 0 indicates nothing waiting, a 1 indicates file waiting, a 2 indicates message waiting, and a 3 indicates that the inactive receiving terminal to which this terminal had previously tried to send is now active.

s. Setup

- (1) Type: Procedure
- (2) Purpose: To establish a connection with another terminal via the Concentrator.
- (3) Description of Parameters: A value of type Integer indicating the address of the connection data structure. A value of the type Boolean indicating the result of the connection set up attempt is the output variable.
- (4) Subroutines Called: N/A.
- (5) Process Description:  
Setup transmits to the Concentrator the connection data structure for the purposes of establishing a connection with another terminal. The connection data structure consists of destination field for the destination terminal(s), a source field for the source terminal, and a process field for the process to be accomplished. Setup sends out a sequence of four end of block codes (0FFh) to indicate the end of the data structure. It then waits to determine the result of the connection set up attempt. If the connection was successful, send\_ready is set to true. If it was not because the destination was inactive, then send\_ready is set to false.

t. Myput

- (1) Type: Procedure
- (2) Purpose: To display integers.
- (3) Description of Parameters: A value of type Integer indicating the integer to be displayed.
- (4) Subroutines Called: N/A.
- (5) Process Description:  
Myput converts the integer input into its ascii equivalent and uses CP/M-86 function call #02 to display it.

u. Put\_str

- (1) Type: Procedure
- (2) Purpose: To display strings.
- (3) Description of Parameters: A value of type String indicating the address of the string to be displayed.

(4) Subroutines Called: N/A.

(5) Process Description:

Put\_str is passed the address of the string to be displayed. The first byte at that address is the string length. The succeeding byte are displayed using CP/M-86 function call #02 until the string length counter equals zero.

v. Endmsg

(1) Type: Procedure

(2) Purpose: To determine if end of message has occurred.

(3) Description of Parameters: None.

(4) Subroutines Called: N/A.

(5) Process Description:

Endmsg waits until a sequence of four end of message codes (0F1h) is received.

w. Search\_first

(1) Type: Procedure

(2) Purpose: To search for the first directory match.

(3) Description of Parameters: A value of the type Integer indicting the buffer address for the directory record is one input parameter. A value of the type Integer indicting the FCB address is the other input parameter. A value of the type Integer indicting the result of the function is one output parameter. A value of the type Integer indicting the location of the matched directory entry is the other output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Search\_first implements CP/M-86 function call #17. It searches the directory of the specified drive for the first match of the file name and type of the specified FCB. When a successful match is found, Search\_first places the 128 byte record containing the matched directory entry and returns an offset code (0, 1, 2, or 3) that specifies the exact location of the entry within the record using the formula: location of entry = (offset \* 32) + DMA. If a match cannot be found, then Search\_first returns 255 (0FFh).

x. Search\_next

(1) Type: Procedure

(2) Purpose: To search for the next directory match.

(3) Description of Parameters: A value of the type Integer indicting the buffer address for the directory record is one input parameter. A value of the type Integer indicting the FCB address is the other input parameter. A value of the type Integer indicting the result of the function is one output parameter. A value of the type Integer

indicating the location of the matched directory entry is the other output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Search\_next implements CP/M-86 function call #18.

It searches the directory of the specified drive for the next match of the file name and type of the specified FCB. When a successful match is found, Search\_first places the 128 byte record containing the matched directory entry and returns an offset code (0, 1, 2, or 3) that specifies the exact location of the entry within the record using the formula: location of entry = (offset \* 32) + DMA. If a match cannot be found, then Search\_first returns 255 (0FFh).

y. End\_block

(1) Type: Procedure

(2) Purpose: To indicate end of block during directory transfer.

(3) Description of Parameters: None.

(4) Subroutines Called: N/A.

(5) Process Description:

End\_block transmits a sequence of four end of block codes (0FFh) to indicate end of block during directory transfers.

z. Send\_string

(1) Type: Procedure

(2) Purpose: To transmit strings.

(3) Description of Parameters: A value of type String indicating the address of the string to be output is the input parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Send\_string is passed the address of the string to be transmitted. The first byte of the input parameter is the length of the string. Send\_string transmits the succeeding bytes one at a time out the modem port (J2) until the string length counter equals zero.

aa. Send\_dir

(1) Type: Procedure

(2) Purpose: To transmit matched directory entries.

(3) Description of Parameters: A value of type Integer indicating the address of the matched directory to be output is one input parameter. A value of the type Integer indicating the size of the directory entry to be transmitted is the other input parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Send\_dir transmits the bytes of the matched directory entry sequentially, one byte at a time, via the modem port (J2) until the directory length counter equals zero.

bb. Driveout  
(1) Type: Procedure  
(2) Purpose: To transmit the disk drive used in a directory transfer.  
(3) Description of Parameters: A value of type Byte indicating the specified drive to be output is the input parameter.  
(4) Subroutines Called: N/A.  
(5) Process Description:  
Driveout transmits the byte representing the specified drive via the modem port (J2).

cc. Drivein  
(1) Type: Procedure  
(2) Purpose: To receive the disk drive used in a directory transfer.  
(3) Description of Parameters: A value of type Byte indicating the specified drive received is the output parameter.  
(4) Subroutines Called: N/A.  
(5) Process Description:  
Drivein receives the byte representing the specified drive via the modem port (J2).

dd. Off  
(1) Type: Procedure  
(2) Purpose: To inform the Concentrator that a terminal is no longer active.  
(3) Description of Parameters: None.  
(4) Subroutines Called: N/A.  
(5) Process Description:  
Off transmits the off code (0Fh) via the modem port (J2).

## J. NAMES

### 1. CONFIGURATION

- a. Language - JANUS/Ada
- b. Compiler Version - 1.47
- c. Linker Version - 1.47
- d. Target Hardware - Intel 86/12A SBC
- e. Operating System - CP/M-86 (version 1.14)
- f. Package description:

The Names specification contains the following global objects:

TYPE conctn  
connection  
TYPE blk  
block  
block\_size  
retrn

space  
input  
pause  
confirm  
drive  
code  
dest  
srce  
send\_ready

MAINTENANCE MANUAL FOR CONCENTRATOR PROGRAMS

## A. POLL

## 1. CONFIGURATION

- a. Language - JANUS/Ada
- b. Compiler Version - 1.47
- c. Linker Version - 1.47
- d. Target Hardware - Intel 86/12A SBC
- e. Operating System - CP/M-86 (version 1.14)
- f. Package description:

The Poll package is the main program for the Concentrator acting as a network switchboard. It contains an infinite loop that polls each one of 23 ports (bypassing port #24 which is designated as the bulletin board port and is never polled) continuously. Poll controls the satisfying of requests from the Z-100 workstations and the storing of those requests in a FIFO queue that cannot be satisfied. For each port Poll checks the queue for waiting processes. If there is a process waiting, Poll will satisfy the waiting process and then attempt to satisfy the polled port's original request. If not, Poll will immediately attempt to satisfy the polled port's request. Poll is responsible for decoding each workstation's request and establishing the proper path between sender and receiver(s). It is also responsible for maintaining the net status; the list of all currently active ports, and transmitting it to workstations requesting it.

## 2. SUBROUTINES

## a. Convert

(1) Type: Procedure

(2) Purpose: To convert the byte information received from the Z-100 workstations concerning source and destination terminals into their integer physical addresses.

(3) Description of Parameters: A value of type integer indicating the index position in the queue of the current process\_status record is the input variable.

(4) Subroutines Called: None

(5) Process Description:

Convert is two large case statements which translate the bytes received from the workstations into the proper integer physical addresses for each port.

## b. Poll calls the following subroutines:

Check\_port  
 Check\_queue  
 Connect  
 Convert  
 Xfer  
 Connxfer

No\_xfer  
Broadcast  
Net\_stat  
Queue\_status

### 3. COMMENTS

Poll is resident in the Concentrator and is invoked by typing the command "poll". It will not function properly if all three 8538 BLC expansion boards are not installed.

To change the port number of the bulletin board, the polling sequence must be changed to bypass the new bulletin board port and the automatic routing routines that route bulletin board requests to the predesignated port must be changed accordingly. Additionally the value of 'bullport' in the procedure Broadcast must be changed.

To expand the system for greater numbers of terminals, add the appropriate number of expansion boards and change the following constants: 'boardno', 'machno', 'maxque', and the procedure Convert which contains the physical addresses. Additionally, the value of 'boardnum' must be changed in the procedure Broadcast.

## B. CONUTIL

### 1. CONFIGURATION

- a. Language - JANUS/Ada
- b. Compiler Version - 1.47
- c. Linker Version - 1.47
- d. Target Hardware - Intel 86/12A SBC
- e. Operating System - CP/M-86 (version 1.14)
- f. Package description:

The Concutil package contains utility programs for the Concentrator.

### 2. SUBROUTINES

#### a. Check\_queue

(1) Type: Procedure

(2) Purpose: To check the queue for waiting processes.

(3) Description of Parameters: A value of type Integer indicating the number of processes waiting in the queue is one input parameter. A value of type Integer indicating the port for whom waiting processes are being checked is the other input parameter. A value of type Integer indicating the position index of the waiting process is one output variable. A value of type Boolean indicating whether or not there are waiting processes is the other output variable.

(4) Subroutines Called:

Check\_port  
Queue\_status

(5) Process Description:

Check\_queue checks the queue for waiting processes. If there are none in the queue then false is returned. If there are processes in the queue, a check is made if they are waiting for the specified port. If not, false is returned. If there are processes in the queue and they are waiting for the specified port, their position in the queue is returned along with a value of true. Check\_queue then tells the specified port what is waiting for it and tells the sender of the waiting process to resend.

b. Net\_stat

(1) Type: Procedure

(2) Purpose: To decode and transmit the list of active terminals in the network to the requestor.

(3) Description of Parameters: A value of type integer indicating the port for which the net status is intended.

(4) Subroutines Called:

Send\_who\_block

(5) Process Description:

Net\_stat controls the transmission of the list of active network terminals. Net\_stat checks the data structure 'active\_list' for those terminals for which true has been recorded, indicating that they are active and stores the terminal number information in the data structure 'who\_list'. It is 'who\_list' that is transmitted to the requestor.

C. COASMLIB

1. CONFIGURATION

a. Language - JANUS/Assembler

b. Compiler Version - 1.50

c. Linker Version - 1.50

d. Target Hardware - Intel 86/12A SBC

e. Operating System - CP/M-86 (version 1.14)

f. Package description:

The Coasmlib package contains the library of assembly language subroutines for the Concentrator.

2. COMMENTS

a. JANUS/Ada parameters for JANUS/Assembler modules are placed on the stack at subroutine call with the last parameter closest to the top and the return address on the very top. Discrete values are passed for parameters of type IN and the address of the parameter is passed for types OUT and IN OUT. Upon return to the calling program OUT and IN OUT parameters are removed from the stack along with the return address.

b. The following subroutines involve input and output:

Check\_port  
Connect  
Queue\_status  
Send\_who\_block  
Broadcast  
Concxfer  
Xfer  
No\_xfer

The method of transmission used involves an immediate echo checking procedure. The sending subroutine transmits bytes of data one at a time. The receiving subroutine receives the data bytes and echos each one immediately upon reception. The sending subroutine compares the echo with the transmitted data and checks for error. If an error is detected, the sending subroutine either simply retransmits or sends an error code to tell the receiving subroutine that the data previously received (and processed) was in error, followed by the retransmitted data. All receiving subroutines contain a finite waiting time after the last data was received to ensure that the final echo was received properly.

### 3. SUBROUTINES

#### a. Check\_port

(1) Type: Procedure

(2) Purpose: To poll network ports looking for the active signal

(3) Description of Parameters: A value of type Integer containing the address of the port to be polled is the input variable. A value of type Boolean indicating the result of the poll is the output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Check\_port polls the port indicated looking for the active signal (0D0h). It will poll for a finite period of time. If no signal, or the wrong signal, is found, ready is set to false. If the active signal is found, ready is set to true. Check\_port is used for two purposes. It is used to initially poll ports for incoming requests (indicated by active signal) and to poll a destination port to determine if it is ready to receive.

#### b. Connect

(1) Type: Procedure

(2) Purpose: To receive the connection record transmitted by the sending Z-100.

(3) Description of Parameters: A value of type Integer containing the address of the port from which the connection record is to be received is the input parameter. A value of type Integer indicating the address of the data structure in which the connection record is to be stored is the output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Connect receives the connection record, sequentially, one byte at a time and stores it in the data structure indicated by the input parameter until a sequence of four finish codes (0FFh), indicating end of block, are received.

c. Queue\_status

(1) Type: Procedure

(2) Purpose: To inform a polled port of the status of waiting processes in the queue.

(3) Description of Parameters: A value of type Integer containing the address of the polled port is one input parameter. A value of type Byte indicating the process waiting in the queue (or none) is the other output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Queue\_status transmits to the port indicated by one input parameter the byte value of the process waiting for that port (or none).

d. Send\_who\_block

(1) Type: Procedure

(2) Purpose: To transmit the data structure containing the net status.

(3) Description of Parameters: A value of type Integer containing the address of the port to which the net status is destined is one input parameter. A value of type Integer indicating the address of the data structure containing the net status is another input parameter. A value of type Integer indicating the length of the data structure is the last output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Send\_who\_block transmits the data structure containing the net status sequentially, one byte at a time, until the length counter equals zero. Then it sends out a sequence of four finish codes (0FFh), indicating end of block.

e. Broadcast

(1) Type: Procedure

(2) Purpose: To transfer data in a broadcast mode: from one to many.

(3) Description of Parameters: A value of type Integer containing the address of the sending port is the input parameter. A value of type Byte containing the address used to store the input temporarily is the output parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Broadcast controls the transmission of data from the sending port to all receiving ports. The data is transmitted one byte at a time as rapidly as possible to all ports (bypassing the sender, and the bulletin board). The first byte is received from the sending port specified in the first input parameter. It is then sent in quick succession to all the ports beginning with the first port in the network. Broadcast increments the receiving port until all the ports are addressed and the byte is transmitted. The input is saved temporarily for error checking. Then Broadcast loops back to receive the echoes. If there are any echoes in error, that port address is saved until all the echoes have been received. Then all the addresses in error are serviced, one at a time until the error is corrected. At this point, or if there were no errors, Broadcast echoes back to the sender the received byte for the sender's error checking. If there was an error, the sender sends out an error code then the retransmitted byte and the entire process is repeated until the error is corrected. If there is no error, the next byte is transmitted to the Concentrator until a sequence of four end of process code echoes (ZF1h) are received from all the receiving terminals. Broadcast waits only a finite period of time for echoes from each receiving terminal, so if a terminal is inactive, the bytes transmitted to it will be continuously overwritten. No attempt is made to bypass inactive terminals.

f. Concxfer

(1) Type: Procedure

(2) Purpose: To transfer data from a sending terminal to a single destination terminal.

(3) Description of Parameters: A value of type Integer containing the address of the sending port is one input parameter. A value of type Integer containing the address of the receiving port is the other input parameter.

(4) Subroutines Called: N/A.

(5) Process Description:

Concxfer controls the transmission of data between two terminals. The first byte is received from the sending port indicated by the first input parameter and transmitted from the receiving port indicated by the second parameter. The echo is then received from the receiver and transmitted to the sender. Concxfer performs no error checking; it merely passes data and echoes back and forth until it receives a sequence of four end of process code echoes (ZF1h) from the receiver. At that point it terminates the connection.

g. Xfer

- (1) Type: Procedure
- (2) Purpose: To inform the sending port that a connection has been established.
- (3) Description of Parameters: A value of type Integer containing the address of the sending port is the input parameter.
- (4) Subroutines Called: N/A.
- (5) Process Description:  
Xfer transmits to the sending port a code (01h) informing it that a connection has been established.

h. No xfer

- (1) Type: Procedure
- (2) Purpose: To inform the sending port that a connection can not be established.
- (3) Description of Parameters: A value of type Integer containing the address of the sending port is the input parameter.
- (4) Subroutines Called: N/A.
- (5) Process Description:  
No xfer transmits to the sending port a code (00h) informing it that a connection can not be established.

D. CONCNAM

1. CONFIGURATION

- a. Language - JANUS /Ada
- b. Compiler Version - 1.47
- c. Linker Version - 1.47
- d. Target Hardware - Intel 86/12A SBC
- e. Operating System - CP/M-86 (version 1.14)
- f. Package description:

The Concname specification contains the following global objects:

TYPE process\_status  
max\_que  
TYPE que  
queue  
resend  
zero  
rchno  
ready  
active\_list

## APPENDIX D

LISTING OF Z-100 PROGRAMS

PACKAGE Names IS

--\* GLOBAL TYPES, CONSTANTS, AND VARIABLES \*--

```

TYPE conctn IS
  RECORD
    process: byte;
    source: byte;
    destination: byte;
  END RECORD;

connection: conctn;

TYPE blk IS ARRAY (1..132) OF byte;

block: blk;

block_size: CONSTANT Integer := 128;
retrn: CONSTANT BYTE := byte (16#0D#);
space: CONSTANT BYTE := byte (16#20#);
input: byte;
pause: byte;
confirm: byte;
drive: byte;
code: integer;
dest, srce: Integer;
send_ready: Boolean;

```

END Names;

=====

PACKAGE Xferfile IS

```

TYPE fcb IS
  RECORD
    dr: byte;
    fn: ARRAY (1..8) OF byte;
    ft: ARRAY (1..3) OF byte;
    ex: byte;
    s1: byte;
    s2: byte;
    rc: byte;
    dn: ARRAY (1..16) OF byte;
    cr: byte;
  END RECORD;

```

```

fcb1: fcb;
fn_length: Integer;

PROCEDURE Sendfile;
PROCEDURE Receivefile;
PROCEDURE Parse_cap (fcb2: OUT fcb; fnlen: OUT Integer);
END Xferfile;

```

```

WITH Myutil, Myasmlib, Names;
PACKAGE BODY Xferfile IS
  USE Myutil, Myasmlib, Names;

```

```

PROCEDURE Sendfile IS

```

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: JULY 1986
--* DESCRIPTION: SENDFILE PROMPTS THE USER FOR FILE NAME *--
--* AND TYPE, OPENS THE FILE AND TRANSMITS EACH 128 BYTE *--
--* RECCRD UNTIL END OF FILE. UPON COMPLETION, SENDFILE *--
--* CLOSSES THE FILE AND RETURNS TO MAIN MENU *--

```

```

xbytes: integer := 0;
ctrl_f: CONSTANT BYTE := byte (16#06#);

```

```

BEGIN

```

```

  Clearscrn;

```

```

  --* SET FCB FOR FILE OPERATIONS *--

```

```

  fcb1.dr := byte(0);
  fcb1.ex := byte(0);
  Reset_disk;

```

```

  New_line;

```

```

  --* PROMPT USER FOR DISK DRIVE *--

```

```

  Drive_select (drive);
  New_line;

```

```

  --* PROMPT USER FOR FILE NAME AND TYPE *--

```

```

  LOOP

```

```

    Put ("ENTER FILE NAME."); New_line;

```

```

    LOOP

```

```

      Put ("FN.FT: ");
      Parse_cap (fcb1, fn_length);
      Put ("FILE ");
      Outconsole (drive);

```

```

Put (":");
FOR i IN 1..fn length LOOP
    Outconsole (fcb1.fn (i) );
END LOOP;
Put (".");
FOR i IN 1..3 LOOP
    Outconsole (fcb1.ft (i) );
END LOOP;
Put (" IS SELECTED. PRESS RETURN TO CONFIRM, ");
Put ("ANY OTHER KEY TO RESELECT.");
Keyin (confirm);
New_line;
IF confirm = retrn THEN
    EXIT;
END IF;
Put ("ENTRY CANCELLED. REENTER FN:FT."); New_line;
New_line;
END LOOP;

Open_file (fcb1'ADDRESS, code);
fcb1.cr := byte (0);

--* SET DMA TO ADDRESS OF DATA STRUCTURE THAT WILL *--
--* HOLD DATA READ FROM FILE *--

Set_DMA (block'ADDRESS);

--* IF CODE = 255 (0FFh) THEN FILE COULD NOT BE *--
--* FOUND AND PROMPT USER TO REENTER FILE NAME AND *--
--* TYPE *--

IF code /= 255 THEN
    Put ("FILE ");
    Outconsole (drive);
    Put (":");
    FOR i IN 1..fn length LOOP
        Outconsole (fcb1.fn (i) );
    END LOOP;
    Put (".");
    FOR i IN 1..3 LOOP
        Outconsole (fcb1.ft (i) );
    END LOOP;
    Put (" IS OPENED."); New_line;
    Clearscrn;
    EXIT;
END IF;
Put ("FILE NOT FOUND. PLEASE TRY AGAIN."); New_line;
END LOOP;

--* PROMPT USER FOR DESTINATION AND SOURCE TERMINAL #'s *--

Enter_machine (dest, srce);

```

```

--* CREATE CONNECTION RECORD *--

connection.destination := byte (dest);
connection.source := byte (srce);
connection.process := ctrl_f;

--* ESTABLISH CONNECTION WITH DESTINATION *--

Put ("WAITING..."); New_line; New_line;
Setup (connection'ADDRESS, send_ready);
IF send_ready THEN
  IF dest = 0 THEN
    Put ("FOR BROADCAST, PAUSE TO ALLOW RECEIVER TO ");
    Put ("GET READY"); New_line;
    Put ("PRESS ANY KEY TO SEND. ");
    Keyin (pause); New_line; New_line;
  END IF;
  Put ("CONNECTION ESTABLISHED, SENDING FILE... ");
  New_line; New_line;

--* READ AND SEND FILE IN 128 BYTE BLOCKS *--

LOOP
  Read_seq (fcb1'ADDRESS, code);
  IF code = 1 THEN
    Yes;
    EXIT;
  ELSE
    No;
  END IF;
  Send_block (block'ADDRESS, block_size);
END LOOP;

Close_file (fcb1'ADDRESS, code);
Put ("FILE SENT."); New_line;
ELSE
  Put ("FILE NOT SENT. DESTINATION INACTIVE."); New_line;
END IF;
Put ("PRESS ANY KEY TO CONTINUE. ");
Keyin (pause);

END Sendfile;

```

---

PROCEDURE Receivefile IS

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: JULY 1986
--* DESCRIPTION: RECEIVEFILE PROMPTS THE USER FOR FILE *--
--* NAME AND TYPE, CREATES THE FILE, AND RECEIVES THE 128 *--

```

```

--* BYTE BLOCK FROM THE SOURCE AND WRITES TO DISK UNTIL *-
--* END OF FILE. THEN IT CLOSES THE FILE AND DISPIAYS # OF *-
--* BYTES RECEIVED. LASTLY IT RETURNS TO MAIN MENU. *-

```

```

rbytes: Integer := 0;
length: Integer;
reason2: STRING := "END OF FILE.";
finished: Boolean := false;

```

```

BEGIN

```

```

  Clearscrn;

```

```

  --* SET FCB FOR FILE OPERATIONS *--

```

```

  fcb1.dr := byte(0);
  fcb1.ex := byte(0);
  Reset_disk;

```

```

  --* PROMPT USER FOR DISK DRIVE *--

```

```

  New_line;
  Drive_select (drive);
  New_line;
  Put ("ENTER FILE NAME."); New_line;

```

```

  --* PROMPT USER FOR FILE NAME AND TYPE *--

```

```

  LOOP

```

```

    Put ("FN.FT: ");
    Parse_cap (fcb1, fn_length);
    New_line;
    Put ("FILE ");
    Outconsole (drive);
    Put (":");
    FOR i IN 1..fn_length LOOP
      Outconsole (fcb1.fn (i) );
    END LOOP;
    Put (".");
    FOR i IN 1..3 LOOP
      Outconsole (fcb1.ft (i) );
    END LOOP;
    Put (" IS SELECTED. PRESS RETURN TO CONFIRM, ");
    New_line;
    Put ("ANY OTHER KEY TO RESELECT.");
    Keyin (confirm);
    New_line;
    IF confirm = retrn THEN
      EXIT;
    END IF;
    Put ("ENTRY CANCELLED. REENTER FN:FT."); New_line;
    New_line;

```

```

  END LOOP;

```

```

Delete_file (fcb1'ADDRESS, code);
Create_file (fcb1'ADDRESS, code);
fcb1.cr := byte (0);

--* SET DMA TO ADDRESS OF DATA STRUCTURE THAT WILL *--
--* HOLD DATA RECEIVED FROM SOURCE *--

Set_DMA (block'ADDRESS);
IF code = 255 THEN
  Put ("DIRECTORY SPACE UNAVAILABLE.");
ELSE
  Put ("FILE ");
  Outconsole (drive);
  Put (":");
  FOR i IN 1..fn length LOOP
    Outconsole (fcb1.fn (i) );
  END LOOP;
  Put (".");
  FOR i IN 1..3 LOOP
    Outconsole (fcb1.ft (i) );
  END LOOP;
  Put (" IS OPENED."); New_line;
  Clearscrn;

--* RECEIVE AND WRITE FILE IN 128 BYTE BLOCKS *--

Put ("RECEIVING FILE..."); New_line;
LOOP
  Endfile (finished);
  EXIT WHEN finished;
  Recv_block (block'ADDRESS, length);
  Write_seq (fcb1'ADDRESS, code);
END LOOP;

IF code = 1 THEN
  Put ("ERROR. NO AVAILABLE DIRECTORY SPACE.");
  New_line;
ELSIF code = 2 THEN
  Put ("ERROR. DISK FULL."); New_line;
ELSE
  Put ("FINISHED WRITING FILE."); New_line; New_line;
END IF;

Close_file (fcb1'ADDRESS, code);
rbytes := rbytes * 128;
Put_int (rbytes); Put (" BYTES RECEIVED."); New_line;
END IF;
Put ("PRESS ANY KEY TO CONTINUE. ");
Keyin (pause);

END Receivefile;

```

PROCEDURE Parse\_cap (fcb2: OUT fcb; fnlen: OUT Integer) IS

```
--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION:  PARSE_CAP PARSES THE USER'S FILE NAME
--* AND TYPE FOR INVALID CP/M-86 CHARACTERS, CHANGES INPUT
--* TO UPPERCASE, AND PLACES IT IN APPROPRIATE FIELDS OF
--* FCB. *
```

```
period: CONSTANT BYTE := byte (16#2E#);
lthan:  CONSTANT BYTE := byte(16#3C#);
gthan:  CONSTANT BYTE := byte(16#3E#);
comma:  CONSTANT BYTE := byte(16#2C#);
semic:  CONSTANT BYTE := byte(16#3B#);
colon:  CONSTANT BYTE := byte(16#3A#);
equal:  CONSTANT BYTE := byte(16#3D#);
qmark:  CONSTANT BYTE := byte(16#3F#);
star:   CONSTANT BYTE := byte(16#2A#);
lbrac:  CONSTANT BYTE := byte(16#5B#);
rbrac:  CONSTANT BYTE := byte(16#5D#);
```

```
TYPE name IS ARRAY (1..8) OF byte;
filename: name;
capital: Integer;
k: Integer := 0;
h: Integer := 0;
```

BEGIN

```
--* PARSE FILE NAME *--
```

LOOP

```
Keyin (input);
Outconsole (input);
CASE input IS
  WHEN lthan!gthan!comma!semic!colon!
    equal!qmark!star!lbrac!rbrac
    => New_line; Put ("INVALID. TRY AGAIN.");
       New_line;
       FOR i IN 1..k LOOP
         Outconsole (filename (i));
       END LOOP;
```

```
  WHEN period => EXIT;
  WHEN OTHERS
    => k := k + 1;
       filename (k) := input;
```

```
  END CASE;
```

```
  EXIT WHEN k = 8;  --* MAX FILE NAME LENGTH *--
END LOOP;
```

```

IF k = 8 THEN
  Put (".");
END IF;

--* PARSE FILE TYPE *--

LOOP
  Keyin (input);
  Outconsole (input);
  CASE input IS
    WHEN lthan!gthan!comma!semic!colon!
      equal!qmark!star!lbrac!rbrac!pericd
      => New_line; Put ("INVALID. TRY AGAIN.");
      New_line;
      FOR I IN 1..k LOOP
        Outconsole (filename (i));
      END LOOP;
      Put (".");
      FOR j IN 1..h LOOP
        Outconsole (fcb2.ft (j));
      END LOOP;

    WHEN OTHERS
      => h := h + 1;
      fcb2.ft (h) := input;

  END CASE;
  EXIT WHEN h = 3;  --* MAX FILE TYPE LENGTH *--
END LOOP;

--* PLACE PARSED INPUT IN FCB ADDING BLANKS TO FILL UP *--
--* FIELDS *--

fnlen := k;
FOR i IN 1..8 LOOP
  fcb2.fn (i) := filename (i);
  IF i = fnlen THEN
    FOR j IN (fnlen + 1)..8 LOOP
      fcb2.fn (j) := space;
    END LOOP;
    EXIT;
  END IF;
END LOOP;
New_line;

--* CAPITALIZE FILE NAME AND TYPE *--

FOR i IN 1..fnlen LOOP
  capital := Integer (fcb2.fn (i));
  CASE capital IS
    WHEN 16#61#..16#7A# => capital := capital - 16#20#;
  
```

```

        WHEN OTHERS          => NULL;
    END CASE;
    fcb2.fn (i) := byte (capital);
END LOOP;

```

```

FOR j IN 1..3 LOOP
    capital := Integer (fcb2.ft (j));
    CASE capital IS
        WHEN 16#61#..16#7A# => capital := capital - 16#20#;
        WHEN OTHERS          => NULL;
    END CASE;
    fcb2.ft (j) := byte (capital);
END LOOP;

```

```

END Parse_cap;

```

```

END Xferfile;

```

```

=====

```

```

PACKAGE Messages IS
    PROCEDURE Talking;
    PROCEDURE Listening;
END Messages;

```

```

WITH Myasmlib, Myutil, Names;
PACKAGE BODY Messages IS
    USE Myasmlib, Myutil, Names;

```

```

    end_of_msg: CONSTANT BYTE := byte (16#1A#); --control Z--
    max_msg_length: CONSTANT := 1600;
    max_line_length: CONSTANT := 80;
    message: ARRAY (1..max_msg_length) OF byte;
    msg_length: Integer;
    line_length: Integer;

```

```

    PROCEDURE Talking IS

```

```

    --* AUTHOR: THOMAS V. WORKS
    --* DATE: AUGUST 1986
    --* DESCRIPTION: TALKING PROMPTS USER TO TYPE MESSAGE. *--
    --* STORES MESSAGE IN DATA STRUCTURE AND TRANSMITS MESSAGE *--
    --* TO DESTINATION AS A SINGLE BLOCK. *--

```

```

    ctrl_m: CONSTANT BYTE := byte (16#0D#);
    ctrl_s: CONSTANT BYTE := byte (16#13#);
    response: tyte;

```

```

BEGIN
  LOOP
    Clearscrn;
    Put ("BEGIN TYPING MESSAGE. USE CTRL Z TO STOP.");
    New_line;
    Put ("MAXIMUM MESSAGE LENGTH IS 1600 CHARACTERS.");
    New_line; New_line;
    line_length := 0;

    --* TYPE IN PAGE FORMAT; 20 LINES, 80 CHARACTERS *--
    --* PER LINE *--

    FOR i IN 1..max_msg_length LOOP
      Keyin (input);
      EXIT WHEN input = end_of_msg;
      message (i) := input;
      msg_length := i;
      line_length := line_length + 1;
      Outconsole (input);
      IF (input = retn) OR
         (line_length = max_line_length) THEN
        New_line;
        line_length := 0;
      END IF;
    END LOOP;
    New_line;

    Put ("END OF MESSAGE."); New_line; New_line;
    Put ("TYPE CTRL S TO SEND. ANY OTHER KEY TO RETYPE ");
    Put ("MESSAGE."); New_line;
    Keyin (response);
    IF response = ctrl_s THEN
      EXIT;
    END IF;
    Put ("MESSAGE ERASED."); New_line;
  END LOOP;
  New_line;
  Put ("IF YOU WANT TO SEND TO THE BULLETIN BOARD,");
  New_line;
  Put ("ENTER 24 FOR DESTINATION MACHINE.");
  New_line; New_line;

  --* PROMPT USER FOR DESTINATION AND SOURCE TERMINAL #'s *--

  Enter_machine (dest, srce);

  --* CREATE CONNECTION RECORD *--

  connection.destination := byte (dest);
  connection.source := byte (srce);
  connection.process := ctrl_m;

```

--\* ESTABLISH CONNECTION WITH DESTINATION \*--

```
Put ("WAITING..."); New_line; New_line;
Setup (connection ADDRESS, send_ready);
IF send_ready THEN
  IF dest = 0 THEN
    Put ("FOR BROADCAST, PAUSE TO ALLOW RECEIVER TO ");
    Put ("GET READY"); New_line;
    Put ("PRESS ANY KEY TO SEND. ");
    Keyin (pause); New_line; New_line;
  END IF;
Put ("CONNECTION ESTABLISHED, SENDING MESSAGE... ");
New_line; New_line;
```

--\* TRANSMIT MESSAGE AS A SINGLE BLOCK \*--

```
Send_block (message ADDRESS, msg_length);
Yes;
```

```
Put ("MESSAGE SENT."); New_line;
ELSEF
  Put ("MESSAGE NOT SENT. DESTINATION INACTIVE.");
  New_line;
END IF;
Put ("PRESS ANY KEY TO CONTINUE. ");
Keyin (pause);
```

END Talking;

PROCEDURE Listening IS

```
--* AUTHOR: THOMAS V. WORKS
--* DATE: AUGUST 1986
--* DESCRIPTION: LISTENING RECEIVES TRANSMITTED MESSAGE *--
--* AND DISPLAYS IT IN A PAGE FORMAT OF 20 LINES, 80 *--
--* CHARACTERS PER LINE. *--
```

char: byte;

BEGIN

```
Clearscrn;
Put ("RECEIVING MESSAGE..."); New_line;

--* RECEIVE ENTIRE MESSAGE *--

Recv_block (message ADDRESS, msg_length);
Endmsg;
Put_int (msg_length); Put (" BYTES RECEIVED."); New_line

--* DISPLAY IN SAME PAGE FORMAT AS TYPED *--

line_length := 0;
```

```

FOR i IN 0..(msg_length - 1) LOOP
  char := message (i);
  line_length := line_length + 1;
  Outconsole (char);
  IF (char = retrn) OR
    (line_length = max_line_length) THEN
    New_line;
    line_length := 0;
  FND IF;
END LOOP;

```

```

New_line; New_line;
Put ("END OF MESSAGE."); New_line;
Put ("PRESS ANY KEY TO CONTINUE. ");
Keyin (pause);

```

END Listening;

END Messages;

=====

```

PACKAGE Directry IS
  PROCEDURE Present_dir;
  PROCEDURE Receive_dir;
END Directry;

```

```

WITH Xferfile, Myutil, Myasmlib, Names;
PACKAGE BODY Directry IS
  USE Xferfile, Myutil, Myasmlib, Names;

```

```

PROCEDURE Present_dir IS

```

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: AUGUST 1986
--* DESCRIPTION: PRESENT_DIR PROMPTS THE USER FOR THE *--
--* REQUESTED DISK DRIVE AND TRANSMITS THE DIRECTORY EIGHT *--
--* ENTRIES AT A TIME (128 BYTES) UNTIL THE ENTIRE *--
--* DIRECTORY IS SENT. *--

```

```

nodir_str: STRING := "NO DIRECTORY ON SELECTED DRIVE.";
dir_size: CONSTANT := 16;
count: Integer;
ctrl_d: CONSTANT BYTE := byte (16#04#);
qmark: CONSTANT BYTE := byte (16#3F#);

```

```

TYPE buff IS ARRAY (1..128) OF byte;
buffer: buff;
dir_addr: Integer;

```

```

BEGIN
  Clearscrn;
  fcb1.dr := byte(0);
  fcb1.ex := byte(0);
  Reset_disk;

  --* WILD CARD FOR MATCHING ENTIRE DIRECTORY *--

  FOR i IN 1..8 LOOP
    fcb1.fn (i) := qmark;
  END LOOP;
  FOR i IN 1..3 LOOP
    fcb1.ft (i) := qmark;
  END LOOP;

  New_line;

  --* PROMPT USER FOR DISK DRIVE *--

  Drive_select (drive);
  New_line;

  --* PROMPT USER FOR DESTINATION AND SOURCE TERMINAL #'s

  Enter_machine (dest, srce);

  --* CREATE CONNECTION RECORD *--

  connection.destination := byte (dest);
  connection.source := byte (srce);
  connection.process := ctrl_d;

  --* ESTABLISH CONNECTION WITH DESTINATION *--

  Put ("WAITING..."); New_line; New_line;
  Setup (connection'ADDRESS, send_ready);
  IF send_ready THEN
    IF dest = 0 THEN
      Put ("FOR BROADCAST, PAUSE TO ALLOW RECEIVER TO ");
      Put ("GET READY"); New_line;
      Put ("PRESS ANY KEY TO SEND. ");
      Keyin (pause); New_line; New_line;
    END IF;

    Put ("CONNECTION ESTABLISHED, SENDING DIRECTORY ");
    Put ("FROM DRIVE ");
    Outconsole (drive); Put (" ... "); New_line; New_line;

    --* SET DMA TO ADDRESS OF DATA STRUCTURE THAT *--
    --* WILL HOLD DIRECTORY ENTRIES *--

    Set_DMA (buffer'ADDRESS);

```

```

--* TRANSMIT DRIVE *--

Driveout (drive);

--* MAKE FIRST DIRECTORY MATCH *--

Search_first (fcb1'ADDRESS, buffer'ADDRESS, code,
              dir_addr);
IF code = 255 THEN

--* NO MATCH, TRANSMIT NO DIRECTORY STRING *--

    Put_str (nodir_str); New_line;
    No;
    Send_string (nodir_str);
    End_block;
    Yes;
ELSE

--* TRANSMIT DIRECTORY ENTRY *--

    No;
    Send_dir (dir_addr, dir_size);
    count := 1;
    LOOP
        LOOP

--* MAKE SUCCESSIVE MATCHES UNTIL END *--
--* OF DIRECTORY (CODE = 255) *--

            Search_next (fcb1'ADDRESS, buffer'ADDRESS,
                        code, dir_addr);
            EXIT WHEN code = 255;

--* TRANSMIT 8 ENTRIES PER BLOCK *--

            Send_dir (dir_addr, dir_size);
            count := count + 1;
            IF count = 8 THEN
                count := 0;
                EXIT;
            END IF;
        END LOOP;
    IF code = 255 THEN
        No;
        End_block;
        EXIT;
    END IF;
    End_block;
    No;

```

--\* PAUSE AFTER EACH BLOCK FOR BROADCAST \*--

```
IF dest = Ø THEN
    Put ("BROADCAST, PRESS ANY KEY TO SEND. ");
    Keyin (pause); New_line;
END IF;
END LOOP;
Yes;
END IF;
Put ("DIRECTORY SENT."); New_line;
ELSE
    Put ("DIRECTORY NOT SENT. DESTINATION INACTIVE.");
    New_line;
END IF;
Put ("PRESS ANY KEY TO CONTINUE. ");
Keyin (pause);
```

END Present\_dir;

-----

PROCEDURE Receive\_dir IS

```
--* AUTHOR: THOMAS V. WORKS
--* DATE: AUGUST 1986
--* DESCRIPTION: RECEIVE_DIR PROMPTS THE USER FOR THE *--
--* FILE NAME AND TYPE IN WHICH HE WISHES TO STORE ENTRIES *--
--* RECEIVED. USER CAN SELECT WHICH BLOCK(S) OF 8 ENTRIES *--
--* HE WISHES TO SAVE, WHICH ARE THEN WRITTEN TO DISK. *--
```

```
choice: byte;
rbytes: integer := Ø;
length: Integer;
finished: Boolean := false;
k: Integer;
start, fini: Integer;
period: CONSTANT BYTE := byte (16#2E#);
no: CONSTANT BYTE := byte (16#6E#);
```

BEGIN

Clearscrn;

--\* SET FCB FOR FILE OPERATIONS \*--

```
fcbl.dr := byte(Ø);
fcbl.ex := byte(Ø);
Reset_disk;
```

--\* PROMPT USER FOR DISK DRIVE \*--

```
New_line;
Drive_select (drive);
```

```

New_line;
--* PROMPT USER FOR FILE NAME AND TYPE *--
Put ("ENTER FILE NAME TO STORE YOUR DIRECTORY.");
New_line;
LOOP
  Put ("FN.FT: ");
  Parse_cap (fcb1, fn_length);
  New_line;
  Put ("FILE ");
  Outconsole (drive);
  Put (":");
  FOR i IN 1..fn_length LOOP
    Outconsole (fcb1.fn (i) );
  END LOOP;
  Put (".");
  FOR i IN 1..3 LOOP
    Outconsole (fcb1.ft (i) );
  END LOOP;
  Put (" IS SELECTED. PRESS RETURN TO CONFIRM, ");
  New_line;
  Put ("ANY OTHER KEY TO RESELECT.");
  Keyin (confirm);
  New_line;
  IF confirm = retn THEN
    EXIT;
  END IF;
  Put ("ENTRY CANCELLED. REENTER FN:FT."); New_line;
  New_line;
END LOOP;

Delete_file (fcb1'ADDRESS, code);
Create_file (fcb1'ADDRESS, code);
fcb1.cr := byte (0);

--* SET DMA TO ADDRESS OF DATA STRUCTURE THAT WILL *--
--* HOLD DATA RECEIVED FROM SOURCE *--

Set_DMA (block'ADDRESS);
Clearscrn;
IF code = 255 THEN
  Put ("DIRECTORY SPACE UNAVAILABLE.");
ELSE
  Put ("FILE ");
  Outconsole (drive);
  Put (":");
  FOR i IN 1..fn_length LOOP
    Outconsole (fcb1.fn (i) );
  END LOOP;
  Put (".");
  FOR i IN 1..3 LOOP

```

```

    Outconsole (fcb1.ft (i) );
END LOOP;
Put (" IS OPENED."); New_line;

--* RECEIVE DRIVE OF INCOMING DIRECTORY *--

Drivein (drive);
Put ("RECEIVING DIRECTORY FROM DRIVE ");
Outconsole (drive); Put (" OF SENDING MACHINE...");
New_line; New_line;
LOOP

    --* RECEIVE IN 128 BYTE BLOCKS (8 ENTRIES) *--
    --* UNTIL END OF DIRECTORY *--

    Erdfile (finished);
    EXIT WHEN finished;
    Recv_block (block'ADDRESS, length);
    IF block (1) /= byte (0) THEN

        --* NO MATCHES, DISPLAY NO DIRECTORY STRING *--

        FOR i IN 1..26 LOOP
            Outconsole (block (i));
        END LOOP;
        New_line;
    ELSE

        --* FORMAT EACH 8 DIRECTORY ENTRIES FOR *--
        --* DISPLAY *--

        start := 1; fini := 16;
        FOR i IN 1..8 LOOP
            FOR j IN start..fini LOOP
                EXIT WHEN block (start) = no;
                IF j = (start + 9) THEN
                    Outconsole (period);
                END IF;
                IF j > (start + 11) THEN
                    block (j) := space;
                    Outconsole (block (j));
                ELSE
                    Outconsole (block (j));
                END IF;
            END LOOP;
            IF i = 4 THEN
                New_line;
            END IF;
            start := start + 16; fini := fini + 16;
        END LOOP;
        New_line;
    END IF;

```

```
New_line; New_line;
Put ("PRESS RETURN IF YOU WANT TO SAVE ON FILE.");
Keyin (choice);
New_line; New_line;
```

```
--* WRITE TO DISK ONLY USER'S CHOICES *--
```

```
IF choice = retrn THEN
    Write_seq (fcb1'ADDRESS, code);
END IF;
END LOOP;
New_line; New_line;

IF code = 1 THEN
    Put ("ERROR. NO AVAILABLE DIRECTORY SPACE.");
    New_line;
ELSEIF code = 2 THEN
    Put ("ERROR. DISK FULL."); New_line;
ELSE
    Put ("FINISHED WRITING FILE."); New_line; New_line;
END IF;
```

```
Close_file (fcb1'ADDRESS, code);
```

```
END IF;
New_line;
Put ("PRESS ANY KFY TO CONTINUE. ");
Keyin (pause);
```

```
END Receive_dir;
```

```
END Directry;
```

```
=====
PACKAGE Who IS
    PROCEDURE Whos_there;
END Who;
```

```
WITH Myasmlib, Myutil, Names;
PACKAGE BODY Who IS
    USE Myasmlib, Myutil, Names;
```

```
PROCEDURE Whos_there IS
```

```
--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: WHOS_THERE RECEIVES NET STATUS FROM THE *--
--* CONCENTRATOR. *--
```

```

machno: CONSTANT := 24;
whos_on: ARRAY (1..machno) OF byte;
number_on: Integer;
ctrl_w: CONSTANT BYTE := byte (16#17#);

BEGIN
  Clear_scrn;
  Put ("FOR NET STATUS, ENTER YOUR MACHINE # FOR ");
  Put ("DESTINATION."); New_line; New_line;

  --* PROMPT USER FOR SOURCE TERMINAL # *--

  Enter_machine (dest, srce);

  --* CREATE CONNECTION RECORD *--

  connection.source := byte (srce);
  connection.destination := byte (dest);
  connection.process := ctrl_w;

  --* ESTABLISH CONNECTION WITH DESTINATION *--

  Setup (connection'ADDRESS, send_ready);

  --* RECEIVE NET STATUS AS A SINGLE BLOCK *--

  Recv_block (whos_on'ADDRESS, number_on);

  --* DISPLAY CURRENTLY ACTIVE TERMINAL #'s *--

  Put ("THE FOLLOWING NUMBERED MACHINES ARE CURRENTLY ");
  Put ("ACTIVE:"); New_line;
  FOR i IN 1..number_on LOOP
    Put_int (Integer (whos_on (i))); New_line;
  END LOOP;

  END Whos_there;

END Who;

```

```

=====

PACKAGE Bullbrd IS
  PROCEDURE Recv_bulletin;
END Bullbrd;

```

```
WITH Myasmlib, Xferfile, Myutil, Names;
PACKAGE BODY Bullbrd IS
  USE Myasmlib, Xferfile, Myutil, Names;
```

```
PROCEDURE Recv_bulletin IS
```

```
--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: RECV_BULLETIN PROMPT USER FOR FILE NAME *--
--* AND TYPE IN WHICH HE WISHES TO STORE MESSAGES RECEIVED *--
--* FROM THE BULLETIN BOARD, OPENS THE FILE, RECEIVES DATA *--
--* IN 128 BYTE BLOCKS, AND WRITES TO DISK THE RECEIVED *--
--* DATA. *--
```

```
  recv_b: CONSTANT BYTE := byte (16#02#);
```

```
  BEGIN
```

```
    Clearscrn;
```

```
    Put ("TO RECEIVE BULLETIN BOARD, ENTER 24 FOR ");
```

```
    Put ("DESTINATION MACHINE."); New_line;
```

```
    Enter_machine (dest, srce);
```

```
    --* CREATE CONNECTION RECORD *--
```

```
    connection.source := byte (srce);
```

```
    connection.destination := byte (dest);
```

```
    connection.process := recv_b;
```

```
    --* ESTABLISH CONNECTION WITH BULLETIN BOARD *--
```

```
    Put ("WAITING..."); New_line; New_line;
```

```
    Setup (connection'ADDRESS, send_ready);
```

```
    IF send_ready THEN
```

```
      Put ("CONNECTION ESTABLISHED. READY TO RECEIVE ");
```

```
      Put ("BULLETIN BOARD."); New_line; New_line;
```

```
      --* RECEIVE MESSAGES FROM BULLETIN BOARD AND *--
```

```
      --* STORE ON FILE *--
```

```
      Receivefile;
```

```
      Put ("BULLETIN BOARD RECEIVED."); New_line;
```

```
    EISE
```

```
      Put ("BULLETIN BOARD INACTIVE."); New_line;
```

```
    END IF;
```

```
    Put ("PRESS ANY KEY TO CONTINUE.");
```

```
    Keyin (pause);
```

```
  END Recv_bulletin;
```

```
END Bullbrd;
```

```

=====
PACKAGE Myutil IS
  PROCEDURE Put_int (output: IN Integer);
  PROCEDURE Clearscrn;
  PROCEDURE Enter_machine (machdest: OUT Integer;
                           machsrce: OUT Integer);
  PROCEDURE Drive_select (d_drive: OUT byte);
END Myutil;

```

```

WITH Myasmlib, Names;
PACKAGE BODY Myutil IS
  USE Myasmlib, Names;

```

```

PROCEDURE Put_int (output: IN Integer) IS

```

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: JUNE 1986
--* DESCRIPTION: PUT_INT DISPLAYS INTEGER VALUES BY
--* SEPARATING THE MOST SIGNIFICANT DIGIT AND DISPLAYING
--* IT UNTIL THERE ARE NO MORE DIGITS.
--*
--*

```

```

  max: Integer := 10000;
  count: Integer := 0;
  zero_ctr: Integer := 1;
  temp1, temp2: Integer;

```

```

BEGIN

```

```

  temp1 := output;
  IF temp1 < 0 THEN
    Put ("-"); --* NEGATIVE NUMBER *--
  END IF;
  IF temp1 = 0 THEN
    Put ("0");
  ELSE
    WHILE max /= 0 LOOP
      LOOP

```

```

        --* REMOVE MOST SIGNIFICANT DIGIT *--

```

```

        temp2 := temp1/max;
        temp1 := temp1 REM max;
        count := count + 1;

```

```

        --* REMOVE LEADING ZEROS *--

```

```

        IF (count = zero_ctr) AND (temp2 = 0) THEN
          zero_ctr := zero_ctr + 1;
          max := max/10;

```

```
EXIT;
END IF;
```

```
--* DISPLAY MOST SIGNIFICANT DIGIT *--
```

```
My_put (temp2);
max := max/10;
IF max = 0 THEN
    EXIT;
END IF;
END LOOP;
```

```
--* UNTIL THERE ARE NO MORE DIGITS *--
```

```
END LOOP;
END IF;
```

```
END Put_int;
```

```
-----
PROCEDURE Clearscrn IS
```

```
--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: CLEARSCRN DISPLAYS THE CLEAR SCREEN *--
--* CODES CAUSING THE SCREEN TO BE CLEARED. *--
```

```
escape: CONSTANT BYTE := byte(16#1B#);
clrscn: CONSTANT BYTE := byte(16#45#);
```

```
BEGIN
    Outconsole (escape);
    Outconsole (clrscn);
    New_line; New_line;
```

```
END Clearscrn;
```

```
-----
PROCEDURE Enter_machine (machdest: OUT Integer;
                        machsrce: OUT Integer) IS
```

```
--* AUTHOR: THOMAS V. WORKS
--* DATE: AUGUST 1986
--* DESCRIPTION: ENTER_MACHINE PROMPTS USER FOR SOURCE *--
--* AND DESTINATION TERMINAL NUMBERS AS A TWO DIGIT *--
--* NUMBER AND THEN CONVERTS IT TO THE APPROPRIATE BYTE *--
--* EQUIVALENT. *--
```

```
machine: ARRAY (1..3) OF byte;
temp1, temp2: Integer;
```

```

BEGIN
Put ("ENTER DESTINATION MACHINE (01,02..24) OR ");
Put ("BROADCAST (00) "); New_line;
Put ("FOLLOWED BY RETURN."); New_line;
LOOP
Put ("NOTE: BE SURE TO ADD LEADING ZERO."); New_line

--* CONVERT TWO DIGIT KEYBOARD INPUT INTO BYTE *--
--* EQUIVALENT FOR DESTINATION TERMINAL *--

FOR i IN 1..3 LOOP
Keyin (input);
IF input = retn THEN
machine (i) := byte (16#30#);
EXIT;
ELSE
machine (i) := input;
END IF;
END LOOP;

Put ("MACHINE NUMBER ");
FOR i IN 1..3 LOOP
Outconsole (machine (i));
END LOOP;
Put (" IS SELECTED. PRESS RETURN TO CONFIRM.");
New_line;
Keyin (confirm);
New_line;
IF confirm = retn THEN
EXIT;
END IF;
Put ("ENTRY CANCELLED."); New_line;
New_line;
END LOOP;
temp1 := Integer (machine (1)) - 16#30#;
temp2 := Integer (machine (2)) - 16#30#;
machdest := temp1 * 10 + temp2;

LOOP
Put ("ENTER YOUR MACHINE. NOTE: BE SURE TO ADD ");
Put ("LEADING ZERO."); New_line;

--* DITTO FOR SOURCE TERMINAL *--

FOR i IN 1..3 LOOP
Keyin (input);
IF input = retn THEN
machine (i) := byte (16#30#);
EXIT;
ELSE
machine (i) := input;
END IF;

```

```

END LOOP;

Put ("MACHINE NUMBER ");
FOR i IN 1..3 LOOP
    Outconsole (machine (i));
END LOOP;
Put (" IS SELECTED. PRESS RETURN TO CONFIRM.");
New_line;
Keyin (confirm);
New_line;
IF confirm = retrn THEN
    EXIT;
END IF;
Put ("ENTRY CANCELLED."); New_line;
New_line;
END LOOP;
temp1 := Integer (machine (1)) - 16#30#;
temp2 := Integer (machine (2)) - 16#30#;
machsrce := temp1 * 10 + temp2;

```

```
END Enter_machine;
```

-----

```
PROCEDURE Drive_select (d_drive: OUT byte) IS
```

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: DRIVE_SELECT PROMPTS USER FOR SELECTED *--
--* DISK DRIVE AND PASSES INPUT TO OPERATING SYSTEM. *--

```

```
disk_drive: Integer;
```

```

A: CONSTANT BYTE := byte (16#41#);
B: CONSTANT BYTE := byte (16#42#);
C: CONSTANT BYTE := byte (16#43#);
D: CONSTANT BYTE := byte (16#44#);
E: CONSTANT BYTE := byte (16#45#);

```

```
--* LOWER CASE *--
```

```

sa: CONSTANT BYTE := byte (16#61#);
sb: CONSTANT BYTE := byte (16#62#);
sc: CONSTANT BYTE := byte (16#63#);
sd: CONSTANT BYTE := byte (16#64#);
se: CONSTANT BYTE := byte (16#65#);

```

```
BEGIN
```

```
LOOP
```

```

Put ("SELECT DRIVE: A, B, C, D, E.");
Keyin (d_drive);
New_line;

```

```

Put ("DRIVE ");
Outconsole (d drive);
Put (" IS SELECTED. PRFSS RETURN TO CONFIRM, ");
New_line;
Put ("ANY OTHER KEY TO RESELECT.");
Keyin (confirm);
New_line;
IF confirm = retrn THEN
    EXIT;
END IF;
Put ("ENTRY CANCELLED."); New_line;
New_line;
END LOOP;

CASE d_drive IS
    WHEN A ! sa =>
        disk_drive := 0; Select_disk (disk_drive);
    WHEN B ! sb =>
        disk_drive := 1; Select_disk (disk_drive);
    WHEN C ! sc =>
        disk_drive := 2; Select_disk (disk_drive);
    WHEN D ! sd =>
        disk_drive := 3; Select_disk (disk_drive);
    WHEN E ! se =>
        disk_drive := 4; Select_disk (disk_drive);
    WHEN OTHERS =>
        Put ("INVALID DRIVE. DEFAULT IS A:");
        New_line;
        disk_drive := 0; Select_disk (disk_drive);
END CASE;
New_line;

END Drive_select;

END Myutil;

```

```

=====
PACKAGE Myasmlib IS
    PROCEDURE Create_file (address: IN Integer;
                           result: OUT Integer);
    PROCEDURE Close_file (address: IN Integer;
                           result: OUT Integer);
    PROCEDURE Open_file (address: IN Integer; result: OUT Integer);
    PROCEDURE Read_seq (address: IN Integer; result: OUT Integer);
    PROCEDURE Write_seq (address: IN Integer; result: OUT Integer);
    PROCEDURE Set_DMA (dma: IN Integer);
    PROCEDURE Delete_file (address: IN Integer;
                            result: OUT Integer);
    PROCEDURE Select_disk (disk: IN Integer);
    PROCEDURE Reset_disk;
    PROCEDURE Keyin (inchar : OUT byte);

```

```

PROCEDURE Outconsole (outchar : IN byte);
PROCEDURE Send_block (address: IN Integer; size: IN Integer);
PROCEDURE Yes;
PROCEDURE No;
PROCEDURE Recv_block (address: IN Integer; len: OUT Integer);
PROCEDURE Endfile (finish: OUT Boolean);
PROCEDURE Active;
PROCEDURE Waiting (stat: OUT byte);
PROCEDURE Setup (addr: IN Integer; rdy: OUT Boolean);
PROCEDURE My_put (inval: IN Integer);
PROCEDURE Put_str (str: IN STRING);
PROCEDURE Endmsg;
PROCEDURE Search_first (address: IN Integer; buff: IN Integer;
                        result: OUT Integer; addr: OUT Integer);
PROCEDURE Search_next (address: IN Integer; buff: IN Integer;
                       result: OUT Integer; addr: OUT Integer);
PROCEDURE End_block;
PROCEDURE Send_string (str: IN STRING);
PROCEDURE Send_dir (dirad: IN Integer; size: IN Integer);
PROCEDURE Driveout (driv: IN byte);
PROCEDURE Drivein (driv: OUT byte);
PROCEDURE Off;
END Myasmlib;

```

PACKAGE ASSEMBLY Myasmlib

```

jmp main

```

```

PROC Create_file;

```

```

--* AUTHOR: THOMAS V. WORKS

```

```

--* DATE: JUNE 1986

```

```

--* DESCRIPTION: CREATE_FILE CREATES A FILE SPECIFIED BY *--
--* THE FCB USING CP/M-86 FUNCTION #22. *--

```

```

cr_code      equ 16h

```

```

        pop ax                ;return address
        pop si                ;code address
        pop dx                ;FCB address
        push dx               ;restore stack
        push si
        push ax
        mov cl, cr_code
        int 224
        mov [si], al
        ret

```

```

END PROC Create_file;

```

PROC Close\_file;

--\* AUTHOR: THOMAS V. WORKS  
--\* DATE: JUNE 1986  
--\* DESCRIPTION: CLOSE\_FILE CLOSES A FILE SPECIFIED BY  
--\* THE FCB USING CP/M-86 FUNCTION #16. \*-

cf\_code equ 10h

```
pop ax           ;return address
pop si          ;code address
pop dx          ;FCB address
push dx         ;restore stack
push si
push ax
mov cl, cf_code
int 224
mov [si], al
ret
```

END PROC Close\_file;

-----  
PROC Open\_file;

--\* AUTHOR: THOMAS V. WORKS  
--\* DATE: JUNE 1986  
--\* DESCRIPTION: OPEN\_FILE OPENS A FILE SPECIFIED BY THE  
--\* FCB USING CP/M-86 FUNCTION #15. \*-

of\_code equ 0fh

```
pop ax           ;return address
pop si          ;code address
pop dx          ;FCB address
push dx         ;restore stack
push si
push ax
mov cl, of_code
int 224
mov [si], al
ret
```

END PROC Open\_file;

-----  
PROC Read\_seq;

--\* AUTHOR: THOMAS V. WORKS  
--\* DATE: JUNE 1986  
--\* DESCRIPTION: READ\_SEQ READS SEQUENTIAL 128 BYTE  
--\* RECORDS FROM THE FILE SPECIFIED BY THE FCB USING  
--\* CP/M-86 FUNCTION #20. \*-

```

rs_code      equ 14h

    pop ax          ;return address
    pop si          ;code address
    pop dx          ;FCB address
    push dx         ;restore stack
    push si
    push ax
    mov cl, rs_code
    int 224
    mov [si], ax
    ret

```

END PROC Read\_seq;

-----  
PROC Write\_seq;

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: JUNE 1986
--* DESCRIPTION:  WRITE_SEQ WRITES SEQUENTIAL 128 BYTE      *--
--* RECORDS TO THE FILE SPECIFIED BY THE FCB USING CP/M-86 *--
--* FUNCTION #21.                                          *--

```

```

ws_code      equ 15h

```

```

    pop ax          ;return address
    pop si          ;code address
    pop dx          ;FCB address
    push dx         ;restore stack
    push si
    push ax
    mov cl, ws_code
    int 224
    mov [si], ax
    ret

```

END PROC Write\_seq;

-----  
PROC Set\_DMA;

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: JUNE 1986
--* DESCRIPTION:  SET_DMA SETS THE DMA TO THE SPECIFIED    *--
--* ADDRESS USING CP/M-86 FUNCTION #26.                    *--

```

```

sdm_code     equ 1ah

```

```

    pop ax          ;return address
    pop dx          ;DMA address
    push ax         ;restore stack

```

```
mov cl, sdm_code
int 224
ret
```

```
END PROC Set_DMA;
```

```
-----
PROC Delete_file;
```

```
--* AUTHOR: THOMAS V. WORKS
--* DATE: JUNE 1986
--* DESCRIPTION: DELETE_FILE DELETES THE FILE SPECIFIED *
--* BY THE FCB USING CP/M-86 FUNCTION #19. *
```

```
df_code equ 13h
```

```
pop ax ;return address
pop si ;code address
pop dx ;FCB address
push dx ;restore stack
push si
push ax
mov cl, df_code
int 224
mov [si], al
ret
```

```
END PROC Delete_file;
```

```
-----
PROC Select_disk;
```

```
--* AUTHOR: THOMAS V. WORKS
--* DATE: JULY 1986
--* DESCRIPTION: SELECT_DISK DESIGNATES THE DEFAULT DISK *
--* DRIVE FOR SUBSEQUENT FILE OPERATIONS USING CP/M-86 *
--* FUNCTION #14. *
```

```
sd_code equ 0eh
```

```
pop ax ;return address
pop dx ;disk drive value
push ax ;restore stack
mov cl, sd_code
int 224
ret
```

```
END PROC Select_disk;
```

```
-----
PROC Reset_disk;
```

```
--* AUTHOR: THOMAS V. WORKS
--* DATE: JULY 1986
--* DESCRIPTION: RESET_DISK RESETS ALL DISK DRIVES TO *

```

```

--* READ/WRITE AND SET THE A DISK AS THE DEFAULT DISK FOR *--
--* ALL SUBSEQUENT FILE OPERATIONS USING CP/M-86 FUNCTION *--
--* #13. *--

```

```

rd_code      equ 0dh

      mov cl, rd_code
      int 224
      ret

```

```

END PROC Reset_disk;
-----

```

```

PROC Keyin;

```

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: APRIL 1986
--* DESCRIPTION:  KEYIN OBTAINS INPUT FROM THE KEYBOARD *--
--* USING CP/M-86 FUNCTION #06. *--

```

```

status_code  equ 0ffh
dirio_code   equ 06h
conout_code  equ 02h

```

```

      pop ax          ;return address
      pop di         ;output address
      push di        ;restore stack
      push ax
nokey:  mov cl, dirio_code
      mov dl, status_code
      int 224
      cmp al, 0      ;if zero, no input from keyboard
      jz nokey
      mov [di], al  ;store value from keyboard
      ret

```

```

END PROC Keyin;
PROC Outconsole;

```

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: APRIL 1986
--* DESCRIPTION:  OUTCONSOLE DISPLAYS OUTPUT TO THE *--
--* CONSOLE DEVICE USING CP/M-86 FUNCTION #02. *--

```

```

      pop bx          ;return address
      pop ax         ;value to be output to console
      push bx        ;restore stack
      mov cl, conout_code
      mov dl, al
      int 224
      ret

```

```

END PROC Outconsole;

```

PROC Send\_block;

```
--* AUTHOR: THOMAS V. WORKS
--* DATE: AUGUST 1986
--* DESCRIPTION: SEND_BLOCK TRANSMITS A BLOCK OF DATA,
--* SEQUENTIALLY ONE BYTE AT A TIME VIA THE MODEM PORT.
--* EACH BYTE SFNT IS ERROR CHECKED BY IMMEDIATE ECHO. THE
--* ADDRESS AND THE LENGTH OF THE DATA BLOCK TO BE
--* TRANSMITTED ARE INPUT PARAMETERS. A SEQUENCE OF FOUR
--* BLOCK CODES (0FFh) INDICATING END OF BLOCK ARE SENT
--* AFTER TFE DATA.
```

```
ctr          equ 03h
io_port      equ 0ECh
recv_rdy     equ 02h
error_code   equ 0EFh
block_code   equ 0FFh
status_port  equ 0EDh

                pop ax          ;return address
                pop bx          ;length of data structure
                pop si          ;data structure address
                push ax         ;restore stack

                mov ch, 4       ;block_code counter
                mov dl, io_port
loopb:         mov al, [si]      ;send out char
                out dx, al
                inc dx          ;statport
loopa:         in al, dx        ;wait for echo
                and al, recv_rdy
                jz loopa
                dec dx          ;dataport
                in al, dx       ;get echo
                cmp al, [si]    ;check for error
                jnz error1
                inc si          ;get new char
                dec bx          ;decrement length
                jnz loopb       ;do again until length = 0
                jmp over

error1:        mov al, error_code ;tell receiver error in
                out dx, al      ;transmission
                inc dx          ;statport
loopd:         in al, dx        ;wait for echo
                and al, recv_rdy
                jz loopd
                dec dx          ;dataport
                in al, dx       ;check to see if error code wa
                cmp al, error_code ;received
```

```

error2:  jnz error1          ;if not, retransmit error code
         mov al, error_code ;send second error code
         out dx, al
         inc dx             ;statport
loopd2:  in al, dx          ;wait for echo
         and al, recv_rdy
         jz loopd2
         dec dx             ;dataport
         in al, dx         ;check to see if error code was
                           ;received
         cmp al, error_code
         jnz error2        ;if not, retransmit error code
         jmp loopb         ;retransmit char

over:    mov al, block_code ;tell receiver end of block
         out dx, al
         inc dx             ;statport
loopc:   in al, dx          ;wait for echo
         and al, recv_rdy
         jz loopc
         dec dx             ;dataport
         in al, dx         ;get echo
         cmp al, block_code ;check for error
         jnz error3
         dec ch             ;send out next block code
         jnz over          ;until four are sent out
         ret               ;done

error3:  mov al, block_code
         out dx, al        ;retransmit
         inc dx            ;statport
         jmp loopc         ;check again

```

END PROC Send\_block;

-----  
PROC Yes;

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: AUGUST 1986
--* DESCRIPTION: YES TRANSMITS A SEQUENCE OF FOUR YES      *--
--* CODES (0F1h) INDICATING END OF PROCESS.                 *--

```

```

yes_code      equ 0F1h

         pop ax
         push ax

         mov ch, 4          ;yes code counter
         mov dl, io_port    ;send out yes code
more2:      mov al, yes_code
         out dx, ax
         inc dx             ;statport

```

```

loop2:   in al, dx           ;wait for echo
         and al, rcv_rdy
         jz loop2
         dec dx           ;dataport
         in al, dx       ;get echo
         cmp al, yes_code ;check for error
         jnz error4     ;if error, retransmit
         dec ch         ;do again until counter = 0
         jnz more2
         ret

```

```

error4:  mov al, yes_code  ;retransmit
         out dx, al
         inc dx           ;statport
         jmp loop2

```

END PROC Yes;

-----  
PROC No;

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: AUGUST 1986
--* DESCRIPTION: NO TRANSMITS A SINGLE NO CODE (6EH)
--* INDICATING PROCESS CONTINUING.

```

```

*--
*--

```

```

no_code      equ 6Eh

```

```

         pop ax
         push ax

more3:     mov dl, io_port   ;send out no code
         mov al, no_code
         out dx, ax
         inc dx           ;statport

loop3:     in al, dx        ;wait for echo
         and al, rcv_rdy
         jz loop3
         dec dx           ;dataport
         in al, dx       ;get echo
         cmp al, no_code  ;check for error
         jnz more3       ;if error, do again
         ret

```

END PROC No;  
PROC Recv\_block;

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: AUGUST 1986
--* DESCRIPTION: RECV_BLOCK RECEIVES A BLOCK OF DATA,
--* SEQUENTIALLY ONE BYTE AT A TIME VIA THE MODEM PORT.
--* THE ADDRESS TO STORE THE RECEIVED THE DATA IS AN INPUT
--* PARAMETER AND THE AMOUNT OF DATA RECEIVED IS AN OUTPUT

```

```

*--
*--
*--
*--

```

```

--* PARAMETER. RECV_BLOCK WAITS UNTIL IT RECEIVES A *--
--* SEQUENCE OF FOUR_BLOCK CODES (0FFh) INDICATING END OF *--
--* DATA BLOCK. *--

```

```

    pop ax                ;return address
    pop si                ;length address
    pop di                ;data structure address
    push di
    push si               ;restore stack
    push ax

    mov bl, ctr           ;timeout counter
    mov ch, 4             ;finish_code counter
    mov cl, 0             ;length counter
    mov dl, status_pprt

loop4:  in al, dx          ;check for incoming char
        and al, rcv_rdy
        jz loop4
        dec dx            ;dataport
        in al, dx         ;get char
        out dx, al        ;echo char
        mov [di], al      ;store char
        cmp al, error_code ;check for error code
        jz error5
        inc di            ;if no error, increment
                        ;location
        inc cl            ;increment length
        cmp al, block_code ;check for end of block
        jnz notyet
        dec ch            ;begin counting block codes
        jz fini           ;jump when number of block
                        ;codes = 4
        inc dx            ;statport
        jmp loop4        ;if not check for next
                        ;finish code
notyet: mov ch, 4         ;reload finish code counter
        inc dx            ;statport
        jmp loop4        ;get next char

error5: inc dx            ;statport
loop5:  in al, dx         ;check for second error code
        and al, rcv_rdy
        jz loop5
        dec dx            ;dataport
        in al, dx         ;get input char
        out dx, al        ;echo input char
        cmp al, error_code ;is this a true error
        jz eloop         ;if yes, jump to error handler
        mov [di], error_code ;if not, treat it like a real
                        ;char and store
        inc di            ;next location
        mov [di], al      ;store the char mistaken as

```

```

                                ;second error code
                                ;next location - now we're
                                ;back to normal
                                ;statport
                                ;get next char
        inc di
                                ;statport
                                ;check for retransmitted char
        inc dx
                                ;dataport
                                ;get retransmitted char
                                ;echo retransmitted char
                                ;overwrite error
        jmp loop4

eloop:   inc dx
loop6:   in al, dx
        and al, recv_rdy
        jz loop6
        dec dx
        in al, dx
        out dx, al
        dec di
        mov [di], al
        inc di
        inc dx
        jmp loop4

fini:    inc dx
count1:  dec bl
                                ;timeout to ensure echo was
                                ;received
                                ;finish if counter = 0 and no
                                ;char received
                                ;wait for input
        jz none
        in al, dx
        and al, recv_rdy
        jz count1
        dec dx
        in al, dx
        out dx, al
        cmp al, block_code
        jz none
        mov bl, ctr
        jmp fini
none:    sub cl, 4
                                ;remove four block codes from
                                ;length
                                ;zero ch
                                ;store length for return
                                ;finished
        mov ch, 0
        mov [si], cx
        ret

```

END PROC Recv\_block;

-----  
PROC Endfile;

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: AUGUST 1986
--* DESCRIPTION:  ENDFILE WAITS TO RECEIVE EITHER A SINGLE *--
--* NO CODE (0eh) INDICATING FILE NOT FINISHED, OR A *--
--* SEQUENCE OF FOUR YES CODES (0F1h) INDICATING FILE *--
--* FINISHED. *--

```

```

file_end      equ 0F1h
no_end       equ 6Fh

        pop ax                ;return address
        pop di               ;address of output variable
        push di              ;restore stack
        push ax
        mov ch, 4            ;file end counter
        mov bl, ctr          ;timeout counter
more5:    mov dl, status_port ;check for input
loop8:    in al, dx
        and al, recv_rdy
        jz loop8
        dec dx                ;dataport
        in al, dx            ;get input
        out dx, al           ;echo input
        cmp al, no_end       ;decode input
        jz done1
        cmp al, file_end
        jnz more5           ;if neither, go back for
                            ;retransmitted input
        dec ch              ;if file end, begin counting
                            ;until four are
                            ;received
done1:    mov cl, al          ;store input temporarily
more6:    inc dx              ;statport
count2:   dec bl            ;timeout to ensure echo was
                            ;received
        jz done2           ;finish if counter = 0 and no
                            ;char received
        in al, dx
        and al, recv_rdy
        jz count2
        dec dx                ;dataport
        in al, dx            ;get input
        out dx, al           ;echo input
        cmp al, file_end     ;one last decode and check
        jz tru
        cmp al, no_end
        jz fal
        mov bl, ctr          ;if neither, do again
        jmp more6
done2:    mov al, cl          ;reload for decode
        cmp al, file_end     ;decode input
        jz tru
        cmp al, no_end
        jz fal
fal:      mov [di], 00        ;false
        ret
tru:      mov [di], 01        ;true
        ret

```

END PROC Endfile;

PROC Active;

--\* AUTHOR: THOMAS V. WORKS  
--\* DATE: SEPTEMBER 1986  
--\* DESCRIPTION: ACTIVE TRANSMITS THE ACTIVE CODE (0D0h) \*--  
--\* TO THE CONCENTRATOR INDICATING AN ACTIVE STATUS AND \*--  
--\* WAITS FOR A REPLY. \*--

ready\_code equ 0D0h

```
                pop ax                ;return address
                push ax               ;restore stack

rdy:            mov dl, io_port        ;dataport
                mov al, ready_code
                out dx, al            ;send out ready code
                inc dx                ;statport
loop9:          in al, dx              ;wait for echo
                and al, recv_rdy
                jz loop9
                dec dx                ;dataport
                in al, dx             ;get echo
                cmp al, ready_code    ;check for error
                jnz rdy               ;if not ready code, start
                                        ;again
                ret                   ;if ready code, finish
```

END PROC Active;

-----  
PROC Waiting;

--\* AUTHOR: THOMAS V. WORKS  
--\* DATE: SEPTEMBER 1986  
--\* DESCRIPTION: WAITING AWAITS THE RESULT OF CHECK\_QUEUE \*--  
--\* THERE ARE FOUR POSSIBLE REPLYS: NOTHING (0), FILE \*--  
--\* WAITING (6), MESSAGE WAITING (0Dh), OR RESEND (1). THE \*--  
--\* REPLY IS AN OUTPUT PARAMETER \*--

```
                pop ax                ;return address
                pop di                ;status address
                push di               ;restore stack
                push ax

loop10:         mov dl, status_port
                in al, dx              ;wait for input
                and al, recv_rdy
                jz loop10
                dec dx                ;dataport
                in al, dx             ;get input
                out dx, al            ;echo input
```

```

more7:   mov [di], al           ;store input
        inc dx              ;statport, wait for confirmation
        mov bl, ctr        ;load timer
count3:  dec bl
        jz finit           ;if no input and timer = 0,
                          ;then first input ok
        in al, dx          ;wait for confirmation
        and al, recv_rdy
        jz count3
        dec dx             ;oops there was an error
        in al, dx          ;get retransmitted input
        out dx, al         ;echo retransmitted input
        mov [di], al       ;store retransmitted input
        jmp more7         ;go back for confirmation
finit:   ret               ;done

```

END PROC Waiting;

-----  
PROC Setup;

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION:  SETUP TRANSMITS TO THE CONCENTRATOR THE *--
--* CONNECTION RECORD, SEQUENTIALLY ONE BYTE AT A TIME. *--
--* THEN IT WAITS FOR A REPLY; XFER (1), OR NO_XFER (0). *--
--* THE REPLY IS A BOOLEAN OUTPUT PARAMETER *--

```

```

        pop ax              ;return address
        pop di              ;sendrdy address
        pop si              ;data structure address
        push di             ;restore stack
        push ax

        mov bl, ctr         ;timeout counter
        mov cl, 2          ;length counter
        mov dl, io_port    ;dataport
start:   mov al, [si]       ;send destination out
        out dx, al
        inc dx              ;statport
here1:   in al, dx          ;wait for echo
        and al, recv_rdy
        jz here1
        dec dx              ;dataport
        in al, dx          ;get echo
        cmp al, [si]       ;check for error
        jnz fault
        inc si              ;go to next location
        dec cl              ;count length
        jnz start          ;jump until length = 2
        jmp finis         ;done

```

```

fault:    mov al, error_code    ;send out error code
          out dx, al
          inc dx                ;statport
here2:    in al, dx             ;wait for echo
          and al, rcv_rdy
          jz here2
          dec dx                ;dataport
          in al, dx             ;get echo
          cmp al, error_code    ;check to see if error code wa
          ;received
          jnz fault             ;if not, retransmit
          jmp start             ;retransmit data

finis:    mov al, block_code    ;send out block code
          out dx, al
          inc dx                ;statport
here3:    in al, dx             ;wait for echo
          and al, rcv_rdy
          jz here3
          dec dx                ;dataport
          in al, dx             ;get echo
          cmp al, block_code    ;check to see if block code was
          ;received
          jnz finis            ;if not, retransmit

          inc dx                ;statport
lupe:    in al, dx             ;wait for sendrdy result
          and al, rcv_rdy
          jz lupe
          dec dx                ;dataport
          in al, dx             ;get result
          out dx, al            ;echo result
          mov [di], al          ;store result
          cmp al, 0             ;check for invalid result
          jz set
          cmp al, 1
          jz set
          mov [di], 0           ;if invalid, set sendrdy to
          ;false

set:      inc dx                ;statport
kount:    dec bl                ;timeout to ensure echo receive
          jz allset
          in al, dx
          and al, rcv_rdy
          jz kount
          dec dx                ;dataport
          in al, dx             ;get input
          out dx, al            ;echo input
          mov [di], al          ;store input
          cmp al, 0             ;check for invalid result
          jz set
          cmp al, 1

```

```

        jz set
        mov [di], 0                ;if invalid, set sendrdy to
                                   ;false
        mov bl, ctr                ;timeout again
        jmp kount

allset:  ret

END PROC Setup;
-----
PROC My_put;

--*  AUTHOR: THOMAS V. WORKS
--*  DATE: JULY 1986
--*  DESCRIPTION:  MYPUT CONVERTS THE INTEGER INPUT          *--
--*  PARAMETER TO ITS ASCII EQUIVALENT AND DISPLAYS IT.     *--

offset    equ 30h

        pop bx                    ;return address
        pop dx                    ;input value
        push bx                   ;restore stack

        mov cl, conout_code
        add dl, offset            ;convert to ascii for output
        int 224
        ret

END PROC My_put;
-----
PROC Put_str;

--*  AUTHOR: THOMAS V. WORKS
--*  DATE: JULY 1986
--*  DESCRIPTION:  PUT_STR DISPLAYS THE STRING INPUT. THE   *--
--*  LENGTH OF THE STRING IS THE FIRST BYTE OF THE STRING. *--

        pop ax                    ;return address
        pop si                    ;string address
        push ax                   ;restore stack

        mov al, [si]              ;first value is string length
        mov di, 0000              ;set di to zero
        mov ah, 00                ;set ah to zero
        mov di, ax                ;move string length to di
more8:   mov cl, conout_code
        inc si                    ;get next char
        mov dl, [si]
        int 224                  ;output to console
        dec di                    ;decrement string length

```

```

        cmp di, 0000
        jnz more2          ;finish when string length is
                           ;zero
        ret

END PROC Put_str;
-----
PROC Endmsg;

--* AUTHCR: THOMAS V. WORKS
--* DATE: JULY 1986
--* DESCRIPTION:  ENDMSG TRANSMITS A SEQUENCE OF FOUR END *--
--* OF MESSAGE CCDES (0F1h) INDICATING END OF MESSAGE. *--

msg_end      equ 0F1h

        pop ax             ;return address
        push ax           ;restore stack

        mov ch, 4         ;load message end counter
        mov bl, ctr       ;load timer
more9:    mov dl, status_port
loop11:   in al, dx       ;wait for message end code
        and al, recv_rdy
        jz loop11
        dec dx           ;dataport
        in al, dx        ;get message end code
        out dx, al       ;echo input
        cmp al, msg_end  ;check for error
        jnz more9       ;if error, get next input
        dec ch          ;count message end codes
        jnz more9       ;until counter = 0
more10:   inc dx         ;statport
count4:   dec bl        ;timeout to ensure echo receive
        jz done3
        in al, dx
        and al, recv_rdy
        jz count4
        dec dx          ;dataport
        in al, dx      ;get input
        out dx, al     ;echo input
        cmp al, msg_end ;one last check
        jz done3
        mov bl, ctr    ;if not message end code, time
                     ;out again

        jmp more10

done3:    ret

END PROC Endmsg;

```

PROC Search\_first;

```
---* AUTHOR: THOMAS V. WORKS
---* DATE: SEPTEMBER 1986
---* DESCRIPTION: SEARCH_FIRST SEARCHES FOR THE FIRST *--
---* INSTANCE OF DIRECTORY MATCH, READS 128 BYTE RECORD *--
---* CONTAINING MATCHED ENTRY INTO DMA, AND COMPUTES OFFSET *--
---* TO ENTRY WITHIN 128 BYTE RECORD USING CP/M-86 FUNCTION *--
---* #17. *--
```

```
sf_code      equ 11h
finish_dir   equ 0ffh
```

```
    pop ax                ;return address
    pop si                ;dir_addr address
    pop di                ;code address
    pop bx                ;buffer address
    pop dx                ;fcb1 address
    push dx               ;restore stack
    push bx
    push di
    push si
    push ax

    mov [si], bx          ;save buffer address
    mov cl, sf_code
    int 224                ;search for first directory
                          ;match
    mov bx, [si]          ;restore buffer address
    mov [di], ax          ;store results of search in
                          ;code
    cmp al, finish_dir    ;are we at the end of the
                          ;directory
    jz done4              ;if yes, done
    mov cl, 32             ;directory match offset =
    mul cl                 ;buffer address + (32 * search
                          ;result)
    add bx, ax
    mov [si], bx          ;store directory match offset
                          ;in dir_addr
```

done4: ret

END PROC Search\_first;

-----  
PROC Search\_next;

```
---* AUTHOR: THOMAS V. WORKS
---* DATE: SEPTEMBER 1986
---* DESCRIPTION: SEARCH_NEXT SEARCHES FOR THE NEXT *--
---* INSTANCE OF DIRECTORY MATCH, READS 128 BYTE RECORD *--
---* CONTAINING MATCHED ENTRY INTO DMA, AND COMPUTES OFFSET *--
```

```

--* TO ENTRY WITHIN 128 BYTE RECORD USING CP/M-86 FUNCTION *-
--* #18, UNTIL END OF DIRECTORY IS REACHED (0FFh). *-

```

```

sn_code      equ 12h

                pop ax                ;return address
                pop si                ;dir_addr address
                pop di                ;code address
                pop bx                ;buffer address
                pop dx                ;fcb1 address
                push dx               ;restore stack
                push bx
                push di
                push si
                push ax

                mov [si], bx          ;save buffer address
                mov cl, sn_code
                int 224                ;search for first directory
                                        ;match
                mov bx, [si]          ;restore buffer address
                mov [di], ax          ;store results of search
                                        ;in code
                cmp al, finish_dir    ;are we at the end of the
                                        ;directory
                jz done5              ;if yes, done
                mov cl, 32            ;directory match offset =
                mul cl                 ;buffer address + (32 * search
                                        ;result)

                add bx, ax
                mov [si], bx          ;store directory match offset
                                        ;in dir_addr

done5:         ret

```

```

END PROC Search_next;
-----

```

```

PROC End_block;

```

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: END_BLOCK TRANSMITS A SEQUENCE OF FOUR *-
--* END OF BLOCK CODES (0FFh) INDICATING END OF BLOCK. *-

```

```

                pop ax;              ;return address
                push ax              ;restore stack

                mov ch, 4            ;yes code counter
                mov dl, io_port      ;send out yes code
more12:         mov al, block_code
                out dx, ax
                inc dx               ;statport
lcp12:         in al, dx             ;wait for echo

```

```

and al, recv_rdy
jz loop12
dec dx                                ;dataport
in al, dx                             ;get echo
cmp al, block_code                    ;check for error
jnz error6                             ;if error, retransmit
dec ch                                ;do again until counter = 0
jnz more12
ret

error6: mov al, block_code             ;retransmit
out dx, al
inc dx                                 ;statport
jmp loop12

END PROC End_block;
-----
PROC Send_string;

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: SEND STRING TRANSMITS A STRING INPUT, *--
--* SEQUENTIALLY ONE BYTE AT A TIME. THE ADDRESS OF THE *--
--* STRING IS AN INPUT PARAMETERS. THE LENGTH IS THE *--
--* FIRST BYTE OF THE STRING. *--

    pop ax                            ;return address
    pop si                            ;string address
    push ax                           ;restore stack

    mov al, [si]                      ;first char is string length
    mov di, 0000                      ;set up and store string length
                                        ;in di

    mov ah, 00
    mov di, ax
    mov dl, io_port
    inc si                            ;increment to first char

loop1b: mov al, [si]                  ;send out char
out dx, al
inc dx                                ;statport
loop1a: in al, dx                    ;wait for echo
and al, recv_rdy
jz loop1a
dec dx                                ;dataport
in al, dx                             ;get echo
cmp al, [si]                          ;check for error
jnz error7
inc si                                ;get new char
dec di                                ;decrement length
jnz loop1b                             ;do again until length = 0
jmp done6

```

```

error7:  mov al, error_code      ;tell receiver error in
                                           ;transmission
        out dx, al
        inc dx
loop1d:  in al, dx                ;statport
        and al, rcv_rdy         ;wait for echo
        jz loop1d
        dec dx
        in al, dx               ;dataport
                                           ;check to see if error code wa
                                           ;received
        cmp al, error_code
        jnz error7              ;if not, retransmit error code
error8:  mov al, error_code      ;send second error code
        out dx, al
        inc dx                   ;statport
loop1c:  in al, dx                ;wait for echo
        and al, rcv_rdy
        jz loop1c
        dec dx                   ;dataport
        in al, dx               ;check to see if error code wa
                                           ;received
        cmp al, error_code
        jnz error8              ;if not, retransmit error code
        jmp loop1b              ;retransmit char

done6:   ret                      ;done

```

```

END PROC Send_string;
PROC Send_dir;

```

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: SEND DIR TRANSMITS A DIRECTORY ENTRY OF *--
--* PREDEFINED LENGTH (BY CONSTANT INPUT PARAMETER). THE *--
--* ADDRESS OF THE ENTRY IS THE OTHER INPUT PARAMETER. *--

```

```

        pop ax                    ;return address
        pop bx                    ;data structure length
        pop si                    ;data structure address
        push ax
loop2b:  mov dl, io_port           ;dataport
        mov al, [si]              ;send out char
        out dx, al
        inc dx                     ;statport
loop2a:  in al, dx                 ;wait for echo
        and al, rcv_rdy
        jz loop2a
        dec dx                     ;dataport
        in al, dx                 ;get echo
        cmp al, [si]              ;check for error
        jnz error9

```

```

        inc si                ;get new char
        dec bx                ;decrement length
        jnz loop2b           ;do again until length = 0
        jmp done7

error9:  mov al, error_code   ;tell receiver error in
        out dx, al           ;transmission

        inc dx                ;statport
loop2d:  in al, dx            ;wait for echo
        and al, rcv_rdy
        jz loop2d
        dec dx                ;dataport
        in al, dx            ;check to see if error code was
        ;received

        cmp al, error_code
        jnz error9           ;if not, retransmit error code
error10: mov al, error_code   ;send second error code
        out dx, al
        inc dx                ;statport
loop2c:  in al, dx            ;wait for echo
        and al, rcv_rdy
        jz loop2c
        dec dx                ;dataport
        in al, dx            ;check to see if error code was
        ;received

        cmp al, error_code
        jnz error10         ;if not, retransmit error code
        jmp loop2b          ;retransmit char
done7:   ret                  ;done

```

```

END PROC Send_dir;
PROC Driveout;

```

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: DRIVEOUT TRANSMITS THE BYTE EQUIVALENT *--
--* OF THE DRIVE OF THE TRANSMITTED DIRECTORY. *--

```

```

        pop ax                ;return address
        pop bx                ;drive value
        push ax               ;restore stack

dout:   mov dl, io_port       ;dataport
        mov al, bl
        out dx, al           ;send out drive
        inc dx                ;statport
loop13: in al, dx            ;wait for echo
        and al, rcv_rdy
        jz loop13
        dec dx                ;dataport
        in al, dx            ;get echo

```

```

        cmp al, bl           ;check for error
        jnz dout           ;if error, start again
        ret                ;if not, finish

```

END PROC Driveout;

-----  
PROC Drivein;

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: DRIVEIN RECEIVES THE BYTE EQUIVALENT OF *--
--* THE DRIVE OF THE TRANSMITTED DIRECTORY. *--

```

```

        pop ax              ;return address
        pop di              ;address for drive
        push di             ;restore stack
        push ax

loop15:  mov bl, ctr        ;timeout counter
        mov dl, status_port
        in al, dx           ;wait for incoming go code
        and al, recv_rdy
        jz loop15
        dec dx              ;dataport
        in al, dx           ;get input
        out dx, al          ;echo input
        mov [di], al        ;store input
more15:  inc dx             ;statport
count5:  dec bl            ;timeout to ensure echo was
                                ;received
        jz done8           ;finish if counter = 0 and
                                ;no char received
        in al, dx           ;wait for input
        and al, recv_rdy
        jz count5
        dec dx              ;dataport
        in al, dx           ;get input
        out dx, al          ;echo input
        cmp al, [di]        ;one last check
        jz done8           ;if not error ,finish
        mov bl, ctr        ;if error, do again
        jmp more12
done8:   ret

```

END PROC Drivein;

-----  
PROC Off;

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: OFF TRANSMITS THE OFF CODE (0Fh) *--

```

```
--* INDICATING TO THE CONCENTRATOR A TERMINAL IS NO LONGER *--  
--* ACTIVE. *--
```

```
off_code      equ 0Fh  
  
    pop ax          ;return address  
    push ax         ;restore stack  
  
    mov dl, io_port ;send out off code  
    mov al, off_code  
    out dx, al  
    ret
```

```
END PROC Off;
```

```
main:
```

```
END Myasmlib;
```

```
=====
```

```
WITH Xferfile, Messages, Myasmlib, Directry,  
    Who, Myutil, Bullbrd, Names;
```

```
PACKAGE BODY Xfermain IS  
    USE Xferfile, Messages, Myasmlib, Directry,  
        Who, Myutil, Bullbrd, Names;
```

```
--*****--  
--* MAIN PROGRAM *--  
--*****--
```

```
status: byte;  
ctrl_f: CONSTANT BYTE := byte (16#06#);  
ctrl_m: CONSTANT BYTE := byte (16#0D#);  
ctrl_d: CONSTANT BYTE := byte (16#04#);  
resend: CONSTANT BYTE := byte (16#01#);  
ctrl_l: CONSTANT BYTE := byte (16#0C#);  
ctrl_r: CONSTIAANT BYTE := byte (16#12#);  
ctrl_s: CONSTANT BYTE := byte (16#13#);  
ctrl_t: CONSTANT BYTE := byte (16#14#);  
ctrl_x: CONSTANT BYTE := byte (16#18#);  
ctrl_w: CONSTANT BYTE := byte (16#17#);  
ctrl_g: CONSTANT BYTE := byte (16#07#);  
ctrl_p: CONSTANT BYTE := byte (16#10#);  
ctrl_b: CONSTANT BYTE := byte (16#02#);
```

```
BEGIN
```

```
    Clearscrn;  
    Put ("Welcome to the NPS Computer Science Labtratory ");  
    Put ("Local Area Network!");
```

```

New_line; New_line;
Put ("Execution Begins. Version 1.3"); New_line;
LOOP
  Put ("WAITING TO BE POLLED..."); New_line;

  --* SEND OUT ACTIVE CODE (0D0h) AND WAIT FOR REPLY *--

  Active;
  Put ("CHECKING FOR INCOMING FILE OR MESSAGE."); New_line;
  Waiting (status);
  New_line;
  CASE status IS
    WHEN byte (0)
      => Put ("NO FILE OR MESSAGE INCOMING."); New_line;

    WHEN ctrl_f
      => Put ("FILE READY TO RECEIVE. PLEASE RECEIVE IT ");
      Put ("BEFORE PROCEEDING."); New_line;
      Put ("FAILURE TO DO SO WILL CAUSE UNPREDICTABLE ");
      Put ("RESULTS"); New_line;

    WHEN ctrl_m
      => Put ("MESSAGE READY TO RECEIVE. PLEASE RECEIVE ");
      Put ("IT BEFORE PROCEEDING."); New_line;
      Put ("FAILURE TO DO SO WILL CAUSE UNPREDICTABLE ");
      Put ("RESULTS"); New_line;

    WHEN ctrl_d
      => Put ("DIRECTORY READY TO RECEIVE. PLEASE RECEIVE ");
      Put ("IT BEFORE PROCEEDING."); New_line;
      Put ("FAILURE TO DO SO WILL CAUSE UNPREDICTABLE ");
      Put ("RESULTS"); New_line;

    WHEN resend
      => Put ("DESTINATION FOR YOUR PREVIOUS SESSION IS ");
      Put ("NOW ACTIVE. PLEASE RESEND."); New_line;
      Put ("FAILURE TO DO SO WILL CAUSE UNPREDICTABLE ");
      Put ("RESULTS"); New_line;

  END CASE;
  New_line;

  --* USER MAIN MENU *--

  Put ("CTRL_S = SEND FILE "); New_line;
  Put ("CTRL_R = RECEIVE FILE "); New_line;
  Put ("CTRL_T = SEND MESSAGE (TALK) "); New_line;
  Put ("CTRL_L = RECEIVE MESSAGE (LISTEN) "); New_line;
  Put ("CTRL_P = SEND DIRECTORY "); New_line;
  Put ("CTRL_G = RECEIVE DIRECTORY "); New_line;
  Put ("CTRL_W = GET NET STATUS (WHO) "); New_line;
  Put ("CTRL_B = RECEIVE BULLETIN BOARD "); New_line;

```

```

New_line;
New_line;
Put ("ENTER INPUT: ");
Keyin (input);
New_line;
CASE input IS
    WHEN ctrl_s => Sendfile;
    WHEN ctrl_r => Receivefile;
    WHEN ctrl_t => Talking;
    WHEN ctrl_l => Listening;
    WHEN ctrl_w => Whos_there;
    WHEN ctrl_g => Receive_dir;
    WHEN ctrl_p => Present_dir;
    WHEN ctrl_b => Recv_bulletin;
    WHEN OTHERS => NULL;
END CASE;
Put ("CTRL_X = EXIT. ANYTHING ELSE TO CONTINUE.");
Keyin (input);
EXIT WHEN input = ctrl_x;
Clearscrn;

```

```
--* LOOP CONTINUOUSLY UNTIL USER EXITS *--
```

```
END LOOP;
```

```
--* TELL CONCENTRATOR NO LONGER ACTIVE *--
```

```
Off;
```

```
END Xfermain;
```

```

=====
WITH Myasmlib, Myutil, Names;
PACKAGE BODY Bulletin IS
    USE Myasmlib, Myutil, Names;

```

```
--** BULLETIN BOARD **--
```

```

max_msg_length: CONSTANT := 1600;
max_msg: CONSTANT := 20;
receive: CONSTANT BYTE := byte (16#0D#); --CTRL_M--
send: CONSTANT BYTE := byte (16#02#); --CTRL_B--

```

```

TYPE msg IS
    RECORD
        message: ARRAY (1..max_msg_length) OF byte;
        msg_length: Integer;
    END RECORD;

```

```
msg_list: APRAY (1..max_msg) OF msg;
```

```

command: byte;
msg_count: Integer := 0;
byte_count: Integer := 0;
msg_block: ARRAY (1..block_size) OF byte;

```

```

BEGIN

```

```

  Clearscrn;

```

```

  Put ("NPS COMPUTER SCIENCE LABRATORY BULLETIN BOARD.");

```

```

  New_line; New_line;

```

```

  LOOP

```

```

    --* TELL CONCENTRATOR BULLETIN BOARD ACTIVE AND WAIT *--
    --* FOR REPLY *--

```

```

    Active;

```

```

    --* MESSAGES INCOMING OR REQUEST TO SEND? *--

```

```

    Waiting (command);

```

```

    IF command = receive THEN

```

```

      msg_count := msg_count + 1;

```

```

      --* RECEIVE MESSAGES UNTIL MSG_COUNT = 20 *--

```

```

      Recv_block (msg_list(msg_count).message^ADDRESS,
                  msg_list(msg_count).msg_length);

```

```

      Endmsg;

```

```

      Put ("*");

```

```

    ELSIF command = send THEN

```

```

      --* SEND ALL MESSAGES CURRENTLY ON BOARD *--

```

```

      FOR i IN 1..msg_count LOOP

```

```

        byte_count := 0;

```

```

        LOOP

```

```

          --* FORMAT MESSAGES IN 128 BYTE BLOCKS FOR *--

```

```

          --* TRANSMISSION. FOR EACH MESSAGE SEND *--

```

```

          --* UNTIL BYTE_COUNT = MSG_LENGTH THEN ADD *--

```

```

          --* BLANKS AS NECESSARY TO FILL IN LAST 128 *--

```

```

          --* BYTE BLOCK. SEND NEXT MESSAGE UNTIL ALL *--

```

```

          --* MESSAGES ARE SENT *--

```

```

          FOR j IN 1..block_size LOOP

```

```

            byte_count := byte_count + 1;

```

```

            IF byte_count > msg_list(i).msg_length THEN

```

```

              msg_block (j) := space;

```

```

            ELSE

```

```

              msg_block (j) :=

```

```

                msg_list(i).message(byte_count);

```

```

            FND IF;

```

```
        END LOOP;
        No;
        Send_block (msg_block'ADDRESS, block_size);
        EXIT WHEN byte_count > msg_list(i).msg_length;
    END LOOP;
```

```
    END LOOP;  --MSG_COUNT--
```

```
        Yes;
    END IF;  --COMMAND--
```

```
END LOOP;  --MAIN--
```

```
END Bulletin;
```

```
=====
```

The following batch file (xfer.sub) is used to compile the preceding programs:

```
era myutil.sym
era myasmlib.sym
era xferfile.sym
era messages.sym
era directry.sym
era who.sym
era bullbrd.sym
era names.sym
era myutil.jrl
era myasmlib.jrl
era xferfile.jrl
era messages.jrl
era directry.jrl
era who.jrl
era bullbrd.jrl
era xfermain.jrl
era xfermain.cmd
janus names.spc
janus myutil.spc
janus myasmlib.spc
janus xferfile.spc
janus messages.spc
janus directry.spc
janus who.spc
janus bullbrd.spc
janus myutil
jasm86 myasmlib
janus xferfile
janus messages
janus directry
```

janus who  
janus bullbrd  
janus xfermain  
jlink xfermain  
era bulletin.jrl  
era bulletin.cmd  
janus bulletin  
jlink bulletin

LISTING OF CONCENTRATOR PROGRAMS

```
PACKAGE Concname IS
```

```
--* GLOBAL TYPES, CONSTANTS, AND VARIABLES *--
```

```
TYPE process_status IS
  RECORD
    sourceport: Integer;
    destport: Integer;
    process_type: byte;
  END RECORD;
```

```
max_que: CONSTANT := 552; --FOR 24 TERMINALS--
```

```
TYPE que IS ARRAY (1..max_que) OF process_status;
```

```
queue: que;
```

```
resend: CONSTANT BYTE := byte (16#01#);
```

```
zero: CONSTANT BYTE := byte (0);
```

```
machno: CONSTANT := 24;
```

```
ready: Boolean;
```

```
active_list: ARRAY (1..machno) OF Boolean;
```

```
END Concname;
```

```
=====
```

```
PACKAGE Concutil IS
```

```
  PROCEDURE Check_queue (number_que: IN Integer;
    port: IN Integer;
    que_id: OUT Integer;
    result_que: OUT Boolean);
```

```
  PROCEDURE Net_stat (destination: IN Integer);
```

```
END Concutil;
```

```
WITH Coasmlib, Concname;
```

```
PACKAGE BODY Concutil IS
```

```
  USE Coasmlib, Concname;
```

```
  PROCEDURE Check_queue (number_que: IN Integer;
    port: IN Integer;
    que_id: OUT Integer;
    result_que: OUT Boolean) IS
```

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: CHECK_QUEUE CHECKS THE QUEUE FOR WAITING *-
--* PROCESSES AND TELLS SOURCE AND DESTINATION WHAT, IF *-
--* ANYTHING, IS WAITING. BOOLEAN RESULT OF THE CHECK IS *-
--* AN OUTPUT PARAMETER. *-

```

```
BEGIN
```

```
IF number_que = 0 THEN
```

```
  --* NOTHING IN QUEUE *--
```

```
  result_que := false;
  Queue_status (port, zero);
```

```
ELSE
```

```
  FOR i IN 1..(number_que + 1) LOOP
    IF queue (i).destport = port THEN
      que_id := i;
      result_que := true;
      EXIT;
```

```
    END IF;
```

```
    que_id := i;
```

```
  END LOOP;
```

```
  IF que_id = (number_que + 1) THEN
```

```
    --* NOTHING IN QUEUE FOR POLLED PORT *--
```

```
    result_que := false;
    Queue_status (port, zero);
```

```
  ELSE
```

```
    FOR i IN 1..255 LOOP
      FOR j IN 1..255 LOOP
```

```
        --* DELAY FOR SOURCE *--
```

```
        NULL;
```

```
      END LOOP;
```

```
    END LOOP;
```

```
    --* POLL SOURCE OF WAITING PROCESS *--
```

```
    Check_port (queue(que_id).sourceport, ready);
```

```
    IF ready THEN
```

```
      --* TELL POLLED PORT WHAT IS WAITING FOR IT *--
```

```
      Queue_status (port, queue(que_id).process_type)
```

```
      --* TELL SOURCE OF WAITING PROCESS TO RESEND *-
```

```
Queue_status (queue(que_id).sourceport, resend);  
ELSE
```

```
--* TELL POLLED PORT TO GO AHEAD *--
```

```
result_que := false;  
Queue_status (port, zero);  
END IF;  
END IF;  
END IF;
```

```
END Check_queue;
```

```
-----  
PROCEDURE Net_stat (destination: IN Integer) IS
```

```
--* AUTHOR: THOMAS V. WORKS  
--* DATE: SEPTEMBER 1986  
--* DESCRIPTION: NET_STAT CHECKS THE ACTIVE_LIST FOR *--  
--* ACTIVE PORTS, PLACES LIST OF ACTIVE PORTS IN WHO_LIST, *--  
--* AND TRANSMITS DATA TO REQUESTING TERMINAL. *--
```

```
wnum: Integer := 0;  
who_length: Integer := 0;  
  
who_list: ARRAY (1..machno) OF byte;
```

```
BEGIN
```

```
FOR i IN 1..machno LOOP  
IF active_list (i) = true THEN
```

```
--* PLACE ACTIVE PORTS IN WHO LIST *--
```

```
wnum := wnum + 1;  
who_list (wnum) := byte (i);  
who_length := who_length + 1;  
END IF;  
END LOOP;
```

```
Send_who_block (destination, who_list'ADDRESS,  
who_length);
```

```
END Net_stat;
```

```
END Concutil;
```

```
=====
```

```
PACKAGE CoasmLib IS
```

```
PROCEDURE Check_port (prt: IN Integer; rdy: OUT Boolean);  
PROCEDURE Connect (prt: IN Integer; addr: IN Integer);
```

```

PROCEDURE Queue_status (prt: IN Integer; proc: IN byte);
PROCEDURE Send_who_block (dest: IN Integer; addr: IN Integer;
                          len: IN Integer);
PROCEDURE Broadcast (s_prt: IN Integer; t_input: OUT byte);
PROCEDURE Concxfer (s_prt: IN Integer; d_prt: IN Integer);
PROCEDURE Xfer (s_prt: IN Integer);
PROCEDURE No_xfer (s_prt: IN Integer);
END Coasmlib;

```

PACKAGE ASSEMBLY Coasmlib

```

jmp main

```

```

PROC Check_port;

```

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: CHECK_PORT CHECKS THE PORTS OF THE *--
--* NETWORK LOOKING FOR THE ACTIVE CODE (0D0h). IT TIMES *--
--* OUT IF THERE IS NO RESPONSE. CHECK_PORT ALSO *--
--* DETERMINES IF A DESTINATION PORT IS ACTIVE. THE *--
--* BOOLEAN RESULT IS THE OUTPUT PARAMETER. *--

```

```

ready_code      equ 2D0h
recv_rdy        equ 02h
timer           equ 10h

```

```

                pop ax                ;return address
                pop di                ;data address
                pop dx                ;dataport
                push dx
                push di                ;restore stack
                push ax

again:          inc dx                ;statport
                mov bl, timer         ;load timer
loop3:          dec bl
                jz nxtprt             ;go to next port if no input
                in al, dx             ;check for input
                and al, recv_rdy
                jz loop3
                dec dx                ;dataport
                in al, dx             ;get input
                out dx, al            ;echo input
                cmp al, ready_code    ;check for error
                jnz again             ;if error, get new input
more:          inc dx                ;statport
                mov bl, timer         ;load timer
time:          dec bl                ;timer to ensure echo received
                jz thsprt             ;go to this port if timer = 0

```

```

        in al, dx                ;check for input
        and al, recv_rdy
        jz time
        dec dx                  ;dataport
        in al, dx                ;get input
        out dx, al               ;echo input
        cmp al, ready_code      ;check for error
        jnz more                ;if error get new input
thsprt:  mov [di], 01           ;set ready to true
        ret
nxtprt:  mov [di], 00           ;set ready to false
        ret

```

END PROC Check\_port;

-----  
PROC Connect;

--\* AUTHOR: THOMAS V. WORKS

--\* DATE: AUGUST 1986

--\* DESCRIPTION: CONNECT RECEIVES THE CONNECTION RECORD \*--

--\* FROM SETUP. \*--

```

error_code      equ 0EFh
finish_code     equ 0FFh

```

```

        pop ax                  ;return address
        pop di                  ;data structure address
        pop dx                  ;dataport
        push ax                 ;restore stack

here4:  inc dx                  ;statport
        in al, dx               ;wait for data
        and al, recv_rdy
        jz here4
        dec dx                  ;dataport
        in al, dx               ;get data
        out dx, al              ;echo data
        cmp al, error_code      ;check for error code
        jz errors
        cmp al, finish_code     ;check for finish code
        jz done
        mov [di], al           ;store data
        inc di                  ;go to next location
        inc dx                  ;statport
        jmp here4              ;get next data

errors:  dec di                 ;go back to previous position
        inc dx                  ;statport
here5:  in al, dx               ;wait for retransmitted data
        and al, recv_rdy
        jz here5
        dec dx                  ;dataport

```

```

        in al, dx                ;get retransmitted data
        out dx, al              ;echo retransmitted data
        mov [di], al           ;overwrite bad data
        inc di                  ;go to next location
        inc dx                  ;statport
        jmp here4              ;get next data

done:    ret

END PROC Connect;

PROC Queue_status;

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: QUEUE_STATUS TELLS THE SOURCE AND *--
--* DESTINATION PORTS ABOUT THE PROCESSES WAITING IN THE *--
--* QUEUE. *--

        pop ax                  ;return address
        pop dx                  ;dataport
        pop si                  ;value of queue status
        push ax                 ;restore stack

redo:    mov ax, si
        out dx, ax              ;send out queue status
        inc dx                  ;statport
loop5:   in al, dx              ;wait for echo
        and al, rcv_rdy
        jz loop5
        dec dx                  ;dataport
        in al, dx              ;get echo
        cmp ax, si             ;check for error
        jnz redo               ;if error, retransmit
        ret                    ;if not, finish

END PROC Queue_status;

```

---

```

PROC Send_who_block;

```

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: SEND_WHO_BLOCK TRANSMITS THE LIST OF *--
--* ACTIVE PORTS FOLLOWED BY A SEQUENCE OF FOUR FINISH *--
--* CODES (0FFh) INDICATING END OF LIST TO THE REQUESTING *--
--* TERMINAL. *--

        pop ax                  ;return address
        pop bx                  ;length of data structure
        pop si                  ;data structure address
        pop dx                  ;destination port (data)
        push ax                 ;restore stack

```

```

loopb:  mov ch, 4                ;finish_code counter
        mov al, [si]           ;send out char
        out dx, al
        inc dx                 ;statport
loopa:  in al, dx               ;wait for echo
        and al, recv_rdy
        jz loopa
        dec dx                 ;dataport
        in al, dx              ;get echo
        cmp al, [si]           ;check for error
        jnz error1
        inc si                  ;get new char
        dec bx                  ;decrement length
        jnz loopb              ;do again until length = 0
        jmp over

error1: mov al, error_code      ;error in transmission
        out dx, al
        inc dx                 ;statport
loopd:  in al, dx               ;wait for echo
        and al, recv_rdy
        jz loopd
        dec dx                 ;dataport
        in al, dx              ;was error code received
        cmp al, error_code
        jnz error1             ;if not, retransmit error code
error2: mov al, error_code      ;send second error code
        out dx, al
        inc dx                 ;statport
loopd2: in al, dx              ;wait for echo
        and al, recv_rdy
        jz loopd2
        dec dx                 ;dataport
        in al, dx              ;was error code received
        cmp al, error_code
        jnz error2             ;if not, retransmit error code
        jmp loopb              ;retransmit char

over:   mov al, finish_code     ;end of transmission
        out dx, al
        inc dx                 ;statport
loopc:  in al, dx               ;wait for echo
        and al, recv_rdy
        jz loopc
        dec dx                 ;dataport
        in al, dx              ;get echo
        cmp al, finish_code     ;check for error
        jnz error3
        dec ch                  ;send out next finish code
        jnz over                ;until four are sent out
        ret                     ;done

```

```

error3:  mov al, finish_code
         out dx, al           ;retransmit
         inc dx              ;statport
         jmp loopc          ;check again

```

```

END PROC Send_who_block;
-----

```

```

PROC Broadcast;

```

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTFMBER 1986
--* DESCRIPTION: BROADCAST TRANSMITS DATA RECEIVED FROM *--
--* THE SOURCE TO ALL ACTIVE DESTINATION TERMINALS, *--
--* BYPASSING THE SOURCE AND THE BULLETIN BOARD PORTS. A *--
--* BYTE IS RECEIVED FROM THE SOURCE AND TRANSMITTED TO *--
--* EACH DESTINATION, THEN BROADCAST CHECKS EACH ECHO FOR *--
--* ERROR. BROADCAST FINISHES WHEN IT RECEIVES A SEQUENCE *--
--* OF FOUR FINISH CODES (0F1h) FROM EACH DESTINATION. *--

```

```

portnum      equ 08h
boardnum     equ 03h
ctr          equ 04h
portone      equ 0100h
bullport     equ 019Ch

```

```

        pop ax              ;return address
        pop di              ;temporary input holder
        pop si              ;source port (data)
        push si             ;restore stack
        push di
        push ax

        mov ch, 0           ;load error code counter
        mov cl, ctr        ;load finish code counter
        mov bl, portnum
        mov bh, boardnum
        mov dx, si         ;load source port
nextch: inc dx              ;statport
l_one:   in al, dx          ;wait for input
        and al, rcv_rdy
        jz l_one
        dec dx              ;dataport
        in al, dx          ;get input
        mov [di], al       ;store input
        mov dx, portone    ;load first destination port
l_two:  cmp dx, si         ;do not send to source port
        jz skip
        cmp dx, bullport   ;or to bulletin board port
        jz skip
        out dx, al         ;send input
skip:   add dx, 4          ;next destination port

```

```

dec bl
jnz l_two ;continue sending until all
;ports are addressed

add dx, 32 ;next board
mov bl, portnum ;reload
dec bh
jnz l_two ;continue sending until all
;boards are addressed
;reload for echo checking

mov bl, portnum
mov bh, boardnum
mov dx, portone ;load first destination port
l_three: cmp dx, si ;do not check source port
jz next
cmp dx, bullport ;or bulletin board
jz next
inc dx ;statport
in al, dx ;wait for echo
dec dx ;dataport
and al, recv_rdy
jz next ;go to next port if no response
in al, dx ;get echo
cmp al, [di] ;check for error
jnz errorb
next: add dx, 4 ;next destination port
dec bl
jnz l_three ;continue receiving until all
;ports are addressed

add dx, 32 ;next board
mov bl, portnum ;reload
dec bh
jnz l_three ;continue receiving until all
;boards are addressed
;reload

mov bh, boardnum
cmp ch, 0 ;if no errors, continue
jz cont

;ERROR HANDLER
loop10: pop dx ;get next error address (data)
loop11: inc dx ;statport
l_six: in al, dx ;wait for echo
and al, recv_rdy
jz l_six
dec dx ;dataport
in al, dx ;get echo
cmp al, error_code ;check for error
jnz reerror
mov al, [di] ;if no error, retransmit char
;input

out dx, al
inc dx ;statport
l_seven: in al, dx ;wait for echo
and al, recv_rdy

```

```

        jz l_seven
        dec dx
        in al, dx
        cmp al, [di]
        jnz reerror
        dec ch
        jnz loop10
        jmp cont

reerror: mov al, error_code
        out dx, al
        jmp loop11

errorb: push dx
        inc ch
        mov al, error_code
        out dx, al
        jmp tack

cont:   mov al, [di]
        mov dx, si
        out dx, al
        cmp al, end_process
        jnz no_end
        dec cl
        jz finis

        jmp nextch

no_end: mov cl, ctr
        jmp nextch

finis:  ret

END PROC Broadcast;

```

-----  
PROC Concxfer;

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: AUGUST 1986
--* DESCRIPTION: CONCXFER TRANSMITS DATA RECEIVED FROM *--
--* THE SOURCE TO THE ACTIVE DESTINATION TERMINAL. A BYTE *--
--* IS RECEIVED FROM THE SOURCE AND TRANSMITTED TO THE *--
--* DESTINATION, WITHOUT ERROR CHECKING. ERROR CHECKING IS *--
--* DONE BY THE TERMINALS. CONCXFER FINISHES WHEN IT *--
--* RECEIVES A SEQUENCE OF FOUR FINISH CODES (0F1h) FROM *--
--* THE DESTINATION. *--

```

```

end_process      equ 0F1h

                pop ax                ;return address
                pop cx                ;destport (data)
                pop bx                ;sourceport (data)
                push ax               ;restore stack

                mov di, 4             ;finish code counter
                mov dx, bx            ;sourceport (data)
start:          inc dx, 0             ;statport
loop1:          in al, dx              ;check for incoming char
                and al, recv_rdy
                jz loop1
                dec dx                ;dataport
                in al, dx             ;get incoming char
                mov dx, cx            ;destport (data)
                out dx, al            ;send char to receiver
                inc dx                ;statport
loop2:          in al, dx              ;check for echo
                and al, recv_rdy
                jz loop2
                dec dx                ;dataport
                in al, dx             ;get echo
                mov dx, bx            ;sourceport (data)
                out dx, al            ;send echo to transmitter
                cmp al, end_process   ;if end process code, begin
                ;counting
                jnz notyet            ;if not, get next char
                dec di                ;until four end process codes
                ;are received

                jz fini
                jmp start
notyet:         mov di, 4             ;reload finish code counter
                jmp start

fini:          ret

```

END PROC Concxfer;

-----  
PROC Xfer;

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTFMBER 1986
--* DESCRIPTION:  XFER TRANSMITS THE XFER CODE (1) TO THE *--
--* SOURCE INDICATING THAT THE DESTINATION TERMINAL IS *--
--* ACTIVE.                                             *--

```

```

                pop ax                ;return address
                pop dx                ;sourceport (data)
                push ax               ;restore stack

```

```

xmit1:  mov al, 01          ;set send_ready to true
        out dx, al
        inc dx            ;statport
loopx1: in al, dx          ;wait for echo
        and al, rcv_rdy
        jz loopx1
        dec dx            ;dataport
        in al, dx         ;get echo
        cmp al, 01       ;check for error
        jnz xmit1        ;if error, retransmit

        ret

```

END PROC Xfer;

-----

PROC No\_xfer;

```

--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: NO_XFER TRANSMITS THE NO_XFER CODE (0) *--
--* TO THE SOURCE INDICATING THAT THE DESTINATION TERMINAL *--
--* IS NOT ACTIVE. *--

```

```

        pop ax            ;return address
        pop dx            ;sourceport (data)
        push ax           ;restore stack

xmit2:  mov al, 00          ;set send_ready to false
        out dx, al
        inc dx            ;statport
loopx2: in al, dx          ;wait for echo
        and al, rcv_rdy
        jz loopx2
        dec dx            ;dataport
        in al, dx         ;get echo
        cmp al, 00       ;check for error
        jnz xmit2        ;if error, retransmit

        ret

```

END PROC No\_xfer;

main:

END Coasmlib;

=====

```

WITH Coasmlib, Concutil, Concname;
PACKAGE BODY Poll IS
    USE Coasmlib, Concutil, Concname;

```

```
--*****--
--* MAIN CONCENTRATOR PROGRAM *--
--*****--
```

```
TYPE conctn IS
  RECORD
    process: byte;
    source: byte;
    destination: byte;
  END RECORD;
```

```
connection: conctn;
```

```
ctrl_f: CONSTANT BYTE := byte (16#06#);
ctrl_m: CONSTANT BYTE := byte (16#0D#);
ctrl_d: CONSTANT BYTE := byte (16#04#);
ctrl_w: CONSTANT BYTE := byte (16#17#);
ctrl_b: CONSTANT BYTE := byte (16#02#);
```

```
bcardno: CONSTANT := 3;
portno: CONSTANT := 8;
firstport: CONSTANT := 16#100#;
lastport: CONSTANT := 16#19C#; --BULLETIN BOARD--
```

```
pollport: Integer;
inqueue: Boolean;
numqueue: Integer := 0;
index: Integer := 0;
new_queue: Integer;
machine_count: Integer := 0;
input: byte;
```

```
PROCEDURE Convert (idx: IN Integer) IS
```

```
--* AUTHOR: THOMAS V. WORKS
--* DATE: SEPTEMBER 1986
--* DESCRIPTION: CONVERT CONVERTS THE CONNECTION RECORD *--
--* RECEIVED FROM THE TERMINAL TO PHYSICAL PORT ADDRESSES. *--
```

```
BEGIN
```

```
  CASE queue(idx).destport IS
    WHEN 1 => queue(idx).destport := 16#100#;
    WHEN 2 => queue(idx).destport := 16#104#;
    WHEN 3 => queue(idx).destport := 16#108#;
    WHEN 4 => queue(idx).destport := 16#10C#;
    WHEN 5 => queue(idx).destport := 16#110#;
    WHEN 6 => queue(idx).destport := 16#114#;
    WHEN 7 => queue(idx).destport := 16#118#;
    WHEN 8 => queue(idx).destport := 16#11C#;
    WHEN 9 => queue(idx).destport := 16#140#;
    WHEN 10 => queue(idx).destport := 16#144#;
```

```

WHEN 11 => queue(idx).destport := 16#148#;
WHEN 12 => queue(idx).destport := 16#14C#;
WHEN 13 => queue(idx).destport := 16#150#;
WHEN 14 => queue(idx).destport := 16#154#;
WHEN 15 => queue(idx).destport := 16#158#;
WHEN 16 => queue(idx).destport := 16#15C#;
WHEN 17 => queue(idx).destport := 16#180#;
WHEN 18 => queue(idx).destport := 16#184#;
WHEN 19 => queue(idx).destport := 16#188#;
WHEN 20 => queue(idx).destport := 16#18C#;
WHEN 21 => queue(idx).destport := 16#190#;
WHEN 22 => queue(idx).destport := 16#194#;
WHEN 23 => queue(idx).destport := 16#198#;
WHEN 24 => queue(idx).destport := 16#19C#;
WHEN OTHERS => NULL;
END CASE;

```

```

CASE queue(idx).sourceport IS
WHEN 1 => queue(idx).sourceport := 16#100#;
WHEN 2 => queue(idx).sourceport := 16#104#;
WHEN 3 => queue(idx).sourceport := 16#108#;
WHEN 4 => queue(idx).sourceport := 16#10C#;
WHEN 5 => queue(idx).sourceport := 16#110#;
WHEN 6 => queue(idx).sourceport := 16#114#;
WHEN 7 => queue(idx).sourceport := 16#118#;
WHEN 8 => queue(idx).sourceport := 16#11C#;
WHEN 9 => queue(idx).sourceport := 16#140#;
WHEN 10 => queue(idx).sourceport := 16#144#;
WHEN 11 => queue(idx).sourceport := 16#148#;
WHEN 12 => queue(idx).sourceport := 16#14C#;
WHEN 13 => queue(idx).sourceport := 16#150#;
WHEN 14 => queue(idx).sourceport := 16#154#;
WHEN 15 => queue(idx).sourceport := 16#158#;
WHEN 16 => queue(idx).sourceport := 16#15C#;
WHEN 17 => queue(idx).sourceport := 16#180#;
WHEN 18 => queue(idx).sourceport := 16#184#;
WHEN 19 => queue(idx).sourceport := 16#188#;
WHEN 20 => queue(idx).sourceport := 16#18C#;
WHEN 21 => queue(idx).sourceport := 16#190#;
WHEN 22 => queue(idx).sourceport := 16#194#;
WHEN 23 => queue(idx).sourceport := 16#198#;
WHEN 24 => queue(idx).sourceport := 16#19C#;
WHEN OTHERS => NULL;
END CASE;

```

```

END Convert;

```

```

BEGIN
  LOOP --MAIN--
    pollport := firstport;
    machine_count := 0;

```

```

Outer:
  FOR i IN 1..boardno LOOP
    FOR j IN 1..portno LOOP
      machine_count := machine_count + 1;
      active_list(machine_count) := false;
      Check_port (pollport, ready);
      IF ready THEN
        active_list(machine_count) := true;

        --* CHECK QUEUE FOR WAITING PROCESSES FOR *--
        --* POLLED PORT *--

        Check_queue (numqueue, pollport, index,
                     inqueue);

        IF inqueue THEN

          --* SERVICE WAITING PROCESS FIRST *--
          --* ESTABLISH CONNECTION WITH SOURCE OF *--
          --* WAITING PROCESS *--

          Connect (queue(index).sourceport,
                  connection'ADDRESS);

          --* DECODE CONNECTION RFCORD *--

          queue(index).sourceport :=
            Integer (connection.source);
          queue(index).destport :=
            Integer (connection.destination);
          queue(index).process_type :=
            connection.process;
          Convert (index);

          --* TELL SOURCE TO SEND *--

          Xfer (queue(index).sourceport);

          --* ESTABLISH DATA COMMUNICATION CHANNEL *--

          Concxfer (queue(index).sourceport,
                   queue(index).destport);

          --* REMOVE PROCESS FROM QUEUE *--

          numqueue := numqueue - 1;
          FOR m IN 1..255 LOOP
            FOR n IN 1..255 LOOP
              NULL;
            --* DELAY TO ALLOW RECEIVER TO GET READY *--
            --* TO SEND *--
          END LOOP;
        END LOOP;
      END LOOP;
    END LOOP;
  END LOOP;

```

```

END LOOP;
Check_port (pollport, ready);

--* IF POLLED PORT DOES NOT SEND IN *--
--* TIME, RESUME POLLING FROM START *--
EXIT Outer WHEN NOT ready;

--* WHEN WAITING PROCESS IS FINISHED *--
--* TELL POLLED PORT NOTHING WAITING *--
--* AND PROCESS ORIGINAL REQUEST *--
Queue_status (pollport, zero);
END IF; --INQUEUE--

--* PROCESS NEW REQUEST *--
--* ESTABLISH CONNECTION WITH SOURCE OF *--
--* ORIGINAL REQUEST *--

Connect (pollport, connection'ADDRESS);

--* LATEST QUEUE POSITION *--

new_queue := numqueue + 1;

--* DECODE CONNECTION *--

queue(new_queue).sourceport :=
    Integer (connection.source);
queue(new_queue).destport :=
    Integer (connection.destination);
queue(new_queue).process_type :=
    connection.process;
Convert (new_queue);

IF connection.destination = byte (0) THEN

--* POLL ALL DESTINATION PORTS EXCEPT *--
--* SOURCE AND BULLETIN BOARD *--

pollport := firstport;
FOR k IN 1..portno LOOP
    IF (pollport /=
        queue(new_queue).sourceport)
        AND (pollport /= lastport) THEN
        Check_port (pollport, ready);
        IF ready THEN

--* TELL DESTINATION *--

            queue_status (pollport,
                connection.process);
        END IF;
    END IF;
END IF;

```

```

        pollport := pollport + 4;
END LOOP;

FOR n IN 1..255 LOOP
    FOR m IN 1..255 LOOP
        NULL; --* DELAY TO ALLOW RECEIVER *--
                --* TO GET READY *--
    END LOOP;
END LOOP;

--* TELL SOURCE TO BROADCAST *--

Xfer (queue(new_queue).sourceport);
Broadcast (queue(new_queue).sourceport,
            input);

--* RESET POLLPORT AND RESUME POLLING *--

pollport := queue(new_queue).sourceport;
ELSIF connection.process = ctrl_w THEN

    --* TELL SOURCE TO RECEIVE NET STATUS *--
    --* THEN SEND NET STATUS *--

    Xfer (pollport);
    Net_stat (pollport);
ELSE

    --* PROCESS NORMAL REQUEST *--

    --* IS DESTINATION ACTIVE? *--

    Check_port (queue(new_queue).destport,
                ready);

    IF ready THEN

        --* TELL DESTINATION WHAT IS COMING *--

        Queue_status (queue(new_queue).destport,
                       queue(new_queue).process_type);

        --* TELL SOURCE TO SEND *--

        Xfer (pollport);
        IF connection.process = ctrl_b THEN

            --* ESTABLISH CONNECTION WITH *--
            --* BULLETIN BOARD *--

            Concxfer (queue(new_queue).destport,
                      queue(new_queue).sourceport);

```

```

ELSE
    --* ESTABLISH DATA COMMUNICATION *--
    --* CFANNEL *--
    Concxfer (queue(new_queue).sourceport,
              queue(new_queue).destport);
END IF;
ELSE
    --* TELL SOURCE, DESTINATION INACTIVE *--
    No_xfer (pollport);
    IF (queue(new_queue).process_type = ctrl_
    OR (queue(new_queue).process_type = ctrl_
    THEN
        --* PLACE PROCESS IN QUFUE *--
        --* IF FILE OR MESSAGE *--
        numqueue := numqueue + 1;
    END IF;
    END IF;
    FND IF;
    END IF; --READY--
    pollport := pollport + 4;
    EXIT WHEN pollport = lastport;
    --* DON'T POLL BULLETIN BOARD *--
    END LOOP; --INNER FOR LOOP--
    pollport := pollport + 32;
    END LOOP Outer;
    FND LOOP; --MAIN LOOP--
END Poll;
=====

```

The following batch file (conc.sub) is used to compile the preceding programs:

```

era coasmlib.sym
era concutil.sym
era concname.sym
era concutil.jrl
era coasmlib.jrl
era poll.jrl
era poll.cmd

```

janus concname.spc  
janus coasmlib.spc  
janus concutil.spc  
jasm86 coasmlib  
janus concutil  
janus poll  
jlink poll

GLOSSARY

## 1. Z-100

Z-100 is the specific model name for the micro-computers used in this network. The vendor is Zenith Data Systems.

## 2. SBC

SBC is an acronym for Single Board Computer. It is a configuration of VLSI (Very Large Scale Integration) circuitry on one computer board capable of performing the functions of a computer. The SBC is the driving force in the Concentrator. The vendor of the 86/12A SBC used in this thesis is Intel Corporation.

## 3. Concentrator

The Concentrator is the collection of hardware and software that performs the network switching functions.

## 4. MULTIBUS

MULTIBUS is the specific model name for the hardware that allows multiple SBC's to communicate directly with common memory.

## 5. Local Area Network

A Local Area Network is any network that operates exclusively within a low radius (max 50 miles) region; usually a single building or a group of buildings.

## 6. Workstation

A Workstation is viewed as the Z-100 microcomputer and associated peripheral devices that perform the application functions of the network.

## 7. Process

Processes are viewed as the transfer of files, messages, or directories between Z-100 workstations. Each process has a sending and a receiving function.

## 8. Communication

Communication is viewed as transmitting data and/or commands between the sending and receiving functions of a process.

## 9. Data Communication Channel

Data Communication Channel refers to the channel or 'pathway' used to transfer intra-process communications between Z-100 workstations.

## 10. Circuit Switching

Circuit Switching refers to the method of network communication whereby the entire message containing data and commands is transmitted from the sender to the receiver along a dedicated communication channel.

## 11. Ports

Ports are channels through which processes communicate.

12. USART

USART is an acronym for Universal Synchronous/Asynchronous Receiver/Transmitter. It is a microprocessor that provides communication interface between computers or between a computer and a peripheral device.

13. NPS

NPS is an acronym for Naval Postgraduate School, Monterey, California.

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2

Thesis  
W8751 Works  
c.1 JANUS/Ada software im-  
plementation of a star  
cluster local area net-  
work of personal compu-  
ters.

Thesis  
W8751 Works  
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