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**CONSOLIDATED TACTICAL NETWORK ANALYSIS FOR
OPTIMIZING BANDWIDTH: MARINE CORPS SUPPORT
WIDE AREA NETWORK (SWAN) AND TCP
ACCELERATORS**

by

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September 2009

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BANDWIDTH: MARINE CORPS SUPPORT WIDE AREA NETWORK (SWAN)
AND TCP ACCELERATORS**

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ABSTRACT

In 2004, the Support Wide Area Network (SWAN) system added significant capability to the way Marines communicate on the battlefield. Today, the SWAN system is still a critical segment in Marine communications and the TCP accelerator is being evaluated for a potential upgrade. Due to the rapid nature of the SWAN procurement process, in-depth testing procedures have never been established for this system. As a result, there are no procedures to effectively test and evaluate SWAN components for equipment upgrade.

Currently, MCSC relies on two IT consulting agencies, the U.S. Army Information Systems Engineering Command and the SWAN lab on Camp Pendleton to evaluate components being considered for upgrade. This thesis explores these testing approaches, specifically addressing the TCP accelerator. It also evaluates the testing efforts and combines them into a single, standardized, repeatable and more accurate test that can be applied to the SWAN system or any other tactical Marine Corps network and their components.

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LIST OF ACRONYMS AND ABBREVIATIONS

ACK	Acknowledgement
BER	Bit Error Rate
BFT	Blue Force Tracker
BLOS	Beyond Line-of-sight
C2PC	Command and Control Personal Computer
COTS	Commercial Off-the-shelf
DISA	Defense Information Systems Agency
DoD	Department of Defense
DSN	Defense Switched Network
FEC	Forward Error Correction
FTP	File Transfer Protocol
GUI	Graphic User Interface
HTTP	Hypertext Transfer Protocol
IETF	Internet Engineering Task Force
IP	Internet Protocol
IT	Information Technology
JNN	Joint Network Node
LAN	Local Area Network
MAC	Media Access Control
Mbps	Megabits per second
MCSC	Marine Corps Systems Command
MCTOG	Marine Corps Tactics and Operations Group
MCTSSA	Marine Corps Tactical Systems Support Activity
MCO	Marine Corps Order

NACK	Negative-Acknowledgement
NIPRNet	Nonsecure Internet Protocol Router Network
NORM	NACK-Oriented Reliable Multicast
NPS	Naval Postgraduate School
NTAS	Network Traffic Analysis System (NTAS)
QoS	Quality of Service
PEP	Protocol Enhancing Proxy
RF	Radio Frequency
RTO	Retransmission Timeout
RTT	Round Trip Time
SCPS	Space Communications Protocol Standard
SIPRNet	Secret Internet Protocol Router Network
SMTP	Simple Mail Transfer Protocol
SNACK	Selective Negative Acknowledgement
SWAN	Support Wide Area Network
SYN	Synchronization
TCP	Transmission Control Protocol
UDP	User Datagram Protocol
UNP	Urgent Needs Process
USMC	United States Marine Corps
VSAT	Very Small Aperture Terminal
WAN	Wide Area Network
WAAS	Wide Area Application Service
WWSS	World-wide Satellite Systems
WPPL	Wireless Point-to-point Link

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Education is earned, never given.

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I. INTRODUCTION

During the 2003 invasion of Iraq (Operation Iraqi Freedom, OIF), the United States Marine Corps (USMC) quickly outgrew the tactical network it was operating. Ground Combat Elements and embedded Logistic Combat Elements moved twice a day, resting for one or two days after every three to four days of movement. The Air Combat Element moved every 7–10 days and subordinate Command Combat Elements moved every one to two weeks, with similar rest schedules (B. Cornell, personal communication, July 2, 2009). This type of movement dispersed combat elements further than anticipated, extending Marine units beyond the design of their communications equipment. To maintain mission coordination of this rapidly-advancing force, the USMC required a network that could be rapidly deployed and provide Beyond Line-of-sight (BLOS) communication capability; the system acquired was the Support Wide Area Network (SWAN).

This BLOS capability was so critical that the normal acquisition process would not be sufficient to fill the need, so the Marine Corps initiated a rapid acquisition process known as the Urgent Needs Process (UNP). This process “synchronizes abbreviated requirements, resourcing and acquisition processes in order to distribute mission-critical warfighting capabilities more rapidly than the deliberate processes permit” (United States Marine Corps, 2008). Additionally, since communicating over the horizon was not uncommon to the commercial sector, a Commercial Off-the-shelf (COTS) solution was chosen to help accelerate the procurement process.

The SWAN system extends Internet services across a BLOS gap and the Wireless Point-to-point Link (WPPL) system distributes those Internet services to forward positions that have line-of-sight radio connectivity¹ to the transmission source. This system was also procured via the same UNP under the same

¹ WPPL can also provide non-line-of-sight service by reflecting the signal off of the atmosphere when conditions are right; however, the range is limited.

statement of need. While this research focuses on the SWAN system, both systems share an important characteristic: they are routable networks that extend Internet capability to Marines operating in remote locations. Being routable allows these networks to fit into the already established internet (little 'i' internet, meaning the Marine Corps network). This routing characteristic has a layered architecture that allows technology to be easily inserted or upgraded without changing the entire system.

The SWAN system has added significant capability to Marines Corps tactical networks. However, through the accelerated procurement process, several standard procurement phases were bypassed to get this equipment into the hands of Marine in combat. Specifically, developmental testing was not required and operational testing was conducted to a limited extent. Developmental testing was not required, since the system was a collection of COTS components that had already been proven to work in the commercial sector; there was no new technology to develop. Since it was a proven commercial solution, operational testing was limited in the interest of time. This allowed testing standards to escape documentation.

Any information technology (IT) solution will eventually require an upgrade. In a March 2009 report, the Defense Science Board Task Force concluded that the "conventional DoD acquisition process is too long and too cumbersome to fit the need of the many IT systems that require continuous changes and upgrades" (Office of the Under Secretary of Defense, 2009, p. iii). Their primary recommendation is to develop "a new acquisition process for information technology . . . [that] is agile and geared to delivering meaningful increments of capability in approximately 18 months or less" (p. iii). Additionally, Moore's Law,² which predicts that IT will double every two years, suggests that

² Moore has stated that he has been misquoted on this law. He originally predicted that complexity was doubling every year, referring to the number of components on a microchip. He later changed it to two years; however, Moore's Law is commonly accepted as 18 months to two years. (Intel 1).

there might be better components available for the SWAN system. One reason IT components can advance so rapidly is that there are hundreds of vendors competing to create the next technological advancement.

The USMC is exploring a replacement for the Transmission Control Protocol (TCP) accelerator, a component in the SWAN system. Since so many companies produce TCP accelerators, how does the Marine Corps choose which one to purchase? Currently, the Marine Corps has three organizations providing input on TCP accelerator platform performance, each conducting their own testing independent of each other. None of these tests accurately represents a Marine Corps tactical network, producing test results that are inaccurate and limited in their usefulness. Additionally, these results cannot be compared to each other, since testbeds and test plans are so vastly different.

The SWAN system is a collection of COTS components that were designed to optimize network flows in the corporate business environment, and not around military requirements. While this COTS solution allowed the Marine Corps to deliver capability to the warfighters quickly and inexpensively, it also meant that the components might not perform optimally in the warfighter's environment since warfighter network traffic patterns are different from commercial networks.

Consider the TCP accelerator, which was designed to optimize corporate use of bandwidth. This device was originally developed to help TCP connections negotiate long delays experienced by large corporations transmitting data over extended distances, such as a credit card company that backs up its databases via satellite or, perhaps, needs to send that data across the transatlantic cable. Both environments have significant delays that degrade the performance of the TCP, the required Internet protocol for this task. Additionally, corporations primarily employ these devices during off-peak times, when bandwidth is cheapest because link congestion is minimal. These connections can be described as sustained, one-to-many, authenticated links.

Compare Blue Force Tracker (BFT) traffic that differs in several ways. This system consists of multiple users constantly updating their positions, constantly entering and exiting the network. These networks consist of short, 'chatty,' many-to-many links that also require authentication and use both TCP and the User Datagram Protocol (UDP). Additionally, these links have a greater probability of being asymmetric and, since they can be located in austere environments, connections may be intermittent due to troop movement or poor connectivity. This illustrates how the TCP accelerator, designed for corporate use and implemented into tactical networks, may not perform optimally for the warfighters.

Being designated a COTS product means that commercial manufacturers performed the research and development, reducing unit cost to the Marine Corps and allowing it to be procured quickly. Each manufacturer individually conducts tests to gather data and compare their product to other vendor devices. Relying on commercial vendor-generated data alone will lead to poor product selection for several reasons. First, vendor reports can bias their own equipment, making it look more capable than it actually is. Second, testbeds between vendors vary drastically, which means test data cannot be accurately compared between vendor claims. Third, vendors do not test how compatible their accelerator may be with current Marine Corps accelerators. Last, and most important, vendor testbeds do not accurately portray the environment in which the Marine Corps will be employing the device. These problems are not surprising since vendors are competing for a government contract, and they want their product to look the best. The bottom line is that the Marine Corps needs to verify that these components will actually fulfill the requirements it has for the devices, under the conditions in which they will be employed.

A. THESIS OBJECTIVES

This thesis will analyze current SWAN testing procedures, with the primary objective to create a standard, repeatable test that represents tactical SWAN

traffic generated by Marine operating forces. The secondary objective is to test and evaluate TCP accelerators and generate data that can be used to help determine the 'best of breed' accelerator for the Marine Corps' need. To accomplish these objectives, a progressively robust test plan will be produced, based on previous tactical network research, and then that plan will be executed over an actual SWAN link. Currently employed TCP accelerators will be base-lined with the test plan, and that data will be compared to data generated by accelerators being considered for purchase. The accelerators will be tested at the Marine Corps Tactical System Support Activity's (MCTSSA) SWAN lab on Camp Pendleton. This testbed is a replica of what Marine operating forces are currently using in Iraq.

B. RELATED WORK

1. Naval Postgraduate Thesis Work

a. *"Optimizing Bandwidth in Tactical Communications Systems"*

The thesis "Optimizing Bandwidth in Tactical Communications Systems," written by Captain Criston Cox, USMC, specifically explored TCP accelerators (Cox, 2005), in an effort to optimize the use of bandwidth, an increasingly limited resource in high demand. Cox explained that even if the full amount of bandwidth in a SATCOM link were available, it would still not be enough to support the number of users found in a division or higher. For this reason, he explains the importance of effective bandwidth management.

The problem Cox addresses is extending the usefulness of the Internet to remote users. While the wired Internet has a high capacity, measured in gigabytes, SATCOM Internet services are funneled into megabits. These space links also have a much greater propagation delay than terrestrial links: respectively, hundreds of milliseconds versus milliseconds. Additionally,

these SATCOM services have many customers under a single satellite footprint. To provide Internet services to many customers through a limited channel requires bandwidth optimization.

Cox outlines several optimization techniques, including compression, caching, and quality of service (QoS), all part of the protocol enhancing proxy (PEP) functionality. All of these techniques are used in today's modern PEP devices, which are also known as TCP accelerators. At the time Cox's thesis was written, SkyX, ComTech (TurboIP), Expand and Peribit were the top PEP vendors. The difficult decision then, like now, was in figuring out which COTS vendor produced the best product for the Marine Corps. To complicate this matter, the Army was also working on procuring and/or updating their own PEP devices.

Cox used the Network Traffic Analysis System (NTAS) to monitor traffic from three different exercises/operations: UFL 04, CG04 and OIF II. He states "NTAS data confirmed the top four protocols of these networks as HTTP, SMTP, FTP and UDP" (p. 50). This traffic was then simulated in the lab during his research using an Application Configuration Utility.

Cox conducted his tests at the MCTSSA SWAN lab on Camp Pendleton. He simulated traffic through a series of switches, routers, accelerators and modems, connected to create a network that would facilitate his accelerator tests. His traffic was then pushed across a simulated satellite link. The network traffic reflected multiple users, using several protocols simultaneously in both directions across the link.

Concepts relevant to this research include: 1) interoperability is not a priority of COTS vendors; 2) caching can save bandwidth when files are being shared regularly over time, allowing for the accelerator device's memory to build up; 3) throughput is a dynamic metric, dependent on many variables; and 4) the top four protocols observed on tactical networks are HTTP, SMTP, FTP, and UDP.

b. “A Conceptual Framework for Tactical Private Satellite Networks”

Brian Conrad, USMC, and Ioannis Tzanos, Hellenic Navy, outline the importance of, and high demand on, satellite communications, especially providing access to lower echelons of command (Conrad & Tzanos, 2008). They state that SWAN provides broadband connectivity, “allow[ing] smaller units access to critical information not previously available” (Conrad & Tzanos, 2008, p. 58). Additionally, SWAN uses commercial bandwidth on COTS equipment, operated by Marines. This capability has transformed USMC communications; however, “the limitations on what kind of information can be passed over this network are constrained by the capacity of the communications link between terminals” (Conrad & Tzanos, 2008, p. 59). Basically, the authors are saying that this communication link is critically important to successful operations, and there is not enough satellite bandwidth to facilitate all the traffic Marines want to push over this link. Since satellite bandwidth is expensive, the smart use of available bandwidth is critical. Updated TCP accelerator technology may contribute to the solution.

Conrad and Tzanos' thesis focused on the architecture of tactical satellite networks, of which SWAN is but one. C2 On-the-move Network, Digital Over-the-horizon Relay (CONDOR) is another system that puts broadband connectivity in the hands of units on the move, consuming more bandwidth. If new accelerator technology can more efficiently use the bandwidth consumed by SWAN traffic, then the saved bandwidth can be used by other users and systems, or perhaps these devices can be scaled to smaller, more mobile platforms.

2. Commercial Information Technology Organizations

Due to the rapidly changing nature of today's technology, the Marine Corps contracts commercial IT consultants to advise on the procurement of IT systems and devices. The following is a description of two of those organizations that are involved in the SWAN system.

a. *MITRE*

MITRE is a "not-for-profit corporation that provide[s] engineering and technical services to the federal government" (MITRE, 2009). They have been in business since 1958, and have earned an international reputation for technical excellence and innovation. MITRE manages four federally-funded research and development centers. One of those centers is for the Department of Defense (DoD), known as the DoD Command, Control, Communications and Intelligence center ("MITRE"). One of the projects being worked on under this contract is the testing of TCP accelerators for the Marine Corps' SWAN system.

While this organization has 7,000 employees working on hundreds of projects, satellite bandwidth is still too expensive for testing purposes. Therefore, MITRE conducts their testing with a satellite simulator. Additionally, since this company does not have access to actual SWAN terminals, they must test accelerators as an independent component on a mock-up terminal.

Over this simulated link, MITRE uses a standard FTP get command to retrieve various file sizes, a stepped approach to putting a load on accelerators. File sizes range from 2 KB to 10 MB. To avoid artificial performance results from TCP accelerator device caching, MITRE adds variation to their files that are being retrieved, simulating a modification to a shared file. Other protocols are tested; however, they are tested in isolation, without other traffic that may be found simultaneously on the tactical network.

MITRE's objective is to test, validate, and compare throughput performance on various TCP accelerator devices in order to advise the Marine Corps on the best product to buy.

b. Sidereal Solutions Incorporated

Sidereal Solutions provides network engineering, satellite communications engineering, technical training, and information technology services to government and commercial entities. Sidereal has a proven track record of excellence and superior service, therefore developing long-lasting relationships while providing significant value for the customer (Sidereal, 2009).

Sidereal (sī-dir-ē-əl) is a small company based in Suwanee, GA, that employs 40 IT professionals, network engineers, and consultants. They provide general support to the Marine Corps for the SWAN system. They have developed several SWAN training and technical manuals for all variants of the SWAN system, and have taught several classes around the world on the systems, to include both the Marine officer course in Quantico, VA, and the enlisted Marine course in Twentynine Palms, CA.

Sidereal is built on intellectual capital, focusing on providing the best service to their customers worldwide. They have a limited testing capability, none of which is for SWAN; however, they have an exceptionally strong relationship with many vendors that manufacture devices compatible with SWAN terminals. Sidereal employees sometimes know more about a vendor's product than the engineers that were on site during this thesis research. They obtain this knowledge by forming and maintaining long-lasting relationships with various vendors, both large and small, and by keeping up-to-date on the latest advancements in networking technology.

While Sidereal does not actually test SWAN components, they do travel to test locations, Marine Communications Schools and remote areas where Marines are deployed using the SWAN system, to provide support. For this research, James Willard, general manager and vice president of Sidereal Solutions, was present during the week of accelerator testing at the Marine Corps' request to provide technical expertise on testing methodology and accuracy.

3. Marine Corps Tactical Systems Support Activity (MCTSSA)

MCTSSA is the “Marine Corps’ organization for integration, interoperability and technical support for tactical C4I systems . . . [They] ensure Marines continue to win battles by:

- Providing technical support in acquiring and sustaining C4ISR products for the operating forces;
- Providing technical support to the Operating Forces for fielded command and control system;
- Providing technical support for systems engineering and integration; and
- Fulfilling the role as the Marine Corps Joint Test Facility for C4I tactical system” (“MCTSSA,” n.d.).

This organization is a West Coast component of Marine Corps Systems Command (MCSC) based out of Quantico, VA.

While MCTSSA is set up to support Operating Forces with respect to communication and networking equipment, they also have the capacity to test and evaluate that equipment and COTS components. The SWAN lab at MCTSSA is continuously involved in the testing of some communications device. For the past several years, they have been testing different TCP accelerators.

One of the most significant and recent findings during the SWAN lab accelerator testing effort in April 2009 was that the TurboIP and the TurboIP G-2 devices were not interoperable with each other. The G-2 is an accelerator that was designed as an upgrade to the TurboIP device. Logical implementation of procured devices is that it should be done gradually, naturally requiring device interoperability. The SWAN lab informed the vendor, who promptly fixed the problem. Testing for this thesis includes interoperability testing to verify vendor claims.

The SWAN lab’s current testing procedure is to conduct FTP get commands of various file sizes (1 mb, 8 mb and 24 mb). The application used to do this is FileZilla, a free open-source program available online. This is a quick

and easy method that can identify which accelerators actually accelerate network traffic, and whether certain devices are compatible. This approach is not representative of actual SWAN traffic.

The personnel at the SWAN lab are motivated to test such equipment to provide data on the best accelerator. They have access to the latest gear the Marines are using in Iraq and Afghanistan. They also have access to actual satellite airtime, making this testbed the most representative of the Marines' operating environment.

4. U.S. Army Information Systems Engineering Command

The SWAN system was rapidly procured using the Army's World-wide Satellite Systems (WWSS) contract, "designed to fund existing and projected bandwidth constraints for DoD transformation programs" (Pike, 2008). At the time, the Army was testing components for their Joint Network Node (JNN) system, which is very similar to SWAN. Both systems being COTS systems, and the DoD's guidance of system interoperability, made the procurement decision easy for which brand of accelerator to be purchased. At the time, ComTech's TurboIP accelerator was the choice made by the Army.

The U.S. Army continues to test TCP accelerator devices for various reasons, most recently for Standard Tactical Entry Point (STEP)/Teleport compatibility. The Army has procured at least three different brands of accelerators for various systems. Their criteria for choosing a vendor is based on current literature reviews, that the devices are Space Communication Protocol Standard (SCPS) compliant and best performer in the Army's testbed.

Their testbed consists of actual equipment employed by Army communicators, linked though a satellite simulator. They use IXChariot as a traffic generator and a stepped approach to testing, which progressively loads the network to see how the accelerators perform. Additionally, they add background traffic to simulate other users utilizing the same link simultaneously.

5. The Problem with Current SWAN Evaluations

Despite all the effort and money going into testing SWAN components, current systems in Iraq still have the same TCP accelerator components that were procured over four years ago. The Army is testing accelerators; the Marine Corps is testing accelerators; and the Marine Corps has hired IT consultants to test and evaluate accelerators. None of these agencies have coordinated their actions, or shared testing procedures or test data. Thus, there are three different efforts to provide better equipment for Marines operating in austere locations, with no conclusive or persuasive decisions.

While these efforts are for the same cause, each produces results using a different method. Some organizations use single protocol tests while others use multiple protocol tests. Some use a single, one-way connection, while others use several bi-directional connections. Even the file sizes that are being used are vastly different. Testbeds are another variable, making these efforts more complicated than necessary. Some testbeds have simulated pieces while others are entirely simulated. Every organization is testing a different pool of vendor components. With so many options producing multiple, incompatible outputs, there is no consistency of data from which a decision can be made.

Another contributing factor that must be addressed is the growing demand on satellite bandwidth, and its increasing cost. As smaller systems are being fielded, making satellite bandwidth more accessible to a greater number of warfighters, the strain on available bandwidth is exacerbated. Thus, it is important to aggressively manage the bandwidth that is available and modern accelerators are designed to do just that. The question remains—which accelerator should be purchased?

Technological advancements continue to develop more rapidly than the acquisition process can facilitate. TCP accelerator technology has matured significantly since the recent TurboIP devices were installed in the SWAN system, and the Marine Corps has not taken advantage of it. A possible solution

to help streamline the procurement of advancing COTS technology, in this case the TCP accelerator, is to consolidate and standardize testing efforts. This thesis will attempt to consolidate those efforts and create a test plan that can be shared, implemented, and repeated across organizations. This will allow test data to be replicated and verified to ensure requirements are met, facilitating quality purchase decisions.

C. THESIS ORGANIZATION

This thesis is organized as follows. Chapter II presents information regarding the architecture, protocols, and technologies used in SWAN networks. Chapter III discusses how experimentation for this research was designed and describes the test template. Chapter IV analyzes the data that was captured during product review and experimentation. Chapter V presents conclusions, makes recommendations drawn from this research, and provides suggestions for future research regarding tactical network evaluations and bandwidth optimization. Chapter VI will summarize the research presented in this thesis.

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II. TECHNOLOGY BACKGROUND

This chapter outlines the protocols that make the Internet possible, and how those protocols are used by the SWAN system to extend the Internet onto the battlefield. Most readers of this thesis will have an understanding of the protocols mentioned; however, there are a few that are not so well known. The purpose of this chapter is to clearly define the SWAN link, and illustrate the several interacting protocols that make this capability possible.

A. NETWORK ARCHITECTURE

The Internet can be illustrated by what is commonly known as the Open System Interconnection (OSI) Seven-layer Model (Figure 1). This model depicts six virtual channels, one between each layer, which function over one physical channel also known as the transmission medium. Layers 1–3 and half of layer 4 handle the transportation of data between hosts, while the other half of layer 4 and layers 5 through 7 handle how the application operates and interacts with the user.

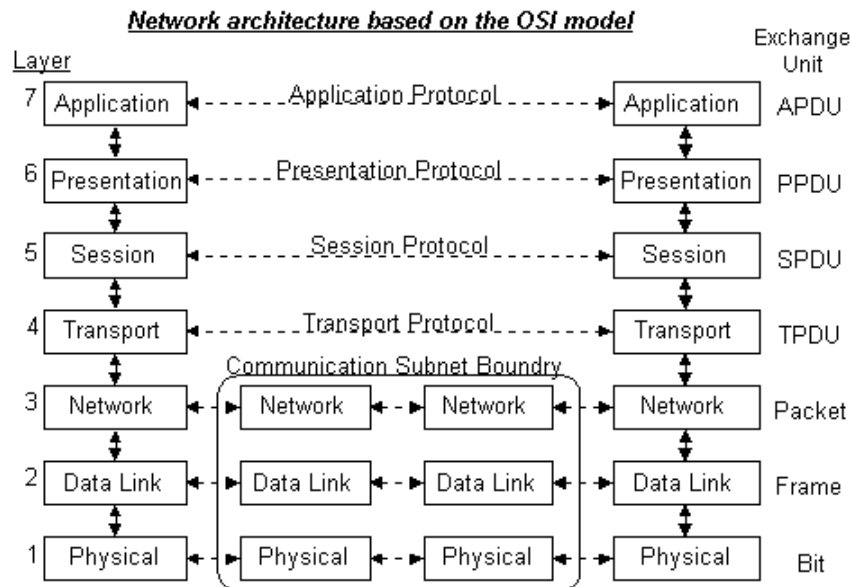


Figure 1. OSI Seven-layer Model (From Cote', 2008, p. 14)

Layer 1 is required for any two hosts or users to communicate. This physical layer is what 1s and 0s, or bits, are transmitted on to deliver data between hosts. This layer can be copper wire, fiber optic cable or even the atmosphere when referring to wireless radio frequency (RF). It is the medium by which two devices are connected.

The other six layers are considered virtual channels because they do not physically connect to each other. They are connected by computer protocols that are transmitted over the physical layer. The relationship between layers is made possible through encapsulation (Figure 2), where a higher layer gets encapsulated inside the lower layers. Think of encapsulation as a series of envelopes, where layer 7 data is put into an envelope with layer 4 headers, and layer 4 headers are put into another envelope with a layer 2 header. At this layer, all the envelopes are then transmitted over the physical layer as 1s and 0s.

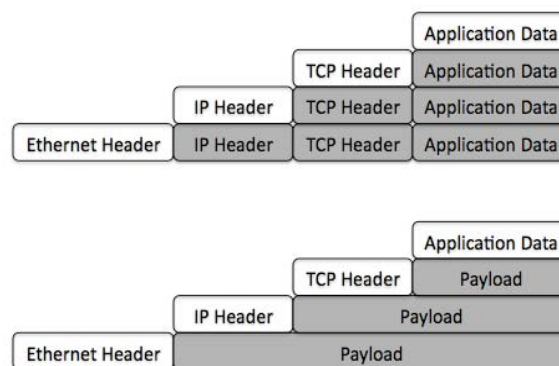


Figure 2. Encapsulation (From Fulp, 2009, p. 11)³

Layer 2 is also known as the data link layer. It provides the instructions on how the data will be formatted and transferred across the physical layer between computers. The layer 2 Ethernet header, shown in Figure 2, is only one of many possible layer 2 protocols, but it is the most common. Ethernet is a frame-based technology that allows computers to be linked together to form a Local Area

³ The top encapsulation drawing illustrates what is physically happening to the data. The bottom drawing illustrates what each layer is experiencing (Fulp, 2009, p. 11).

Network (LAN). What is most important to note about the Ethernet framing structure is that it is reusable, which makes the integration of existing and future components easy as long as the standard is adhered to.

The layer 2 addressing scheme is known as the Media Access Control (MAC) number or burned in address (bia). This address is unique to a device's NIC and it has the following 12-hex digit format: 00:0c:39:72:6a:79. The device that 'speaks' layer 2 language is called a switch. Switches reduce network traffic by consolidating which hosts see certain network traffic. They do this by matching a particular host to one of the switch's port numbers. When traffic from a host enters through a switch port, the switch associates one of its particular port numbers with a specific end user's MAC address and stores that host's location on the switch. Then, when any traffic with that particular MAC address arrives, it only forwards the traffic to those hosts on that port. So, instead of broadcasting all network traffic to every end user on the network, the switch sends the traffic to the specific port where the end user resides. Briefly, a switch provides hop-to-hop data delivery on the same network.

The network layer (layer 3) provides end-to-end (source to destination) packet delivery for computer communications that occur between different networks. The layer 3 addressing scheme is known as the Internet Protocol (IP) address. This address scheme is hierarchical, meaning there is a network identification part (172.30.XXX.XXX), and a host identification part (XXX.XXX.193.10). Network size and configuration determine where the network and host portions of the IP address are defined, but the format (XXX.XXX.XXX.XXX) is the same for all IP addresses. The IP address is found in the IP header, which leads the datagram through the Internet.

Layer 4, the transport layer, interacts with layers 3 and 5 to establish and manage the end-to-end connection or session. Layers 5 through 7 interact with the user on the user's terminal. All seven layers are indifferent about the

components and transmission mediums that connect the two terminals. Layer independence creates the 'virtual connections' alluded to earlier and are key to the flexibility of the Internet.

1. Local Area Network (LAN)

At the infancy of the Digital Age, a single dedicated line was used to allow one computer to communicate with one—and only one—other computer. This connection was typically done with a wire called twisted pair; today it is done with category 5 cable (Cat V cable). The purpose of this direct connection was speed, provided by universal, physical connections inside the computer, called sockets. Sockets are connected, one to another, and then to other parts in the computer by wires. These wires carry data and power for various components in the form of electrical current.

A cable connected the first two computers that were linked together to transfer data. Each end of the cable was connected to a circuit board, which was plugged into a socket. Since a socket has the fastest access to a computer's memory, this direct connection facilitated 'wicked' fast speeds of data transfer between the two computers. This provided each computer direct access to the other computer's memory, making data access no different than accessing a computer's own memory. While this method of communication was fast, there was one big disadvantage: scalability.

It "required considerable effort to add a new computer to the network" (Comer, 2007, p. 50), since two computers needed to have the same circuit boards and a dedicated cable. But, what if computer A needed to be connected to two or more other computers at the same time? Computer A would need one circuit board and one wire for each connection, for a total of two circuit boards and two wires. Computers B and C would each have one circuit board and one wire connecting to computer A. Additionally, if computers B and C wanted to

connect, they would each need another circuit board and wire. Simply put, for every new computer added to the network, the number of connections doubled. The development of LANs solved this problem.

LANs were made possible by a component called a Network Interface Card (NIC). The NIC standardized how computers connected to LANs, thereby decreasing the number of connections in a network. For example, a network of six computers connected point-to-point would require 15 connections:

$$\frac{n(n-1)}{2}$$

where n is the number of computers (Metcalf's Law). A LAN utilizing NICs only requires n connections. Figure 3 illustrates Metcalf's Law and the beauty of LAN technology. Network scalability was the most significant change that LAN technology produced.

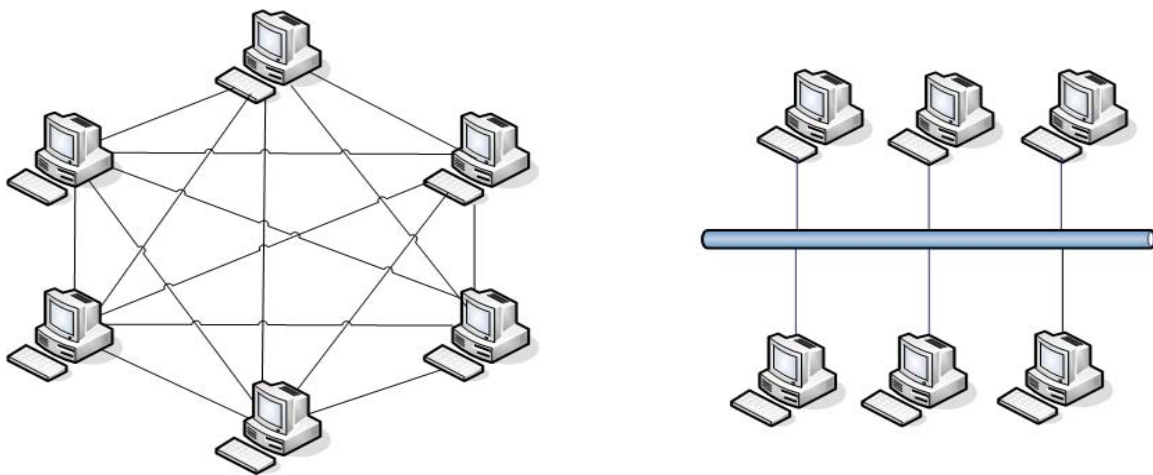


Figure 3. Network without (left) and with NICs

LANs are where the end users reside. They are created by connecting user terminals to each other and to other components, such as printers or file servers. While LANs have no definitive beginning, they have multiple ends or end users. These end users connect to share data and resources efficiently. When an end user from a LAN requires a connection to another LAN a router is

needed. A router is the gateway to other networks. They are layer 3 devices that make network-to-network connections possible and therefore create internetworks.

a. *Internet Protocol (IP)*

The glue that holds LANs and the Internet together is known as the TCP/IP protocol suite. It is called a suite because it is a collection of many protocols, TCP/IP being the most fundamental and frequently used.

A protocol is a common language by which computers communicate. It is a set of rules or standards used by computers to convey, transfer and share information across a network. These rules can be implemented at the hardware or software level, or using a combination of the two. The IP is a software protocol that facilitates basic computer communication. "The IP provides for transmitting blocks of data called datagrams [or packets] from source to destination, where the source and destination are hosts identified by fixed length addresses" (Postel, 1981, RFC 791, p. 1). These addresses are naturally called IP addresses.

The IP simply specifies how packets must be formed. Its simplicity provides for the required flexibility that facilitates networking. The protocol is both stateless and connectionless. Stateless means packets can traverse the network and arrive in any order. Connectionless means that packet delivery is unreliable or that there is no acknowledgement or verification of delivery. The IP standard accommodates a variety of underlying network technologies. WANs and LANs can connect regardless of network speeds, connection-orientation, or physical medium (wired, wireless, radio, fiber optics, free space optics, etc.) as long as the IP is adhered to. This packet formation is understood by all components in the network, which allow the packets to be routed from its source to its destination. Additionally, since IP is a published standard specifying exactly

how packets need to be formed, multiple vendors can design network components that are interoperable, making IP the protocol that stitches LANs and WANs together.

The IP header or preamble to the packet (Figure 4) contains the layer 3 IP addresses that get read by layer 2 devices (switch). This is encapsulation at work and the underlying principle that makes internetworking flexible.

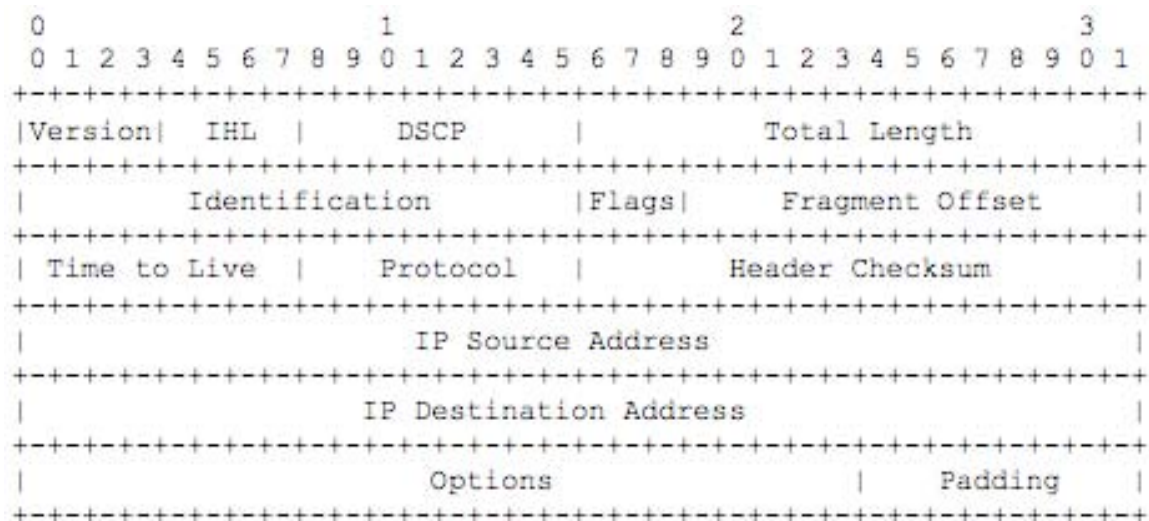


Figure 4. IP Header (From Postel, RFC 791, p. 11)

2. Wide Area Networks (WAN)

A WAN is nothing more than two or more LANs connected to each other through routers, extending the reach and size of a network. They are the proverbial Internet 'cloud' that extends the reach of the Internet over a broader geographical area. These networks can be linked by any number of physical connections such as: leased telephone lines, fiber optic cables, free space optics or satellites, both terrestrial and/or space. No users connect to the WAN, only routers. Users exist on LANs extended off of the opposite side of the router. This research focuses on wireless, satellite WAN connectivity.

a. *Terrestrial–Wide Area Network (T-WAN)*

T-WANs extend communication over distant geographical areas and are generally connected by cable and fiber optics. An analogy would be how a home computer connects to the largest network in the world, the Internet, via an Internet Service Provider (ISP). The home computer is physically connected to the telephone company's wires running along the street. For military applications, T-WANs require a significant military presence since the security of the cables must be protected for the network to function reliably.

An example of a military T-WAN would be the network on the Al Asad Airbase, Iraq. This network spans both the north and south sides of the airfield, integrating ground, aviation and logistic combat elements, which includes several units and thousands of warfighters.

b. *Radio Frequency–Wide Area Network (RF-WAN)*

RF-WANs allow networks to span larger geographical areas without the burden of physical infrastructure and security, though RF signals do require some protection from jamming. This is accomplished by using the atmosphere and the wireless transmission of data. These are the networks that are most desired in remote locations where warfighters have limited to no communication infrastructure. These WANs are also useful when two T-WANs located in a combat area are separated by a significant geographical measure and there is a need for those networks to communicate.

In this case, as with all other WANs, end users do not directly connect to it. Instead, users connect to the LAN, which in turn gets connected to a router, and all the router traffic is transmitted via radio signal to the next router. Thus, any two LANs are simply one router hop away from each other and WANs allow them to connect over large distances. There are two RF-WAN systems in the Marine Corps: WPPL and SWAN.

(1). Wireless Point-to-Point Link (WPPL). WPPL is a communication system that provides WAN connectivity over distant geographical areas with high-powered antennas. It is generally provides a line-of-sight connection, however, the RF signal can be bounced off the atmosphere for non-line-of-sight connectivity if the atmospheric conditions permit. Specific to the Marine Corps, these networks exist in Iraq. One example is the WAN connection between the router at Camp Fallujah and the router at Al Taqaddum Airbase, which are separate by 20 miles (32 km).

The advantages of WPPL connectivity are that no wires need protection between the LANs and it does not require capacity limited satellite access, as it is a terrestrial system. A limitation to WPPL is that the antennas require an almost unobstructed, direct line-of-sight view of each other. This means that terrain, buildings, or weather could potentially reduce this system's functionality. It is effective in Iraq because the terrain is relatively flat and the cultural centers do not build excessively vertical; it is not as flexible in Afghanistan where the terrain is more rugged.

(2). Support Wide Area network (SWAN). SWAN is a communication system that provides WAN connectivity over distance geographical areas via satellite connection. This system was procured as a BLOS system. It has the same set up as a WPPL; however, these antennas can access satellites, overcoming the direct line-of-sight limitation in WPPL. These systems are deployed in Iraq, Afghanistan and the Horn of Africa.

The advantages of SWAN connectivity are that no wires need to be protected between the LANs and direct line-of-sight is not required, so terrain and vertical development are not as limiting to communications. This aids in extending the Internet into remote locations. The greatest limitation to SWAN systems is that it provides connectivity through space, where the point-to-point relay is 22,300 miles away, which causes long transmission delays. This is the primary problem with SWAN links: long delays.

(3) SWAN vs. WPPL. There are important differences that exist between these two networking systems. WPPL systems can connect networks separated by double-digit miles with double-digit capacity, both values depending on separation, atmospheric and terrain in between. The connection delays experienced on these systems are double double-digit milliseconds (ms). SWAN systems connect networks that are separated by hundreds or thousands of miles, provides single digit Mbps capacity and experience delays in excess of 500 ms. This highlights the second problem with SWAN links: funneling high capacity data across a low capacity link.

	Distance (miles)	Capacity (Mbps)	Delay (ms)
WPPL	< 50	10-50	< 50
SWAN	0 to Thousands	< 2.5	> 500

Table 1. Summary: WPPL vs. SWAN

3. LANs and WANs

LANs are comprised of many users that share a connection via wires and/or fiber optic cables, all located within relative close proximity. This close proximity allows for very short propagation delays, on the order of fractions of milliseconds (ms). Short distances also allow large network capacities, generally measured in Gigabits (Gb). There are no differences between military and commercial LANs, it is the capacity and delay that are important to note.

WANs are comprised of routers that connect LANs over a much broader geographical area; they are contained inside the network. They can be connected via wires, fiber optic cables or wirelessly by antennas or satellites. This research focuses on the SWAN system, which wirelessly connects LANs separated BLOS. Propagation delay for these networks is on the order of hundreds of milliseconds (ms) and capacity is generally measured in Megabits (Mb), at least three orders of magnitude smaller than LANs. Again, these properties are not very different between commercial and military networks. Comparing delays and capacities between LANs and WANs highlights the

problem being investigated in this research. Many users on a high capacity, short delay LAN, wanting to use a lower capacity, long delay WAN creates a restricting bottleneck. The problem can be isolated between the routers that connect the two LANs, the very definition of a WAN. The TCP accelerator helps mitigate the problem by making WAN connections behave like LAN connections. This is accomplished by transparently ensuring that data arrives at its destination as quickly and reliably as possible, a layer 4 function.

Layers 1, 2 and 3 of the OSI Model (Figure 1) make up the Communication Subnet Boundary. This boundary of the IP structure is indifferent about whether or not it is on a LAN or a WAN; an illustration of the value and flexibility built into the Internet network structure. There is a difference once layer 4, the transport layer, becomes involved. Transport layer protocols, often referred to as end-to-end protocols, have timing mechanisms that facilitate their operation, and the transmission environment determines the performance of those protocols.

B. END-TO-END PROTOCOLS

End-to-end protocols are categorized in the transport layer (layer 4) of the OSI model. They are instructions on how data is transferred from one end user to another. Remember that the IP (layer 3) provides a best-effort delivery infrastructure. It is layer 4's responsibility to execute that delivery. The transport layer adds a port number after the IP address to properly route the packets to the correct port on the end user's machine. The address scheme now looks something like this: XXX.XXX.XXX.XXX:21.

There are several layer 4 protocols but the two most frequently used are UDP and TCP. TCP provides guaranteed or reliable packet delivery at a bandwidth premium, while UDP provides faster service with no guarantee of delivery (TCP) at minimal bandwidth cost. This research and SWAN networks focus on these two end-to-end protocols.

1. User Datagram Protocol (UDP)

UDP has been called “TCP’s undisciplined little brother” (Fulp, 2009, p. 133). It provides procedures for data to be transferred between programs with minimal protocol mechanisms and therefore does not guarantee delivery like TCP. The protocol is considered connectionless and unreliable and can be thought of as a fire-and-forget procedure. Connectionless means that this protocol does not have to establish a connection with the other end terminal before data is transferred. Unreliable means that data is sent under the assumption that it will arrive at its destination without follow-up to validate delivery. If the packet does not make it to its destination, the sender will never know. The sender will have to make the request again and UDP will attempt to deliver the packet as if it were the first attempt; or in the case of real-time, streaming traffic, the data is no longer relevant and not worth retransmitting.

The benefit of the UDP is that it has low overhead. This is obvious when comparing UDP and TCP headers (Figures 5 & 6). The UDP header is streamlined because it does not have to establish an initial connection, nor does it have to account for connection-oriented criteria such as sequence numbers, acknowledgement numbers, and window sizes. Its unreliable, connectionless nature means that some packet loss, errors or duplication may occur. This is the only useful protocol for communications such as Voice over IP (VoIP), Video Conferencing (VTC), and streaming video where real-time information is key and a few lost packets will not make a difference. Imagine having a cell phone conversation with another person while drive through a tunnel and you miss some of the conversation, this is similar to a lost packet. Now, you can still understand the conversation because the small packets you missed were easy to fill in. Using UDP means that a few lost packets are acceptable.

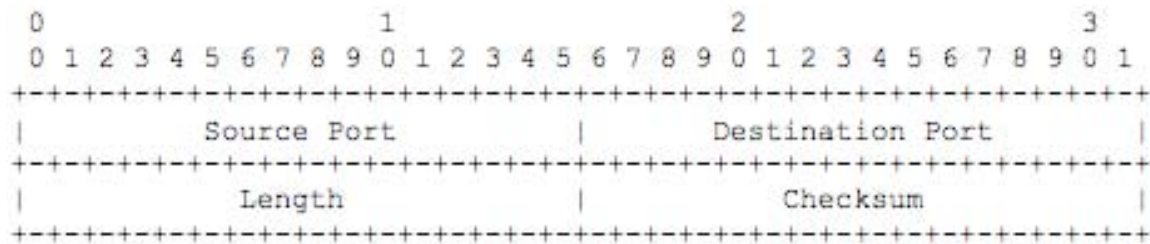


Figure 5. UDP Header (From Postel, 1980, p. 1)

Applications such as Domain Name System (DNS), Simple Network Management Protocol (SNMP) and Routing Information Protocol (RIP) use UDP because they are simple transactions requiring only one request followed by a short reply, if any. Since UDP is connectionless and unreliable, applications that use it require little to no attention in the challenging and lossy satellite environment. However, this is not the type of connection that is desirable for data that requires guaranteed delivery. For these applications, TCP is the protocol of choice.

2. Transmission Control Protocol (TCP)

“The primary purpose of the TCP is to provide a reliable, securable logical circuit or...communication service between pairs of processes in a multi-network environment” (Postel, 1981, p. 3). “Secure logical circuit” here does not mean an encrypted connection, it simply means a dedicated circuit to facilitate packet delivery. This protocol is the responsible, connection-oriented big brother to UDP in layer 4 of the OSI model. Its mechanism provides for packet tracking and accountability through the use of sequence and acknowledgement numbers (Figure 6), and it also attempts to provide efficient use of bandwidth through its sliding window mechanism. All this reliable functionality is designed to ride on top of the less reliable IP. This is what makes the TCP/IP protocol so flexible, functional, and popular.

For the purposes of this research, it is important to understand three parts of the TCP functionality: connection setup, end-to-end reliability, and flow control. Connection setup is classified under the session layer (layer 5) of the OSI model.

This is the additional overhead that UDP does not have. It creates the reliable connection between exactly two end terminals. End-to-end reliability and flow control fall under the transport layer, which facilitates the virtual connections between higher layers in the OSI model.

TCP adds its own header onto the IP header (Figure 6). It contains additional information on how TCP packets will be delivered to their appropriate applications. Specifically, this header adds source and destination port numbers, allowing the packet to map to an application (for example, port 20 maps to FTP control). The source and destination port numbers, the sequence and acknowledgement numbers, TCP flags and window are the central header fields that facilitate the TCP connection.

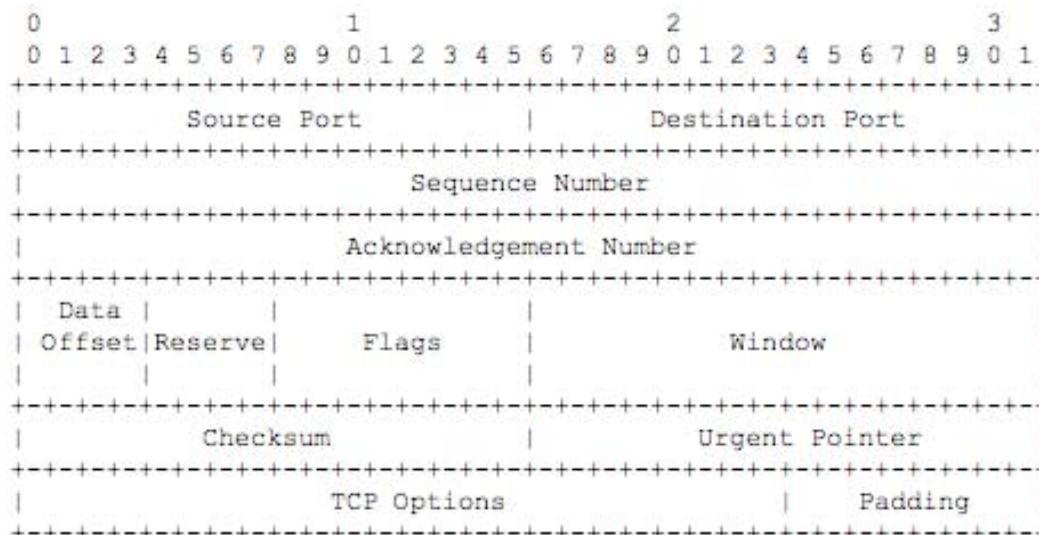


Figure 6. TCP Header (Postel, 1981, RFC 793, p. 15)

Since TCP is connection-oriented, establishing the connection is key. By associating an IP address (from the IP header) and port number on one host, with another IP address and port number on the other host, TCP creates a dedicated connection called a socket pair. The socket pair is established through a process known as a 3-way handshake.

The 3-way handshake is initiated with a request packet that contains no data, only the TCP synchronization (SYN) flag set to 1.⁴ If this packet is received and the receiving host agrees to participate using TCP, then the recipient replies with both the SYN and Acknowledgment (ACK) flags set to 1. The initiator responds with the ACK flag set, completing the 3-way handshake (Figure 7). This process creates a dedicated connection that will provide reliable and accountable packet transfers. The socket pair is called a dedicated connection because network resources are now allocated for this particular link.

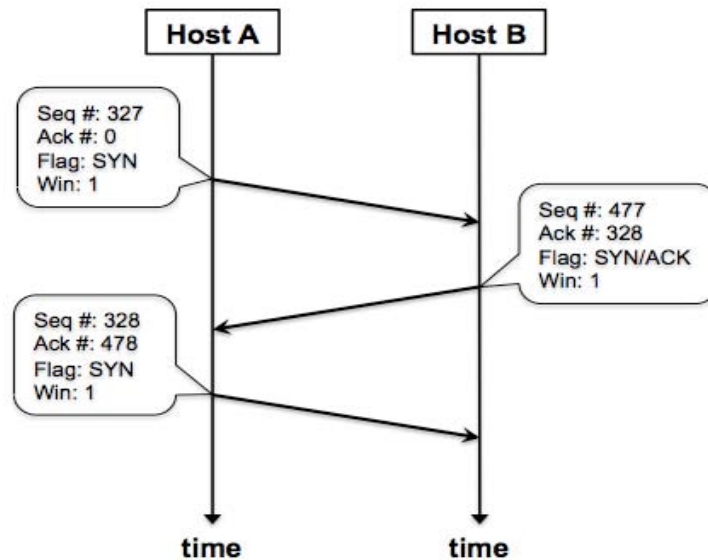


Figure 7. TCP 3-Way Handshake (From Fulp, 2009, p. 143)

Once the connection is established, the TCP accounts for each packet with sequence and acknowledgement numbers, and provides reliability with the same SYN, SYN/ACK and ACK flags used in the 3-way handshake. Data transfers are broken down into small units called packets. These packets are assigned a sequence number allowing them to travel the internetwork via many different routes, arriving at their destination in any order. The TCP buffers these packets until they can be reordered to recreate the original message. These buffers also aid in identifying packet loss, which is part of TCP's 'guaranteed,' reliable delivery.

⁴ This refers to the standard binary number system where 1 = on and 0 = off.

TCP does this with the window value in the TCP header. Once data begins to flow between the two end terminals, each sender “return[s] a “window” [value] with every ACK indicating a range of acceptable sequence numbers beyond that last segment successfully received. The window indicates an allowable number of octets that the sender may transmit before receiving further permission [to send more segments]” (Postel, 1981, RFC 793, p. 4). This process is known as flow control, congestion control or the sliding window effect.

Flow control is necessary because networks can be unpredictable in the amount of traffic that may be transiting them at any point in time. Being a polite protocol, TCP desires to “achieve high utilization, avoid congestion . . . share bandwidth” (Low, 2002, p. 24) and avoid “inappropriately large bursts of data [onto the network]” (Allman, Glover and Sanchez, 1999, p. 9). Additionally, the protocol must allow for the recovery of lost or damaged packets. All this is made possible by the following four TCP algorithms: Slow Start, Congestion Avoidance, Fast Restart and Fast Recovery.

Since the 3-way handshake does not carry any data and the window size is set to 1, the TCP does not know the link status. Therefore, TCP begins transmitting data with the slow start algorithm, which slowly probes the network to determine its available capacity. Slow start will increase the size of the window exponentially on each successive ACK until a certain threshold is met, after which the congestion avoidance algorithm takes over. The congestion avoidance algorithm will continue to increase the window size linearly “to slowly probe the network for additional capacity” (Allman et al., 1999, p. 9) on each successful ACK. This process will continue until congestion is detected, after which TCP reverts to either slow start or congestion avoidance at half the window size. For the purposes of this research, the window size growth of these algorithms is noted in Figure 8.

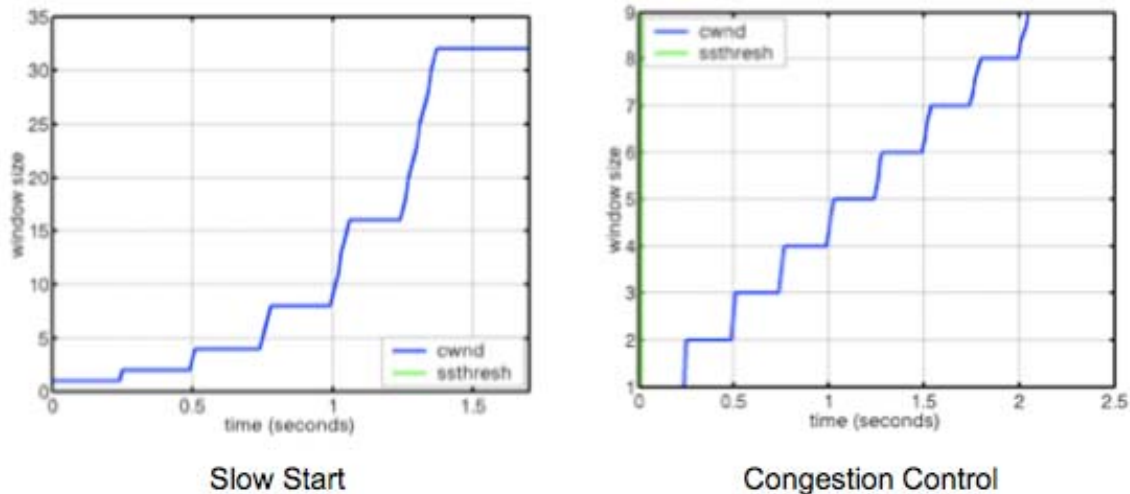


Figure 8. TCP Window Growth: Exponential vs. Linear (From Low, 2002, pp. 33, 35)

TCP detects congestion by packet loss, indicated in two ways: 1) retransmission timeouts (RTO), and 2) receiving two duplicate ACKs (Low, 2002, p. 36). When a sender transmits a packet, it maintains a timer in the TCP buffer. If this timer expires before the corresponding ACK is received, the packet gets retransmitted, TCP assumes significant congestion in the link and cannot infer why, so it reverts to slow start to probe the network again. This timer is based on network round trip time (RTT). Lost packets can also be identified if a sender receives two duplicate ACKs (for a total of three ACKs). It is not concerned with one ACK, as packets may be arriving out of order or the network may have a long delay (such as a space link) and the packet may still be 'in flight' (somewhere between sender and receiver). However, when duplicate ACKs arrive, "TCP knows that packets are still flowing . . . and can therefore infer that congestion is not that bad" (Allman et al., 1999, p. 10). TCP cuts the window size in half and continues to operate in congestion control mode (Allman et al., 1999).

The fast retransmit algorithm is employed when duplicate ACKs are detected. These packets get retransmitted, regardless of the RTO status. Packet retransmission also triggers the fast recovery algorithm to adjust the congestion window. Fast recovery cuts the current window size in half, allowing

“TCP to keep data flowing through the network at half the rate it was when the loss was detected” (Allman et al., 1999, p. 10). This keeps TCP in congestion avoidance mode, and out of slow start.

Lastly, since TCP is the responsible layer 4 protocol, it manages—along with layer 5—the logical tear down of the connection with an exchange of finish (FIN) flags. The teardown process releases network resources for allocation to another connections.

While this explanation seems lengthy, it is necessary to understand this protocol in order to make sense of the data that will be generated during experimentation. The TCP is connection intensive and therefore consumes more network resources than UDP. Three of the top four protocols found transiting SWAN networks are TCP based: File Transfer Protocol (FTP), Simple Mail Transfer Protocol (SMTP) and Hypertext Transfer Protocol (HTTP). Understanding TCP and the other three protocols just mentioned, will help in understanding SWAN traffic patterns and how to better manage what satellite bandwidth is available.

a. *Early Open*

Early open is a not a widely used technique that takes advantage of the empty packets in the 3-way handshake. Each packet has the capability to carry 65,535 bytes of data, but according to the TCP algorithm, no data is sent during the connection establishment. These three transactions are trivial for a LAN connection with gigabit capacity; however, they are of particular interest in long delay satellite networks. The problem is highlighted when multiple subscribers use the TCP to send small packets of data (less than 65,535 bytes) across the link. If a message is small, the subscriber must wait until the three other packets establish the connection before the one and only message packet gets sent. When many users send several short messages via TCP, it is easy to see how the link can be consumed with 3-way handshake traffic. Early open uses the request packet in the handshake to deliver data. If the entire message

fits into the initial packet and the FIN flag is set to 1, then it only takes one throw across the WAN to deliver a message that would otherwise require four throws.

3. Space Communications Protocol Standard (SPCS)

The space environment is the medium used by SWAN to extend the Internet to Marines in remote, BLOS locations. While TCP was designed to be flexible for various network configurations, the space environment presents some unique challenges. Allman et al. (1999) state, “There is an inherent delay in the delivery of a message over a satellite link due to the finite speed of light and the altitude of communications satellites” (p. 2). These elements of the space environment degrade the performance of TCP over satellite links (Allman et al., 1999).

In the 1990s, new protocols were being developed by the armed services for every new mission being conducted in space to improve TCP performance in this environment. This uncoordinated effort led to expensive, proprietary, stovepipe solutions that had no longevity. To reduce cost and allow different satellite access points to be more interoperable, NASA, the U.S. Space Command and Jet Propulsion Labs embarked on a joint effort to “develop an interoperable suite of end-to-end data protocols for satellite networks” (Hooke, 2004). The Space Communications Protocol Standards (SCPS) suite was developed.

In 2002, the Joint Terminal Engineering Office declared the SCPS-TP the “most effective and interoperable solution for TCP enhancements” over satellite communication links. This protocol also “demonstrated both TCP traffic enhancement capability and interoperability with other TCP devices.” As a result of the successful testing, SCPS was declared the *de facto* protocol for future space links devices involving TCP network traffic (Hooke, 2004). In 2007, SCPS became an official mandate in the DoD IT Standards Registry.⁵

⁵ An IETF RFC does not officially address the SCPS.

SCPS is an open-source suite of protocols designed to efficiently facilitate satellite and wireless communications. The suite is comprised of a file handling protocol (FP), a transport protocol (TP), a security protocol (SP) and a networking protocol (NP). Within this suite of protocols, SCPS-TP is the only required variant, as it facilitates multi-vendor interoperability; other variants are optional. For the purposes of this research SCPS-TP will be the protocol of interest, because it is the TCP surrogate in space. The military designation for this protocol is MIL-STD-2045-44000, which is also ISO standard 15892.

Global Protocols was the first commercial vendor to implement SCPS-TP into communication hardware. Their implementation is commonly known as Skipware, and it has become an industry standard.

While SCPS provides support for connectionless multicasting, it does not support reliable multicasting; more simply, it does not guarantee packet delivery to a group of subscribers. This is a design problem that exists in all currently employed transport protocols. As the DoD becomes more network-centric, there is a growing need for a protocol with this capability.

4. Negative-acknowledgement (NACK)–Oriented Reliable Multicast (NORM)

Net Centric Warfare is characterized by the ability of geographically dispersed forces to create a high level of shared battlespace awareness that can be exploited via self-organized and other network centric operations to achieve commanders' intent. (Alberts, 1999, p. 88)

This statement summarizes where nearly every aspect of the DoD is headed in the future. It suggests that warfighters will be dispersed, capable of accessing and contributing to near a real-time knowledge pool, in order to make rapid battlefield decisions independently. This concept will require new systems and new protocols. More importantly, Network Centric Operations will require a shift from a “point-to-point” to a “many-to-many” mindset.

TCP is a point-to-point protocol. It creates dedicated socket pair connections and is therefore considered a unicast protocol that establishes a one-to-one relationship between end users. UDP is both a unicast and a multicast protocol. Since there is no dedicated connection to set up, its messages can easily be sent from one host to one or many other hosts, making it a one-to-many protocol. The problem with UDP is that there is no guarantee that the message will arrive at its destination.

BFT is a dynamic system used to keep commanders updated on the location of tactical units. As units are on the move, they regularly send short, bursty UDP updates to refresh their location. However, if without a guarantee of delivery, there is no way to be sure the position is properly updated. To create a Network Centric warfighting force, data, information and knowledge need to flow undisturbed and complete to participating warfighters to give them the best chance to accomplish their mission. This will require a reliable, connection-oriented, TCP like protocol.

A hybrid layer 4 protocol that combines the reliability of TCP with the multicast capability of UDP would be the ideal solution. NORM is an experimental layer 4 protocol being developed by the Internet Engineering Task Force (IETF) that integrates the desirable features of both protocols. The idea of this project is to create an efficient and reliable protocol, capable of distributing data to a group of participants, using the IP datagram services. When it is successful, the DoD will be closer to being Network Centric. Some of the issues that it will have to overcome are caching, retransmission, packet repair and ordering, all within the contents of group dynamics. Group dynamics consists of participants joining late, leaving, and rejoining, all while being kept up-to-speed on the developing situation (Adamson et al., 2004, p. 4).

The research in this thesis began by exploring this important experimental protocol; however, the more immediate issue of testing and updating SWAN terminals overtook the focus of this study.

C. APPLICATIONS

None of the aforementioned OSI model layers or protocols interact directly with the user. The application layer (layer 7) is where software and users generate the functional data to be transferred to another end user. This data gets packaged inside a lower layer 'envelopes' and then transmitted over the physical medium.

While there is a long list of protocols that fall into the application layer, this research will focus on the three most common to SWAN networks: FTP, HTTP and SMTP.

1. File Transfer Protocol (FTP)

The FTP is the most fundamental and efficient type of computer communication. This protocol allows files to be copied from one computer to another by simply moving blocks of data (a block of data is a smaller chunk of a file). Since transferring files is what networking is all about, it is no surprise that FTP is such a common protocol on the Internet and SWAN networks. RFC 959 states "[t]he objectives of FTP are: 1) to promote sharing of computer programs, data and/or files, 2) to encourage indirect or implicit use of remote computers, 3) to shield a user from variation in file storage systems among hosts, and 4) to transfer data reliably and efficiently" (Postel and Reynolds, 1985, p. 1).

This protocol can be used to easily share mission files for combined arms coordination; access large, common data stores such as detainee biological data; and to distribute updates to those databases. FTP is connection-oriented and therefore uses the TCP.

FTP operates on a client-server architecture, where the client is the requestor of data and the server is where the requested data is stored. The FTP uses two TCP connections: a control connection and a data connection. The control connection is used to establish an FTP session and then to manage it with basic FTP commands. The control connection does not transfer files, only

FTP commands. The data connection does the actual transfer of files. This separate connection is created each time a file is sent from either the client or the server and is terminated when the transfer is complete.

The client actively sends a control command requesting to open an FTP session from an available ephemeral port number (typically a port number larger than 1023). The FTP server passively listens for control connections on TCP port number 21. This control connection allows other commands to be sent by either the client or the server. When a data transfer command is issued, a second TCP connection is established for the exchange of data between terminals.

The two most common commands used during an FTP session are *get* and *put*. The *get* command, followed by a file name, will retrieve that file if it exists on the server (ftp> get textfile.txt). The *put* command will put the file on the server (ftp> put textfile.txt). These two basic commands illustrate why this protocol is so popular, it is simple and it facilitates the basic purpose of networking computers.

It is important to understand this protocol when analyzing traffic patterns, because it does not have a unique header. To identify this protocol during packet analysis, analysts must identify the port numbers the protocol uses, or how to identify it in the TCP header (protocol field).

2. Hypertext Transfer Protocol (HTTP)

Mission planning involves several moving parts involving warfighters who are dispersed geographically. It is common for aircrews to plan missions with units who are dispersed throughout all of Al Anbar province, Iraq. This dispersion requires all warfighters to share information for coordination of effort. Planning documents may consist of images, sound bites, text or a combination thereof. These files could be sent to all units that are participating, but what happens when there is an update to the mission? One update could be vital, and all the information would have to be pushed out to the supporting units again.

This process is not only time-consuming for the lead unit, it also needlessly consumes network resources. One solution is to pass mission information through a Webpage that can be accessed by those units participating in the mission. To make this possible, an HTTP server is setup to facilitate efficient and reliable information sharing.

The Marine Corps' objective in the information age is to push information to decision makers so that the right decision can be acted upon in a timely manner. The SWAN system has facilitated that through a network solution where distributed warfighters can collaborate through the use of hypermedia. RFC 2616 describes HTTP as "an application-level protocol for distributed, collaborative hypermedia information system" (Fielding et al., 1999, p. 1). This description fits into the SWAN system's mission and the concept of Network Centric Operations.

The HTTP is more complicated than FTP. Basic HTTP communication consists of a request for information from a resource that exists on the same server. However, most communications do not take place with this direct connection. Instead, the HTTP requests often have several intermediary connections between many requestors and several servers, each of which may be engaged in multiple, simultaneous communications.

Usually, the client initiates an HTTP request to establish a TCP connection on server port 80. Once established, a request command is sent to the server. The server responds with a status (blank) line and a message/response of its own. The response has a header and a body where the reply message is located (Figure 9).

```
Terminal — bash — 76x26
Last login: Mon May 4 17:41:36 on ttys000
Shane:~ shane$ telnet lulas.com 80
Trying 63.166.108.41...
Connected to lulas.com.
Escape character is '^['.
GET /index.html http/1.1
Host: lulas.com
Request
HTTP/1.1 200 OK
Content-Type: text/html; charset=us-ascii
Server: Microsoft-HTTPAPI/2.0
Date: Tue, 5 May 2009 02:48:00 GMT
Connection: close
Response Header
<!DOCTYPE HTML PUBLIC "-//W3C//DTD HTML 4.01//EN" "http://www.w3.org/TR/html4/strict.dtd">
<HTML><HEAD><TITLE>Bad Request</TITLE>
<META HTTP-EQUIV="Content-Type" Content="text/html; charset=us-ascii"></HEAD>
<BODY><h2>Bad Request</h2>
<hr><p>HTTP Error 400. The request is badly formed.</p>
</BODY></HTML>
Response Message
Connection closed by foreign host.
Shane:~ shane$
```

Figure 9. HTTP Request and Response Header and Body

HTTP allows users to share a variety of file types, facilitating warfighter collaboration. For this research, it is important to understand what the HTTP protocol looks like in order to make any sense of, or identify its traffic patterns.

3. Simple Mail Transfer Protocol (SMTP)

Networking was created to make communication and file sharing more efficient. The most widely used electronic communication application is e-mail. E-mail is made possible by the SMTP. RFC 821 states that SMTP was designed to “transfer mail reliably and efficiently” (Postel, 1982, p. 1). FTP and HTTP also facilitate reliable and efficient communication, but they require both the sender and receiver to be connected at the same time. To facilitate communication with a host that is not on the network, SMTP is used.

E-mail traffic is user-oriented, meaning it is sent from one user to another user, not from one computer to another computer. This means that the standard IP addressing will not work to deliver an e-mail to a user, simply because the user is not always receiving their e-mail at the same computer. Instead, a user accesses their e-mail from a particular server that is always connected to the Internet. This server serves as a middleman that receives the message when

the user is not logged in. When the server identifies that the user is logged in, it will deliver the message to the user. Kozierok (2005) describes the process in three steps:

1. Transaction Initiation and Sender identification: The sender establishes a connection with the SMTP server, informing the server that it wants to send a message. This message includes the e-mail address of the sender.
2. Recipient Identification: The sender tells the SMTP server the e-mail address of the recipient.
3. Mail Transfer: Sender transfers the e-mail message to the SMTP server ("The TCP/IP Guide").

The process does not end here. If the e-mail address is not a local SMTP server address, then the server has to look up the address and forward the message to the appropriate SMTP server. When the recipient logs onto their e-mail server, they connect via a SMTP connection to retrieve the message.

SMTP comes in a variety of formats; however, for the purposes of this research it has two main sections: the message header, which contains important control and descriptive data; and the body/payload that carries the data. These connections normally occur on port 25.

The point of this description is to illustrate that SMTP is more complex than FTP or HTTP. It is a more 'chatty' protocol as it frequently sets up and tears down TCP connections for short-term use. Additionally, since SMTP is a connection-oriented and user-oriented protocol, it becomes a good surrogate to represent BFT, an application that is chatty by nature. Understanding the protocol is essential to identifying its behavior during network device testing.

D. TCP ACCELERATION EXPLAINED

TCP acceleration is used to obtain better throughput for Internet connections without modifying end applications that require reliable connectivity

over challenging environments. A challenging environment can be any network that experiences long delays, high bit error rates or where the network is asymmetric or experiences intermittent connectivity. Since TCP is connection-oriented and sees delay as congestion, it is easy to see how space links can quickly degrade TCP performance. The growing use of geosynchronous satellites to extend the Internet onto the battlefield and TCP's poor performance in that environment drove the development of the PEP device⁶.

1. Legacy Performance Enhancing Proxy (PEP) Functionality

Regardless of which vendor produces the accelerator device today, they all have the same basic functionality as those currently used in the Marine Corps. They achieve better TCP performance by enhancing the algorithms. A PEP is a transport layer gateway that aids in moving network traffic across challenging links without modifying application protocols, facilitating reliable end-to-end connections. These devices are typically set up to bracket the satellite link. They are connected just before the router on the LAN side, which allows them to see all network traffic before it reaches the WAN (Figure 11).

Recall that TCP is a bandwidth aggressive, yet polite protocol. The four congestion control algorithms discussed in Section B.2 define this behavior. These algorithms use packet loss and/or ACK delays to regulate the amount of data being pushed across the network; this is commonly referred to as window scaling.

PEP devices facilitate TCP connectivity over satellite links with three separate connections—a technique referred to as TCP spoofing (Figure 10 & 11). The first and third connections are between the originating application on the host and their respective PEP device on the LAN. The second connection is formed between the two PEP devices. These devices intercept and terminate TCP connections from the application and then establish a new connection

⁶ PEP devices and TCP accelerators are used synonymously.

directly between the PEP and the application.⁷ Enhanced window scaling algorithms, designed to perform better in space links, are then substituted in the connection between PEPs. This technique isolates the adverse effects of the challenging environment to a protocol designed to operate in it.

The top portion of Figure 10 (yellow) shows a normal TCP algorithm transiting a 560 ms RTT connection. This long delay will degrade TCP performance if the protocol is left to its own algorithms. When SCPS-TP algorithms are substituted (Figure 10, green), the PEP device connects directly to the application with a 10 ms TCP connection, while simultaneously establishing a surrogate connection between PEP devices to negotiate the space portion. This is TCP acceleration in a nutshell.

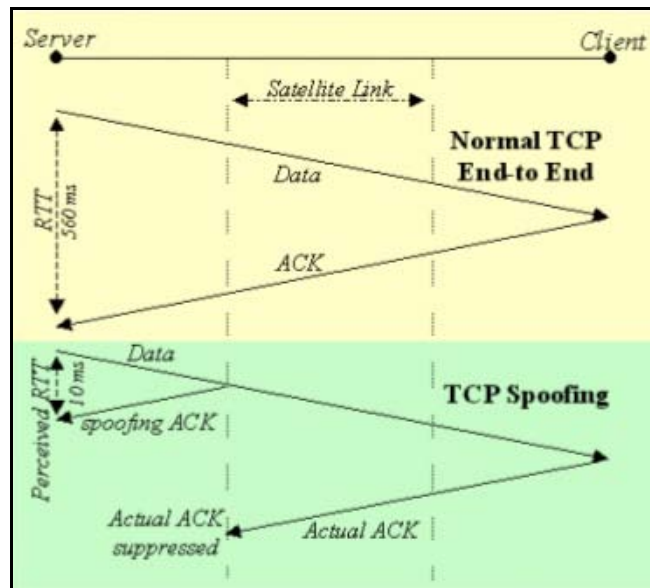


Figure 10. TCP Spoofing (From Inglis, n.d.)

⁷ The application does not know, nor does it care, that it is connected to a proxy endpoint and not the end application it is ultimately interacting with. This provides the transparent end-to-end functionality desired in a connection-oriented protocol.

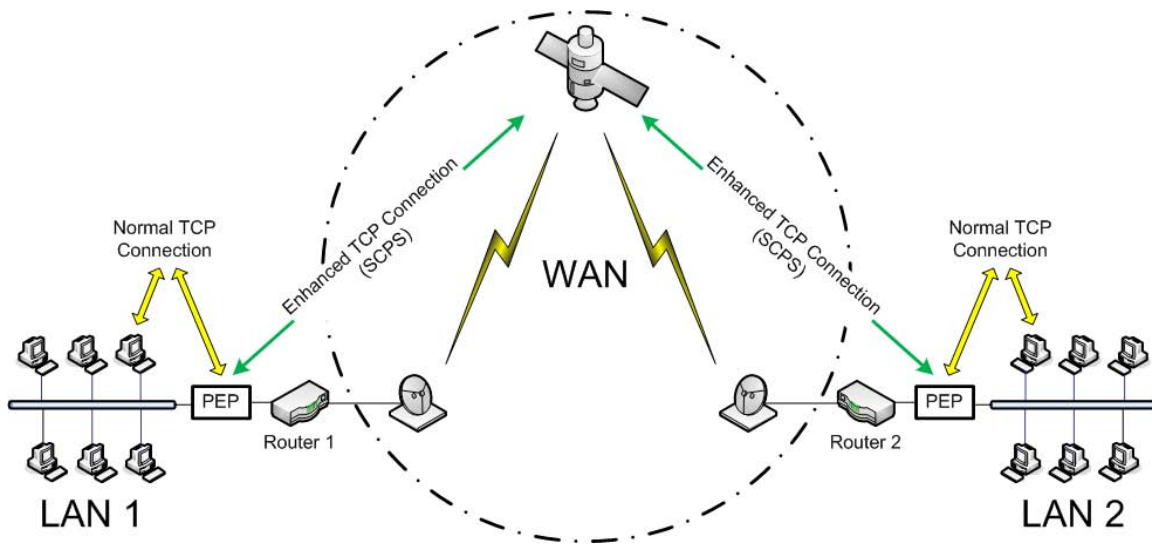


Figure 11. TCP Spoofing, Big Picture

While any vendor can create enhanced protocols, DISA has mandated the use of SCPS-TP. SCPS-TP does not modify the underlying TCP connection, allowing applications to experience the same reliable and efficient service the TCP was designed to deliver. The benefit of a transparent standard is that it is device independent; meaning, the networks on either side of the WAN can be asymmetric⁸ as long as SCPS is being employed. This is especially important when integrating new devices with legacy devices.

SCPS-TP is an open source collection of space link, performance-enhancing algorithms. Being a standard, they facilitate space networking component interoperability, while providing commercial vendors the opportunity to modify those algorithms for increased performance. The development of proprietary algorithms that interface with SCPS creates the differences between vendor accelerator products.

The TurboIP device, currently installed in SWAN systems, uses enhanced algorithms and compression to optimize WAN bandwidth utilization. There are three basic algorithms that make TCP acceleration possible. First, the quick start

⁸ Asymmetric means that both sides of the network are not configured with the same components. A PEP device on only one side of the link will allow traffic to flow unaccelerated, however, a PEP device is required on both sides for traffic to be accelerated.

algorithm is more aggressive at using available bandwidth than the slow start algorithm in the standard TCP. This is made possible when the PEP device terminates the original TCP connection and substitutes the optimal algorithms for the space link portion of the connection. Second, enhanced congestion control algorithms are more aggressive and efficient at regulating network traffic through window scaling. The standard TCP window size is limited to 64 Kbytes, while enhanced TCP algorithms support window sizes up to 1 Gbyte. Third, PEP devices use Selective Negative Acknowledgements (SNACKs) algorithms to identify and retransmit lost packets. Instead of requesting all packets after the one lost packet, SNACKs simply requests specifically numbered packets that were lost. This reduces the amount of retransmission traffic on the WAN.

Compression optimizes bandwidth to a lesser extent by encoding files with fewer bits. Fewer bits equate to less network traffic on the WAN; however, it is not as effective as protocol enhancement. The encoding scheme must be known on both sides of the link for compression to even operate. This can cause an interoperability problem if one side of the link does not understand the compression scheme. For PEP devices that do compression, they learn ahead of time which links can and cannot perform compression. On links that cannot understand the compression scheme, compression is not used, even if it is turned on. Therefore, it is not as effective at optimizing WAN bandwidth as the aforementioned algorithms.

2. Modern PEP functionality

Modern PEP devices employ three additional bandwidth optimization techniques: Application Streamlining, Caching, and Data Deduplication.

Application streamlining refers to algorithms that reduce the amount of short and frequent (often referred to as 'chatty') connection traffic that transits the WAN. Examples of chatty applications are HTTP and SMTP. These algorithms consolidate and perform most of the chatty behavior on the LAN before the traffic transits the WAN. Specifically for TCP connections, application streamlining

reduces the number of round trips a particular connection must make. This reduces the amount of traffic on the WAN by reducing the number of chatty connections that span the lossy, high latency space link.

Caching is another technique that reduces the amount of network traffic crossing the WAN. This technique stores a copy of requested files on a hard drive located on the LAN. When another host on the same LAN requests the same file that traffic gets delivered locally from the hard drive instead of transiting the WAN. This keeps WAN resources available for other network traffic.

Since these hard drives do not have infinite memory capacity, there are two common cache management techniques: First In First Out (FIFO) and Least Frequently Used (LFU). FIFO overwrites files in sequential order. LFU is the preferred method of cache management and it simply overwrites files that are used less frequently.

Data deduplication is a subset of caching and it is the newest technique in WAN optimization. Sophisticated traffic pattern recognition algorithms index all the data that passes through these devices. If indexed data is requested subsequent times, only a small pointer is sent instead of the entire file. Data deduplication reduces WAN traffic by sending smaller pointers of previously requested files. If a file has changed, only the changed portion gets sent across the WAN in its entirety; the rest is sent via reference pointers. For example, it is much cheaper in bandwidth cost to send a 4-byte reference pointer and a 5 MB change to a file, than it is to send an entire 50 MB file. Even though the speed of a packet across a WAN is almost the speed of light, the fastest packet is the one that is already there.

All PEP devices contain some combination of legacy and modern optimization techniques and each vendor implements them differently. These various implementations are proprietary trade secrets—not SCPS or standards based and therefore have no solid definition—that are protected by law, and that make one device perform different from another. Devices that have proprietary

internal functionality are often referred to as a 'black box.' While it is easy to see what the data looks like going into and coming out of the device, it is impossible to know what goes on inside, unless you were involved in its design. Since the commercial sector produces many different TCP accelerator black boxes, it is necessary for the Marine Corps to test various products in a realistic environment to determine which one will best suit the Marine Corps' needs.

E. WEB CACHE COMMUNICATION PROTOCOL (WCCP)

WCCP is an open standard, Cisco Systems software protocol that redirects traffic to a cache memory location. This protocol can be enabled in either the SWAN switch or router (both Cisco products). As traffic passes through the WCCP enabled component, it is checked against the cache. If the traffic does not exist in the cache, a copy is placed there and sent to the accelerator, in its entirety, for transmission over the WAN. If the traffic does exist in the cache memory, then smaller reference pointers to that specific file on the other side of the WAN are sent, instead of the whole file. If there are changes to a file that exist in the cache, then the file transits the WAN in two parts: 1) as reference pointers to the unchanged portion of that file on the other side of the link; and 2) as new data in the file from updates or additions. The file gets reassembled on the other side and also gets updated in the cache for future reference. Bottom line is if a file exists on both sides of the WAN, then only smaller reference pointers transit the WAN, and not the entire file. Only new files and changes to existing files transit the WAN in their entirety.

III. NETWORK TEST DESIGN

This chapter describes the reusable test template developed in this research.

A. PURPOSE

Networks are dynamic in nature. Placing a network in an austere combat environment makes a tactical network on which lives may depend. These tactical networks often operate at a high utilization rate, relying on the guaranteed service of the TCP. Cox noted that I MEF's GMF links were "91 to 98 percent utilized, between 0200 and 0600, on 09 November 2004" (Cox, 2005, p. 33). Reliance on information transmitted via satellite links has only increased since then.

The purpose of this research is two-fold: 1) Consolidate three testing efforts into one simple, yet realistic and repeatable effort that will reduce cost and provide faster more accurate results; and 2) evaluate modern TCP accelerators to replace the original, aging components.

B. PHYSICAL LAB DESCRIPTION

The most important consideration in evaluating tactical networks and their components is how well the experimental design represents the real world network. With a real world testbed, accurate results can be obtained indicating how well a component being evaluated should perform for the Marine who actually employs it. This research focuses on building a realistic lab environment and generating network traffic that represents Marine SWAN traffic. The idea is to combine and outline readily available assets to create a testing environment that is cost effective, emulates Marine network configurations, and can generate reliable, repeatable, and useful data that can be used to make procurement or network configuration decisions.

1. Testbed Components

The lab for this research is unique compared to any other vendor or IT consulting organization. Most importantly, it is comprised of *actual* equipment currently being used in the Marine Corps. Two SWAN-C (GSWAN) terminals were provided by MCTSSA, identical to those being employed in Iraq. The terminals were set up and connected via an *actual* geosynchronous satellite link in the SWAN lab on Camp Pendleton. This link simulates a WAN that spans from the East Coast to the West Coast (Figure 12). Utilizing actual equipment to test network components is essential to obtaining accurate results that will provide the most benefit to the Marine Corps.

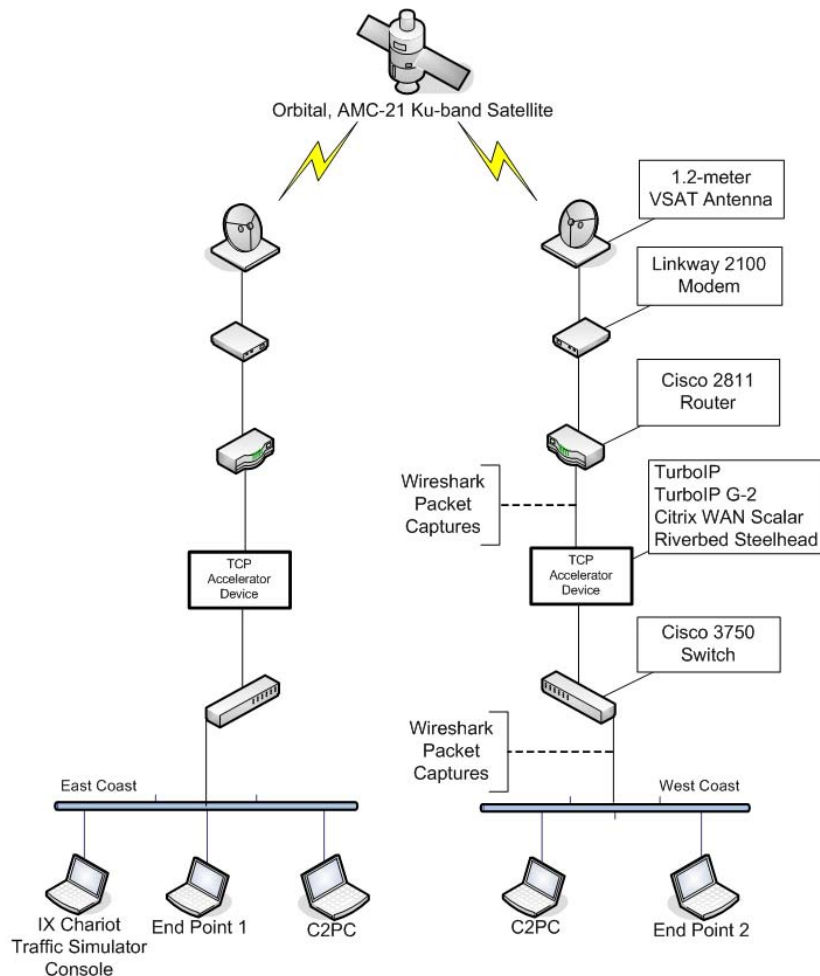


Figure 12. Testbed Environment for SWAN TCP Accelerators⁹

⁹ Both sides of this network are configured with the same components.

An alternative testbed configuration involves WCCP. Employing this cache protocol places the accelerator device directly on the LAN and not inline like the other testbed configuration (compare Figures 12 and 13). A trace route of a packet on a WCCP configured network goes like this: Endpoint, Switch and then handled by the WCCP, WAAS, back to the Switch, Router, Modem, Antenna and then across the link. The reverse happens on the other side.

For this study, WCCP was configured on the switch, though it is preferable that it be configured in the router. As traffic entered the switch, it was immediately processed by the WCCP, then redirected back out to the WAAS for the necessary performance enhancements, before transiting the WAN. This configuration is required for the Cisco-WAAS device; however, the Citrix and Riverbed devices can also be configured to operate with WCCP. The preferred testbed configuration is the inline setup in Figure 12.

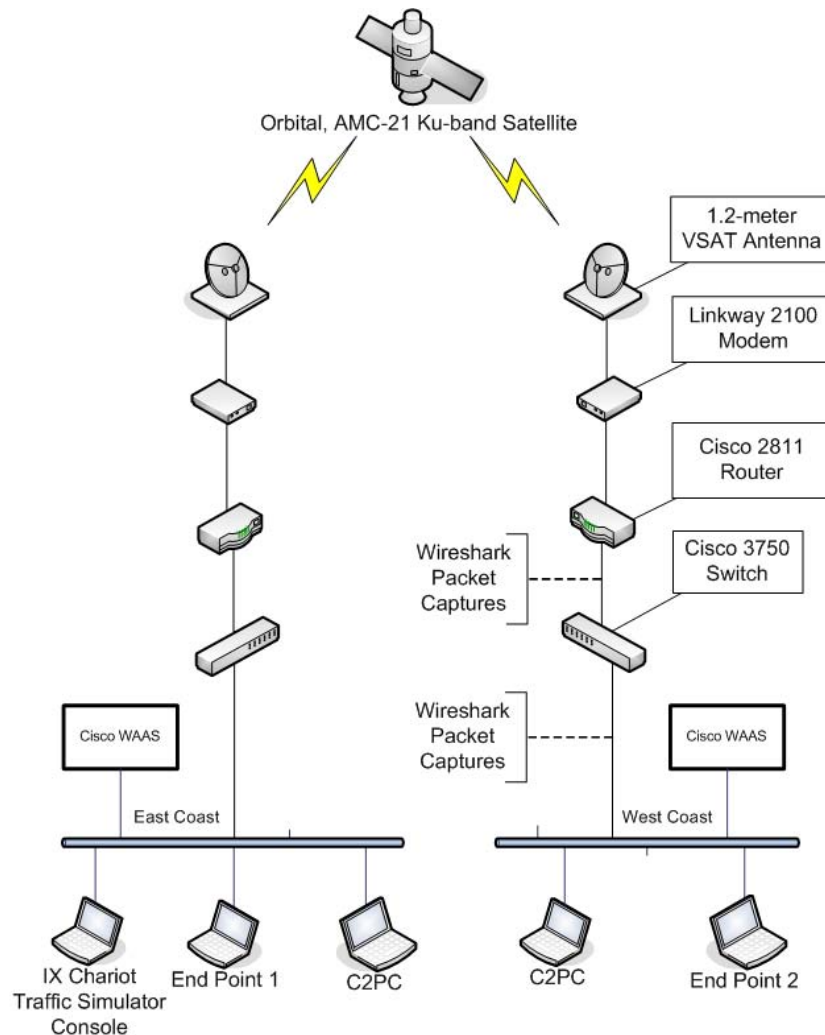


Figure 13. Testbed: WCCP Configured, Used for the Cisco WAAS Device

2. Testbed Characteristics

TCP accelerator devices address a WAN problem. While LANs have virtually all the necessary bandwidth they need, WANs are much more restrictive in nature due to their long delay, lossy environment and much lower data capacity.

a. WAN: GSWAN (SWAN-C)

The GSWAN for this research was designed to provide Force Recon teams, remote BLOS access into the tactical network (NIPRNet, SIPRNet and DSN) in Iraq. It is comprised of an RF package and a data package. The

RF package consisted of a 1.2-meter Very Small Aperture (VSAT) antenna and a Linkway 2100 modem. The data package consisted of a Cisco 3750 switch, TurboIP accelerator and a Cisco 2811 router.

b. AMC-21 Satellite

The AMC-21 satellite was built by Orbital for AMERICOM, who is a broadband service provider. This geosynchronous (GEO) satellite provides fixed communications in the Ku-band over the Continental U.S., Alaska, Hawaii, and Caribbean. The satellite carries 24 Ku-band transponders designed “specifically for telephony, data and broadcasting” (“AMC-21 Fact Sheet,” 2009). It was launched into its GEO orbit on August 14, 2008, from Kourou, French Guiana. It is located at 125 degrees west longitude, and at its zenith, it is 35,888 km (22,300 miles) from the earth’s surface. This means that the fastest possible round trip time (RTT) for a signal, using the speed of light as 3×10^8 km/hr, is 431 ms. Since the lab location was not at nadir, the RTT can be expected to be longer. For this research the average RTT was 665 ms, calculated using the *ping* command that transited the network from east to west (“AMC-21 Fact Sheet,” 2009).

“Satellite channels are dominated by two fundamental characteristics: noise and bandwidth” (Allman et al., 1999, p. 3). Due to distance and atmospheric condition, signals that transit space experience significant attenuation and therefore bit errors. “Typical bit error rates (BER) for a satellite link . . . are on the order of 1 error per 10 million bits (1×10^{-7}) or less,” commonly referred to as 10^{-7} (Allman et al., 1999, p. 3). The BER during the week of testing was 10^{-7} , which is considered clean.

An operator offsite configures the MRT, which controls the satellite power balance to maintain an acceptable BER. Table 2 indicates the settings used during the week of testing. The bandwidth factor (BWF) is a setting that controls the rate of carrier timeslot allocations during ramp up and ramp down (start and end of transmissions). It is a 4-digit hex number and the normal

Marine SWAN setting is 0x2802. The first two digits, 28, indicate the ramp up allocation and the last two digits, 02, are the ramp down allocation. The setting for this research was 0x104A, which is better than what Marines actual use. This indicates that lab results may be slightly better than those experienced in the field; however, the relative performance between accelerators is constant.

Symbol Rate	2.5 Msps
FEC	7/8
Traffic Burst Rate	64 KBps
Bandwidth Factor	0x104A

Table 2. Satellite Power Balance Settings

The radio spectrum is a limited natural resource, hence there is a restricted amount of bandwidth available to satellite systems which is typically controlled by licenses. This scarcity makes it difficult to trade bandwidth to solve other design problems. (Allman et al., 1999, p. 3)

The AMC-21 satellite characteristics available during the week of testing are summarized in Table 3.

			Xpndr BW	Usable BW	Leased BW		
			36 MHz	36 MHz	36 MHz		
Data Rate	Modulation	FEC Rate	Symbol Rate	Allocated BW	Allocated PEB	Transmit CTR Freq	Receive CTR Freq
4004 kbps	QPSK	7/8	2500 ksps	3250 kHz	3695 kHz	14170.125 MHz	11870.125 MHz

Table 3. AMC-21 Satellite Capabilities (From Master Transmission Plan, 2009)

c. **Network Configuration**

Each device tested was configured with the following Marine SWAN settings (Table 4). These setting are start values for the accelerators to base their algorithms on. While the devices are capable of detecting these numbers automatically, they achieve their best performance when set manually. Those devices using Skipware have a similar configuration GUI that allows the values in Table 1 to be set manually. The TurboIP, TurboIP-G2 and the Riverbed devices all use Skipware. The other two devices have their own network configuration pages that are easy to navigate to input these settings.

	Transmission Rate (TR)	MTU
LAN	100 Mbps	1500
WAN	3 Mbps	1300
Congestion Control	Per-Connection	
Channel Access	TDMA	
Caveats	Riverbed WAN TR was set to 2 Mbps due to license restrictions	

Table 4. Gateway Configuration

3. Software Tools

a. *IxChariot*

IxChariot is [an] industry leading test tool for simulating real-world applications to predict device and system performance under realistic load conditions. Comprised of the IxChariot Console, Performance Endpoints and IxProfile, the IxChariot product family offers thorough network performance assessment and device testing by simulating hundreds of protocols across thousands of network endpoints. IxChariot provides the ability to confidently assess the performance characteristics of any application running on wired and wireless networks. (IxChariot, 2008)

IxChariot was the traffic-generating tool used for this research. This tool was chosen because it was readily available through the Naval Postgraduate School's Graduate School of Operational and Information Sciences and it was relatively simple to learn. Ixia, the maker of IxChariot, also offers a free version called Qcheck. This network evaluation tool was also available at NPS, but it is not capable of the robust analysis functionality provided in IxChariot. Additionally, the U.S. Army uses IxChariot for their network evaluations, even for TCP accelerator testing.

SmartBits is a different network traffic-generating tool that was available at MCTSSA for the research done by Cox. As noted in his thesis, SmartBits was most likely incompatible with SCPS due to the "way SmartBits handles SACKs [Selective Acknowledgements]" (Cox, 2005, p. 35). "SmartBits implemented its own TCP/IP stack rather than simulating something like IxChariot. This limited the usefulness of Smartbits in modeling actual application

performance” (J. Willard, personal communication, August 18, 2009). The MCTSSA SWAN lab still has this tool in their lab; however, due to its complexity and therefore low frequency of use, nobody knew how to employ it. Fortunately, there was a better, more robust tool available for the research done in this thesis.

IxChariot setup consists of two endpoint terminals and a control console. While one of the endpoint computers could also act as the control console, it is recommended that two separate machines be used. This separates the amount of IxChariot test setup traffic that may interfere with or reduce network performance. IxChariot works by sending all test data (the scripts) to the endpoints, coordinating port numbers and protocols. After test setup, the console sends an execute command to the initiating endpoint. Endpoint 1 reports testing results to the console during and after the test (Figure 14). Generating realistic traffic is the second important ingredient to accurate network evaluations.

For this testbed the IxChariot console was connected to the switch on the East terminal. Endpoint one was also connected to the East switch, while Endpoint two was connected to the West switch.

To ensure this traffic-generating tool accurately represents TCP and other tactical network protocols, a careful look at the traffic is required. Understanding what that generated traffic actually looks like to each device being evaluated, requires another software tool—a network protocol analyzer.

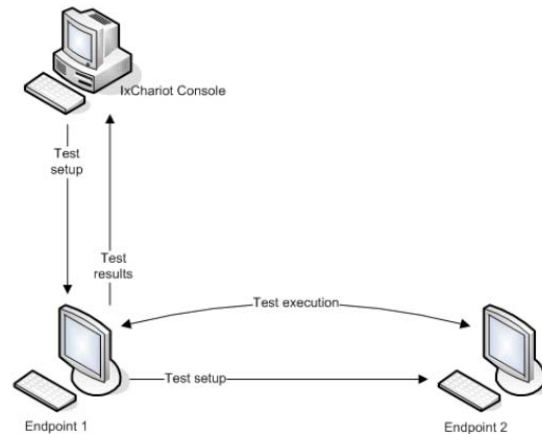


Figure 14. IxChariot Test Process (From Ixia, 2007, p. 2-2)

b. Wireshark

To look deeper into the traffic IxChariot generates and to understand what is happening to accelerated TCP traffic, Wireshark was used to capture and analyze packets sent through the SWAN link. “Wireshark is the world's foremost network protocol analyzer, and is the *de facto* (and often *de jure*) standard across many industries and educational institutions. [Its] development thrives thanks to the contributions of networking experts across the globe [and] is the continuation of a project that started in 1998” (Combs, n.d.). This tool is freeware and is relatively easy to learn.

Since there are two tested configurations, inline and WCCP (Figures 12 and 13), there are different locations for packet captures. Four locations are necessary for each testbed: two LAN capture sites and two WAN capture sites, one on each side of the SWAN connection. The inline configuration is the easiest, and preferred. Packets were captured just before the switch on the LAN side, and immediately after the accelerator on the WAN side. The WCCP configuration is more complex since the packets get redirected at the switch. For this configuration, packets were captured just before the switch for LAN traffic and then immediately after the switch, post acceleration, for WAN traffic. Remember, with the WCCP configuration, packets go to the switch

for redirection to the cache and then to the accelerator located on the LAN. After acceleration, these packets get sent back to the switch, then the router and over the WAN.

4. Network Traffic Generating Approach

The whole idea behind generating traffic is simply to recreate actual network traffic in a lab environment without interrupting forward deployed operations or training exercises. The author was unable to visit a Marine Corps Tactics and Operations Group (MCTOG) training exercise to capture SWAN traffic packets due to schedule coordination and data classification. Without actual traffic to analyze, the author took a stepped approach in building scripts for the traffic generator that can be characterized as multiple users, simultaneously using multiple protocols that transfer various file sizes being transmitted in both directions. This network traffic will be referred to as multi-user/protocol/direction.

Based on Cox's work, the top four protocols used over a SWAN link are FTP, HTTP, SMTP and UDP. Included with the IxChariot software package are base scripts that represent these protocols. These scripts were modified to progressively load the network with larger file transactions and more users. The base protocol scripts were first tested individually over the SWAN link to ensure the simulated protocol accurately represented the actual protocol. This exercise also served as a baseline to understand how the IxChariot scripts perform in the satellite network environment. From this data, a multi-user/protocol/direction test could be built to better represent actual traffic.

The number of connections on a SWAN link is rarely one, nor are those connections made in only one direction. This is how some testing efforts were conducted. Running only one script in one direction will not accurately represent the traffic experienced in tactical networks. Therefore, the scripts run during this research used 10-pair, five simulating a connection from the East Coast to the West Coast and five connecting the other direction. This simulates multiple connections transiting the network in both directions at the same time.

a. *Single Protocol Scripts*

The Throughput script was used to baseline test the link for maximum throughput. This script sends the specified file size from one endpoint to the other and waits for an acknowledgement (Ixia, 2007, p. 8-83). File size was incremented from 100KB to 1 MB to 10 MB. This script, unaccelerated, provided the baseline to compare accelerated results to.

The FTPget script was used to simulate an FTP get command. File size was incremented from 100 KB to 1 MB to 10 MB. When this file is run bi-directionally, it is equivalent to FTP *get* and *put* commands being run at the same time.

The HTTPgif script was used to simulate the transfer of graphic files from an HTTP server. File size was incremented from 100 KB to 1 MB to 10 MB.

The SMTP script was used to simulate typical e-mail traffic. This script includes an additional 20-byte header along with the selected file size. Since e-mail traffic typically consists of smaller files these scripts were modified as such. File size was incremented from 1 KB to 100KB to 1 MB.

The NetMtgV script was used to simulate streaming video, a UDP protocol, with factory set defaults. As illustrated in Figure 15, the TCP accelerator does not touch UDP traffic, referred to as pass through, and therefore limited testing was done with this script.

A summary of the script configuration for the individual protocol tests is provided in Table 5.

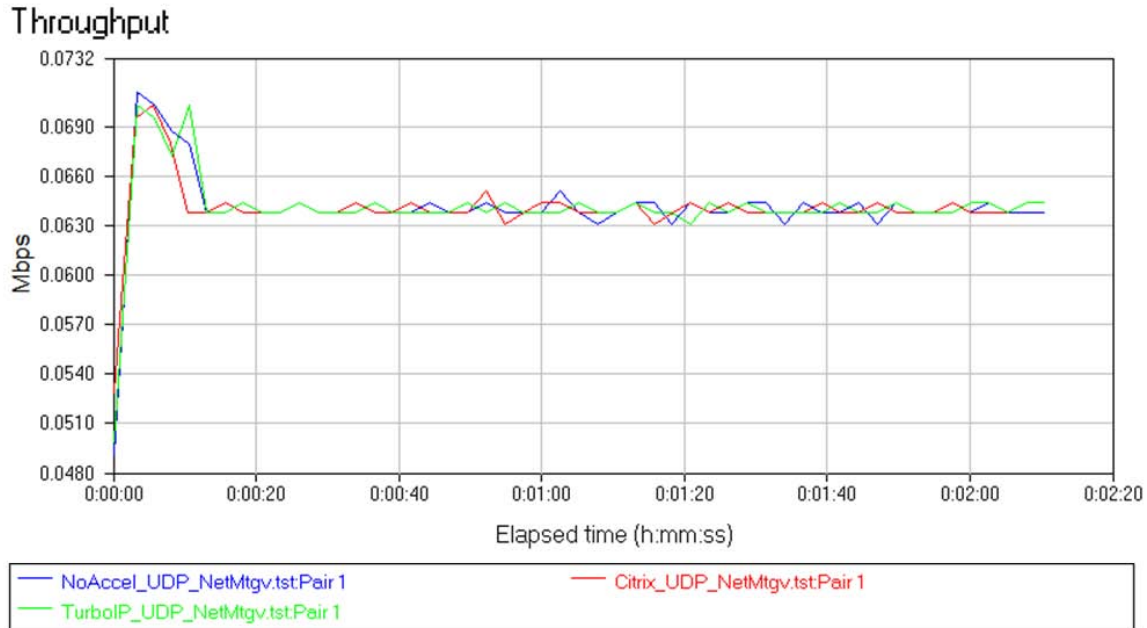


Figure 15. Graph: UDP Traffic Pass Through

b. IxChariot Script Modification

Lastly, each script can be modified to the user's needs. File size and type, the number of transactions and timing records, and delays between transactions and window buffer sizes are just a few of the parameters that can be tailored for particular network needs. This research only modified five of these variables: *number_of_timing_records*; *transactions_per_record*; *file_size*; *close_type*, and *transactions_delay*.

IxChariot scripts operate on two loops, one imbedded inside the other. The outer loop is the timing record that can be characterized as the entire test, comprised of all the variables and administrative tasks required to conduct the test and gather the necessary performance data. The *number_of_timing_records* variable defines this loop. This loop will set up the endpoints to execute the test and also gather the specified amount of timing records. The inner loop defines the actual test itself. The *transactions_per_record* variable establishes how many times the script should be executed for each timing record; basically, it sets up the protocol, transfers the specified file size, disconnects the protocol connection and

then reports results. Together, these two variables establish how many transactions are pushed through the network. These two variables were used to execute several transactions of individual protocols. Both variables, along with the *file_size* variable are the primary elements that control how long each test will take. As lab and satellite time were limited, these variables were manipulated to maximize the amount of tests that could be conducted during this research. The script variable *file_size* was modified to gradually increase the load on the network as previously described.

The *close_type* variable has two options, default and normal. Default simply drops the connection when the file transfer is done, while normal closes the connection via standard protocol behavior. This research set all script to 'normal'.

Since automation allows transactions to be fired more rapidly than humanly possible, the *transaction_delay* variable was used to make traffic patterns more realistic. The *transaction_delay* variable was set to normalize the transaction delays between one and four seconds. Table 5 summarized the five variables that were modified during this research and Figure 16 depicts the script editor dialogue box.

Script	Throughput ¹	FTP ²		HTTP ⁴		SMTP	
Variable	Default	Default	Modified ³	Default	Modified	Default	Modified
number_of_timing_records	20	50	50/50/30	50	20	50	20
transaction_per_record	1	1	4/1/201	1	1	1	1
file_size ³ (MB)	0.1/1/10	0.1	0.1/1/10	0.1	0.1/1/10	.001	0.001/0.1/1
close_type	DEFAULT	DEFAULT	Normal	DEFAULT	Normal	DEFAULT	Normal
transaction_delay ⁵ (seconds)	0	0	1-4	0	1-4	0	0
send_data_rate	UNLIMITED	UNLIMITD	UNLIMITD	UNLIMITD	UNLIMITD	UNLIMITD	UNLIMITD

1-For the Throughput script, only the file size was modified, all other settings were script DEFAULT.

2-As the file sizes increased, the number of timing records was reduced in the interest of time.

3-The forward slash separates the three tests that were run for each individual script of varying file size.

4-Since HTTP is a 'chatty' protocol, the number of timing records was reduced in the interest of time.

5-transaction_delay was normalized between the amount of time shown in the table.

Table 5. Summary of Modifications to IxChariot Script Variables

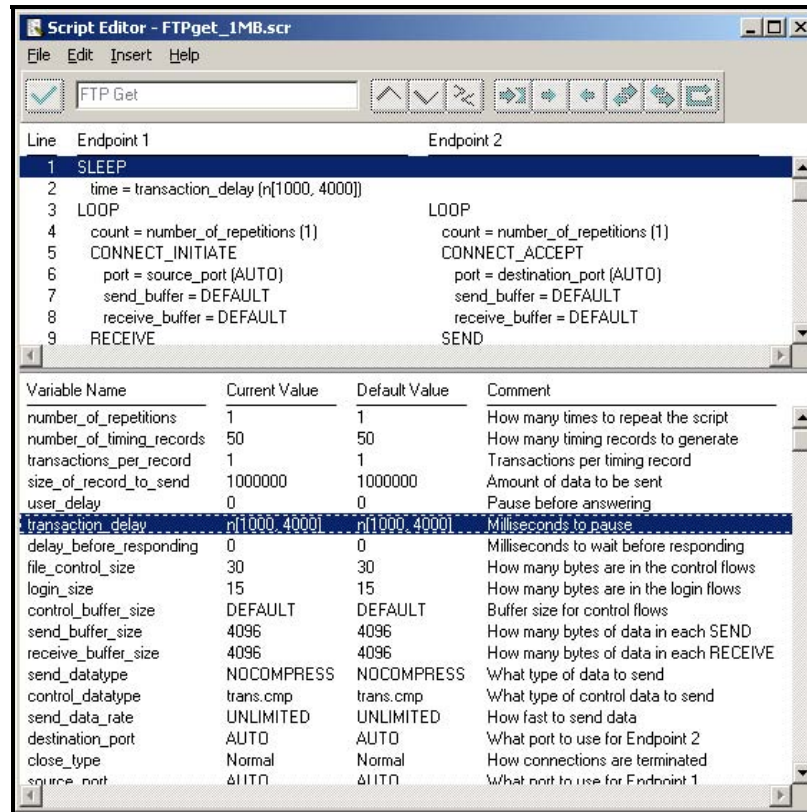


Figure 16. Script Editor Dialogue Box

c. Multi-User/Protocol/Direction Scripts

The results of the single protocol tests provided input to build a more dynamic test that was better representative of real-world traffic. Since this particular IxChariot license was limited to 10-pair, the single protocols were parsed as follows: two-pair were used for FTP connections; two-pair were used for HTTP connections; and six-pair were used for SMTP connections. While real-world traffic was not obtained, it is a reasonable assumption that actual operational traffic would consist of some file sharing (FTP), some Webpage requests (HTTP) mixed with a preponderance of e-mail traffic (SMTP). Table 6 summarizes the scripts that make up multi-user/protocol/direction test used to evaluate candidate TCP accelerator devices (Table 5 summarizes their internal details).

Script	File Size	Pairs	Transactions	TCP Connections
FTPget	1 MB	2	40	2
HTTPgif	1 MB	2	40	10 ¹
SMTP	1 MB	6	120	> 10 ¹
Totals		10	200	

Table 6. Summary of Multi-user/Protocol/Direction Test Script

C. VARIATIONS

This research focuses on TCP acceleration as it currently exists: in a separate box, such as the TurboIP or Riverbed Steelhead devices. However, it would be much more convenient, cost effective and easily scalable if TCP acceleration were to reside in the host terminal itself, as a software solution.

There are open source (freeware) versions of TCP acceleration available; however, this study was unable to evaluate any of them. The NORM protocol is one such software solution that may be a reasonable replacement to the TCP or the accelerator device, as a reliable method of packet delivery with the added capability of reliable multicast. As a software protocol, NORM resides on the host. This makes NORM a preferred choice over other TCP acceleration solutions.

D. LIMITATIONS

This test template accounts for the bulk consolidation of current testing methods. The following sections identify a few limitations for which this study was unable to account.

1. Traffic Generation

The traffic generated in this study is not a perfect match to Fleet Marine Force SWAN traffic; however, it is a better representation than any of the other tests currently being funded. Since this study was unable to procure any actual

traffic from actual SWAN links being employed by Marines, several assumptions were made in constructing test scripts (file size, number of users, relative protocol activity).

Additionally, the traffic-generating tool had a 10-test pair license restriction. This limited the number of simulated users to 20 (10 users on the each side of the link).

2. Multicast

The SWAN terminals and the accelerator device are all capable of multicast traffic. Even the SWAN lab, where these tests were conducted, is capable of supporting such tests. However, due to lab time and lack of a third candidate device from each vendor, multicast testing was not conducted. With this test template and the knowledge that a realistic testbed is available, this should be the next step in TCP acceleration testing.

IV. DATA ANALYSIS

A. EXISTING TCP ACCELERATOR TESTS REVIEW

There are three organizations that are either directly or indirectly testing TCP accelerators for the Marine Corps: the U.S. Army Information Engineering Command at Fort Huachuca, AZ; the MITRE Corporation in Bedford, MA; and MCTSSA on Camp Pendleton, CA. While each testing approach has its individual strengths and weaknesses, none of them generates accurate performance data useful for the Marine Corps to base procurement decisions on.

The SWAN system fills a specific capability gap and none of the testing efforts accurately simulate that environment. The two parts necessary to accurately simulate the SWAN environment, are the testbed and the network traffic used to run through the testbed to gather performance data.

Testbed composition varies from the use of actual SWAN terminal equipment, to full up simulations. The one testbed that uses actual equipment lacks valid network traffic to load the network with realistic scenarios. The other two testbeds are in part or all simulation. Even though the SWAN system is built from common networking components, simulating all or part of that network can incorporate inaccuracies in data generation. While simulations have advantages, their individual settings must accurately represent the SWAN environment, and to compare performance data, their individual settings should be close to identical; current testing efforts have neither.

The satellite simulation in current SWAN testing efforts is a perfect example. Those tests that used a simulated satellite only used a propagation delay of 250ms to 500 ms, when the actual delay experienced by deployed Marines is between 600 and 700 ms. While this is an easy fix in a simulator, there is no standard that current SWAN testing efforts are adhering to—a problem dating back to at least 2005. Another example of tested disparity

is that only one incorporates a KG-175B TACLANE mini-encryptor. This device may or may not have an affect on performance data, but it is a difference that makes data comparison difficult.

The biggest difference between testing efforts is how network traffic is modeled. None of the traffic patterns came even close to representing SWAN traffic. While this research was unable to obtain actual SWAN traffic, some logical assumptions can be made. First, SWAN terminals connect two or more LANs; therefore, there is more than one end user using the connection. Second, all the users do not use the same applications; therefore, there is more than one protocol transiting the SWAN link at any one time. Third, since there are users on both sides using the connection, network traffic travels in both directions. Cox characterized the data similarly. He stated that, "None of the tests reviewed measured [performance] on a highly saturated, low bandwidth link with multiple users, simultaneous TCP connections, and multiple protocols" (Cox, 2005, p. 33): all errors still being repeated today.

Two of the three testing efforts used only one protocol to simulate network traffic in one direction, and were performed by a single user. The protocol used was an actual FTP session. This is not nearly enough to saturate a SWAN connection as experienced by deployed Marines. FTP traffic implies large, multi-packet files, and real world traffic is small, often single-packet chunks of data. Another contributing factor to inaccurate network traffic is resource limitations. It is not reasonably possible for a single lab to generate an accurate amount of protocol traffic to saturate an actual SWAN link. Nor can a single lab reasonably produce an accurate number of users interacting on the satellite connection.

Simulators are not to blame for these uncoordinated efforts, nor should simulators be dismissed from use. Simulators have an essential utility, but they must represent the real world, otherwise, their output will have very limited use. Additionally, simulations should be repeatable, allowing for identical data to be gathered under various lab setups.

The raw data generated from these tests can easily be compared (Mbps vs. Mbps); however, the approach taken to generate that data makes a difference, which can affect performance results and future procurement decisions. The three efforts currently employed to evaluate TCP accelerators are uncoordinated, expensive and not representative of the environment that the device will be used in. However, there are elements in each organization's approach that can easily be combined and tailored specifically for testing SWAN networks—each at a smaller cost, and producing better results.

This research combined those elements into a standard test that facilitates real world SWAN network traffic more accurately than current efforts. The data collected from tests conducted in this testbed are easy to setup, repeatable and provide more accurate data. This data can be used to compare various vendor products and predict how well different network configurations may perform in the real world.

B. TCP ACCELERATOR PLATFORM OVERVIEW

There are several vendors that produce TCP accelerators. The shortlist of products for this research was derived by MCTSSA. The following is a brief overview of the test participants: Comtech-TurboIP; Comtech-TurboIP-G2; Citrix-WANScaler; Cisco-WAAS; and Riverbed-Steelhead. Images of these devices and their user interfaces can be found in the Appendix (Figures 31–39).

1. Comtech–TurboIP

This is the default accelerator currently used in the SWAN system; it is the device that all other accelerators will be compared too. This device simply performs standard PEP functionality, substituting space tolerant algorithms for native TCP algorithms. This device also has compression functionality; however, the USMC does not employ this mode. Setup for the TurboIP is quick and easy and Marines are familiar with it. The form factor for this device is convenient, as

it fits into the network package flyaway kit just above the router¹⁰. The user interface (Figure 31) is simple, intuitive and useful, even for the unfamiliar user. This interface is a Global Protocols, Skipware standard, also used by some competitors.

2. TurboIP-G2

This device is also produced by Comtech and is being procured by both the Army and the Marine Corps. The G2 performs legacy PEP functionality with improved algorithms for greater performance. The manufacturer advertises caching capabilities; however the device tested did not have this option available. Tests were conducted on single protocol scripts to compare the G2's compression mode on and off. The device performed equally well in both modes. The remaining tests were done with compression turned off, since this reduces complexity. Data deduplication will be available in the future as an add-on for this device. Setting up the TurboIP-G2 is plug and play, especially easy since this device was designed to replace the original TurboIP and built by the same manufacturer. This device comes in two form factors: standard size and ½-wide. The standard size easily replaces the current accelerator. The ½ size version provides the same functionality with a smaller form factor for easier storage and greater portability. It can be mounted in the same location as the standard accelerator with the 19" rack mount kit. The user interface is the same as the TurboIP device (Figure 31).

The remaining devices perform all legacy PEP functionality plus some or all modern functionality.

3. CISCO-Wide Area Application Service (WAAS)

This device has modern PEP functionality that includes application streamlining, caching and data deduplication. The form factor for the WAAS is completely different than that of all other devices. The WAAS is a small

¹⁰ Note that the SWAN system and its flyaway kit were designed with the TurboIP device in mind.

component that is installed directly into a slot on the front of the router. For this research, it was installed differently because the particular device that shipped to MCTSSA was not compatible with the SWAN standard Cisco 2811 router. Instead, it was installed in a surrogate router (Cisco 3825) that provided power and a place to connect to the network. WCCP functionality was enabled in the switch. This caused several problems getting the WAAS device to operate properly. It took the Cisco representative four days to set up the device, almost precluding it from testing. Fortunately, due to testing efficiencies designed in this research, the Cisco-WAAS device was run through most of the tests in less than a day. An advantage of this form factor is that it eliminates approximately ten pounds, attributed to other accelerator components like the TurboIP device (Figure 17, device form factor comparison). The user interface is also simple and intuitive to use. The software provides visual dashboards and graphing tools that present network performance real time (Figures 33 and 34).

4. CITRIX-WANScaler Defense Edition

The Citrix WANScaler is being procured by the Army for the Warfighter Information Network-Tactical (WIN-T) program. This device performs modern algorithms, compression, caching and to some degree, application streamlining. The compression functionality acts a lot like data deduplication, checking the cache site first and compressing only those files that have not transited the WAN. The application streamlining functionality only works on CIFS files. The WANScaler is also capable of interfacing with a WCCP; however, for this study the device was set up inline with the other networking components. Setup for this device required minimal effort, as it was a plug-and-play replacement for the original accelerator. The form factor allows the WANScaler to fit inside the network flyaway kit, in place of the TurboIP device. The user interface (Figure 34) is easy and intuitive to use. The device has some software tools that can be used for real-time network performance evaluations, such as monitoring the performance of each connection (Figures 35 and 36).

5. Riverbed-Steelhead-550

The Riverbed Steelhead device performs all legacy and modern TCP accelerator functionality, conveniently in one device. This device has an internal hard drive that facilitates the modern functionality. Setup required minimal effort with assistance from the Riverbed engineer. Network configuration for the SCPS virtual machine was intuitive because the user interface (Figure 37) is the same as the TurboIP. The form factor for the Riverbed accelerator does not conform to the current SWAN terminal flyaway kit, but the device comes with a rack mount that extends to fit a standard 19-inch rack. This device has the most robust software suite, facilitating greater network analysis and observation. In addition to dashboard gadgets and graphs, this software suite includes individual connection monitoring and a network analysis feature that allows packet captures on both the LAN and the WAN at the same time without connecting other packet capture devices to either network (Figures 38 and 39).



Figure 17. Accelerator Device Form Factor Comparison

Candidate Device	Model	SCPS	SNMP	WCCP Capable	IPv6	TCP Enhanced Algorithms 1	Compression	Caching	Application Streaming	Data De-Duplication
TurboIP	TurboIP	x	x			x	x			
G2	G2	x	x		x	x	x	2		5
Cisco	NME-WAE-522	x	x	x		x	x	x	x	x
Citrix	Defense Edition	x	x	x		x	3	x	4	
Riverbed	Steelhead-550M	x	x	x	x	x	x	x	x	x

1-Also referred to as Window Scaling

2-HTTP only. More capability will be offered as an add-on in the future.

3-Acts like data deduplication.

4-CIFS-based files only.

5-Available as an add-on in the future.

Table 7. Candidate Device Capability Summary

C. NETWORK TRAFFIC VALIDATION: ACTUAL VS. SIMULATED FTP

One of the most important questions to answer in a test environment is whether any simulation is valid. To validate the traffic generated in this research, performance data and packet captures were collected and compared to actual and simulated FTP connections.

Table 8 shows that the average throughput performance for actual and simulated FTP traffic is reasonably similar. This indicates that the simulated FTP protocol traffic closely represents actual FTP traffic. It is important to note that actual FTP sessions can be time consuming, reducing the number of sessions that can realistically be conducted in the lab. Additionally, it would be difficult to set up and measure performance characteristics of multiple, actual FTP connections. Conversely, the traffic generator can conduct significantly more transactions in a shorter amount of time.

File Size	FTP Performance		Script, 100 sessions, 1-way 1 KB, 50 records, 2 session per
	Actual KBytes/sec	Simulated KBytes/sec	
1 MB	9.45	9.669	
8 MB	9.73		
Average	9.59	9.669	

Table 8. FTP Throughput Performance, No Acceleration: Actual vs. Simulated

Packet analysis showed a difference between actual and simulated FTP traffic. As expected, the actual FTP session established a TCP connection with a 3-way handshake via control port 21, and when the '*get filename*' command was given, data transferred on port 20. Packets from the traffic generator simulate the FTP by substituting TCP connections for the FTP connections. Simulated packets indicated a 3-way handshake with a SYN, SYN/ACK, ACK sequence; however, these connections occurred on non-standard ports. (Figures 18 and 19 note the protocol column)

	Time	Source	Destination	Protocol	Info
35	48.366835	214.43.238.67	214.43.237.66	TCP	ecolor-imager > ftp [SYN] Seq=0 Win=65535 Len=0 MSS=1460
36	49.011306	214.43.237.66	214.43.238.67	TCP	ftp > ecolor-imager [SYN, ACK] Seq=0 Ack=1 Win=16384 Len=0 MSS=512
37	49.011584	214.43.238.67	214.43.237.66	TCP	ecolor-imager > ftp [ACK] Seq=1 Ack=1 Win=65535 Len=0
38	49.686042	214.43.237.66	214.43.238.67	FTP	Response: 220-FileZilla Server version 0.9.23 beta
39	49.713196	214.43.237.66	214.43.238.67	FTP	Response: 220-written by Tim Kosse (Tim.Kosse@gmx.de)
40	49.713469	214.43.238.67	214.43.237.66	TCP	ecolor-imager > ftp [ACK] Seq=1 Ack=88 Win=65448 Len=0

Figure 18. Wireshark Packet Capture: Actual FTP Traffic

	Time	Source	Destination	Protocol	Info
25	26.906073	214.43.238.67	224.0.0.10	EIGRP	Hello
26	27.273822	214.43.237.66	214.43.238.67	TCP	proxy-gateway > netiq-endpt [SYN] Seq=0 Win=65535 Len=0 MSS=512
27	27.274110	214.43.238.67	214.43.237.66	TCP	netiq-endpt > proxy-gateway [SYN, ACK] Seq=0 Ack=1 Win=16384 Len=0 MSS=1460
28	27.463058	214.43.237.66	214.43.238.67	TCP	netiq-endpt > bmcpatrolrvu [ACK] Seq=1 Ack=69 Win=65467 Len=512
29	27.516804	214.43.237.66	214.43.238.67	TCP	netiq-endpt > bmcpatrolrvu [PSH, ACK] Seq=513 Ack=69 Win=65467 Len=197
30	27.517077	214.43.238.67	214.43.237.66	TCP	bmcpatrolrvu > netiq-endpt [ACK] Seq=69 Ack=710 Win=65535 Len=0

Figure 19. Wireshark Packet Capture: Simulated FTP Traffic (From IxChariot)

This data supports the idea that the IxChariot tool accurately simulates FTP. Based on this data, this research assumes that IxChariot will also accurately simulate HTTP, SMTP and UDP traffic.

Since SWAN traffic is not homogeneous, other protocols are required to create realistic traffic loads. Network traffic for SWAN links, and nearly any other tactical network, is comprised of multiple users, simultaneously using multiple protocols, sending data in both directions across the link. Therefore, network evaluations should include traffic loads that represent multiple users, simultaneously using multiple protocols, sending data in both directions across the link.

D. SINGLE PROTOCOL SCRIPTS

Single protocol scripts were tested to gain an understanding of how the traffic-generating tool performed for each protocol under study. The Throughput, FTP, HTTP and SMTP scripts were individually tested to evaluate and determine a reasonable number of transactions for each protocol to perform within the allotted lab time. These initial, isolated tests also served as a baseline to which follow-on testing could be compared. These scripts were run through the testbed unaccelerated (No Accel) and then through the TurboIP device for baseline measurements. Next, those same scripts were repeatedly run across the network again, after reconfiguring each SWAN terminal with a candidate device, in place of the TurboIP device. Throughput metrics are provided in Table 9.

Recall that a few of the devices use a compression technique to optimize WAN performance. This research explored the compression capabilities of the TurboIP-G2 and the Citrix-WANScaler. Since the TurboIP-G2 did not demonstrate significant WAN optimization with data compression turned on in single protocol tests, this device was tested in its non-compression mode. The Citrix-WANScaler performed much better when using its compression technique, and was therefore tested as such. (Table 9 also displays the compression mode on/off throughput results for these two devices.) The devices were not ‘tweaked’ beyond the standard network configuration settings described in Chapter III.

The tests in Table 9 are organized as follows. Horizontally across the top, the devices are listed from no acceleration (No Accel) and the currently employed accelerator device (TurboIP) on the left (the baselines), to progressively more modern technology on the right. From top to bottom, the test scripts are listed beginning with an actual FTP session at the top and progressing down with more chatty, bandwidth intensive protocols. At the bottom are listed the total test times for all tests per device. (The test time for the Cisco WAAS device is considerably lower. This device had setup issues that later required abbreviated testing due to limited lab time.)

The data in Table 9 support the assumption that since IxChariot accurately represents actual unaccelerated FTP traffic, other protocols are also accurately represented. Notice how performance degrades as the protocol scripts become more chatty (compare performance vertically). From this same comparison, the data indicate that modern TCP accelerators, the devices that employ enhanced protocol algorithms, optimize WAN connections.

Script	Pairs	Timing Records	Transactions per Record	File Size MB	Average Throughput (Mbps)							
					No Accel	TurbolP	TurbolP G-2	TurbolP G-2 Compression	Cisco WAAS	Citrix WAN Scaler	Citrix WAN Scaler Compression	Riverbed Stealhead
Actual FTP	-	-	-	1.0	0.0095	0.0612	0.0647	-	0.1641	0.0401	0.0768	0.0956
	-	-	-	8.0	0.0097	0.1810	0.1679	-	2.7113	0.1196	0.6420	3.4635
Throughput	1	20	1	0.1	0.3210	0.4120	0.2880	-	0.7850	0.4180	0.9650	0.9130
	1	20	1	1.0	0.4460	1.0580	1.3900	-	4.7190	1.2510	5.9280	6.7900
	1	20	1	10.0	0.4610	1.6960	1.7890	1.784	28.3410	1.6620	21.9170	36.4750
FTP_get	10	50	4	0.1	0.6270	1.0430	1.1410	-	2.2560	0.9440	1.9310	2.2210
	10	50	1	1.0	1.1630	1.7180	1.7020	-	-	1.1150	7.7430	15.6610
	2	30	1	10.0	0.2750	1.7190	1.5380	-	16.8610	1.2630	19.5700	20.3450
HTTPgif	1	20	1	0.1	0.0960	0.1340	0.1360	-	0.3520	0.1310	0.3370	0.4450
	1	20	1	1.0	0.3510	0.6150	0.6830	-	-	0.4920	3.1920	3.9690
	1	20	1	10.0	0.4690	1.6940	1.5910	1.597	16.3450	1.3100	9.1770	20.2790
SMTP	10	20	5	0.001	0.0170	0.0200	0.0190	-	0.0210	0.0200	0.0210	0.0170
	10	20	5	0.1	0.7160	0.7500	0.7990	-	-	0.6590	1.4810	1.5740
	10	20	5	1.0	1.5720	1.7090	-	-	10.6950	1.3440	11.7980	14.7490
Test Time				Minute	599.8	239.1	170.9	31.8	30.5	303.7	60.7	49.3
				Hours	10.00	3.99	2.85	0.53	0.51	5.06	1.01	0.82

Table 9. Throughput: Single Protocol, Various File Size

Based on the performance metric of raw throughput, the results clearly show that modern TCP accelerator technology significantly optimizes WAN resources. As the files get larger, the traffic pattern recognition technique, in modern accelerators, facilitates data deduplication. This reduced traffic frees up bandwidth resources for other communications that may need to use the WAN connection. There is also significant time savings, as shown at the bottom of the table: 600 minutes to conduct all the tests, unaccelerated to 49 minutes with modern accelerator technology. Individually, these single protocol scripts do not represent actual Marine SWAN network traffic. These tests are simply baselines that provide a general feel for how accurately the traffic generator represents

traffic and it provides some data on which to reference accelerator performance. These tests were also used to evaluate a few components with compression turned on and off, specifically the TurboIP-G2 and the Citrix-WANScaler.

Figure 20 compares the performance for each device tested with five different individual protocols. These protocols were run with different files sizes; however, Figure 20 only illustrates the largest file size for each protocol. The Throughput script is a baseline test that returns performance results indicating the best throughput possible. From left to right the performance degrades, another indication that each protocol is progressively more chatty and therefore consuming more bandwidth. The Citrix device is the one exception. Due to the way the Citrix WANScaler handles HTTP specific traffic, there is a decrease in performance from the FTP to the HTTP test scripts. The WANScaler user guide indicates that for HTTP traffic, flow control and compression are disabled by default. This is a device-specific rule that reflects how Citrix defines HTTP traffic. There are settings that can be adjusted to circumvent this degradation in performance. This rule was not obvious during the week of testing.

The best performing accelerator was the Riverbed-Steelhead. This device showed significantly higher throughput for all single protocol tests than the other devices, especially with larger file sizes and on more chatty protocols.

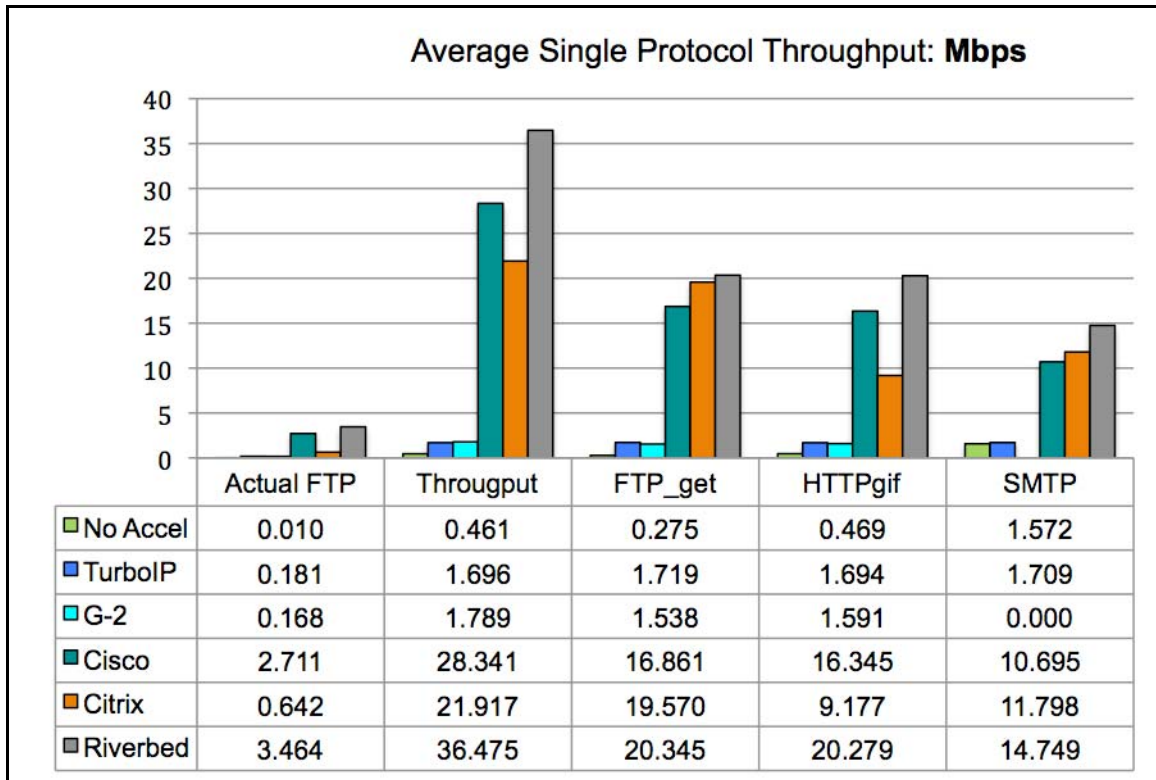


Figure 20. Throughput: Single Protocol Scripts

E. IXCHARIOT OUTPUT

The IxChariot traffic generator is a powerful tool that offers valuable insight into network and network device performance. Figures 21 through 25 illustrate the usefulness of this software tool; but more importantly, they illustrate the necessity of conducting tests with multiple users, simultaneously using multiple protocols, being conducted bi-directionally. These figures are unaccelerated tests that progressively add complexity to the network. It is important to note that the IxChariot Graphic User Interface (GUI) is simple and intuitive to use and it offers far too many analysis options to include in this research.

Figure 21 is a single FTP session that is repeated 500 times (10 records, with 50 transactions per record). To conduct this many FTP sessions manually would take an unreasonable amount of time and resources. This is the first instance illustrating that current testing methods are not representative of Marine SWANs. Though not shown in this view, the average throughput for this test was

0.005 Mbps. This FTP script is comprised of continuous, back-to-back FTP transactions, conducted much faster than humanly possible, even with multiple users. Figure 22 adds a second pair, each communicating in the opposite direction. The average throughput, as shown in the IxChariot GUI, is 0.164 Mbps. Together, Figures 21 and 22 indicate that a single FTP session uses some bandwidth and multiple users naturally use more bandwidth. While coordinating two or more simultaneous FTP transactions manually would not be difficult, performing 500 transactions each would be very complex. This highlights the importance of automated traffic generation.

Figure 23 illustrates the incorporation of a transaction delay, normally distributed from 1 to 4 seconds, between each FTP session to better represent human interaction. While this delay has no data to support the value chosen, it is a starting point for creating traffic that can better represent Marine SWAN traffic. This figure depicts each transaction with vertical bars. The average throughput, 0.144 Mbps, when compared to 0.164 Mbps (Figure 22), indicate that there is a performance price paid for the delay between transactions. Therefore, the delay is necessary when building automated traffic patterns to represent human-generated traffic patterns.

Figure 24 incorporates eight additional pairs of users, for a total of 10 connections, five connecting from East coast to the West coast, and five connecting in the other direction. Here, there are 50 FTP sessions conducted between each pair, with a 1–4 second delay between transaction and each transaction transfers 1 MB of data. There are 500 total transactions, transferring 1 MB of data per transaction, totaling 500 MB of data across the WAN via FTP transactions. Here, there is greater link utilization, 1.163 Mbps, attributed to more users; more users equate to more data consuming available bandwidth resources. This test script better represents what actual SWAN link transactions look like. Again, a single FTP session conducted in one direction, a method used

in other testing efforts, does not accurately portray tactical networks and therefore does not generate accurate data on which to base component procurement decisions.

From the single protocol test data, a single multi-user/protocol/direction test was constructed. This test makes optimal use of the 10-pair test limit in the IxChariot license, a few days of actual satellite airtime and actual SWAN terminals.¹¹ The mix of traffic was based on previous research by Cox, and there was a logical assumption made that many users will be using the same link at the same time, using different protocols in both directions, across the WAN. Table 10 summarizes the test recipe. (Table 10 is a repeat of Table 6, provided here for reader convenience.)

Script	File Size	Pairs	Transactions	TCP Connections
FTPget	1 MB	2	40	2
HTTPgif	1 MB	2	40	10 ¹
SMTP	1 MB	6	120	> 10 ¹
Totals		10	200	

Table 10. Summary of Multi-user/Protocol/Direction Test Script

UDP, the fourth most popular protocol, was not included due to the limited number of pairs, and as noted in Figure 15, UDP traffic simply passes through the TCP accelerator. Future testing should include UDP traffic to add congestion and bandwidth competition to the WAN, making traffic patterns even more realistic.

Figure 25 shows performance data from the unaccelerated multi-user/protocol/direction test, indicating an average throughput of 1.530 Mbps. This test is a better representation of SWAN traffic. The next section compares this test across accelerator devices.

¹¹ SWAN links are probably saturated with far more than 10-pair of connecting hosts.

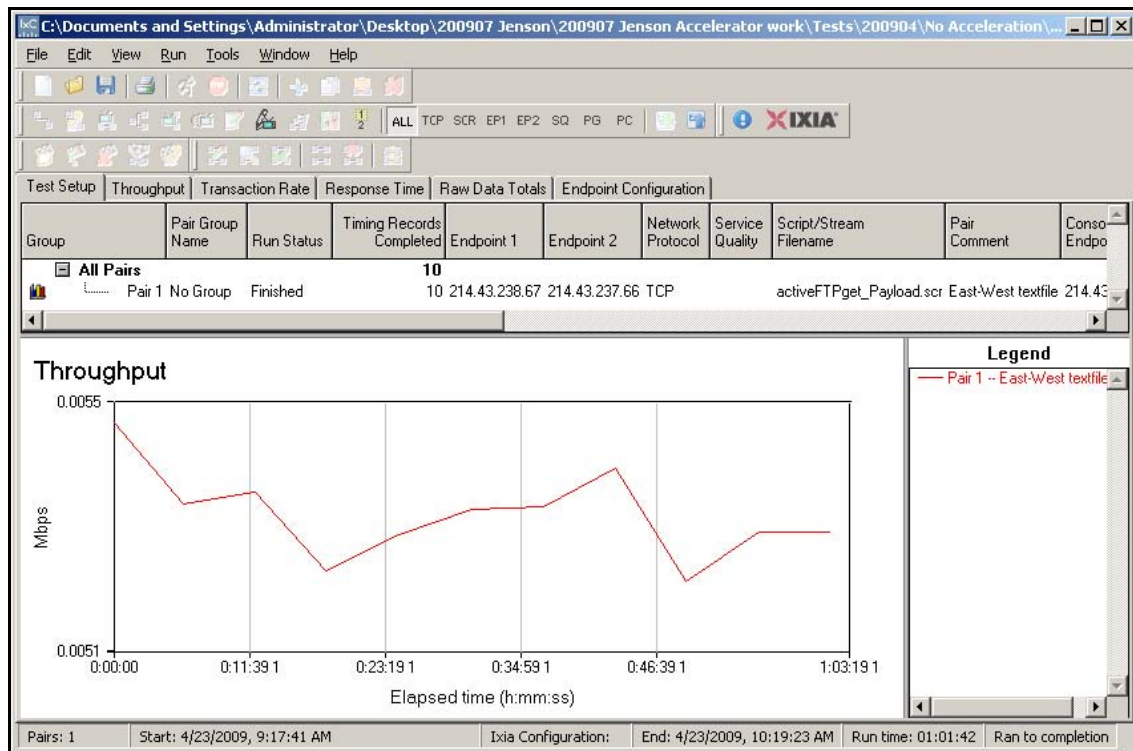


Figure 21. IxChariot GUI: Single-pair, Continuous FTP Session¹²

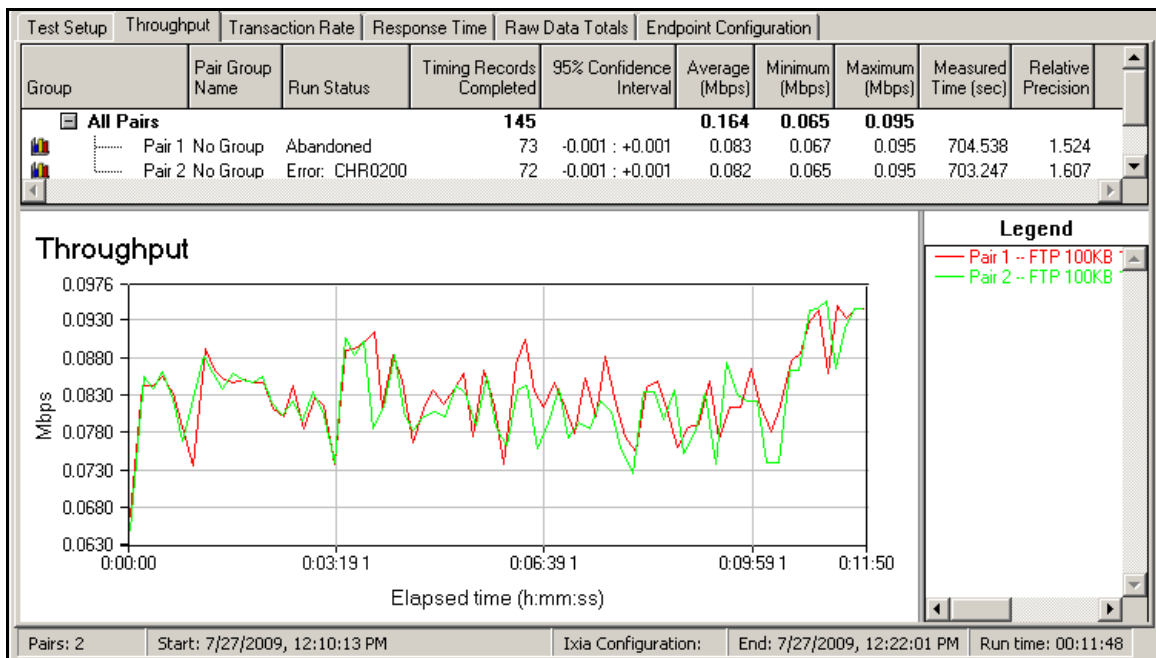


Figure 22. IxChariot GUI: Two-pair, Continuous FTP Sessions

¹² Figure 20 includes the entire display, while other figures include only important differences.

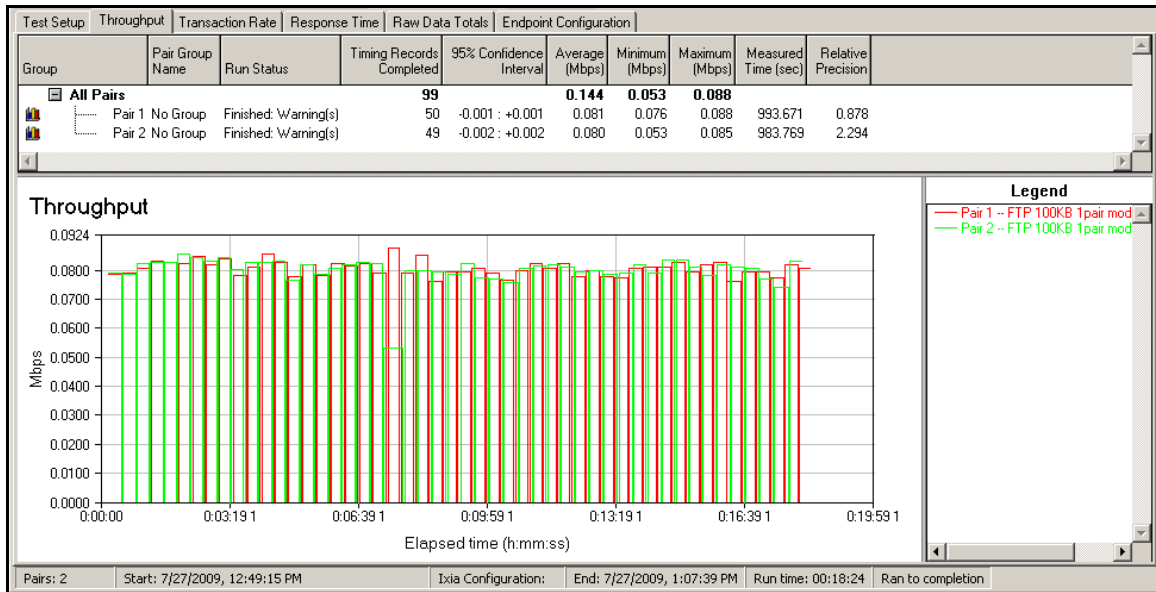


Figure 23. IxChariot GUI: Two-pair, Transaction Delayed FTP Sessions

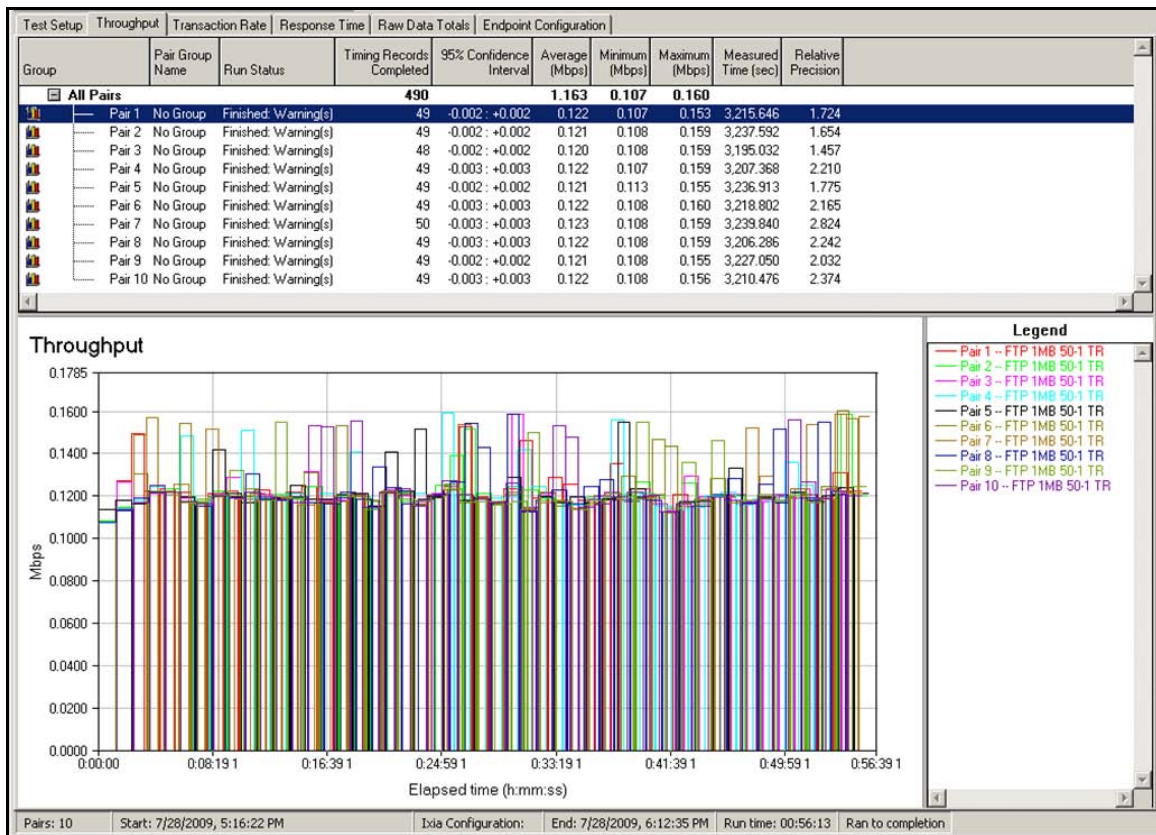


Figure 24. IxChariot GUI: 10-pair, Transaction Delayed FTP Sessions

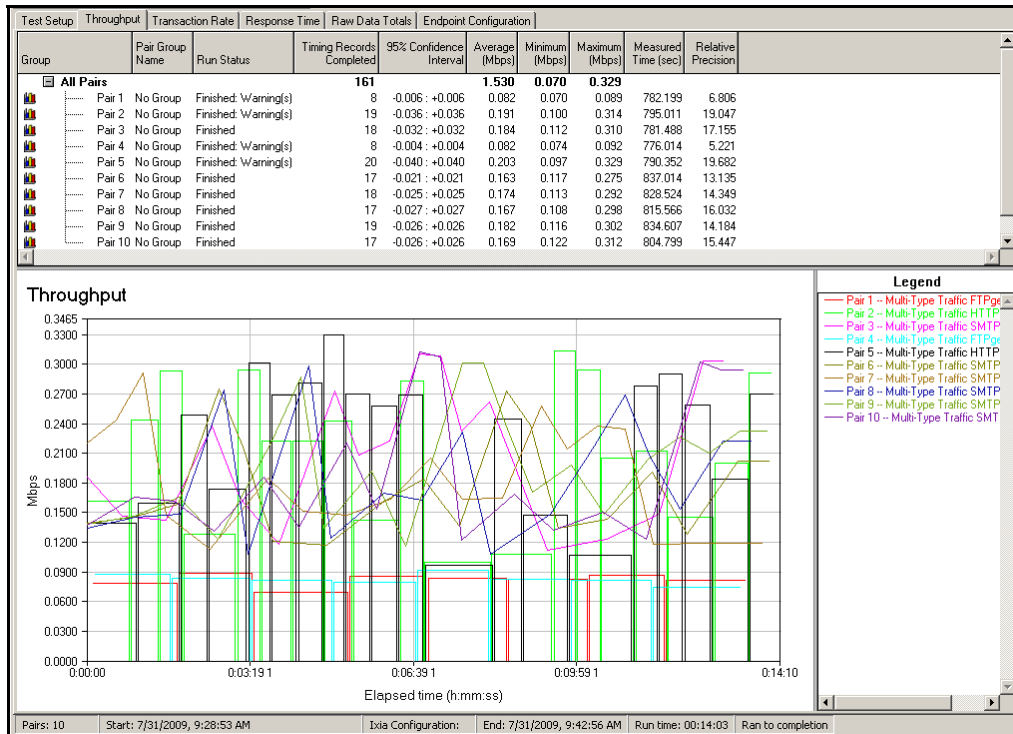


Figure 25. IxChariot GUI: Multiple Protocol Test, Unaccelerated

F. MULTIPLE PROTOCOL SCRIPTS

Since a single protocol does not represent actual SWAN traffic, multiple protocols were run across the link simultaneously, from multiple users communicating in both directions.

This test consisted of 20 separate, 1 MB FTP transactions run in both directions (40 total); 20 separate, 1 MB HTTP transactions run in both directions (40 total); and 60 separate, 100 KB SMTP transactions run in both directions (120 total). There are a total of 200 possible upper level transactions in this test. Upper level refers to the protocol: FTP, HTTP and SMTP. There are thousands of lower-level transactions that occur in this test. The lower level transactions exist inside the protocol, such as the two that exist inside of the FTP: the data and control transactions. This test achieves the objective of multiple users, simultaneously using multiple protocols, in both directions.

Some of the transactions for this test did not run to completion (Figure 26 and Table 11). This test was set up to run until the first test pair reached completion, after which all current connections were terminated normally. If all tests were allowed to run to completion, some test pairs would finish faster, since they are less chatty, allowing the clock to run with fewer bytes being transferred. This would reduce performance results since the throughput calculation is based on time. Again the Riverbed-Steelhead is the top performer, completing more transactions in less time with a significantly higher throughput (Figures 26–28).

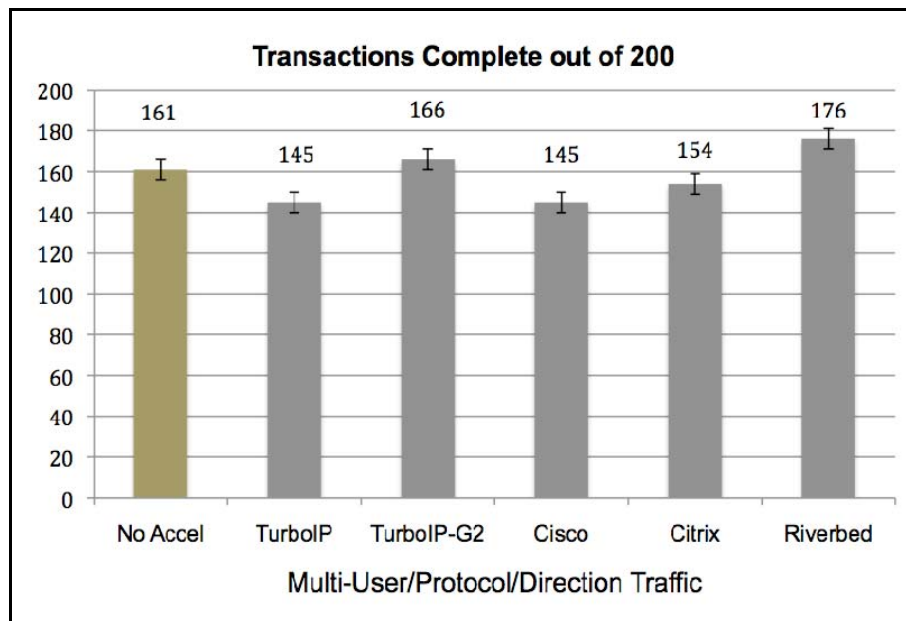


Figure 26. Transactions Complete: Multi-user/Protocol/Direction Test

	Transaction Breakdown						
	Number of Transaction	Number of Transactions Complete % Complete					
FTP (1MB)	40	16	27	30	33	27	34
		40%	68%	75%	83%	68%	85%
HTTP (1MB)	40	39	38	37	39	40	37
		98%	95%	93%	98%	100%	93%
SMTP (1MB)	120	106	80	99	73	87	105
		88%	67%	83%	61%	73%	88%
Total Transactions	200	161	145	166	145	154	176
		81%	73%	83%	73%	77%	88%

Table 11. Multi-user/Protocol/Direction Test, Transaction Completion Breakdown

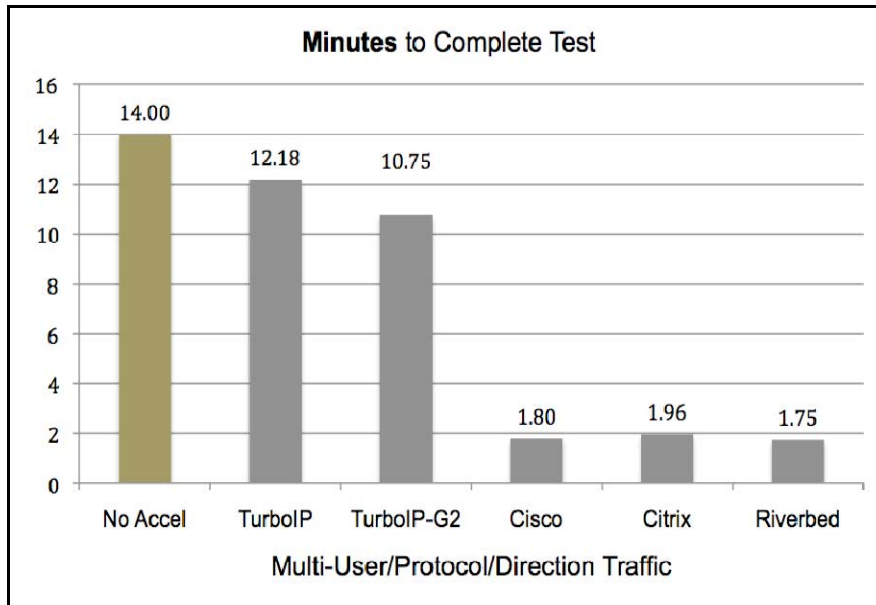


Figure 27. Time Results: Multi-user/Protocol/Direction Test

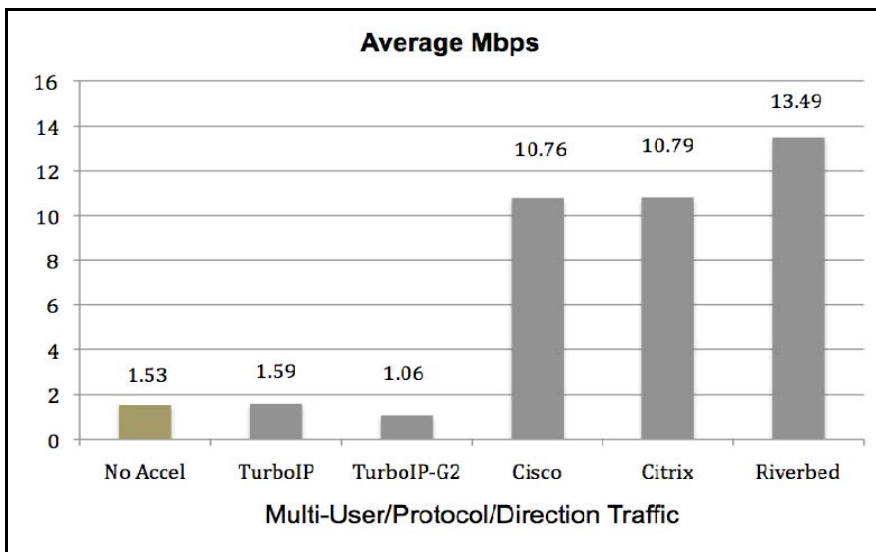


Figure 28. Throughput Results: Multi-user/Protocol/Direction Test

The IxChariot GUI provides an excellent illustration of the importance of a multi-user/protocol/direction traffic load and the value of modern accelerator technology (Appendix, Figures 40–45). As the graphs are analyzed from no acceleration, to more modern acceleration technology, the trend shows that application streamlining is present and beneficial. Both of the TurboIP devices and unaccelerated traffic have a more random protocol performance than

modern accelerators. The Cisco, Citrix and Riverbed devices show greater protocol organization, a benefit realized in greater bandwidth throughput and time.

G. TCP ACCELERATOR INTEROPERABILITY

The deployment of new equipment often requires overlapping functionality between new and old devices. Therefore, it is important to consider and test how well those devices interoperate. This segment of testing evaluates how well each of the candidate devices interoperate with the existing TurboIP device. The TurboIP device was installed on the simulated West Coast terminal and the candidate device was installed on the East Coast terminal. For each candidate device, the same multi-user/protocol/direction test script was used from the previous tests. A summary of the performance data for each interoperability test is shown in Figure 29. (IxChariot Interoperability test output is provided in the Appendix, Figures 46–50.) All of these devices are based on the SCPS-TP standard, mandated by DISA, meaning all candidate devices should, and they did, operate seamlessly with the currently deployed TurboIP accelerator.

The first column in Figure 29 is the TurboIP device paired with a like TurboIP device for reference. The following columns are the TurboIP device paired with a candidate device. Only one of the candidate devices had any performance variance outside the reference and none of them outperformed the homogenous TurboIP pair. This indicates that the devices are interoperable and that there is no performance degradation from what is currently being used in Marine tactical networks.

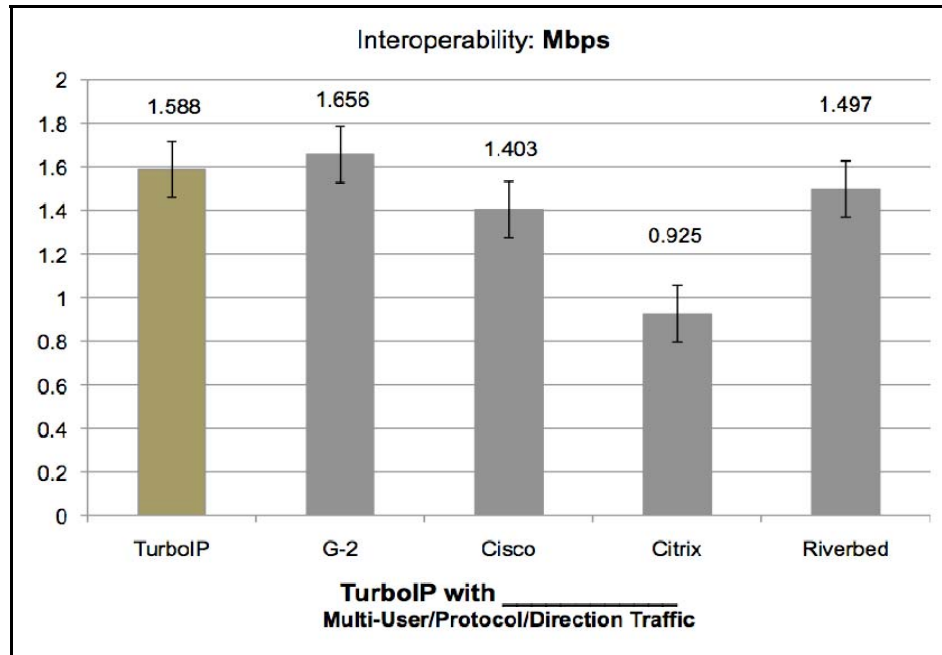


Figure 29. Throughput Results: Interoperability

The Citrix device performed at 2.3 standard deviations below the reference; however, IxCharoit reported an error with one of the test pairs, terminating the remaining test pairs. This error may have been caused by the compression mode on the Citrix device, but nothing conclusive can be drawn from the gathered data, and lab time precluded running this test again. Overall, the SCPS-TP standard in each accelerator facilitates interoperability, but only at legacy device performance.

Like any software solution, backward compatibility is important. Comparing homogeneous device performance and device interoperability with TurboIP, there is an obvious degradation in modern PEP devices. This is attributed to the TurboIP's legacy-only PEP functionality. It illustrates that technology has significantly changed over the five years that the SWAN system has been in service. It also highlights Moore's Law, suggesting that current TCP accelerator devices should be upgraded. Additionally, an upgrade to the TurboIP-G2 would be short lived, requiring another upgrade in the near future.

Notice that the Riverbed-TurboIP combination executed this test faster, than the TurboIP-TurboIP pair (Figure 30); the variance bars indicate that the difference is significant. This test was designed to turn off after one protocol script finished transferring all of its data. In this case, the Riverbed-TurboIP combination completed a protocol test pair (the FTP script) faster than any other interoperability test pair. This can be attributed to Riverbed's application streamlining, where the chattiness is consolidated on the LAN before the WAN transmission, thereby decreasing link utilization time.

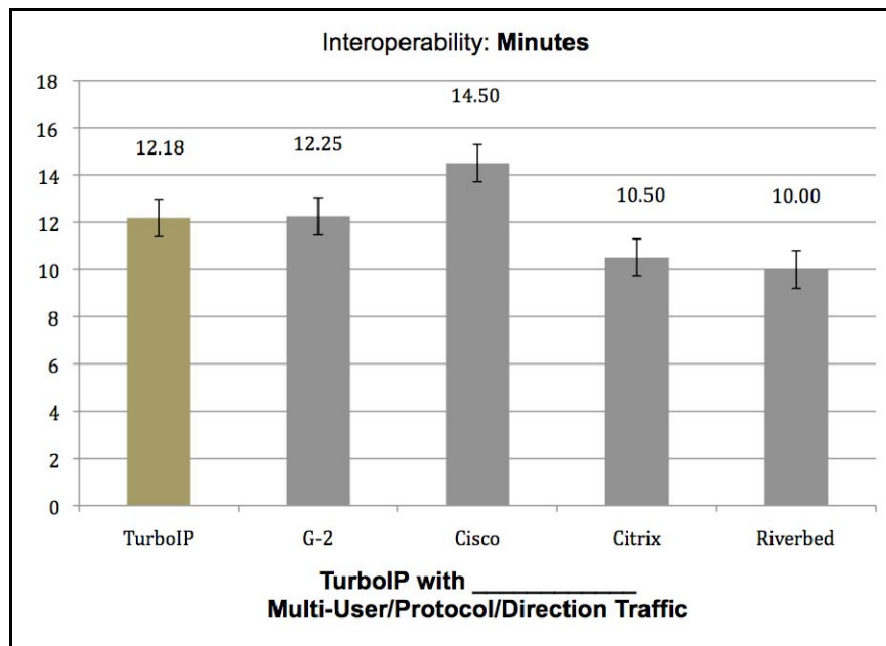


Figure 30. Time Results: Interoperability

H. WIRESHARK OUTPUT

Wireshark representations of the multi-user/protocol/direction test data support all previous analysis. An entire thesis could be done on TCP accelerator packet analysis, this section will address three aspects: TCP algorithms, network traffic (reduction and organization) and highlight the value of IxChariot as a network performance analysis tool.

1. TCP Algorithms

Wireshark IO graph analysis (Appendix, Figures 51–56)¹³ indicates that all the devices use the slow start algorithm, except the Cisco-WAAS device. They each take approximately 40 seconds to ramp up to their maximum data rate, indicated in packets per second (pkts/sec). The Cisco-WAAS device reaches its maximum rate in 27 seconds. (What the Cisco-WAAS device is actually doing is beyond the scope of this research.) Packet analysis of the 3-way handshake for each device, confirm that none of them use early open, as none of the handshake traffic contains data.

The uniform peaks and troughs for each individual graph indicate the TCP congestion control algorithm. The TurboIP and TurboIP-G2 are very similar to each other and to the unaccelerated graph. The difference in performance can be seen in the average maximum transfer rate (average of the peaks). Unaccelerated connections ran at 250 pkts/sec and both TurboIP devices average 500 pkts/sec. The increased data rate is made possible by enhanced window scaling: 65 Kilobytes (KB) for a normal TCP connection and 14 Gigabytes (GB) and 44 GB, respectively for the TurboIP devices.

Analyzing the three modern devices (Cisco, Citrix, Riverbed) in the same fashion shows a significant improvement in performance. Data rate: 3500, 500 and 500 pkts/sec respectively. Window size: 65 KB, 8 GB and 14 GB respectively. The jagged peaks are quite different between the modern devices, this illustrates the different proprietary implementation of the SCPS. (Again, the precise internal workings of these devices are beyond the scope of this study.)

¹³ Notice the red arrow on the No Acceleration, TurboIP and TurboIP-G2 graphs, Figures 51, 52 and 53 respectively. Since the horizontal sizes of these graphs were so large, the center segment was removed to conserve space. The blue arrow highlights the splice.

2. Network Traffic

a. Traffic Reductions

Comparing the overall area under the IO graphs generated in Wireshark, it is clear that modern accelerators (Cisco, Citrix and Riverbed) achieve better performance by reducing the amount of traffic that transits the WAN. Modern accelerators also transmit that data faster: 700 and 800 seconds for legacy accelerators; 140 seconds for modern accelerators, an 81% savings in bandwidth usage. By reducing traffic through caching, application streamlining and data deduplication, modern TCP accelerators leave more bandwidth available for other communications. Additionally, by transferring that data more efficiently, more bandwidth is available more often; both desirable qualities in today's tactical networks.

b. Traffic Organization

Though not included as figures, the packet captures showed significant traffic organization in modern PEP devices over the legacy PEP devices during the multi-user/protocol/direction test. The TurboIP packet captures indicated several 'TCP Dup Ack' (duplicate ACKs) and 'TCP Retransmission' packets. These packets were sprinkled throughout the entire connection. Each duplicate or retransmitted packet equates to one less original packet being sent across the network. The TurboIP-G2 also had several retransmissions due to lost segments. Multiply these by thousands of connections between multiple users, using different protocols all sending traffic both directions, and this consumes massive amounts of bandwidth that could otherwise be used for original traffic.

The modern PEP devices also had some lost, duplicate and retransmitted packets, but not nearly as many. This can be connected to the fact that they send less traffic across the WAN, meaning they naturally experience fewer errors. Fewer errors equates to fewer retransmissions and more available bandwidth. These devices also demonstrated a more efficient handling of these

inevitable packet losses. All three modern PEP devices neatly regrouped lost packet before they were resent, thus establishing one TCP connection to retransmit many 'Dup ACKs'. While all devices have some implementation of SNACKs, the modern accelerators demonstrated a more organized method. This traffic organization appears to aid in the efficient handling of errors, leaving more bandwidth available for other network traffic.

3. IxChariot

While a detailed study of packet captures indicated some traffic organization, the IxChariot throughput graphs for the multi-user/protocol/direction tests clearly illustrated it (compare Figures 40–45). Beginning with the unaccelerated tests, and including the two legacy accelerators, traffic patterns vacillate significantly, especially the more chatty protocol SMTP. Proceeding through the modern accelerator IxChariot graphs, there is a significantly noticeable streamlining of the chatty SMTP traffic. These organized traffic patterns aid in making modern accelerators efficient bandwidth managers. This pictorial explanation is not so easy to find in Wireshark packet captures. This comparison exercise highlights the value IxChariot has in network analysis.

Wireshark and IxChariot together both help illustrate vendor claims of component capabilities. Through this analysis, modern accelerators reduce network traffic and organize it more efficiently for better SWAN link utilization. Even though what happens inside the device is proprietary, this analysis was able to verify those vendor claims.

I. OTHER TEST RESULTS

1. U.S. Army Information Systems Engineering Command

The U.S. Army Information Systems Engineering Command conducted an accelerator evaluation in October 2007. Though the specific results are for official use only, every test they conducted also indicated that the Riverbed

device outperformed all other candidates in throughput and time. However, the Army's evaluation has two problems that make the results inaccurate for use by the Marine Corps.

First, the lab environment is not representative of SWAN tactical networks. The lab was a generic setup with a simulated satellite link that connected two LANs. The simulated satellite link RTT delay for the Army's evaluation was 250 milliseconds (ms). The actual average RTT in the SWAN connection for this thesis work was 665 ms. Second, the traffic generated does not represent SWAN tactical network traffic. These tests were primarily single protocol. A few tests contained two protocols, but none contained more than two protocols. As demonstrated in this analysis, single protocols or tests scripts that do not load the network with reasonable traffic will produce results that cannot reasonably be correlated to the real world.

While these tests were conducted on basic networking components on a simulated WAN, there was one element that future Marine Corps testing should consider. The Army used a KG-175B TACLANE mini encryptor inline with the other networking components. While in theory it should not make a difference, since the encryption occurs before the accelerator, it would be worth testing to validate that assumption. The Army's test connects the TACLANE between the accelerator and the router, similar to SWAN setups.

2. MITRE

MITRE SWAN research is in its infancy. During conversations with MITRE employees, they agree that actual SWAN traffic must be recreated to generate accurate results. Their testing consisted of an actual, single protocol transaction over the WAN link in one direction. Again, this approach is not representative of Marine SWAN traffic. This approach is also difficult to scale to the size of tactical networks. These tests, like the Army tests, used simulated SWAN terminals and a simulated satellite connection. They initially used 500 ms, but have been advised that 665 ms is more realistic.

MITRE is a little late to the game on accelerator testing. There are far better options available to the Marine Corps, than to spend time and money allowing MITRE to research this system.

3. MCTSSA

MCTSSA's greatest strength is that they have access to the latest Marine tactical network equipment and an actual satellite link to conduct testing on. This is the most important and expensive part of quality testing and it is necessary for accurate results. The tests that are conducted at MCTSSA are single user, single protocol, and conducted only in one direction. Again, this does not accurately represent Marine Corps SWAN traffic.

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V. CONCLUSION, RECOMMENDATIONS AND FUTURE WORK

The primary objective of this research was to create a standard, repeatable test that represents SWAN traffic generated by Marine operating forces. The intent of this test is to provide network decision makers repeatable procedures that generate accurate data that can be used to effectively evaluate network and network component performance. This objective was accomplished in three steps:

- 1) By developing a repeatable and realistic testbed template (Chapter III, Figure 12);
- 2) By employing readily available diagnostic tools to sense, organize and view performance data (IxChariot and Wireshark); and
- 3) By developing a network traffic load that better represents Marine Corps SWAN traffic.

The secondary objective was to use this test template and traffic load to generate TCP accelerator data to help determine the 'best of breed' device for the Marine Corps' needs.

A. CONCLUSION

The three testing efforts currently being funded to procure updated TCP accelerators are inefficient and ineffective. They are disparate and uncoordinated, each generating data that does not accurately represent Marine Corps SWAN traffic. These testing efforts had simulated networks and traffic patterns that were all configured differently, producing results there were difficult to compare.

This research consolidated elements from the three testing efforts into an accurate and reliable test plan that is more cost effective than the other testing methods. This approach uses the same traffic-generating tool the U.S. Army employs, but with more robust test scripts that represent SWAN traffic. The test

scripts built represent multiple users, simultaneously using multiple protocols, in both directions. These test scripts were combined into one common test that can easily and repeatedly be run through an actual SWAN link, reconfigured with multiple candidate TCP accelerators. The test can be applied to other networks as-is or easily modified to emulate other types of network traffic. The results show that the test is more dynamic and better represents the assumed chattiness in actual links. When this test was used to evaluate candidate TCP accelerator devices, the results clearly show that modern TCP accelerator technology significantly optimizes bandwidth utilization in the SWAN.

There were four candidate TCP accelerators tested against the current TurboIP device. The data supports, as Moore's Law suggests, that the TCP accelerator component of the SWAN system is in need of an upgrade in technology. While the legacy accelerator that was procured five years ago still functions well, modern accelerators optimize WAN bandwidth in two ways. First, by reducing the amount of traffic that is sent across the WAN and second, by organizing protocol traffic, which then uses significantly less time to transit the link, making bandwidth available more of the time. Both functions help better utilize the available bandwidth more efficiently.

These devices are in fact in need of an upgrade. It is not realistic to always purchase the latest and greatest technology upgrade; however, in this case where bandwidth demand is continually increasing and modern accelerator devices provide significant bandwidth savings, it makes sense to procure the technology. Additionally, compare the cost of purchasing another satellite or additional bandwidth, to that of upgrading TCP accelerators that optimize already purchased bandwidth. The Marine Corps could buy back-to-back increments of accelerator upgrades for a decade to equal the cost of another satellite.

B. RECOMMENDATIONS

1. TCP Accelerator Testing for the SWAN System

Since the three testing efforts evaluated in this research do not generate accurate data on which to base decisions, it is recommend that MCSC adopt the testing approach outlined in this thesis. This can be accomplished in the three steps: a) Purchase a quality network traffic-generating tool; b) Establish testing procedures for SWAN systems at MCTSSA, most of which is outlined in this thesis; and c) Incorporate already contracted IT consultants into these decisions.

a. Network Traffic-Generating Tool

The Marine Corps has the ideal SWAN testbed already set up in the SWAN lab on Camp Pendleton. They have actual SWAN terminals and an actual satellite link that are configured to perform like those systems that are forward deployed with our Marines. The only thing missing in this test environment is a robust traffic-generating tool. IxChariot was the tool used for this research and it is the same tool employed by the U.S. Army. This software tool was easy to learn, and it had a robust set of analysis capabilities that would help Marine network analysts and network decision makers test and evaluate tactical networks for TCP accelerator performance, and any other network component or network configuration.

Another option would be to coordinate testing with the Army. Since actual traffic patterns for the Marine Corps and the Army probably do not differ drastically and the fact that DoD IT and communication systems are required to be interoperable, it would make sense to combine these efforts so that test data can be more valuable to both service. This option would facilitate greater Marine Corps input into component procurement for Marine specific systems, while at the same time giving the Army greater insight into the Marine Corps' needs. This synergy would aid in the faster procurement of COTS solutions, delivering better, more capable systems to the warfighter.

Either recommendation would require the Marine Corps to purchase a network traffic generator. The author recommends the IxChariot software tool with a floating license that includes at least 200-pairs (product numbers: 920-0034).

b. Test Procedures

TCP accelerator and SWAN testing procedures need to be standardized and documented, at the very least within in the Marine Corps. A standardized test would allow the Marine Corps to not only test organically, but also provide better guidance to IT consulting firms. Currently, test knowledge resides in the SWAN lab personnel, undocumented, and in IT firms outside the control of the Marine Corps. A small employee turn over at either location could result in the loss of some or all previous testing knowledge. Additionally, there is no historical data currently available to compare today's TCP accelerators or network performance to. Standardizing SWAN test procedures will allow the Marine Corps to track accelerator performance over time, making future evaluations more valuable and efficient. It could also be used to provide better guidance for evaluations done by IT consultants. Using IxChariot is one way to facilitate testing standards and it would also retain testing data for future comparison.

The Marine Corps has organic assets to facilitate the collection of information necessary to evaluate modern accelerator technology or any other segment of the SWAN system. These organic assets exist at MCTSSA. While MCTSSA's testing efforts are currently incomplete, some simple, cost effective and time saving modifications would make this effort more comprehensive, accurate and valuable to decision makers.

The primary elements of this test are the traffic generating tool and the accurate and realistic test environment. With these two elements, this test can be applied to any network configuration to evaluate performance. These procedures can easily be shared with other organizations to compare network

performance. They could even be used to replicate network problems being experienced by Marines who are forward deployed and call back to MCTSSA for support. The bottom line is this test is repeatable, accurate, and flexible to changing networks or different types of networks.

c. IT Consultants

While the MITRE Corporation may provide excellent service on their DoD contracts, the testing and evaluation of SWAN components is not optimal. They have several employees working on the SWAN project and have not produced any solid recommendation for the two years of their research. Their contract linked to SWAN equipment should be allowed to expire.

Sidereal Solutions has provided valuable input into the SWAN program, and should remain in the Marine Corps' budget. James Willard, Vice President and General Manager of Sidereal, should have a voice in all SWAN component procurement decisions, as well as in standardizing testing procedures and purchasing of traffic-generating equipment. Mr. Willard is very knowledgeable about the SWAN system and the many vendors that build components for this COTS solution. His contribution to this research and future SWAN system decisions are invaluable.

2. TCP Accelerator Selection

There were four candidate TCP accelerators tested against the current TurboIP device: the TurboIP-G2, Cisco-WAAS, Citrix-WANScaler and the Riverbed-Steelhead. The Riverbed accelerator outperformed all other devices in single and multiple protocol tests, single and multiple user tests, as well as interoperability tests. (Of particular note, the Riverbed device, paired with a TurboIP device, outperformed a homogeneous pair of TurboIP devices.) Riverbed-Steelhead device also has the most complete and functional network-performance monitoring software.

This thesis is not the only indicator that the Riverbed device is the best choice. The U.S. Army Information Systems Engineering Command collected similar results, even though their tests were not as complete. The Riverbed Steelhead device will give the SWAN system greater capacity to facilitate communications, allowing Marines to maintain their tactical edge now and well into the future.

3. Technology Modifications

Early open is a TCP technique, briefly mentioned Chapter II, which should become an available feature in the near future. Since wireless and satellite links are including more individual warfighters who will be generating large amounts of small network traffic, the early open technique would pay immediate dividends to reducing volumes of network congestion. Perhaps the SCPS-TP standard could be refreshed to incorporate this technique for widest dissemination. If not the SCPS-TP standard, then this technique should be recommended to TCP accelerator vendors for incorporation into future software upgrades.

C. FUTURE WORK

1. Multicast

Computers were initially designed to speak to each other via protocols that were designed in the 1960s and 1970s, though they have been updated, are still in use today. This research began exploring multicast in the tactical environment; however, the more immediate problem of addressing the testing procedures for the current SWAN systems in the USMC took precedence. TCP accelerators are a short-term, intermediate solution to the larger reliable multicast problem. A reliable multicast software protocol would be the next big step for extending the Internet into the battlefield.

The trend is to push the Internet deeper into the battlefield and farther down the chain of command, facilitating the accurate and timely exchange of information. Blue Force Tracker is an example where the Internet is becoming

more available in mobile platforms such as tanks, aircraft, ships and even down to the individual warfighter. This growth presents several problems such as reliably sharing individual data with multiple end users, on networks that are bandwidth challenged and doing it with authentication, where subscribers are dynamically entering and exiting the network continuously. This growth will require an increase in systems like RF-WANs, both on the ground (WPPL) and SATCOM (SWAN). The consequent opportunities are significant.

This solution is not military specific. Reliable multicast capabilities have many commercial application of which emergency services are but one. Therefore, this software protocol should eventually reside in the operating system stack, and be distributed as such.

The Internet Engineering Task Force is working on one such experimental protocol called Negative Acknowledgement (NACK)-Oriented Reliable Multicast (NORM). Explored as a thesis topic, this protocol would provide valuable insight into how this next generation protocol will help solidify network-centric operations in the DoD. The author would recommend that this research be done by a minimum of two students working on different aspects of NORM. One student would focus on understanding, installing, and modifying the NORM source code. This area of focus would be best suited to a Computer Science student or a proficient programmer¹⁴. The other student would focus on the integration and testing of this reliable multicast protocol on DoD networks. An accurate test template is contained in this thesis (Chapter III). In addition to the template, keep in mind that more than one end terminal will be required. Links between Camp Pendleton, Camp Roberts and NPS are all within a reasonable distance and all support DoD networking research. This protocol will become standard in future network-centric operations and should be explored by NPS students for its incorporation into the DoD and Marine Corps tactical networks.

¹⁴ NORM source code is available at <http://downloads.pf.itd.nrl.navy.mil/norm/>.

2. Traffic Composition

This research built robust test scripts for testing tactical SWANs. Actual traffic patterns from SWAN networks were not obtained for this research. The importance of this cannot be over emphasized for future study and analysis. The following is a list of sources, in order of precedence, from where traffic should be captured, analyzed and modeled for future research and lab testing:

- a. Network traffic that is forward deployed, such as SWAN traffic in Iraq, Afghanistan or the Horn of Africa.
- b. Training exercises where the SWAN terminals are actually separated by significant, BLOS geography. An excellent place to start would be the monthly training exercises out of Twentynine Palms, CA, where satellite links are established with SWAN terminals from around the country, including Camp Lejuene and Hawaii.
- c. Training exercises conducted at the Communications Schools in Twentynine Palms, CA, or Quantico, VA.

The traffic patterns generated from the U.S. Army Information Systems Engineering Command and the MITRE Corporation do not accurately represent real world Marine traffic and should be avoided at this time. These traffic patterns are not robust enough to load the network or accelerator devices with traffic that would produce valuable information.

This research used network traffic as described by Criston Cox in his 2005 thesis, along with some logical characteristics drawn from the composition of the Internet. Network traffic is dynamic and SWAN traffic is probably quite different depending on organizational level and theater employment. For example, traffic between the MEF and Division is probably different than that between Regiment and Battalion. Also, traffic in Iraq is probably different than that in Afghanistan or the Horn of Africa.

Characterizations should include what current patterns looks like and what the future trends will be. Currently, with respect to modern TCP accelerator technology, caching and data deduplication, it would be useful to know how much network traffic is new, and how much is repeated, since repeated traffic does not transit the WAN. Considering the goal of network-centric operations, future network traffic will consist of a large number of users sending smaller packets over wireless communication links.

For these reasons, a traffic composition study of Marine Corps networks would benefit network configuration considerations. Further study should not focus on SWAN traffic alone, but rather characterize network traffic within the Marine Corps as a whole. Other networking traffic to consider is administrative networks and inter-service networks.

3. Computing Protocols

The four protocols tested during this research only represent the four primary protocols as identified by Criston Cox (Cox, 2005). The multi-user/protocol/direction test recipe developed in this research is not perfect, although it is a better representation than current testing efforts. It was constructed based on data gather in 2005 and the reasonable assumption that SMTP should be the dominant application protocol that uses a TCP connection. This assumption did not consider that the SMTP traffic file size would be much smaller than the other bandwidth competing protocols (FTP and HTTP). Additionally, this test did not include any UDP traffic in the protocol mix. Based on this research, future test recipes should look something like Table 12. This recipe is based on the 10-pair license limit and should be scaled appropriately on IxChariot chassis with more capabilities. Since the reliable delivery of packets is desirable, the TCP is the primary connection protocol that should be tested. UDP is important and even though the accelerator does not touch the traffic, it should be included to evaluate performance with other non-TCP traffic competing for bandwidth.

Script	File Size	Pairs	Transactions	TCP Connections
FTPget	1 MB	2	125	2
HTTPgif	1 MB	2	125	10 ¹
SMTP	1 KB	4	250	> 10 ¹
NetMtg	Stream	2	Stream	UDP
Totals		10	500+	

Table 12. Test Recipe for Future Tests

4. Cost Analysis

Today, the Marine Corps and DoD generate more data than ever. As storage gets cheaper, we find ways to fill it, and what we store we eventually share. The traffic that transits the WAN is not all new data, but mostly a modification to previously exchanged data. This is where data deduplication makes such a significant difference. Modern accelerators perform optimization by reducing the traffic that transits the WAN. All of the devices that were tested require an investment in money. With any IT solution, its return on investment (ROI) must be considered.

A relevant study would explore the savings these devices offer by making current bandwidth more available through data deduplication and application streamlining. By reducing that data that transits the WAN, the accelerator is essentially making this limited resource more available for use. The cost savings in this would add even more credibility to the procurement of future accelerators. The study should strive to identify a method that can be applied to both TCP accelerators and other IT components, in an efficient and timely manner.

5. Open Source Solutions

This research explored proprietary vendor products that bear a significant cost. There are, however, open source solutions to WAN optimization. These solutions offer similar capabilities at no cost with the added benefit of having multiple peer reviews. One of the reasons Macintosh and Linux computers are so secure and successful is that they are built on the Unix platform, which is an

open system. This allows the user to study how the system works and make adjustments to improve it. These are the same reasons that SCPS-TP and other standards now exist for TCP acceleration.

SCPS-TP is an open source standard, designed so that any developer can make modification to it for improvement, and yet still be interoperable with current systems. A performance study including open source solutions such as NORM could reveal an even more cost effective method to optimizing WAN performance.

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VI. SUMMARY

The Support Wide Area Network has been a valuable addition to communications in the Marine Corps. It has taken the power and flexibility of the Internet and extended it into remote locations, facilitating mission accomplishment for Marines on the tip of the spear. This system's effectiveness is attributed to two critical factors in network-centric operations: 1) the system facilitates communication beyond line-of-sight; and 2) it does so as a routable network segment (Figures 11 and 12).

Central to the SWAN's effectiveness is its modularity. This modularity provides for interoperability and maintainability. Its interoperability is manifested through its routable characteristics. It simply directs an already formatted data packet to another terminal through the challenging space environment, without modifying the packet. This means that it does not matter what component is on the other side of the link, as long as that component can process a standard Internet packet. The SWAN is maintainable through interoperable components. These components can be easily replaced if broken, or updated with better technology. The ability to upgrade components like the TCP accelerator, allows the entire system—in this case the tactical BLOS network—to operate more efficiently without making the costly upgrade of replacing the entire system.

The SWAN's efficiency comes from its ability to squeeze as much effective capability out of the available bandwidth. As the warfighter's demand on bandwidth intensive systems continues to grow, budgeting efforts will have to be split between equipment like the SWAN system and bandwidth resources. Since monetary resources are limited and inevitably must be split, it makes economic sense to procure components that better manage the expensive and limited bandwidth resource. This is an area that can benefit from both modern accelerator technology and reliable multicast (NORM).

With the exception of the space segment, virtually all of the SWAN components can be expected to be upgraded, sometimes several times, within the lifetime of the overall program. This leads to two observations: 1) modularity is important for maintainability; and 2) some components, like the accelerators, need to be refreshed on a planned, regular and frequent basis.

The SWAN system was procured through the Urgent Needs Process, allowing it to forego the time consuming timeline of normal programs of record. Programs of record have a history of being over budget, behind schedule, and often deliver aged capabilities. Recently, the SWAN system was declared a program of record and is already subject to these unintended consequences. For example, the most recent SWAN-D upgrade will include the TurboIP-G2, a necessary replacement for the end-of-life TurboIP device. The data in this research clearly show that this technology is already outdated and that better, more capable components exist. Yet, the Marine Corps will continue to purchase this upgrade and deliver it to the Marines who deserve more advanced equipment that is readily available.

Information Technology systems, by their very nature, age rapidly. The latest DoD findings have confirmed that the procurement cycle for IT systems is “too long and cumbersome” (Office of the Under Secretary of Defense, 2009, p. iii). The SWAN system must not succumb to becoming outdated due to this slow acquisition process. A contributing factor to the long procurement process can be attributed to the lack of fast and accurate testing. Since COTS network components have many vendors, accurate network testing must include two key elements: 1) an accurate testbed and 2) near real world network traffic. This research provides recommendations for both, with respect to the SWAN system; however, this approach can be applied to any tactical or administrative network in the Marine Corps and the DoD.

The Marine Corps has the means to streamline the process of keeping SWAN system components, and other networking devices, more up-to-date than they do presently. The facilities and equipment are available at MCTSSA. The

only elements missing are a robust network traffic generator and a simple test plan to accurately and quickly evaluate network components. Specific recommendations for both are provided in this thesis.

The TCP accelerator is a component that is overdue for replacement. Modern accelerator technologies should be procured now because their cost and benefit easily outweigh the alternative option of purchasing more bandwidth. Additionally, work should begin on the next generation upgrade. In this next procurement, include the multicast transport in the equation, where the cost/benefit numbers are even more convincing.

Since IT technology breakthroughs are unpredictable, it is difficult to determine when component upgrades should be revisited. Fast, accurate and documented testing can facilitate the evaluation of whether or not a component should even be considered for an upgrade. The testing methodology recommended in this thesis is an excellent and efficient start.

This research identified three parallel testing efforts that are incompatible, and suggested a method to consolidate and streamline the testing of SWAN components, in order to keep these systems fully capable. This research has also generated an initial test plan that can be easily updated or rapidly reconfigured to more closely represent SWAN traffic for realistic network testing. These simple cost effect steps can provide better equipment to forward deployed Marines faster than the current process, allowing them to maintain their tactical edge and continue to win battles.

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APPENDIX

A. CANDIDATE DEVICES

1. Comtech-TurboIP (Current Device)

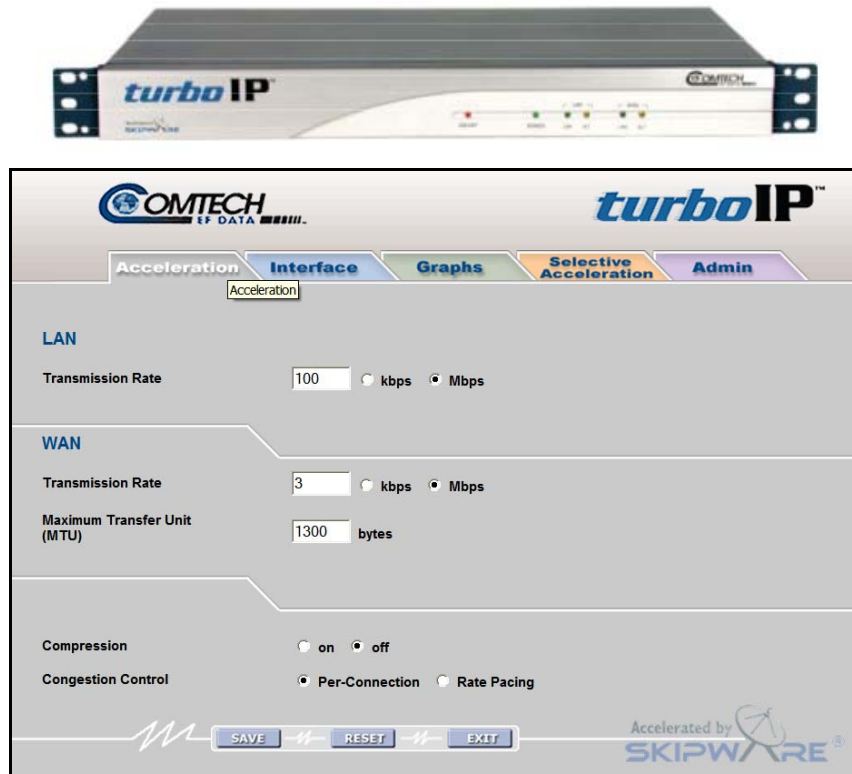


Figure 31. TurboIP, Device and Configuration Interface

2. Comtech-TurboIP-G2



Figure 32. TurboIP-G2, Device

3. Cisco-WAAS

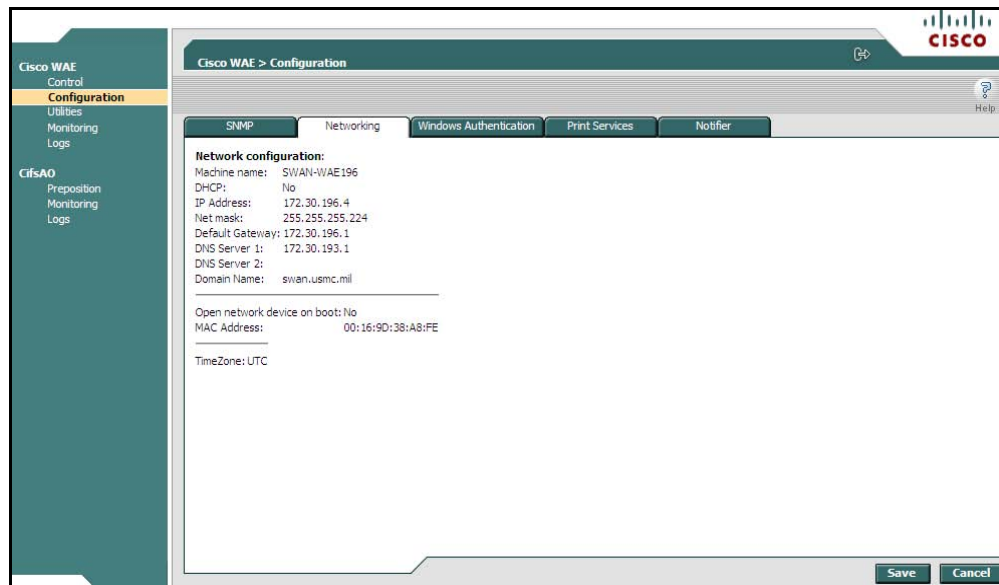


Figure 33. Cisco-WAAS, Device and Configuration Interface

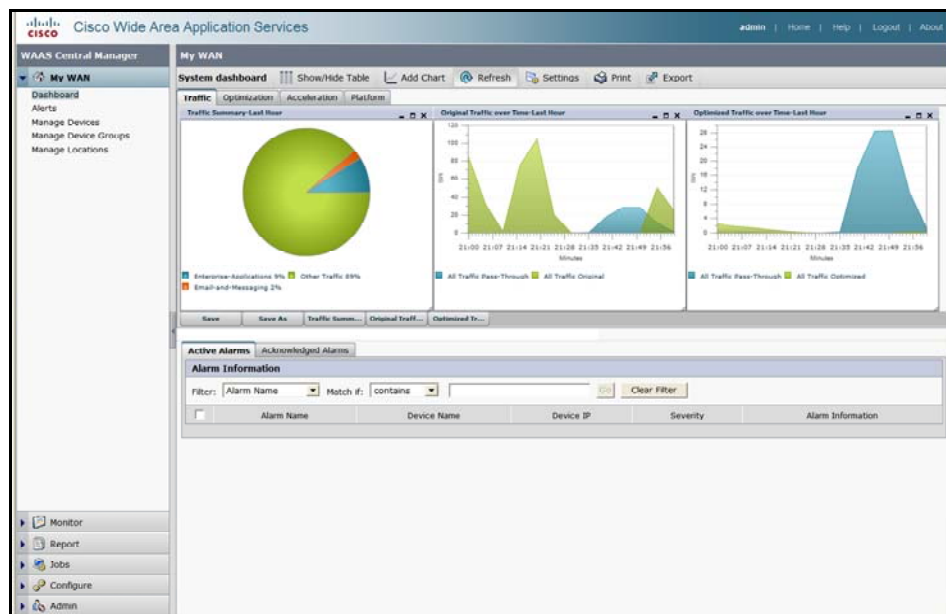


Figure 34. Cisco-WAAS, Performance Monitor Screen Capture

4. Citrix-WANScaler



Figure 35. Citrix-WANScaler, and Configuration Interface

Active Connections

CIFS Status

Service Class Statistics

Compression Status

QoS Statistics

WCCP Status

Repeater Plug-ins

MAPI Status

ICA Status

Configure Settings

Bandwidth Management

Proxy

Interface

Tuning

SNMP

Date/Time

Logging

Alert

UI

CIFS

Service Class

Service Class Policy

QoS

IP Address

High Availability

Group Mode

WCCP

Repeater Plug-in

Reporting

Service Class Statistics

Line Utilization Graph

Compressibility Graph

Monitoring: Service Class Statistics

Service Class Name	Current Accelerated Connections	Total Accelerated Connections	Total Accelerated Bytes	Total Accelerated Packets	Action
Unclassified TCP	1	9	147.1M	161.4K	
Passthrough Traffic	0	0	0	0	
HTTP (Private)	0	0	0	0	
HTTPS (Private)	0	0	0	0	
HTTP (Internet)	0	0	0	0	
HTTPS (Internet)	0	0	0	0	
FTP Control	1	1	2.5K	36	
FTP Data	0	2	10.1M	13.1K	
CIFS	0	0	0	0	
SMTP	0	0	0	0	
PortMapper	0	0	0	0	
Terminal Services	0	0	0	0	
LDAP	0	0	0	0	
SSH	0	0	0	0	
POP3	0	0	0	0	
Kerberos	0	0	0	0	
ICA	0	0	0	0	
DNS	0	0	0	0	

Unclassified TCP

Details

Reset

Figure 36. Citrix-WANScaler, Individual Connection Monitor

5. Riverbed-Steelhead



Figure 37. Riverbed-Steelhead, Device and Configuration Interface

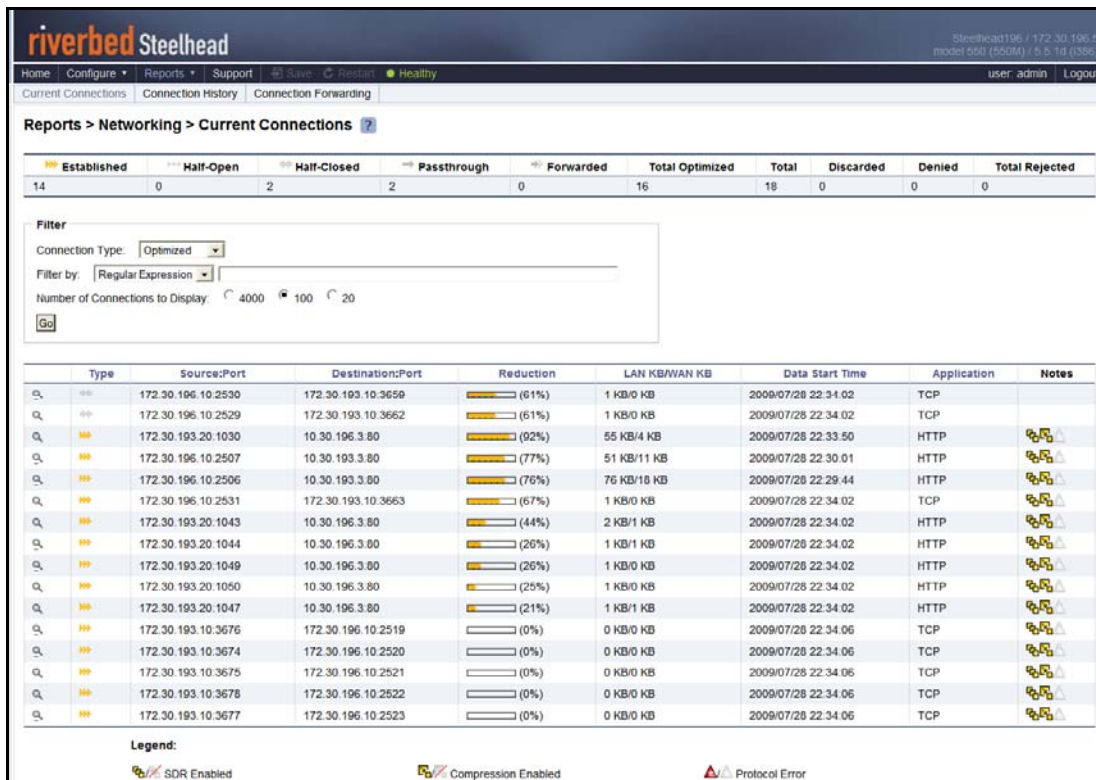


Figure 38. Riverbed–Steelhead, Individual Connection Monitor

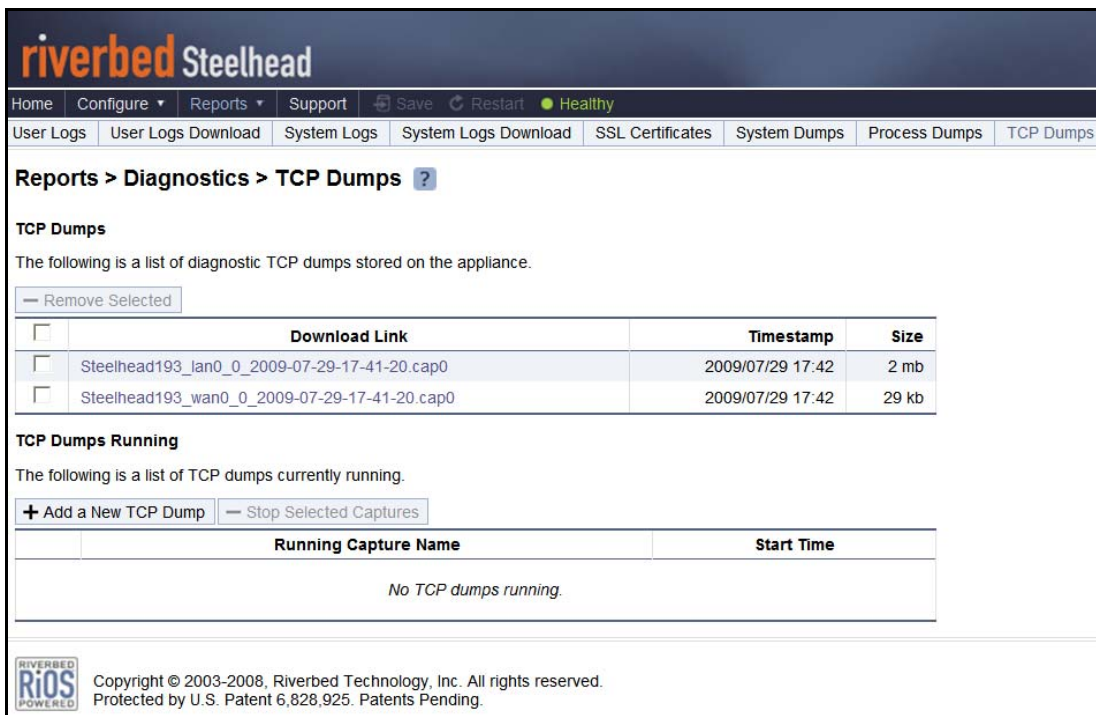


Figure 39. Riverbed–Steelhead, Packet Capture Interface

B. MULTI-USER/PROTOCOL/DIRECTION TRAFFIC

1. No Acceleration (Unaccelerated)

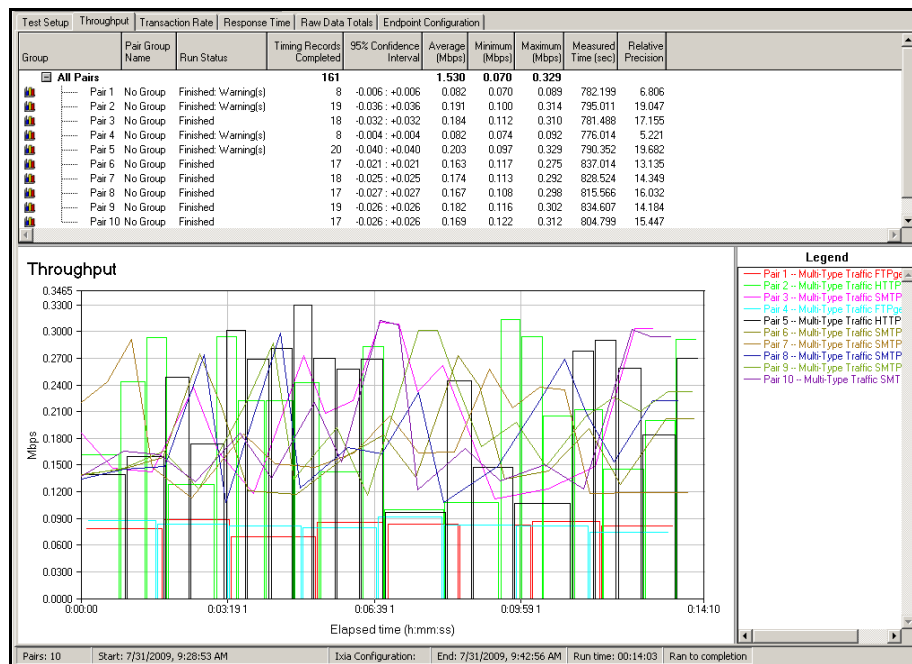


Figure 40. IxChariot GUI: Multi-user/Protocol/Direction Test, Unaccelerated

2. TurboIP

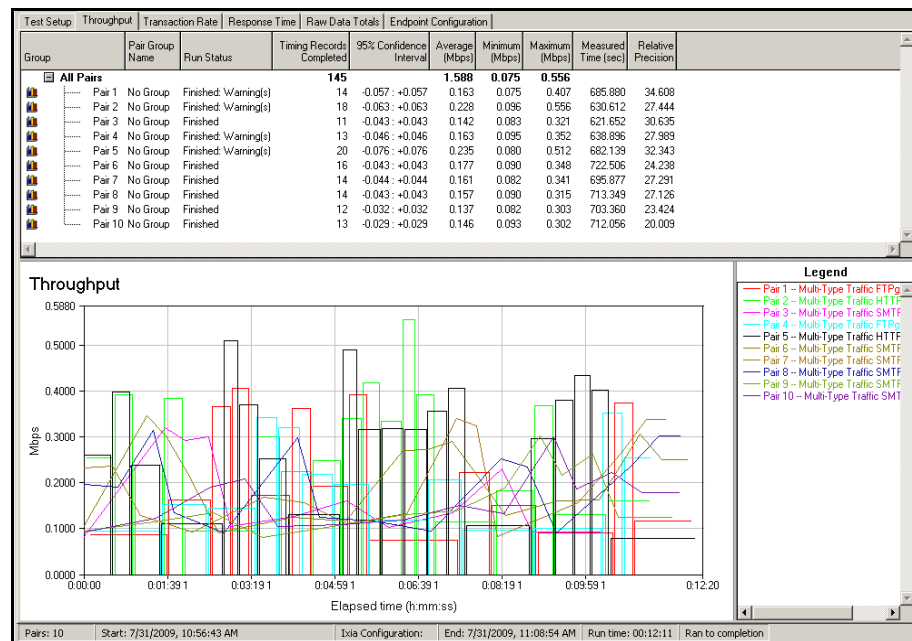


Figure 41. IxChariot GUI: Multi-user/Protocol/Direction, TurboIP

3. TurboIP-G2

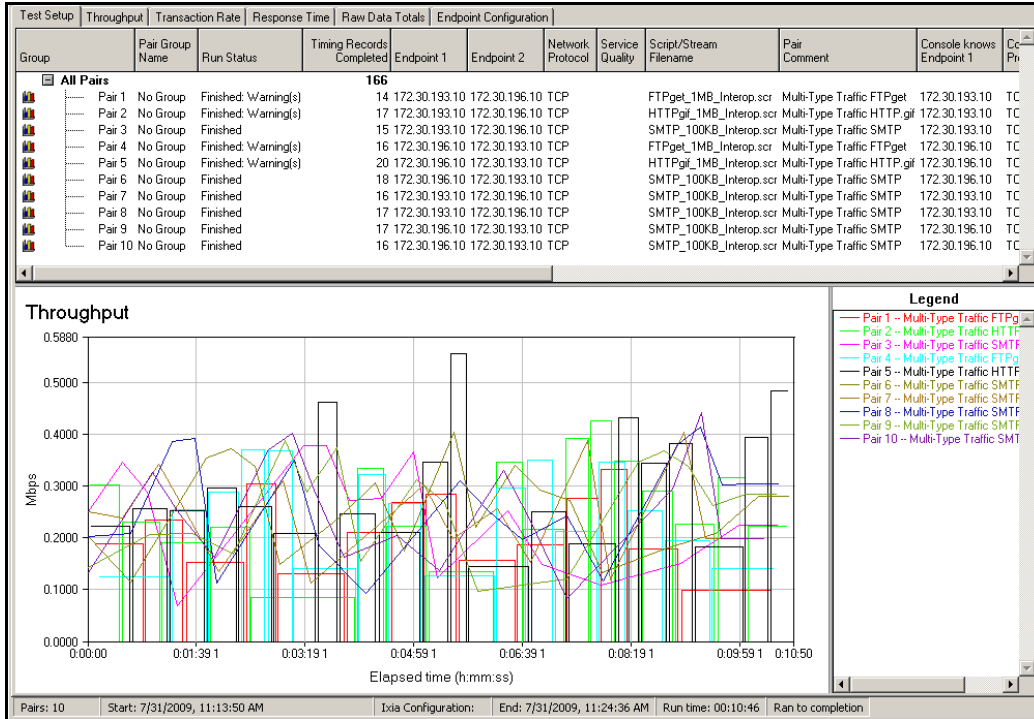


Figure 42. IxChariot GUI: Multi-user/Protocol/Direction, TurboIP-G2

4. Cisco-WAAS



Figure 43. IxChariot GUI: Multi-user/Protocol/Direction, Cisco-WAAS

5. Citrix-WANScaler

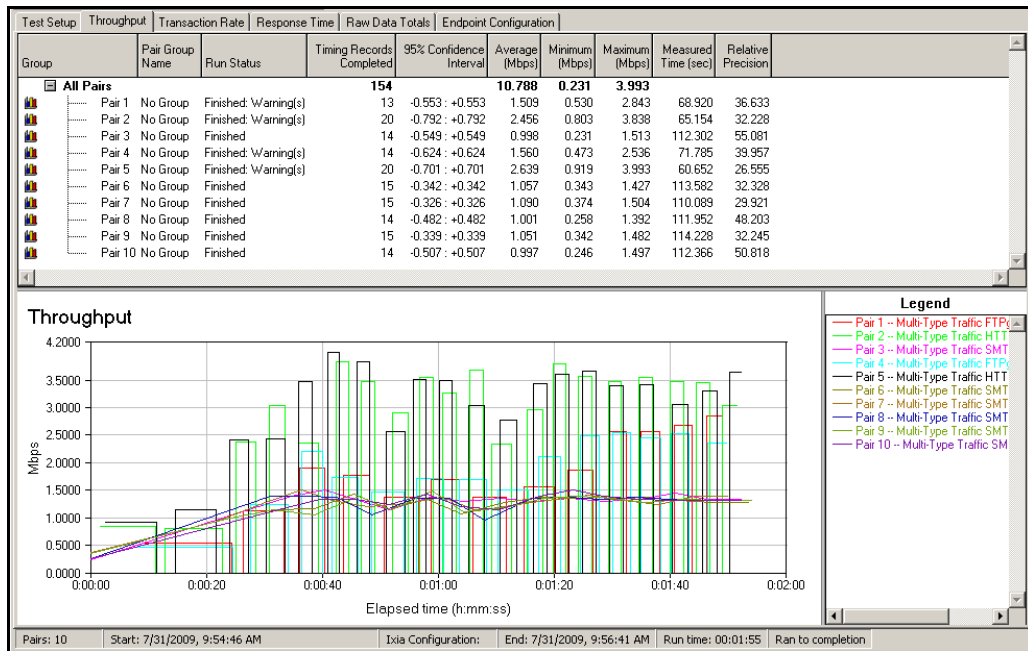


Figure 44. IxChariot GUI: Multi-user/Protocol/Direction, Citrix-WANScaler

6. Riverbed-Steelhead

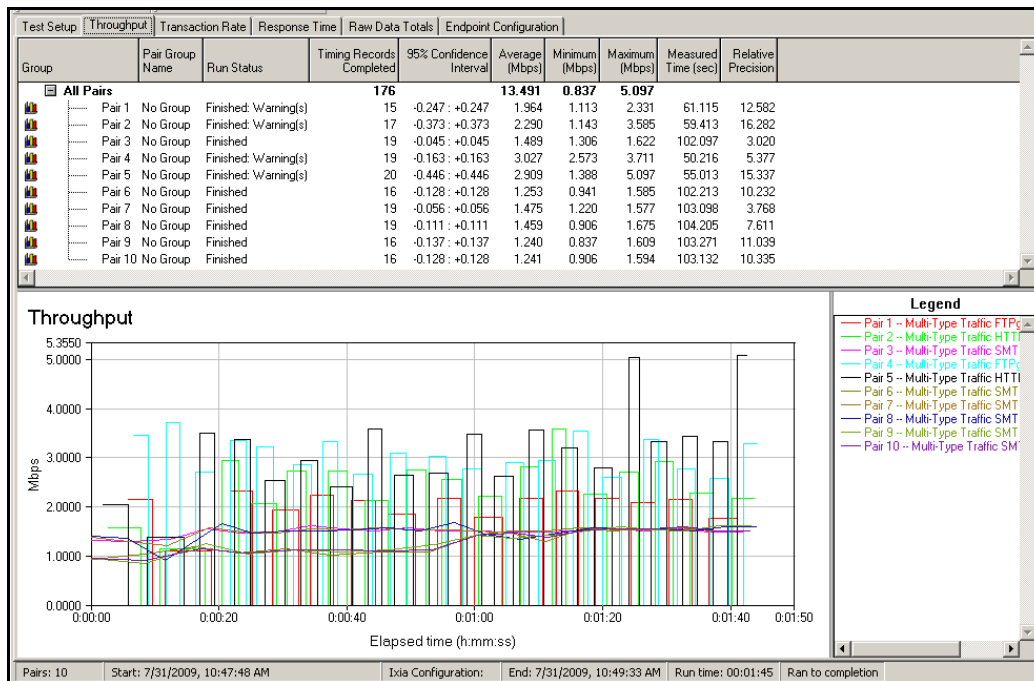


Figure 45. IxChariot GUI: Multi-user/Protocol/Direction, Riverbed-Steelhead

C. INTEROPERABILITY

1. TurboIP with TurboIP (reference)

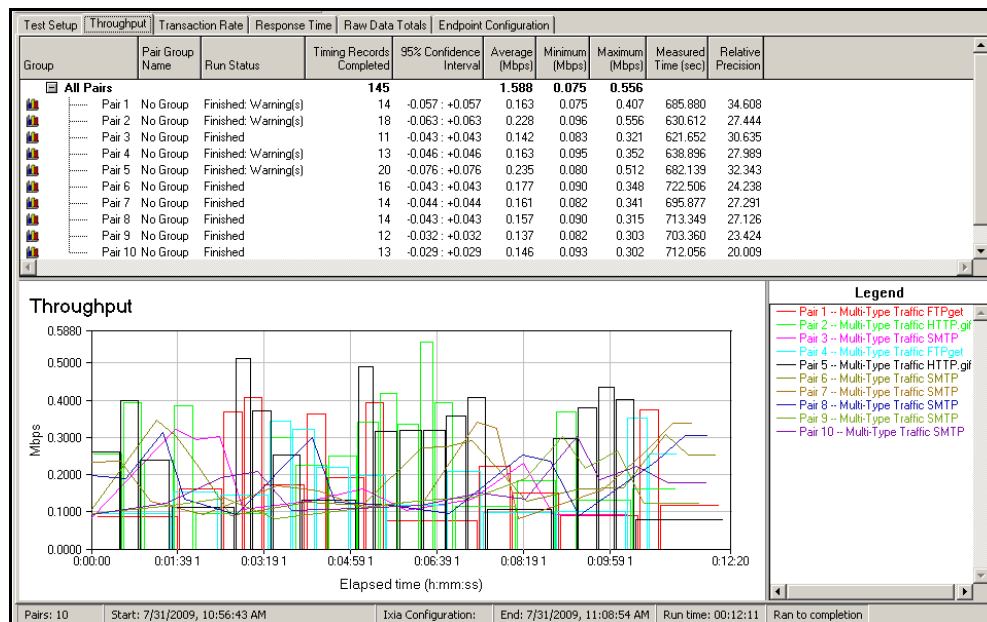


Figure 46. IxChariot GUI: Interoperability Test, TurboIP–TurboIP

2. TurboIP with TurboIP-G2

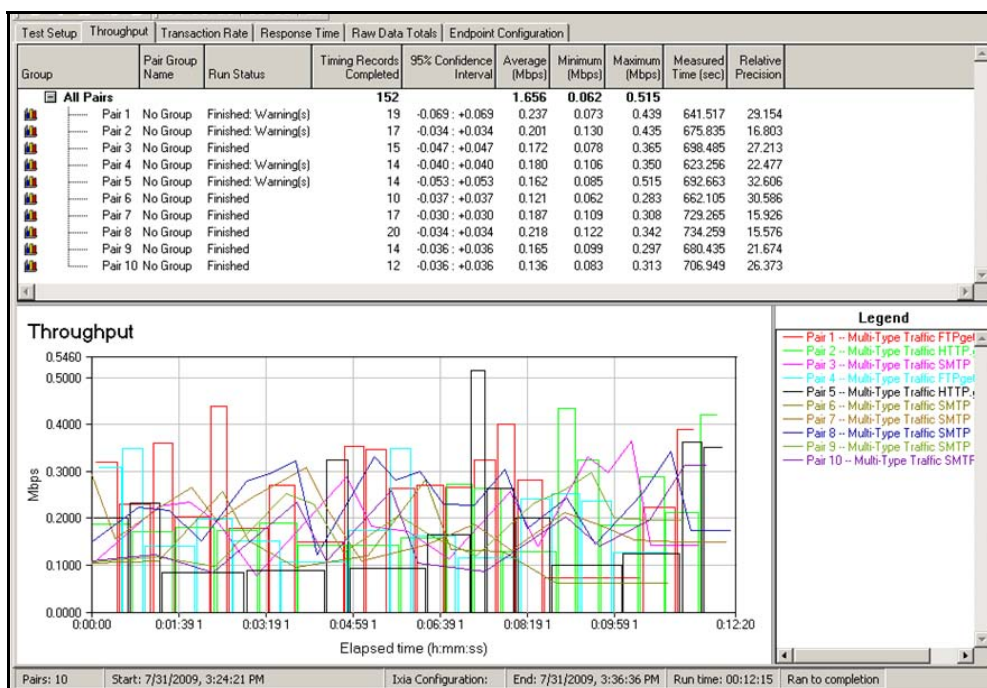


Figure 47. IxChariot GUI: Interoperability Test, TurboIP–TurboIP-G2

3. TurboIP with Cisco-WAAS

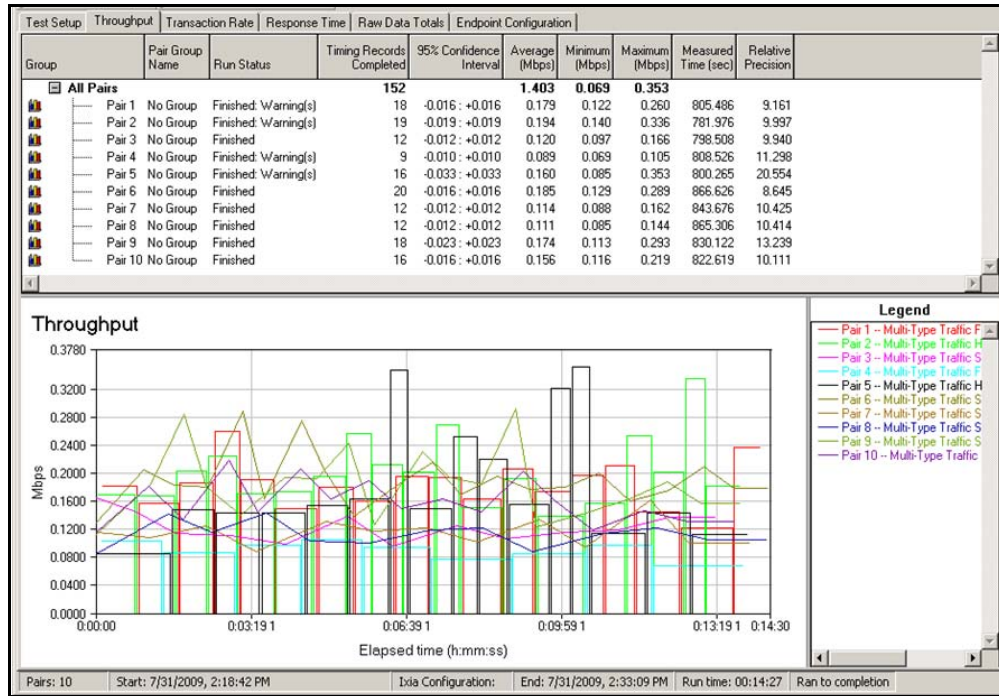


Figure 48. IxChariot GUI: Interoperability Test, TurboIP–Cisco

4. TurboIP with Citrix-WANScaler

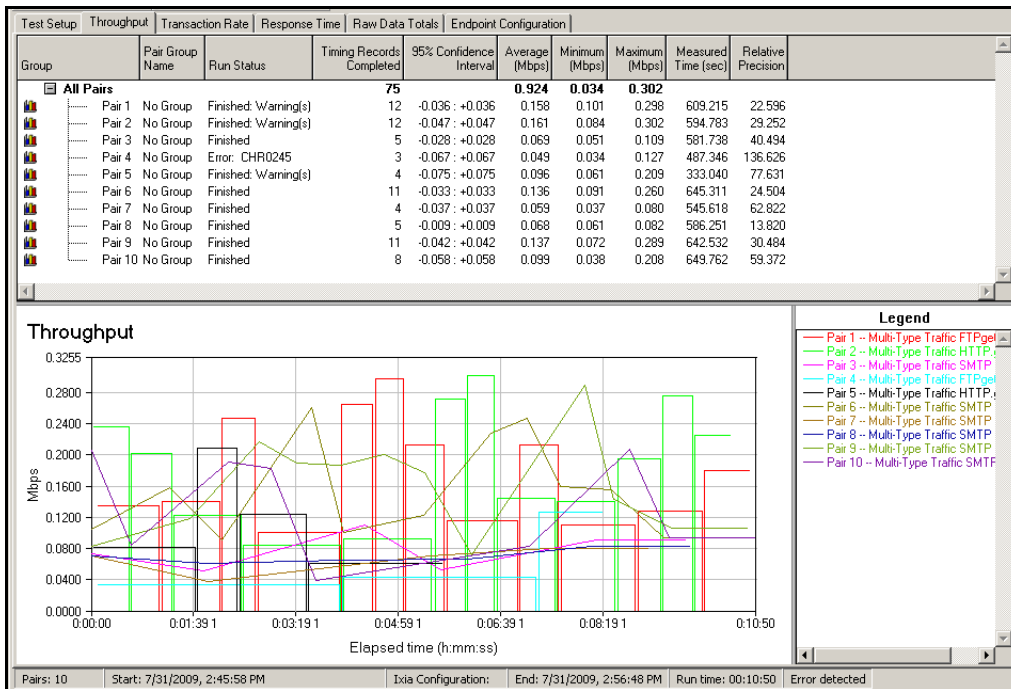


Figure 49. IxChariot GUI: Interoperability Test, TurboIP–Citrix

5. TurboIP with Riverbed–Steelhead

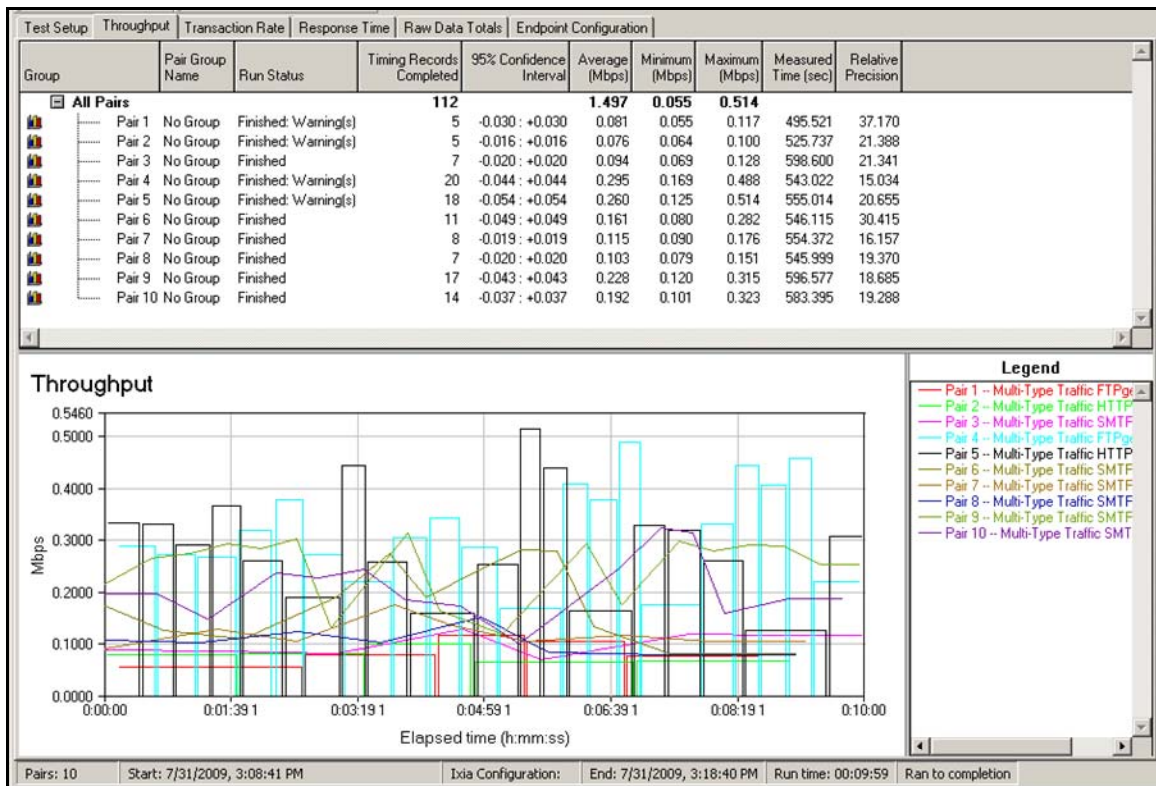


Figure 50. IxChariot GUI: Interoperability Test, TurboIP–Riverbed

D. WIRESHARK ANALYSIS

1. No Acceleration (Unaccelerated)

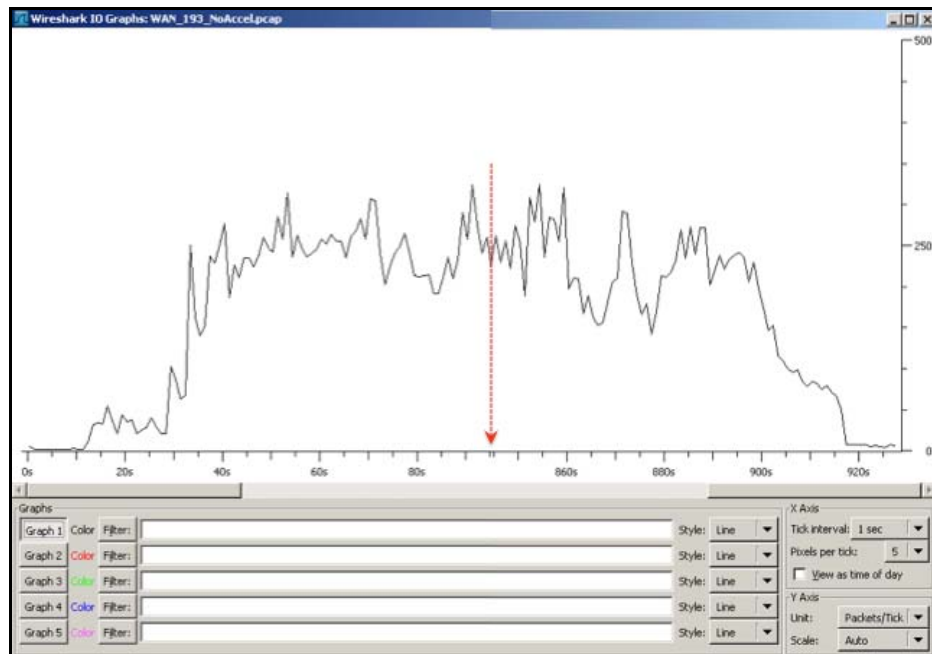


Figure 51. Wireshark: Multi-protocol Test, No Acceleration

2. TurboIP

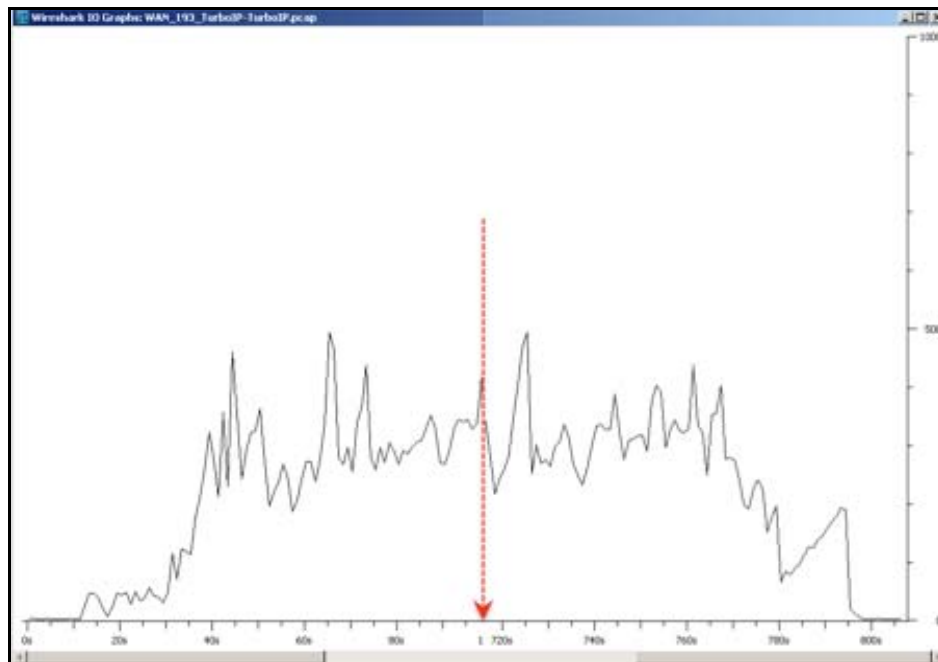


Figure 52. Wireshark: Multi-protocol Test, TurboIP

3. TurboIP-G2

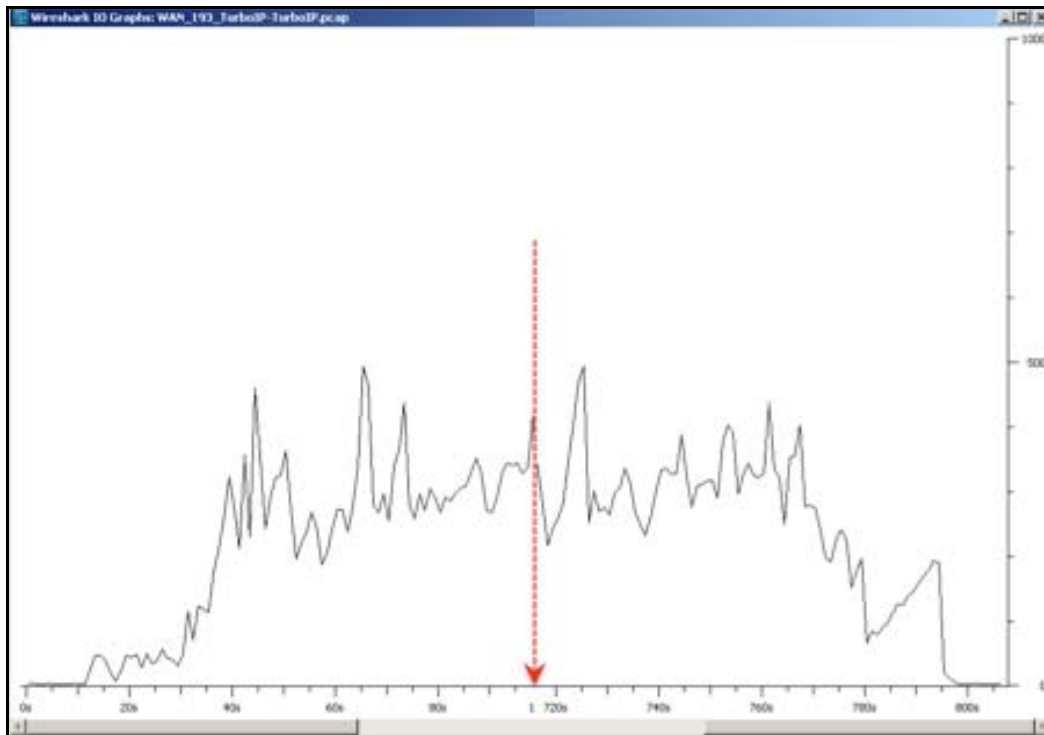


Figure 53. Wireshark: Multi-protocol Test, TurboIP-G2

4. Cisco-WAAS

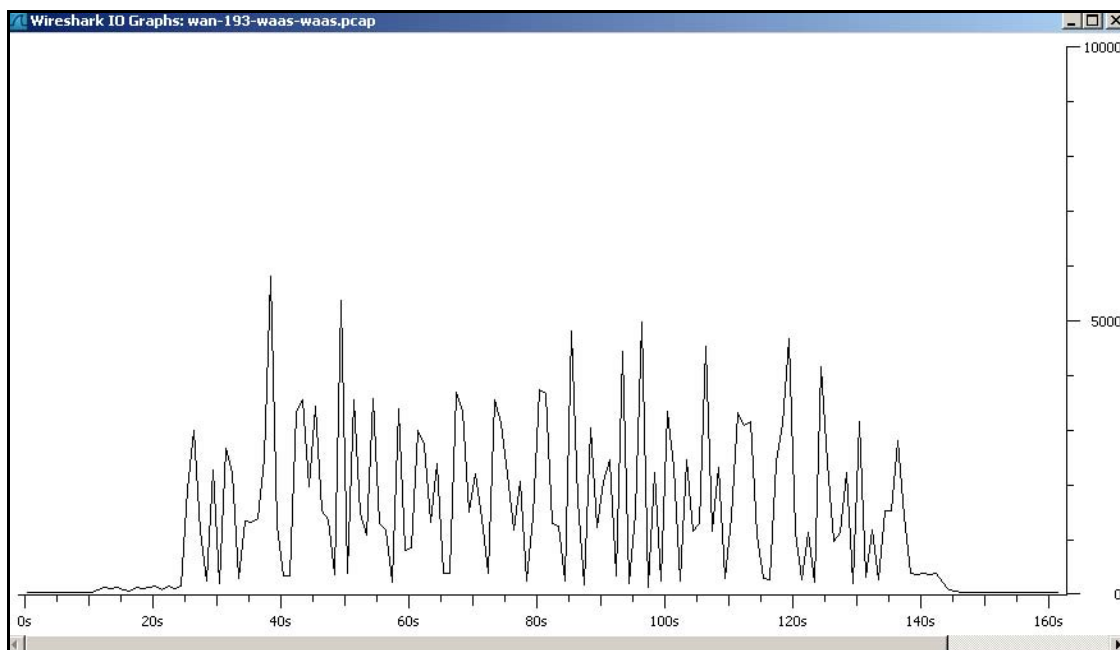


Figure 54. Wireshark: Multi-protocol Test, Cisco-WAAS

5. Citrix–WANScaler

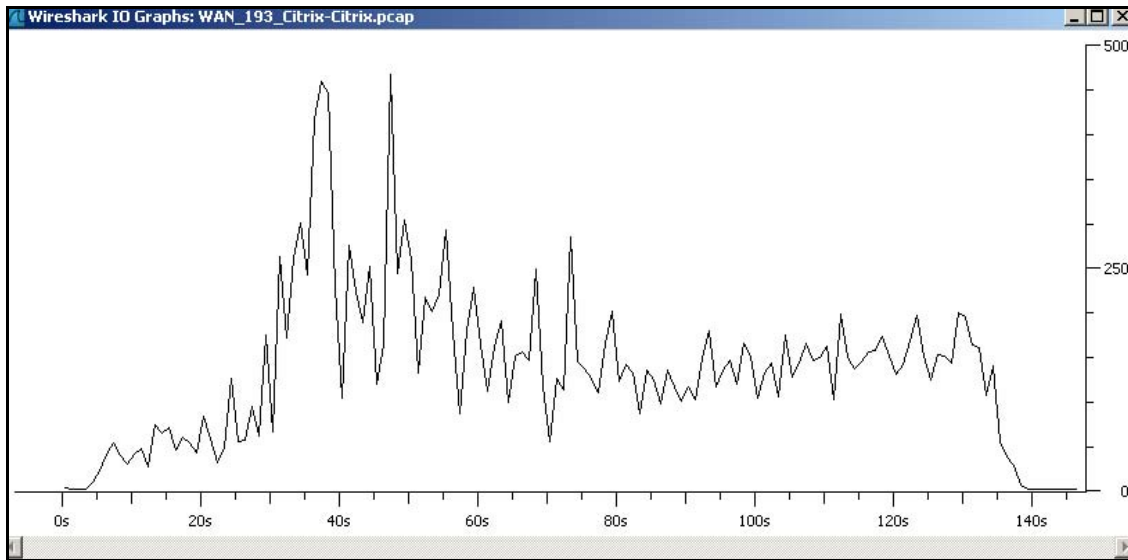


Figure 55. Wireshark: Multi-protocol Test, Citrix–WANScaler

6. Riverbed–Steelhead

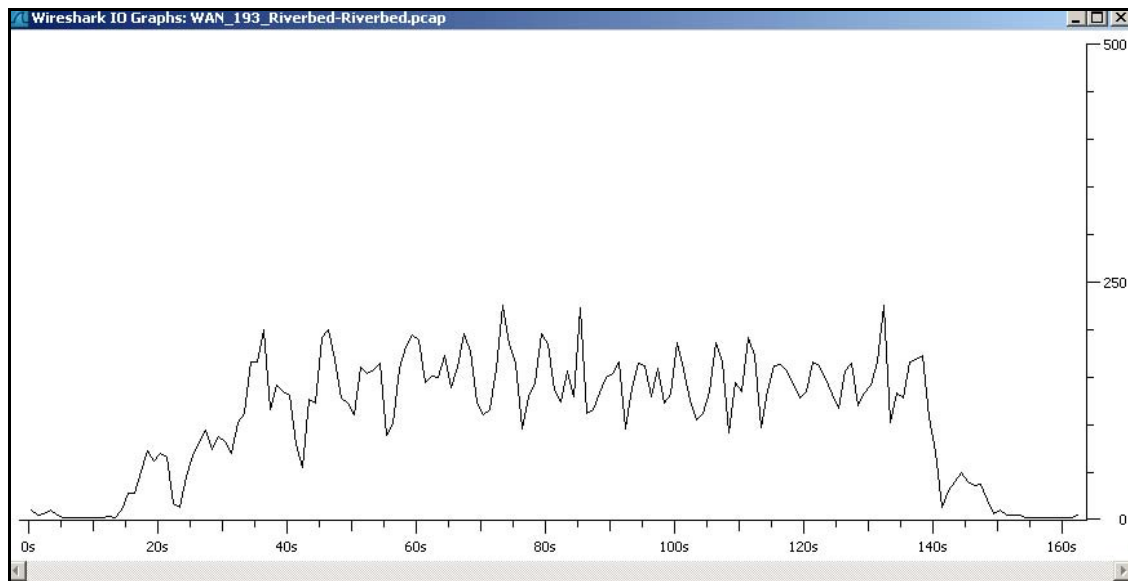


Figure 56. Wireshark: Multi-protocol Test, Riverbed–Steelhead

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