

High - Torque Quiet Gear

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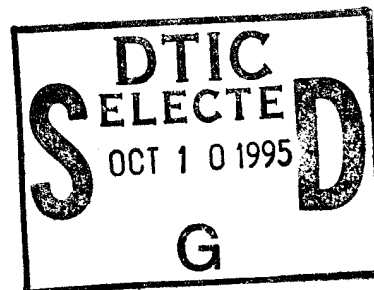
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3 HIGH-TORQUE QUIET GEAR

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5 STATEMENT OF GOVERNMENT INTEREST

6 The invention described herein may be manufactured and used
7 by or for the Government of the United States of America for
8 governmental purposes without payment of any royalties thereon or
9 therefor.

10
11 BACKGROUND OF THE INVENTION

12 (1) Field of the Invention

13 The instant invention relates to gear train systems, and
14 more particularly to a high-torque quiet gear for quieting gear
15 train noise over a wide range of applications.

16 (2) Description of the Prior Art

17 Existing gear trains produce harmonic vibrations which
18 results from the meshing and releasing of gears as they rotate.
19 This vibration frequently produces structural and airborne noise
20 levels which are unacceptable.

21 Gear noise is presently controlled by designing a gear train
22 system which minimizes the backlash between meshing teeth of a
23 gear train. In addition, various gear teeth configurations have
24 been developed to ensure that more than one tooth is engaged at
25 all times. Close tolerance machining of parts, closely
26 controlling the center to center location of meshing gears,

1 selecting proper materials, controlling system speed of
2 operation, insuring proper system lubrication, limiting piece
3 part loads and isolation of the entire system can also be used to
4 quiet a system.

5 Another known method of reducing gear backlash is the
6 provision of elastomeric members inserted between the drive shaft
7 and the gear to reduce the transmission of vibration and noise
8 from the drive shaft to the gear or vice-versa. In this regard,
9 the U.S. Patent to Knapp et al., No. 4,269,262 is representative
10 of the state of the prior art. The patent to Knapp et al.
11 discloses a gear structure comprising a cylindrical core, an
12 annular ring gear and an elastomeric cushion positioned between
13 the core and the ring gear. Inwardly and outwardly radially
14 projecting portions of the elastomeric cushion are respectively
15 bonded, usually with an adhesive, to the exterior surface of the
16 core and the interior surface of the ring gear.

17 In general, these types of gear configurations have been
18 found to reduce vibration and noise transmitted from the drive
19 shaft to the gear. However, the gear configurations have a
20 distinct disadvantage in that the bonded area of the elastomer is
21 subjected to high shear forces when torque is transmitted through
22 the system. It has been found that upon repeated use, the bonded
23 surface is highly susceptible to failure, and is the weak link in
24 a multiple piece gear system.

1 therefrom, and an outer ring member having a plurality of
2 circumferentially spaced teeth extending radially inwardly
3 therefrom, and further having a plurality of gear formations on
4 the outer surface thereof. The inwardly radiating teeth of the
5 ring member are received in spaced relation in corresponding
6 spaces formed between adjacent arms of the hub. An elastomeric
7 member is received in and fills the space formed between the
8 inner hub and the outer ring member to form a resilient
9 connection between the arms of the hub and the teeth of the ring
10 member. The side surfaces of the arms and the teeth extend
11 generally parallel to each other and at least partially overlap
12 in a longitudinal direction. The purpose of this configuration
13 is to place the elastomeric member in compression when torque is
14 applied to the hub. Since elastomeric material is relatively
15 incompressible, the result is low shear loads on the adhesive
16 bonds which hold the elastomeric member to both the inner hub and
17 outer ring member.

18 Other objects, features and advantages of the invention
19 shall become apparent as the description thereof proceeds when
20 considered in connection with the accompanying illustrative
21 drawings.

1 preferably rectangular in configuration and have opposing side
2 surfaces 24.

3 The ring member 14 includes a plurality of circumferentially
4 spaced teeth 26 which extend radially inwardly therefrom, and
5 further includes a plurality of outwardly extending gear
6 formations 28 for intermeshing with other gears (not shown). The
7 instant illustrations specifically show a spur gear
8 configuration; however, it is to be understood that the concept
9 is applicable to any gear tooth configuration. The ring member
10 14 and hub 12 are received in assembled relation wherein the
11 teeth 26 of the ring member 14 are received in closely spaced
12 relation in corresponding spaces formed between the arms 22 of
13 the hub 12. In this connection, it is noted that the teeth 26
14 are formed with an outwardly tapered configuration so that the
15 side surfaces 30 of the teeth are positioned in generally
16 parallel relation to the side surfaces 24 of the arms 22. It is
17 further pointed out that the teeth 26 and arms 22 at least
18 partially overlap, or intermesh, in the longitudinal direction.

19 The elastomeric member 16 is received in the space formed by
20 the spaced hub 12 and ring member 14 so as to form a resilient
21 connection between the hub 12 and the ring member 14. The
22 elastomeric member 16 may comprise any suitable elastomeric
23 material such as natural or synthetic rubber or the like which is
24 relatively incompressible. The elastomeric member 16 is
25 preferably bonded to the hub 12 and ring gear 14 by a suitable
26 adhesive (not shown) which is effective for establishing a secure

1 bond between the elastomeric material and the material of the hub
2 12 and ring member 14. In most instances the hub 12 and ring
3 member 14 are constructed from metallic materials, although other
4 rigid plastics and synthetic materials are also contemplated

5 With the present gear construction 10, any vibration caused
6 by gear formations 28 meshing with another gear will not be
7 directly transmitted to the gear's drive shaft. Rather, the
8 inwardly extending teeth 26 of the outer ring member 14 are
9 isolated from the hub 12 by the elastomeric member 16. This
10 elastomeric member 16 effectively isolates any vibrations which
11 are developed by the gear formations 28 from reaching the drive
12 shaft. Furthermore, the purpose of the overlapping arm/tooth
13 configuration is to make sure that the loads transmitted through
14 the gear 10 put the elastomeric member 16 in compression rather
15 than shear. Since the elastomeric material is relatively
16 incompressible, the result is a low shear force on the adhesive
17 bonds which hold the elastomeric material to both the inner hub
18 12 and the outer ring member 14.

19 It can thus be seen that the instant invention provides an
20 effective quiet gear construction 10 which is particularly useful
21 in high-torque applications. The elastomeric member 16
22 effectively absorbs and reduces vibrations transmitted through
23 the gear construction, while the intermeshing arm/tooth
24 configuration reduce shear loads which routinely cause failure in
25 the prior art constructions. For these reasons, the instant

1 invention is believed to represent a significant improvement in
2 the art.

3 While there is shown and described herein certain specific
4 structure embodying the invention, it will be manifest to those
5 skilled in the art that various modifications and rearrangements
6 of the parts may be made without departing from the spirit and
7 scope of the underlying inventive concept and that the same is
8 not limited to the particular forms herein shown and described
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3 HIGH-TORQUE QUIET GEAR

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5 ABSTRACT OF THE DISCLOSURE

6 A high-torque quiet gear construction consists of an inner
7 hub having a plurality of circumferentially spaced arms extending
8 radially outwardly therefrom, and an outer ring member having a
9 plurality of circumferentially spaced teeth extending radially
10 inwardly therefrom. The ring member further includes a plurality
11 of gear formations on an outer surface thereof for intermeshing
12 with other gears. The teeth of the ring member are received in
13 spaced relation in corresponding spaces formed between adjacent
14 arms of the hub. An elastomeric member is received in the space
15 formed between the hub and the ring member to form a resilient
16 correction between the arms of the hub and the teeth of the ring
17 member. The side surfaces of the arms and the teeth extend
18 generally parallel to each other and at least partially overlap
19 in a longitudinal direction. The purpose of this configuration
20 is to place the elastomeric member in compression when torque is
21 applied to the hub. Since elastomeric material is relatively
22 incompressible, the result is low shear loads on the adhesive
23 bonds which hold the elastomeric member to both the hub and outer
24 ring member.

