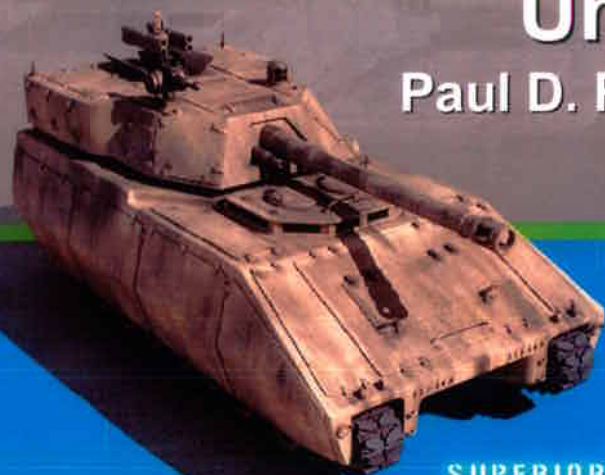


16967



Army Support to Future Combat Systems Unmanned Ground Vehicles

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TARDEC – Warren, MI



AUVSI Unmanned Systems Program Review

7 February 2007

SUPERIOR TECHNOLOGY



FOR A



SUPERIOR ARMY



TARDEC
U.S. ARMY TANK AUTOMOTIVE RESEARCH, DEVELOPMENT AND ENGINEERING CENTER

RDECOM

TACOM
The Soldier and Ground Systems
Life Cycle Management Command

16967

Report Documentation Page				Form Approved OMB No. 0704-0188	
Public reporting burden for the collection of information is estimated to average 1 hour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing the collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing this burden, to Washington Headquarters Services, Directorate for Information Operations and Reports, 1215 Jefferson Davis Highway, Suite 1204, Arlington VA 22202-4302. Respondents should be aware that notwithstanding any other provision of law, no person shall be subject to a penalty for failing to comply with a collection of information if it does not display a currently valid OMB control number.					
1. REPORT DATE 07 FEB 2007		2. REPORT TYPE N/A		3. DATES COVERED -	
4. TITLE AND SUBTITLE Army Support to Future Combat Systems Unmanned Ground Vehicles				5a. CONTRACT NUMBER	
				5b. GRANT NUMBER	
				5c. PROGRAM ELEMENT NUMBER	
6. AUTHOR(S) Rogers, Paul D.				5d. PROJECT NUMBER	
				5e. TASK NUMBER	
				5f. WORK UNIT NUMBER	
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) US ARMY TACOM 6501 E 11 Mile Road, Warren, MI 48397-5000				8. PERFORMING ORGANIZATION REPORT NUMBER 16967	
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES)				10. SPONSOR/MONITOR'S ACRONYM(S) TACOM TARDEC	
				11. SPONSOR/MONITOR'S REPORT NUMBER(S) 16967	
12. DISTRIBUTION/AVAILABILITY STATEMENT Approved for public release, distribution unlimited					
13. SUPPLEMENTARY NOTES The original document contains color images.					
14. ABSTRACT					
15. SUBJECT TERMS					
16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT SAR	18. NUMBER OF PAGES 12	19a. NAME OF RESPONSIBLE PERSON
a. REPORT unclassified	b. ABSTRACT unclassified	c. THIS PAGE unclassified			



Army Support to FCS UGV's

- *Unmanned systems concept of operations in the future force*
- *Technology challenges to achieve FCS end state*
- *Priorities driving S&T investment*
- *Bridging the gap between current and desired performance capabilities*
- *Joint Center - Unmanned Ground Vehicles (JC-UGV) for development and transition of robotic ground vehicle technologies*

Future Unmanned Systems

The Future: Fully networked near-autonomous systems working hand in hand with Soldiers

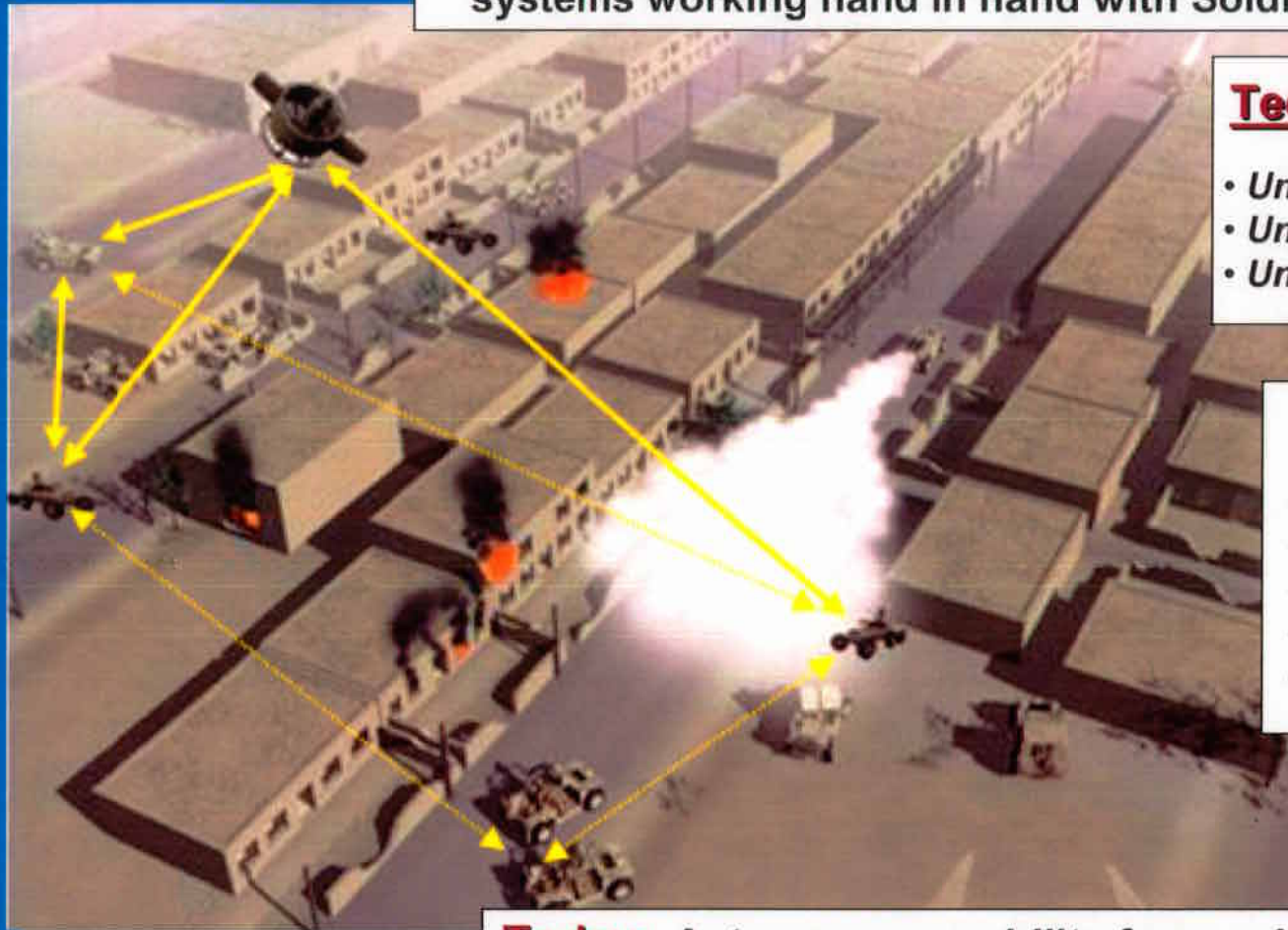
Technologies Covering

- *Unmanned Air Vehicles*
- *Unmanned Ground Vehicles*
- *Unattended Ground Sensors*

Core Technologies

- *Perception*
- *Intelligence*
- *Command & Control*
- *Platforms*
- *Safety*

Today: Autonomous mobility from point A to Point B in static environments



Solving Tomorrow's Challenges Today

Teleoperation

Protection

Safe Operations

Bandwidth

Power & Energy

Planning

Classification

Affordability

Latency

Convoy

Weaponization

Behaviors

Sensing

OCU

Mobility

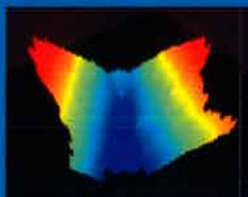
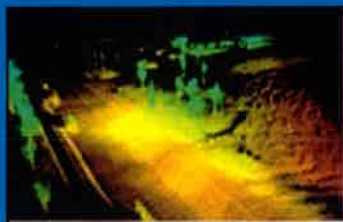
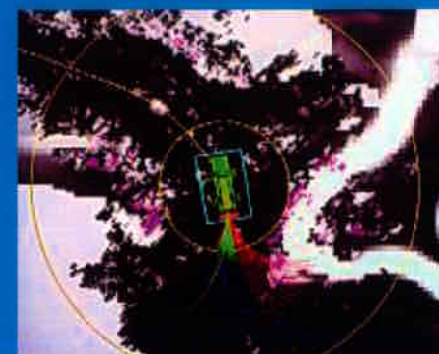
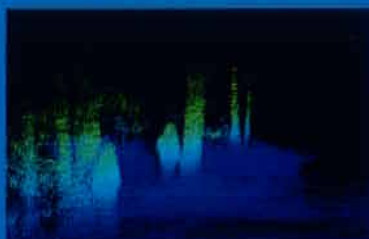
Resolution

Interoperability

Payloads

Army S&T Priorities for FCS Threshold Requirements

Intelligence/Tactical Behaviors



- Threat response/self security
- Tactical behaviors
- Formations/leader-follower

UGV Control for Overall System Effectiveness



- Warfighter machine interface
- Battle command integration
- Network constraints
- Weaponization

Safe Operations in Dynamic Environments



- Vehicle safety
- 360° Awareness

Platform Mobility Maturation



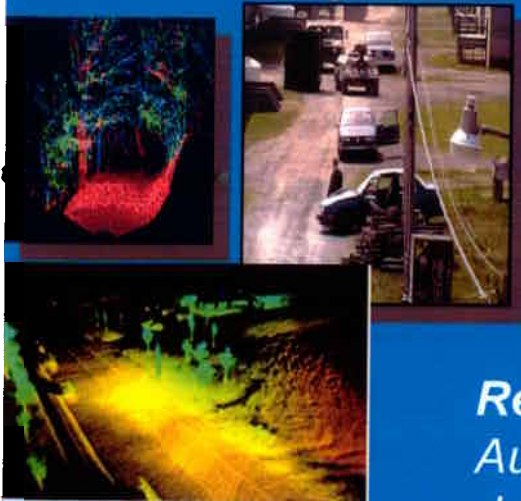
- SWaP Constraints
- Mobility enhancements
- Endurance

Intelligence/Tactical Behaviors

Current Performance

- Point A to Point B autonomous navigation using a priori terrain info and local sensing for driving and situational awareness
- S&T progressing intelligent tactical behaviors in realistic scenarios
 - ARL Robotics Collaborative Technology Alliance
 - TARDEC/AMRDEC Robotic Collaboration ATO
 - TARDEC/ARL Near Autonomous Unmanned Systems ATO

Perception and World Modeling



Deliberative and reactive planning



Layered detection and response



Required Performance

Autonomous, yet Soldier-like navigational decision making, threat detection and response, and collaborative behaviors to achieve a military objective

Formation control





Safe Operations in Dynamic Environments

Current Performance

- Autonomous maneuver in complex terrain with stationary obstacles
- S&T progressing autonomous navigation in realistic scenarios
 - ARL Robotics Collaborative Technology Alliance
 - TARDEC Robotic Collaboration ATO
 - DARPA Urban Challenge



Data collections with moving obstacles



Pedestrian Detection/Avoidance

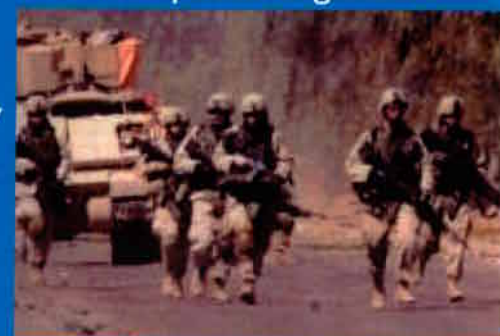


Understanding dynamic environments for reactive planning



Required Performance

Autonomous maneuver in close proximity to pedestrians and vehicles to enable effective and safe Soldier robot teaming



UGV Control Integration (UCI) Overall System Effectiveness



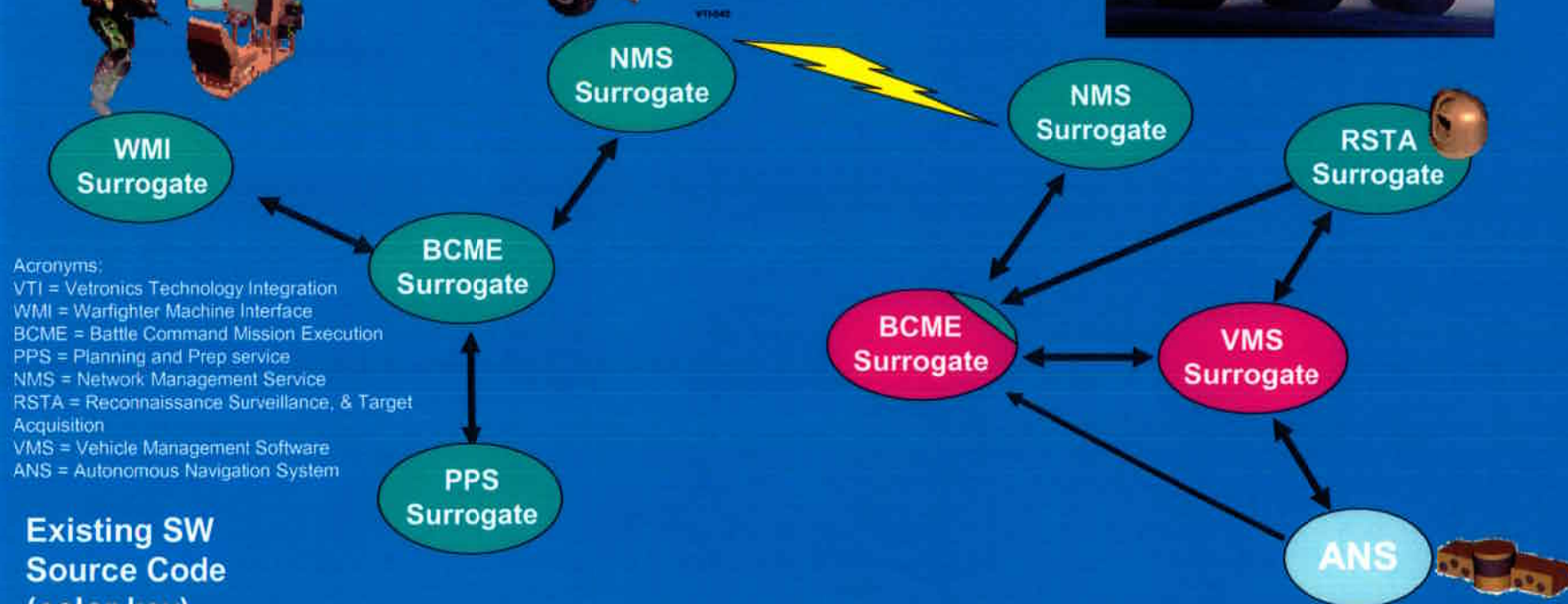
MGV Crewmen



TARDEC
Stryker



DARPA
Crusher 1.0



Existing SW
Source Code
(color key)



*Existing Operational Codes are Modified to enable
FCS Representative Interfaces to be Monitored for Performance In
UGV Functional Testing*

Platform Mobility Maturation

Crusher 2.0 – Armed Robotic Vehicle



Crusher 1.0
Baseline Design

ARV SFR
Guidance

FCS ANS
Hardware/Software

UCI
Hardware/Software



System Integration Team

Army S&T
FCS LSI
DARPA
Industry

Key Tasks:
Complete Crusher2.0 Design
Fabricate Crusher 2.0
Integrate UCI HW/SW
Integrate ICS, Soscoe2.5, BC
System Shakeout

Crusher 2.0

This concept leverages:

- Army S&T mobility expertise/investment
- FCS/ARV SFR
- DARPA UPI lessons learned
- Industry expertise

Weight = 9.31T including FCS payload allocations
98" max width, 97" max height, 172" max length
Speed = 80kph at weight on road, 45kph x-country
400km range/70 gal diesel fuel
Acceleration (0-48kph, 0% grade, 49° C) – 10.5s





Joint Center for UGVs (JC-UGV)

Mission and Focus

Partner with universities to establish robotics curriculums and build expertise in military ground robotics to meet customer needs

University Outreach

Partnering with consortiums and national industrial base to develop and transition cutting-edge unmanned vehicle technologies to the Warfighter

Industry Partnering

Congressional Language

The budget request included \$110.0 million in PE 63005A, for combat vehicle and automotive advanced technology. Under this account, the Army pursues survivability and mobility, communications, energy and power, and **autonomous technology improvements for manned and unmanned ground systems**. The committee recommends an increase of \$35.0 million in PE 63005A for acceleration of research in all of these areas, and \$10.0 million for **unmanned ground vehicle prototype research to promote near-term transition of robotic ground vehicle technologies**.

Life Cycle Support

Partner with TACOM LCMC and RS JPO for total lifecycle decision and systems engineering support for the development and sustainment of robotics technologies

Government Research

TARDEC, the JC-UGV, RDECOM and OGA labs developing applied technologies to deliver the best possible solution to the Soldier

JC-UGV

R&D, Acquisition and Sustainment



Unmanned Systems Community



JC-UGV Collocation With the TACOM LCMC, RS JPO and TARDEC Fosters Technology Transfers Between Manned and Unmanned Systems

Manned Systems Community



Enabling Technologies

- Small UGV Prime Power
- UGV Armor and active protection
- Signature reduction
- Active suspensions
- Band track
- Power Mgmt
- Alternative power

T
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- Drivers' assistant
- Indirect vision driving
- Enhanced SA
- Auto NAV
- Tactical behaviors
- Reduced logistics
- Reduced human threat

JC-UGV Coordination of TACOM/TARDEC Core Capabilities

Power and Energy

Fuel Cells
Pulse Power
Hybrid Electric
Intelligent Power Management
Batteries

FY06 >\$100M
Manned

Survivability

Signature Management
Active Protection
Lightweight Multi-Functional Armors
Landmine Protection
Laser Vision/sensor Protection

Mobility

Engines
Transmissions
Suspension
Tracks/Wheels
Vehicle Structures

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Intelligent Systems

Perception
Tele-operation
Autonomous Navigation & Intelligence
Human-Robot Interaction and Control
Actuator Kits

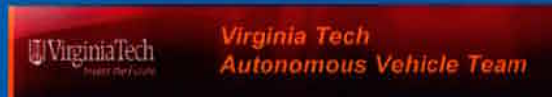
FY 06 >\$20M
Unmanned



Partnering Opportunities to Deliver Technology to the Warfighter

University Outreach

- Establish robotics curriculums to build expertise in military robotics
- Fund long term and quick reaction technology development efforts focused on transitional solutions to material developers
- Foster individual efforts at local, state and national universities using various mechanisms



Industry

- Maximize use of regional capabilities in automotive and defense based technologies.
- Exchange ideas and invest in technology development through existing CRADAs and contracts.



Small Business

- Utilize SBIR and STTR programs to allow small high-tech U.S. Businesses and academia the opportunity to provide innovative R&D solutions to critical DoD needs.
- Propose new SBIR topics and Invest in existing SBIR enhancements/plus-ups to companies developing unmanned ground vehicle technologies

- Intelligent Mobility
- Innovative Control
- Adaptive Payloads
- Advanced Sensors
- Intrinsic Mobility



Forging relationships with leading national institutions