

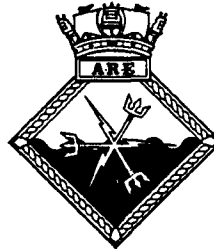
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# A NOTE ON THE GAUSSIAN INTEGRATION FORMULA

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FIGURES

1. Gaussian Integration Of The Function  $\sin(x)$

A Note On The Gaussian Integration Formula

ABSTRACT

The Gaussian integration method is described together with the 2-point implementation for numerical integration. A FORTRAN program is given and the result of a test example.

## BACKGROUND

1. This work was originally completed some years ago and the software, which is incorporated in a Maths Library on the UDT computer facility, has been used extensively. Gauss' formula provides a method for calculating the definite integral of a given function. *Legendre's Gauss 2*

### THEORY

2. If  $P_m(x)$ ,  $P_n(x)$ ,  $x \in \mathbb{R}$ , are polynomials of degree  $m, n$  respectively, with  $m \geq n$ , then polynomials  $q(x)$ ,  $r(x)$  exist such that:

$$P_m(x) = P_n(x)q(x) + r(x) \quad 1.$$

where the degree of  $q(x)$  is  $m-n$  and the degree of  $r(x)$  is  $n-1$  at most. The polynomials  $q(x)$ ,  $r(x)$  are unique and called the quotient and remainder of  $P_m(x)$  with reference to  $P_n(x)$ .

3. Consider:

$$\int_{-1}^{+1} P_{2n+1}(x) dx$$

and let  $P_{n+1}(x)$  be a Legendre polynomial of degree  $n+1$ . Then by equation 1:

$$\int_{-1}^{+1} P_{2n+1}(x) dx = \int_{-1}^{+1} \{P_{n+1}(x)q_n(x) + r_n(x)\} dx \quad 2.$$

But any polynomial of degree  $n$  can be expressed as a linear combination of Legendre polynomials of degree  $k \leq n$ . Thus

$$q_n(x) = \sum_{k=0}^n a_k P_k(x) \quad 3.$$

and therefore, using the orthogonal properties of Legendre functions:

$$\int_{-1}^{+1} P_{n+1}(x)q_n(x) dx = 0 \quad 4.$$

gives:

$$\int_{-1}^{+1} P_{2n+1}(x) dx = \int_{-1}^{+1} r_n(x) dx \quad 5.$$

4. We seek solutions of the form:

$$\begin{aligned} \int_{-1}^{+1} P_{2n+1}(x) dx &= \sum_{k=0}^n a_k P_{2n+1}(x_k) \\ &= \sum_{k=0}^n a_k \{ P_{n+1}(x_k) q_n(x_k) + r_n(x_k) \} \end{aligned} \quad 6.$$

but equation 5 shows the integral is independent of the choice of  $q_n(x)$  and therefore equation 6 is true iff  $x_k$  are the  $n+1$  roots of  $P_{n+1}(x)$ . Let:

$$\omega_{n+1}(x) = \prod_{k=0}^n (x-x_k) \quad 7.$$

then expanding in partial fractions gives:

$$\frac{r_n(x)}{\omega_{n+1}(x)} = \sum_{k=0}^n \frac{r_n(x_k)}{\omega'_{n+1}(x_k)(x-x_k)} \quad 8.$$

Integration of equation 8 gives:

$$\int_{-1}^{+1} r_n(x) dx = \int_{-1}^{+1} \sum_{k=0}^n \frac{\omega_{n+1}(x) r_n(x_k) dx}{\omega'_{n+1}(x_k)(x-x_k)} \quad 9.$$

Therefore:

$$\int_{-1}^{+1} P_{2n+1}(x) dx = \sum_{k=0}^n a_k P_{2n+1}(x_k) \quad 10.$$

where:

$$a_k = \int_{-1}^{+1} \frac{\omega_{n+1}(x) dx}{-1 \omega'_{n+1}(x_k)(x-x_k)} \quad 11.$$

5. If we use the Hermite interpolation formula to represent a function  $f(x)$  by a polynomial of degree  $2n+1$ , the error in the integral formula is given by:

$$e_n = \frac{f^{(2n+2)}(\xi)}{(2n+2)!} \int_{-1}^{+1} \prod_{k=0}^n (x-x_k)^2 dx \quad 12.$$

where  $-1 \leq \xi \leq +1$ .

6. There are  $n+1$  values of  $x_k$ , and hence this method of integration is called the  $n+1$  point method. For the Gaussian 2-point integral formula put  $n=1$  and then  $x_k$   $k=0,1$  are the zeros of  $P_2(x)$ , ie  $x_k$  are given by:

$$(3x^2-1)/2 = 0$$

therefore:

$$x_k = \pm 1/\sqrt{3}$$

and:

$$\omega_{n+1}(x) = (x^2 - 1/3)$$

Hence the weighting factors are:

$$\begin{aligned} a_k &= \int_{-1}^{+1} \frac{x \pm 1/\sqrt{3}}{2x} dx \\ &= 1 \end{aligned}$$

Finally the formula is:

$$\int_{-1}^{+1} f(x) dx = f\left(\frac{1}{\sqrt{3}}\right) + f\left(-\frac{1}{\sqrt{3}}\right) + \frac{f^{(4)}(\xi)}{135} \quad 13.$$

7. In general  $\int_a^b f(x) dx$  can be transformed to the form of equation 13. Furthermore the accuracy can be improved by subdividing the interval  $a,b$ . Let each subinterval have half width  $h$ , where:

$$h = (b-a)/2n$$

Then:

$$\begin{aligned} \int_a^b f(x) dx &= \sum_{k=0}^{n-1} \int_{2kh+a}^{2(k+1)h+a} f(x) dx \\ &= \sum_{k=0}^{n-1} h \int_{-1}^{+1} f(x) dx' \end{aligned}$$

where:

$$x = x'h + h(2k+1) + a$$

and so by equation 13:

$$\int_a^b f(x)dx = h \sum_{k=0}^{n-1} \left\{ f\left(a+h(2k+1/3)\right) + f\left(a+h(2k+1-1/3)\right) \right\} + \frac{h \cdot n \cdot h^4 f^{(4)}(\xi)}{135} \quad 14.$$

8. The error term in equation 14 can be written:

$$e_n = \frac{(b-a)^5 f^{(4)}(\xi)}{2^5 n^4 135}$$

Taking 2n intervals the error will be:

$$\begin{aligned} e_{2n} &= \frac{(b-a)^5 f^{(4)}(\xi)}{2^5 2^4 n^4 135} \\ &= \frac{e_n}{16} \end{aligned}$$

Put:

$$\begin{aligned} \int_a^b f(x)dx &= I_n + e_n \\ &= I_{2n} + e_{2n} \end{aligned}$$

then a closer approximation is given by:

$$\int_a^b f(x)dx = I_{2n} + (I_{2n} - I_n)/15 \quad 15.$$

9. Gauss' integral formula is not suitable to evaluate an integral of a function given in tabular form, but when the function is given as an analytic expression the method is very useful. A FORTRAN procedure is described to compute:

$$I = \int_a^b f(x)dx + \varepsilon$$

where:

$$|\varepsilon| \leq \text{tol}$$

REAL FUNCTION GAUSS\_INTEGRATION(F,A,B,TOL)

C Description:

C Integrates the function F(x) over the range (A,B), where F is a  
C real function (to be provided). The repeated two-point Gauss  
C method is used until successive approximations differ by less  
C than 15\*TOL.

C Author:

C C Richardson, ARE (Portland)

C History:

C Issue 1.0 22 July 1982  
C Mod 1.1 6 August 1985

C Modifications:

C 1.1 To adopt coding standard

C Subroutine Arguments:

\* REAL F ! (R) Function  
\* A,B ! (R) Limits  
\* Tol ! (R) Required accuracy

C Local Variables:

\* REAL P1,P2, ! Integration estimates  
\* H, ! Subinterval half width  
\* Cd,G  
INTEGER Nc ! Number of subintervals

C Main Entry Point:

Nc=8 ! Number of subintervals  
DO WHILE ((Nc .LT. 31).OR.(ABS(P2-P1) .GT. 15.\*tol))  
P1=P2 ! Save last estimate  
H=(B-A)/(2\*Nc) ! Subinterval half-width  
Cd=A-H  
G=H/1.73205081  
P2=0. ! Partial sum  
DO M=1,Nc  
Cd=Cd+H+H  
P2=P2+F(Cd-G)  
P2=P2+F(Cd+G)  
ENDDO  
P2=P2\*H ! Estimated result  
Nc=2\*Nc  
ENDDO  
GAUSS\_INTEGRATION=P2+(P2-P1)/15.  
RETURN  
END

PROGRAM GAUSS\_INTEGRATION\_TEST

```

C      Description:
C      Test Gaussian integration by computing the integral of Sin(x)
C      over the range (A,B).

C      Author:
C      C Richardson, ARE (Portland)

C      History:
C      Issue 1.0      22 July      1982

C      Local Variables:
      REAL          A,B,          !Integration interval
      P              P            !Workspace

      EXTERNAL F

C      Main Entry Point:
100   FORMAT(A)

      TYPE *, 'The integration interval A,B must be specified'
      A=ASKR('Enter value of A (Degrees)')
      B=ASKR('Enter value of B (Degrees)')

      CALL PLOT_INIT ('WINDOW=A4-V')          !Initialise graphics
      CALL CHAR_SIZE(1.5,2.0)
      CALL GRID_LIN_LIN(30.,50.,180.,200.,A,-1.,B,1.,1)
      CALL CURVE(F,A,B,1.)                   !Draw function over A,B
      CALL MOVE((A+B)/2.,-1.)                !Annotate axes
      CALL CHAR_POSN(-7.5,-2.)
      CALL PLOT_TEXT('Angle (Degrees)',15)
      CALL MOVE(A,0.)
      CALL CHAR_POSN(-4.,0.)
      CALL CHAR_ANGLE(90.)
      CALL CHAR_POSN(-3.,0.)
      CALL PLOT_TEXT('Sin(X)',6)
      CALL CHAR_ANGLE(0.)
      P=GAUSS_INTEGRATION(F,A,B,.00001)      !Calculate numerical integral
      P=P/57.29578
      CALL MOVE(A,1.)                         !Annotate graph
      CALL CHAR_POSN(0.,1.5)
      CALL PLOT_TEXT('Numeric Integral=',18)
      CALL PLOT_NUM(P,3,4)
      P=COSD(A)-COSD(B)
      CALL MOVE(A,1.)                         !Calculate analytic integral
      CALL CHAR_POSN(0.,0.5)                  !Annotate graph
      CALL PLOT_TEXT('Analytic Integral=',18)
      CALL PLOT_NUM(P,3,4)
      CALL ORIGIN(0.,0.)                      !Plot title
      CALL SCALE(1.,1.)
      CALL MOVE(30.,20.)
      CALL CHAR_SIZE(1.8,2.4)
      CALL PLOT_TEXT(
      'Fig 1. Gaussian Integration Of The Function Sin(X)',51)
      ACCEPT 100,P
      CALL PLOT_FIN
      END

      FUNCTION F(X)                          !A typical function
      F=SIND(X)
      RETURN
      END

```

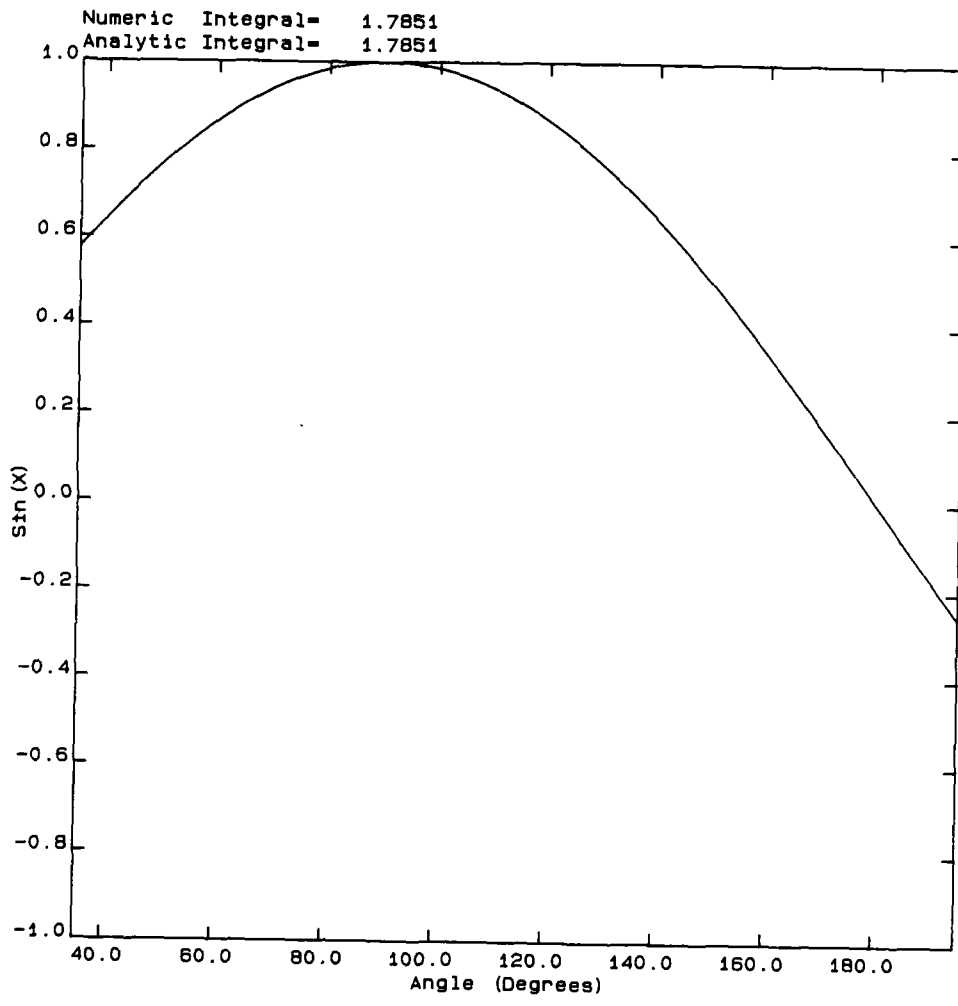


Fig 1. Gaussian Integration Of The Function Sin (X)  
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