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**A POSTERIORI ERROR ESTIMATION
"NEW" APPROACH**

by

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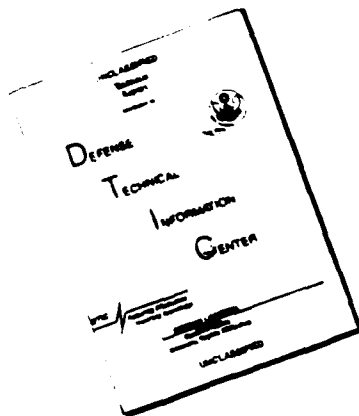
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A POSTERIORI ERROR ESTIMATION

"NEW" APPROACH

PATRICK J. RABIER

1. Preliminaries.

Let V be a real Hilbert space and $a : V \times V \rightarrow \mathbb{R}$ a continuous bilinear form. It is a more or less standard result that if a satisfies the conditions

$$(1.1a) \quad \inf_{v \neq 0} \sup_{w \neq 0} \frac{a(v, w)}{\|v\| \|w\|} \geq c > 0,$$

where c is a constant, and

$$(1.1b) \quad \{a(v, w) = 0, \forall v \in V\} \Rightarrow w = 0,$$

then there is $L \in GL(V)$, unique, such that

$$(1.2) \quad a(v, w) = (Lv, w),$$

and hence given $\ell \in V'$, there is a unique solution $u \in V$ of the problem

$$(1.3) \quad a(u, v) = \ell(v), \quad \forall v \in V.$$

Indeed, existence of $L \in \mathcal{L}(V)$ in (1.2) follows from the Riesz representation theorem, and (1.1a) easily implies that L is one-to-one with closed range. Next, from closedness of $\text{rge } L$ and the relation $\text{rge } L = (\ker L^*)^\perp$, and since condition (1.1b) implies $\ker L^* = \{0\}$, we infer that L is onto V , i.e. $L \in GL(V)$ by Banach's theorem. Next, if g represents ℓ via the Riesz representation theorem, that is, $\ell(v) = (g, v)$, $\forall v \in V$, $u = L^{-1}g$ is the unique solution of (1.3).

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Conditions (1.1a/b) include, but are not limited to, the case when a satisfies the hypothesis of the Lax-Milgram lemma

From now on, we assume that $V = H_0^1(\Omega)$ where $\Omega \subset \mathbb{R}^n$ is a bounded open subset with Lipschitz continuous boundary Γ .

Let $(\Omega_K)_{1 \leq K \leq N}$ be a collection of open subsets of Ω with Lipschitz continuous boundaries Γ_K , and such that $\Omega_K \cap \Omega_L = \emptyset$ if $K \neq L$ and $\bigcup_{K=1}^N \Omega_K = \Omega$. For convenience, we shall refer to (Ω_K) as a "partition" $\mathcal{P}$ of Ω .

We shall denote by $\mathcal{I}$ the set of pairs (K, L) with $K \neq L$ such that $\text{meas}(\Gamma_K \cap \Gamma_L) > 0$. Here, "meas" refers to the Γ_K -, or equivalently Γ_L - Lebesgue measure. Also, we set

$$\mathcal{I}_K = \{1 \leq L \leq N : (K, L) \in \mathcal{I}\}, \quad 1 \leq K \leq N,$$

and

$$\Gamma_{KL} = \Gamma_K \cap \Gamma_L, \quad \forall (K, L) \in \mathcal{I}.$$

Let $\Gamma_{\mathcal{I}}$ be the disjoint union

$$\Gamma_{\mathcal{I}} = \coprod_{(K, L) \in \mathcal{I}} \Gamma_{KL}$$

(hence, in $\Gamma_{\mathcal{I}}$, Γ_{KL} and Γ_{LK} are different although they coincide as subsets of $\mathbb{R}^n$).

We introduce the space

$$L^2(\Gamma_{\mathcal{I}}) = \prod_{(K, L) \in \mathcal{I}} L^2(\Gamma_{KL}).$$

Elements of $L^2(\Gamma_{\mathcal{I}})$ thus are collections $\lambda = (\lambda_{KL})$ with $\lambda_{KL} \in L^2(\Gamma_{KL})$. Note that the functions λ_{KL} and λ_{LK} are generally different, despite the fact that they are both defined in the same subset $\Gamma_K \cap \Gamma_L$ of $\mathbb{R}^n$.

It is clear that there is a canonical identification

$$L^2(\Gamma_{\mathcal{I}}) \simeq \prod_{K=1}^N L^2(\Gamma_K \setminus \Gamma)$$

obtained by associating with $\lambda = (\lambda_{KL}) \in L^2(\Gamma_{\mathcal{I}})$ the collection (λ_K) defined by

$$\lambda_K|_{\Gamma_{KL}} = \lambda_{KL}, \quad \forall L \in \mathcal{I}_K,$$

and vice-versa.

In future considerations, it will be convenient to use both notations (λ_{KL}) and (λ_K) for elements of $L^2(\Gamma_I)$. No confusion should arise from this since the number of indices used immediately identifies which definition of $L^2(\Gamma_I)$ is being used.

The norm of $L^2(\Gamma_I)$ is the natural one, namely

$$|\lambda|_{0,\Gamma_I} = \left(\sum_{(K,L) \in \mathcal{I}} |\lambda_{KL}|_{0,\Gamma_{KL}}^2 \right)^{1/2} = \left(\sum_{K=1}^N |\lambda_K|_{0,\Gamma \setminus \Gamma_K}^2 \right)^{1/2}.$$

We shall also consider the spaces

$$V_K = \{v_K \in H^1(\Omega_K) : v_K = 0 \text{ in } \Gamma \cap \Gamma_K\},$$

with norm induced by the norm of $H^1(\Omega_K)$, and their product

$$H_0^1(\mathcal{P}) = \prod_{K=1}^N V_K,$$

equipped with the product norm, denoted by $\|\cdot\|_{1,\mathcal{P}}$.

Elements V of $H_0^1(\mathcal{P})$ can be viewed as N -tuples (V_K) with $v_K \in V_K$ or as functions in Ω (defined almost everywhere) such that $v_K = v|_{\Omega_K} \in V_K$. Both points of view will be used later, and once again no confusion should arise from this.

A restriction map (trace) is defined:

$$v \in H_0^1(\mathcal{P}) \longmapsto (v_K|_{\Gamma_{K+1}}) \in L^2(\Gamma_I),$$

which is evidently continuous for the norm of the spaces involved.

There is a canonical embedding

$$H_0^1(\Omega) \hookrightarrow H_0^1(\mathcal{P})$$

defined by $v \longmapsto (v_K)$ where $v_K = v|_{\Omega_K}$. On the other hand, the space $L^2(\Gamma_I)$ can be split into the direct sum

$$L^2(\Gamma_I) = \Lambda_+ \oplus \Lambda_-.$$

where

$$\Lambda_+ = \{(\Gamma_{KL}) : \Gamma_{KL} = \Gamma_{LK}, \quad \forall (K, L) \in \mathcal{I}\}$$

and

$$\Lambda_- = \{(\Gamma_{KL}) : \Gamma_{KL} = -\Gamma_{LK}, \quad \forall (K, L) \in \mathcal{I}\}.$$

The following result characterizes the element of $H_0^1(\Omega)$ among the elements of $H_0^1(\mathcal{P})$:

Proposition 1.1: Let $v = (v_K) \in H_0^1(\mathcal{P})$. Then, $v \in H_0^1(\Omega)$ if and only if $(v_K)_{\Gamma_K \setminus \Gamma} \in \Lambda_+$.

Proof: If $v \in \mathcal{D}(\Omega)$ and $v_K = v|_{\Omega_K}$, it is obvious that $v_K|_{\Gamma_{KL}} = v_L|_{\Gamma_{KL}}$, i.e. $(v_K)_{\Gamma_K \setminus \Gamma} \in \Lambda_+$. By denseness of $\mathcal{D}(\Omega)$ into $H_0^1(\Omega)$, continuity of the trace $H_0^1(\mathcal{P}) \rightarrow L^2(\Gamma_{\mathcal{I}})$ and closedness of Λ_+ in $L^2(\Gamma_{\mathcal{I}})$, this relation extends to the whole space $H_0^1(\Omega)$.

Conversely, we have $H_0^1(\mathcal{P}) \hookrightarrow L^2(\Omega)$ in the obvious way, and for $\varphi \in \mathcal{D}(\Omega)$ and $v \in H_0^1(\mathcal{P})$, we have

$$\left(\frac{\partial v}{\partial x_i}, \varphi\right) = -\left(v, \frac{\partial \varphi}{\partial x_i}\right) = -\sum_{K=1}^N \int_{\Omega_K} v_K \frac{\partial \varphi}{\partial x_i} = \sum_{K=1}^N \int \frac{\partial v_K}{\partial x_i} \varphi - \sum_{K=1}^N \int_{\Gamma_K} v_K \varphi \nu_{K_i},$$

where $\nu_K = (\nu_{K1}, \dots, \nu_{Kn})$ is the outward unit normal vector along Γ_K . Since $\varphi = 0$ on Γ , we find

$$\sum_{K=1}^N \int_{\Gamma_K} v_K \varphi \nu_{K_i} = \sum_{(K,L) \in \mathcal{I}} \int_{\Gamma_{KL}} v_K \varphi \nu_{K_i},$$

and the terms $\int_{\Gamma_{KL}} v_L \varphi \nu_{L_i}$ cancel out from the hypothesis $v_K = v_L$ on Γ_{KL} since $\nu_{K_i} = -\nu_{L_i}$. It follows that

$$\left(\frac{\partial v}{\partial x_i}, \varphi\right) = \sum_{K=1}^N \int_{\Omega_K} \frac{\partial v_K}{\partial x_i} \varphi,$$

i.e. $\partial v / \partial x_i$ is represented by the $L^2(\Omega)$ function defined by $\partial v_K / \partial x_i$ in Ω_K , $1 \leq K \leq N$.

Thus, $v \in H^1(\Omega)$, and since $v = 0$ in $\bigcup_{K=1}^N (\Gamma_K \cap \Gamma) = \Gamma$, we have $v \in H_0^1(\Omega)$. $\square$

2. The space Λ_- .

Every element $\lambda \in \Lambda_-$ can be viewed as an element of $(H_0^1(\mathcal{P}))' = \prod_{K=1}^N V_K'$ via

$$\langle \lambda, w \rangle = \sum_{K=1}^N \int_{\Gamma_K \setminus \Gamma} \lambda_K w_K$$

note that

$$(2.1) \quad \langle \lambda, w \rangle = 0, \quad \forall w \in H_0^1(\Omega), \quad \forall \lambda \in \Lambda_-.$$

since

$$\sum_{K=1}^N \int_{\Gamma_K \setminus \Gamma} \lambda_K w_K = \sum_{(K,L) \in \mathcal{I}} \int_{\Gamma_{KL}} \lambda_K w_K,$$

and the terms $\int_{\Gamma_{KL}} \lambda_K w_K$ and $\int_{\Gamma_{KL}} \lambda_L w_L$ cancel out because $w_K = w_L$ on Γ_{KL} (see Proposition 1.1) and $\lambda_K = -\lambda_L$ on Γ_{KL} if $\lambda \in \Lambda_-$.

Definition 2.1: The space $\tilde{\Lambda}_-$ is the closure of Λ_- in $(H_0^1(\mathcal{P}))' = \prod_{K=1}^N V_K'$.

By definition, every $\lambda \in \tilde{\Lambda}_-$ is the limit in $(H_0^1(\mathcal{P}))'$ of a sequence $\lambda^j \in \Lambda_-$. Since $\langle \lambda^j, w \rangle = 0, \forall w \in H_0^1(\Omega)$ from (2.1), we obtain by continuity that

$$(2.2) \quad \langle \lambda, w \rangle = 0, \quad \forall \lambda \in \tilde{\Lambda}_-, \quad \forall w \in H_0^1(\Omega).$$

Let $A = (a_{ij}) \in (L^\infty(\Omega))^{n \times n}$ and let $H_{0,A}^1(\Omega)$ be the subspace

$$H_{0,A}^1(\Omega) = \{v \in H_0^1(\Omega) : \nabla \cdot A \nabla v \in L^2(\Omega)\},$$

equipped with the norm

$$\|v\|_{1,A,\Omega} = (\|v\|_{1,\Omega}^2 + \|\nabla \cdot A \nabla v\|_{0,\Omega}^2)^{1/2}.$$

Proposition 2.1: The mapping

$$v \in \mathcal{D}(\Omega) \longmapsto \left(\frac{\partial v_K}{\partial \nu_A} \right) = (A \nabla v_K \cdot \nu_K) \in \Lambda_-$$

(where $v_K = v|_{\Omega_K}$, $1 \leq K \leq N$) can be extended as a linear continuous mapping from $H_{0,A}^1(\Omega)$ into $\tilde{\Lambda}_-$.

Proof: It is plain that $(\partial v_K / \partial \nu_A) \in \bar{\Lambda}_-$ as soon as $v \in \mathcal{D}(\Omega)$. In addition, by Green's formula,

$$\int_{\Gamma_K} \frac{\partial v_K}{\partial \nu_A} w_K = \int_{\Omega_K} \nabla A v_K \cdot \nabla w_K + \int_{\Omega_K} \nabla \cdot (A \nabla v_K) w_K, \quad \forall w_K \in V_K.$$

Thus, adding up these relations, we find

$$| \left(\left(\frac{\partial v_K}{\partial \nu_A} \right), w \right) | \leq C \|v\|_{1,A,\Omega} \|w\|_{1,\mathcal{P}}, \quad \forall w \in H_0^1(\mathcal{P}),$$

where $C > 0$ is a constant depending only upon A . Hence,

$$\left\| \left(\frac{\partial v_K}{\partial \nu_A} \right) \right\|_{*,\mathcal{P}} \leq C \|v\|_{1,A,\Omega}, \quad \forall v \in \mathcal{D}(\Omega),$$

where $\|\cdot\|_{*,\mathcal{P}}$ denote the norm in $(H_0^1(\mathcal{P}))'$. That $(\partial v_K / \partial \nu_A)$ can be extended as an element of $\bar{\Lambda}_-$ for $v \in H_{0,A}^1(\Omega)$ follows from this inequality and denseness of $\mathcal{D}(\Omega)$ into $H_{0,A}^1(\Omega)$ (for the $\|\cdot\|_{1,A,\Omega}$ norm) by standard arguments. $\square$

Remark 2.1: Because $\bar{\Lambda}_- \subset (H_0^1(\mathcal{P}))' = \prod_{K=1}^N V_K'$, elements of $\bar{\Lambda}_-$ are N -tuples $\lambda = (\lambda_K)$ with $\lambda_K \in V_K'$ but unlike elements of $\bar{\Lambda}_-$, they cannot be identified with collections (λ_{KL}) for $(K, L) \in \mathcal{I}$ (since elements of V_K' are not functions, they cannot be restricted to subsets). $\square$

3. Application to error estimation in linear problems.

In addition to the coefficients $A = (a_{ij}) \in (L^\infty(\Omega))^{n \times n}$ of the previous section, we also consider $b = (b_i) \in (L^\infty(\Omega))^n$ and $c \in L^\infty(\Omega)$, and set

$$a(v, w) = \int_{\Omega} A \nabla v \cdot \nabla w + \int_{\Omega} (b \cdot \nabla v) w + \int_{\Omega} c v w, \quad \forall v, w \in H_0^1(\Omega).$$

We shall henceforth assume that $a(\cdot, \cdot)$ above satisfies the conditions (1.1a/b). Among other things, this ensures that given $f \in L^2(\Omega)$, there is a unique solution $u \in H_0^1(\Omega)$ of the problem

$$a(u, v) = \int_{\Omega} f v, \quad \forall v \in H_0^1(\Omega).$$

Observe that u solves the PDE

$$(3.1) \quad -\nabla \cdot (A \nabla u) + b \cdot \nabla u + cu = f \quad \text{in } \Omega,$$

whence $\nabla \cdot (A \nabla u) = b \cdot \nabla u + cu - f \in L^2(\Omega)$, i.e. $u \in H_{0,A}^1(\Omega)$.

For $1 \leq K \leq N$, let $a_K : V_K \times V_K \rightarrow \mathbb{R}$ be the (continuous) bilinear form

$$a_K(v_K, w_K) = \int_{\Omega_K} A \nabla v_K \cdot \nabla w_K + \int_{\Omega_K} (b \cdot \nabla v_K) w_K + \int_{\Omega_K} c v_K w_K, \quad \forall v_K, w_K \in V_K.$$

We assume that each bilinear form a_K satisfies the conditions (1.1a/b), so that given $\hat{u} \in H_0^1(\Omega)$ the problem

$$(3.2) \quad a_K(\phi_K, v_K) = \int_{\Omega_K} f v_K = a_K(\hat{u}, v) + \langle \lambda_K, v_K \rangle, \quad \forall v_K \in V_K$$

has a unique solution $\phi_K(\lambda_K) \in V_K$ for every $\lambda_K \in V'_K$. In particular, given $\lambda = (\lambda_K) \in \bar{\Lambda}_-$, there is a unique $\phi(\lambda) \in H_0^1(\mathcal{P})$ such that $\phi_K = \phi_K(\lambda_K)$ solves (3.2) for $1 \leq K \leq N$. The following theorem shows that the error $u - \hat{u}$ is characterized by a property of $\phi(\lambda)$ holding for one and only one $\lambda \in \bar{\Lambda}_-$.

Theorem 3.1: The following conditions are equivalent:

- (i) $\phi(\lambda) \in H_0^1(\Omega)$,
- (ii) $(\phi_K(\lambda_K))|_{\Gamma_{K\Gamma}} \in \Lambda_+$,
- (iii) $\phi(\lambda) = u - \hat{u}$,
- (iv) $\lambda = (\partial u_K / \partial \nu_A)$.

Proof: For (i) $\Leftrightarrow$ (ii), see Proposition 1.1. Before proving that (i) $\Leftrightarrow$ (iii) $\Leftrightarrow$ (iv), let us note that from (3.1) and Green's formula, we have

$$\int_{\Omega_K} f v_K = a_K(u, v_K) - \langle \frac{\partial u_K}{\partial \nu_A}, v_K \rangle,$$

where $\partial u_K / \partial \nu_A \in V'_K$ vanishes in $H_0^1(\Omega_K)$ (the validity of Green's formula above is due to $u \in H_{0,A}^1(\Omega)$). By substitution into (3.2), we get

$$(3.3) \quad a_K(\phi_K(\lambda_K), v_K) = a_K(u - \hat{u}, v_K) + \langle \lambda_K - \frac{\partial u_K}{\partial \nu_A}, v_K \rangle, \quad \forall v_K \in V_K,$$

and hence

$$\sum_{K=1}^N a_K(\phi_K(\lambda_K), v_K) = \sum_{K=1}^N a_K(u - \hat{u}, v_K) + \sum_{K=1}^N \langle \lambda_K - \frac{\partial u_K}{\partial \nu_A}, v_K \rangle, \quad \forall v \in H_0^1(\mathcal{P}).$$

(i) $\Rightarrow$ (iii): Choose $v \in H_0^1(\Omega)$ in the above relation. From (2.2) and $\lambda, (\partial u_K / \partial \nu_A) \in \Lambda_-$, it follows that

$$\sum_{K=1}^N a_K(\phi_K(\lambda_K), v_K) = \sum_{K=1}^N a_K(u - \hat{u}, v_K), \quad \forall v \in H_0^1(\Omega).$$

But $u - \hat{u} \in H_0^1(\Omega)$ and $\phi(\lambda) \in H_0^1(\Omega)$ from (i), so that the above equality reads

$$a(\phi(\lambda), v) = a(u - \hat{u}, v), \quad \forall v \in H_0^1(\Omega),$$

i.e. $\phi(\lambda) = u - \hat{u}$ since $a(\cdot, \cdot)$ satisfies (1.1a/b).

(iii) $\Rightarrow$ (iv): If $\phi(\lambda) = u - \hat{u}$, then $\phi_K(\lambda_K) = (u - \hat{u})|_{\Omega_K}$ and (3.3) yields

$$\langle \lambda_K - \frac{\partial u_K}{\partial \nu_A}, v_K \rangle = 0, \quad \forall v_K \in V_K, \quad 1 \leq K \leq N.$$

As a result, $\lambda_K = \partial u_K / \partial \nu_A$ (equality in V'_K), $1 \leq K \leq N$, i.e. $\lambda = (\partial u_K / \partial \nu_A)$.

(iv) $\Rightarrow$ (i): If $\lambda = (\partial u_K / \partial \nu_A)$, then $\lambda_K = \partial u_K / \partial \nu_A$, $1 \leq K \leq N$, and (3.3) shows that $\phi_K(\lambda_K)$ is characterized by

$$a_K(\phi_K(\lambda_K), v_K) = a_K(u - \hat{u}, v_K), \quad \forall v_K \in V_K.$$

But certainly $\phi_K(\lambda_K) = (u - \hat{u})|_{\Omega_K}$ satisfies the above relation, and hence is the unique solution of (3.3). This shows that $\phi(\lambda) = u - \hat{u} \in H_0^1(\Omega)$. $\square$

Corollary 3.1: The functional

$$\lambda \in \Lambda_- \longmapsto J(\lambda) = \frac{1}{2} \sum_{\substack{(K,L) \in \mathcal{I} \\ K > L}} |\phi_K(\lambda_K) - \phi_L(\lambda_L)|_{0,\Gamma_{KL}}^2$$

has the unique minimizer $\lambda = (\partial u_K / \partial v_A)$, for which $\phi(\lambda) = u - \bar{u}$.

Proof: From (iv) $\Rightarrow$ (ii) in Theorem 3.1, we have $J((\partial u_K / \partial v_A)) = 0$, and hence $\lambda = (\partial u_K / \partial v_A)$ is a minimizer of J since $J \geq 0$. This also shows that $J(\lambda) = 0$ for any minimizer of J but then $\lambda = (\partial u_K / \partial v_A)$ from (ii) $\Rightarrow$ (iv) in Theorem 3.1. Thus, $\lambda = (\partial u_K / \partial v_A)$ is the unique minimizer of J , and $\phi(\lambda) = u - \bar{u}$ by (iv) $\Rightarrow$ (iii) in Theorem 3.1. $\square$

Corollary 3.1 suggests a strategy to calculate the error $u - \bar{u}$, by minimizing the functional J in (3.4). It is important to notice that the functional J is quadratic. More specifically, denote by $\beta_K \in V_K$ the (unique) solution of

$$a_K(\beta_K, v_K) = \int_{\Omega_K} f v_K - a_K(\bar{u}, v_K), \quad \forall v_K \in V_K,$$

and let $U_K \in \mathcal{L}(V'_K, V_K)$ be defined by

$$a_K(U_K v_K^*, v_K) = (v_K^*, v_K), \quad \forall v_K^* \in V'_K, \quad \forall v_K \in V_K.$$

Then, $\phi_K(\lambda_K) = U_K \lambda_K + \beta_K$, $1 \leq K \leq N$, for $\lambda \in \Lambda_+$, and

$$J(\lambda) = \frac{1}{2} \sum_{\substack{(K,L) \in \mathcal{I} \\ K > L}} \left\{ |U_K \lambda_K - U_L \lambda_L|_{0, \Gamma_{KL}}^2 + 2 \int_{\Gamma_{KL}} (U_K \lambda_K - U_L \lambda_L)(\beta_K - \beta_L) + |\beta_K - \beta_L|_{0, \Gamma_{KL}}^2 \right\}$$

that is,

$$(3.5) \quad J(\lambda) = \frac{1}{2} \sigma(\lambda, \lambda) + \sum_{\substack{(K,L) \in \mathcal{I} \\ K > L}} \int_{\Gamma_{KL}} (U_K \lambda_K - U_L \lambda_L)(\beta_K - \beta_L) + \frac{1}{2} \sum_{\substack{(K,L) \in \mathcal{I} \\ K > L}} |\beta_K - \beta_L|_{0, \Gamma_{KL}}^2,$$

where, for $\lambda, \mu \in \Lambda_+$ we have set

$$\sigma(\lambda, \mu) = \sum_{\substack{(K,L) \in \mathcal{I} \\ K > L}} \int_{\Gamma_{KL}} (U_K \lambda_K - U_L \lambda_L)(U_K \mu_K - U_L \mu_L)$$

Lemma 3.1: The bilinear mapping σ is an inner product in $\tilde{\Lambda}_-$.

Proof: It is obvious that σ is bilinear and symmetric. That $\sigma(\lambda, \lambda) = 0 \Rightarrow \lambda = 0$ follows from (ii) $\Rightarrow$ (iii) in Theorem 3.1 for the special case when $f = 0$ (hence $u = 0$) and $\tilde{u} = 0$ in (3.2). $\square$

The norm in $\tilde{\Lambda}_-$ induced by the inner product $\sigma(\cdot, \cdot)$ will henceforth be referred to as the " σ -norm". It is easily seen that $\tilde{\Lambda}_-$ cannot be complete for the σ -norm, and hence we shall call Λ_-^σ the completion of $\tilde{\Lambda}_-$ for the σ -norm. From the trace theorems, there is a constant $C > 0$ such that

$$\sigma(\lambda, \lambda)^{1/2} \leq C \|\lambda\|_{\bullet, \mathcal{P}}, \quad \forall \lambda \in \tilde{\Lambda}_-,$$

i.e. the σ -norm is weaker than the $\|\cdot\|_{\bullet, \mathcal{P}}$ norm in $\tilde{\Lambda}_-$.

Theorem 3.2: The functional J is continuous and coercive in $\tilde{\Lambda}_-$ equipped with the σ -norm. As a result, it can be extended as a continuous and coercive quadratic functional in Λ_-^σ with the same minimum value (that is, 0). In particular, $\lambda = (\partial u_K / \partial \nu_A)$ remains the unique minimizer of J in Λ_-^σ .

Proof: Continuity and coercivity of J in $\tilde{\Lambda}_-$ for the σ norm is trivial from (3.5). That it can be extended to Λ_-^σ with the same minimum value is also trivial (using denseness of $\tilde{\Lambda}_-$ in its completion Λ_-^σ). It thus remains nonnegative and has a unique minimizer in $\tilde{\Lambda}_-$, and this minimizer must be $(\partial u_K / \partial \nu_A)$ since $J((\partial u_K / \partial \nu_A)) = 0$. $\square$

We now face the key problem in following the above approach: In practice, the minimizer $(\partial u_K / \partial \nu_A)$ of J will be obtained via minimizing sequences $\lambda^j \in \tilde{\Lambda}_-$. By denseness of $\tilde{\Lambda}_-$ in Λ_-^σ , such sequences can be chosen in Λ_- (and even in Λ_- by denseness of $\tilde{\Lambda}_-$ in Λ_-), and for each index j we obtain an element $\phi(\lambda^j) \in H_0^1(\mathcal{P})$. It is easily seen that $\phi(\lambda^j)$ need not approach $u - u$ in $H_0^1(\mathcal{P})$ as j tends to ∞ . This is related to the fact that the σ -norm is too weak to ensure continuity of the bilinear form

$$(\lambda, v) \in \Lambda_- \times H_0^1(\mathcal{P}) \longmapsto \sum_{k=1}^N (\lambda_k, v_k)$$

when $\tilde{\Lambda}_-$ is equipped with the σ -norm. Thus, in practice, minimizing the functional J using minimizing sequences (the only possible option since $(\partial u_K / \partial \nu_A)$ is of course unknown) will not necessarily provide the desired result, i.e. will not yield an approximation on $u - \tilde{u}$ in $H_0^1(\mathcal{P})$. Fortunately, this difficulty can be overcome because of the following result.

Theorem 3.3: Suppose that $u \in H^s(\Omega)$ for some $s > 3/2$. Then:

(i) There are minimizing sequences (λ^j) of J such that $\lambda^j \in \Lambda_-$ and (λ^j) is bounded in Λ_- (that is, bounded in $L^2(\Gamma_T)$).

(ii) If (λ^j) is a minimizing sequence of J such that $\lambda^j \in \Lambda_-$ and (λ^j) is bounded in Λ_- , we have

$$\lim_{j \rightarrow \infty} \|\phi(\lambda^j) - (u - \tilde{u})\|_{1, \mathcal{P}} = 0.$$

Proof: If $u \in H^s(\Omega)$ for $s > 3/2$, then $\partial u_K / \partial \nu_A \in H^{s-\frac{1}{2}}(\Gamma_K) \subset L^2(\Gamma_K)$, $1 \leq K \leq N$. Thus, in particular, $(\partial u_K / \partial \nu_A) \in L^2(\Gamma_T)$. Also, if $u \in C^\infty(\bar{\Omega})$, it is obvious that $(\partial u_K / \partial \nu_A) \in \Lambda_-$, and this relation remains valid for $u \in H^s(\Omega)$ ($s > 3/2$) by denseness of $C^\infty(\bar{\Omega})$ into $H^s(\Omega)$, continuity of the mapping $v \in H^s(\Omega) \mapsto (\partial v_K / \partial \nu_A) \in L^2(\Gamma_T)$ and closedness of Λ_- in $L^2(\Gamma_T)$. Existence of minimizing sequences (λ^j) with $\lambda^j \in \Lambda_-$ and (λ^j) bounded in Λ_- follows at once from this result (choose e.g. $\lambda^j = (\partial u_K / \partial \nu_A)$, $\forall j$).

Next, let (λ^j) be any minimizing sequence of J such that $\lambda^j \in \Lambda_-$ and (λ^j) is bounded in Λ_- . By compactness of the embedding $L^2(\Gamma_K \setminus \Gamma) \hookrightarrow V'_K$, there is $\lambda \in (H_0^1(\mathcal{P}))' = \prod_{K=1}^N V'_K$ and a subsequence (λ^{j_k}) such that $\lim_{k \rightarrow \infty} \|\lambda^{j_k} - \lambda\|_{*, \mathcal{P}} = 0$. Thus, $\lambda \in \tilde{\Lambda}_-$ by definition of the space $\tilde{\Lambda}_-$. Since the functional J is continuous for the σ -norm (see Theorem 3.2), hence for the stronger $\|\cdot\|_{*, \mathcal{P}}$ norm, we have $J(\lambda) = \lim_{k \rightarrow \infty} J(\lambda^{j_k})$, so that λ minimizes J . It follows that $\lambda = (\partial u_K / \partial \nu_A)$ (see Theorem 3.2).

The above reveals that $(\partial u_K / \partial \nu_A)$ is the unique cluster point of the sequence (λ^j) in Λ_- , so that the whole sequence (λ^j) converges to $(\partial u_K / \partial \nu_A)$ in $\tilde{\Lambda}_-$. This amounts to saying that λ_K^j tends to $\partial u_K / \partial \nu_A$ in V'_K for every $1 \leq K \leq N$. Now, from (3.3) we have

$$a_K(\phi_K(\lambda_K^j) - (u - \tilde{u}), v_K) \leq \|\lambda_K^j - \frac{\partial u_K}{\partial \nu_A}\|_{*, \Omega_K} \|v_K\|_{1, \Omega_K}, \quad \forall v_K \in V_K.$$

Taking the supremum over $v_K \in V_K$, $\|v_K\|_{1,\Omega_K} \leq 1$, and using the fact that $a_K(\cdot, \cdot)$ satisfies the conditions (1.1a/b), we get

$$\|\phi_K(\lambda_K^j) - (u - \hat{u})\|_{1,\Omega_K} \leq C_K \|\lambda_K^j - \frac{\partial u_K}{\partial \nu_A}\|_{*,\Omega_K},$$

where $C_K > 0$ is a constant independent of j . Thus,

$$\left(\sum_{K=1}^N \|\phi_K(\lambda_K^j) - (u - \hat{u})\|_{1,\Omega_K}^2 \right)^{1/2} \leq C \left(\sum_{K=1}^N \|\lambda_K^j - \frac{\partial u_K}{\partial \nu_A}\|_{*,\Omega_K}^2 \right)^{1/2},$$

with $C = \max_{1 \leq K \leq N} C_K$, and the right-hand side is just $C \|\lambda^j - \left(\frac{\partial u_K}{\partial \nu_A} \right)\|_{*,\mathcal{P}}$ and hence tends to 0 as j tends to ∞ as noted earlier in the proof. $\square$

By a method of proof similar to that of Theorem 3.3, we obtain the following result without any extra assumption of regularity for the solution u :

Theorem 3.4: (i) There are minimizing sequences (λ^j) of J with $\lambda^j \in \bar{\Lambda}_-$ and (λ^j) bounded in $\bar{\Lambda}_-$.

(ii) If (λ^j) is a minimizing sequence of J such that $\lambda^j \in \bar{\Omega}$ and (λ^j) is bounded in $\bar{\Omega}$, we have

$$\lim_{j \rightarrow \infty} \|\phi(\lambda^j) - (u - \hat{u})\|_{r,\mathcal{P}} = 0,$$

for every $0 \leq r < 1$, where $\|\cdot\|_{r,\mathcal{P}}$ is the product norm of the space $H^r(\mathcal{P}) = \prod_{K=1}^N H^r(\Omega_K)$.

Proof: (i) is trivial by considering the constant sequence $(\partial u_K / \partial \nu_A)$. (ii) Let (λ^j) be a minimizing sequence in $\bar{\Lambda}_-$ which is bounded in $\bar{\Lambda}_-$, and let λ be a cluster point of (λ^j) for the weak topology of Λ_- (Λ_- is a closed subspace of the Hilbert space $\prod_{K=1}^N V'_K$). If (λ^{j_k}) is a subsequence tending to λ , we still have $J(\lambda) = \lim_{k \rightarrow \infty} J(\lambda^{j_k}) = 0$ because J is convex and continuous for the $\|\cdot\|_{*,\mathcal{P}}$ norm, hence weakly lower semicontinuous. Thus, once again, $\lambda = (\partial u_K / \partial \nu_A)$ and the whole sequence (λ^j) tends weakly to $(\partial u_K / \partial \nu_A)$. At this point, note that together with this result, (3.3) implies that $\phi_K(\lambda_K^j)$ tends weakly to $(u - \hat{u})|_{\Omega_K}$ in V_K . If $L_K \in GL(V_K)$ is defined by

$$a_K(v_K, w_K) = (L_K, v_K, w_K), \quad \forall v_K, w_K \in V_K,$$

where $(\cdot, \cdot)$ denotes the inner product of $H^1(\Omega_K)$, we have $\phi_K(\lambda_K^j) - (u - \hat{u})|_{\Omega_K} = L_K g_K^j$ where $g_K^j \in V_K$ is defined by

$$(g_K^j, v_K) = (\lambda_K^j - \frac{\partial u_K}{\partial \nu_A}, v_K), \quad \forall v_K \in V_K$$

That $g_K^j \rightarrow 0$ in V_K follows from $\lambda_K^j - \partial u_K / \partial \nu_A \rightarrow 0$ in V_K' and hence $\phi_K(\lambda^j) \rightarrow (u - \hat{u})|_{\Omega_K}$ by continuity of L_K .

The theorem now follows from compactness of the embedding $H^r(\Omega_K) \hookrightarrow H^1(\Omega_K)$ for $0 \leq r < 1$, $1 \leq K \leq N$. $\square$

The practical aspects of Theorems 3.3 and 3.4 is captured by the following corollary.

Corollary 3.2: Let $B \subset \bar{\Lambda}_-$ be any closed ball such that $(\partial u_K / \partial \nu_A) \in B$. Then, B is closed in $\bar{\Lambda}_-$, $\inf_{\lambda \in B} J(\lambda) = \inf_{\lambda \in \bar{\Lambda}_-} J(\lambda)$ and if $\lambda^j \in B$ is a minimizing sequence of $J|_B$, we have

$$\lim_{j \rightarrow \infty} \|\phi(\lambda^j) - (u - \hat{u})\|_{r, \mathcal{P}} = 0,$$

for every $0 \leq r < 1$.

Furthermore, if $u \in H^s(\Omega)$ for some $s > 3/2$ and $B \subset \Lambda_-$ is any closed ball such that $(\partial u_K / \partial \nu_A) \in B$, then B is closed in Λ_- , $\inf_{\lambda \in B} J(\lambda) = \inf_{\lambda \in \Lambda_-} J(\lambda)$ and if $\lambda^j \in B$ is a minimizing sequence of $J|_B$, we have

$$\lim_{j \rightarrow \infty} \|\phi(\lambda^j) - (u - \hat{u})\|_{1, \mathcal{P}} = 0.$$

Proof: That B is closed in $\bar{\Lambda}_-$ follows from weak compactness of B in its ambient space: If $\lambda^j \in B$ and $\lambda^j \rightarrow \lambda \in \bar{\Lambda}_-$ in $\bar{\Lambda}_-$, let $\mu \in B$ be such that $\lambda^{j^*} \rightarrow \mu$ in $\bar{\Lambda}_-$ or Λ_- . In both cases, this implies $\lambda^{j^*} \rightarrow \mu$ in $\bar{\Lambda}_-$ since the embeddings $\Lambda_- \hookrightarrow \bar{\Lambda}_- \hookrightarrow \bar{\Lambda}_-$ are continuous, whence $\mu = \lambda$ and $\lambda \in B$. That the infimum of J is the same in B and in the whole space $\bar{\Lambda}_-$ is trivial from $(\partial u_K / \partial \nu) \in B$ being the unique minimizer of J in $\bar{\Lambda}_-$. Convergence of $\phi(\lambda^j)$ to $u - \hat{u}$ follows from Theorems 3.3 and 3.4. $\square$

In practical applications, the hypothesis that some ball B containing $(\partial u_K / \partial \nu_A)$ is known is not a severe limitation since some useful information can be derived from the approximate solution $\hat{u}$. See Section 4.

4. Practical Aspects.

In practice, the approximate solution $\hat{u}$ will be a finite element approximation $u^h \in V^h$ where V^h is a finite element subspace of $H_0^1(\Omega)$ and the partition $\mathcal{P}$ corresponds to the partition of Ω into elements. It is certainly not restrictive to assume that u^h is a "reasonable" approximation of u , as opposed to a completely random element of V^h , and hence that despite the fact that $\|u - u^h\|_{1,\Omega}$ may not be small, or small enough, still the derivative $(\partial u_K^h / \partial \nu_A)$ gives some idea of where in $\bar{\Lambda}_-$ (or Λ_- if $u \in H^s(\Omega)$, $s > 3/2$) $(\partial u_K / \partial \nu_A)$ is. One problem is that, in general, $(\partial u_K^h / \partial \nu_A) \notin \Lambda_-$, but this is easily remedied by replacing $(\partial u_K^h / \partial \nu_A)$ by say, $(\frac{\partial u_K^h}{\partial \nu_A})_{1/2} \equiv (\frac{1}{2}(\partial u_K^h / \partial \nu_A - \partial_L^h / \partial \nu_A))_{(K,L) \in \mathcal{I}}$. Other weighted averages, as suggested in [] can also be used.

The ball B of Corollary 3.2 can be chosen as any ball with center $(\partial u / \partial \nu_A)_{1/2}$ and arbitrary radius $R > 0$. Because of denseness of Λ_- in $\bar{\Lambda}_-$ and $\bar{\Lambda}_-$, finite-dimensional approximations of the space Λ_-^c can be obtained by choosing a scale Λ_-^j of finite-dimensional subspaces of Λ_- . One possible choice is given by collections $\lambda = (\lambda_K)$ such that λ_K is a polynomial of degree $\leq j$ on each face of Ω_K not lying on the boundary of Ω . It should be kept in mind that membership to Λ_- requires the condition $\lambda_{K|_{\Gamma_{KL}}} = -\lambda_{L|_{\Gamma_{KL}}}$, and hence λ_K and λ_L cannot be chosen independently. Because no continuity condition is required of λ_K at the intersection of two faces, bases for such spaces are easily found. For instance, if $j = 0$, a basis is given by the collections (λ_{KL}) where $\lambda_{KL} = 0$ if $(K, L) \neq (K_0, L_0)$ where $(K_0, L_0) \in \mathcal{I}$ satisfies $K_0 > L_0$, $\lambda_{K_0 L_0} = 1$, $\lambda_{L_0 K_0} = -1$, letting (K_0, L_0) run over all such pairs. It should be clear how this procedure can be extended to obtain bases for arbitrary polynomial degree j .

One may then define λ^j to be the minimizer of J in $B \cap \Lambda_-^j$, a closed convex subset of Λ_-^j . The sequence (λ^j) is a minimizing sequence for J in B , and hence the conclusion of Corollary 3.2 regarding convergence of $\phi(\lambda^j)$ to $u - u^h (= u - \hat{u}$ here) applies. Rather than minimizing J in $B \cap \Lambda_-^j \rightarrow 0$ a constrained problem - it seems advisable to minimize J in Λ^j (a linear problem) and check whether this minimizer is in B , and modify the choice of the minimizer only if this is not the case (i.e. the minimizer is unreasonably far from $(\partial u_K^h / \partial \nu_A)_{1/2}$).

Naturally, replacing Λ_- by a finite dimensional approximation Λ_-^j is not enough, since

$\phi(\lambda)$ cannot be calculated exactly. However, since $\phi(\lambda) = (\phi_K(\lambda_K))$ is obtained by solving independent local problems, numerical approximations can be obtained at a low cost with high accuracy. In other words, the error between $\phi(\lambda)$ and its numerical approximation may be considered negligible when compared with $\|u - u^h\|_{1,\Omega}$, and hence the convergence result of Corollary 3.2 may be used safely with $\phi(\lambda)$ replaced by its numerical approximation.

Remark 4.1: When the spaces Λ_-^j are those previously described, i.e. their elements are collections of polynomials with degree $\leq j$ on the interfaces, it is desirable that the space chosen for the approximation of $\phi_K(\lambda_K)$ when $\lambda = (\lambda_K) \in \Lambda_-^j$, contains the polynomials of degree $\leq j + 1$ in Ω_K . Indeed, λ_K is used to obtain an approximation of $\partial u_K / \partial \nu_A$ whereas $\phi_K(\lambda_K)$ represents an approximation of $(u - u^h)|_{\Omega_K}$, and hence polynomials with degree at least $j + 1$ should be used to approximate $\phi_K(\lambda_K)$ for consistency (assuming $A = (a_{ij})$ essentially constant on each element). The above considerations also show that $j + 1$ should be at least equal to the degree of the polynomials used for the calculation of u^h , which comes as no surprise. $\square$

5. Nonlinear problems.

Let $a(\cdot, \cdot), a_K(\cdot, \cdot)$ be the same bilinear forms as in Section 3, and let $F : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ be a mapping such that $F(\cdot, \cdot)$ is of class C^1 for almost all $x \in \Omega$ and $F(\cdot, y)$ is measurable for every $y \in \mathbb{R}$. We also assume that there are constants $\beta \geq 0, \gamma \geq 0$ such that

$$|D_y F(x, y)| \leq \beta + \gamma |y|^{p-2}$$

for almost all $x \in \Omega$ and every $y \in \mathbb{R}$, where $p > 2$ is a real number satisfying $p \leq \frac{2n}{n-2}$ if $n > 2$. This implies that the mapping

$$\tilde{F} : u \in L^p(\Omega) \Rightarrow F(u) \in L^{p^*}(\Omega) \quad (p^* = p/(p-1))$$

defined by $\tilde{F}(u)(x) = F(x, u(x))$ is of class C^1 with derivative

$$D\tilde{F}(u)h = D_y F(x, u(x))h(x).$$

It then follows from Taylor's formula that

$$|\tilde{F}(u) - \tilde{F}(v)|_{0,p^*,\Omega} \leq C((\text{meas } \Omega)^{\frac{p-2}{p}} + \gamma(|u|_{0,p,\Omega}^{p-2} + |v|_{0,p,\Omega}^{p-2}))|u - v|_{0,p,\Omega},$$

for every pair $(u, v) \in (L^p(\Omega))^2$, where $C > 0$ is a constant independent of u and v .

This shows that if $u^h \in V^h$ is a finite element approximation of $u \in H_0^1(\Omega)$ such that

$$\lim_{h \rightarrow 0} \|u - u^h\|_{1,\Omega} = 0, \quad \lim_{h \rightarrow 0} \frac{|u - u^h|_{0,p,\Omega}}{\|u - u^h\|_{1,\Omega}} = 0,$$

we have

$$(5.1) \quad |\tilde{F}(u) - \tilde{F}(u^h)|_{0,p^*,\Omega} \leq \epsilon(h) \|u - u^h\|_{1,\Omega},$$

with $\lim_{h \rightarrow 0} \epsilon(h) = 0$.

Suppose now that u solves the problem

$$a(u, v) + \int_{\Omega} \tilde{F}(u)v = \int_{\Omega} f v, \quad \forall v \in H_0^1(\Omega),$$

i.e. $u \in H_0^1(\Omega)$ and

$$-\nabla \cdot (A \nabla u) + b \cdot \nabla u + cu + \tilde{F}(u) = f \quad \text{in } \Omega.$$

In analogy with what was done in Section 3, let $\lambda \in \tilde{\Lambda}_-$ and solve, for $1 \leq K \leq N$,

$$\begin{cases} a_K(\phi_K(\lambda_K), v_K) = \int_{\Omega_K} f v_K - a_K(u^h, v_K) - \int_{\Omega_K} F(u^h) v_K + \langle \lambda_K, v_K \rangle \\ \forall v_K \in V \end{cases}$$

that is,

$$(5.2) \quad \begin{cases} a_K(\phi_K(\lambda_K), v_K) = a_K(u - u^h, v_K) + \int_{\Omega_K} (\tilde{F}(u) - \tilde{F}(u^h)) v_K + \langle \lambda_K - \frac{\partial u_K}{\partial \nu_A}, v_K \rangle \\ \forall v_K \in V. \end{cases}$$

By the method of proof of Theorem 3.1, it is easily seen that the only case when $\phi(\lambda) = (\phi_K(\lambda_K)) \in H_0^1(\Omega)$ is when $\phi(\lambda)$ coincides with the solution $\psi^h \in H_0^1(\Omega)$ (not ψ^h) of

$$(5.3) \quad a(\psi^h, v) = a((u - u^h), v) + \int_{\Omega} (\tilde{F}(u) - \tilde{F}(u^h))v, \quad \forall v \in H_0^1(\Omega),$$

and that if so, $\lambda_K = \partial(\psi^h + u^h)_K / \partial \nu_A$, $1 \leq K \leq N$. In fact, in terms of ψ^h above, (5.2) reads

$$\begin{cases} a_K(\phi_K(\lambda_K), v_K) = a_K(\psi^h, v_K) + \langle \lambda_K - \frac{\partial(\psi^h + u^h)_K}{\partial \nu_A}, v_K \rangle \\ \forall v_K \in V_K. \end{cases}$$

This relation can be used to show that if (λ^j) is a minimizing sequence of the functional J of Section 3 (which now has unique minimizer $(\partial(\psi^h + u^h)_K / \partial \nu_A)$) and if (λ^j) is bounded in Λ_- , then

$$(5.4) \quad \lim_{j \rightarrow \infty} \|\phi(\lambda^j) - \psi^h\|_{1, \mathcal{P}} = 0.$$

(And if (λ^j) is only bounded in $\bar{\Lambda}_-$,

$$\lim_{j \rightarrow \infty} \|\phi(\lambda^j) - \psi^h\|_{r, \mathcal{P}} = 0, \quad \forall 0 \leq r < 1.)$$

To obtain an estimate for $\|\phi(\lambda^j) - (u - u^h)\|_{1, \mathcal{P}}$, write

$$(5.5) \quad \|\phi(\lambda^j) - (u - u^h)\|_{1, \mathcal{P}} \leq \|\phi(\lambda^j) - \psi^h\|_{1, \mathcal{P}} + \|(u - u^h) - \psi^h\|_{1, \Omega}.$$

From (5.3),

$$a(\psi^h - (u - u^h), v) = \int_{\Omega} (\tilde{F}(u) - \tilde{F}(u^h))v.$$

Taking the supremum over $v \in H_0^1(\Omega)$, $\|v\|_{1, \Omega} \leq 1$ and using the fact that $a(\cdot, \cdot)$ satisfies (1.1a/b), we get

$$a\|\psi^h - (u - u^h)\|_{1, \Omega} \leq \sup_{\|v\|_{1, \Omega} \leq 1} \int_{\Omega} (\tilde{F}(u) - \tilde{F}(u^h))v,$$

where $c > 0$ is a constant independent of u and h . Next, using $|\int_{\Omega}(\tilde{F}(u) - \tilde{F}(u^h))v| \leq |\tilde{F}(u) - \tilde{F}(u^h)|_{0,p^*,\Omega} \|v\|_{0,p,\Omega}$ and continuity of the embedding $H_0^1(\Omega) \hookrightarrow L^p(\Omega)$, we obtain

$$\|\psi^h - (u - u^h)\|_{1,\Omega} \leq C|\tilde{F}(u) - \tilde{F}(u^h)|_{0,p^*,\Omega},$$

where $C > 0$ is a constant independent of u and h . Finally, using (5.1) we see that

$$\|\psi^h - (u - u^h)\|_{1,\Omega} \leq C\epsilon(h)\|u - u^h\|_{1,\Omega}.$$

Substituting into (5.5), we get

$$\|\phi(\lambda^j) - (u - u^h)\|_{1,p} \leq \|\psi(\lambda^j) - \psi^h\|_{1,p} + C\epsilon(h)\|u - u^h\|_{1,\Omega}.$$

and, in particular, if (5.4) holds:

$$(5.6) \quad \lim_{j \rightarrow \infty} \|\phi(\lambda^j) - (u - u^h)\|_{1,p} \leq C\epsilon(h)\|u - u^h\|_{1,\Omega},$$

i.e. $\|\psi(\lambda^j) - (u - u^h)\|_{1,p}$ becomes negligible with respect to $\|u - u^h\|_{1,\Omega}$ when $\phi(\lambda^j)$ is a good enough approximation of ψ^h because $\lim_{h \rightarrow 0} \epsilon(h) = 0$.

Remark 5.1: From (5.6), it also follows that $u^h + \phi(\lambda^j)$ is a better (enhanced) approximation of u than u^h . Interestingly, this enhanced solution is obtained by solving only *linear* problems (calculation of $\phi(\lambda^j)$). $\square$

