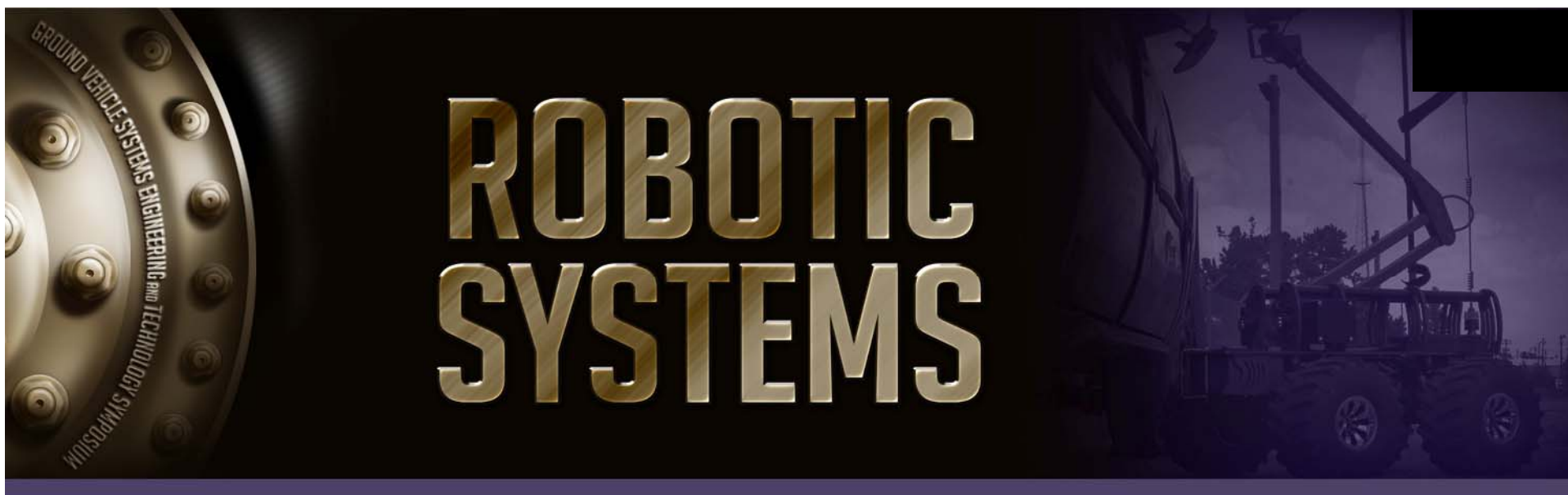




REMOTE MUNITIONS DEPLOYMENT FROM AN UNMANNED GROUND VEHICLE

Jeremy Gray

James Mason, Patrick Griffin, Charles Dean

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- High-risk missions often entail ground forces being required to manually emplace and deploy obstacle breaching munitions to generate a footpath through anti-personnel obstacles.
- A safer method for obstacle breaching is highly desired.
- Implementation of UGVs with live munitions has been demonstrated to mitigate risk by generating an increased stand-off distance while operating the system from a concealed position.
- This paper presents the research, development, and testing results of the integration of live munitions with UGV platforms.



UGV Mounted Deployment

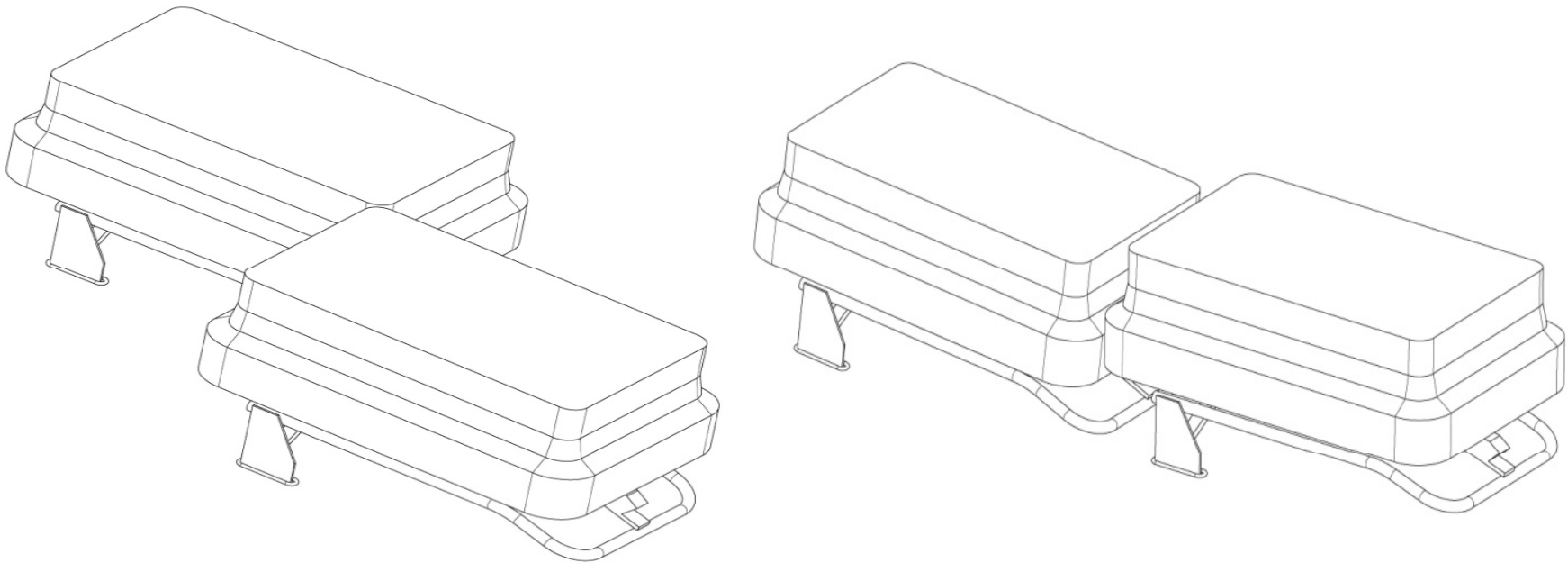
**ROBOTIC
SYSTEMS**

- Previous development and testing overview
 - Integration on mid-size UGV platform
 - Munitions mounted directly to platform payload deck
 - Did not develop integrated firing mechanism
 - Encompassed commercial off the shelf remote firing system
 - UGV not field ready, nor existing equivalent fielded
 - Unknown munitions configuration
 - Platform mobility was limited depending on configuration
 - Needed to test out munitions alignment configuration
 - Offset alignment per the training manual
 - In-line alignment for optimal UGV deployment

UGV Mounted Deployment – APOBS configuration

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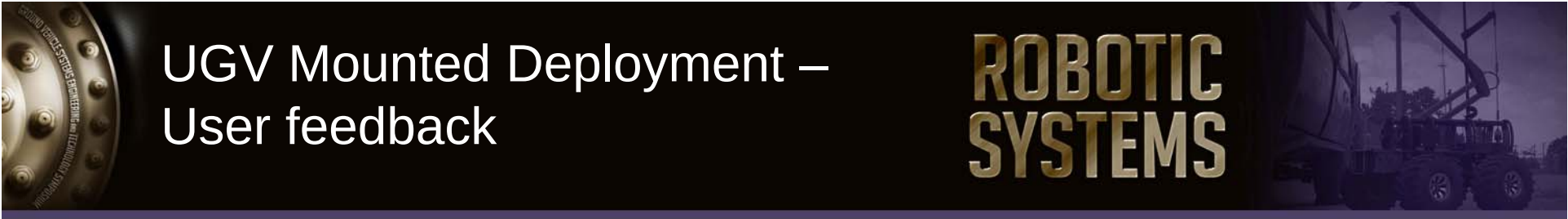
- Offset versus in-line configuration, both approaches were experimented with



UGV Mounted Deployment – Experimentation

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UGV Mounted Deployment – User feedback

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- Overall
 - Users indicated a UGV deployment system for APOBS effectively supports breaching missions.
 - Users indicated it is a great desire to have a system that has munitions deployment functionality.
- Mid-size UGV Platform
 - Difficult to transport a platform of its size
 - Pre-set poses for firing positions would be preferred
 - Attachment of munitions directly on UGV causes vibrations and bouncing, which may cause damage to munitions
- Firing system
 - Recommended integrated firing system and increased stand-off distance.
- Configuration
 - In-line configuration increased UGV mobility.
 - Users were concerned with difficulty and time required to load/attach munitions set



Trailer-Mounted Deployment

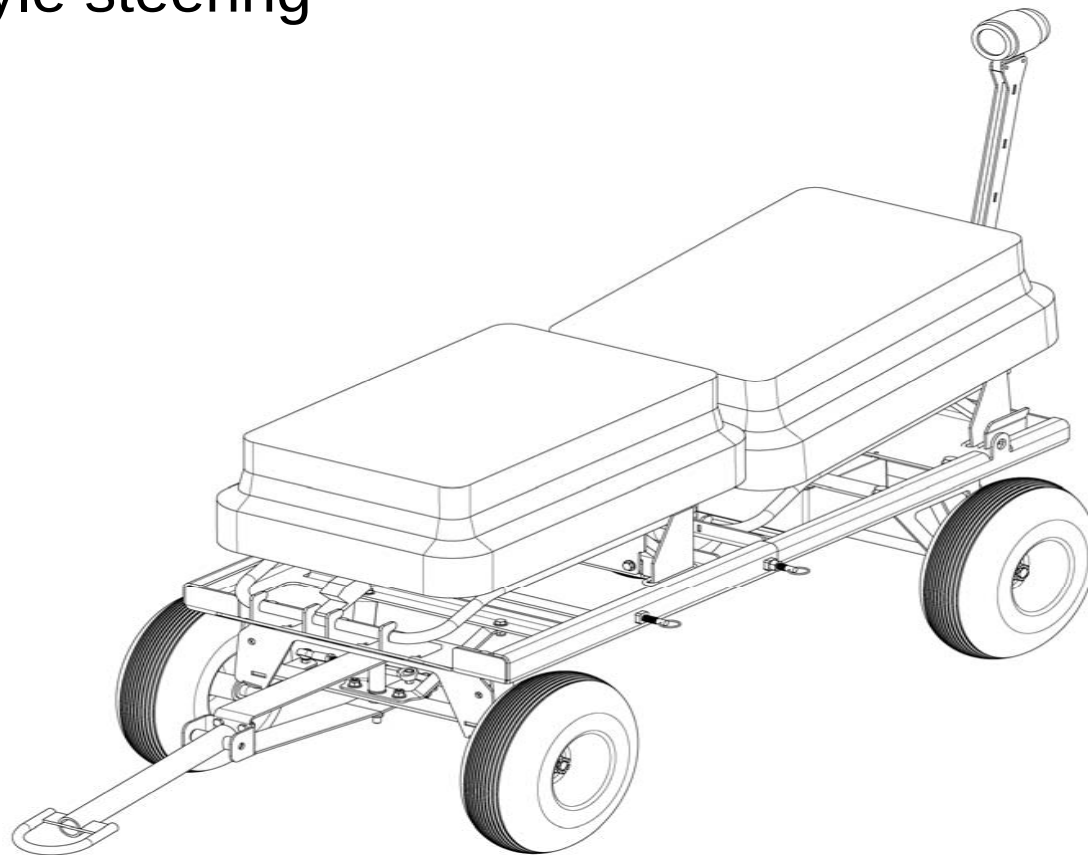
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- Key system features and improvements
 - Towability by small UGV
 - Quickly assembled munitions trailer
 - “Snap-in” munitions system
 - Rear target aiming camera
 - Inexpensive appliqué kit for current fielded systems
 - Break-away capability
 - Ability to reuse or stow trailer after breaching mission completion

Trailer-Mounted Deployment – Trailer Design

**ROBOTIC
SYSTEMS**

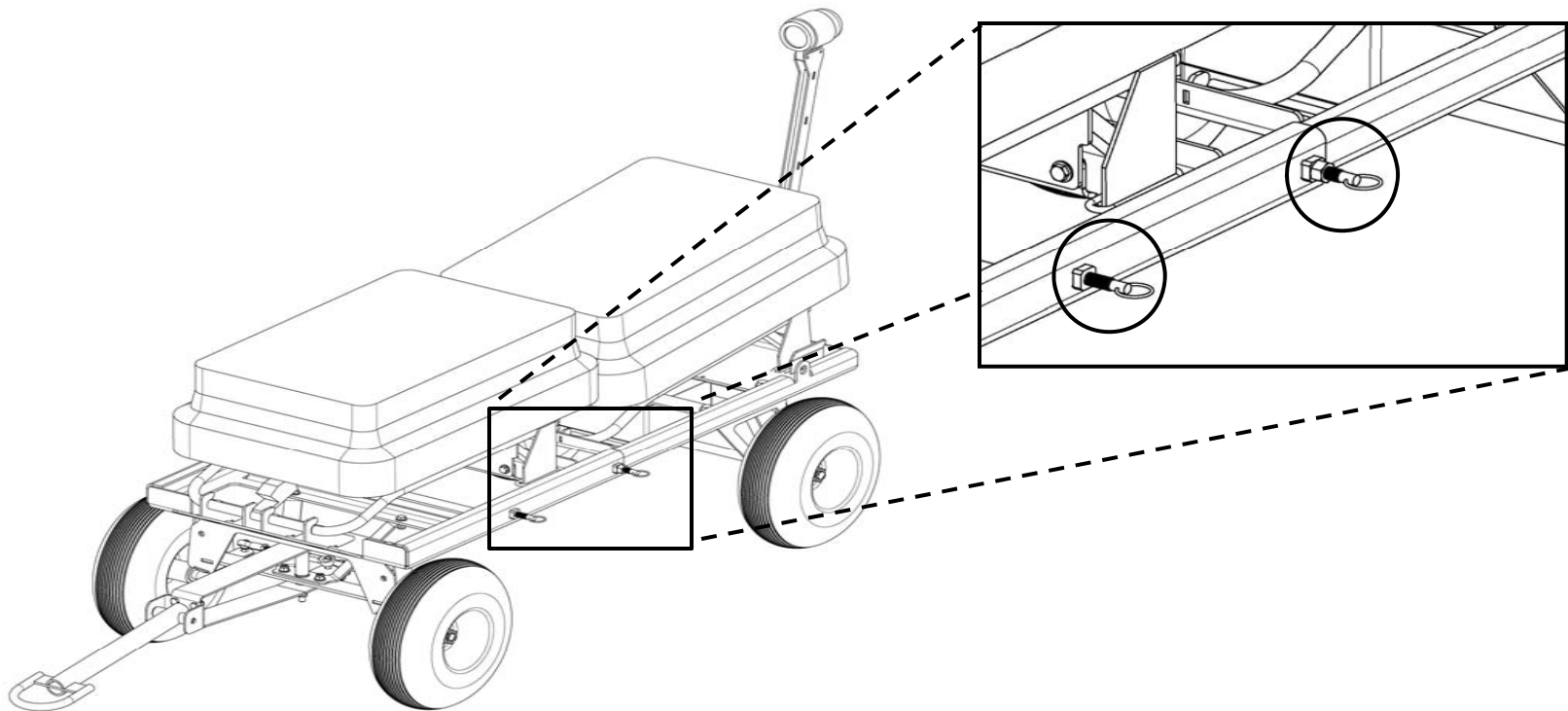
- Independent four wheel C-channel steel frame with Ackerman style steering



Trailer-Mounted Deployment – Trailer Design

ROBOTIC SYSTEMS

- Quick release pins for assembling trailer sections



Trailer-Mounted Deployment – Trailer Design

ROBOTIC SYSTEMS

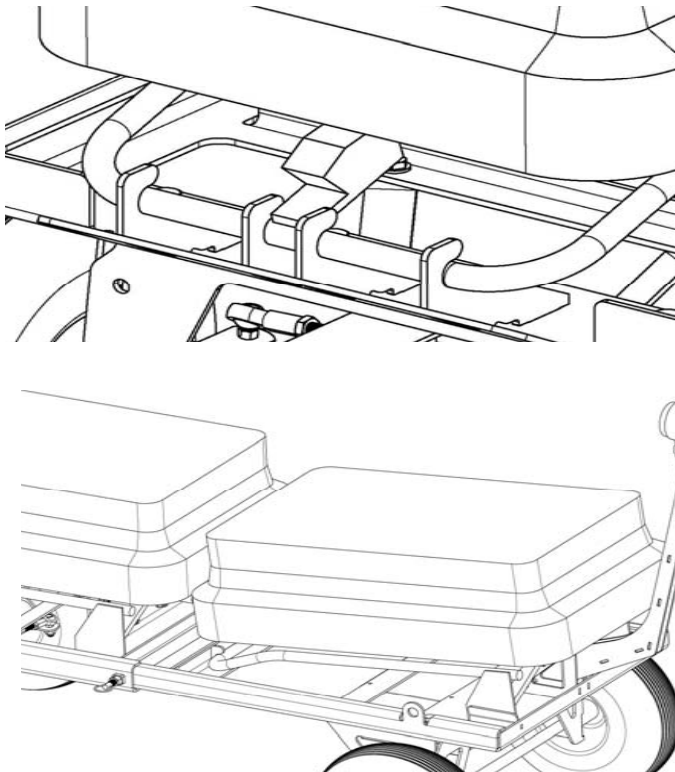
- Storage/Shipping
 - Designed to be collapsed to fit in existing fielded small UGV shipping container



Trailer-Mounted Deployment – “Snap-in” Munitions

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- Utilizing “in-line” configuration, ALICE packs are located into place by toe lugs and locked into place.



Munitions are located by toe lugs

Front – spring loaded latch/release mechanism

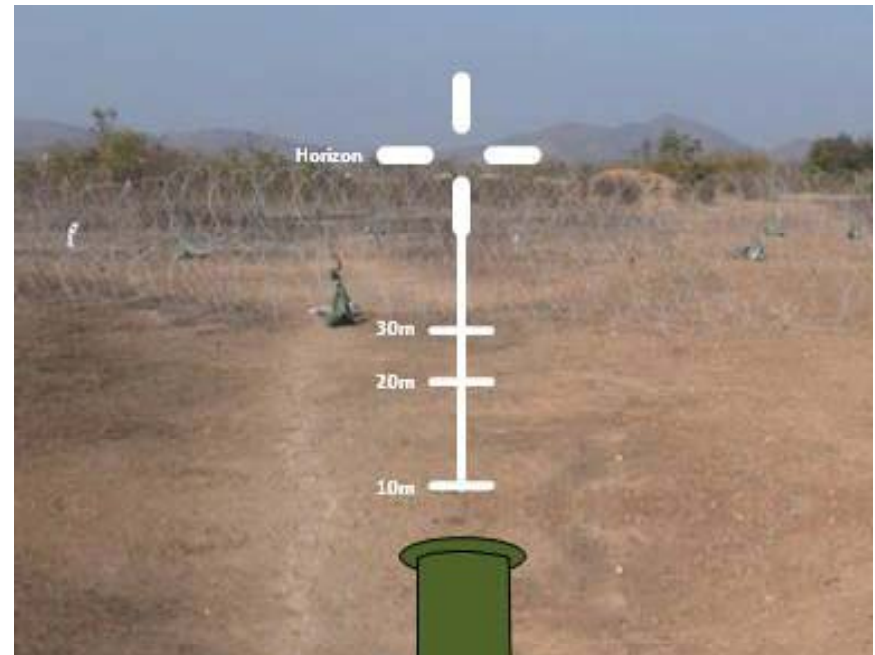
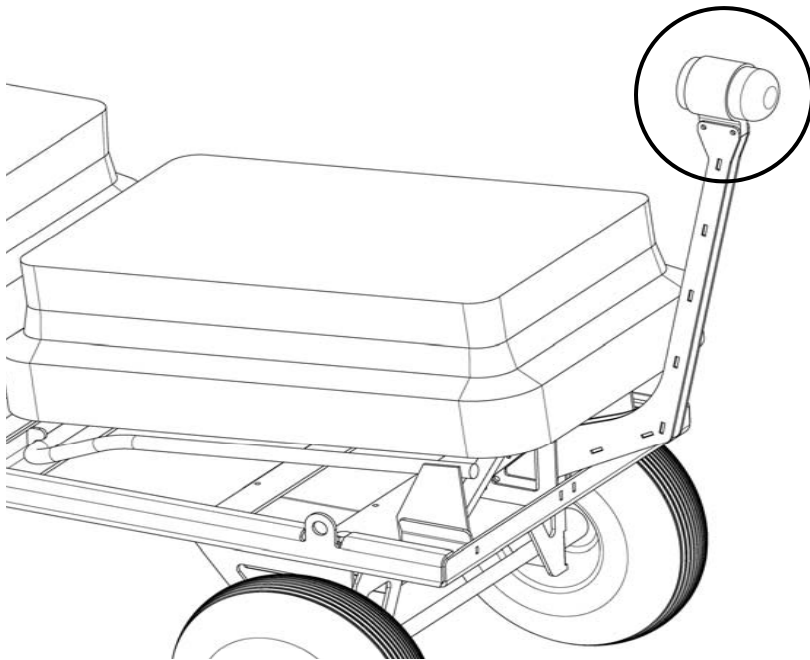
Rear – wedged into place by flange at the back trailer deck



Trailer-Mounted Deployment – Rear Target Aiming Camera

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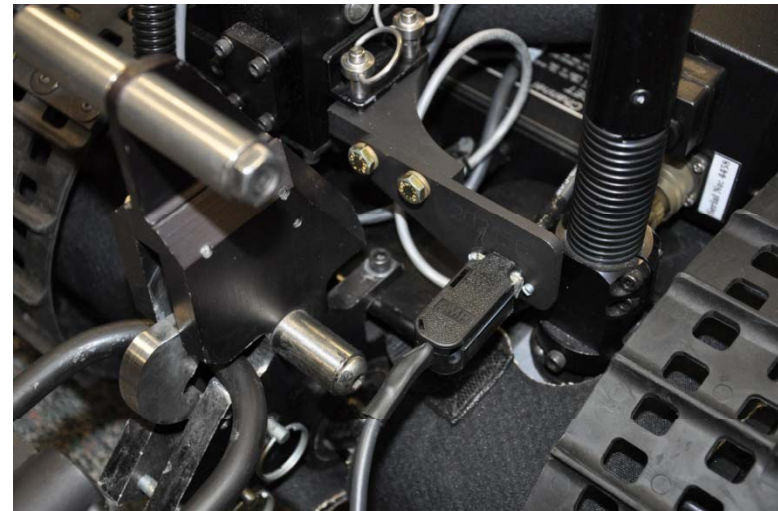
- Forward-facing camera to facilitate aiming, range estimation, and local situational awareness with image overlay.



Trailer-Mounted Deployment – Appliqué & Break-Away Capability

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- Appliqué kit for small unmanned ground vehicles
 - “Plug-in-play” design for fielded systems.
 - Rear camera relocation, installation of trailer hitch and USTI kit.
 - Does not require platform or software modifications.
 - Only requires integrated OCU fire control and fire set box on platform
- Break-away capability from munitions



Trailer-Mounted Deployment – Completed System

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Thank You

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SYSTEMS**

Future work

Questions?