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**LARGE-SCALE SIMULATIONS OF MONOLITHIC
AND SEGMENTED PROJECTILES
IMPACTING SPACED ARMOR**

**DANIEL R. SCHEFFLER
THOMAS M. SHERRICK**

FEBRUARY 1990

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1. INTRODUCTION

Within the last several years there has been a lot of interest in the performance of segmented kinetic energy penetrators at velocities greater than 2 km/s. Both experimental and analytical investigations of the penetration mechanisms have been conducted. For example, in 1981 V. Kucher¹, conducted 2-D simulations of a segmented projectile that showed improved performance for segmented projectiles and improved performance with increased segment spacing. Since then, several computer studies have been conducted, among them W. de Rosset and K. D. Kimsey², D. R. Scheffler³, and R. T. Sedgwick and co-workers⁴, all showed improved penetrator performance for the segmented rod over an equivalent mass and diameter monolithic rod. In addition to computer simulations, experiments conducted by A. Charters^{5,6,7} and Bell⁸ also suggest that segmented penetrators exhibit improved performance.

Numerical simulations are well suited for the study of segmented kinetic energy penetrators. Numerical studies permit the examination of segmented penetrators without the typical problems encountered in ballistic tests such as; alignment of the individual segments, constraints of pre-extended projectile lengths, projectile yaw, structural integrity of the launch package, and synergistic effects of carrier tubes or carrier rods on overall penetration. Thus, simulations can increase our understanding of the penetration phenomenon as well as supplement the limited ballistic test data.

Most of the data in the literature concentrates on the performance of high-velocity segmented kinetic energy penetrators against semi-infinite steel armor. Some ballistic tests of segmented projectiles impacting spaced plate arrays have been conducted; however, the data is sparse. For example, A. Charters^{5,6,7} conducted a limited number of ballistic tests showing that each segment "punches through" a target plate in an array allowing the remaining segments to pass through undisturbed, each defeating one plate. Since computations are well suited for modeling segmented projectile impacts, a series of three-dimensional simulations have been conducted to characterize the penetration/perforation phenomenon against spaced armor. The projectile impacts were modeled using version 121 of the HULL finite-difference code.

HULL^{10,11} is an Eulerian wave propagation code that uses a second order accurate finite-difference scheme. The material advection scheme is first order. The code solves the partial differential equations of continuum mechanics ignoring heat conduction and viscosity terms. The Mie-Gruneisen equation of state is used to model solids. After vaporization occurs, the Gamma Law equation is used to model the gas. Explosives can be modeled using the Jones-Wilkins-Lee equation of state. Material failure models include: maximum principle stress, maximum principle strain, and the Hancock-Mackenzie triaxial failure model¹². When material failure occurs, a numerically significant void (i.e. air), is introduced in the cell which permits relaxation of the tensile forces. Recompression is permitted.

2. SIMULATION MATRIX

A series of three-dimensional simulations have been conducted to determine the performance of segmented projectiles striking spaced armor. The performance of the segmented projectile is measured relative to an equivalent mass monolithic penetrator. The length-to-diameter ratio, L/D, of the monolithic tungsten alloy (90W-7Ni-3Fe) penetrator is 20, with a total mass of 274 grams. The segmented projectile geometry separates the monolithic rod into N individual segments with the same diameter as the monolithic projectile.

A number of impact conditions have been modeled to characterize the effects of: striking velocity (1.5-4.0 km/s); target thickness-to-penetrator diameter ratio, T/D, (2 and 4); segment spacing-to-penetrator diameter ratio, S/D, (0 to 8); and the number of individual segments, N, (5 and 20) on penetration/perforation performance. The computational matrix is summarized in the Table 1. For the cases modeled, the target was comprised of two rolled homogeneous armor (RHA) plates with the same T/D ratio and a normal spacing of 50.8 mm at an obliquity of 60 degrees.

Table 1. Computational Matrix (Nominal Projectile Mass 274 grams).

Problem No.	Velocity (km/s)	N*	S/D*	T/D
5.0004	1.5	5	1	2
5.0000	1.5	1	0	2
5.0005	2.0	5	1	2
5.0001	2.0	1	0	2
5.0006	3.0	5	1	2
5.0002	3.0	1	0	2
5.0007	4.0	5	1	2
5.0003	4.0	1	0	2
518.8800	2.0	5	1	4
6.0002	2.0	1	0	4
518.8833	3.0	5	1	4
6.0003	3.0	1	0	4
518.8844	4.0	5	1	4
6.0004	4.0	1	0	4
7.0001	4.0	5	4	4
7.0002	4.0	5	8	4
8.0000	4.0	20	1	4

*NOTE: N = 1 implies a monolithic projectile
D = 10mm constant projectile diameter

In an effort to preserve material interfaces and minimize material diffusion typically encountered in Eulerian codes, a constant subgrid was chosen for the x-y plane covering a region two diameters away from the penetrator. The constant subgrid provides six cells across the diameter of the penetrator. Beyond the constant subgrid in the x-y plane, an expansion factor of 1.1 was used to keep problem size and runtime within practical limits. In the z-direction, or axial direction, a constant cell spacing was used, which was 1.5 times the spacing of the constant subgrid in the x-y plane. The number of cells used to model a particular problem depended on the size of the target plates and overall length of the penetrator; however, the cell sizes in the constant sub-grid remained the same for all simulations. Appendix A contains a listing of KEEL input data for all of the problems modeled. If the only difference in a particular problem was the striking velocity, input data is listed for only one velocity.

The hydrodynamic behavior of the metals were modeled using the Mie-Gruneisen equation of state. The coefficients for the equation of state data were obtained from Kohn¹³.

An incremental elastic-plastic formulation following the description given by Wilkins¹⁴ is used to describe the deviatoric response of the metals. An elastic-perfectly plastic model has been used for the tungsten alloy and RHA with

20 kb^{1/2} and 15 kb^{1/2} yield strengths, respectively. A complete listing of the material properties and equation of state data are provided in Appendix B.

3. RESULTS AND DISCUSSION

Residual penetrator mass and residual kinetic energy have been used to measure performance. The greater the residual penetrator mass at a given velocity, the greater its performance. Residual mass was determined using the same technique ballisticians use to determine residual mass from radiographs. The complete set of density contour plots from which residual mass was determined can be found in Appendix C. Residual kinetic energy was determined using the residual mass from density contour plots and the velocity from velocity histograms. For the segmented penetrators residual energy is the summation of the individual segment residuals.

Results for the simulations against the RHA spaced plates for T/D of 2 are summarized in Table 2. Table 2 shows a significantly greater (31 percent) residual mass for the monolithic penetrator at a velocity of 1.5 km/s. The residual kinetic energy of both monolithic and segmented penetrators are about the same. At higher striking velocities the segmented penetrator shows essentially the same if not greater performance than the monolithic penetrator. Figures 1 to 5 show velocity histograms and density contour plots for the segmented penetrator at a velocity of 1.5 km/s at various times. The figures show a sequence of events in which individual segments collide and eventually become misaligned, i.e. not colinear. At 2 km/s collisions between individual segments still occur. Figures 6 to 8 show the lead segment losing velocity after perforating the first target allowing the next segment to catch up. However, misalignment of individual segments is not observed. The collisions tend to make the segmented rod appear much like a monolithic rod since the lead segment is not entirely eroded before being impacted by a subsequent segment. At 4 km/s, see Figures 9 and 10, most of the lead segment is eroded in perforating the first target plate. Though the lead segment is impacted by the second segment, only minimal loss of kinetic energy takes place in the second segment. Trailing segments uninvolved in collision retain their initial velocities and suffer no loss in kinetic energy. Due to the decrease in the time interval between target plates, no further collisions occur until lead segments impact the next plate.

TABLE 2. Residual Mass of Monolithic and Segmented Rods (N=5, S/D=1) against T/D=2 Spaced Plates

Striking Velocity (km/s)	Striking Energy (MJ)	Segmented Residual Mass (gms)	Segmented Residual Energy (MJ)	Monolithic Residual Mass (gms)	Monolithic Residual Energy (MJ)
1.5	0.308	47.9	0.016	63.0	0.018
2.0	0.548	107.0	0.166	108.0	0.147
3.0	1.233	149.0	0.637	143.0	0.589
4.0	2.192	152.0	1.183	150.0	1.141

Results for the simulations against the RHA spaced plates for T/D of 4 are summarized in Table 3. Simulations at a velocity of 1.5 km/s were conducted, however, both the monolithic and segmented penetrators failed to perforate the second target plate and are therefore not included. Table 3 shows higher residual mass for the segmented penetrator at all striking velocities. The data presented in Table 3 shows the greater the striking velocity, the greater the increase in residual mass. Figures 11 and 12 show velocity histograms and contour plots for the segmented penetrator at a velocity of 2.0 km/s. As with the simulation for the T/D of 2 case at a velocity of 1.5 km/s, individual

segment interactions occur which lead to the misalignment of segments. At 3 km/s, more of the lead segment is eroded before any interaction occurs, see Figure 13. In Figure 13, what appears to be a single segment is a fraction of the preceding segment and the subsequent segment. The alignment of the segments is less severely affected, see Figure 14. Segment interactions are also observed well after perforation of the second target plate, leading to severe misalignment of the segments, see Figure 15. At 4 km/s the lead segment is almost entirely eroded before interactions occur, see Figure 16. In Figure 16, what appears to be a single lead segment is the almost entirely eroded second segment being impacted by the third segment.

TABLE 3. Residual Mass of Monolithic and Segmented Rods (N=5, S/D=1) against T/D=4 Spaced Plates

Striking Velocity (km/s)	Striking Energy (MJ)	Segmented Residual Mass (gms)	Segmented Residual Energy (MJ)	Monolithic Residual Mass (gms)	Monolithic Residual Energy (MJ)
2.0	0.548	18.4	0.0018	14.6	0.0003
3.0	1.233	68.6	0.250	58.1	0.186
4.0	2.192	99.9	0.725	62.0	0.413

The interactions between segments for both T/D of 2 and 4, suggest a spacing of 1 D is not optimum. The effect of segment spacing on performance for the T/D of 4 target has been studied numerically for segment spacing-to-penetrator diameter ratios, S/D, of 4 and 8. No segment interactions occurred in perforating the spaced plate array. However, the two lead segments for the S/D of 4 case collided well after ($t=100$ micro-seconds) perforating the second plate. This occurs because the lead segment did not completely erode during perforation of the second spaced plate. Thus the lead segment loses velocity allowing remaining segments to catch up. Table 4 shows the affect of segment spacing on penetrator performance. Note that as S/D increases the residual penetrator mass increases.

TABLE 4. Residual Mass vs Segment Spacing for Vs = 4.0 km/s, N = 5, and T/D = 4 Plates

Spacing Diameter	Residual Mass (gms)	Residual Energy (MJ)
none	62.0	0.413
1	99.0	0.725
4	108.0	0.864
8	126.0	0.985
1*	129.0	1.183

* 20 Segment Rod

Table 4 also presents the results for a 20 segment projectile with a S/D of 1. These results suggest that trailing segments, unaffected by impact with the spaced plates and/or individual segment interactions, retain more kinetic energy than an equivalent monolithic rod. Figures 17 and 18 show velocity histograms and density contour plots of the 20 segment penetrator and the equivalent monolithic penetrator. The monolithic penetrator's velocity is

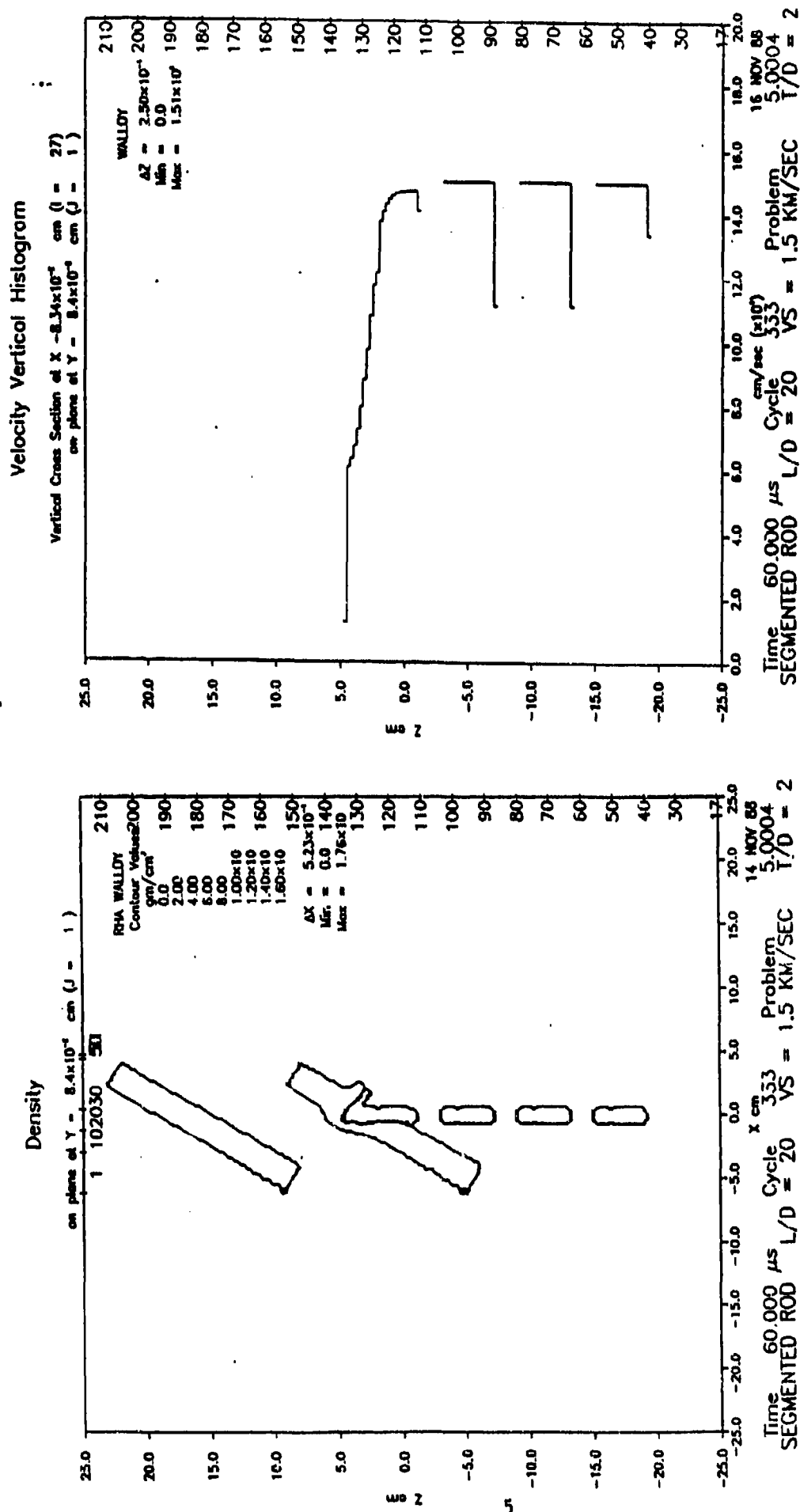


Figure 1. Segmented penetrator, $N=5$, $V=1.5$ km/s into 00° RHA ($T/D=2$) at 80 micro-seconds

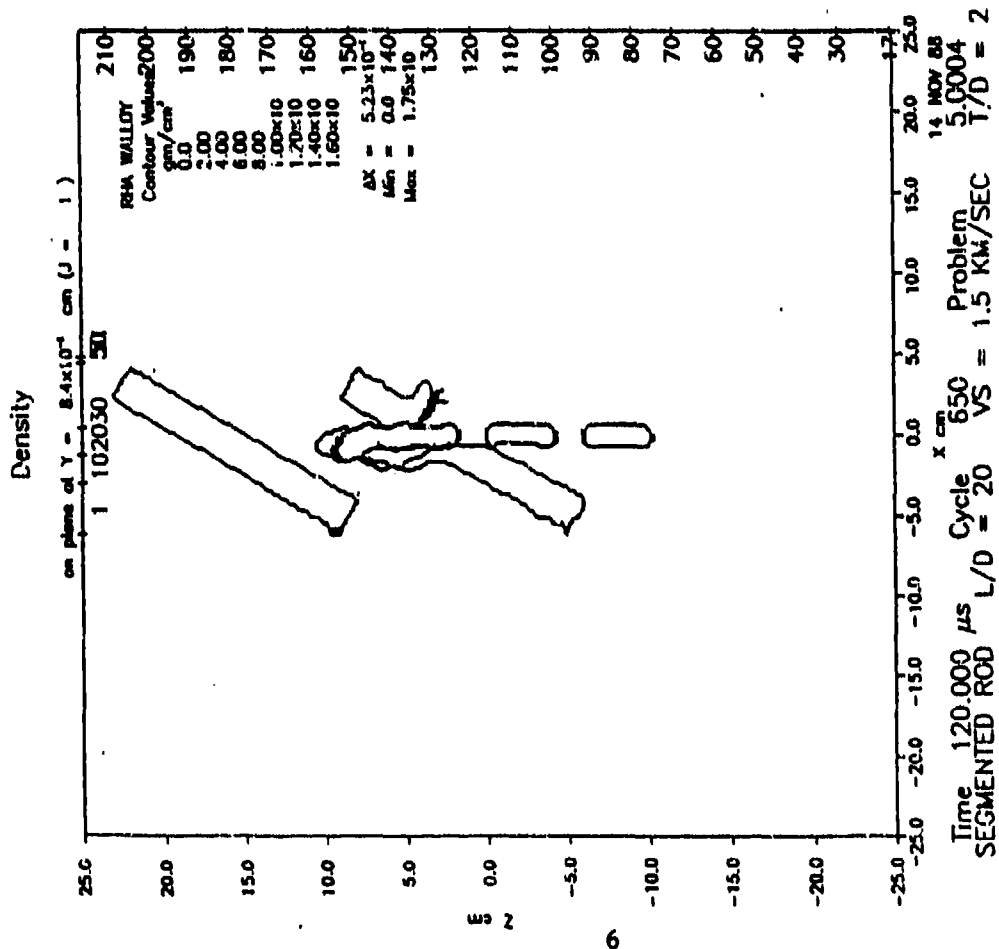
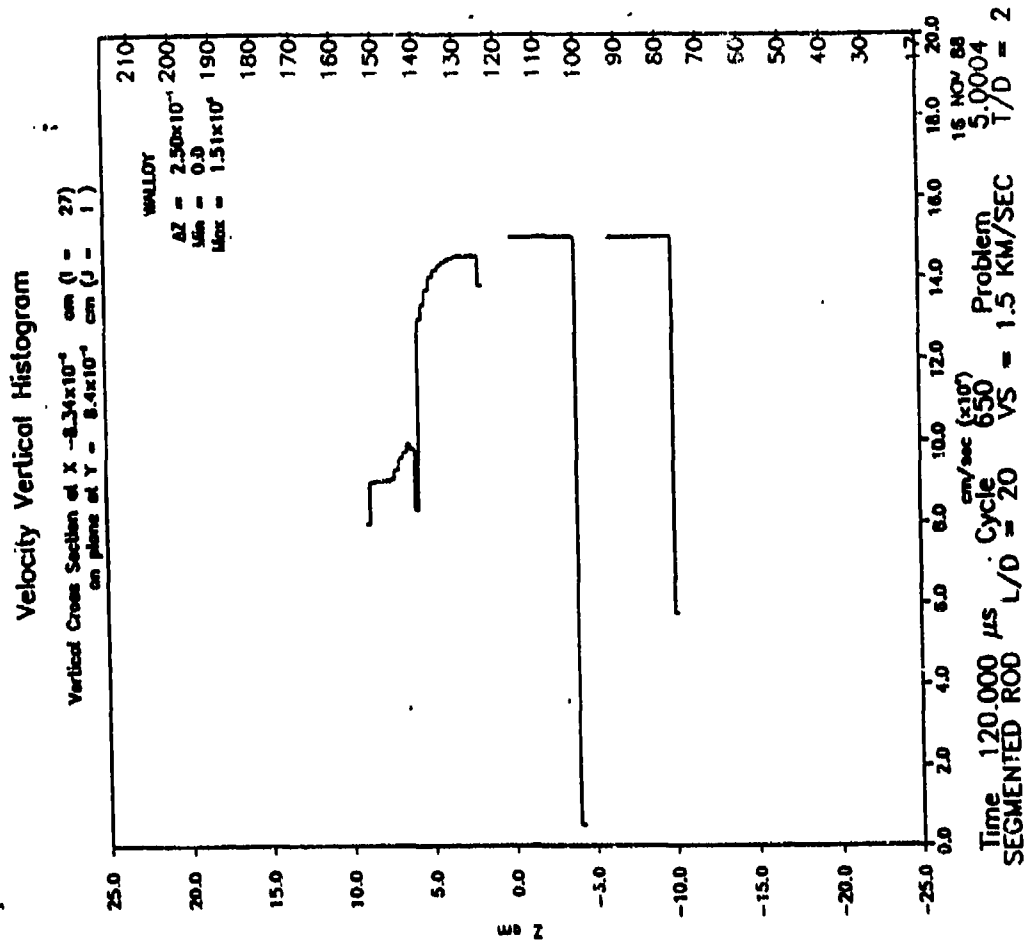
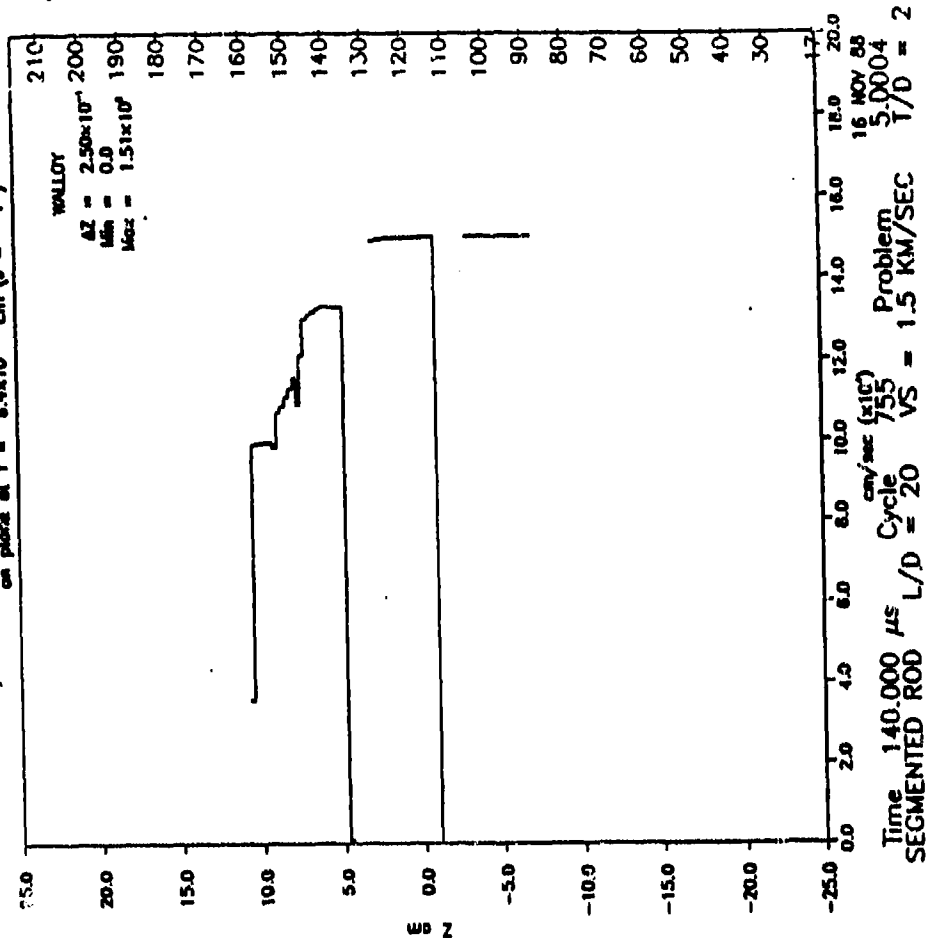


Figure 2. Segmented penetrator, N=5, V=1.5 km/s into 60° RHA (T/D=2) at 120 micro-seconds

Velocity Vertical Histogram

Vertical Cross Section of X = 8.34×10^{-4} cm (J = 27)
on plane of Y = 8.4×10^{-4} cm (J = 1)



Density

on plane of Y = 8.4×10^{-4} cm (J = 1)

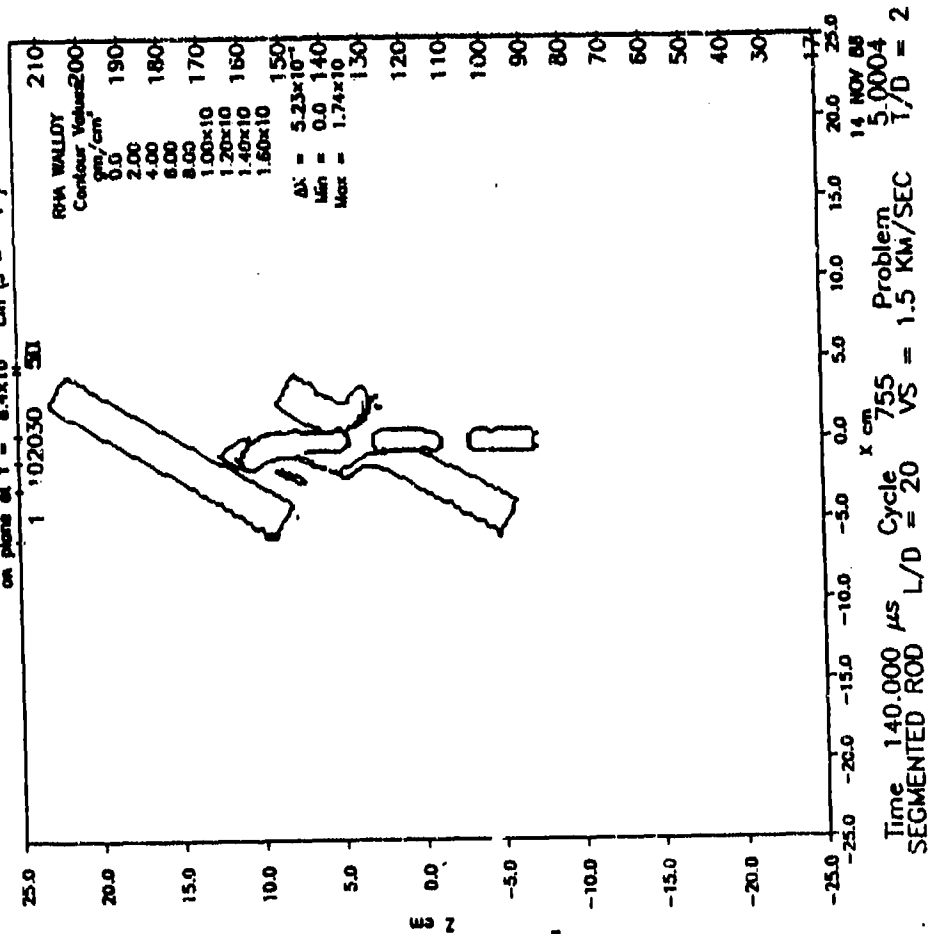


Figure 3. Segmented penetrator, N=5, V=1.5 km/s into 60° RHA (T/D=2) at 140 micro-seconds

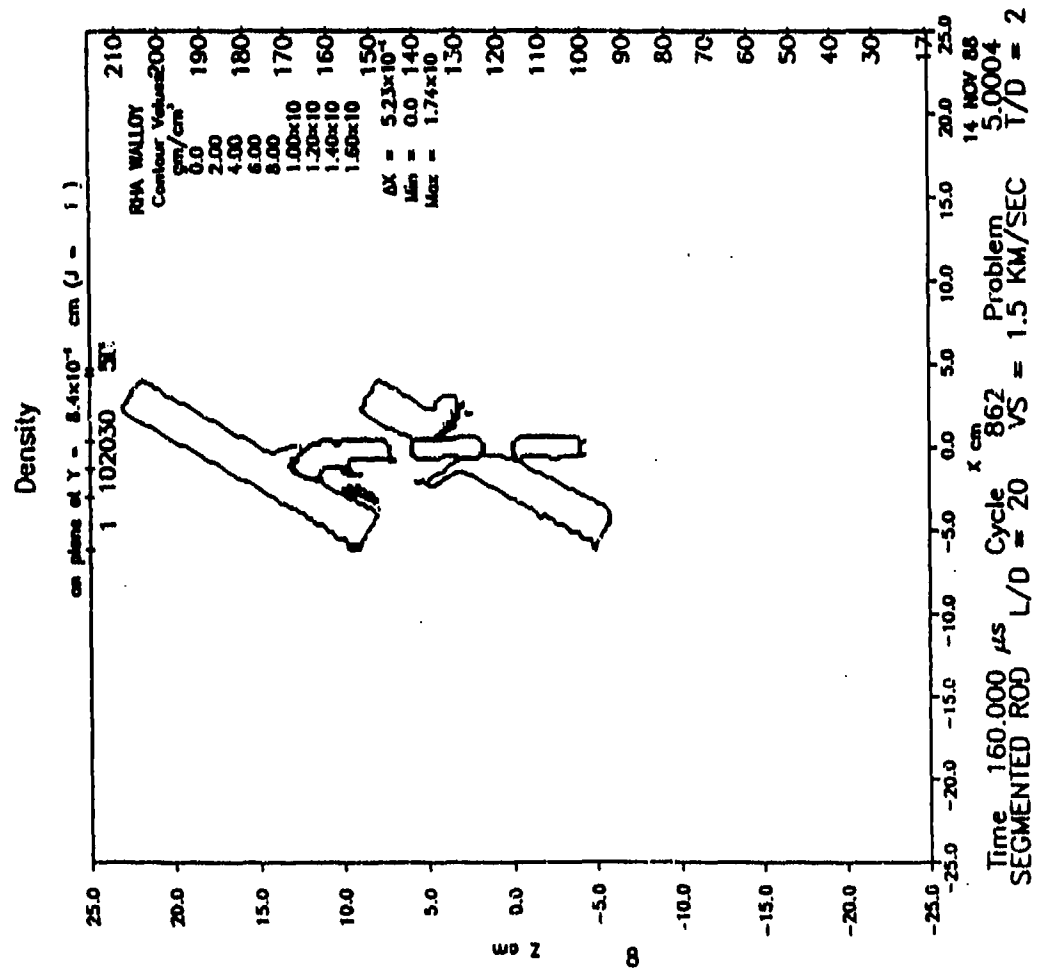
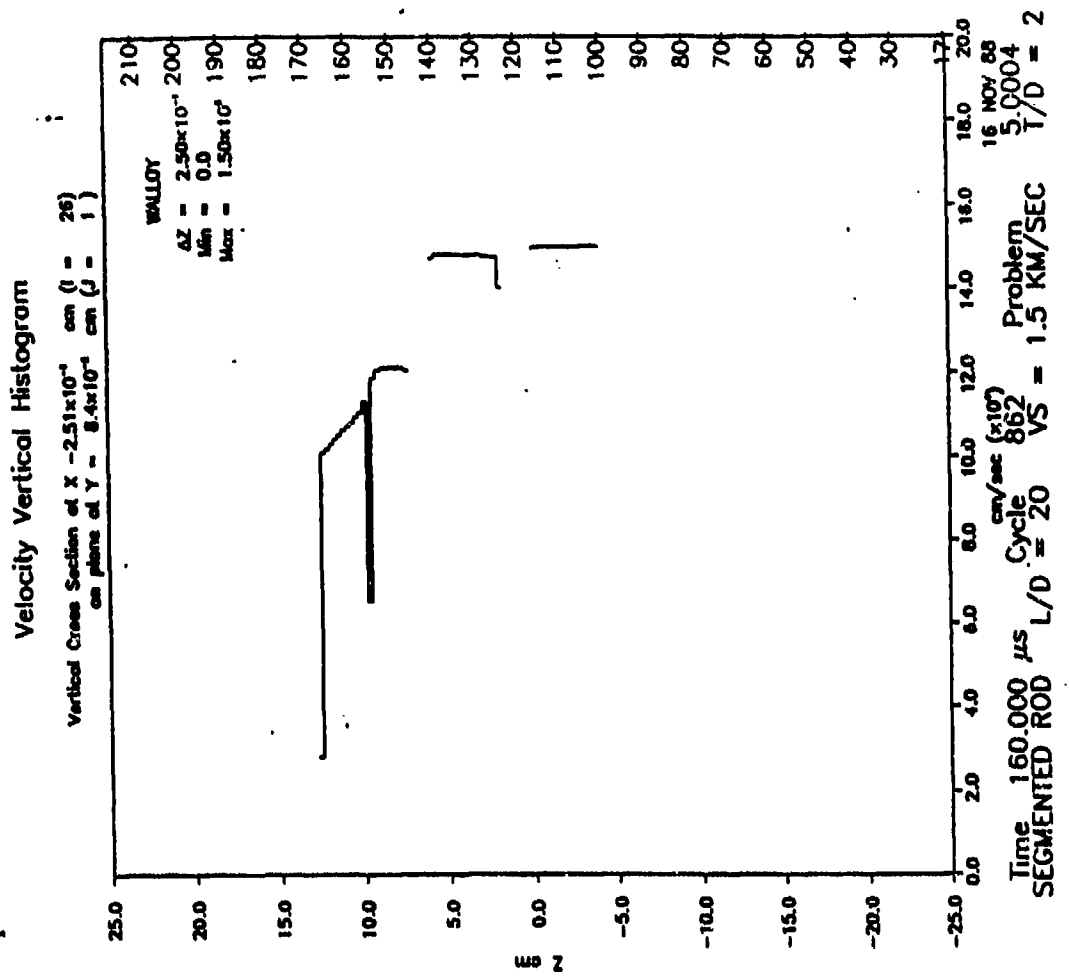


Figure 4. Segmented penetrator, N=5, V=1.5 km/s into 60° RHA (T/D=2) at 160 micro-seconds

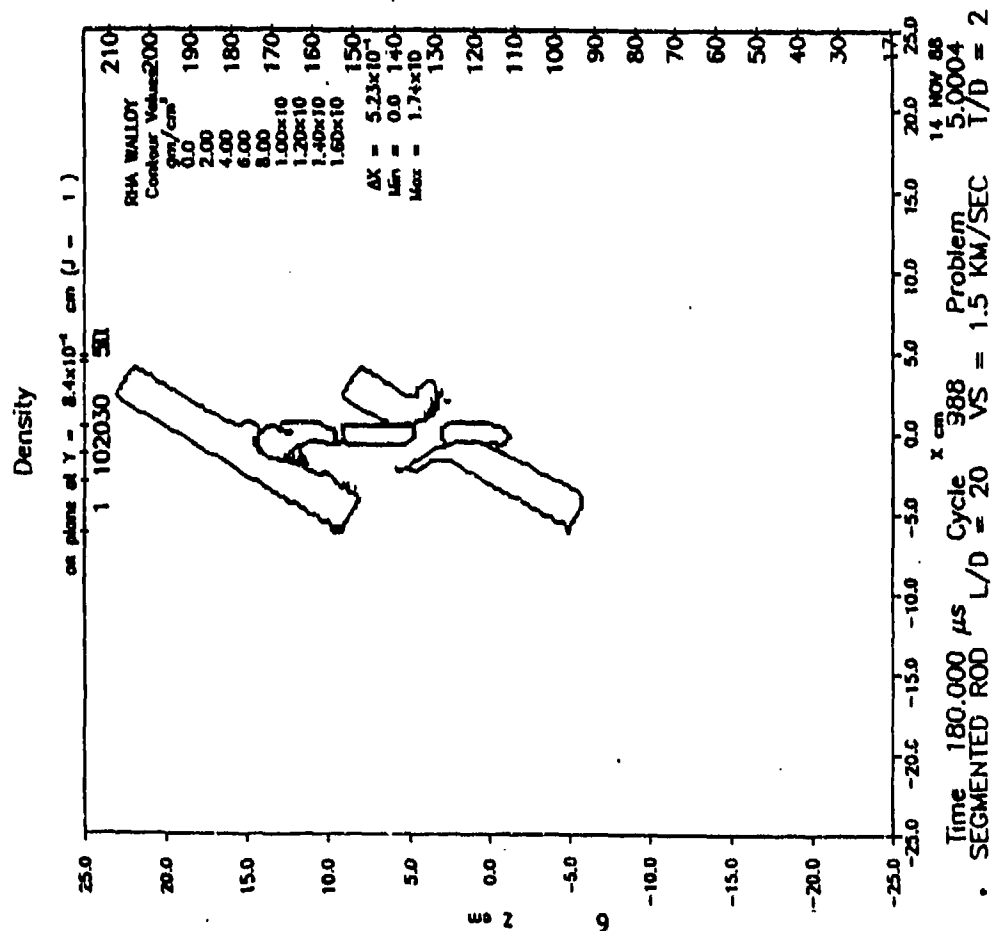
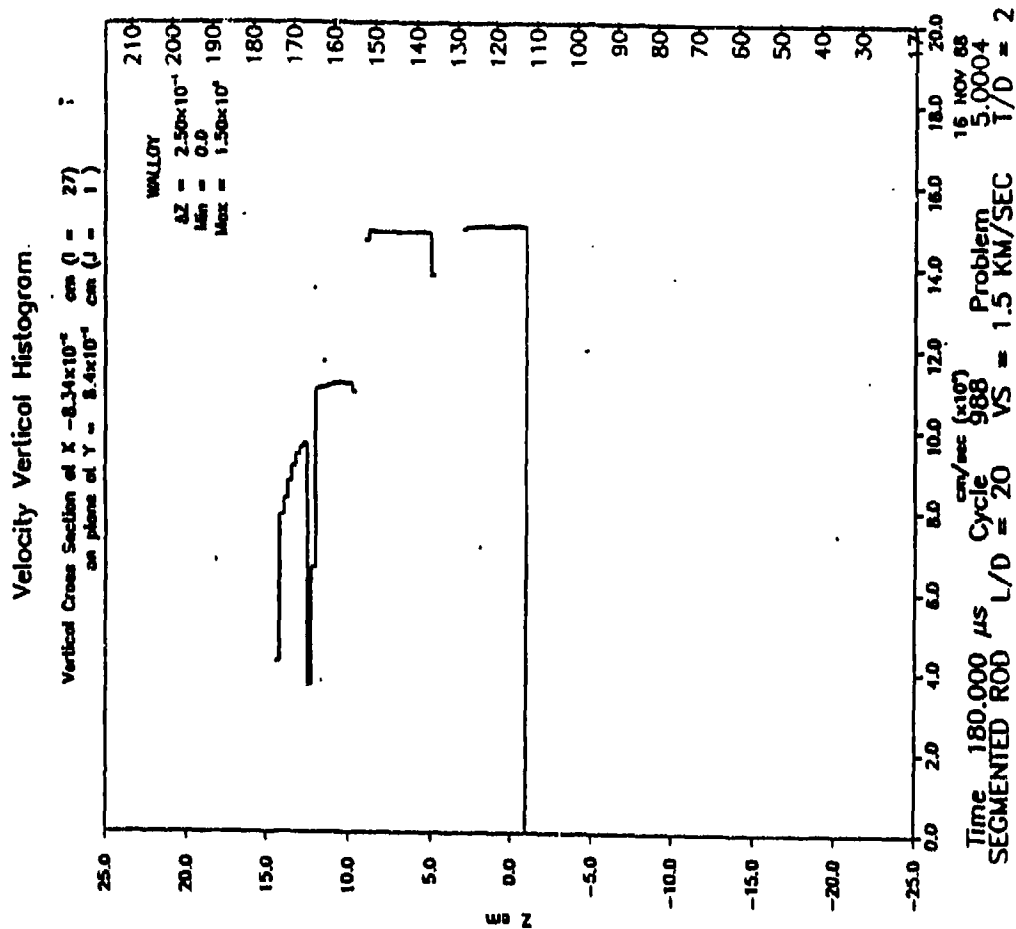
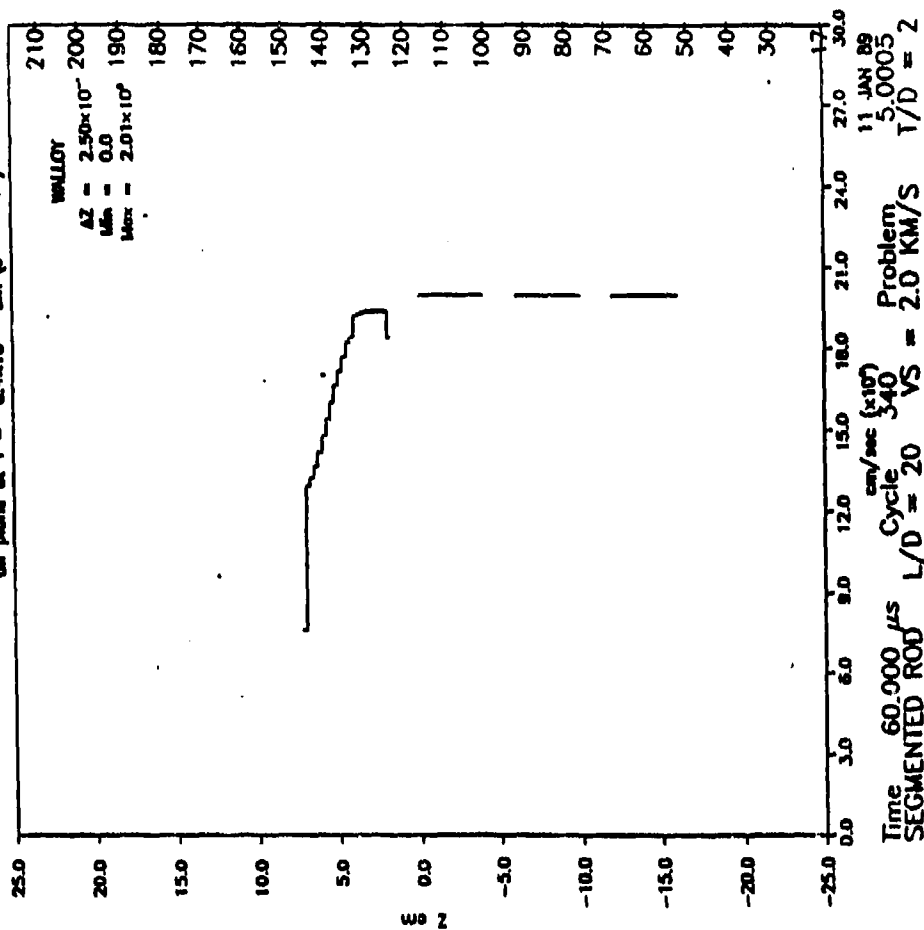


Figure 5. Segmented penetrator, $N=5$, $V=1.5$ km/s into 60° RHA ($T/D=2$) at 180 micro-seconds

Density

Vertical Cross Section of X - 8.34×10^{-4} cm ($\beta = 27$)
on plane of Y - 8.4×10^{-4} cm ($\beta = 1$)



Density

Vertical Cross Section of X - 8.34×10^{-4} cm ($\beta = 27$)
on plane of Y - 8.4×10^{-4} cm ($\beta = 1$)

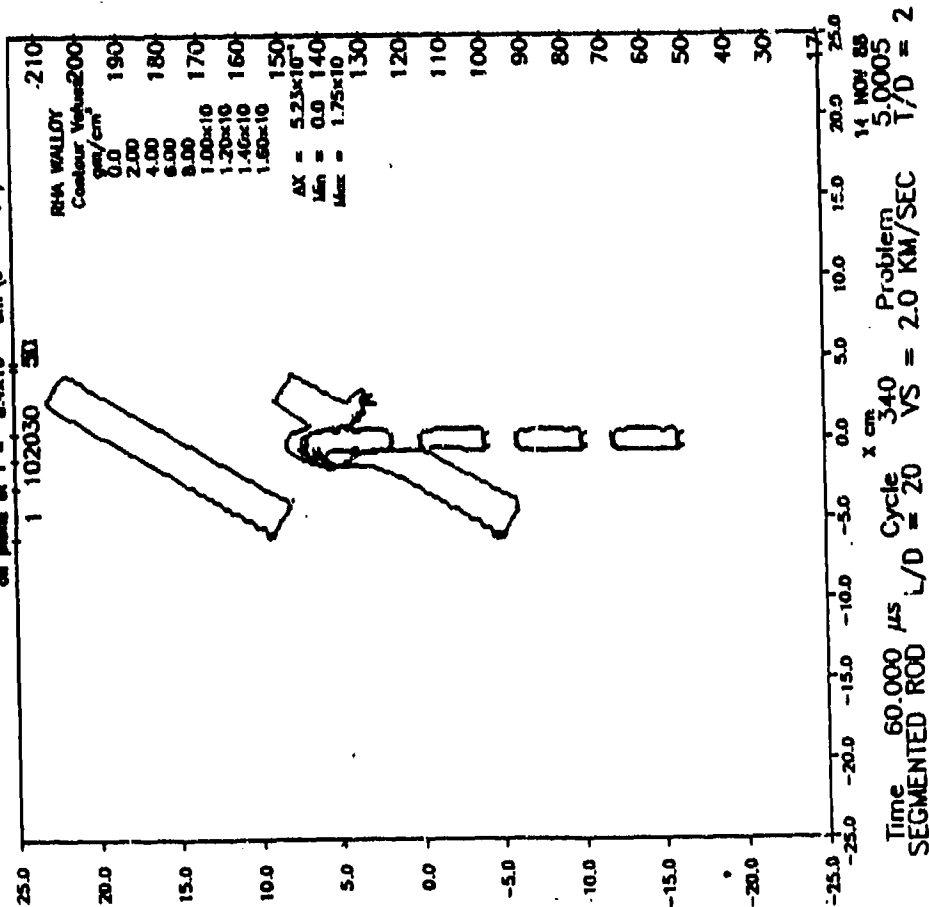


Figure 6. Segmented penetrator, $N=5$, $V=2.0$ km/s into 60° RHA ($T/D=2$) at 60 micro-seconds

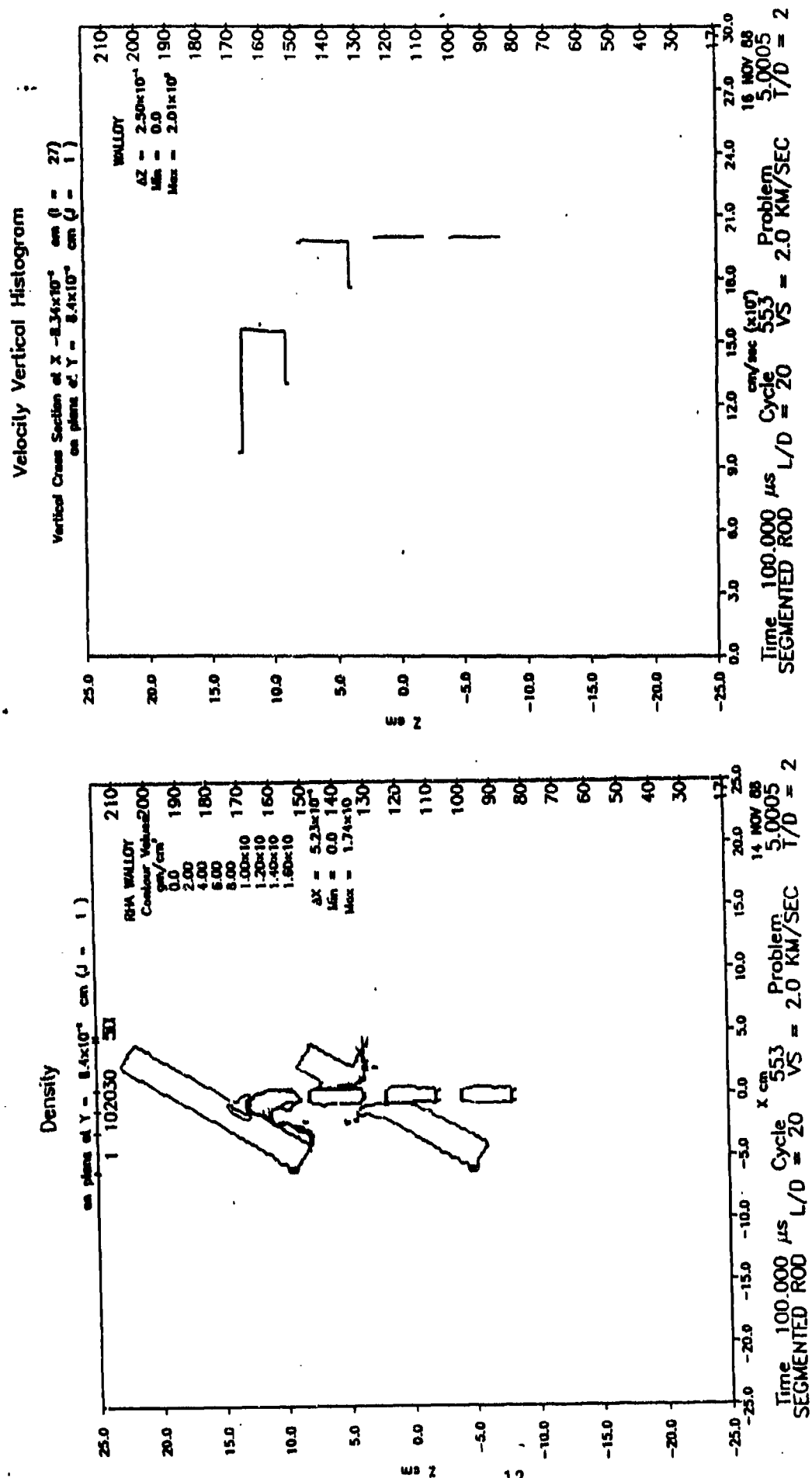
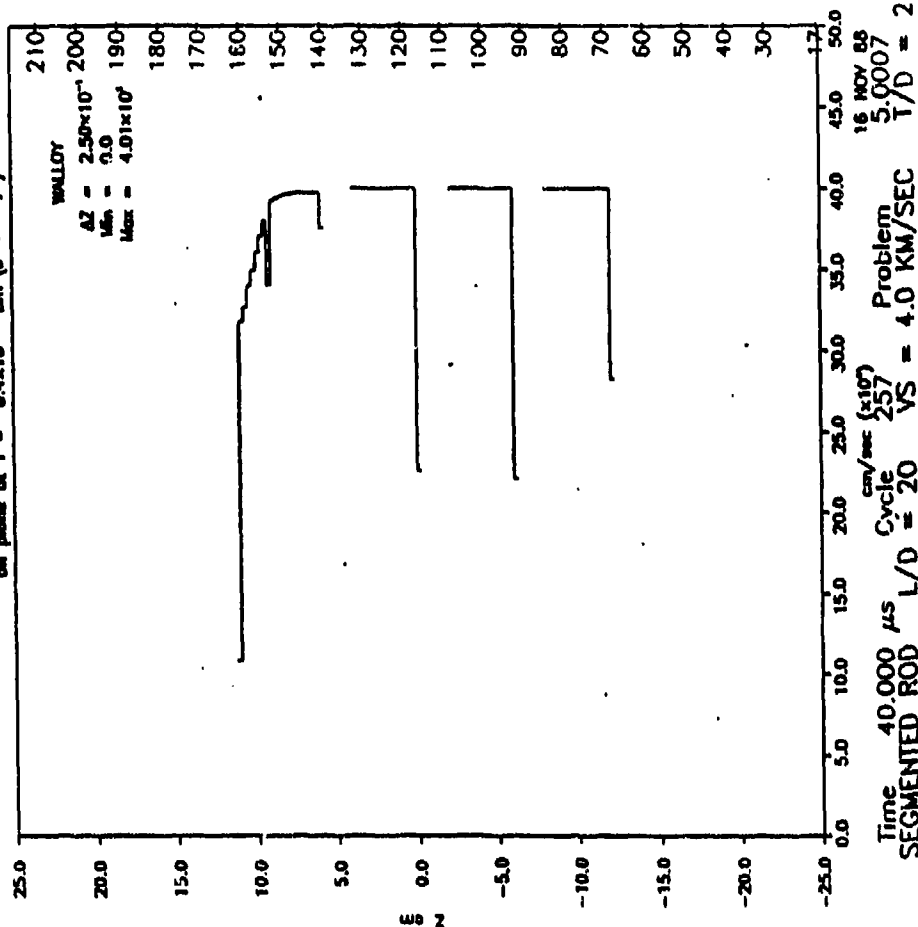


Figure 8. Segmented penetrator, N=5, V=2.0 km/s into 60° RHA (T/D=2) at 100 micro-seconds

Velocity Vertical Histogram

Vertical Cross Section at $X = 8.34 \times 10^{-4}$ cm ($I = 27$)
on plane of $Y = 8.4 \times 10^{-4}$ cm ($J = 1$)



Density

on plane of $Y = 8.4 \times 10^{-4}$ cm ($J = 1$)

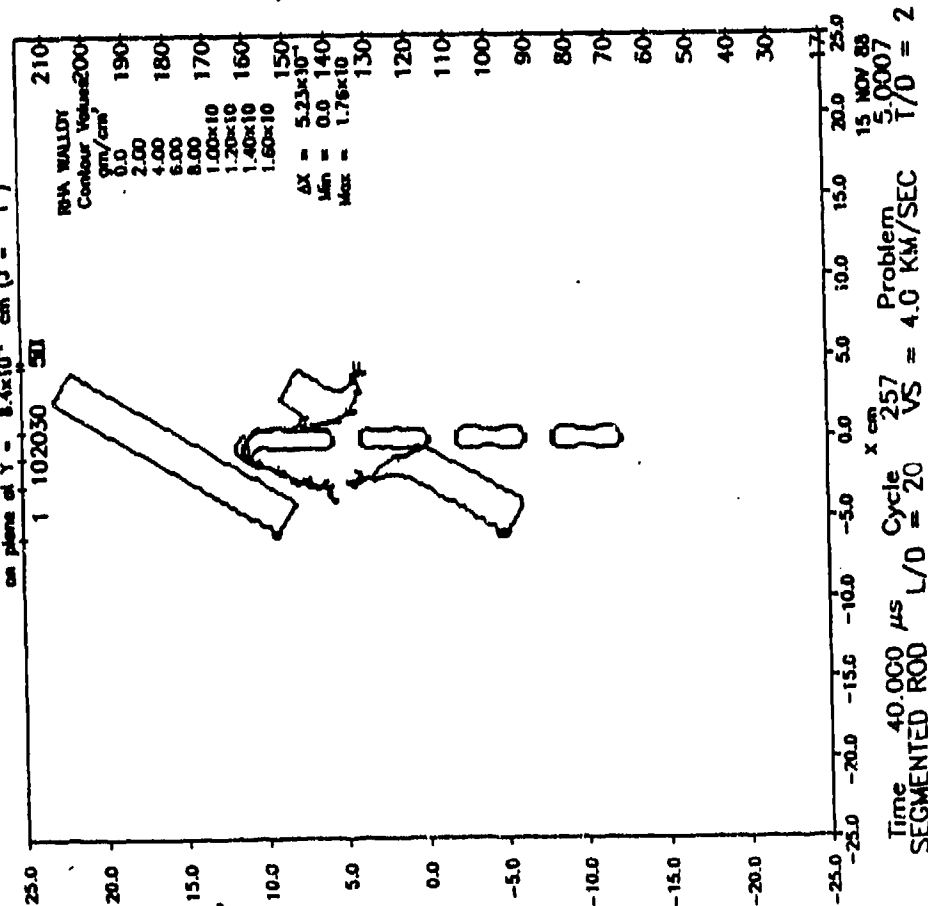
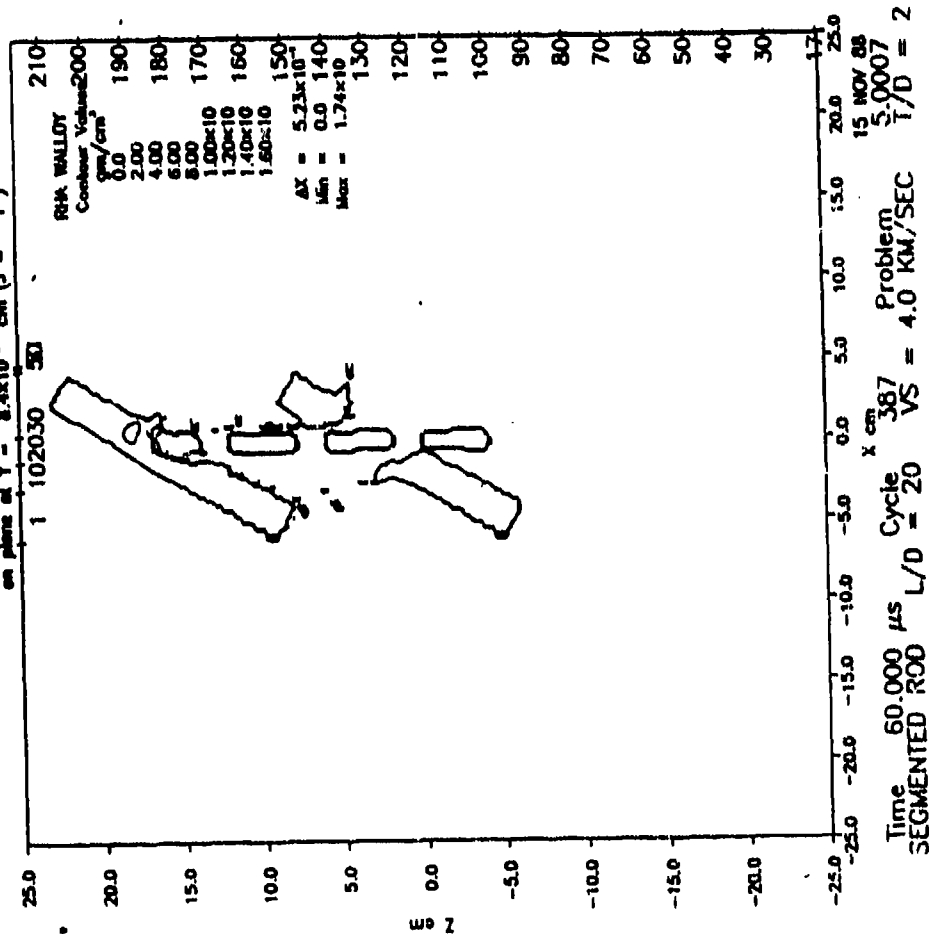


Figure 9. Segmented penetrator, $N=5$, $V=4.0$ km/s into 00° RHA ($T/D=2$) at 40 micro-seconds

Density

on plane of Y = 8.4×10^{-4} cm (J = 1)



Velocity Vertical Histogram

Vertical Cross Section of X = -8.34×10^{-4} cm (J = 27)
 on plane of Y = 8.4×10^{-4} cm (J = 1)

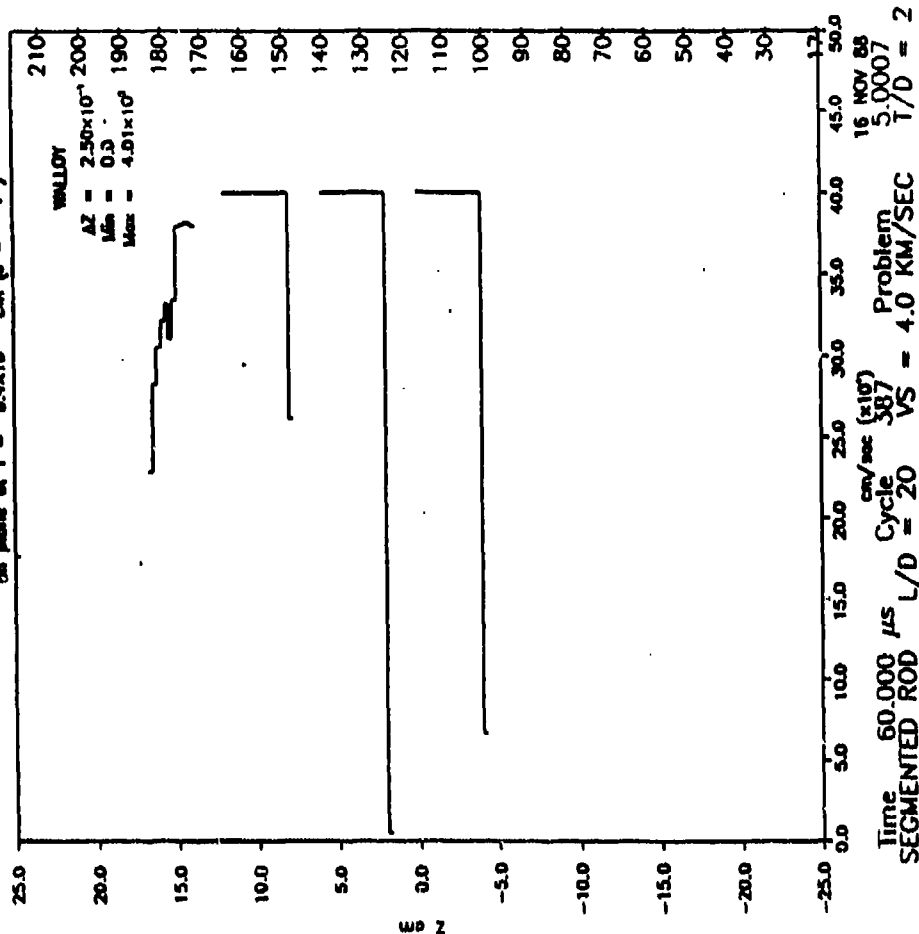


Figure 10. Segmented penetrator, N=5, V=4.0 km/s into 60° RHA (T/D=2) at 60 micro-seconds

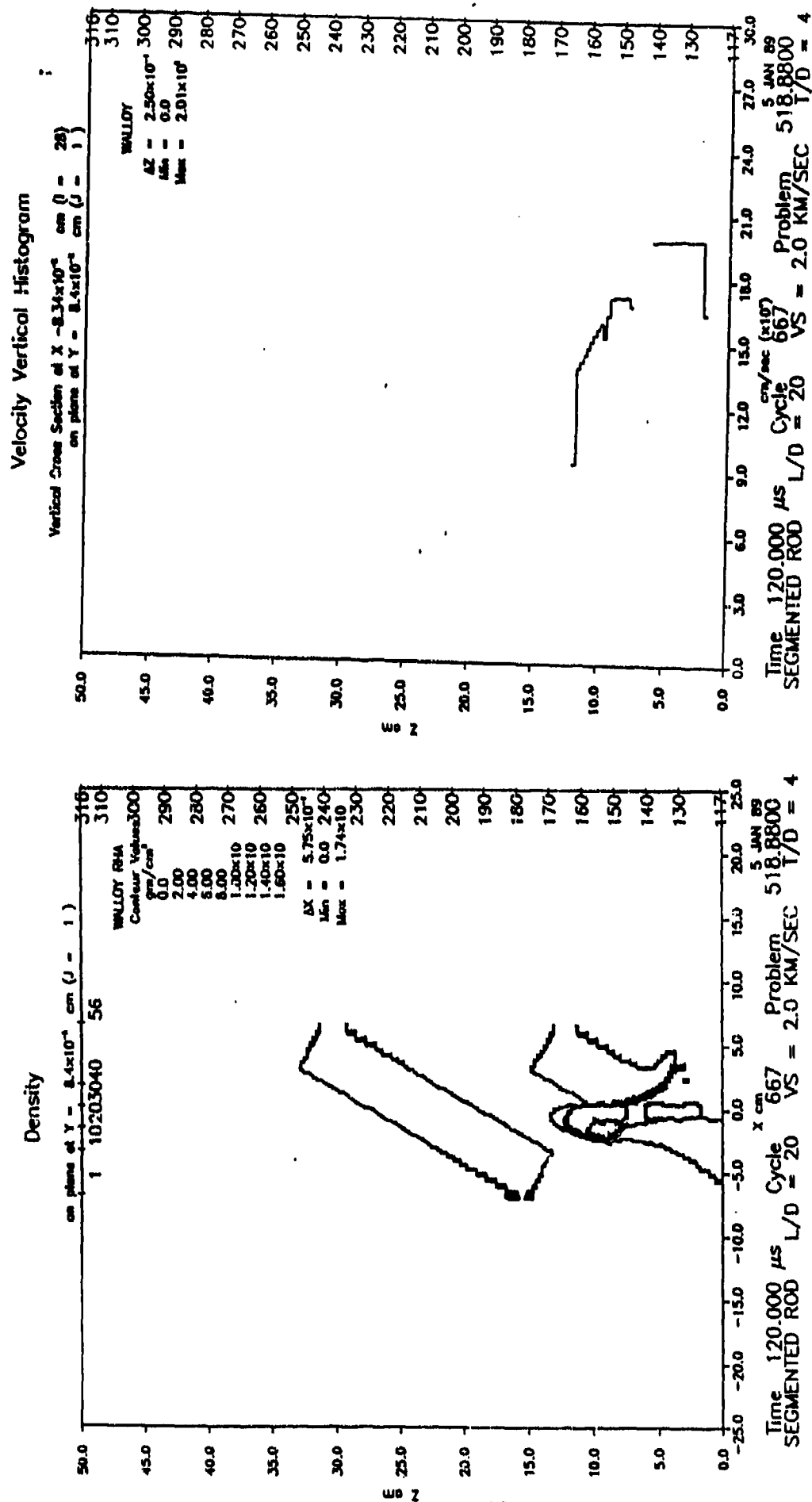


Figure 11. Segmented penetrator, N=5, V=2.0 km/s into 60° RHA (T/D=4) at 120 micro-seconds

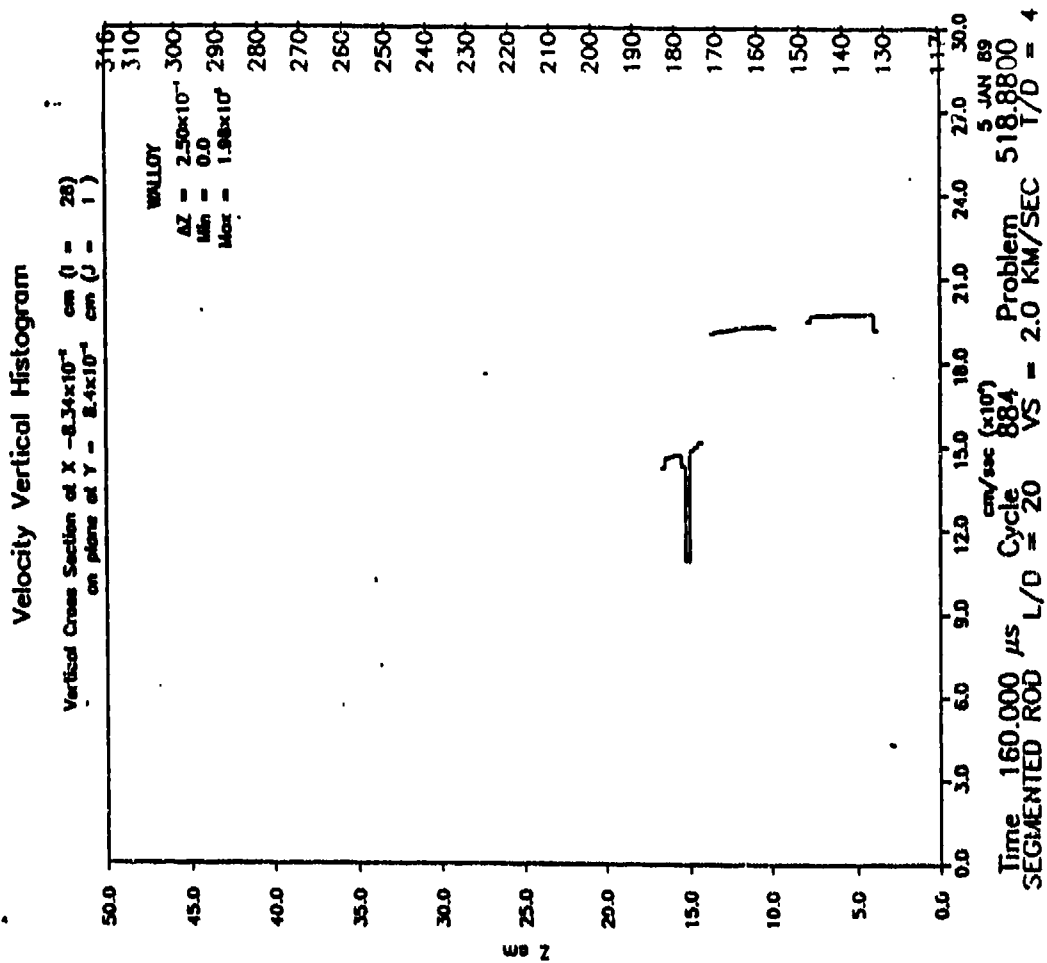
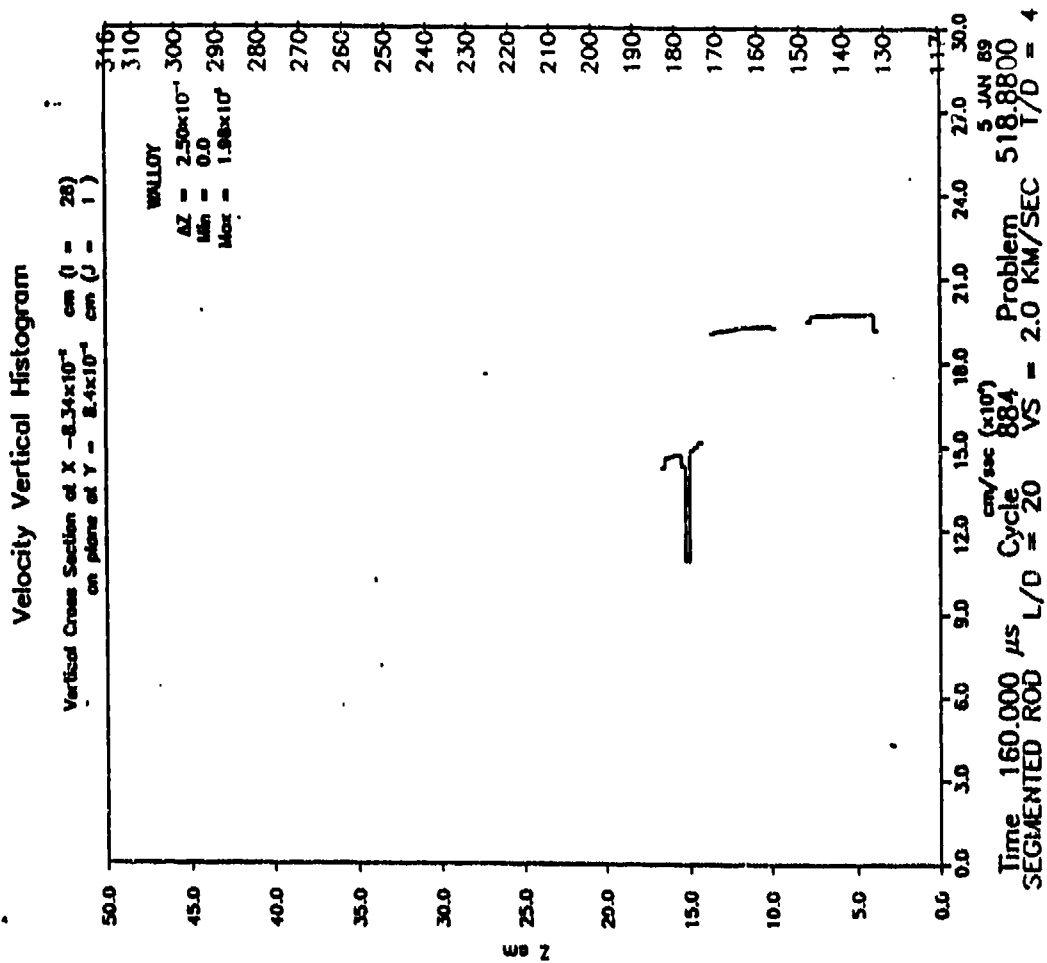
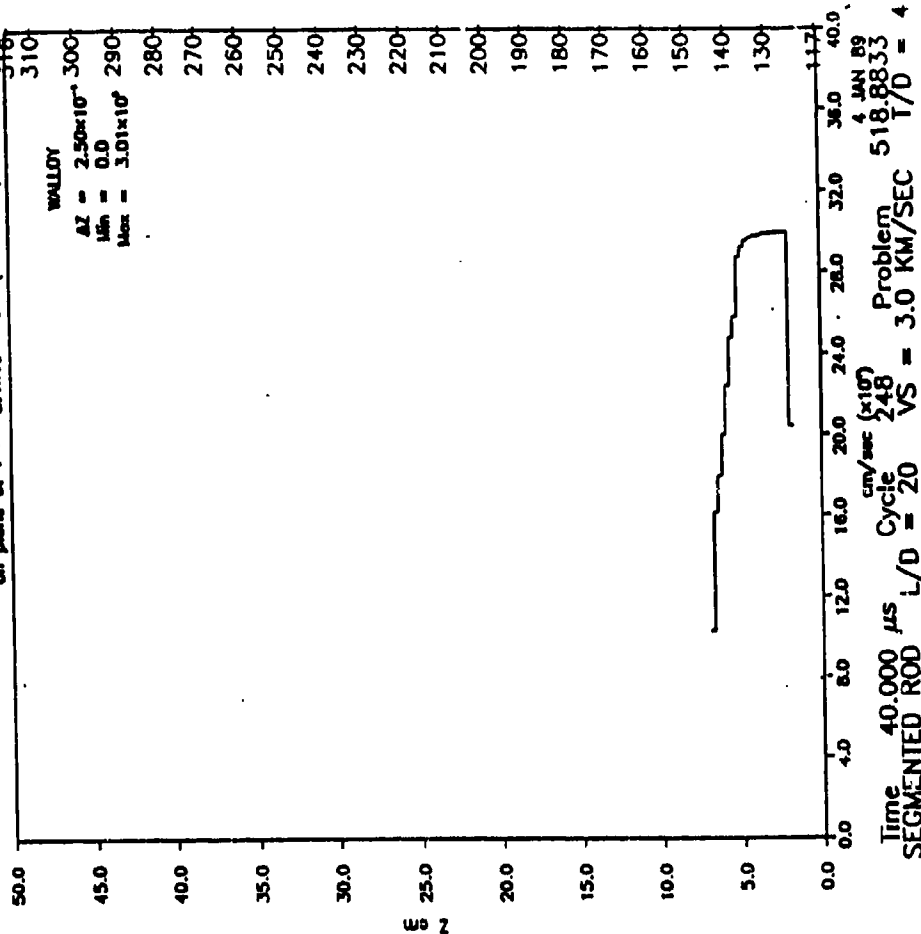


Figure 12. Segmented penetrator, $N=5$, $V=2.0$ km/s into 60° RHA ($T/D=4$) at 160 micro-seconds

Density

Vertical Cross Section at X = -8.34×10^{-4} cm (J = 28)
on plane at Y = -8.4×10^{-4} cm (J = 1)



Velocity Vertical Histogram

Vertical Cross Section at X = -8.34×10^{-4} cm (J = 28)
on plane at Y = -8.4×10^{-4} cm (J = 1)

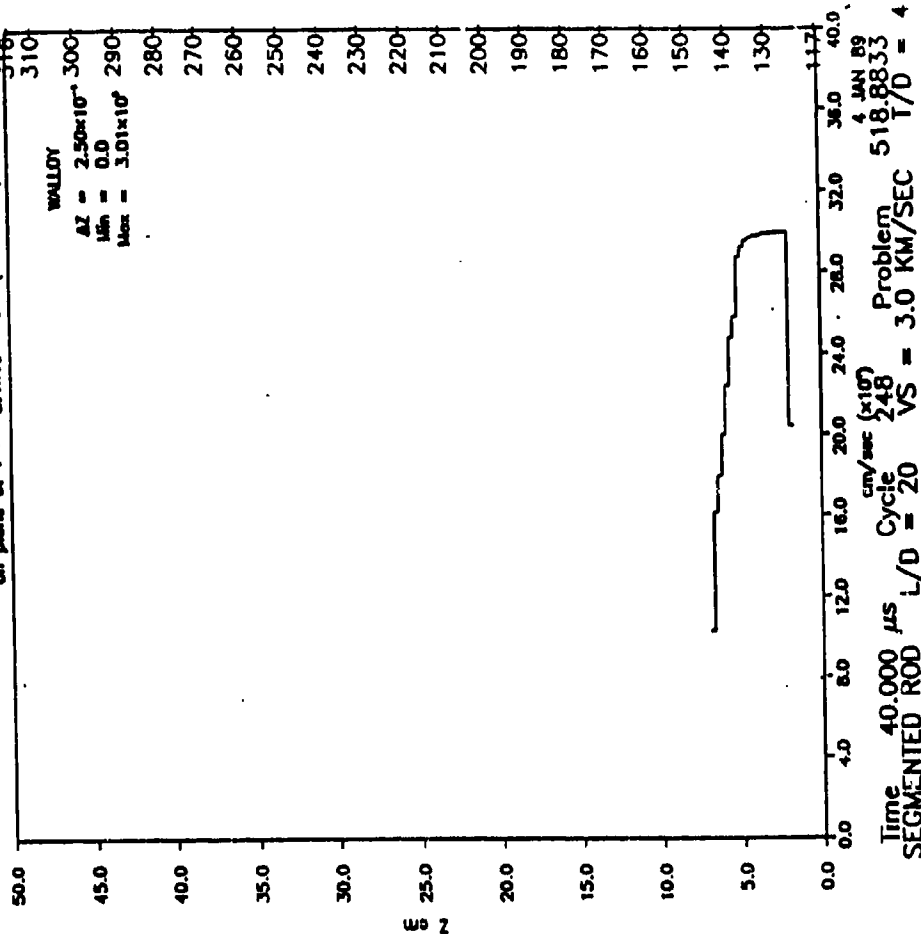


Figure 13. Segmented penetrator, N=5, V=3.0 km/s into 60° RHA (T/D=4) at 40 micro-seconds

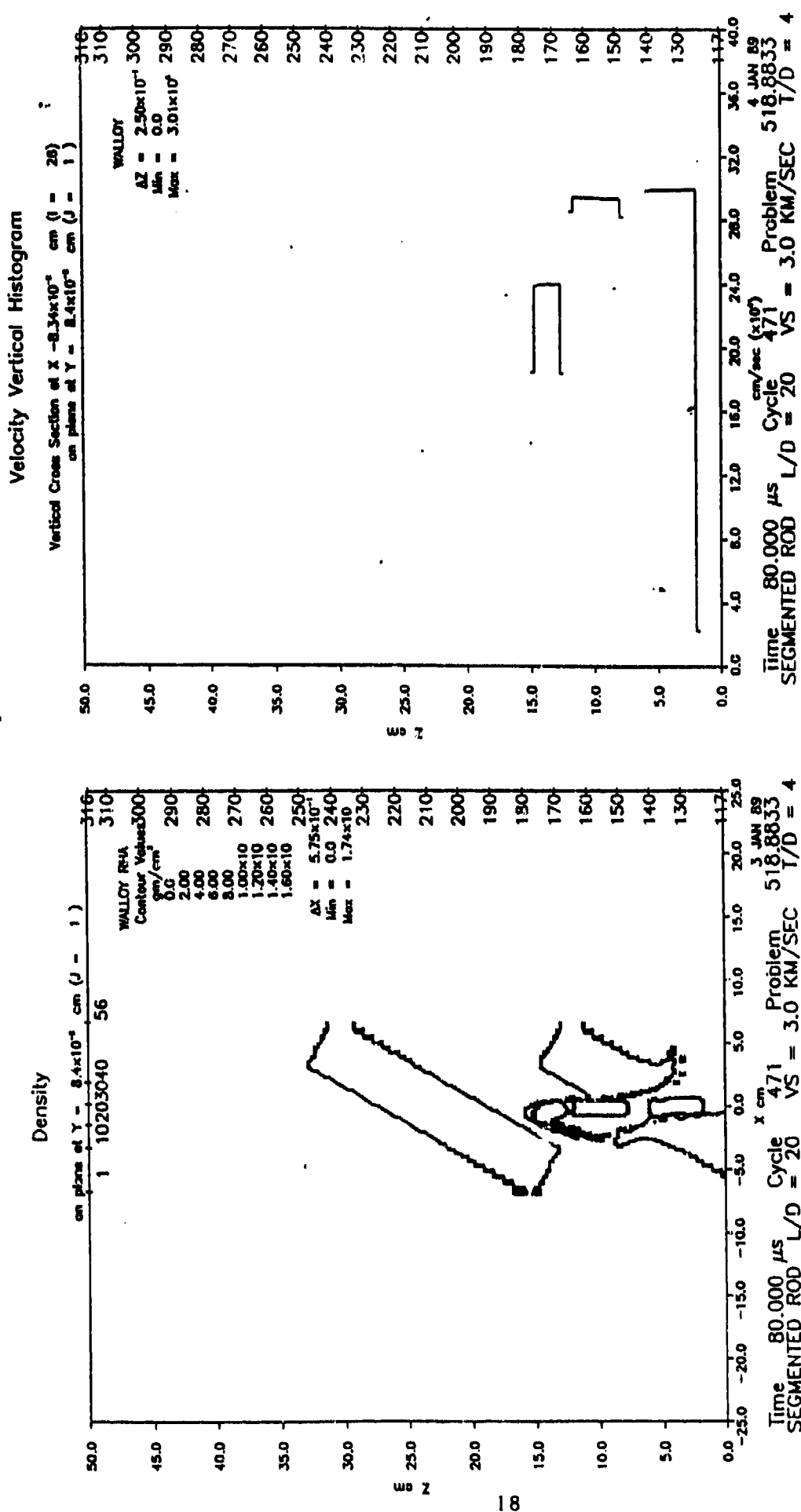


Figure 14. Segmented penetrator, $N=5$, $V=3.0$ km/s into 60° RHA ($T/D=4$) at 80 micro-seconds

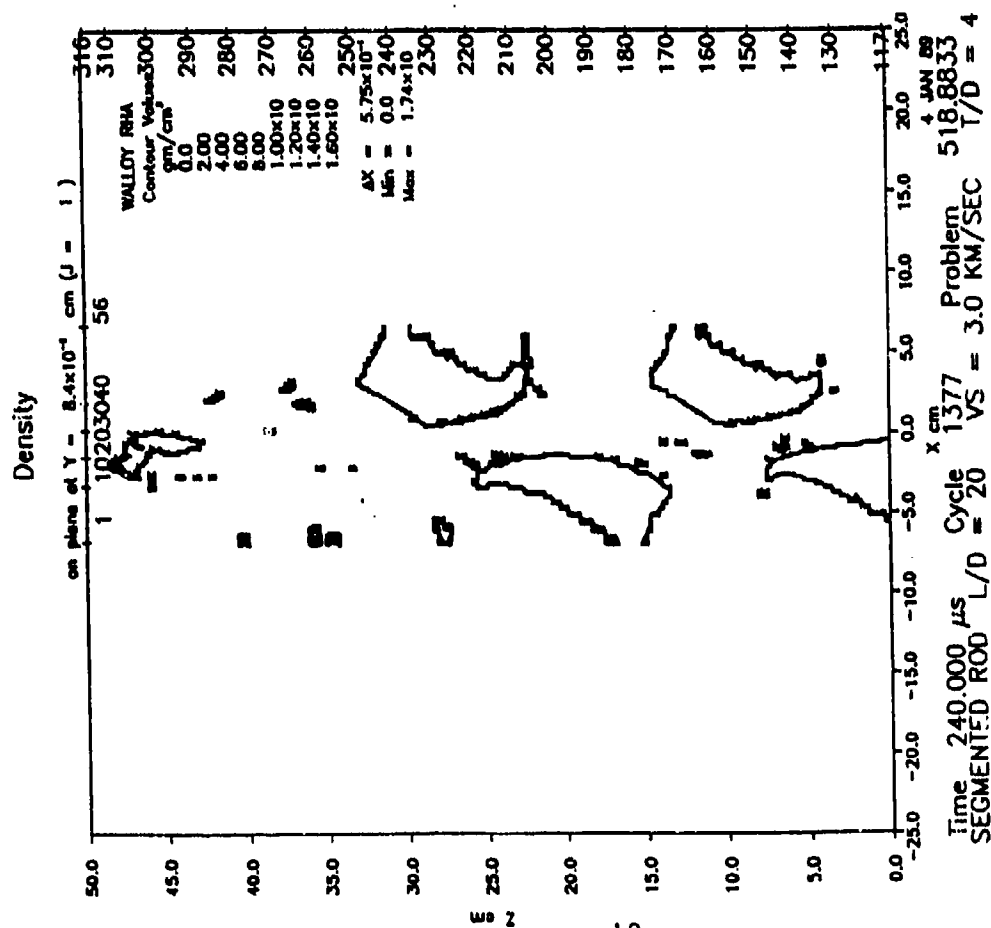
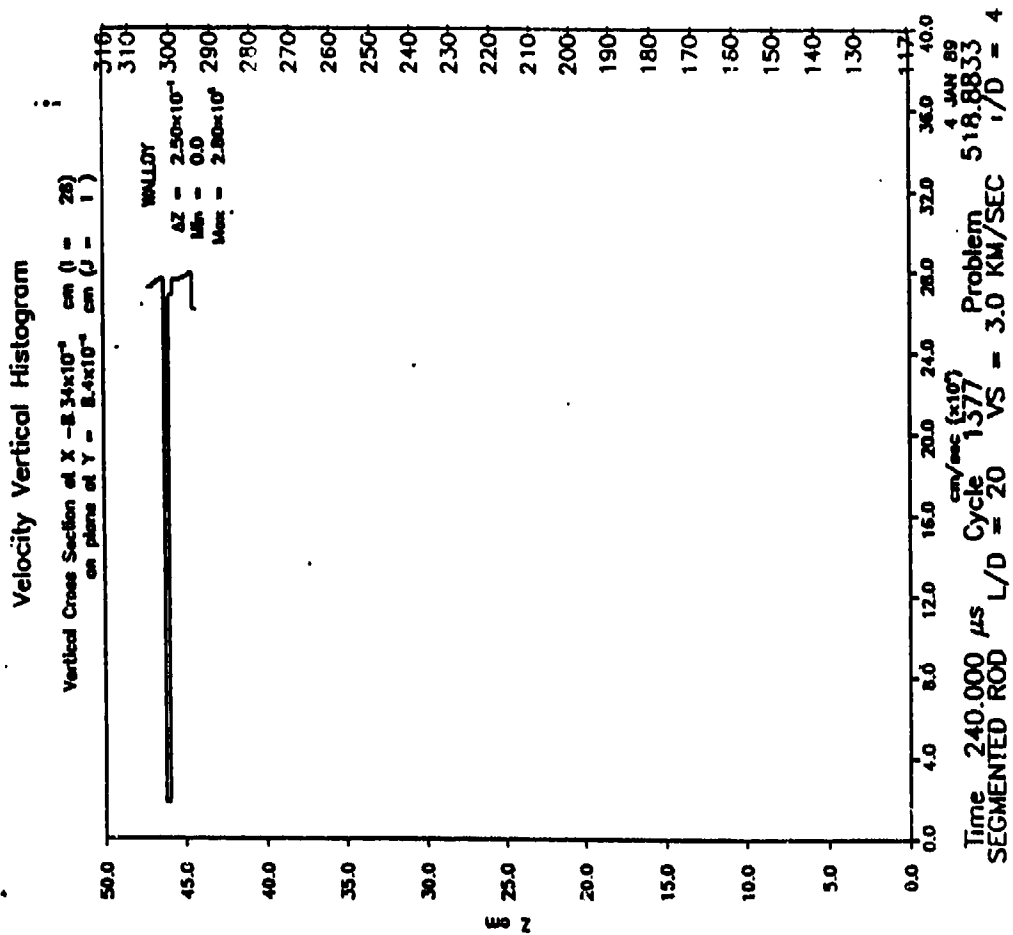


Figure 15. Segmented penetrator, $N=5$, $V=3.0$ km/s into 60° RHA ($T/D=4$) at 240 micro-seconds

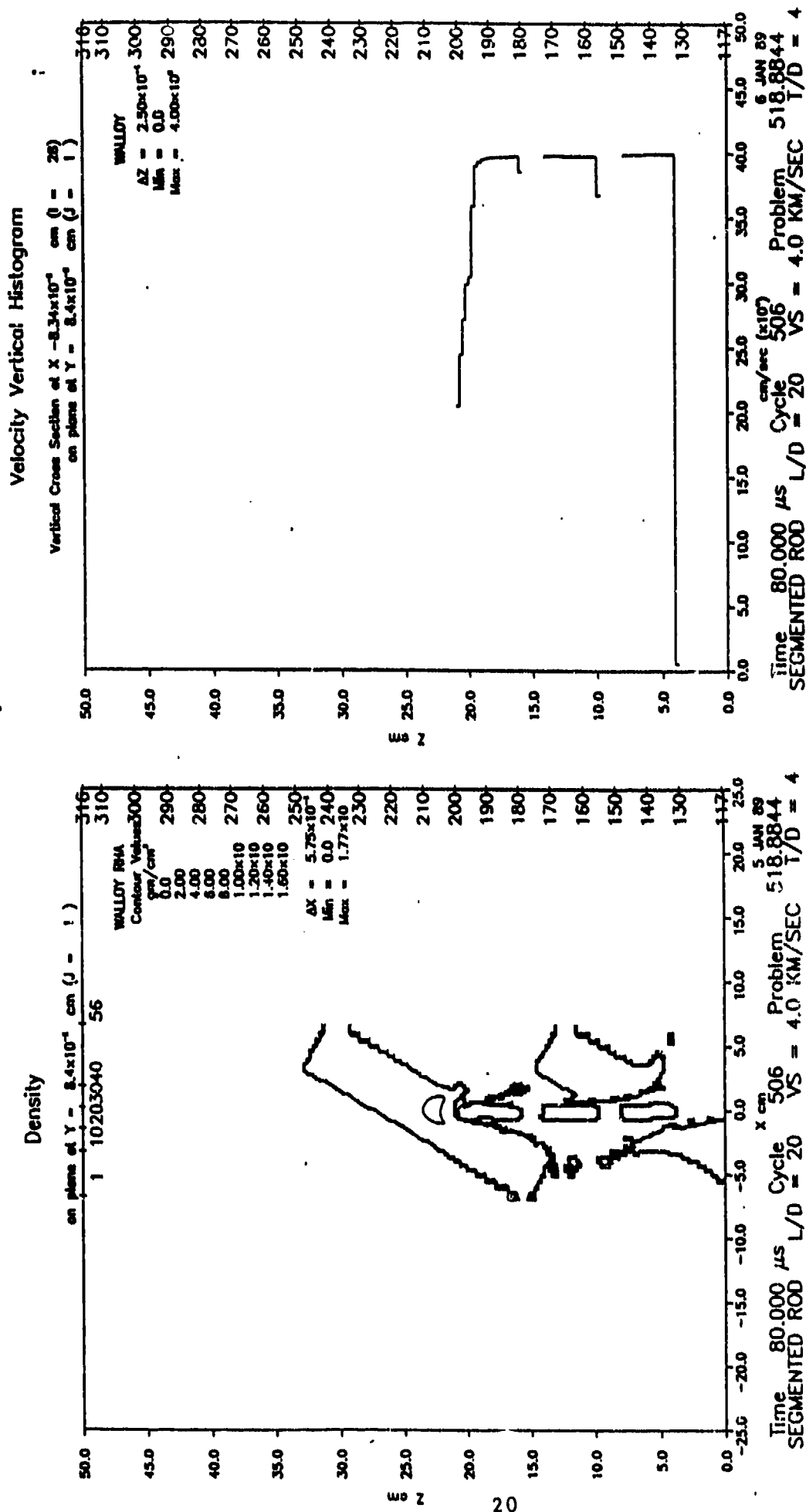


Figure 16. Segmented penetrator, N=5, V=4.0 km/s into 60° RIIA (T/D=4) at 120 micro-seconds

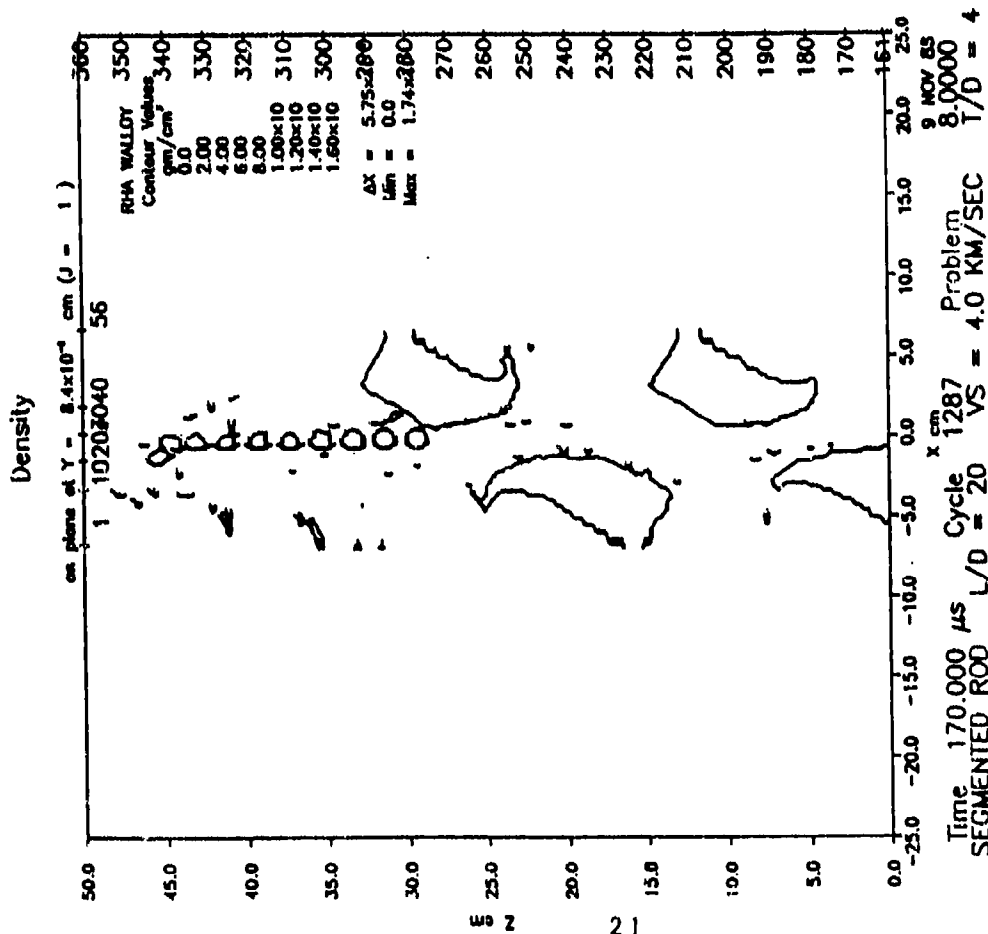
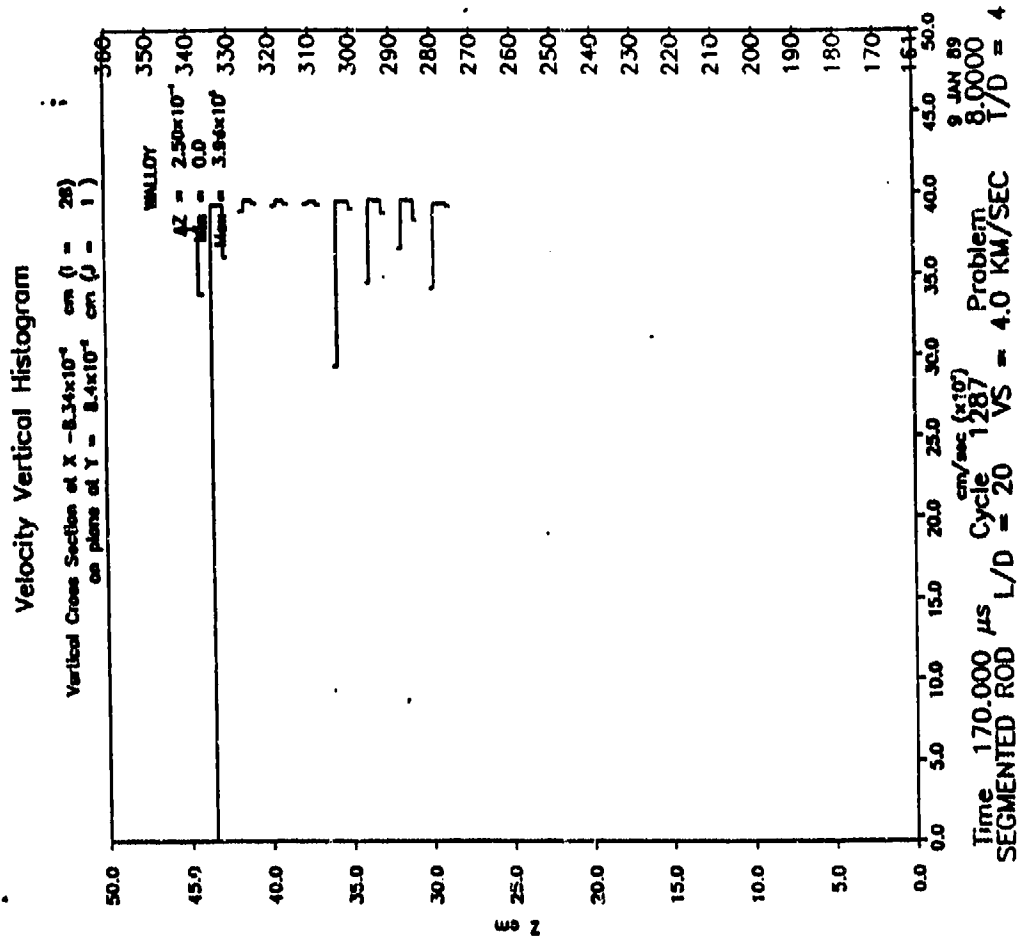


Figure 17. Segmented penetrator, $N=20$, $V=4.0$ km/s into 60° RHA ($T/D=4$) at 170 micro-seconds

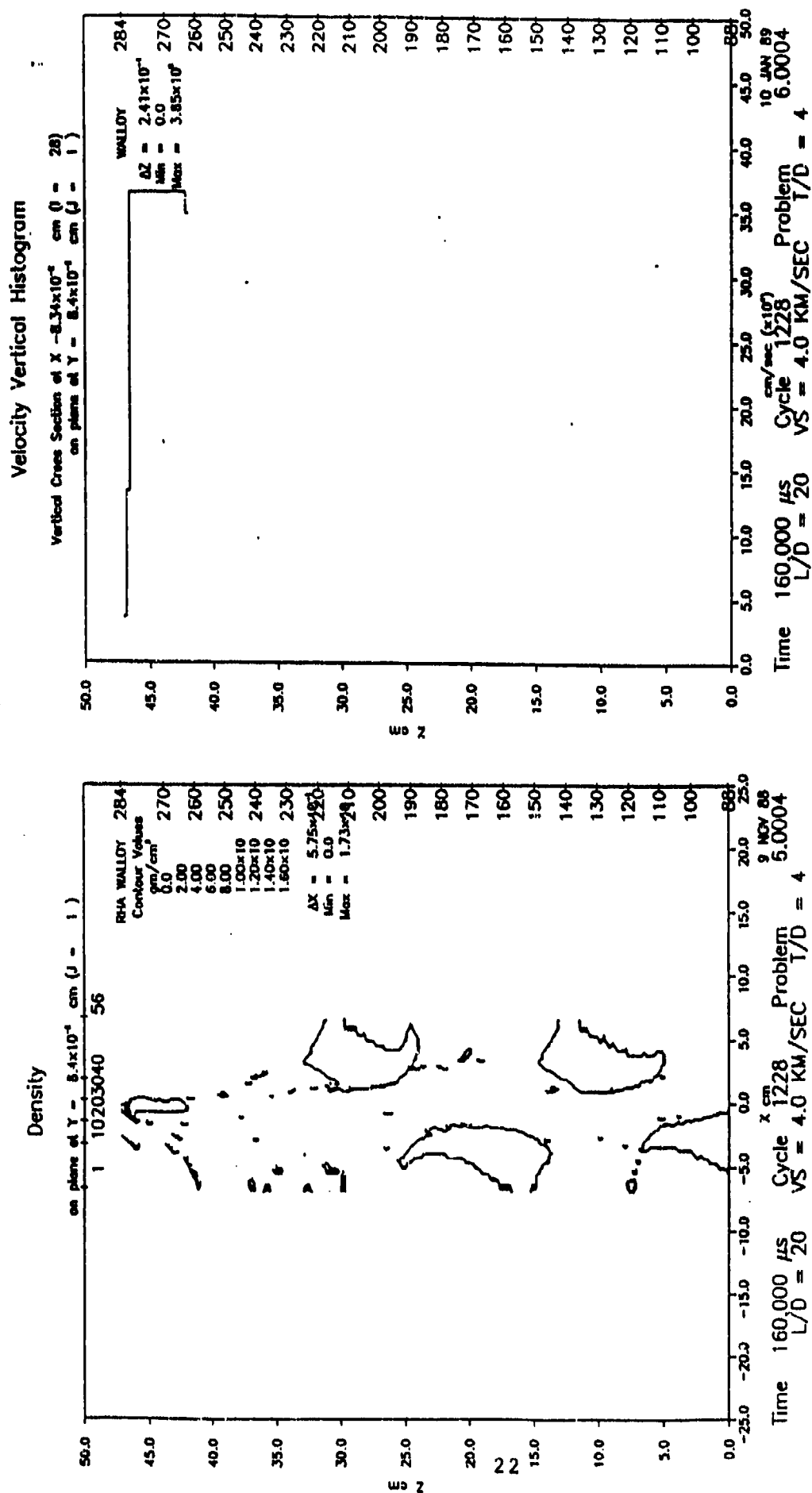


Figure 18. Monolithic penetrator, $N=1$, $V=4.0$ km/s into 60° RHA ($T/D=4$) at
160 micro-seconds

reduced while perforating the spaced plate array, while trailing segments unaffected by interactions retain their initial striking velocity. Table 4 shows a 108 percent improvement in residual mass over the equivalent monolithic rod. The improvement in residual mass of the 5 segment penetrator with an S/D of 8 over the equivalent monolithic rod is 103 percent.

4. CONCLUSIONS

A number of 3-D simulations have been conducted to determine the performance of segmented rods impacting spaced plate arrays. The performance of segmented rods is characterized based on residual mass and kinetic energy. In general, segmented rods outperform their monolithic counterparts for the spaced plate arrays studied at velocities above 2 km/s. The increase in performance is enhanced for thick target plates. Furthermore, the simulations show that increasing the spacing between segments increases performance. It is desirable, though not always practical, for spacing to be such that every segment acts as an independent penetrator. Finally, it should be noted that increasing the number of segments increases the residual mass and kinetic energy. The increase in performance derived from a greater number of segments is greater than the increase derived from increased segment spacing.

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APPENDIX A - KEEL Input Data

KEEL Input For Monolithic Penetrators Into T/D=2 Spaced Plates

KEEL PROBLEM 5.0000

NM=3 AIR=1 WALLOY=2 RHA=3

DIMEN=3 VISC=1 FLUXER=3 STRESS=1

IMAX=51 JMAX=31 KMAX=241 IQ=50 JQ=30 KQ=240

FAIL=1 STRAIN=1 REZONE=0

NSTN=2 NOP=2000

AREF=.TRUE. BREF=.FALSE. FREF=.FALSE.

LREF=.FALSE. RREF=.FALSE. TREF=.FALSE.

HEADER

L/D = 20 VS = 1.5 KM/SEC T/D = 2

MESH

CONSTANT SUBGRID NX=30 X0=-2.5 XMAX=2.5 RXNEG=1.1 RXPOS=1.1

XOLIM=-6.42045 XMLIM=4.98957

NY=15 Y0=0.0 YMAX=2.5 RYPOS=1.1

YOLIM=0. YMLIM=9.09078

NZ=241 Z0=-21.0 ZMAX=39.25 RZNEG=1.0

RZPOS=1.0

ZOLIM=-21.0 ZMLIM=39.25

GENERATE

PACKAGE WALLOY W=1.5E5

CYLINDER XC=0.0 YC=0.0 ZB=-20. ZT=0.0 RADIUS=.5

PACKAGE AIR W=1.5E5

CYLINDER XC=0.0 YC=0.0 ZB=-1.0E20 ZT=-20. RADIUS=.5

PACKAGE RHA

BOX X1=-8.0 X2=8.0 Y1=0.0 Y2=8.0 Z1=0.0 Z2=2.0

XCC=0.0 YCC=0.0 ZCC=0.86603

ANGLB=60

PACKAGE RHA

BOX X1=-8.0 X2=8.0 Y1=0.0 Y2=8.0 Z1=0.0 Z2=2.0

XCC=0.0 YCC=0.0 ZCC=15.02603

ANGLB=60

PACKAGE AIR W=1.0E4 BOX FILL

STATION XS=0. YS=0. ZL=0.

XS=0. YS=0. ZL=-20.

END

KEEL Input For Segmented Penetrators Into T/D = 2 Spaced Plates

KEEL PROBLEM 5.0004
 NM=3 AIR=1 WALLOY=2 RHA=3
 DIMEN=3 VISC=1 FLUXER=3 STRESS=1
 IMAX=51 JMAX=31 KMAX=273 IQ=50 JQ=30 KQ=272
 FAIL=1 STRAIN=1 REZONE=0
 NSTN=2 NOP=2000
 AREF=.TRUE. BREF=.FALSE. FREF=.FALSE.
 LREF=.FALSE. RREF=.FALSE. TREF=.FALSE.
 HEADER
 L/D = 20 VS = 1.5 KM/S T/D = 2
 MESH
 CONSTANT SUBGRID NX=30 XO=-2.5 XMAX=2.5 RXNEG=1.1 RXPOS=1.1
 XOLIM=-6.42045 XMLIM=4.98957
 NY=15 YO=0.0 YMAX=2.5 RYPOS=1.1
 YOLIM=0. YMLIM=9.09078
 NZ=273 ZO=-29.0 ZMAX=39.25 RZNEG=1.0
 RZPOS=1.0
 ZOLIM=-29.0 ZMLIM=39.25
 GENERATE
 PACKAGE WALLOY W=1.5E5
 CYLINDER XC=0.0 YC=0.0 ZB=-4. ZT=0.0 RADIUS=.5
 PACKAGE AIR W=1.5E5
 CYLINDER XC=0.0 YC=0.0 ZB=-6. ZT=-4. RADIUS=.5
 PACKAGE WALLOY W=1.5E5
 CYLINDER XC=0.0 YC=0.0 ZB=-10. ZT=-8. RADIUS=.5
 PACKAGE AIR W=1.5E5
 CYLINDER XC=0.0 YC=0.0 ZB=-12. ZT=-10. RADIUS=.5
 PACKAGE WALLOY W=1.5E5
 CYLINDER XC=0.0 YC=0.0 ZB=-16. ZT=-12. RADIUS=.5
 PACKAGE AIR W=1.5E5
 CYLINDER XC=0.0 YC=0.0 ZB=-18. ZT=-16. RADIUS=.5
 PACKAGE WALLOY W=1.5E5
 CYLINDER XC=0.0 YC=0.0 ZB=-22. ZT=-18. RADIUS=.5
 PACKAGE AIR W=1.5E5
 CYLINDER XC=0.0 YC=0.0 ZB=-24. ZT=-22. RADIUS=.5
 PACKAGE WALLOY W=1.5E5
 CYLINDER XC=0.0 YC=0.0 ZB=-28. ZT=-24. RADIUS=.5
 PACKAGE AIR W=1.5E5
 CYLINDER XC=0.0 YC=0.0 ZB=-1.0E20 ZT=-28. RADIUS=.5
 PACKAGE RHA
 BOX X1=-8.0 X2=8.0 Y1=0.0 Y2=8.0 Z1=0.0 Z2=2.0
 XCC=0.0 YCC=0.0 ZCC=0.86603
 ANGLB=60
 PACKAGE RHA
 BOX X1=-8.0 X2=8.0 Y1=0.0 Y2=8.0 Z1=0.0 Z2=2.0
 XCC=0.0 YCC=0.0 ZCC=15.02603
 ANGLB=60
 PACKAGE AIR W=1.0E4 BOX FILL
 STATION XS=0. YS=0. ZL=0.
 XS=0. YS=0. ZL=-28.
 END

KEEL Input For Monolithic Penetrators Into T/D=4 Spaced Plates

KEEL PROBLEM 6.0001
 NM=3 AIR=1 WALLOY=2 RHA=3
 DIMEN=3 VISC=1 FLUXER=3 STRESS=1
 IMAX=56 JMAX=33 KMAX=284 IQ=55 JQ=32 KQ=283
 FAIL=. STRAIN=1 REZONE=0
 NSTN=2 NOP=2000
 AREF=.TRUE. BREF=.FALSE. FREF=.FALSE.
 LREF=.FALSE. RREF=.FALSE. TREF=.FALSE.
 HEADER
 L/D = 20 VS = 1.5 KM/SEC T/D = 4
 MESH
 CONSTANT SUBGRID NX=30 X0=-2.5 XMAX=2.5 RXNEG=1.1 RXPOS=1.1
 XOLIM=-6.99583 XMLIM=6.99583
 NY=15 Y0=0.0 YMAX=2.5 RYPOS=1.1
 YOLIM=0. YMLIM=10.85985
 NZ=296 Z0=-21.0 ZMAX=47.25 RZNEG=1.0
 RZPOS=1.0
 ZOLIM=-21.0 ZMLIM=50.
 GENERATE
 PACKAGE WALLOY W=1.5E5
 CYLINDER XC=0.0 YC=0.0 ZB=-20. ZT=-0.0 RADIUS=.5
 PACKAGE AIR W=1.5E5
 CYLINDER XC=0.0 YC=0.0 ZB=-1.0E20 ZT=-20. RADIUS=.5
 PACKAGE RHA
 BOX X1=-10.0 X2=10.0 Y1=0.0 Y2=10.0 Z1=0.0 Z2=4.0
 XCC=1.7321 YCC=0.0 ZCC=3.86603
 ANGLB=60
 PACKAGE RHA
 BOX X1=-10.0 X2=10.0 Y1=0.0 Y2=10.0 Z1=0.0 Z2=4.0
 XCC=1.7321 YCC=0.0 ZCC=22.02603
 ANGLB=60
 PACKAGE AIR W=1.0E4 BOX FILL
 STATION XS=0. YS=0. ZL=0.
 XS=0. YS=0. ZL=-20.
 END

KEEL Input For Segmented Penetrators Into T/D=4 Spaced Plates

KEEL PROBLEM 518.88

NM=3 AIR=1 WALLOY=2 RHA=3

DIMEN=3 VISC=1 FLUXER=3 STRESS=1

IMAX=56 JMAX=33 KMAX=316 IQ=53 JQ=32 KQ=315

FAIL=1 STRAIN=1 REZONE=0

NSTN=2 NOP=2000

AREF=.TRUE. BREF=.FALSE. FREF=.FALSE.

LREF=.FALSE. RREF=.FALSE. TREF=.FALSE.

HEADER

SEGMENTED ROD L/D = 20 VS = 2.0 KM/SEC T/D = 4

MESH

CONSTANT SUBGRID NX=30 X0=-2.5 XMAX=2.5 RXNEG=1.1 RXPOS=1.1

XOLIM=-6.99583 XMLIM=6.99583

NY=15 Y0=0.0 YMAX=2.5 RYPOS=1.1

YOLIM=0. YMLIM=10.85985

NZ=316 Z0=-29.0 ZMAX=50. RZNEG=1.0

RZPOS=1.0

ZOLIM=-29.0 ZMLIM=50.

GENERATE

PACKAGE WALLOY W=2.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-4. ZT=0.0 RADIUS=.5

PACKAGE AIR W=2.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-6. ZT=4. RADIUS=.5

PACKAGE WALLOY W=2.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-10. ZT=6. RADIUS=.5

PACKAGE AIR W=2.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-12. ZT=10. RADIUS=.5

PACKAGE WALLOY W=2.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-16. ZT=12. RADIUS=.5

PACKAGE AIR W=2.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-18. ZT=16. RADIUS=.5

PACKAGE WALLOY W=2.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-22. ZT=18. RADIUS=.5

PACKAGE AIR W=2.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-24. ZT=22. RADIUS=.5

PACKAGE WALLOY W=2.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-28. ZT=24. RADIUS=.5

PACKAGE AIR W=2.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-1.0E20 ZT=28. RADIUS=.5

PACKAGE RHA

BOX X1=-10.0 X2=10.0 Y1=0.0 Y2=10.0 Z1=0.0 Z2=4.0

XCC=1.7321 YCC=0.0 ZCC=3.86603

ANGLB=60

PACKAGE RHA

BOX X1=-10.0 X2=10.0 Y1=0.0 Y2=10.0 Z1=0.0 Z2=4.0

XCC=1.7321 YCC=0.0 ZCC=22.02603

ANGLB=60

PACKAGE AIR W=1.0E4 BOX FILL

STATION XS=0. YS=0. ZL=0.

XS=0. YS=0. ZL=-28.

END

KEEL Input For S/D=4 Segmented Penetrator Into T/D=4 Spaced Plates

KEEL PROBLEM 7.0001

NM=3 AIR=1 WALLOY=2 RHA=3

DIMEN=3 VISC=1 FLUXER=3 STRESS=1

IMAX=56 JMAX=33 KMAX=348 IQ=55 JQ=32 KQ=347

FAIL=1 STRAIN=1 REZONE=0

NSTN=2 NOP=2000

AREF=.TRUE. BREF=.FALSE. FREF=.FALSE.

LREF=.FALSE. RREF=.FALSE. TREF=.FALSE.

HEADER

SEGMENTED ROD L/D = 20 VS = 4.0 KM/SEC T/D = 4

MESH

CONSTANT SUBGRID NX=30 X0=-2.5 XMAX=2.5 RXNEG=1.1 RXPOS=1.1

XOLIM=-6.99583 XMLIM=6.99583

NY=15 Y0=0.0 YMAX=2.5 RYPOS=1.1

YOLIM=0. YMLIM=10.85985

NZ=348 Z0=-37.0 ZMAX=50. RZNEG=1.0

RZPOS=1.0

ZOLIM=-37.0 ZMLIM=50.

GENERATE

PACKAGE WALLOY W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-4. ZT=0.0 RADIUS=.5

PACKAGE AIR W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-8. ZT=4. RADIUS=.5

PACKAGE WALLOY W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-12. ZT=8. RADIUS=.5

PACKAGE AIR W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-16. ZT=12. RADIUS=.5

PACKAGE WALLOY W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-20. ZT=16. RADIUS=.5

PACKAGE AIR W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-24. ZT=20. RADIUS=.5

PACKAGE WALLOY W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-28. ZT=24. RADIUS=.5

PACKAGE AIR W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-32. ZT=28. RADIUS=.5

PACKAGE WALLOY W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-36. ZT=32. RADIUS=.5

PACKAGE AIR W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-1.0E20 ZT=36. RADIUS=.5

PACKAGE RHA

BOX X1=-10.0 X2=10.0 Y1=0.0 Y2=10.0 Z1=0.0 Z2=4.0

XCC=1.7321 YCC=0.0 ZCC=3.86603

ANGLB=60

PACKAGE RHA

BOX X1=-10.0 X2=10.0 Y1=0.0 Y2=10.0 Z1=0.0 Z2=4.0

XCC=1.7321 YCC=0.0 ZCC=22.02603

ANGLB=60

PACKAGE AIR W=1.0E4 BOX FILL

STATION XS=0. YS=0. ZL=0.

XS=0. YS=0. ZL=-52.

END

KEEL Input For S/D=8 Segmented Penetrator Into T/D=4 Spaced Plates

NM=3 AIR=1 WALLOY=2 RHA=3
 DIMEN=3 VISC=1 FLUXER=3 STRESS=1
 IMAX=56 JMAX=33 KMAX=412 IQ=55 JQ=32 KQ=411
 FAIL=1 STRAIN=1 REZONE=0
 NSTN=2 NOP=2000
 AREF=.TRUE. BREF=.FALSE. FREF=.FALSE.
 LREF=.FALSE. RREF=.FALSE. TREF=.FALSE.
 HEADER
 SEGMENTED ROD L/D = 20 VS = 4.0 KM/SEC T/D = 4
 MESH
 CONSTANT SUBGRID NX=30 X0=-2.5 XMAX=2.5 RXNEG=-1.1 RXPOS=1.1
 XOLIM=-6.99583 XMLIM=6.99583
 NY=15 Y0=0.0 YMAX=2.5 RYPOS=1.1
 YOLIM=0. YMLIM=10.85985
 NZ=412 Z0=-53.0 ZMAX=50. RZNEG=-1.0
 RZPOS=1.0
 ZOLIM=-53.0 ZMLIM=50.
 GENERATE
 PACKAGE WALLOY W=4.0E5
 CYLINDER XC=0.0 YC=0.0 ZB=-4. ZT=0.0 RADIUS=.5
 PACKAGE AIR W=4.0E5
 CYLINDER XC=0.0 YC=0.0 ZB=-12. ZT=-4. RADIUS=.5
 PACKAGE WALLOY W=4.0E5
 CYLINDER XC=0.0 YC=0.0 ZB=-16. ZT=-12. RADIUS=.5
 PACKAGE AIR W=4.0E5
 CYLINDER XC=0.0 YC=0.0 ZB=-24. ZT=-16. RADIUS=.5
 PACKAGE WALLOY W=4.0E5
 CYLINDER XC=0.0 YC=0.0 ZB=-28. ZT=-24. RADIUS=.5
 PACKAGE AIR W=4.0E5
 CYLINDER XC=0.0 YC=0.0 ZB=-36. ZT=-28. RADIUS=.5
 PACKAGE WALLOY W=4.0E5
 CYLINDER XC=0.0 YC=0.0 ZB=-40. ZT=-36. RADIUS=.5
 PACKAGE AIR W=4.0E5
 CYLINDER XC=0.0 YC=0.0 ZB=-48. ZT=-40. RADIUS=.5
 PACKAGE WALLOY W=4.0E5
 CYLINDER XC=0.0 YC=0.0 ZB=-52. ZT=-48. RADIUS=.5
 PACKAGE AIR W=4.0E5
 CYLINDER XC=0.0 YC=0.0 ZB=-1.0E20 ZT=-52. RADIUS=.5
 PACKAGE RHA
 BOX X1=-10.0 X2=10.0 Y1=0.0 Y2=10.0 Z1=0.0 Z2=4.0
 XCC=1.7321 YCC=0.0 ZCC=3.86603
 ANGLB=60
 PACKAGE RHA
 BOX X1=-10.0 X2=10.0 Y1=0.0 Y2=10.0 Z1=0.0 Z2=4.0
 XCC=1.7321 YCC=0.0 ZCC=22.02603
 ANGLB=60
 PACKAGE AIR W=1.0E4 BOX FILL
 STATION XS=0. YS=0. ZL=0.
 XS=0. YS=0. ZL=-52.
 END

KEEL Input For 20 Segment S/D=1 Penetrator Into T/D=4 Spaced Plates

KEEL PROBLEM 8.0000

NM=3 AIR=1 WALLOY=2 RHA=3

DIMEN=3 VISC=1 FLUXER=3 STRESS=1

IMAX=56 JMAX=33 KMAX=360 IQ=55 JQ=32 KQ=359

FAIL=1 STRAIN=1 REZONE=0

NSTN=2 NOP=2000

AREF=.TRUE. BREF=.FALSE. FREF=.FALSE.

LREF=.FALSE. RREF=.FALSE. TREF=.FALSE.

HEADER

SEGMENTED ROD L/D = 20 VS = 4.0 KM/SEC T/D = 4

MESH

CONSTANT SUBGRID NX=30 X0=-2.5 XMAX=2.5 RXNEG=1.1 RXPOS=1.1

XOLIM=-6.99583 XMLIM=6.99583

NY=15 Y0=0.0 YMAX=2.5 RYPOS=1.1

YGLIM=0. YMLIM=10.85985

NZ=360 Z0=-40.0 ZMAX=50. RZNEG=1.0

RZPOS=1.0

ZOLIM=-40.0 ZMLIM=50.

GENERATE

PACKAGE WALLOY W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-1. ZT=0.0 RADIUS=.5

PACKAGE AIR W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-2. ZT=-1. RADIUS=.5

PACKAGE WALLOY W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-3. ZT=-2. RADIUS=.5

PACKAGE AIR W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-4. ZT=-3. RADIUS=.5

PACKAGE WALLOY W=4.0E5

CYLINDER XC=0.0 YC=0.0 ZB=-5. ZT=-4. RADIUS=.5

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END

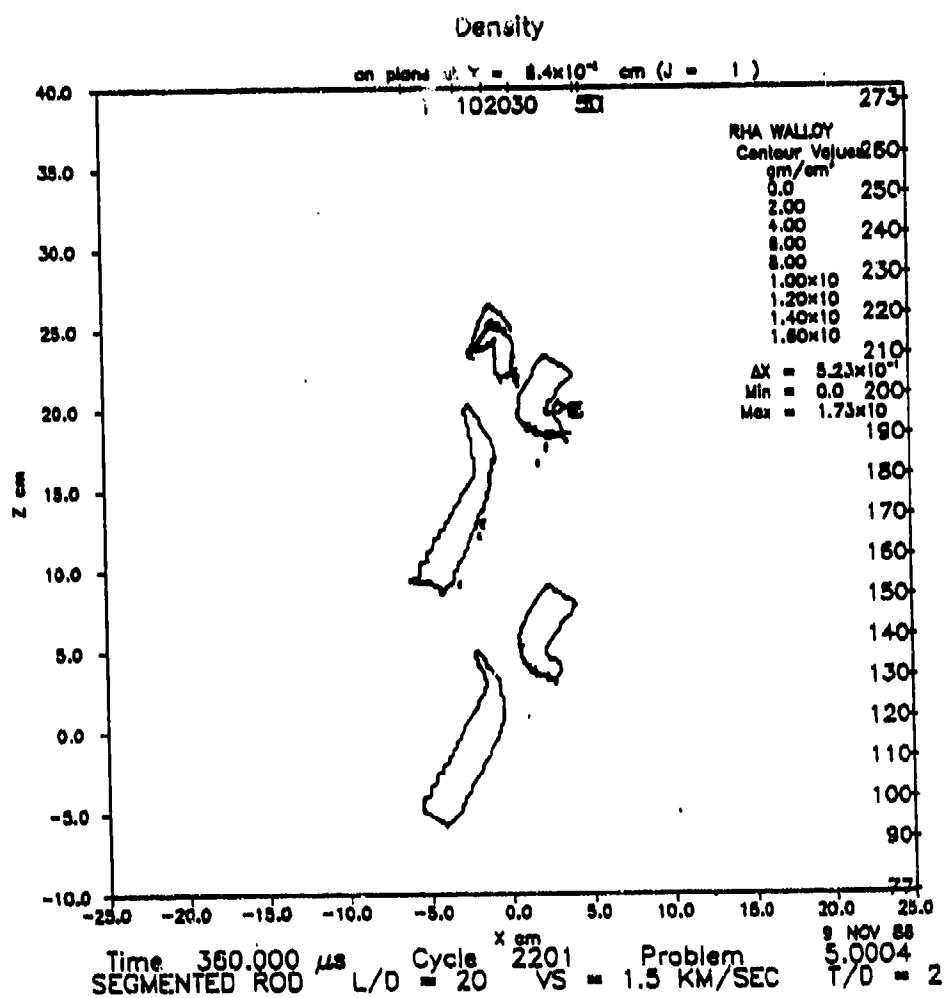
APPENDIX B - Material Properties

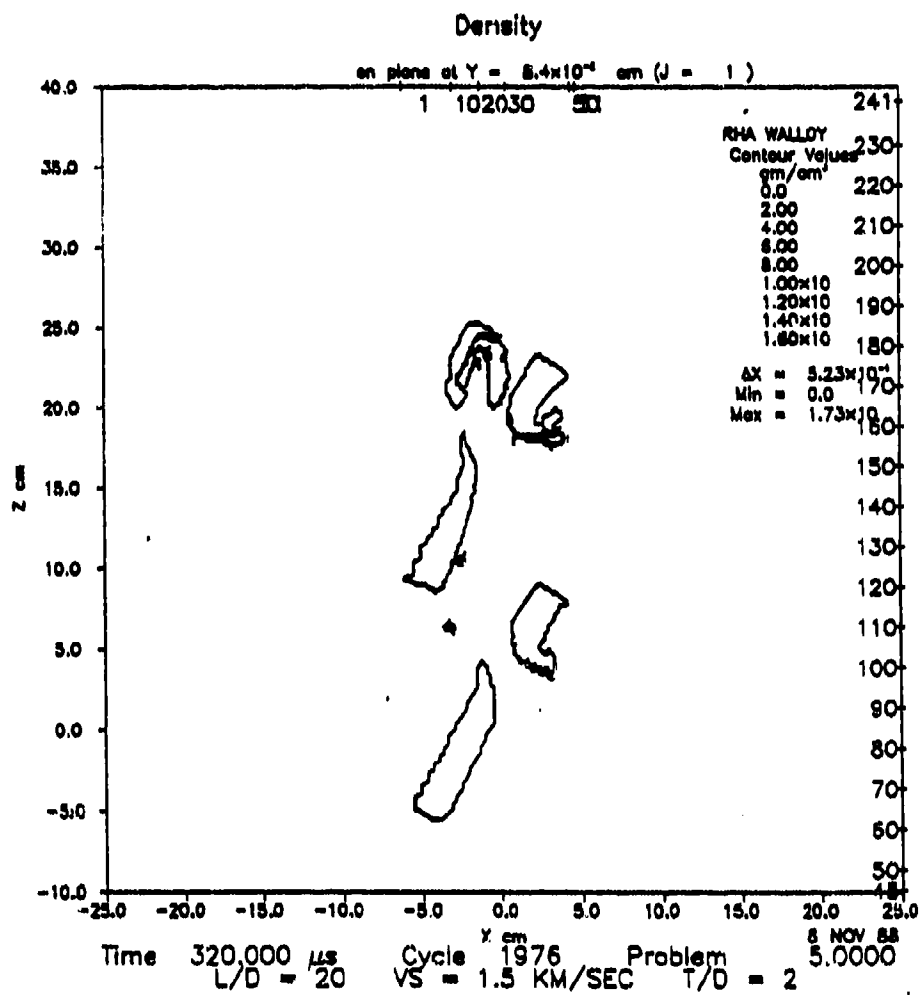
APPENDIX B

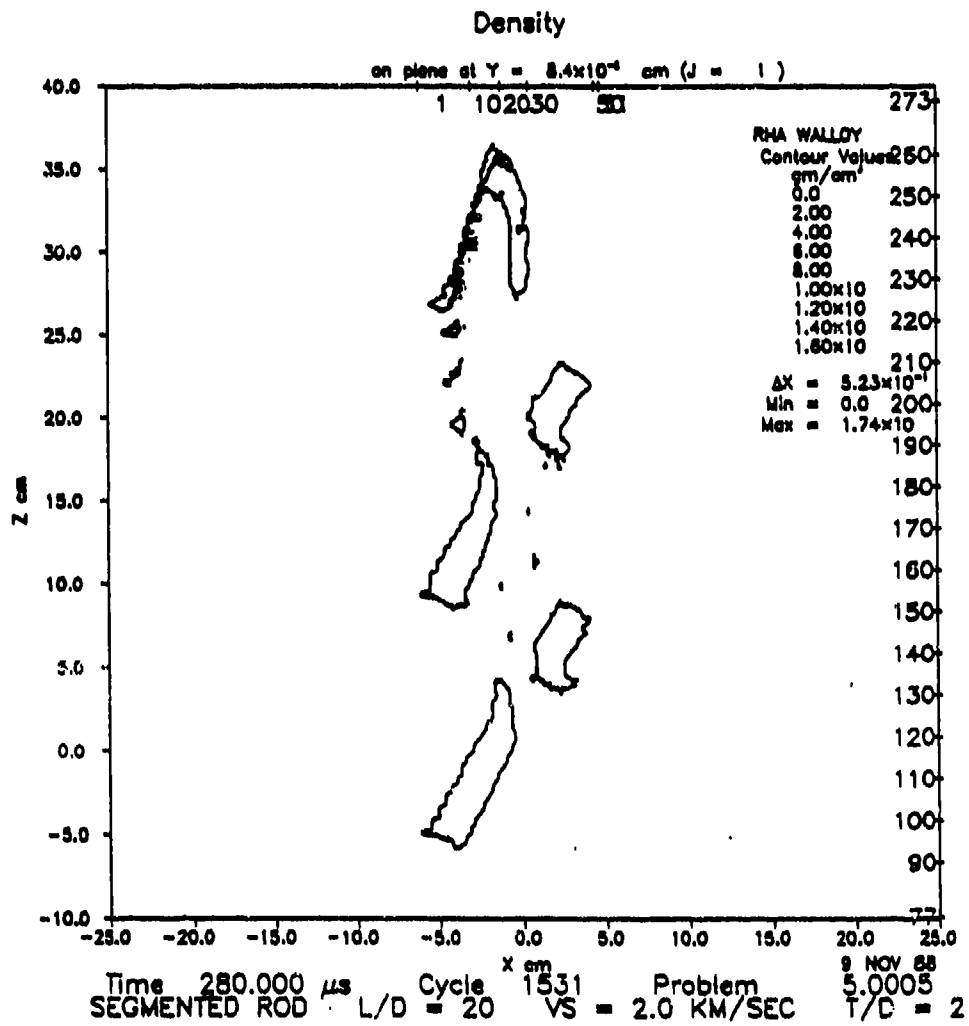
Material Properties and Equation of State Data

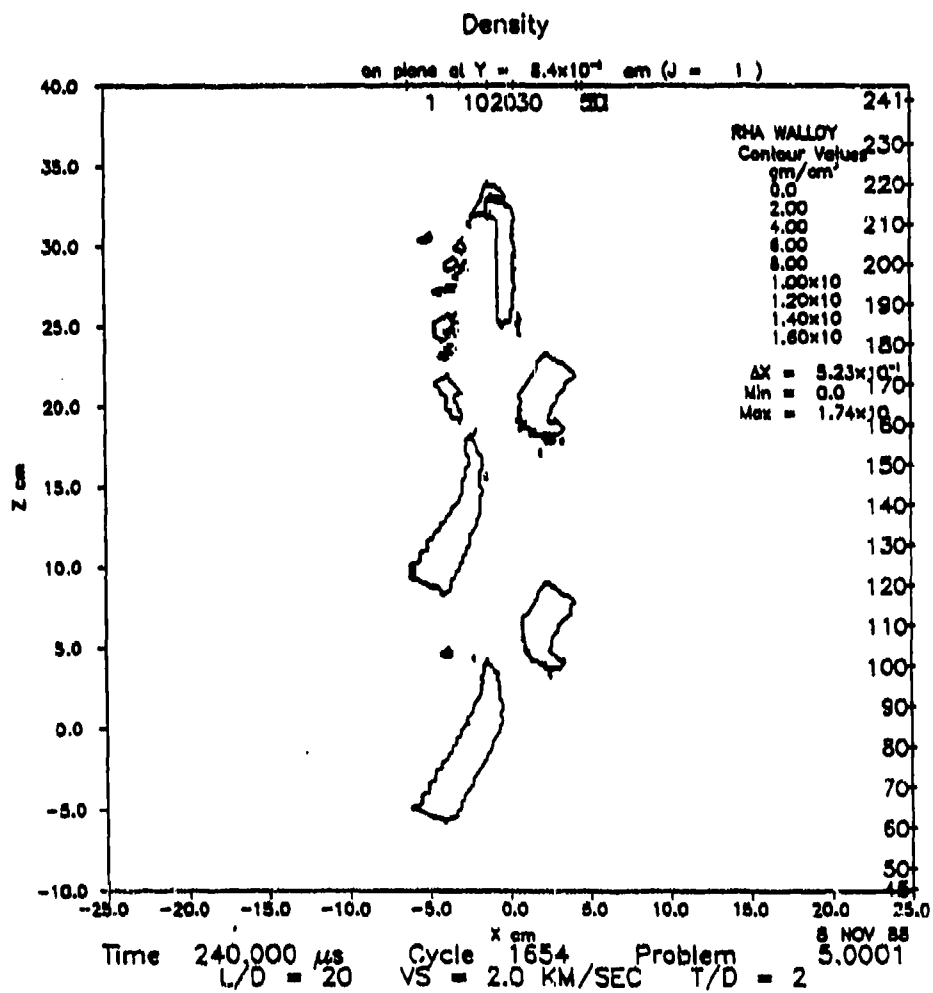
	RHA	TUNGSTEN
Ambient density (g/cc)	7.86	17.3
Ambient sound speed (cm/s)	4.61e5	4.0e5
Shock velocity/particle velocity slope	1.73	1.268
Initial Gruneisen ratio	1.67	1.43
Minimum Pressure (dynes/cm ²)	-1.0e20	-10.e9
Poisson's ratio	0.26	0.3
Atomic weight	55.85	184.
Debye's temperature (K)	355	270
Vapor coefficient	0.25	0.2
Ambient energy per unit mass (ergs/g)	0.0	0.0
Ambient melt energy per unit mass (ergs/g)	7.4e9	4.77e9
Fusion energy per unit mass (ergs/g)	2.74e9	1.84e9
Sublimation energy per unit mass (ergs/g)	74.2e9	46.e9
Ambient vaporization energy per unit mass (ergs/g)	22.4e9	13.6e9
Ambient energy per unit mass at end of vaporization (ergs/g)	86.8e9	58.4e9
Initial yield strength (dynes/cm ²)	15.e9	20.e9
Saturation yield strength (dynes/cm ²)	15.e9	20.e9
Plastic strain at saturation yield strength	0.3	0.3
Yield strength ratio for first point on thermal softening curve	0.9	0.9
Energy ratio for first point on thermal softening curve	0.5	0.5
Yield strength ratio for second point on thermal softening curve	0.9	0.9
Energy ratio for second point on thermal softening curve	0.5	0.5
Second coefficient in Hugoniot pressure curve (dynes/cm ²)	4.21968e12	4.6987e12
Third coefficient in Hugoniot pressure curve (dynes/cm ²)	5.12915e12	3.345e12
Ultimate failure stress (dynes/cm ²)	42.e9	1.e50
Ultimate failure strain	1.75	0.14

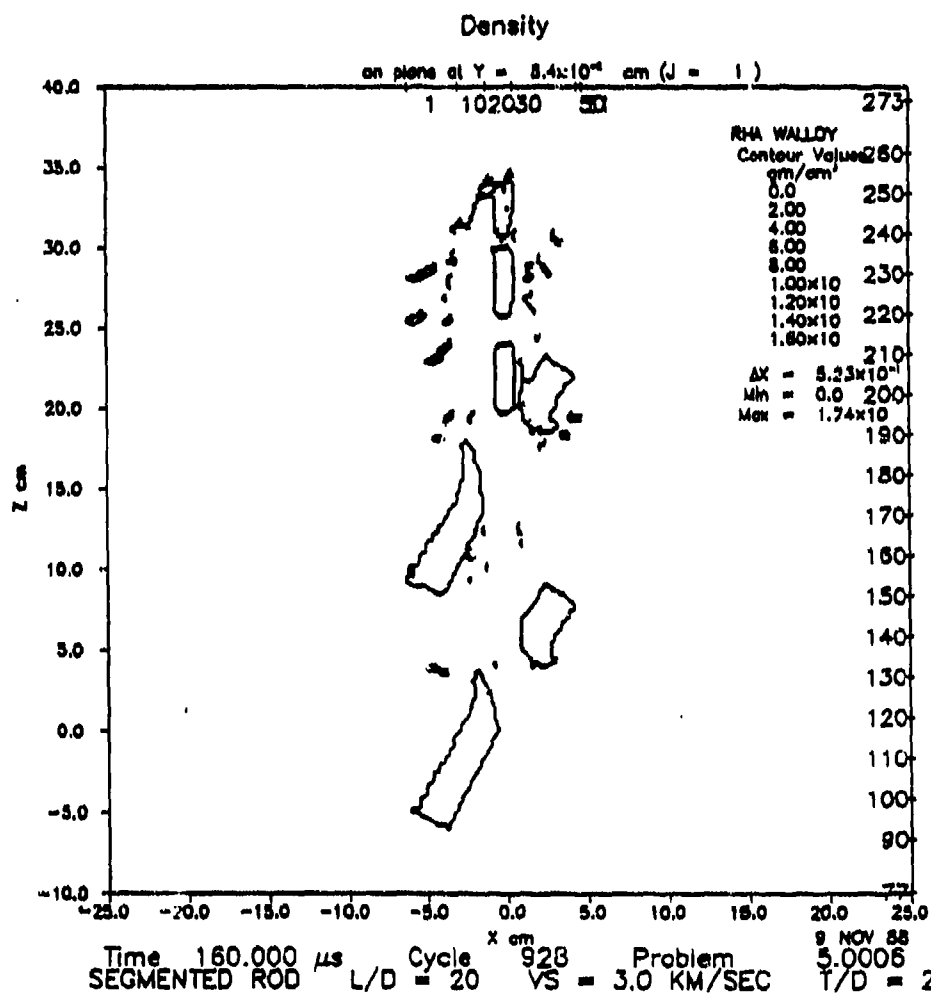
APPENDIX C - Plots Used For Residual Mass Calculations

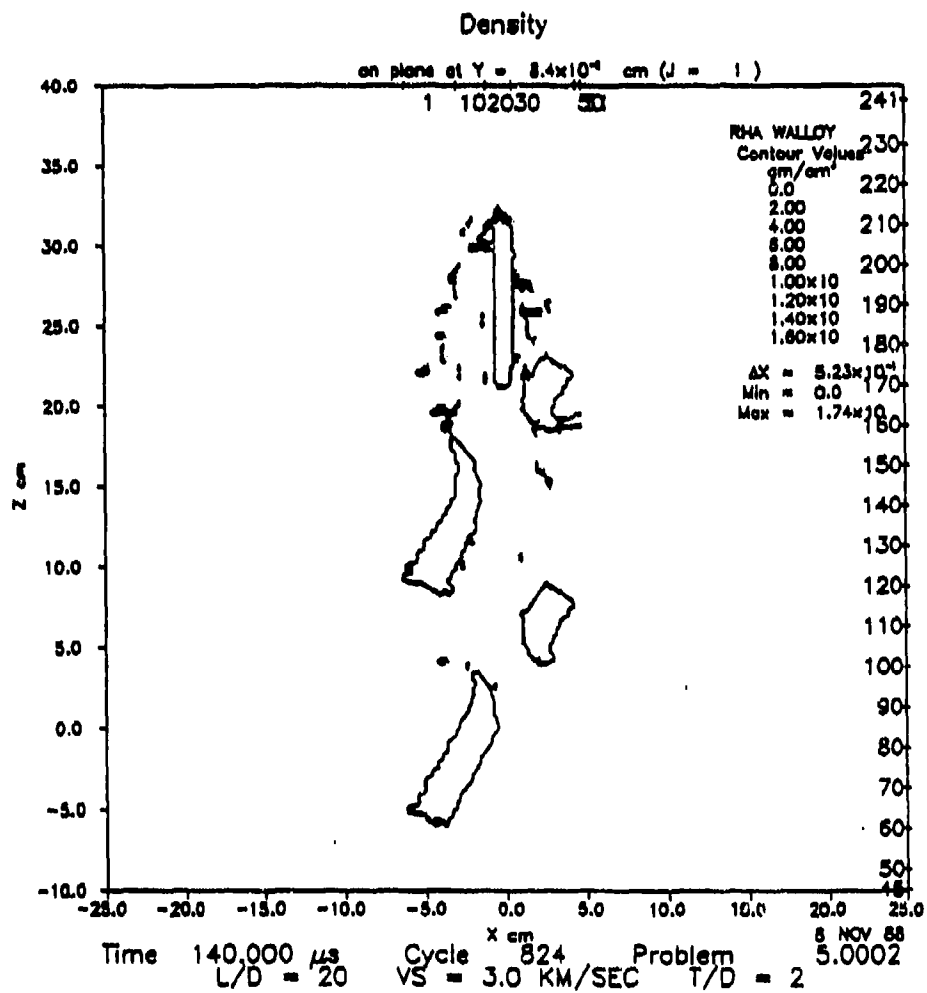


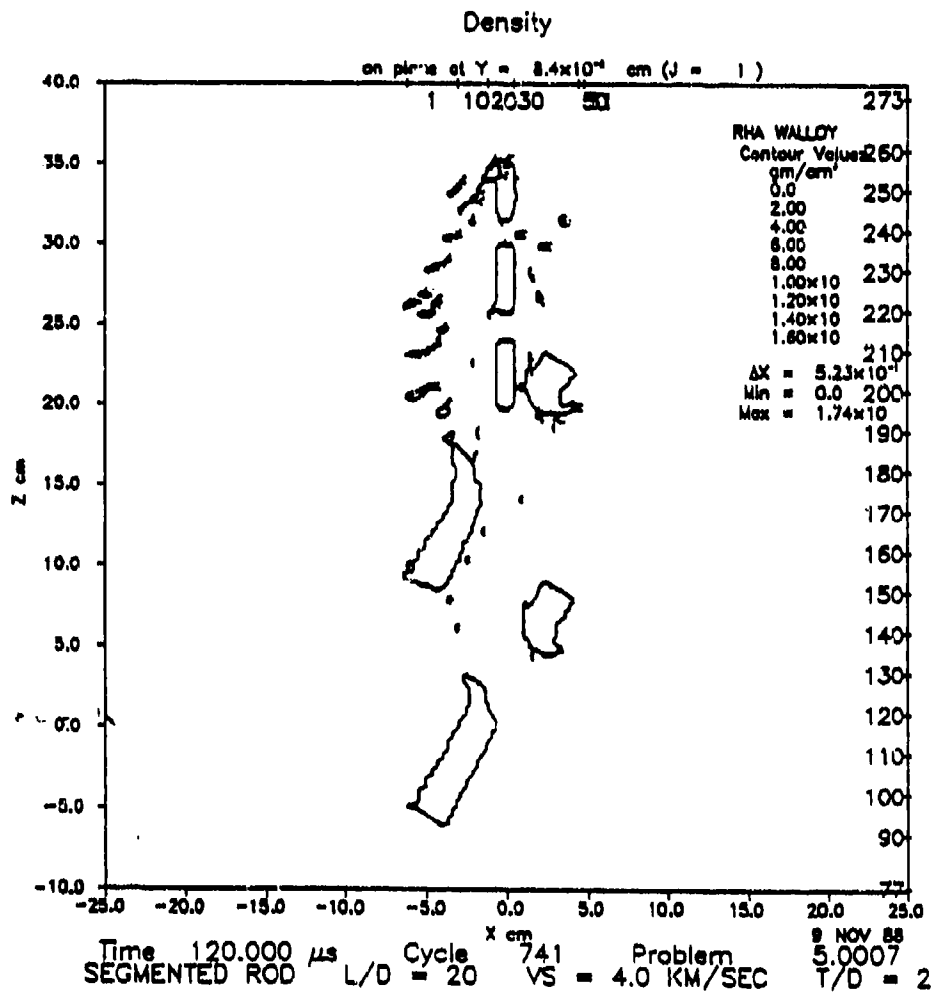


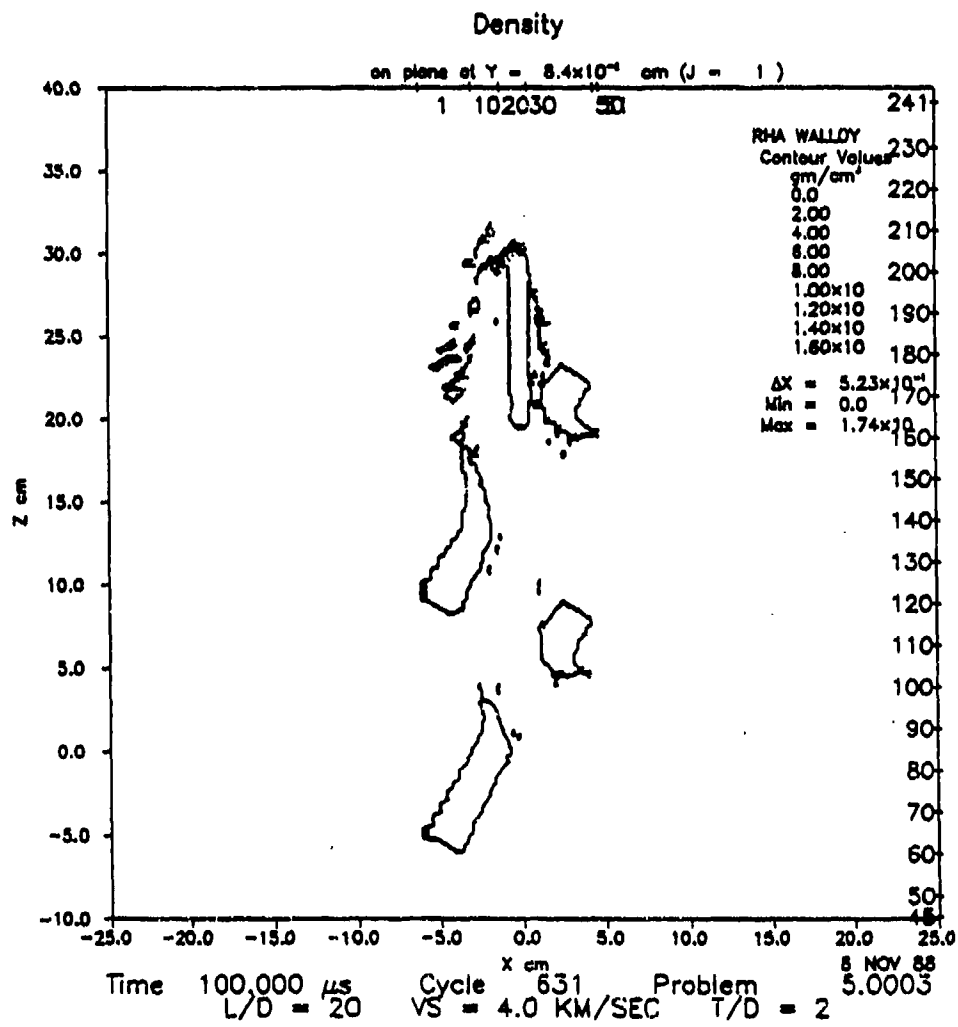


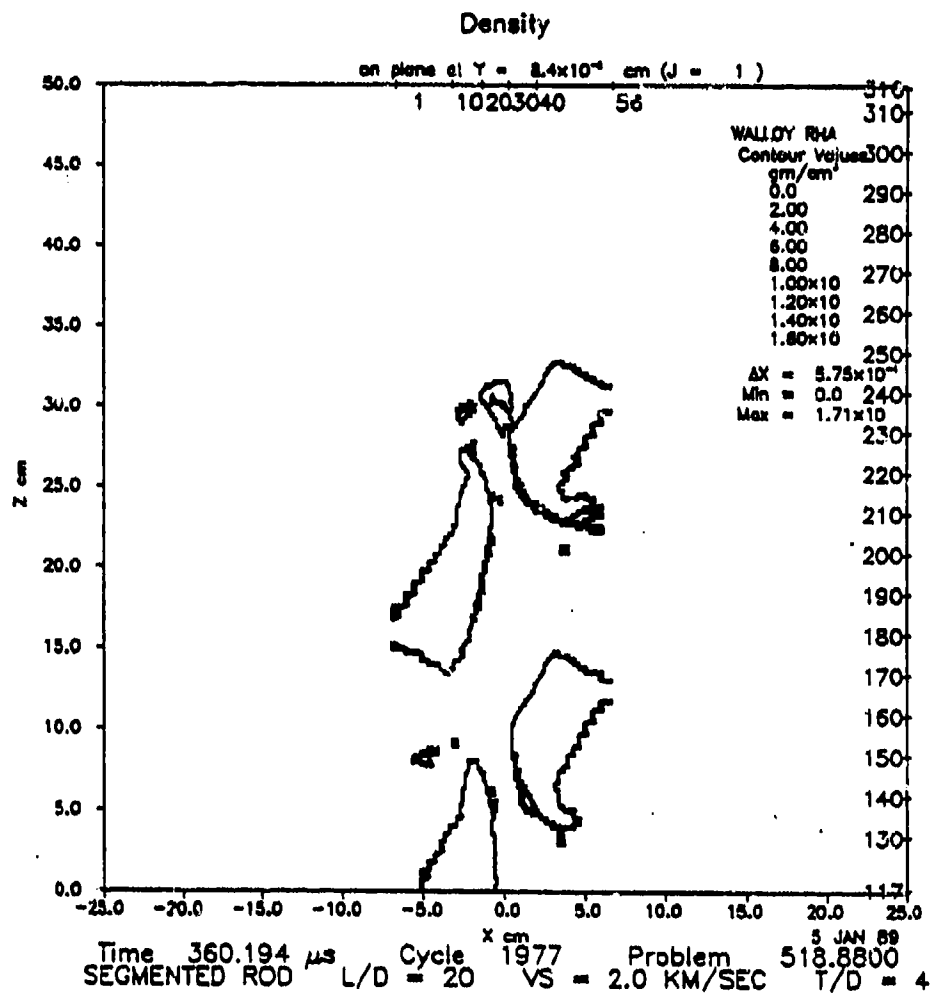


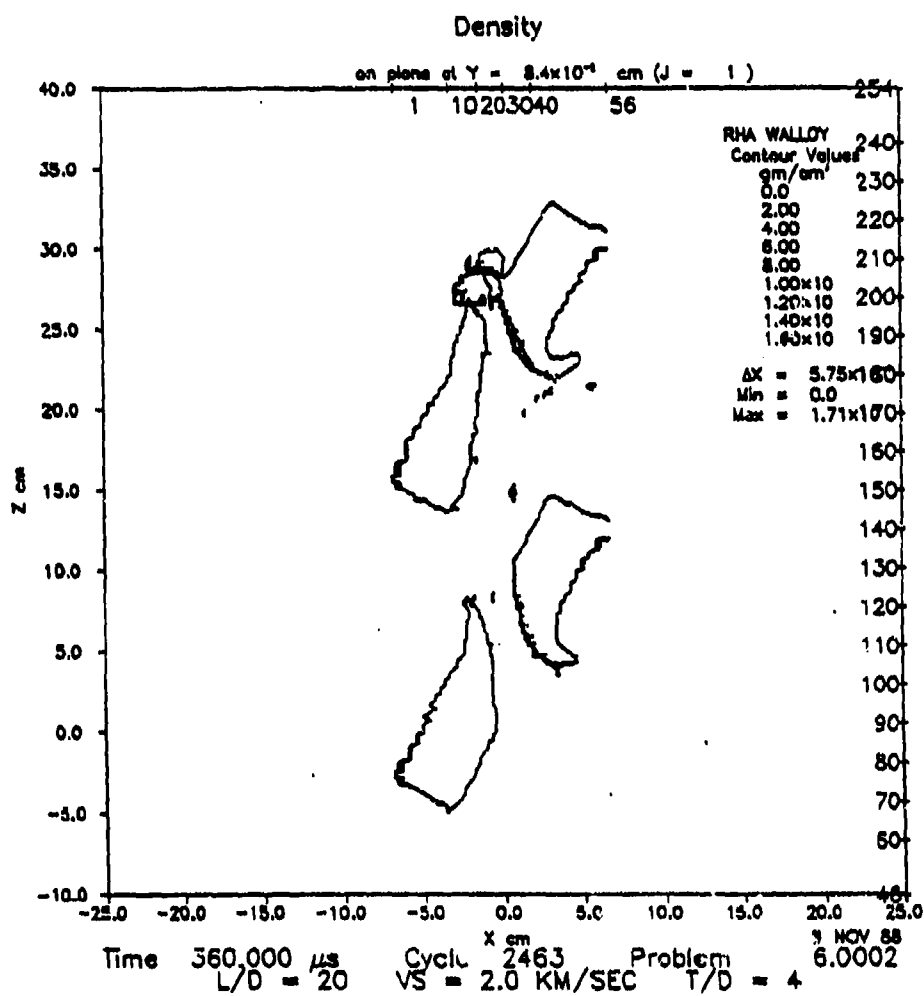


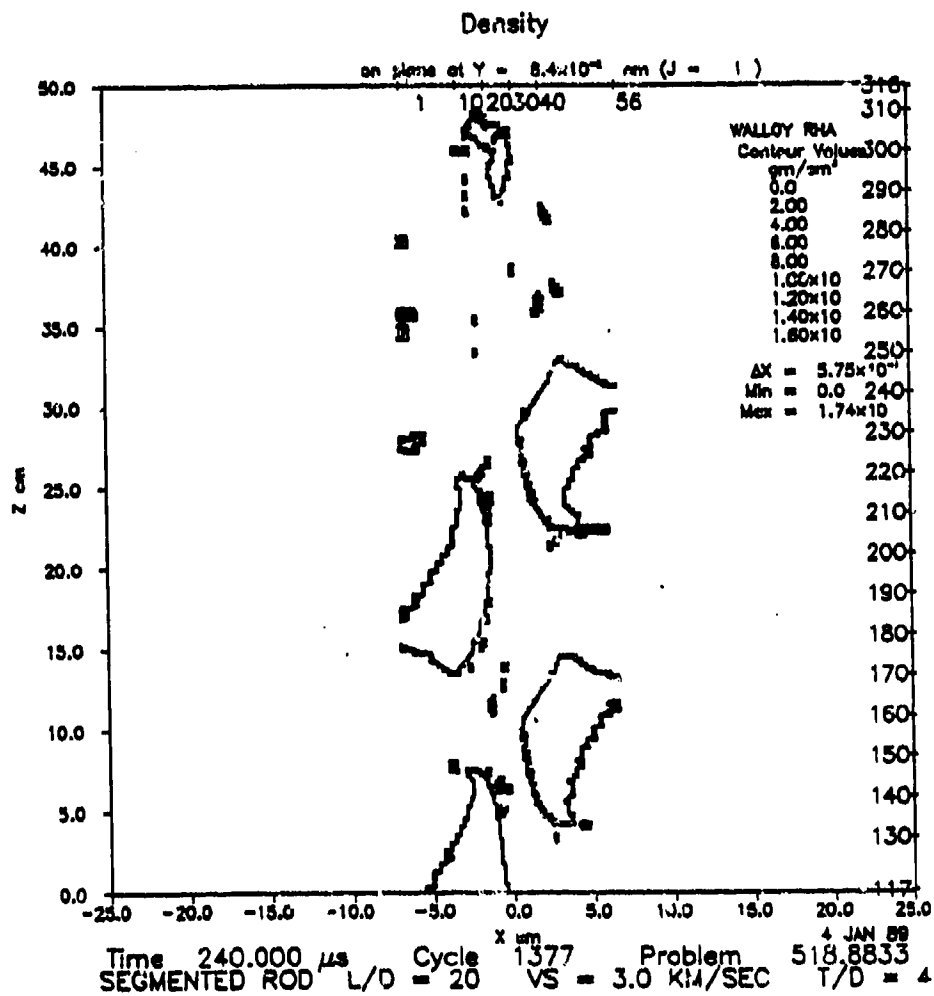


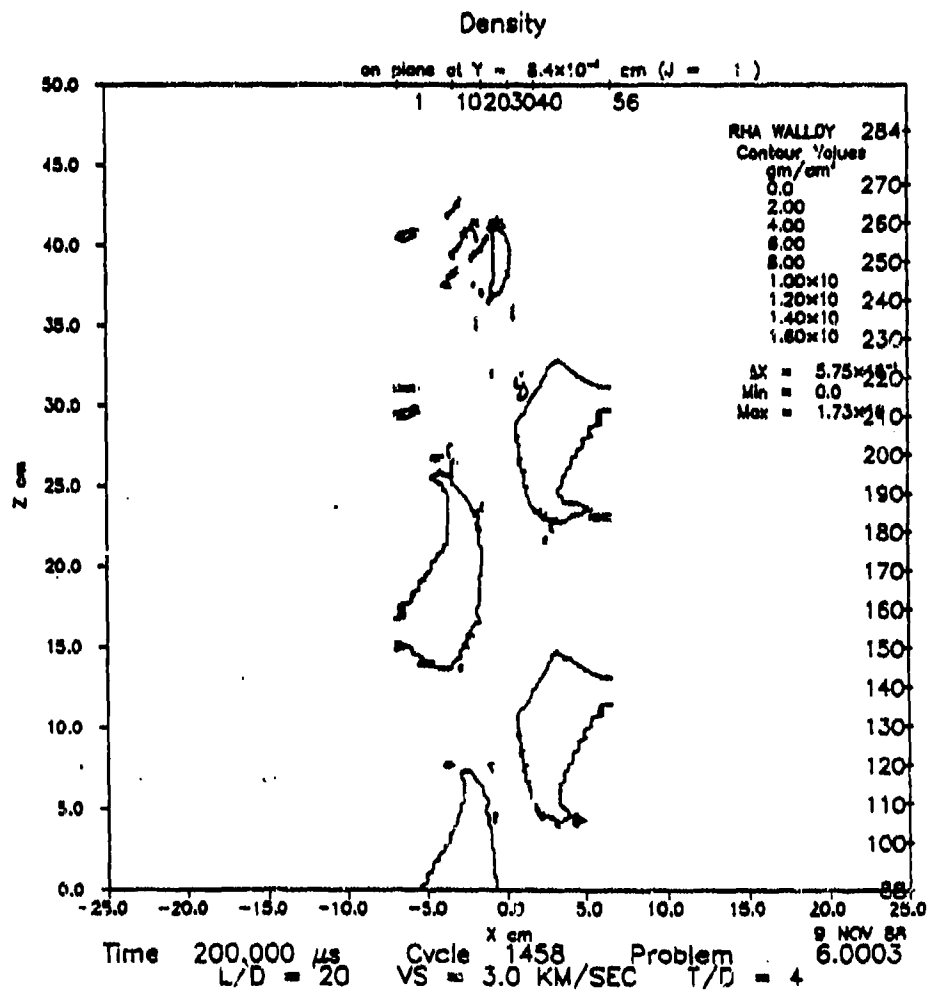


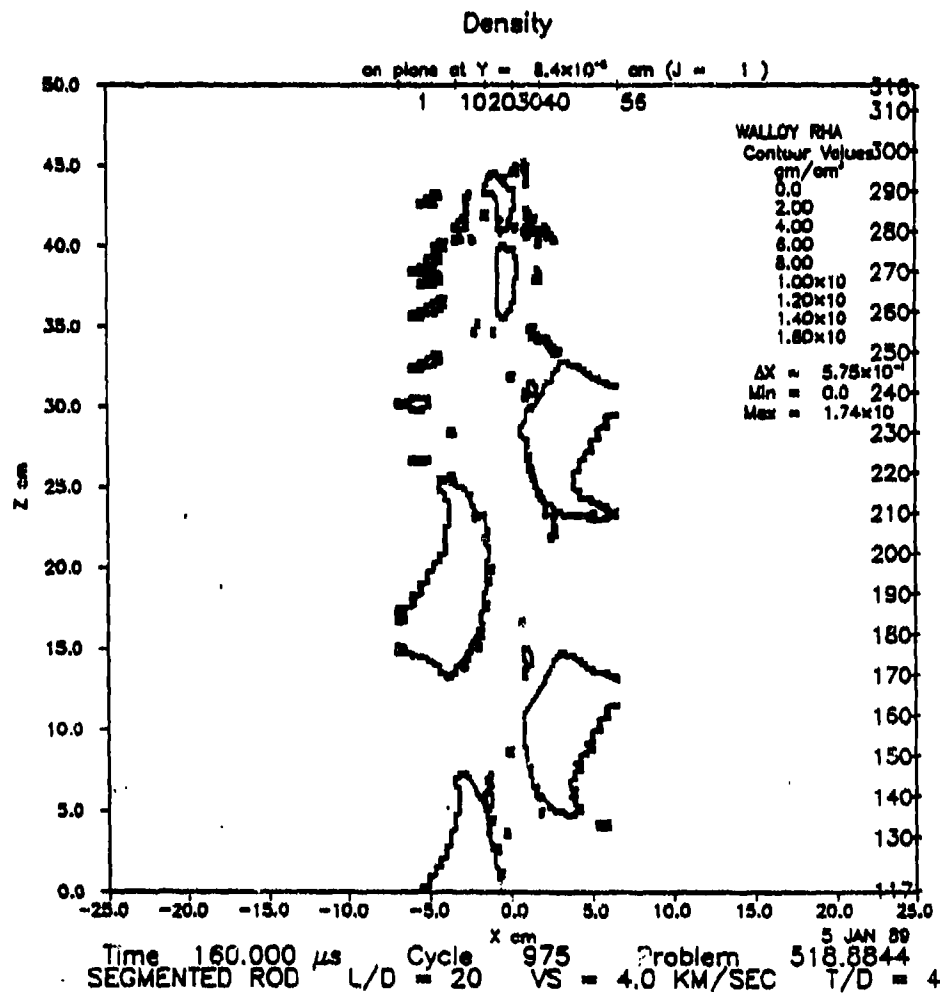


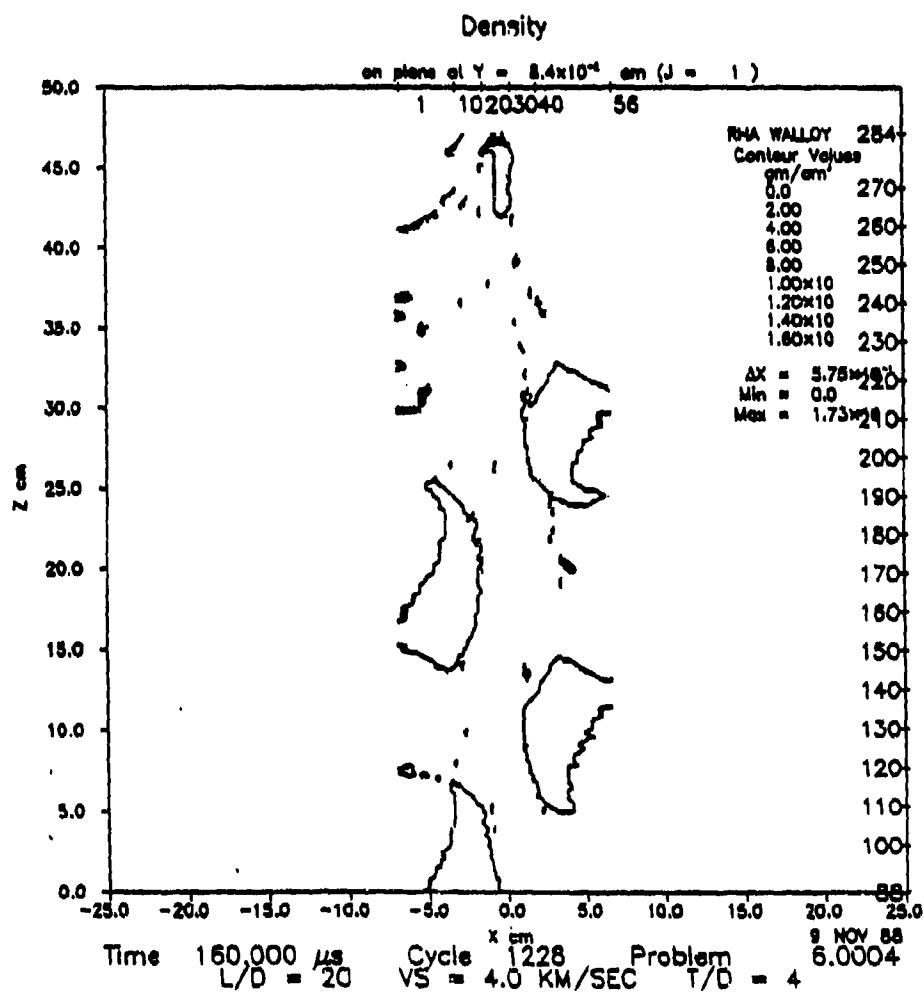


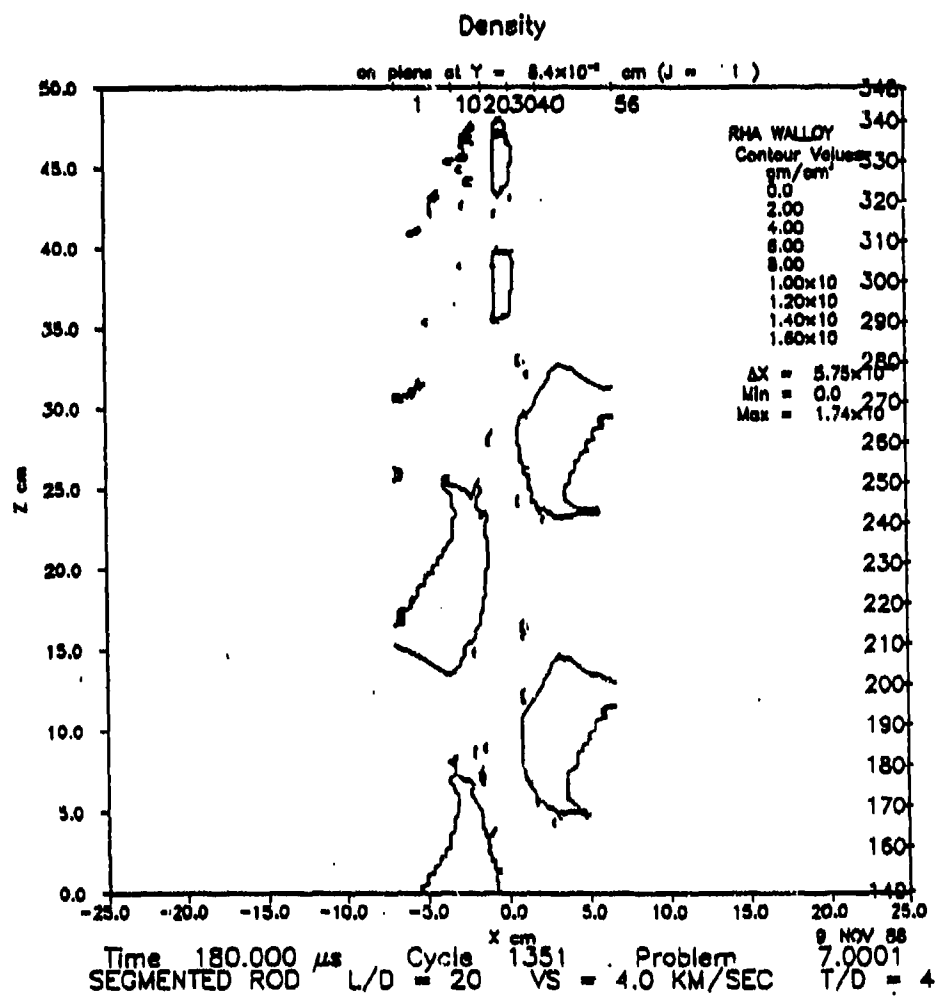


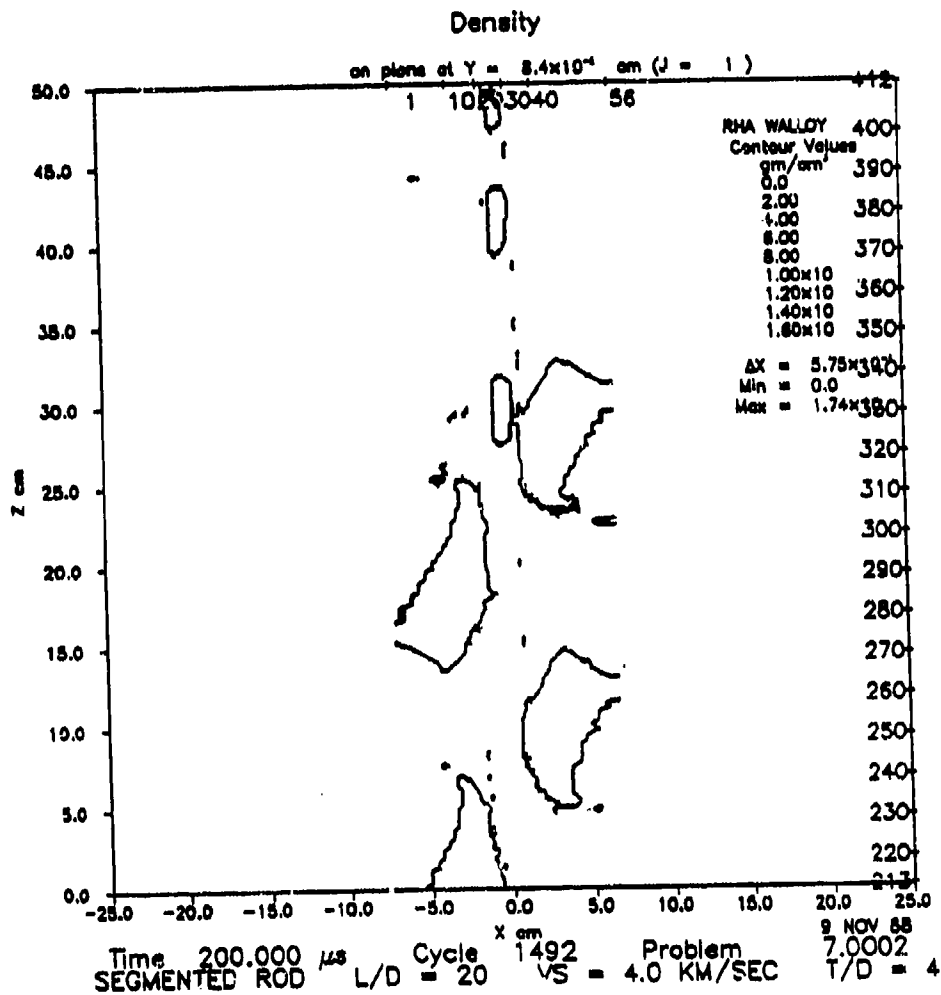


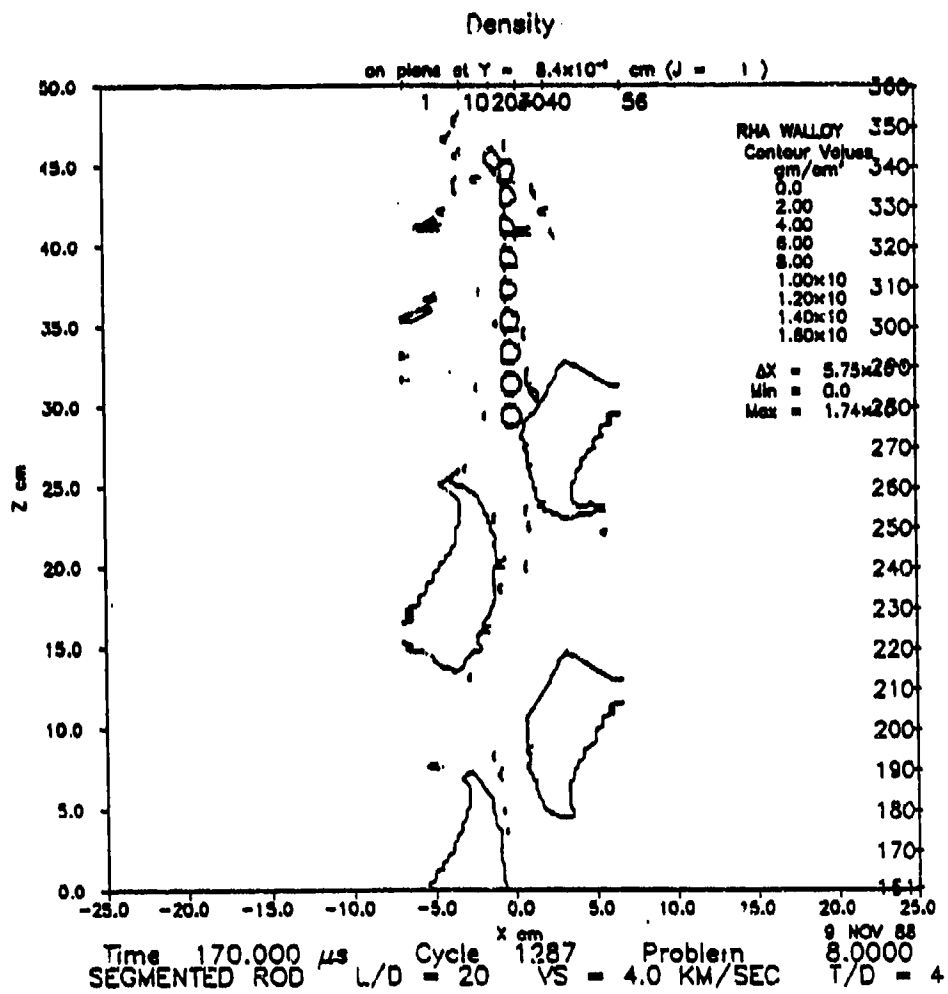












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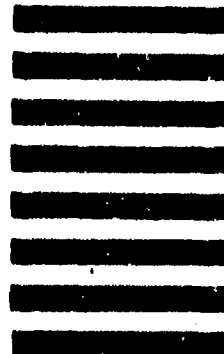


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