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14. ABSTRACT The mass, velocity distribution, droplet size and distribution of liquid spray has a primary effect on the combustion heat release process. This heat release process then affects emissions like Nitrogen Oxides (NO _x) and Carbon Monoxide (CO). Computational Fluid Dynamics gives the engineer insight into these processes, but various setup options exist (number of droplet groups, initial droplet temperature) for spray initial conditions. This paper studies these spray initial condition options using the National Combustion Code (NCC) on a single swirler Lean Direct Injection (LDI) flame tube. Using laminar finite rate chemistry, comparisons are made against experimental data for velocity measurements, temperature, and emissions (NO _x , CO).					
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The Effect of Spray Initial Conditions on Heat Release and Emissions in LDI CFD Calculations

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The mass, velocity distribution, droplet size and distribution of liquid spray has a primary effect on the combustion heat release process. This heat release process then affects emissions like Nitrogen Oxides (NO_x) and Carbon Monoxide (CO). Computational Fluid Dynamics gives the engineer insight into these processes, but various setup options exist (number of droplet groups, initial droplet temperature) for spray initial conditions. This paper studies these spray initial condition options using the National Combustion Code (NCC) on a single swirler Lean Direct Injection (LDI) flame tube. Using laminar finite rate chemistry, comparisons are made against experimental data for velocity measurements, temperature, and emissions (NO_x, CO).

Introduction

The use of combustion Computational Fluid Dynamics (CFD) in the development of combustion technology has been greatly facilitated by the advancements made during the last decade in the areas of combustion modeling, numerical simulation, and computing platform. Further development of verification, validation, and uncertainty quantification will profoundly impact the reliability and utility of these modeling and simulation tools. Under the NASA Fundamental Aeronautics Program, an assessment of existing computational tools for emissions and flow field is being carried out. As a first step, the present effort aims at establishing the baseline for prediction methods and experimental data for Lean Direct Injection (LDI)^{1, 2, 3} combustion in confined, swirling flows. Combustion codes based on Reynold Averaged Navier-Stokes (RANS), Very Large Eddy Simulation (VLES), and traditional Large Eddy Simulation (LES) will be used; the present paper reports the preliminary investigation using the National Combustion Code (NCC).

The National Combustion Code (NCC) is a state of the art CFD program specifically designed for combustion processes. A short summary of the features of the NCC pertaining to this paper are: the use of unstructured grids⁴, massively parallel computing – with almost perfectly linear scalability^{5, 6}, a dynamic wall function with the effect of adverse pressure gradient⁷, low Reynolds number wall treatment⁸, and a cubic non-linear k-epsilon turbulence model^{9, 10}, lagrangian liquid phase spray model¹¹, and stiff laminar chemistry integration. Recently, viscous low-speed preconditioning^{12, 13} has been added to improve the low-speed convergence of the NCC in viscous regions, and the ability to handle multiple sets of periodic boundary conditions has also been added. The combination of these features is usually not available in other CFD codes and gives the NCC an advantage when computing recirculating, turbulent, reacting, spray flows. Previously, the NCC has undergone extensive validation studies for simple flows^{14, 15}, complex flows¹⁶, NO_x emissions prediction performance¹⁷, and traditional gas turbine combustor / injectors¹⁸.

This paper extends the LDI combustion CFD analysis of Davoudzadeh.^{19, 20} Where previous work only looked at non-reacting flows, this paper will compare the NCC using a steady-state RANS approach against experimental data for a confined, reacting spray flow. This paper will show the sensitivity to the spray initial conditions, particularly the number of droplet groups used to define the distribution, and the initial temperature.

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I. Flow Modeling

A. Geometry and Mesh Generation

The single-element LDI swirler configuration is illustrated in Figure 1. Each element consists of an air passage with an upstream air swirler and a converging-diverging venturi section. The fuel is injected through the center of swirler and the fuel tip is at the throat of the venturi. The air swirlers have helical, axial vanes with downstream vane angles of 60° . There are six vanes with an inside diameter of 9.3 mm and an outside diameter of 22.1 mm. The air then dumps into a 50.8 by 50.8 mm combustion section.

Since the NCC allows for unstructured elements, the grid may be composed of any type and mix of three-dimensional elements. However, hexahedral elements were chosen because they are more efficient at filling a volume with a smaller number of elements compared to an all tetrahedral grid. Hexahedral elements also allow a better calculation of the normal derivatives that are crucial for accurate boundary layer resolution. Approximately 850,000 elements were used. The “Gridgen” mesh generation software was used to create all the grids used in the numerical simulation reported in this paper.

B. Air Flow Conditions

An inlet boundary condition is used, with the air flow speed (20.14 m/s) normal to the inlet face, density (1.19 Kg/m^3), turbulence intensity level (approximately 5%), turbulence mixing length (.15m), and static temperature (294.28 °K). The inlet pressure in these boundary conditions are calculated, not specified (because they are subsonic). The exit boundary condition for single-element specifies static pressure. The operating pressure of the combustor is approximately 1 atm, while the equivalence ratio is 0.75. The measured pressure drop (as a percentage of P3) during the experiments was measured at 4 %.

C. Liquid Spray Conditions

The spray evaporation process was modeled as a lagrangian particle, where each particle represents a group of actual spray droplets. The droplets are represented as a group rather than an individual droplet because calculating each droplet is impractical, as it is too computationally intense. From examining the spray experimental data, a Sauter Mean Diameter (SMD, D_{32}) of 32 microns was used for all calculations. The hollow spray cone had a total angle of 90.0° and a cone thickness of 14.0° . A mass flow of $4.15\text{E-}04 \text{ kg/s}$ and an initial velocity of 20.0 m/s was prescribed. Simulations were performed with three, nine, and eighteen droplet groups. Figure 3 shows the cumulative dropsizes distribution (Given by Raju¹¹) used as the spray initial condition. Three droplet groups is not an adequate representation of the spray distribution; this was used as starting point for calculations. Using nine and eighteen droplet groups, the drop size distribution is represented accurately. A well represented (nine droplet groups and above) distribution at a 32 micron SMD has a droplet size range from one to ninety-five microns. Ninety-six streams and thirty-two rays were used for the spatial distribution for the spray. The lagrangian solution process uses an “unsteady” spray model. Droplet groups are only integrated for a fraction of their lifetime (but restarted at this point for the next iteration), rather than completely to steady-state. A time step of $5.0\text{E-}07$ was used as the integration time step (DTML in NCC terminology), and an integration time of $1.0\text{E-}04$ (DGML). New droplet groups were introduced every integration time. This process is thought to allow better load balancing on parallel computing platforms, possibly allowing better coupling with the CFD solver.

D. Chemistry Model

Ideally, we would prefer to use detailed chemical kinetic models. There are two problems with this approach: 1) Jet-A is a fuel and not a substance, and there are no universally accepted surrogate fuel models for Jet-A; 2) the computational costs associated with these models make them impractical when fine computational grids are used. Originally, a single-step, global chemistry model was used, shown in Table 1. This model was based on propane kinetics²¹, which are close to Jet-A’s reaction rates. The single-step model allowed an easier start up in the solution process, by reducing the computational requirements during the ignition phase. Single-step models do not allow emissions calculations, only heat release. Because of this, a reduced ten-step, twelve species model based on propane kinetics^{22,23} was used, as shown in Table 2. The mechanism was developed by a gradual reduction of reaction steps and species using sensitivity techniques. The reduced mechanism also describes the formation of

Carbon Monoxide and Nitrogen Oxide. However, only one nitrogen-oxide species, NO, has been used in the reduced mechanism. NO in the reduced mechanism represents the whole family of nitrogen oxides including nitric oxide by Zeldovich²⁴ reactions, prompt NO reactions by Fenimore²⁵, and nitrogen oxide formation through nitrous oxide.

E. NCC Computations

Staging was used in the solution process; cold-flow calculations and initial combustion calculations were performed using a single-step chemistry model with lagrangian spray until a steady state solution was obtained. The final stage of CFD calculations was performed by switching from the one-step chemistry model to the reduced chemistry model; this was done by changing the input chemistry-parameters of the code. It is important to note that no turbulence – chemistry interaction model was used for this case. Based on past experience, this is an adequate engineering modeling assumption.[‡]

The NCC computations for reacting and non-reacting flow were run in general until the flow residuals were reduced three orders of magnitude. The mass flow rates at the boundary conditions were also monitored as a convergence criterion. Dissipation (JST type) was set at 0.0 for second order dissipation (ϵ_2) and .1 for fourth order dissipation (ϵ_4).²⁶ The value of k_2 , the constant that scales the second order dissipation gradient switch, was set at 0.50. Setting the second order dissipation to zero is absolutely necessary to accurately resolving flow features, like jets. A CFL number of 1.0 was used. A cubic, non-linear k-epsilon model with a variable C_{μ} coefficient was used. This model was selected because of the swirling flow. A dynamic wall function with pressure gradient effects was used to model near wall turbulent flow effects.

Computations were performed on a variety of computer platforms, namely SGI Columbia supercomputer at NASA Ames and clusters (Mac OSX and Linux) at NASA Glenn. The Columbia supercomputer was preferred because it was considerably faster because of its high speed, low-latency interconnect. This interconnect was important because the Lagrangian spray model created a load unbalance in compute nodes. The high speed interconnect seemed to mitigate the load imbalance. It takes approximately one week to complete a single LDI combustion case using 64 processors. After the baseline run was completed, new runs starting from the baseline case took about two days to one week, depending on the number of spray particles used.

II. Experimental Data

The experimental data is provided by Jun Cai, S.-M. Jeng, and R. Tacina²⁷, and by Yongqiang Fu and San-Mou Jeng.²⁸ Velocity measurements were taken with a two-component Laser Doppler Velocimetry (LDV) system, temperature measurements were taken with thermocouples, and emissions data was gathered via an isokinetic probe and gas analyzer. Quartz makes up the combustion section. The combustor experiments have significant convective and radiative heat losses. The temperature measurements reported are not corrected to adiabatic conditions. The heat transfer losses will cause a 200 to 300 °K temperature difference between the experimental data and the NCC computations. Experimental droplet measurements are collected with a Phase Doppler Particle Analyzer (PDPA).

III. Results and Discussion

A. Process Overview

Table 3 shows the CFD calculations performed to date. In Figure 4, streamlines visualize the flow as it passes through the helical swirler and into the combustion chamber. Note the strength of the recirculation zones by the track of the streamlines. Contours of axial velocity are also shown. Blue indicates negative axial velocity (and the recirculation zones) and red indicates positive axial velocity. The recirculation zone size and strength affects combustion stability and emissions. Figure 5 shows the vaporization process. The liquid droplets (small spheres) vaporize before combustion occurs. The fuel vapor is shown by the green iso-surface. This fuel vapor mixes further

[‡] Results will challenge this assumption. However, the cost of running a complex turbulence-chemistry interaction model is very prohibitive, even for supercomputers like NASA's Columbia.

with air and then burns. Contours of gas temperature along a centerline cut visualize this combustion process. Blue indicates room temperature and red is at the adiabatic flame temperature. Note how the flame shape is bound by the fuel vapor region.

B. Flow Comparison

Figure 6 shows a comparison of axial velocity at the centerline. All of the simulations show general agreement with the experimental data, but appear out of phase. The experimental data also shows a dip in axial velocity from 0 – 10 mm from the combustor face. The calculations do not produce this dip in axial velocity. Figure 7 gives some hints to why calculations do not agree. Error bars show the root mean square (RMS) values of axial velocity of the experimental data and the calculations. (The RMS values for the CFD calculations are assuming isotropic turbulence; RMS values are the same for each velocity and are calculated from the turbulent kinetic energy.) The RMS values are very large in the 0 – 10 mm range. Given this high turbulent intensity, the turbulence model (and the RANS assumption) will not be able to reproduce this result. Figure 8 shows a spanwise comparison of axial velocity. In general, the calculations trend better with the experimental data further downstream. The 3mm location shows a complete disagreement between the experimental data and CFD calculations. This disagreement was also shown by the centerline comparison. Both nine droplet group simulations match the data better at the 3mm location, but the reason is not understood. Figure 9 shows the comparison with radial velocity for spanwise rakes. The data is reasonably matched in all locations. The simulations performed with more droplet groups tend to match the data better in the 3 and 9mm locations. Figure 10 shows a comparison of turbulent kinetic energy along the centerline. (The turbulent kinetic energy for the experimental data was created by duplicating the RMS value for the radial velocity to get the three values needed to calculate the turbulent kinetic energy. The RMS of axial velocity is the other component.) A very interesting result occurs - changing the number of droplet groups drastically changes the turbulent kinetic energy produced. The nine droplet group simulations appear to qualitatively match the experimental data. Why this exactly occurs is unknown.[§]

C. Temperature Comparison

As a reminder, experimental temperature is not corrected due to heat losses. Comparing temperature along the center, Figure 11, as great deal of variation is produced. The one-step model shows a fast reaction rate, while the ten-step kinetic model shows that process is a function of the number of droplet groups used. While the nine and eighteen droplet group distributions do not have a difference in droplet distribution, the eighteen droplet group computation shows a much faster reaction rate. In general, the CFD calculations at least qualitatively match the shape of the experimental centerline temperature. The more droplet groups used, the better the agreement. Using a lower droplet temperature (300°K) also seems to affect the solution positively. The spanwise rakes, Figure 12 and Figure 13, also compare the CFD calculations against experimental temperature. Generally, the comparison agrees more downstream. Near the injector, there is a considerable difference. At the 5mm rake, only the calculations with large numbers of droplets agree qualitatively with the experimental data. However, the experimental data shows a strong peak temperature at the center of the rake. None of the CFD calculations reproduced this shape accurately. At the 10mm rake, the agreement is better, but only the simulations with adequate droplet distributions (nine and eighteen droplet groups), give the qualitative shape. The shape of the peak temperature is still not reproduced accurately.

D. Emissions Comparison

Figure 14 compares the amount of CO along the centerline. (Please note: the Y axis is a log scale.) All of the ten-step simulations reproduce the general amounts of CO. The more droplet groups used, the better the agreement with the experimental data. Using a lower initial droplet temperature seems to positively affect the comparison. We would like to point out that we have not done any error analysis on this data. Measuring CO is difficult, because it requires an isokinetic condition to prevent CO from oxidizing to form CO₂. Spanwise rakes of CO are shown in

[§] While there is no turbulence – chemistry interaction, there is a coupling with the heat release and the turbulence equations. The heat release process essentially modifies the expansion and shear the flow is experiencing. This shear then is an input into the turbulence equations. We do not claim that a turbulence – chemistry interaction is not needed.

Figure 15. Once again, the more droplet groups used, the better the result. Only the simulations using nine and eighteen droplet groups qualitatively agreed with the experimental data, particularly the shapes. While it appears the CFD calculations quantitatively agree with the experiments, for the reasons given above, this may not be correct. Looking at the NO_x amounts along the centerline, Figure 16, we see that the differences increase while proceeding downstream. Using more droplet groups does not improve the CFD results. Figure 17 shows the spanwise NO_x amounts. Close to the injector face, the CFD calculations qualitatively agree with the experimental data. Moving downstream from the injector face, the comparison is worse. From this comparison, we believe the ten-step kinetic model is not adequate for predicting amounts of NO_x .

E. Droptime and Mesh Resolution – Sources of Error

Looking at Figure 18, we compare computed Sauter Mean Diameter, after the lagrangian particle is injected into the simulation. The CFD and experimental data are measured in essentially the same way – by probes to count each droplet size. Details on exactly how this is done will be reported in a later paper. While the overall shape is reproduced by the CFD calculations, the dip in experimental droplet size is not captured by the calculations. Also, the CFD calculations differ by more than a factor of two. We believe the 32 micron SMD given to the distribution is too small. For this case, a 70 micron droplet size would be more appropriate. Figure 19 shows the recirculation zone, via velocity vectors, near the fuel injector tip. The strength of the recirculation zone is large enough to possibly cause secondary droplet breakup. For a better comparison in the future, secondary droplet breakup should be used. Looking at the gaseous fuel mass fraction at the injector tip, Figure 20, there is a considerable amount of evaporation that occurs. Computational grid also determines the solution accuracy near the injector tip. Figure 21 shows the mesh spacing near the injector tip. Given the amount of change that occurs, the mesh should be refined in this area.

IV. Conclusions

These CFD calculations are a step forward in anchoring CFD codes, like the NCC, to a swirling, reacting spray flow. The current results are acceptable, but can and will be improved. The improvements that will be made are: using a better reduced Jet-A kinetic mechanism, using a larger Sauter Mean Diameter, adding a secondary droplet breakup model, improving the mesh density near the injector tip, and using a consistent turbulence – chemistry interaction model.

Acknowledgments

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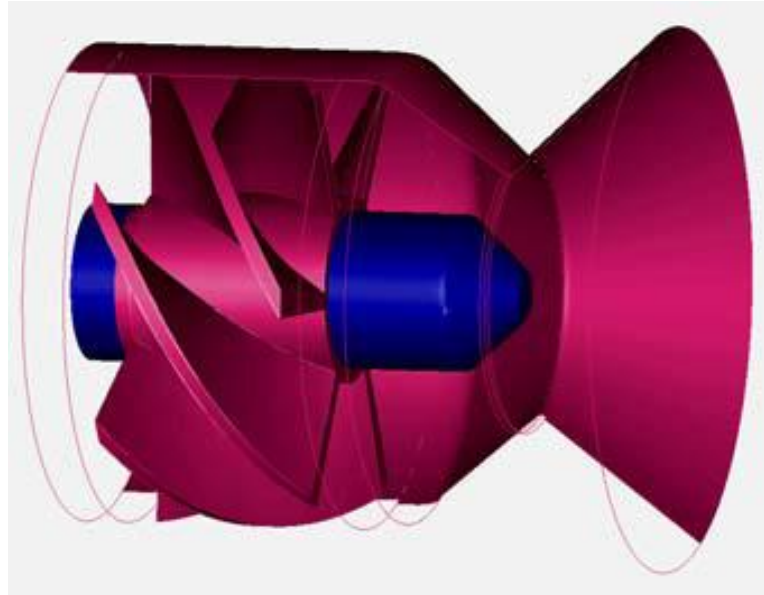


Figure 1. Single element LDI injector geometry.

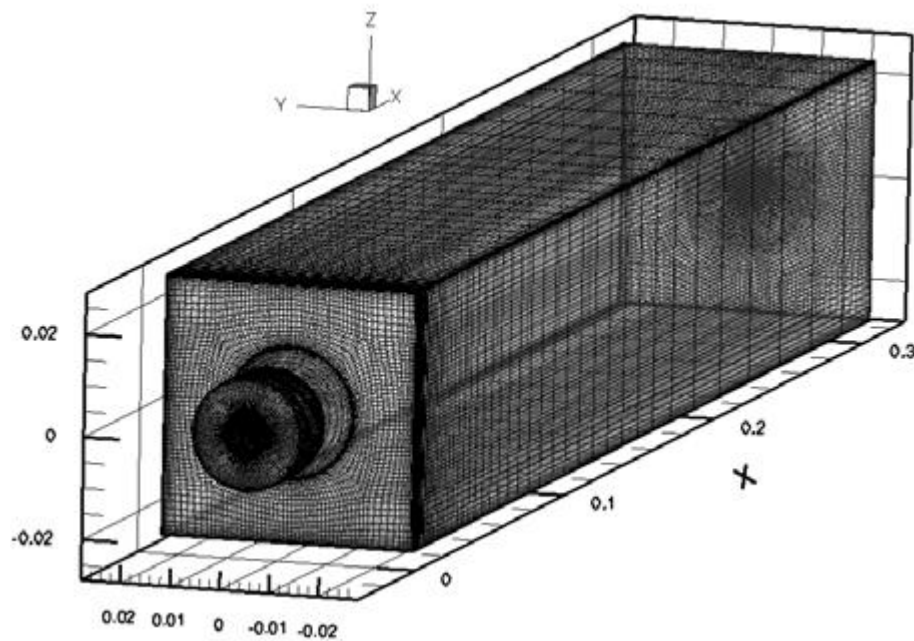


Figure 2. Computational grid for the single element LDI combustor.

Table 1 Single Step (Global) Chemistry Model.

	Reaction	A (mole – cm – sec– K)	n	E (cal/mole)
1	4 C₁₂H₂₃ + 71 O₂ => 48 CO₂ + 46 H₂O <i>GLO / C₁₂H₂₃ 0.10 /</i> <i>GLO / O₂ 1.65 /</i>	8.60E+11	0.00	3.00E+4

Table 2. Reduced 10 Step, 12 Species Chemistry Model in Chemkin Format.

	Reaction	A (mole – cm – sec – K)	n	E (cal/mole)
1	4 C₁₂H₂₃ + 47 O₂ => 48 CO + 46 H₂O <i>GLO / C₁₂H₂₃ 0.1 /</i> <i>GLO / O₂ 1.6 /</i>	1.46E+13	0.00	3.40E+4
2	H₂ + O₂ <=> H₂O + O	3.98E+11	1.00	4.80E+4
3	H₂ + O <=> H + OH	3.00E+14	0.00	6.00E+3
4	H + O₂ <=> O + OH	4.00E+14	0.00	1.80E+4
5	CO + OH <=> CO₂ + H	1.51E+07	1.28	-7.58E+2
6	H₂O + O₂ <=> 2O + H₂O	3.17E+12	2.00	1.12E+5
7	CO + H₂O <=> CO₂ + H₂	5.50E+04	1.28	-1.00E+3
8	N₂ + O <=> N + NO	1.00E+14	0.00	7.50E+4
9	N + O₂ <=> NO + O	6.30E+09	1.10	6.28E+3
10	N + OH <=> NO + H	3.80E+13	0.00	0.00E+0

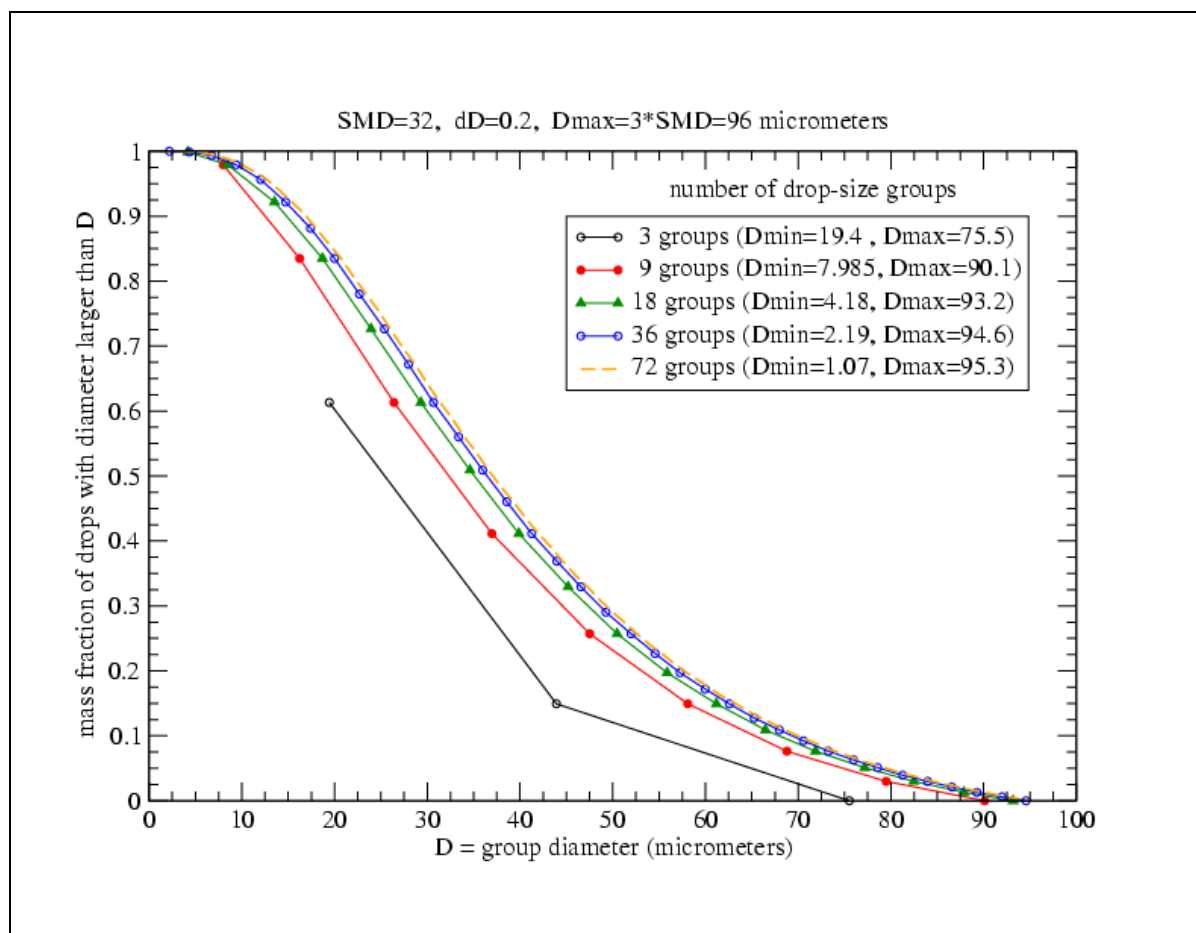


Figure 3. Cumulative drop size distribution (spray initial condition).

Table 3. Summary of CFD calculations.

Chemistry Model	Number of Droplet Groups	Droplet Initial Temperature [°K]
1 Step	3	350
10 Step	3	350
10 Step	9	350
10 Step	9	300
10 Step	18	350

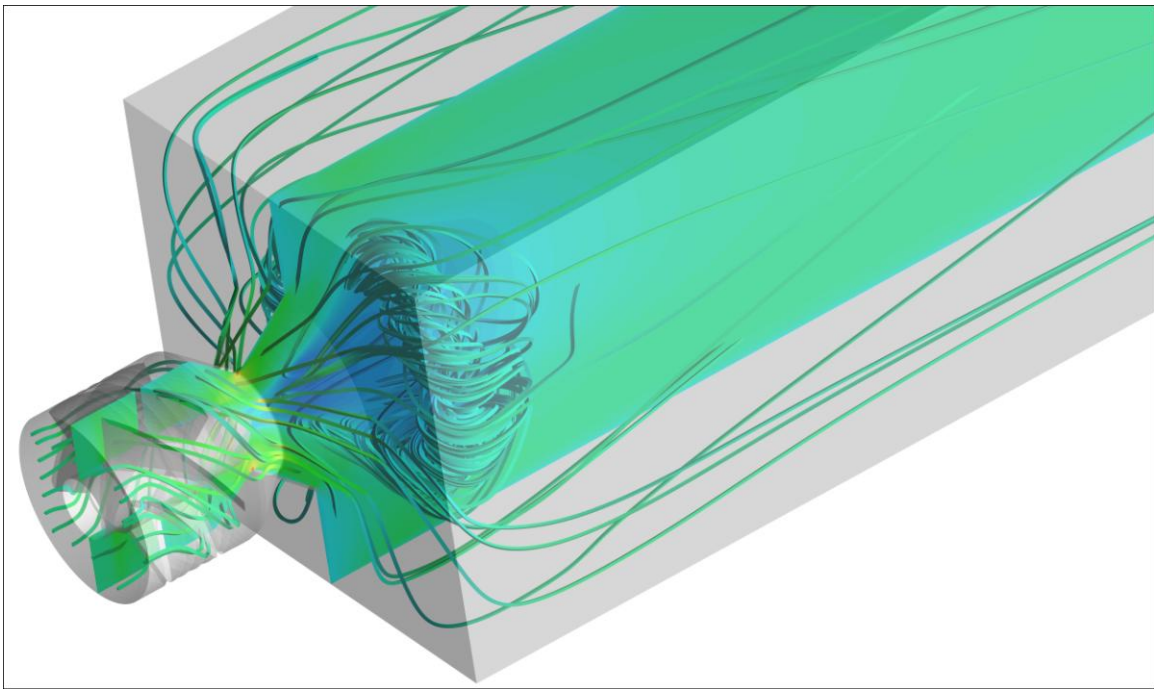


Figure 4 Flow visualization using streamlines and contours of axial velocity at an axial mid-plane.

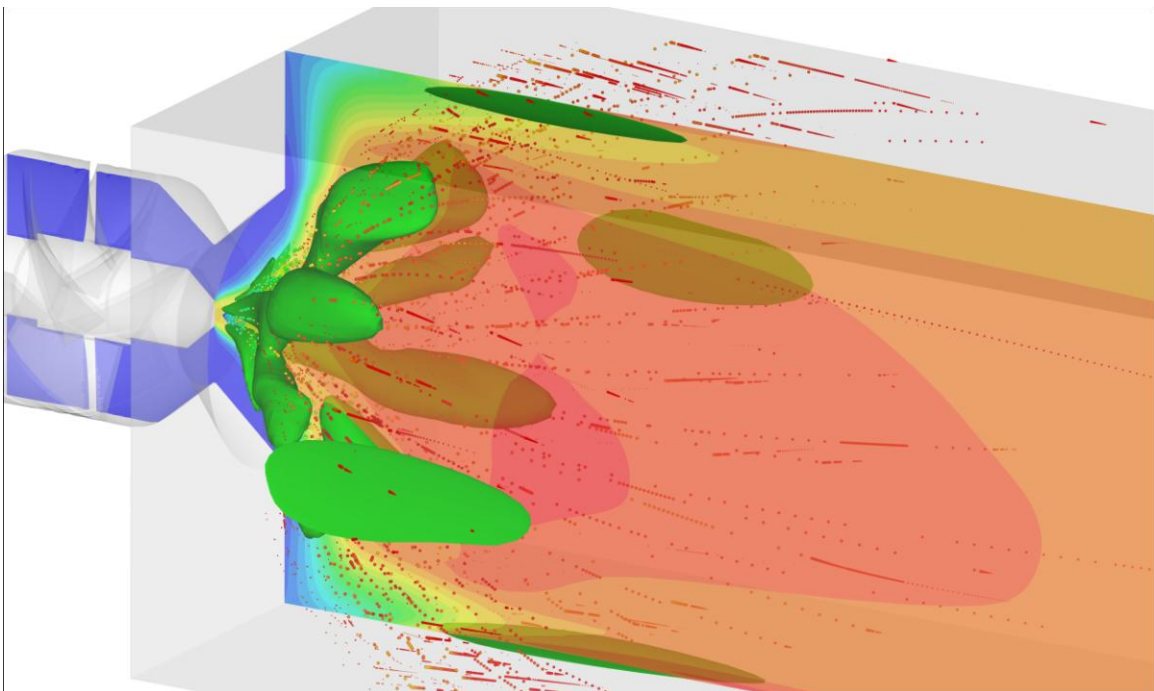


Figure 5 Flow visualization of the heat release process using the largrangian droplet groups, contours of temperature at an axial mid-plane, and iso-surfaces of the fuel mass fraction.

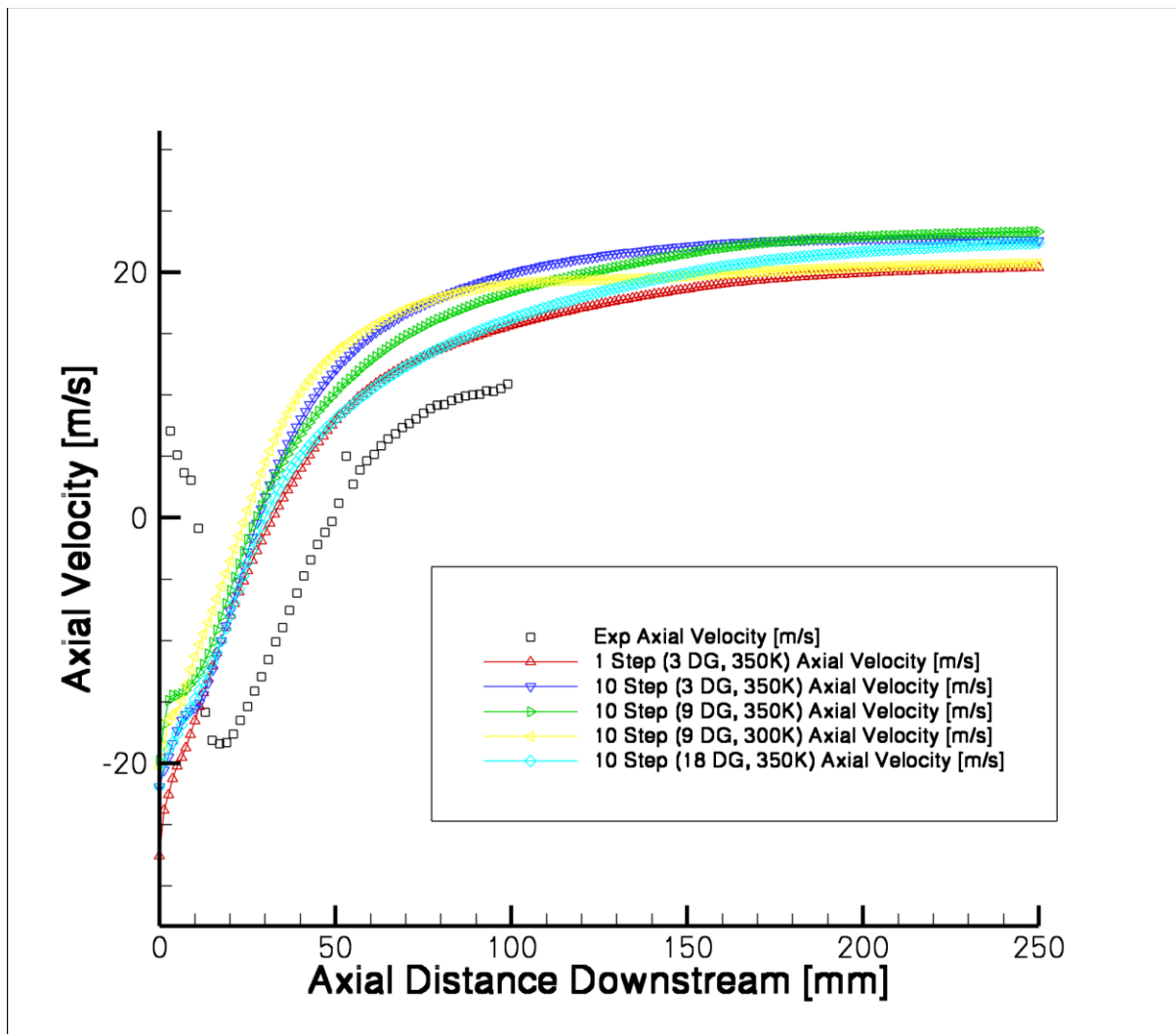


Figure 6. Comparison of axial velocity versus axial distance at the centerline.

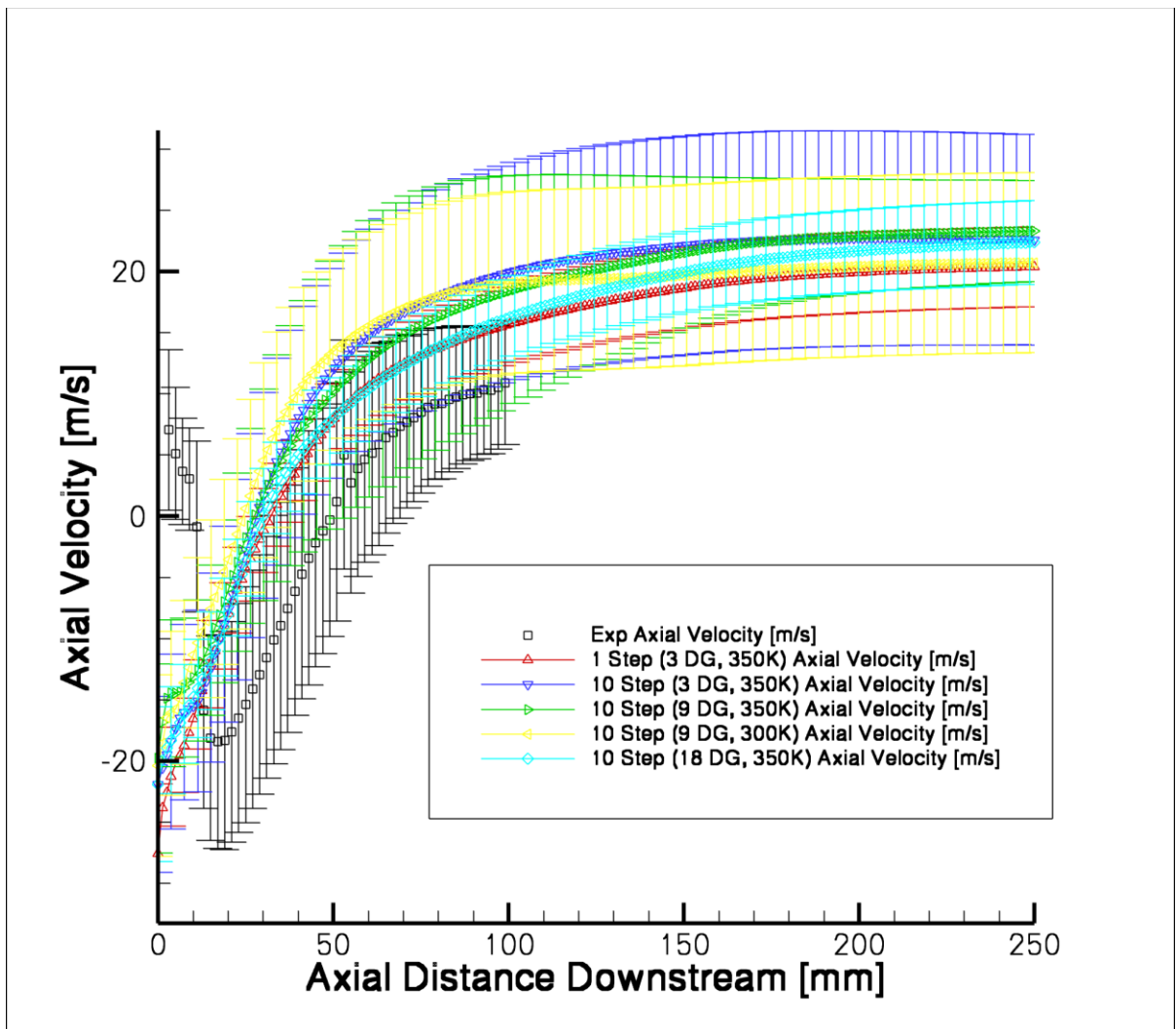


Figure 7. Comparison of axial velocity with RMS values as error bars versus axial distance at the centerline.

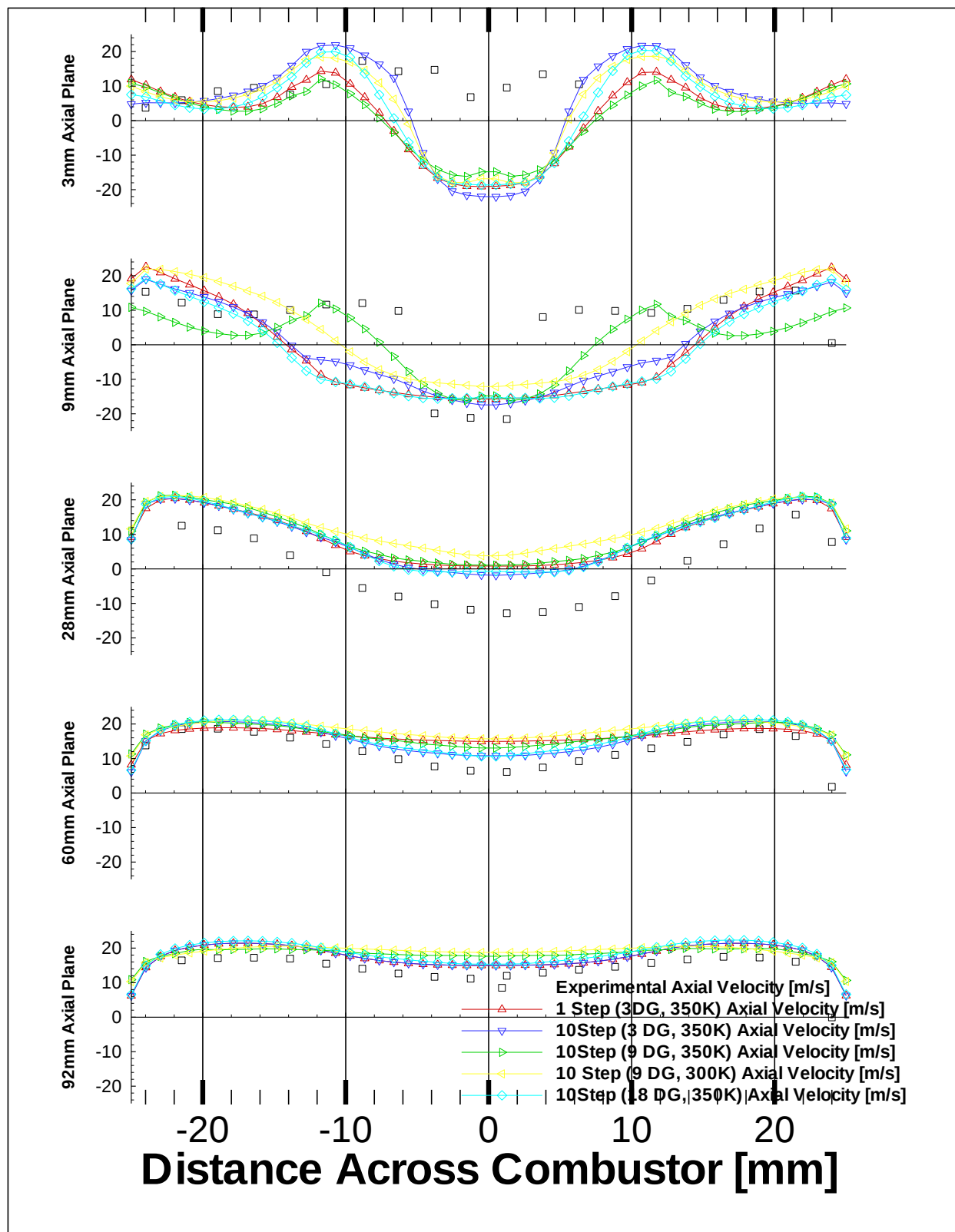


Figure 8. Comparison of axial velocity versus spanwise distance in the axial Y-Z plane with Z = 0 mm.

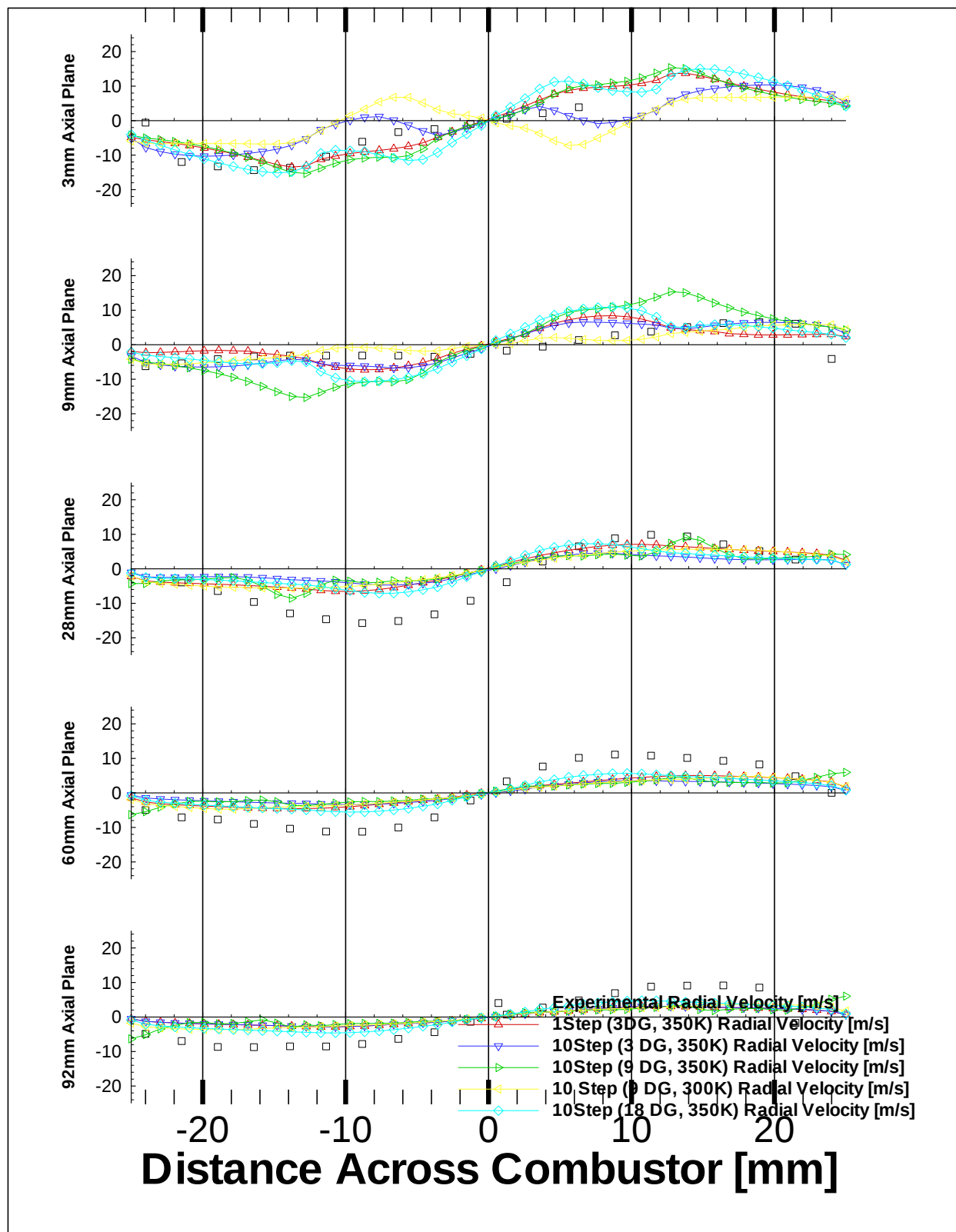


Figure 9. Comparison of radial velocity versus spanwise distance in the axial Y-Z plane with Z = 0 mm.

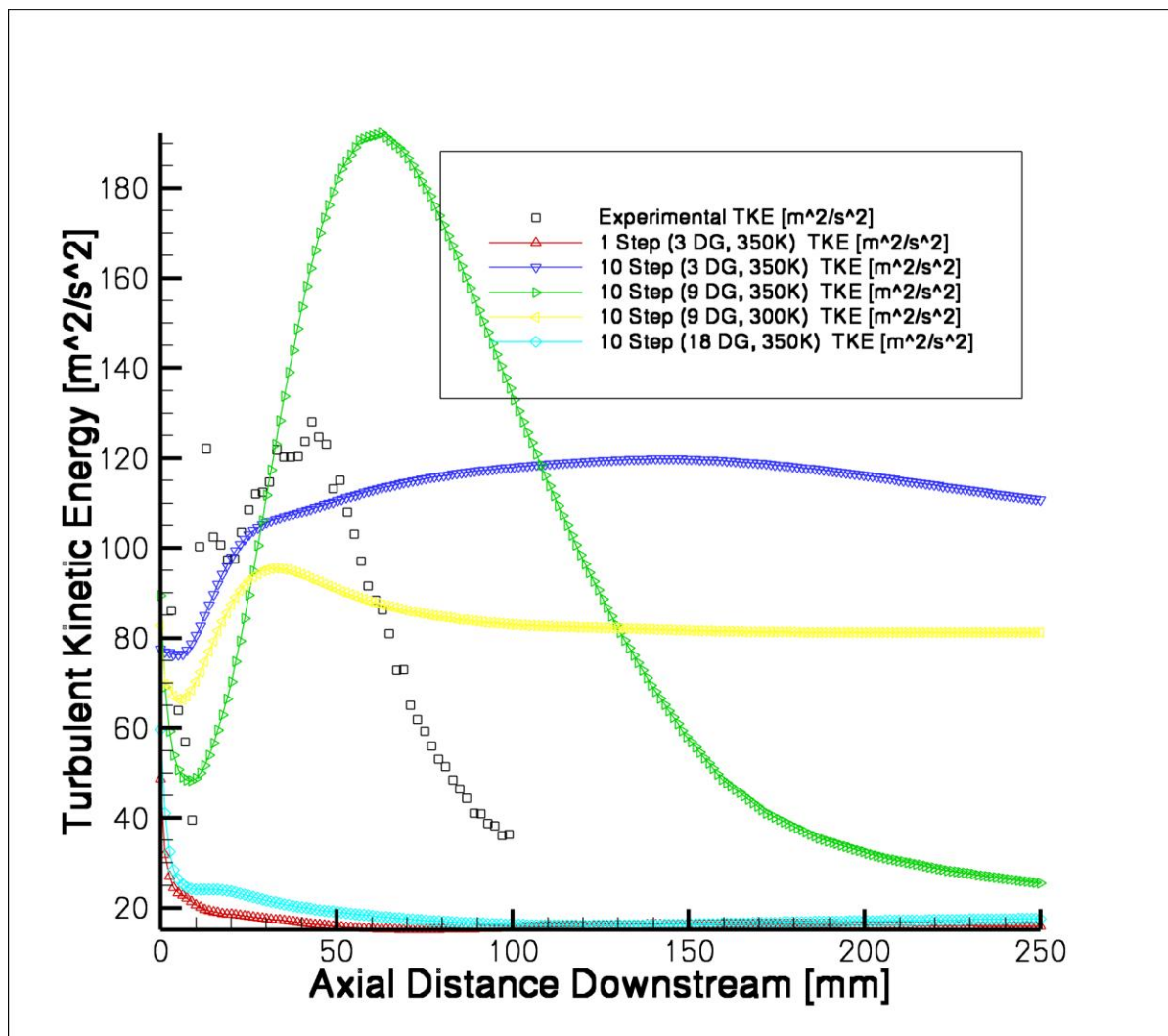


Figure 10. Comparison of turbulent kinetic energy versus axial distance at the centerline.

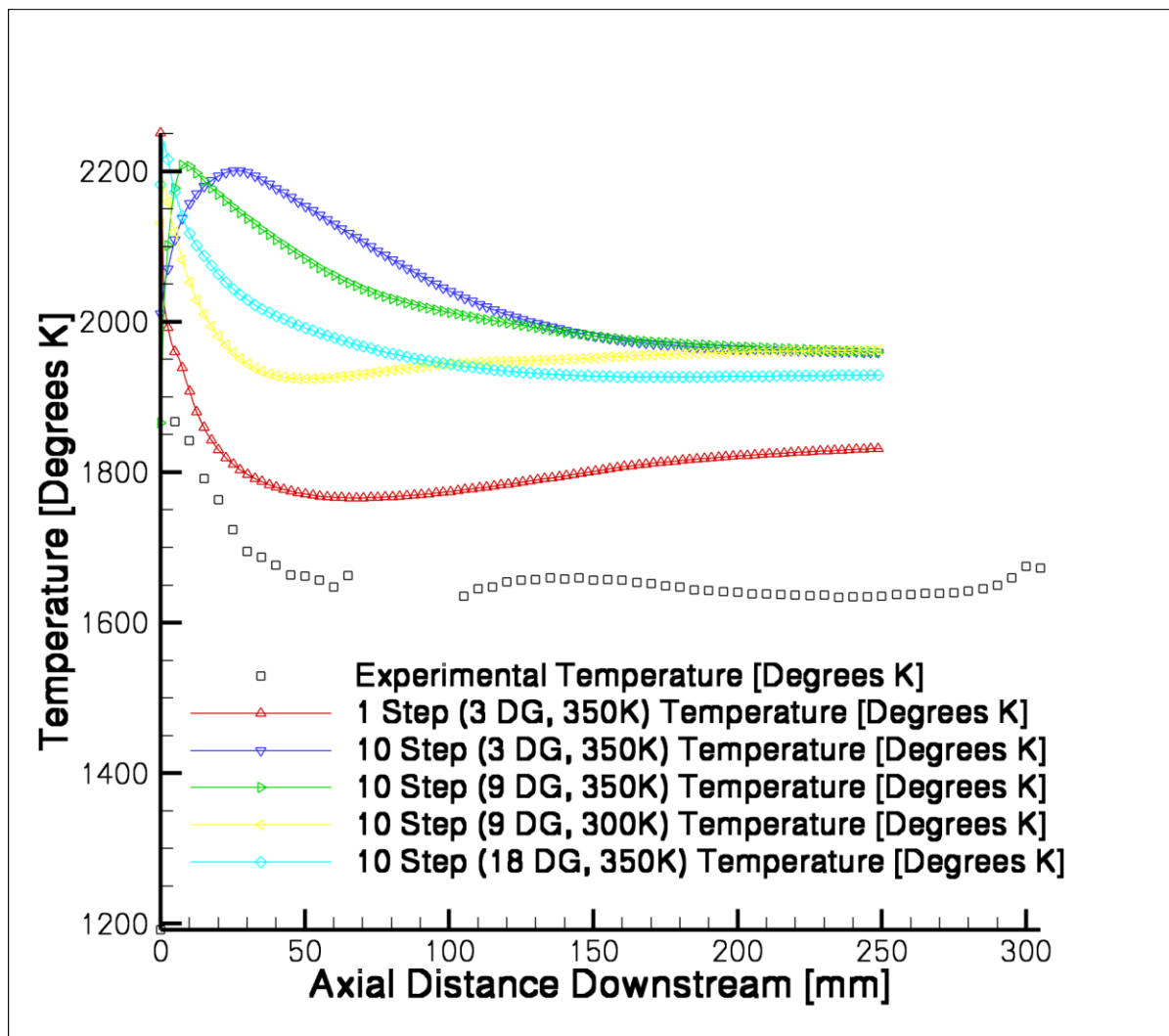


Figure 11. Comparison of temperature versus axial distance at the centerline.

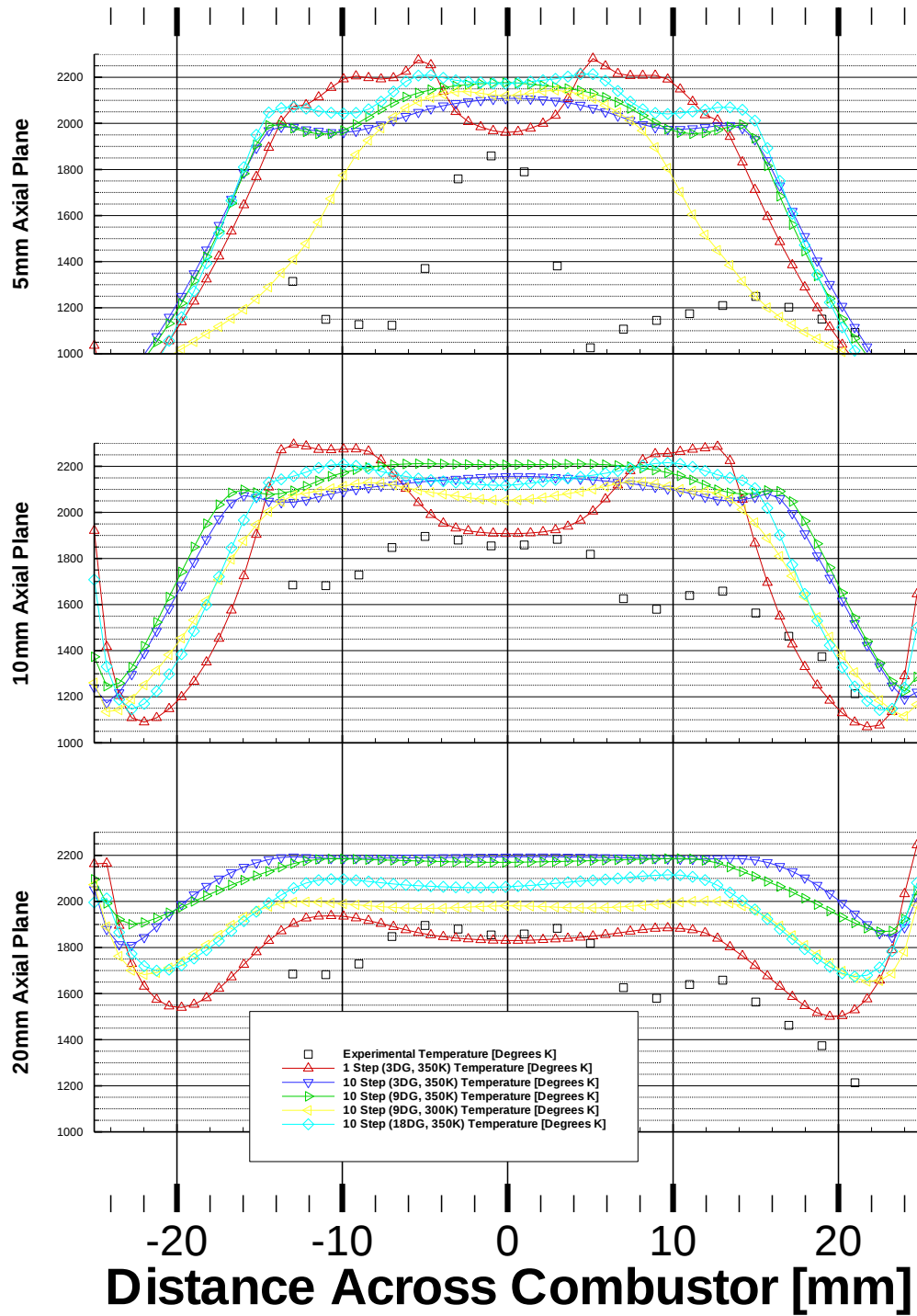


Figure 12. Comparison of temperature versus spanwise distance in the axial Y-Z plane with Z = 0 mm.

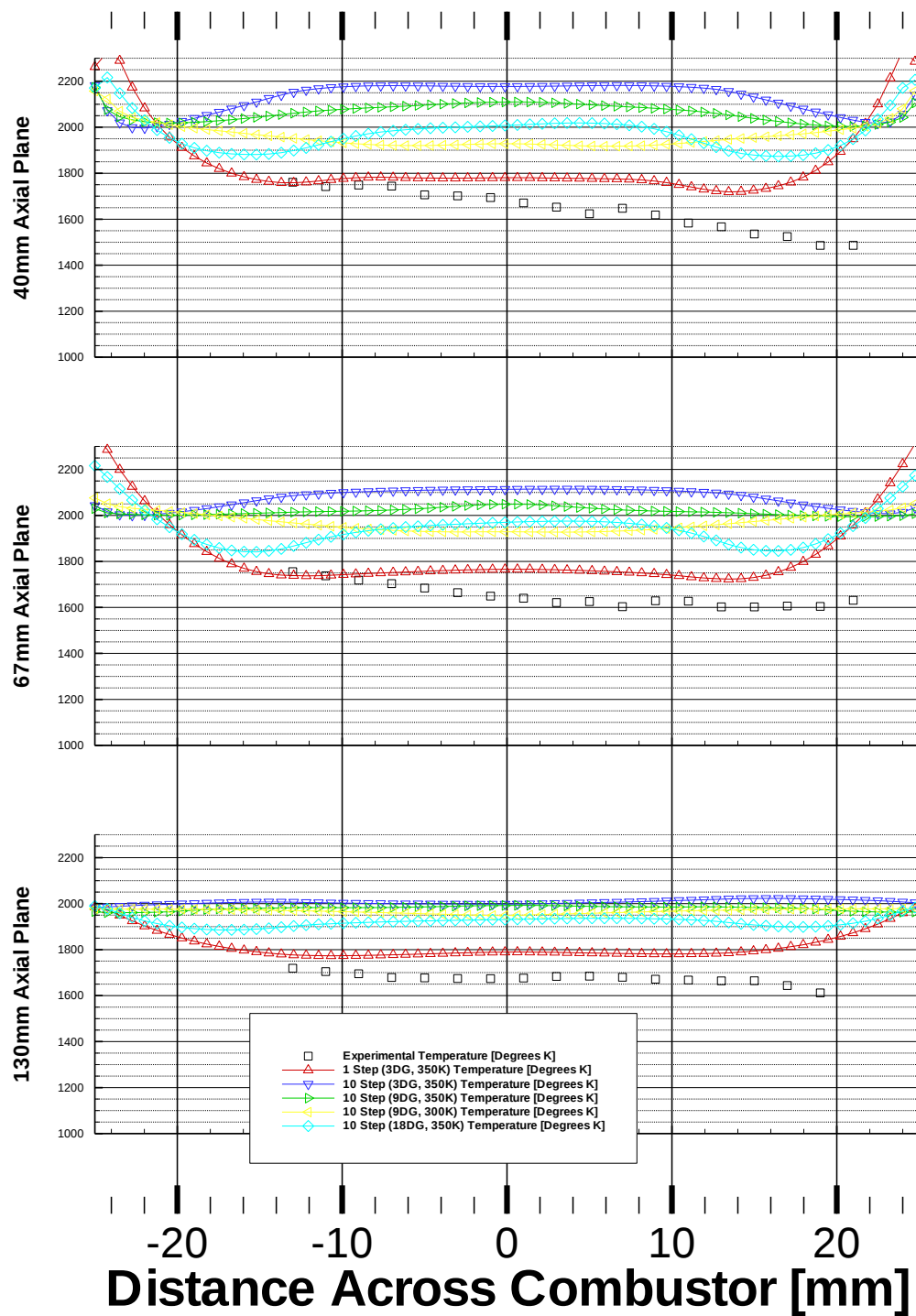


Figure 13. Comparison of temperature versus spanwise distance in the axial Y-Z plane with Z = 0 mm.

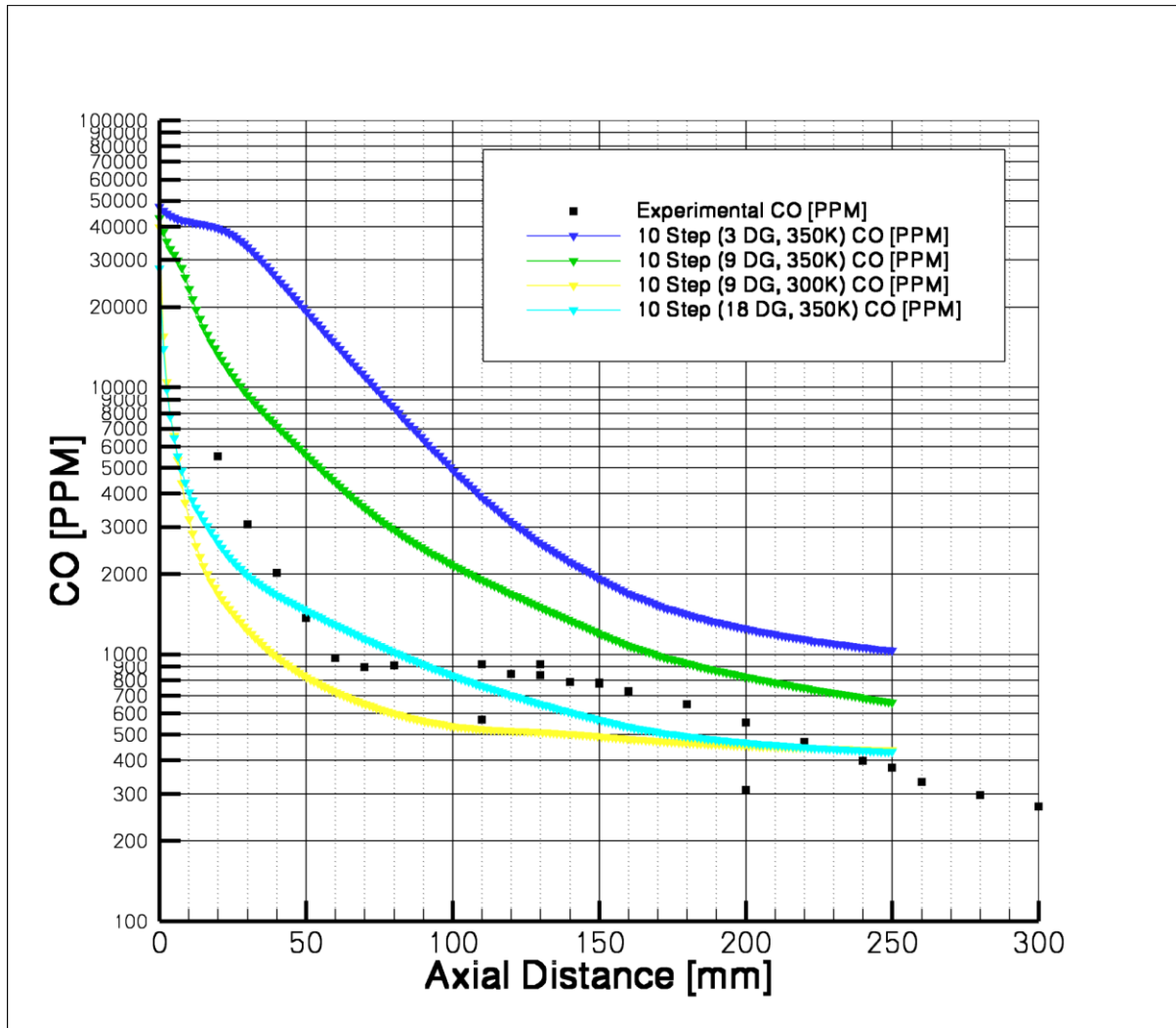


Figure 14. Comparison of Carbon Monoxide amounts versus axial distance at the centerline.

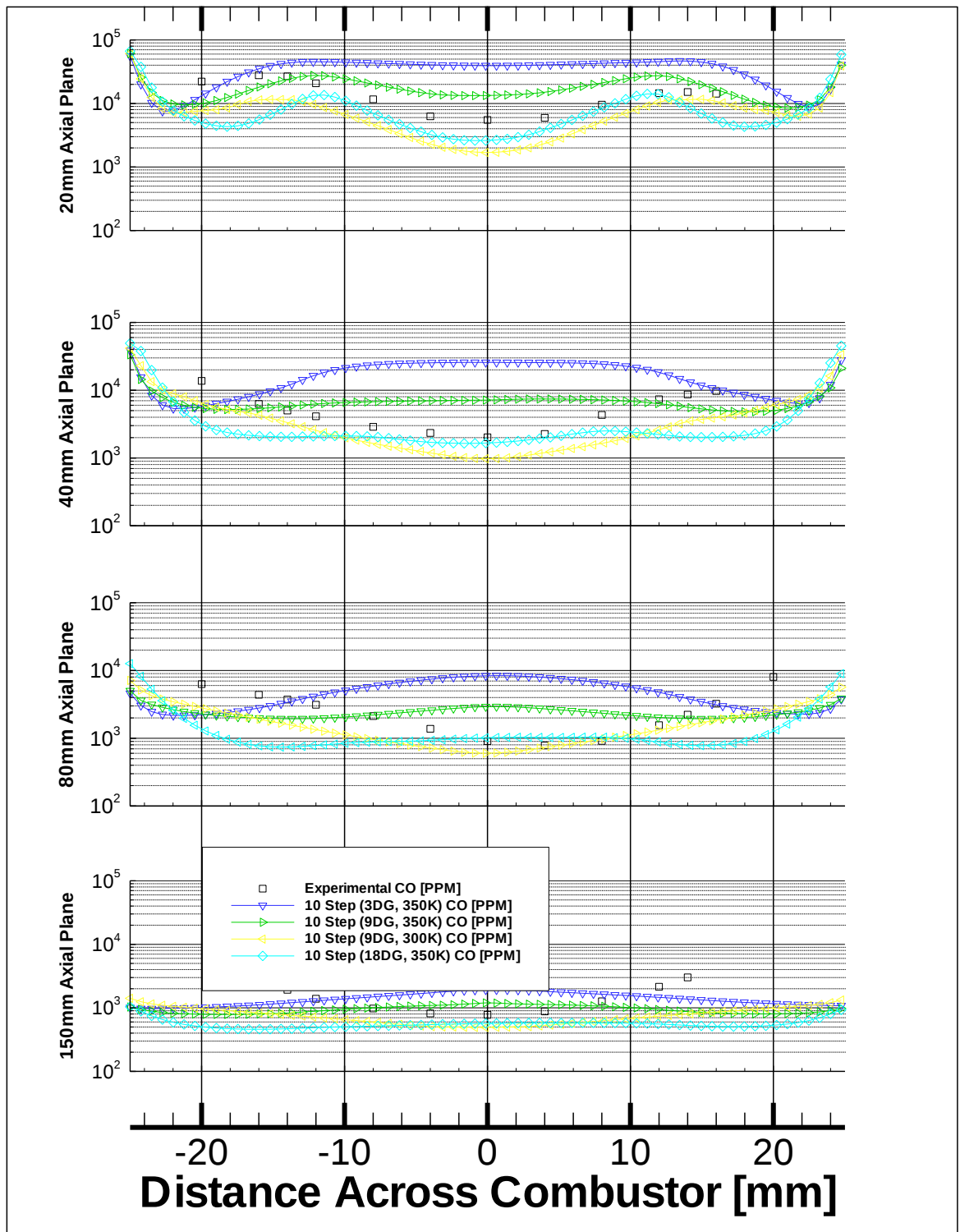


Figure 15. Comparison of Carbon Monoxide amounts versus spanwise distance in the axial Y-Z plane with $Z = 0$ mm.

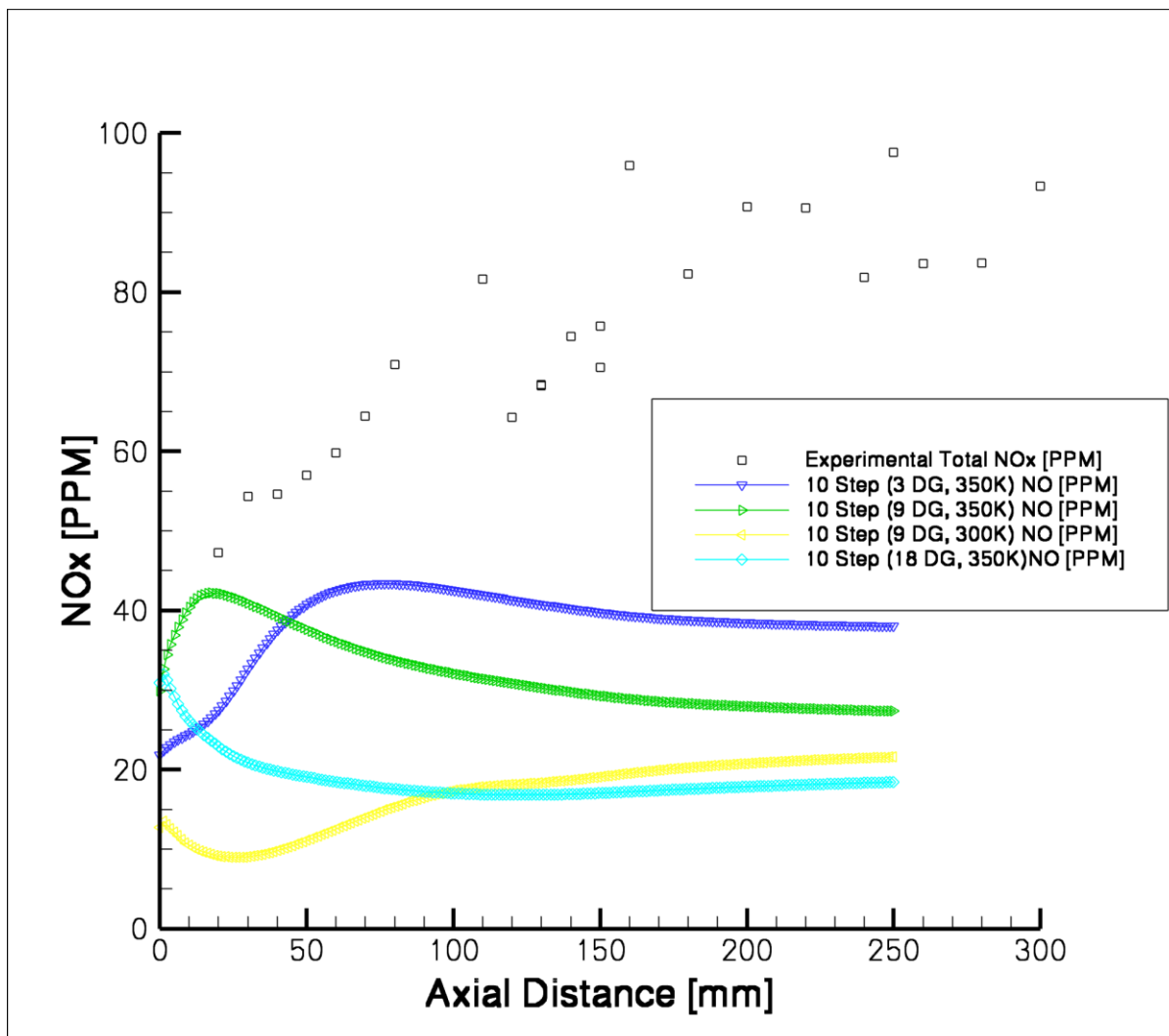


Figure 16. Comparison of Nitrogen Oxides amount versus axial distance at the centerline.

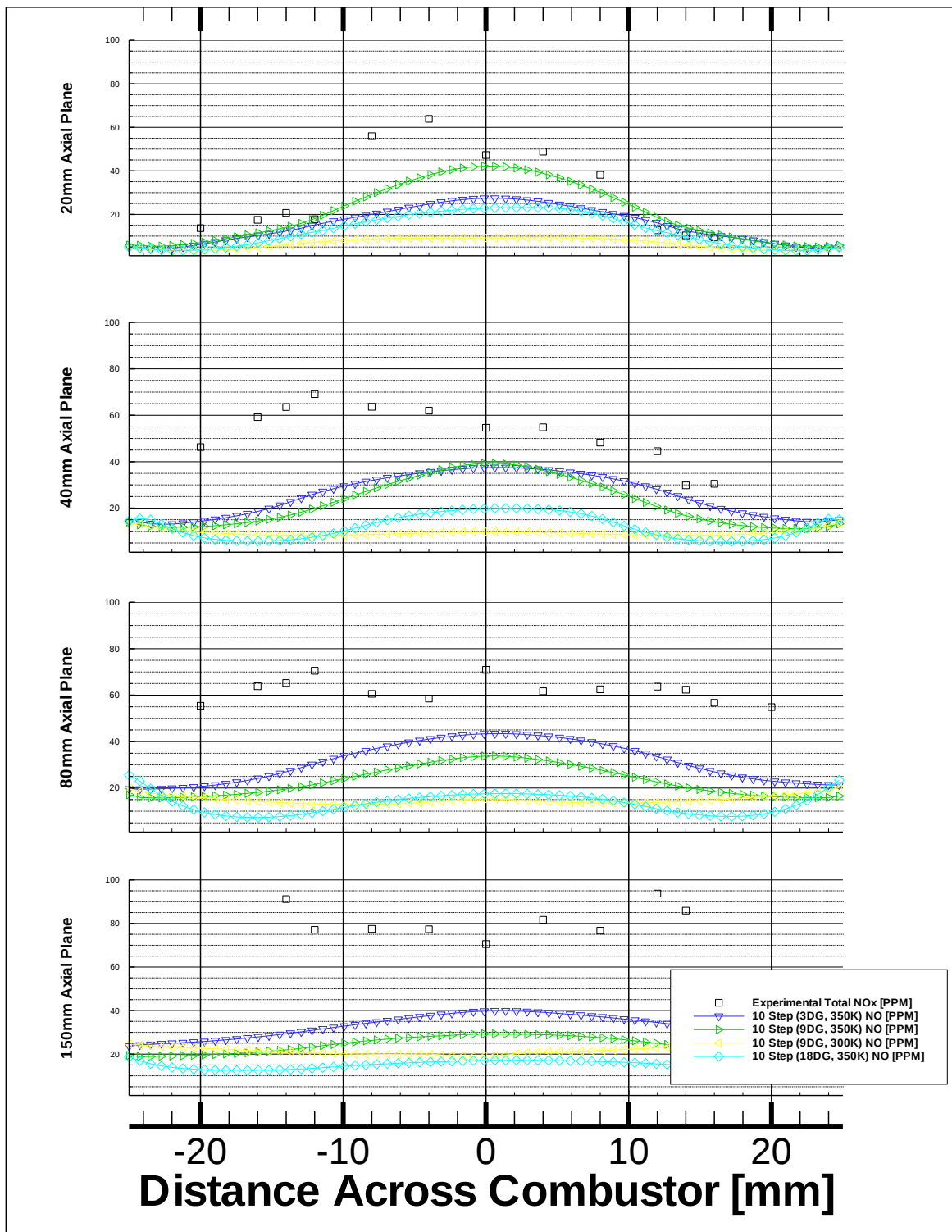


Figure 17. Comparison of Nitrogen Oxides amount versus spanwise distance in the axial Y-Z plane with Z = 0 mm.

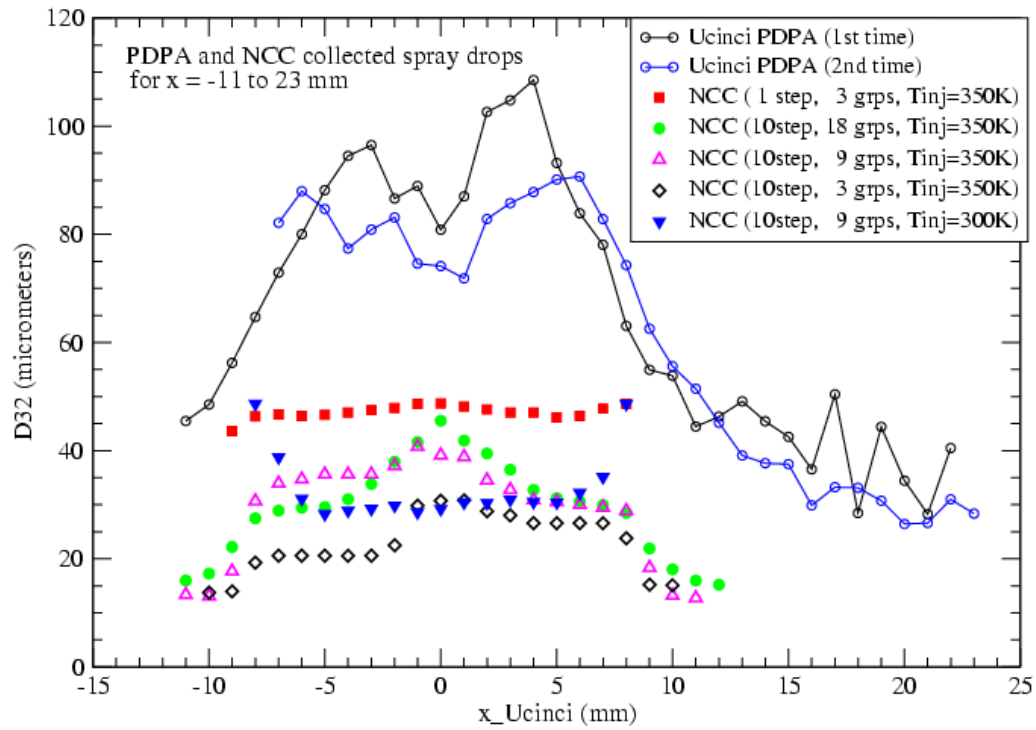


Figure 18. Sauter Mean Diameter (SMD, D32) for an axial distance of 5mm from the combustor face, spanwise rake along the $Y = 0$ mm.

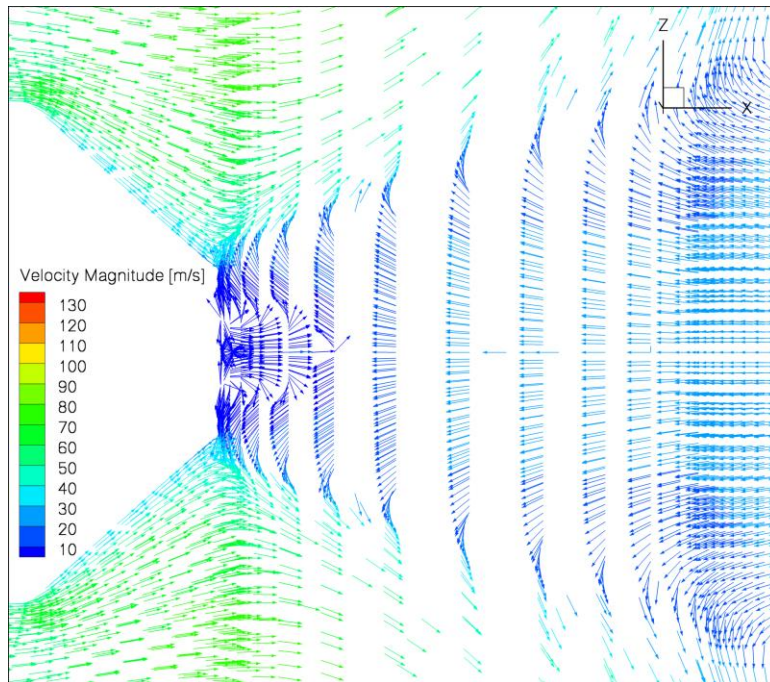


Figure 19. Velocity vectors colored by velocity magnitude in an axial slice at the Y=0mm mid-plane.

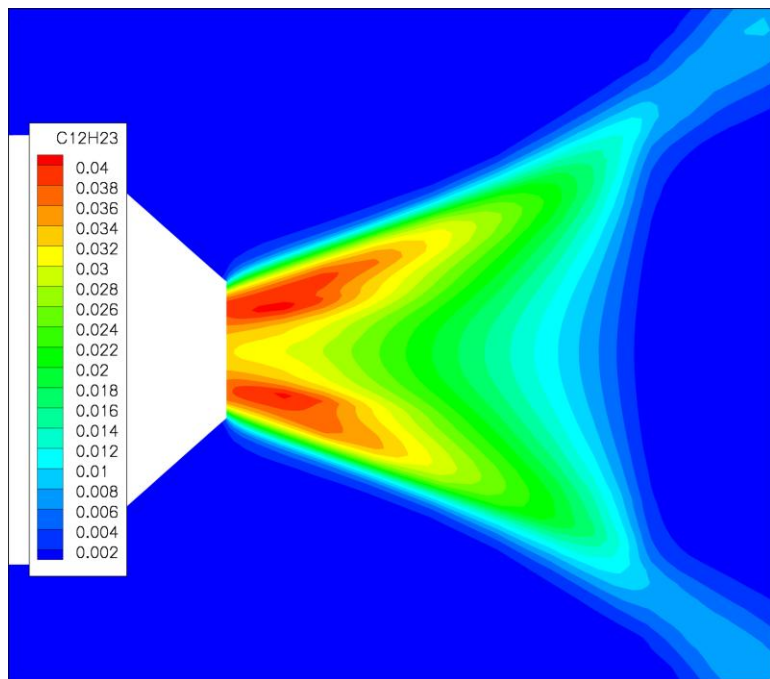


Figure 20. Contours of fuel mass fraction ($C_{12}H_{23}$) in an axial slice at the Y=0mm mid-plane.

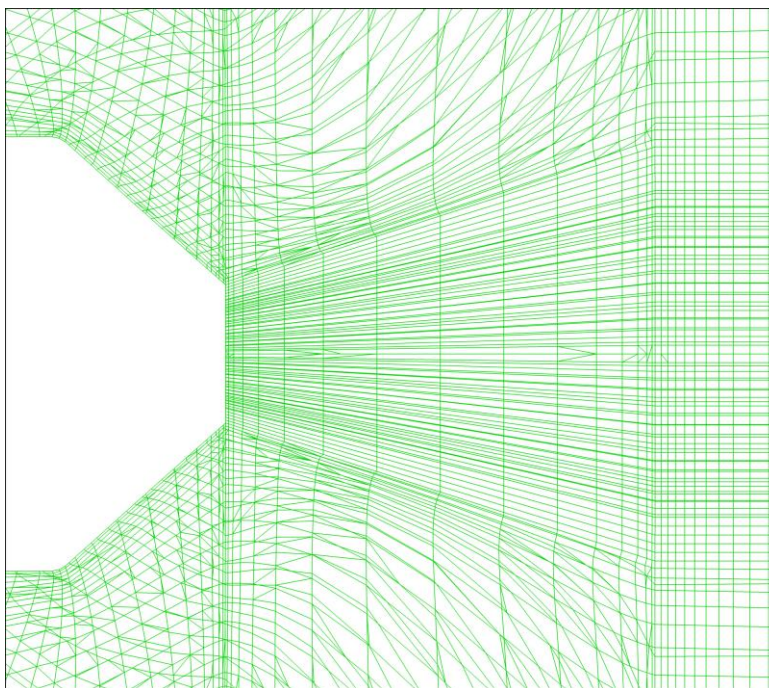


Figure 21. Approximate visualization of the computational mesh in an axial slice in at the Y=0mm mid-plane.

COMPUTATIONAL METHOD:

The computational work performed to produce the numerical results presented in this paper uses the National Combustion Code (NCC), developed at NASA Glenn Research Center (GRC) for comprehensive modeling and simulation of aerospace combustion systems.

The focus in the development of the integrated system of computer codes has been to calculate the fluid, thermal, and chemical characteristics of real-world combustors to an appropriate level of accuracy and turnaround time desired by designers and analysts. The two foremost important obstacles to turnaround time have been grid generation and single processing.

Uses of unstructured or overset grids and parallel computing minimize the overall time needed to achieve a numerical solution. Thus the main focus has been to incorporate a numerical scheme that allows use of large number (thousands) of processors in parallel to shorten the solution time and to provide speed-ups that does not deteriorate with addition of more processors.

The main flow solver for the code used in this work is based on an explicit four-stage Runge-Kutta scheme, which is very suitable for parallelization. Figure 1 shows an example of the speedup that has been achieved with the code on an SGI Origin 2000 [1]. This 3-D test case uses 1.3 million tetrahedral elements for simulation of a premixed hydrogen/air combustor [2], using the Intrinsic Low Dimensional Manifold (ILDm) kinetics module [3,4]. The parallel speedup metric is calculated by taking the ratio of the time per iteration for the serial case versus the time per iteration for the parallel case. The parallel efficiency is the ratio of the parallel speedup to the number of processors used in the calculation. In the calculations presented in this paper, the authors increased the number of processors from 200 to 400 and achieved approximately a factor of two speedup for a 2.5 million elements domain.

To ease-up the grid generation task, the code is designed to use unstructured meshes. It uses triangular and/or quadrilateral elements in the 2-D cases, and tetrahedrons, wedges, pyramids, and hexahedrons in the 3-D cases. A combination of these grid types can be used to create hybrid grids. For example, to resolve the boundary

layer one may choose to use hexahedron elements in the wall region and transition out of the boundary layer to tetrahedron elements via pyramid elements.

In brief, the flow solver solves unsteady, 3-D, compressible Navier-Stokes equations. The discretization begins by dividing the computational domain into a large number of elements, which can be of mixed types. A central-difference finite-volume scheme augmented with numerical dissipation is used to generate the discretized equations, which are then advanced temporally by an explicit 4-stage Runge-Kutta scheme. For low Mach number compressible flow, a pre-conditioning is applied to the governing equations, and the solution is advanced temporally by a so-called “dual-time-step” approach, in which the Runge-Kutta scheme is used for the “inner” iteration. The turbulence model used in the present work is a cubic non-linear k-epsilon model [8] with low Reynolds number wall integration. A description of this solver and some benchmark test cases can be found in Refs. [5-6].

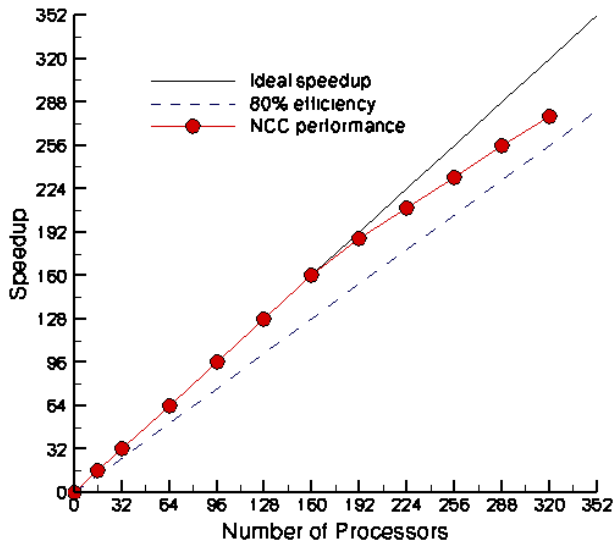


Fig 22. Speedup curve for the 1.3M element test case (Quealy, 2002 [1])

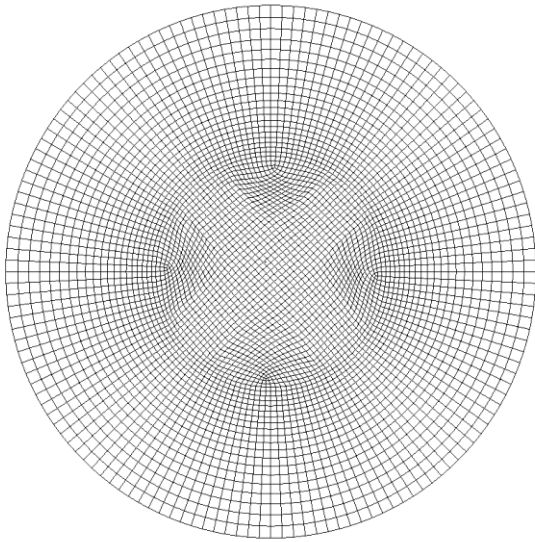
COMPUTATIONAL DOMAIN AND THE MESH:

The numerical simulation is performed for the whole geometry including the flow development sections for the air, six swirling air passages for each module and the rectangular section combustion chambers.

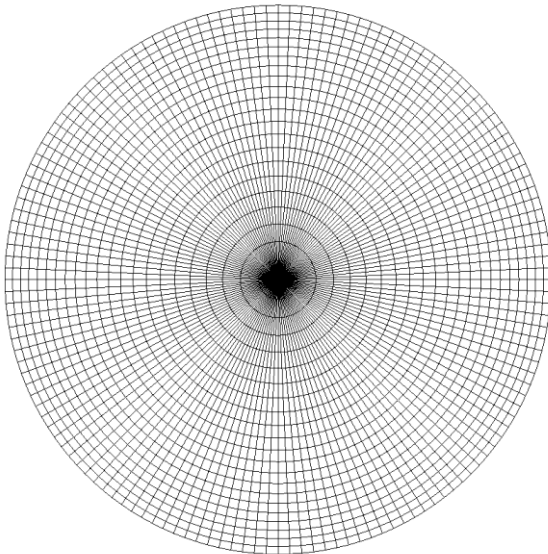
Several grid densities are generated to consider the grid effects. For the single-element geometry three grids with different grid densities namely coarse, medium, and fine are used. The grid densities for the coarse, medium, and fine grids are 240,384 elements, 624,384 elements, and 861,823 elements, respectively. The grids consist of hexahedron-only elements. In contrast to grid topologies where the centerline becomes the axis of singularity around which wedge type elements are generated, in this all-hexahedron mesh, there is no axis of singularity (see Figure 3).

Since the computational code allows for unstructured elements, the hexahedron elements can be constructed in any arbitrary arrangements relative to each other. This allows some degrees of freedom for creating the grid which in turn accelerates the grid generation process. The grid generation part of the computational work took approximately one week to complete. Although creation of the all-hexahedron grids requires more effort, relative to tetrahedron grids, but it reduces overall number of elements required to achieve the same solution accuracy.

The Gridgen software is used to create all the grids used in the numerical simulation reported in this paper.



- **Hex-only Mesh**
- **No Axis Singularity**



- **Hex-wedge Mesh**
- **Axis Singularity**

Figure 23. Centerline region grid topologies.