

# MIO Cortex: Memory Mechanisms for Operator-Expert Networked Decision Support



Dr. Alex Bordetsky, Professor  
Steven Mullins, PhD student  
19 Jun 2013

## Report Documentation Page

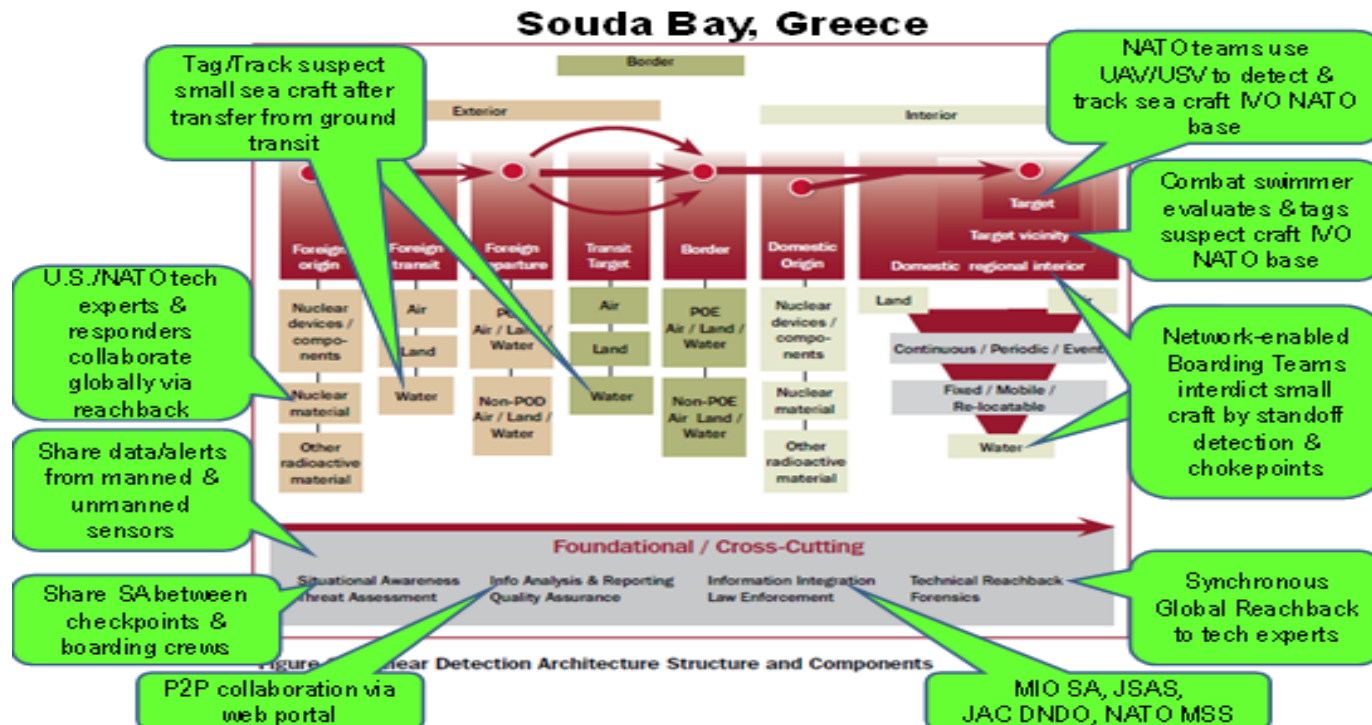
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# CENETIX - Background

- **Who:** Since 2010, researchers led by the U.S. Naval Postgraduate School has conducted a series of experiments at the Center for NETwork Innovation and eXperimentation
- **Objective:** specifically address the threats to the U.S. and NATO installation overseas.
- **Purpose:** examine NWDSS means to detect and interdict nuclear and radiological materials.
- **Where:** portions of the Baltic and the Mediterranean Seas.
- **Results:** operational models which contribute (green inserts) to development of the GNDA\*



# TMS as Network - Characteristics

## Processes

1. Directory Updating
  - Knowing who knows who in a group
2. Information Allocation
  - Assigning memory items to specific group members
3. Retrieval Coordination
  - Accessing or retrieving knowledge by leveraging who knows what

## As a Knowledge Mesh Network

- Knowledge Distribution (implicit/explicit)
- Knowledge Links (strong/weak)
- Knowledge Flow/Transfer
- SME Reachback

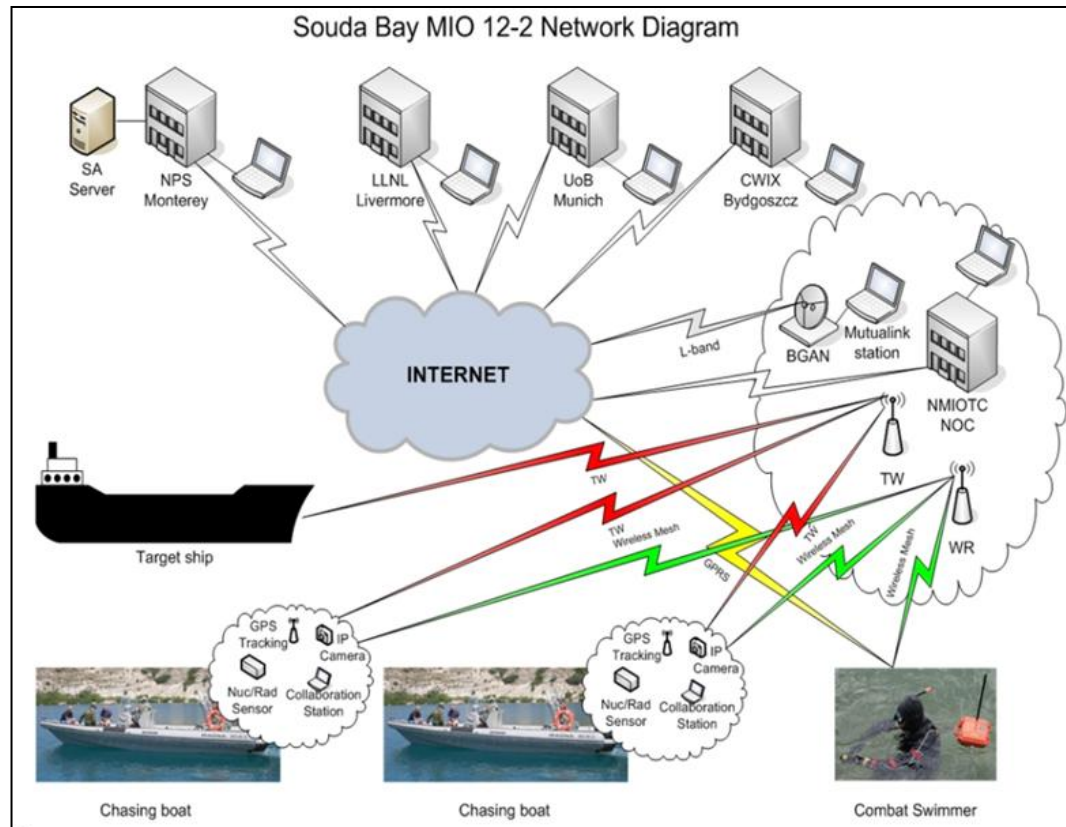
# Campaign of Experimentation - MIO

We are examining:

- Phenomenon and functionality of a *memory system* capable of supporting collective expert networks
- *Networked decision support* in the context of a maritime interdiction operation (MIO). Two dimensions of knowledge in such networked DSS:
  - *social or organizational memory* as exemplified by reach back to subject matter experts
  - *software encoded knowledge bases* distributed across a MIO services network.
- A *transactive memory system (TMS)* as a mechanism unifying network knowledge formation, generation, flow/sharing, retrieval, use; a knowledge network that –
  - *forms and evolves* through the process of discovery and
  - forms *strong/weak ties* between info sensors and expert nodes, producing shared analyses.
- *Clustering* in social networking between mobile operators and reachback experts
- And describe the potential architecture of a *human-machine “cortex”* using a MIO-related social network.

# Some Characteristics of Operator-Expert Knowledge Network Nodes

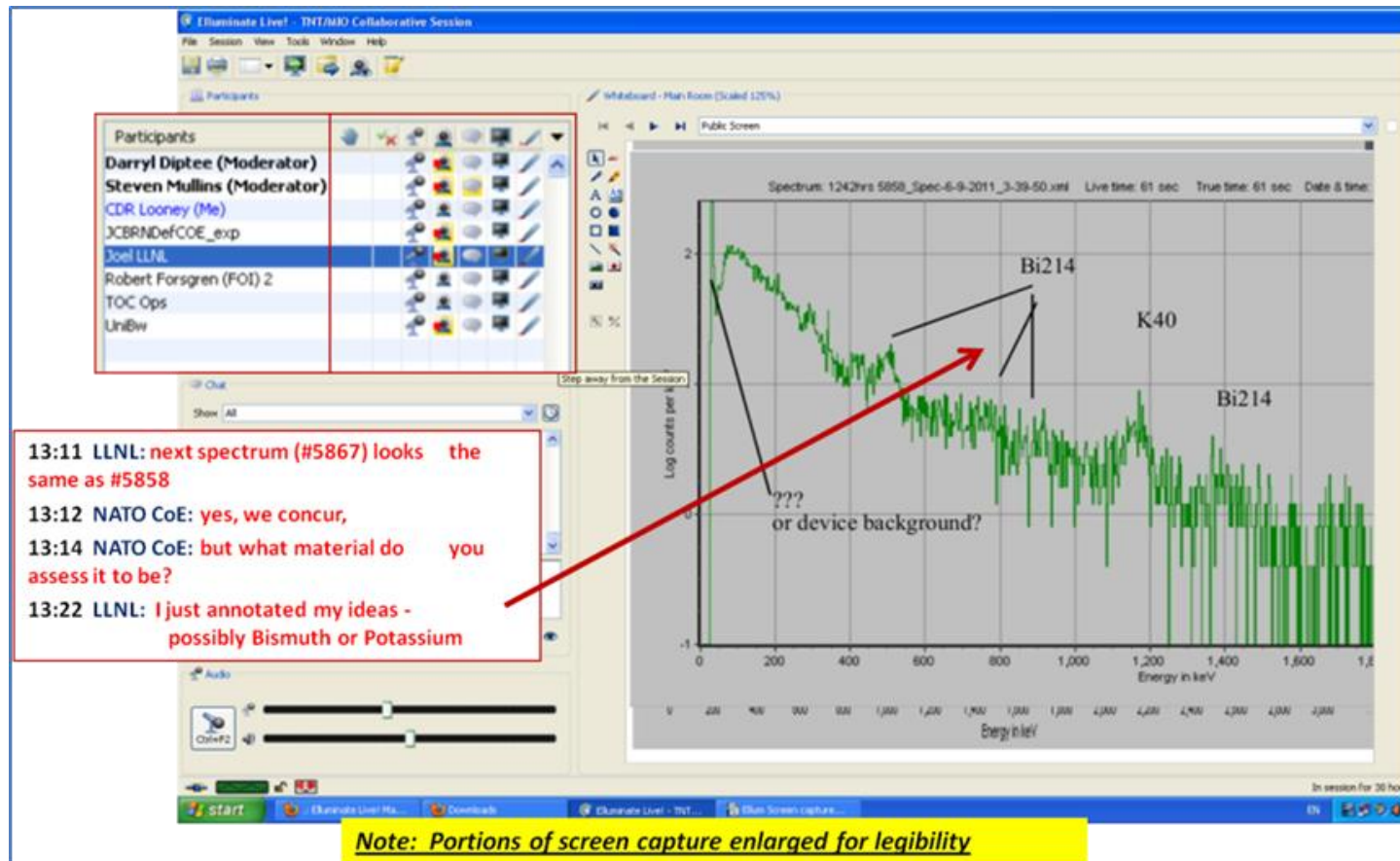
- Transient Membership
- Heterogeneity
- Homophily\*
- Memory



\* Hawkins, J. and Blakeslee, S. (2004) *On Intelligence*. St. Martin's Griffin, NY.

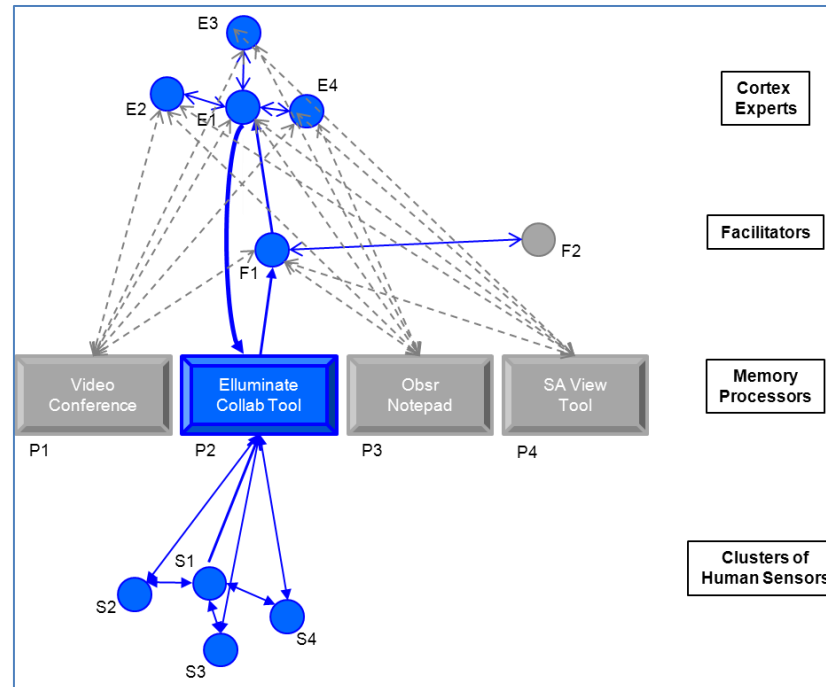
# Cortex Model of MIO Transactive Memory: centered on a Whiteboard

There is a correspondence between a human sensor-to-processor-to-cortex\* and a network as identified through observations in experiments



\*Rodriguez, M. (2004) The hyper-cortex of human collective intelligence systems 6

# MIO Cortex as a Whiteboard-centered Network

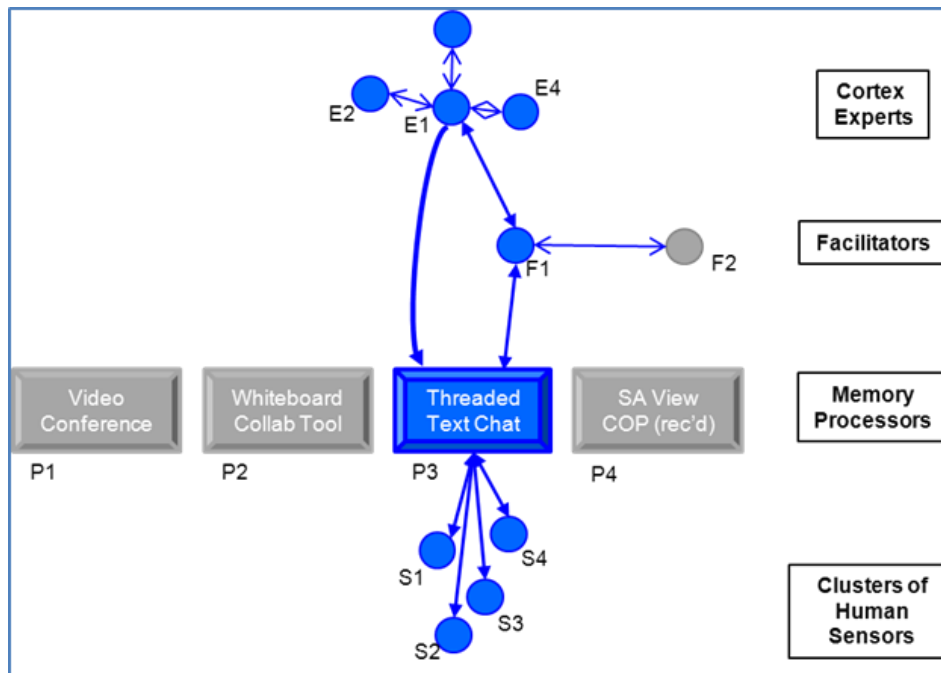


Nodes	Name	Description	Linkages
E1-E4	Cortex Experts	Members of a cluster of Subject Matter Experts	bidirectional
F1-F2	Facilitators	Stewards, connectors	-
P1-P4	Processors	The four primary MIO experimentation tools: <ul style="list-style-type: none"> <li>• Video Conference – Video Conferencing Tool</li> <li>• Elluminate – White Board &amp; Audio Chat Tool</li> <li>• Observer Notepad – Threaded Text Chat Tool</li> <li>• SA COP – Common Operational Picture Tool</li> </ul>	directed
S1-S4	Sensors	Human Sensors (possibly aided by unattended sensors)	-

# MIO Cortex: centered on threaded Text Chat

6/12/2012 1:40:11 AM	<b>Blue Boat:</b> We have detected target boat suspect material at 20-25 meters on the starboard side and we are increasing distance.	 <a href="#">Replace</a> <a href="#">Delete</a>		} Bursts
6/12/2012 1:40:07 AM	<b>MOC OPS:</b> Roger, blue boat. Continue detection attempts. Standing by for your update.	 		
6/12/2012 1:37:03 AM	<b>Blue Boat:</b> We are in the wake of the target vessel at a distance of 20-25 meters, we have no detection, we will proceed at the starboard side of the target vessel.	 		
6/12/2012 1:36:25 AM	<b>MOC OPS:</b> JCBRN: Stand by for file for your analysis.	 		
6/12/2012 1:35:53 AM	<b>MOC OPS:</b> Blue boat: We can see you in VC1. Please commence detection.	 		
6/12/2012 2:07:36 AM	<b>MOC OPS:</b> Passenger ship in AOR.	 <a href="#">Replace</a> <a href="#">Delete</a>		} Bursts
6/12/2012 2:07:35 AM	<b>JCBRNDCOE(Obs):</b> to MOC/Blue Boat: What is the difference between detection #1 and detection #2? Please be as specific as possible.	 		
6/12/2012 2:04:24 AM	<b>JCBRNDCOE(Obs):</b> Blue Boat: We confirm Attached detection #1.	 		
6/12/2012 2:01:48 AM	<b>Blue Boat:</b> Detection #2	 <a href="#">Replace</a> <a href="#">Delete</a>		
6/12/2012 2:00:47 AM	<b>MOC OPS:</b> JCBRN: Detection file is now uploaded at Blue Boat's post from 1:50:11 hours.	 		
6/14/2012 1:24:29 AM	<b>LLNL Sensor update.</b> File <i>Spec-6-14-2012_4-33-41.xml</i> is attached.	 <a href="#">Replace</a> <a href="#">Delete</a>		} Bursts
6/14/2012 1:24:26 AM	<b>LLNL Sensor update.</b> File <i>Spec-6-14-2012_4-28-24.xml</i> is attached.	 <a href="#">Replace</a> <a href="#">Delete</a>		
6/14/2012 1:24:26 AM	<b>LLNL Sensor update.</b> File <i>Spec-6-14-2012_4-27-32.xml</i> is attached.	 <a href="#">Replace</a> <a href="#">Delete</a>		
6/14/2012 1:24:20 AM	<b>LLNL Sensor update.</b> File <i>Spec-6-14-2012_4-26-56.xml</i> is attached.	 <a href="#">Replace</a> <a href="#">Delete</a>		
6/14/2012 1:24:20 AM	<b>LLNL Sensor update.</b> File is attached.	 <a href="#">Replace</a> <a href="#">Delete</a>		
6/14/2012 1:22:35 AM	<b>MOC OPS:</b> Boat video visible in VC1.	 		
6/14/2012 1:14:38 AM	<b>MOC OPS:</b> Vessels underway.	 		

# MIO Cortex as a Text Chat-centered Network

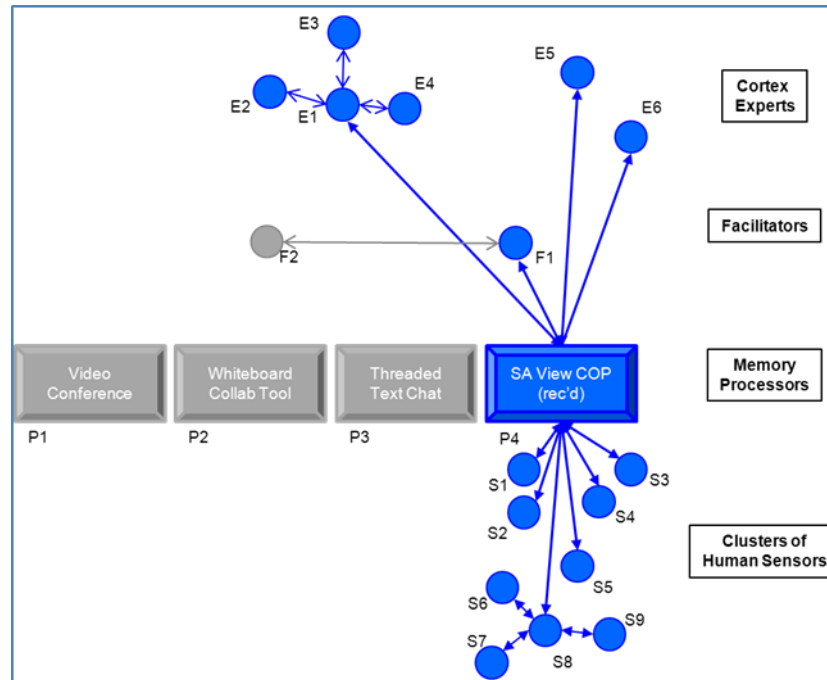


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S1-S4	Sensors	Human Sensors (possibly aided by unattended sensors)	-

# MIO Cortex actions: centered on a SA View tool



# MIO Cortex as a SA view sharing Network



Nodes	Name	Description	Linkages
E1-E4	Cortex Experts	Members of a cluster of Subject Matter Experts	bidirectional
F1-F2	Facilitators	Stewards, connectors	-
P1-P4	Processors	The four primary MIO experimentation tools: <ul style="list-style-type: none"> <li>• Video Conference – Video Conferencing Tool</li> <li>• Elluminate – White Board &amp; Audio Chat Tool</li> <li>• Observer Notepad – Threaded Text Chat Tool</li> <li>• SA COP – Common Operational Picture Tool</li> </ul>	directed
S1-S4	Sensors	Human Sensors (possibly aided by unattended sensors)	-

# Discussion

- The noticeable differences in cortex topology illustrate that the type of the *memory processor* used (i.e. the collaboration platform) defines a very different network as a cortex model of TM.
- The threaded text chat centered part of cortex sometimes keeps experts at *two degrees of separation* from the sensor nodes.
  - These links are frequently lengthened by Facilitator intervention.
- *Clustering effect* is very strong in the White Board centered part of the cortex.
  - It is noticeably defined by the changing mesh of weak and strong ties.
- These differences highlight the interesting *dynamics in MIO cortex behavior*.
  - By switching between different memory processors, i.e. collaborative platforms, we move from one knowledge flow topology to another with different combinations of strong and weak ties usage as well as facilitator roles.

# Conclusion

- We describe the emergence of Transactive Memory structures for a collective network of experts and operators (sensors), based upon observations of ongoing MIO detection and interdiction experiments.
- We consider the memory mechanism supporting a MIO networked DSS environment, as a network parallel to a human cortex. The MIO cortex reveals itself through observation of its expert nodes.
- In the environment of a MIO experiment, different collaborative tools play the role of memory processors.
- These observations make subsequent experimental studies of MIO Cortex bursts and clustering interesting and challenging.